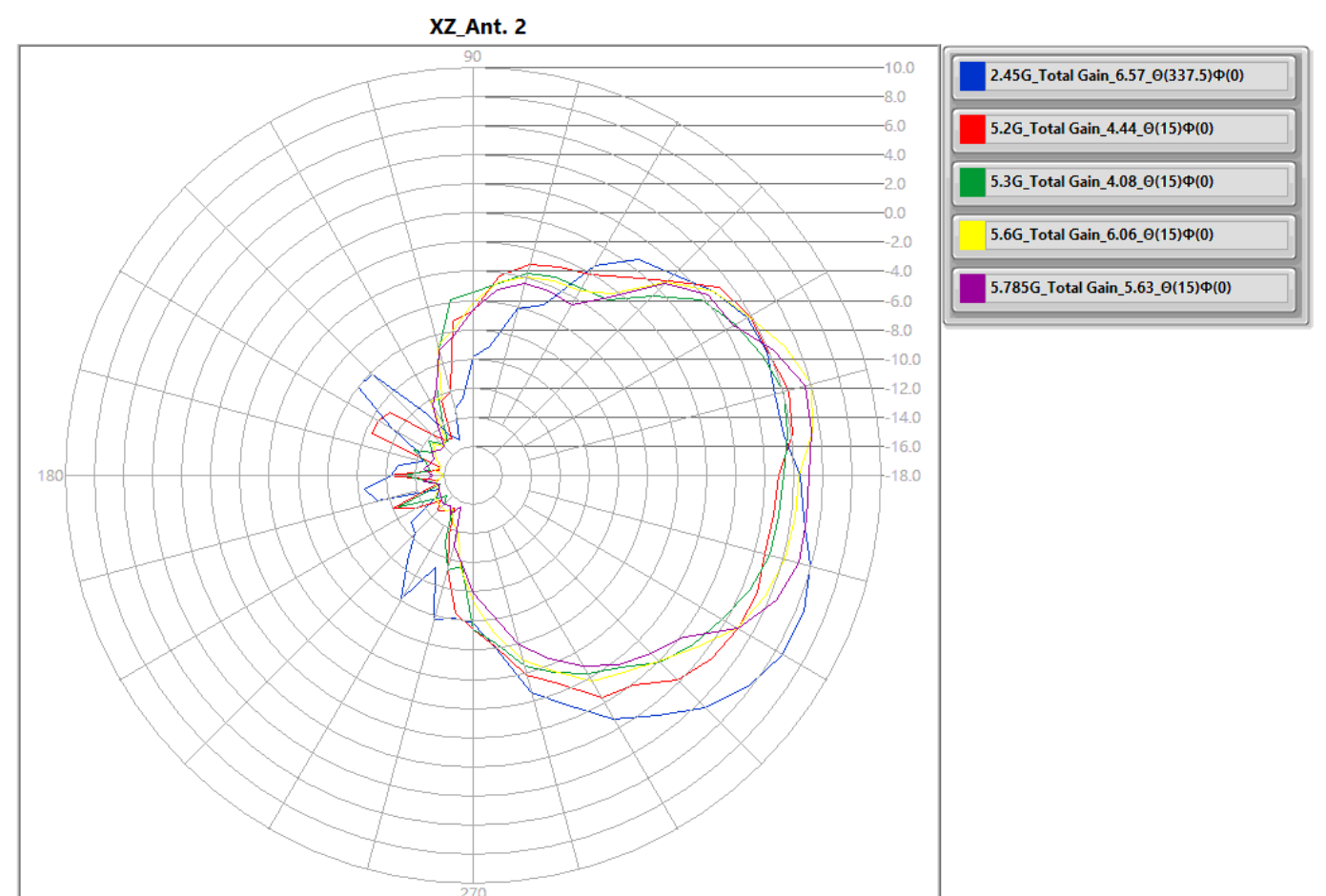
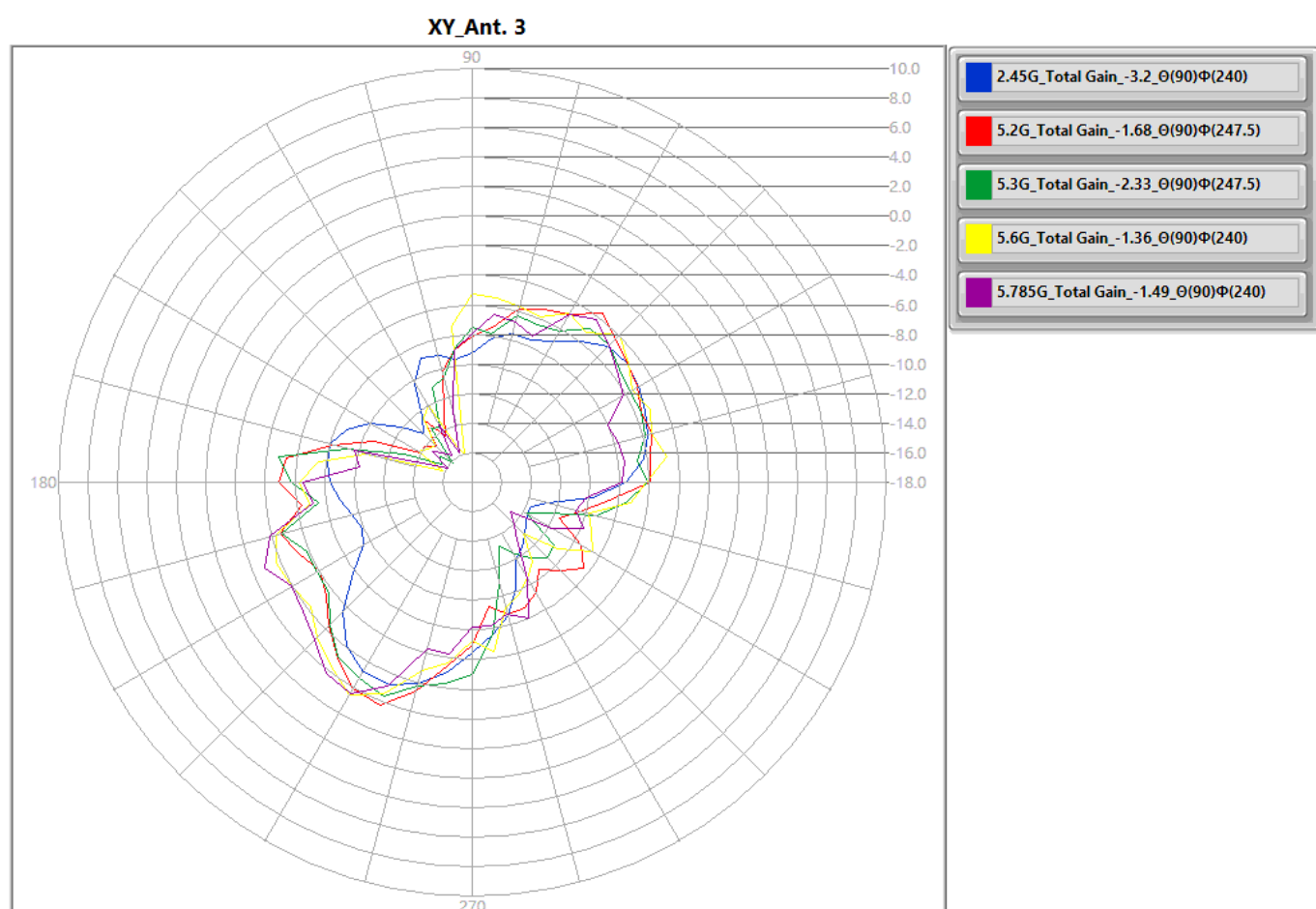
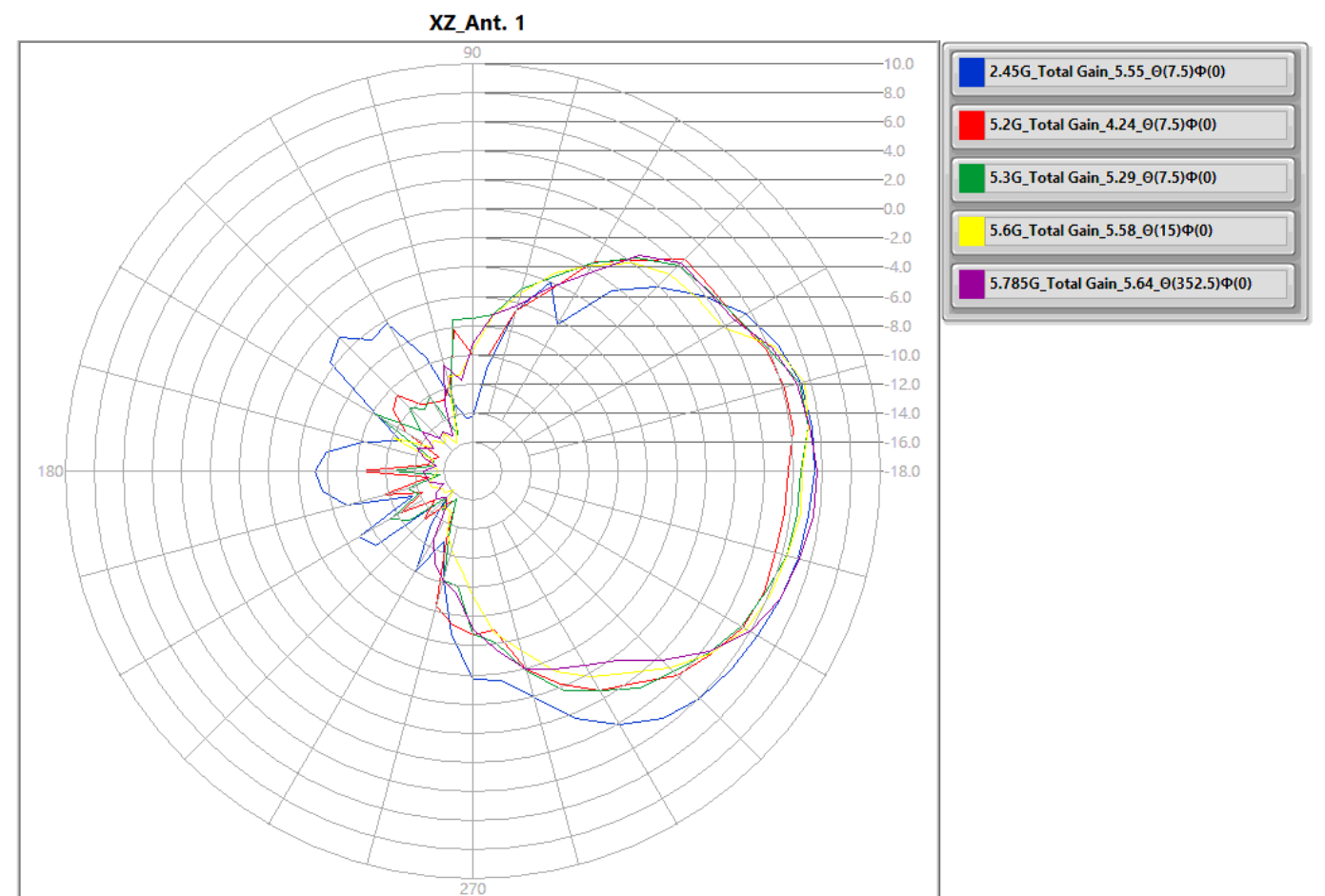
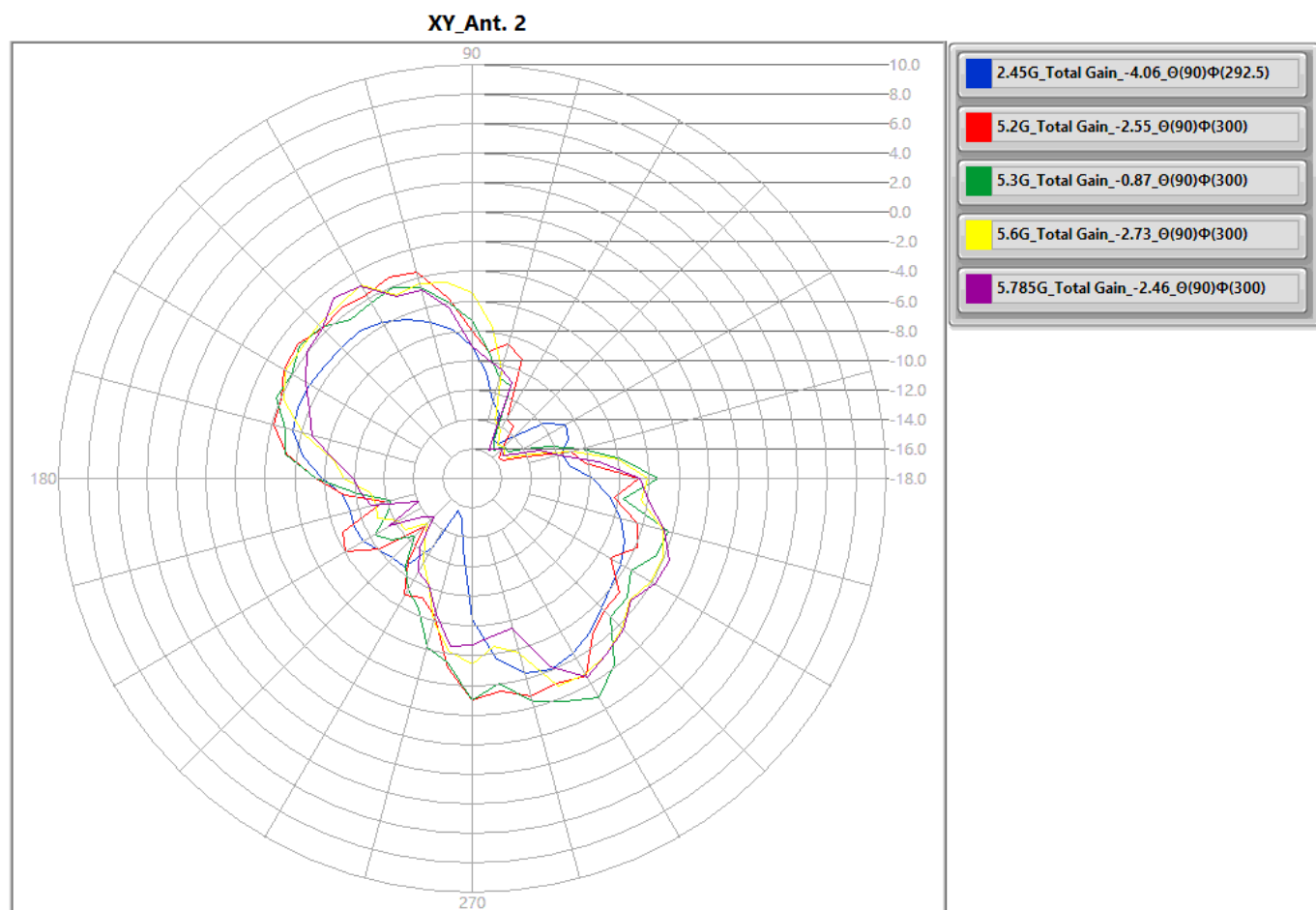
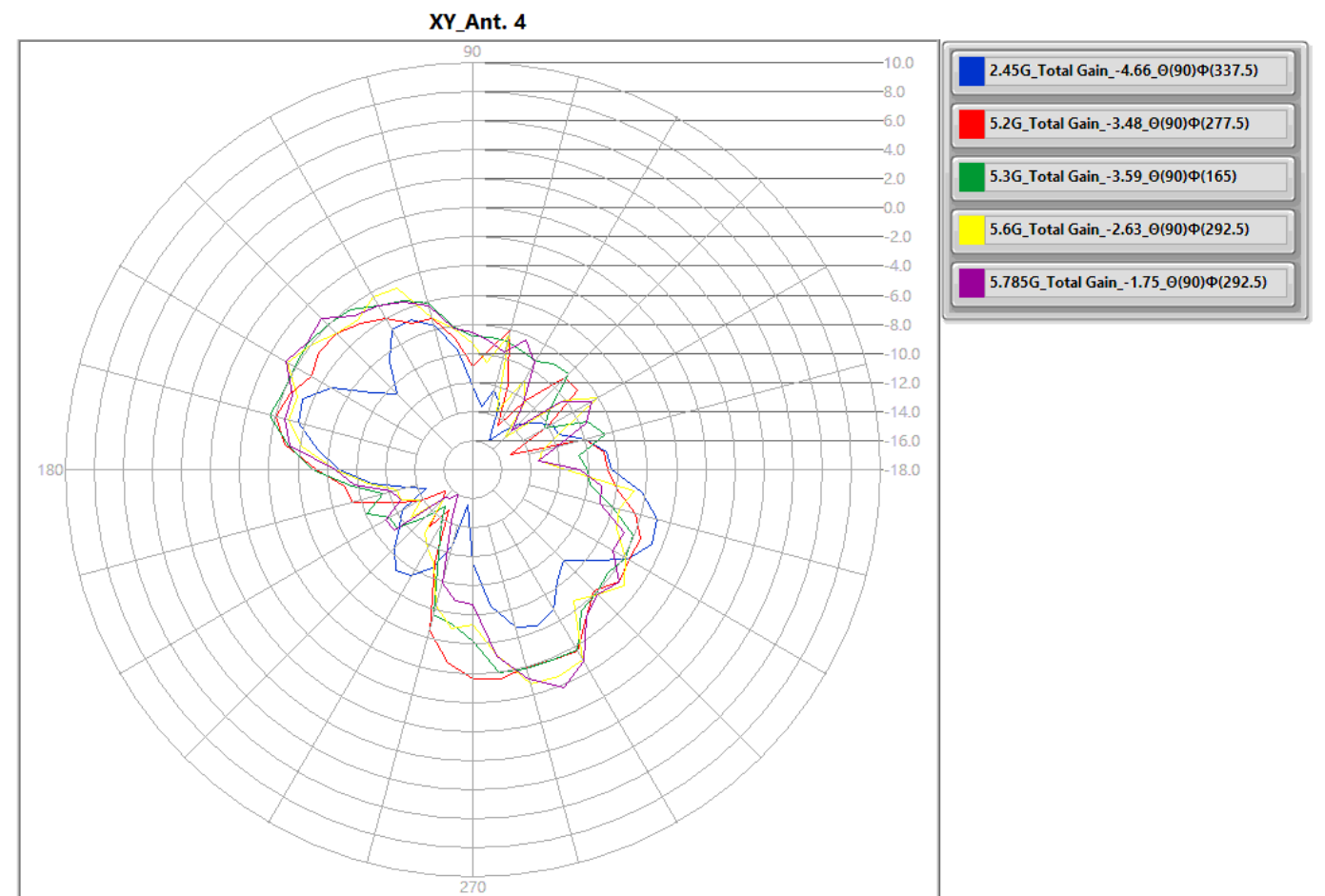
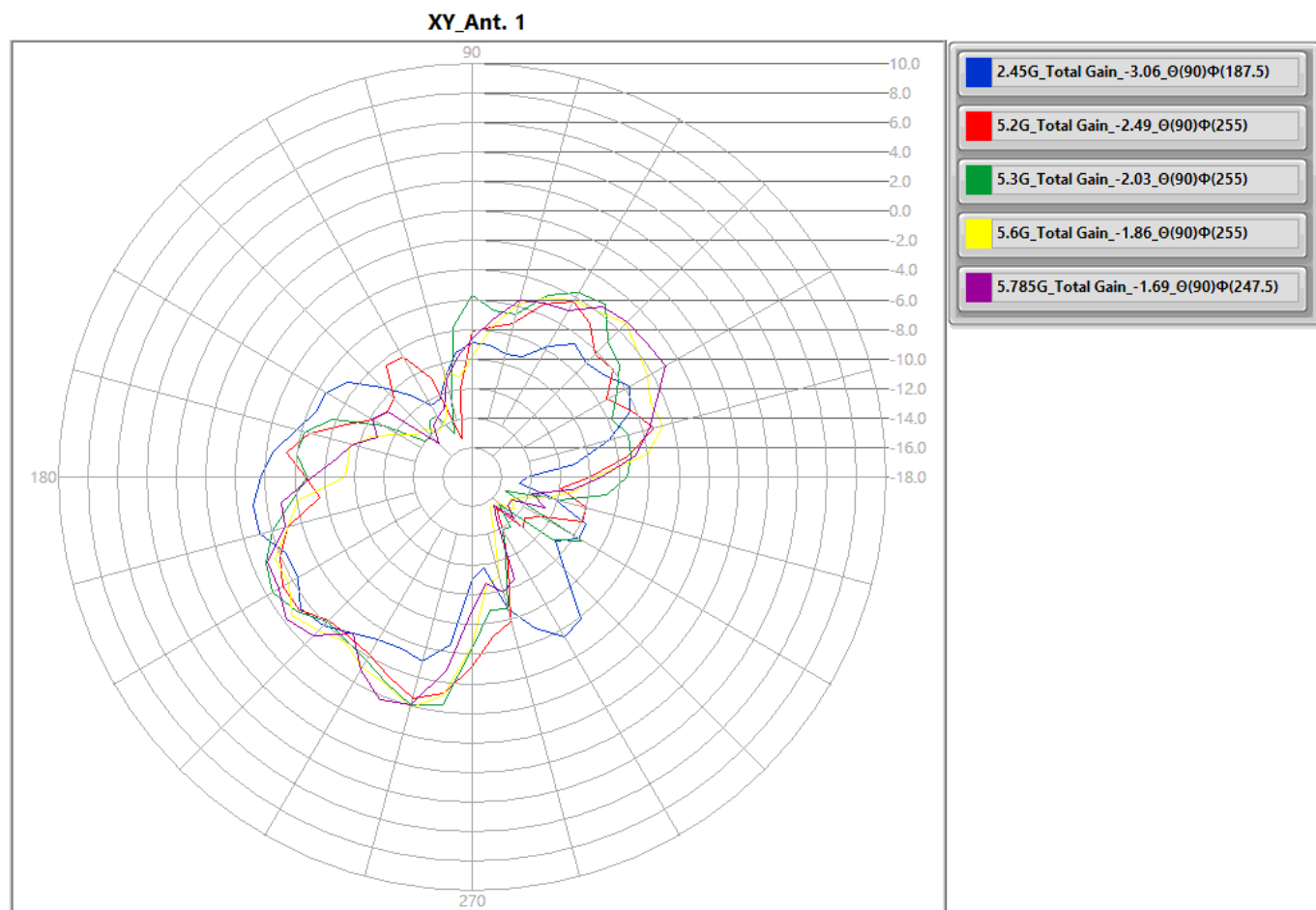
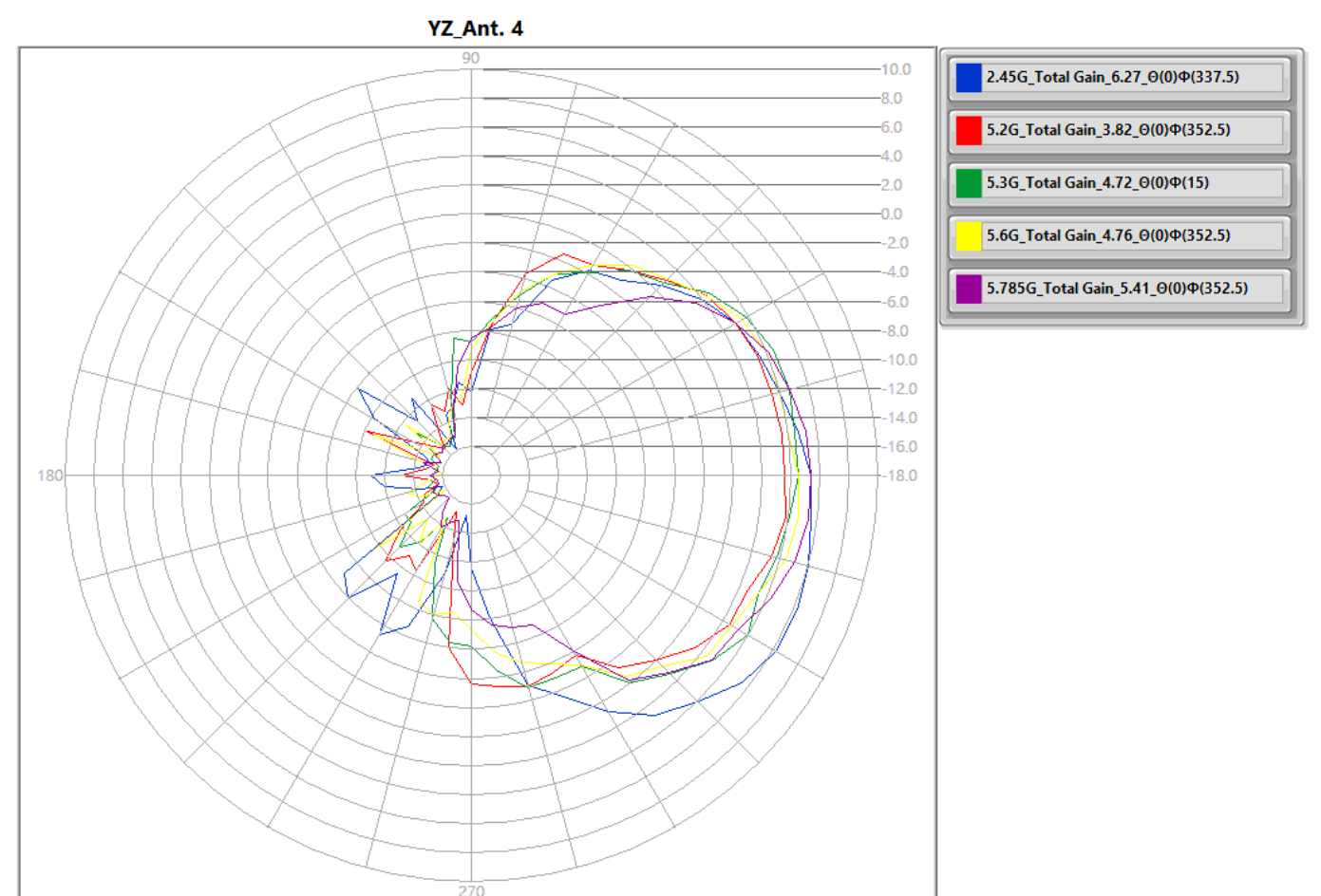
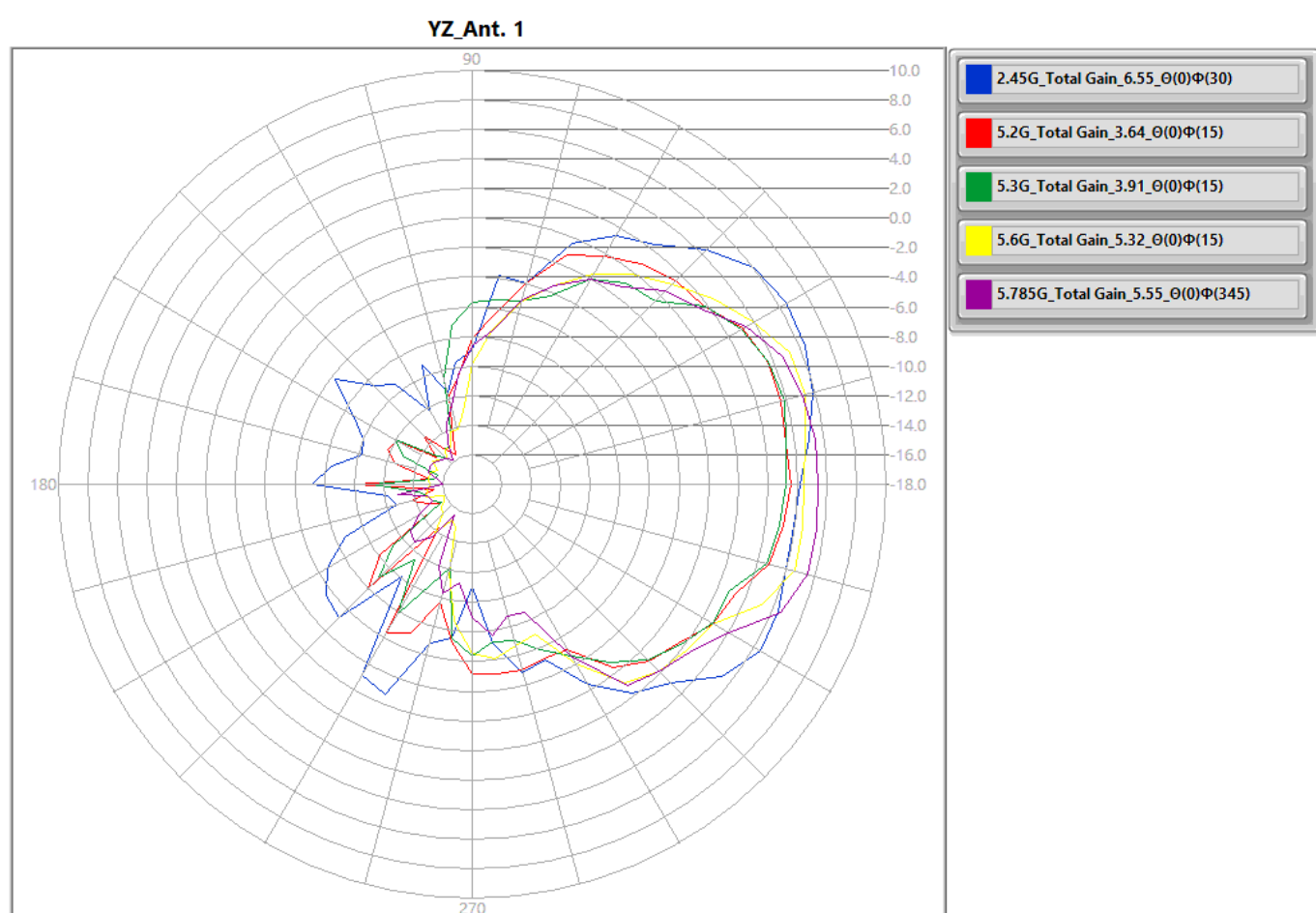
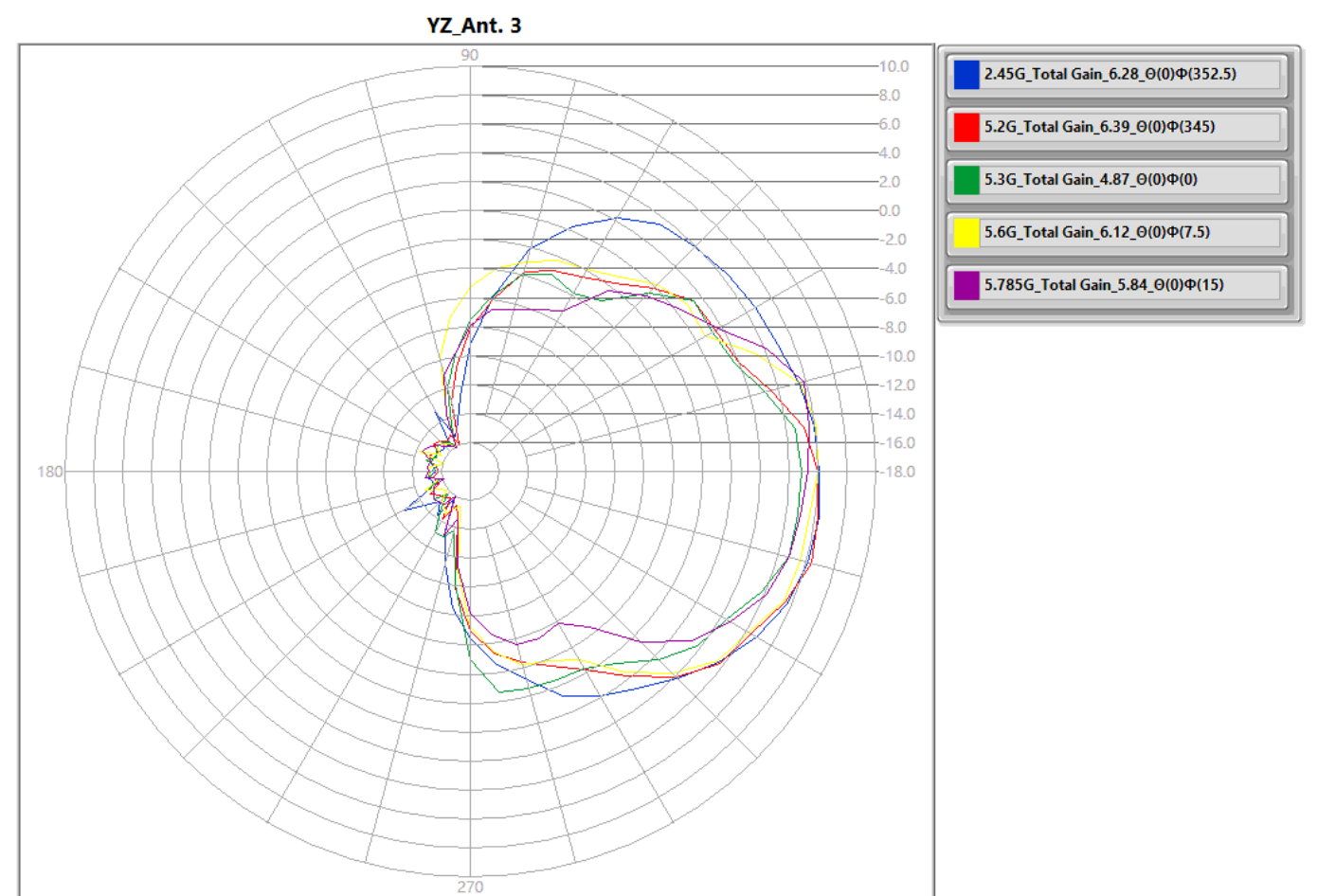
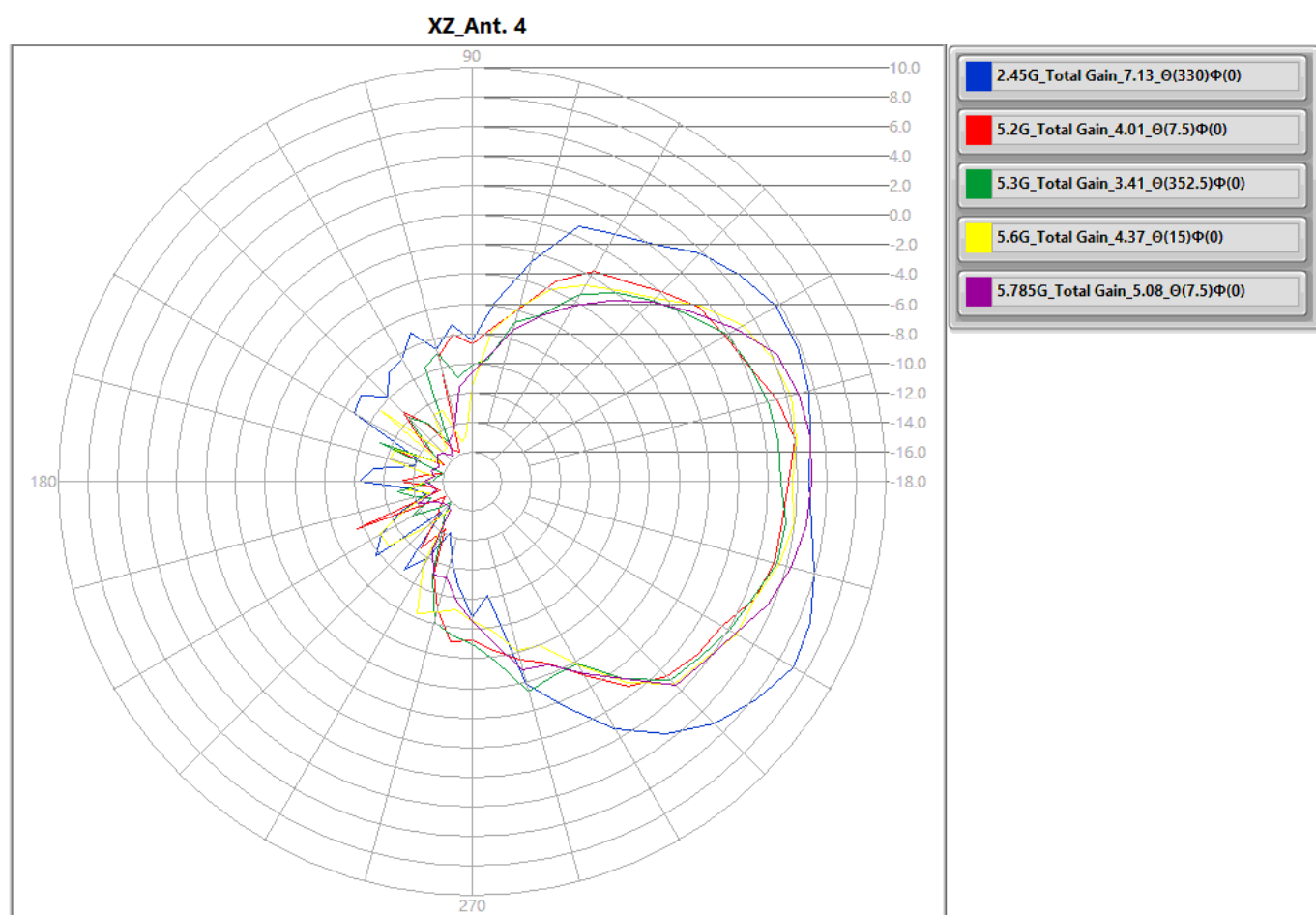
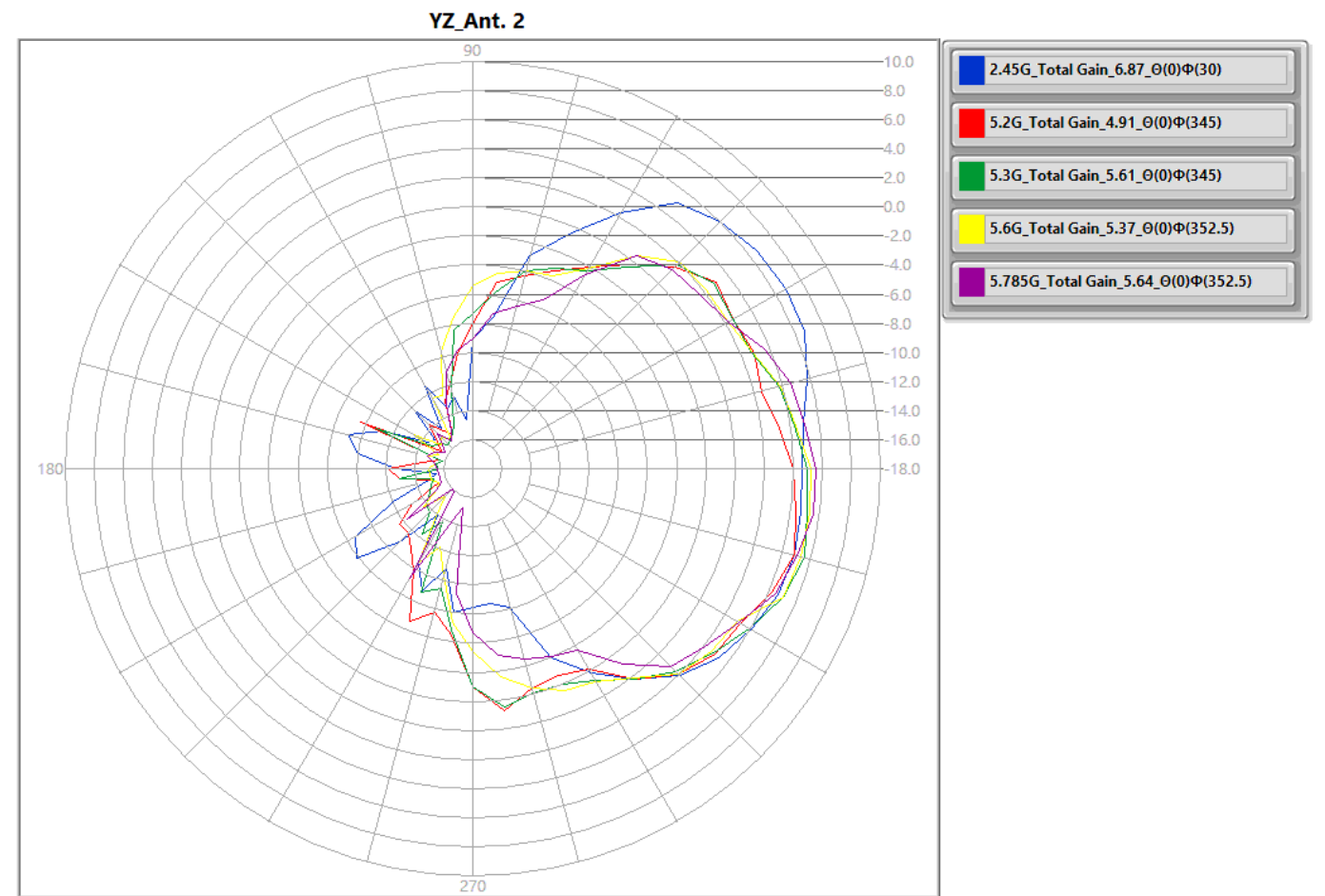
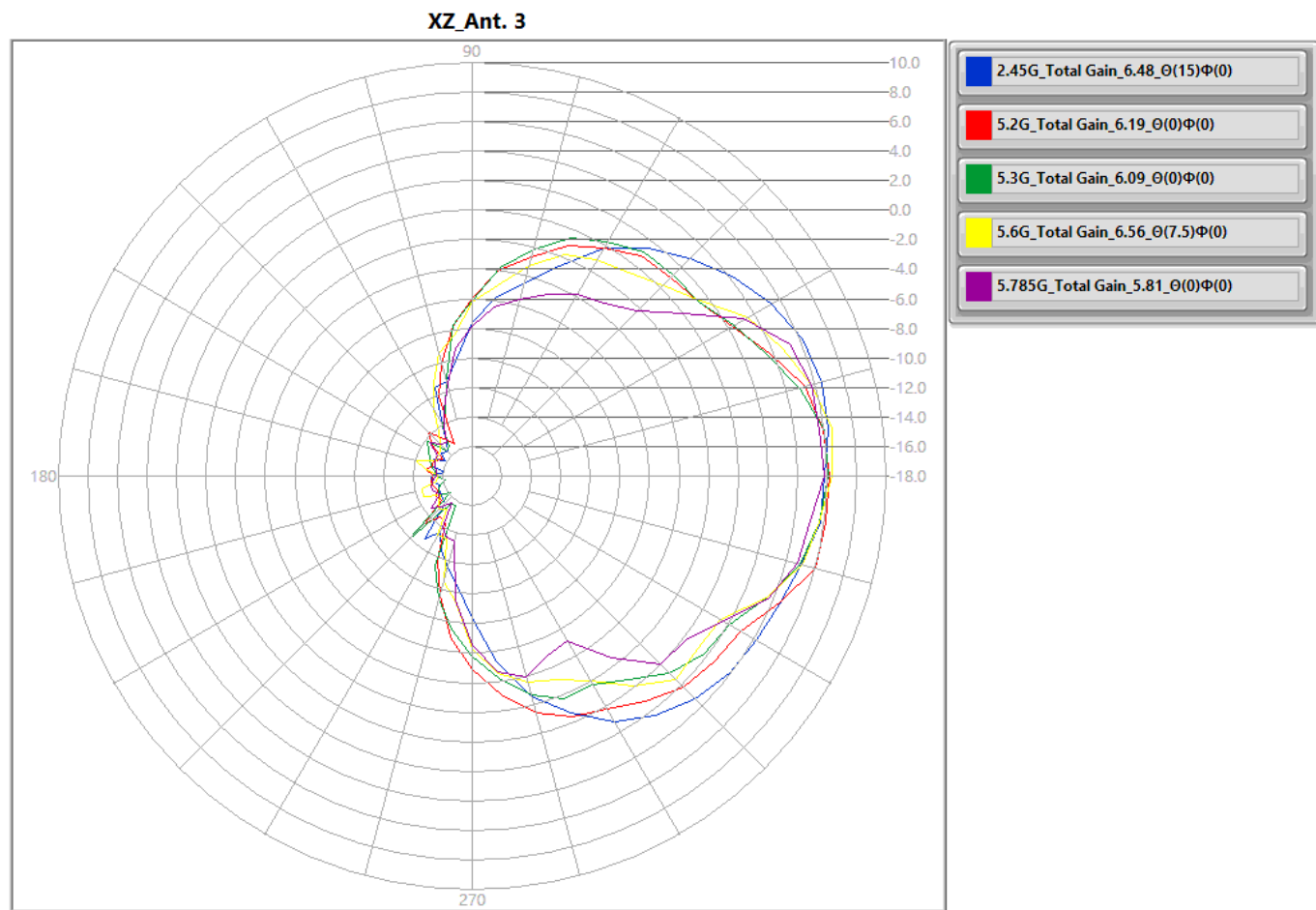


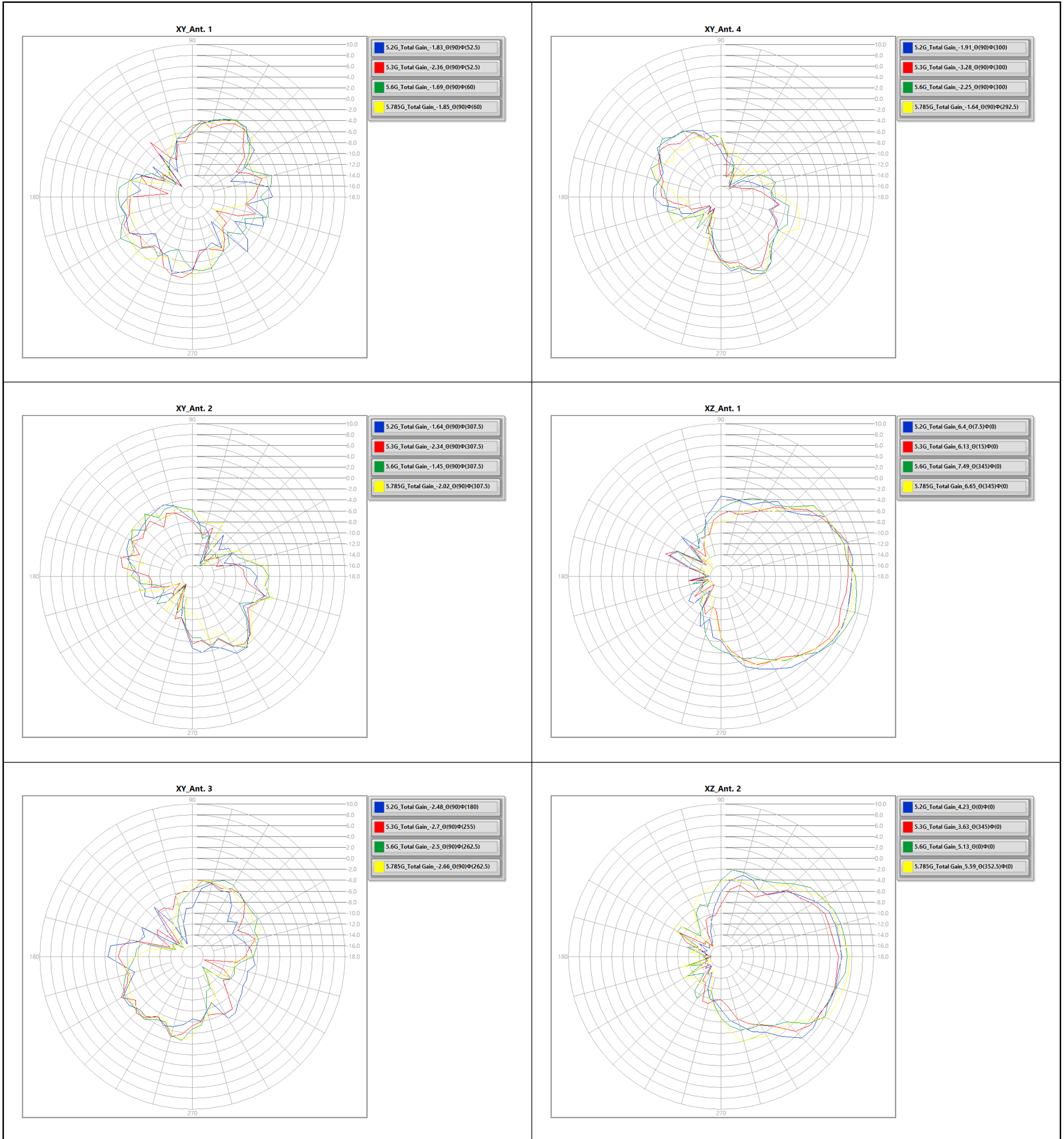
E1(XY plane) – $\Theta(90)\Phi(0-360)$
E2(XZ plane) – $\Theta(0-180)\Phi(0)$ and $\Theta(0-180)\Phi(180)$
E3(YZ plane) – $\Theta(0-180)\Phi(90)$ and $\Theta(0-180)\Phi(270)$

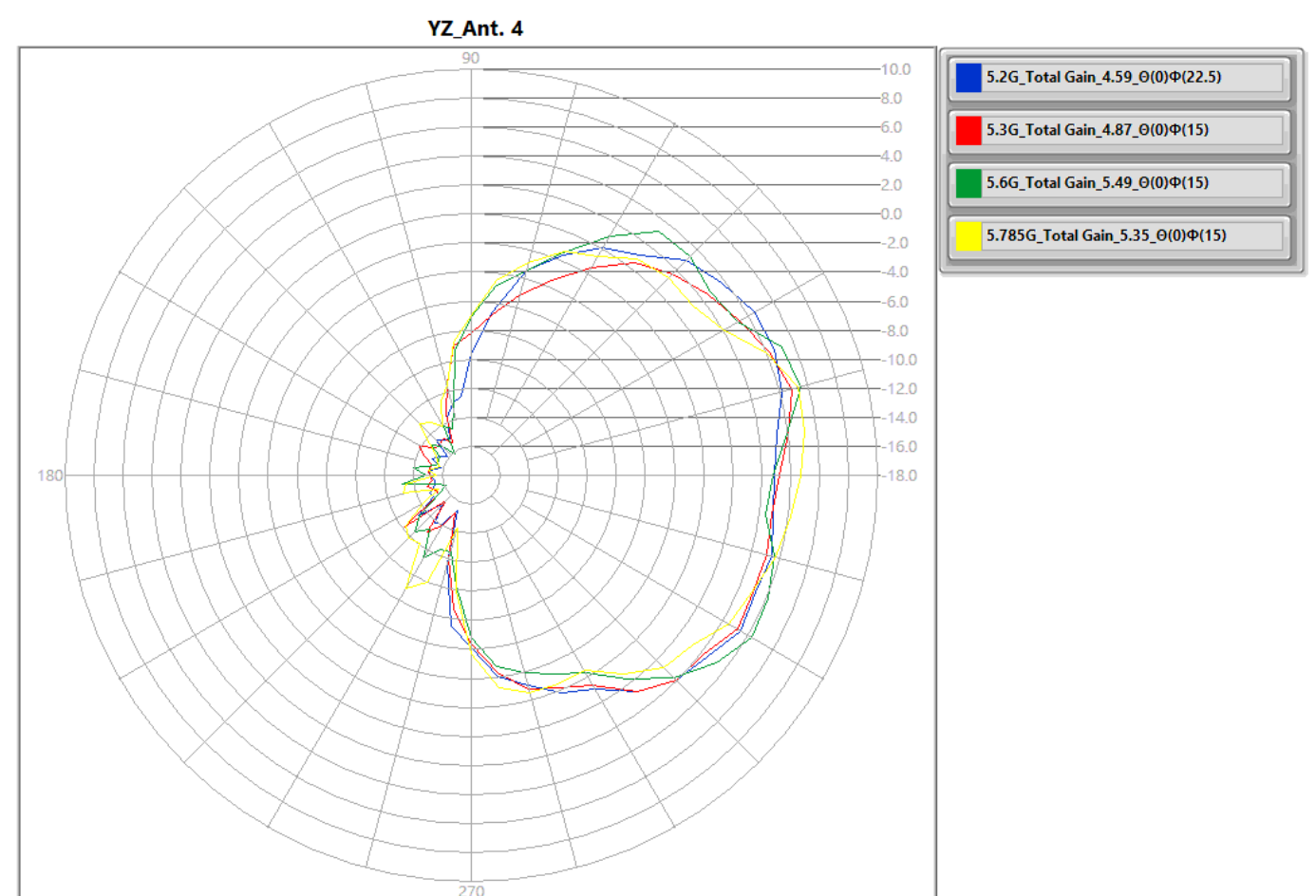
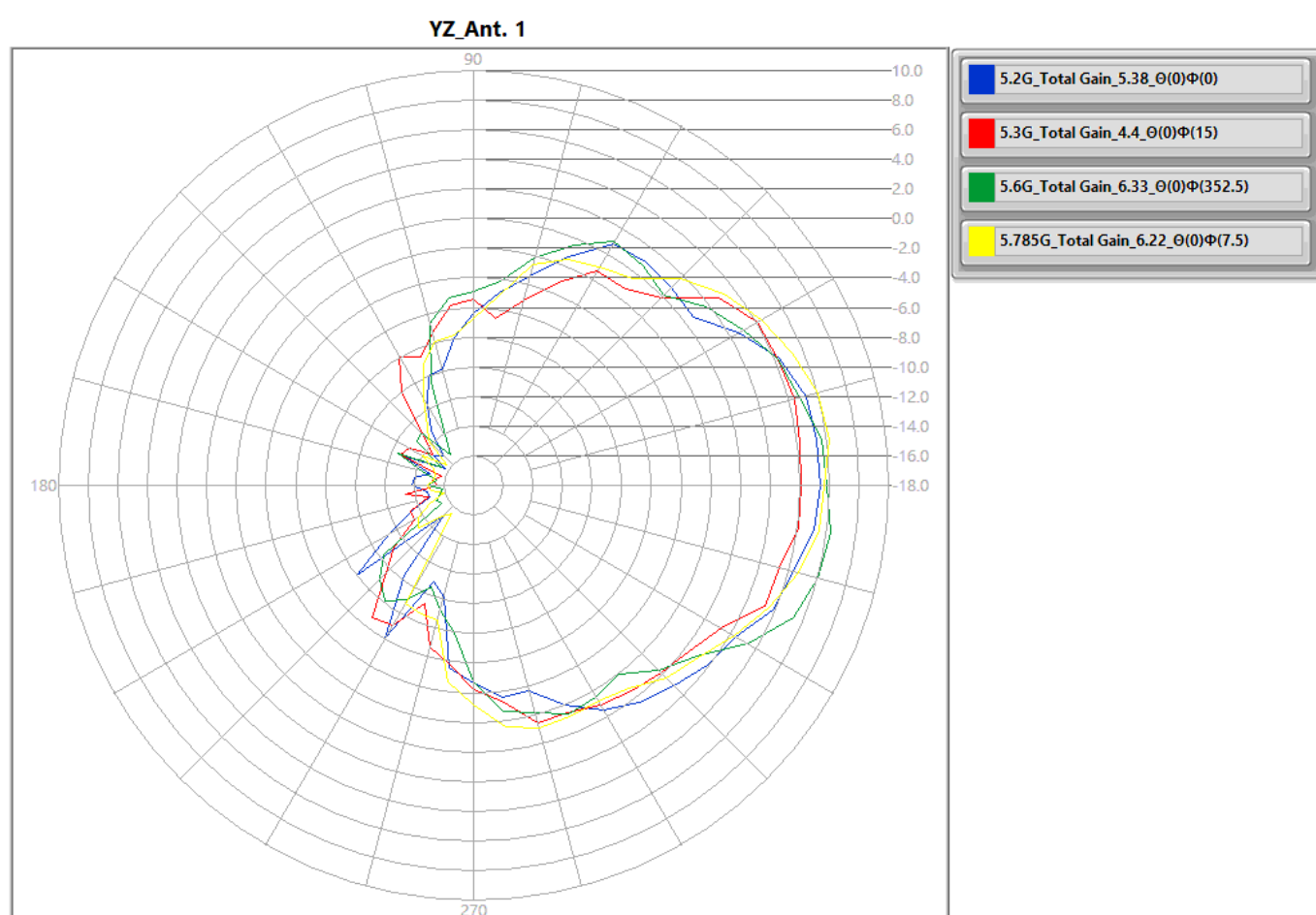
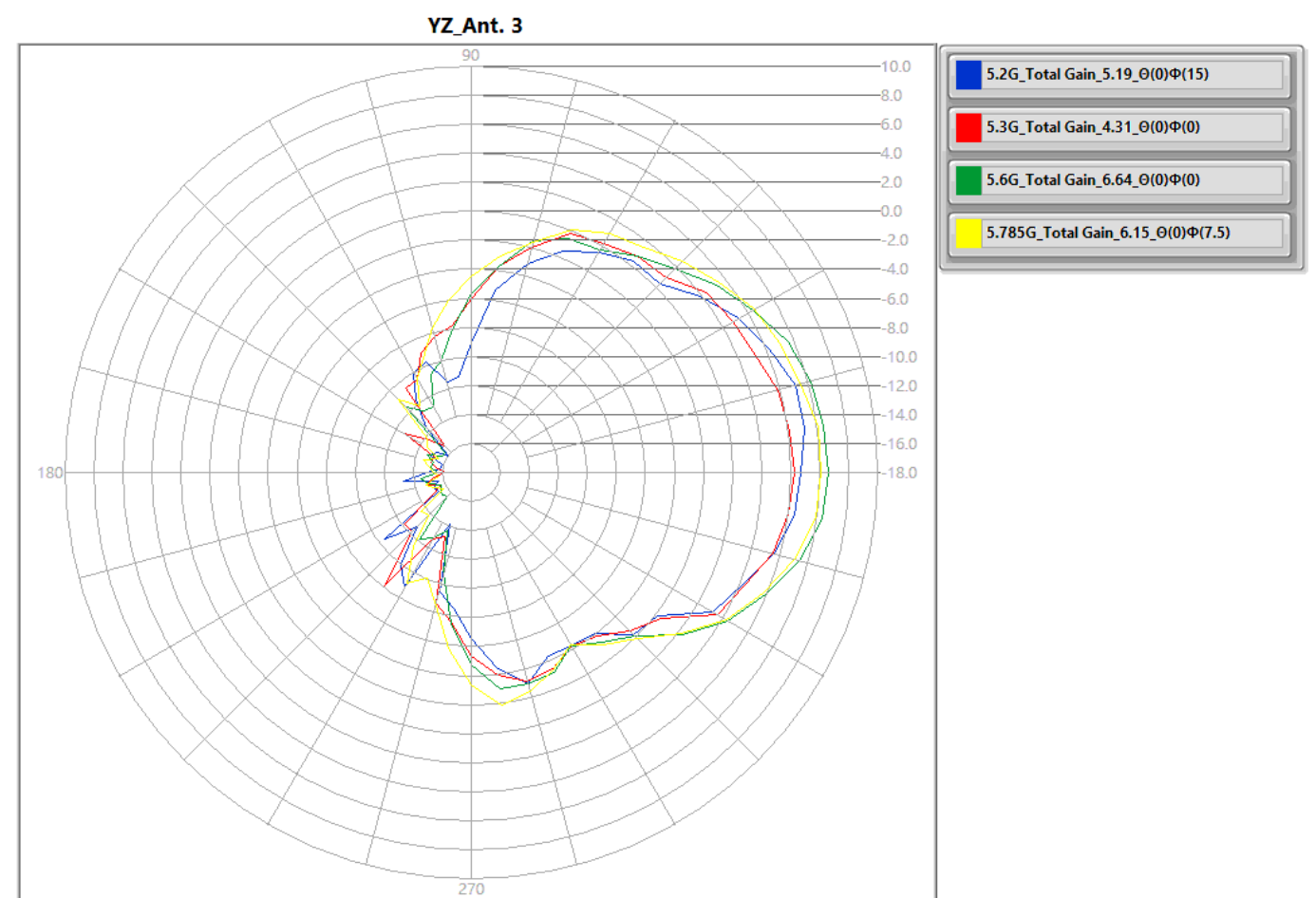
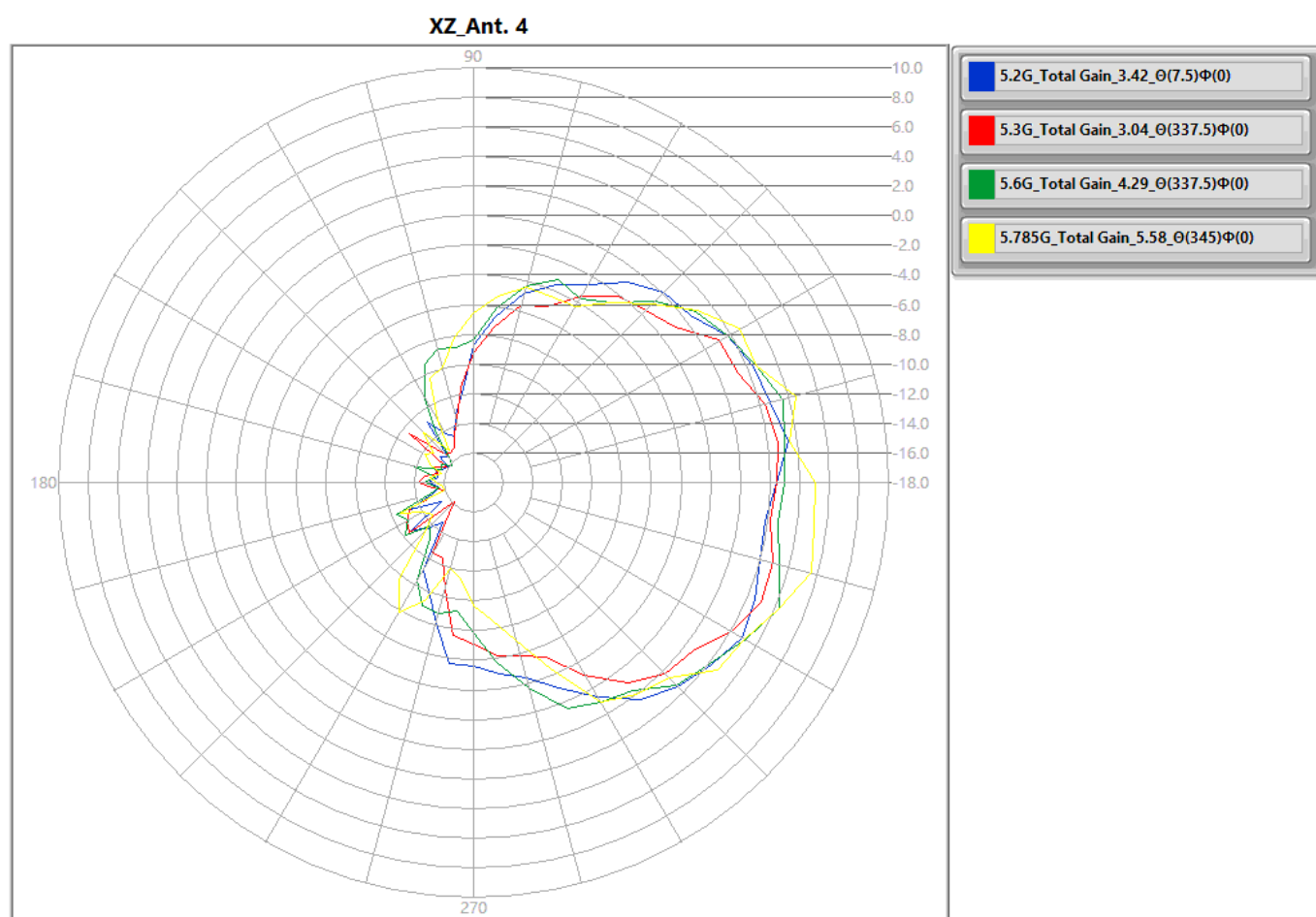
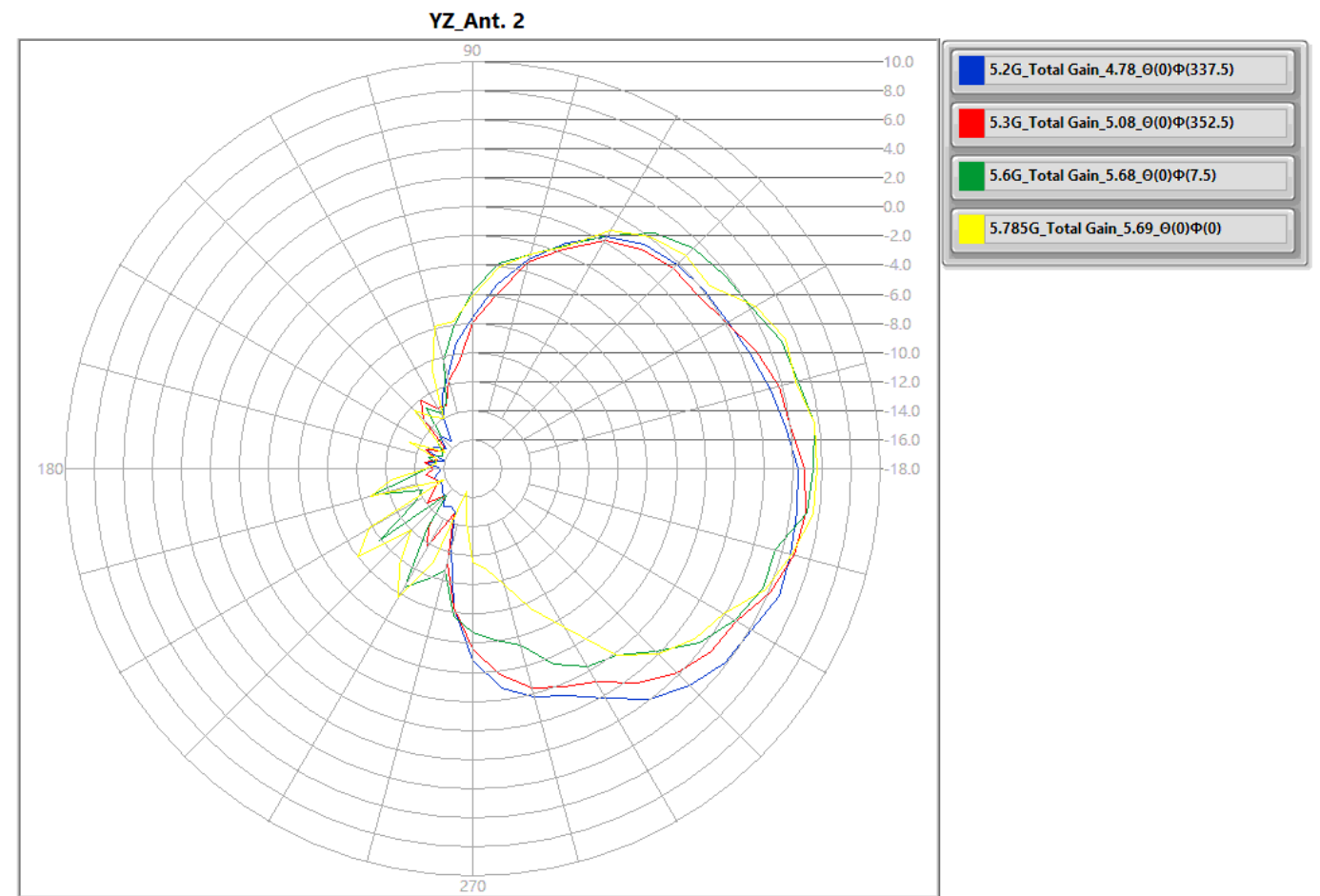
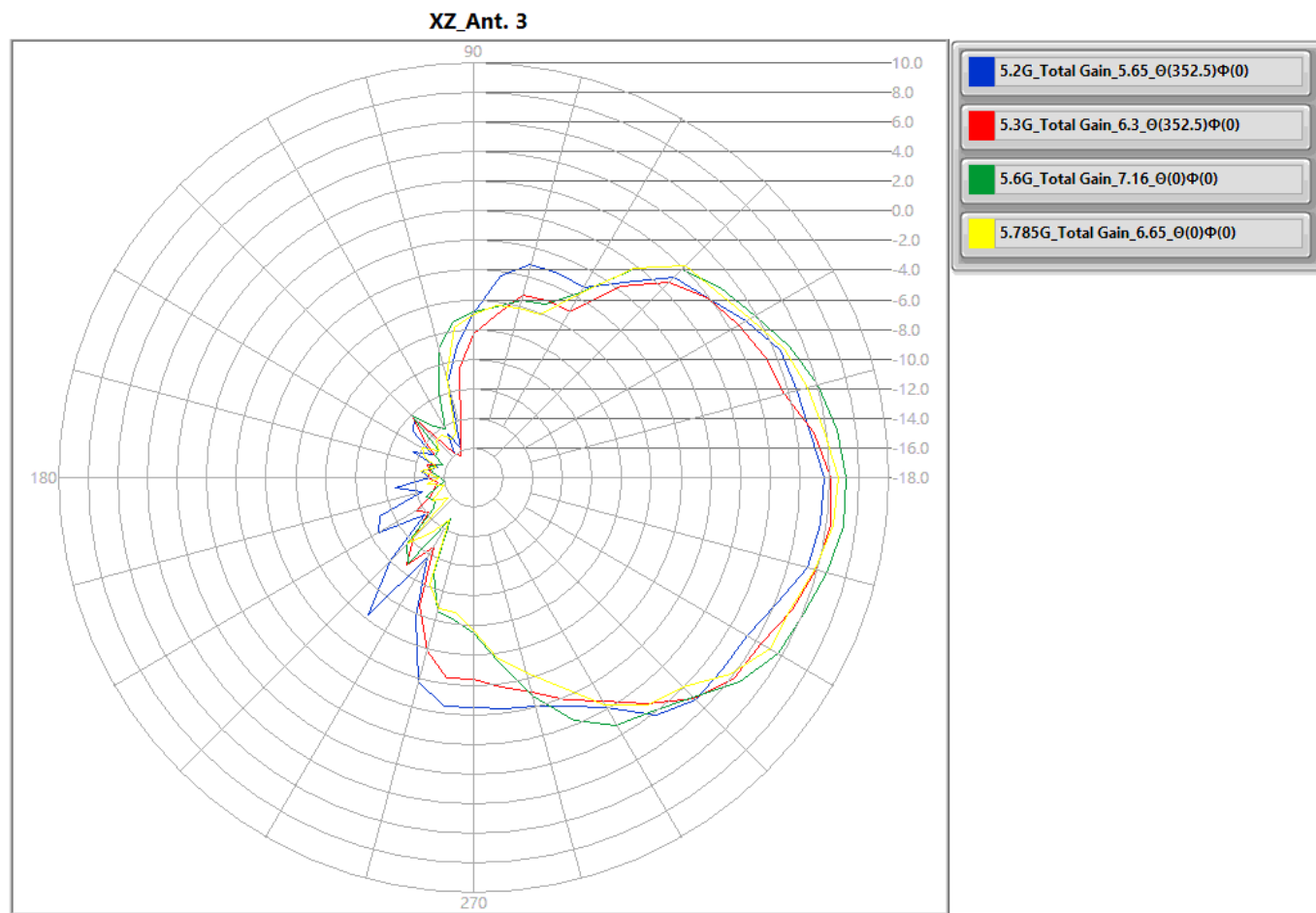




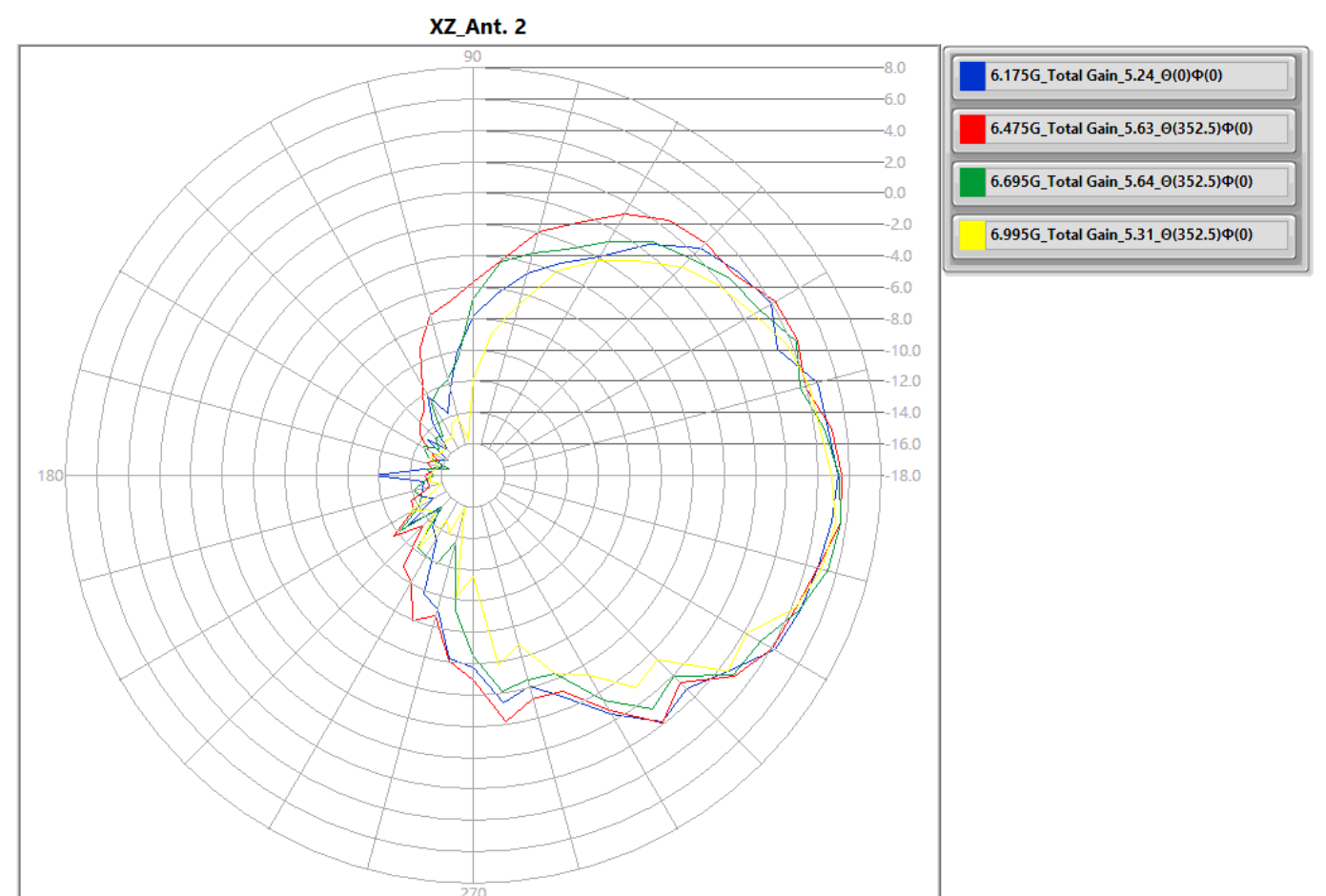
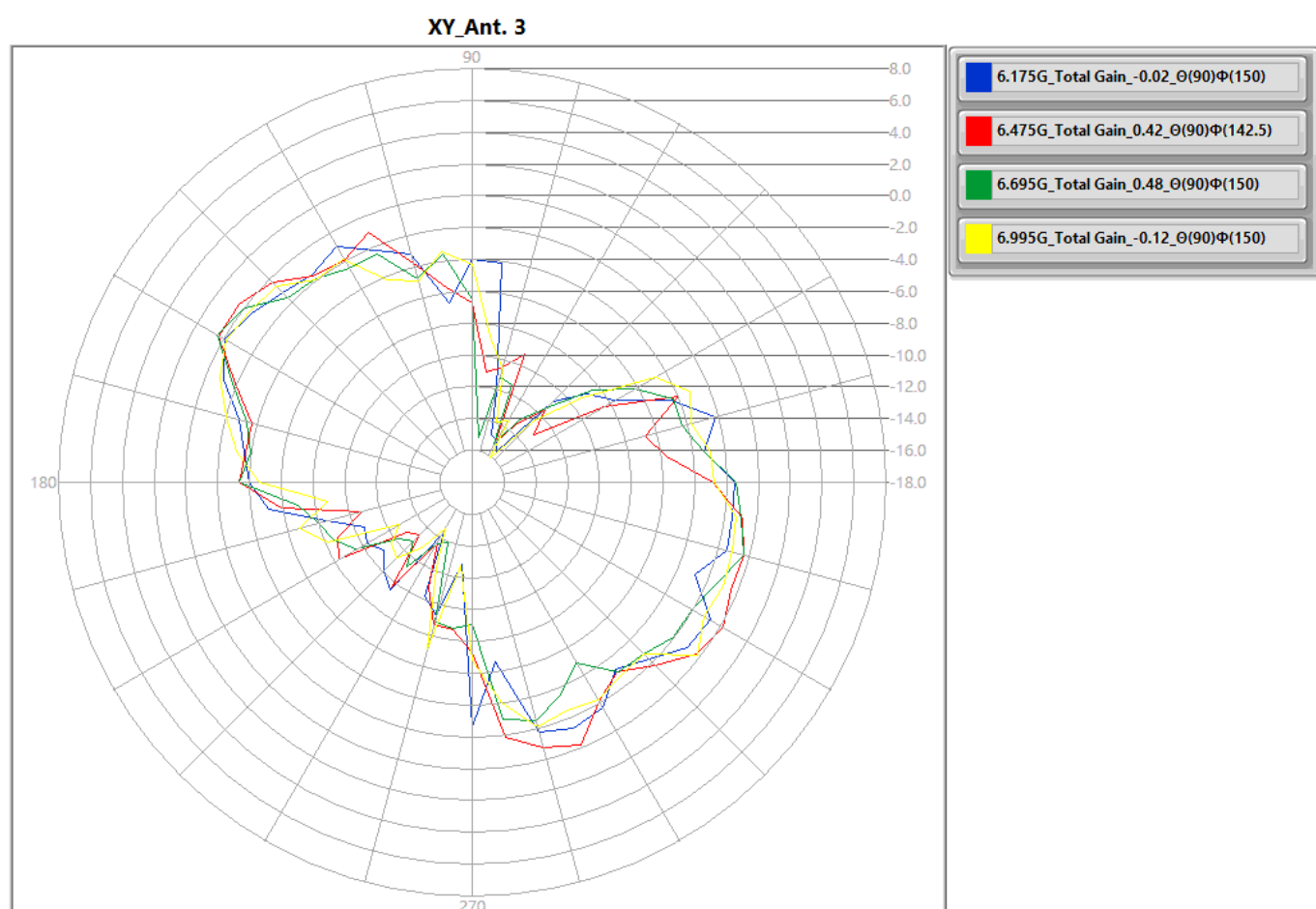
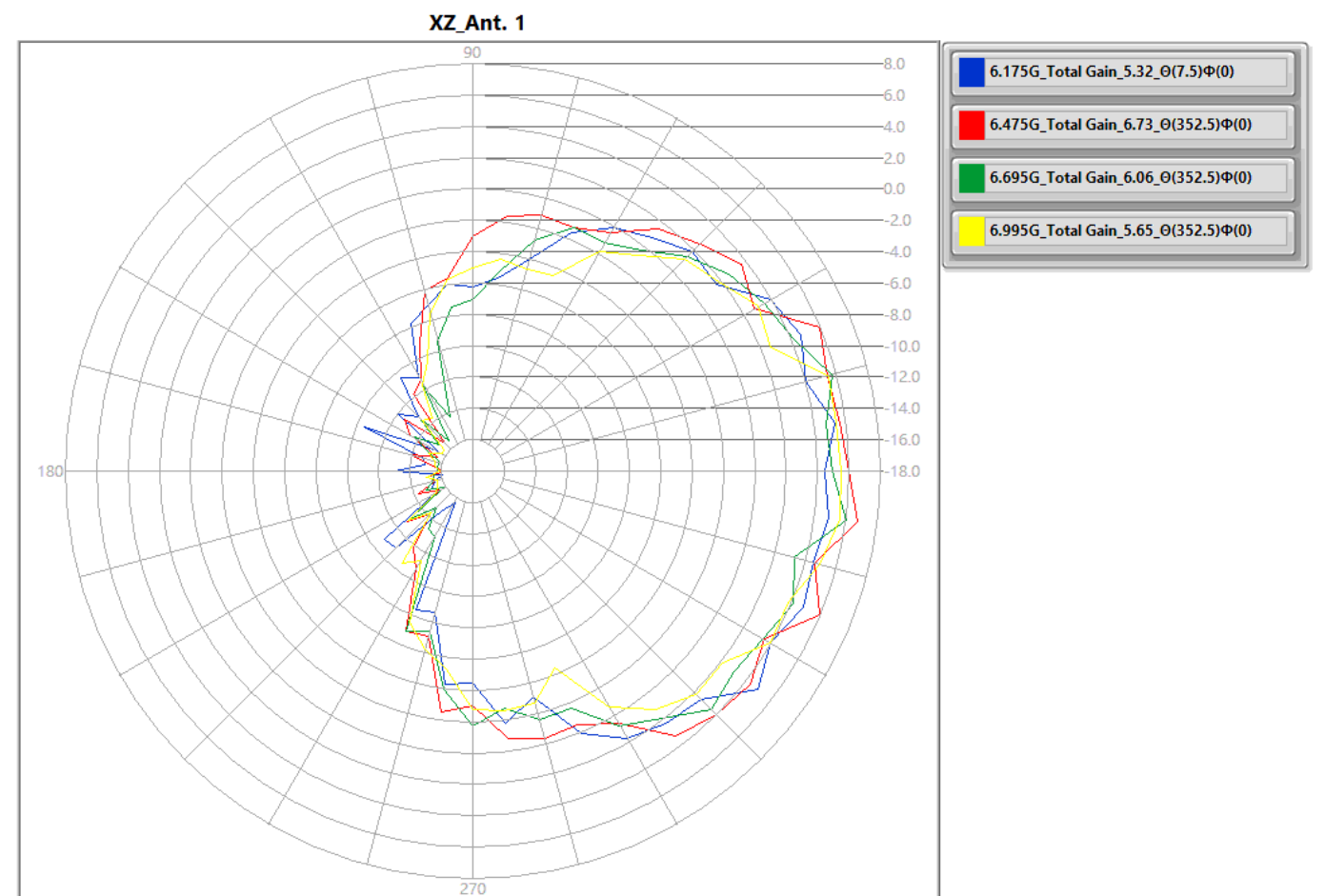
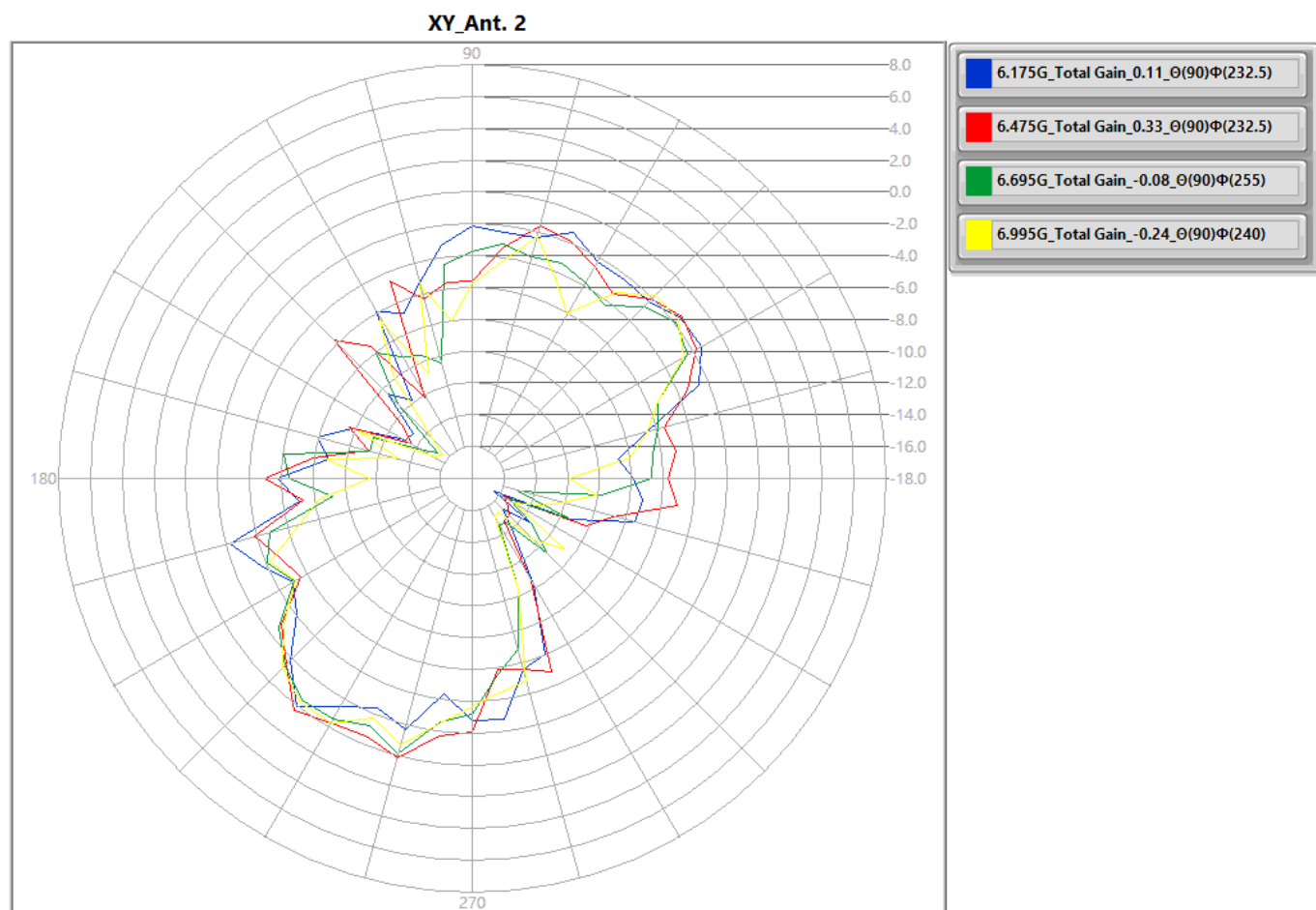
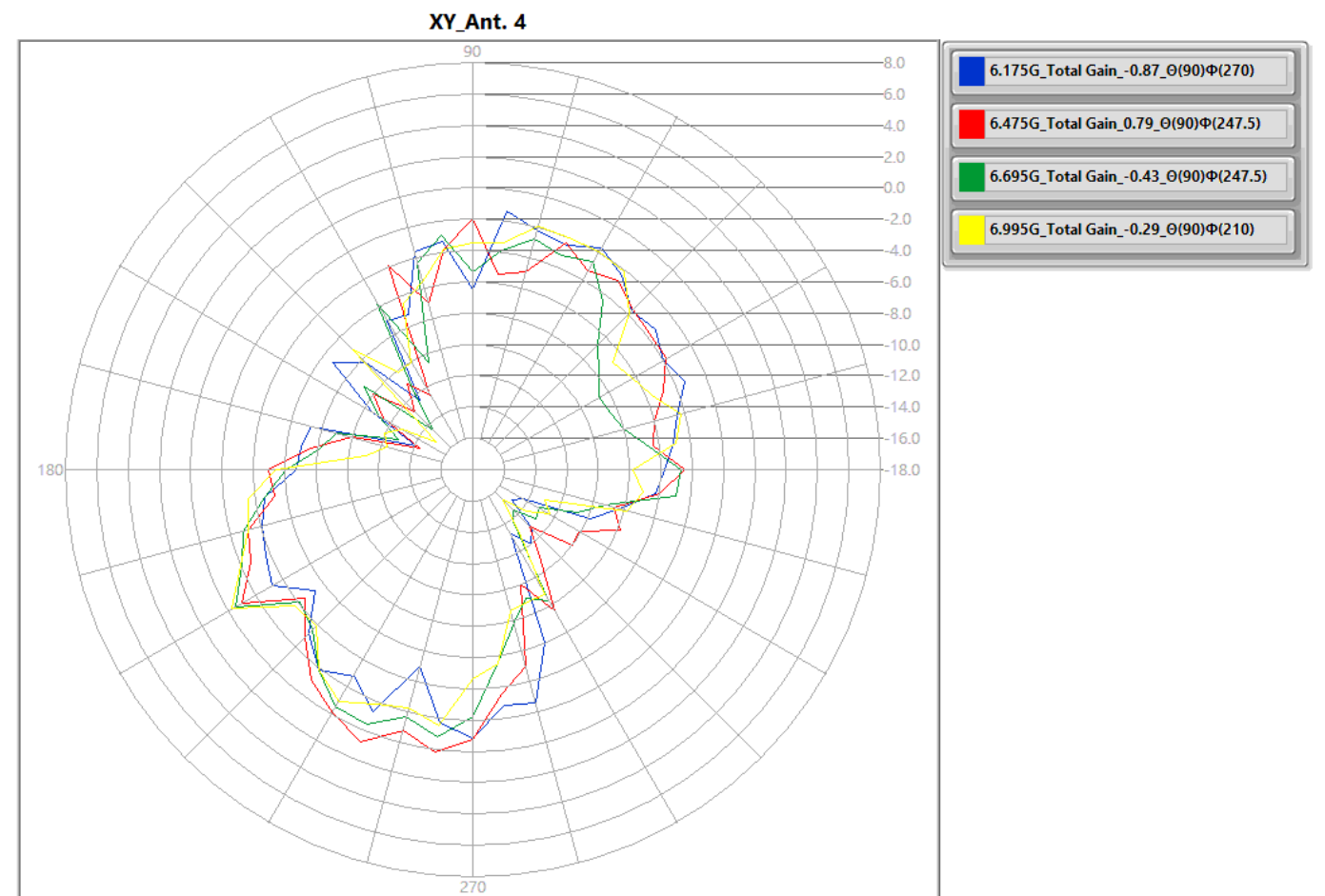
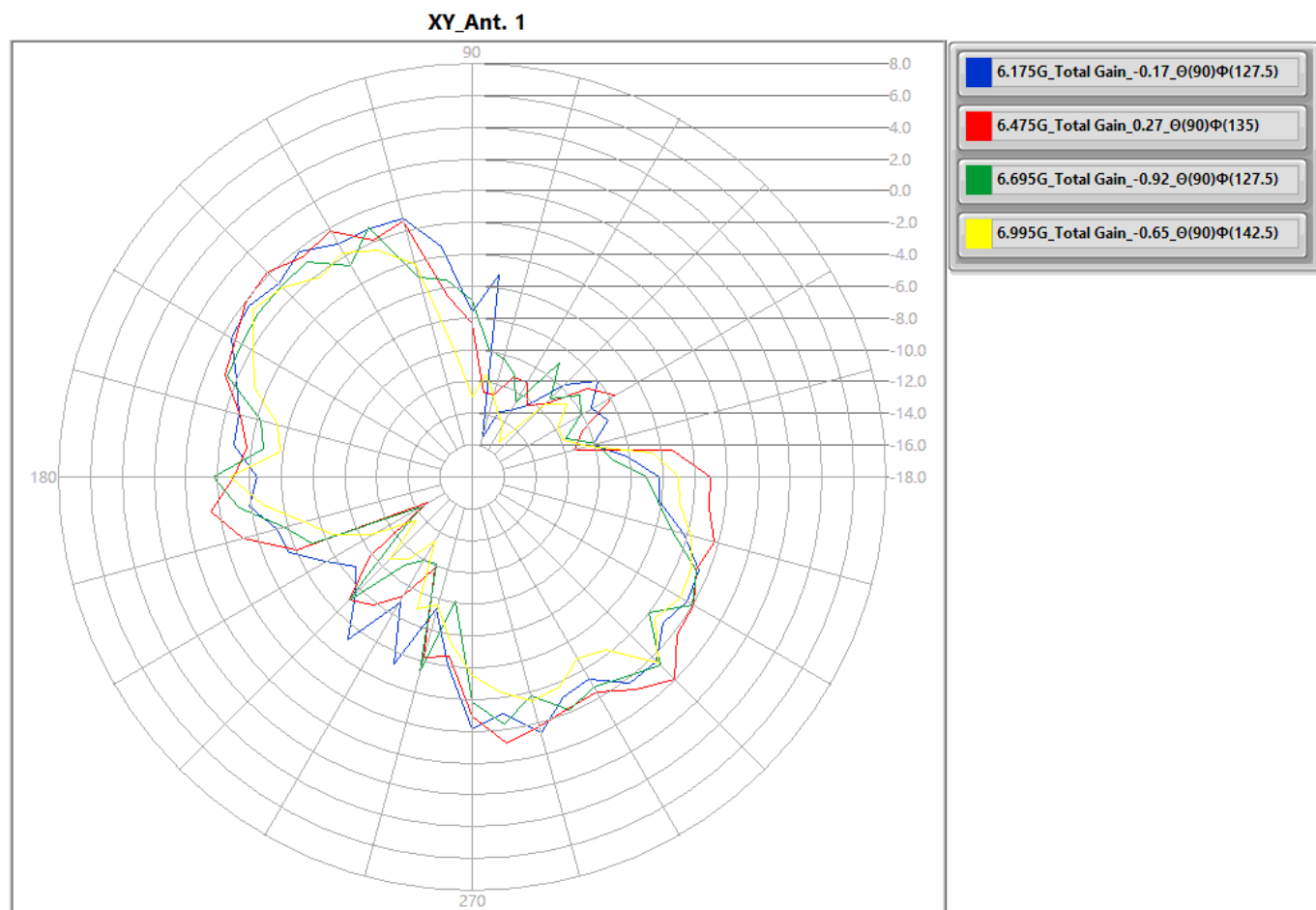


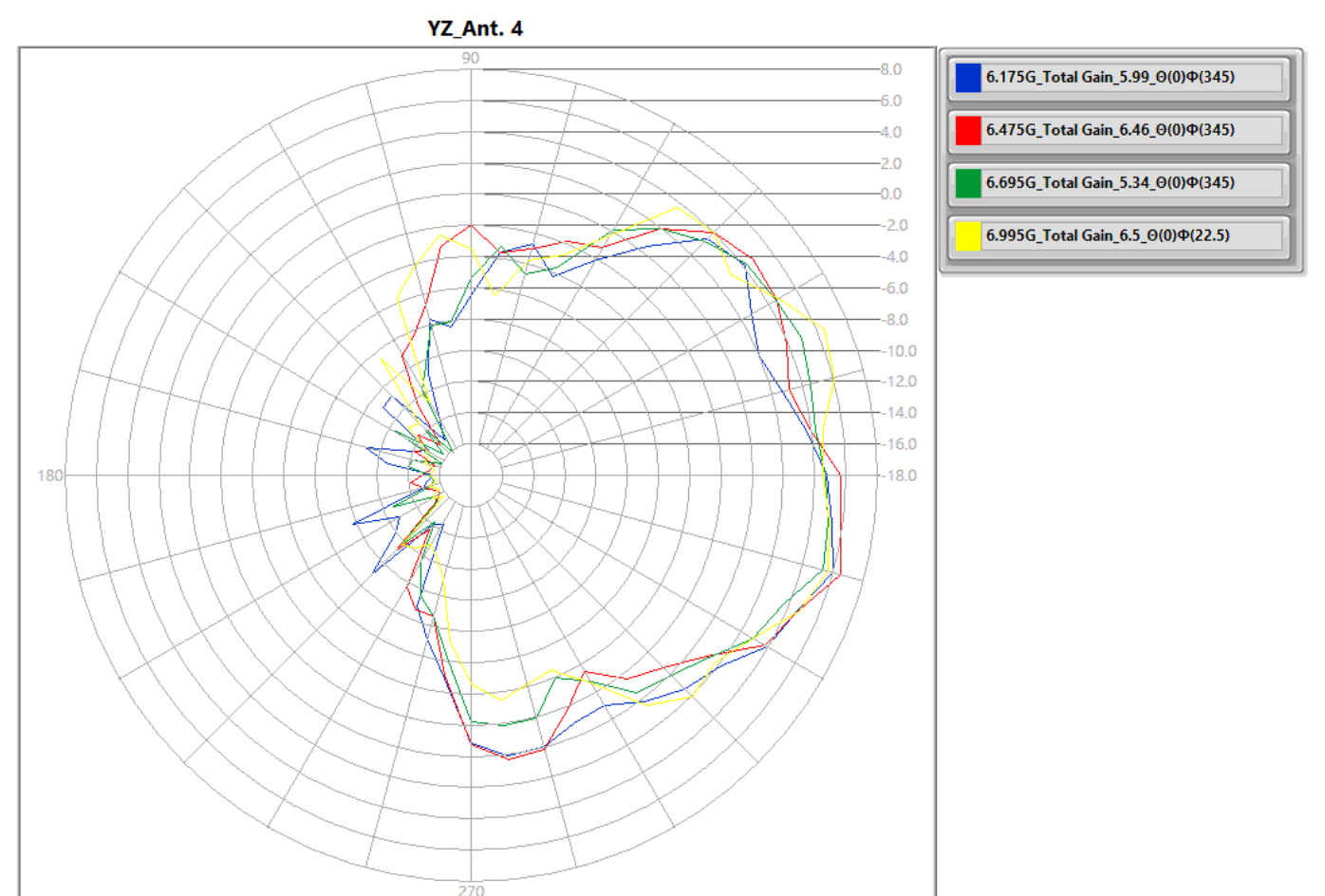
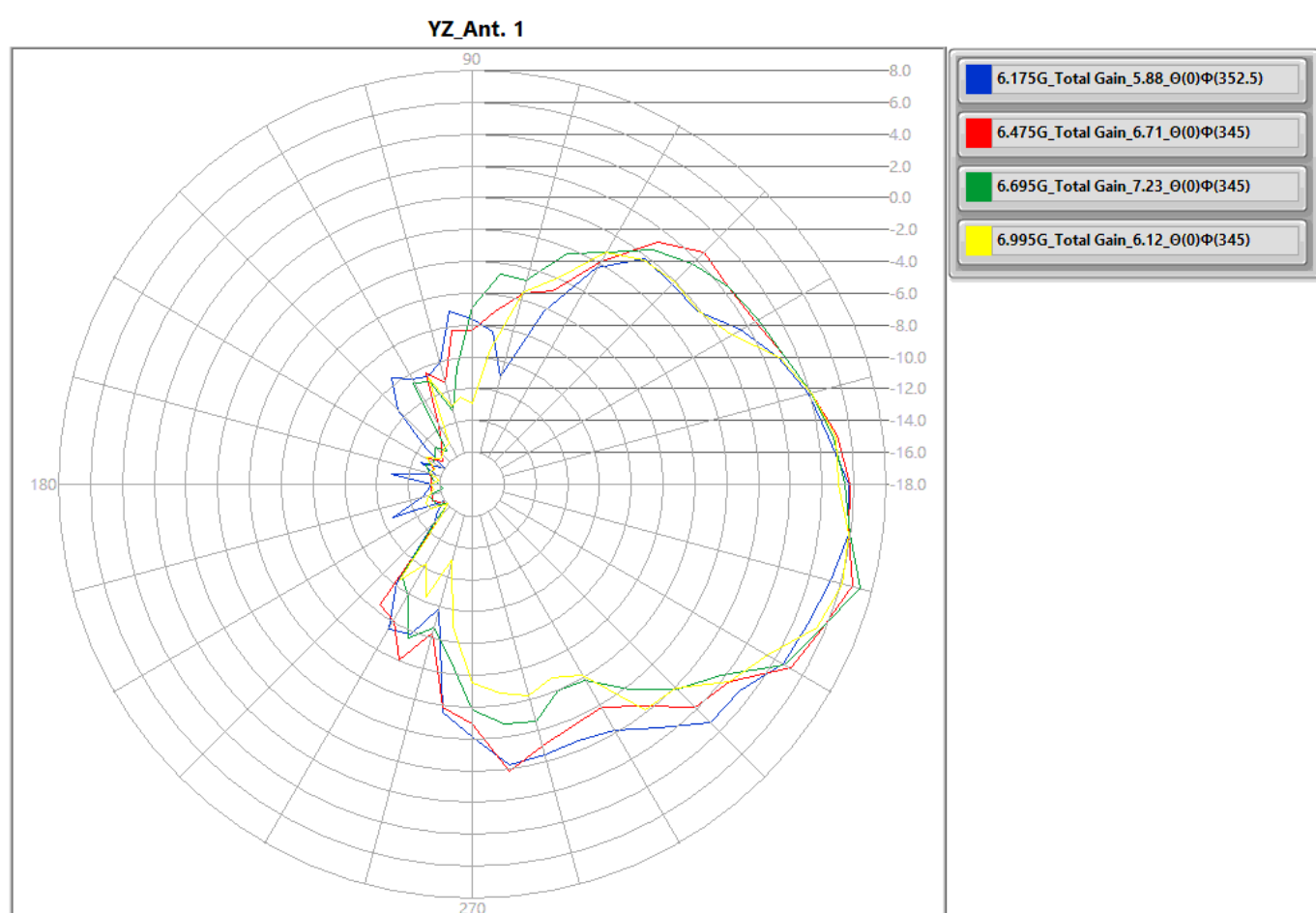
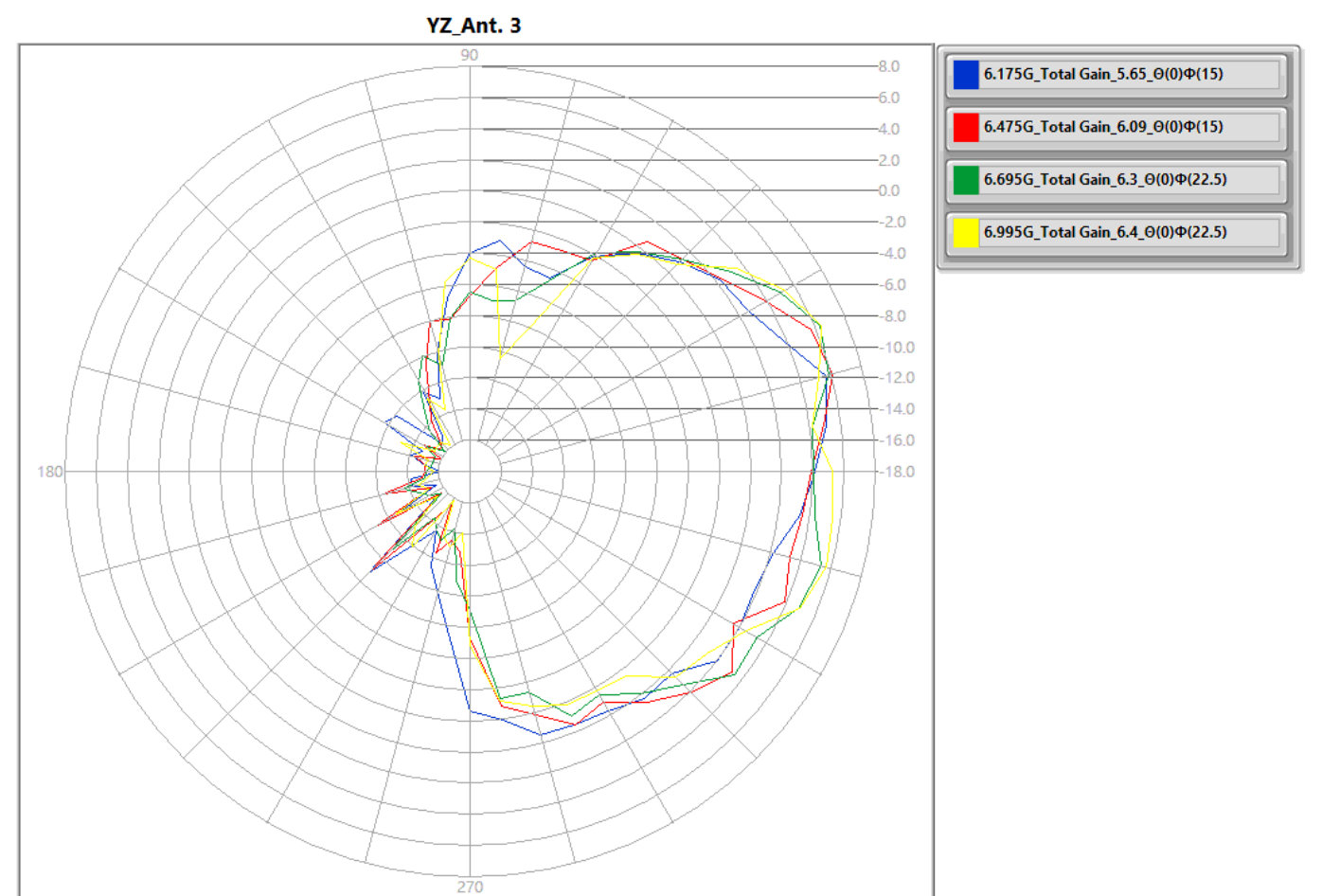
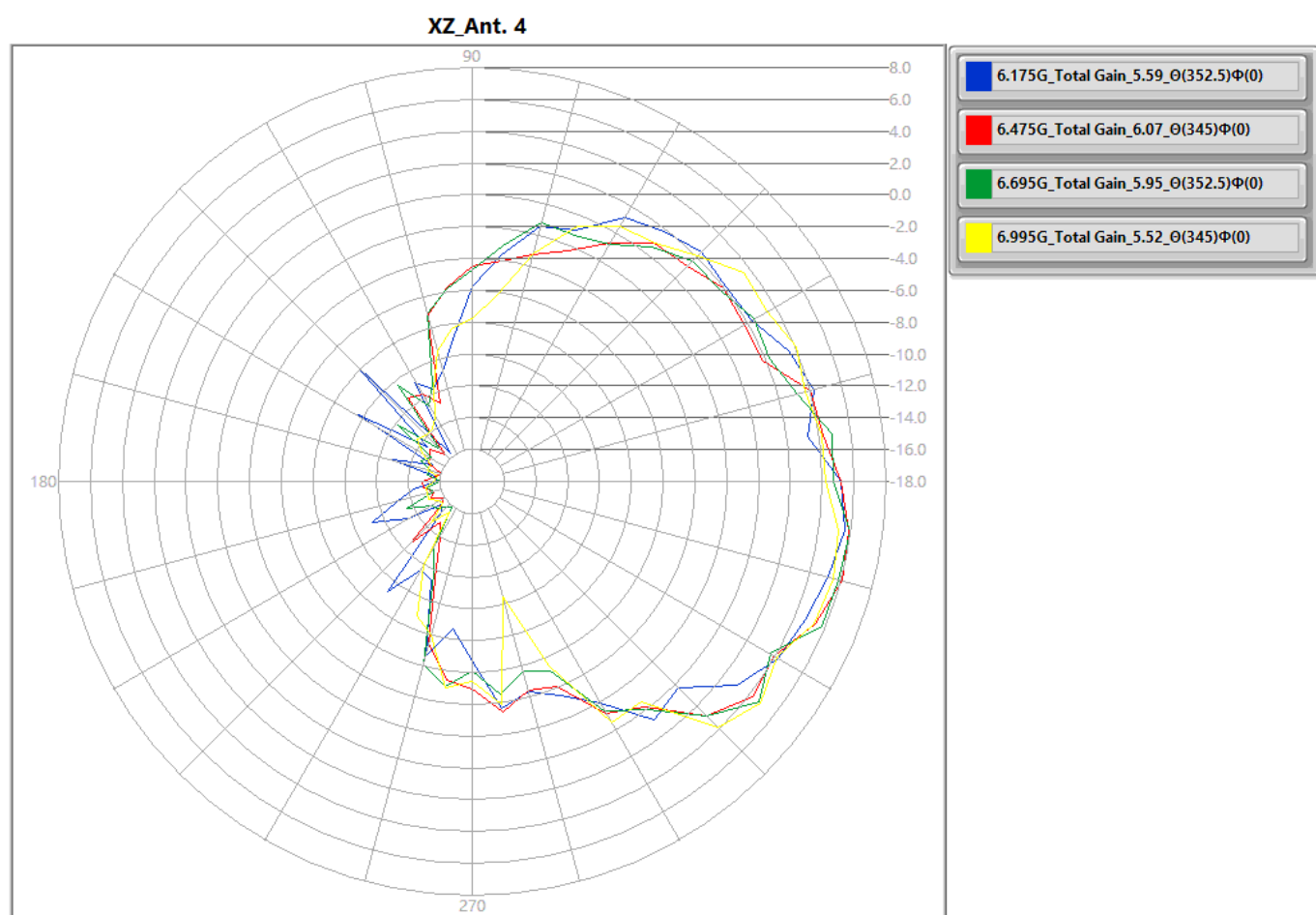
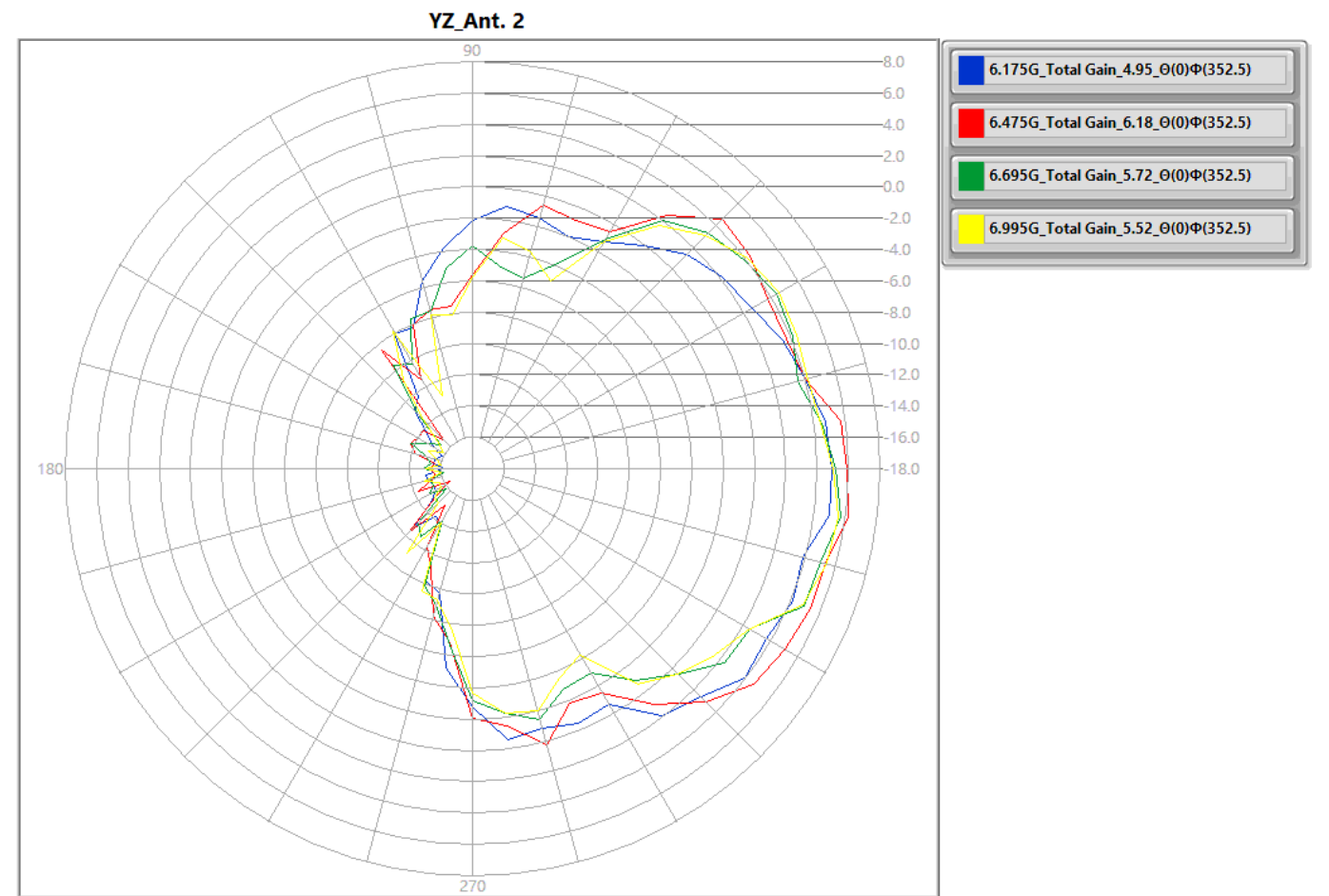
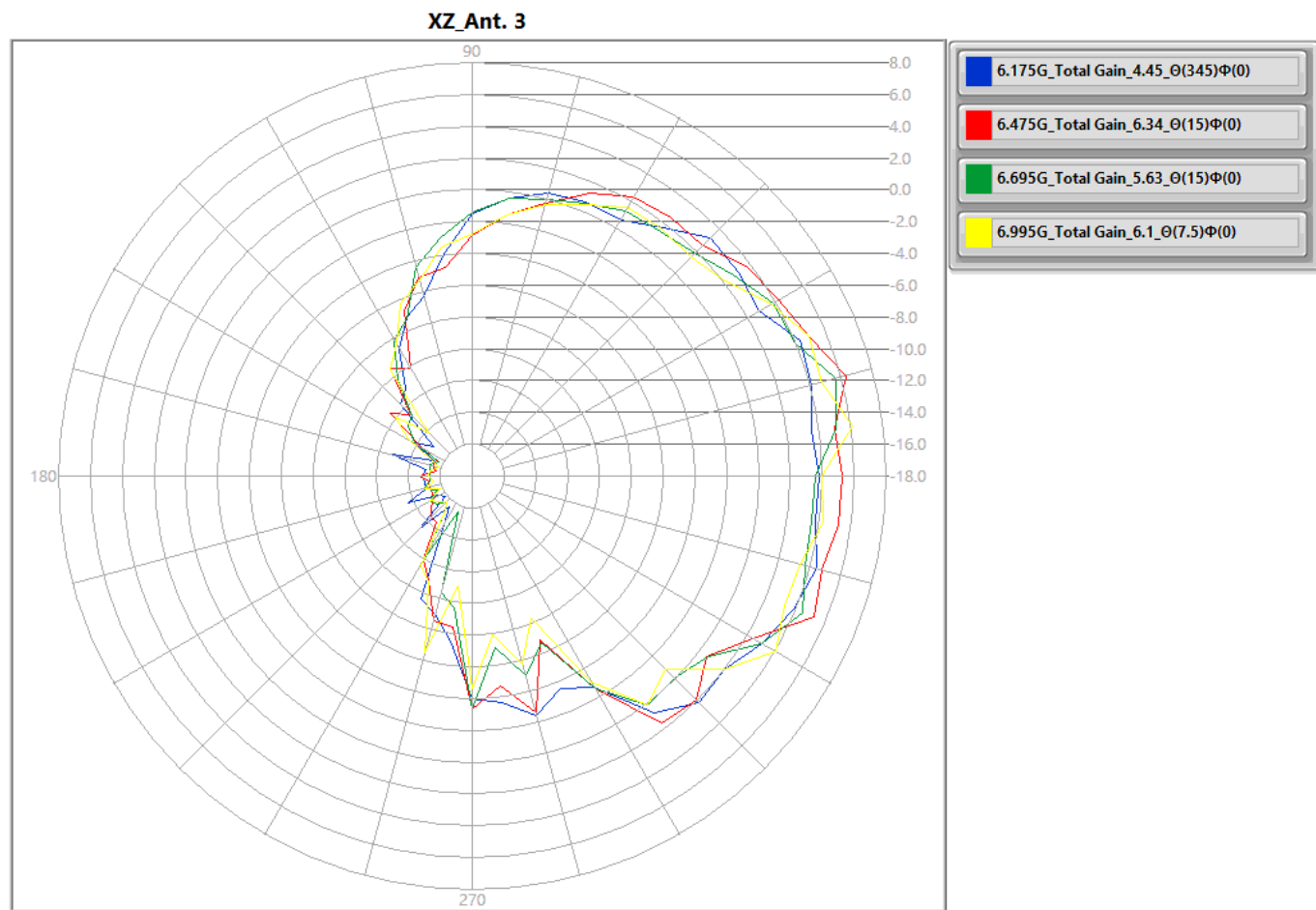
E1(XY plane) – $\Theta(90)\Phi(0-360)$
E2(XZ plane) – $\Theta(0-180)\Phi(0)$ and $\Theta(0-180)\Phi(180)$
E3(YZ plane) – $\Theta(0-180)\Phi(90)$ and $\Theta(0-180)\Phi(270)$





E1(XY plane) – $\Theta(90)\Phi(0-360)$
E2(XZ plane) – $\Theta(0-180)\Phi(0)$ and $\Theta(0-180)\Phi(180)$
E3(YZ plane) – $\Theta(0-180)\Phi(90)$ and $\Theta(0-180)\Phi(270)$







Total Gain Data

Sporton International Inc. Hsinchu Laboratory

E1(XY plane) – $\Theta(90)\Phi(0-360)$
 E2(XZ plane) – $\Theta(0-180)\Phi(0)$ and $\Theta(0-180)\Phi(180)$
 E3(YZ plane) – $\Theta(0-180)\Phi(90)$ and $\Theta(0-180)\Phi(270)$

