

### SAR TEST REPORT

**REPORT NO.:** SA960427H06

**MODEL NO.:** 164-R9570

**RECEIVED:** Apr. 27, 2007

**TESTED:** May 18, 2007

**ISSUED:** May 22, 2007

**APPLICANT:** Teradyne Diagnostic Solutions Ltd

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No.: 2177-01



## **TABLE OF CONTENTS**

1.	CERTIFICATION	
2.	GENERAL INFORMATION	
2.1	GENERAL DESCRIPTION OF EUT	.4
2.2	GENERAL DESCRIPTION OF APPLIED STANDARDS	.5
2.3	GENERAL INOFRMATION OF THE SAR SYSTEM	.5
2.4	GENERAL DESCRIPTION OF THE SPATIAL PEAK SAR EVALUATION	.8
3.	DESCRIPTION OF SUPPORT UNITS	
4.	DESCRIPTION OF TEST MODES AND CONFIGURATIONS	
	DESCRIPTION OF ANTENNA LOCATION	
	DESCRIPTION OF ASSESSMENT POSITION	
	DESCRIPTION OF TEST MODE	
4.4.	SUMMARY OF TEST RESULTS	
5.	TEST RESULTS	
5.1	TEST PROCEDURES	
5.2	MEASURED SAR RESULTS	
5.3	SAR LIMITS	18
5.4	RECIPES FOR TISSUE SIMULATING LIQUIDS	
5.5	TEST EQUIPMENT FOR TISSUE PROPERTY	
6.	SYSTEM VALIDATION	
6.1	TEST EQUIPMENT	
6.2	TEST PROCEDURE	
6.3	VALIDATION RESULTS	25
6.4	SYSTEM VALIDATION UNCERTAINTIES	
7.	MEASUREMENT SAR PROCEDURE UNCERTAINTIES	
	PROBE CALIBRATION UNCERTAINTY	
	ISOTROPY UNCERTAINTY	
	BOUNDARY EFFECT UNCERTAINTY	
	PROBE LINEARITY UNCERTAINTY	
	READOUT ELECTRONICS UNCERTAINTY	
	RESPONSE TIME UNCERTAINTY	
	INTEGRATION TIME UNCERTAINTY	
	PROBE POSITIONER MECHANICAL TOLERANCE	
	PHANTOM UNCERTAINTY	
	DASY4 UNCERTAINTY BUDGET	
	INFORMATION ON THE TESTING LABORATORIES	
Ο.	INFORMATION ON THE TESTING LABORATORIES	3 <del>4</del>
APPE	ENDIX A: TEST CONFIGURATIONS AND TEST DATA	
APPE	ENDIX B: ADT SAR MEASUREMENT SYSTEM	
	ENDIX C: PHOTOGRAPHS OF SYSTEM VALIDATION	
	ENDIX D: SYSTEM CERTIFICATE & CALIBRATION	
, vi i L	LIBITED. STOTEM CERTIFICATE & OTTEM TOTAL	



#### CERTIFICATION

**PRODUCT:** Wireless Card for VCM and VMM

**MODEL:** 164-R9570 **BRAND**: TERADNE

**APPLICANT:** Teradyne Diagnostic Solutions Ltd

**TESTED:** May 18, 2007

**TEST SAMPLE: ENGINEERING SAMPLE** 

STANDARDS: FCC Part 2 (Section 2.1093)

FCC OET Bulletin 65, Supplement C (01-01)

**RSS-102** 

IEEE 1528-2003

The above equipment (model: 164-R9570) has been tested by Advance Data **Technology Corporation**, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's EMC characteristics under the conditions specified in this report.

Peggy Chen , DATE: May 22, 2007

**TECHNICAL** 

Stanely Hou , DATE: May 22, 2007 ACCEPTANCE

Responsible for RF

, **DATE**: May 22, 2007 **APPROVED BY** 



#### 2. GENERAL INFORMATION

#### 2.1 GENERAL DESCRIPTION OF EUT

PRODUCT	Wireless Card for VCM and VMM
MODEL NO.	164-R9570
FCC ID	VBD-35540121
POWER SUPPLY	5Vdc from host equipment
CLASSIFICATION	Portable device, production unit
MODULATION TYPE	CCK, DQPSK, DBPSK for DSSS, 64QAM, 16QAM, QPSK, BPSK for OFDM
RADIO TECHNOLOGY	DSSS, OFDM
TRANSFER RATE	802.11b: 11/5.5/2/1Mbps 802.11g: 54/48/36/24/18/12/9/6Mbps
FREQUENCY RANGE	2412MHz ~ 2462MHz
NUMBER OF CHANNEL	11
CHANNEL FREQUENCIES UNDER TEST AND ITS CONDUCTED OUTPUT POWER	57.544mW / Ch1: 2412MHz (for DSSS) 57.544mW / Ch6: 2437MHz (for DSSS) 57.544mW / Ch11: 2462MHz (for DSSS) 39.811mW / Ch11: 2462MHz (for OFDM)
AVERAGE SAR (1g)	0.482W/kg
ANTENNA TYPE	Ceramic antenna with 2dBi gain
DATA CABLE	NA
I/O PORTS	PCMCIA
ACCESSORY DEVICES	NA

#### NOTE:

- 1. The EUT, operates in the 2.4GHz frequency range, lets you connect IEEE 802.11g or IEEE 802.11b devices to the network. With its high-speed data transmissions of up to 54Mbps.
- 2. Normal operating condition of the EUT shall be plugged into the notebook. Then the property of the EUT shall be complied with the portable device according to the FCC 2.1093.
- 3. The above EUT information was declared by the manufacturer and for more detailed features description, please refer to the manufacturer's specifications or User's Manual.



#### 2.2 GENERAL DESCRIPTION OF APPLIED STANDARDS

According to the specifications of the manufacturer, this product must comply with the requirements of the following standards:

FCC Part 2 (2.1093)
FCC OET Bulletin 65, Supplement C (01- 01)
RSS-102
IEEE 1528-2003

All test items have been performed and recorded as per the above standards.

#### 2.3 GENERAL INOFRMATION OF THE SAR SYSTEM

DASY4 (software 4.7 Build 53) consists of high precision robot, probe alignment sensor, phantom, robot controller, controlled measurement server and near-field probe. The robot includes six axes that can move to the precision position of the DASY4 software defined. The DASY4 software can define the area that is detected by the probe. The robot is connected to controlled box. Controlled measurement server is connected to the controlled robot box. The DAE includes amplifier, signal multiplexing, AD converter, offset measurement and surface detection. It is connected to the Electro-optical coupler (ECO). The ECO performs the conversion form the optical into digital electric signal of the DAE and transfers data to the PC.

#### **ET3DV6 ISOTROPIC E-FIELD PROBE**

**CONSTRUCTION** Symmetrical design with triangular core.

Built-in optical fiber for surface detection system.

Built-in shielding against static charges.

PEEK enclosure material (resistant to organic solvents,

e.g., glycolether).

**FREQUENCY** 10 MHz to 3 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)

**DYNAMIC RANGE** 5  $\mu$ W/g to > 100 mW/g; Linearity:  $\pm$  0.2 dB

**OPTICAL SURFACE** 

**DETECTION** 

± 0.2 mm repeatability in air and clear liquids over diffuse

reflecting surfaces

**DIMENSIONS** Overall length: 330 mm (Tip Length: 16 mm)

Tip diameter: 6.8 mm (Body diameter: 12 mm) Distance from probe tip to dipole centers: 2.7 mm



**APPLICATION** General dosimetric measurements up to 3 GHz

Compliance tests of mobile phones

Fast automatic scanning in arbitrary phantoms (ET3DV6)

#### NOTE

1. The Probe parameters have been calibrated by the SPEAG. Please reference "APPENDIX D" for the Calibration Certification Report.

- 2. For frequencies above 800 MHz, calibration in a rectangular wave-guide is used, because wave-guide size is manageable.
- 3. For frequencies below 800 MHz, temperature transfer calibration is used because the wave-guide size becomes relatively large.

#### **TWIN SAM V4.0**

CONSTRUCTION The shell corresponds to the specifications of the Specific

Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-2003, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

SHELL THICKNESS 2 ± 0.2 mm

FILLING VOLUME Approx. 25 liters

**DIMENSIONS** Height: 810 mm; Length: 1000 mm; Width: 500 mm

#### SYSTEM VALIDATION KITS:

**CONSTRUCTION** Symmetrical dipole with I/4 balun enables measurement of feedpoint

impedance with NWA matched for use near flat phantoms filled with

brain simulating solutions.

Includes distance holder and tripod adaptor

**CALIBRATION** Calibrated SAR value for specified position and input power at the flat

phantom in brain simulating solutions

FREQUENCY 2450 MHz

**RETURN LOSS** > 20 dB at specified validation position

**POWER** > 100 W (f < 1GHz); > 40 W (f > 1GHz)



**OPTIONS** 

Dipoles for other frequencies or solutions and other calibration conditions upon request

#### **DEVICE HOLDER FOR SAM TWIN PHANTOM**

#### CONSTRUCTION

The device holder for the mobile phone device is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles. The holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon$  =3 and loss tangent  $\delta$  =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered. The device holder for the portable device makes up of the polyethylene foam. The dielectric parameters of material close to the dielectric parameters of the air.

#### **DATA ACQUISITION ELECTRONICS**

#### **CONSTRUCTION**

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplex, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe is mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



#### 2.4 GENERAL DESCRIPTION OF THE SPATIAL PEAK SAR EVALUATION

The DASY4 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the micro-volt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Norm<sub>i</sub>, a<sub>i0</sub>, a<sub>i1</sub>, a<sub>i2</sub>

Conversion factor ConvF<sub>i</sub>Diode compression point dcp<sub>i</sub>

Device parameters: - Frequency F

- Crest factor Cf

Media parameters: - Conductivity  $\sigma$ 

- Density  $\rho$ 

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \bullet \frac{cf}{dcp_i}$$

 $V_i$  = compensated signal of channel i (i = x, y, z) $U_i$  = input signal of channel I (i = x, y, z)

Cf =crest factor of exciting field (DASY parameter) dcp<sub>i</sub> =diode compression point (DASY parameter)



From the compensated input signals the primary field data for each channel can be evaluated:

E-fieldprobes: 
$$E_i = \sqrt{\frac{V_1}{Norm_i \cdot ConvF}}$$

H-fieldprobes: 
$$H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

 $V_i$  =compensated signal of channel I (i = x, y, z)

Norm<sub>i</sub> = sensor sensitivity of channel i  $\mu V/(V/m)$ 2 for (i = x, y, z)

E-field Probes

ConvF = sensitivity enhancement in solution

a<sub>ii</sub> = sensor sensitivity factors for H-field probes

F = carrier frequency [GHz]

E<sub>i</sub> = electric field strength of channel i in V/m H<sub>i</sub> = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$$

SAR = local specific absorption rate in mW/g

 $E_{tot}$  = total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm3



Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid. The entire evaluation of the spatial peak values is performed within the Post-processing engine (SEMCAD). The system always gives the maximum values for the 1 g and 10 g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- 1. The extraction of the measured data (grid and values) from the Zoom Scan
- 2. The calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- 3. The generation of a high-resolution mesh within the measured volume
- 4. The interpolation of all measured values from the measurement grid to the high-resolution grid
- 5. The extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- 6. The calculation of the averaged SAR within masses of 1 g and 10 g.

The probe is calibrated at the center of the dipole sensors that is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated. The angle between the probe axis and the surface normal line is less than 30 degree.

In the Area Scan, the gradient of the interpolation function is evaluated to find all the extreme of the SAR distribution. The uncertainty on the locations of the extreme is less than 1/20 of the grid size. Only local maximum within -2 dB of the global maximum are searched and passed for the Cube Scan measurement. In the Cube Scan, the interpolation function is used to extrapolate the Peak SAR from the lowest measurement points to the inner phantom surface (the extrapolation distance). The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5mm.



The maximum search is automatically performed after each area scan measurement. It is based on splines in two or three dimensions. The procedure can find the maximum for most SAR distributions even with relatively large grid spacing. After the area scanning measurement, the probe is automatically moved to a position at the interpolated maximum. The following scan can directly use this position for reference, e.g., for a finer resolution grid or the cube evaluations. The 1g and 10g peak evaluations are only available for the predefined cube 7 x 7 x 7 scans. The routines are verified and optimized for the grid dimensions used in these cube measurements. The measured volume of 30 x 30 x 30mm contains about 30g of tissue. The first procedure is an extrapolation (incl. boundary correction) to get the points between the lowest measured plane and the surface. The next step uses 3D interpolation to get all points within the measured volume in a 1mm grid (42875 points). In the last step, a 1g cube is placed numerically into the volume and its averaged SAR is calculated. This cube is the moved around until the highest averaged SAR is found. If the highest SAR is found at the edge of the measured volume, the system will issue a warning: higher SAR values might be found outside of the measured volume. In that case the cube measurement can be repeated, using the new interpolated maximum as the center.



#### 3. DESCRIPTION OF SUPPORT UNITS

The EUT has been tested as an independent unit together with other necessary accessories or support units. The following support units or accessories were used to form a representative test configuration during the tests.

NO.	PRODUCT	BRAND	MODEL NO.	SERIAL NO.	FCC ID
1	Notebook	HP	nx6215	CND5390CMP	FCC DoC Approved

NO.	SIGNAL CABLE DESCRIPTION OF THE ABOVE SUPPORT UNITS
1	NA

**NOTE:** All power cords of the above support units are non shielded (1.8m).



## 4. DESCRIPTION OF TEST MODES AND CONFIGURATIONS

#### 4.1. DESCRIPTION OF ANTENNA LOCATION





#### 4.2. DESCRIPTION OF ASSESSMENT POSITION

The following test configurations have been applied in this test report:



A: NOTEBOOK MODEL: nx6215

The bottom of the EUT face to the phantom with 10mm-separation distance.

**NOTE:** The bottom of the notebook contacts the bottom of the flat phantom with 0mm-separation distance.

#### 4.3. DESCRIPTION OF TEST MODE

TEST MODE		ASSESSMENT POSTITION	TESTED CHANNEL	REMARK
1	DSSS	А	L, M, H	-
2	OFDM	А	Н	-

#### 4.4. SUMMARY OF TEST RESULTS

MODULATION TECHNOLOGY	DSSS	OFDM		
TEST MODE	1	2		
CHANNEL	MEASURED VALUE OF 1g SAR ( W/kg)			
LOW	0.180	-		
MIDDLE	0.337	-		
HIGH	0.482	0.171		

**NOTE:** The worst value has been marked by boldface.



#### 5. TEST RESULTS

#### 5.1 TEST PROCEDURES

The EUT (Wireless Card for VCM and VMM) plugged into the notebook. Use the software to control the EUT channel and transmission power. Then record the conducted power before the testing. Place the EUT to the specific test location. After the testing, must writing down the conducted power of the EUT into the report. The SAR value was calculated via the 3D spline interpolation algorithm that has been implemented in the software of DASY4 SAR measurement system manufactured and calibrated by SPEAG. According to the IEEE 1528 standards, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Verification of the power reference measurement
- Area scan
- Zoom scan
- Power reference measurement

The area scan was performed for the highest spatial SAR location. The zoom scan with 30mm x 30mm x 30mm volume was performed for SAR value averaged over 1g and 10g spatial volumes.



In the zoom scan, the distance between the measurement point at the probe sensor location (geometric center behind the probe tip) and the phantom surface is 4.0 mm and maintained at a constant distance of  $\pm 1.0$  mm during a zoom scan to determine peak SAR locations. The distance is 4mm between the first measurement point and the bottom surface of the phantom. The secondary measurement point to the bottom surface of the phantom is with 9mm separation distance. The cube size is 7 x 7 x 7 points consist of 343 points and the grid space is 5mm.

The measurement time is 0.5 s at each point of the zoom scan. The probe boundary effect compensation shall be applied during the SAR test. Because of the tip of the probe to the Phantom surface separated distances are longer than half a tip probe diameter.

In the area scan, the separation distance is 4mm between the each measurement point and the phantom surface. The scan size shall be included the transmission portion of the EUT. The measurement time is the same as the zoom scan. At last the reference power drift shall be less than  $\pm 5\%$ .



#### 5.2 MEASURED SAR RESULTS

	RONMENTA DITION		Air Temperature:23.2°C, Liquid Temperature:22.1°C Humidity:61%RH							
TEST	ED BY	9	Sam (	Onn			DATE		May 18, 2007	
Chan.	From (8411-)	Modu	ılation		ed Power W)	Power	Device	Device	Antenna	Measured
Cnan.	Freq. (MHz)	Tech	nique	Begin Test	After Test	Drift (%)	Use Power	Test Position	Position	1g SAR (W/kg)
1	2412 (Low)	DS	sss	57.544	57.024	-0.90	Standard Battery from host	1	Internal Fixed	0.180
6	2437 (Mid.)	DS	sss	57.544	56.926	-1.07	Standard Battery from host	1	Internal Fixed	0.337
11	2462 (High)	DS	sss	57.544	56.812	-1.27	Standard Battery from host	1	Internal Fixed	0.482
11	2462 (High)	OF	·DМ	39.811	39.293	-1.30	Standard Battery from host	2	Internal Fixed	0.171

#### NOTE:

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, **1.6 W/kg**, is applied.
- 3. Please see the Appendix A for the data.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



#### 5.3 SAR LIMITS

	SAR (W/kg)				
HUMAN EXPOSURE	(General Population / Uncontrolled Exposure Environment)	(Occupational / controlled Exposure Environment)			
Spatial Average ( whole body)	0.08	0.4			
Spatial Peak (averaged over 1 g)	1.6	8.0			
Spatial Peak (hands / wrists / feet / ankles averaged over 10 g)	4.0	20.0			

#### NOTE:

- 1. This limits accord to 47 CFR 2.1093 Safety Limit.
- 2. The EUT property been complied with the partial body exposure limit under the general population environment.



#### 5.4 RECIPES FOR TISSUE SIMULATING LIQUIDS

For the measurement of the field distribution inside the SAM phantom, the phantom must be filled with 25 litters of tissue simulation liquid.

The following ingredients are used:

• WATER- Deionized water (pure H20), resistivity \_16 M - as basis for the liquid

• SUGAR- Refined sugar in crystals, as available in food shops - to reduce relative

permittivity

• SALT- Pure NaCl - to increase conductivity

• CELLULOSE- Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in water,

20\_C),

CAS # 54290 - to increase viscosity and to keep sugar in solution

• PRESERVATIVE- Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS # 55965-84-9 - to

prevent the spread of bacteria and molds

• **DGMBE-** Diethylenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH,

CAS # 112-34-5 - to reduce relative permittivity

#### THE RECIPES FOR 2450MHz SIMULATING LIQUID TABLE

Ingredient	Head Simulating Liquid 2450MHz (HSL-2450)	Muscle Simulating Liquid 2450MHz (MSL-2450)	
Water	45%	69.83%	
DGMBE	55%	30.17%	
Salt	NA	NA	
Dielectric Parameters at 22°℃	f= 2450MHz ε= 39.2 ± 5% σ= 1.80 ± 5% S/m	f= 2450MHz ε= 52.7 ± 5% σ= 1.95 ± 5% S/m	



Testing the liquids using the Agilent Network Analyzer E8358A and Agilent Dielectric Probe Kit 85070D. The testing procedure is following as

- 1. Turn Network Analyzer on and allow at least 30 min. warm up.
- 2. Mount dielectric probe kit so that interconnecting cable to Network Analyzer will not be moved during measurements or calibration.
- 3. Pour de-ionized water and measure water temperature (±1°).
- 4. Set water temperature in Agilent-Software (Calibration Setup).
- 5. Perform calibration.
- 6. Validate calibration with dielectric material of known properties (e.g. polished ceramic slab with >8mm thickness  $\epsilon$ '=10.0,  $\epsilon$ "=0.0). If measured parameters do not fit within tolerance, repeat calibration (±0.2 for  $\epsilon$ ': ±0.1 for  $\epsilon$ ").
- 7. Conductivity can be calculated from  $\varepsilon$ " by  $\sigma = \omega \varepsilon_0 \varepsilon$ " = $\varepsilon$ " f [GHz] / 18.
- 8. Measure liquid shortly after calibration. Repeat calibration every hour.
- 9. Stir the liquid to be measured. Take a sample (~50ml) with a syringe from the center of the liquid container.
- 10. Pour the liquid into a small glass flask. Hold the syringe at the bottom of the flask to avoid air bubbles
- 11. Put the dielectric probe in the glass flask. Check that there are no air bubbles in front of the opening in the dielectric probe kit.
- 12. Perform measurements.
- 13. Adjust medium parameters in DASY4 for the frequencies necessary for the measurements ('Setup Config', select medium (e.g. Brain 900 MHz) and press 'Option'-button.
- 14. Select the current medium for the frequency of the validation (e.g. Setup Medium Brain 900 MHz).



#### FOR 2.4GHz BAND SIMULATING LIQUID

LIQUID TYPE		HSL	-2450	MSL-2450		
SIMULAT	TING LIQUID	N	IA	22.1		
TEST DA	ATE .	١	IA	May 1	8, 2007	
TESTED	BY	٨	IA	Sam	n Onn	
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE	
2412		NA	NA	52.8	53.6	
2437	Permitivity	NA	NA	52.7	53.5	
2450	(ε)	NA	NA	52.7	53.5	
2462		NA	NA	52.7	53.5	
2412	Conductivity	NA	NA	1.91	1.94	
2437	Conductivity	NA	NA	1.94	1.97	
2450	(σ) S/m	NA	NA	1.95	1.99	
2462		NA	NA	1.97	2.00	
Dielectric Parameters Required at 22℃		f= 2450MHz ε= 39.2 ± 5% $\sigma$ = 1.80 ± 5% S/m		f= 2450MHz ε= 52.7 ± 5% σ= 1.95 ± 5% S/m		

#### 5.5 TEST EQUIPMENT FOR TISSUE PROPERTY

ITEM	NAME	BAND	TYPE	SERIES NO.	CALIBRATED UNTIL
1	Network Analyzer	Agilent	E8358A	US41480538	Nov. 06, 2007
2	Dielectric Probe	Agilent	85070D	US01440176	NA

#### NOTE:

- 1. Before starting, all test equipment shall be warmed up for 30min.
- 2. The tolerance (k=1) specified by Agilent for general dielectric measurements, deriving from inaccuracies in the calibration data, analyzer drift, and random errors, are usually ±2.5% and ±5% for measured permittivity and conductivity, respectively. However, the tolerances for the conductivity is smaller for material with large loss tangents, i.e., less than ±2.5% (k=1). It can be substantially smaller if more accurate methods are applied.



#### 6. SYSTEM VALIDATION

The system validation was performed in the flat phantom with equipment listed in the following table. Since the SAR value is calculated from the measured electric field, dielectric constant and conductivity of the body tissue, and the SAR is proportional to the square of the electric field. So, the SAR value will be also proportional to the RF power input to the system validation dipole under the same test environment. In our system validation test, 250mW RF input power was used.

#### **6.1 TEST EQUIPMENT**

ITEM	NAME	BAND	TYPE	SERIES NO.	CALIBRATED UNTIL
1	SAM Phantom	S&P	QD000 P40 CA	PT-1150	NA
2	Signal Generator	Agilent	E8257C	MY43320668	Dec. 28, 2007
3	E-Field Probe	S&P	ET3DV6	1790	Nov. 22, 2007
4	DAE	S&P	DAE3 V1	510	Sep. 06, 2007
5	Robot Positioner	Staubli Unimation	NA	NA	NA
6	Validation Dipole	S&P	D2450V2	716	Aug. 20, 2007

NOTE: Before starting the measurement, all test equipment shall be warmed up for 30min.



#### 6.2 TEST PROCEDURE

Before the system performance check, we need only to tell the system which components (probe, medium, and device) are used for the system performance check; the system will take care of all parameters. The dipole must be placed beneath the flat section of the SAM Twin Phantom with the correct distance holder in place. The distance holder should touch the phantom surface with a light pressure at the reference marking (little cross) and be oriented parallel to the long side of the phantom. Accurate positioning is not necessary, since the system will search for the peak SAR location, except that the dipole arms should be parallel to the surface. The device holder for mobile phones can be left in place but should be rotated away from the dipole.

- 1.The "Power Reference Measurement" and "Power Drift Measurement" jobs are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the amplifier output power. If it is too high (above ±0.1 dB), the system performance check should be repeated; some amplifiers have very high drift during warm-up. A stable amplifier gives drift results in the DASY system below ±0.02 dB.
- 2.The "Surface Check" job tests the optical surface detection system of the DASY system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above ±0.1mm). In that case it is better to abort the system performance check and stir the liquid. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within ±30°.) However, varying breaking indices of different liquid compositions might also influence the distance. If the indicated difference varies from the actual setting, the probe parameter "optical surface



- 3. The "Area Scan" job measures the SAR above the dipole on a plane parallel to the surface. It is used to locate the approximate location of the peak SAR. The proposed scan uses large grid spacing for faster measurement; due to the symmetric field, the peak detection is reliable. If a finer graphic is desired, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result.
- 4. The "Zoom Scan" job measures the field in a volume around the peak SAR value assessed in the previous "Area Scan" job (for more information see the application note on SAR evaluation).

About the validation dipole positioning uncertainty, the constant and low loss dielectric spacer is used to establish the correct distance between the top surface of the dipole and the bottom surface of the phantom, the error component introduced by the uncertainty of the distance between the liquid (i.e., phantom shell) and the validation dipole in the DASY4 system is less than ±0.1mm.

$$SAR_{tolerance}[\%] = 100 \times (\frac{(a+d)^2}{a^2} - 1)$$

As the closest distance is 10mm, the resulting tolerance SAR $_{tolerance}$ [%] is <2%.



#### **6.3 VALIDATION RESULTS**

2450MHz SYSTEM VALIDATION TEST IN THE MUSCLE SIMULATING LIQUID						
TEST FREQUENCY (MHz)	REQUIRED SAR (mW/g)	MEASURED SAR (mW/g)	DEVIATION (%)	SEPARATION DISTANCE	TEST DATE	
MSL2450	13.4 (1g)	13.2	-1.49	10mm	May 18, 2007	
TESTED BY	Sam Onn					

**NOTE:** Please see Appendix for the photo of system validation test.



#### **6.4 SYSTEM VALIDATION UNCERTAINTIES**

In the table below, the system validation uncertainty with respect to the analytically assessed SAR value of a dipole source as given in the IEEE 1528 standard is given. This uncertainty is smaller than the expected uncertainty for mobile phone measurements due to the simplified setup and the symmetric field distribution.

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C <sub>i</sub> )		Standard Uncertainty (±%)		(v <sub>i</sub> )
				(1g)	(10g)	(1g)	(10g)	
Measurement System								
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	8
Axial Isotropy	4.7	Rectangular	√3	1	1	2.7	2.7	8
Hemispherical Isotropy	0	Rectangular	√3	1	1	0	0	8
Boundary effect	1.0	Rectangular	√3	1	1	0.6	0.6	8
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	$\infty$
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	8
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	$\infty$
Response Time	0	Rectangular	√3	1	1	0	0	$\infty$
Integration Time	0	Rectangular	√3	1	1	0	0	$\infty$
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	$\infty$
Probe Positioner	0.4	Rectangular	√3	1	1	0.2	0.2	$\infty$
Probe positioning	2.9	Rectangular	√3	1	1	1.7	1.7	∞
Algorithms for Max. SAR Evaluation	1.0	Rectangular	√3	1	1	0.6	0.6	$\infty$
		Dipol	е					
Dipole Axis to Liquid Distance	2.0	Rectangular	√3	1	1	1.2	1.2	8
Input power and SAR drift measurement	4.7	Rectangular	√3	1	1	2.7	2.7	8
		Phantom and Tiss	ue Paramet	ers				
Phantom Uncertainty	4.0	Rectangular	√3	1	1	2.3	2.3	8
Liquid Conductivity (target)	5.0	Rectangular	√3	0.64	0.43	1.8	1.2	∞
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	8
Liquid Permittivity (target)	5.0	Rectangular	√3	0.6	0.49	1.7	1.4	$\infty$
Liquid Permittivity (measurement)	2.5	Normal	1	0.6	0.49	1.5	1.2	$\infty$
Combined Standard Uncertainty					8.4	8.1	$\infty$	
Coverage Factor for 95%						kp=2		
Expanded Uncertainty (K=2)					16.8	16.2		

**NOTE:** About the system validation uncertainty assessment, please reference the section 7.



#### 7. MEASUREMENT SAR PROCEDURE UNCERTAINTIES

The assessment of spatial peak SAR of the hand handheld devices is according to IEEE 1528. All testing situation shall be met below these requirements.

- The system is used by an experienced engineer who follows the manual and the guidelines taught during the training provided by SPEAG.
- The probe has been calibrated within the requested period and the stated uncertainty for the relevant frequency bands does not exceed 4.8% (k=1).
- The validation dipole has been calibrated within the requested period and the system performance check has been successful.
- The DAE unit has been calibrated within the within the requested period.
- The minimum distance between the probe sensor and inner phantom shell is selected to be between 4 and 5mm.
- The operational mode of the DUT is CW, CDMA, FDMA or TDMA (GSM, DCS, PCS, IS136 and PDC) and the measurement/integration time per point is >500 ms.
- The dielectric parameters of the liquid have been assessed using Agilent 85070D dielectric probe kit or a more accurate method.
- The dielectric parameters are within 5% of the target values.
- The DUT has been positioned as described in section 3.

#### 7.1. PROBE CALIBRATION UNCERTAINTY

SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN50361, IEC 62209, etc.) under ISO17025. The uncertainties are stated on the calibration certificate. For the most relevant frequency bands, these values do not exceed 4.8% (k=1). If evaluations of other bands are performed for which the uncertainty exceeds these values, the uncertainty tables given in the summary have to be revised accordingly.



#### 7.2. ISOTROPY UNCERTAINTY

The axial isotropy tolerance accounts for probe rotation around its axis while the hemispherical isotropy error includes all probe orientations and field polarizations. These parameters are assessed by SPEAG during initial calibration. In 2001, SPEAG further tightened its quality controls and warrants that the maximal deviation from axial isotropy is  $\pm 0.20$  dB, while the maximum deviation of hemispherical isotropy is  $\pm 0.40$  dB, corresponding to  $\pm 4.7\%$  and  $\pm 9.6\%$ , respectively. A weighting factor of cp equal to 0.5 can be applied, since the axis of the probe deviates less than 30 degrees from the normal surface orientation.

#### 7.3. BOUNDARY EFFECT UNCERTAINTY

The effect can be estimated according to the following error approximation formula

$$SAR_{tolerance}[\%] = SAR_{be}[\%] \times \frac{(d_{be} + d_{step})^2}{2d_{step}} \frac{e^{\frac{-d_{be}}{\delta/2}}}{\delta/2}$$

$$d_{be} + d_{step} < 10mm$$

The parameter  $d_{be}$  is the distance in mm between the surface and the closest measurement point used in the averaging process;  $d_{step}$  is the separation distance in mm between the first and second measurement points;  $\delta$  is the minimum penetration depth in mm within the head tissue equivalent liquids (i.e.,  $\delta$ = 13.95 mm at 3GHz); SAR<sub>be</sub> is the deviation between the measured SAR value at the distance  $d_{be}$  from the boundary and the wave-guide analytical value SAR<sub>ref</sub>.DASY4 applies a boundary effect compensation algorithm according to IEEE 1528, which is possible since the axis of the probe never deviates more than 30 degrees from the normal surface orientation. SAR<sub>be</sub>[%] is assessed during the calibration process and SPEAG warrants that the uncertainty at distances larger than 4mm is always less than 1%.In summary, the worst case boundary effect SAR tolerance[%] for scanning distances larger than 4mm is <  $\pm$  0.8%.



#### 7.4. PROBE LINEARITY UNCERTAINTY

Field probe linearity uncertainty includes errors from the assessment and compensation of the diode compression effects for CW and pulsed signals with known duty cycles. This error is assessed using the procedure described in IEEE 1528. For SPEAG field probes, the measured difference between CW and pulsed signals, with pulse frequencies between 10 Hz and 1 kHz and duty cycles between 1 and 100, is  $< \pm 0.20$  dB ( $< \pm 4.7\%$ ).

#### 7.5. READOUT ELECTRONICS UNCERTAINTY

All uncertainties related to the probe readout electronics (DAE unit), including the gain and linearity of the instrumentation amplifier, its loading effect on the probe, and accuracy of the signal conversion algorithm, have been assessed accordingly to IEEE 1528. The combination (root-sum-square RSS method) of these components results in an overall maximum error of ±1.0%.

#### 7.6. RESPONSE TIME UNCERTAINTY

The time response of the field probes is assessed by exposing the probe to a well-controlled electric field producing SAR larger than 2.0 W/kg at the tissue medium surface. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/of switch of the power source. Analytically, it can be expressed as:

$$SAR_{tolerance} [\%] = 100 \times (\frac{T_m}{T_m + \tau e^{-T_m/\tau} - \tau} - 1)$$

where Tm is 500 ms, i.e., the time between measurement samples, and  $_{\rm T}$  the time constant. The response time  $_{\rm T}$  of SPEAG's probes is <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.



#### 7.7. INTEGRATION TIME UNCERTAINTY

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization and can be assessed as follows

$$SAR_{tolerance} [\%] = 100 \times \sum_{all sub-frames} \frac{t_{frame}}{t_{\text{integration}}} \frac{slot_{idle}}{slot_{total}}$$

The tolerances for the different systems are given in Table 7.1, whereby the worst-case  $SAR_{tolerance}$  is 2.6%.

System	SAR <sub>tolerance</sub> %		
CW	0		
CDMA*	0		
WCDMA*	0		
FDMA	0		
IS-136	2.6		
PDC	2.6		
GSM/DCS/PCS	1.7		
DECT	1.9		
Worst-Case	2.6		

**TABLE 7.1** 



#### 7.8. PROBE POSITIONER MECHANICAL TOLERANCE

The mechanical tolerance of the field probe positioner can introduce probe positioning uncertainties. The resulting SAR uncertainty is assessed by comparing the SAR obtained according to the specifications of the probe positioner with respect to the actual position defined by the geometric enter of the probe sensors. The tolerance is determined as:

$$SAR_{tolerance} [\%] = 100 \times \frac{d_{ph}}{\delta/2}$$

The specified repeatability of the RX robot family used in DASY4 systems is  $\pm 25 \,\mu m$ . The absolute accuracy for short distance movements is better than  $\pm 0.1 \,mm$ , i.e., the SAR<sub>tolerance</sub>[%] is better than 1.5% (rectangular).

#### 7.9. PROBE POSITIONING

The probe positioning procedures affect the tolerance of the separation distance between the probe tip and the phantom surface as:

$$SAR_{tolerance} [\%] = 100 \times \frac{d_{ph}}{\delta/2}$$

where  $d_{ph}$  is the maximum deviation of the distance between the probe tip and the phantom surface. The optical surface detection has a precision of better than 0.2 mm, resulting in an SAR<sub>tolerance</sub>[%] of <2.9% (rectangular distribution). Since the mechanical detection provides better accuracy, 2.9% is a worst-case figure for DASY4 system.



#### 7.10. PHANTOM UNCERTAINTY

The SAR measurement uncertainty due to SPEAG phantom shell production tolerances has been evaluated using

$$SAR_{tolerance}[\%] \cong 100 \times \frac{2d}{a},$$
  $d << a$ 

For a maximum deviation d of the inner and outer shell of the phantom from that specified in the CAD file of  $\pm 0.2$  mm, and a 10mm spacing a between source and tissue liquid, the calculated phantom uncertainty is  $\pm 4.0\%$ .



#### 7.11. DASY4 UNCERTAINTY BUDGET

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C <sub>i</sub> )		Standard Uncertainty (±%)		(v <sub>i</sub> )
				(1g)	(10g)	(1g)	(10g)	
Measurement Equipment								
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	$\infty$
Axial Isotropy	4.7	Rectangular	√3	1	1	1.9	1.9	$\infty$
Hemispherical Isotropy	9.6	Rectangular	√3	1	1	3.9	3.9	$\infty$
Boundary effect	1.0	Rectangular	√3	1	1	0.6	0.6	8
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	8
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	$\infty$
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	$\infty$
Response Time	0.8	Normal	1	1	1	0.8	0.8	$\infty$
Integration Time	2.6	Normal	1	1	1	2.6	2.6	$\infty$
Noise	0.0	Normal	1	0	0	0	0	∞
		Mechanical Co	onstraints					
Scanning System	0.4	Rectangular	√3	1	1	0.2	0.2	$\infty$
Phantom Shell	4.0	Rectangular	√3	1	1	2.3	2.3	$\infty$
Probe Positioning	2.9	Rectangular	√3	1	1	1.7	1.7	$\infty$
Device Positioning	2.9	Normal	1	1	1	2.9	2.9	875
		Physical Par	ameters					
Liquid Conductivity (target)	5.0	Rectangular	√3	0.7	0.5	2	1.4	∞
Liquid Conductivity (measurement)	4.3	Rectangular	√3	0.7	0.5	1.7	1.2	∞
Liquid Permittivity (target)	5.0	Rectangular	√3	0.6	0.5	1.7	1.4	$\infty$
Liquid Permittivity (measurement)	4.3	Rectangular	√3	0.6	0.5	1.5	1.2	∞
Power Drift	5	Rectangular	√3	1	1	2.9	2.9	8
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	$\infty$
Post-Processing								
Extrapolation and Integration	1	Rectangular	√3	1	1	0.6	0.6	$\infty$
Combined Standard Uncertainty					9.9	9.7		
Coverage Factor for 95%						kp=2		
Expanded Uncertainty (K=2)						19.9	19.3	

#### **TABLE 7.2**

The table 7.2: Worst-Case uncertainty budget for DASY4 assessed according to IEEE 1528. The budget is valid for the frequency range 300MHz ~ 3GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



#### 8. INFORMATION ON THE TESTING LABORATORIES

We, ADT Corp., were founded in 1988 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved by the following approval agencies according to ISO/IEC 17025.

USA FCC, UL, A2LA Germany TUV Rheinland

Japan VCCI Norway NEMKO

Canada INDUSTRY CANADA, CSA

R.O.C. CNLA, BSMI, NCC

**Netherlands** Telefication

Singapore PSB , GOST-ASIA(MOU)

Russia CERTIS(MOU)

Copies of accreditation certificates of our laboratories obtained from approval agencies can be downloaded from our web site:

<u>www.adt.com.tw/index.5/phtml</u>. If you have any comments, please feel free to contact us at the following:

 Linko EMC/RF Lab:
 Hsin Chu EMC/RF Lab:

 Tel: 886-2-26052180
 Tel: 886-3-5935343

 Fax: 886-2-26051924
 Fax: 886-3-5935342

#### Hwa Ya EMC/RF/Safety/Telecom Lab:

Tel: 886-3-3183232 Fax: 886-3-3185050

Web Site: www.adt.com.tw

The address and road map of all our labs can be found in our web site also.



# APPENDIX A: TEST DATA Liquid Level Photo







Date/Time: 2007/5/18 16:33:36

Test Laboratory: Advance Data Technology

#### NX6125-11b-Ch1-Mode 1

#### DUT: Wireless Card for VCM and VMM; Type: 164-R9570; Test Frequency: 2412 MHz

Communication System: 802.11b ; Frequency: 2412 MHz ; Duty Cycle: 1:1 ; Modulation type: DBPSK Medium: MSL2450 Medium parameters used: f = 2412 MHz;  $\sigma = 1.94$  mho/m;  $\epsilon_r = 53.6$ ;  $\rho = 1000$  kg/m³ ; Liquid level : 151 mm

Phantom section: Flat Section ; Separation distance : 10 mm (The bottom side of the EUT to the Phantom)

Antenna type: Ceramic Antenna; Air temp.: 23.2 degrees; Liquid temp.: 22.1 degrees

#### DASY4 Configuration:

- Probe: ET3DV6 SN1790; ConvF(4.35, 4.35, 4.35); Calibrated: 2006/11/23
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2006/9/7
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**Low Channel 1/Area Scan (7x10x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.152 mW/g

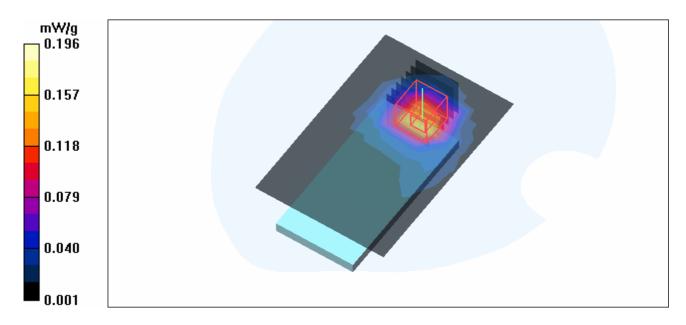
## **Low Channel 1/Zoom Scan (7x7x7) (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 9.16 V/m

Peak SAR (extrapolated) = 0.389 W/kg

SAR(1 g) = 0.180 mW/g; SAR(10 g) = 0.090 mW/g

Maximum value of SAR (measured) = 0.196 mW/g





Date/Time: 2007/5/18 16:54:21

Test Laboratory: Advance Data Technology

#### NX6125-11b-Ch6-Mode 1

#### DUT: Wireless Card for VCM and VMM; Type: 164-R9570; Test Frequency: 2437 MHz

Communication System: 802.11b ; Frequency: 2437 MHz ; Duty Cycle: 1:1 ; Modulation type: DBPSK Medium: MSL2450 Medium parameters used: f = 2437 MHz;  $\sigma = 1.97$  mho/m;  $\epsilon_r = 53.5$ ;  $\rho = 1000$  kg/m³ ; Liquid level : 151 mm

Phantom section: Flat Section; Separation distance: 10 mm (The bottom side of the EUT to the Phantom)

Antenna type: Ceramic Antenna; Air temp.: 23.2 degrees; Liquid temp.: 22.1 degrees

#### DASY4 Configuration:

- Probe: ET3DV6 SN1790; ConvF(4.35, 4.35, 4.35); Calibrated: 2006/11/23
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2006/9/7
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Mid Channel 6/Area Scan (7x10x1): Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.290 mW/g

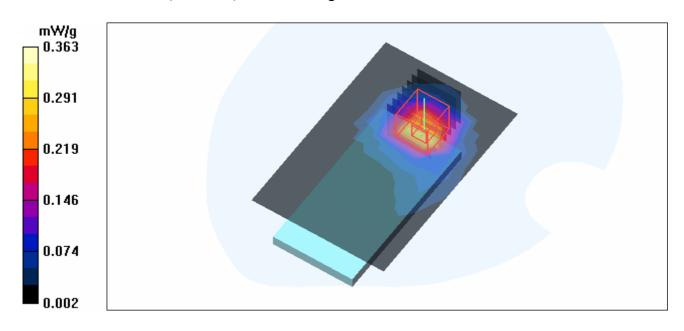
## **Mid Channel 6/Zoom Scan (7x7x7) (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 12.0 V/m

Peak SAR (extrapolated) = 0.750 W/kg

SAR(1 g) = 0.337 mW/g; SAR(10 g) = 0.167 mW/g

Maximum value of SAR (measured) = 0.363 mW/g





Date/Time: 2007/5/18 17:13:10

Test Laboratory: Advance Data Technology

#### NX6125-11b-Ch11-Mode 1

#### DUT: Wireless Card for VCM and VMM; Type: 164-R9570; Test Frequency: 2462 MHz

Communication System: 802.11b ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: DBPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz;  $\sigma = 2$  mho/m;  $\epsilon_r = 53.5$ ;  $\rho = 1000$  kg/m³ ; Liquid level : 151 mm

Phantom section: Flat Section; Separation distance: 10 mm (The bottom side of the EUT to the Phantom)

Antenna type: Ceramic Antenna; Air temp.: 23.2 degrees; Liquid temp.: 22.1 degrees

#### DASY4 Configuration:

- Probe: ET3DV6 SN1790; ConvF(4.35, 4.35, 4.35); Calibrated: 2006/11/23
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2006/9/7
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**High Channel 11/Area Scan (7x10x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.414 mW/g

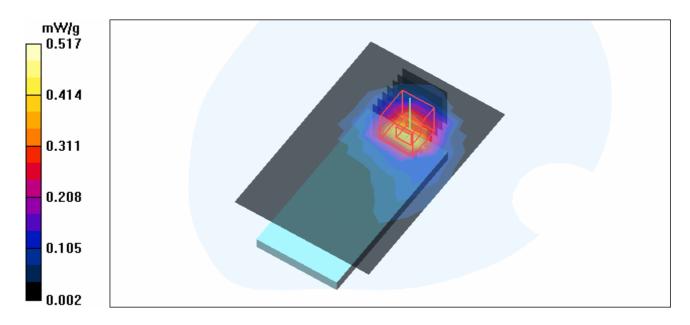
## **High Channel 11/Zoom Scan (7x7x7) (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 13.7 V/m

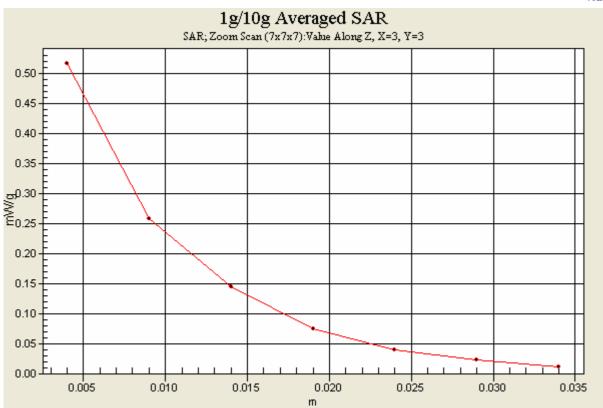
Peak SAR (extrapolated) = 1.08 W/kg

SAR(1 g) = 0.482 mW/g; SAR(10 g) = 0.238 mW/g

Maximum value of SAR (measured) = 0.517 mW/g









Date/Time: 2007/5/18 17:33:39

Test Laboratory: Advance Data Technology

#### NX6125-11g-Ch11-Mode 1

#### DUT: Wireless Card for VCM and VMM; Type: 164-R9570; Test Frequency: 2462 MHz

Communication System: 802.11g ; Frequency: 2462 MHz ; Duty Cycle: 1:1 ; Modulation type: BPSK Medium: MSL2450 Medium parameters used: f = 2462 MHz;  $\sigma = 2$  mho/m;  $\epsilon_r = 53.5$ ;  $\rho = 1000$  kg/m³ ; Liquid level : 151 mm

Phantom section: Flat Section; Separation distance: 10 mm (The bottom side of the EUT to the Phantom)

Antenna type: Ceramic Antenna; Air temp.: 23.2 degrees; Liquid temp.: 22.1 degrees

#### DASY4 Configuration:

- Probe: ET3DV6 SN1790; ConvF(4.35, 4.35, 4.35); Calibrated: 2006/11/23
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2006/9/7
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

## **High Channel 11/Area Scan (7x10x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 0.149 mW/g

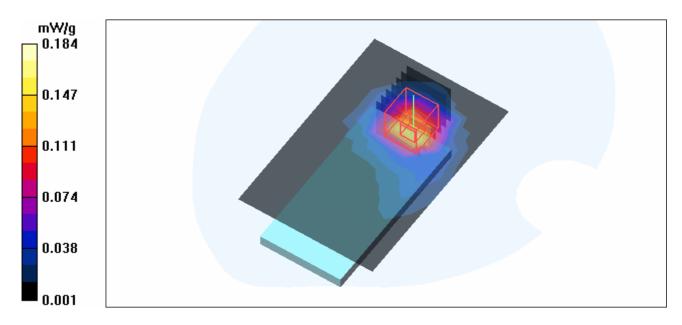
## **High Channel 11/Zoom Scan (7x7x7) (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 8.04 V/m

Peak SAR (extrapolated) = 0.383 W/kg

SAR(1 g) = 0.171 mW/g; SAR(10 g) = 0.085 mW/g

Maximum value of SAR (measured) = 0.184 mW/g





Date/Time: 2007/5/18 15:52:19

Test Laboratory: Advance Data Technology

#### System Validation Check-MSL 2450MHz

#### DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 716; Test Frequency: 2450 MHz

Communication System: CW ; Frequency: 2450 MHz; Duty Cycle: 1:1; Modulation type: CW Medium: MSL2450;Medium parameters used: f = 2450 MHz;  $\sigma$  = 1.99 mho/m;  $\epsilon_r$  = 53.5;  $\rho$  = 1000 kg/m³ ; Liquid level : 151 mm

Phantom section: Flat Section; Separation distance: 10 mm (The feetpoint of the dipole to the Phantom) Air temp.: 23.2 degrees; Liquid temp.: 22.1 degrees

#### DASY4 Configuration:

- Probe: ET3DV6 SN1790; ConvF(4.35, 4.35, 4.35); Calibrated: 2006/11/23
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn510; Calibrated: 2006/9/7
- Phantom: SAM 12; Type: SAM V4.0; Serial: TP 1202
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

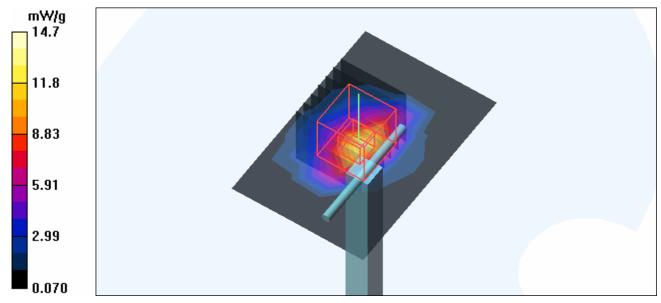
## **d=10mm, Pin=250mW/Area Scan (5x7x1):** Measurement grid: dx=15mm, dy=15mm Maximum value of SAR (measured) = 14.0 mW/g

## **d=10mm, Pin=250mW/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 90.9 V/m; Power Drift = -0.171 dB Peak SAR (extrapolated) = 31.1 W/kg

SAR(1 g) = 13.2 mW/g; SAR(10 g) = 6.04 mW/g

Maximum value of SAR (measured) = 14.7 mW/g



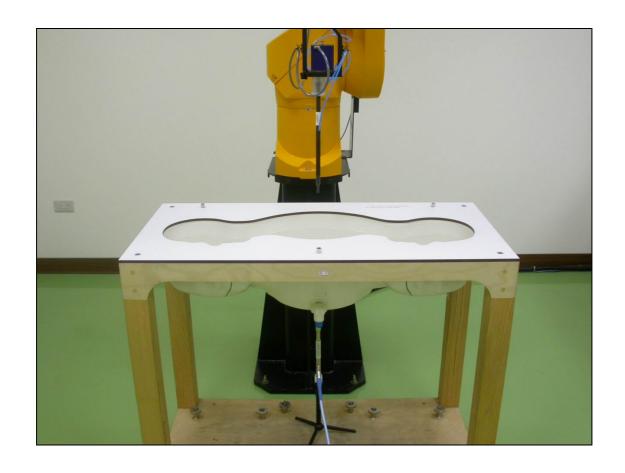


### **APPENDIX B: ADT SAR MEASUREMENT SYSTEM**





## **APPENDIX C: PHOTOGRAPHS OF SYSTEM VALIDATION**





### **APPENDIX D: SYSTEM CERTIFICATE & CALIBRATION**

**D1: SAM PHANTOM** 

# Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland, Phone +41 1 245 97 00, Fax +41 1 245 97 79

#### Certificate of conformity / First Article Inspection

Item .	SAM Twin Phantom V4.0		
Type No	QD 000 P40 CA		
Series No	TP-1150 and higher		
Manufacturer / Origin -	Untersee Composites		
	Hauptstr. 69	•	
	CH-8559 Fruthwilen		
	Switzerland		

#### **Tests**

The series production process used allows the limitation to test of first articles. Complete tests were made on the pre-series Type No. QD 000 P40 AA, Serial No. TP-1001 and on the series first article Type No. QD 000 P40 BA, Serial No. TP-1006. Certain parameters have been retested using further series units (called samples).

Test	Requirement	Details	Units tested
Shape	Compliance with the geometry according to the CAD model.	IT'IS CAD File (*)	First article, Samples
Material thickness	Compliant with the requirements according to the standards	2mm +/- 0.2mm in specific areas	First article, Samples
Material parameters	Dielectric parameters for required frequencies	200 MHz - 3 GHz Relative permittivity < 5 Loss tangent < 0.05.	Material sample TP 104-5
Material resistivity	The material has been tested to be compatible with the liquids defined in the standards	Liquid type HSL 1800 and others according to the standard.	Pre-series, First article

#### **Standards**

- [1] CENELEC EN 50361
- [2] IEEE P1528-200x draft 6.5
- [3] IEC PT 62209 draft 0.9
- (\*) The IT'IS CAD file is derived from [2] and is also within the tolerance requirements of the shapes of [1] and [3].

#### Conformity

Based on the sample tests above, we certify that this item is in compliance with the uncertainty requirements of SAR measurements specified in standard [1] and draft standards [2] and [3].

Date

28.02.2002

Signature / Stamp

Engineering AG

Zeughausstrasse 43, CH-8004 Zurlch
Tel. +41 1 245 97 00, Fex +41 1 245 97 79

Schmid & Partner

Page

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F. Bumbult



## **D2: DOSIMETRIC E-FIELD PROBE**

#### **Calibration Laboratory of** Schmid & Partner

**Engineering AG** Zeughausstrasse 43, 8004 Zurich, Switzerland





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**Swiss Calibration Service** 

Accredited by the Swiss Federal Office of Metrology and Accreditation The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates Accreditation No.: SCS 108

S

Client

ADT (Auden)

CONTRACTOR NO. 12 KELLENDYOS

[3/1= 5];V==[3]\E			
Object	EERIDVO SNEE	790	
Calibration procedure(s)	QA CAL-01.v5 Calibration proc	edure for desimetric E-field probes	
Calibration date:	November 23, 2	006	
Condition of the calibrated item	in Tolerance		
This calibration certificate docum The measurements and the unce	ents the traceability to na rtainties with confidence	ational standards, which realize the physical units of probability are given on the following pages and are	measurements (SI). part of the certificate.
All calibrations have been conduc	cted in the closed laborate	ory facility: environment temperature (22 ± 3)°C and	d humidity < 70%.
Calibration Equipment used (M&	ΓE critical for calibration)		
Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Power sensor E4412A	MY41495277	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Power sensor E4412A	MY41498087	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Reference 3 dB Attenuator	SN: S5054 (3c)	10-Aug-06 (METAS, No. 217-00592)	Aug-07
Reference 20 dB Attenuator	SN: S5086 (20b)	4-Apr-06 (METAS, No. 251-00558)	Apr-07
Reference 30 dB Attenuator	SN: S5129 (30b)	10-Aug-06 (METAS, No. 217-00593)	Aug-07
Reference Probe ES3DV2	SN: 3013	2-Jan-06 (SPEAG, No. ES3-3013_Jan06)	Jan-07
DAE4	SN: 654	21-Jun-06 (SPEAG, No. DAE4-654_Jun06)	Jun-07
Secondary Standards	lıD#	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (SPEAG, in house check Nov-05)	In house check: Nov-07
•	US37390585	18-Oct-01 (SPEAG, in house check Oct-06)	In house check: Oct-07
Network Analyzer HP 8753E	0537390363	10-Oct-01 (GPLAG, III House check Oct-00)	III NOOOO ONOON. OOL O.
	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	26.14
		<i>-</i>	
Approved by:	Niels Kuster	Quality Manager	
			Jesued: November 23, 2006

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#### **Calibration Laboratory of**

Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland





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Glossary:

TSL NORMx,y,z tissue simulating liquid sensitivity in free space

ConF

sensitivity in TSL / NORMx,y,z

DCP

diode compression point

Polarization φ
Polarization θ

 $\phi$  rotation around probe axis  $\vartheta$  rotation around an axis that is in the plane normal to probe axis (at

measurement center), i.e.,  $\vartheta = 0$  is normal to probe axis

#### Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003

b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001

#### Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z \* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

November 23, 2006

## ET3DV6 SN:1790

# Probe ET3DV6

SN:1790

Manufactured:

May 28, 2003

Last calibrated:

December 20, 2004

Recalibrated:

November 23, 2006

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

Page 3 of 9

#### DASY - Parameters of Probe: ET3DV6 SN:1790

Sensitivity in Free Space <sup>A</sup>			Diode C	ompression	В
NormX	<b>2.04</b> ± 10.1%	μ <b>V/(V/m)</b> ²	DCP X	<b>91</b> mV	
NormY	<b>2.10</b> ± 10.1%	μ <b>V/(V/m)</b> ²	DCP Y	<b>93</b> mV	
NormZ	<b>1.84</b> ± 10.1%	μV/(V/m) <sup>2</sup>	DCP Z	98 mV	

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

#### **Boundary Effect**

TSL 900 MHz Typical SAR gradient: 5 % per mm

Sensor Center to	o Phantom Surface Distance	3.7 mm	4.7 mm
SAR <sub>be</sub> [%]	Without Correction Algorithm	9.2	4.9
SAR <sub>be</sub> [%]	With Correction Algorithm	0.1	0.2

TSL 1750 MHz Typical SAR gradient: 10 % per mm

Sensor Center t	o Phantom Surface Distance	3.7 mm	4.7 mm
SAR <sub>be</sub> [%]	Without Correction Algorithm	12.6	8.4
SAR <sub>be</sub> [%]	With Correction Algorithm	0.5	0.0

#### Sensor Offset

Probe Tip to Sensor Center 2.7 mm

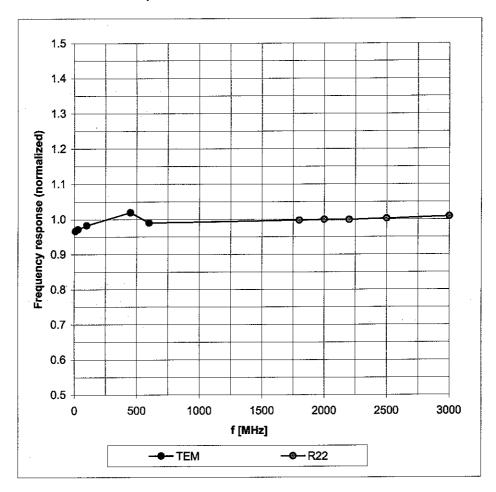
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>&</sup>lt;sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

<sup>&</sup>lt;sup>B</sup> Numerical linearization parameter: uncertainty not required.

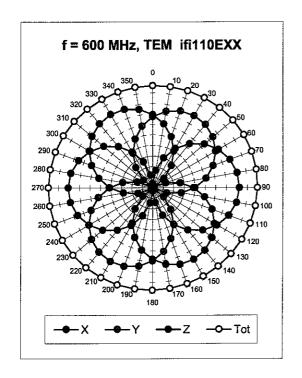
## Frequency Response of E-Field

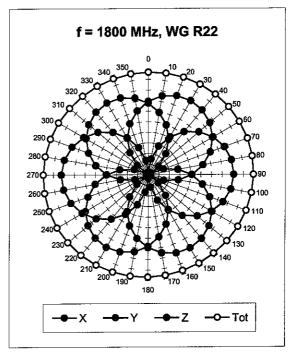
(TEM-Cell:ifi110 EXX, Waveguide: R22)

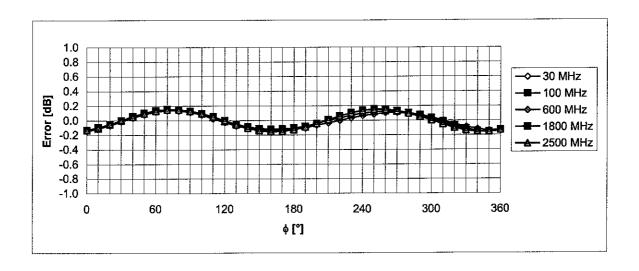


Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

## Receiving Pattern ( $\phi$ ), $\theta$ = 0°



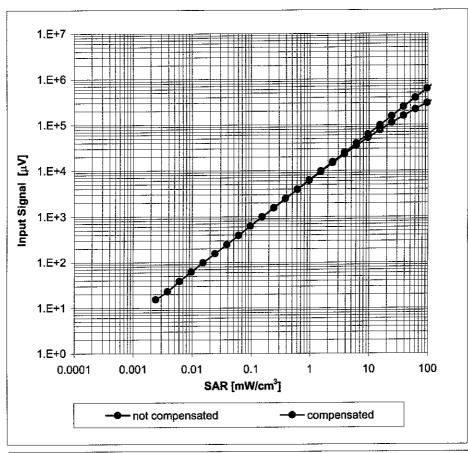


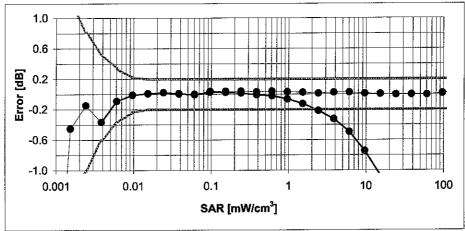


Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

## Dynamic Range f(SAR<sub>head</sub>)

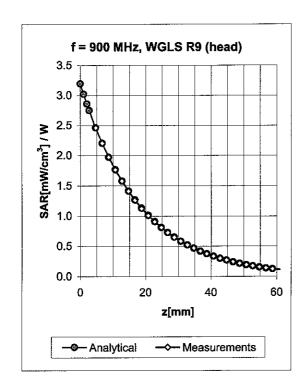
(Waveguide R22, f = 1800 MHz)

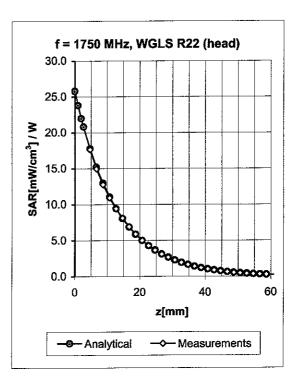




Uncertainty of Linearity Assessment: ± 0.6% (k=2)

#### **Conversion Factor Assessment**



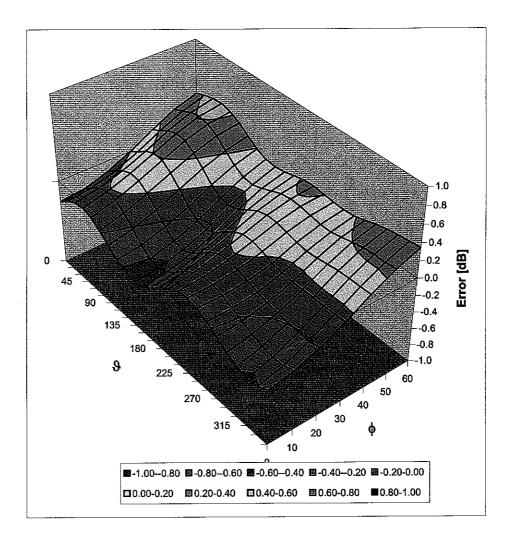


f [MHz]	Validity [MHz] <sup>c</sup>	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.32	2.45	6.71 ± 11.0% (k=2)
1750	± 50 / ± 100	Head	40.1 ± 5%	1.37 ± 5%	0.50	2.47	5.48 ± 11.0% (k=2)
1950	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.57	2.47	5.27 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.66	1.94	4.76 ± 11.8% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	0.32	2.78	6.35 ± 11.0% (k=2)
1750	± 50 / ± 100	Body	53.4 ± 5%	1.49 ± 5%	0.55	2.76	4.85 ± 11.0% (k=2)
1950	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.70	2.39	4.59 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.64	1.81	4.35 ± 11.8% (k=2)

 $<sup>^{\</sup>rm c}$  The validity of  $\pm$  100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

## **Deviation from Isotropy in HSL**

Error ( $\phi$ ,  $\vartheta$ ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)



D3: DAE

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Accreditation No.: SCS 108

Client

ADT (Auden)

Certificate No: DAE3-510\_Sep06

CALIBRATION C	ERTIFICATE		
Object	DAE3 - SD 000 D	03 AA - SN: 510	
Calibration procedure(s)	QA CAL-06.v12 Calibration proced	dure for the data acquisition electi	ronics (DAE)
Calibration date:	September 07, 20	106	
Condition of the calibrated item	In Tolerance		
The measurements and the uncert	tainties with confidence pro	onal standards, which realize the physical units obability are given on the following pages and $ m y$ facility: environment temperature (22 $\pm$ 3)°C	are part of the certificate.
Calibration Equipment used (M&TE	E critical for calibration)		
Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Fluke Process Calibrator Type 702	2 SN: 6295803	7-Oct-05 (Sintrel, No.E-050073)	Oct-06
	1		
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
Calibrator Box V1.1	SE UMS 006 AB 1002	15-Jun-06 (SPEAG, in house check)	In house check Jun-07
			•
		<i>!</i>	
			· ·
			· •
	Nama	Function	Signature
Calibrated by:	Name Daniel Steinacher	Function Technician	
,			isi Stenade
Approved by:	Fin Bomholt	R&D Director	21 m
		y and the second of the second	j. 1. J. Kron. ? 11-y-
			Issued: September 7, 2006

Certificate No: DAE3-510\_Sep06

Page 1 of 5

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Accreditation No.: SCS 108

#### Glossary

DAE

data acquisition electronics

Connector angle

information used in DASY system to align probe sensor X to the robot

coordinate system.

#### **Methods Applied and Interpretation of Parameters**

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters contain technical information as a result from the performance test and require no uncertainty.
- DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
- Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
- Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
- AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
- Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
- Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
- Input resistance: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
- Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
- Power consumption: Typical value for information. Supply currents in various operating modes.

#### **DC Voltage Measurement**

A/D - Converter Resolution nominal

High Range:

1LSB = 1LSB =  $6.1\mu V$ ,

full range =

-100...+300 mV

Low Range:

61nV,

full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Υ	Z
High Range	404.194 ± 0.1% (k=2)	404.254 ± 0.1% (k=2)	404.622 ± 0.1% (k=2)
Low Range	3.97522 ± 0.7% (k=2)	3.96545 ± 0.7% (k=2)	3.95957 ± 0.7% (k=2)

#### **Connector Angle**

Connector Angle to be used in DASY system	42°±1°

Certificate No: DAE3-510\_Sep06

Page 3 of 5

#### **Appendix**

1. DC Voltage Linearity

High Range		Input (μV)	Reading (μV)	Error (%)
Channel X	+ Input	200000	200000.2	0.00
Channel X	+ Input	20000	20007.72	0.04
Channel X	- Input	20000	-19999.52	0.00
Channel Y	+ Input	200000	199999.5	0.00
Channel Y	+ Input	20000	20005.14	0.03
Channel Y	- Input	20000	-20000.72	0.00
Channel Z	+ Input	200000	200000.5	0.00
Channel Z	+ Input	20000	20006.06	0.03
Channel Z	- Input	20000	-20002.05	` 0.01

Low Range		Input (μV)	Reading (μV)	Error (%)
Channel X	+ Input	2000	1999.9	0.00
Channel X	+ Input	200	200.02	0.01
Channel X	- Input	200	-200.32	0.16
Channel Y	+ Input	2000	2000.0	0.00
Chännel Y	+ Input	200	199.46	-0.27
Channel Y	- Input	200	-200.72	0.36
Channel Z	+ Input	2000	1999.9	0.00
Channel Z	+ Input	200	199.12	-0.44
Channel Z	- Input	200	-201.06	0.53

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	17.19	16.90
	- 200	-16.29	-16.91
Channel Y	200	14.52	14.16
	- 200	-15.49	-15.51
Channel Z	200	-8.86	-9.32
<del></del>	- 200	7.79	7.80

#### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	ja4	1.86	-0.06
Channel Y	200	0.60	-	4.31
Channel Z	200	-2.51	-0.39	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15894	16343
Channel Y	16116	16300
Channel Z	16080	16129

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input  $10M\Omega$ 

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	0.39	-0.84	1.32	0.26
Channel Y	-1.02	-1.58	0.05	0.26
Channel Z	0.18	-0.50	1.13	0.28

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MOhm)	, Measuring (MOhm)
Channel X	0.2001	199.6
Channel Y	0.2001	198.3
Channel Z	0.2001	199.1

8. Low Battery Alarm Voltage (verified during pre'test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	9

Certificate No: DAE3-510\_Sep06 Page 5 of 5



### **D4: SYSTEM VALIDATION DIPOLE**

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Client

ADT (Auden)

CALIBRATION C	ERTIFICATE		
Object	D2450V2 - SN: 7	16	
Calibration procedure(s)	QA CAL-05.v6 Calibration proce	dure for dipole validation kits	
Calibration date:	August 21, 2006		
Condition of the calibrated item	In Tolerance		
1	-	onal standards, which realize the physical units of robability are given on the following pages and are	* *
All calibrations have been condu	cted in the closed laborator	y facility: environment temperature (22 ± 3)°C and	I humidity < 70%.
Calibration Equipment used (M&	TE critical for calibration)		
Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	04-Oct-05 (METAS, No. 251-00516)	Oct-06
Power sensor HP 8481A	US37292783	04-Oct-05 (METAS, No. 251-00516)	Oct-06
Reference 20 dB Attenuator	SN: 5086 (20g)	10-Aug-06 (METAS, No 217-00591)	Aug-07
Reference 10 dB Attenuator	SN: 5047.2 (10r)	10-Aug-06 (METAS, No 217-00591)	Aug-07
Reference Probe ES3DV2	SN 3025	28-Oct-05 (SPEAG, No. ES3-3025_Oct05)	Oct-06
DAE4	SN 601	15-Dec-05 (SPEAG, No. DAE4-601_Dec05)	Dec-06
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (SPEAG, in house check Oct-05)	In house check: Oct-07
RF generator Agilent E4421B	MY41000675	11-May-05 (SPEAG, in house check Nov-05)	In house check: Nov-07
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (SPEAG, in house check Nov-05)	In house check: Nov-06
		<b>- S</b>	,
Colibrated by	Name Mike Meili	Function	Signature
Calibrated by:	wike Well	Laboratory Technician	7.172 in
Approved by:	Katja Pokovic	Technical Manager	Da i llaf
			Issued: August 22, 2006

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Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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#### Glossary:

TSL

tissue simulating liquid

ConvF N/A

sensitivity in TSL / NORM x,y,z not applicable or not measured

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

#### Additional Documentation:

d) DASY4 System Handbook

#### **Methods Applied and Interpretation of Parameters:**

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

Certificate No: D2450V2-716\_Aug06 Page 2 of 9

#### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY4	V4.7
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V5.0	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz ± 1 MHz	

#### **Head TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	39.8 ± 6 %	1.80 mho/m ± 6 %
Head TSL temperature during test	(22.7 ± 0.2) °C		

#### SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	condition	
SAR measured	250 mW input power	14.0 mW / g
SAR normalized	normalized to 1W	56.0 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	56.4 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	condition	
SAR measured	250 mW input power	6.53 mW / g
SAR normalized	normalized to 1W	26.1 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	26.3 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	52.1 ± 6 %	1.97 mho/m ± 6 %
Body TSL temperature during test	(23.4 ± 0.2) °C		Sand on the Park

### SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	13.4 mW / g
SAR normalized	normalized to 1W	53.6 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	53.0 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	6.20 mW / g
SAR normalized	normalized to 1W	24.8 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	24.6 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### **Appendix**

#### **Antenna Parameters with Head TSL**

Impedance, transformed to feed point	54.2 Ω + 1.9 jΩ
Return Loss	– 27.0 dB

#### **Antenna Parameters with Body TSL**

Impedance, transformed to feed point	49.7 Ω + 3.7 jΩ
Return Loss	28.7 dB

#### **General Antenna Parameters and Design**

Electrical Delay (one direction)	1.147 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

#### **Additional EUT Data**

Manufactured by	SPEAG
Manufactured on	September 10, 2002

#### DASY4 Validation Report for Head TSL

Date/Time: 21.08.2006 14:39:00

Test Laboratory: SPEAG, Zurich, Switzerland

#### **DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN716**

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: HSL U10 BB 060425;

Medium parameters used: f = 2450 MHz;  $\sigma = 1.84 \text{ mho/m}$ ;  $\varepsilon_r = 39.8$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

Probe: ES3DV2 - SN3025 (HF); ConvF(4.4, 4.4, 4.4); Calibrated: 28.10.2005

Sensor-Surface: 4mm (Mechanical Surface Detection)

Electronics: DAE4 Sn601; Calibrated: 15.12.2005

Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA

Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

#### Pin = 250 mW; d = 10 mm 2/Zoom Scan (7x7x7)/Cube 0:

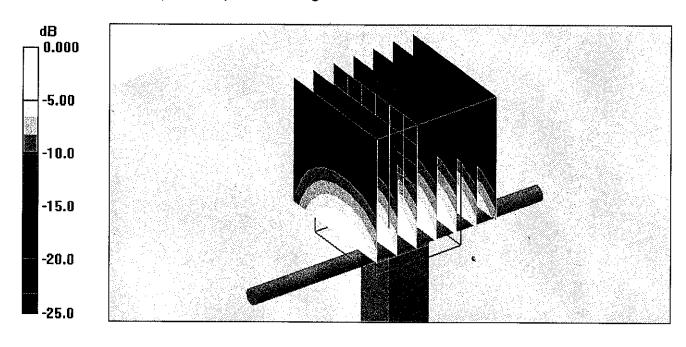
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 89.6 V/m; Power Drift = 0.022 dB

Peak SAR (extrapolated) = 28.9 W/kg

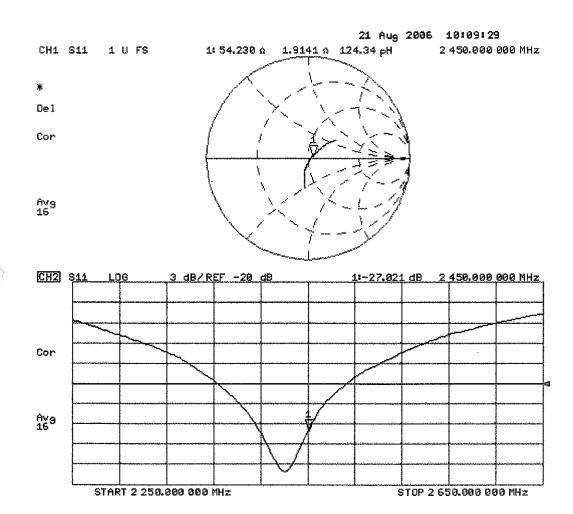
SAR(1 g) = 14 mW/g; SAR(10 g) = 6.53 mW/g

Maximum value of SAR (measured) = 15.5 mW/g



0 dB = 15.5 mW/g

### Impedance Measurement Plot for Head TSL



#### **DASY4 Validation Report for Body TSL**

Date/Time: 21.08.2006 16:08:52

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN716

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: MSL U10;

Medium parameters used: f = 2450 MHz;  $\sigma = 1.96 \text{ mho/m}$ ;  $\varepsilon_r = 51.9$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

#### **DASY4** Configuration:

• Probe: ES3DV2 - SN3025 (HF); ConvF(4.06, 4.06, 4.06); Calibrated: 28.10.2005

• Sensor-Surface: 4mm (Mechanical Surface Detection)

Electronics: DAE4 Sn601; Calibrated: 15.12.2005

• Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA

• Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

#### Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

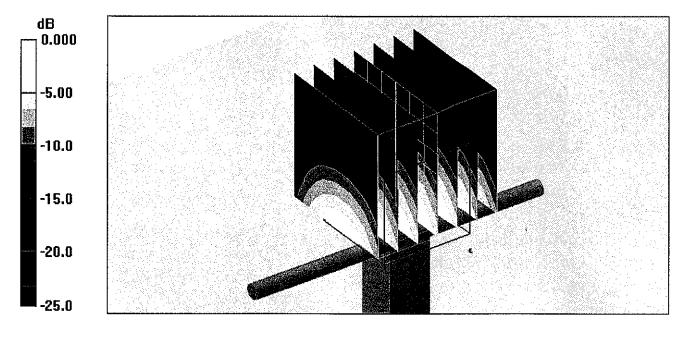
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 87.4 V/m; Power Drift = 0.018 dB

Peak SAR (extrapolated) = 28.8 W/kg

SAR(1 g) = 13.4 mW/g; SAR(10 g) = 6.2 mW/g

Maximum value of SAR (measured) = 14.8 mW/g



0 dB = 14.8 mW/g

### Impedance Measurement Plot for Body TSL

