



# Certificate of Conformity

**APPLICANT** : Via One Networks, LLC  
**EQUIPMENT** : GSM Dual Band GPRS Function  
Digital Mobile Telephone  
**BRAND NAME** : WP  
**MODEL NAME** : WP8

THE EQUIPMENT WAS **PASSED** THE TEST PERFORMED ACCORDING TO

**EN 50360:2001**

**EN 62311:2008**

**EN 62209-1:2006**

**IEC 62209-2:2008**

**IC RSS-102 Issue 3 (2009)**

**FCC 47 CFR Part 2 (2.1093)**

**IEEE C95.1-1999**

**IEEE 1528-2003**

**FCC OET Bulletin 65 Supplement C (Edition 01-01)**

THE TEST WAS CARRIED OUT ON Sep. 09, 2009 AT **SPORTON INTERNATIONAL INC. LAB.**

A handwritten signature in blue ink that reads 'Roy Wu'. The signature is written in a cursive style and is positioned above a horizontal line.

**Roy Wu / Manager**

**SPORTON INTERNATIONAL INC.**

**No. 52, Hwa Ya 1<sup>st</sup> Rd., Hwa Ya Technology Park, Kwei-Shan Hsiang, Tao Yuan Hsien, Taiwan, R.O.C.**


# FCC SAR Test Report

**APPLICANT** : Via One Networks, LLC  
**EQUIPMENT** : GSM Dual Band GPRS Function Digital Mobile Telephone  
**BRAND NAME** : WP  
**MODEL NAME** : WP8  
**STANDARD** : IC RSS-102 Issue 3 (2009)  
FCC 47 CFR Part 2 (2.1093)  
IEEE C95.1-1999  
IEEE 1528-2003  
FCC OET Bulletin 65 Supplement C (Edition 01-01)

The product was received on Sep. 04, 2009 and completely tested on Sep. 09, 2009. We, SPORTON INTERNATIONAL INC., would like to declare that the tested sample has been evaluated in accordance with the procedures and shown the compliance with the applicable technical standards.

The test results in this report apply exclusively to the tested model / sample. Without written approval of SPORTON INTERNATIONAL INC., the test report shall not be reproduced except in full.

Reviewed by:



Roy Wu / Manager



**SPORTON INTERNATIONAL INC.**

No. 52, Hwa Ya 1<sup>st</sup> Rd., Hwa Ya Technology Park, Kwei-Shan Hsiang, Tao Yuan Hsien, Taiwan, R.O.C.



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### Revision History

REPORT NO.	VERSION	DESCRIPTION	ISSUED DATE
FA990421	Rev. 01	Initial issue of report	Sep. 11, 2009



### 1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) were found during testing for **Via One Networks, LLC GSM Dual Band GPRS Function Digital Mobile Telephone WP WP8**, which are as follows (with expanded uncertainty 21.8 % for 300 MHz to 3 GHz).

Band	Position	SAR <sub>1g</sub> (W/kg)
GSM1900	Head	0.61
	Body	1.26

They are in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6 W/kg) specified in IC RSS-102 Issue 3 (2009), FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1999, and had been tested in accordance with the measurement methods and procedures specified in IEEE 1528-2003 and FCC OET Bulletin 65 Supplement C (Edition 01-01).



## 2. Administration Data

### 2.1 Testing Laboratory

Test Site	SPORTON INTERNATIONAL INC.
Test Site Location	No. 52, Hwa Ya 1 <sup>st</sup> Rd., Hwa Ya Technology Park, Kwei-Shan Hsiang, Tao Yuan Hsien, Taiwan, R.O.C. TEL: +886-3-327-3456 FAX: +886-3-328-4978
Test Site No.	<b>Sporton Site No. :</b> SAR02-HY

### 2.2 Applicant

Company Name	Via One Networks, LLC
Address	525 Broadway, 5th Fl, New York, NY 10012

### 2.3 Manufacturer

Company Name	CK TELECOM LTD.
Address	Technology Road, High-Tech Development Zone, Heyuan, Guangdong, P.R. China

### 2.4 Application Details

Date of Receipt of Application	Sep. 04, 2009
Date of Start during the Test	Sep. 09, 2009
Date of End during the Test	Sep. 09, 2009

### 3. General Information

#### 3.1 Description of Device Under Test (DUT)

Product Feature & Specification	
DUT Type	GSM Dual Band GPRS Function Digital Mobile Telephone
Brand Name	WP
Model Name	WP8
Tx Frequency	1850 MHz ~ 1910 MHz
Rx Frequency	1930 MHz ~ 1990 MHz
Maximum Output Power to Antenna	28.64 dBm
Antenna Type	Fixed Internal Antenna
HW Version	CAT_V3.0
SW Version	CAT_WP_L4EN_203_090902_LY3_SIV100AB_SA75_CTF_FM_BT_LCD18
Type of Modulation	GMSK
DUT Stage	Identical Prototype

List of Accessory:

Specification of Accessory		
AC Adapter	Brand Name	WP
	Model Name	CHG5065-3C
	Power Rating	I/P:90-240Vac, 50-60Hz, 0.1A; O/P: 5.0Vdc, 650mA
Battery	Brand Name	WP
	Model Name	Cat383450
	Power Rating	3.7Vdc, 650mAh
LCD Panel	Type	Li-ion
	Brand Name	TRULY
	Model Name	TFT-GG1P4104UTSW-W-E

**Remark:** The above DUT's information was declared by manufacturer. Please refer to the specifications or user's manual for more detailed description.

#### 3.2 Product Photos

Please refer to Appendix D.



### 3.3 Applied Standards

The Specific Absorption Rate (SAR) testing specification, method and procedure for this GSM Dual Band GPRS Function Digital Mobile Telephone is in accordance with the following standards:

- IC RSS-102 Issue 3 (2009)
- FCC 47 CFR Part 2 (2.1093)
- IEEE C95.1-1999
- IEEE 1528-2003
- FCC OET Bulletin 65 Supplement C (Edition 01-01)
- FCC KDB 648474 D01 v01r05
- FCC KDB 941225 D03 v01

### 3.4 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

### 3.5 Test Conditions

#### 3.5.1 Ambient Condition

Ambient Temperature	20 to 24 °C
Humidity	< 60 %

#### 3.5.2 Test Configuration

The device was controlled by using a base station emulator. Communication between the device and the emulator was established by air link. The distance between the DUT and the antenna of the emulator is larger than 50 cm and the output power radiated from the emulator antenna is at least 30 dB smaller than the output power of DUT. The DUT was set from the emulator to radiate maximum output power during all tests.

For WWAN SAR testing, the DUT is in GSM or GPRS link mode.

In general, the crest factor is 8.3 for GSM and GPRS multi-slot class 8, 4 for GPRS multi-slot class 10, and 2 for GPRS multi-slot class 12.





In GPRS link mode, the DUT was set in GPRS multi-slot class 12 with 4 uplink slots due to maximum source-based time-averaged output power as following table:

Source-Based Time-Averaged Power			
Band	GSM1900		
Channel	512	661	810
GPRS 8	19.64	19.59	19.51
GPRS 10	22.59	22.56	22.48
GPRS 12	<b>25.52</b>	25.47	25.37

**Note:**

The source-based time-averaged power is linearly scaled the maximum burst averaged power based on time slots. The calculated method are shown as below:

Source based time averaged power = Maximum burst averaged power (1 slot) - 9 dB

Source based time averaged power = Maximum burst averaged power (2 slots) - 6 dB

Source based time averaged power = Maximum burst averaged power (4 slots) - 3 dB

The maximum burst averaged power can be referred to section 11.1 of this report.

## 4. Specific Absorption Rate (SAR)

### 4.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

### 4.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density ( $\rho$ ). The equation description is as below:

$$\text{SAR} = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$\text{SAR} = c \left( \frac{\delta T}{\delta t} \right)$$

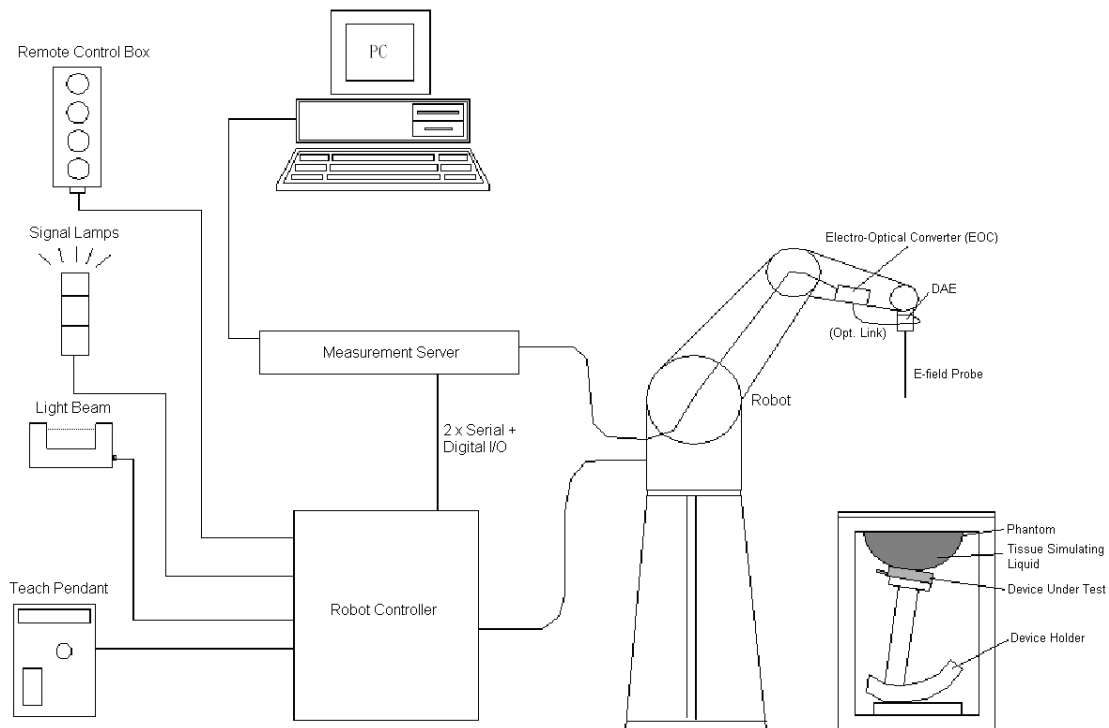
Where: C is the specific heat capacity,  $\delta T$  is the temperature rise and  $\delta t$  is the exposure duration, or related to the electrical field in the tissue by

$$\text{SAR} = \frac{\sigma |E|^2}{\rho}$$

Where:  $\sigma$  is the conductivity of the tissue,  $\rho$  is the mass density of the tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

## 5. SAR Measurement System



**Fig 5.1 SPEAG DASY4 or DASY5 System Configurations**

The DASY4 or DASY5 system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (ECO) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY4 or DASY5 software
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system

Some of the components are described in details in the following sub-sections.

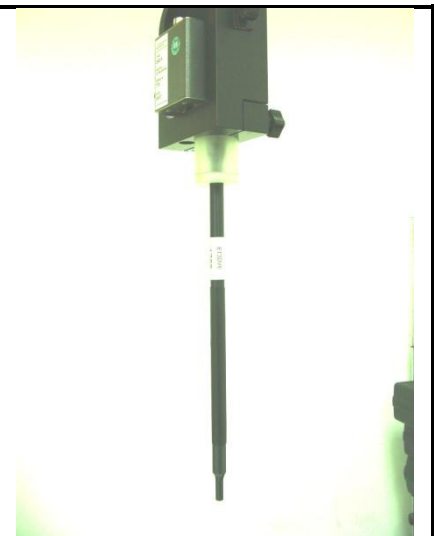
**5.1 E-Field Probe**

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG).The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

**5.1.1 E-Field Probe Specification**

**<ET3DV6>**

<b>Construction</b>	Symmetrical design with triangular core Built-in optical fiber for surface detection system. Built-in shielding against static charges. PEEK enclosure material (resistant to organic solvents, e.g., DGBE)
<b>Frequency</b>	10 MHz to 3 GHz; Linearity: $\pm 0.2$ dB
<b>Directivity</b>	$\pm 0.2$ dB in HSL (rotation around probe axis) $\pm 0.4$ dB in HSL (rotation normal to probe axis)
<b>Dynamic Range</b>	5 $\mu$ W/g to 100 mW/g; Linearity: $\pm 0.2$ dB
<b>Dimensions</b>	Overall length: 330 mm (Tip: 16 mm) Tip diameter: 6.8 mm (Body: 12 mm) Distance from probe tip to dipole centers: 2.7 mm



**Fig 5.2 Photo of ET3DV6**

**<EX3DV3 Probe>**

<b>Construction</b>	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)
<b>Frequency</b>	10 MHz to 6 GHz; Linearity: $\pm 0.2$ dB
<b>Directivity</b>	$\pm 0.3$ dB in HSL (rotation around probe axis) $\pm 0.5$ dB in tissue material (rotation normal to probe axis)
<b>Dynamic Range</b>	10 $\mu$ W/g to 100 mW/g; Linearity: $\pm 0.2$ dB (noise: typically $< 1$ $\mu$ W/g)
<b>Dimensions</b>	Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm



**Fig 5.3 Photo of EX3DV3**

**5.1.2 E-Field Probe Calibration**

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than  $\pm 10\%$ . The spherical isotropy shall be evaluated and within  $\pm 0.25$  dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

**5.2 Data Acquisition Electronics (DAE)**

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



**Fig 5.4 Photo of DAE**

**5.3 Robot**

The SPEAG DASY system uses the high precision robots (DASY4: RX90BL; DASY5: TX90XL) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version (DASY4: CS7MB; DASY5: CS8c) from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability  $\pm 0.035$  mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)



**Fig 5.5 Photo of DASY4**



**Fig 5.6 Photo of DASY5**

### **5.4 Measurement Server**

The measurement server is based on a PC/104 CPU board with CPU (DASY4: 166 MHz, Intel Pentium; DASY5: 400 MHz, Intel Celeron), chipdisk (DASY4: 32 MB; DASY5: 128 MB), RAM (DASY4: 64 MB, DASY5: 128 MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.




Fig 5.7 Photo of Server for DASY4



Fig 5.8 Photo of Server for DASY5


**5.5 Phantom**

**<SAM Twin Phantom>**

<b>Shell Thickness</b>	2 ± 0.2 mm; Center ear point: 6 ± 0.2 mm	 <p><b>Fig 5.9 Photo of SAM Phantom</b></p>
<b>Filling Volume</b>	Approx. 25 liters	
<b>Dimensions</b>	Length: 1000 mm; Width: 500 mm; Height: adjustable feet	
<b>Measurement Areas</b>	Left Hand, Right Hand, Flat Phantom	

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

**<ELI4 Phantom>**

<b>Shell Thickness</b>	2 ± 0.2 mm (sagging: <1%)	 <p><b>Fig 5.10 Photo of ELI4 Phantom</b></p>
<b>Filling Volume</b>	Approx. 30 liters	
<b>Dimensions</b>	Major ellipse axis: 600 mm Minor axis: 400 mm	

The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.

## 5.6 Device Holder

### <Device Holder for SAM Twin Phantom>

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of  $\pm 0.5$  mm would produce a SAR uncertainty of  $\pm 20$  %. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity  $\epsilon = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

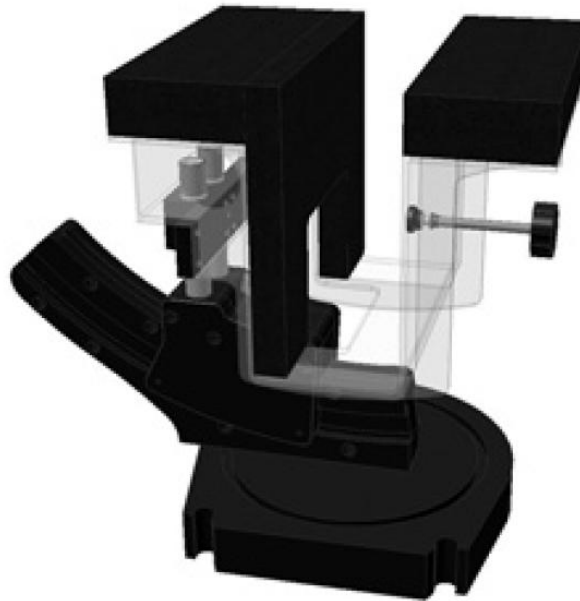


Fig 5.11 Device Holder



**<Laptop Extension Kit>**

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the mounting device in place of the phone positioned. The extension is fully compatible with the SAM Twin and ELI phantoms.



**Fig 5.12**      **Laptop Extension Kit**



## 5.7 Data Storage and Evaluation

### 5.7.1 Data Storage

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

### 5.7.2 Data Evaluation

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software :

<b>Probe parameters :</b>	- Sensitivity	Norm <sub>i</sub> , a <sub>10</sub> , a <sub>11</sub> , a <sub>12</sub>
	- Conversion factor	ConvF <sub>i</sub>
	- Diode compression point	dcp <sub>i</sub>
<b>Device parameters :</b>	- Frequency	f
	- Crest factor	cf
<b>Media parameters :</b>	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.

The formula for each channel can be given as :

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with  $V_i$  = compensated signal of channel i, (i = x, y, z)  
 $U_i$  = input signal of channel i, (i = x, y, z)  
 cf = crest factor of exciting field (DASY parameter)  
 dcp<sub>i</sub> = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated :

$$\text{E-field Probes : } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$\text{H-field Probes : } H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

with  $V_i$  = compensated signal of channel i, (i = x, y, z)  
 Norm<sub>i</sub> = sensor sensitivity of channel i, (i = x, y, z),  $\mu\text{V}/(\text{V/m})^2$  for E-field Probes  
 ConvF = sensitivity enhancement in solution  
 a<sub>ij</sub> = sensor sensitivity factors for H-field probes  
 f = carrier frequency [GHz]  
 $E_i$  = electric field strength of channel i in V/m  
 $H_i$  = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$E_{\text{tot}} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$\text{SAR} = E_{\text{tot}}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g  
 $E_{\text{tot}}$  = total field strength in V/m  
 $\sigma$  = conductivity in [mho/m] or [Siemens/m]  
 $\rho$  = equivalent tissue density in  $\text{g/cm}^3$

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.



**5.8 Test Equipment List**

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	Dosimetric E-Filed Probe	ET3DV6	1787	May 26, 2009	May 25, 2010
SPEAG	Dosimetric E-Filed Probe	ET3DV6	1788	Sep. 23, 2008	Sep. 22, 2009
SPEAG	Dosimetric E-Filed Probe	EX3DV3	3514	Jan. 21, 2009	Jan. 20, 2010
SPEAG	835MHz System Validation Kit	D835V2	499	Mar. 17, 2008	Mar. 16, 2010
SPEAG	900MHz System Validation Kit	D900V2	190	Jul. 21, 2009	Jul. 20, 2011
SPEAG	1800MHz System Validation Kit	D1800V2	2d076	Jul. 20, 2009	Jul. 19, 2011
SPEAG	1900MHz System Validation Kit	D1900V2	5d041	Mar. 28, 2008	Mar. 27, 2010
SPEAG	2000MHz System Validation Kit	D2000V2	1010	Sep. 17, 2008	Sep. 16, 2010
SPEAG	2300MHz System Validation Kit	D2300V2	1004	Feb. 17, 2009	Feb. 16, 2011
SPEAG	2450MHz System Validation Kit	D2450V2	736	Jul. 20, 2009	Jul. 19, 2011
SPEAG	2600MHz System Validation Kit	D2600V2	1003	Feb. 17, 2009	Feb. 16, 2011
SPEAG	3500MHz System Validation Kit	D3500V2	1007	Feb. 06, 2009	Feb. 05, 2011
SPEAG	5GHz System Validation Kit	D5GHzV2	1006	Jan. 24, 2008	Jan. 23, 2010
SPEAG	Data Acquisition Electronics	DAE3	577	Aug. 24, 2009	Aug. 23, 2010
SPEAG	Data Acquisition Electronics	DAE4	778	Sep. 22, 2008	Sep. 21, 2009
SPEAG	Data Acquisition Electronics	DAE4	679	Jun. 23, 2009	Jun. 22, 2010
SPEAG	Device Holder	N/A	N/A	NCR	NCR
SPEAG	SAM Phantom	QD 000 P40 C	TP-1303	NCR	NCR
SPEAG	SAM Phantom	QD 000 P40 C	TP-1383	NCR	NCR
SPEAG	SAM Phantom	QD 000 P40 C	TP-1446	NCR	NCR
SPEAG	SAM Phantom	QD 000 P40 C	TP-1477	NCR	NCR
SPEAG	ELI4 Phantom	QD 0VA 001 BB	1026	NCR	NCR
SPEAG	ELI4 Phantom	QD 0VA 001 BA	1029	NCR	NCR
Agilent	PNA Series Network Analyzer	E8358A	US40260131	Apr. 17, 2009	Apr. 16, 2010
Agilent	Wireless Communication Test Set	E5515C	MY48360820	Dec. 15, 2008	Dec. 14, 2009
R&S	Universal Radio Communication Tester	CMU200	105934	Nov. 11, 2008	Nov. 10, 2009
Agilent	Dielectric Probe Kit	85070D	US01440205	NCR	NCR
Agilent	Dual Directional Coupler	778D	50422	NCR	NCR
AR	Power Amplifier	5S1G4M2	0328767	NCR	NCR
R&S	Power Meter	NRVD	101394	Oct. 20, 2008	Oct. 19, 2009
R&S	Power Sensor	NRV-Z1	100130	Oct. 20, 2008	Oct. 19, 2009
R&S	Spectrum Analyzer	FSP7	101131	Mar. 12, 2009	Mar. 11, 2010

**Table 5.1 Test Equipment List**

**Note:** The calibration certificate of DASY can be referred to appendix C of this report.

## 6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.2.

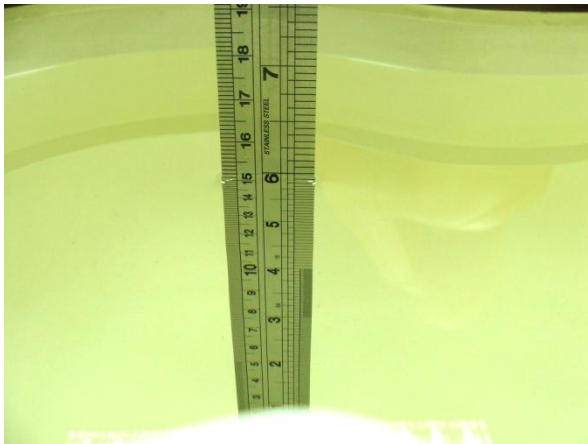


Fig 6.1 Photo of Liquid Height for Head SAR



Fig 6.2 Photo of Liquid Height for Body SAR

The following table gives the recipes for tissue simulating liquid.

Frequency (MHz)	Water (%)	Sugar (%)	Cellulose (%)	Salt (%)	Preventol (%)	DGBE (%)	Conductivity ( $\sigma$ )	Permittivity ( $\epsilon_r$ )
<b>For Head</b>								
835	40.3	57.9	0.2	1.4	0.2	0	0.90	41.5
900	40.3	57.9	0.2	1.4	0.2	0	0.97	41.5
1800, 1900, 2000	55.2	0	0	0.3	0	44.5	1.40	40.0
2450	55.0	0	0	0	0	45.0	1.80	39.2
<b>For Body</b>								
835	50.8	48.2	0	0.9	0.1	0	0.97	55.2
900	50.8	48.2	0	0.9	0.1	0	1.05	55.0
1800, 1900, 2000	70.2	0	0	0.4	0	29.4	1.52	53.3
2450	68.6	0	0	0	0	31.4	1.95	52.7

Table 6.1 Recipes of Tissue Simulating Liquid

The following table gives the targets for tissue simulating liquid.

Frequency (MHz)	Liquid Type	Conductivity ( $\sigma$ )	$\pm 5\%$ Range	Permittivity ( $\epsilon_r$ )	$\pm 5\%$ Range
835	Head	0.90	0.86 ~ 0.95	41.5	39.4 ~ 43.6
900	Head	0.97	0.92 ~ 1.02	41.5	39.4 ~ 43.6
1800, 1900, 2000	Head	1.40	1.33 ~ 1.47	40.0	38.0 ~ 42.0
2450	Head	1.80	1.71 ~ 1.89	39.2	37.2 ~ 41.2
835	Body	0.97	0.92 ~ 1.02	55.2	52.4 ~ 58.0
900	Body	1.05	1.00 ~ 1.10	55.0	52.3 ~ 57.8
1800, 1900, 2000	Body	1.52	1.44 ~ 1.60	53.3	50.6 ~ 56.0
2450	Body	1.95	1.85 ~ 2.05	52.7	50.1 ~ 55.3

**Table 6.2 Targets of Tissue Simulating Liquid**

The dielectric parameters of the liquids were verified prior to the SAR evaluation using an Agilent 85070D Dielectric Probe Kit and an Agilent Network Analyzer.

The following table shows the measuring results for simulating liquid.

Frequency (MHz)	Liquid Type	Temperature ( $^{\circ}\text{C}$ )	Conductivity ( $\sigma$ )	Permittivity ( $\epsilon_r$ )	Measurement Date
1900	Head	21.5	1.43	38.9	Sep. 09, 2009
1900	Body	21.3	1.55	52.2	Sep. 09, 2009

**Table 6.3 Measuring Results for Simulating Liquid**

## **7. Uncertainty Assessment**

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and knowledge of the behavior and properties of relevant materials and instruments, manufacture’s specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 7.1

<b>Uncertainty Distributions</b>	<b>Normal</b>	<b>Rectangular</b>	<b>Triangular</b>	<b>U-Shape</b>
Multi-plying Factor <sup>(a)</sup>	1/k <sup>(b)</sup>	1/√3	1/√6	1/√2

- (a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
- (b)  $\kappa$  is the coverage factor

**Table 7.1 Standard Uncertainty for Assumed Distribution**

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual “root-sum-squares” (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is showed in Table 7.2.



Error Description	Uncertainty Value (±%)	Probability Distribution	Divisor	Ci (1g)	Standard Uncertainty (1g)
<b>Measurement System</b>					
Probe Calibration	5.9	Normal	1	1	± 5.9 %
Axial Isotropy	4.7	Rectangular	√3	0.7	± 1.9 %
Hemispherical Isotropy	9.6	Rectangular	√3	0.7	± 3.9 %
Boundary Effects	1.0	Rectangular	√3	1	± 0.6 %
Linearity	4.7	Rectangular	√3	1	± 2.7 %
System Detection Limits	1.0	Rectangular	√3	1	± 0.6 %
Readout Electronics	0.3	Normal	1	1	± 0.3 %
Response Time	0.8	Rectangular	√3	1	± 0.5 %
Integration Time	2.6	Rectangular	√3	1	± 1.5 %
RF Ambient Noise	3.0	Rectangular	√3	1	± 1.7 %
RF Ambient Reflections	3.0	Rectangular	√3	1	± 1.7 %
Probe Positioner	0.4	Rectangular	√3	1	± 0.2 %
Probe Positioning	2.9	Rectangular	√3	1	± 1.7 %
Max. SAR Eval.	1.0	Rectangular	√3	1	± 0.6 %
<b>Test Sample Related</b>					
Device Positioning	2.9	Normal	1	1	± 2.9 %
Device Holder	3.6	Normal	1	1	± 3.6 %
Power Drift	5.0	Rectangular	√3	1	± 2.9 %
<b>Phantom and Setup</b>					
Phantom Uncertainty	4.0	Rectangular	√3	1	± 2.3 %
Liquid Conductivity (Target)	5.0	Rectangular	√3	0.64	± 1.8 %
Liquid Conductivity (Meas.)	2.5	Normal	1	0.64	± 1.6 %
Liquid Permittivity (Target)	5.0	Rectangular	√3	0.6	± 1.7 %
Liquid Permittivity (Meas.)	2.5	Normal	1	0.6	± 1.5 %
<b>Combined Standard Uncertainty</b>					± 10.9 %
<b>Coverage Factor for 95 %</b>					K = 2
<b>Expanded Uncertainty</b>					± 21.8 %

Table 7.2 Uncertainty Budget of DASY for frequency range 300 MHz to 3 GHz



## 8. SAR Measurement Evaluation

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

### 8.1 Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

### 8.2 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

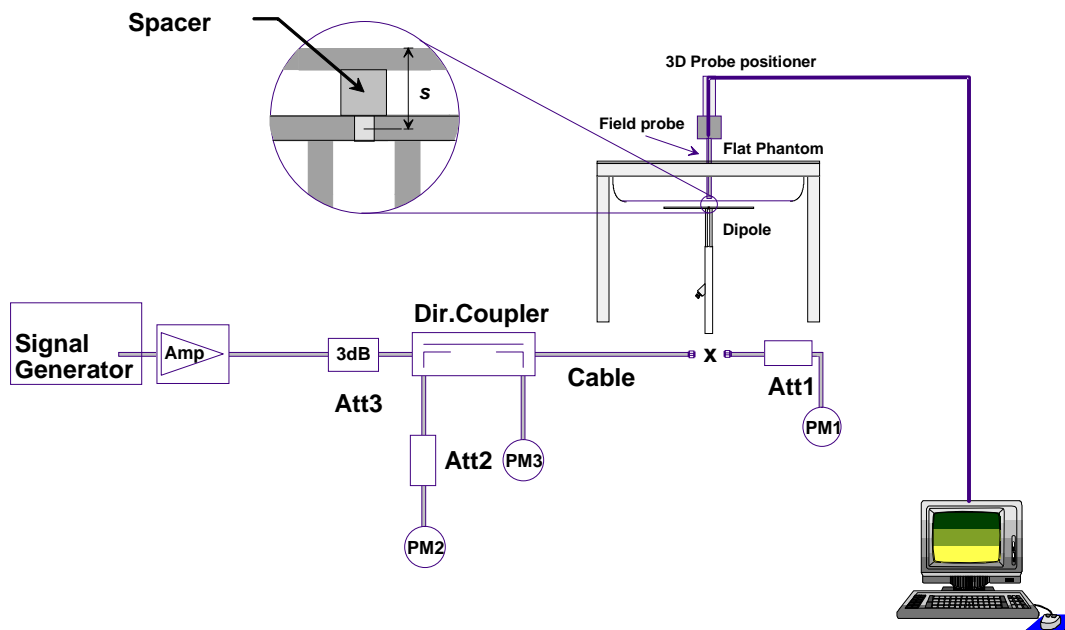
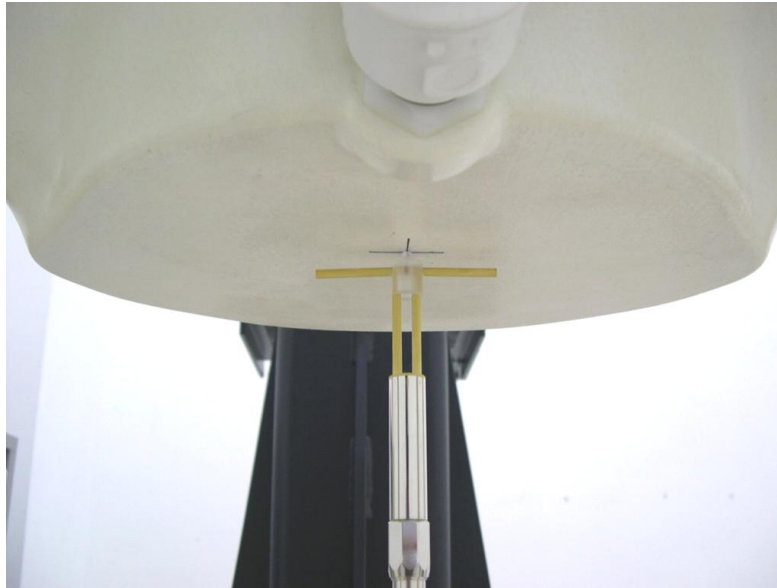


Fig 8.1 System Setup for System Evaluation

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. Calibrated Dipole

The output power on dipole port must be calibrated to 20 dBm (100 mW) before dipole is connected.



**Fig 8.2 Photo of Dipole Setup**

**8.3 Validation Results**

Comparing to the original SAR value provided by SPEAG, the validation data should be within its specification of 10 %. Table 8.1 shows the target SAR and measured SAR after normalized to 1W input power. The table below indicates the system performance check can meet the variation criterion and the plots can be referred to appendix A of this report.

Measurement Date	Frequency (MHz)	Targeted SAR <sub>1g</sub> (W/kg)	Measured SAR <sub>1g</sub> (W/kg)	Deviation (%)
Sep. 09, 2009	1900	40.10	40.60	1.25

**Table 8.1 Target and Measurement SAR after Normalized**

## 9. DUT Testing Position

This DUT was tested in six different positions. They are right cheek, right tilted, left cheek, left tilted, face of the DUT with phantom 1.5 cm gap, and bottom of the DUT with phantom 1.5 cm gap as illustrated below:

### 1. Define two imaginary lines on the handset

- (a) The vertical centerline passes through two points on the front side of the handset - the midpoint of the width  $w_t$  of the handset at the level of the acoustic output, and the midpoint of the width  $w_b$  of the bottom of the handset.
- (b) The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output. The horizontal line is also tangential to the face of the handset at point A.
- (c) The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output; however, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset, especially for clamshell handsets, handsets with flip covers, and other irregularly shaped handsets.

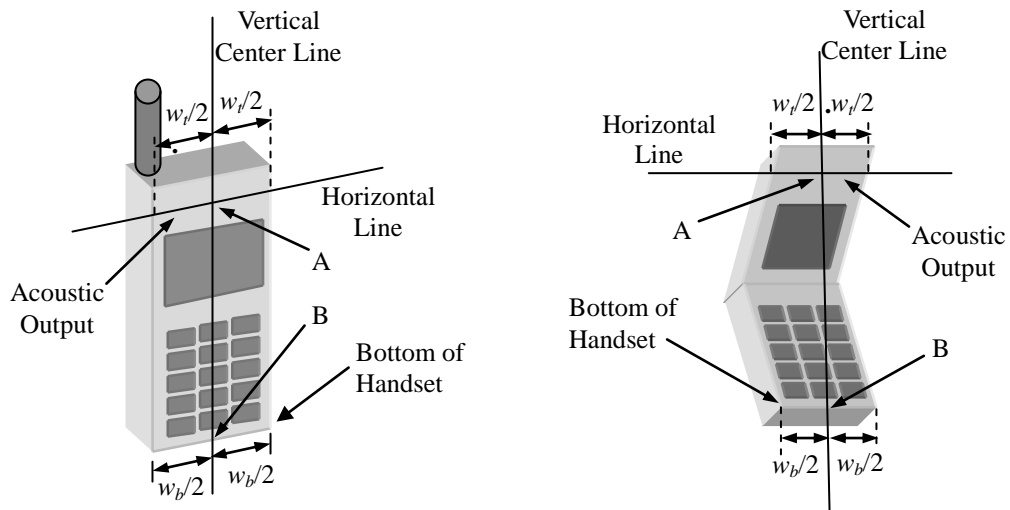
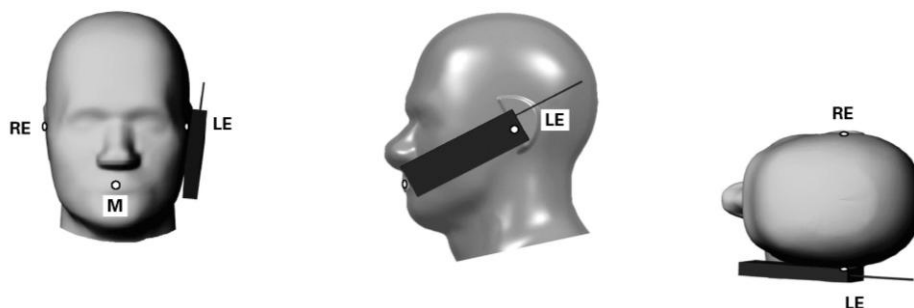


Fig 9.1 Illustration for Handset Vertical and Horizontal Reference Lines

**2. Cheek Position**

- (a) To position the device with the vertical center line of the body of the device and the horizontal line crossing the center piece in a plane parallel to the sagittal plane of the phantom. While maintaining the device in this plane, align the vertical center line with the reference plane containing the three ear and mouth reference point (M: Mouth, RE: Right Ear, and LE: Left Ear) and align the center of the ear piece with the line RE-LE.
- (b) To move the device towards the phantom with the ear piece aligned with the line LE-RE until the phone touched the ear. While maintaining the device in the reference plane and maintaining the phone contact with the ear, move the bottom of the phone until any point on the front side is in contact with the cheek of the phantom or until contact with the ear is lost (see Fig. 9.2).



**Fig 9.2 Illustration for Cheek Position**

**3. Tilted Position**

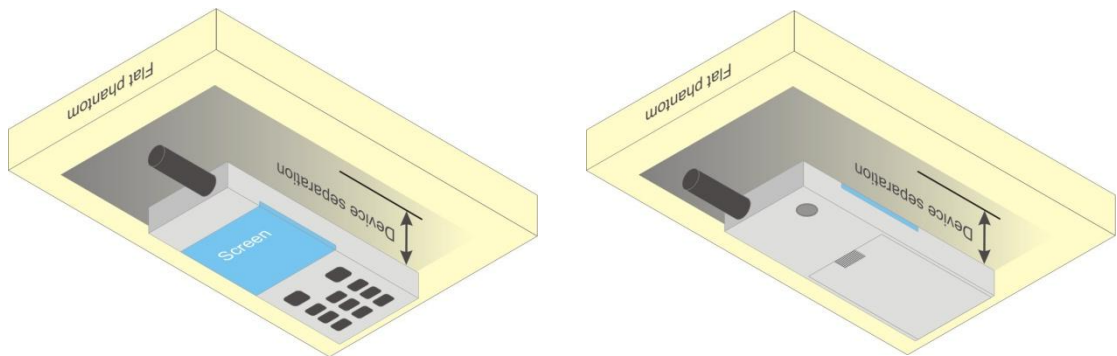
- (a) To position the device in the “cheek” position described above.
- (b) While maintaining the device the reference plane described above and pivoting against the ear, moves it outward away from the mouth by an angle of 15 degrees or until contact with the ear is lost (see Fig. 9.3).



**Fig 9.3 Illustration for Tilted Position**

#### 4. Body Worn Position

- (a) To position the device parallel to the phantom surface with either keypad up or down.
- (b) To adjust the device parallel to the flat phantom.
- (c) To adjust the distance between the device surface and the flat phantom to 1.5 cm.



**Fig 9.4 Illustration for Body Worn Position**

#### 5. DUT Setup Photos

Please refer to Appendix E for the test setup photos.

## **10. Measurement Procedures**

The measurement procedures are as follows:

- (a) For WWAN function, link DUT with base station emulator in middle channel
- (b) Set base station emulator to allow DUT to radiate maximum output power
- (c) Measure output power through RF cable and power meter
- (d) Place the DUT in the positions described in the last section
- (e) Set scan area, grid size and other setting on the DASY software
- (f) Taking data for the middle channel on each testing position
- (g) Find out the largest SAR result on these testing positions of each band
- (h) Measure SAR results for the lowest and highest channels in worst SAR testing position

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

### **10.1 Spatial Peak SAR Evaluation**

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g



## **10.2 Scan Procedures**

First Area Scan is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an Area Scan is defined by the grid extent, grid step size and grid offset. Next, in order to determine the EM field distribution in a three-dimensional spatial extension, Zoom Scan is required. The Zoom Scan measures 5x5x7 points with step size 8, 8 and 5 mm for 300 MHz to 3 GHz. The Zoom Scan is performed around the highest E-field value to determine the averaged SAR-distribution over 10 g.

## **10.3 SAR Averaged Methods**

In DASy, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

## 11. SAR Test Results

### 11.1 Conducted Power (Unit: dBm)

Band	GSM1900		
Channel	512	661	810
Frequency (MHz)	1850.2	1880.0	1909.8
GSM	28.62	28.57	28.49
GPRS 8	28.64	28.59	28.51
GPRS 10	28.59	28.56	28.48
GPRS 12	28.52	28.47	28.37

### 11.2 Test Records for Head SAR Test

Plot No.	Band	Mode	Test Position	Channel	SAR <sub>1g</sub> (W/kg)
#05	GSM1900	GSM	Right Cheek	661	0.306
#06	GSM1900	GSM	Right Tilted	661	0.262
#07	GSM1900	GSM	Left Cheek	661	0.506
#08	GSM1900	GSM	Left Tilted	661	0.401
<b>#09</b>	<b>GSM1900</b>	<b>GSM</b>	<b>Left Cheek</b>	<b>512</b>	<b>0.61</b>
#10	GSM1900	GSM	Left Cheek	810	0.333

### 11.3 Test Records for Body SAR Test

Plot No.	Band	Mode	Test Position	Separation Distance (cm)	Channel	SAR <sub>1g</sub> (W/kg)
#01	GSM1900	GPRS12	Bottom	1.5	661	1.1
#02	GSM1900	GPRS12	Face	1.5	661	0.314
<b>#03</b>	<b>GSM1900</b>	<b>GPRS12</b>	<b>Bottom</b>	<b>1.5</b>	<b>512</b>	<b>1.26</b>
#04	GSM1900	GPRS12	Bottom	1.5	810	0.822

Test Engineer : Robert Liu





## **12. References**

- [1] IC RSS-102 Issue 3, "Radio Frequency Exposure Compliance of Radiocommunication Apparatus (All Frequency Bands)", June 2009
- [2] FCC 47 CFR Part 2 "Frequency Allocations and Radio Treaty Matters; General Rules and Regulations"
- [3] IEEE Std. C95.1-1999, "IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz", 1999
- [4] IEEE Std. 1528-2003, "Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- [5] FCC OET Bulletin 65 (Edition 97-01) Supplement C (Edition 01-01), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields", June 2001
- [6] SPEAG DASY System Handbook
- [7] FCC KDB 248227 D01 v01r02, "SAR Measurement Procedures for 802.11 a/b/g Transmitters", May 2007
- [8] FCC KDB 447498 D01 v03r03, "Mobile and Portable Device RF Exposure Procedures and Equipment Authorization Policies", January 2009
- [9] FCC KDB 447498 D02 v01, "SAR Measurement Procedures for USB Dongle Transmitters", December 2008
- [10] FCC KDB 616217 D01 v01, "SAR Evaluation Considerations for Laptop Computers with Antennas Built-in on Display Screens", December 2007
- [11] FCC KDB 648474 D01 v01r05, "SAR Evaluation Considerations for Handsets with Multiple Transmitters and Antennas", September 2008
- [12] FCC KDB 941225 D01 v02, "SAR Measurement Procedures for 3G Devices – CDMA 2000 / Ev-Do / WCDMA / HSDPA / HSPA", October 2007
- [13] FCC KDB 941225 D03 v01, "Recommended SAR Test Reduction Procedures for GSM / GPRS / EDGE", December 2008



## **Appendix A. Plots of System Performance Check**

The plots are shown as follows.

## System Check\_1900 MHz\_090909

### DUT: Dipole 1900 MHz

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: MSL\_1900\_090909 Medium parameters used:  $f = 1900$  MHz;  $\sigma = 1.55$  mho/m;  $\epsilon_r = 52.2$ ;  $\rho = 1000$

kg/m<sup>3</sup>

Ambient Temperature : 22.9 ; Liquid Temperature : 21.3

#### DASY5 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.49, 4.49, 4.49); Calibrated: 2009/5/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn679; Calibrated: 2009/6/23
- Phantom: SAM - Front; Type: SAM; Serial: TP-1446
- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Pin=100mW/Area Scan (61x61x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 4.71 mW/g

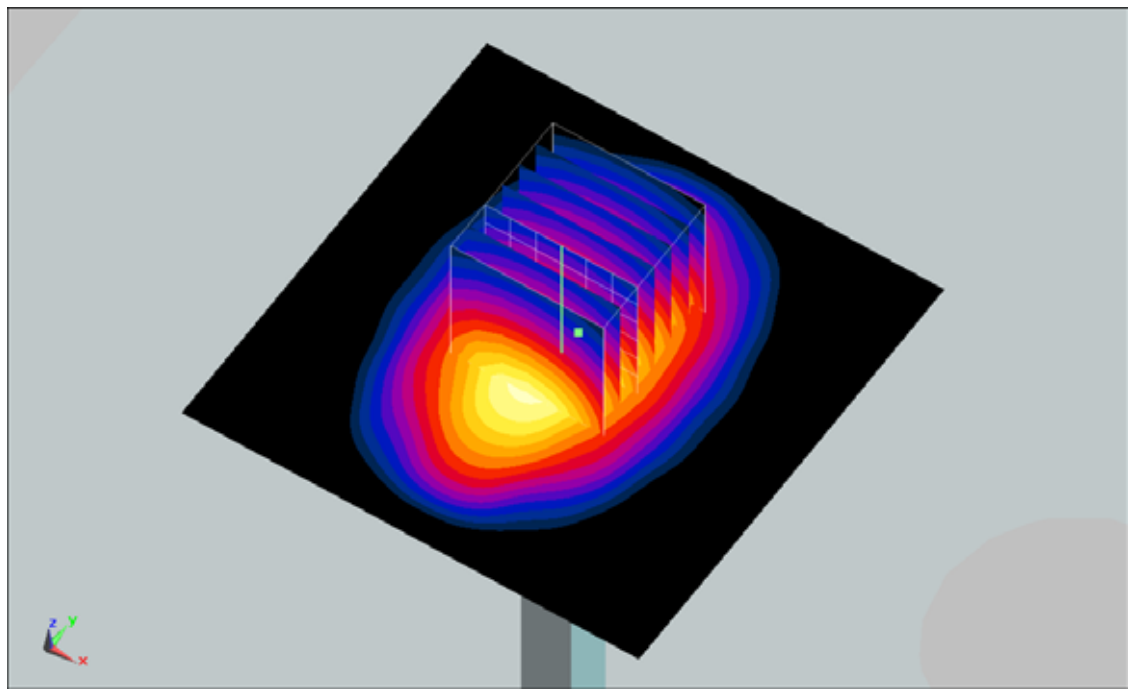
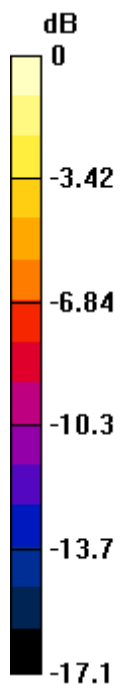
**Pin=100mW/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 60.3 V/m; Power Drift = 0.000904 dB

Peak SAR (extrapolated) = 6.23 W/kg

**SAR(1 g) = 4.06 mW/g; SAR(10 g) = 2.19 mW/g**

Maximum value of SAR (measured) = 4.63 mW/g



0 dB = 4.63mW/g



## ***Appendix B. Plots of SAR Measurement***

The plots are shown as follows.

**#05 GSM1900\_Right Cheek\_Ch661**

**DUT: 990421**

Communication System: PCS; Frequency: 1880 MHz; Duty Cycle: 1:2

Medium: HSL\_1900\_090909 Medium parameters used:  $f = 1880$  MHz;  $\sigma = 1.41$  mho/m;  $\epsilon_r = 39$ ;  $\rho = 1000$

kg/m<sup>3</sup>

Ambient Temperature : 22.7 ; Liquid Temperature : 21.5

DASY5 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(5.12, 5.12, 5.12); Calibrated: 2009/5/26

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE4 Sn679; Calibrated: 2009/6/23

- Phantom: SAM-Back; Type: QD 000 P40 C; Serial: TP-1383

- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Ch661/Area Scan (51x91x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.290 mW/g

**Ch661/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 10.7 V/m; Power Drift = -0.167 dB

Peak SAR (extrapolated) = 0.437 W/kg

**SAR(1 g) = 0.306 mW/g; SAR(10 g) = 0.181 mW/g**

Maximum value of SAR (measured) = 0.343 mW/g

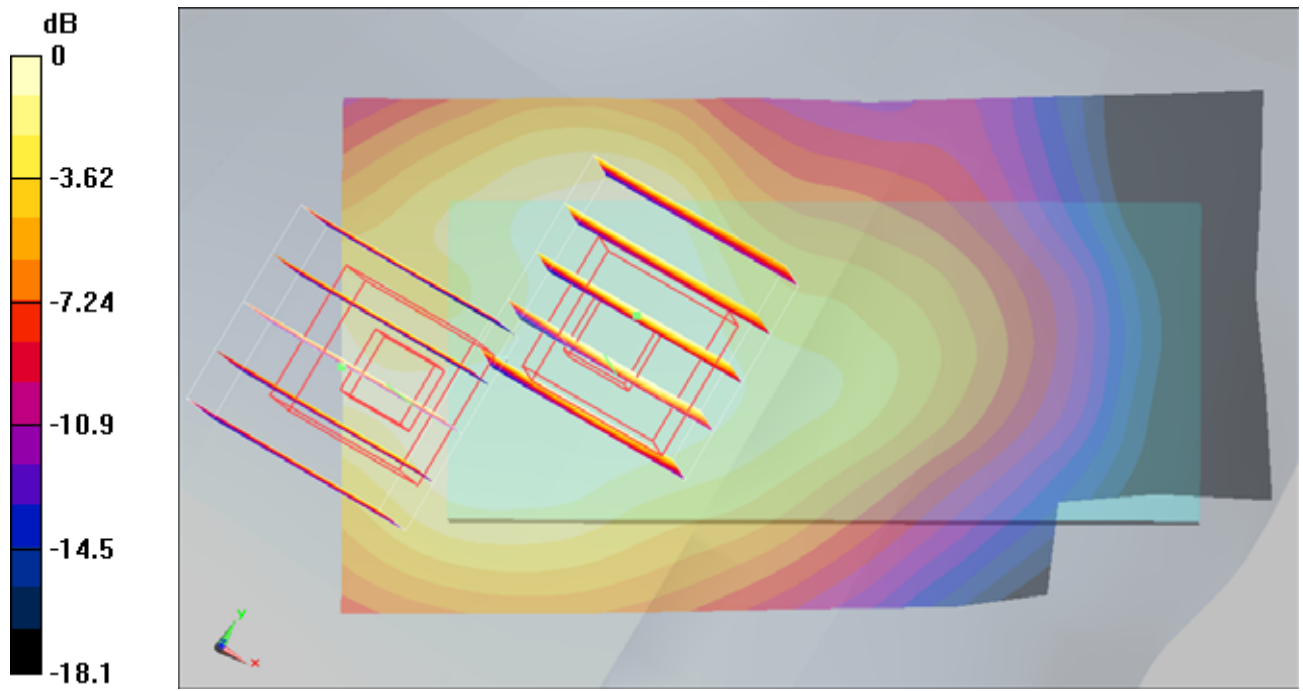
**Ch661/Zoom Scan (5x5x7)/Cube 1:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 10.7 V/m; Power Drift = -0.167 dB

Peak SAR (extrapolated) = 0.359 W/kg

**SAR(1 g) = 0.213 mW/g; SAR(10 g) = 0.119 mW/g**

Maximum value of SAR (measured) = 0.237 mW/g



0 dB = 0.237mW/g

## #06 GSM1900\_Right Tilted\_Ch661

### DUT: 990421

Communication System: PCS; Frequency: 1880 MHz; Duty Cycle: 1:2

Medium: HSL\_1900\_090909 Medium parameters used:  $f = 1880$  MHz;  $\sigma = 1.41$  mho/m;  $\epsilon_r = 39$ ;  $\rho = 1000$

kg/m<sup>3</sup>

Ambient Temperature : 22.7 ; Liquid Temperature : 21.5

#### DASY5 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(5.12, 5.12, 5.12); Calibrated: 2009/5/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn679; Calibrated: 2009/6/23
- Phantom: SAM-Back; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Ch661/Area Scan (51x91x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.266 mW/g

**Ch661/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 10.9 V/m; Power Drift = -0.081 dB

Peak SAR (extrapolated) = 0.401 W/kg

**SAR(1 g) = 0.262 mW/g; SAR(10 g) = 0.148 mW/g**

Maximum value of SAR (measured) = 0.288 mW/g

**Ch661/Zoom Scan (5x5x7)/Cube 1:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

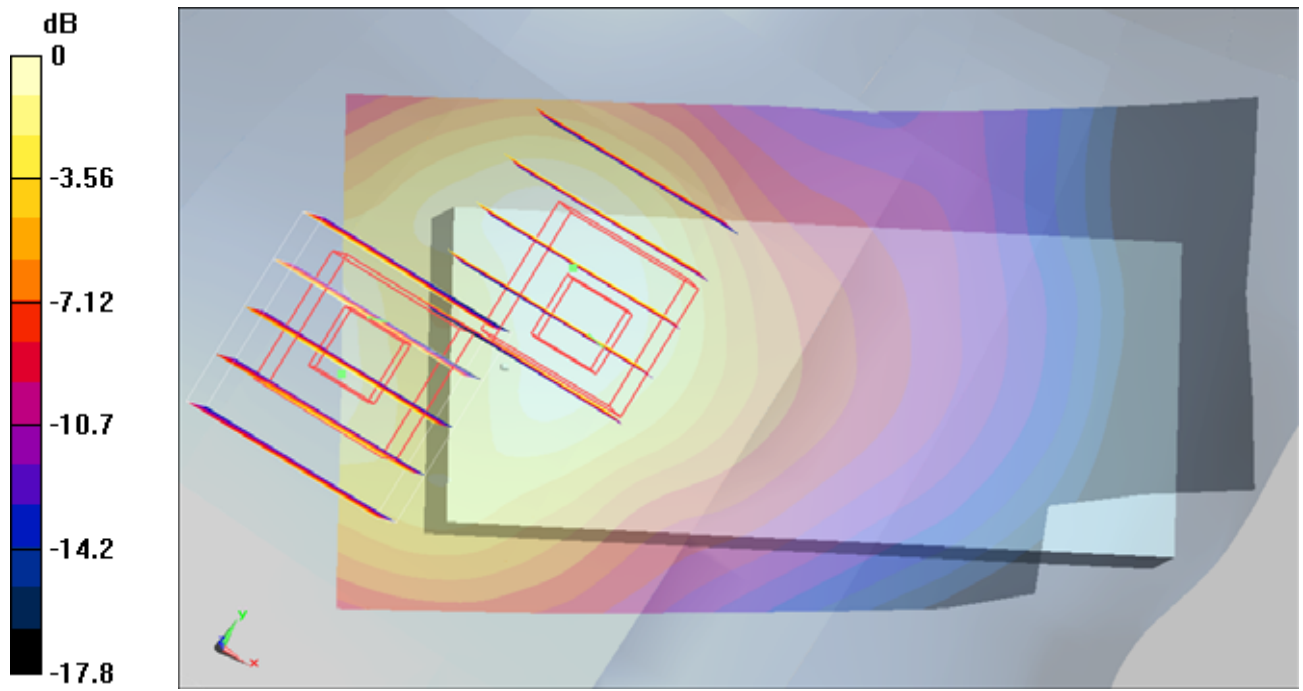
Reference Value = 10.9 V/m; Power Drift = -0.081 dB

Peak SAR (extrapolated) = 0.399 W/kg

**SAR(1 g) = 0.232 mW/g; SAR(10 g) = 0.125 mW/g**

Maximum value of SAR (measured) = 0.254 mW/g





0 dB = 0.254mW/g

**#09 GSM1900\_Left Cheek\_Ch512**

**DUT: 990421**

Communication System: PCS; Frequency: 1850.2 MHz; Duty Cycle: 1:2

Medium: HSL\_1900\_090909 Medium parameters used :  $f = 1850.2 \text{ MHz}$ ;  $\sigma = 1.38 \text{ mho/m}$ ;  $\epsilon_r = 39.2$ ;  $\rho = 1000$

$\text{kg/m}^3$

Ambient Temperature : 22.7 ; Liquid Temperature : 21.5

**DASY5 Configuration:**

- Probe: ET3DV6 - SN1787; ConvF(5.12, 5.12, 5.12); Calibrated: 2009/5/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn679; Calibrated: 2009/6/23
- Phantom: SAM-Back; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Ch512/Area Scan (51x91x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.693 mW/g

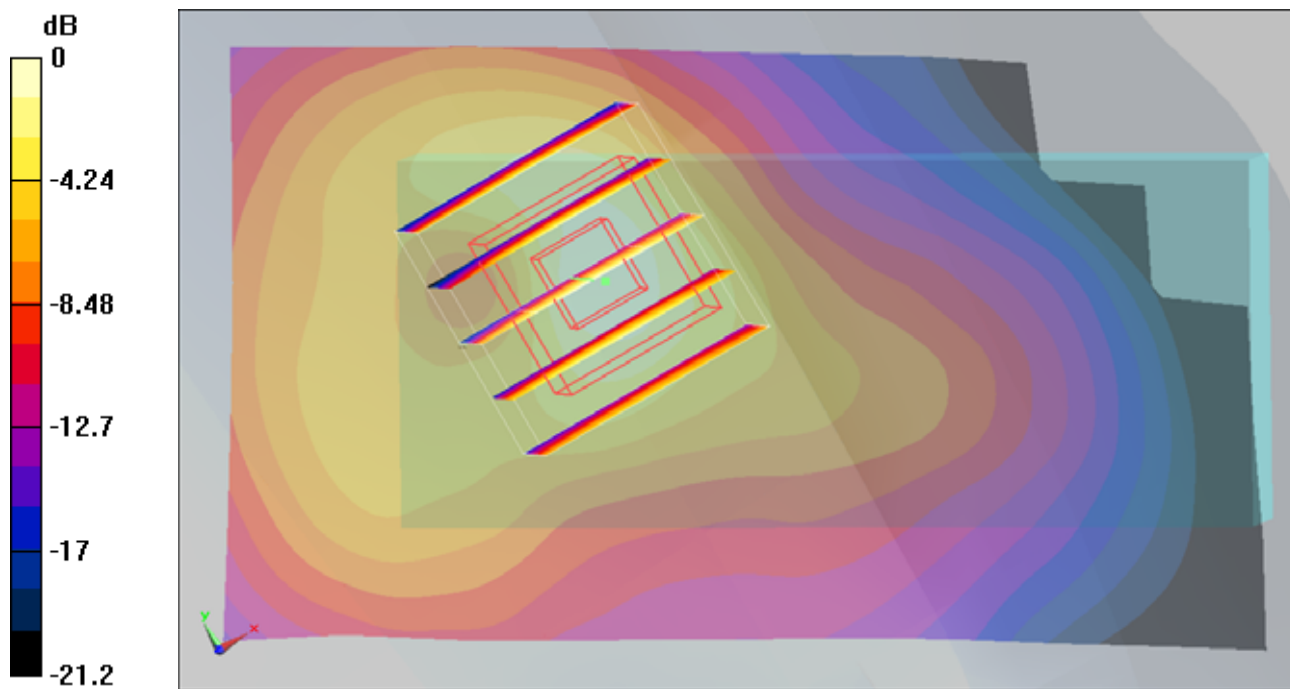
**Ch512/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 10.6 V/m; Power Drift = -0.069 dB

Peak SAR (extrapolated) = 0.997 W/kg

**SAR(1 g) = 0.610 mW/g; SAR(10 g) = 0.326 mW/g**

Maximum value of SAR (measured) = 0.684 mW/g



0 dB = 0.684mW/g

#09 GSM1900\_Left Cheek\_Ch512\_2D

DUT: 990421

Communication System: PCS; Frequency: 1850.2 MHz; Duty Cycle: 1:2

Medium: HSL\_1900\_090909 Medium parameters used :  $f = 1850.2$  MHz;  $\sigma = 1.38$  mho/m;  $\epsilon_r = 39.2$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 22.7 ; Liquid Temperature : 21.5

DASY5 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(5.12, 5.12, 5.12); Calibrated: 2009/5/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn679; Calibrated: 2009/6/23
- Phantom: SAM-Back; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Ch512/Area Scan (51x91x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.693 mW/g

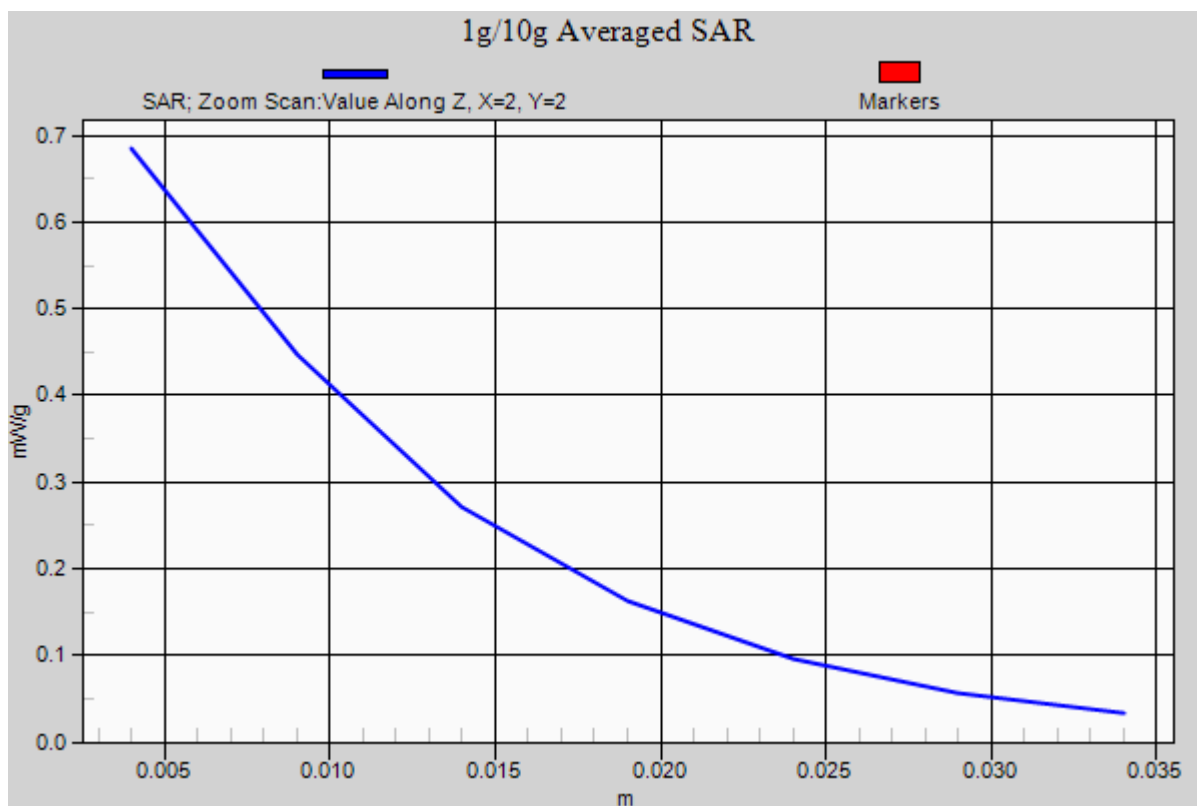
**Ch512/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 10.6 V/m; Power Drift = -0.069 dB

Peak SAR (extrapolated) = 0.997 W/kg

**SAR(1 g) = 0.610 mW/g; SAR(10 g) = 0.326 mW/g**

Maximum value of SAR (measured) = 0.684 mW/g



**#08 GSM1900\_Left Tilted\_Ch661**

**DUT: 990421**

Communication System: PCS; Frequency: 1880 MHz; Duty Cycle: 1:2

Medium: HSL\_1900\_090909 Medium parameters used:  $f = 1880$  MHz;  $\sigma = 1.41$  mho/m;  $\epsilon_r = 39$ ;  $\rho = 1000$

kg/m<sup>3</sup>

Ambient Temperature : 22.7 ; Liquid Temperature : 21.5

DASY5 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(5.12, 5.12, 5.12); Calibrated: 2009/5/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn679; Calibrated: 2009/6/23
- Phantom: SAM-Back; Type: QD 000 P40 C; Serial: TP-1383
- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Ch661/Area Scan (51x91x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.419 mW/g

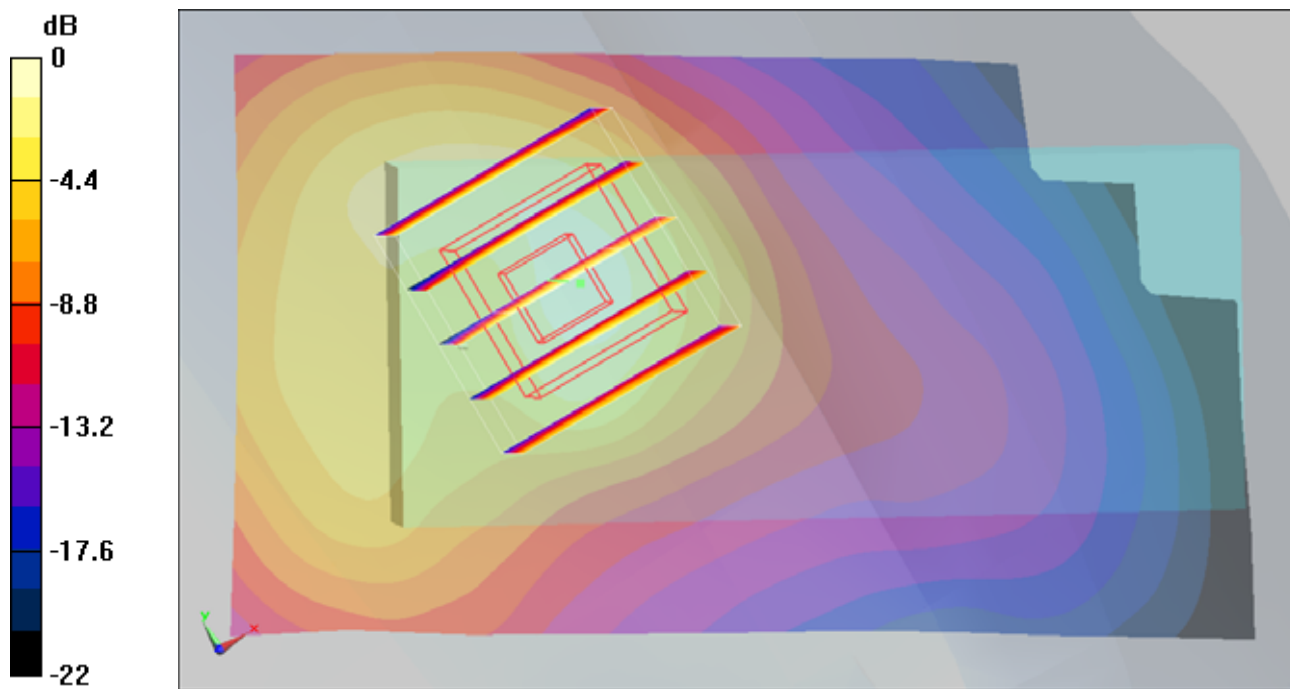
**Ch661/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 9.49 V/m; Power Drift = -0.108 dB

Peak SAR (extrapolated) = 0.646 W/kg

**SAR(1 g) = 0.401 mW/g; SAR(10 g) = 0.213 mW/g**

Maximum value of SAR (measured) = 0.442 mW/g



0 dB = 0.442mW/g

**#02 GSM1900\_GPRS12\_Face\_1.5cm\_Ch661**

**DUT: 990421**

Communication System: PCS; Frequency: 1880 MHz; Duty Cycle: 1:2

Medium: MSL\_1900\_090909 Medium parameters used:  $f = 1880$  MHz;  $\sigma = 1.52$  mho/m;  $\epsilon_r = 52.3$ ;  $\rho = 1000$

kg/m<sup>3</sup>

Ambient Temperature : 22.9 ; Liquid Temperature : 21.3

DASY5 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.49, 4.49, 4.49); Calibrated: 2009/5/26

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE4 Sn679; Calibrated: 2009/6/23

- Phantom: SAM - Front; Type: SAM; Serial: TP-1446

- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Ch661/Area Scan (51x91x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.335 mW/g

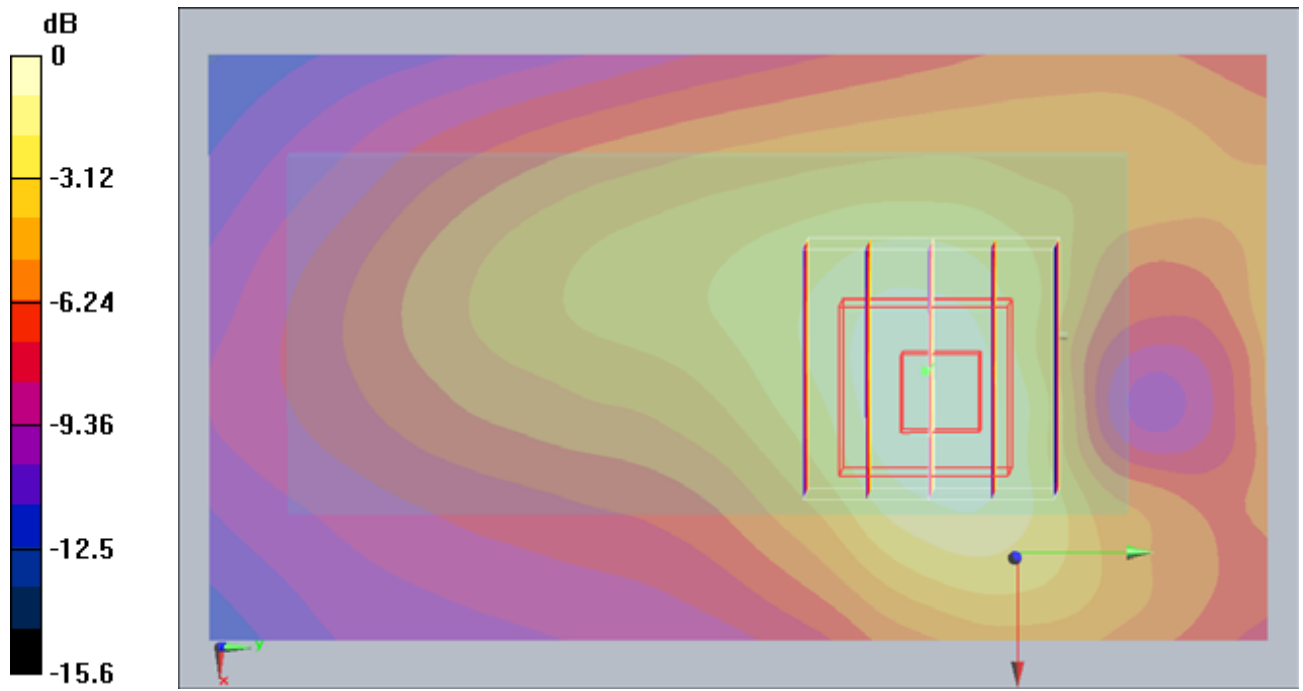
**Ch661/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 9.33 V/m; Power Drift = -0.078 dB

Peak SAR (extrapolated) = 0.490 W/kg

**SAR(1 g) = 0.314 mW/g; SAR(10 g) = 0.190 mW/g**

Maximum value of SAR (measured) = 0.332 mW/g



0 dB = 0.332mW/g



**#03 GSM1900\_GPRS12\_Bottom\_1.5cm\_Ch512**

**DUT: 990421**

Communication System: PCS; Frequency: 1850.2 MHz; Duty Cycle: 1:2

Medium: MSL\_1900\_090909 Medium parameters used :  $f = 1850.2$  MHz;  $\sigma = 1.49$  mho/m;  $\epsilon_r = 52.4$ ;  $\rho = 1000$

kg/m<sup>3</sup>

Ambient Temperature : 22.9 ; Liquid Temperature : 21.3

DASY5 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.49, 4.49, 4.49); Calibrated: 2009/5/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn679; Calibrated: 2009/6/23
- Phantom: SAM - Front; Type: SAM; Serial: TP-1446
- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Ch512/Area Scan (51x91x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 1.35 mW/g

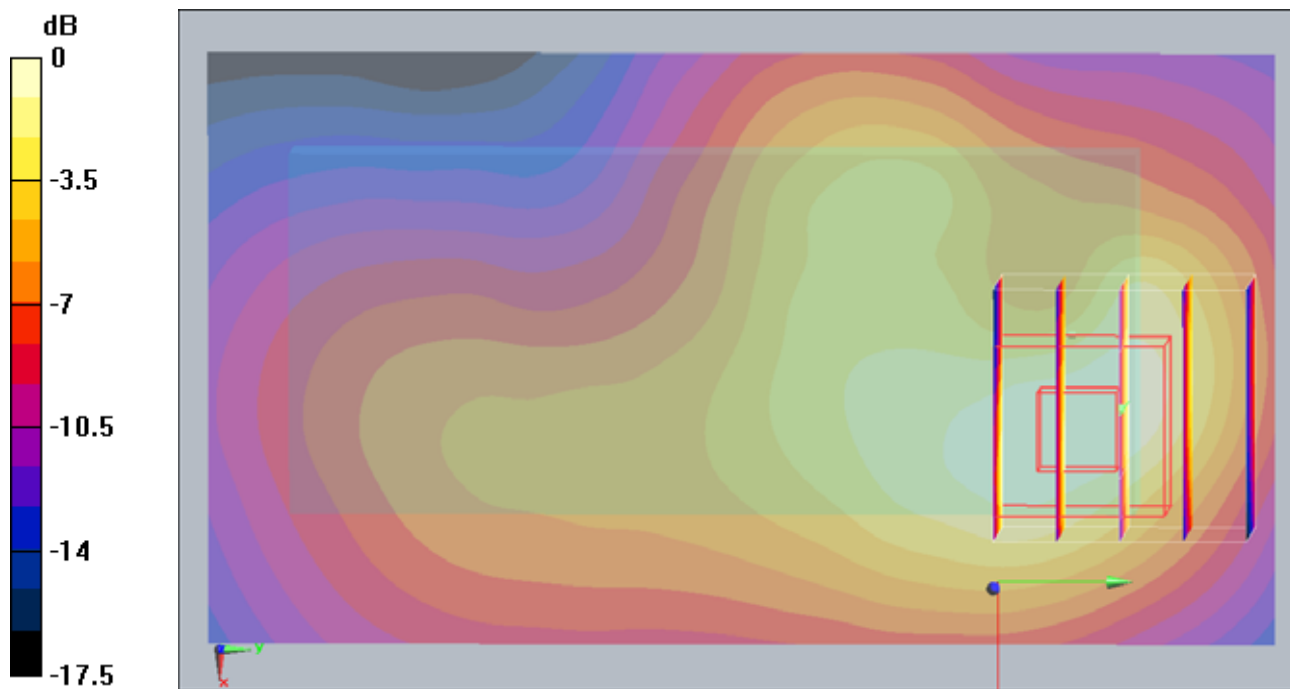
**Ch512/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 25.9 V/m; Power Drift = -0.192 dB

Peak SAR (extrapolated) = 1.87 W/kg

**SAR(1 g) = 1.26 mW/g; SAR(10 g) = 0.738 mW/g**

Maximum value of SAR (measured) = 1.35 mW/g



#03 GSM1900\_GPRS12\_Bottom\_1.5cm\_Ch512\_2D

DUT: 990421

Communication System: PCS; Frequency: 1850.2 MHz; Duty Cycle: 1:2

Medium: MSL\_1900\_090909 Medium parameters used :  $f = 1850.2$  MHz;  $\sigma = 1.49$  mho/m;  $\epsilon_r = 52.4$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Ambient Temperature : 22.9 ; Liquid Temperature : 21.3

DASY5 Configuration:

- Probe: ET3DV6 - SN1787; ConvF(4.49, 4.49, 4.49); Calibrated: 2009/5/26
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn679; Calibrated: 2009/6/23
- Phantom: SAM - Front; Type: SAM; Serial: TP-1446
- Measurement SW: DASY5, V5.0 Build 125; SEMCAD X Version 13.4 Build 125

**Ch512/Area Scan (51x91x1):** Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 1.35 mW/g

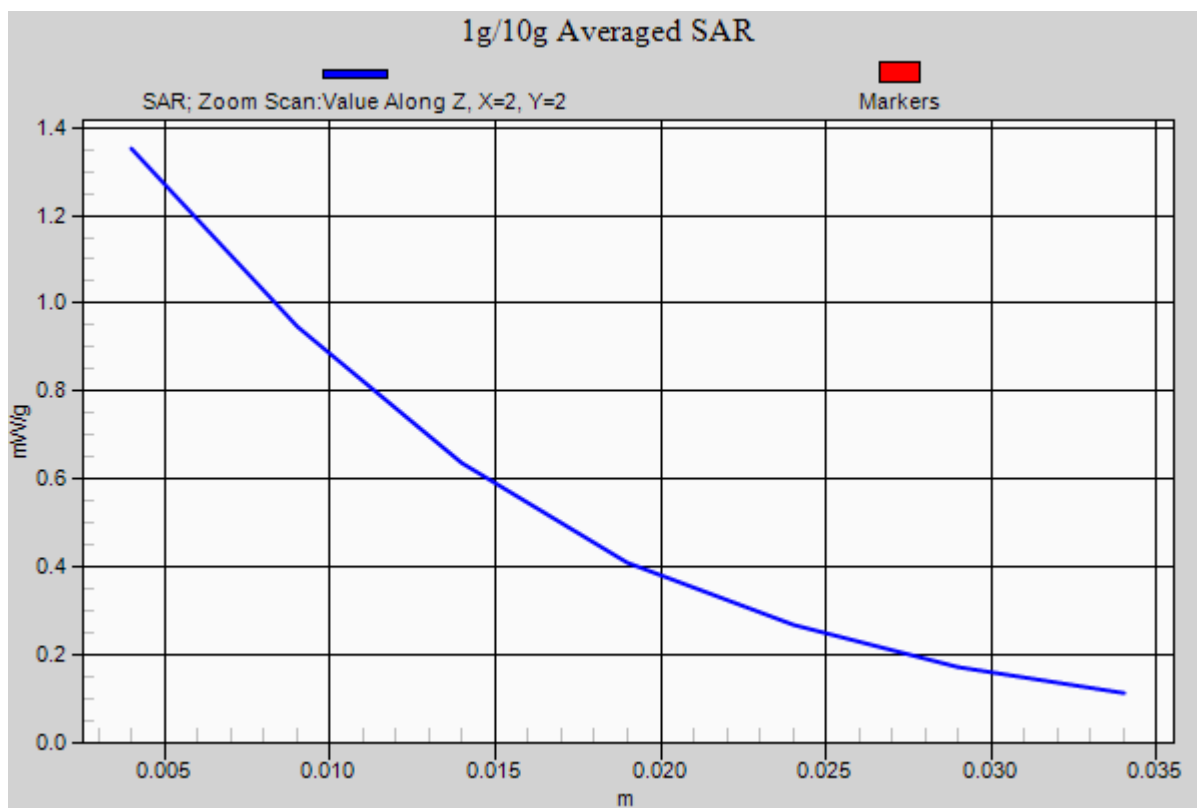
**Ch512/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 25.9 V/m; Power Drift = -0.192 dB

Peak SAR (extrapolated) = 1.87 W/kg

**SAR(1 g) = 1.26 mW/g; SAR(10 g) = 0.738 mW/g**

Maximum value of SAR (measured) = 1.35 mW/g





## **Appendix C. DASYS Calibration Certificate**

The DASYS calibration certificates are shown as follows.



Calibration Laboratory of Schmid & Partner Engineering AG, Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst, Service suisse d'étalonnage, Servizio svizzero di taratura, Swiss Calibration Service

Accredited by the Swiss Federal Office of Metrology and Accreditation. The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client: Sporton (Auden)

Certificate No: D1900V2-5d041\_Mar08

CALIBRATION CERTIFICATE

Object: D1900V2 - SN: 5d041
Calibration procedure(s): QA CAL-05.v7 Calibration procedure for dipole validation kits
Calibration date: March 18, 2008
Condition of the calibrated item: In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility; environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Table with 4 columns: Primary Standards, ID #, Cal Date (Calibrated by, Certificate No.), Scheduled Calibration. Includes items like Power meter EPM-442A, Power sensor HP 8481A, Reference 20 dB Attenuator, etc.

Calibrated by: Marcel Fehr, Laboratory Technician
Approved by: Katja Pokovic, Technical Manager

Issued: March 18, 2008

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



Calibration Laboratory of  
Schmid & Partner  
Engineering AG  
Zeughausstrasse 43, 8004 Zurich, Switzerland



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The Swiss Accreditation Service is one of the signatories to the EA  
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

**Glossary:**

TSL tissue simulating liquid  
ConvF sensitivity in TSL / NORM x,y,z  
N/A not applicable or not measured

**Calibration is Performed According to the Following Standards:**

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
- Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

**Additional Documentation:**

- DASY4 System Handbook

**Methods Applied and Interpretation of Parameters:**

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.



**Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY4	V4.7
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V5.0	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	1900 MHz ± 1 MHz	

**Head TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	40.0	1.40 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	40.2 ± 6 %	1.47 mho/m ± 6 %
Head TSL temperature during test	(21.1 ± 0.2) °C	---	---

**SAR result with Head TSL**

SAR averaged over 1 cm <sup>2</sup> (1 g) of Head TSL	condition	
SAR measured	250 mW input power	10.1 mW / g
SAR normalized	normalized to 1W	40.4 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	<b>39.5 mW / g ± 17.0 % (k=2)</b>

SAR averaged over 10 cm <sup>2</sup> (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	5.20 mW / g
SAR normalized	normalized to 1W	20.8 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	<b>20.6 mW / g ± 16.5 % (k=2)</b>

<sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"



### Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	53.3	1.52 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	51.6 ± 8 %	1.57 mho/m ± 6 %
Body TSL temperature during test	(21.4 ± 0.2) °C	---	---

### SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	10.4 mW / g
SAR normalized	normalized to 1W	41.6 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	40.1 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	
SAR measured	250 mW input power	5.44 mW / g
SAR normalized	normalized to 1W	21.8 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	21.3 mW / g ± 16.5 % (k=2)

---

<sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"





**Appendix**

**Antenna Parameters with Head TSL**

Impedance, transformed to feed point	54.0 $\Omega$ + 5.1 j $\Omega$
Return Loss	- 24.2 dB

**Antenna Parameters with Body TSL**

Impedance, transformed to feed point	48.0 $\Omega$ + 6.1 j $\Omega$
Return Loss	- 23.6 dB

**General Antenna Parameters and Design**

Electrical Delay (one direction)	1.199 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

**Additional EUT Data**

Manufactured by	SPEAG
Manufactured on	July 04, 2003

DASY4 Validation Report for Head TSL

Date/Time: 18.03.2008 12:05:10

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d041

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: HSL U10 BB;

Medium parameters used:  $f = 1900$  MHz;  $\sigma = 1.47$  mho/m;  $\epsilon_r = 40.2$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3025; ConvF(4.9, 4.9, 4.9); Calibrated: 01.03.2008
- Sensor-Surface: 3.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn909; Calibrated: 03.09.2007
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA ;
- Measurement SW: DASY4, V4.7 Build 55; Postprocessing SW: SEMCAD, V1.8 Build 172

**Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:**

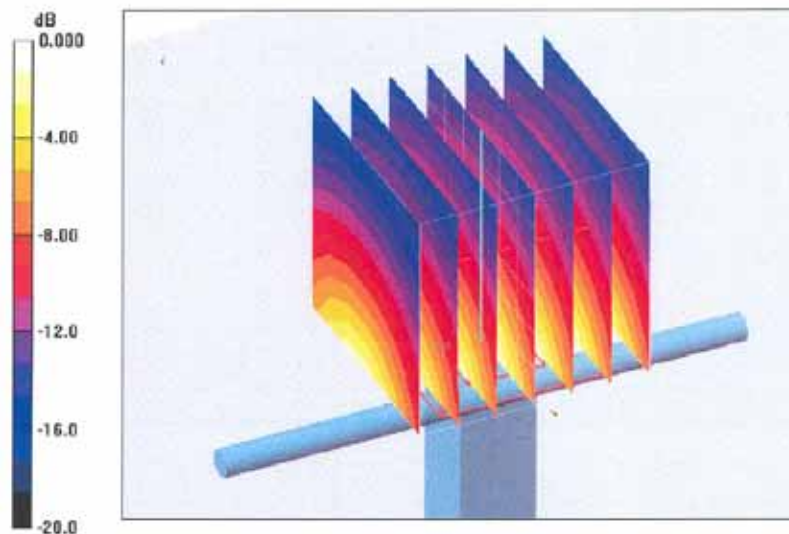
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 91.7 V/m; Power Drift = 0.013 dB

Peak SAR (extrapolated) = 19.1 W/kg

**SAR(1 g) = 10.1 mW/g; SAR(10 g) = 5.2 mW/g**

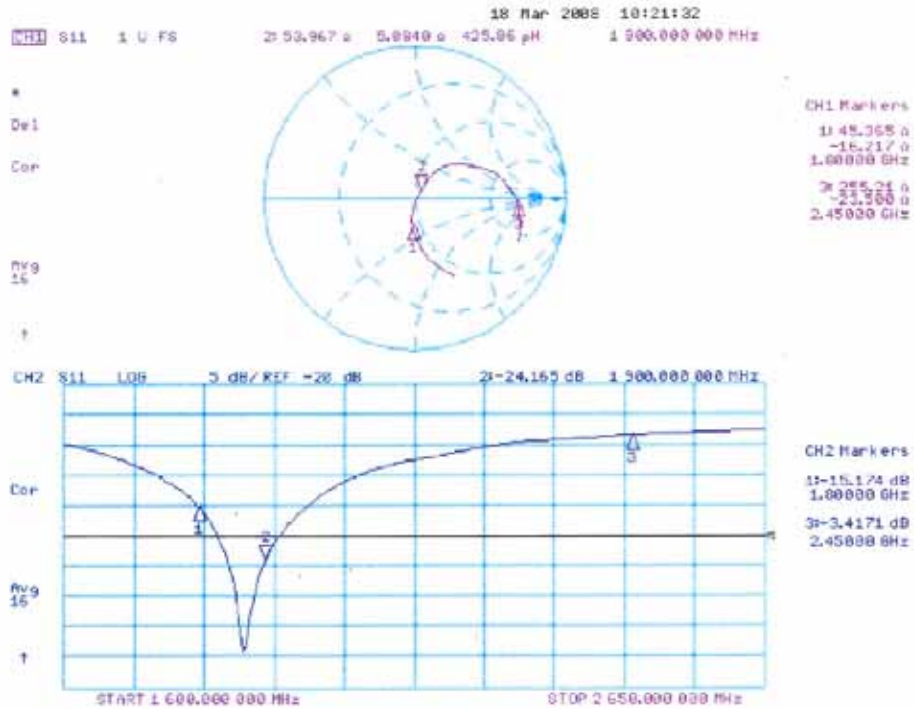
Maximum value of SAR (measured) = 11.8 mW/g



0 dB = 11.8mW/g



Impedance Measurement Plot for Head TSL



DASY4 Validation Report for Body TSL

Date/Time: 14.03.2008 13:22:24

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d041

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: MSL U10 BB;

Medium parameters used:  $f = 1900$  MHz;  $\sigma = 1.57$  mho/m;  $\epsilon_r = 51.7$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3025; ConvF(4.5, 4.5, 4.5); Calibrated: 01.03.2008
- Sensor-Surface: 3.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn909; Calibrated: 03.09.2007
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; ;
- Measurement SW: DASY4, V4.7 Build 55; Postprocessing SW: SEMCAD, V1.8 Build 172

**Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:**

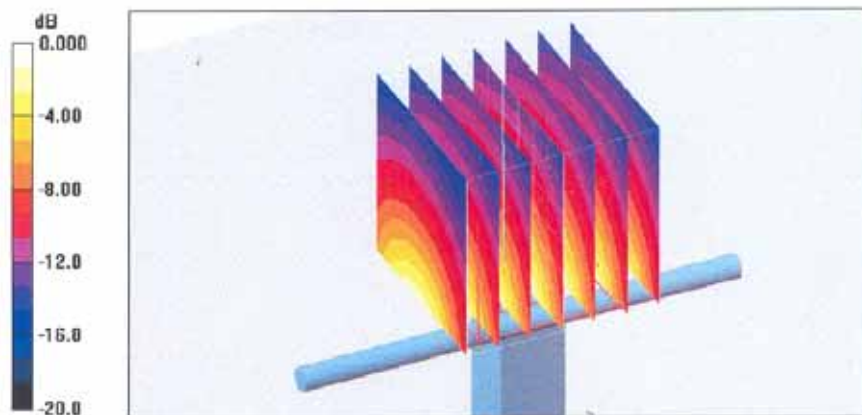
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 89.7 V/m; Power Drift = 0.004 dB

Peak SAR (extrapolated) = 18.6 W/kg

**SAR(1 g) = 10.4 mW/g; SAR(10 g) = 5.44 mW/g**

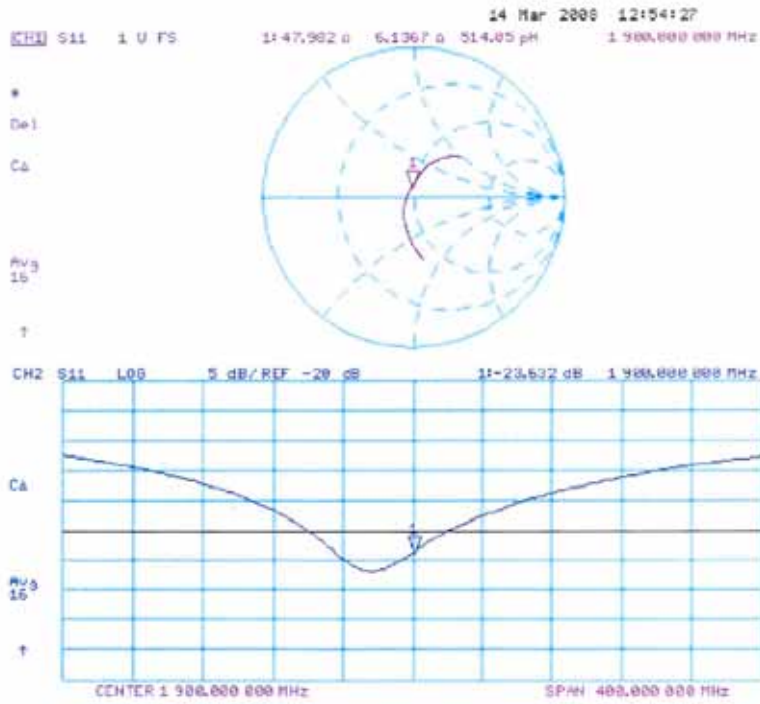
Maximum value of SAR (measured) = 12.0 mW/g



0 dB = 12.0mW/g



Impedance Measurement Plot for Body TSL





Calibration Laboratory of Schmid & Partner Engineering AG, Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: SCS 108

Client Auden

Certificate No: DAE4-679\_Jun09

CALIBRATION CERTIFICATE

Object: DAE4 - SD 000 D04 BJ - SN: 679
Calibration procedure(s): QA CAL-06.v12 Calibration procedure for the data acquisition electronics (DAE)
Calibration date: June 23, 2009
Condition of the calibrated item: In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Table with 4 columns: Standards, ID #, Date, and Scheduled. Rows include Primary Standards (Fluke Process Calibrator, Keithley Multimeter) and Secondary Standards (Calibrator Box).

Calibrated by: Eric Hainfeld, Technician
Approved by: Fin Bomholt, R&D Director
Signatures of Eric Hainfeld and Fin Bomholt

Issued: June 23, 2009

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**Calibration Laboratory of**  
Schmid & Partner  
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The Swiss Accreditation Service is one of the signatories to the EA  
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

## Glossary

**DAE** data acquisition electronics  
**Connector angle** information used in DASY system to align probe sensor X to the robot coordinate system.

## Methods Applied and Interpretation of Parameters

- **DC Voltage Measurement:** Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- **Connector angle:** The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - **DC Voltage Measurement Linearity:** Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - **Common mode sensitivity:** Influence of a positive or negative common mode voltage on the differential measurement.
  - **Channel separation:** Influence of a voltage on the neighbor channels not subject to an input voltage.
  - **AD Converter Values with inputs shorted:** Values on the internal AD converter corresponding to zero input voltage
  - **Input Offset Measurement:** Output voltage and statistical results over a large number of zero voltage measurements.
  - **Input Offset Current:** Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - **Input resistance:** DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - **Low Battery Alarm Voltage:** Typical value for information. Below this voltage, a battery alarm signal is generated.
  - **Power consumption:** Typical value for information. Supply currents in various operating modes.



**DC Voltage Measurement**

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 $\mu$ V , full range = -100...+300 mV  
Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.503 $\pm$ 0.1% (k=2)	404.926 $\pm$ 0.1% (k=2)	405.103 $\pm$ 0.1% (k=2)
Low Range	3.98274 $\pm$ 0.7% (k=2)	3.92959 $\pm$ 0.7% (k=2)	3.98854 $\pm$ 0.7% (k=2)

**Connector Angle**

Connector Angle to be used in DASY system	316 $^{\circ}$ $\pm$ 1 $^{\circ}$
---	-----------------------------------





**Appendix**

**1. DC Voltage Linearity**

High Range	Input ( $\mu\text{V}$ )	Reading ( $\mu\text{V}$ )	Error (%)
Channel X + Input	200000	199999.9	0.00
Channel X + Input	20000	20004.11	0.02
Channel X - Input	20000	-20002.63	0.01
Channel Y + Input	200000	200000	0.00
Channel Y + Input	20000	20003.98	0.02
Channel Y - Input	20000	-20001.91	0.01
Channel Z + Input	200000	199999.9	0.00
Channel Z + Input	20000	20001.57	0.01
Channel Z - Input	20000	-20004.84	0.02

Low Range	Input ( $\mu\text{V}$ )	Reading ( $\mu\text{V}$ )	Error (%)
Channel X + Input	2000	2000.1	0.00
Channel X + Input	200	200.27	0.13
Channel X - Input	200	-200.34	0.17
Channel Y + Input	2000	2000.1	0.00
Channel Y + Input	200	199.56	-0.22
Channel Y - Input	200	-200.06	0.03
Channel Z + Input	2000	1999.9	0.00
Channel Z + Input	200	199.18	-0.41
Channel Z - Input	200	-201.05	0.53

**2. Common mode sensitivity**

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading ( $\mu\text{V}$ )	Low Range Average Reading ( $\mu\text{V}$ )
Channel X	200	2.30	1.94
	-200	-1.31	-2.38
Channel Y	200	6.13	4.89
	-200	-6.12	-6.48
Channel Z	200	-4.86	-5.43
	-200	2.27	3.92

**3. Channel separation**

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X ( $\mu\text{V}$ )	Channel Y ( $\mu\text{V}$ )	Channel Z ( $\mu\text{V}$ )
Channel X	200	-	1.95	-0.44
Channel Y	200	1.03	-	3.64
Channel Z	200	-1.59	0.33	-



4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16178	16934
Channel Y	15450	15973
Channel Z	16051	16646

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10MΩ

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	0.17	-2.20	1.69	0.48
Channel Y	-1.14	-3.43	1.00	0.63
Channel Z	-0.55	-1.73	1.00	0.44

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MΩ)	Measuring (MΩ)
Channel X	0.2000	200.8
Channel Y	0.2000	199.3
Channel Z	0.1999	198.3

8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9



Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: SCS 108

Client Sporton (Auden)

Certificate No: ET3-1787\_May09

CALIBRATION CERTIFICATE
Object: ET3DV6 - SN:1787
Calibration procedure(s): QA CAL-01.v6 and QA CAL-23.v3
Calibration date: May 26, 2009
Condition of the calibrated item: In Tolerance
This calibration certificate documents the traceability to national standards...
Calibration Equipment used (M&TE critical for calibration)
Primary Standards table with columns: Primary Standards, ID #, Cal Date (Certificate No.), Scheduled Calibration
Secondary Standards table with columns: Secondary Standards, ID #, Check Date (in house), Scheduled Check
Calibrated by: Marcel Fehr, Laboratory Technician
Approved by: Katja Pokovic, Technical Manager
Issued: May 27, 2009



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Zeughausstrasse 43, 8004 Zurich, Switzerland



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**Glossary:**

TSL	tissue simulating liquid
NORM <sub>x,y,z</sub>	sensitivity in free space
ConvF	sensitivity in TSL / NORM <sub>x,y,z</sub>
DCP	diode compression point
Polarization $\varphi$	$\varphi$ rotation around probe axis
Polarization $\vartheta$	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis

**Calibration is Performed According to the Following Standards:**

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

**Methods Applied and Interpretation of Parameters:**

- NORM<sub>x,y,z</sub>:** Assessed for E-field polarization  $\vartheta = 0$  ( $f \leq 900$  MHz in TEM-cell;  $f > 1800$  MHz: R22 waveguide). NORM<sub>x,y,z</sub> are only intermediate values, i.e., the uncertainties of NORM<sub>x,y,z</sub> does not effect the E<sup>2</sup>-field uncertainty inside TSL (see below ConvF).
- NORM(f)<sub>x,y,z</sub> = NORM<sub>x,y,z</sub> \* frequency\_response** (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP<sub>x,y,z</sub>:** DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters:** Assessed in flat phantom using E-field (or Temperature Transfer Standard for  $f \leq 800$  MHz) and inside waveguide using analytical field distributions based on power measurements for  $f > 800$  MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM<sub>x,y,z</sub> \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from  $\pm 50$  MHz to  $\pm 100$  MHz.
- Spherical isotropy (3D deviation from isotropy):** in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset:** The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.



ET3DV6 SN:1787

May 26, 2009

# Probe ET3DV6

## SN:1787

Manufactured:	May 28, 2003
Last calibrated:	August 26, 2008
Modified:	May 20, 2009
Recalibrated:	May 26, 2009

Calibrated for DASYS Systems

(Note: non-compatible with DASYS2 system!)



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DASY - Parameters of Probe: ET3DV6 SN:1787

Sensitivity in Free Space<sup>A</sup>

Diode Compression<sup>B</sup>

NormX	1.63 ± 10.1%	μV/(V/m) <sup>2</sup>	DCP X	95 mV
NormY	1.72 ± 10.1%	μV/(V/m) <sup>2</sup>	DCP Y	94 mV
NormZ	2.14 ± 10.1%	μV/(V/m) <sup>2</sup>	DCP Z	94 mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

Boundary Effect

TSL 835 MHz Typical SAR gradient: 5 % per mm

Sensor Center to Phantom Surface Distance		3.7 mm	4.7 mm
SAR <sub>be</sub> [%]	Without Correction Algorithm	10.0	5.9
SAR <sub>be</sub> [%]	With Correction Algorithm	0.9	0.6

TSL 1750 MHz Typical SAR gradient: 10 % per mm

Sensor Center to Phantom Surface Distance		3.7 mm	4.7 mm
SAR <sub>be</sub> [%]	Without Correction Algorithm	12.3	8.4
SAR <sub>be</sub> [%]	With Correction Algorithm	0.9	0.7

Sensor Offset

Probe Tip to Sensor Center 2.7 mm

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

<sup>B</sup> Numerical linearization parameter: uncertainty not required.

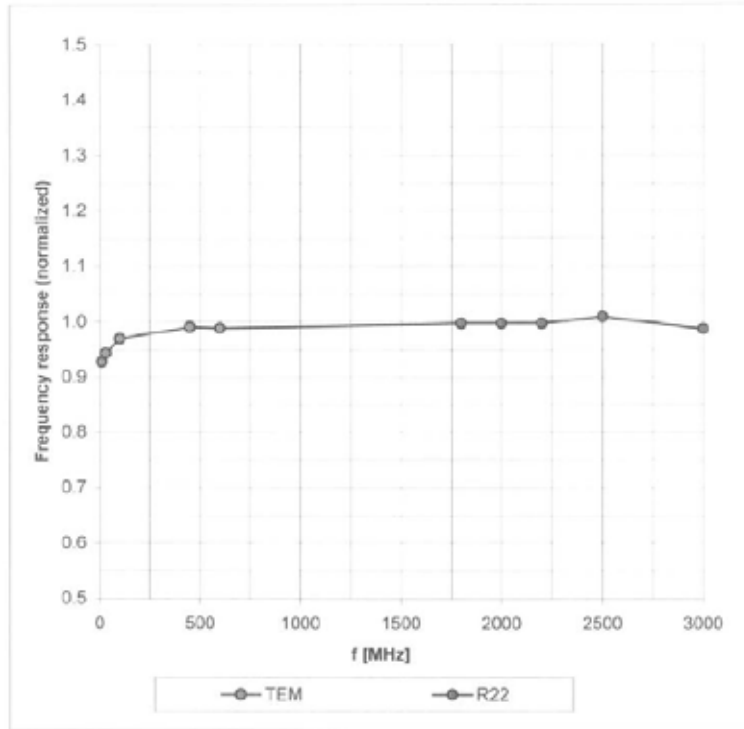


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### Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)



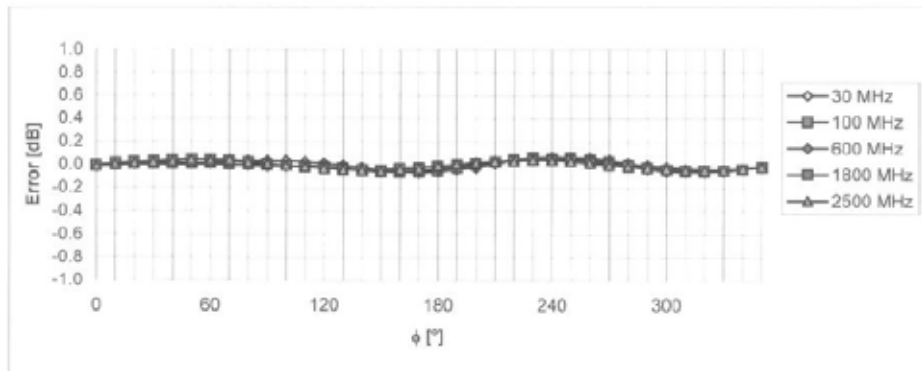
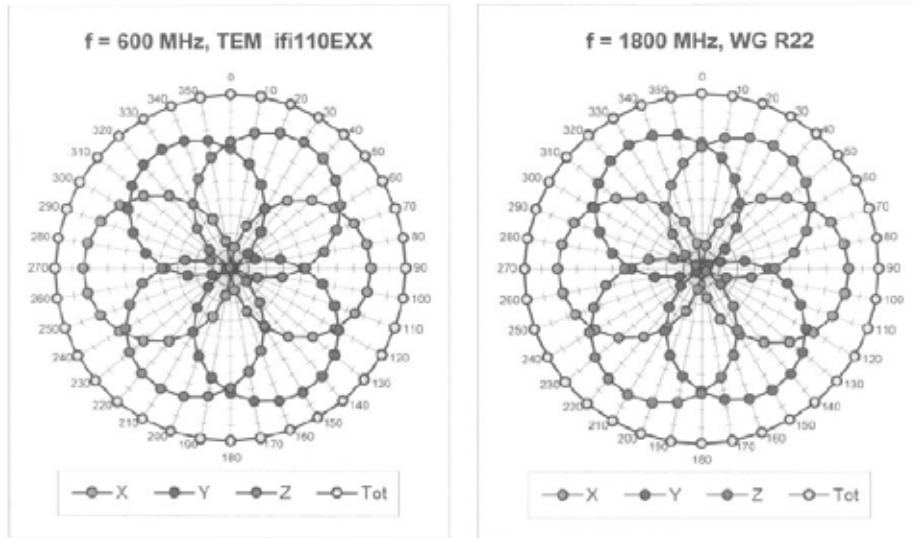
Uncertainty of Frequency Response of E-field:  $\pm 6.3\%$  (k=2)



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Receiving Pattern ( $\phi$ ),  $\vartheta = 0^\circ$



Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  ( $k=2$ )

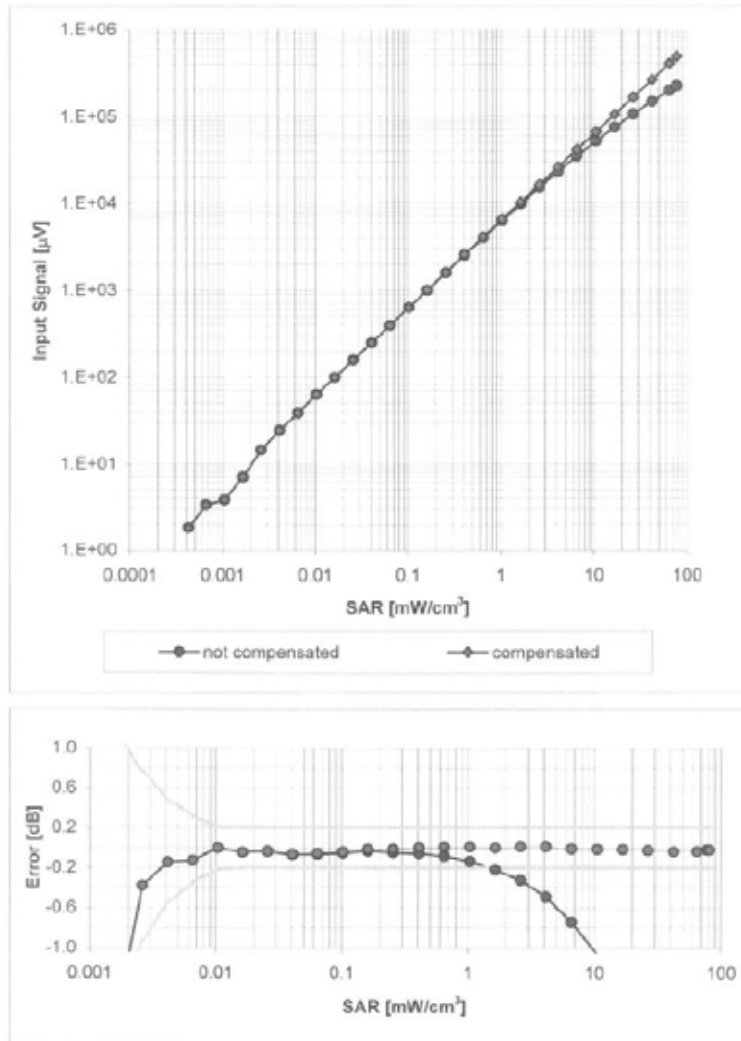




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### Dynamic Range $f(SAR_{head})$ (Waveguide R22, $f = 1800$ MHz)



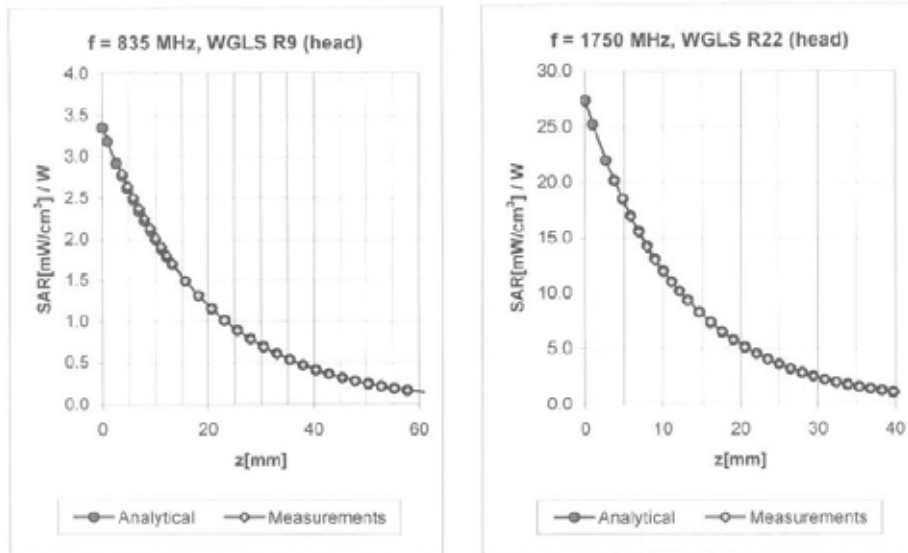
Uncertainty of Linearity Assessment:  $\pm 0.6\%$  ( $k=2$ )



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### Conversion Factor Assessment



f [MHz]	Validity [MHz] <sup>c</sup>	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
835	± 50 / ± 100	Head	41.5 ± 5%	0.90 ± 5%	0.52	2.01	6.26 ± 11.0% (k=2)
1750	± 50 / ± 100	Head	40.1 ± 5%	1.37 ± 5%	0.49	2.72	5.34 ± 11.0% (k=2)
1900	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.58	2.44	5.12 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.99	1.69	4.51 ± 11.0% (k=2)
835	± 50 / ± 100	Body	55.2 ± 5%	0.97 ± 5%	0.39	2.37	6.09 ± 11.0% (k=2)
1750	± 50 / ± 100	Body	53.4 ± 5%	1.49 ± 5%	0.63	3.27	4.82 ± 11.0% (k=2)
1900	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.90	2.43	4.49 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.80	1.50	3.96 ± 11.0% (k=2)

<sup>c</sup> The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

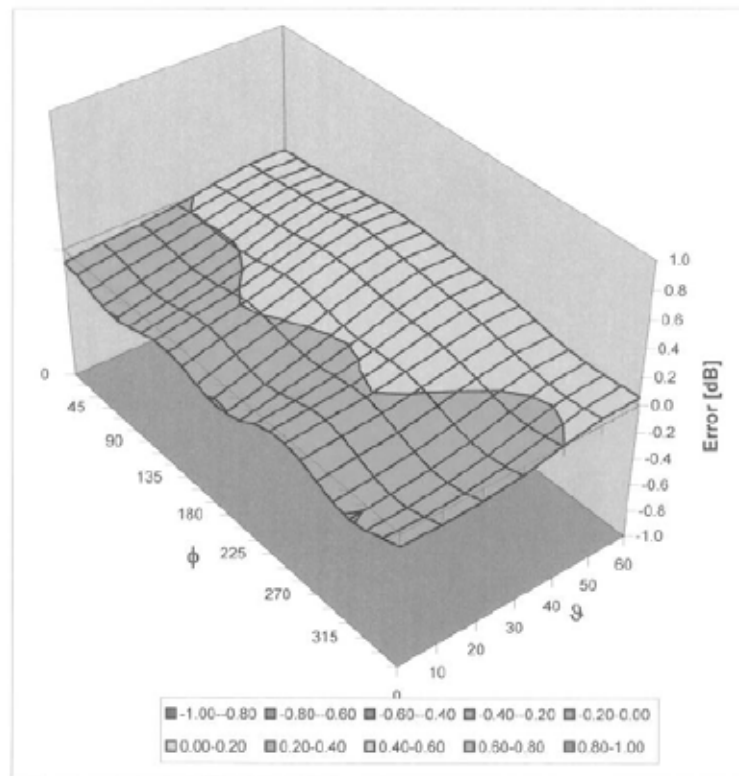


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May 26, 2009

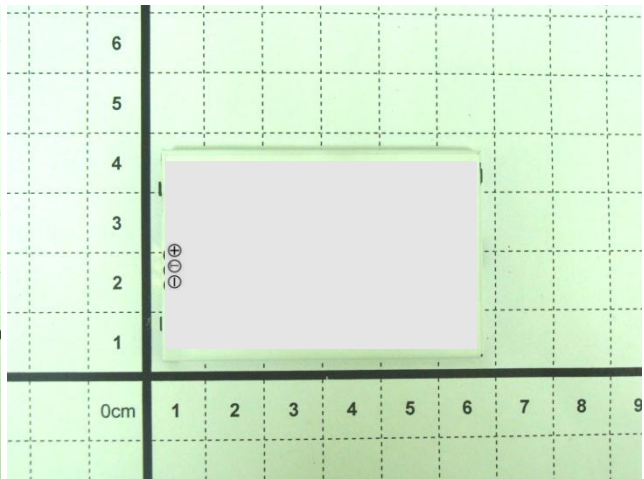
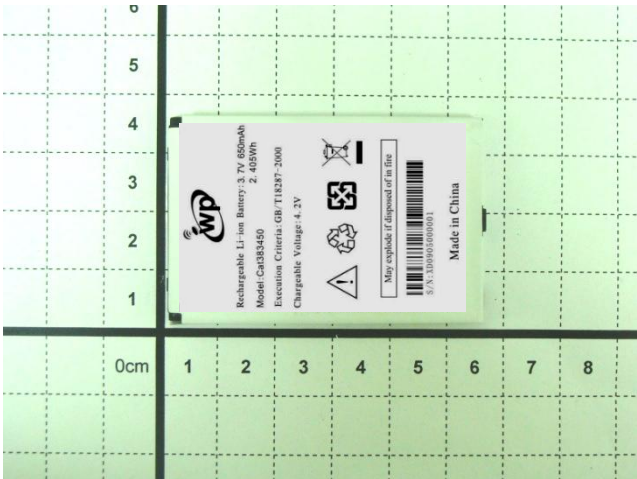
### Deviation from Isotropy in HSL

Error ( $\phi$ ,  $\theta$ ),  $f = 900$  MHz

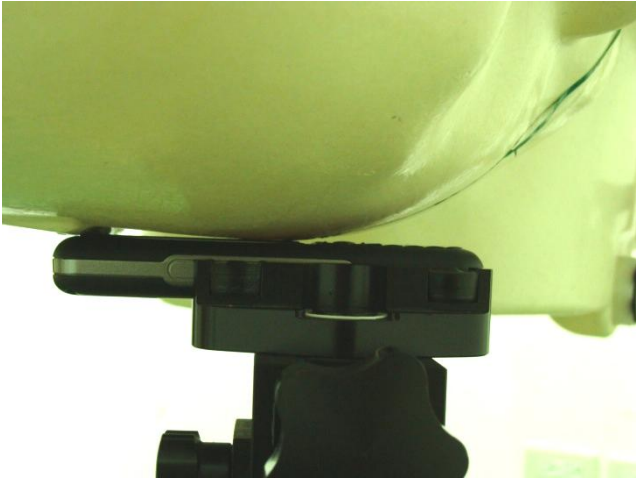


Uncertainty of Spherical Isotropy Assessment:  $\pm 2.6\%$  ( $k=2$ )

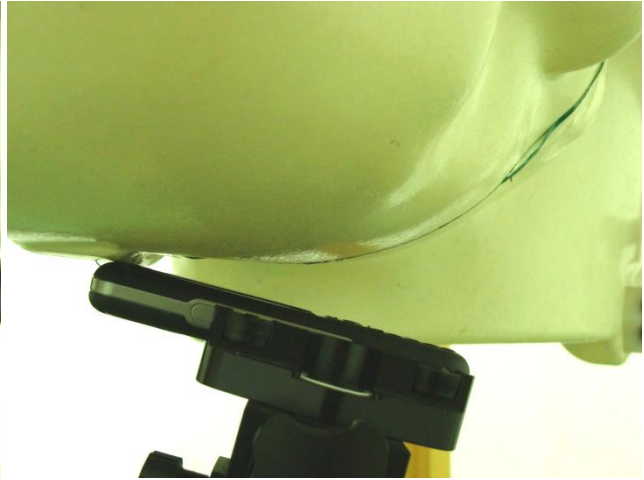
Appendix D. Product Photos



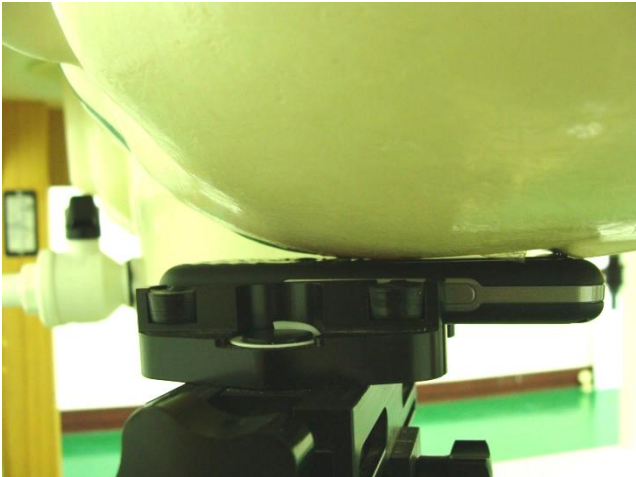
## Appendix E. Test Setup Photos



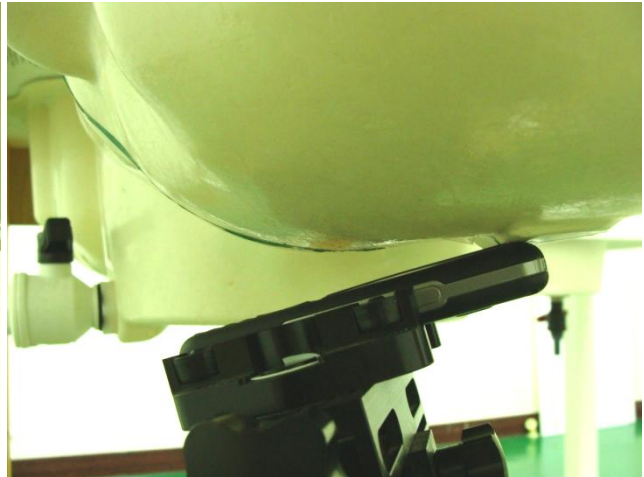
Right Cheek



Right Tilted



Left Cheek



Left Tilted



Face of the DUT with Phantom 1.5 cm Gap



Bottom of the DUT with Phantom 1.5 cm Gap