



# SAR EVALUATION REPORT

For

# Teltronic S.A.U.

Poligono Malpica C/F-Oeste, Zaragoza, 50057, Spain

FCC ID: WT7PTRKTHTT500800 IC: 8624A-PTHTT800

Model: HTT-500 806-870MHz

Report Type: Product Type:

Original Report Portable Radio

**Test Engineer:** Quinn Jiang

**Report Number:** R1010252-SAR

**Report Date:** 2010-11-17

Victor Zhang

**Reviewed By:** RF Lead

**Prepared By:** Bay Area Compliance Laboratories Corp. (BACL)

(84) 1274 Anvilwood Avenue, Supplyale CA 94089 USA

Sunnyvale, CA 94089, USA

Tel: (408) 732-9162 Fax: (408) 732 9164

**Note**: This test report is prepared for the customer shown above and for the device described herein. It may not be duplicated or used in part without prior written consent from Bay Area Compliance Laboratories Corp. This report **must not** be used by the customer to claim product certification, approval, or endorsement by NVLAP\*, NIST, or any agency of the Federal Government.

<sup>\*</sup> This report may contain data that are not covered by the NVLAP accreditation and are marked with an asterisk "\*" ....

SAR Evaluation Results				
Rule Part(s):	CFR 47 §2.1093, IC RSS-102, Issue 4			
Test Procedure(s):	FCC OET Bulletin 65 C; IEEE 1528-2003			
Exposure Category:	Occupational/Controlled Exposure			
Device Type:	Portable Radio			
Modulation Type:	$\pi/4$ DQPSK, TDMA 4-slots.			
TX Frequency Range:	806-870 MHz			
Maximum Conducted Power Tested:	30.23 dBm			
Antenna Type(s) Tested:	External Antenna			
Body-Worn Accessories:	Belt clip and Remote Speaker Microphone			
Face-Head Accessories:	None			
Battery Type (s) Tested:	7.4 Vdc Rechargeable Li-Pol Battery			
Max. SAR Level(s) Measured:	Body Worn: 0.186 W/kg (1g Body Tissue) Face Hold: 0.735 W/Kg (1g Head Tissue)			

This wireless device has been shown to be capable of compliance for localized specific absorption rate (SAR) for General Population/Uncontrolled Exposure limits specified in ANSI/IEEE Standards and has been tested in accordance with the measurement procedures specified in FCC OET 65 Supplement C.

The results and statements contained in this report pertain only to the device(s) evaluated.



**EUT Photo** 

# **TABLE OF CONTENTS**

REFERENCE, STANDARDS AND GUILDELINES	5
SAR LIMITS	
EUT DESCRIPTION	7
FACILITIES AND ACCREDITATION	8
DESCRIPTION OF TEST SYSTEM	9
MEASUREMENT SYSTEM DIAGRAM	
SYSTEM COMPONENTS	
DASY4 MEASUREMENT SERVER  DATA ACQUISITION ELECTRONICS	
PROBES	
TESTING EQUIPMENT	20
EQUIPMENTS LIST & CALIBRATION INFO	20
SAR MEASUREMENT SYSTEM VERIFICATION	21
SYSTEM ACCURACY VERIFICATION	21
SAR MEASUREMENT RESULTS	22
SAR TEST DATA	22
APPENDIX A – MEASUREMENT UNCERTAINTY	23
APPENDIX B – PROBE CALIBRATION CERTIFICATES	24
APPENDIX C – DIPOLE CALIBRATION CERTIFICATES	35
APPENDIX D - TEST SYSTEM VERIFICATIONS SCANS	45
LIQUID MEASUREMENT RESULT	45
APPENDIX E – EUT SCAN RESTLTS	47
APPENDIX F – OUTPUT POWER MEASUREMENT	53
TEST BLOCK DIAGRAM AND PROCEDURE	
TEST EQUIPMENT LISTS AND DETAILS	
APPENDIX G – TEST SET UP PHOTOS	
BODY WORN - BACK TOUCH TO FLAT PHANTOM	
FACE HELD - 2.5 CM SEPARATION TO FLAT PHANTOM	54
RIGHT HEAD TOUCH	
APPENDIX H- EUT PHOTOS	
EUT – FRONT VIEW EUT – BACK VIEW	
EUT – SIDE VIEW	
EUT – BATTERY OFF VIEW	58
EUT – BATTERY VIEW	
APPENDIX I - INFORMATIVE REFERENCES	61

# **DOCUMENT REVISION HISTORY**

Revision Number	Report Number	Description of Revision	Date of Revision	
0	R1010252-SAR	Original Report	2010-11-17	

## REFERENCE, STANDARDS AND GUILDELINES

#### FCC:

The Report and Order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mw/g as recommended by the ANSI/IEEE standard C95.1-1992 [6] for an uncontrolled environment (Paragraph 65). According to the Supplement C of OET Bulletin 65 "Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

This report describes the methodology and results of experiments performed on wireless data terminal. The objective was to determine if there is RF radiation and if radiation is found, what is the extent of radiation with respect to safety limits. SAR (Specific Absorption Rate) is the measure of RF exposure determined by the amount of RF energy absorbed by human body (or its parts) – to determine how the RF energy couples to the body or head which is a primary health concern for body worn devices. The limit below which the exposure to RF is considered safe by regulatory bodies in North America is 1.6 mw/g average over 1 gram of tissue mass.

#### CE:

The order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 2 mw/g as recommended by the EN50360 for an uncontrolled environment. According to the Standard, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

This report describes the methodology and results of experiments performed on wireless data terminal. The objective was to determine if there is RF radiation and if radiation is found, what is the extent of radiation with respect to safety limits. SAR (Specific Absorption Rate) is the measure of RF exposure determined by the amount of RF energy absorbed by human body (or its parts) – to determine how the RF energy couples to the body or head which is a primary health concern for body worn devices. The limit below which the exposure to RF is considered safe by regulatory bodies in Europe is 2 mw/g average over 10 gram of tissue mass.

The test configurations were laid out on a specially designed test fixture to ensure the reproducibility of measurements. Each configuration was scanned for SAR. Analysis of each scan was carried out to characterize the above effects in the device.

There was no SAR of any concern measured on the device for any of the investigated configurations.

## **SAR Limits**

# FCC Limit (1g tissue)

	SAR (W/Kg)				
EXPOSURE LIMITS	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)			
Spatial Average (averaged over the whole body)	0.08	0.4			
Spatial Peak (averaged over any 1 g of tissue)	1.6	8.0			
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0			

## CE Limit (10g tissue)

	SAR (W/Kg)				
EXPOSURE LIMITS	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)			
Spatial Average (averaged over the whole body)	0.08	0.4			
Spatial Peak (averaged over any 1 g of tissue)	2.0	10			
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0			

Population/Uncontrolled Environments are defined as locations where there is the exposure of individual who have no knowledge or control of their exposure.

Occupational/Controlled Environments are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure (i.e. as a result of employment or occupation).

Occupational/Controlled Environments Spatial Peak limit 8.0 w/kg (FCC) & 10 w/kg (CE) applied to the EUT.

# **EUT DESCRIPTION**

The  $Teltronic\ S.A.U$  product, model HTT-500 or the "EUT" as referred to in this report is a portable radio operates at UHF band.

Items	Technical Specification
Frequency Range	806-870 MHZ
Modulation	π/4 DQPSK, TDMA 4-slots
Maximum Output Power	30.23 dBm
Dimension	14.5(H) x 6.0(W) x 3.5(D) cm
Weight (with battery)	Approx.396.5g
Operation Mode	Face-Hold Body-worn (With Belt clip and Remote Speaker Microphone)

<sup>\*</sup>The data gathered are from a typical production sample provided by the manufacturer, serial number: R1010252-1.

# FACILITIES AND ACCREDITATION

The test site used by Bay Area Compliance Laboratories Corp. (BACL) to collect data is located at 1274 Anvilwood Ave, Sunnyvale, California 94089, USA.

BACL is a National Institute of Standards and Technology (NIST) accredited laboratory under the National Voluntary Laboratory Accredited Program (Lab Code 200167-0).



The current scope of accreditations can be found at: <a href="http://ts.nist.gov/ts/htdocs/210/214/scopes/2001670.htm">http://ts.nist.gov/ts/htdocs/210/214/scopes/2001670.htm</a>

## **DESCRIPTION OF TEST SYSTEM**

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG) which is the fourth generation of the system shown in the figure hereinafter:



The system is based on a high precision robot (working range greater than 0.9m), which positions the probes with a positional repeatability of better than  $\pm 0.02$ mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit.

The SAR measurements were conducted with the dosimetric probe ET3DV6 SN: 1604 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure with accuracy of better than  $\pm 10\%$ . The spherical isotropy was evaluated with the procedure and found to be better than  $\pm 0.25$ dB.

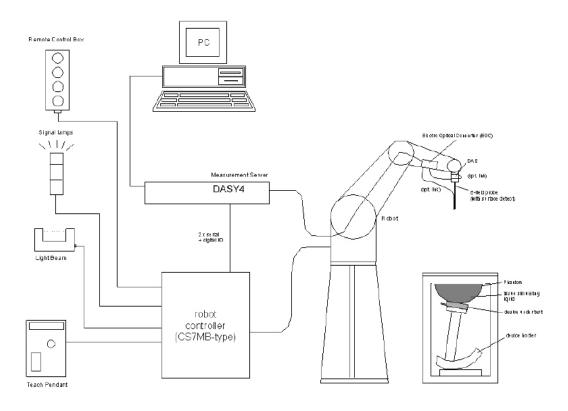
The phantom used was the Generic Twin Phantom. The ear was simulated as a spacer of 4 mm thickness between the earpiece of the phone and the tissue simulating liquid. The Tissue simulation liquid used for each test is in according with the FCC OET65 supplement C as listed below.

Ingredients	Frequency (MHz)									
(% by weight)	45	450 835		35	5 915		1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78

## **IEEE SCC-34/SC-2 P1528 Recommended Tissue Dielectric Parameters**

Frequency	Head		В	ody
(MHz)	ε <sub>r</sub>	σ (S/m)	ε <sub>r</sub>	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

## **Measurement System Diagram**



The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A Data Acquisition Electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-Optical Converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows XP.

- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing to validate the proper functioning of the system.

## **System Components**

- DASY4 Measurement Server
- Data Acquisition Electronics
- Probes
- •Light Beam Unit
- Medium
- SAM Twin Phantom
- •Device Holder for SAM Twin Phantom
- System Validation Kits
- •Robot

#### **DASY4 Measurement Server**

The DASY4 measurement server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chip disk and 64MB RAM. The necessary circuits for communication with either the DAE4 (or DAE3) electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board.



The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pinout and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server.

# **Data Acquisition Electronics**

The data acquisition electronics DAE3 consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.



#### **Probes**

The DASY system can support many different probe types.

**Dosimetric Probes:** These probes are specially designed and calibrated for use in liquids with high permittivities. They should not be used in air, since the spherical isotropy in air is poor ( $\pm 2$  dB). The dosimetric probes have special calibrations in various liquids at different frequencies.

Free Space Probes: These are electric and magnetic field probes specially designed for measurements in free space. The z-sensor is aligned to the probe axis and the rotation angle of the x-sensor is specified. This allows the DASY system to automatically align the probe to the measurement grid for field component measurement. The free space probes are generally not calibrated in liquid. (The H-field probes can be used in liquids without any change of parameters.)

**Temperature Probes:** Small and sensitive temperature probes for general use. They use a completely different parameter set and different evaluation procedures. Temperature rise features allow direct SAR evaluations with these probes.

### **ET3DV6 Probe Specification**

Construction Symmetrical design with triangular core Built-in optical fiber for surface detection System Built-in shielding against static charges Calibration In air from 10 MHz to 2.5 GHz In brain and muscle simulating tissue at Frequencies of 450 MHz, 900 MHz and 1.8 GHz (accuracy  $\pm$  8%) Frequency 10 MHz to > 6 GHz; Linearity:  $\pm$  0.2 dB (30 MHz to 3 GHz) Directivity  $\pm$  0.2 dB in brain tissue (rotation around

probe axis)

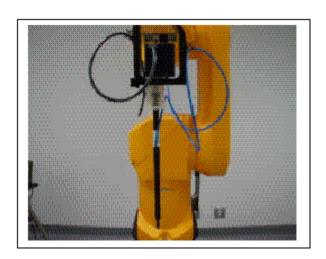
 $\pm$  0.4 dB in brain tissue (rotation normal probe axis) Dynamic 5 mw/g to > 100 mw/g;

Range Linearity:  $\pm 0.2 \text{ dB}$ 

Surface  $\pm$  0.2 mm repeatability in air and clear liquids

Detection over diffuse reflecting surfaces. Dimensions Overall length: 330 mm

Tip length: 16 mm



Photograph of the probe

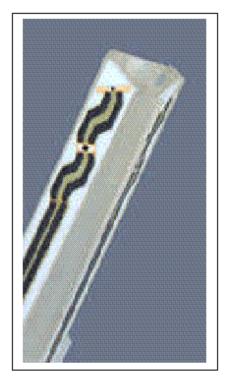
Body diameter: 12 mm Tip diameter: 6.8 mm

Distance from probe tip to dipole centers: 2.7 mm Application General dosimetric up to 3 GHz

Compliance tests of mobile phones

Fast automatic scanning in arbitrary phantoms

The SAR measurements were conducted with the dosimetric probe ET3DV6 designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY3 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.



Inside view of ET3DV6 E-field Probe

#### **E-Field Probe Calibration Process**

Each probe is calibrated according to a dosimetric assessment procedure described in [6] with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure described in [7] and found to be better than +/-0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1 GHz, and in a waveguide above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

#### **Data Evaluation**

The DASY4 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Normi, ai0, ai1, ai2

Conversion factor ConvFiDiode compression point dcpi

Device parameters: - Frequency

- Crest factor

Media parameters: - Conductivity σ

- Density

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DCtransmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

With  $V_i$  = compensated signal of channel i (i =x, y, z)

U<sub>i</sub> = input signal of channel i (i =x, y, z) cf = crest factor of exciting field (DASY parameter)

dcp<sub>i</sub> = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E – field  
probes : 
$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

H – fieldprobes: 
$$H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

With Vi = compensated signal of channel i (i = x, y, z)

 $Norm_i = sensor sensitivity of channel i (i = x, y, z)$ 

 $\mu V/(V/m)^2$  for E-field probes

ConF = sensitivity enhancement in solution

= sensor sensitivity factors for H-field probes

= carrier frequency [GHz]

= electric field strength of channel i in V/m

= diode compression point (DASY parameter)

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$$

With SAR = local specific absorption rate in mW/g

 $E_{tot}$  = total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

Note that the density is normally set to 1, to account for actual brain density rather than the density of the simulation liquid.

## **Light Beam Unit**

The light beam switch allows automatic "tooling" of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, so that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.

#### Medium

#### **Parameters**

The parameters of the tissue simulating liquid strongly influence the SAR in the liquid. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE 1528-2003).

#### Parameter measurements

Several measurement systems are available for measuring the dielectric parameters of liquids:

- The open coax test method (e.g., HP85070 dielectric probe kit) is easy to use, but has only moderate accuracy. It is calibrated with open, short, and deionized water and the calibrations a critical process.
- The transmission line method (e.g., model 1500T from DAMASKOS, INC.) measures the transmission and reflection in a liquid filled high precision line. It needs standard two port calibration and is probably more accurate than the open coax method.
- The reflection line method measures the reflection in a liquid filled shorted precision lined, the method is not suitable for these liquids because of its low sensitivity.
- The slotted line method scans the field magnitude and phase along a liquid filled line. The evaluation is straight forward and only needs a simple response calibration. The method is very accurate, but can only be used in high loss liquids and at frequencies above 100 to 200MHz. Cleaning the line can be tedious.

#### **SAM Twin Phantom**

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left hand
- Right hand
- Flat phantom

The phantom table comes in two sizes: A  $100 \times 50 \times 85$  cm (L x W x H) table for use with free standing robots (DASY4 professional system option) or as a second phantom and a  $100 \times 75 \times 85$  cm(L x W x H) table with reinforcements for table mounted robots (DASY4 compact system option).



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids) A white cover is provided to tap the phantom during o\_-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

The phantom can be used with the following tissue simulating liquids:

- Water-sugar based liquids can be left permanently in the phantom. Always cover the liquid if the system is not used, otherwise the parameters will change due to water evaporation.
- Glycol based liquids should be used with care. As glycol is a softener for most plastics, the liquid should be taken out of the phantom and the phantom should be dried when the system is not used (desirable at least once a week).
- Do not use other organic solvents without previously testing the phantom resistiveness.

#### **Device Holder for SAM Twin Phantom**

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source in 5mm distance, a positioning uncertainty of  $\pm 0.5$ mm would produce a SAR uncertainty of  $\pm 20\%$ . An accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions, in which the devices must be measured, are defined by the standards. The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation centers for both scales are the ear reference point ERP). Thus the device needs no repositioning when changing the angles.





The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity "=3 and loss tangent \_=0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

## **System Validation Kits**

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. For that purpose a well defined SAR distribution in the flat section of the SAM twin phantom is produced.

System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder. Dipoles are available for the variety of frequencies between 300MHz and 6 GHz (dipoles for other frequencies or media and other calibration conditions are available upon request).

The dipoles are highly symmetric and matched at the center frequency for the specified liquid and distance to the flat phantom (or flat section of the SAM-twin phantom). The accurate distance between the liquid surface and the dipole center is achieved with a distance holder that snaps on the dipole.

#### Robot

The DASY4 system uses the high precision industrial robots RX60L, RX90 and RX90L, as well as the RX60BL and RX90BL types out of the newer series from Stäubli SA (France). The RX robot series offers many features that are important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance-free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchrony motors; no stepper motors)
- Low ELF interference (the closed metallic construction shields against motor control fields)

For the newly delivered DASY4 systems as well as for the older DASY3 systems delivered since 1999, the CS7MB robot controller version from Stäubli is used. Previously delivered systems have either a CS7 or CS7M controller; the differences to the CS7MB are mainly in the hardware, but some procedures in the robot software from Stäubli are also not completely the same. The following descriptions about robot hard- and software correspond to CS7MB controller with software version 13.1 (edit S5). The actual commands, procedures and configurations, also including details in hardware, might differ if an older robot controller is in use. In this case please also refer to the Stäubli manuals for further information.



# TESTING EQUIPMENT

# **Equipments List & Calibration Info**

Type / Model	Calibration Due Date	S/N	
DASY4 Professional Dissymmetric System	N/A	N/A	
Robot RX60L	N/A	CS7MBSP / 467	
Robot Controller	N/A	F01/5J72A1/A/01	
Dell Computer Dimension 3000	N/A	N/A	
SPEAG EDC3	N/A	N/A	
SPEAG DAE3	2010-11-22	456	
DASY4 Measurement Server	N/A	1176	
SPEAG E-Field Probe ET3DV6	2011-09-16	1604	
Antenna, Dipole, ALS-D-835-S-2	2011-11-05	210-00564	
SPEAG Generic Twin Phantom	N/A	N/A	
Brain Equivalent Matter (835 MHz)	Each Time	N/A	
Muscle Equivalent Matter (835 MHz)	Each Time	N/A	
Agilent, Spectrum Analyzer E4446A	2011-08-18	US44300386	
Microwave Amp. 8349A	N/A	2644A02662	
Power Meter Agilent E4419B	2011-09-01	MY4121511	
Power Sensor Agilent E9301A	2011-02-19	US39211706	
Agilent E5515C	2011-04-23	GB44051221	
Dielectric Probe Kit HP85070A	N/A	US99360201	
Agilent, Signal Generator, 8648C	2011-02-25	3847M00143	
Amplifier, ST181-20	N/A	E012-0101	
Antenna, Horn SAS-200/571	2011-04-20	A052704	

# SAR MEASUREMENT SYSTEM VERIFICATION

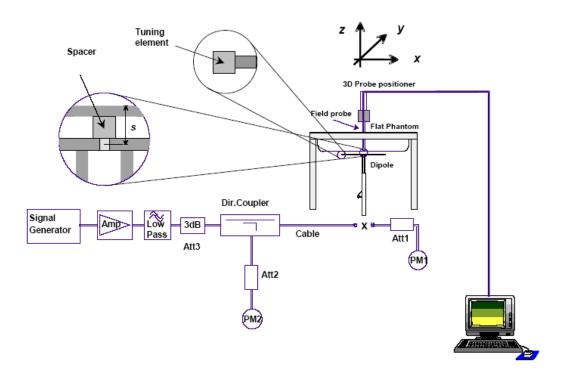
# **System Accuracy Verification**

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of  $\pm 10\%$ . The validation results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

IEEE P1528 recommended reference value for Head

Frequency (MHz)	1 g SAR	10 g SAR	Local SAR at surface (above feed point)	Local SAR at surface (v=2cm offset from feed point)
300	3.0	2.0	4.4	2.1
450	4.9	3.3	7.2	3.2
835	9.5	6.2	14.1	4.9
900	10.8	6.9	16.4	5.4
1450	29.0	16.0	50.2	6.5
1800	38.1	19.8	69.5	6.8
1900	39.7	20.5	72.1	6.6
2000	41.1	21.1	74.6	6.5
2450	52.4	24.0	104.2	7.7
3000	63.8	25.7	140.2	9.5

## **System Setup Block Diagram**



# SAR MEASUREMENT RESULTS

This page summarizes the results of the performed dosimetric evaluation. The plots with the corresponding SAR distributions, which reveal information about the location of the maximum SAR with respect to the device, could be found in Appendix E.

## **SAR Test Data**

## **Test Environmental Conditions**

Temperature:	20° C - 22° C
<b>Relative Humidity:</b>	55% - 60° C
ATM Pressure:	101.4 kPa

<sup>\*</sup> Testing was performed by Quinn Jiang from 2010-11-08 to 2010-11-09 in SAR chamber.

Test Position	Accessory	Frequency (MHz)	Liquid Type	Phantom Type	1 g SAR (W/Kg) Value	FCC Limit (W/Kg)	Ref. Plot
Body Worn	Belt clip and Remote Speaker Microphone	851.1	Body	Flat	0.186	8.0	1
2.5 cm Face up	None	851.1	Head	Flat	0.335	8.0	2
Right Head Touch	None	851.1	Head	Right Head	0.556	8.0	3
Right Head Tilt	None	851.1	Head	Right Head	0.402	8.0	4
Left Head Touch	None	851.1	Head	Left Head	0.534	8.0	5
Left Head Tilt	None	851.1	Head	Left Head	0.735	8.0	6

#### Note:

"TETRA access scheme is TDMA with 4 physical channels per carrier. The channel bandwidth is 25 kHz. As a result, the equipment meets a spectrum efficiency standard of one voice channel per 6.25 kHz of channel bandwidth. Modulation is  $\pi/4$ -DQPSK with 18Ksym/sec. This modulation is based on transmitting two bits per symbol, so the data rate on each sub-carrier is 9000 bits/sec (higher than 4800 bits per second per 6.25 kHz of channel bandwidth)."

# APPENDIX A – MEASUREMENT UNCERTAINTY

The uncertainty budget has been determined for the DASY4 measurement system and is given in the following Table.

DASY4 Uncertainty Budget According to IEEE 1528								
Error Description	Uncertainty Value	Prob. Dist.	Div.	(c i) 1g	(c i) 10g	Std. Unc. (1g)	Std. Unc. (10g)	(v i) veff
		Measu	ırement	System				
Probe Calibration	± 5.9%	N	1	1	1	± 5.9%	± 5.9%	$\infty$
Axial Isotropy	± 4.7%	R	$\sqrt{3}$	0.7	0.7	± 1.9%	± 1.9%	$\infty$
Hemispherical Isotropy	± 9.6%	R	$\sqrt{3}$	0.7	0.7	± 3.9%	± 3.9%	~
Boundary Effects	± 1.0%	R	$\sqrt{3}$	1	1	± 0.6%	± 0.6%	œ
Linearity	± 4.7%	R	$\sqrt{3}$	1	1	± 2.7%	± 2.7%	~
System Detection Limits	± 1.0%	R	$\sqrt{3}$	1	1	± 0.6%	± 0.6%	$\infty$
Readout Electronics	± 0.3%	N	1	1	1	± 0.3%	± 0.3%	~
Response Time	± 0.8%	R	$\sqrt{3}$	1	1	± 0.5%	± 0.5%	$\infty$
Integration Time	± 2.6%	R	$\sqrt{3}$	1	1	± 1.5%	± 1.5%	~
RF Ambient Conditions	± 3.0%	R	$\sqrt{3}$	1	1	± 1.7%	± 1.7%	~
Probe Positioner	± 0.4%	R	$\sqrt{3}$	1	1	± 0.2%	± 0.2%	~
Probe Positioning	± 2.9%	R	$\sqrt{3}$	1	1	± 1.7%	± 1.7%	~
Max. SAR Eval.	± 1.0%	R	$\sqrt{3}$	1	1	± 0.6%	± 0.6%	~
		Test S	Sample 1	Related				
Device Positioning	± 2.9%	N	1	1	1	± 2.9%	± 2.9%	145
Device Holder	± 3.6%	N	1	1	1	± 3.6%	± 2.6%	5
Power Drift	± 5.0%	R		1	1	± 2.9%	± 2.9%	∞
		Phan	tom and	l Setup				
Phantom Uncertainty	± 4.0%	R	$\sqrt{3}$	1	1	± 2.3%	± 2.3%	∞
Liquid Conductivity (Target)	± 5.0%	R	$\sqrt{3}$	0.64	0.43	± 1.8%	± 1.2%	∝
Liquid Conductivity (meas.)	± 2.5%	N	1	0.64	0.43	± 1.6%	± 1.1%	∞
Liquid Permittivity (Target)	± 5.0%	R	$\sqrt{3}$	0.6	0.49	± 1.7%	± 1.4%	∝
Liquid Permittivity (Target)	± 2.5%	N	1	0.6	0.49	± 1.5%	± 1%	$\infty$
Combined Std. Uncertainty						± 10.8%	± 10.6%	330
Expanded STD Uncertainty						± 21.6%	± 21.1%	

## APPENDIX B – PROBE CALIBRATION CERTIFICATES

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
Servizio svizzero di taratura
S Swiss Calibration Service

Accreditation No.: SCS 108

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA

Multilateral Agreement for the recognition of calibration certificates

Client BACL Certificate No: ET3-1604\_Sep10

CALIBRATION CERTIFICATE Object ET3DV6 - SN:1604 Calibration procedure(s) QA CAL-01.v6, QA CAL-12.v6, QA CAL-23.v3 and QA CAL-25.v2 Calibration procedure for dosimetric E-field probes Calibration date September 16, 2010 This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI), The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility; environment temperature (22 ± 3)°C and humidity < 70% Calibration Equipment used (M&TE critical for calibration) Primary Standards ID# Cal Date (Certificate No.) Scheduled Calibration Power meter E4419B GR41293874 1-Apr-10 (No. 217-01136) Apr-11 Power sensor E4412A MY41495277 1-Apr-10 (No. 217-01136) Apr-11 Power sensor E4412A MY41498087 1-Apr-10 (No. 217-01136) Apr-11 Reference 3 dB Attenuator SN: S5054 (3c) 30-Mar-10 (No. 217-01159) Mar-11 30-Mar-10 (No. 217-01161) Reference 20 dB Attenuator SN: S5086 (20b) Mar-11 Reference 30 dB Attenuator SN: S5129 (30b) 30-Mar-10 (No. 217-01160) Mar-11 Reference Probe ES3DV2 SN: 3013 30-Dec-09 (No. ES3-3013\_Dec09) Dec-10 DAE4 SN: 660 20-Apr-10 (No. DAE4-660 Apr10) Apr-11 Secondary Standards ID# Check Date (in house) Scheduled Check 4-Aug-99 (in house check Oct-09) RF generator HP 8648C US3642U01700 In house check: Oct-11 Network Analyzer HP 8753E US37390585 18-Oct-01 (in house check Oct-09) In house check: Oct10 Name Function Calibrated by: Jeton Kastrati Laboratory Technician Approved by: Katja Pokovic Technical Manager Issued: September 16, 2010 This calibration certificate shall not be reproduced except in full without written approval of the laboratory

Certificate No: ET3-1604\_Sep10

Page 1 of 11

Veritied ok Janger 9/24/2010

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
Servizio svizzero di taratura
S Swiss Calibration Service

Accreditation No.: SCS 108

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA

Multilateral Agreement for the recognition of calibration certificates

Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConvF sensitivity in TSL / NORMx,y,z
DCP diode compression point

CF crest factor (1/duty\_cycle) of the RF signal A, B, C modulation dependent linearization parameters

Polarization  $\phi$   $\phi$  rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 9 = 0 is normal to probe axis

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- EC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

#### **Methods Applied and Interpretation of Parameters:**

- NORMx,y,z: Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
   NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart). This linearization is
  implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included
  in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C are numerical linearization parameters assessed based on the data of
  power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the
  maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Certificate No: ET3-1604\_Sep10 Page 2 of 11

# Probe ET3DV6

SN:1604

Manufactured: July 30, 2001

Last calibrated: September 23, 2008 Recalibrated: September 16, 2010

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

Certificate No: ET3-1604\_Sep10

Page 3 of 11

# DASY/EASY - Parameters of Probe: ET3DV6 SN:1604

#### **Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (μV/(V/m) <sup>2</sup> ) <sup>A</sup>	1.93	1.86	1.92	± 10.1%
DCP (mV) <sup>8</sup>	91.4	91.1	91.5	

#### **Modulation Calibration Parameters**

	ation ballbration aralloto	<u>.                                    </u>						
UID	Communication System Name	PAR		A dB	B dBuV	С	VR mV	Unc <sup>E</sup> (k=2)
10000	cw	0.00	x	0.00	0.00	1.00	300.0	± 1.5%
			Y	0.00	0.00	1.00	300.0	
			Z	0.00	0.00	1.00	300.0	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Certificate No: ET3-1604\_Sep10

Page 4 of 11

<sup>^</sup> The uncertainties of NormX,Y,Z do not affect the E2-field uncertainty inside TSL (see Pages 5 and 6).

<sup>&</sup>lt;sup>8</sup> Numerical linearization parameter: uncertainty not required.

E Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

# DASY/EASY - Parameters of Probe: ET3DV6 SN:1604

## Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz]	Validity [MHz] <sup>C</sup>	Permittivity	Conductivity	ConvF X Co	nvFY Co	nvF Z	Alpha	Depth Unc (k=2)
450	± 50 / ± 100	43.5 ± 5%	0.87 ± 5%	7.32	7.32	7.32	0.20	2.22 ± 13.3%
835	± 50 / ± 100	41.5 ± 5%	0.90 ± 5%	6.26	6.26	6.26	0.43	2.21 ± 11.0%
900	± 50 / ± 100	41.5 ± 5%	0.97 ± 5%	6.12	6.12	6.12	0.34	2.66 ± 11.0%
1810	± 50 / ± 100	40.0 ± 5%	1.40 ± 5%	5.14	5.14	5.14	0.60	2.51 ± 11.0%
1900	± 50 / ± 100	40.0 ± 5%	1.40 ± 5%	5.04	5.04	5.04	0.69	2.17 ± 11.0%
2450	± 50 / ± 100	39.2 ± 5%	1.80 ± 5%	4.33	4.33	4.33	0.99	1.63 ± 11.0%

<sup>&</sup>lt;sup>c</sup> The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

Certificate No: ET3-1604\_Sep10

## DASY/EASY - Parameters of Probe: ET3DV6 SN:1604

## Calibration Parameter Determined in Body Tissue Simulating Media

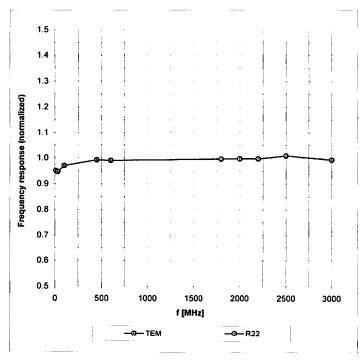
f [MHz]	Validity [MHz] <sup>C</sup>	Permittivity	Conductivity	ConvF X Co	nvF Y Co	nvF Z	Alpha	Depth Unc (k=2)
450	± 50 / ± 100	56.7 ± 5%	0.94 ± 5%	7.72	7.72	7.72	0.13	2.30 ± 13.3%
835	± 50 / ± 100	55.2 ± 5%	0.97 ± 5%	6.10	6.10	6.10	0.31	2.92 ± 11.0%
900	± 50 / ± 100	55.0 ± 5%	1.05 ± 5%	6.09	6.09	6.09	0.28	3.23 ± 11.0%
1810	± 50 / ± 100	53.3 ± 5%	1.52 ± 5%	4.61	4.61	4.61	0.75	2.61 ± 11.0%
1900	± 50 / ± 100	53.3 ± 5%	1.52 ± 5%	4.44	4.44	4.44	0.88	2.41 ± 11.0%
2450	± 50 / ± 100	52.7 ± 5%	1.95 ± 5%	4.06	4.06	4.06	0.99	1.32 ± 11.0%

<sup>&</sup>lt;sup>C</sup> The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

Certificate No: ET3-1604\_Sep10

# Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)

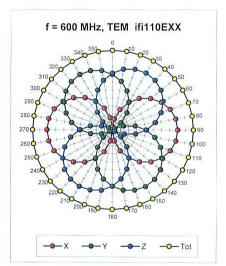


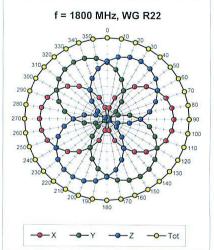
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

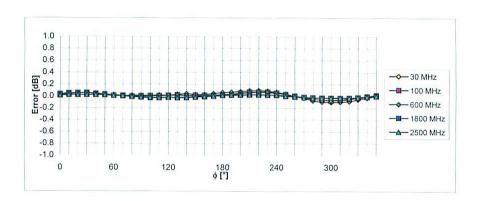
Certificate No: ET3-1604\_Sep10

Page 7 of 11

# Receiving Pattern ( $\phi$ ), $\vartheta = 0^{\circ}$







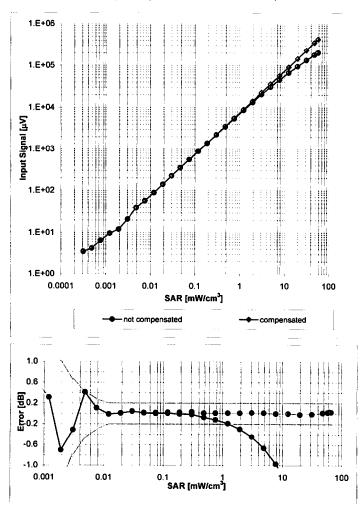
Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Certificate No: ET3-1604\_Sep10

Page 8 of 11

# Dynamic Range f(SAR<sub>head</sub>)

(Waveguide R22, f = 1800 MHz)

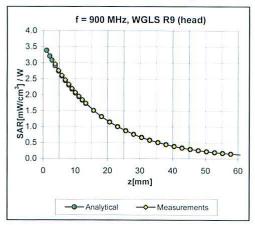


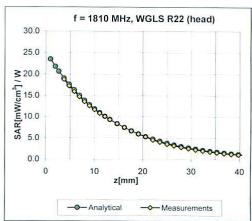
Uncertainty of Linearity Assessment: ± 0.6% (k=2)

Certificate No: ET3-1604\_Sep10

Page 9 of 11

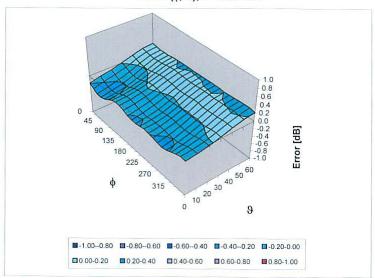
## **Conversion Factor Assessment**





# Deviation from Isotropy in HSL

Error (φ, θ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Certificate No: ET3-1604\_Sep10

Page 10 of 11

# **Other Probe Parameters**

Sensor Arrangement	Triangular
Connector Angle (°)	Not applicable
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	enabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	6.8 mm
Probe Tip to Sensor X Calibration Point	2.7 mm
Probe Tip to Sensor Y Calibration Point	2.7 mm
Probe Tip to Sensor Z Calibration Point	2.7 mm
Recommended Measurement Distance from Surface	4 mm

Certificate No: ET3-1604\_Sep10 Page 11 of 11

# **APPENDIX C – DIPOLE CALIBRATION CERTIFICATES**

#### NCL CALIBRATION LABORATORIES

Calibration File No: DC-1176 Project Number: BACB-5547

# CERTIFICATE OF CALIBRATION

It is certified that the equipment identified below has been calibrated in the NCL CALIBRATION LABORATORIES by qualified personnel following recognized procedures and using transfer standards traceable to NRC/NIST.

Validation Dipole

Manufacturer: APREL Laboratories Part number: ALS-D-835-S-2 Frequency; 835 MHz Serial No: 210-00664

Customer: Bay Area Compliance Laboratory

Calibrated: 4<sup>th</sup> November 2010 Released on: 5<sup>th</sup> November 2010

This Calibration Certificate is Intemplete Unides Accompanied with the Calibration Results Summary

Released By:

NCL CALIBRATION LABORATORIES

51 SPECTRUM WAY NEPEAN, ONTARIO CANADA K2R 1E6 Division of APREL Lab. TEL: (613) 820-4988 FAX: (613) 820-4162

## NCL Calibration Laboratories

Division of APREL Laboratories.

## Conditions

Dipole 210-00564 was new and taken from stock prior to calibration.

Ambient Temperature of the Laboratory:

22 °C +/- 0.5°C

Temperature of the Tissue:

21 °C +/- 0.5°C

We the undersigned attest that to the best of our knowledge the calibration of this device has been accurately conducted and that all Information contained within this report has been reviewed for accuracy.

Stuart Nicol

C. Teodorian

This page has been reviewed for content and attested to by signature within this document.

Division of APREL Laboratories.

## Calibration Results Summary

The following results relate the Calibrated Dipole and should be used as a quick reference for the user.

#### Mechanical Dimensions

Length:

162.2 mm

Height:

89.4 mm

#### Electrical Specification

SWR:

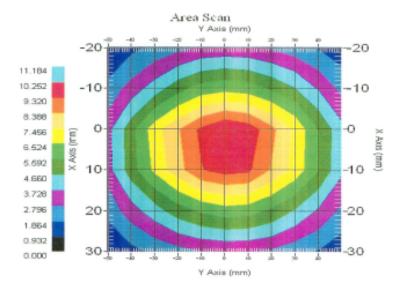
1.085 U -29.149 dB

Return Loss: Impedance:

 $50.605 \Omega$ 

#### System Validation Results

Frequency	1 Gram	10 Gram	Peak
835 MHz	9.51	6.15	14.19



This page has been reviewed for content and attested to by signature within this document.

Division of APREL Laboratories.

#### Introduction

This Calibration Report has been produced in line with the SSI Dipole Calibration Procedure SSI-TP-018-ALSAS. The results contained within this report are for Validation Dipole 210-00564. The calibration routine consisted of a three-step process. Step 1 was a mechanical verification of the dipole to ensure that it meets the mechanical specifications, Step 2 was an Electrical Calibration for the Validation Dipole, where the SWR, Impedance, and the Return loss were assessed. Step 3 involved a System Validation using the ALSAS-10U, along with APREL E-020 130 MHz to 26 GHz E-Field Probe Serial Number 212.

#### References

SSI-TP-018-ALSAS Dipole Calibration Procedure
SSI-TP-016 Tissue Calibration Procedure
IEEE 1528 "Recommended Practice for Determining the Peak Spatial-Average
Specific Absorption Rate (SAR) in the Human Body Due to Wireless
Communications Devices: Experimental Techniques"

#### Conditions

Dipole 210-00564 was new taken from stock.

Ambient Temperature of the Laboratory: 22 °C +/- 0.5 °C Temperature of the Tissue: 20 °C +/- 0.5 °C

This page has been reviewed for content and attested to by signature within this document.

Division of APREL Laboratories.

## **Dipole Calibration Results**

#### Mechanical Verification

APREL	APREL	Measured	Measured
Length	Height	Length	Height
161.0 mm	89.8 mm	162.2 mm	89.4 mm

#### Tissue Validation

Head Tissue 835MHz	Measured
Dielectric constant, ε <sub>r</sub>	41.10
Conductivity, o [S/m]	0.91

This page has been reviewed for content and attested to by signature within this document.

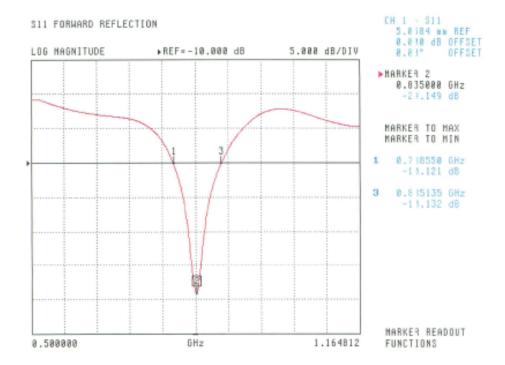
Division of APREL Laboratories.

#### Electrical Calibration

Test	Result		
S11 RL	-29.149 dB		
SWR	1.085 U		
Impedance	50.605 Ω		

The Following Graphs are the results as displayed on the Vector Network Analyzer.

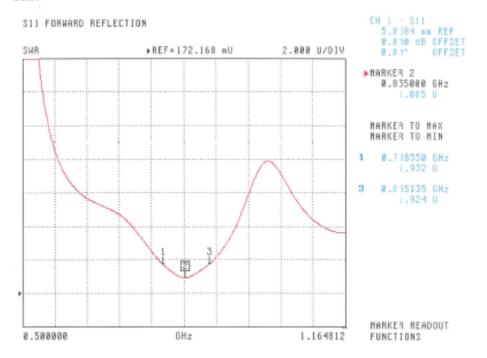
#### S11 Parameter Return Loss



This page has been reviewed for content and attested to by signature within this document.

Division of APREL Laboratories.

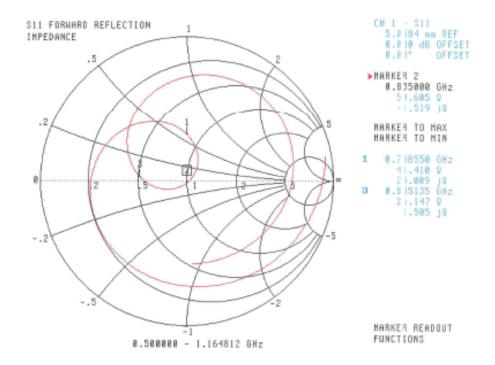
#### SWR



This page has been reviewed for content and attested to by signature within this document.

Division of APREL Laboratories.

## Smith Chart Dipole Impedance

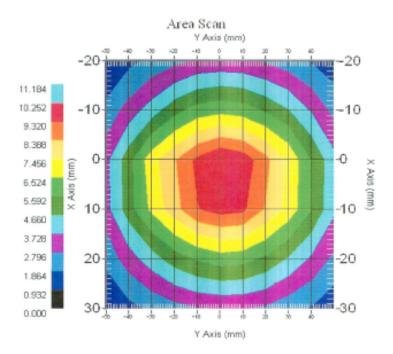


This page has been reviewed for content and attested to by signature within this document.

Division of APREL Laboratories.

## System Validation Results Using the Electrically Calibrated Dipole

Head Tissue Frequency	1 Gram	10 Gram	Peak Above Feed Point
835 MHz	9.51	6.15	14.19



This page has been reviewed for content and attested to by signature within this document.

Division of APREL Laboratories.

## **Test Equipment**

The test equipment used during Probe Calibration, manufacturer, model number and, current calibration status are listed and located on the main APREL server R:\NCL\Calibration Equipment\Instrument List 2010.

10

This page has been reviewed for content and attested to by signature within this document.

# APPENDIX D - TEST SYSTEM VERIFICATIONS SCANS

# **Liquid Measurement Result**

Testing was performed by Quinn Jiang on 2010-11-08

Simulant	Freq. [MHz]	Parameters	Liquid Temp [°C]	Target Value	Measured Value	Deviation [%]	Limits [%]
		εr	22	41.5	41.5	0	±5
Head	835	σ	22	0.90	0.89	-1.1	±5
		1g SAR	22	9.5	9.3	-2.11	±10

 $\varepsilon r$  = relative permittivity,  $\sigma$  = conductivity and  $\rho$ =1000 kg/m3

## **System Performance Test (835 MHz Head Tissue)**

## Dipole 835 MHz; Type: ALS-D-835-S-2; Serial: SN: 210-00564

Communication System: CW; Frequency: 835 MHz; Duty Cycle: 1:1

Medium parameters used: f = 835 MHz;  $\sigma = 0.89$  mho/m;  $\varepsilon_r = 41.5$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

## DASY4 Configuration:

• Probe: ET3DV6 - SN1604; ConvF(6.26, 6.26, 6.26); Calibrated: 9/16/2010

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn456; Calibrated: 11/8/2007

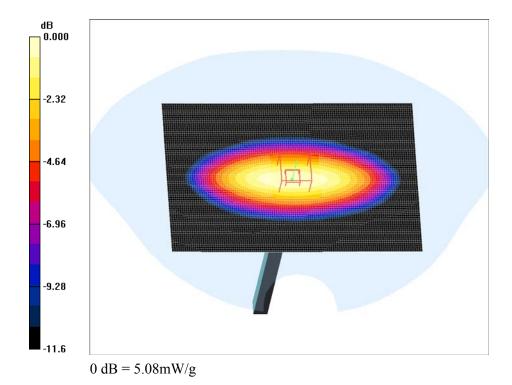
Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032

Measurement SW: DASY4, V4.6 Build 23; Post processing SW: SEMCAD, V1.8 Build 184

**d =15 mm, Pin = 0.5 W/Area Scan (81x121x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 5.02 mW/g

**d =15 mm, Pin = 0.5 W/Zoom Scan (8x8x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 78.3 V/m; Power Drift = -0.044 dB Peak SAR (extrapolated) = 7.21 W/kg

#### SAR (1 g) = 4.65 mW/g; SAR (10 g) = 2.95 mW/gMaximum value of SAR (measured) = 5.08 mW/g



835 MHz System Validation

## APPENDIX E – EUT SCAN RESTLTS

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Body Worn to Flat Phantom with Belt clip and Remote Speaker Microphone (Low Channel)

Teltronic S.A.U; Type: HTT-500; Serial: R1010252-1

Communication System: Low Channel; Frequency: 851.1 MHz; Duty Cycle: 1:4

Medium parameters used (interpolated): f = 851.1 MHz;  $\sigma = 0.971 \text{ mho/m}$ ;  $\varepsilon_r = 55.7$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

#### DASY4 Configuration:

• Probe: ET3DV6 - SN1604; ConvF(6.1, 6.1, 6.1); Calibrated: 9/16/2010

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn456; Calibrated: 11/8/2007

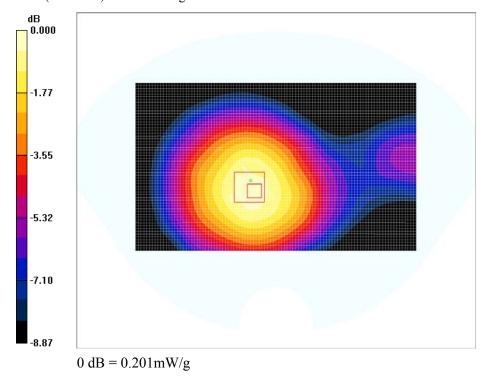
• Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032

Measurement SW: DASY4, V4.6 Build 23; Post processing SW: SEMCAD, V1.8 Build 184

**Body Worn to Flat Phantom with Clip /Area Scan (61x101x1):** Measurement grid: dx=20mm, dy=20mm Maximum value of SAR (interpolated) = 0.190 mW/g

**Body Worn to Flat Phantom with Clip /Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 14.1 V/m; Power Drift = -0.170 dB Peak SAR (extrapolated) = 0.263 W/kg

SAR (1 g) = 0.186 mW/g; SAR (10 g) = 0.138 mW/gMaximum value of SAR (measured) = 0.201 mW/g



## 2.5 cm Face Up to Flat Phantom (Low Channel)

## Teltronic S.A.U; Type: HTT-500; Serial: R1010252-1

Communication System: Low Channel; Frequency: 851.1 MHz; Duty Cycle: 1:4

Medium parameters used (interpolated): f = 851.1 MHz;  $\sigma = 0.971 \text{ mho/m}$ ;  $\varepsilon_r = 55.7$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

## DASY4 Configuration:

• Probe: ET3DV6 - SN1604; ConvF(6.1, 6.1, 6.1); Calibrated: 9/16/2010

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn456; Calibrated: 11/8/2007

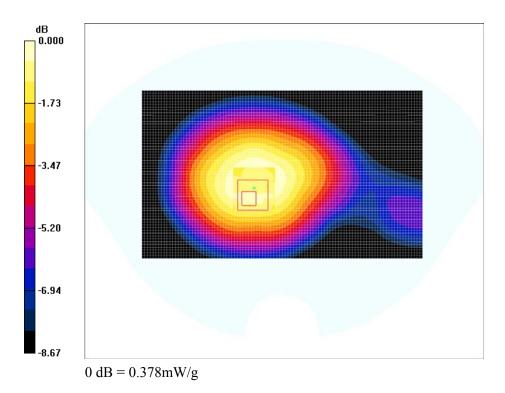
Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032

Measurement SW: DASY4, V4.6 Build 23; Post processing SW: SEMCAD, V1.8 Build 184

**2.5 cm Face Up to Flat Phantom /Area Scan (61x101x1):** Measurement grid: dx=20mm, dy=20mm Maximum value of SAR (interpolated) = 0.386 mW/g

**2.5 cm Face Up to Flat Phantom /Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 16.3 V/m; Power Drift = -0.043 dB Peak SAR (extrapolated) = 0.466 W/kg

#### SAR (1 g) = 0.335 mW/g; SAR (10 g) = 0.236 mW/gMaximum value of SAR (measured) = 0.378 mW/g



## **Right Head Touch (Low Channel)**

## Teltronic S.A.U; Type: HTT-500; Serial: R1010252-1

Communication System: Low Channel; Frequency: 851.1 MHz; Duty Cycle: 1:4 Medium parameters used (interpolated): f = 851.1 MHz;  $\sigma = 0.901$  mho/m;  $\epsilon_r = 41.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Right Section

#### DASY4 Configuration:

• Probe: ET3DV6 - SN1604; ConvF(6.26, 6.26, 6.26); Calibrated: 9/16/2010

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn456; Calibrated: 11/8/2007

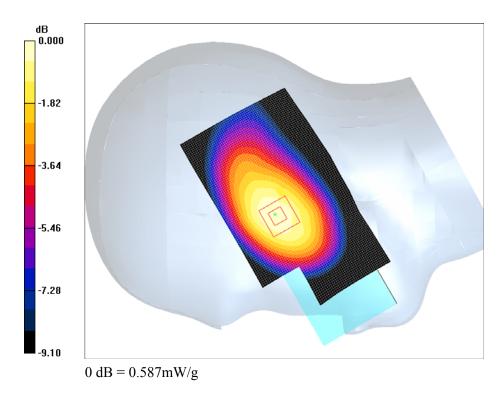
Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032

Measurement SW: DASY4, V4.6 Build 23; Post processing SW: SEMCAD, V1.8 Build 184

**Right Head Touch/Area Scan (61x101x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.590 mW/g

**Right Head Touch/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 20.8 V/m; Power Drift = -2.11 dB Peak SAR (extrapolated) = 0.741 W/kg

#### SAR (1 g) = 0.556 mW/g; SAR (10 g) = 0.408 mW/gMaximum value of SAR (measured) = 0.587 mW/g



## **Right Head Tilt (Low Channel)**

## Teltronic S.A.U; Type: HTT-500; Serial: R1010252-1

Communication System: Low Channel; Frequency: 851.1 MHz; Duty Cycle: 1:4

Medium parameters used (interpolated): f = 851.1 MHz;  $\sigma = 0.901 \text{ mho/m}$ ;  $\varepsilon_r = 41.3$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Right Section

#### DASY4 Configuration:

• Probe: ET3DV6 - SN1604; ConvF(6.26, 6.26, 6.26); Calibrated: 9/16/2010

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn456; Calibrated: 11/8/2007

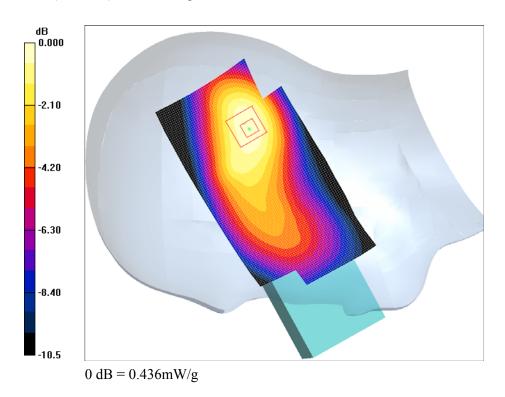
• Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032

Measurement SW: DASY4, V4.6 Build 23; Postprocessing SW: SEMCAD, V1.8 Build 184

**Right Head Tilt /Area Scan (61x111x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.445 mW/g

**Right Head Tilt /Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 21.0 V/m; Power Drift = -0.092 dB Peak SAR (extrapolated) = 0.589 W/kg

#### SAR (1 g) = 0.402 mW/g; SAR (10 g) = 0.283 mW/gMaximum value of SAR (measured) = 0.436 mW/g



#### **Left Head Touch (Low Channel)**

## Teltronic S.A.U; Type: HTT-500; Serial: R1010252-1

Communication System: Low Channel; Frequency: 851.1 MHz; Duty Cycle: 1:4

Medium parameters used (interpolated): f = 851.1 MHz;  $\sigma = 0.901 \text{ mho/m}$ ;  $\varepsilon_r = 41.3$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Left Section

#### DASY4 Configuration:

• Probe: ET3DV6 - SN1604; ConvF(6.26, 6.26, 6.26); Calibrated: 9/16/2010

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn456; Calibrated: 11/8/2007

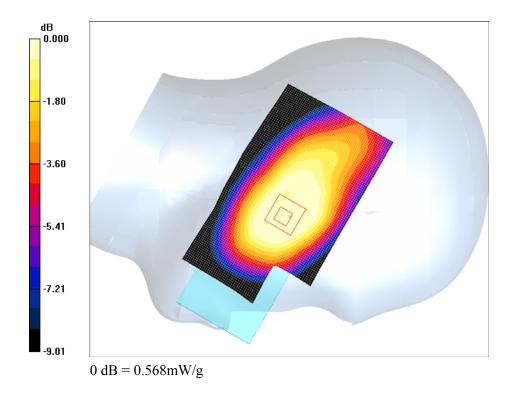
Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032

Measurement SW: DASY4, V4.6 Build 23; Post processing SW: SEMCAD, V1.8 Build 184

**Left Head Touch/Area Scan (61x101x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.723 mW/g

**Left Head Touch/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 21.3 V/m; Power Drift = 0.250 dB Peak SAR (extrapolated) = 0.675 W/kg

#### SAR (1 g) = 0.534 mW/g; SAR (10 g) = 0.402 mW/gMaximum value of SAR (measured) = 0.568 mW/g



## **Left Head Tilt (Low Channel)**

## Teltronic S.A.U; Type: HTT-500; Serial: R1010252-1

Communication System: Low Channel; Frequency: 851.1 MHz; Duty Cycle: 1:4

Medium parameters used (interpolated): f = 851.1 MHz;  $\sigma = 0.901 \text{ mho/m}$ ;  $\varepsilon_r = 41.3$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Left Section

## DASY4 Configuration:

• Probe: ET3DV6 - SN1604; ConvF(6.26, 6.26, 6.26); Calibrated: 9/16/2010

• Sensor-Surface: 4mm (Mechanical Surface Detection)

• Electronics: DAE3 Sn456; Calibrated: 11/8/2007

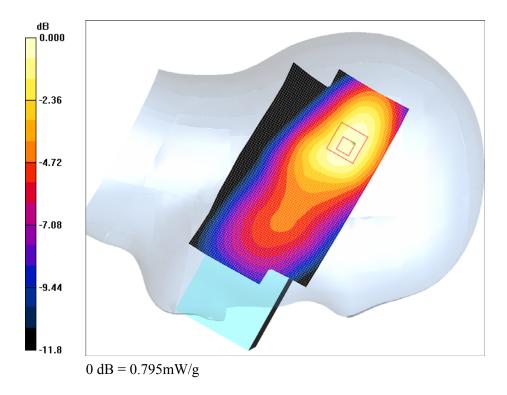
• Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032

Measurement SW: DASY4, V4.6 Build 23; Post processing SW: SEMCAD, V1.8 Build 184

**Left Head Tilt /Area Scan (61x111x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.787 mW/g

**Left Head Tilt /Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 24.5 V/m; Power Drift = -2.38 dB Peak SAR (extrapolated) = 1.16 W/kg

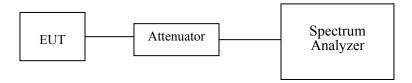
#### SAR (1 g) = 0.735 mW/g; SAR (10 g) = 0.471 mW/gMaximum value of SAR (measured) = 0.795 mW/g



# APPENDIX F – OUTPUT POWER MEASUREMENT

# **Test Block Diagram and Procedure**

The RF output of the transmitter was connected to the input of the spectrum analyzer through sufficient attenuation.



# **Test Equipment Lists and Details**

Manufacturer	Description	Model Number	S/N	Calibration Due Date
Agilent	Spectrum Analyzer	E4440A	MY44303352	2011-05-09

## **Test Results**

Frequency	Measured Conducted Output Power			
(MHz)	(dBm)	(Watt)		
806.1	29.42	0.87		
815	29.31	0.85		
823.9	29.28	0.85		
851.1	30.23	1.05		
860	30.17	1.04		
868.9	29.94	0.99		

# APPENDIX G – TEST SET UP PHOTOS

# **Body Worn - Back Touch to Flat Phantom**

(With Belt clip and Remote Speaker Microphone)



Face Held - 2.5 cm Separation to Flat Phantom



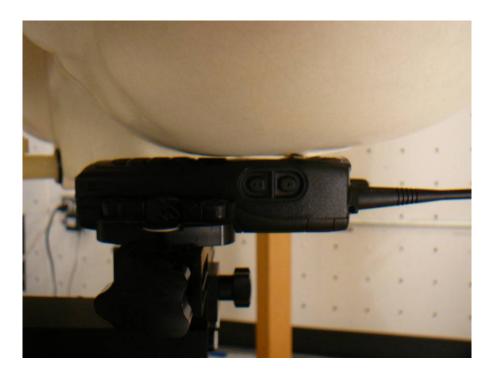
# **Right Head Touch**



**Right Head Tilt** 



# **Left Head Touch**



**Left Head Tilt** 



# **APPENDIX H-EUT PHOTOS**

**EUT – Front View** 



**EUT – Back View** 



**EUT – Side View** 

Confidentiality

**EUT – Battery off View** 



# **EUT – Battery View**



**EUT - Remote Speaker Microphone** 



**EUT - Belt Clip** 



## APPENDIX I - INFORMATIVE REFERENCES

- [1] Federal Communications Commission, \Report and order: Guidelines for evaluating the environmental effects of radiofrequency radiation", Tech. Rep. FCC 96-326, FCC, Washington, D.C. 20554, 1996.
- [2] David L. Means Kwok Chan, Robert F. Cleveland, \Evaluating compliance with FCC guidelines for human exposure to radiofrequency electromagnetic fields", Tech. Rep., Federal Communication Commission, O\_ce of Engineering & Technology, Washington, DC, 1997.
- [3] Thomas Schmid, Oliver Egger, and Niels Kuster, \Automated E-\_eld scanning system for dosimetric assessments", IEEE Transactions on Microwave Theory and Techniques, vol. 44, pp. 105{113, Jan. 1996.
- [4] Niels Kuster, Ralph K.astle, and Thomas Schmid, \Dosimetric evaluation of mobile communications equipment with known precision", IEICE Transactions on Communications, vol. E80-B, no. 5, pp. 645 (652, May 1997.
- [5] CENELEC, \Considerations for evaluating of human exposure to electromagnetic fields (EMFs) from mobile telecommunication equipment (MTE) in the frequency range 30MHz 6GHz", Tech. Rep., CENELEC, European Committee for Electrotechnical Standardization, Brussels, 1997.
- [6] ANSI, ANSI/IEEE C95.1-1992: IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz, The Institute of Electrical and Electronics Engineers, Inc., New York, NY 10017, 1992.
- [7] Katja Pokovic, Thomas Schmid, and Niels Kuster, \Robust setup for precise calibration of E-field probes in tissue simulating liquids at mobile communications frequencies", in ICECOM 97, Dubrovnik, October 15{17, 1997, pp. 120-24.
- [8] Katja Pokovic, Thomas Schmid, and Niels Kuster, \E-field probe with improved isotropy in brain simulating liquids", in Proceedings of the ELMAR, Zadar, Croatia, 23 {25 June, 1996, pp. 172-175.
- [9] Volker Hombach, Klaus Meier, Michael Burkhardt, Eberhard K. uhn, and Niels Kuster, \The dependence of EM energy absorption upon human head modeling at 900 MHz", IEEE Transactions on Microwave Theory and Techniques, vol. 44, no. 10, pp. 1865-1873, Oct. 1996.
- [10] Klaus Meier, Ralf Kastle, Volker Hombach, Roger Tay, and Niels Kuster, \The dependence of EM energy absorption upon human head modeling at 1800 MHz", IEEE Transactions on Microwave Theory and Techniques, Oct. 1997, in press.
- [11] W. Gander, Computermathematik, Birkhaeuser, Basel, 1992.
- [12] W. H. Press, S. A. Teukolsky, W. T. Vetterling, and B. P. Flannery, Numerical Recepies in C, The Art of Scientific Computing, Second Edition, Cambridge University Press, 1992. Dosimetric Evaluation of Sample device, month 1998 9
- [13] NIS81 NAMAS, \The treatment of uncertainty in EMC measurement", Tech. Rep., NAMAS Executive, National Physical Laboratory, Teddington, Middlesex, England, 1994.
- [14] Barry N. Taylor and Christ E. Kuyatt, \Guidelines for evaluating and expressing the uncertainty of NIST measurement results", Tech. Rep., National Institute of Standards and Technology, 1994. Dosimetric Evaluation of Sample device, month 1998 10.

\*\*\*\*\* END OF REPORT \*\*\*\*\*