



1 Features

- The AWA24S is a 2.4-GHz Direct Sequence Spread Spectrum (DSSS) radio module which includes the Cypress radio integrated circuit WirelessUSB™ LP CYRF6936 and an integrated PA
- Operates in the unlicensed worldwide Industrial, Scientific and Medical (ISM) band (2.400 GHz–2.483 GHz)
- Less than 100 mA operating current (Transmit @ 22 dBm)
- Transmit power up to +23 dBm
- Receive sensitivity up to –93 dBm
- Sleep Current < 10 µA
- Outdoor LOS range of up to 1Km.
- DSSS data rates up to 250 kbps, GFSK data rate of 1 Mbps
- Auto Transaction Sequencer (ATS) - no micro controller intervention
- Framing, Length, CRC16, and Auto ACK
- Fast Startup and Fast Channel Changes
- Separate 16-byte Transmit and Receive FIFOs
- Auto Rate™ - dynamic data rate reception
- Receive Signal Strength Indication (RSSI)
- 4-MHz SPI microcontroller interface
- No proprietary software required
- Serial Peripheral Interface (SPI) control while in sleep mode
- Vertical or horizontal mounting
- Operating voltage 3.3 volts
- Operating temperature from 0 to 70°C
- Size: 25.4 mm X 20.30mm (0.8" x 1.0")
- Weight: 5 grams
- FCC Modular Approval Grant to meet FCC Part 15, EN 300 328-1, EN 301 489-1, EN 301 489-7 and Industry Canada RSS-210 standards
- An FCC Module Approval (MA) Grant provides customers significant cost savings, by allowing customers to adopt the AWA24S FCC ID into their own products

2 Functional Description

The Artaflex AWA24S Wireless Radio Module offers a complete radio module solution for integration into existing or new 2.4-GHz products.

The AWA24S is tested for functional operation and is FCC/ETSI (EU)/Industry Canada certified.

The AWA24S is available in a small PCB design and can be mounted horizontally or vertically to the device PCB via a 12-pin header / Socket.

3 Application

• PC Human Interface Devices (HID)

- Wireless Keyboards and Mice
- VOIP and Wireless Headsets
- Wireless Gamepads
- Remote Control

• White Goods (Smart Appliances)

- Air Conditioners
- Kitchen Compactors
- Dishwashers
- Washers
- Dryers

• Consumer

- Sports and Leisure Equipment
- Remote Controls
- Audio Subwoofer
- Presenter Tools
- Locator Alarms
- Toys

• Building/Home Automation

- Automatic Meter Readers (AMR)
- On-Site Paging Systems
- Garage door opener
- Alarm and Security
- Lighting Control
- Climate Control
- Fan Control

• Industrial Control

- Active RFID and asset tracking systems
- Inventory Management
- Point-of-sale systems
- Factory Automation
- Data Acquisition

• Transportation

- Remote Keyless Entry with acknowledgement (RKE)
- Airline Baggage Tracking
- Diagnostics



4 Functional Overview

The AWA24S Module provides a complete SPI to RF antenna wireless MODEM. The module is designed to implement wireless device links operating in the worldwide 2.4-GHz ISM frequency band. It is intended for systems compliant with world-wide regulations covered by Europe ETSI EN 301 489-1, ETSI EN 301 489-7, & ETSI EN 300 328-1, USA FCC Part 15 and Industry Canada RSS-210 standards.

The module contains a 2.4-GHz 1-Mbps GFSK radio transceiver, packet data buffering, packet framer, DSSS baseband controller, Received Signal Strength Indication (RSSI), and SPI interface for data transfer and device configuration.

The radio supports 98 discrete 1-MHz channels (regulations may limit the use of some of these channels in certain jurisdictions). In DSSS modes the baseband performs DSSS spreading/de-spreading, while in GFSK Mode (1 Mb/s - GFSK) the baseband performs Start of Frame (SOF), End of Frame (EOF) detection and CRC16 generation and checking. The baseband may also be configured to automatically transmit Acknowledge (ACK) handshake packets whenever a valid packet is received.

When in receive mode, with packet framing enabled, the device is always ready to receive data transmitted at any of the supported bit rates, except SDR, enabling the implementation of mixed-rate systems in which different devices use different data rates. This also enables the implementation of dynamic data rate systems, which use high data rates at shorter distances and/or in a low-moderate interference environment, and change to lower data rates at longer distances and/or in high interference environments.

4.1 Link Layer Modes

The AWA24S module supports the following data packet framing features:

SOP – Packets begin with a 2-symbol Start of Packet (SOP) marker. This is required in GFSK and 8DR modes, but is optional in DDR mode and is not supported in SDR mode; if framing is disabled then an SOP event is inferred whenever two successive correlations are detected. The SOP_CODE_ADR code used for the SOP is different from that used for the “body” of the packet and if desired may be a different length. SOP must be configured to be the same length on both sides of the link.

EOP – There are two options for detecting the end of a packet. If SOP is enabled, then a packet length field may be enabled. GFSK and 8DR must enable the length field. This is the first 8-bits after the SOP symbol, and is transmitted at the payload data rate. If the length field is enabled, an End of Packet (EOP) condition is inferred after reception of the number of bytes defined in the length field, plus two bytes for the CRC16 (if enabled—see below). The alternative to using the length field is to infer an EOP condition from a configurable number of successive non-correlations; this option is not available in GFSK mode and is only recommended to enable when using SDR mode.

CRC16 – The device may be configured to append a 16-bit CRC16 to each packet. The CRC16 uses the USB CRC polynomial with the added programmability of the seed. If enabled, the receiver will verify the calculated CRC16 for the payload data against the received value in the CRC16 field. The starting value for the CRC16 calculation is configurable, and the CRC16 transmitted may be calculated using either the loaded seed value or a zero seed; the received data CRC16 will be checked against both the configured and zero CRC16 seeds.

CRC16 detects the following errors:

- Any one bit in error
- Any two bits in error (no matter how far apart, which column, and so on)
- Any odd number of bits in error (no matter where they are)
- An error burst as wide as the checksum itself

4.2 Packet Buffers

All data transmission and reception utilizes the 16-byte packet buffers—one for transmission and one for reception.

The transmit buffer allows a complete packet of up to 16-bytes of payload data to be loaded in one burst SPI transaction, and then transmitted with no further micro controller intervention. Similarly, the receive buffer allows an entire packet of payload data up to 16 bytes to be received with no firmware intervention required until packet reception is complete.

The AWA24S module supports packet length of up to 40 bytes; interrupts are provided to allow a micro controller to use the transmit and receive buffers as FIFOs. When transmitting a packet longer than 16 bytes, the micro controller can load 16-bytes initially, and add further bytes to the transmit buffer as transmission of data creates space in the buffer. Similarly, when receiving packets longer than 16 bytes, the micro controller must fetch received data from the FIFO periodically during packet reception to prevent it from overflowing.

4.3 Auto Transaction Sequencer (ATS)

The AWA24S module provides automated support for transmission and reception of acknowledged data packets.

When transmitting a data packet, the device automatically starts the crystal and synthesizer, enters transmit mode, transmits the packet in the transmit buffer, and then automatically switches to receive mode and waits for a handshake packet and then automatically reverts to sleep mode or idle mode when either an ACK packet is received, or a timeout period expires.

Similarly, when receiving in transaction mode, the device waits in receive mode for a valid packet to be received, and then automatically transitions to transmit mode, transmits an ACK packet, and then switches back to receive mode to await the next packet. The contents of the packet buffers are not affected by the transmission or reception of ACK packets.

In each case, the entire packet transaction takes place without any need for micro controller firmware action; to transmit data the micro controller simply needs to load the data packet to be transmitted, set the length, and set the TX GO bit. Similarly, when receiving packets in transaction mode, firmware simply needs to retrieve the fully received packet in response to an interrupt request indicating reception of a packet.

4.4 Data Rates

By combining the DATA_CODE_ADR code lengths and data transmission modes described above, the AWA24S supports the following modes and data rates.

Table 1 - Data Rates

| RF Transmission Mode | Raw Data Rate kbps |
|------------------------------|--------------------|
| GFSK | 1,000.00 |
| 32-Chip 8DR | 250.00 |
| 64-chip 8DR ^[2] | 125.00 |
| 32-chip DDR ^[3] | 62.50 |
| 64-chip DDR ^[3] | 31.25 |
| 64-chip SDR ^[2,3] | 15.63 |

5 SPI Communication

The AWA24S has an SPI interface supporting communications between an application MCU and one or more slave devices (including the AWA24S). The SPI interface supports single-byte and multi-byte serial transfers using either 4-pin or 3-pin interfacing. The SPI communications interface consists of Slave Select (\overline{SS}), Serial Clock (SCK), and Master Out- Slave In (MOSI), Master In-Slave Out (MISO), or Serial Data (SDAT).

The SPI communications is as follows:

- Command Direction (bit 7) = "1" enables SPI write transaction. A "0" enables SPI read transactions.
- Command Increment (bit 6) = "1" enables SPI auto address increment. When set, the address field automatically increments at the end of each data byte in a burst access, otherwise the same address is accessed.
- Six bits of address.
- Eight bits of data.

The device receives SCK from an application MCU on the SCK pin. Data from the application MCU is shifted in on the MOSI pin. Data to the application MCU is shifted out on the MISO pin. The active-low Slave Select (\overline{SS}) pin must be asserted to initiate an SPI transfer.

The application MCU can initiate SPI data transfers via a multi byte transaction. The first byte is the Command/Address byte, and the following bytes are the data bytes as shown in Figure 2 through Figure 5.

The SPI communications interface has a burst mechanism, where the first byte can be followed by as many data bytes as desired. A burst transaction is terminated by deasserting the slave select (\overline{SS} = 1).

The SPI communications interface single read and burst read sequences are shown in Figure 3 and Figure 4, respectively.

The SPI communications interface single write and burst write sequences are shown in Figure 5 and Figure 6, respectively.

This interface may optionally be operated in a 3-pin mode with the MISO and MOSI functions combined in a single bidirectional data pin (SDAT). When using 3-pin mode, user firmware should ensure that the MOSI pin on the MCU is in a high impedance state except when MOSI is actively transmitting data.

The device registers may be written to or read from 1 byte at a time, or several sequential register locations may be written/read in a single SPI transaction using incrementing burst mode. In addition to single byte configuration registers, the device includes register files; register files are FIFOs written to and read from using non-incrementing burst SPI transactions.

The IRQ pin function may optionally be multiplexed onto the MOSI pin; when this option is enabled the IRQ function is not available while the \overline{SS} pin is low. When using this configuration, user firmware should ensure that the MOSI pin on the AWA24S is in a high impedance state whenever the \overline{SS} pin is high.

The SPI interface is not dependent on the internal 12-MHz clock, and registers may therefore be read from or written to while the device is in sleep mode, and the 12-MHz oscillator disabled.

Figure 2 – SPI Transaction Format

| Bit # | Byte 1 | | | Byte 1+N |
|----------|--------|-----|---------|----------|
| | 7 | 6 | [5:0] | |
| Bit Name | DIR | INC | Address | Data |

Figure 3 - SPI Single Read Sequence

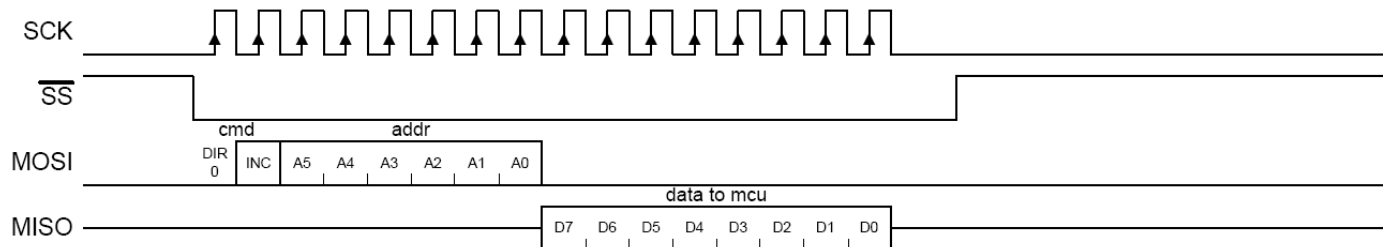


Figure 4 - SPI Incrementing Burst Read Sequence

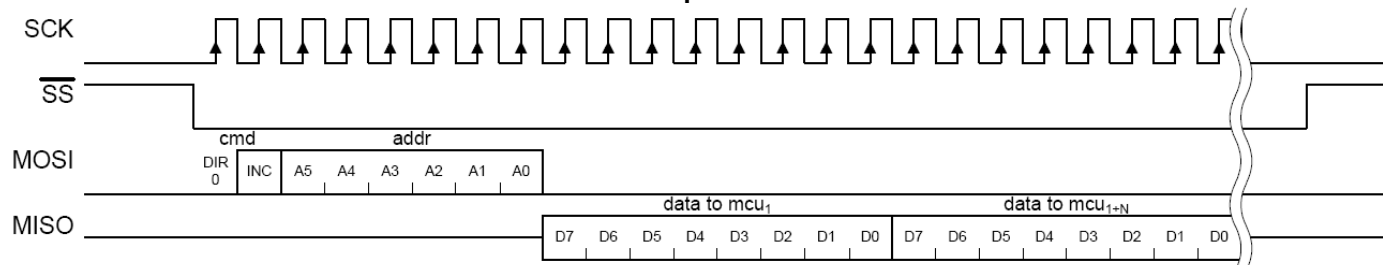


Figure 5 - SPI Single Write Sequence

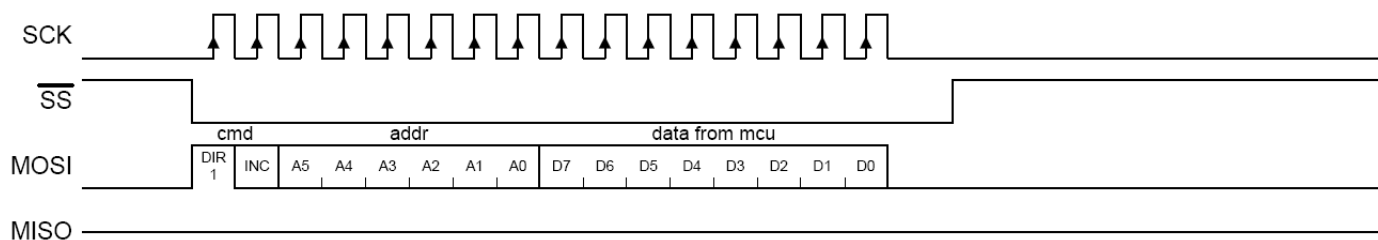
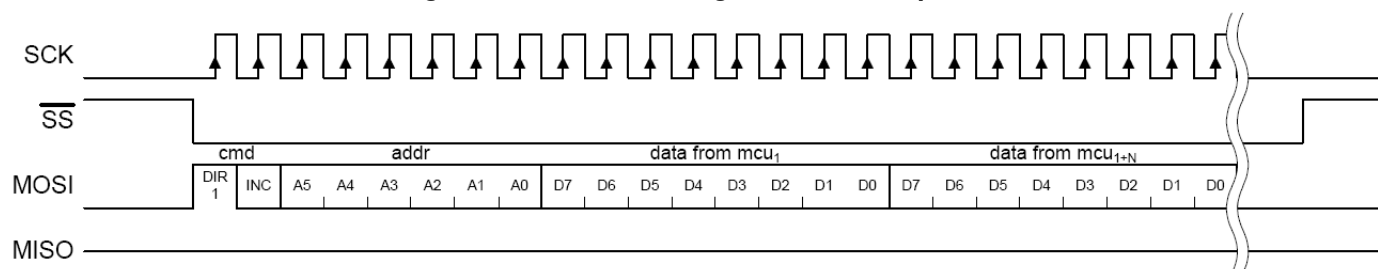


Figure 6 - SPI Incrementing Burst Write Sequence



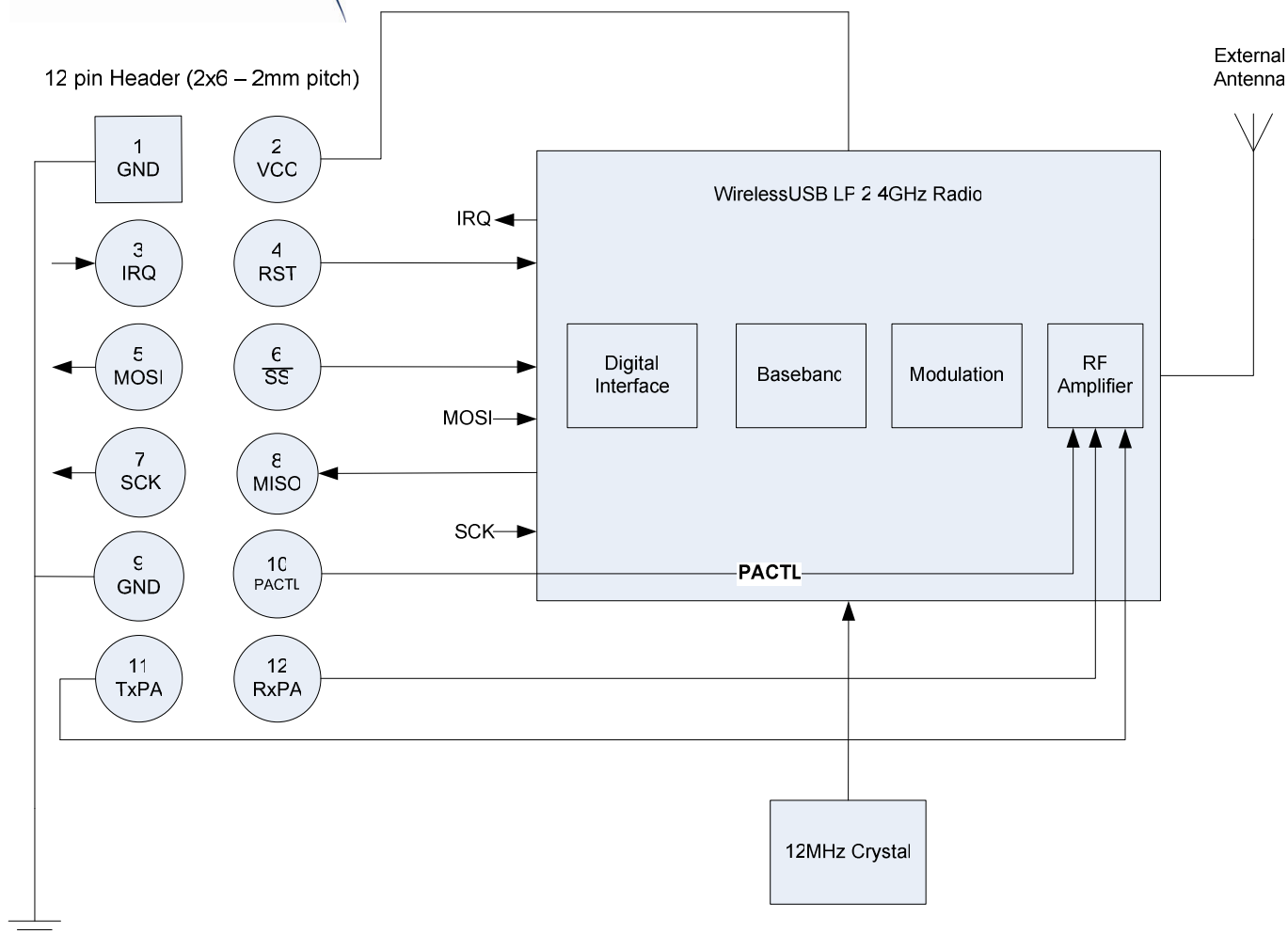


Figure 1 - Module Block Diagram

6 Power Management (Modem Chip)

The operating voltage of the module is 3.3V DC, which is applied to the V_{cc} pin 2 of the connector. The device can be shutdown to a fully static sleep mode by writing to the FRC END = 1 and END STATE = 000 bits in the XACT_CFG_ADR register over the SPI interface. The CY6936 chip will enter sleep mode within 35- μ s after the last SCK positive edge at the end of this SPI transaction. Alternatively, the CY6936 chip may be configured to automatically enter sleep mode after completing packet transmission or reception. When in sleep mode, the on-chip oscillator is stopped, but the SPI interface remains functional. The CY6936 chip will wake from sleep mode automatically when the module is commanded to enter transmit or receive mode. When resuming from sleep mode, there is a short delay while the oscillator restarts. The CY6936 chip may be configured to assert the IRQ pin when the oscillator has stabilized.

3 Low Noise Amplifier (LNA) and Received Signal Strength Indication (RSSI)

The gain of the receiver may be controlled directly by clearing the AGC EN bit and writing to the Low Noise Amplifier (LNA) bit of the RX_CFG_ADR register. When the LNA bit is cleared, the receiver gain is reduced by approximately 20 dB, allowing accurate reception of very strong received signals (for example when operating a receiver very close to the transmitter). Approximately 30 dB of receiver attenuation can be added by setting the Attenuation (ATT) bit; this allows data reception to be limited to devices at very short ranges. Disabling AGC and enabling LNA is recommended unless receiving from a device using external PA.

When the module is in receive mode the RSSI_ADR register returns the relative signal strength of the on-channel signal power.

When receiving, the module will automatically measure and store the relative strength of the signal being received as a 5-bit value. An RSSI reading is taken automatically when the SOP is detected. In addition, a new RSSI reading is taken every time the previous reading is read from the RSSI_ADR register, allowing the background RF energy level on any given channel to be easily measured when RSSI is read when no signal is being received. A new reading can occur as fast as once every 12 μ s.

4 RF Power Amplifier

The RF Amplifier used in this module is a GaAs MMIC. This device realizes high efficiency, high gain and high output power, housed in a 6-pin plastic package TSON (Thin small Out-line Non Leaded). It has a very low shut down current (5uA) as well as a very high power efficiency (up to 60%), these features enables the module to work longer in a power sensitive applications.

The Tx and Rx operations of this module is controlled by using Pin 11(TXPA), Pin 12 (RXPA) and Pin 10 (PACTL) of the 12 Pin Header Interface. Amplifier Power can be changed by controlling the voltage level at PIN10 (PACTL). Biasing 3.3V at "PACTL" will set up the power to the maximum. A "0V" at PACTL will bring the Amplifier stage into a shutdown mode. PACTL will require a strong current drive as it can sink up to 16mA of current when biased at 3.3V. All three pins (Pin 10,11,12) will be required to control the amplifier in a proper manner. PACTL should always be set to 0V in receive mode.

As European communication standard (ETSI) has different limits for Max RF Power that a DSSS device can transmit, It is strongly recommended that for any application in Europe while driving pin 10 with a 3.3V source a 150 Ohm limiting resistor should be added in between Pin 10 and 3.3V driver.

Table 2 – Radio Mode

| Radio Mode | TXPA (Pin 11) | RXPA (Pin 12) | *PACTL (Pin 10) |
|------------|---------------|---------------|-----------------|
| Receive | Low | High | 0V |
| Transmit | High | Low | 0.5V – 3.3V |

* In Transmit mode Voltage at PACTL pin should be applied after setting TXPA High and RXPA Low. In RX mode PACTL should be turned off first.

**5 Absolute Maximum Ratings**

| | |
|--|----------------------------|
| Storage Temperature | -65°C to +150°C |
| Ambient Temperature with Power Applied | -55°C to +125°C |
| Supply Voltage on any power supply pin relative to | $V_{SS} - 0.3V$ to $+3.9V$ |
| DC Voltage to Logic Inputs ^[3] | -0.3V to $V_{IO} + 0.3V$ |
| DC Voltage applied to Outputs in High-Z State | -0.3V to $V_{IO} + 0.3V$ |
| Static Discharge Voltage (Digital) ^[4] | >2000V |
| Static Discharge Voltage (RF) ^[4] | 1100V |
| PACTL Bias | 3.7V |

6 Operating Conditions

| | | | |
|--|--------|---------|-------|
| V_{CC} | 2.4V | to | 3.6V |
| T_A (Ambient Temperature under Bias) | 0°C | to | +70°C |
| Ground Voltage | 0V | | |
| F_{OSC} (Crystal Frequency) | 12 MHz | ±30 ppm | |

7 DC Characteristics (T = 25°C, V_{CC} = 3V, f_{OSC} = 12.000 MHz, *PACTL = 3.3V)**Table 3 - DC Characteristics**

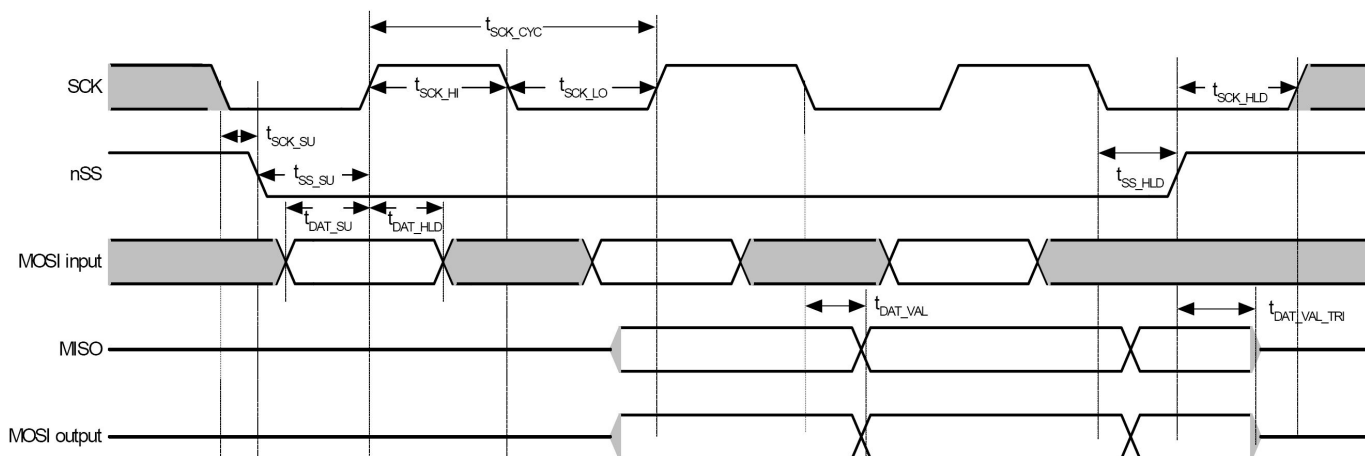
| Parameter | Description | Conditions | Min. | Typ. | Max. | Unit |
|-----------------------|-----------------------------|-----------------|------|------|----------------|------|
| V_{CC} | Power Supply Voltage | 0 to 70°C | 1.8 | | 3.6 | V |
| V_{IO} | Voltage applied to I/O | | | | $V_{CC} + 0.7$ | V |
| I_{synth} | I_{CC} during Synth Start | | | 8.4 | | mA |
| TX I_{CC5} | I_{CC} during Transmit | *PA = 5 | | 90 | 100 | mA |
| TX I_{CC6} | I_{CC} during Transmit | *PA = 6 | | 90 | 100 | mA |
| TX I_{CC7} | I_{CC} during Transmit | *PA = 7 | | 110 | 170 | mA |
| RX I_{CCoff} | I_{CC} during Receive | LNA off, ATT on | | 20 | | mA |
| RX I_{CCon} | I_{CC} during Receive | LNA on, ATT off | | 23 | | mA |
| I_{SB} | Sleep Mode Current I_{CC} | | | 6.8 | 10.0 | µA |

8 AC Characteristics^[5]

Table 4 – SPI Interface^[6]

| Parameter | Description | Min. | Typ. | Max. | Unit |
|---------------------|---|-------|------|------|------|
| t_{SCK_CYC} | SPI Clock Period | 238.1 | | | nS |
| t_{SCK_HI} | SPI Clock High Time | 100 | | | nS |
| t_{SCK_LO} | SPI Clock Low Time | 100 | | | nS |
| t_{DAT_SU} | SPI Input Data Set-up Time | 25 | | | nS |
| t_{DAT_HLD} | SPI Input Data Hold Time | 10 | | | nS |
| t_{DAT_VAL} | SPI Output Data Valid Time | 0 | | 50 | nS |
| $t_{DAT_VAL_TRI}$ | SPI Output Data Tri-state (MOSI from Slave Select Deassert) | | | 20 | nS |
| t_{SS_SU} | SPI Slave Select Set-up Time before first positive edge of SCK ^[7] | 10 | | | nS |
| t_{SS_HLD} | SPI Slave Select Hold Time after last negative edge of SCK | 10 | | | nS |
| t_{SS_PW} | SPI Slave Select Minimum Pulse Width | 20 | | | nS |
| t_{SCK_SU} | SPI Slave Select Set-up Time | 10 | | | nS |
| t_{SCK_HLD} | SPI SCK Hold Time | 10 | | | nS |
| t_{RESET} | Minimum RST pin pulse width | 10 | | | nS |

Figure 7 - SPI Timing



Notes

[5] AC values are not guaranteed if voltage on any pin exceeds V_{IO} .

[6] $C_{LOAD} = 30$ pF.

[7] SCK must start low at the time \overline{SS} goes low, otherwise the success of SPI transactions are not guaranteed.

Table 5 – Radio Parameters

| Parameter Description | Conditions | Min. | Typ. | Max. | Unit |
|---|--------------------------|-------|-------|-------|----------|
| RF Frequency Range | | 2.400 | | 2.483 | GHz |
| Receiver (T=25°C, VCC = 3.0V, f _{osc} = 12.000000MHz, BER < 1E-3) | | | | | |
| Sensitivity 125kbps 64-8DR | BER 1E-3 | | -93 | | dBm |
| Sensitivity 250-kbps 32-8DR | BER 1E-3 | | -89 | | dBm |
| Sensitivity | CER 1E-3 | -80 | -83 | | dBm |
| Sensitivity GFSK | BER 1E-3, ALL SLOW = 1 | | -80 | | dBm |
| LNA gain | | | 22.8 | | dB |
| ATT gain | | | -31.7 | | dB |
| Maximum Received Signal | LNA On | -15 | -6 | | dBm |
| RSSI value for PWR _{in} -60 dBm | LNA On | | 21 | | Count |
| RSSI slope | | | 1.9 | | dB/Count |
| Receive Spurious Emission | | | | | |
| 800 MHz | 100-kHz ResBW | | -79 | | dBm |
| 1.6GHz | 100-kHz ResBW | | -71 | | dBm |
| 3.2 GHz | 100-kHz ResBW | | -65 | | dBm |
| Transmitter (T = 25°C, VCC = 3.0V, PACTL = 3.3V) | | | | | |
| Maximum RF Transmit Power | PA = 7 | +20 | +21 | +23 | dBm |
| Maximum RF Transmit Power | PA = 6 | 17 | 20 | +21 | dBm |
| Maximum RF Transmit Power | PA = 5 | 15 | 17 | 18 | dBm |
| Maximum RF Transmit Power | PA = 4 | 12 | 13 | 15 | dBm |
| Maximum RF Transmit Power | PA = 3 | 9 | 10 | 12 | dBm |
| Maximum RF Transmit Power | PA = 2 | 4 | 5 | 7 | dBm |
| Maximum RF Transmit Power | PA = 1 | -2 | -1 | 0 | dBm |
| Maximum RF Transmit Power | PA = 0 | -7 | -5 | -2 | dBm |
| RF Power Control Range | | | 39 | | dB |
| RF Power Control Range Step Size | seven steps, monotonic | 2 | | 5 | dB |
| Frequency Deviation Min | PN Code Pattern 10101010 | | 270 | | kHz |
| Frequency Deviation Max | PN Code Pattern 11110000 | | 323 | | kHz |
| Error Vector Magnitude (FSK error) | >0 dBm | | 10 | | %rms |
| Occupied Bandwidth | -6 dBc, 100-kHz ResBW | 500 | 876 | 1000 | kHz |



Table 5 – Radio Parameters (continued)

| Parameter Description | Conditions | Min. | Typ. | Max. | Unit |
|--|--|------|------|------|---------|
| Transmit Spurious Emission (PA = 7) | | | | | |
| In-band Spurious Second Channel Power (± 2 MHz) | | | -38 | | dBm |
| In-band Spurious Third Channel Power (> 3 MHz) | | | -44 | | dBm |
| Non-Harmonically Related Spurs (800MHz) | | | -38 | | dBm |
| Non-Harmonically Related Spurs (1.6GHz) | | | -34 | | dBm |
| Non-Harmonically Related Spurs (3.2GHz) | | | -47 | | dBm |
| Harmonic Spurs (Second Harmonic) | | | -43 | | dBm |
| Harmonic Spurs (Third Harmonic) | | | -48 | | dBm |
| Fourth and Greater Harmonics | | | -59 | | dBm |
| Power Management (with 30ppm crystal) | | | | | |
| Crystal start to 10ppm | | | 0.7 | 1.3 | ms |
| Crystal start to IRQ | XSIRQ EN = 1 | | 0.6 | | ms |
| Synth Settle | Slow channels | | | 270 | μ s |
| Synth Settle | Medium channels | | | 180 | μ s |
| Synth Settle | Fast channels | | | 100 | μ s |
| Link turn-around time | GFSK | | | 30 | μ s |
| Link turn-around time | 250 kbps | | | 62 | μ s |
| Link turn-around time | 125 kbps | | | 94 | μ s |
| Link turn-around time | <125 kbps | | | 31 | μ s |
| Max. packet length | <60ppm crystal-to-crystal all modes except 64-DDR | | | 40 | bytes |
| Max. packet length | <60ppm crystal-to-crystal 64-DDR | | | 16 | bytes |

10 RF Regulatory Requirements

To satisfy FCC RF exposure requirements for mobile transmitting devices, a separation distance of 20 cm or more should be maintained between the antenna of this device and persons during device operation. To ensure compliance, operations at closer than this distance is not recommended.

The suggested antenna is an external $\frac{1}{2}$ dipole type, and it has been qualified and approved for use under the Modular Approval certification. This antenna is designed to be compatible with the RF impedance and frequency range of the AWA24S.

The suggested antenna has been specifically tested with the AWA24S, and has been certified through the regulatory agencies in the US, Canada, and European Union for authorized use. Use of an altered antenna in the AWA24S voids the MA grant for the AWA24S. Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

NOTE: The manufacturer is not responsible for any radio or TV interference caused by unauthorized modifications to this equipment. Such modifications could void the user's authority to operate the equipment.

For more details on the proper installation requirements please review Artaflex User Manual "UMAWA24S".

11 Pin Description

Table 6 - Connector Pin Information

| Pin | Name | Type | Default | Description |
|-----|-----------------|-------|---------|--|
| 1 | GND | Power | GND | Ground |
| 2 | VCC | Power | VCC | Main Supply 2.4 to 3.6 volts |
| 3 | IRQ | I/O | - | Interrupt output (configurable active high or low), or GPIO |
| 4 | RST | Input | Input | Module Reset. Internal on Chip 10k-ohm pull-down resistor. Active HIGH |
| 5 | MOSI | I/O | Input | SPI data input, or SDAT |
| 6 | \overline{SS} | Input | Pull Up | SPI Interface enable, Active LOW |
| 7 | SCK | Input | Input | SPI Clock |
| 8 | MISO | I/O | Hi Z | SPI data output pin or GPIO in 3-pin SPI mode. |
| 9 | GND | Power | GND | Ground |
| 10 | *PACTL | Power | VCC | Power Control – max power at 3.3V - Shut down “0V” |
| 11 | TXPA | Input | Input | Active High to set Module into a Transmit mode (RXPA = Low) |
| 12 | RXPA | Input | Input | Active High to set the Module into a Receive mode (TXPA = Low) |

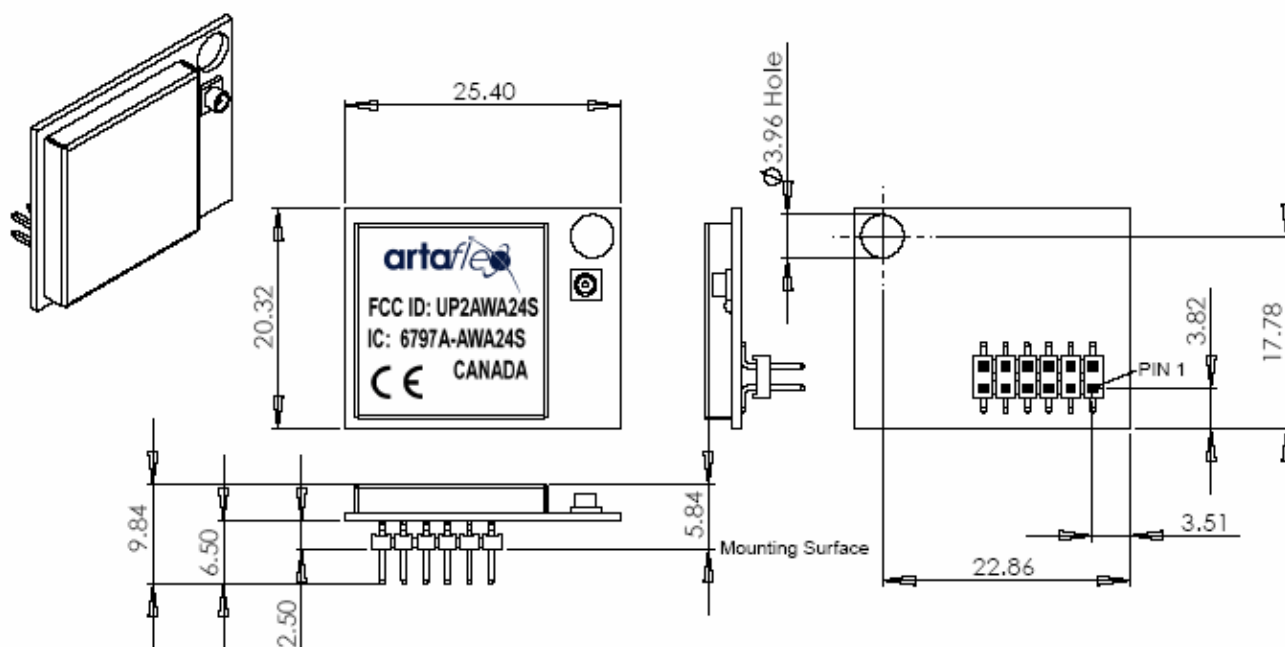
* Pin 10 will require a high current drive as it can sink up to 16mA of current when biased above 2V

12 Reference Documentation

Technical information such as register settings, timing, application interfaces, clocking, and power management for the Cypress Semiconductor CYRF6936 WirelessUSB™ LP 2.4-GHz DSSS Radio System-on-Chip and the CY7C64215 enCoRe™ Full Speed USB Controller are available at www.cypress.com

The datasheet for CYRF6936 is available at:

http://download.cypress.com.edgesuite.net/design_resources/datasheets/contents/cyrf6936_8.pdf



14.1 Standard Part Numbers

Table 7 – Standard Part Numbers

| Part Number | Description | Temperature |
|---------------|---|-------------|
| AWA24S-12H2-C | 2.4GHz DSSS PA Radio with 12 Pin Header in Commercial Temperature | 0 to 70°C |
| AWA24S-12S2-C | 2.4GHz DSSS PA Radio with 12 Pin Socket in Commercial Temperature | 0 to 70°C |

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