ion 2.0 Issue Date: 05 July 2012

Appendix 5. System Check

Prior to the assessment, the system was verified in the flat region of the phantom. 900 MHz, 1900 MHz and 2450 MHz dipoles were used. A forward power of 250 mW was applied to the dipole and the system was verified to a tolerance of $\pm 5\%$ for the 900 MHz, 1900 MHz and 2450 MHz dipoles.

The applicable verification normalised to 1 Watt.

System Check 850/900 Head

Date: 07/06/2012 Validation Dipole and Serial Number: D900V2: SN: 124

validation Dipole and Serial Number: D900V2; SN: 124								
Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
		900 24.0°C	°C 23.0°C	ε _r	41.50	42.97	3.54	5.00
Head	Hood 000			σ	0.97	0.95	-2.45	5.00
Tieau 900	900			1g SAR	11.00	10.68	-2.91	5.00
				10g SAR	7.01	6.92	-1.28	5.00

System Check 850/900 Body

Date: 07/06/2012

Validation Dipole and Serial Number: D900V2; SN: 124

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
	900	23.0°C	20.4°C	ε _r	55.00	54.24	-1.39	5.00
Body				σ	1.05	1.01	-3.95	5.00
				1g SAR	11.10	11.36	2.34	5.00
				10g SAR	7.14	7.36	3.08	5.00

Date: 08/06/2012

Validation Dipole and Serial Number: D900V2; SN: 124

Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body 900		23.0 °C	22.3 °C	ε _r	55.00	53.91	-1.99	5.00
	900			σ	1.05	1.02	-2.81	5.00
				1g SAR	11.10	11.04	-0.54	5.00
				10g SAR	7.14	7.12	-0.28	5.00

Page: 138 of 144 RFI Global Services Ltd.

Version 2.0 Issue Date: 05 July 2012

System Check 1900 Head

Date: 03/06/2012 Validation Dipole and Serial Number: D1900V2; SN: 540								
Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
			23.0°C 23.0°C	ε _r	40.00	38.88	-2.80	5.00
Head	1900 23.0	23 N°C		σ	1.40	1.43	2.25	5.00
Tieau 1900	1900	23.0 C		1g SAR	40.30	39.64	-1.64	5.00
			10g SAR	21.00	20.68	-1.52	5.00	

System Check 1900 Body

Date: 03/06/2012 Validation Dipole and Serial Number: D1900V2; SN: 540								
Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
		1900 23.0°C 21.5°		ε _r	53.30	51.97	-2.50	5.00
Body	1000 22.0		C 21.5°C	σ	1.52	1.56	2.35	5.00
Body 1900	1500			1g SAR	40.70	40.40	-0.74	5.00
				10g SAR	21.60	21.64	0.19	5.00

Page: 139 of 144 RFI Global Services Ltd.

Serial No: RFI-SAR-RP87473JD03A V2.0 Issue Date: 05 July 2012

System Check 2450 Head

Date: 09/06/2012 Validation Dipole and Serial Number: D2450V2; SN: 725 Measured Deviation Limit Frequency Room Liquid Target Simulant **Parameters** Temp (MHz) Temp Value Value (%) (%) 39.20 38.26 -2.41 5.00 ϵ_{r} σ 1.80 1.83 1.78 5.00 23.0 °C Head 2450 23.0 °C 1g SAR 52.90 52.40 -0.95 5.00 10g SAR 24.70 24.08 -2.51 5.00

System Check 2450 Body

Date: 11/06/2012 Validation Dipole and Serial Number: D2450V2; SN: 725								
Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
	Body 2450 24.0 °C		ε _r	52.70	50.55	-4.08	5.00	
Rody		24.0 °C	24.0 °C	σ	1.95	2.01	2.95	5.00
B00y 2430				1g SAR	51.90	52.40	0.96	5.00
				10g SAR	24.10	24.08	-0.08	5.00

Page: 140 of 144 RFI Global Services Ltd.

Issue Date: 05 July 2012

Appendix 6. Simulated Tissues

The body mixture consists of water, Polysorbate 20 and salt. Visual inspection is made to ensure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue.

Ingredient	Frequency
	835/850/900 MHz Head
De-Ionized Water	52.87
Polysorbate 20 (Tween 20)	46.10
Salt	1.03

Ingredient	Frequency
	835/850/900 MHz Body
De-Ionized Water	71.30
Polysorbate 20 (Tween 20)	28.00
Salt	0.70

Ingredient	Frequency
	1800/1900 MHz Head
De-Ionized Water	55.40
Polysorbate 20 (Tween 20)	44.22
Salt	0.38

Ingredient	Frequency
	1800/1900 MHz Body
De-Ionized Water	71.50
Polysorbate 20 (Tween 20)	28.00
Salt	0.50

Ingredient	Frequency
	2450 MHz Head
De-Ionized Water	55.75
Polysorbate 20 (Tween 20)	45.25

Ingredient	Frequency	
	2450 MHz Body	
De-Ionized Water	71.70	
Polysorbate 20 (Tween 20)	28.00	
Salt	0.30	

Page: 141 of 144 RFI Global Services Ltd.

Issue Date: 05 July 2012

Appendix 7. DASY4 System Details

A.7.1. DASY4 SAR Measurement System

RFI Global Services Ltd, SAR measurement facility utilises the Dosimetric Assessment System (DASY™) manufactured by Schmid & Partner Engineering AG (SPEAG™) of Zurich, Switzerland. The DASY4 system is comprised of the robot controller, computer, near-field probe, probe alignment sensor, and the SAM phantom containing brain or muscle equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF). A cell controller system contains the power supply, robot controller; teach pendant (Joystick), and remote control. This is used to drive the robot motors. The Staubli robot is connected to the cell controller to allow software manipulation of the robot. The data acquisition electronics (DAE) performs signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection etc. The DAE is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card. The DAE3 utilises a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching mulitplexer, a fast 16bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe-mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

Page: 142 of 144 RFI Global Services Ltd.

A 7.2 DASVA SAD System Specifications	
A.7.2. DASY4 SAR System Specifications Robot System	
Positioner:	Stäubli Unimation Corp. Robot Model: RX90L
Repeatability:	0.025 mm
No. of Axis:	6
Serial Number:	F00/SD89A1/A/01
Reach:	1185 mm
Payload:	3.5 kg
Control Unit:	CS7
Programming Language:	V+
Robot System	VT
Positioner:	Stäubli Unimation Corp. Robot Model: RX90L
Repeatability:	0.025 mm
No. of Axis:	6
Serial Number:	F01/5J86A1/A/01
Reach:	1185 mm
Payload:	3.5 kg
Control Unit:	CS7
	V+
Programming Language: Data Acquisition Electronic (DAE) System	·
Serial Number:	DAE3 SN:394
Serial Number:	DAE3 SN:432
PC Controller	DALO 011.402
PC:	Dell Precision 340
Operating System:	Windows 2000
Data Card:	DASY4 Measurement Server
Serial Number:	1080
Data Converter	
Features:	Signal Amplifier, multiplexer, A/D converted and control logic.
Software:	DASY4 Software
Connecting Lines:	Optical downlink for data and status info. Optical uplink for commands and clock.
PC Interface Card	
Function:	24 bit (64 MHz) DSP for real time processing Link to DAE3 16 nit A/D converter for surface detection system serial link to robot direct emergency stop output for robot.

Issue Date: 05 July 2012

Page: 143 of 144 RFI Global Services Ltd.

DASY4 SAR System Specifications (Continued)	
E-Field Probe	
Model:	EX3DV4
Serial No:	3814
Construction:	Triangular core
Frequency:	10 MHz to >6 GHz
Linearity:	±0.2 dB (30 MHz to 6 GHz)
Probe Length (mm):	330
Probe Diameter (mm):	12
Tip Length (mm):	20
Tip Diameter (mm):	2.5
Sensor X Offset (mm):	1
Sensor Y Offset (mm):	1
Sensor Z Offset (mm):	1
E-Field Probe	
Model:	ET3DV6
Serial No:	1587
Construction:	Triangular core
Frequency:	10 MHz to 3.0 GHz
Linearity:	±0.2 dB (10 MHz to 3.0 GHz)
Probe Length (mm):	337
Probe Diameter (mm):	10
Tip Length (mm):	10
Tip Diameter (mm):	6.8
Sensor X Offset (mm):	2.7
Sensor Y Offset (mm):	2.7
Sensor Z Offset (mm):	2.7
Phantom	
Phantom:	SAM Phantom
Shell Material:	Fibreglass
Thickness:	2.0 ±0.1 mm

Page: 144 of 144 RFI Global Services Ltd.