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Appendix 5. Validation of System

Prior to the assessment, the system was verified in the flat region of the phantom. A 1900 MHz dipole was used. A forward power of 250 mW was applied to the dipole and the system was verified to a tolerance of $\pm 5\%$ for the 1900 MHz dipole. The applicable verification (normalised to 1 Watt).

verification (normalised to 1 Watt).									
Date: 19/11/2010									
Validation Dipole and Serial Number: D1900V2; SN: 540									
Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)	
		23.0 °C	23.3 °C	ε _r	53.30	51.03	-4.26	5.00	
Body	1900			σ	1.52	1.58	3.88	5.00	
				1g SAR	40.90	42.40	3.67	5.00	
				10g SAR	21.50	21.52	0.09	5.00	
Date: 19/11/2010									
Simulant	Frequency (MHz)	Room Temp	Liquid Temp	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)	
Head	1900	23.0 °C	22.0°C	ε _r	40.00	38.28	-4.30	5.00	
rieau				σ	1.40	1.37	-1.95	5.00	

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Appendix 6. Simulated Tissues

The body mixture consists of water and glycol. Visual inspection is made to ensure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue.

Ingredient	Frequency	
	1800/1900 MHz Head	
De-Ionized Water	55.40	
Polysorbate 20 (Tween 20)	44.22	
Salt	0.38	

Ingredient	Frequency	
	1800/1900 MHz Body	
De-Ionized Water	71.50	
Polysorbate 20 (Tween 20)	28.00	
Salt	0.50	

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Appendix 7. DASY4 System Details

A.7.1. DASY4 SAR Measurement System

RFI Global Services Ltd, SAR measurement facility utilises the Dosimetric Assessment System (DASY™) manufactured by Schmid & Partner Engineering AG (SPEAG™) of Zurich, Switzerland. The DASY4 system is comprised of the robot controller, computer, near-field probe, probe alignment sensor, and the SAM phantom containing brain or muscle equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF). A cell controller system contains the power supply, robot controller; teach pendant (Joystick), and remote control. This is used to drive the robot motors. The Staubli robot is connected to the cell controller to allow software manipulation of the robot. The data acquisition electronics (DAE) performs signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection etc. The DAE is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card. The DAE3 utilises a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe-mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

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A.7.2. DASY4 SAR System Specifications Robot System Positioner: Stäubli Unimation Corp. Robot Model: RX90L Repeatability: 0.025 mm No. of Axis: 6 Serial Number: F00/SD89A1/A/01 Reach: 1185 mm Payload: 3.5 kg Control Unit: CS7 Programming Language: V+ Data Acquisition Electronic (DAE) System					
Positioner: Repeatability: No. of Axis: Serial Number: Reach: Payload: Control Unit: Programming Language: Data Acquisition Electronic (DAE) System Stäubli Unimation Corp. Robot Model: RX90L 0.025 mm F00/SD89A1/A/01 F00/SD89A1/A/01 CS7 FV0/SD89A1/A/01 CS7 V+					
Repeatability: No. of Axis: 6 Serial Number: F00/SD89A1/A/01 Reach: 1185 mm Payload: Control Unit: CS7 Programming Language: V+ Data Acquisition Electronic (DAE) System					
No. of Axis: Serial Number: F00/SD89A1/A/01 Reach: 1185 mm Payload: Control Unit: CS7 Programming Language: V+ Data Acquisition Electronic (DAE) System	Stäubli Unimation Corp. Robot Model: RX90L				
Serial Number: F00/SD89A1/A/01 Reach: 1185 mm Payload: 3.5 kg Control Unit: CS7 Programming Language: V+ Data Acquisition Electronic (DAE) System					
Reach: 1185 mm Payload: 3.5 kg Control Unit: CS7 Programming Language: V+ Data Acquisition Electronic (DAE) System					
Payload: 3.5 kg Control Unit: CS7 Programming Language: V+ Data Acquisition Electronic (DAE) System					
Control Unit: CS7 Programming Language: V+ Data Acquisition Electronic (DAE) System	1185 mm				
Programming Language: V+ Data Acquisition Electronic (DAE) System					
Data Acquisition Electronic (DAE) System	CS7				
	Data Acquisition Electronic (DAE) System				
Serial Number: DAE3 SN:394					
PC Controller					
PC: Dell Precision 340					
Operating System: Windows 2000					
Data Card: DASY4 Measurement Server	DASY4 Measurement Server				
Serial Number: 1080					
Data Converter					
Features: Signal Amplifier, multiplexer, A/D converted and clogic.	ontrol				
Software: DASY4 Software					
Connecting Lines: Optical downlink for data and status info. Optical uplink for commands and clock.					
PC Interface Card					
Function: 24 bit (64 MHz) DSP for real time processing Link DAE3 16 nit A/D converter for surface detection s serial link to robot direct emergency stop output for robot.	ystem				

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DASY4 SAR System Specifications (Continued)				
E-Field Probe				
Model:	EX3DV3			
Serial No:	3508			
Construction:	Triangular core			
Frequency:	10 MHz to >6 GHz			
Linearity:	±0.2 dB (30 MHz to 6 GHz)			
Probe Length (mm):	330			
Probe Diameter (mm):	12			
Tip Length (mm):	20			
Tip Diameter (mm):	2.5			
Sensor X Offset (mm):	1			
Sensor Y Offset (mm):	1			
Sensor Z Offset (mm):	1			
Phantom				
Phantom:	SAM Phantom			
Shell Material:	Fibreglass			
Thickness:	2.0 ±0.1 mm			

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