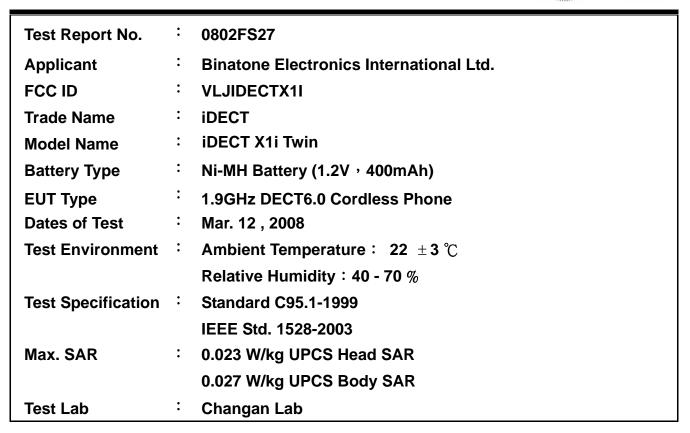


# A Test Lab Techno Corp.

Changan Lab : No. 140 -1, Changan Street, Bade City, Taoyuan County, Taiwan R.O.C. Tel: 886-3-271-0188 / Fax: 886-3-271-0190

SAR EVALUATION REPORT





- 1. The test operations have to be performed with cautious behavior, the test results are as attached.
- 2. The test results are under chamber environment of A Test Lab Techno Corp. A Test Lab Techno Corp. does not assume responsibility for any conclusions and generalizations drawn from the test results with regard to other specimens or samples.
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Measurement Center Manager

Sam Chuang

**Testing Engineer** 

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### 1. <u>Description of Equipment Under Test (EUT)</u>

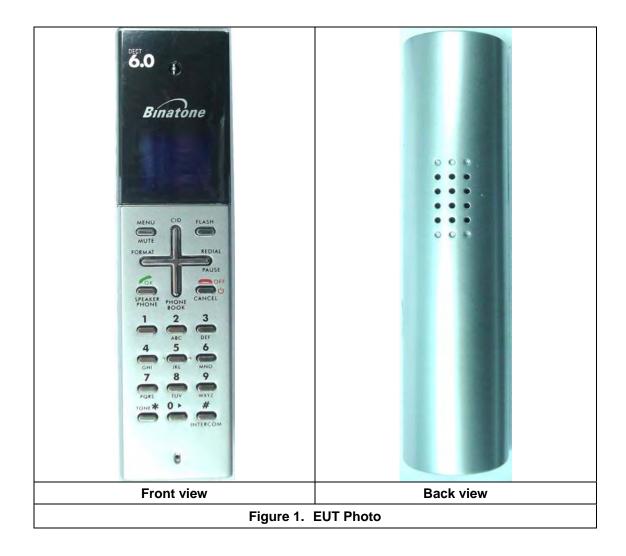
Applicant :

Binatone Electronics International Ltd. Floor 23A, 9 Des Voeux Road West, Sheung Wan, Hong Kong

Manufacturer Manufacturer Address		Huiyang CCT Telecommunications Products Co. Ltd. CCT Technology Park, San He Economic Developmental Zone, Huiyang District, Huizhou, Guangdong Province
EUT Type	:	1.9GHz DECT6.0 Cordless Phone
FCC ID	:	VLJIDECTX1I
Trade Name	:	iDECT
Model Name	:	iDECT X1i Twin
Battery Type	:	Ni-MH Battery (1.2V , 400mAh)
Test Device	:	Production Unit
Tx Frequency	:	1921.536 -1928.448 MHz ( UPCS )
Max. RF Conducted Power	:	0.114 W (20.57 dBm ) UPCS
Max. SAR Measurement	:	0.023 W/kg UPCS Head SAR
		0.027 W/kg UPCS Body SAR
HW Version	:	NA
SW Version	:	NA
Antenna Type	:	Internal Type
Antenna Gain	:	0dBi
Device Category	:	Portable
RF Exposure Environment	:	General Population / Uncontrolled
Battery Option	:	Standard
Application Type	:	Certification

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment / general population exposure limits specified in Standard C95.1-1999 and had been tested in accordance with the measurement procedures specified in IEEE Std. 1528-2003.







### 2. <u>Other Accessories</u>

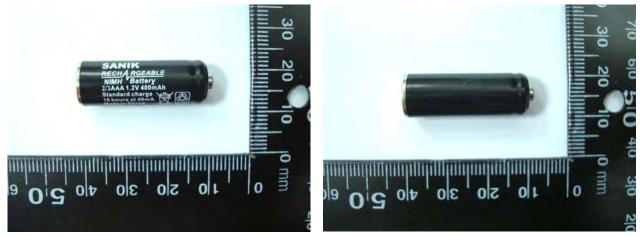


Figure 2. Battery (Ni-MH 1.2V, 400mAh)



Figure 3. Base



Figure 4. Base - AC Power



### 3. <u>Introduction</u>

The A Test Lab Techno Corp. has performed measurements of the maximum potential exposure to the user of **Binatone Electronics International Ltd. Trade Name : iDECT Model(s) : iDECT X1i Twin**. The test procedures, as described in American National Standards, Institute C95.1 - 1999 (1), FCC/OET Bulletin 65 Supplement C [July 2001] were employed and they specify the maximum exposure limit of 1.6mW/g as averaged over any 1 gram of tissue for portable devices being used within 20cm between user and EUT in the uncontrolled environment. A description of the product and operating configuration, detailed summary of the test results, methodology and procedures used in the equipment used are included within this test report.



### 4. SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dw) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (P). It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Figure 5).

$$SAR = \frac{d}{dt} \left( \frac{dw}{dm} \right) = \frac{d}{dt} \left( \frac{dw}{\rho dv} \right)$$

Figure 5. SAR Mathematical Equation

SAR is expressed in units of Watts per kilogram (W/kg)

$$SAR = \frac{\sigma E^2}{\rho}$$

Where :

 $\sigma$  = conductivity of the tissue (S/m)

 $\rho$  = mass density of the tissue (kg/m<sup>3</sup>)

E = RMS electric field strength (V/m)

#### \*Note:

The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane [2]



### 5. SAR Measurement Setup

These measurements were performed with the automated near-field scanning system DASY5 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9m) which positions the probes with a positional repeatability of better than  $\pm 0.02$ mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines (length = 300mm) to the data acquisition unit.

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and remote control, is used to drive the robot motors. The Measurement Server is based on a PC/104 CPU board with a 400MHz intel ULV Celeron, 128MB chipdisk and 128MB RAM. The necessary circuits for communication with either the DAE4 (or DAE3) electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY5 I/O-board, which is directly connected to the PC/104 bus of the CPU board. The PC consists of the Intel Core(TM)2 CPU @1.86GHz computer with Windows XP system and SAR Measurement Software DASY5, Post Processor SEMCAD, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection...etc. is connected to the Electro-optical converter (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the Measurement Server.



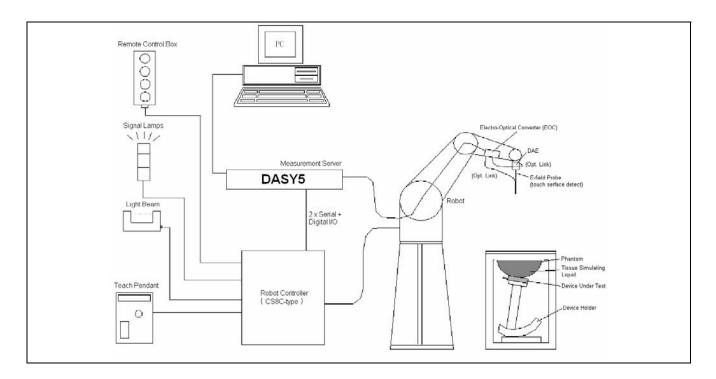


Figure 6. SAR Lab Test Measurement Setup

The DAE4 (or DAE3) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail in [3].



### 6. <u>System Components</u>

### 6.1 DASY5 E-Field Probe System

The SAR measurements were conducted with the dosimetric probe ES3DV3 or ET3DV6 (manufactured by SPEAG), designed in the classical triangular configuration [3] and optimized for dosimetric evaluation. The probes is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.



### 6.1.1 E-Field Probe Specification

Construction	Symmetrical design with triangular core				
	Built-in optical fiber for surface detection				
	System				
	Built-in shielding against static charges				
	PEEK enclosure material				
	(resistant to organic solvents, e.q., glycol)				
Calibration	In air from 10 MHz to 6 GHz				
	In brain and muscle simulating tissue at				
	frequencies of 450MHz, 900MHz, 1800MHz, 1950MHz,				
	2000MHz and 2450MHz (accuracy $\pm 8\%$ )				
	Calibration for other liquids and frequencies upon request				
Frequency	10 MHz to $>$ 6 GHz; Linearity: $\pm$ 0.2 dB				
	(30 MHz to 3 GHz)				
Directivity	$\pm 0.3$ dB in brain tissue (rotation around probe axis)				
	$\pm 0.5$ dB in brain tissue (rotation normal probe axis)				
Dynamic Range	10 $\mu$ W/g to > 100mW/g; Linearity: ±0.2dB				
Surface Detection	$\pm 0.2$ mm repeatability in air and clear liquids				
	over diffuse reflecting surface(ET3DV6 only)				
Dimensions	Overall length: 330mm				
	Tip length: 20mm				
	Body diameter: 12mm				
	Tip diameter: 2.5mm				
	Distance from probe tip to dipole centers: 1.0mm				
Application	General dosimetry up to 6GHz				
	Compliance tests of mobile phones				
	Fast automatic scanning in arbitrary phantoms				



Figure 7. E-field Probe



Figure 8. Probe setup on robot



#### 6.1.2 E-Field Probe Calibration

Each probe is calibrated according to a dosimetric assessment procedure described in [4] with accuracy better than  $\pm 10\%$ . The spherical isotropy was evaluated with the procedure described in [5] and found to be better than  $\pm 0.25$ dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1GHz, and in a wave guide above 1GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$\mathsf{SAR} = \mathsf{C}\frac{\Delta T}{\Delta t}$$

Where :

 $\Delta t$  = Exposure time (30 seconds),

- **C** = Heat capacity of tissue (head or body),
- $\Delta T$  = Temperature increase due to RF exposure.

$$\mathsf{SAR} = \frac{|\mathbf{E}|^2 \, \boldsymbol{\sigma}}{\boldsymbol{\rho}}$$

Where :

σ = Simulated tissue conductivity,

Or

 $\boldsymbol{\rho}$  = Tissue density (kg/m<sup>3</sup>).

### 6.2 Data Acquisition Electronic (DAE) System

#### Cell Controller

Processor :	Intel Core(TM)2 CPU
Clock Speed :	@ 1.86GHz
Operating System :	Windows XP Professional
Data Converter	
Features :	Signal Amplifier, multiplexer, A/D converter, and control logic
Software :	DASY5 v5.0 (Build 91) & SEMCAD X Version 12.4 Build 52
Connecting Lines :	Optical downlink for data and status info
	Optical uplink for commands and clock



### 6.3 Robot

Positioner :	Stäubli Unimation Corp. Robot Model: TX90XL			
Repeatability :	±0.02 mm			
No. of Axis:	6			

#### 6.4 Measurement Server

Processor :	PC/104 with a 400MHz intel ULV Celeron
I/O-board :	Link to DAE4(or DAE3)
	16-bit A/D converter for surface detection system
	Digital I/O interface
	Serial link to robot
	Direct emergency stop output for robot

#### 6.5 Device Holder for Transmitters

In combination with the SAM Twin Phantom V4.0, the Mounting Device (POM) enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation points is the ear opening. The devices can be easily, accurately, and repeat ably positioned according to the IEEE SCC34-SC2 and CENELEC specifications. The device holder can be locked at different phantom locations (left head, right head, and flat phantom).

**\*Note**: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produced infinite number of configurations [6]. To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.

Larger DUT cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values. Therefore those devices are normally only tested at the flat part of the SAM.

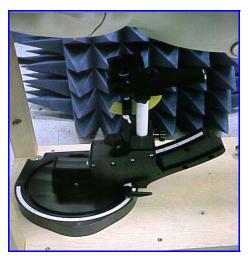


Figure 9. Device Holder



#### 6.6 Phantom - SAM v4.0

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-2003, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.



Figure 10.SAM Twin Phantom

Shell Thickness	2 ±0.2 mm
Filling Volume	Approx. 25 liters
Dimensions	810×1000×500 mm (H×L×W)

Table 1. Specification of SAM v4.0

#### 6.7 Data Storage and Evaluation

#### 6.7.1 Data Storage

The DASY5 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension .DA4. The postprocessing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.



#### 6.7.2 Data Evaluation

The DASY5 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software :

Probe parameters :	- Sensitivity	Normi, ai0, ai1, ai2
	- Conversion factor	ConvFi
	- Diode compression point	dcpi
Device parameters :	- Frequency	f
	- Crest factor	cf
Media parameters :	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as :

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with

h  $V_i$  = compensated signal of channel *i* (*i* = x, y, z)

 $U_i$  = input signal of channel *i* (*i* = x, y, z)

cf = crest factor of exciting field (DASY parameter)

*dcp*<sub>i</sub> = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated :

E-field probes :

$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$



#### H-field probes :

$$H_{i} = \sqrt{V_{i}} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^{2}}{f}$$

with 
$$V_i$$
 = compensated signal of channel *i* (*i* = x, y, z)

*Norm*<sub>i</sub> = sensor sensitivity of channel i (i = x, y, z)

 $\mu$  V/(V/m)<sup>2</sup> for E-field Probes

- ConvF = sensitivity enhancement in solution
- $a_{ij}$  = sensor sensitivity factors for H-field probes
- f = carrier frequency [GHz]
- $E_i$  = electric field strength of channel *i* in V/m
- Hi = magnetic field strength of channel *i* in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

 $E_{tot}$  = total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

**\*Note**: that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770}$$
 or  $P_{pwe} = \frac{H_{tot}^2}{37.7}$ 

with  $P_{pwe}$  = equivalent power density of a plane wave in mW/cm<sup>2</sup>

 $E_{tot}$  = total electric field strength in V/m

 $H_{tot}$  = total magnetic field strength in A/m



### 7. <u>Test Equipment List</u>

Manufacturer	Ianufacturer Name of Equipment		Serial Number	r Calibration Last Cal. Due Date		
SPEAG	Dosimetric E-Filed Probe	ET3DV3	3150	Jan. 09, 2008	Jan. 09, 2009	
SPEAG	SPEAG 1950MHz System Validation Kit		1117	Dec. 20, 2007	Dec. 20, 2008	
SPEAG	Data Acquisition Electronics	DAE4	779	Nov. 30, 2007	Nov. 30, 2008	
SPEAG	Device Holder	N/A	N/A	NCR	NCR	
SPEAG	Phantom	SAM V4.0	TP-1150	NCR	NCR	
SPEAG	Robot	Staubli TX90XL	F07/564ZA1/C/01	NCR	NCR	
SPEAG	Software	DASY5 V5.0 Build 91	N/A	NCR	NCR	
SPEAG	Software	SEMCAD V12.4 Build 52	N/A	NCR	NCR	
SPEAG	Measurement Server	SE UMS 011 AA	1025	NCR	NCR	
R & S	Wireless Communication Test Set	CMU200	112387	Apr. 02, 2007	Apr. 02, 2008	
Agilent	Agilent ENA Series Network Analyzer		MY42402996	Oct. 23, 2007	Oct. 23, 2008	
Agilent	Agilent Dielectric Probe Kit		US99360094	NCR	NCR	
Agilent	Power Meter	E4418B	GB40206143	May. 23, 2007	May. 23, 2008	
Agilent	Agilent Power Sensor		3318A20779	May. 28, 2007	May. 28, 2008	
Agilent	Agilent Signal Generator		3847A05201	May. 28, 2007	May. 28, 2008	
Agilent	Dual Directional Coupler	778D	50334	NCR	NCR	
Mini-Circuits	Power Amplifier	ZHL-42W-SMA	D111103#5	NCR	NCR	
Mini-Circuits	Power Amplifier	ZVE-8G-SMA	D042005 671800514	NCR	NCR	

Table 2. Test Equipment List



### 8. <u>Tissue Simulating Liquids</u>

The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue. The dielectric parameters of the liquids were verified prior to the SAR evaluation using an 85070C Dielectric Probe Kit and an 8720ES Network Analyzer.

INGREDIENT	FREQUENCY			
	HSL1.9GHz (Head)	MSL1.9GHz (Body)		
Water	55.41%	69.79%		
DGBE	44.51%	30.00%		
Salt	0.08%	0.20%		

Table 3. Recipes for Head & Body Tissue Simulating Liquids

#### IEEE SCC-34/SC-2 in 1528 recommended Tissue Dielectric Parameters

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in human head. Other head and body tissue parameters that have not been specified in 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equation and extrapolated according to the head parameter specified in 1528.



Target Frequency	He	ad	Body		
(MHz)	٤r	<b>σ</b> (S/m)	٤r	<b>σ</b> (S/m)	
150	52.3	0.76	61.9	0.80	
300	45.3	0.87	58.2	0.92	
450	43.5	0.87	56.7	0.94	
835	41.5	0.90	55.2	0.97	
900	41.5	0.97	55.0	1.05	
915	41.5	0.98	55.0	1.06	
1450	40.5	1.20	54.0	1.30	
1610	40.3	1.29	53.8	1.40	
1800 - 2000	40.0	1.40	53.3	1.52	
2450	39.2	1.80	52.7	1.95	
3000	38.5	2.40	52.0	2.73	
5800	35.3	5.27	48.2	6.00	
( $\boldsymbol{\epsilon}_{r}$ = relative permittivity, $\boldsymbol{\sigma}$ = conductivity and $\boldsymbol{\rho}$ = 1000 kg/m <sup>3</sup> )					

 Table 4. Tissue dielectric parameters for head and body phantoms

### 8.1 Liquid Confirmation

#### 8.1.1 Parameters

•	Liquid Verify Ambient Temperature : 22 ± 3 °C ; Relative Humidity : 40 -70%								
Liquid Type	Liquid Type Frequency Temp (°C) Parameters Target Value Value Deviation (%) Limit (%) Measured Date								
1950MHz	1950MHz 22.0		22.0	٤٢	40.0	40.5	1.25 %	±5%	Mar 12 2009
Head		σ	1.40	1.38	-1.43 %	±5%	Mar. 12, 2008		
1950MHz Body	/Hz	4050141	٤r	53.3	52.3	-1.88 %	±5%	Mar. 40, 0000	
	1950MHz	22.0	σ	1.52	1.53	0.66%	±5%	Mar. 12, 2008	

 Table 5. Measured Tissue dielectric parameters for head and body phantoms



### 8.1.2 Liquid Depth

The liquid level was during measurement 15cm  $\pm$ 0.5cm.

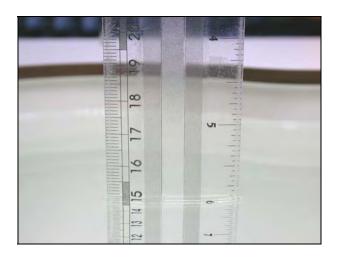


Figure 11. Head-Tissue-Simulating-Liquid

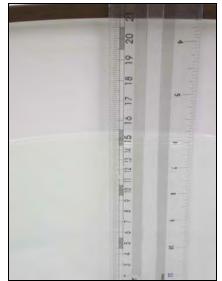


Figure 12. Body-Tissue-Simulating-Liquid



### 9. <u>Measurement Process</u>

### 9.1 Device and Test Conditions

The Test Device was provided by **Binatone Electronics International Ltd.** for this evaluation. The spatial peak SAR values were assessed for the lowest, middle and highest channels defined by UPCS (Ch0 = 1928.448MHz, Ch2 = 1924.992MHz, Ch4 = 1921.536MHz) systems. The antenna(s), battery and accessories shall be those specified by the manufacturer. The battery shall be fully charged before each measurement and there shall be no external connections.

Usage		Operates with a normal mode by client				
	ween antenna axis at the liquid surface:	For head, EUT left head, right head, to phantom 0mm separation. For Body, EUT back to phantom 0mm separation.				
Simulating h	uman Head/Body	Head and Body				
EUT Battery		Fully-charged with Ni-MH batteries.				
Conducted	Channel	Frequency MHz	Before SAR Test (dBm)	After SAR Test (dBm)		
power	Highest Channel - 0	1928.448	20.57	20.56		
	Middle Channel - 2	1924.992	20.42	20.40		
	Lowest Channel - 4	1921.536	20.36	20.34		

Note: The EUT take Ni-MH battery as its power source. Each test was preceded under the condition of fully-charged EUT.



### 9.2 System Performance Check

### 9.2.1 Symmetric Dipoles for System Validation

Symmetrical dipole with I/4 balun enables measurement of feed point impedance with NWA matched for use near flat phantoms filled with head simulating solutions Includes distance holder and tripod adaptor Calibration Calibrated SAR value for specified position and input
power at the flat phantom in head simulating solutions.
450, 900, 1800, 1950, 2000, 2450, 5200, 5600, 5800MHz
> 20 dB at specified validation position
> 100 W (f < 1GHz); > 40 W (f > 1GHz)
Dipoles for other frequencies or solutions and other
calibration conditions are available upon request
D450V2 : dipole length 270 mm; overall height 330 mm
D900V2 : dipole length 149 mm; overall height 330 mm
D1800V2 : dipole length 72 mm; overall height 300 mm
D1950V2 : dipole length 62 mm; overall height 300 mm
D2000V2 : dipole length 65 mm; overall height 300 mm
D2450V2 : dipole length 51.5 mm; overall height 300 mm
D5GHzV2 : dipole length 20.6 mm; overall height 450 mm



Figure 13. Validation Kit



### 9.2.2 Validation

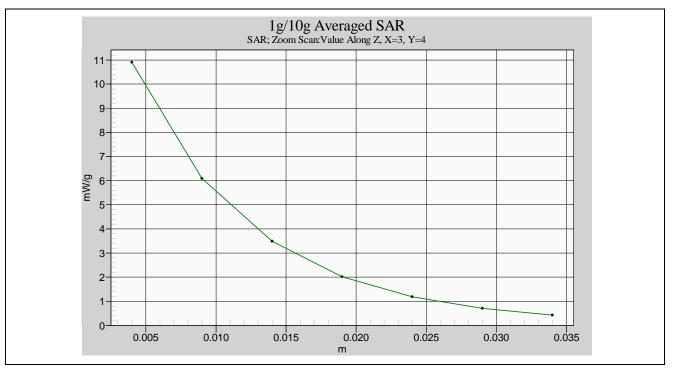
Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of  $\pm$  7%. The validation was performed at 1950MHz.

Validation kit		Mixture Type	SAF [mW	•	SAR <sub>10g</sub> [mW/g]		Date of Calibration	
D1950V3-SN1117		Head	40.0		20.96		Dec, 20, 2007	
D100010	ONTH?	Body	41.2		21.76		Dec, 20, 2007	
Frequency (MHz)	Power	SAR <sub>1g</sub>	SAR <sub>10g</sub>	Drift (dB)	Difference percentage		Date	
		(mW/g) (m\	(mW/g)	(UB)	1g	10g		
1950	250mW	9.7	5.02	0.024	-3.0 %	-4.2 %	Mar. 12, 2008	
(Head)	Normalize to 1 Watt	38.8	20.08	0.024	-5.0 /0	-4.2 /0	Mai. 12, 2000	
1950 (Body)	250mW	10.3	5.32	0.027	0.0 %	-2.2 %	Mar. 12, 2008	
	Normalize to 1 Watt	41.2	21.28	0.027	0.0 %	-2.2 /0	iviai. 12, 2000	

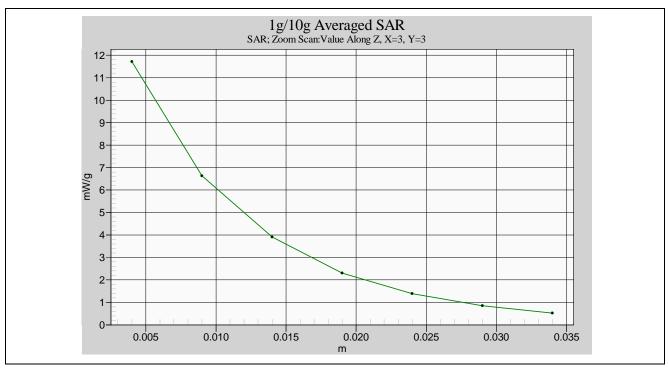
Detail results see Appendix A.







Head-Tissue-Simulating-Liquid 2GHz







### 9.3 Dosimetric Assessment Setup

#### 9.3.1 Headset Test Position - Body-Worn

#### **Body-Worn Configuration**

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a handset output should be tested with a handset connected to the device.

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. For this test :

- The EUT is placed into the holster/belt clip and the holster is positioned against the surface of the phantom in a normal operating position.
- Since this EUT doesn't supply any body-worn accessory to the end user, a distance of 2 mm was tested to confirm the necessary "minimum SAR separation distance".
- (\*Note : This distance includes the 2 mm phantom shell thickness.)



#### 9.3.2 Measurement Procedures

The evaluation was performed with the following procedures :

- Surface Check : A surface check job gathers data used with optical surface detection. It determines the distance from the phantom surface where the reflection from the optical detector has its peak. Any following measurement jobs using optical surface detection will then rely on this value. The surface check performs its search a specified number of times, so that the repeatability can be verified. The probe tip distance is 1.3mm to phantom inner surface during scans.
- **Reference :** The reference job measures the field at a specified reference position, at 4 mm from the selected section's grid reference point.
- Area Scan : The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines can find the maximum locations even in relatively coarse grids. When an area scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. Any following zoom scan within the same procedure will then perform fine scans around these maxima. The area covered the entire dimension of the EUT and the horizontal grid spacing was 15 mm × 15 mm.
- Zoom Scan : Zoom scans are used to assess the highest averaged SAR for cubic averaging volumes with 1 g and 10 g of simulated tissue. The zoom scan measures 5 x 5 x 7 points in a 32 x 32 x 30 mm cube whose base faces are centered around the maxima returned from a preceding area scan within the same procedure.
- **Drift :** The drift job measures the field at the same location as the most recent reference job within the same procedure, with the same settings. The drift measurement gives the field difference in dB from the last reference measurement. Several drift measurements are possible for each reference measurement. This allows monitoring of the power drift of the device in the batch process. If the value changed by more than 5%, the evaluation was repeated.



### 9.4 Spatial Peak SAR Evaluation

The DASY5 software includes all numerical procedures necessary to evaluate the spatial peak SAR values. Based on the Draft: SCC-34, SC-2, WG-2 - Computational Dosimetry, IEEE P1529/D0.0 (Draft Recommended Practice for Determining the Spatial-Peak Specific Absorption Rate (SAR) Associated with the Use of Wireless Handsets - Computational Techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement in a volume of (32×32×30)mm<sup>3</sup> (5×5×7 points). The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan. If the 10g cube or both cubes are not entirely inside the measured volumes, the system issues a warning regarding the evaluated spatial peak values within the Postprocessing engine (SEMCAD). This means that if the measured volume is shifted, higher values might be possible. To get the correct values you can use a finer measurement grid for the area scan. In complicated field distributions, a large grid spacing for the area scan might miss some details and give an incorrectly interpolated peak location.

The entire evaluation of the spatial peak values is performed within the Postprocessing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into three stages:

#### Interpolation and Extrapolation

The probe is calibrated at the center of the dipole sensors which is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated.

In DASY5, the choice of the coordinate system defining the location of the measurement points has no influence on the uncertainty of the interpolation, Maxima Search and SAR extrapolation routines. The interpolation, Maxima Search and extrapolation routines are all based on the modified Quadratic Shepard's method [7].



### 10. Measurement Uncertainty

Measurement uncertainties in SAR measurements are difficult to quantify due to several variables including biological, physiological, and environmental. However, we estimate the measurement uncertainties in SAR to be less than  $\pm 21.9 \%$  [8].

According to Std. C95.3 [9], the overall uncertainties are difficult to assess and will vary with the type of meter and usage situation. However, accuracy's of  $\pm 1$  to 3 dB can be expected in practice, with greater uncertainties in near-field situations and at higher frequencies (shorter wavelengths), or areas where large reflecting objects are present. Under optimum measurement conditions, SAR measurement uncertainties of at least  $\pm 2$ dB can be expected.

According to CENELEC [10], typical worst-case uncertainty of field measurements is  $\pm 5$  dB. For well-defined modulation characteristics the uncertainty can be reduced to  $\pm 3$  dB.



Error Description	Uncertainty value	Prob. Dist.	Div.	( <i>ci</i> ) 1g	( <i>ci</i> ) 10g	Std. Unc. (1g)	Std. Unc. (10g)	(vi) veff
Measurement System								
Probe Calibration	± 5.9 %	Ν	1	1	1	± 5.9 %	± 5.9 %	
Axial Isotropy	± 4.7 %	R		0.7	0.7	± 1.9 %	± 1.9 %	$\infty$
Hemispherical Isotropy	± 9.6 %	R	$\sqrt{3}$	0.7	0.7	± 3.9 %	± 3.9 %	$\infty$
Boundary Effects	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	$\infty$
Linearity	± 4.7 %	R	$\sqrt{3}$	1	1	± 2.7 %	± 2.7 %	$\infty$
System Detection Limits	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	$\infty$
Readout Electronics	± 0.3 %	N	1	1	1	± 0.3 %	± 0.3 %	$\infty$
Response Time	± 0.8 %	R	$\sqrt{3}$	1	1	± 0.5 %	± 0.5 %	$\infty$
Integration Time	± 2.6 %	R	$\sqrt{3}$	1	1	± 1.5 %	± 1.5 %	$\infty$
RF Ambient Noise	± 3.0 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	$\infty$
RF Ambient Reflections	± 3.0 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	$\infty$
Probe Positioner	± 0.4 %	R	$\sqrt{3}$	1	1	± 0.2 %	± 0.2 %	$\infty$
Probe Positioning	± 2.9 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	$\infty$
Max. SAR Eval.	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	$\infty$
Test Sample Related				•			•	
Device Positioning	± 2.9 %	Ν	1	1	1	± 2.9 %	± 2.9 %	145
Device Holder	± 3.6 %	Ν	1	1	1	± 3.6 %	± 3.6 %	5
Power Drift	± 5.0 %	R	$\sqrt{3}$	1	1	± 2.9 %	± 2.9 %	$\infty$
Phantom and Setup				•			•	
Phantom Uncertainty	± 4.0 %	R	$\sqrt{3}$	1	1	± 2.3 %	2.3 %	$\infty$
Liquid Conductivity (target)	± 5.0 %	R	$\sqrt{3}$	0.64	0.43	± 1.8 %	1.2 %	$\infty$
Liquid Conductivity (meas.)	± 2.5 %	N	1	0.64	0.43	± 1.6 %	1.1 %	$\infty$
Liquid Permittivity (target)	± 5.0 %	R	$\sqrt{3}$	0.6	0.49	± 1.7 %	1.4 %	$\infty$
Liquid Permittivity (meas.)	± 2.5 %	N	1	0.6	0.49	± 1.5 %	1.2 %	$\infty$
Combined Std. Uncertainty					± 10.9 %	± 10.7 %	387	
Expanded STD Uncertainty					± 21.9 %	± 21.4 %		

Table 6. Uncertainty Budget of DASY



### 11. SAR Test Results Summary

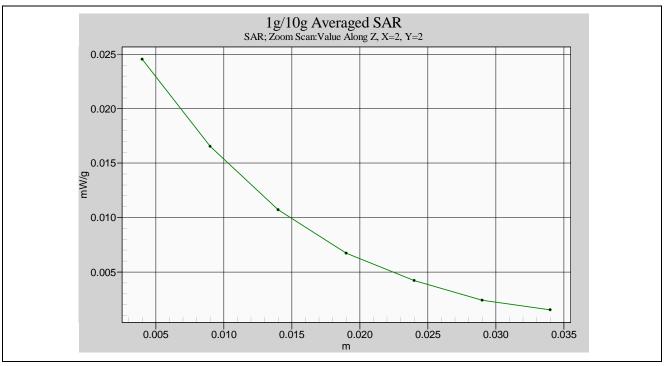
### 11.1 UPCS Head SAR

Ambient : Temperature	<b>∍(</b> ℃)∶	22	<u>± 3 Rel</u>	ative HUMI	): (%) TIC			40 -	70	
Liquid : Mixture Type	9:	HSL	HSL1950Liquid Temperature (°C) :Depth of liquid (cm) :					<u> </u>		
Measuremen Crest Factor	be S/N:			_	31	50				
Frequen	су	Battery	Phantom	Accessory	SAR₁g [mW/g]	Power Drift	Temp.		Remark	
MHz	СН	Dattery	Position	Position		(dB)	Amb.	Liq.		
1928.448	0	Ni-MH	Right-Cheek	N/A	0.022	0.189	22.0	22.0	-	
1924.992	2	Ni-MH	Right-Cheek	N/A	0.023	-0.139	22.0	22.0	-	
1921.536	4	Ni-MH	Right-Cheek	N/A	0.022	-0.184	22.0	22.0	-	
1928.448	0	Ni-MH	<b>Right-Tilted</b>	N/A	0.012	0.144	22.0	22.0	-	
1924.992	2	Ni-MH	<b>Right-Tilted</b>	N/A	0.012	-0.049	22.0	22.0	-	
1921.536	4	Ni-MH	<b>Right-Tilted</b>	N/A	0.016	0.033	22.0	22.0	-	
1928.448	0	Ni-MH	Left-Cheek	N/A	0.020	0.181	22.0	22.0	-	
1924.992	2	Ni-MH	Left-Cheek	N/A	0.020	0.133	22.0	22.0	-	
1921.536	4	Ni-MH	Left-Cheek	N/A	0.021	0.187	22.0	22.0	-	
1928.448	0	Ni-MH	Left-Tilted	N/A	0.013	0.155	22.0	22.0	-	
1924.992	2	Ni-MH	Left-Tilted	N/A	0.012	0.062	22.0	22.0	-	
1921.536	4	Ni-MH	Left-Tilted	N/A	0.013	0.020	22.0	22.0	-	
Uncon	Std. C95.1-1999 - Safety Limit Spatial Peak Uncontrolled Exposure/General Population					1.6 W/I Averaged				

Detail results see Appendix B.



### Z-axis Plot of SAR Measurement



SAR Measurement \_ Right Cheek CH2

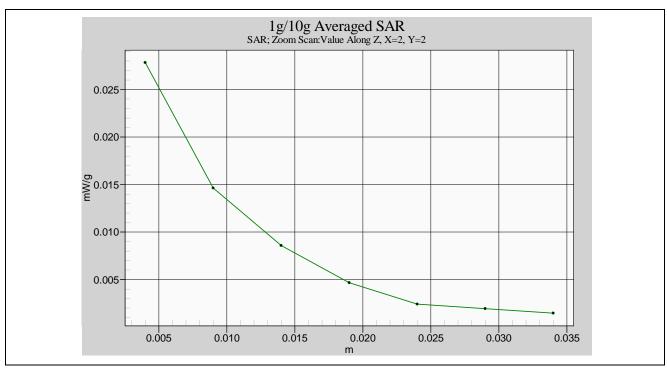


### 11.2 UPCS Body SAR

Ambient : Tempera		c):	22 ± 3	Relative	HUMIDITY		40-70			
Liquid : Mixture	Туре :	_	MSL1950	Liquid T		22.0 15				
Measuren Crest Fa		_	24	Probe S/N :					3150	
Frequer	псу	Battery	Phantom	Accessory	SAR <sub>1g</sub>	Power Drift (dB)	Temp.		Remark	
MHz	СН	Battery	Position		[mW/g]		Amb.	Liq.	Nemark	
1928.448	0	Ni-MH	Flat	N/A	0.025	0.167	22.0	22.0	-	
1924.992	2	Ni-MH	Flat	N/A	0.027	0.150	22.0	22.0	-	
1921.536	4	Ni-MH	Flat	N/A	0.026	0.186	22.0	22.0	-	
Uncon	Std. C95.1-1999 - Safety Limit Spatial Peak Uncontrolled Exposure/General Population					1.6 W Average	//kg (m\ ed over			

Detail results see Appendix B.

### Z-axis Plot of SAR Measurement



#### SAR Measurement \_ Flat CH2



### 11.3 EUT Steup Up Phote

**UPCS Head SAR** 

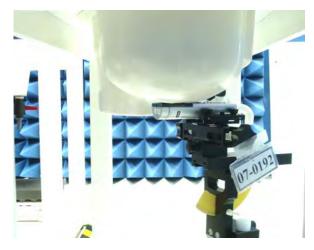


Figure 14. Right Head SAR Test Setup (Cheek)

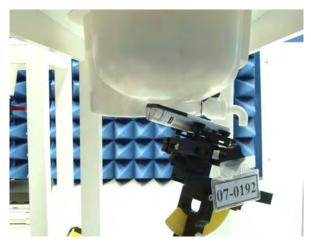


Figure 15. Right Head SAR Test Setup (Tilted)



Figure 16. Left Head SAR Test Setup (Cheek)

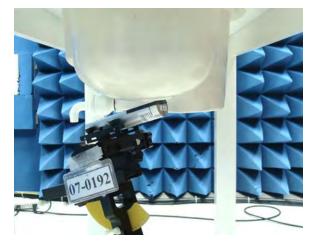


Figure 17. Left Head SAR Test Setup (Tilted)



### UPCS Body SAR



Figure 18. Body SAR Test Setup\_ (Flat Section)



Human Exposure	Population Uncontrolled Exposure ( W/kg ) or (mW/g)	Occupational Controlled Exposure ( W/kg ) or (mW/g)	
Spatial Peak SAR* (head)	1.60	8.00	
Spatial Peak SAR** (Whole Body)	0.08	0.40	
Spatial Peak SAR*** (Partial-Body)	1.60	8.00	
Spatial Peak SAR**** (Hands / Feet / Ankle / Wrist )	4.00	20.00	

#### 11.4 Std. C95.1-1999 RF Exposure Limit

Table 7. Safety Limits for Partial Body Exposure

#### Notes :

- \* The Spatial Peak value of the SAR averaged over any 1 gram of tissue.
   ( defined as a tissue volume in the shape of a cube ) and over the appropriate averaging time.
- \*\* The Spatial Average value of the SAR averaged over the whole body.
- \*\*\* The Spatial Average value of the SAR averaged over the partial body.
- \*\*\*\* The Spatial Peak value of the SAR averaged over any 10 grams of tissue.( defined as a tissue volume in the shape of a cube ) and over the appropriate averaging time.

**Population / Uncontrolled Environments :** are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

*Occupational / Controlled Environments :* are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).



### 12. <u>Conclusion</u>

The SAR test values found for the portable mobile phone **Binatone Electronics International Ltd. Trade** Name: iDECT Model(s): iDECT X1i Twin are below the maximum recommended level of 1.6 W/kg (mW/g).



## 13. <u>References</u>

- [1] Std. C95.1-1999, "American National Standard safety levels with respect to human exposure to radio frequency electromagnetic fields, 300KHz to 100GHz", New York.
- [2] NCRP, National Council on Radiation Protection and Measurements, "*Biological Effects and Exposure Criteria for Radio frequency Electromagnetic Fields*", NCRP report NO. 86, 1986.
- [3] T. Schmid, O. Egger, and N. Kuster, "Automatic E-field scanning system for dosimetric assessments", IEEE Transactions on Microwave Theory and Techniques, vol. 44, pp, 105-113, Jan. 1996.
- [4] K. Poković, T. Schmid, and N. Kuster, "Robust setup for precise calibration of E-field probes in tissue simulating liquids at mobile communications frequency", in ICECOM'97, Dubrovnik, October 15-17, 1997, pp.120-124.
- [5] K. Poković, T. Schmid, and N. Kuster, "*E-field probe with improved isotropy in brain simulating liquids*", in Proceedings of the ELMAR, Zadar, Croatia, 23-25 June, 1996, pp.172-175.
- [6] N. Kuster, and Q. Balzano, "Energy absorption mechanism by biological bodies in the near field of dipole antennas above 300MHz", IEEE Transaction on Vehicular Technology, vol. 41, no. 1, Feb. 1992, pp. 17-23.
- [7] Robert J. Renka, "*Multivariate Interpolation Of Large Sets Of Scattered Data*", University of North Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148.
- [8] N. Kuster, R. Kastle, T. Schmid, Dosimetric evaluation of mobile communications equipment with known precision, IEEE Transaction on Communications, vol. E80-B, no. 5, May 1997, pp. 645-652.
- [9] Std. C95.3-1991, "IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave, New York: IEEE, Aug. 1992.
- [10]CENELEC CLC/SC111B, European Prestandard (prENV 50166-2), *Human Exposure to Electromagnetic Fields High-frequency*: 10KHz-300GHz, Jan. 1995.



# Appendix A - System Performance Check

See following Attached Pages for System Performance Check.



Date/Time: 3/12/2008 11:39:19 AMDate/Time: 3/12/2008 11:46:29 AM

## System Performance Check at 1950MHz\_20080312\_Head

#### DUT: Dipole 1950 MHz; Type: D1950V3; Serial: D1950V3 - SN:1117

Communication System: CW; Frequency: 1950 MHz;Duty Cycle: 1:1 Medium parameters used: f = 1950 MHz;  $\sigma = 1.38$  mho/m;  $\varepsilon_r = 40.5$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

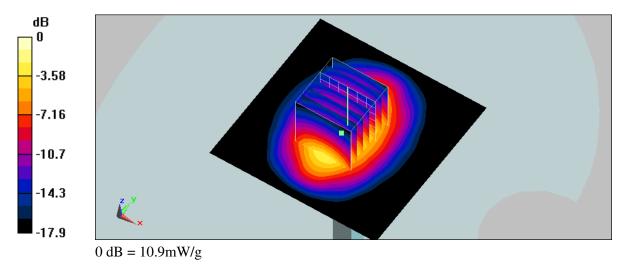
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### System Performance Check at 1950MHz/Area Scan (61x61x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 11.1 mW/g

#### System Performance Check at 1950MHz/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 91.2 V/m; Power Drift = 0.024 dB Peak SAR (extrapolated) = 17.7 W/kg SAR(1 g) = 9.7 mW/g; SAR(10 g) = 5.02 mW/g Maximum value of SAR (measured) = 10.9 mW/g



1/2



Date/Time: 3/12/2008 7:04:37 PMDate/Time: 3/12/2008 7:09:05 PM

## System Performance Check at 1950MHz\_20080312\_Body

#### DUT: Dipole 1950 MHz; Type: D1950V3; Serial: D1950V3 - SN:1117

Communication System: CW; Frequency: 1950 MHz;Duty Cycle: 1:1 Medium parameters used: f = 1950 MHz;  $\sigma = 1.53$  mho/m;  $\varepsilon_r = 52.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

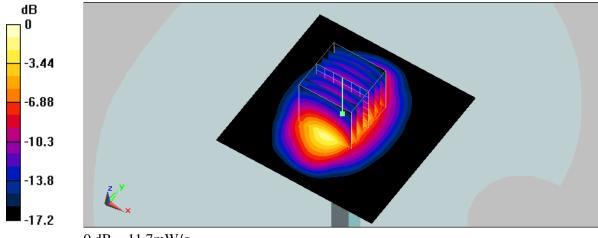
- Probe: ES3DV3 SN3150; ConvF(4.55, 4.55, 4.55); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

#### System Performance Check at 1950MHz/Area Scan (61x61x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 11.8 mW/g

#### System Performance Check at 1950MHz/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 86 V/m; Power Drift = 0.027 dB Peak SAR (extrapolated) = 19.1 W/kg SAR(1 g) = 10.3 mW/g; SAR(10 g) = 5.32 mW/g Maximum value of SAR (measured) = 11.7 mW/g



 $0 \, dB = 11.7 \, mW/g$ 



## Appendix B - SAR Measurement Data

See following Attached Pages for SAR Measurement Data.



Date/Time: 3/12/2008 4:34:54 PMDate/Time: 3/12/2008 4:48:25 PM

## **RC\_Dect CH0**

### DUT: iDECT X1i Twin; Type: 1.9GHz DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1928.448 MHz;Duty Cycle: 1:24 Medium parameters used (interpolated): f = 1928.448 MHz;  $\sigma$  = 1.36 mho/m;  $\varepsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

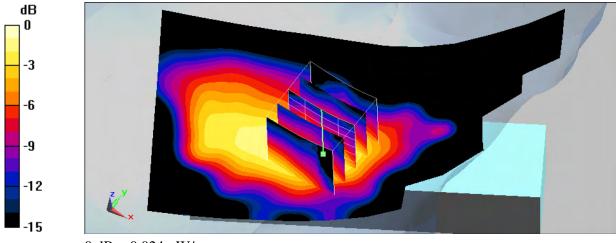
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

## Right Cheek/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.026 mW/g

### **Right Cheek/Zoom Scan (5x5x7)/Cube 0:**

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.31 V/m; Power Drift = 0.189 dB Peak SAR (extrapolated) = 0.035 W/kg SAR(1 g) = 0.022 mW/g; SAR(10 g) = 0.013 mW/g Maximum value of SAR (measured) = 0.024 mW/g



 $0 \, dB = 0.024 \, mW/g$ 



Date/Time: 3/12/2008 2:23:02 PMDate/Time: 3/12/2008 2:30:25 PM

## **RC\_Dect CH2**

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1924.992 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1924.992 MHz;  $\sigma$  = 1.36 mho/m;  $\varepsilon_r$ = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

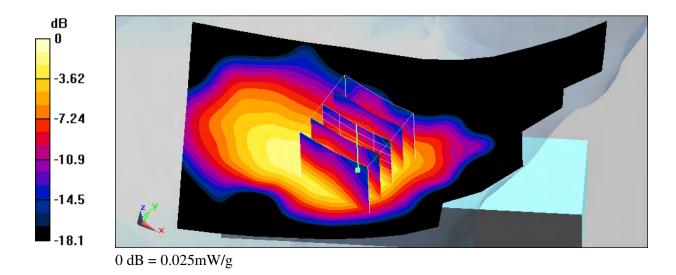
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

### **Right Cheek/Area Scan (61x111x1):**

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.026 mW/g

### **Right Cheek/Zoom Scan (5x5x7)/Cube 0:**

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 3.24 V/m; Power Drift = -0.139 dB Peak SAR (extrapolated) = 0.035 W/kg SAR(1 g) = 0.023 mW/g; SAR(10 g) = 0.013 mW/g Maximum value of SAR (measured) = 0.025 mW/g





Date/Time: 3/12/2008 12:13:33 PMDate/Time: 3/12/2008 12:20:54 PM

## **RC\_Dect CH4**

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1921.536 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1921.536 MHz;  $\sigma$  = 1.36 mho/m;  $\epsilon_r$ = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

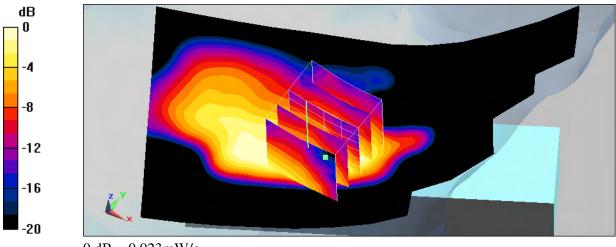
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

### **Right Cheek/Area Scan (61x111x1):**

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.044 mW/g

### **Right Cheek/Zoom Scan (5x5x7)/Cube 0:**

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 3.26 V/m; Power Drift = -0.184 dB Peak SAR (extrapolated) = 0.033 W/kg SAR(1 g) = 0.022 mW/g; SAR(10 g) = 0.013 mW/g Maximum value of SAR (measured) = 0.023 mW/g



 $0 \, dB = 0.023 \, mW/g$ 



Date/Time: 3/12/2008 4:56:21 PMDate/Time: 3/12/2008 5:03:42 PM

## **RT\_Dect CH0**

#### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1928.448 MHz;Duty Cycle: 1:24 Medium parameters used (interpolated): f = 1928.448 MHz;  $\sigma$  = 1.36 mho/m;  $\varepsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

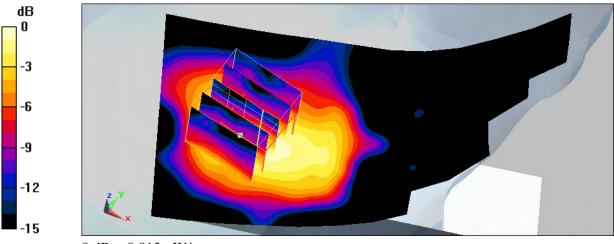
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

### **Right Tilted/Area Scan (61x111x1):**

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.013 mW/g

### Right Tilted/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.02 V/m; Power Drift = 0.144 dB Peak SAR (extrapolated) = 0.020 W/kg SAR(1 g) = 0.012 mW/g; SAR(10 g) = 0.00697 mW/g Maximum value of SAR (measured) = 0.013 mW/g



 $0 \, dB = 0.013 \, mW/g$ 



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## **RT\_Dect CH2**

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1924.992 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1924.992 MHz;  $\sigma$  = 1.36 mho/m;  $\epsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

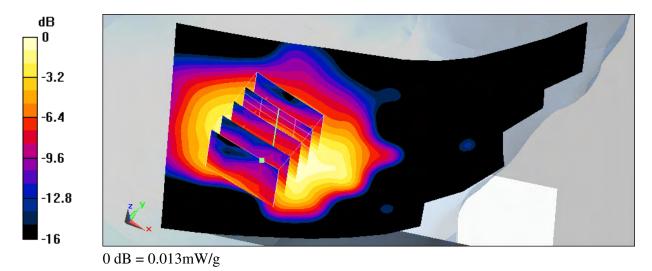
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

## **Right Tilted/Area Scan (61x111x1):**

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.013 mW/g

### **Right Tilted/Zoom Scan (5x5x7)/Cube 0:**

Measurement grid: dx=8mm, dy=8mm, dz=5mmReference Value = 3.04 V/m; Power Drift = -0.049 dB Peak SAR (extrapolated) = 0.017 W/kg SAR(1 g) = 0.012 mW/g; SAR(10 g) = 0.00712 mW/g Maximum value of SAR (measured) = 0.013 mW/g



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## **RT\_Dect CH4**

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1921.536 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1921.536 MHz;  $\sigma$  = 1.36 mho/m;  $\epsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

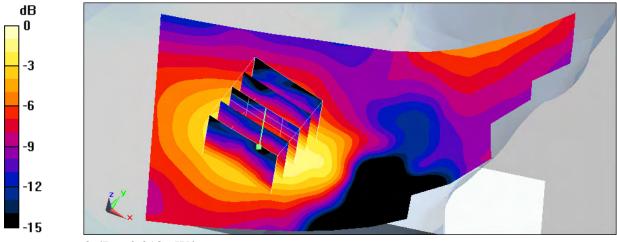
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

## **Right Tilted/Area Scan (61x111x1):**

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.017 mW/g

### **Right Tilted/Zoom Scan (5x5x7)/Cube 0:**

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.42 V/m; Power Drift = 0.033 dB Peak SAR (extrapolated) = 0.024 W/kg SAR(1 g) = 0.016 mW/g; SAR(10 g) = 0.00964 mW/g Maximum value of SAR (measured) = 0.018 mW/g



 $0 \, dB = 0.018 \, mW/g$ 



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## LC\_Dect CH0

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1928.448 MHz;Duty Cycle: 1:24 Medium parameters used (interpolated): f = 1928.448 MHz;  $\sigma$  = 1.36 mho/m;  $\varepsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

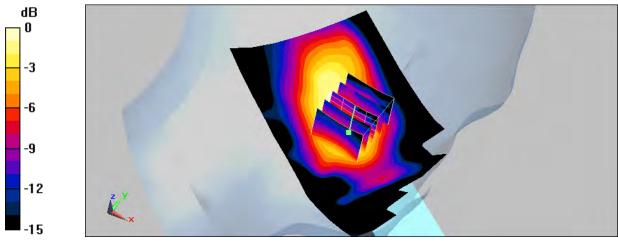
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

## Left Cheek/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.025 mW/g

### Left Cheek/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.27 V/m; Power Drift = 0.181 dB Peak SAR (extrapolated) = 0.031 W/kg SAR(1 g) = 0.020 mW/g; SAR(10 g) = 0.012 mW/g Maximum value of SAR (measured) = 0.022 mW/g



 $0 \, dB = 0.022 mW/g$ 



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# LC\_Dect CH2

## DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1924.992 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1924.992 MHz;  $\sigma$  = 1.36 mho/m;  $\epsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

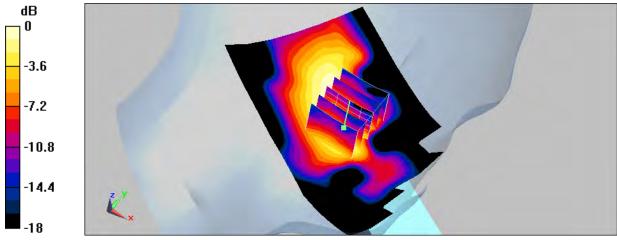
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

## Left Cheek/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.027 mW/g

## Left Cheek/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.36 V/m; Power Drift = 0.133 dB Peak SAR (extrapolated) = 0.031 W/kg SAR(1 g) = 0.020 mW/g; SAR(10 g) = 0.012 mW/g Maximum value of SAR (measured) = 0.022 mW/g



 $0 \, dB = 0.022 \, mW/g$ 



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## LC\_Dect CH4

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1921.536 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1921.536 MHz;  $\sigma$  = 1.36 mho/m;  $\epsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

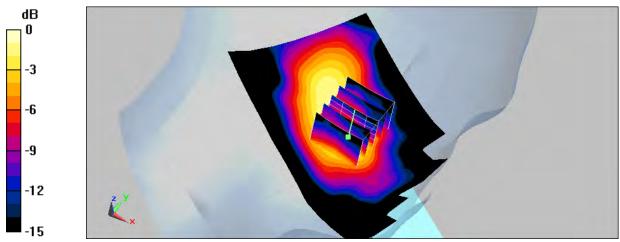
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

### Left Cheek/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.026 mW/g

### Left Cheek/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.39 V/m; Power Drift = 0.187 dB Peak SAR (extrapolated) = 0.034 W/kg SAR(1 g) = 0.021 mW/g; SAR(10 g) = 0.012 mW/g Maximum value of SAR (measured) = 0.023 mW/g



 $0 \, dB = 0.023 \, mW/g$ 



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## LT\_Dect CH0

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1928.448 MHz;Duty Cycle: 1:24 Medium parameters used (interpolated): f = 1928.448 MHz;  $\sigma$  = 1.36 mho/m;  $\varepsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

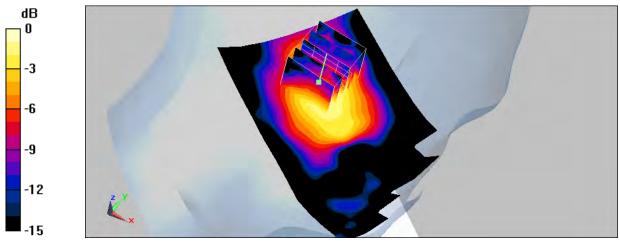
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

## Left Tilted/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mmMaximum value of SAR (interpolated) = 0.014 mW/g

### Left Tilted/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.05 V/m; Power Drift = 0.155 dB Peak SAR (extrapolated) = 0.019 W/kg SAR(1 g) = 0.013 mW/g; SAR(10 g) = 0.00754 mW/g Maximum value of SAR (measured) = 0.014 mW/g



0 dB = 0.014 mW/g



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# LT\_Dect CH2

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1924.992 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1924.992 MHz;  $\sigma$  = 1.36 mho/m;  $\epsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

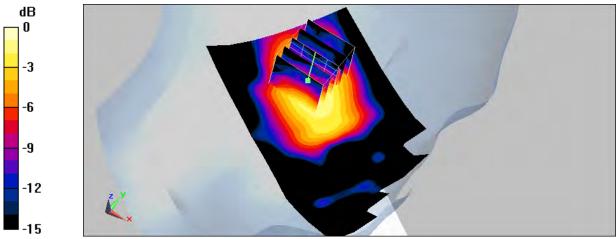
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

## Left Tilted/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.014 mW/g

## Left Tilted/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.11 V/m; Power Drift = 0.062 dB Peak SAR (extrapolated) = 0.020 W/kg SAR(1 g) = 0.012 mW/g; SAR(10 g) = 0.00725 mW/g Maximum value of SAR (measured) = 0.014 mW/g



 $0 \, dB = 0.014 \, mW/g$ 



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# LT\_Dect CH4

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1921.536 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1921.536 MHz;  $\sigma$  = 1.36 mho/m;  $\epsilon_r$  = 40.6;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Left Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

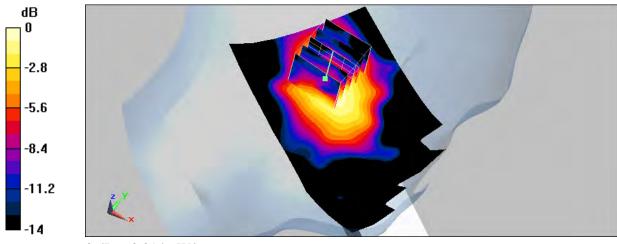
- Probe: ES3DV3 SN3150; ConvF(4.84, 4.84, 4.84); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

## Left Tilted/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.015 mW/g

### Left Tilted/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.21 V/m; Power Drift = 0.020 dB Peak SAR (extrapolated) = 0.019 W/kg SAR(1 g) = 0.013 mW/g; SAR(10 g) = 0.00765 mW/g Maximum value of SAR (measured) = 0.014 mW/g



 $0 \, dB = 0.014 \, mW/g$ 



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## Flat\_Dect CH0

#### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1928.448 MHz;Duty Cycle: 1:24 Medium parameters used (interpolated): f = 1928.448 MHz;  $\sigma$  = 1.51 mho/m;  $\varepsilon_r$  = 52.4;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

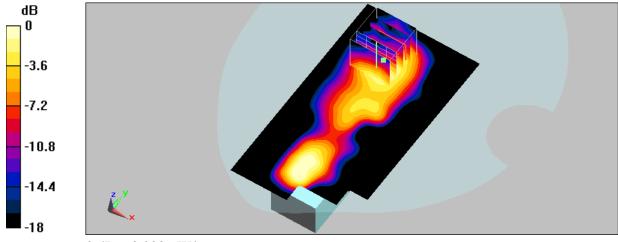
- Probe: ES3DV3 SN3150; ConvF(4.55, 4.55, 4.55); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

### Flat/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.036 mW/g

### Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.56 V/m; Power Drift = 0.167 dB Peak SAR (extrapolated) = 0.049 W/kg SAR(1 g) = 0.025 mW/g; SAR(10 g) = 0.015 mW/g Maximum value of SAR (measured) = 0.028 mW/g



0 dB = 0.028 mW/g



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## Flat\_Dect CH2

#### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1924.992 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1924.992 MHz;  $\sigma$  = 1.51 mho/m;  $\epsilon_r$  = 52.4;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

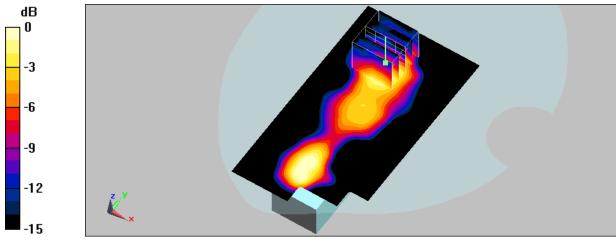
- Probe: ES3DV3 SN3150; ConvF(4.55, 4.55, 4.55); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

### Flat/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.041 mW/g

### Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.62 V/m; Power Drift = 0.150 dB Peak SAR (extrapolated) = 0.054 W/kg SAR(1 g) = 0.027 mW/g; SAR(10 g) = 0.014 mW/g Maximum value of SAR (measured) = 0.028 mW/g



 $0 \, dB = 0.028 \, mW/g$ 



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## Flat\_Dect CH4

### DUT: iDECT X1i Twin; Type: 1.9GH DECT6.0 Cordless Phone; FCC ID: VLJIDECTX1I

Communication System: DECT; Frequency: 1921.536 MHz;Duty Cycle: 1:24 Medium parameters used: f = 1921.536 MHz;  $\sigma$  = 1.5 mho/m;  $\epsilon_r$  = 52.4;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

DASY5 Configuration:

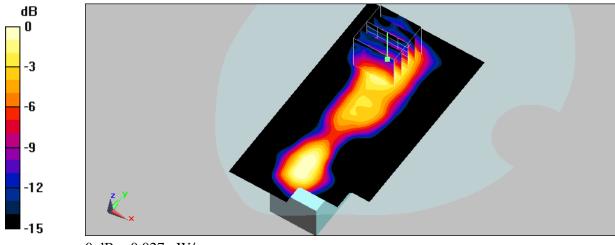
- Probe: ES3DV3 SN3150; ConvF(4.55, 4.55, 4.55); Calibrated: 1/9/2008
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn779; Calibrated: 11/30/2007
- Phantom: SAM with CRP; Type: SAM; Serial: TP-1150 and higher
- Measurement SW: DASY5, V5.0 Build 91; SEMCAD X Version 12.4 Build 52

### Flat/Area Scan (61x111x1):

Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (interpolated) = 0.038 mW/g

### Flat/Zoom Scan (5x5x7)/Cube 0:

Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 3.65 V/m; Power Drift = 0.186 dB Peak SAR (extrapolated) = 0.054 W/kg SAR(1 g) = 0.026 mW/g; SAR(10 g) = 0.014 mW/g Maximum value of SAR (measured) = 0.027 mW/g



 $0 \, dB = 0.027 \, mW/g$ 



# Appendix C - Calibration

All of the instruments Calibration information are listed below.

- Dipole \_ D1950V3 SN:1117 Calibration No.D1950V3-1117\_Dec07
- Probe \_ ET3DV3SN:3150 Calibration No.ET3-3150\_Jan08
- DAE \_ DAE4 SN:779Calibration No.DAE4-779\_Nov07