

No. 2009EEE04061

For

WANLIDA GROUP CO.,LTD.

**NoteBook** 

PC-91002

With

Wi-Fi module 802.11 b/g

Module Name: WT-mU-MTRa01

Module Version: 1.0

FCCID: XB5-UMS5001-1

Issued Date: 2009-8-26

CNAS L0442



No. DAT-P-114/01-01

Note:

The test results in this test report relate only to the devices specified in this reproduced except in full without the written approval of TMC Beijing.

#### Test Laboratory:

TMC Beijing, Telecommunication Metrology Center of Ministry of Information Industry No. 52, Huayuan Bei Road, Haidian District, Beijing, P. R. China 100083.

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# 1 Test Laboratory

## 1.1 Testing Location

Company Name:

TMC Beijing, Telecommunication Metrology Center of MII

Address:

No 52, Huayuan beilu, Haidian District, Beijing, P.R. China

Postal Code:

100083

Telephone:

+86-10-62303288

Fax:

+86-10-62304793

# 1.2 Testing Environment

Temperature:

18°C~25 °C,

Relative humidity:

30%~ 70%

Ground system resistance:

< 0.5 Ω

Ambient noise is checked and found very low and in compliance with requirement of standards. Reflection of surrounding objects is minimized and in compliance with requirement of standards.

# 1.3 Project Data

Project Leader:

Sun Qian

Test Engineer:

Lin Xiaojun

Testing Start Date:

June 20, 2009

Testing End Date:

June 20, 2009

# 1.4 Signature

Lin Xiaoiun

(Prepared this test report)

Sun Qian

(Reviewed this test report)

Lu Bingsong

Deputy Director of the laboratory

(Approved this test report)



# 2 Client Information

# 2.1 Applicant Information

Company Name: TUV SUD China Shenzhen branch

Address /Post: 6/F, H Hall, Century Craftwork Culture Square No. 4001 Fuqiang

Road, Futian District, shenzhen, P.R.China

City: Shenzhen
Postal Code: 518048
Country: China

Telephone: +86 (0) 755-88286998-273 Fax: +86 (0) 755-88285299

## 2.2 Manufacturer Information

Company Name: WANLIDA GROUP CO.,LTD.

Address /Post: WANLIDA INDUSTRY ZONE, NANJING ,FUJIAN, CHINA

City: Xiamen

Postal Code: /

Country: China

Telephone: // Fax: //



# 3 Equipment Under Test (EUT) and Ancillary Equipment (AE)

#### 3.1 About EUT

Description: Notebook PC with WiFi and Bluetooth module

Model Name: PC-91002 Brand Name: WANLIDA

Frequency Band: 802.11b/g 2.45GHz

Note: The EUT in this report is the same as the one in the report NO.2009EEE04060,but the CPU type is different, this one is CPU N280 and that one is CPU N270.





Picture 1: Constituents of the sample

# 3.2 Internal Identification of AE used during the test

AE ID*	Description	Model	SN	Manufacturer
AE1	Adapter	MPA-12030	/	WANLIDA GROUP
				CO.,LTD
AE2	Battery	BT-9004	/	YOKU ENERGY(ZHANG
				ZHOU)CO.,LTD

<sup>\*</sup>EUT/AE ID: is used to identify the test sample in the lab internally.



#### **4 CHARACTERISTICS OF THE TEST**

#### 4.1 Applicable Limit Regulations

**EN 50360–2001:** Product standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones.

It specifies the maximum exposure limit of **2.0 W/kg** as averaged over any 10 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

**ANSI C95.1–1999:** IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

47 CFR §2.1093: Radiofrequency radiation exposure evaluation: portable devices.

They specify the maximum exposure limit of **1.6 W/kg** as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

# 4.2 Applicable Measurement Standards

**EN 62209-1–2006:** Human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices – Human models, instrumentation, and procedures –Part 1: Procedure to determine the specific absorption rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz).

**IEEE 1528–2003:** Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques.

**OET Bulletin 65 (Edition 97-01) and Supplement C(Edition 01-01):** Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits.

**IEC 62209-2 (Draft)**: Human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices – Human models, instrumentation, and procedures – Part 2: Procedure to determine the Specific Absorption Rate (SAR)in the head and body for 30MHz to 6GHz Handheld and Body-Mounted Devices used in close proximity to the Body.

**KDB 447498 D01**: Mobile and Portable Device RF Exposure Procedures and Equipment Authorization Policies v03r02

KDB 941225 D02: Guidance for Requesting a Permit-But-Ask for 3GPP R6-HSPA v01

KDB 248227:SAR Measurement Procedures for 802.11 a/b/g transmitter

**KDB 616217**:SAR Evaluation Considerations for Laptop Computers with Antennas Built-in on Display Screens.

They specify the measurement method for demonstration of compliance with the SAR limits for such equipments.



# **5 OPERATIONAL CONDITIONS DURING TEST**

## **5.1 Schematic Test Configuration**

#### 5.1.1 Test positions

The EUT is tested at the following 6 test positions(the antenna of the WiFi module is located along the top edge of the display):

Test position 1:The bottom of the computer is in direct contact against the flat phantom, and the display opens to the perpendicular position.

Test position 2:The bottom of the computer is in direct contact against the flat phantom, and the display folds over on to the keyboard section.

Test position 3:The cover of the computer is in direct contact against the flat phantom, and the display opens to the perpendicular position.

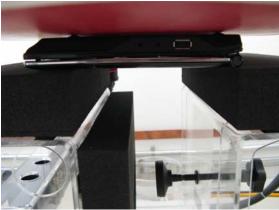
Test position 4:The cover of the computer is in direct contact against the flat phantom, and the display folds over on to the keyboard section.

Test position 5:The top side of the display is in direct contact against the flat phantom, and the display opens to the perpendicular position.

Test position 6:The top side of the display is in direct contact against the flat phantom, and the display folds over on to the keyboard section.









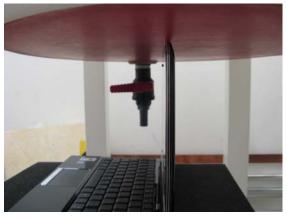
Picture 2-b: Test position 2



Picture 2-c: Test position 3

Picture 2-d: Test position 4







Picture 2-e: Test position 5

Picture 2-f: Test position 6

## 5.1.2 Body SAR Measurement Description

The EUT has two transmitter: WiFi 802.11b/g and bluetooth module, the distance between the BT antenna and WiFi antennas is greater than 20cm and the BT output power is 4dBm which less than 60/f(GHz). Therefore BT stand-alone SAR and simultaneous transmissions SAR are both not required to be carried out.



Picture 3 antenna positions



#### WiFi 802.11b/g 2.45GHz band

Because SAR is not required for 802.11g channels since the output power is less than 0.25dB higher than that measured on the corresponding 802.11b channels, and for each frequency band, testing at higher data rates is not required when the maximum average output power for each of these configuration is less than 0.25dB higher than those measured at the lowest data rate. According to the following conducted power, the EUT should be tested for "802.11b 1Mbps" first, and the "802.11g 6Mbps channel 11"should be performed for the corresponding 802.11b test position.

A communication link is set up with the test mode software for WiFi mode test. The test mode software we used is 2006\_03\_03\_RT2573\_RT2528\_ATE\_Release\_1\_0\_0\_3 with the version of 1.0.0.3 supported by company Ralink. The Absolute Radio Frequency Channel Number (ARFCN) is allocated to 1, 6 and 11 respectively in the case of 2450 MHz. During the test, at the each test frequency channel, the EUT is operated at the RF continuous emission mode. The tests are performed for WiFi at middle frequency first for all the 6 test positions, and then to low and high if necessary. according to the 3 dB rule, "if the SAR measured at the middle channel for each test configuration is at least 3 dB lower than the SAR limit, testing at the high and low channels is optional for such test configuration(s)."

The conducted power for WiFi is as following:

### 802.11b(dBm)

Channel\data	1Mbps	2Mbps	5.5Mbps	11Mbps
rate				
1	18.71	18.34	18.21	15.78
6	18.74	18.24	18.44	13.94
11	17.29	17.10	17.30	14.01

#### 802.11g(dBm)

Channel\data	6Mbps	9Mbps	12Mbps	18Mbps	24Mbps	36Mbps	48Mbps	54Mbps
rate								
1	16.44	16.01	15.95	16.33	16.40	16.44	16.02	15.59
6	17.72	17.02	17.52	17.32	17.42	17.62	17.61	17.02
11	18.92	18.45	18.14	18.66	18.71	18.11	17.06	17.55

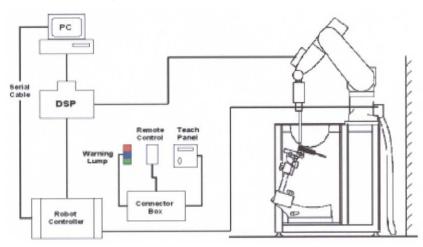
## 5.2 SAR Measurement Set-up

These measurements were performed with the automated near-field scanning system DASY4 Professional from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9m), which positions the probes with a positional repeatability of better than  $\pm$  0.02mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines (length =300mm) to the data acquisition unit.

A cell controller system contains the power supply, robot controller, teaches pendant (Joystick), and remote control, is used to drive the robot motors. The PC consists of the Micron Pentium III 800 MHz computer with Windows 2000 system and SAR Measurement Software DASY4



Professional, A/D interface card, monitor, mouse, and keyboard. The Stäubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.



Picture 4: SAR Lab Test Measurement Set-up

The DAE consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

#### 5.3 Dasy4 E-field Probe System

The SAR measurements were conducted with the dosimetric probe EX3DV4 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the standard procedure with an accuracy of better than  $\pm$  10%. The spherical isotropy was evaluated and found to be better than  $\pm$  0.25dB.

#### **EX3DV4 Probe Specification**

Construction Symmetrical design with triangular core

Built-in shielding against static charges

PEEK enclosure material (resistant to organic

solvents, e.g., DGBE)

Calibration Basic Broad Band Calibration in air

Conversion Factors (CF) for HSL 900 and HSL 1750

Additional CF for other liquids and frequencies

upon request



Picture 5: EX3DV4 E-field Probe



Frequency 10 MHz to 6 GHz; Linearity: ± 0.2 dB (30 MHz to 6GHz)

Directivity  $\pm$  0.3 dB in HSL (rotation around probe axis)

± 0.5 dB in tissue material (rotation normal to probe axis)

Dynamic Range 10 μW/g to > 100 mW/g; Linearity: ± 0.2 dB

Dimensions Overall length: 330 mm (Tip: 20 mm)

Tip diameter: 2.5 mm (Body: 12 mm)

Typical distance from probe tip to dipole

centers: 1 mm

Application High precision dosimetric measurements in

any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz

with precision of better 30%.



#### 5.4 E-field Probe Calibration

#### Picture6:EX3DV4 E-field probe

Each probe is calibrated according to a dosimetric assessment procedure with accuracy better than  $\pm$  10%. The spherical isotropy was evaluated and found to be better than  $\pm$  0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1 GHz, and in a wave guide above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$\mathbf{SAR} = \mathbf{C} \frac{\Delta \mathbf{T}}{\Delta t}$$

Where:  $\Delta t = \text{Exposure time (30 seconds)}$ ,

C = Heat capacity of tissue (brain or muscle),

 $\Delta T$  = Temperature increase due to RF exposure.

Or

$$SAR = \frac{|E|^2 \sigma}{\rho}$$

Where:

 $\sigma$  = Simulated tissue conductivity,

 $\rho$  = Tissue density (kg/m<sup>3</sup>).



**Picture 7: Device Holder** 



# 5.5 Other Test Equipment

#### 5.5.1 Device Holder for Transmitters

In combination with the Generic Twin Phantom V3.0, the Mounting Device (POM) enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeatably positioned according to the FCC and CENELEC specifications. The device holder can be locked at different phantom locations (left

head, right head, flat phantom).



**Picture 8: Generic Twin Phantom** 

#### 5.5.2 Phantom

The Generic Twin Phantom is constructed of a fiberglass shell integrated in a wooden table. The shape of the shell is based on data from an anatomical study designed to determine the maximum exposure in at least 90% of all users. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents the evaporation of the liquid. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot.

Shell Thickness 2±0. I mm
Filling Volume Approx. 20 liters

Dimensions 810 x 1000 x 500 mm (H x L x W)

Available Special

## **5.6 Equivalent Tissues**

The liquid used for the frequency range of 2000-3000 MHz consisted of water, Glycol monobutyl, and salt. The liquid has been previously proven to be suited for worst-case. The Table 4 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528.

**Table 1: Composition of the Body Tissue Equivalent Matter** 

MIXTURE %	FREQUENCY 2450MHz			
Water	72.60			
Glycol monobutyl	27.22			
Salt	0.18			
Dielectric Parameters Target Value	f=2450MHz ε=52.7 σ=1.95			



# 5.7 System Specifications

# 5.7.1 Robotic System Specifications

# **Specifications**

Positioner: Stäubli Unimation Corp. Robot Model: RX90L

Repeatability: ±0.02 mm

No. of Axis: 6

## **Data Acquisition Electronic (DAE) System**

#### **Cell Controller**

Processor: Pentium III Clock Speed: 800 MHz

**Operating System: Windows 2000** 

**Data Converter** 

Features: Signal Amplifier, multiplexer, A/D converter, and control logic

Software: DASY4 software

**Connecting Lines:** Optical downlink for data and status info.

Optical uplink for commands and clock

#### **6 TEST RESULTS**

#### **6.1 Dielectric Performance**

#### Table 2: Dielectric Performance of Body Tissue Simulating Liquid

Measurement is made at temperature 23.3 °C and relative humidity 49%.Liquid temperature during the test: 22.5°C/FrequencyPermittivity εConductivity σ (S/m)Target value2450 MHz52.71.95Measurement value<br/>(Average of 10 tests)2450 MHz50.681.93



# 6.2 System Validation

#### **Table 3: System Validation**

Measurement is made at temperature 23.3 °C and relative humidity 49%. input power 250 mW. Liquid temperature during the test: 22.5°C

Measurement Date: June 20,2009

	Dipole calibration	Frequency		Permittivity ε		Conductivity σ (S/m)	
Liquid	Target value	2450	MHz	40.5		1.85	
parameters	Actual Measurement value	2450 MHz		38.9		1.83	
	Frequency	Target value (W/kg)		Measured value (W/kg)		Deviation	
Verification results		10 g Average	1 g Average	10 g Average	1 g Average	10 g Average	1 g Average
	2450 MHz	5.91	13.07	6.08	13.21	2.88%	1.07%

Note: Target values are the data of the dipole validation results divided by 4 which indicates the input power is 250mW, please check Annex F for the Dipole Calibration Certificate.

# 6.3 Summary of Measurement Results

Since the EUT is the same as PC-91002 in the report NO.2009EEE04060, but with different CPU types. This will not influence the SAR values .We only performed the test for the worst case in the report No.2009EEE04060, and the result is as following.

Table 4: SAR Values (WiFi 802.11b 2450 MHz)

Limit of SAR (W/kg)	10 g Average	1 g Average	Power
Limit of SAR (W/kg)	2.0	1.6	Drift
Test Case	Measurement Result		(dB)
	(W/kg)		
	10 g Average	1 g Average	
		)	

#### 6.4 Conclusion

Localized Specific Absorption Rate (SAR) of this portable wireless device has been measured in all cases requested by the relevant standards cited in Clause 4.2 of this report. Maximum localized SAR is below exposure limits specified in the relevant standards cited in Clause 4.1 of this test report.

# 7 Measurement Uncertainty

SN	а	Туре	С	d	e = f(d,k)	f	h = c x f / e	k
	Uncertainty Component		Tol.	Prob	Div.	Ci	1 g	Vi



			(± %)	Dist.		(1 g)	u <sub>i</sub> (±%)	
1	System repetivity	Α	0.5	N	1	1	0.5	9
	Measurement System							
2	Probe Calibration	В	5	N	2	1	2.5	$\infty$
3	Axial Isotropy	В	4.7	R	√3	(1-cp) <sup>1/</sup>	4.3	∞
4	Hemispherical Isotropy	В	9.4	R	√3	√cp		$\infty$
5	Boundary Effect	В	0.4	R	√3	1	0.23	$\infty$
6	Linearity	В	4.7	R	√3	1	2.7	$\infty$
7	System Detection Limits	В	1.0	R	√3	1	0.6	$\infty$
8	Readout Electronics	В	1.0	N	1	1	1.0	$\infty$
9	RF Ambient Conditions	В	3.0	R	√3	1	1.73	$\infty$
10	Probe Positioner Mechanical Tolerance	В	0.4	R	√3	1	0.2	$\infty$
11	Probe Positioning with respect to Phantom Shell	В	2.9	R	√3	1	1.7	$\infty$
12	Extrapolation, interpolation and Integration Algorithms for Max. SAR Evaluation	В	3.9	R	√3	1	2.3	~
	Test sample Related							
13	Test Sample Positioning	Α	4.9	N	1	1	4.9	N- 1
14	Device Holder Uncertainty	Α	6.1	N	1	1	6.1	N- 1
15	Output Power Variation - SAR drift measurement	В	5.0	R	√3	1	2.9	$\infty$
	Phantom and Tissue Parameters				I	I	I	
16	Phantom Uncertainty (shape and thickness tolerances)	В	1.0	R	√3	1	0.6	8
17	Liquid Conductivity - deviation from target values	В	5.0	R	√3	0.64	1.7	∞
18	Liquid Conductivity - measurement uncertainty	В	5.0	N	1	0.64	1.7	М
19	Liquid Permittivity - deviation from target values	В	5.0	R	√3	0.6	1.7	$\infty$
20	Liquid Permittivity - measurement uncertainty	В	5.0	N	1	0.6	1.7	М
	Combined Standard Uncertainty			RSS			11.25	
	Expanded Uncertainty (95% CONFIDENCE INTERVAL)			K=2			22.5	



# **8 MAIN TEST INSTRUMENTS**

**Table 5: List of Main Instruments** 

No.	Name	Туре	Serial Number	Calibration Date	Valid Period	
01	Network analyzer	HP 8753E	US38433212	August 30,2008	One year	
02	Power meter	NRVD	101253	June 20, 2008	One year	
03	Power sensor	NRV-Z5	100333	Julie 20, 2000	One year	
04	Power sensor	NRV-Z6	100011	September 2, 2008	One year	
05	Signal Generator	E4433B	US37230472	September 4, 2008	One Year	
06	Amplifier	VTL5400	0505	No Calibration Requested		
07	E-field Probe	SPEAG EX3DV4	3617	July 9, 2008	One year	
08	DAE	SPEAG DAE4	786	November 24, 2008	One year	
09	Dipole Validation Kit	IndexSAR IXD-245	0102	October,2008	Two years	

\*\*\*END OF REPORT BODY\*\*\*



# ANNEX A MEASUREMENT PROCESS

The evaluation was performed with the following procedure:

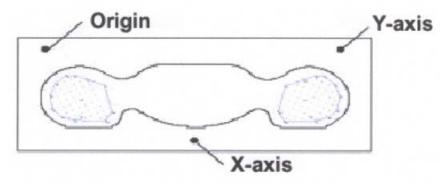
Step 1: Measurement of the SAR value at a fixed location above the reference point was measured and was used as a reference value for assessing the power drop.

Step 2: The SAR distribution at the exposed side of the phantom was measured at a distance of 3.9 mm from the inner surface of the shell. The area covered the entire dimension of the flat phantom and the horizontal grid spacing was 10 mm x 10 mm. Based on this data, the area of the maximum absorption was determined by spline interpolation.

Step 3: Around this point, a volume of 30 mm  $\times$  30 mm  $\times$  30 mm was assessed by measuring 7  $\times$  7 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure:

- a. The data at the surface were extrapolated, since the center of the dipoles is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2 mm. The extrapolation was based on a least square algorithm. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
- b. The maximum interpolated value was searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot"-condition (in  $x \sim y$  and z-directions). The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
- c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

Step 4: Re-measurement the SAR value at the same location as in Step 1. If the value changed by more than 5%, the evaluation is repeated.



Picture A: SAR Measurement Points in Area Scan



# ANNEX B TEST LAYOUT



Picture B1: Specific Absorption Rate Test Layout



Picture B2 Liquid depth in the Flat Phantom (2450MHz)



# ANNEX C GRAPH RESULTS

#### WiFi 802.11b 2450MHz Test Position 3 Middle

Date/Time: 6/20/2009 20:09:04 Date/Time: 6/20/2009 20:54:06

Electronics: DAE4 Sn786

Medium: Body 2450

Medium parameters used (interpolated): f = 2437 MHz;  $\sigma = 1.91 \text{ mho/m}$ ;  $\epsilon_r = 50.7$ ;

 $\rho = 1000 \text{ kg/m}^3$ 

Ambient Temperature: 23.3°C Liquid Temperature: 22.5°C

Communication System: WiFi 802.11 b Frequency: 2437 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3617 ConvF(6.88, 6.88, 6.88)

# Test Position 3\_ Channel Middle/Area Scan (161x201x1): Measurement grid:

dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 1.17 mW/g

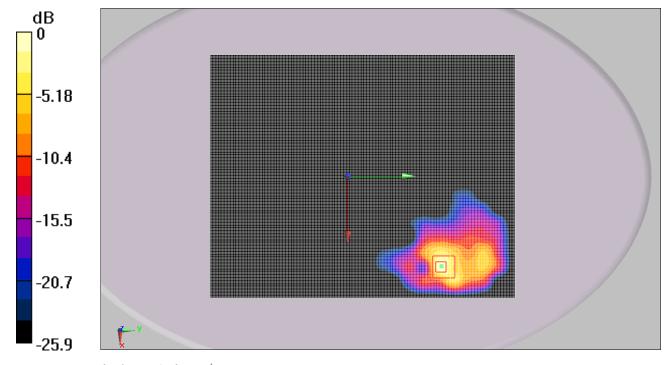
# Test Position 3\_ Channel Middle/Zoom Scan (7x7x7)/Cube 0: Measurement

grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.723 V/m; Power Drift = 0.113 dB

Peak SAR (extrapolated) = 2.47 W/kg

SAR(1 g) = 0.979 mW/g; SAR(10 g) = 0.396 mW/gMaximum value of SAR (measured) = 1.07 mW/g



 $0 \, dB = 1.07 \, mW/g$ 

Fig.1 2450MHz CH6 Test Position 3-WiFi 802.11b



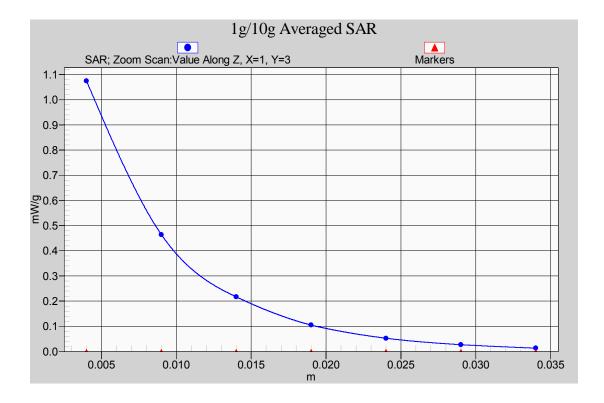


Fig.2 Z-Scan at power reference point (2450MHz CH6 Test Position 3-WiFi 802.11b)



# ANNEX D SYSTEM VALIDATION RESULTS

## 2450MHz

Date/Time: 6/20/2009 7:06:13 Date/Time: 6/20/2009 7:35:29

Electronics: DAE4 Sn786

Medium: Head 2450

Medium parameters used (interpolated): f = 2450 MHz;  $\sigma = 1.83 \text{ mho/m}$ ;  $\epsilon_r = 38.9$ ;

 $\rho = 1000 \text{ kg/m}^3$ 

Ambient Temperature: 23.3°C Liquid Temperature: 22.5°C Communication System: CW Frequency: 2450 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3617 ConvF(7.19, 7.19, 7.19)

System Validation/Area Scan (101x101x1): Measurement grid: dx=10mm,

dy=10mm

Maximum value of SAR (interpolated) = 14.6 mW/g

System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm,

dy=5mm, dz=5mm

Reference Value = 87.2 V/m; Power Drift = -0.1 dB

Peak SAR (extrapolated) = 19.4 W/kg

SAR(1 g) = 13.21 mW/g; SAR(10 g) = 6.08 mW/g

Maximum value of SAR (measured) = 14.7 mW/g

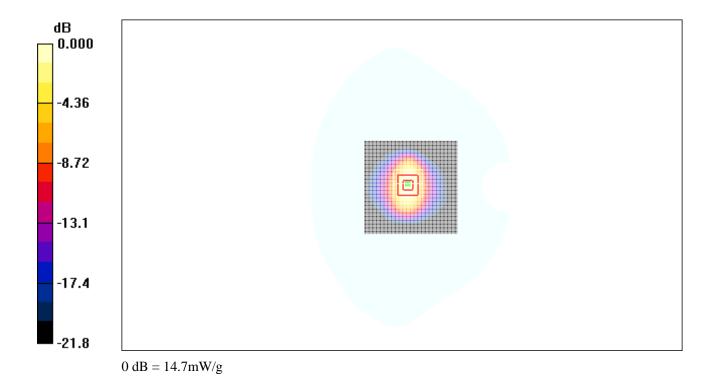
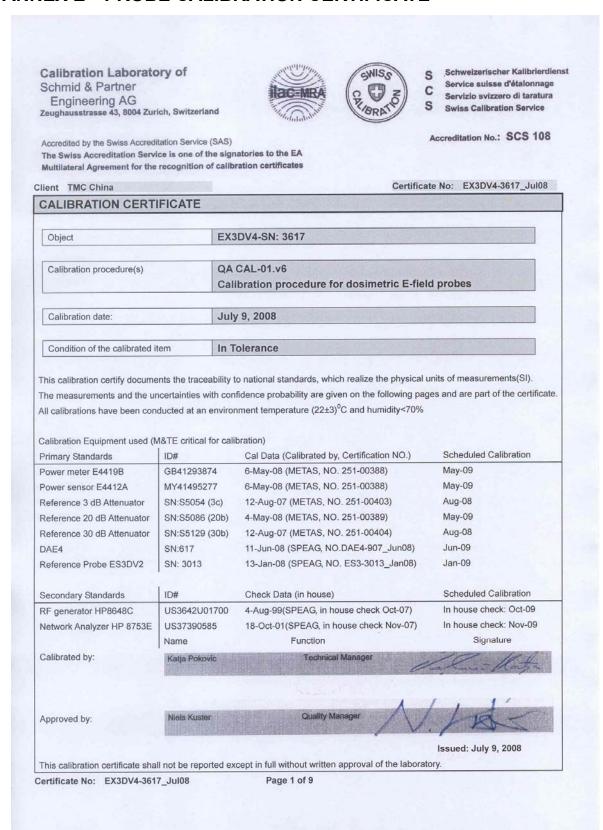


Fig.2 validation 2450MHz 250mW



# ANNEX E PROBE CALIBRATION CERTIFICATE





Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
Service sulsse d'étalonnage
Servizio svizzero di taratura
S Swiss Calibration Service

Accreditation No.: SCS 108

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

#### Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConF sensitivity in TSL / NORMx,y,z
DCP diode compression point
Polarization 

### protection of tissue simulating liquid
sensitivity in free space
diode compression point

### protection of tissue simulating liquid

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at

measurement center), i.e., 9 = 0 is normal to probe axis

# Calibration is Performed According to the Following Standards:

 a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003

 EC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

#### Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart). This
  linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of
  the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.



July 9, 2008

# **Probe EX3DV4**

SN: 3617

Manufactured:

May 3, 2007

Calibrated:

July 9, 2008

Calibrated for DASY4 System

Certificate No: EX3DV4-3617\_Jul08

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#### DASY - Parameters of Probe: EX3DV4 SN:3617

Sensitivity in Free Space<sup>A</sup>

Diode Compression<sup>B</sup>

NormX	0.420±10.1%	$\mu V/(V/m)^2$	DCP X	89mV
NormY	0.440±10.1%	$\mu V/(V/m)^2$	DCP Y	88mV
NormZ	0.310±10.1%	$\mu V/(V/m)^2$	DCP Z	91mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors) Please see Page 8

**Boundary Effect** 

Typical SAR gradient: 11% per mm TSL 2450MHz

Sensor Center to	o Phantom Surface Distance	2.0 mm	3.0 mm
SARbe[%]	Without Correction Algorithm	3.7	1.8
SARbe[%]	With Correction Algorithm	0.1	0.0

TSL 5200MHz Typical SAR gradient: 25% per mm

Sensor Center t	2.0 mm	3.0 mm	
SARbe[%]	Without Correction Algorithm	10.1	3.7
SARbe[%]	With Correction Algorithm	0.2	0.1

Sensor Offset

Probe Tip to Sensor Center

1.0 mm

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2,which for a normal distributio Corresponds to a coverage probability of approximately 95%.

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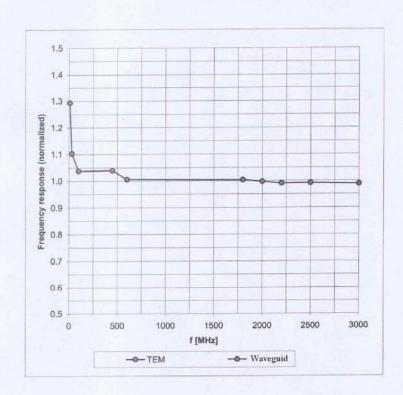
<sup>&</sup>lt;sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

<sup>B</sup> Numerical linearization parameter: uncertainty not required.



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# Frequency Response of E-Field



Uncertainty of Frequency Response of E-field: ±6.3% (k=2)

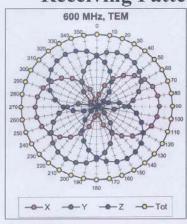
Certificate No: EX3DV4-3617\_Jul08

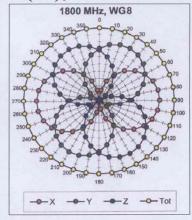
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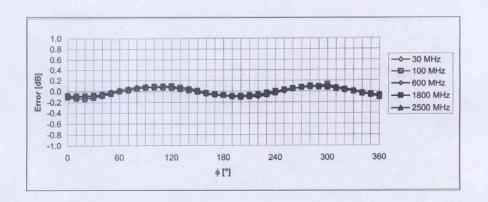


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Receiving Pattern ( $\phi$ ),  $\theta = 0^{\circ}$ 







Uncertainty of Axial Isotropy Assessment: ±0.5% (k=2)

Certificate No: EX3DV4-3617\_Jul08

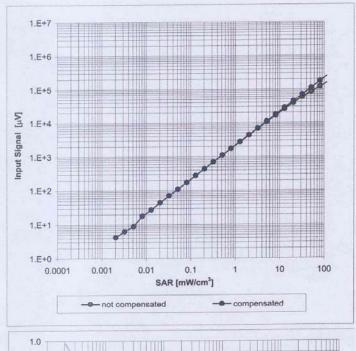
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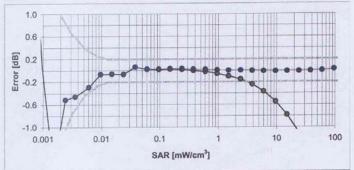


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# Dynamic Range f(SAR<sub>head</sub>)

(Waveguide: WG8, f = 1800 MHz)





Uncertainty of Linearity Assessment: ±0.6% (k=2)

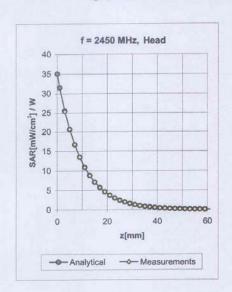
Certificate No: EX3DV4-3617\_Jul08

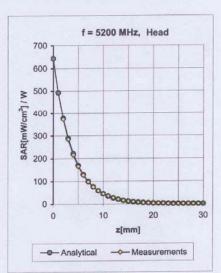
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# **Conversion Factor Assessment**





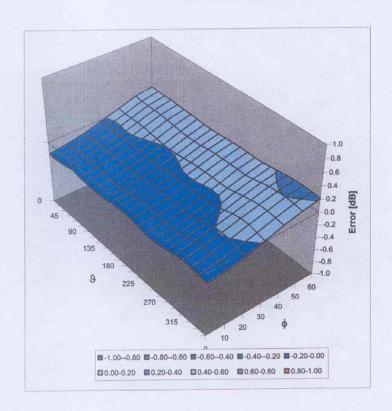
f[MHz]	Validity[MHz]C	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF	Uncertainty
2450	±50/±100	Head	39.2±5%	1.80±5%	0.33	1.00	7.19	±11.8% (k=2)
2600	±50/±100	Head	39.0±5%	1.96±5%	0.36	1.21	7.16	$\pm 11.8\%$ (k=2)
5200	$\pm 50 / \pm 100$	Head	36.0±5%	4.66±5%	0.35	1.60	5.33	±13.1% (k=2)
5800	±50/±100	Head	35.3±5%	5.27±5%	0.35	1.60	4.69	±13.1% (k=2)
2450	±50/±100	Body	52.7±5%	1.95±5%	0.36	1.00	6.88	±11.8% (k=2)
2600	±50/±100	Body	52.5±5%	2.16±5%	0.36	1.05	6.84	$\pm 11.8\%$ (k=2)
5200	±50/±100	Body	49.0±5%	5.30±5%	0.35	1.70	4.64	±13.1% (k=2)
5800	±50/±100	Body	48.2±5%	6.00±5%	0.30	1.70	4.53	±13.1% (k=2)

 $<sup>^{\</sup>circ}$  The validity of  $\pm 100$  MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.



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# Deviation from Isotropy Error $(\phi, \theta)$ , f = 900 MHz



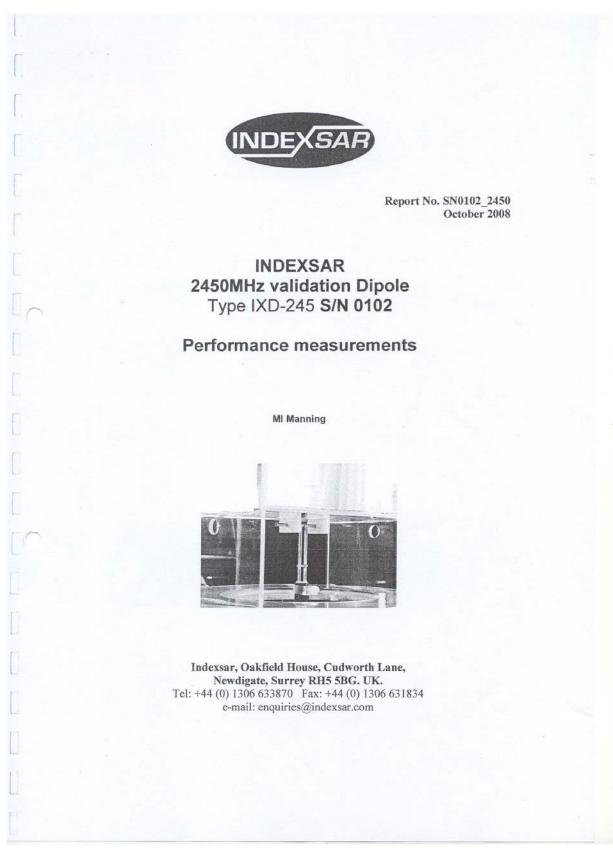
Uncertainty of Spherical Isotropy Assessment: ±2.6% (k=2)

Certificate No: EX3DV4-3617\_Jul08

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# ANNEX F DIPOLE CALIBRATION CERTIFICATE





#### 1. Measurement Conditions

Measurements were performed using a box-shaped phantom made of PMMA with dimensions designed to meet the accuracy criteria for reasonably-sized phantoms that do not have liquid capacities substantially in excess of the volume of liquid required to fill the Indexsar upright SAM phantoms used for SAR testing of handsets against the ear.

An HP 8753B vector network analyser was used for the return loss measurements. The dipole was placed in a special holder made of low-permittivity, low-loss materials. This holder enables the dipole to be positioned accurately in the centre of the base of the Indexsar box-phantom used for flat-surface testing and validation checks.

The validation dipoles are supplied with special spacers made from a low-permittivity, low-loss foam material. These spacers are fitted to the dipole arms to ensure that, when the dipole is offered up to the phantom surface, the spacing between the dipole and the liquid surface is accurately aligned according to the guidance in the relevant standards documentation. The spacers are rectangular with a central hole equal to the dipole arm diameter and dimensioned so that the longer side can be used to ensure a spacing of 15mm from the liquid in the phantom (for tests at 900MHz and below) and the shorter side can be used for tests at 1800MHz and above to ensure a spacing of 10mm from the liquid in the phantom. The spacers are made on a CNC milling machine with an accuracy of 1/40th mm but they may suffer wear and tear and need to be replaced periodically. The material used is Rohacell, which has a relative permittivity of approx. 1.05 and a negligible loss tangent.

The apparatus supplied by Indexsar for dipole validation tests thus includes:

Balanced dipoles for each frequency required are dimensioned according to the guidelines given in IEEE 1528 [1]. The dipoles are made from semi-rigid 50 Ohm co-ax, which is joined by soldering and is gold-plated subsequently. The constructed dipoles are easily deformed, if mis-handled, and periodic checks need to be made of their symmetry.

Rohacell foam spacers designed for presenting the dipoles to 2mm thick PMMA box phantoms. These components also suffer wear and tear and should be replaced when the central hole is a loose-fit on the dipole arms or if the edges are too worn to ensure accurate alignment. The standard spacers are dimensioned for use with 2mm wall thickness (additional spacers are available for 4mm wall thickness).



#### 2. Typical SAR Measurement

A SAR validation check is performed with the box-phantom located on the SARA2 phantom support base on the SARA2 robot system. Tests are then conducted at a feed power level of approx. 0.25 W. The actual power level is recorded and used to normalise the results obtained to the standard input power conditions of  $1\,W$  (forward power). The ambient temperature is  $22^{\circ}C$  +/-  $1^{\circ}C$  and the relative humidity is around 40% during the measurements.

The phantom is filled with a 2450MHz brain liquid using a recipe from [1], which has the following electrical parameters (measured using an Indexsar DiLine kit) at 2450MHz:

Relative Permittivity

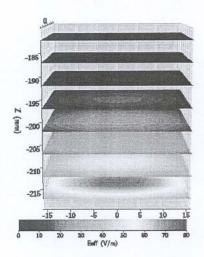
40.5

Conductivity

1.85 S/m

The SARA2 software version 2.2 VPM is used with an Indexsar probe previously calibrated using waveguides.

The 3D measurements made using the dipole at the bottom of the phantom box is shown below:



The results, normalised to an input power of 1W (forward power) are typically:

Averaged over 1 cm3 (1g) of tissue

52.26 W/kg

Averaged over 10cm3 (10g) of tissue 23.65 W/kg

These results can be compared with Table 8.1 in [1]. The agreement is within 10%.



#### 4. Dipole handling

The dipoles are made from standard, copper-sheathed coaxial cable. In assembly, the sections are joined using ordinary soft-soldering. This is necessary to avoid excessive heat input in manufacture, which would destroy the polythene dielectric used for the cable. The consequence of the construction material and the assembly technique is that the dipoles are fragile and can be deformed by rough handling. Conversely, they can be straightened quite easily as described in this report.

If a dipole is suspected of being deformed, a normal workshop lathe can be used as an alignment jig to restore the symmetry. To do this, the dipole is first placed in the headstock of the lathe (centred on the plastic or brass spacers) and the headstock is rotated by hand (do NOT use the motor). A marker (lathe tool or similar) is brought up close to the end of one dipole arm and then the headstock is rotated by 0.5 rev. to check the opposing arm. If they are not balanced, judicious deformation of the arms can be used to restore the symmetry.

If a dipole has a failed solder joint, the dipole can be fixed down in such a way that the arms are co-linear and the joint re-soldered with a reasonably-powerful electrical soldering iron. Do not use gas soldering irons. After such a repair, electrical tests must be performed as described below.

Please note that, because of their construction, the dipoles are short-circuited for DC signals.

#### 5. Tuning the dipole

The dipole dimensions are based on calculations that assumed specific liquid dielectric properties. If the liquid dielectric properties are somewhat different, the dipole tuning will also vary. A pragmatic way of accounting for variations in liquid properties is to 'tune' the dipole (by applying minor variations to its effective length). For this purpose, Indexsar can supply short brass tube lengths to extend the length of the dipole and thus 'tune' the dipole. It cannot be made shorter without removing a bit from the arm. An alternative way to tune the dipole is to use copper shielding tape to extend the effective length of the dipole. Do both arms equally.

It should be possible to tune a dipole as described, whilst in place in the measurement position as long as the user has access to a VNA for determining the return loss.

#### 6. References

[1] Draft recommended practice for determining the peak spatial-average specific absorption rate (SAR) in the human body due to wireless communications devices: Experimental Techniques.