

Appendix 5. Validation of System

Prior to the assessment, the system was verified in the flat region of the phantom. 2450 MHz and 5GHz dipoles were used. A forward power of 250 mW was applied to the dipole and the system was verified to a tolerance of $\pm 5\%$ for the 2450 MHz and 5GHz dipoles. The applicable verification (normalized to 1 Watt).

Date: 21/03/2011

Validation Dipole and Serial Number: D2450V2; SN: 725

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	2450	23.0 °C	22.0 °C	ϵ_r	52.70	51.25	-2.75	5.00
				Σ	1.95	1.99	1.94	5.00
				1g SAR	51.90	52.40	0.96	5.00
				10g SAR	24.10	23.92	-0.75	5.00

Date: 22/03/2011

Validation Dipole and Serial Number: D2450V2; SN: 725

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	2450	23.0 °C	23.0 °C	ϵ_r	52.70	51.25	-2.75	5.00
				Σ	1.95	1.99	1.94	5.00
				1g SAR	51.90	52.40	0.96	5.00
				10g SAR	24.10	24.04	-0.25	5.00

Date: 26/03/2011

Validation Dipole and Serial Number: D5GHzV2; SN: 1016

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	5800	23.0 °C	22.0 °C	ϵ_r	48.20	47.05	-0.02	5.00
				Σ	6.00	6.16	0.03	5.00
				1g SAR	71.70	73.03	1.85	5.00
				10g SAR	19.70	20.44	3.73	5.00

Date: 08/04/2011**Validation Dipole and Serial Number: D5GHzV2: SN: 1016**

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	5200	23.0 °C	23.0 °C	ϵ_r	49.01	49.47	0.52	5.00
				Σ	5.30	5.28	-0.37	5.00
				1g SAR	76.70	78.93	2.91	5.00
				10g SAR	22.05	21.21	4.01	5.00

Date: 08/04/2011**Validation Dipole and Serial Number: D5GHzV2: SN: 1016**

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	5500	23.0 °C	23.0 °C	ϵ_r	48.60	48.37	-0.47	5.00
				Σ	5.65	5.77	2.12	5.00
				1g SAR	82.80	83.20	0.48	5.00
				10g SAR	22.83	23.44	2.67	5.00

Appendix 6. Simulated Tissues

The body mixture consists of de-ionised water, Polysorbate 20, Polysorbate 80 and salt. Visual inspection is made to ensure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue.

Ingredient	Frequency
	2450 MHz Body
De-Ionized Water	71.70
Polysorbate 20 (Tween 20)	28.00
Salt	0.30

Ingredient	Frequency
	5200 - 5800 MHz Body
De-Ionized Water	80.00
Polysorbate 80 (Tween 80)	20.00

Appendix 7. DASY4 System Details

A.7.1. DASY4 SAR Measurement System

RFI Global Services Ltd, SAR measurement facility utilises the Dosimetric Assessment System (DASY™) manufactured by Schmid & Partner Engineering AG (SPEAG™) of Zurich, Switzerland. The DASY4 system is comprised of the robot controller, computer, near-field probe, probe alignment sensor, and the SAM phantom containing brain or muscle equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF). A cell controller system contains the power supply, robot controller; teach pendant (Joystick), and remote control. This is used to drive the robot motors. The Staubli robot is connected to the cell controller to allow software manipulation of the robot. The data acquisition electronics (DAE) performs signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection etc. The DAE is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card. The DAE3 utilises a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16-bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe-mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

A.7.2. DASY4 SAR System Specifications**Robot System**

Positioner:	Stäubli Unimation Corp. Robot Model: RX90L
Repeatability:	0.025 mm
No. of Axis:	6
Serial Number:	F00/SD89A1/A/01
Reach:	1185 mm
Payload:	3.5 kg
Control Unit:	CS7
Programming Language:	V+

Data Acquisition Electronic (DAE) System

Serial Number:	DAE3 SN:450
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PC Controller

PC:	Dell Precision 340
Operating System:	Windows 2000
Data Card:	DASY4 Measurement Server
Serial Number:	1080

Data Converter

Features:	Signal Amplifier, multiplexer, A/D converted and control logic.
Software:	DASY4 Software
Connecting Lines:	Optical downlink for data and status info. Optical uplink for commands and clock.

PC Interface Card

Function:	24 bit (64 MHz) DSP for real time processing Link to DAE3 16 bit A/D converter for surface detection system serial link to robot direct emergency stop output for robot.
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DASY4 SAR System Specifications (Continued)**E-Filed Probe**

Model:	EX3DV3
Serial No:	3508
Construction:	Triangular core
Frequency:	10 MHz to >6 GHz
Linearity:	± 0.2 dB (30 MHz to 6 GHz)
Probe Length (mm):	330
Probe Diameter (mm):	12
Tip Length (mm):	20
Tip Diameter (mm):	2.5
Sensor X Offset (mm):	1
Sensor Y Offset (mm):	1
Sensor Z Offset (mm):	1

Phantom

Phantom:	SAM Phantom
Shell Material:	Fibreglass
Thickness:	2.0 $\pm$ 0.1 mm

Phantom

Phantom:	OVAL Phantom
Shell Material:	Fibreglass
Thickness:	3.0 $\pm$ 0.1 mm