CETECOM ICT Services GmbH

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Accredited testing laboratory

DAR registration number: DAT-P-176/94-D1

Federal Motor Transport Authority (KBA) DAR registration number: KBA-P 00070-97

Test report no. : 2-4189-01-08/05

Type identification: GIGASET S45 and E45

Test specification : IEEE P1528/D1.2 FCC-ID : TVU-S45-E45 Certification-No.IC : 267U-S45E45

As of 2006-01-30 Page 1 of 86

CETECOM ICT Services GmbH

Test report no.: 2-4189-01-08/05



Table of Contents

| General Information | 3 |
|--|----|
| 1.1 Notes | |
| 1.1.1 Statement of Compliance | |
| 1.2 Testing laboratory | |
| 1.3 Details of applicant | |
| 1.4 Application details | |
| 1.5 Test item | |
| 1.6 Test specification(s) | |
| 1.6.1 RF exposure limits | |
| 2 Technical test | |
| 2.1 Summary of test results | |
| 2.2 Test environment | |
| 2.3 Measurement and test set-up2.4 Measurement system | |
| 2.4.1 System Description | |
| 2.4.1 System Description 2.4.2 Test environment | |
| 2.4.3 Probe description | |
| 2.4.4 Phantom description | |
| 2.4.5 Device holder description | |
| 2.4.6 Scanning procedure | |
| 2.4.7 Spatial Peak SAR Evaluation | |
| 2.4.8 Data Storage and Evaluation | |
| 2.4.9 Test equipment utilized | |
| 2.4.10 Tissue simulating liquids: dielectric properties | |
| 2.4.11 Tissue simulating liquids: parameters | |
| 2.4.12 Measurement uncertainty evaluation for SAR test | |
| 2.4.13 Measurement uncertainty evaluation for system validation | |
| 2.4.14 System validation | |
| 2.4.15 Validation procedure | |
| 2.5 Test results (Head and Body SAR) | |
| 2.5.1 General description of test procedures | |
| 2.6 Test results (conducted power measurement) | |
| | |
| | |
| Annex 1 System performance verification S45 | 24 |
| Annex 2 Measurement results (printout from DASY TM) S45 | |
| Annex 2.1 Z-axis scans | |
| Annex 3 System performance verification E45 | |
| Annex 4 Measurement results (printout from DASY TM) E45 | |
| Annex 4.1 Z-axis scans | |
| Annex 5 Photo documentation | |
| Annex 6 RF Technical Brief Cover Sheet acc. to RSS-102 | |
| Annex 6.1 Declaration of RF Exposure Compliance | |
| Annex 7 Calibration parameters | 86 |



1 General Information

1.1 Notes

The test results of this test report relate exclusively to the test item specified in 1.5. The CETECOM ICT Services GmbH does not assume responsibility for any conclusions and generalisations drawn from the test results with regard to other specimens or samples of the type of the equipment represented by the test item. The test report may only be reproduced or published in full. Reproduction or publication of extracts from the report requires the prior written approval of the CETECOM ICT Services GmbH.

1.1.1 Statement of Compliance

The SAR values found for the GIGASET S45 and E45 DECT UPCS handset are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1 g tissue according to the FCC rule §2.1093, the ANSI/IEEE C 95.1:1999, the NCRP Report Number 86 for uncontrolled environment, according to the Health Canada's Safety Code 6 and the Industry Canada Radio Standards Specification RSS-102 for General Population/Uncontrolled exposure.

For body worn operation, this phone has been tested and meets FCC RF exposure guidelines when used with any accessory that contains no metal. Use of other accessories may not ensure compliance with FCC RF exposure guidelines.

The measurement together with the test system set-up is described in chapter 2.3 of this test report. A detailed description of the equipment under test can be found in chapter 1.5.

| | | • | |
|---|------|-----------|--|
| | OCT | engineer: | |
| • | C.51 | envincei. | |
| | | | |

2006-01-30 Oleksandr Hnatovskiy

Date Name Signature

Technical responsibility for area of testing:

2006-01-30 Thomas Vogler Name Signature

As of 2006-01-30 Page 3 of 86

CETECOM ICT Services GmbH

Test report no.: 2-4189-01-08/05



1.2 Testing laboratory

CETECOM ICT Services GmbH Untertuerkheimer Straße 6-10, 66117 Saarbruecken

Germany

Telephone: + 49 681 598 - 0 Fax: + 49 681 598 - 8475

e-mail: <u>info@ict.cetecom.de</u>
Internet: <u>http://www.cetecom-ict.de</u>

State of accreditation: The Test laboratory (area of testing) is accredited according to DIN EN

ISO/IEC 17025. DAR registration number: DAT-P-176/94-D1

Test location, if different from CETECOM ICT Services GmbH

Name: --Street: --Town: --Country: --Phone: --Fax: ---

1.3 Details of applicant

Name: Siemens Home and Office Communication

Devices GmbH & Co.KG

Street: Frankenstr. 2
Town: 46395 Bocholt
Country: Germany

Contact: Uwe Alt

Telephone: +49 (0) 2871 91-28 57

1.4 Application details

Date of receipt of application: 2006-01-13
Date of receipt of test item: 2006-01-27
Start/Date of test: 2006-01-31
End of test: 2006-02-03

Person(s) present during the test: Mr. Jürgen Voigt

As of 2006-01-30 Page 4 of 86

CETECOM ICT Services GmbH

Test report no.: 2-4189-01-08/05



1.5 Test item

Description of the test item: DECT UPCS handset

Type identification: GIGASET S45 and E45

FCC-ID: TVU-S45-E45 Certification No. IC 267U-S45E45

Serial number: N/A

Manufacturer:

Name: Siemens Home and Office Communication

Street: Frankenstr. 2
Town: 46395 Bocholt

Country: Germany

| additional information on the DUT: | |
|------------------------------------|---|
| daviaa tyma : | portable device |
| device type : | |
| exposure category: | uncontrolled environment / general population |
| test device production information | identical prototype |
| device operating configurations : | |
| operating mode(s) | UPCS |
| modulation | TDMA |
| no. of timeslots in uplink: | 1 of 24 |
| operating frequency range(s) | UPCS 1900 |
| | 1921.5 MHz ~ 1928.5 MHz (channels 1 to 5) |
| peak output power (conducted S45): | 100 mW (20.0 dBm) |
| peak output power (conducted E45): | 100 mW (20.0 dBm) |
| test channel (mid): | 3 |
| hardware version: | N/A |
| software version: | N/A |
| antenna type: | Integrated antenna |
| accessories / | Mono headset |
| body-worn configurations: | |
| battery options (S45): | 1.2V×2 NiMH batteries AAA |
| battery options (E45): | 2.4V 360mAh battery |

As of 2006-01-30 Page 5 of 86



1.6 Test specification(s)

Supplement C (Edition 01-01) to OET Bulletin 65 (Edition 97-01)

IEEE P1528/D1.2 (April 21, 2003)

RSS-102: Radio Frequency Exposure Compliance of Radiocommunication Apparatus (All Frequency Bands (Issue 2 of November 2005)

Canada's Safety Code 6: Limits of Human Exposure to Radiofrequency Electromagnetic Fields in the Frequency Range from 3 kHz to 300 GHz (99-EHD-237)

IEEE Std C95.3 – 1991, IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave.

IEEE Std C95.1 – 1999, IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz – 300 GHz.

1.6.1 RF exposure limits

| Human Exposure | Uncontrolled Environment General Population | Controlled Environment Occupational |
|--------------------------|--|-------------------------------------|
| Spatial Peak SAR* | General Topulation | Occupational |
| (Brain) | 1.60 mW/g | 8.00 mW/g |
| Spatial Average SAR** | 0.08 mW/g | 0.40 mW/g |
| (Whole Body) | 0.00 m W/g | 0.10 m W/g |
| Spatial Peak SAR*** | 4.00 mW/g | 20.00 mW/g |
| (Hands/Feet/Ankle/Wrist) | 4.00 m w/g | 20.00 III W/g |

Table 1: RF exposure limits

The limit applied in this test report is shown in **bold** letters

Notes:

- * The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time
- ** The Spatial Average value of the SAR averaged over the whole body.
- *** The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

As of 2006-01-30 Page 6 of 86



2 Technical test

2.1 Summary of test results

| No deviations from the technical specification(s) were ascertained in the course of the tests performed. | |
|--|--|
| The deviations as specified in 2.5 were ascertained in the course of the tests performed. | |

2.2 Test environment

General Environment conditions in the test area are as follows:

Ambient temperature: $20^{\circ}\text{C} - 24^{\circ}\text{C}$ Tissue simulating liquid: $20^{\circ}\text{C} - 24^{\circ}\text{C}$ Humidity: 40% - 50%

Exact temperature values for each test are shown in the table(s) under 2.5. and/or on the measurement plots.

2.3 Measurement and test set-up

The measurement system is described in chapter 2.4.

The test setup for the system validation can be found in chapter 2.4.14.

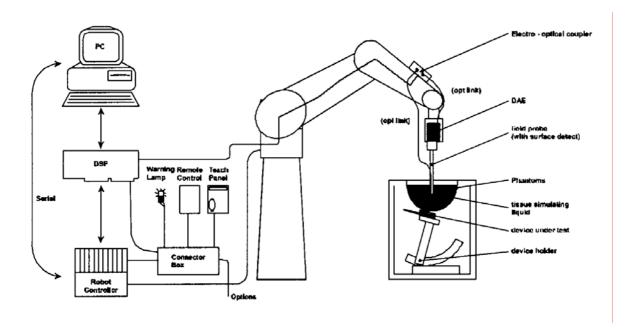
A description of positioning and test signal control can be found in chapter 2.5 together with the test results.

As of 2006-01-30 Page 7 of 86



2.4 Measurement system

2.4.1 System Description



The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- A unit to operate the optical surface detector which is connected to the EOC.
- The <u>Electro-Optical Coupler (EOC)</u> performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY4 measurement server.
- The DASY4 measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows 2000
- DASY4 software and SEMCAD data evaluation software.
- Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.
- The generic twin phantom enabling the testing of left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- System validation dipoles allowing to validate the proper functioning of the system.

As of 2006-01-30 Page 8 of 86



2.4.2 Test environment

The DASY4 measurement system is placed at the head end of a room with dimensions:

 $5 \times 2.5 \times 3 \text{ m}^3$, the SAM phantom is placed in a distance of 75 cm from the side walls and 1.1m from the rear wall. Above the test system a 1.5 x 1.5 m² array of pyramid absorbers is installed to reduce reflections from the ceiling.

Picture 1 of the photo documentation shows a complete view of the test environment.

The system allows the measurement of SAR values larger than 0.005 mW/g.

2.4.3 Probe description

Isotropic E-Field Probe ET3DV6 for Dosimetric Measurements

| Technical data according to manufacturer information | | | | | |
|--|--|--|--|--|--|
| Construction | Symmetrical design with triangular core | | | | |
| | Built-in optical fiber for surface detection system | | | | |
| | Built-in shielding against static charges | | | | |
| | PEEK enclosure material (resistant to organic | | | | |
| | solvents, e.g., glycolether) | | | | |
| Calibration | In air from 10 MHz to 2.5 GHz | | | | |
| | In head tissue simulating liquid (HSL) at 900 (800- | | | | |
| | 1000) MHz and 1.8 GHz (1700-1910 MHz) | | | | |
| | (accuracy \pm 9.5%; k=2) Calibration for other liquids | | | | |
| | and frequencies upon request | | | | |
| Frequency | 10 MHz to 3 GHz (dosimetry); Linearity: ± 0.2 dB | | | | |
| | (30 MHz to 3 GHz) | | | | |
| Directivity | \pm 0.2 dB in HSL (rotation around probe axis) | | | | |
| | \pm 0.4 dB in HSL (rotation normal to probe axis) | | | | |
| Dynamic range | 5 μ W/g to > 100 mW/g; Linearity: \pm 0.2 dB | | | | |
| Optical Surface Detection | \pm 0.2 mm repeatability in air and clear liquids over | | | | |
| | diffuse reflecting surfaces (ET3DV6 only) | | | | |
| Dimensions | Overall length: 330 mm | | | | |
| | Tip length: 16 mm | | | | |
| | Body diameter: 12 mm | | | | |
| | Tip diameter: 6.8 mm | | | | |
| | Distance from probe tip to dipole centers: 2.7 mm | | | | |
| Application | General dosimetry up to 3 GHz | | | | |
| | Compliance tests of mobile phones | | | | |
| | Fast automatic scanning in arbitrary phantoms | | | | |
| | (ET3DV6) | | | | |

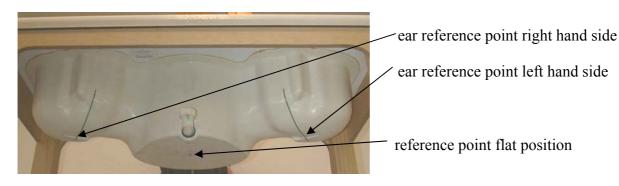
As of 2006-01-30 Page 9 of 86



2.4.4 Phantom description

The used SAM Phantom meets the requirements specified in Edition 01-01 of Supplement C to OET Bulletin 65 for Specific Absorption Rate (SAR) measurements.

The phantom consists of a fibreglass shell integrated in a wooden table. It allows left-hand and right-hand head as well as body-worn measurements with a maximum liquid depth of 18 mm in head position and 22 mm in planar position (body measurements). The thickness of the Phantom shell is 2 mm +/- 0.1 mm.



2.4.5 Device holder description

The DASY4 device holder has two scales for device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The plane between the ear openings and the mouth tip has a rotation angle of 65°. The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. This device holder is used for standard mobile phones or PDA's only. If necessary an additional support of polystyrene material is used.



Larger DUT's (e.g. notebooks) cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values.

Therefore those devices are normally only tested at the flat part of the SAM.

As of 2006-01-30 Page 10 of 86



2.4.6 Scanning procedure

The DASY4 installation includes predefined files with recommended procedures for measurements and validation. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.

- The "reference" and "drift" measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT's output power and should vary max. +/- 5 %.
- The "surface check" measurement tests the optical surface detection system of the DASY4 system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above \pm 0.1mm). To prevent wrong results tests are only executed when the liquid is free of air bubbles. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within \pm 30°.)
- The "area scan" measures the SAR above the DUT or verification dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The robot performs a stepped movement along one grid axis while the local electrical field strenth is measured by the probe. The probe is touching the surface of the SAM during acquisition of measurement values. The standard scan uses large grid spacing for faster measurement. Standard grid spacing for head measurements is 15 mm in x- and y- dimension. If a finer resolution is needed, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result. For special applications where the standard scan method does not find the peak SAR within the grid, e.g. mobile phones with flip cover, the grid can be adapted in orientation. Results of this coarse scan are shown in annex 2.
- A "7x7x7 zoom scan" measures the field in a volume around the 2D peak SAR value acquired in the previous "coarse" scan. This is a fine 7x7 grid where the robot additionally moves the probe in 7 steps along the z-axis away from the bottom of the Phantom. Grid spacing for the cube measurement is 5 mm in x and y-direction and 5 mm in z-direction. DASY4 is also able to perform repeated zoom scans if more than 1 peak is found during area scan. In this document, the evaluated peak 1g and 10g averaged SAR values are shown in the 2D-graphics in annex 2. Test results relevant for the specified standard (see chapter 1.6.) are shown in table form in chapter 2.5.
- A Z-axis scan measures the total SAR value at the x-and y-position of the maximum SAR value found during the cube 7x7x7 scan. The probe is moved away in z-direction from the bottom of the SAM phantom in 2mm steps. This measurement shows the continuity of the liquid and can depending in the field strength also show the liquid depth. A z-axis scan of the measurement with maximum SAR value is shown in annex 2.

As of 2006-01-30 Page 11 of 86



2.4.7 Spatial Peak SAR Evaluation

The spatial peak SAR - value for 1 and 10 g is evaluated after the Cube measurements have been done. The basis of the evaluation are the SAR values measured at the points of the fine cube grid consisting of 7 x 7 x 7 points. The algorithm that finds the maximal averaged volume is separated into three different stages.

- The data between the dipole center of the probe and the surface of the phantom are extrapolated. This data cannot be measured since the center of the dipole is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is about 1 mm (see probe calibration sheet). The extrapolated data from a cube measurement can be visualized by selecting 'Graph Evaluated'.
- The maximum interpolated value is searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10 g) are computed using the 3d-spline interpolation algorithm. If the volume cannot be evaluated (i.e., if a part of the grid was cut off by the boundary of the measurement area) the evaluation will be started on the corners of the bottom plane of the cube.
- All neighboring volumes are evaluated until no neighboring volume with a higher average value is found.

Extrapolation

The extrapolation is based on a least square algorithm [W. Gander, Computermathematik, p.168-180]. Through the points in the first 3 cm along the z-axis, polynomials of order four are calculated. These polynomials are then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from each other.

Interpolation

The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a knot"-condition [W. Gander, Computermathematik, p.141-150] (x, y and z -direction) [Numerical Recipes in C, Second Edition, p.123ff].

Volume Averaging

At First the size of the cube is calculated. Then the volume is integrated with the trapezoidal algorithm. $8000 \text{ points } (20 \times 20 \times 20)$ are interpolated to calculate the average.

Advanced Extrapolation

DASY4 uses the advanced extrapolation option which is able to compansate boundary effects on E-field probes.

As of 2006-01-30 Page 12 of 86



2.4.8 Data Storage and Evaluation

Data Storage

The DASY4 software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension ".DA4". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation by SEMCAD

Device parameters:

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

| Probe parameters: | - Sensitivity | $Norm_i$, a_{i0} , a_{i1} , a_{i2} |
|-------------------|---------------|---|
|-------------------|---------------|---|

 $\begin{array}{lll} \text{- Conversion factor} & \text{ConvF}_i \\ \text{- Diode compression point} & \text{Dcpi} \\ \text{- Frequency} & \text{f} \\ \text{- Crest factor} & \text{cf} \end{array}$

Media parameters: - Conductivity σ

- Density ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY4 components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics.

As of 2006-01-30 Page 13 of 86

CETECOM ICT Services GmbH

Test report no.: 2-4189-01-08/05



If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot cf/dcp_i$$

with V_i = compensated signal of channel i (i = x, y, z) U_i = input signal of channel i (i = x, y, z)

cf = crest factor of exciting field (DASY parameter) dcp_i = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: $E_i = (V_i / Norm_i \cdot ConvF)^{1/2}$

H-field probes: $H_i = (V_i)^{1/2} \cdot (a_{i0} + a_{i1}f + a_{i2}f^2)/f$

with V_i = compensated signal of channel i (i = x, y, z)

Norm_i = sensor sensitivity of channel i (i = x, y, z)

 $[mV/(V/m)^2]$ for E-field Probes

ConvF = sensitivity enhancement in solution

 a_{ij} = sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

E_i = electric field strength of channel i in V/m H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = (E_x^2 + E_y^2 + E_z^2)^{1/2}$$

The primary field data are used to calculate the derived field units.

$$SAR = (E_{tot}^2 \cdot \sigma) / (\rho \cdot 1000)$$

with SAR = local specific absorption rate in mW/g

 E_{tot} = total field strength in V/m

 σ = conductivity in [mho/m] or [Siemens/m]

 ρ = equivalent tissue density in g/cm³

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid. The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{\text{pwe}} = E_{tot}^2 / 3770$$
 or $P_{\text{pwe}} = H_{tot}^2 \cdot 37.7$

with P_{nwe} = equivalent power density of a plane wave in mW/cm²

 E_{tot} = total electric field strength in V/m H_{tot} = total magnetic field strength in A/m

As of 2006-01-30 Page 14 of 86



2.4.9 Test equipment utilized

This table gives a complete overview of the SAR measurement equipment

Devices used during the test described in chapter 2.5. are marked \boxtimes

| | Manufacturer | Device | Туре | Serial number | Date of last calibration)* |
|-------------|------------------------------------|---|---------------------|---------------|-----------------------------|
| | Schmid & Partner Engineering AG | Dosimetric E-Field Probe | ET3DV6 | 1558 | September 6, 2005 |
| | Schmid & Partner Engineering AG | Dosimetric E-Field Probe | ET3DV6 | 1559 | June 10, 2005 |
| | Schmid & Partner Engineering AG | 900 MHz System Validation Dipole | D900V2 | 102 | August 31, 2005 |
| | Schmid & Partner Engineering AG | 1800 MHz System Validation Dipole | D1800V2 | 287 | September 1, 2005 |
| | Schmid & Partner Engineering AG | 1900 MHz System Validation Dipole | D1900V2 | 5d009 | August 30, 2005 |
| | Schmid & Partner Engineering AG | 2450 MHz System Validation Dipole | D2450V2 | 710 | August 23, 2005 |
| | Schmid & Partner Engineering AG | Data acquisition electronics | DAE3V1 | 413 | January 12, 2005 |
| | Schmid & Partner Engineering AG | Software | DASY 4 V4.5 | | N/A |
| | Schmid & Partner Engineering AG | Phantom | SAM | | N/A |
| | Rohde & Schwarz | Universal Radio Communication Tester | CMU 200 | 832221/0055 | January 12, 2006 |
| | Agilent | Network Analyser 300 kHz to 3 GHz | 8753C | 2936A00872 | July 15, 2004 |
| | Agilent | Dielectric Probe Kit | 85070C | US99360146 | N/A |
| | Agilent | Peak Power Analyzer | 8990A | 3128A00169 | August 23, 2005 |
| | Agilent | Peak Power Sensor | 84813A | 3125A00111 | August 25, 2005 |
| | Agilent | Signal Generator | 8665A | 2833A00112 | November 08, 2005 |
| | Amplifier Reasearch | Amplifier | 25S1G4 (25 Watt) | 20452 | N/A |
| \boxtimes | Agilent | Power Meter | 438A | 2804U01006 | February 4, 2006 |
| \boxtimes | Agilent | Power Meter Sensor | 8482A | 2703A03025 | February 4, 2006 |

^{)* :} Network analyzer probe calibration against air, destilled water and a 50 Ohm resistor performed before measuring liquid parameters.

As of 2006-01-30 Page 15 of 86



2.4.10 Tissue simulating liquids: dielectric properties

The following materials are used for producing the tissue-equivalent materials

(liquids used for tests described in chapter 2.5. are marked with \boxtimes):

| Ingredients | Frequency (MHz) | | | | | |
|----------------|-----------------|-------|-------|----------|--------|-------------|
| (% of weight) | | | | | | |
| frequency band | <u>450</u> | 835 | 900 | <u> </u> | ∑ 1900 | <u>2450</u> |
| Tissue Type | Head | Head | Head | Head | Head | Head |
| Water | 38.56 | 41.45 | 40.92 | 52.64 | 54.9 | 62.7 |
| Salt (NaCl) | 3.95 | 1.45 | 1.48 | 0.36 | 0.18 | 0.5 |
| Sugar | 56.32 | 56.0 | 56.5 | 0.0 | 0.0 | 0.0 |
| HEC | 0.98 | 1.0 | 1.0 | 0.0 | 0.0 | 0.0 |
| Bactericide | 0.19 | 0.1 | 0.1 | 0.0 | 0.0 | 0.0 |
| Triton X-100 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 36.8 |
| DGBE | 0.0 | 0.0 | 0.0 | 47.0 | 44.92 | 0.0 |

Table 2: Head tissue dielectric properties

| Ingredients | Frequency (MHz) | | | | | |
|----------------|-----------------|------|-------|----------|--------|-------------|
| (% of weight) | | | | | | |
| frequency band | <u>450</u> | 835 | 900 | <u> </u> | ∑ 1900 | <u>2450</u> |
| Tissue Type | Body | Body | Body | Body | Body | Body |
| Water | 51.16 | 52.4 | 56.0 | 69.91 | 69.91 | 73.2 |
| Salt (NaCl) | 1.49 | 1.40 | 0.76 | 0.13 | 0.13 | 0.04 |
| Sugar | 46.78 | 45.0 | 41.76 | 0.0 | 0.0 | 0.0 |
| HEC | 0.52 | 1.0 | 1.21 | 0.0 | 0.0 | 0.0 |
| Bactericide | 0.05 | 0.1 | 0.27 | 0.0 | 0.0 | 0.0 |
| Triton X-100 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 |
| DGBE | 0.0 | 0.0 | 0.0 | 29.96 | 29.96 | 26.7 |

Table 3: Body tissue dielectric properties

Salt: 99+% Pure Sodium Chloride Sugar: 98+% Pure Sucrose Water: De-ionized, $16M\Omega$ + resistivity HEC: Hydroxyethyl Cellulose

DGBE: 99+% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]

Triton X-100(ultra pure): Polyethylene glycol mono [4-(1,1,3,3-tetramethylbutyl)phenyl]ether

As of 2006-01-30 Page 16 of 86



2.4.11 Tissue simulating liquids: parameters

| Used Target Frequency | Target Head Tissue | | | sured Tissue | Measured Date |
|--------------------------|-----------------------|--------------------|--------------|--------------------|------------------|
| [MHz] | Permittivity | Conductivity [S/m] | Permittivity | Conductivity [S/m] | |
| 1900 | 40.0 | 1.40 | 40.1 | 1.43 | 2006-01-27 |

Table 4: Parameter of the head tissue simulating liquid

| Used Target | Target | | Measured | | Measured |
|--------------------|--------------------|--------------|--------------|--------------|------------|
| Frequency | puency Body Tissue | | Body | Tissue | Date |
| [MHz] | Permittivity | Conductivity | Permittivity | Conductivity | |
| | | [S/m] | _ | [S/m] | |
| 1900 | 53.3 | 1.52 | 52.7 | 1.56 | 2006-01-27 |

Table 5: Parameter of the body tissue simulating liquid

Note: The dielectric properties have been measured using the contact probe method at 21°C.

As of 2006-01-30 Page 17 of 86



2.4.12 Measurement uncertainty evaluation for SAR test

The overall combined measurement uncertainty of the measurement system is \pm 10,3% (K=1). The expanded uncertainty(k=2) is assessed to be \pm 20.6%

This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

| Error Sources | Uncertainty Value | Probability Distribution | Divi- sor | c _i | c _i 10g | Standard Uncertainty 1g | Standard Uncertainty 10g | v _i ² or v _{eff} |
|----------------------------------|----------------------|-----------------------------|--------------|----------------|-----------------------|-------------------------------|--------------------------------|--|
| Measurement System | | | | | | | | |
| Probe calibration | ± 4.8% | Normal | 1 | 1 | 1 | ± 4.8% | ± 4.8% | ∞ |
| Axial isotropy | ± 4.7% | Rectangular | √3 | 0.7 | 0.7 | ± 1.9% | ± 1.9% | ∞ |
| Hemispherical isotropy | ± 9.6% | Rectangular | √3 | 0.7 | 0.7 | ± 3.9% | ± 3.9% | 8 |
| Spatial resolution | ± 0.0% | Rectangular | √3 | 1 | 1 | ± 0.0% | ± 0.0% | 8 |
| Boundary effects | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | 8 |
| Probe linearity | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | ∞ |
| System detection limits | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Readout electronics | ± 1.0% | Normal | 1 | 1 | 1 | ± 1.0% | ± 1.0% | ∞ |
| Response time | ± 0.8% | Rectangular | √3 | 1 | 1 | ± 0.5% | ± 0.5% | ∞ |
| Integration time | ± 2.6% | Rectangular | √3 | 1 | 1 | ± 1.5% | ± 1.5% | ∞ |
| RF ambient conditions | ± 3.0% | Rectangular | √3 | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Probe positioner | ± 0.4% | Rectangular | √3 | 1 | 1 | ± 0.2% | ± 0.2% | ∞ |
| Probe positioning | ± 2.9% | Rectangular | √3 | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Max. SAR evaluation | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Test Sample Related | | | | | | | | |
| Device positioning | ± 2.9% | Normal | 1 | 1 | 1 | ± 2.9% | ± 2.9% | 145 |
| Device holder uncertainty | ± 3.6% | Normal | 1 | 1 | 1 | ± 3.6% | ± 3.6% | 5 |
| Power drift | ± 5.0% | Rectangular | √3 | 1 | 1 | ± 2.9% | ± 2.9% | ∞ |
| Phantom and Set-up | | | | | | | | |
| Phantom uncertainty | ± 4.0% | Rectangular | √3 | 1 | 1 | ± 2.3% | ± 2.3% | ∞ |
| Liquid conductivity (target) | ± 5.0% | Rectangular | √3 | 0.64 | 0.43 | ± 1.8% | ± 1.2% | ∞ |
| Liquid conductivity (meas.) | ± 2.5% | Normal | 1 | 0.64 | 0.43 | ± 1.6% | ± 1.1% | ∞ |
| Liquid permittivity (target) | ± 5.0% | Rectangular | √3 | 0.6 | 0.49 | ± 1.7% | ± 1.4% | ∞ |
| Liquid permittivity (meas.) | ± 2.5% | Normal | 1 | 0.6 | 0.49 | ± 1.5% | ± 1.2% | ∞ |
| Combined Uncertainty | | | | | | ± 10.3% | ± 10.0% | 330 |
| Expanded Std. Uncertainty | | | | | | ± 20.6% | ± 20.1% | |

Table 6: Measurement uncertainties

As of 2006-01-30 Page 18 of 86



2.4.13 Measurement uncertainty evaluation for system validation

The overall combined measurement uncertainty of the measurement system is \pm 8.4% (K=1).

The expanded uncertainty(k=2) is assessed to be $\pm 16.8\%$

This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

| Error Sources | Uncertainty Value | Probability Distribution | Divi- sor | c _i | c _i 10g | Standard Uncertainty 1g | Standard Uncertainty 10g | v _i ² or v _{eff} |
|----------------------------------|----------------------|-----------------------------|--------------|----------------|-----------------------|-------------------------------|--------------------------------|---|
| Measurement System | | | | | | | | |
| Probe calibration | ± 4.8% | Normal | 1 | 1 | 1 | ± 4.8% | ± 4.8% | ∞ |
| Axial isotropy | ± 4.7% | Rectangular | √3 | 0.7 | 0.7 | ± 1.9% | ± 1.9% | ∞ |
| Hemispherical isotropy | ± 0.0% | Rectangular | $\sqrt{3}$ | 0.7 | 0.7 | ± 0.0% | ± 3.9% | ∞ |
| Boundary effects | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Probe linearity | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | ∞ |
| System detection limits | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Readout electronics | ± 1.0% | Normal | 1 | 1 | 1 | ± 1.0% | ± 1.0% | ∞ |
| Response time | ± 0.0% | Rectangular | √3 | 1 | 1 | ± 0.0% | ± 0.0% | ∞ |
| Integration time | ± 0.0% | Rectangular | √3 | 1 | 1 | ± 0.0% | ± 0.0% | ∞ |
| RF ambient conditions | ± 3.0% | Rectangular | √3 | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Probe positioner | ± 0.4% | Rectangular | √3 | 1 | 1 | ± 0.2% | ± 0.2% | ∞ |
| Probe positioning | ± 2.9% | Rectangular | $\sqrt{3}$ | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Max. SAR evaluation | ± 1.0% | Rectangular | $\sqrt{3}$ | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Test Sample Related | | | | | | | | |
| Dipole axis to liquid distance | ± 2.0% | Normal | 1 | 1 | 1 | ± 1.2% | ± 1.2% | ∞ |
| Power drift | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | ∞ |
| Phantom and Set-up | | | | | | | | |
| Phantom uncertainty | ± 4.0% | Rectangular | √3 | 1 | 1 | ± 2.3% | ± 2.3% | ∞ |
| Liquid conductivity (target) | ± 5.0% | Rectangular | √3 | 0.64 | 0.43 | ± 1.8% | ± 1.2% | ∞ |
| Liquid conductivity (meas.) | ± 2.5% | Normal | 1 | 0.64 | 0.43 | ± 1.6% | ± 1.1% | ∞ |
| Liquid permittivity (target) | ± 5.0% | Rectangular | $\sqrt{3}$ | 0.6 | 0.49 | ± 1.7% | ± 1.4% | ∞ |
| Liquid permittivity (meas.) | ± 2.5% | Normal | 1 | 0.6 | 0.49 | ± 1.5% | ± 1.2% | ∞ |
| Combined Uncertainty | | | | | | ± 8.4% | ± 8.1% | |
| Expanded Std. Uncertainty | | | | | _ | ± 16.8% | ± 16.2% | |

Table 7: Measurement uncertainties

As of 2006-01-30 Page 19 of 86



2.4.14 System validation

The system validation is performed for verifying the accuracy of the complete measurement system and performance of the software. The system validation is performed with tissue equivalent material according to IEEE P1528 (described above). The following table shows validation results for all frequency bands and tissue liquids used during the tests of the test item described in chapter 1.5. (graphic plot(s) see annex 1).

| Validation Kit | Frequency | Target Peak SAR (1000 mW) (+/- 10%) | Target SAR _{1g} (1000 mW) (+/- 10%) | Measured Peak SAR | Measured SAR _{1g} | Measured date |
|-----------------------|------------------|--|--|----------------------|-------------------------------|------------------|
| D1900V2 S/N: 5d009 | 1900 MHz head | 69.6 mW/g | 38.2 mW/g | 69.9 mW/g | 40.5 mW/g | 2006-01-27 |
| D1900V2 S/N: 5d009 | 1900 MHz body | 66.4 mW/g | 38.5 mW/g | 69.2 mW/g | 40.6 mW/g | 2006-01-27 |
| D1900V2 S/N: 5d009 | 1900 MHz head | 69.6 mW/g | 38.2 mW/g | 71.0 mW/g | 40.5 mW/g | 2006-01-30 |
| D1900V2 S/N: 5d009 | 1900 MHz body | 66.4 mW/g | 38.5 mW/g | 70.0 mW/g | 40.4 mW/g | 2006-01-31 |

Table 8: Results system validation

As of 2006-01-30 Page 20 of 86

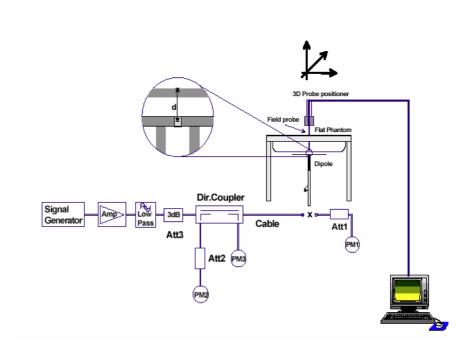


2.4.15 Validation procedure

The validation is performed by using a validation dipole which is positioned parallel to the planar part of the SAM phantom at the reference point. The distance of the dipole to the SAM phantom is determined by a plexiglass spacer. The dipole is connected to the signal source consisting of signal generator and amplifier via a directional coupler, N-connector cable and adaption to SMA. It is fed with a power of 1000 mW. To adjust this power a power meter is used. The power sensor is connected to the cable before the validation to measure the power at this point and do adjustments at the signal generator. At the outputs of the directional coupler both return loss as well as forward power are controlled during the validation to make sure that emitted power at the dipole is kept constant. This can also be checked by the power drift measurement after the test (result on plot).

Validation results have to be equal or near the values determined during dipole calibration (target SAR in table above) with the relevant liquids and test system.





As of 2006-01-30 Page 21 of 86



2.5 Test results (Head and Body SAR)

| The table contains the measured SAR values averaged over a mass of 1 g | | | | | | | | |
|--|-------------|--------------------|---------------------|----------|--------------------|--|--|--|
| Channel / frequency | Position | Left hand position | Right hand position | Limit | Liquid temperature | | | |
| | Gigaset S45 | | | | | | | |
| 3 / 1925 MHz | cheek | 0.055 W/kg | 0.051 W/kg | 1.6 W/kg | 21.5/21.5 °C | | | |
| 3 / 1925 MHz | tilted 15° | 0.035 W/kg | 0.035 W/kg | 1.6 W/kg | 21.5/21.5 °C | | | |
| Gigaset E45 | | | | | | | | |
| 3 / 1925 MHz | cheek | 0.063 W/kg | 0.059 W/kg | 1.6 W/kg | 20.0/20.0 °C | | | |
| 3 / 1925 MHz | tilted 15° | 0.033 W/kg | 0.036 W/kg | 1.6 W/kg | 20.0/20.0 °C | | | |
| 1 / 1921.5 MHz | cheek | not necessary | not necessary | 1.6 W/kg | °C | | | |
| 5 / 1928.5 MHz | cheek | not necessary | not necessary | 1.6 W/kg | °C | | | |

Table 9: Test results (Head SAR 1900 MHz)

Note: The SAR test shall be performed at the high, middle and low frequency channels of each operating mode. If the SAR measured at mid-band channel for each test configuration is at least 3.0 dB lower than the SAR limit (< 0.8 W/kg), testing at the high and low channels is optional.

| The table contains the measured SAR values averaged over a mass of 1 g | | | | | | | | |
|--|-------------|-------------------|----------|--------------------|--|--|--|--|
| Channel / frequency | Position | Body worn | Limit | Liquid temperature | | | | |
| | Gigaset S45 | | | | | | | |
| 3 / 1925 MHz | front | 0.061 W/kg | 1.6 W/kg | 21.3°C | | | | |
| 3 / 1925 MHz | rear | 0.089 W/kg | 1.6 W/kg | 21.1°C | | | | |
| Gigaset E45 | | | | | | | | |
| 3 / 1925 MHz | front | 0.077 W/kg | 1.6 W/kg | 20.2°C | | | | |
| 3 / 1925 MHz | rear | 0.120 W/kg | 1.6 W/kg | 20.2°C | | | | |
| 1 / 1921.5 MHz | rear | not necessary | 1.6 W/kg | | | | | |
| 5 / 1928.5 MHz | rear | not necessary | 1.6 W/kg | | | | | |

Table 10: Test results (Body SAR 1900 MHz)

Note: The SAR test shall be performed at the high, middle and low frequency channels of each operating mode. If the SAR measured at mid-band channel for each test configuration is at least 3.0 dB lower than the SAR limit (< 0.8 W/kg), testing at the high and low channels is optional.

As of 2006-01-30 Page 22 of 86



2.5.1 General description of test procedures

The device was tested using integrated test software functions to set test channels and maximum output power to the DUT.

Test positions as described in the tables above are in accordance with the specified test standard. The conducted output power was measured using an integrated RF connector and attached RF cable. Tests in body position were performed without any distance between DUT and SAM.

2.6 Test results (conducted power measurement)

The output power was measured using an integrated RF connector and attached RF cable. The conducted output power was measured before and after each SAR measurement. The resulting power values were within a 0.2 dB tolerance of the values shown below.

| UPCS | (S45) | UPCS (E45) | | | |
|---------|------------|------------|------------|--|--|
| Channel | peak power | Channel | peak power | | |
| 3 | 20.0 dBm | 3 | 20.0 dBm | | |

Table 11: Test results conducted peak power measurement

As of 2006-01-30 Page 23 of 86



Annex 1 System performance verification S45

Date/Time: 2006-01-27 10:15:08Date/Time: 2006-01-27 10:19:15

SystemPerformanceCheck-D1900 head 2006-01-27

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d009

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: HSL1900 Medium parameters used (interpolated): f = 1900 MHz; $\sigma = 1.43 \text{ mho/m}$; $\varepsilon_r = 40.1$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

d=10mm, Pin=1000mW/Area Scan (51x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 50.4 mW/g

d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

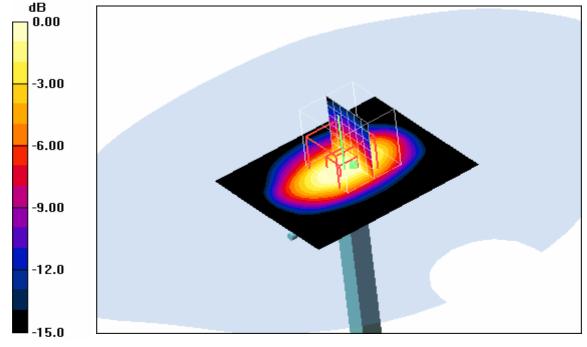
dz=5mm

Reference Value = 181.2 V/m; Power Drift = 0.017 dB

Peak SAR (extrapolated) = 69.9 W/kg

SAR(1 g) = 40.5 mW/g; SAR(10 g) = 21.5 mW/g

Maximum value of SAR (measured) = 45.4 mW/g



0 dB = 45.4 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.6 °C; liquid temperature: 21.5 °C

As of 2006-01-30 Page 24 of 86



Date/Time: 2006-01-27 12:41:03Date/Time: 2006-01-27 12:45:07

SystemPerformanceCheck-D1900 body 2006-01-27

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d009 Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: M1900 Medium parameters used (interpolated): f = 1900 MHz; $\sigma = 1.56 \text{ mho/m}$; $\epsilon_r = 52.7$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.27, 4.27, 4.27); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

d=10mm, Pin=1000mW/Area Scan (51x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 50.7 mW/g

d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

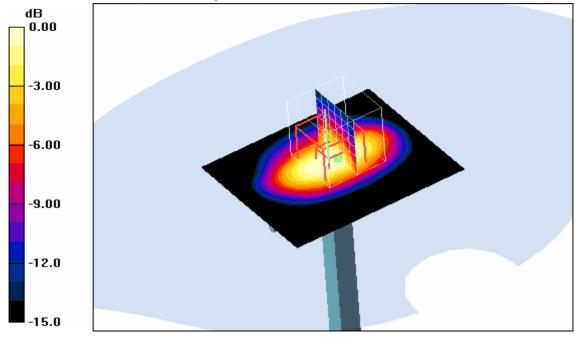
dz=5mm

Reference Value = 167.7 V/m; Power Drift = 0.054 dB

Peak SAR (extrapolated) = 69.2 W/kg

SAR(1 g) = 40.6 mW/g; SAR(10 g) = 21.7 mW/g

Maximum value of SAR (measured) = 45.3 mW/g



0 dB = 45.3 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) :

ambient temperature: 23.2°C; liquid temperature: 21.3°C

As of 2006-01-30 Page 25 of 86



Annex 2 Measurement results (printout from DASY TM) S45

Remark: results of conducted power measurements: see chapter 2.5/2.6 (if applicable)

Date/Time: 2006-01-27 10:39:59Date/Time: 2006-01-27 10:45:35

P1528 OET65-LeftHandSide-DECT

DUT: Siemens; Type: Gigaset S45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: HSL1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.43$ mho/m; $\varepsilon_r = 40.1$; $\rho = 1000$ kg/m³

Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Middle/Area Scan (51x81x1): Measurement grid: dx=15mm, dy=15mm

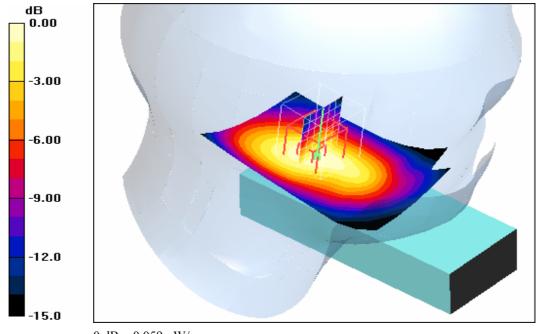
Maximum value of SAR (interpolated) = 0.061 mW/g

Touch position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 5.36 V/m; Power Drift = -0.031 dB

Peak SAR (extrapolated) = 0.085 W/kg

SAR(1 g) = 0.055 mW/g; SAR(10 g) = 0.033 mW/gMaximum value of SAR (measured) = 0.059 mW/g



0 dB = 0.059 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions):

ambient temperature: 22.6°C; liquid temperature: 21.5°C

As of 2006-01-30 Page 26 of 86



Date/Time: 2006-01-27 11:02:48Date/Time: 2006-01-27 11:08:52

P1528 OET65-LeftHandSide-DECT

DUT: Siemens; Type: Gigaset S45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: HSL1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.43$ mho/m; $\varepsilon_r = 40.1$; $\rho = 1000$ kg/m³

Phantom section: Left Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Tilt position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.039 mW/g

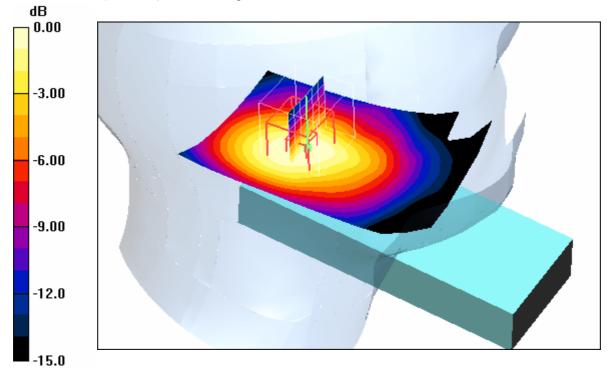
Tilt position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 5.00 V/m; Power Drift = -0.074 dB

Peak SAR (extrapolated) = 0.056 W/kg

SAR(1 g) = 0.035 mW/g; SAR(10 g) = 0.021 mW/g Maximum value of SAR (measured) = 0.037 mW/g



0 dB = 0.037 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.6°C; liquid temperature: 21.5°C

As of 2006-01-30 Page 27 of 86



Date/Time: 2006-01-27 11:29:19Date/Time: 2006-01-27 11:37:14

P1528_OET65-RightHandSide-DECT

DUT: Siemens; Type: Gigaset S45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: HSL1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.43$ mho/m; $\varepsilon_r = 40.1$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Middle/Area Scan (51x121x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.055 mW/g

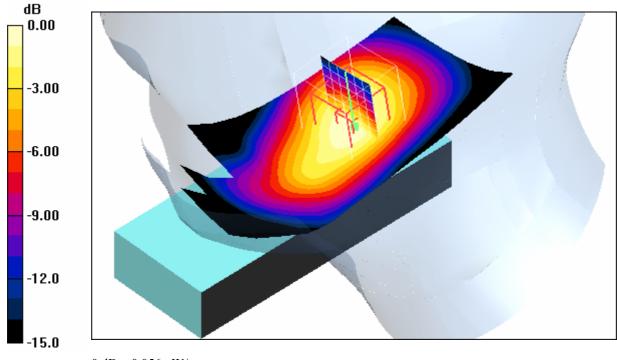
Touch position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 5.07 V/m; Power Drift = 0.069 dB

Peak SAR (extrapolated) = 0.078 W/kg

SAR(1 g) = 0.051 mW/g; SAR(10 g) = 0.030 mW/gMaximum value of SAR (measured) = 0.056 mW/g



0 dB = 0.056 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.6°C; liquid temperature: 21.5°C

As of 2006-01-30 Page 28 of 86



Date/Time: 2006-01-27 11:52:03Date/Time: 2006-01-27 11:58:07

P1528_OET65-RightHandSide-DECT

DUT: Siemens; Type: Gigaset S45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: HSL1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.43$ mho/m; $\varepsilon_r = 40.1$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Tilt position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.037 mW/g

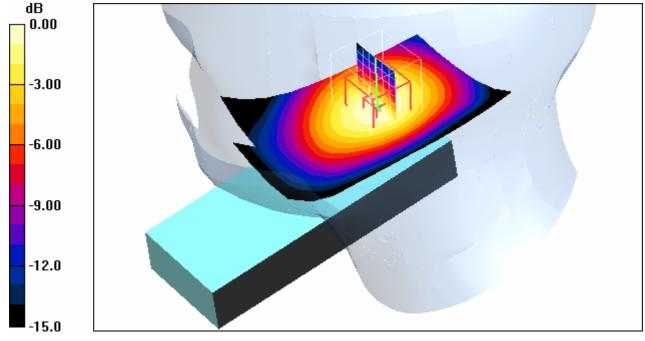
Tilt position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 4.98 V/m; Power Drift = -0.043 dB

Peak SAR (extrapolated) = 0.054 W/kg

SAR(1 g) = 0.035 mW/g; SAR(10 g) = 0.021 mW/g Maximum value of SAR (measured) = 0.038 mW/g



0 dB = 0.038 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.6°C; liquid temperature: 21.5°C

As of 2006-01-30 Page 29 of 86



Date/Time: 2006-01-27 13:12:59Date/Time: 2006-01-27 13:20:56

P1528_OET65-Body-DECT USA

DUT: Siemens; Type: Gigaset S45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: M1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.56$ mho/m; $\varepsilon_r = 52.7$; $\rho = 1000$ kg/m³

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.27, 4.27, 4.27); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Front position - Middle/Area Scan (61x101x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.069 mW/g

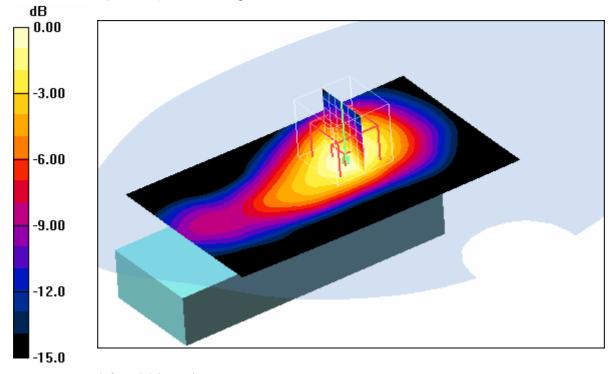
Front position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 4.83 V/m; Power Drift = 0.012 dB

Peak SAR (extrapolated) = 0.099 W/kg

SAR(1 g) = 0.061 mW/g; SAR(10 g) = 0.036 mW/gMaximum value of SAR (measured) = 0.067 mW/g



0 dB = 0.067 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions): touched ambient temperature: 23.2°C; liquid temperature: 21.3°C

As of 2006-01-30 Page 30 of 86



Date/Time: 2006-01-27 13:39:55Date/Time: 2006-01-27 13:47:35

P1528_OET65-Body-DECT USA

DUT: Siemens; Type: Gigaset S45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: M1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.56$ mho/m; $\varepsilon_r = 52.7$; $\rho = 1000$ kg/m³

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.27, 4.27, 4.27); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Rear position - Middle/Area Scan (61x101x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.101 mW/g

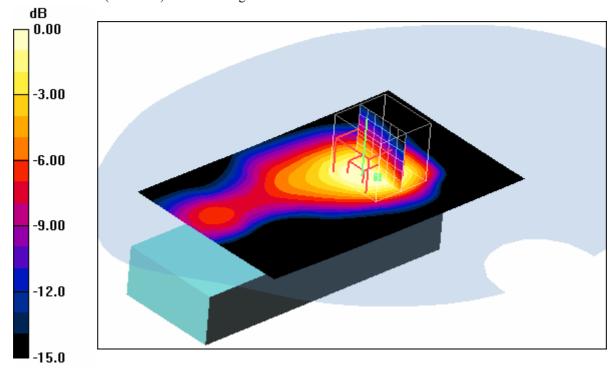
Rear position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 6.70 V/m; Power Drift = -0.027 dB

Peak SAR (extrapolated) = 0.151 W/kg

SAR(1 g) = 0.089 mW/g; SAR(10 g) = 0.051 mW/gMaximum value of SAR (measured) = 0.099 mW/g



0 dB = 0.099 mW/g

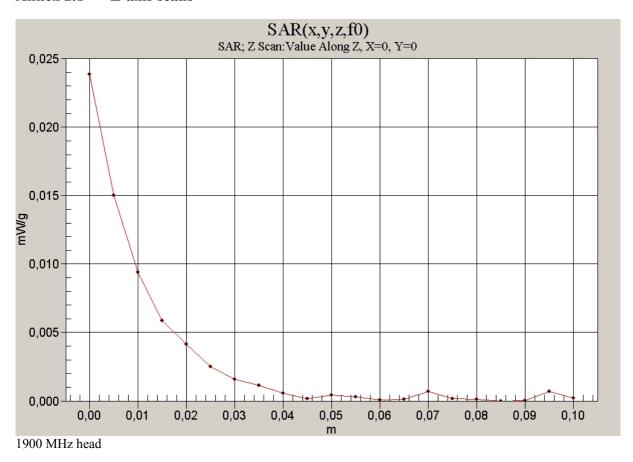
Additional information:

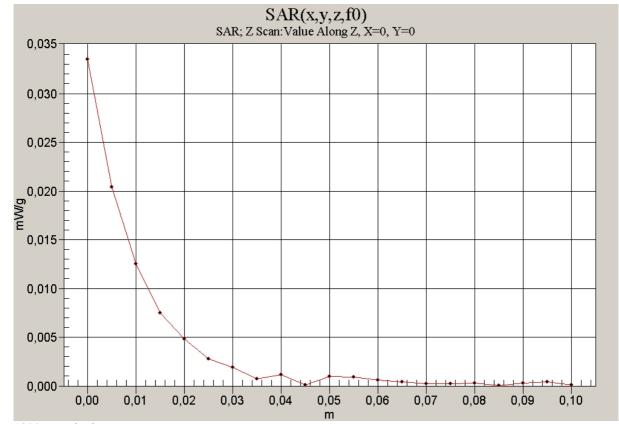
position or distance of DUT to SAM (if not standard head positions) : touched ambient temperature: 23.0° C; liquid temperature: 21.1° C

As of 2006-01-30 Page 31 of 86



Annex 2.1 Z-axis scans





1900 MHz body

As of 2006-01-30 Page 32 of 86



Annex 3 System performance verification E45

Date/Time: 2006-01-30 09:53:12Date/Time: 2006-01-30 09:57:17

SystemPerformanceCheck-D1900 head 2006-01-30

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d009 Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: HSL1900 Medium parameters used (interpolated): f = 1900 MHz; $\sigma = 1.43 \text{ mho/m}$; $\varepsilon_r = 40.1$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn413; Calibrated: 2006-01-12

- Phantom: SAM 12; Type: SAM; Serial: 1043

- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

d=10mm, Pin=1000mW/Area Scan (51x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 49.7 mW/g

d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

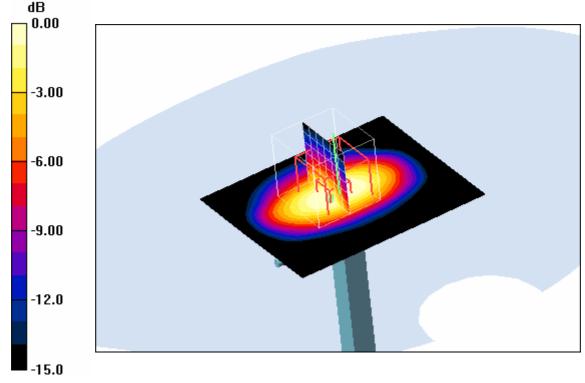
dz=5mm

Reference Value = 180.8 V/m; Power Drift = 0.046 dB

Peak SAR (extrapolated) = 71.0 W/kg

SAR(1 g) = 40.5 mW/g; SAR(10 g) = 21.2 mW/g

Maximum value of SAR (measured) = 45.2 mW/g



0 dB = 45.2 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.1°C; liquid temperature: 20.2°C

As of 2006-01-30 Page 33 of 86



Date/Time: 2006-01-31 09:27:24Date/Time: 2006-01-31 09:31:26

SystemPerformanceCheck-D1900 body 2006-01-31

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d009 Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: M1900 Medium parameters used (interpolated): f = 1900 MHz; $\sigma = 1.56 \text{ mho/m}$; $\epsilon_r = 52.7$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.27, 4.27, 4.27); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

d=10mm, Pin=1000mW/Area Scan (51x61x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 50.7 mW/g

d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

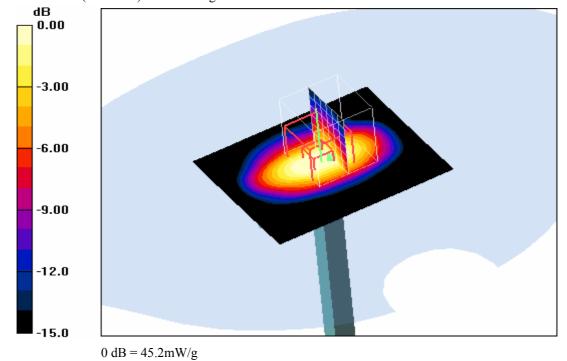
dz=5mm

Reference Value = 174.0 V/m; Power Drift = 0.01 dB

Peak SAR (extrapolated) = 70.0 W/kg

SAR(1 g) = 40.4 mW/g; SAR(10 g) = 21.4 mW/g

Maximum value of SAR (measured) = 45.2 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 22.5°C; liquid temperature: 20.8°C

As of 2006-01-30 Page 34 of 86



Annex 4 Measurement results (printout from DASY TM) E45

Date/Time: 2006-01-30 12:57:00Date/Time: 2006-01-30 13:02:34

P1528_OET65-LeftHandSide-DECT

DUT: Siemens; Type: Gigaset E45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: HSL1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.43$ mho/m; $\varepsilon_r = 40.1$; $\rho = 1000$ kg/m³

Phantom section: Left Section DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn413; Calibrated: 2006-01-12

- Phantom: SAM 12; Type: SAM; Serial: 1043

- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Middle/Area Scan (51x81x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.071 mW/g

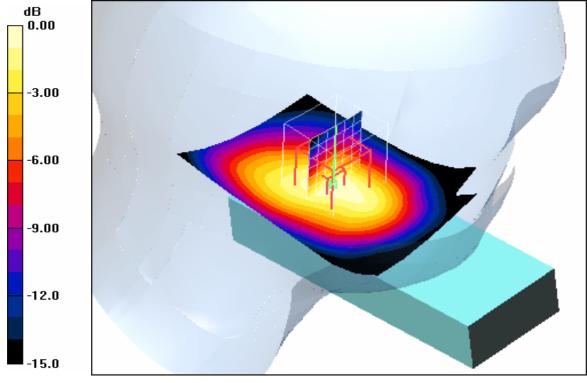
Touch position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 4.51 V/m; Power Drift = 0.065 dB

Peak SAR (extrapolated) = 0.099 W/kg

SAR(1 g) = 0.063 mW/g; SAR(10 g) = 0.037 mW/g Maximum value of SAR (measured) = 0.068 mW/g



0 dB = 0.068 mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 23.3°C; liquid temperature: 20.0°C

As of 2006-01-30 Page 35 of 86



Date/Time: 2006-01-30 13:19:01Date/Time: 2006-01-30 13:25:14

P1528 OET65-LeftHandSide-DECT

DUT: Siemens; Type: Gigaset E45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: HSL1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.43$ mho/m; $\varepsilon_r = 40.1$; $\rho = 1000$ kg/m³

Phantom section: Left Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Tilt position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.035 mW/g

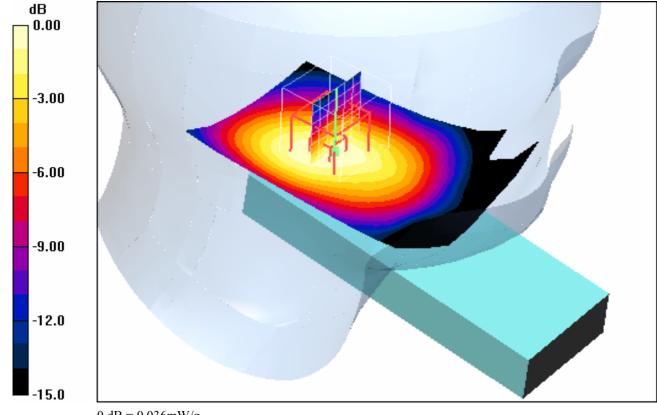
Tilt position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 4.55 V/m; Power Drift = 0.015 dB

Peak SAR (extrapolated) = 0.054 W/kg

SAR(1 g) = 0.033 mW/g; SAR(10 g) = 0.019 mW/g Maximum value of SAR (measured) = 0.036 mW/g



0~dB=0.036mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 23.3°C; liquid temperature: 20.0°C

As of 2006-01-30 Page 36 of 86



Date/Time: 2006-01-30 13:40:49Date/Time: 2006-01-30 13:47:35

P1528_OET65-RightHandSide-DECT

DUT: Siemens; Type: Gigaset E45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: HSL1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.43$ mho/m; $\varepsilon_r = 40.1$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Touch position - Middle/Area Scan (51x111x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.063 mW/g

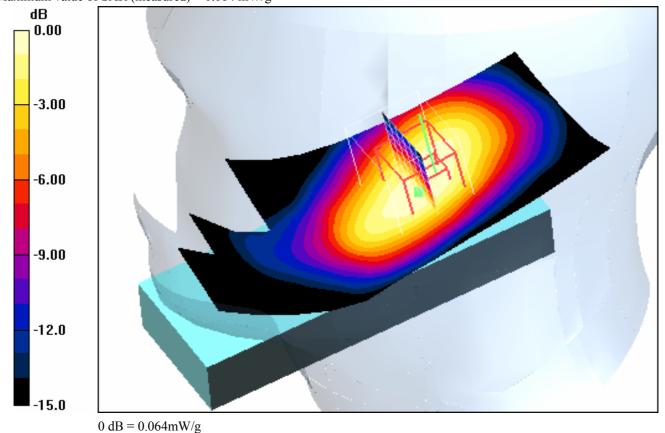
Touch position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 4.89 V/m; Power Drift = 0.193 dB

Peak SAR (extrapolated) = 0.096 W/kg

SAR(1 g) = 0.059 mW/g; SAR(10 g) = 0.035 mW/gMaximum value of SAR (measured) = 0.064 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 23.4°C; liquid temperature: 20.0°C

As of 2006-01-30 Page 37 of 86



Date/Time: 2006-01-30 14:05:15Date/Time: 2006-01-30 14:11:15

P1528_OET65-RightHandSide-DECT

DUT: Siemens; Type: Gigaset E45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: HSL1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.43$ mho/m; $\varepsilon_r = 40.1$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.73, 4.73, 4.73); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Tilt position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.038 mW/g

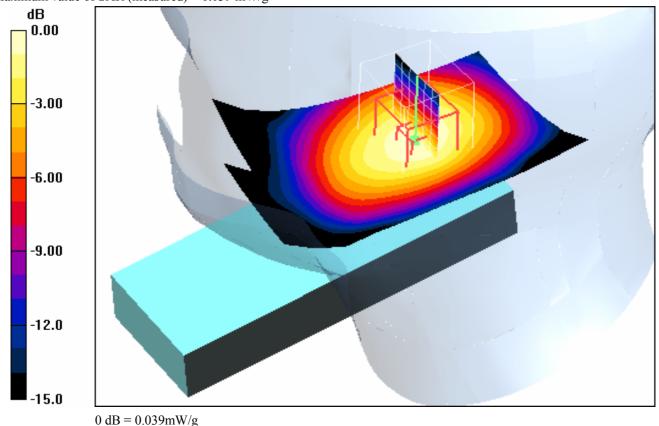
Tilt position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 4.86 V/m; Power Drift = 0.037 dB

Peak SAR (extrapolated) = 0.059 W/kg

SAR(1 g) = 0.036 mW/g; SAR(10 g) = 0.021 mW/gMaximum value of SAR (measured) = 0.039 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions) : ambient temperature: 23.4°C; liquid temperature: 20.0°C

As of 2006-01-30 Page 38 of 86



Date/Time: 2006-01-31 12:02:26Date/Time: 2006-01-31 12:10:24

P1528 OET65-Body-DECT USA

DUT: Siemens; Type: Gigaset E45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: M1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.56$ mho/m; $\varepsilon_r = 52.7$; $\rho = 1000$ kg/m³

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.27, 4.27, 4.27); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Front position - Middle/Area Scan (61x111x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.086 mW/g

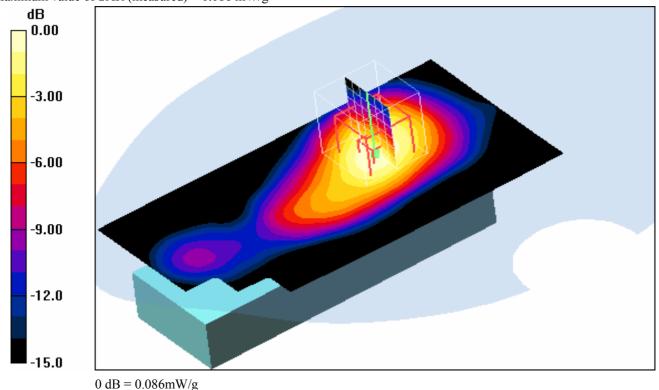
Front position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 4.79 V/m; Power Drift = 0.027 dB

Peak SAR (extrapolated) = 0.130 W/kg

SAR(1 g) = 0.077 mW/g; SAR(10 g) = 0.045 mW/gMaximum value of SAR (measured) = 0.086 mW/g



Additional information:

position or distance of DUT to SAM (if not standard head positions): touched ambient temperature: 23.0°C; liquid temperature: 20.2°C

As of 2006-01-30 Page 39 of 86



Date/Time: 2006-01-31 12:31:14Date/Time: 2006-01-31 12:39:18

P1528 OET65-Body-DECT USA

DUT: Siemens; Type: Gigaset E45; Serial: n.a.

Communication System: DECT USA; Frequency: 1925 MHz; Duty Cycle: 1:24

Medium: M1900 Medium parameters used (extrapolated): f = 1925 MHz; $\sigma = 1.56$ mho/m; $\varepsilon_r = 52.7$; $\rho = 1000$ kg/m³

Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 SN1558; ConvF(4.27, 4.27, 4.27); Calibrated: 2005-09-06
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 2006-01-12
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.5 Build 19; Postprocessing SW: SEMCAD, V1.8 Build 146

Rear position - Middle/Area Scan (61x111x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 0.166 mW/g

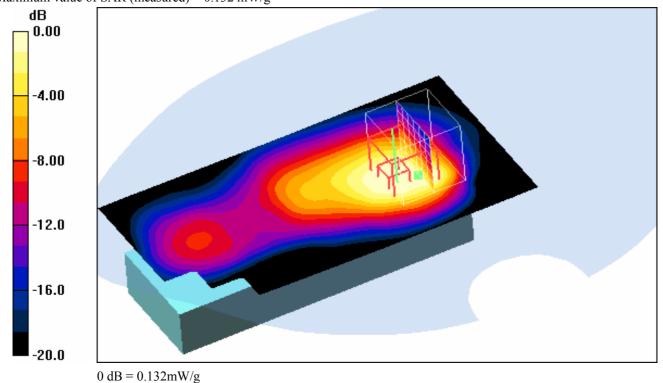
Rear position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm,

dz=5mm

Reference Value = 7.15 V/m; Power Drift = -0.022 dB

Peak SAR (extrapolated) = 0.213 W/kg

SAR(1 g) = 0.120 mW/g; SAR(10 g) = 0.065 mW/gMaximum value of SAR (measured) = 0.132 mW/g



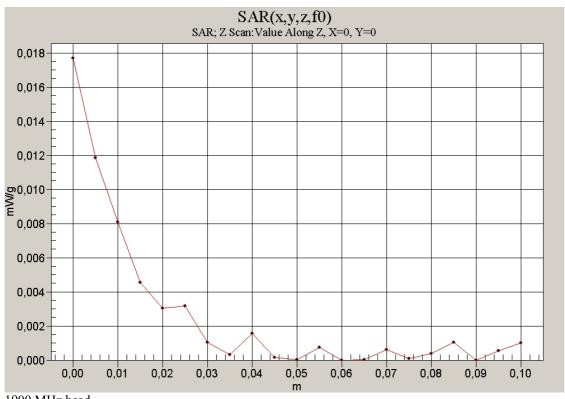
Additional information:

position or distance of DUT to SAM (if not standard head positions) : touched ambient temperature: 23.1° C; liquid temperature: 20.2° C

As of 2006-01-30 Page 40 of 86

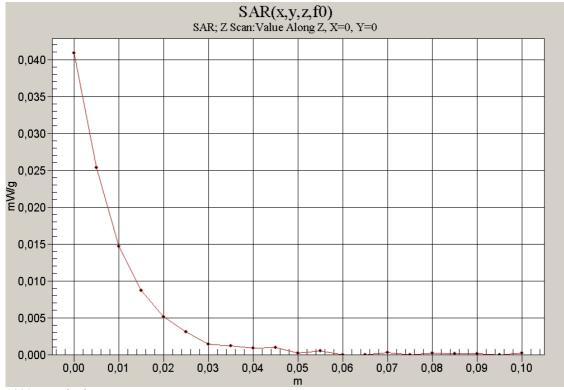


Annex 4.1 Z-axis scans



1900 MHz head

Remark: Z scan ripple occurs due to low SAR level at measurement point.



1900 MHz body

As of 2006-01-30 Page 41 of 86

CETECOM ICT Services GmbH

Test report no.: 2-4189-01-08/05



Annex 5 Photo documentation

Picture no. 1

Measurement System DASY 4



As of 2006-01-30 Page 42 of 86



Picture no. 2

DUT S45 - front view



As of 2006-01-30 Page 43 of 86



Picture no. 3

DUT S45 - side view



As of 2006-01-30 Page 44 of 86



Picture no. 4

DUT S45 - rear view



As of 2006-01-30 Page 45 of 86



Picture no. 5

DUT S45 - rear view (open)



As of 2006-01-30 Page 46 of 86



Picture no. 6

DUT S45 - rear view (open) without batteries



As of 2006-01-30 Page 47 of 86

CETECOM ICT Services GmbH

Test report no.: 2-4189-01-08/05



Picture no. 7

Batteries



As of 2006-01-30 Page 48 of 86



Picture no. 8

Test position left hand touched



As of 2006-01-30 Page 49 of 86



Picture no. 9

Test position left hand touched



As of 2006-01-30 Page 50 of 86



Picture no. 10

Test position left hand touched

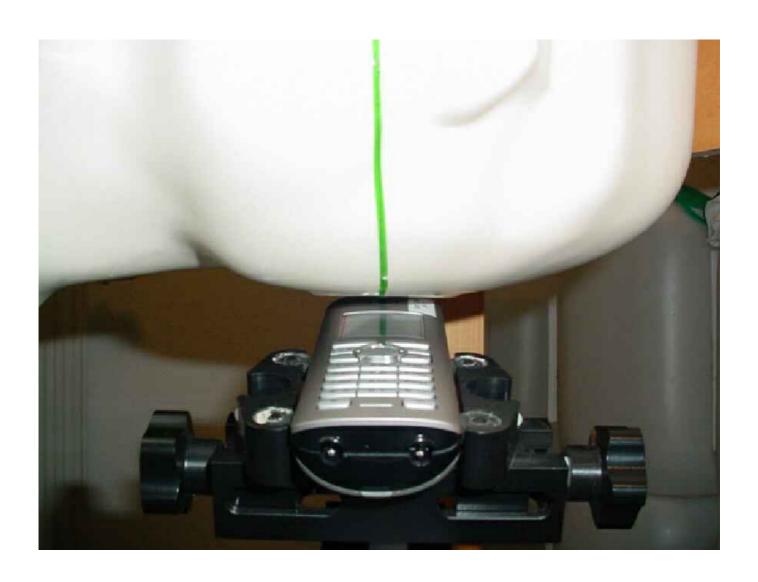


As of 2006-01-30 Page 51 of 86



Picture no. 11

Test position left hand tilted 15°



As of 2006-01-30 Page 52 of 86



Picture no. 12

Test position left hand tilted 15°

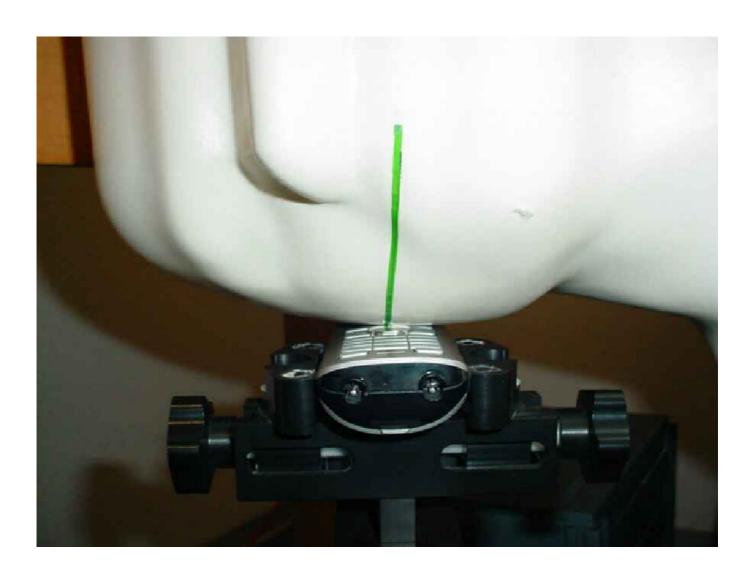


As of 2006-01-30 Page 53 of 86



Picture no. 13

Test position right hand touched



As of 2006-01-30 Page 54 of 86



Picture no. 14

Test position right hand touched



As of 2006-01-30 Page 55 of 86



Picture no. 15

Test position right hand touched

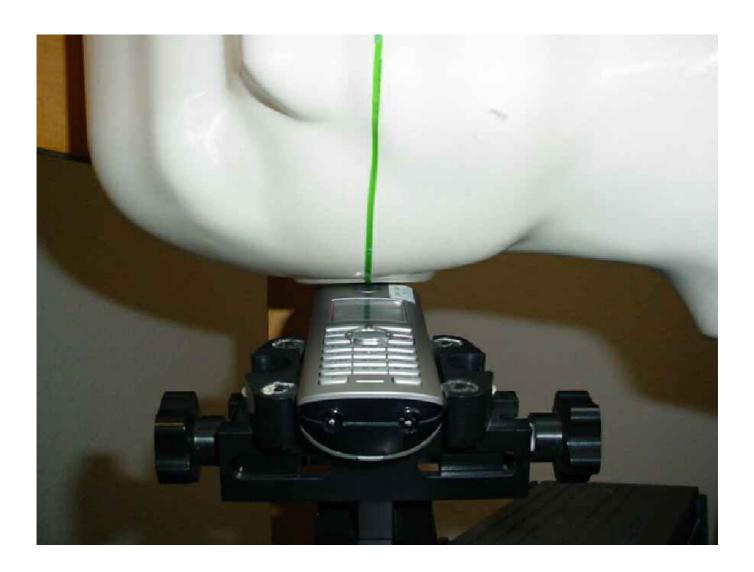


As of 2006-01-30 Page 56 of 86



Picture no. 16

Test position right hand tilted 15°



As of 2006-01-30 Page 57 of 86



Picture no. 17

Test position right hand tilted 15°



As of 2006-01-30 Page 58 of 86



Picture no. 18

Test position body worn front side touched



As of 2006-01-30 Page 59 of 86



Picture no. 19

Test position body worn front side touched



As of 2006-01-30 Page 60 of 86



Picture no. 20

Test position body worn rear side touched



As of 2006-01-30 Page 61 of 86



Picture no. 21

Test position body worn rear side touched



As of 2006-01-30 Page 62 of 86



Picture no. 22

DUT E45 - front view



As of 2006-01-30 Page 63 of 86



Picture no. 23

DUT E45 - side view



As of 2006-01-30 Page 64 of 86



Picture no. 24

DUT E45 - rear view



As of 2006-01-30 Page 65 of 86



Picture no. 25

DUT E45 - rear view (open)



As of 2006-01-30 Page 66 of 86



Picture no. 26

DUT E45 - rear view (open) without battery



As of 2006-01-30 Page 67 of 86



Picture no. 27

Battery

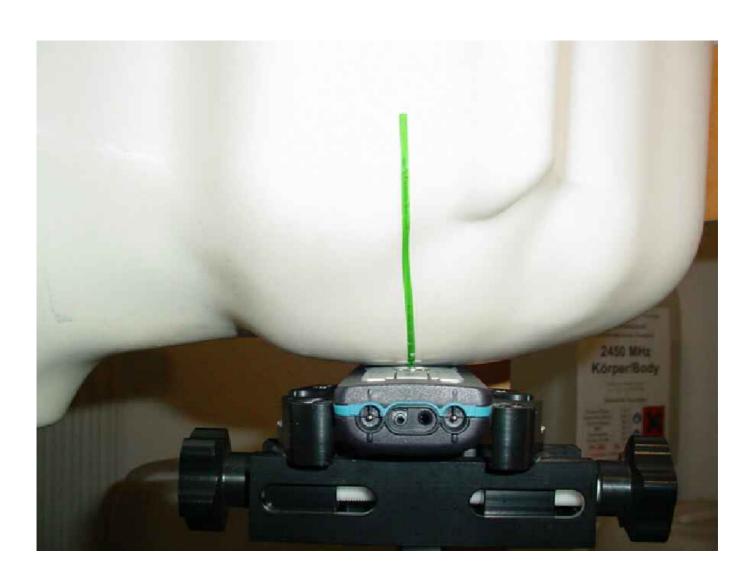


As of 2006-01-30 Page 68 of 86



Picture no. 28

Test position left hand touched



As of 2006-01-30 Page 69 of 86



Picture no. 29

Test position left hand touched

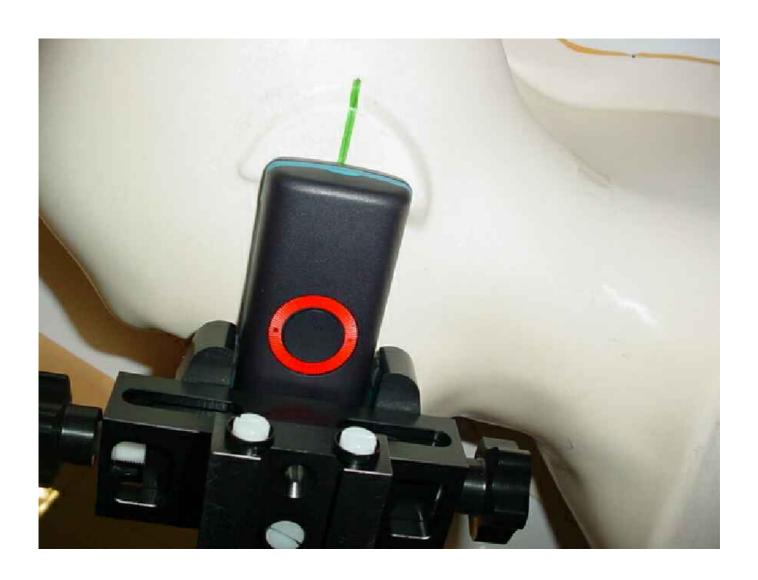


As of 2006-01-30 Page 70 of 86



Picture no. 30

Test position left hand touched

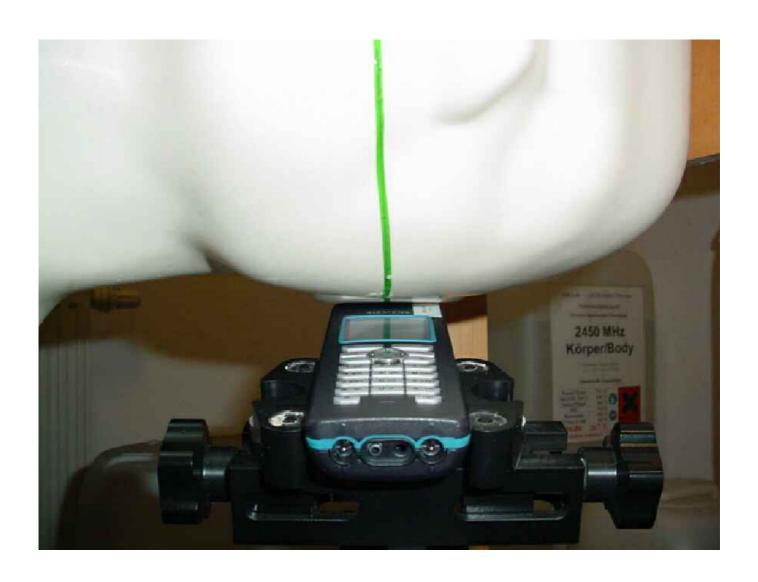


As of 2006-01-30 Page 71 of 86



Picture no. 31

Test position left hand tilted 15°



As of 2006-01-30 Page 72 of 86



Picture no. 32

Test position left hand tilted 15°

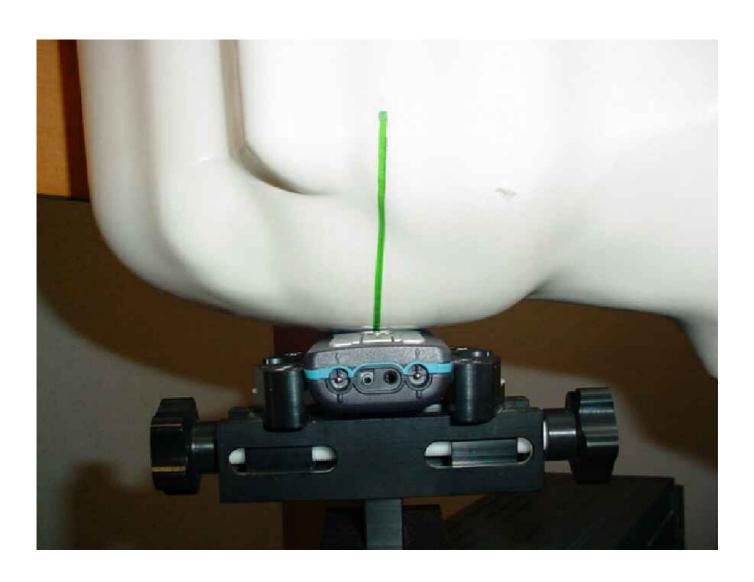


As of 2006-01-30 Page 73 of 86



Picture no. 33

Test position right hand touched



As of 2006-01-30 Page 74 of 86



Picture no. 34

Test position right hand touched



As of 2006-01-30 Page 75 of 86



Picture no. 35

Test position right hand touched



As of 2006-01-30 Page 76 of 86



Picture no. 36

Test position right hand tilted 15°



As of 2006-01-30 Page 77 of 86



Picture no. 37

Test position right hand tilted 15°

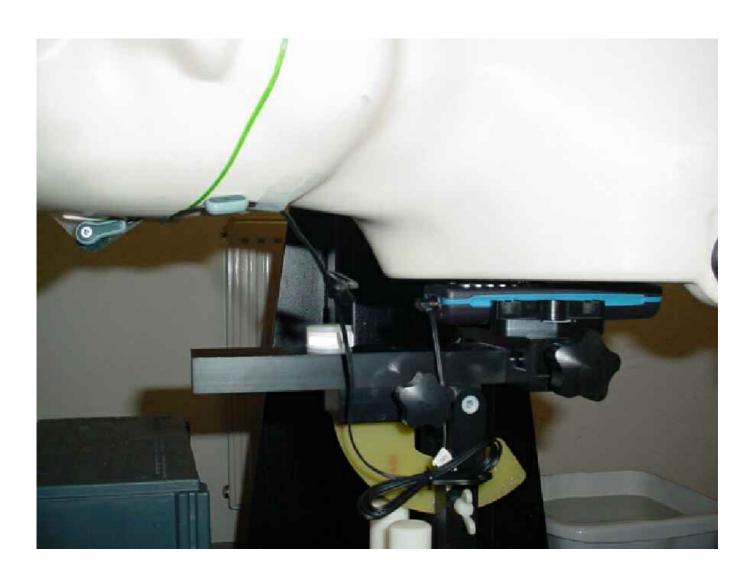


As of 2006-01-30 Page 78 of 86



Picture no. 38

Test position body worn front side touched



As of 2006-01-30 Page 79 of 86



Picture no. 39

Test position body worn front side touched

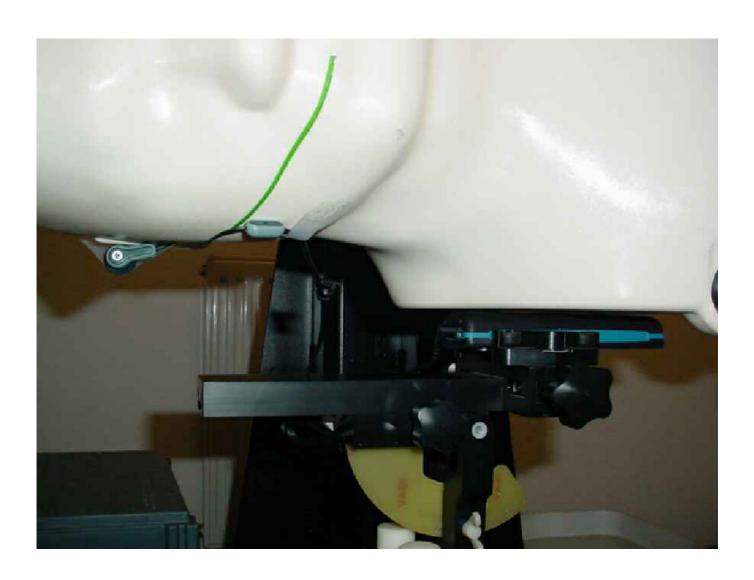


As of 2006-01-30 Page 80 of 86



Picture no. 40

Test position body worn rear side touched



As of 2006-01-30 Page 81 of 86



Picture no. 41

Test position body worn rear side touched



As of 2006-01-30 Page 82 of 86



Picture no. 42

Liquid depth 1900 MHz head simulating liquid



As of 2006-01-30 Page 83 of 86



Picture no. 43

Liquid depth 1900 MHz body simulating liquid



As of 2006-01-30 Page 84 of 86

CETECOM ICT Services GmbH

Test report no.: 2-4189-01-08/05



Annex 6 RF Technical Brief Cover Sheet acc. to RSS-102

1. COMPANY NUMBER: 267U

2. MODEL NUMBER: S45E45

3. MANUFACTURER: Siemens Home and Office Communication

4. TYPE OF EVALUATION:

| (| (a) | SAR Evaluation: | Device used | l in the | Vicinity | of the Human | ı Head |
|---|-----|------------------------|-------------|----------|----------|----------------|--------|
| | | | Device asec | | , , , | or the reminer | |

• Multiple transmitters: Yes ☐ No ☒

ullet Evaluated against exposure limits: General Public Use igtimes Controlled Use igthightarrow

• Duty cycle used in evaluation: 4 %

• Standard used for evaluation: RSS-102 Issue 2 (2005-11)

• SAR value: 0.063 W/kg. Measured ⊠ Computed □ Calculated □

(b) SAR Evaluation: Body-worn Device

• Multiple transmitters: Yes ☐ No ☒

ullet Evaluated against exposure limits: General Public Use igtimes Controlled Use igthightarrow

• Duty cycle used in evaluation: 4 %

• Standard used for evaluation: RSS-102 Issue 2 (2005-11)

• SAR value: 0.120 W/kg. Measured \square Computed \square Calculated \square

Annex 6.1 Declaration of RF Exposure Compliance

ATTESTATION: I attest that the information provided in Annex 6 is correct; that a Technical Brief was prepared and the information it contains is correct; that the device evaluation was performed or supervised by me; that applicable measurement methods and evaluation methodologies have been followed and that the device meets the SAR and/or RF exposure limits of RSS-102.

Signature: Date: 2006-01-30

NAME: Thomas Vogler

TITLE: Dipl.-Ing. (FH)

COMPANY: CETECOM ICT Services GmbH

As of 2006-01-30 Page 85 of 86



Annex 7 Calibration parameters

Calibration parameters are described in the additional document :

Appendix to test report report no. 2-4189-01-08/05' Calibration data, Phantom certificate and detail information of the DASY4 System

As of 2006-01-30 Page 86 of 86