# **SAR Test Report**

Report No.: AGC06283160201FH01

**FCC ID** : X9PSM9001

**APPLICATION PURPOSE**: Original Equipment

**PRODUCT DESIGNATION**: iphone Dual sim Card

**BRAND NAME** : N/A

MODEL NAME : SM9001

**CLIENT**: SHENZHEN PAOLUY TECHNOLOGY CO., LTD.

**DATE OF ISSUE** : Mar. 24,2016

IEEE Std. 1528:2013

**STANDARD(S)** : FCC 47CFR § 2.1093

IEEE/ANSI C95.1:1992

V1.0

REPORT VERSION :

Attestation of Global Compliance (Shenzhen) Co., Ltd.

### **CAUTION:**

This report shall not be reproduced except in full without the written permission of the test laboratory and shall not be quoted out of context.



Page 2 of 38

### **Report Revise Record**

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	1	Mar. 24,2016	Valid	Original Report

Page 3 of 38

Test Report Certification		
Applicant Name	SHENZHEN PAOLUY TECHNOLOGY CO., LTD.	
Applicant Address	No.31, Furong Road, Gushu Village Xixiang Town, Baoan District, Shenzhen, China	
Manufacturer Name	SHENZHEN PAOLUY TECHNOLOGY CO., LTD.	
Manufacturer Address	No.31, Furong Road, Gushu Village Xixiang Town, Baoan District, Shenzhen, China	
Product Designation	iphone Dual sim Card	
Brand Name	N/A	
Model Name	SM9001	
Different Description	N/A	
EUT Voltage	DC3.7V by battery	
Applicable Standard	IEEE Std. 1528:2013 FCC 47CFR § 2.1093 IEEE/ANSI C95.1:1992	
Test Date	Mar. 19,2016 to Mar. 22,2016	
	Attestation of Global Compliance(Shenzhen) Co., Ltd.	
Performed Location	2 F, Building 2, No.1-No.4, Chaxi Sanwei Technical Industrial Park, Gushu, Xixiang Street, Bao'an District, Shenzhen, China	
Report Template	AGCRT-US-2.5G/SAR (2016-01-01)	

	Dolly Wang	
Tested By	Bobby wang(Wang Zhicheng)	Mar. 24,2016
	Angels li	
Checked By	Angela Li(Li Jiao)	Mar. 24,2016
Authorized By	gelyn zhong	
Admonzed by	Solger Zhang(Zhang Hongyi) Authorized Officer	Mar. 24,2016

Page 4 of 38

### **TABLE OF CONTENTS**

1. SUMMARY OF MAXIMUM SAR VALUE	5
2. GENERAL INFORMATION	6
2.1. EUT DESCRIPTION	6
3. SAR MEASUREMENT SYSTEM	7
3.1. THE DASY5 SYSTEM USED FOR PERFORMING COMPLIANCE TESTS CONSISTS OF FOLLOWING ITEMS	
3.3. DATA ACQUISITION ELECTRONICS DESCRIPTION	8
3.4. ROBOT	_
3.6. Device Holder	10
3.7. MEASUREMENT SERVER	
4. SAR MEASUREMENT PROCEDURE	
4.1. SPECIFIC ABSORPTION RATE (SAR)	
4.2. SAR MEASUREMENT PROCEDURE	
4.3. RF Exposure Conditions	
5. TISSUE SIMULATING LIQUID	16
5.1. THE COMPOSITION OF THE TISSUE SIMULATING LIQUID	
5.2. TISSUE DIELECTRIC PARAMETERS FOR BODY PHANTOMS	
6. SAR SYSTEM CHECK PROCEDURE	
6.1. SAR SYSTEM CHECK PROCEDURES	
6.2. SAR SYSTEM CHECK	
7. EUT TEST POSITION	
7.4. Body Worn Position	
8. SAR EXPOSURE LIMITS	
9. TEST EQUIPMENT LIST	
10. MEASUREMENT UNCERTAINTY	
11. CONDUCTED POWER MEASUREMENT	27
12. TEST RESULTS	28
12.1. SAR TEST RESULTS SUMMARY	28
APPENDIX A. SAR SYSTEM CHECK DATA	32
APPENDIX B. SAR MEASUREMENT DATA	34
APPENDIX C. TEST SETUP PHOTOGRAPHS & EUT PHOTOGRAPHS	38
APPENDIX D. CALIBRATION DATA	38

Page 5 of 38

### 1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Frequency Band	Highest Reported 1g-SAR(W/Kg)  Body-worn(with 0mm separation)	SAR Test Limit (W/Kg)
GSM 850	1.079	
PCS 1900	1.195	1.6
Simultaneous Reported SAR	1.216	
SAR Test Result	PASS	

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6W/Kg) specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:1992 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 648474 D04 Handset SAR v01r03
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04
- KDB 941225 D01 3G SAR Procedures v03r01

Page 6 of 38

### 2. GENERAL INFORMATION

2.1. EUT Description	
General Information	
Product Designation	iphone Dual sim Card
Test Model	SM9001
Hardware Version	SM-9001_Ver 1.3
Software Version	4.0
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Internal
GSM	
Support Band	⊠GSM 850 ⊠PCS 1900 □GSM 900 □DCS 1800
TX Frequency Range	GSM 850 : 820-850MHz;; PCS 1900: 1850-1910MHz;
RX Frequency Range	GSM 850 : 869~894MHz; PCS 1900: 1930~1990MHz
Release Version	R99
Type of modulation	GMSK for GSM
Antenna Gain	1.0dBi
Max. Average Power (Max. Peak Power)	GSM850: 31.24dBm(32.43dBm) ;PCS1900: 28.29dBm(29.79dBm)
Bluetooth	
Bluetooth Version	□V2.0         □V2.1         □V2.1+EDR         □V3.0         □V3.0+HS         □V4.0
Operation Frequency	2402~2480MHz
Type of modulation	⊠GFSK □Π/4-DQPSK □8-DPSK
Mar.Peak Power	-3.30dBm
Antenna Gain	0.3dBi
Accessories	
Battery	Brand name: N/A Model No. : 284040P Voltage and Capacitance: 3.7 V & 500mAh
Note:1.CMU200 can meas	sure the average power and Peak power at the same time

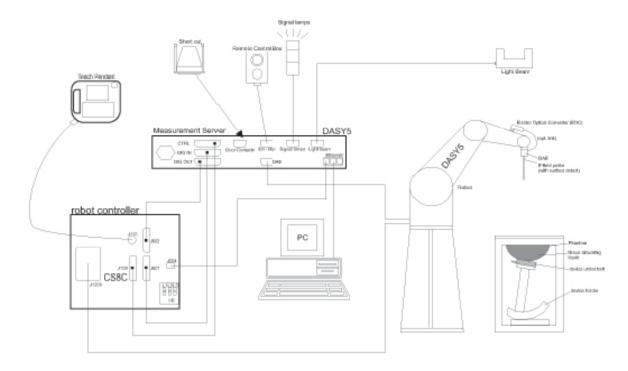
2. The sample used for testing is end product.

Product	Type	
Product		☐ Identical Prototype

Page 7 of 38

### 3. SAR MEASUREMENT SYSTEM

### 3.1. The DASY5 system used for performing compliance tests consists of following items



- A standard high precision 6-axis robot with controller, teach pendant and software.
- Data acquisition electronics (DAE) which attached to the robot arm extension. The DAE consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock
- A dosimetric probe equipped with an optical surface detector system.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital Communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- A Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- Phantoms, device holders and other accessories according to the targeted measurement.

Page 8 of 38

#### 3.2. DASY5 E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SPEAG. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528 and relevant KDB files.) The calibration data are in Appendix D.

### **Isotropic E-Field Probe Specification**

Model	ES3DV3		
Manufacture	SPEAG		
frequency	0.15GHz-3 GHz Linearity:±0.2dB(150 MHz-3 GHz)		
Dynamic Range	0.01W/Kg-100W/Kg Linearity:±0.2dB		
Dimensions	Overall length:337mm Tip diameter:4mm Typical distance from probe tip to dipole centers:2mm		
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 3 GHz with precision of better 30%.		

### 3.3. Data Acquisition Electronics description

The data acquisition electronics (DAE) consist if a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converte and a command decoder with a control logic unit. Transmission to the measurement sever is accomplished through an optical downlink fir data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

DAE4

Input Impedance	200MOhm	RESIDE.
The Inputs	Symmetrical and floating	S S S S S S S S S S S S S S S S S S S
Common mode rejection	above 80 dB	DAREA DAVE OF DE PROPERTO March Mr. S.

Page 9 of 38

### 3.4. Robot

The DASY system uses the high precision robots (DASY5:TX60) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from is used.

The XL robot series have many features that are important for our application:

High precision (repeatability 0.02 mm)

High reliability (industrial design)

Jerk-free straight movements

Low ELF interference (the closed metallic construction shields against motor control fields)

6-axis controller



### 3.5. Light Beam Unit

The light beam switch allows automatic "tooling" of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip.

The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned prob.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position. e, the same position will be reached with another aligned probe within 0



Page 10 of 38

### 3.6. Device Holder

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR).

Thus the device needs no repositioning when changing the angles. The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\epsilon$ =3 and loss tangent  $\delta$  = 0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



#### 3.7. Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chip-disk (DASY5: 128MB), RAM (DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DAYS I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.



Page 11 of 38

## 3.8. PHANTOM SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

Left head Right head Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

### **ELI4 Phantom**

Flat phantom a fiberglass shell flat phantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom



Page 12 of 38

### 4. SAR MEASUREMENT PROCEDURE

### 4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of given mass density ( $\rho$ ). The equation description is as below:

$$SAR = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg) SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \frac{dT}{dt} \Big|_{t=0}$$

Where

SAR is the specific absorption rate in watts per kilogram; E is the r.m.s. value of the electric field strength in the tissue in volts per meter; or is the conductivity of the tissue in siemens per metre; or is the density of the tissue in kilograms per cubic metre; or is the heat capacity of the tissue in joules per kilogram and Kelvin;

 $\frac{dT}{dt}$  | t=0 is the initial time derivative of temperature in the tissue in kelvins per second

Page 13 of 38

#### 4.2. SAR Measurement Procedure

#### Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance os sensor calibration points to probe tip as `defined in the probe properties,

### Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528 and IEC62209 standards, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 ± 1 mm	½·δ·ln(2) ± 0.5 mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30° ± 1°	20° ± 1°
	≤2 GHz: ≤15 mm 2 – 3 GHz: ≤12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
Maximum area scan spatial resolution: Δx <sub>Area</sub> , Δy <sub>Area</sub>	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

### Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g abd 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

Page 14 of 38

### Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan spatial resolution: Δx <sub>Zoom</sub> , Δy <sub>Zoom</sub>		≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*	
	uniform grid: Δz <sub>Zoom</sub> (n)		≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
Maximum zoom scan spatial resolution, normal to phantom surface	$\begin{array}{c} \Delta z_{Z00m}(1)\text{: between} \\ 1^{\text{st}} \text{ two points closest} \\ \text{to phantom surface} \\ \\ \Delta z_{Z00m}(n>1)\text{:} \\ \text{between subsequent} \\ \text{points} \end{array}$	1 <sup>st</sup> two points closest	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$		
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

### Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

<sup>\*</sup> When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

Page 15 of 38

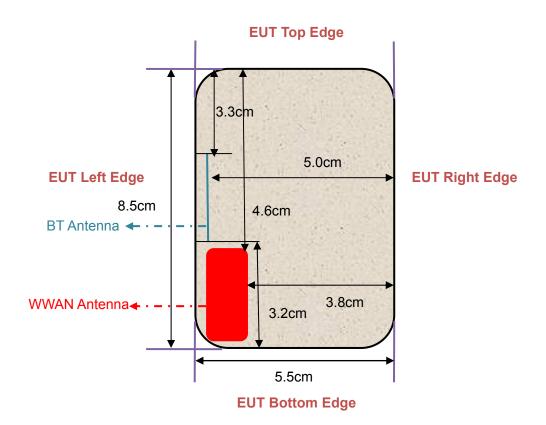
### 4.3. RF Exposure Conditions

Test Configuration and setting:

The EUT is a model of GSM Portable Mobile Station (MS). It supports GSM, BT.

For WWAN SAR testing, the device was controlled by using a base station emulator. Communication between the device and the emulator were established by air link. The distance between the EUT and the antenna is larger than 50cm, and the output power radiated from the emulator antenna is at least 30db smaller than the output power of EUT.

### **Antenna Location: (the front view)**



Page 16 of 38

### 5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 5.2

5.1. The composition of the tissue simulating liquid

Ingredients	850MHz	1900MHz
(% Weight)	Body	Body
Water	52.5%	40.4%
Sugar	45%	58%
HEC	1%	1%
Bactericide	0.1%	0.1%
NaCI	1.4%	0.5%
TOTAL	100.0%	100.0%

### 5.2. Tissue Dielectric Parameters for Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in IEEE 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in IEEE 1528

Target Frequency	body				
(MHz)	εr	σ (S/m)			
300	58.2	0.92			
450	56.7	0.94			
835	55.2	0.97			
900	55.0	1.05			
915	55.0	1.06			
1450	54.0	1.30			
1610	53.8	1.40			
1800 – 2000	53.3	1.52			
2450	52.7	1.95			
3000	52.0	2.73			
5800	48.2	6.00			

( $\varepsilon r = relative permittivity$ ,  $\sigma = conductivity and <math>\rho = 1000 \text{ kg/m}3$ )

Page 17 of 38

### 5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using DASY5 Dielectric Probe Kit and R&S Network Analyzer ZVL6.

	Tissue Stimulant Measurement for 835MHz							
	Fr.	Dielectric Parameters (±5%)		Tissue				
	(MHz)	er 55.20(52.44-57-96)	δ[s/m]0.97(0.9215-1.0185)	Temp [°C]	Test time			
	824.2	56.08	0.94					
Body	826.4	56.01	0.96					
	835	55.74	0.97	20.2	Mar. 19,2016			
	836.6	55.36	0.98	20.2	IVIAI. 19,2010			
	846.6	56.08	0.94					
	848.8	56.01	0.96					

Tissue Stimulant Measurement for 1900MHz							
	Fr.	Dielectric Par	Dielectric Parameters (±5%)				
	(MHz)	εr53.30(50.635-55.965)	δ[s/m]1.52(1.444-1.596)	Temp [°C]	Test time		
	1850.2	54.36	1.47				
Body	1852.4	54.00	1.50				
	1880	53.98	1.52	22.0	Mar. 22,2016		
	1900	53.32	1.53	22.0	IVIAI. 22,2010		
	1907.6	54.36	1.47				
	1909.8	54.00	1.50				

Page 18 of 38

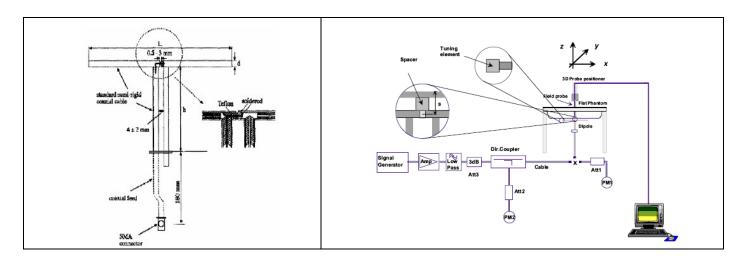
### 6. SAR SYSTEM CHECK PROCEDURE

### 6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each DASY system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

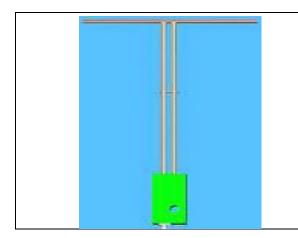
The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.



Page 19 of 38

### 6.2. SAR System Check

### 6.2.1. Dipoles



The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. the table below provides details for the mechanical and electrical Specifications for the dipoles.

Frequency	L (mm)	h (mm)	d (mm)
835MHz	161.0	89.8	3.6
1900MHz	68	39.5	3.6

Page 20 of 38

### 6.2.2. System Check Result

System Performance Check at 835 MHz & 1900MHz for Body								
Validation Kit: SN 30/14 DIP 0G835-332 & SN 46/11DIP 1G900-187								
Frequency		get (W/Kg)	Reference Result (± 10%)		Tested Value(W/Kg)		Tissue Temp.	Test time
[MHz]	1g	10g	1g	10g	1g	10g	[°C]	
835	9.93	6.35	8.937-10.923	5.715-6.985	9.921	6.244	20.2	Mar. 19,2016
1900	40.74	21.43	36.666-44.814	19.287-23.573	39.939	21.238	22.0	Mar. 22,2016

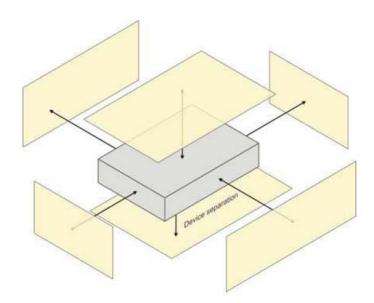
Page 21 of 38

### 7. EUT TEST POSITION

This EUT was tested in **Body back and Body front and 4 edges**.

### 7.4. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **0mm**.



Page 22 of 38

### 8. SAR EXPOSURE LIMITS

SAR assessments have been made in line with the requirements of IEEE-1528, and comply with ANSI/IEEE C95.1-1992 "Uncontrolled Environments" limits. These limits apply to a location which is deemed as "Uncontrolled Environment" which can be described as a situation where the general public may be exposed to an RF source with no prior knowledge or control over their exposure.

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

Page 23 of 38

### 9. TEST EQUIPMENT LIST

9. ILSI EQUIFINE	Manufacturer/		Current	Next calibration
Equipment description	Model	Identification No.	calibration date	date
Stäubli Robot	Stäubli-TX60	F13/5Q2UD1/A/01	N/A	N/A
Robot Controller	Stäubli-CS8	139522	N/A	N/A
TISSUE Probe	SATIMO	SN 45/11 OCPG45	12/02/2015	12/01/2016
E-Field Probe	Speag- ES3DV3	SN:3337	10/01/2015	09/30/2016
SAM Twin Phantom	Speag-SAM	1790	N/A	N/A
Device Holder	Speag-SD 000 H01 KA	SD 000 H01 KA	N/A	N/A
DAE4	Speag-SD 000 D04 BM	1398	02/02/2016	02/01/2017
SAR Software	Speag-DASY5	DASY52.8	N/A	N/A
Liquid	SATIMO	-	N/A	N/A
Radio Communication Tester	R&S-CMU200	069Y7-158-13-712	03/04/2016	03/03/2017
Dipole	SATIMO SID835	SN30/14 DIP 0G835-332	09/01/2014	08/31/2017
Dipole	SATIMO SID1900	SN46/11 DIP 1G900-187	11/14/2013	11/13/2016
Signal Generator	Agilent-E4438C	MY44260051	03/04/2016	03/03/2017
Spectrum Analyzer E4440	Agilent	US41421290	07/23/2015	07/22/2016
Network Analyzer	Rhode & Schwarz ZVL6	SN100132	03/04/2016	03/03/2017
Attenuator	Warison /WATT-6SR1211	N/A	N/A	N/A
Attenuator	Mini-circuits / VAT-10+	N/A	N/A	N/A
Amplifier	EM30180	SN060552	03/04/2016	03/03/2017
Directional Couple	Werlatone/ C5571-10	SN99463	07/29/2015	07/28/2016
Directional Couple	Werlatone/ C6026-10	SN99482	07/29/2015	07/28/2016
Power Sensor	NRP-Z21	1137.6000.02	10/20/2015	10/19/2016
Power Sensor	NRP-Z23	US38261498	03/04/2016	03/03/2017
Power Viewer	R&S	V2.3.1.0	N/A	N/A

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

- 1. There is no physical damage on the dipole;
- 2. System validation with specific dipole is within 10% of calibrated value;
- 3. Return-loss is within 20% of calibrated measurement;
- 4. Impedance is within  $5\Omega$  of calibrated measurement.

Page 24 of 38

### 10. MEASUREMENT UNCERTAINTY

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type An evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table as follow.

Uncertainty Distributions	Normal	Rectangular	Triangular	U-Shape
Multi-plying Factor(a)	1/k(b)	1/√3	1/√6	1/√2

- (a) Standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
- (b)  $\kappa$  is the coverage factor

#### **Table 13.1 Standard Uncertainty for Assumed Distribution (above table)**

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following tables.

Page 25 of 38

DAYS5 Measurement Uncertainty							
Measurement		r 150 MHz to 3			er 1 gra	m / 10 gram.	
Error Description	Uncertainty value(±10%	Probability Distribution	Divisor	(Ci) 1g	(Ci) 10g	Standard Uncertainty (1g)	Standard Uncertainty (10g)
Measurement System							
Probe Calibration	6.3	Normal	1	1	1	6.3	6.3
Axial Isotropy	0.5	Rectangular	$\sqrt{3}$	1	1	0.29	0.29
Hemispherical Isotropy	2.6	Rectangular	$\sqrt{3}$	1	1	1.50	1.50
Linearity	0.6	Rectangular	$\sqrt{3}$	1	1	0.35	0.35
Probe Modulation Response	3.3	Rectangular	$\sqrt{3}$	1	1	1.91	1.91
System Detection Limits	0.9	Rectangular	$\sqrt{3}$	1	1	0.52	0.52
Boundary Effects	0.9	Rectangular	$\sqrt{3}$	0	0	0	0
Readout Electronics	0.2	Normal	$\sqrt{3}$	1	1	0.12	0.12
Response Time	0	Rectangular	$\sqrt{3}$	1	1	0	0
Integration Time	0	Rectangular	$\sqrt{3}$	1	1	0	0
RF Ambient Noise	0.9	Rectangular	$\sqrt{3}$	1	1	0.52	0.52
RF Ambient Reflection	0.9	Rectangular	$\sqrt{3}$	1	1	0.52	0.52
Probe Positioner	0.7	Rectangular	$\sqrt{3}$	1	1	0.40	0.40
Probe Positioning	6.5	Rectangular	$\sqrt{3}$	1	1	3.75	3.75
Post-processing	3.8	Rectangular	$\sqrt{3}$	1	1	2.19	2.19
Test Sample Related							
Device Positioning	3.6	Normal	1	1	1	3.6	3.6
Device Holder	2.9	Normal	1	1	1	2.9	2.9
Measurement SAR Drift	5.0	Rectangular	$\sqrt{3}$	1	1	2.89	2.89
Power Scaling	0.0	Rectangular	$\sqrt{3}$	1	1	0	0
Phantom and Setup							
Phantom Uncertainty	3.9	Rectangular	$\sqrt{3}$	1	1	2.25	2.25
Liquid Conductivity(Meas.)	2.4	Normal	1	0.78	0.71	1.87	1.70
Liquid Conductivity(Target)	4.9	Rectangular	$\sqrt{3}$	0.64	0.43	1.81	1.22
Liquid Permittivity(Meas.)	2.4	Normal	1	0.26	0.26	0.62	0.62
Liquid Permittivity((Target)	4.9	Rectangular	$\sqrt{3}$	0.6	0.49	1.70	1.39
Liquid Conductivity-temperature uncertainty	1.6	Rectangular	$\sqrt{3}$	0.78	0.71	0.72	0.66
Liquid Permittivity-temperature uncertainty	0.2	Rectangular	$\sqrt{3}$	0.23	0.26	0.03	0.03
Combined Standard Uncerta	10.26	10.143					
Coverage Factor for 95%					K=		
Expanded Uncertainty	±20.52%	±20.29%					

Page 26 of 38

DAYS5 S	system Che	eck Uncertainty	for 150	) MHz to	3GHz a	veraged ran	ge	
Error Description	Uncer. value (±10%)	Prob. Dist.	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	(v <sub>i</sub> ) V <sub>eff</sub>
Measurement System								
Probe Calibration	6.3	Normal	1	1	1	6.3	6.3	8
Axial Isotropy	0.5	Rectangular	$\sqrt{3}$	1	1	0.29	0.29	8
Hemispherical Isotropy	2.6	Rectangular	$\sqrt{3}$	1	1	1.50	1.50	8
Boundary Effects	0.9	Rectangular	$\sqrt{3}$	0	0	0.00	0.00	8
Linearity	0.6	Rectangular	$\sqrt{3}$	1	1	0.35	0.35	8
System Detection Limits	0.9	Rectangular	$\sqrt{3}$	1	1	0.52	0.52	8
Modulation Response	3.3	Rectangular	$\sqrt{3}$	1	1	1.91	1.91	8
Readout Electronics	0.2	Normal	1	1	1	0.2	0.2	∞
Response Time	0	Rectangular	$\sqrt{3}$	1	1	0	0	8
Integration Time	0	Rectangular	$\sqrt{3}$	1	1	0	0	8
RF Ambient Noise	0.9	Rectangular	$\sqrt{3}$	1	1	0.52	0.52	8
RF Ambient Reflection	0.9	Rectangular	$\sqrt{3}$	1	1	0.52	0.52	8
Probe Positioner	0.7	Rectangular	$\sqrt{3}$	1	1	0.402	0.402	∞
Probe Positioning	6.5	Rectangular	$\sqrt{3}$	1	1	3.752	3.752	8
Max. SAR Eval.	1.9	Rectangular	$\sqrt{3}$	1	1	1.10	1.10	8
Dipole Related								
Deviation of exp. dipole	5.3	Rectangular	$\sqrt{3}$	1	1	3.06	3.06	∞
Dipole Axis to Liquid Dist.	2.0	Rectangular	$\sqrt{3}$	1	1	1.15	1.15	8
Input power & SAR drift	3.3	Rectangular	$\sqrt{3}$	1	1	1.91	1.91	8
Phantom and Setup								
Phantom Uncertainty	3.9	Rectangular	$\sqrt{3}$	1	1	2.25	2.25	8
SAR correction	1.8	Rectangular	$\sqrt{3}$	1	0.84	1.04	0.87	8
Liquid Conductivity(Meas.)	2.4	Normal	1	0.78	0.71	1.87	1.70	8
Liquid Permittivity(Meas.)	2.4	Normal	1	0.26	0.26	0.62	0.62	8
Temp. unc Conductivity	1.6	Rectangular	$\sqrt{3}$	0.78	0.71	0.72	0.66	8
Temp. unc Permittivity	0.2	Rectangular	$\sqrt{3}$	0.23	0.26	0.03	0.03	8
Combined Std. Uncertainty		-				9.22	9.15	
Expanded STD Uncertainty						±18.44%	±18.3%	

Page 27 of 38

### 11. CONDUCTED POWER MEASUREMENT

### **GSM BAND**

Mode	Frequency(MHz)	Avg. Burst Power(dBm)	Duty cycle Factor(dBm)	Frame Power(dBm)
	824.2	31.24	-9	22.24
GSM 850	836.6	31.16	-9	22.16
	848.8	31.11	-9	22.11
	1850.2	28.29	-9	19.29
PCS1900	1880	28.22	-9	19.22
	1909.8	28.21	-9	19.21

Note 1:

The Frame Power (Source-based time-averaged Power) is scaled the maximum burst average power based on time slots. The calculated methods are show as following:

Frame Power = Max burst power (1 Up Slot) – 9 dB

### Bluetooth V4.0

Bidotootii_1110			
Modulation	Channel	Frequency(MHz)	Peak Power (dBm)
	0	2402	-3.60
GFSK	19	2440	-3.30
	39	2480	-3.68

Page 28 of 38

### 12. TEST RESULTS

### 12.1. SAR Test Results Summary

### 12.1.1. Test position and configuration

Body SAR was performed with the device 0mm from the phantom.

#### 12.1.2. Operation Mode

- 1. Per KDB 447498 D01 v06 ,for each exposure position, if the highest 1-g SAR is  $\leq$  0.8 W/kg, testing for low and high channel is optional.
- 2. Per KDB 865664 D01 v01r04,for each frequency band, if the measured SAR is ≥0.8W/Kg, testing for repeated SAR measurement is required, that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.
  - (1) When the original highest measured SAR is  $\geq$ 0.8W/Kg, repeat that measurement once.
  - (2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is >1.20 or when the original or repeated measurement is ≥1.45 W/Kg.
  - (3) Perform a third repeated measurement only if the original, first and second repeated measurement is  $\geq$ 1.5 W/Kg and ratio of largest to smallest SAR for the original, first and second measurement is  $\geq$  1.20.
- 3. Body-worn exposure conditions are intended to voice call operations, therefore GSM voice call mode is selected to be test.
- 4. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:
  - Maximum Scaling SAR =tested SAR (Max.)  $\times$  [maximum turn-up power (mw)/ maximum measurement output power(mw)]

Page 29 of 38

### 12.1.3. Test Result

SAR MEASUREMENT									
Depth of Liquid (cm):>15 Relative Humidity (%): 55.4									
Product: iphone Dual sim Card									
Test Mode: GSM850 with GMSK modulation									
Position Mode Ch. Fr. (MHz) Power Ct. (MHz) Power Ct. (MHz) Power Ct. (MHz) Rower Ct. (MHz) Ro								Limit (W/kg)	
Body back	voice	128	824.2	0.15	0.726	31.5	31.24	0.771	1.6
Body back	voice	190	836.6	0.12	0.901	31.5	31.16	0.974	1.6
Body back	voice	251	848.8	0.16	0.986	31.5	31.11	1.079	1.6
Body front	voice	190	836.6	-0.03	0.310	31.5	31.16	0.335	1.6
Edge 1 (Top)	voice	190	836.6	0.08	0.048	31.5	31.16	0.052	1.6
Edge 2(Right)	voice	190	836.6	0.13	0.054	31.5	31.16	0.058	1.6
Edge 3(Bottom)	voice	190	836.6	-0.05	0.138	31.5	31.16	0.149	1.6
Edge 4(Left)	voice	190	836.6	0.14	0.343	31.5	31.16	0.371	1.6

Note:

<sup>•</sup>The test separation for body is 0mm of all above table.

SAR MEASUREMENT									
Depth of Liquid (cm):>15 Relative Humidity (%): 56.3									
Product: iphone Dual sim Card									
Test Mode: PCS1900 with GMSK modulation									
Position   Mode   Ch     Dritt   (1a)   - 1   Power   SAR									Limit (W/kg)
Body back	voice	512	1850.2	0.09	1.00	28.5	28.29	1.050	1.6
Body back	voice	661	1880.0	0.04	1.12	28.5	28.22	1.195	1.6
Body back	voice	810	1909.8	0.07	0.925	28.5	28.21	0.989	1.6
Body front	voice	661	1880.0	0.03	0.417	28.5	28.22	0.445	1.6
Edge 1 (Top)	voice	661	1880.0	-0.08	0.194	28.5	28.22	0.207	1.6
Edge 2(Right)	voice	661	1880.0	0.09	0.073	28.5	28.22	0.078	1.6
Edge 3(Bottom)	voice	661	1880.0	-0.06	0.295	28.5	28.22	0.315	1.6
Edge 4(Left)	voice	661	1880.0	0.07	0.587	28.5	28.22	0.626	1.6

Note:

<sup>·</sup> When the 1-g Reported SAR is ≤ 0.8 W/kg, testing for low and high channel is optional. Refer to KDB 447498.

<sup>·</sup> When the 1-g Reported SAR is ≤ 0.8 W/kg, testing for low and high channel is optional. Refer to KDB 447498.

<sup>•</sup>The test separation for body is 0mm of all above table.

Page 30 of 38

#### **Simultaneous Multi-band Transmission Evaluation:**

NO	Simultaneous state	Portable Handset
	Simultaneous state	Body-worn
2	GSM(voice)+Bluetooth(data)	Yes

### NOTE:

- 1. There is only BT antenna.
- 2. For simultaneous transmission at head and body exposure position, 2 transmitters simultaneous transmission was the worst state.
- 3. Based upon KDB 447498 D01, BT SAR is excluded as below table.
- 4. Based upon KDB 447498 D01, for handsets the test separation distance is determined by the smallest distance between the outer surface of the device and the user; which is 0mm for body-worn SAR.
- 5. According to KDB 447498 D01 4.3.1, Standalone SAR test exclusion is as follow: For 100 MHz to 6 GHz and test separation distances ≤ 50 mm, the 1-g and 10-g SAR test exclusion thresholds are determined by the following:

[(max. power of channel, including tune-up tolerance, mW) / (min. test separation distance, mm)] • [ $\sqrt{f(GHz)}$ ]  $\leq 3.0$  for 1-g SAR, and  $\leq 7.5$  for 10-g extremity SAR, where

- f(GHz) is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation<sup>31</sup>
- The result is rounded to one decimal place for comparison
- The values 3.0 and 7.5 are referred to as numeric thresholds in step b) below

The test exclusions are applicable only when the minimum test separation distance is  $\leq$  50 mm, and for transmission frequencies between 100 MHz and 6 GHz. When the minimum test separation distance is  $\leq$  5 mm, a distance of 5 mm according to 4.1 f) is applied to determine SAR test exclusion.

- 6. If the test separation distance is <5mm, 5mm is used for excluded SAR calculation.
- 7. According to KDB 447498 D01 4.3.2, simultaneous transmission SAR test exclusion is as follow:
  - (1) Simultaneous transmission SAR test exclusion is determined for each operating configuration and exposure condition according to the reported standalone SAR of each applicable simultaneous transmitting antenna.
  - (2) Any transmitters and antennas should be considered when calculating simultaneous mode.
  - (3) For mobile phone and PC, it's the sum of all transmitters and antennas at the same mode with same position in each applicable exposure condition
  - (4) When the standalone SAR test exclusion of section 4.3.2 is applied to an antenna that transmits simultaneously with other antennas, the standalone SAR must be estimated according to the following to det
    - (max. power of channel, including tune-up tolerance, mW)/(min. test separation distance, mm)]·[ $\sqrt{f(GHz)/x}$ ] W/kg for test separation distances  $\leq$  50 mm; where x = 7.5 for 1-g SAR, and x = 18.75 for 10-g SAR.
- 8. When the sum of SAR is larger than the limit, SAR test exclusion is determined by the SAR to peak location separation ratio. The simultaneous transmitting antennas in each operating mode and exposure condition combination must be considered one pair at a time to determine the SAR to peak location separation ratio to qualify for test exclusion. The ratio is determined by (SAR1 + SAR2)1.5/Ri, rounded to two decimal digits, and must be ≤ 0.04 for all antenna pairs in the configuration to qualify for 1-g SAR test exclusion.

Page 31 of 38

Estimated SAR			luding Tune-up ance	Separation Distance (mm)	Estimated SAR (W/kg)	
		dBm	mW	Distance (IIIII)		
BT Body		-3	0.501	0	0.0209	

Maximum test results (WWAN) with BT SAR:

BT: Body (0cm gap): 0.0209 W/kg

### Sum of the SAR for GSM 850 & BT:

RF Exposure	Test Position	Simultaneo	us Transmission Scenario	Σ1-g SAR	SPLSR (Yes/No)
Conditions		GSM 850	Bluetooth	(W/Kg)	
Body-worn (Voice)	Rear	1.079	0.0209	1.100	No
	Front	0.335	0.0209	0.356	No
	Edge 1	0.052	0.0209	0.073	No
	Edge 2	0.058	0.0209	0.079	No
	Edge 3	0.149	0.0209	0.170	No
	Edge 4	0.371	0.0209	0.392	No

#### Sum of the SAR for GSM 1900 &Wi-Fi & BT:

RF Exposure	Test Position	Simultaneo	us Transmission Scenario	Σ1-g SAR	SPLSR (Yes/No)
Conditions		GSM 1900	Bluetooth	(W/Kg)	
Body-worn (Voice)	Rear	1.195	0.0209	1.216	No
	Front	0.445	0.0209	0.466	No
	Edge 1	0.207	0.0209	0.228	No
	Edge 2	0.078	0.0209	0.099	No
	Edge 3	0.315	0.0209	0.336	No
	Edge 4	0.626	0.0209	0.647	No

#### Note:

<sup>·</sup>According to KDB 447498 D01 General RF Exposure Guidance, when the simultaneous transmission SAR is less than 1.6 W/Kg, SPLSR assessment is not required.

SPLSR mean is "The SAR to Peak Location Separation Ratio".

Page 32 of 38

### APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab Date: Mar. 19,2016

System Check Body 835 MHz

DUT: Dipole 835 MHz Type: SID 835

Communication System CW; Communication System Band: D835 (835.0 MHz); Duty Cycle: 1:1;

Frequency: 835 MHz; Medium parameters used: f = 835 MHz;  $\sigma = 0.97$  mho/m;  $\epsilon r = 55.74$ ;  $\rho = 1000$  kg/m<sup>3</sup>;

Phantom section: Flat Section; Input Power=18dBm

Ambient temperature ( $^{\circ}$ C): 20.5, Liquid temperature ( $^{\circ}$ C): 20.2

#### **DASY Configuration:**

• Probe: ES3DV3 - SN3337; ConvF(6.31, 6.31, 6.31); Calibrated:10/01/2015;

- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0, 31.0
- Electronics: DAE4 SN1398; Calibrated: 02/02/2016
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

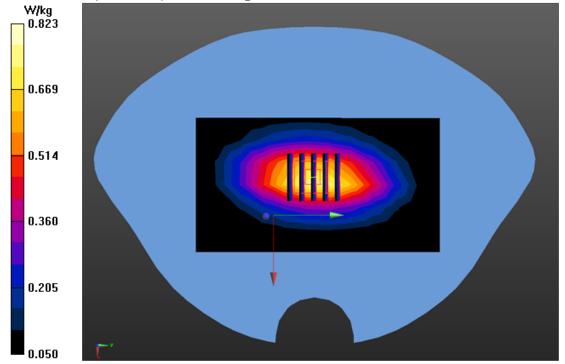
Configuration/System Check 835MHz Body/ Area Scan (7x12x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.749 W/kg

Configuration/System Check 835MHz Body/ Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dv=8mm, dz=5mm

Reference Value = 29.361 V/m; Power Drift = -0.07 dB

Peak SAR (extrapolated) = 1.04 W/kg

SAR(1 g) = 0.626 W/kg; SAR(10 g) = 0.394 W/kg Maximum value of SAR (measured) = 0.823 W/kg



Page 33 of 38

Date: Mar. 22,2016

Test Laboratory: AGC Lab System Check Body 1900MHz

DUT: Dipole 1900 MHz; Type: SID 1900

Communication System: CW; Communication System Band: D1900 (1900.0 MHz); Duty Cycle:1:1;

Frequency: 1900 MHz; Medium parameters used: f = 1900 MHz;  $\sigma = 1.50$  mho/m;  $\epsilon r = 54.00$ ;  $\rho = 1000$  kg/m<sup>3</sup>;

Phantom section: Flat Section; Input Power=18dBm

Ambient temperature ( $^{\circ}$ ):22.1, Liquid temperature ( $^{\circ}$ ): 22.0

### DASY Configuration:

- Probe: ES3DV3 SN3337; ConvF(4.83,4.83, 4.83); Calibrated:10/01/2015;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0, 31.0
- Electronics: DAE4 SN1398; Calibrated: 02/02/2016
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

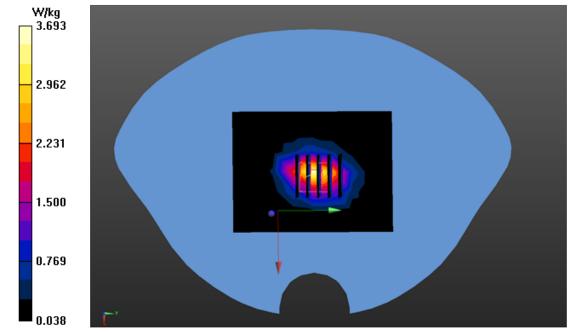
Configuration/System Check 1900MHz Body/ Area Scan (6x9x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 3.68 W/kg

Configuration/System Check 1900MHz Body/Zoom Scan (5x5x7)/ Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 51.571 V/m; Power Drift = 0.13 dB

Peak SAR (extrapolated) = 5.03 W/kg

**SAR(1 g) = 2.52 W/kg; SAR(10 g) = 1.34 W/kg** Maximum value of SAR (measured) = 3.69 W/kg



Page 34 of 38

### APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab Date: Mar. 19,2016

GSM 850 High- Body- Back(MS)

DUT: iphone Dual sim Card; Type: SM9001

Communication System: UID 0, Generic GSM (0); Communication System Band: GSM 850; Duty Cycle: 1:8.3; Frequency: 848.8 MHz; Medium parameters used: f = 835 MHz;  $\sigma = 0.97$  mho/m;  $\epsilon r = 55.74$ ;  $\rho = 1000$  kg/m³;

Phantom section: Flat Section

Ambient temperature (°C):20.5, Liquid temperature (°C): 20.2

#### **DASY Configuration:**

• Probe: ES3DV3 - SN3337; ConvF(6.31, 6.31, 6.31); Calibrated:10/01/2015;

- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0, 31.0
- Electronics: DAE4 SN1398; Calibrated: 02/02/2016
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QDOVA002AA;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

BODY/BACK-H/Area Scan (8x11x1): Measurement grid: dx=15mm, dy=15mm

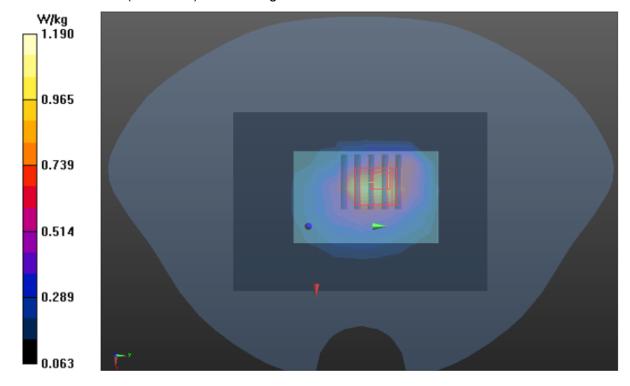
Maximum value of SAR (measured) = 1.05 W/kg

BODY/BACK-H/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

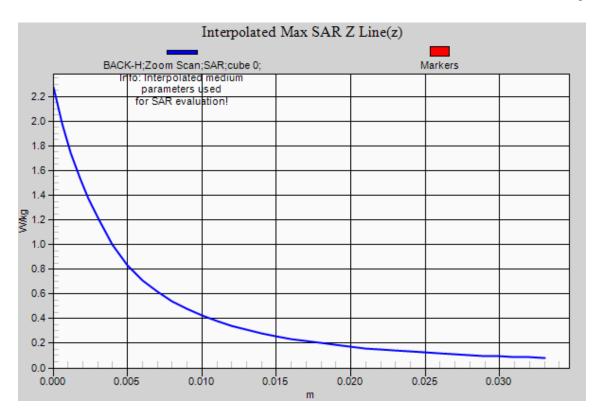
Reference Value = 30.183 V/m; Power Drift = 0.16 dB

Peak SAR (extrapolated) = 2.27 W/kg

SAR(1 g) = 0.986 W/kg; SAR(10 g) = 0.572 W/kg Maximum value of SAR (measured) = 1.19 W/kg



Page 35 of 38



Page 36 of 38

**Test Laboratory: AGC Lab** Date: Mar. 22,2016

PCS 1900 Mid-Body- Back(MS) **DUT: iphone Dual sim Card;** 

**Type: SM9001** 

Communication System: UID 0, Generic GSM (0); Communication System Band: PCS 1900; Duty Cycle: 1:8.3; Frequency: 1880 MHz; Medium parameters used: f = 1900 MHz;  $\sigma = 1.50 \text{ mho/m}$ ;  $\epsilon r = 54.00$ ;  $\rho = 1000 \text{ kg/m}^3$ ;

Phantom section: Flat Section

Ambient temperature ( $^{\circ}$ ):22.1, Liquid temperature ( $^{\circ}$ ): 22.0

### **DASY Configuration:**

- Probe: ES3DV3 SN3337; ConvF(4.83,4.83, 4.83); Calibrated:10/01/2015;
- Sensor-Surface: 3mm (Mechanical Surface Detection), z = 1.0, 31.0
- Electronics: DAE4 SN1398; Calibrated: 02/02/2016
- Phantom: SAM (20deg probe tilt) with CRP v5.0; Type: QD000P40CD;
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

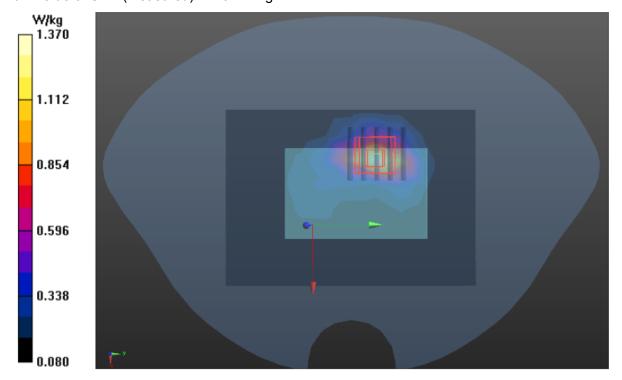
BODY/BACK/Area Scan (8x11x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 1.42 W/kg

BODY/BACK/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

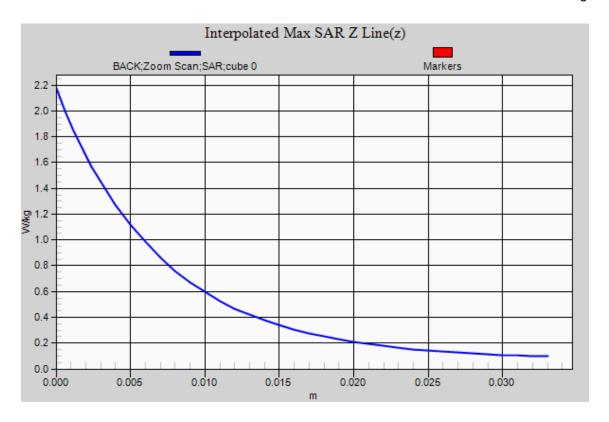
Reference Value = 10.651 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 2.17 W/kg

SAR(1 g) = 1.12 W/kg; SAR(10 g) = 0.577 W/kgMaximum value of SAR (measured) = 1.37 W/kg



Page 37 of 38



Page 38 of 38

### **APPENDIX C. TEST SETUP PHOTOGRAPHS & EUT PHOTOGRAPHS**

Refer to Attached files.

### **APPENDIX D. CALIBRATION DATA**

Refer to Attached files.