TTL

## ANT1:

## Front

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ |  |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Rear

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 5}$ | $\mathbf{2 4}$ | $\mathbf{2 3}$ | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ |  |  |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ | $\mathbf{2 2}$ | $\mathbf{2 3}$ | $\mathbf{2 4}$ | $\mathbf{2 5}$ |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |

## Top Edge

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 5}$ | $\mathbf{2 4}$ | $\mathbf{2 3}$ | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

TTL

## Right Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ | $\mathbf{1 0}$ | $\mathbf{9}$ |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

ANT2:
Front
Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ |  |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |  |

## Rear

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 5}$ | $\mathbf{2 4}$ | $\mathbf{2 3}$ | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ | $\mathbf{2 2}$ | $\mathbf{2 3}$ | $\mathbf{2 4}$ | $\mathbf{2 5}$ |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Top Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 5}$ | $\mathbf{2 4}$ | $\mathbf{2 3}$ | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 5}$ | $\mathbf{2 4}$ | $\mathbf{2 3}$ | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |

ANT3:
Front
Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ |  |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |  |

## Rear

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 4}$ | $\mathbf{2 3}$ | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ | $\mathbf{2 1}$ | $\mathbf{2 2}$ | $\mathbf{2 3}$ | $\mathbf{2 4}$ |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |

## Top Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 4}$ | $\mathbf{2 3}$ | $\mathbf{2 2}$ | $\mathbf{2 1}$ | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

Per FCC KDB Publication 616217 D04v01r02, the influence of table tilt angles to proximity sensor triggering is determined by positioning each edge that contains a transmitting antenna, perpendicular to the flat phantom, at the smallest sensor triggering test distance by rotating the device around the edge next to the phantom in $\leq 10^{\circ}$ increments until the tablet is $\pm 45^{\circ}$ or more from the vertical position at $0^{\circ}$.


The front/rear evaluation


The top edge evaluation


## The Right edge evaluation

Based on the above evaluation, we come to the conclusion that the sensor triggering is not released and normal maximum output power is not restored within the $\pm 45^{\circ}$ range at the smallest sensor triggering test distance declared by manufacturer.

## ANNEX J Extended Calibration SAR Dipole

Referring to KDB865664 D01, if dipoles are verified in return loss (<-20dBm, within $20 \%$ of prior calibration), and in impedance (within 5 ohm of prior calibration), the annual calibration is not necessary and the calibration interval can be extended.

Justification of Extended Calibration SAR Dipole D750V2- serial no. 1017

| Head |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Date of <br> Measurement | Return-Loss <br> $(\mathrm{dB})$ | Delta (\%) | Real <br> Impedance <br> (ohm) | Delta <br> (ohm) | Imaginary <br> Impedance <br> (johm) | Delta <br> (johm) |  |
| $2021-7-12$ | -28.76 | 1 | 53.78 | 1 | -0.182 | 1 |  |
| $2022-7-09$ | -28.73 | 0.10 | 53.62 | 0.16 | -1.13 | 0.948 |  |

Justification of Extended Calibration SAR Dipole D1750V2- serial no. 1003

| Head |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Date of <br> Measurement | Return-Loss <br> $(\mathrm{dB})$ | Delta (\%) | Real <br> Impedance <br> (ohm) | Delta <br> (ohm) | Imaginary <br> Impedance <br> (johm) | Delta <br> (johm) |
| $2021-7-12$ | -47.038 | 1 | 49.667 | 1 | 0.293 | 1 |
| $2022-7-09$ | -45.852 | 2.52 | 48.53 | -1.137 | 0.321 | 0.028 |

Justification of Extended Calibration SAR Dipole D2450V2- serial no. 853

| Head |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Date of <br> Measurement | Return-Loss <br> $(\mathrm{dB})$ | Delta (\%) | Real <br> Impedance <br> (ohm) | Delta <br> (ohm) | Imaginary <br> Impedance <br> (johm) | Delta <br> (johm) |  |
| $2021-07-26$ | -25.94 | 1 | 53.58 | $/$ | 0.38 | 1 |  |
| $2022-07-20$ | -26.43 | 1.01 | 53.65 | -0.07 | 0.22 | 0.16 |  |

Justification of Extended Calibration SAR Dipole D2600V2- serial no. 1012

| Head |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Date of <br> Measurement | Return-Loss <br> $(\mathrm{dB})$ | Delta (\%) | Real <br> Impedance <br> (ohm) | Delta <br> (ohm) | Imaginary <br> Impedance <br> (johm) | Delta <br> (johm) |
| $2021-07-26$ | -24.094 | $/$ | 47.848 | $/$ | -5.727 | $/$ |
| $2022-07-20$ | -25.123 | -4.27 | 47.543 | -0.305 | -5.657 | 0.07 |

The Return-Loss is $<-20 \mathrm{~dB}$, and within $20 \%$ of prior calibration; the impedance is within 5 ohm of prior calibration. Therefore the value result should support extended cabration.

## ANNEX K Accreditation Certificate



