

Note 1: This is the level at the input of the receiver assuming a 0 dBi receive antenna.

Note 2: Throughout these test procedures an additional 1 dB has been added to the amplitude of the test transmission waveforms to account for variations in measurement equipment. This will ensure that the test signal is at or above the detection threshold level to trigger a DFS response.

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Note3: EIRP is based on the highest antenna gain. For MIMO devices refer to KDB Publication 662911 D01.

DFS Radar Signal Parameter Values:

| Parameter | Value | | |
|-----------------------------------|---|--|--|
| Non-occupancy period | Minimum 30 minutes | | |
| Channel Availability Check Time | 60 seconds | | |
| Channel Move Time | 10 seconds (See Note 1.) | | |
| | 200 milliseconds + an aggregate of 60 | | |
| Channel Closing Transmission Time | milliseconds over remaining 10 second period. | | |
| | (See Notes 1 and 2.) | | |
| U-NII Detection Bandwidth | Minimum 100% of the U-NII 99% transmission | | |
| | power bandwidth. (See Note 3.) | | |

Note 1: Channel Move Time and the Channel Closing Transmission Time should be performed with Radar Type 0. The measurement timing begins at the end of the Radar Type 0 burst.

Note 2: The Channel Closing Transmission Time is comprised of 200 milliseconds starting at the beginning of the Channel Move Time plus any additional intermittent control signals required to facilitate a Channel move (an aggregate of 60 milliseconds) during the remainder of the 10 second period. The aggregate duration of control signals will not count quiet periods in between transmissions.

Note 3: During the U-NII Detection Bandwidth detection test, radar type 0 should be used. For each frequency step the minimum percentage of detection is 90 percent. Measurements are performed with no data traffic.

DFS Radar Signal Parameter:

Radar Type 0 was used in the evaluation of the Client device for the purpose of measuring the Channel Move Time and the Channel Closing Transmission Time

Table 1-Short Pulse Radar Test Waveforms

| Radar Type | Pulse Width (µsec) | PRI (µsec) | Number of Pulses | Minimum Percentage of Successful Detection | Minimum Trials | |
|---------------|--------------------------|------------------|---|---|-------------------|--|
| 0 | 1 | 1428 | 18 | See Note 1. | See Note 1. | |
| 1 | 1 | Test A Test B | Roundup $ \begin{pmatrix} \left(\frac{1}{360}\right) \\ \left(\frac{19 \cdot 10^6}{\text{PRI}_{\mu sec}}\right) \end{pmatrix} $ | 60% | 30 | |
| 2 | 1-5 | 150-230 | 23-29 | 60% | 30 | |
| 3 | 6-10 | 200-500 | 16-18 | 60% | 30 | |
| 4 | 11-20 | 200-500 | 12-16 | 60% | 30 | |
| | Aggrega | ate (Radar 1 | Types 1-4) | 80% | 120 | |

Note 1: Short Pulse Radar Type 0 should be used for the detection bandwidth test, channel move time, and channel closing time tests.

Test A: 15 unique PRI values randomly selected from the list of 23 PRI values in Table 5a

Test B: 15 unique PRI values randomly selected within the range of 518-3066 μ sec, with a minimum increment of 1 μ sec, excluding PRI values selected in Test A

A minimum of 30 unique waveforms are required for each of the Short Pulse Radar Types 2 through 4. If more than 30 waveforms are used for Short Pulse Radar Types 2 through 4, then each additional waveform must also be unique and not repeated from the previous waveforms.

If more than 30 waveforms are used for Short Pulse Radar Type 1, then each additional waveform is generated with Test B and must also be unique and not repeated from the previous waveforms in Tests A or B.

The aggregate is the average of the percentage of successful detections of short pulse radar types

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Table 2-Long Pulse Radar Test Waveform

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| Radar Type | | Chirp Width (MHz) | | Number of Pulses per Burst | Number of Bursts | Minimum Percentage of Successful Detection | Minimum Trials |
|---------------|--------|-------------------------|-----------|----------------------------------|---------------------|--|-------------------|
| 5 | 50-100 | 5-20 | 1000-2000 | 1-3 | 8-20 | 80% | 30 |

Table 3-Frequency Hopping Radar Test Waveform

| Radar Type | Pulse Width (µsec) | PRI (µsec) | Pulses per Hop | Hopping Rate (kHz) | Hopping Sequence Length (msec) | Minimum Percentage of Successful Detection | Minimum Trials |
|---------------|--------------------------|---------------|-------------------|-----------------------|---|--|-------------------|
| 6 | 1 | 333 | 9 | 0.333 | 300 | 70% | 30 |

In-Service Monitoring: Channel Move Time, Channel Closing Transmission Time and Non-Occupancy Period

Limit of In-Service Monitoring:

Reference to DFS Radar Signal Parameter Values.

Test Procedures:

- a) One frequency will be chosen from the Operating Channels of the EUT within the 5250-5350 MHz or 5470-5725 MHz bands. For 802.11 devices, the test frequency must contain control signals. This can be verified by disabling channel loading and monitoring the spectrum analyzer. If no control signals are detected, another frequency must be selected within the emission bandwidth where control signals are detected.
- b) In case the EUT is a Master Device, a U-NII device operating as a Client Device will be used and it is assumed that the Client will associate with the EUT (Master). For radiated tests, the emissions of the Radar Waveform generator will be directed towards the Master Device. If the Master Device has antenna gain, the main beam of the antenna will be directed toward the radar emitter. Vertical polarization is used for testing.
- c) The TCP protocol unicast data stream was generated by the iperf software command line with at least 17% activity ratio over any 100ms period.
- d) Timing plots are reported with calculations demonstrating a minimum channel loading of approximately 17% or greater. For example, channel loading can be estimated by setting the spectrum analyzer for zero span and approximate the Time On/ (Time On + Off Time).
- e) At time T0 the Radar Waveform generator sends a Burst of pulses for one of the Short Pulse Radar Types 1-4 at DFS Detection Threshold levels on the Operating Channel. An additional 1 dB is added to the radar test signal to ensure it is at or above the DFS Detection Threshold, accounting for equipment variations/errors.
- f) Observe the transmissions of the EUT at the end of the radar Burst on the Operating Channel for duration greater than 10 seconds. Measure and record the transmissions from the EUT during the observation time (Channel Move Time). Measure and record the Channel Move Time and Channel Closing Transmission Time if radar detection occurs.
- g) When operating as a Master Device, monitor the EUT for more than 30 minutes following instant T2 to verify that the EUT does not resume any transmissions on this Channel. Perform this test once and record the measurement result.

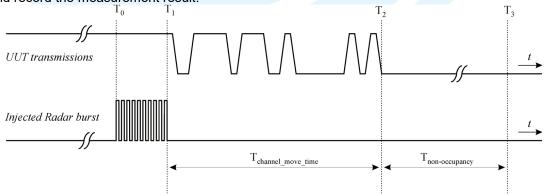
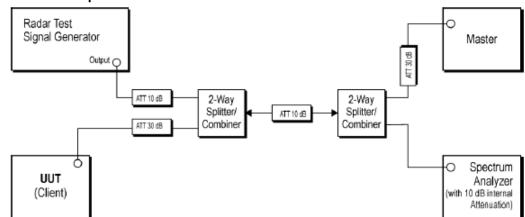


Figure 17: Channel Closing Transmission Time, Channel Move Time and Non-Occupancy Period

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Conducted test setup



Setup for Client with injection at the Master

Equipment Used: Refer to section 3 for details.

Test Result: Result of Channel Move Time, Channel Closing Transmission Time and

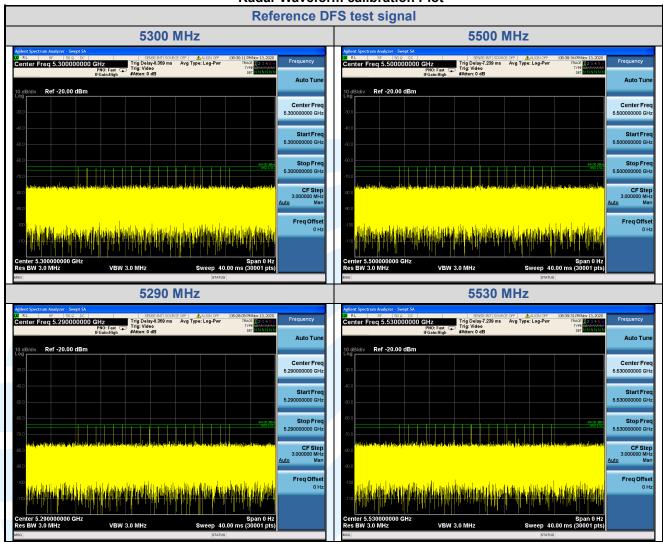
Non-Occupancy Period for Client Beacon Tes

The measurement data as follows:

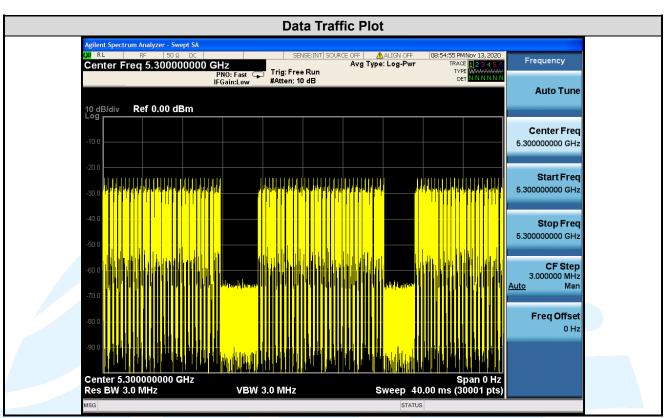
| BW / Channel | Test Item | Test Result | Limit | Pass/Fail |
|-------------------|--------------------------------------|-----------------|------------|-----------|
| | Channel Move Time | 0.52 s | < 10s | Pass |
| 20 MHz / 5300 MHz | Channel Closing Transmission Time | 2.8 ms | < 200+60ms | Pass |
| | Non-Occupancy Period | No transmission | 30 minutes | Pass |
| | Channel Move Time | 0.6058 s | < 10s | Pass |
| 20 MHz / 5500 MHz | Channel Closing Transmission Time | 2.8 ms | <200+60ms | Pass |
| | Non-Occupancy Period | No transmission | 30 minutes | Pass |
| | Channel Move Time | 0.6094 s | < 10s | Pass |
| 80 MHz / 5290 MHz | Channel Closing Transmission Time | 4.8 ms | < 200+60ms | Pass |
| | Non-Occupancy Period | No transmission | 30 minutes | Pass |
| | Channel Move Time | 0.5142 s | < 10s | Pass |
| 80 MHz / 5530 MHz | Channel Closing Transmission Time | 2.8 ms | < 200+60ms | Pass |
| | Non-Occupancy Period | No transmission | 30 minutes | Pass |

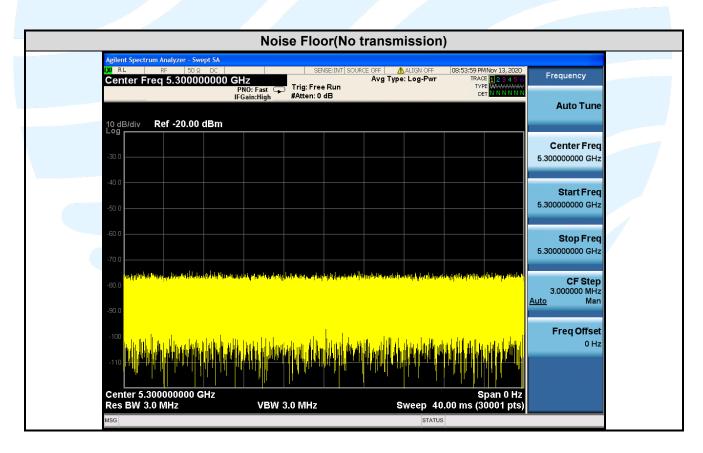


Radar Waveform calibration Plot

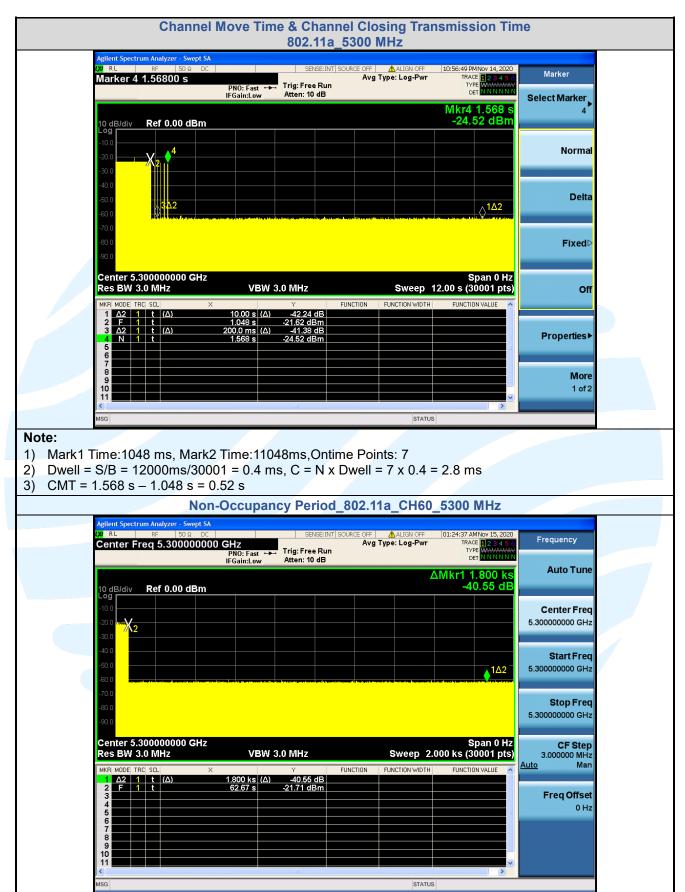




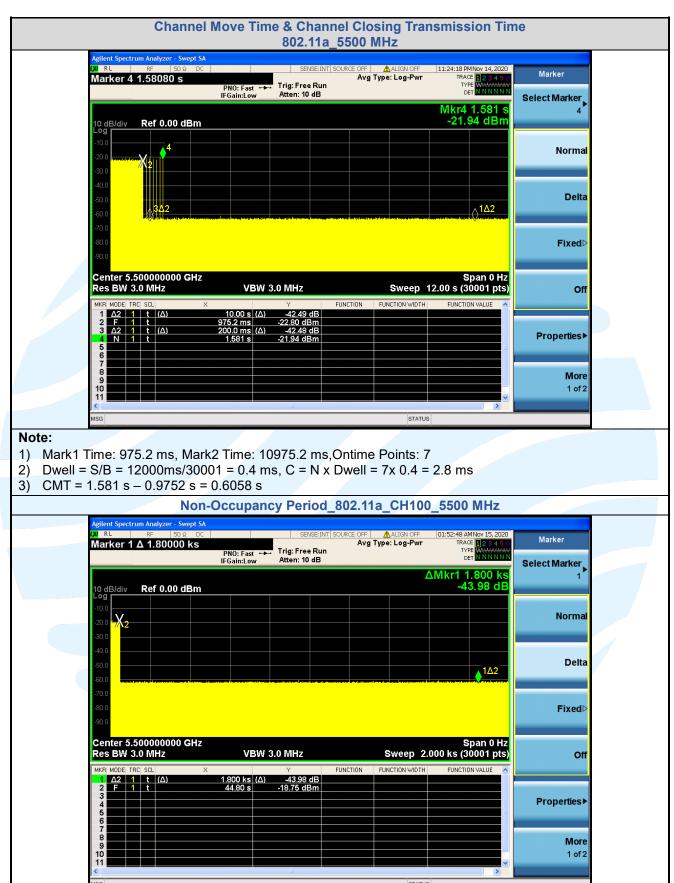




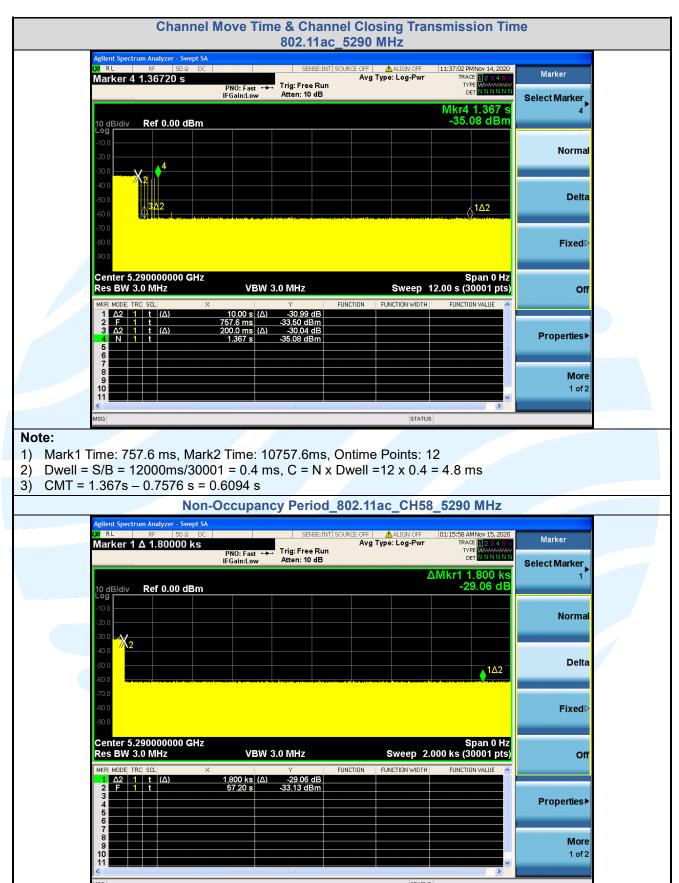




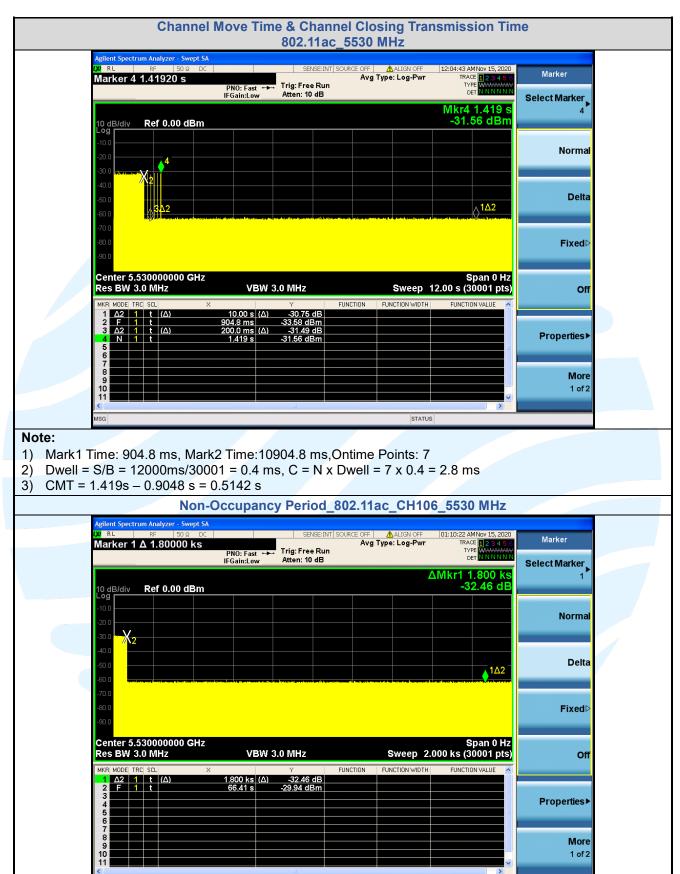












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5.9AC POWER LINE CONDUCTED EMISSION

FCC 47 CFR Part 15 Subpart E Section 15.407 (b)(6)

Test Requirement: FCC 47 CFR Part 15 Subpart C Section 15.207

RSS-Gen Issue 5, Section 8.8 ANSI C63.10-2013, Section 6.2.

Limits:

Test Method:

| Frequency range | Limits (dB(μV) | | | |
|-----------------|----------------|----------|--|--|
| (MHz) | Quasi-peak | Average | | |
| 0,15 to 0,50 | 66 to 56 | 56 to 46 | | |
| 0,50 to 5 | 56 | 46 | | |
| 5 to 30 | 60 | 50 | | |

Remark:

1. The lower limit shall apply at the transition frequencies.

The limit decreases linearly with the logarithm of the frequency in the range 0.15 to 0.50 MHz.

Test Setup: Refer to section 4.5.2 for details.

Test Procedures:

Test frequency range: 150KHz-30MHz

1) The mains terminal disturbance voltage test was conducted in a shielded room.

- 2) The EUT was connected to AC power source through a LISN 1 (Line Impedance Stabilization Network) which provides a 50Ω/50μH + 5Ω linear impedance. The power cables of all other units of the EUT were connected to a second LISN 2, which was bonded to the ground reference plane in the same way as the LISN 1 for the unit being measured. A multiple socket outlet strip was used to connect multiple power cables to a single LISN provided the rating of the LISN was not exceeded.
- 3) The tabletop EUT was placed upon a non-metallic table 0.8m above the ground reference plane. And for floor-standing arrangement, the EUT was placed on the horizontal ground reference plane,
- 4) The test was performed with a vertical ground reference plane. The rear of the EUT shall be 0.4 m from the vertical ground reference plane. The vertical ground reference plane was bonded to the horizontal ground reference plane. The LISN 1 was placed 0.8 m from the boundary of the unit under test and bonded to a ground reference plane for LISNs mounted on top of the ground reference plane. This distance was between the closest points of the LISN 1 and the EUT. All other units of the EUT and associated equipment was at least 0.8 m from the LISN 2.
- 5) In order to find the maximum emission, the relative positions of equipment and all of the interface cables must be changed according to ANSI C63.10 on conducted measurement.

Equipment Used: Refer to section 3 for details.

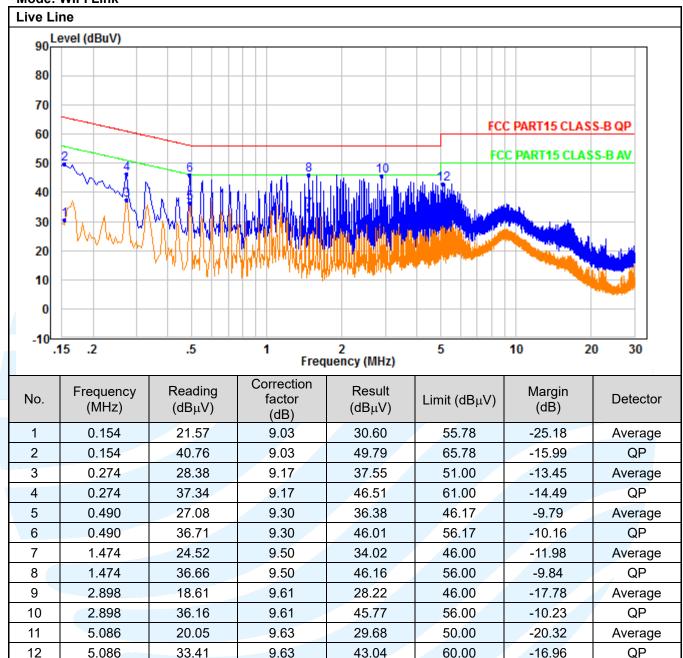
Test Result: Pass



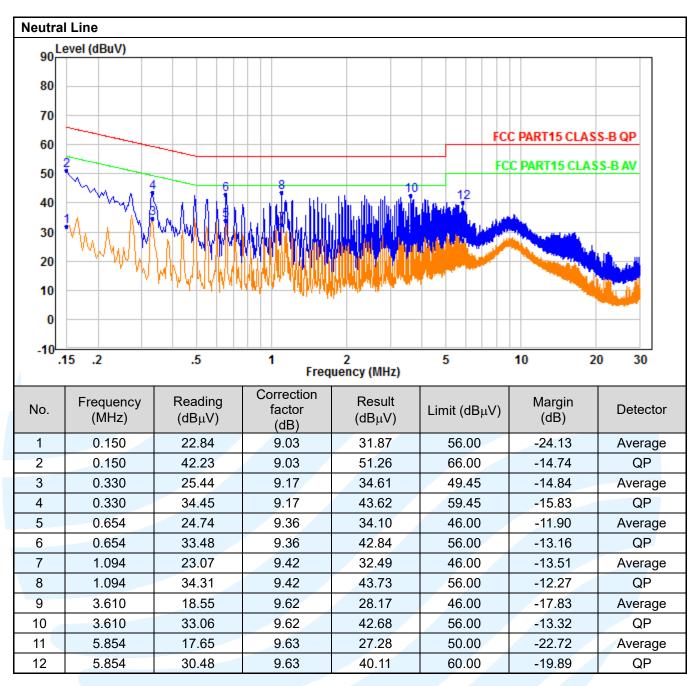
The measurement data as follows:

Quasi Peak and Average:

Mode: WIFI Link







Remark:

- 1. Correct Factor = LISN Factor + Cable Loss + Pulse Limiter Factor, the value was added to Original Receiver Reading by the software automatically.
- 2. Result = Reading + Correct Factor.
- 3. Margin = Result Limit
- 4. An initial pre-scan was performed on the Phase and neutral lines with peak detector. Quasi-Peak and Average measurement were performed at the frequencies with maximized peak emission were detected.
- 5. All possible modes of operation were investigated, and testing at two nominal voltages of 240V/50Hz and 120V/60Hz, only the worst case emissions reported.

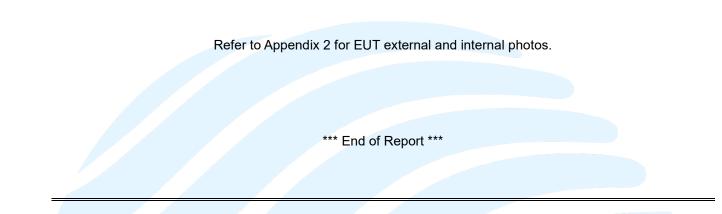


APPENDIX 1 PHOTOS OF TEST SETUP

See test photos attached in Appendix 1 for the actual connections between Product and support equipment.

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APPENDIX 2 PHOTOS OF EUT CONSTRUCTIONAL DETAILS



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