Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, $f=5750 \mathrm{MHz} /$ Zoom Scan, dist $=1.4 \mathrm{~mm}(8 \times 8 \times 7) /$ Cube 0: Measurement grid: $\mathrm{dx}=4 \mathrm{~mm}, \mathrm{dy}=4 \mathrm{~mm}, \mathrm{dz}=1.4 \mathrm{~mm}$
Reference Value $=70.45 \mathrm{~V} / \mathrm{m}$; Power Drift $=0.09 \mathrm{~dB}$
Peak SAR $($ extrapolated $)=30.8 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=7.94 \mathrm{~W} / \mathrm{kg} ; \operatorname{SAR}(10 \mathrm{~g})=\mathbf{2 . 2 5} \mathrm{W} / \mathrm{kg}$
Smallest distance from peaks to all points 3 dB below $=7.2 \mathrm{~mm}$
Ratio of SAR at M2 to SAR at M1 $=66.2 \%$
Maximum value of SAR $($ measured $)=19.3 \mathrm{~W} / \mathrm{kg}$


Impedance Measurement Plot for Head TSL


## ANNEX I Sensor Triggering Data Summary

SAR sensor trigger Diagram:


|  | serial number | Trigger scene | SAR test scene | Side | declarative distance |
| :---: | :---: | :---: | :---: | :---: | :---: |
| ANT1 LB/MB Ant | 1 | 234G sar sensor trigger | Body sar back | Back (mm) | 16 mm |
|  | 2 | 234G sar sensor trigger | Body sar front | Front(mm) | 17 mm |
|  | 3 | 234G sar sensor trigger | Body sar top | top(mm) | 12 mm |
|  | 4 | 234G sar sensor trigger | Body sar left | Right(mm) | 13mm |
| ANT2 HB/UHB Ant | 5 | 234G sar sensor trigger | Body sar back | Back (mm) | 16 mm |
|  | 6 | 234G sar sensor trigger | Body sar front | Front(mm) | 20mm |
|  | 7 | 234G sar sensor trigger | Body sar top | top(mm) | 18mm |
| ANT3 WIFI Ant | 8 | vifi sar sensor trigger | Body sar back | Back (mm) | 18mm |
|  | 9 | vifi sar sensor trigger | Body sar front | Front(mm) | 16 mm |
|  | 10 | vifi sar sensor trigger | Body sar top | top(mm) | 16 mm |

Per FCC KDB Publication 616217 D04v01r02, this device was tested by the manufacturer to determine the proximity sensor triggering distances for the rear and bottom edge of the device. The measured output power within $\pm 5 \mathrm{~mm}$ of the triggering points (or until touching the phantom) is included for rear and each applicable edge.

To ensure all production units are compliant it is necessary to test SAR at a distance 1 mm less than the smallest distance from the device and SAR phantom (determined from these triggering tests according to the KDB $616217 \mathrm{D} 04 \mathrm{v} 01 \mathrm{rO2}$ ) with the device at maximum output power without power reduction. These SAR tests are included in addition to the SAR tests for the device touching the SAR phantom, with reduced power.

We tested the power and got the different proximity sensor triggering distances for front, rear, left and top edge for ANT1. The manufacturer has declared 17 mm is the most conservative triggering distance for ANT1 with front edge. The 16 mm distance for rear edge. The 12 mm distance for top edge. The 13 mm distance for Right edge. So base on the most conservative triggering distance of 17/16/12/13mm, additional SAR measurements were required at 16/15/11/12mm from the highest SAR position between front/rear/top/right edge of ANT1.

We tested the power and got the different proximity sensor triggering distances for front, rear, left and top edge for ANT2. The manufacturer has declared 20 mm is the most conservative triggering distance for ANT2 with front edge. The 16 mm distance for rear edge. The 18 mm distance for top edge. So base on the most conservative triggering distance of $20 / 16 / 18 \mathrm{~mm}$, additional SAR measurements were required at $19 / 15 / 17 \mathrm{~mm}$ from the highest SAR position between front/rear/top edge of ANT2.

We tested the power and got the different proximity sensor triggering distances for front, rear, left and top edge for ANT3. The manufacturer has declared 16 mm is the most conservative triggering distance for ANT3 with front edge. The 18 mm distance for rear edge. The 16 mm distance for top edge. So base on the most conservative triggering distance of $16 / 18 / 16 \mathrm{~mm}$, additional SAR measurements were required at $15 / 17 / 15 \mathrm{~mm}$ from the highest SAR position between front/rear/top edge of ANT3.

TTL

## ANT1:

## Front

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ |  |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Rear

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ |  |  |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ |  |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |  |

## Top Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

TTL

## Right Edge

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ | $\mathbf{1 0}$ | $\mathbf{9}$ | $\mathbf{8}$ |  |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{8}$ | $\mathbf{9}$ | $\mathbf{1 0}$ | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ |  |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |  |

ANT2:
Front
Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ | $\mathbf{2 2}$ | $\mathbf{2 3}$ | $\mathbf{2 4}$ | $\mathbf{2 5}$ |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |

## Rear

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance $[\mathbf{m m}]$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Top Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ | $\mathbf{2 2}$ | $\mathbf{2 3}$ |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

ANT3:
Front
Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Rear

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance $[\mathbf{m m}]$ | $\mathbf{2 3}$ | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Top Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ |  |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |

Per FCC KDB Publication 616217 D04v01r02, the influence of table tilt angles to proximity sensor triggering is determined by positioning each edge that contains a transmitting antenna, perpendicular to the flat phantom, at the smallest sensor triggering test distanceby rotating the device around the edge next to the phantom in $\leq 10^{\circ}$ increments until the tablet is $\pm 45^{\circ}$ or more from the vertical position at $0^{\circ}$.


The front/rear evaluation


The top edge evaluation


## The Right edge evaluation

Based on the above evaluation, we come to the conclusion that the sensor triggering is not released and normal maximum output power is not restored within the $\pm 45^{\circ}$ range at the smallest sensor triggering test distancedeclared by manufacturer.

## ANNEX J Accreditation Certificate



