Dipole Calibration for Body Tissue/Pin $=100 \mathrm{~mW}$, dist $=10 \mathrm{~mm}, \mathrm{f}=5300 \mathrm{MHz} /$ Zoom Scan, dist $=1.4 \mathrm{~mm}(8 \times 8 \times 7) /$ Cube 0 : Measurement grid: $\mathrm{dx}=4 \mathrm{~mm}, \mathrm{dy}=4 \mathrm{~mm}, \mathrm{dz}=1.4 \mathrm{~mm}$ Reference Value $=67.12 \mathrm{~V} / \mathrm{m}$; Power Drift $=-0.07 \mathrm{~dB}$
Peak SAR $($ extrapolated $)=29.1 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=\mathbf{7 . 3 6} \mathrm{W} / \mathrm{kg} ; \operatorname{SAR}(10 \mathrm{~g})=2.06 \mathrm{~W} / \mathrm{kg}$
Smallest distance from peaks to all points 3 dB below $=7.2 \mathrm{~mm}$
Ratio of SAR at M2 to SAR at M1 $=66.1 \%$
Maximum value of SAR $($ measured $)=17.3 \mathrm{~W} / \mathrm{kg}$
Dipole Calibration for Body Tissue/Pin $=100 \mathrm{~mW}$, dist $=10 \mathrm{~mm}, \mathrm{f}=5500 \mathrm{MHz} /$ Zoom Scan,
dist $=1.4 \mathrm{~mm}(8 \times 8 \times 7) /$ Cube 0 : Measurement grid: $\mathrm{dx}=4 \mathrm{~mm}, \mathrm{dy}=4 \mathrm{~mm}, \mathrm{dz}=1.4 \mathrm{~mm}$
Reference Value $=68.41 \mathrm{~V} / \mathrm{m}$; Power Drift $=-0.05 \mathrm{~dB}$
Peak SAR $($ extrapolated $)=33.0 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=\mathbf{7 . 8 6} \mathrm{W} / \mathrm{kg} ; \operatorname{SAR}(10 \mathrm{~g})=2.17 \mathrm{~W} / \mathrm{kg}$
Smallest distance from peaks to all points 3 dB below $=7.2 \mathrm{~mm}$
Ratio of SAR at M2 to SAR at M1 $=64.2 \%$
Maximum value of SAR $($ measured $)=19.0 \mathrm{~W} / \mathrm{kg}$
Dipole Calibration for Body Tissue/Pin $=100 \mathrm{~mW}$, dist $=10 \mathrm{~mm}, \mathrm{f}=5600 \mathrm{MHz} /$ Zoom Scan,
dist $=1.4 \mathrm{~mm}(8 \times 8 x 7) /$ Cube 0 : Measurement grid: $\mathrm{dx}=4 \mathrm{~mm}, \mathrm{dy}=4 \mathrm{~mm}, \mathrm{dz}=1.4 \mathrm{~mm}$
Reference Value $=67.25 \mathrm{~V} / \mathrm{m}$; Power Drift $=-0.08 \mathrm{~dB}$
Peak SAR (extrapolated) $=33.2 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=7.72 \mathrm{~W} / \mathrm{kg} ; \operatorname{SAR}(10 \mathrm{~g})=2.15 \mathrm{~W} / \mathrm{kg}$
Smallest distance from peaks to all points 3 dB below $=7.2 \mathrm{~mm}$
Ratio of SAR at M2 to SAR at M1 $=63.4 \%$
Maximum value of SAR $($ measured $)=18.7 \mathrm{~W} / \mathrm{kg}$
Dipole Calibration for Body Tissue/Pin $=100 \mathrm{~mW}$, dist $=10 \mathrm{~mm}, \mathrm{f}=5750 \mathrm{MHz} /$ Zoom Scan, dist $=1.4 \mathrm{~mm}(8 \times 8 x 7) /$ Cube 0: Measurement grid: $d x=4 \mathrm{~mm}, \mathrm{dy}=4 \mathrm{~mm}, \mathrm{dz}=1.4 \mathrm{~mm}$
Reference Value $=65.67 \mathrm{~V} / \mathrm{m}$; Power Drift $=-0.06 \mathrm{~dB}$
Peak SAR $($ extrapolated $)=34.2 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=\mathbf{7 . 6 1} \mathrm{W} / \mathrm{kg} ; \operatorname{SAR}(10 \mathrm{~g})=2.11 \mathrm{~W} / \mathrm{kg}$
Smallest distance from peaks to all points 3 dB below $=7.2 \mathrm{~mm}$
Ratio of SAR at M2 to SAR at M1 $=62 \%$
Maximum value of SAR (measured) $=18.7 \mathrm{~W} / \mathrm{kg}$
Dipole Calibration for Body Tissue/Pin $=100 \mathrm{~mW}$, dist $=10 \mathrm{~mm}, \mathrm{f}=5800 \mathrm{MHz} /$ Zoom Scan, dist $=1.4 \mathrm{~mm}(8 \times 8 \times 7) /$ Cube 0: Measurement grid: $\mathrm{dx}=4 \mathrm{~mm}, \mathrm{dy}=4 \mathrm{~mm}, \mathrm{dz}=1.4 \mathrm{~mm}$
Reference Value $=65.55 \mathrm{~V} / \mathrm{m}$; Power Drift $=-0.06 \mathrm{~dB}$
Peak SAR $($ extrapolated $)=32.7 \mathrm{~W} / \mathrm{kg}$
$\operatorname{SAR}(1 \mathrm{~g})=\mathbf{7 . 4 2} \mathrm{W} / \mathrm{kg} ; \operatorname{SAR}(10 \mathrm{~g})=2.04 \mathrm{~W} / \mathrm{kg}$
Smallest distance from peaks to all points 3 dB below $=7.2 \mathrm{~mm}$
Ratio of SAR at M2 to SAR at M1 $=62.5 \%$
Maximum value of SAR $($ measured $)=18.2 \mathrm{~W} / \mathrm{kg}$


Impedance Measurement Plot for Body TSL (5200, 5250, 5300, 5500 MHz )


Impedance Measurement Plot for Body TSL (5600, 5750, 5800 MHz )


## ANNEX I Sensor Triggering Data Summary

SAR sensor trigger Diagram:


| Antenna | Trigger <br> Position | Trigger <br> Distance (mm) |
| :---: | :---: | :---: |
| ANT0\&ANT1 | Rear | 15 |
|  | Bottom | 11 |
|  | Front | 10 |
|  | Left | 10 |
| ANT3\&ANT4 | Rear | 15 |
|  | Top | 11 |
|  | Front | 10 |
|  | Left | 10 |

Per FCC KDB Publication 616217 D04v01r02, this device was tested by the manufacturer to determine the proximity sensor triggering distances for the rear and bottom edge of the device. The measured output power within $\pm 5 \mathrm{~mm}$ of the triggering points (or until touching the phantom) is included for rear and each applicable edge.

To ensure all production units are compliant it is necessary to test SAR at a distance 1 mm less than the smallest distance from the device and SAR phantom (determined from these triggering tests according to the KDB $616217 \mathrm{D} 04 \mathrm{v} 01 \mathrm{rO2}$ ) with the device at maximum output power without power reduction. These SAR tests are included in addition to the SAR tests for the device touching the SAR phantom, with reduced power.

We tested the power and got the different proximity sensor triggering distances for rear, bottom, front and left edge for ANT0\&ANT1. The manufacturer has declared 15 mm is the most conservative triggering distance for ANT0\&ANT1 with rear edge. The 11 mm distance for bottom edge. The 10 mm distance for front and left edge. So base on the most conservative triggering distance of $15 / 11 / 10 / 10 \mathrm{~mm}$, additional SAR measurements were required at 14/10/9/9mm from the highest SAR position between rear/bottom/front/left edge of main antenna.

We tested the power and got the different proximity sensor triggering distances for rear, bottom, front and left edge for ANT3\&ANT4. The manufacturer has declared 15 mm is the most conservative triggering distance for ANT3\&ANT4 with rear edge. The 11mm distance for top edge. The 10 mm distance for front and left edge. So base on the most conservative triggering distance of $15 / 11 / 10 / 10 \mathrm{~mm}$, additional SAR measurements were required at $14 / 10 / 9 / 9 \mathrm{~mm}$ from the highest SAR position between rear/top/front/left edge of main antenna.

## Main antenna - ANTO

## Rear

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ | $\mathbf{1 0}$ |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 0}$ | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |

## Bottom

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Front Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Left Edge

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ | $\mathbf{1 0}$ | $\mathbf{9}$ | $\mathbf{8}$ | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ |  |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Main antenna- ANT4

## Rear

Moving device toward the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{2 0}$ | $\mathbf{1 9}$ | $\mathbf{1 8}$ | $\mathbf{1 7}$ | $\mathbf{1 6}$ | $\mathbf{1 5}$ | $\mathbf{1 4}$ | $\mathbf{1 3}$ | $\mathbf{1 2}$ | $\mathbf{1 1}$ | $\mathbf{1 0}$ |  |  |  |  |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |  |  |  |  |

Moving device away from the phantom:

| sensor near or far(KDB 6162176.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{1 0}$ | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ | $\mathbf{1 6}$ | $\mathbf{1 7}$ | $\mathbf{1 8}$ | $\mathbf{1 9}$ | $\mathbf{2 0}$ |  |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |  |

## Bottom

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Front Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |

## Left Edge

Moving device toward the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 |
| Main antenna | Far | Far | Far | Far | Far | Near | Near | Near | Near | Near | Near |

Moving device away from the phantom:

| sensor near or far(KDB 616217 6.2.6) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Distance [mm] | $\mathbf{5}$ | $\mathbf{6}$ | $\mathbf{7}$ | $\mathbf{8}$ | $\mathbf{9}$ | $\mathbf{1 0}$ | $\mathbf{1 1}$ | $\mathbf{1 2}$ | $\mathbf{1 3}$ | $\mathbf{1 4}$ | $\mathbf{1 5}$ |  |  |  |  |
| Main antenna | Near | Near | Near | Near | Near | Near | Far | Far | Far | Far | Far |  |  |  |  |

Per FCC KDB Publication 616217 D04v01r02, the influence of table tilt angles to proximity sensor triggering is determined by positioning each edge that contains a transmitting antenna, perpendicular to the flat phantom, at the smallest sensor triggering test distanceby rotating the device around the edge next to the phantom in $\leq 10^{\circ}$ increments until the tablet is $\pm 45^{\circ}$ or more from the vertical position at $0^{\circ}$.


The front/rear evaluation


The Left edge evaluation
Based on the above evaluation, we come to the conclusion that the sensor triggering is not released and normal maximum output power is not restored within the $\pm 45^{\circ}$ range at the smallest sensor triggering test distance declared by manufacturer.

## ANNEX J Accreditation Certificate



