

Test of: Datalogic Mobile SRL
Kyman Module

To: OET Bulletin 65 Supplement C: (2001-01)

Appendix 4. Photographs

This appendix contains the following photographs:

Photo Reference Number	Title
PHT/49622JD01/001	Test configuration for the measurement of Specific Absorption Rate (SAR)
PHT/49622JD01/002	Front Of EUT Facing Phantom With 0mm Separation
PHT/49622JD01/003	Rear Of EUT Facing Phantom With 0mm Separation
PHT/49622JD01/004	Rear Of EUT Facing Phantom With Belt Clip 0mm Separation
PHT/49622JD01/005	Front View Of EUT
PHT/49622JD01/006	Rear View Of EUT
PHT/49622JD01/007	Internal View Of EUT
PHT/49622JD01/008	Battery View Of EUT
PHT/49622JD01/009	EUT Belt Clip
PHT/49622JD01/010	EUT Elastic Strap and Stylus
PHT/49622JD01/011	Fluid Level of 2450MHz Body Fluid

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PHT/49622JD01/001: Test configuration for the measurement of Specific Absorption Rate (SAR)



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PHT/49622JD01/002: Front Of EUT Facing Phantom With 0mm Separation



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PHT/49622JD01/003: Rear Of EUT Facing Phantom With 0mm Separation



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PHT/49622JD01/004: Rear Of EUT Facing Phantom With Belt Clip 0mm Separation



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PHT/49622JD01/005: Front View Of EUT



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PHT/49622JD01/006: Rear View Of EUT



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PHT/49622JD01/007: Internal View Of EUT



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PHT/49622JD01/008: Battery View Of EUT



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PHT/49622JD01/009: EUT Belt Clip



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PHT/49622JD01/010: EUT Elastic Strap and Stylus



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PHT/49622JD01/011: Fluid Level of 2450MHz Body Fluid



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Appendix 5. Validation of System

Prior to the assessment, the system was verified in the flat region of the phantom.

A 2450 MHz dipole was used. A forward power of 250 mW was applied to the dipole and the system was verified to a tolerance of $\pm 5\%$ for the 2450 MHz dipole. The applicable verification (normalised to 1 Watt).

Date:10/12/2007

Validation Dipole and Serial Number:D2450V2:SN:725

Simulant	Frequency (MHz)	Room Temperature	Liquid Temperature	Parameters	Target Value	Measured Value	Deviation (%)	Limit (%)
Body	2450	23.0 °C	23.0 °C	ϵ_r	52.70	51.64	-0.02	5.00
				σ	1.95	1.91	-0.02	5.00
				1g SAR	53.30	53.60	0.56	5.00
				10g SAR	24.50	23.44	-4.33	5.00

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Appendix 6. Simulated Tissues

The body mixture consists of water and glycol. Visual inspection is made to ensure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the tissue.

Ingredient	Frequency
	2450 MHz Body
De-Ionised Water	68.64
Diglycol Butyl Ether (DGBE)	31.37

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Appendix 7. DASY4 System Details

A.7.1. DASY4 SAR Measurement System

RFI Global Services Ltd, SAR measurement facility utilises the Dosimetric Assessment System (DASY™) manufactured by Schmid & Partner Engineering AG (SPEAG™) of Zurich, Switzerland. The DASY4 system is comprised of the robot controller, computer, near-field probe, probe alignment sensor, and the SAM phantom containing brain or muscle equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF). A cell controller system contains the power supply, robot controller; teach pendant (Joystick), and remote control. This is used to drive the robot motors. The Staubli robot is connected to the cell controller to allow software manipulation of the robot. The data acquisition electronics (DAE) performs signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection etc. The DAE is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card. The DAE3 utilises a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16-bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe-mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.

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A.7.2. DASY4 SAR System Specifications

Robot System

Positioner:	Stäubli Unimation Corp. Robot Model: RX90L
Repeatability:	0.025 mm
No. of Axis:	6
Serial Number:	F00/SD89A1/A/01
Reach:	1185 mm
Payload:	3.5 kg
Control Unit:	CS7
Programming Language:	V+

Data Acquisition Electronic (DAE) System

Serial Number:	DAE3 SN:394
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Cell Controller

PC:	Dell Precision 340
Operating System:	Windows 2000
Data Card:	DASY4 Measurement Server
Serial Number:	1080

Data Converter

Features:	Signal Amplifier, multiplexer, A/D converted and control logic.
Software:	DASY4 Software
Connecting Lines:	Optical downlink for data and status info. Optical uplink for commands and clock.

PC Interface Card

Function:	24 bit (64 MHz) DSP for real time processing Link to DAE3 16 nit A/D converter for surface detection system serial link to robot direct emergency stop output for robot.
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DASY4 SAR System Specifications (Continued)

E-Field Probe

Model:	EX3DV3
Serial No:	3508
Construction:	Triangular core
Frequency:	10 MHz to >6 GHz
Linearity:	± 0.2 dB (30 MHz to 6 GHz)
Probe Length (mm):	330
Probe Diameter (mm):	12
Tip Length (mm):	20
Tip Diameter (mm):	2.5
Sensor X Offset (mm):	1
Sensor Y Offset (mm):	1
Sensor Z Offset (mm):	1

Phantom

Phantom:	SAM Phantom
Shell Material:	Fibreglass
Thickness:	2.0 \pm 0.1 mm
