

# SAR TEST REPORT

Applicant	:	SteelSeries ApS.
Address	:	656 W Randolph St., Suite 3E Chicago, IL 60661, USA
Manufacturer	:	SteelSeries ApS.
Address	:	656 W Randolph St., Suite 3E Chicago, IL 60661, USA
Equipment	:	Wireless Headset
Model No.	:	HS42
Trade Name	:	<b>io steel</b> series
FCC ID	:	ZHK-HS42

## I HEREBY CERTIFY THAT:

The sample was received on Aug. 07, 2023 and the testing was completed on Sep. 06, 2023 at Cerpass Technology Corp. The test result refers exclusively to the test presented test model / sample. Without written approval of Cerpass Technology Corp., the test report shall not be reproduced except in full.

Approved by:

Vic Hsiao / Supervisor

Laboratory Accreditation:

Cerpass Technology Corporation Test Laboratory





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# History of this test report

Attachment No.	Issued Date	Description
23060229-TRFCC05	Nov. 10, 2023	Original



## 1. Summary of Maximum SAR Value

Results for highest reported SAR values for each frequency band and mode are as below:

Band	Mode	Highest Body standalone SAR 1g (W/kg)
FHSS	GFSK	0.11
DTS	GFSK	0.09

Note:

1. The SAR criteria (Head & Body: SAR-1g1.6 W/kg, and Extremity: SAR-10g 4.0 W/kg) for general population/uncontrolled exposure is specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1992 and ISEDRSS 102, Issue 5.

2. According to 47 CFR part 2.1093, the MPE limits specified in part 1.1310 apply to portable devices that transmit at frequencies above 6 GHz. The localized power density limit for general population exposure is 1.0 mW/cm (equal to 10 W/m) for frequency up to 100 GHz.

3. The lab has reduced the uncertainty risk factor from test equipment, environment and staff technicians which according to the standard on contract. Therefore, the test result will only be determined by standard requirement.

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# 2. Test Configuration of Equipment under Test

Operation Frequency Range	2400MHz-2483.5MHz		
Center Frequency Range	2402MHz-2480MHz		
Madulation Type	DTS: GFSK		
Modulation Type	FHSS: GFSK, $\pi$ /4-DQPSK		
Modulation Technology	DTS, FHSS		
Data Rate	DTS: 1Mbps, 2Mbps		
Dala Rale	FHSS: 1Mbps, 2Mbps		
Antenna Type	Metal Antenna		
Antenna Gain	4.01 dBi		
Battery	Huizhou Everpower Technology Co., Ltd. \ PL603033 \ 3.7V		
	Perfect Fortune Electric Wire & Cable (Shen Zhen) Co., Ltd. \		
USB-C to USB-A Charging	122331330016 \ 1.5M		
cable	Perfect Fortune Electric Wire & Cable (Shen Zhen) Co., Ltd. \		
	122331330020 \ 1.5M		

Note: For more details, please refer to the User's manual of the EUT.

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## 3. General Information of Test

	Cerpass Technology Corporation Test Laboratory
	Address: No.10, Ln. 2, Lianfu St., Luzhu Dist., Taoyuan City
Test Site	33848, Taiwan (R.O.C.)
	Tel:+886-3-3226-888
	Fax:+886-3-3226-881

Test Item	Test Site	Tested By		
SAR	RFSAR01-NK	Roy		

Test Site	Test Period	Temp.	Humi.
RFSAR01-NK	2023/09/04	22.5	48

Note:

The SAR measurement facilities used to collect data are within Cerpass SAR Lab list below test site location are accredited to ISO 17025 by Taiwan Accreditation Foundation (TAF code:1439) and the FCC designation No. TW1439 under the FCC 2.948(e) by Mutual Recognition Agreement (MRA) in FCC test.

## 4. Remarks and comments

Variability and simultaneous transmission results shown in this report are based on the highest SAR value obtained among all antenna manufacturers.

3.Only the plots for the test positions with the highest measured SAR per band/mode are included in Annex C as required per FCC OET KDB 865664 D02, paragraph 2.3.8.

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## 5. Basic restrictions and Standards

#### 5.1 Test Standards

FCC 47 CFR Part 2 (2.1093)

IEEE C95.1

#### 5.2 Reference Standards

FCC KDB Publication 865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04 FCC KDB Publication 447498 D01 General RF Exposure Guidance v06 FCC KDB Publication 447498 D04 Interim General RF Exposure Guidance v01 FCC KDB Publication 447498 D02: SAR procedure for USB dongle transmitter v02r01 FCC KDB Publication 248227 D01 802.11 Wi-Fi SAR v02r02 FCC KDB Publication 941225D06 Hot Spot SAR v02r01 IEEE 62209-1528 : 2020

#### 5.3 Environment Condition

ltem	Target
Ambient Temperature( $^{\circ}$ C)	18~25
Temperature of Simulant( $^{\circ}$ C)	20~22
Relative Humidity(%RH)	30~70

#### 5.4 **RF Exposure Limits**

SAR assessments have been made in line with the requirements of FCC 47CFR Part 2.1093 and ISED RSS 102 issue 5 on the limitation of exposure of the general population / uncontrolled exposure for portable devices.

Exposure Type	General Population / Uncontrolled Environment
Peak spatial-average SAR (averaged over any 1 gram of tissue)	1.6 W/kg
Whole body average SAR	0.08 W/kg
Peak spatial-average SAR (extremities) (averaged over any 10 grams of tissue)	4.0 W/kg

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## 6. Test & System Description

## 6.1 SAR Definition

Specific Absorption rate is defined as the time derivative of the incremental energy (dW) a bsorbed by (dissipated in) and incremental mass (dm) contained in a volume element (dV) of a given density ( $\rho$ ).

$$SAR = \frac{d}{dt} \cdot \left(\frac{dW}{dm}\right) = \frac{d}{dt} \cdot \left(\frac{dW}{\rho \cdot dV}\right)$$

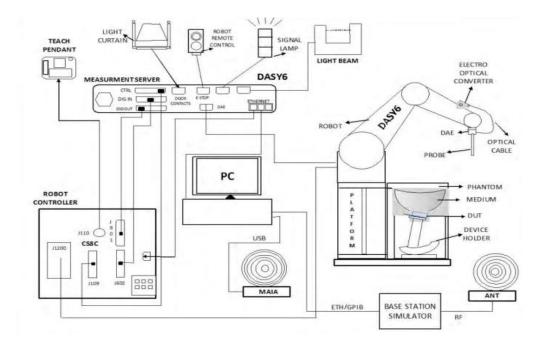
SAR is expressed in units of watts per kilogram (W/kg). SAR can be related to the electric field at a point by Where:

- $\sigma$  = Conductivity of the tissue (S/m)
- $\rho$  = Mass density of the tissue (kg/m3)
- E = RMS electric field strength (V/m)

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## 6.2 SAR Measurement System



- A standard high precision 6-axis robot (Staübli TX/RX family) with controller, teach pendant and software. It includes an arm extension for accommodating the data acquisitionelectronics (DAE)
- ✓ An isotropic field probe optimized and calibrated for the targeted measurements.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- ✓ The Electro-optical Converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. The EOC signal is transmitted to the measurement server.
- ✓ The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movements interrupts.
- ✓ The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- ✓ A computer running Win10 professional operating system and the cDASY6 and DASY5 V5.2 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- ✓ The phantom, the device holder and other accessories according to the targeted measurement.





#### 6.3 Probes

The SAR measurement is conducted with the dosimetric probe manufactured by SPEAG. The

probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric

probe has special calibration in liquid at different frequency.

SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN 62209-1, IEC 62209, etc.) under ISO 17025. The calibration data are in Appendix A.

Model	EX3DV4	
Construction	Symmetrical design with triangular core Built-in shielding against static charges	
	PEEK enclosure material (resistant to organic solvents, e.g.	, DGBE)
Frequency	4 MHz to 10 GHz	
	Linearity: ± 0.2 dB (30 MHz to 10 GHz)	
Directivity	± 0.1 dB in TSL (rotation around probe axis)	
	± 0.3 dB in TSL (rotation normal to probe axis)	
Dynamic	10 μW/g to 100 mW/g	
Range	Linearity: $\pm$ 0.2 dB (noise: typically < 1 $\mu$ W/g)	
Dimensions	Overall length: 330 mm (Tip: 20 mm)	/
	Tip diameter: 2.5 mm (Body: 12 mm)	
	Typical distance from probe tip to dipole centers: 1 mm	

## 6.4 Data Acquisition Electronics (DAE)

Model	DAE4	
Construction	Signal amplifier, multiplexer, A/D converter and control logic. Serial optical link for communication with DASY embedded system (fully remote controlled). Two step probe touch detector for mechanical surface detection and emergency robot stop.	
Measurement	-100 to +300 mV (16 bit resolution and two range	0
Range	settings: 4 mV, 400 mV)	
Input Offset	< 5 μV (with auto zero)	
Voltage		
Input Bias	Input Bias Current	
Current		
Dimensions	60 x 60 x 68 mm	





#### 6.5 Robot

The DASY5 system uses the high precision robots TX60 L type out of the newer series from Stäubli SA (France). For the 6-axis controller DASY6 system, the CS8C robot controller version from Stäubli is used.

The XL robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic
- construction shields against motor control fields)
- 6-axis controller



The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- Right head
- Flat phantom

The ELI4 Phantom also is a fiberglass shell phantom with 2mm shell thickness. It has 30 liters filling volume, and with a dimension of 600mm for major ellipse axis, 400mm for minor axis. It is intended for compliance testing of handheld and body-mounted wireless devices in frequency range of 30 MHz to 6GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.





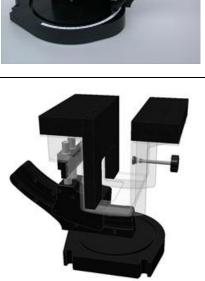
The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.



## 6.7 Device Holder

The DASY5 device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).Thus the device needs no repositioning when changing the angles. The DASY5 device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon r = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

The laptop extension is lightweight and made of POM, acrylic glass and foam. It fits easily on upper part of the mounting device in place of the phone positioned. The extension is fully compatible with the SAM Twin and ELI phantoms.



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Name of Equipment	Manufacturer	Type/Model	Serial Number	Calibration Cycle(year)	Calibration Period
Robot	Staubli	TX60L Lspeag	F13/5P6VA1/A/01	/	NCR
DASY Test Software	Staubli	cDASY6 V16.0.2.136	/	/	NCR
DASY Test Software	Staubli	DASY5.2	14.6.14.7483	/	NCR
Signal Grenerator	KEYSIGHT	N5183A	MY50142931	1	2024/3/2
S-Parameter Network Analyzer	Agilent	E5071C	70045-459-220-350	1	2023/8/17
Dielectric parameter probes	SPEAG	DAKS-3.5	1121	1	NCR
Power Meter	Anritsu	ML2495A	1224005	1	2024/4/28
Power Sensor	Anritsu	MA2411B	1207295	1	2024/4/28
Data Acquisition Electronics	SPEAG	DAE4	1379	1	2024/6/16
Dosimetric E-Field Probe	SPEAG	EX3DV4	3927	1	2024/6/26
2450MHz System Validation Dipole	SPEAG	D2450V2	914	3	2024/8/26
Amplifier	Mini-Circuits	ZVE-8G+	70501814	/	NCR
Amplifier	Mini-Circuits	ZVE-3W-183+	N636102230	/	NCR
Thermometer	Hi Sun	TH05A	11442	1	2024/7/27

## 6.8 Test Equipment and Ancillaries Used for Tests

\*Please Refer to the Appendix A. DASY Calibration Certificate.

Note:

- 1. Prior to system verification and validation, the path loss from the signal generator to the system check source and the power meter, which includes the amplifier, cable, attenuator and directional coupler, was measured by the network analyzer. The reading of the power meter was offset by the path loss difference between the path to the power meter and the path to the system check source to monitor the actual power level fed to the system check source.
- 2. Referring to KDB 865664 D01v01r04, the dipole calibration interval can be extended to 3 years with justification. The dipoles are also not physically damaged, or repaired during the interval.
- 3. The justification data of dipole can be found in Appendix B. The return loss is < -20dB, within 20% of prior calibration, the impedance is within 5 ohm of prior calibration

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## 7. The SAR Measurement Procedure

#### 7.1 System Performance Check

#### 7.1.1 Purpose

- 1. To verify the simulating liquids are valid for testing.
- 2. To verify the performance of testing system is valid for testing.

#### 7.1.2 Tissue Dielectric Parameters for Head Phantoms

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15 cm. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 10 % are listed in Table.

Frequency (MHz)	Target Permittivity	Range of ±10 %	Target Conductivity	Range of ±10 %
450	43.5	39.2 ~ 47.9	0.87	0.78 ~ 0.96
750	41.9	37.7 ~ 46.1	0.89	0.80 ~ 0.98
835	41.5	37.4 ~ 45.7	0.90	0.81 ~ 0.99
900	41.5	37.4 ~ 45.7	0.97	0.87 ~ 1.07
1450	40.5	36.5 ~ 44.6	1.20	1.08 ~ 1.32
1500	40.4	36.4 ~ 44.4	1.23	1.11 ~ 1.35
1640	40.2	36.2 ~ 44.2	1.31	1.18 ~ 1.44
1750	40.1	36.1 ~ 44.1	1.37	1.23 ~ 1.51
1800	40.0	36.0 ~ 44.0	1.40	1.26 ~ 1.54
1900	40.0	36.0 ~ 44.0	1.40	1.26 ~ 1.54
2000	40.0	36.0 ~ 44.0	1.40	1.26 ~ 1.54
2100	39.8	35.8 ~ 43.8	1.49	1.34 ~ 1.64
2300	39.5	35.6 ~ 43.5	1.67	1.50 ~ 1.84
2450	39.2	35.3 ~ 43.1	1.80	1.62 ~ 1.98
2600	39.0	35.1 ~ 42.9	1.96	1.76 ~ 2.16
3000	38.5	34.7 ~ 42.4	2.40	2.16 ~ 2.64
3500	37.9	34.1 ~ 41.7	2.91	2.62 ~ 3.20
4000	37.4	33.7 ~ 41.1	3.43	3.09 ~ 3.77
4500	36.8	33.1 ~ 40.5	3.94	3.55 ~ 4.33
5000	36.2	32.6 ~ 39.8	4.45	4.01 ~ 4.90
5200	36.0	32.4 ~ 39.6	4.66	4.19 ~ 5.13
5400	35.8	32.2 ~ 39.4	4.86	4.37 ~ 5.35
5600	35.5	32.0 ~ 39.1	5.07	4.56 ~ 5.58
5800	35.3	31.8 ~ 38.8	5.27	4.74 ~ 5.80
6000	35.1	31.6 ~ 38.6	5.48	4.93 ~ 6.03
6500	34.5	31.1 ~ 38.0	6.07	5.46 ~ 6.68
7000	33.9	30.5 ~ 37.3	6.65	5.99 ~ 7.32

<Tissue Dielectric Parameters in IEEE 1528-2013 and IEC/IEEE 62209-1528>

Note:

1.According to April 2019 TCB workshop, Effective February 19,2019,FCC has permitted the use of single head-tissue simulating liquid specified in IEC 62209-1 for all SAR tests.



#### 7.1.3 Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using DASY5 Dielectric Assessment Kit and Agilent Vector Network Analyzer E5071C.

#### Please Refer to the Appendix B System Performance Check.

Note:

- 1. The Delta Permittivity% and Delta Conductivity% should be both within ±5% limit of target values.
- Refer to KDB 865664 D01 v01r04, The depth of body tissue-equivalent liquid in a phantom must be ≥ 15.0 cm with ≤ ± 0.5 cm variation for SAR measurements ≤ 3 GHz and ≥ 10.0 cm with ≤ ± 0.5 cm variation for measurements > 3 GHz.

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#### 7.1.4 System Performance Check Procedure

The DASY5 installation includes predefined files with recommended procedures for measurements and the system performance check. They are read-only document files and destined as fully defined but unmeasured masks, so the finished system performance check must be saved under a different name. The system performance check document requires the SAM Twin Phantom or ELI4 Phantom, so the phantom must be properly installed in your system. (User defined measurement procedures can be created by opening a new document or editing an existing document file). Before you start the system performance check, you need only to tell the system with which components (probe, medium, and device) you are performing the system performance check; the system will take care of all parameters.

**The Power Reference Measurement and Power Drift Measurement** jobs are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the Dipole output power. If it is too high (above  $\pm 0.2$  dB), the system performance check should be repeated;

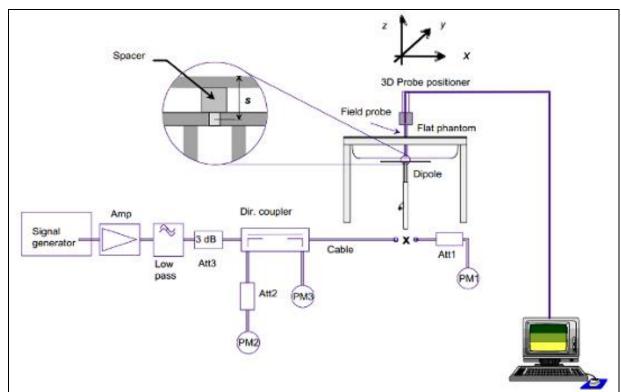
**The Surface Check** job tests the optical surface detection system of the DASY5 system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above  $\pm 0.1$ mm). In that case it is better to abort the system performance check and stir the liquid;

■ **The Area Scan** job measures the SAR above the dipole on a plane parallel to the surface. It is used to locate the approximate location of the peak SAR. The proposed scan uses large grid spacing for faster measurement; due to the symmetric field, the peak detection is reliable;

**The Zoom Scan** job measures the field in a volume around the peak SAR value assessed in the previous Area Scan job (for more information see the application note on SAR evaluation). If the system performance check gives reasonable results. The dipole input power(forward power) was 250mW, 1 g and 10 g spatial average SAR values normalized to 1W dipole input power give reference data for comparisons and it's equal to 10x(dipole forward power). The next sections analyze the expected uncertainties of these values, as well as additional checks for further information or troubleshooting.

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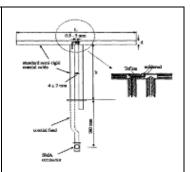




## 7.1.5 System Performance Check Setup

#### 7.1.6 Validation Dipoles

The dipoles use is based on the IEEE Std.1528-2013 and FCC KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04 standard, and is complied with mechanical and electrical specifications in line with the requirements of both EN62209-1 and EN62209-2. The table below provides details for the mechanical and electrical specifications for the dipoles.



#### 7.1.7 Result of System Performance Check: Valid Result

Please Refer to the Appendix B System Performance Check.

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## 8. SAR Measurement Procedure

#### 8.1 Test Procedures

#### Step 1 Setup a Connection

First, engineer should record the conducted power before the test. Then establish a call in handset at the maximum power level with a base station simulator via air interface, or make the EUT estimate by itself in testing band. Place the EUT to the specific test location. After the testing, must export SAR test data by SEMCAD. Then writing down the conducted power of the EUT into the report, also the SAR values tested.

#### **Step 2 Power Reference Measurements**

To measure the local E-field value at a fixed location which value will be taken as a reference value for calculating a possible power drift.

#### Step 3 Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE Standard 1528 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan). If only one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of Zoom Scans has to be increased accordingly.

	$\leq$ 3 GHz	> 3 GHz	
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1 \text{ mm}$	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$	
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^{\circ} \pm 1^{\circ}$	$20^\circ \pm 1^\circ$	
	$\leq$ 2 GHz: $\leq$ 15 mm 2 - 3 GHz: $\leq$ 12 mm	$\begin{array}{l} 3-4 \text{ GHz:} \leq 12 \text{ mm} \\ 4-6 \text{ GHz:} \leq 10 \text{ mm} \end{array}$	
Maximum area scan spatial resolution: $\Delta x_{Area}$ , $\Delta y_{Area}$	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.		

#### Area Scan Parameters extracted from KDB 865664 D01v01r04

#### Step 4 Zoom Scan

Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The Zoom Scan measures points (refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1 g and 10 g and displays these values next to the job's label.



			$\leq$ 3 GHz	> 3 GHz
Maximum zoom scan spatial resolution: $\Delta x_{Zoom}$ , $\Delta y_{Zoom}$		$\leq 2 \text{ GHz}$ : $\leq 8 \text{ mm}$ 2 - 3 GHz: $\leq 5 \text{ mm}^*$	$\begin{array}{l} 3-4 \; \mathrm{GHz:} \leq 5 \; \mathrm{mm}^* \\ 4-6 \; \mathrm{GHz:} \leq 4 \; \mathrm{mm}^* \end{array}$	
Maximum zoom scan spatial resolution, normal to phantom surface	uniform	grid: ∆z <sub>Zoom</sub> (n)	$\leq$ 5 mm	$\begin{array}{c} 3-4 \ \mathrm{GHz:} \leq 4 \ \mathrm{mm} \\ 4-5 \ \mathrm{GHz:} \leq 3 \ \mathrm{mm} \\ 5-6 \ \mathrm{GHz:} \leq 2 \ \mathrm{mm} \end{array}$
	graded	$\Delta z_{Zoom}(1)$ : between 1 <sup>st</sup> two points closest to phantom surface	$\leq$ 4 mm	$3-4 \text{ GHz:} \le 3 \text{ mm}$ $4-5 \text{ GHz:} \le 2.5 \text{ mm}$ $5-6 \text{ GHz:} \le 2 \text{ mm}$
	grid	Δz <sub>Zoom</sub> (n>1): between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$	
Minimum zoom scan volume	x, y, z	_	$ \begin{array}{c} 3 - 4 \text{ GHz:} \ge 2 \\ 2 & 30 \text{ mm} \end{array} \\ \begin{array}{c} 3 - 4 \text{ GHz:} \ge 2 \\ 4 - 5 \text{ GHz:} \ge 2 \\ 5 - 6 \text{ GHz:} \ge 2 \end{array} $	

#### Zoom Scan Parameters extracted from KDB 865664 D01 v01r04

When zoom scan is required and the reported SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is  $\leq 1.4$  W/kg,  $\leq 8$  mm,  $\leq 7$  mm and  $\leq 5$  mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

#### **Step 5 Power Drift Measurements**

Repetition of the E-field measurement at the fixed location mentioned in Step 1 to make sure the two results differ by less than  $\pm 0.2$  dB.

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#### 8.2 RF Exposure Positions

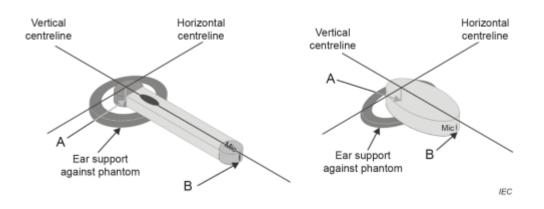
#### 8.2.1 DUTs with alternative form factor

The basic principles identified and specified in 7.2.4 may be applied to devices with similar form factors. Wireless headsets (e.g. connected by Bluetooth) are examples of head-mounted devices that may be evaluated by applying these principles.

The geometry and coordinate mapping system shown in Figure 18 is applicable. Point A, being the acoustic output, is located at the mid-point of the width, and point B, being the primary microphone, is located at the bottom of the device (the end closest to the mouth). Note that for the purpose of applying the positioning procedures, the DUT is considered to be a conventional bar type (rectangular, cuboid) form factor.

Prior to using 7.2.7, consideration shall be made of the available operating modes and the maximum operating power levels, because some devices might not require testing.

All details relating to alternative form factor DUTs shall be fully documented in the measurement report, including diagrams or photographs. Sound engineering practice shall be applied to implement the mapping of an alternate form factor device.



An alternative form factor DUT with reference points and reference lines

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#### 8.3 Measurement Evaluation

#### <WLAN >

#### Initial Test Configuration

An initial test configuration is determined for OFDM transmission modes in 2.4 GHz and 5 GHz bands according to the channel bandwidth, modulation and data rate combination(s) with the highest maximum output power specified for production units in each standalone and aggregated frequency band. When the same maximum power is specified for multiple transmission modes in a frequency band, the largest channel bandwidth, lowest order modulation, lowest data rate and lowest order 802.11a/g/n/ac mode is used for SAR measurement, on the highest measured output power channel in the initial test configuration, for each frequency band.

#### **Subsequent Test Configuration**

SAR measurement requirements for the remaining 802.11 transmission mode configurations that have not been tested in the initial test configuration are determined separately for each standalone and aggregated frequency band, in each exposure condition, according to the maximum output power specified for production units. Additional power measurements may be required to determine if SAR measurements are required for subsequent highest output power channels in a subsequent test configuration. When the highest reported SAR for the initial test configuration according to the initial test position or fixed exposure position requirements, is adjusted by the ratio of the subsequent test configuration to initial test configuration specified maximum output power and the adjusted SAR is  $\leq 1.2$  W/kg, SAR is not required for that subsequent test configuration.

#### SAR Test Configuration and Channel Selection

When multiple channel bandwidth configurations in a frequency band have the same specified maximum output power, the initial test configuration is using largest channel bandwidth, lowest order modulation, lowest data rate, and lowest order 802.11 mode (i.e., 802.11a is chosen over 802.11n then 802.11ac or 802.11g is chosen over 802.11n). After an initial test configuration is determined, if multiple test channels have the same measured maximum output power, the channel chosen for SAR measurement is determined according to the following.

1) The channel closest to mid-band frequency is selected for SAR measurement.

2) For channels with equal separation from mid-band frequency; for example, high and low channels or two mid-band channels, the higher frequency (number) channel is selected for SAR measurement.

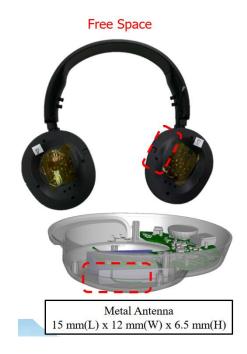


# 9. Wi-Fi SAR Exclusion and Results

9.1 Measured Conducted Average Power

Please Refer to the Appendix C Measured Conducted Power.

9.2 Antenna Location



Antennas	Wireless Interface	
Main Ant	FHSS	
	DTS	

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#### Please Refer to the Appendix D SAR measurement data.

#### **General Note:**

1. Per KDB 447498 D01v06, the reported SAR is the measured SAR value adjusted for maximum tune-up tolerance.

a. Tune-up scaling Factor = tune-up limit power (mW) / EUT RF power (mW), where tune-up limit is the maximum rated power among all production units.

b. For SAR testing of WLAN signal with non-100% duty cycle, the measured SAR is scaled-up by the duty cycle scaling factor which is equal to "1/(duty cycle)"

c. For WWAN: Reported SAR(W/kg)= Measured SAR(W/kg)\*Tune-up Scaling Factor d. For WLAN/Bluetooth: Reported SAR(W/kg)= Measured SAR(W/kg)\* Duty Cycle scaling factor \* Tune-up scaling factor

2. Per KDB 447498 D01v06, for each exposure position, testing of other required channels within the operating mode of a frequency band is not required when the reported 1-g or 10-g SAR for the mid-band or highest output power channel is:

• ≤ 0.8 W/kg or 2.0 W/kg, for 1-g or 10-g respectively, when the transmission band is ≤ 100 MHz

•  $\leq$  0.6 W/kg or 1.5 W/kg, for 1-g or 10-g respectively, when the transmission band is between 100 MHz and 200 MHz

•  $\leq$  0.4 W/kg or 1.0 W/kg, for 1-g or 10-g respectively, when the transmission band is  $\geq$  200 MHz 3. Per KDB 865664 D01v01r04, for each frequency band, repeated SAR measurement is required only when the measured SAR is  $\geq$ 0.8W/kg.

#### WLAN Note:

 Per KDB248227 D01 v02r02 section 5.2.1 2), when the reported SAR is > 0.8 W/kg, SAR is required for that exposure configuration using the next highest measured output power channel. When any reported SAR is > 1.2 W/kg, SAR is required for the third channel; i.e., all channels require testing.

2. When the highest reported SAR for DSSS is adjusted by the ratio of OFDM to DSSS specified maximum output power and the adjusted SAR is  $\leq$  1.2 W/kg, 802.11g/n OFDM SAR is not required, per KDB248227 D01 v02r01 section 5.2.2 2).

## 9.4 SAR Measurement Variability

According to KDB 865664 D01v01r04, SAR measurement variability must be assessed for each frequency band, which is determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media are required for SAR measurements in a frequency band, the variability measurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium. The following procedures are applied to determine if repeated measurements are required:

1. The original highest measured Reported SAR 1-g is  $\geq$  0.80 W/kg, repeated that measurement once.

2. Perform a second repeated measurement the ratio of the largest to the smallest SAR for the original and first repeated measurements is <1.2 W/kg, or when the original or repeated measurement is  $\geq$  1.45 W/kg (~10% from the 1-g SAR limit).

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## 10. Simultaneous Transmission Analysis

1. The reported SAR summation is calculated based on the same configuration and test position.

8. Per KDB 447498 D01v06, simultaneous transmission SAR is compliant if,

i)Scalar SAR summation < 1.6W/kg.

ii)SPLSR =  $(SAR1 + SAR2)^{1.5}$  / (min. separation distance, mm), and the peak separation distance is determined from the square root of [(x1-x2)2 + (y1-y2)2 + (z1-z2)2], where (x1, y1, z1) and (x2, y2, z2) are the coordinates of

the extrapolated peak SAR locations in the zoom scan.

iii)If SPLSR ≤ 0.04, simultaneously transmission SAR measurement is not necessary.

iv)Simultaneously transmission SAR measurement, and the reported multi-band SAR < 1.6W/kg. v) The SPLSR calculated results please refer to section 8.2.

#### 10.1 Co-location

N/A

#### **10.2 SPLSR Evaluation**

N/A

## **11. Measurement Uncertainty**

According to KDB 865664 D01, SAR measurement uncertainty analysis is required in SAR reports only when the highest measured SAR in a frequency band is  $\geq$  1.5 W/kg for 1-g SAR, and  $\geq$  3.75 W/kg for 10-g SAR. The procedures described in IEEE Std 1528-2013should be applied. The expanded SAR measurement uncertainty must be  $\leq$  30%, for a confidence interval of k = 2. When the highest measured SAR within a frequency band is < 1.5 W/kg for 1-g and < 3.75 W/kg for 10-g, the extensive SAR measurement uncertainty analysis described in IEEE Std 1528-2013 is not required in SAR reports submitted for equipment approval. Hence, the measurement uncertainty analysis is not required in this SAR report because the test result met the condition.

-----THE END OF REPORT------

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Appendix A. DASY Calibration Certificate

# **IMPORTANT NOTICE**

## USAGE OF THE DAE4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

**Battery Exchange**: The battery cover of the DAE4 unit is fixed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

**Shipping of the DAE**: Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

**E-Stop Failures**: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

**Repair**: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

**DASY Configuration Files:** Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

#### Important Note:

Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

#### Important Note:

Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the Estop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

#### Important Note:

To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.

# Calibration Laboratory of Schmid & Partner

Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland AC-MRA

CCRED

S Schweizerischer Kalibrierdienst

C Service suisse d'étalonnage

Servizio svizzero di taratura

Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

#### Client Cerpass Taoyuan

Certificate No: DAE4-1379\_Jun23

CALIBRATION C	ERTIFICATE						
Object	DAE4 - SD 000 D	04 BJ - SN: 1379					
Calibration procedure(s)	QA CAL-06.v30 Calibration proced	QA CAL-06.v30 Calibration procedure for the data acquisition electronics (DAE)					
Calibration date:	June 16, 2023						
The measurements and the uncer	tainties with confidence pro	nal standards, which realize the physical units of obability are given on the following pages and an facility: environment temperature (22 $\pm$ 3)°C and	e part of the certificate.				
	L						
Primary Standards Keithley Multimeter Type 2001	ID # SN: 0810278	Cal Date (Certificate No.) 29-Aug-22 (No:34389)	Scheduled Calibration				
		23 Aug 22 (10.04003)	Aug-23				
Secondary Standards	ID #	Check Date (in house)	Scheduled Check				
Auto DAE Calibration Unit Calibrator Box V2.1	SE UWS 053 AA 1001 SE UMS 006 AA 1002	27-Jan-23 (in house check) 27-Jan-23 (in house check)	In house check: Jan-24				
			In house check: Jan-24				
· · ·							
Calibrated by	Name	Function	Signature				
Calibrated by:	Adrian Gehring	Laboratory Technician	AS				
Approved by:	Sven Kühn	Technical Manager	W. Rfuner				
This calibration cartificate shall po	the reproduced export in f	ull without written approval of the laboratory.	Issued: June 16, 2023				
		an manour million approval of the laboratory.					

# Calibration Laboratory of Schmid & Partner

Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





- S Schweizerischer Kalibrierdienst
- C Service suisse d'étalonnage
  - Servizio svizzero di taratura
- S Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS) The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

## Glossary

DAE Connector angle data acquisition electronics

information used in DASY system to align probe sensor X to the robot coordinate system.

## Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
  - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
  - AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
  - Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
  - Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - *Input resistance:* Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
  - *Power consumption:* Typical value for information. Supply currents in various operating modes.

## **DC Voltage Measurement**

A/D - Converter Resolution nominal

 $\begin{array}{cccc} \mbox{High Range:} & 1LSB = & 6.1 \mu V \ , & \mbox{full range} = & -100...+300 \ mV \\ \mbox{Low Range:} & 1LSB = & 61nV \ , & \mbox{full range} = & -1.....+3mV \\ \mbox{DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec} \end{array}$ 

Calibration Factors	Calibration Factors X		Z	
High Range	403.881 ± 0.02% (k=2)	404.146 ± 0.02% (k=2)	404.089 ± 0.02% (k=2)	
Low Range	4.00875 ± 1.50% (k=2)	3.97946 ± 1.50% (k=2)	3.99983 ± 1.50% (k=2)	

# **Connector Angle**

Connector Angle to be used in DASY system	149.5 ° ± 1 °
---	---------------

## Appendix (Additional assessments outside the scope of SCS0108)

## 1. DC Voltage Linearity

High Range		Reading (µV)	Difference (µV)	Error (%)
Channel X	+ Input	200038.63	1.85	0.00
Channel X	+ Input	20005.58	-1.16	-0.01
Channel X	- Input	-20004.36	1.15	-0.01
Channel Y	+ Input	200038.73	2.14	0.00
Channel Y	+ Input	20001.87	-4.76	-0.02
Channel Y	- Input	-20006.79	-1.04	0.01
Channel Z	+ Input	200042.52	5.70	0.00
Channel Z	+ Input	20004.67	-2.01	-0.01
Channel Z	- Input	-20006.51	-0.72	0.00

Low Range		Reading (µV)	Difference (µV)	Error (%)
Channel X	+ Input	2002.06	0.01	0.00
Channel X	+ Input	201.46	-0.44	-0.22
Channel X	- Input	-198.42	-0.36	0.18
Channel Y	+ Input	2002.34	0.44	0.02
Channel Y	+ Input	200.81	-0.90	-0.45
Channel Y	- Input	-198.98	-0.61	0.31
Channel Z	+ Input	2001.83	-0.00	-0.00
Channel Z	+ Input	201.36	-0.34	-0.17
Channel Z	- Input	-199.01	-0.66	0.33

## 2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (µV)
Channel X	200	-17.84	-19.50
	- 200	19.60	18.15
Channel Y	200	-4.17	-4.94
	- 200	3.55	2.83
Channel Z	200	-9.64	-9.69
	- 200	9.32	8.86

## 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (µV)	Channel Z (µV)
Channel X	200	÷	-1.42	-4.60
Channel Y	200	6.93	-	1.45
Channel Z	200	9.63	5.30	-

## 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16006	13535
Channel Y	16225	13741
Channel Z	15826	15645

#### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec Input  $10M\Omega$ 

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	0.80	-0.07	3.26	0.52
Channel Y	-0.08	-1.78	1.81	0.51
Channel Z	1.05	-0.30	3.15	0.74

#### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

# 7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

## 8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)	
Supply (+ Vcc)	+7.9	
Supply (- Vcc)	-7.6	

# 9. **Power Consumption** (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9