

EUROFINS PRODUCT SERVICE GMBH

# SAR Test - Report

**SAR Compliance Test Report** 

GSM/GPRS mobile phone with GPS Pegasus

Test report no.:

G0M21003-2994-S-8

Curofins Product Service GmbH Storkower Str. 38c, 15526 Reichenwalde, Germany

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#### 1 General Information

#### 1.1 Notes

The results of this test report relate exclusively to the item tested as specified in chapter "Description of test item" and are not transferable to any other test items.

Eurofins Product Service GmbH is not responsible for any generalisations and conclusions drawn from this report. Any modification of the test item can lead to invalidity of test results and this test report may therefore be not applicable to the modified test item.

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#### **Operator:**

19.04.2010

Date

Eurofins -Lab. Name

Signature

#### Technical responsibility for area of testing:

Eurofins

19.04.2010

T. Jahn

p.p

Date

Name

B. Pudell

Signature



#### **1.2 Testing laboratory**

#### 1.2.1 Location

EUROFINS PRODUCT SERVICE GMBH Storkower Straße 38c D-15526 Reichenwalde b. Berlin Germany Telephone : +49 33631 888 00 Fax : +49 33631 888 660

#### **1.2.2** Details of accreditation status

#### DAR ACCREDITED TESTING LABORATORY

DAR-REGISTRATION NUMBER: DAT-P-268/08

#### **RECOGNIZED NOTIFIED BODY EMC** REGISTRATION NUMBER: BNetzA-bS EMV-07/61

#### **RECOGNIZED NOTIFIED BODY R&TTE** REGISTRATION NUMBER: BNetzA-bS-02/51-53

### FCC FILED TEST LABORATORY

REG.-NO. 96970

### A2LA ACCREDITED TESTING LABORATORY

CERTIFICATE NO. 1983.01

#### **BLUETOOTH QUALIFICATION TEST FACILITY (BQTF)** ACCREDITED BY BLUETOOTH QUALIFICATION REVIEW BOARD

#### INDUSTRY CANADA FILED TEST LABORATORY

REG. NO. IC 3470

**Statement:** The tests documented within this report are carried out in accordance with the scope of accreditation of test laboratory Eurofins Product Service GmbH.

#### 1.3 Details of approval holder

Name	: BARTEC GmbH
Street	: Max-Eyth-Straße 16
Town	: 97980 Bad Mergentheim
Country	: Germany
Telephone	: +49 7931 597 361
Fax	: +49 7931 597 183
Contact	: Herr B. Eckert



#### **1.4 Manufacturer**: (if applicable)

Name Street Town Country

- : Falcom Wireless Communications GmbH
- : Gewerbering 6
- : 98704 Langewiesen
- : Germany

#### 1.5 Application details

Date of receipt of application	: 25.03.2010
Date of receipt of test item	: 25.03.2010
Date of test	: 29.03.2010 - 01.04.2010

#### 1.6 Test item

FCC ID	: TBUPEGASUS
Description of test item	: GSM/GPRS mobile phone with GPS
Type identification	: Pegasus
Serial number	: 17-C110-1Q11 Identical prototype
Device category	: PCE (Licensed Portable Transmitter held to ear)

#### Technical data

<u>GSM / PCS</u> Frequency range	: <u>GSM 850 / GPRS</u>	PCS 1900 / / GPRS
TX Frequency range	: 824.2 - 848.8 MHz	1850.2 - 1909.9 MHz
RX Frequency range	: 869.2 - 893.8 MHz	1930.2 - 1989.8 MHz
Max. radiated output power	: 14,07 dBm (0,03 W)	27,96 dBm (0,63 W)
Power supply	: 3.7VDC Li-Ion Battery	
Antenna Tx	: integral	
Antenna RX	: integral	
Additional information	: Tx and Rx. antenna are the s This test sample was test	

This test sample was tested according FCC OET Bulletin 65, Supplement C, Edition 01-01 on the used Frequency band..



#### 1.7 Test Results

Max. SAR Measurement GSM (Head) Max. SAR Measurement GSM (Body) Max. SAR Measurement PCS (Head) Max. SAR Measurement PCS (Body) : 0.066 W/kg (averaged over 1 gram) : 0.045 W/kg (averaged over 1 gram) : 0.755 W/kg (averaged over 1 gram) : 0.455 W/kg (averaged over 1 gram)

This EUT has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528-2003, December 2003.

#### 1.8 Test standards

Standards	: -	IEEE Std. 1528-2003, December 2003
FCC Rule Part(s)	: -	FCC OET Bulletin 65, Supplement C, Edition 01-01



#### 2 Technical test

#### 2.1 Summary of test results

#### **Applicable Configuration**

Handset (Head)	Х
Handset (Body)	Х
Headset (Head)	
Body Worn Equipment	

EUT complies with the RF radiation exposure limits of the FCC as shown by the SAR measurement results. These measurements are taken to simulate the RF effects exposure under worst-case conditions. The EUT complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables. [1]

In case of multiple hotspots the secondary hotspots within 2 dB of the maximum SAR value will be recorded and displayed in the measurement plots. The secondary hotspots with a peak SAR value below 0.5 W/kg will not be measured by the system, due to the high margin to the limits.

#### 2.2 Test environment

Room temperature	: 22.′	1 - 22	.6 ° C
Liquid temperature	: 22.0	) - 22	.3 ° C
Relative humidity content	: 20		75 %
Air pressure	: 86		103 kPa
Details of power supply	: 3.7\	/DC	



#### 2.3 Test equipment utilized

No.	Measurement device:	Туре:	Manufacturer:
ETS 0449	Stäubli Robot	RX90B L	Stäubli
ETS 0450	Stäubli Robot Controller	CS/MBs&p	Stäubli
ETS 0451	DASY 4 Measurement Server		Schmid & Partner
ETS 0452	Control Pendant		Stäubli
ETS 0453	Compaq Computer	Pentium IV, 2 GHz,	Schmid & Partner
ETS 0454	Dabu Acquisition Electronics	DAE3V1	Schmid & Partner
ETS 0455	Dummy Probe		Schmid & Partner
ETS 0456	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner
ETS 0457	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner
ETS 0458	Dosimetric H-Field Probe	H3DV6	Schmid & Partner
ETS 0479	System Validation Kit	D300V3	Schmid & Partner
ETS 0480	System Validation Kit	D450V3	Schmid & Partner
ETS 0459	System Validation Kit	D900V2	Schmid & Partner
ETS 0460	System Validation Kit	D1800V2	Schmid & Partner
ETS 0461	System Validation Kit	D1900V2	Schmid & Partner
ETS 0462	System Validation Kit	D2450V2	Schmid & Partner
ETS 0463	Probe Alignment Unit	LBV2	Schmid & Partner
ETS 0464	SAM Twin phantom	V 4.0	Schmid & Partner
ETS 0513	Flat phantom	V 4.4	Schmid & Partner
ETS 0467	Oval flat phantom	ELI 4	Schmid & Partner
ETS 0465	Mounting Device	V 3.1	Schmid & Partner
ETS 0224a	Millivoltmeter	URV 5	Rohde & Schwarz
ETS 0219	Power sensor	NRV-Z2	Rohde & Schwarz
ETS 0268	RF signal generator	SMP 02	Rohde & Schwarz
ETS 0322	Insertion unit	URV5-Z4	Rohde & Schwarz
ETS 0466	Directional Coupler	HP 87300B	HP
ETS 0231	Radio Communication Tester	CMD65	Rohde & Schwarz
ETS 0484	Universal Radio Communication Tester	CMU 200	Rohde & Schwarz
ETS 0468	Network Analyzer 300 kHz to 3 GHz	8753C	Agilent
ETS 0469	Dielectric Probe Kit	85070C	Agilent



#### 2.4 Definitions

SA

#### 2.4.1 SAR

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy (*dW*) absorbed by (dissipated in) an incremental mass (*dm*) contained in a volume element (*dV*) of a given density ( $\rho_t$ ), expressed in watts per kilogram (W/kg).

$$\mathsf{R} = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho_t dV} \right) = \frac{\sigma}{\rho_1} |E|$$

where:

$$\frac{dW}{dt} = \int_{V} E \cdot J \, dV = \int_{V} \sigma E^2 dV$$

#### 2.4.2 Uncontrolled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category, and the general population/uncontrolled exposure limits apply to these devices. [2].

#### 2.4.3 Controlled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on methods to minimize such exposure risks. [2].



#### 2.5 Measurement System Description

#### 2.5.1 System Setup

Measurements are performed using the DASY4 automated dosimetric assessment system (figure 1) made by Schmid & Partner Engineering AG (SPEAG)in Zurich, Switzerland.



Figure 1

The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, ADconversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- An unit to operate the optical surface detector which is connected to the EOC.
- The Electro-optical converter (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the measurement server.
- The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows NT.
- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes (see Application Notes).
- System validation dipoles allowing to validate the proper functioning of the system.



#### 2.5.2 Phantom Description



(Figure 2.1)

The SAM twin phantom V4.0 (figure 2.1) is a fiberglass shell phantom with 2 mm shell thickness. It has three measurement areas:

- Left hand
- Right hand
- Flat phantom



The Oval flat phantom (ELI 4) (figure 2.2) is a fiberglass shell phantom with 2 mm thickness.

The phantom is integrated in a wooden table.

The bottom plate of the table contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids).

A cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible.

On the phantom top, three reference markers are provided to identify the phantom positions with respect to the robot.



#### 2.5.3 Tissue Simulating Liquids

The parameters of the tissue simulating liquid strongly influence the SAR. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE P1528-2003.

Tissue dielectric properties

	Head		Bo	ody
Frequency (MHz)	Relative Dielectric Constant (ε <sub>r</sub> )	Conductivity (σ) (S/m)	Relative Dielectric Constant (ε <sub>r</sub> )	Conductivity (σ) (S/m)
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
1450	40.5	1.20	54.0	1.30
1800	40.0	1.40	53.3	1.52
1900	40.0	1.40	53.3	1.52
2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73



#### 2.5.4 Device Holder

The DASY device holder (figure 3.1 and 3.2) is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The rotation centers for both scales is the ear opening. Thus the device needs no repositioning when changing the angles.



Figure 3.1

Figure 3.2

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\varepsilon = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



#### 2.5.5 Probes

The SAR measurements were conducted with the dosimetric probe ET3DV6 (figure 4), designed in the classical triangular configuration and optimized for dosimetric evaluation. [3] The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2<sup>nd</sup> order fitting. The approach is stopped at reaching the maximum.



Figure 4

#### Probe Specifications

Calibration:	In air from 10 MHz to 2.5 GHz In brain and muscle simulating tissue at Frequencies of 835 MHz, 900 MHz, 1800 MHz, 1900 MHz and 2450 MHz Calibration certificates please find attached.
Frequency:	10 MHz to > 3 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity:	$\pm$ 0.2 dB in HSL (rotation around probe axis) $\pm$ 0.4 dB in HSL (rotation normal probe axis)
Dynamic Range:	5 μW/g to > 100 mW/g;
Linearity:	± 0.2 dB
Dimensions:	Overall length: 330 m Tip length: 16 mm Body diameter: 12 mm Tip diameter: 6.8 mm Distance from probe tip to dipole centers: 2.7 mm
Application:	General dosimetry up to 3 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms



#### 2.6 Test System Specification

<b>Positioner</b> Robot: Repeatability: No. of axis:	Stäubli Animation Corp. Robot Model: RX90B L 0.02 mm 6
Data Acquisition Electronic (DAE)	System
Processor:	Pentium IV
Clock Speed:	2.0 GHz
Operating System:	Windows 2000
Data Card:	DASY4 PC-Board
Data Converter	
Features:	Signal Amplifier, multiplexer, A/D converter, & control logic
Software:	DASY4 software
Connecting Lines:	Optical downlink for data and status info.
5	Optical uplink for commands and clock
DO Interface Cond	
PC Interface Card Function:	24 bit (64 MHz) DSP for real time processing
Function.	Link to DAE3
	16 bit A/D converter for surface detection system
	serial link to robot
	direct emergency stop output for robot
E-Field Probes	
Model:	ET3DV6 SN1711
Construction:	Triangular core fiber optic detection system
Frequency:	10 MHz to 6 GHz
Linearity:	± 0.2 dB (30MHz to 3 GHz)
Phantom	
Phantom 1:	Oval flat phantom (ELI 4)
Shell Material:	Fiberglass
	$2.0 \pm 0.2 \text{ mm}$
Thickness:	$2.0 \pm 0.2$ mm
Phantom 2:	SAM Twin Phantom (V4.0)
Shell Material:	Fiberglass
Thickness:	$2.0 \pm 0.2 \text{ mm}$
THENIC35.	



#### 2.7 Measurement Procedure

The evaluation was performed using the following procedure:

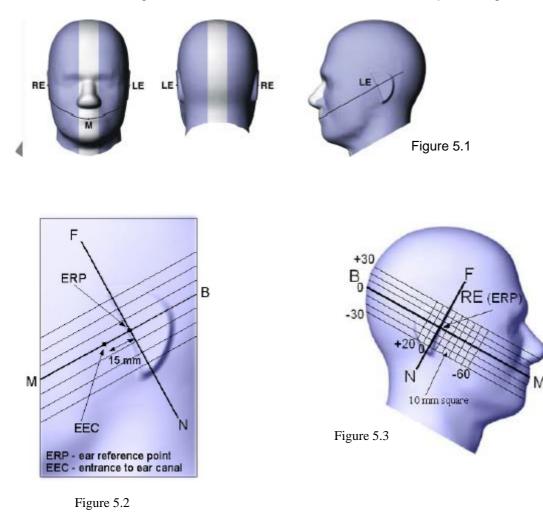
- 1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value.
- 2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9 mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 10 mm x 10 mm.
- 3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 30 mm x 30 mm x 30 mm (fine resolution volume scan, zoom scan) was assessed by measuring 5 x 5 x 5 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure:
  - a. The data at the surface was extrapolated, since the center of the dipoles is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2 mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
  - b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g or 10 g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions) [4] [5]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
  - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
- 4. The SAR reference value, at the same location as procedure # 1, was re-measured. If the value changed by more than 5 %, the evaluation is repeated.



#### 2.8 Reference Points

#### 2.8.1 Ear Reference Points

Figure 5.1 shows the front, back and side vies of SAM. The point "M" is the reference point for the center of mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15 mm posterior to the entrance to ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 5.2. The plane passing through the two ear reference points and M is defined as the Reference Plane. The line N-F (Neck-Front) perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 5.3). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines should be marked on the external phantom shell to facilitate handset positioning. Posterior to the N-F line, the thickness of the N-F line, the ear is truncated as illustrated in Figure 5.2. The ear truncation is introduced to avoid the handset from touching the ear lobe, which can cause unstable handset positioning at the cheek. [6]





#### 2.8.2 Handset Reference Points

Two imaginary lines on the handset were defined: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width wt of the handset at the level of the acoustic output (point A on Figures 6.1 and 6.2), and the midpoint of the width wb of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 6.1). The two lines intersect at point A. For many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. The vertical centerline is not necessarily parallel to the front face of the handset (see Figure 6.2), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets. [6]

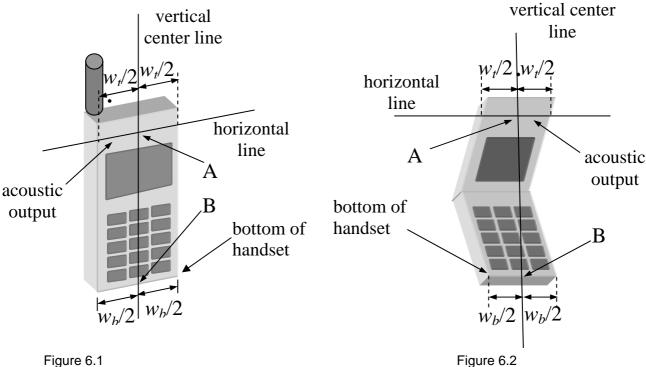


Figure 6.1



#### 2.9 Test Positions

#### 2.9.1 "Cheek" / "Touch" Position

The EUT was positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.

The EUT was translated towards the phantom along the line passing through RE and LE until the handset touches the pinna.

While maintaining the handset in this plane, the EUT was rotated it around the LE-RE line until the vertical centerline was in the plane normal to MB-NF including the line MB (called the reference plane).

The EUT was rotated around the vertical centerline until the handset (horizontal line) was symmetrical with respect to the line NF.

While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, the EUT was rotated about the line NF until any point on the handset was in contact with a phantom point below the pinna (cheek). [6] See Figure 7.



Figure 7



#### 2.9.2 "Tilted" Position

The EUT was in "cheek position".

While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.

The EUT was rotated around the horizontal line by 15 degrees.

While maintaining the orientation of the handset, the EUT was moved towards the phantom on a line passing through RE and LE until any part of the handset touched the ear. The tilted position is obtained when the contact is on the pinna. If the contact was at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset would be reduced. In this case, the tilted position is obtained if any part of the handset was in contact with the pinna as well as a second part of the handset was in contact with the back of the head). [6] See Figure 8.



Figure 8



#### 2.9.3 Belt Clip/Holster Configuration

Test configurations for body-worn operated EUTs are carried out while the belt-clip and/or holster is attached to the EUT and placed against a flat phantom in a regular configuration (see Figure 9). An EUT with a headset output is tested with a headset connected to the device.

Body dielectric parameters are used.

There are two categories for accessories for body-worn operation configurations:

- 1. accessories not containing metallic components
- 2. accessories containing metallic components.

When the EUT is equipped with accessories not containing metallic components the tests are done with the accessory that dictates the closest spacing to the body. For accessories containing metallic parts a test with each one is implemented. If the multiple accessories share an identical metallic component (e.g. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that has the closest spacing to the body is tested.

In case that a EUT authorized to be body-worn is not supplied or has no options to be operated with any accessories, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters operating in front of a person's face (e.g. push-to-talk configurations) are tested for SAR compliance with the front of the device positioned to face the flat platform. SAR Compliance tests for shoulder, waist or chest-worn transmitters are carried out with the accessories including headsets and microphones attached to the device and placed against a flat phantom in a regular configuration.

The SAR measurements are performed to investigate the worst-case positioning. This is documented and used to perform Body SAR testing. [2].



Figure 9



#### 2.9.4 Headset Configuration

Headsets which have their radiating structure in close proximity to the head are measured according to the following conditions.

- Head tissue liquid is used.
- The EUT is positioned on the surface of the head of phantom according the picture below. Right and left position is tested according to the normal use (see figure 10).
- Additional metallic parts like clips or others are subject of testing, too.



Figure 10

Headsets which have their radiating structure in close proximity to the body are tested as body worn equipment.



#### 2.10 Measurement uncertainty

The uncertainty budget has been determined for the DASY4 system performance check according to IEEE Std. 1528-2003 December 2003.

	Tol.	Prob.	Div.	( <sup>c</sup> i) <sup>1</sup>	Std. unc.	( <sup>v</sup> i) <sup>2</sup>
Error Description	(± %)	dist.		(1 g)	(1 g) (± %)	
Measurement System						
Probe Calibration	4.8	N	1	1	4.8	œ
Axial Isotropy	4.7	R	<sup>∨</sup> З	0.7	1.9	œ
Hemispherical Isotropy	9.6	R	<sup>√</sup> 3	0.7	3.9	$\infty$
Boundary Effects	1.0	R	<sup>۷</sup> З	1	0.6	$\infty$
Linearity	4.7	R	<sup>∨</sup> З	1	2.7	$\infty$
System Detection Limit	1.0	R	<sup>۷</sup> З	1	0.6	$\infty$
Readout Electronics	1.0	N	1	1	1.0	$\infty$
Response Time	0.8	R	<sup>۷</sup> З	1	0.5	$\infty$
Integration Time	2.6	R	<sup>۷</sup> З	1	1.5	$\infty$
RF Ambient Conditions	3.0	R	<sup>v</sup> 3	1	1.7	$\infty$
Probe Positioner	0.4	R	<sup>√</sup> 3	1	0.2	$\infty$
Probe Positioning	2.9	R	<sup>∨</sup> З	1	1.7	$\infty$
Algorithms for Max. SAR Eval.	1.0	R	<sup>۷</sup> З	1	0.6	$\infty$
Test Sample Related						
Device Positioning	2.9	Ν	1	1	2.9	145
Device Holder	3.6	N	1	1	3.6	5
Power Drift	5.0	R	<sup>∨</sup> 3	1	2.9	$\infty$
Phantom and Setup						
Phantom Uncertainty	4.0	R	<sup>√</sup> 3	1	2.3	$\infty$
Liquid Conductivity (target)	5.0	R.	<sup>۷</sup> З	0.64	1.8	$\infty$
Liquid Conductivity (meas.)	2.6	N	1	0.64	1.7	$\infty$
Liquid Permittivity (target)	5.0	R	<sup>۷</sup> З	0.6	1.7	ø
Liquid Permittivity (meas.)	3.8	Ν	1	0.6	2.3	ø
Combined Standard Uncertainty					10.4	330
Expanded Uncertainty kp = 2						
Coverage Factor for 95 %					20.8	

The budget is valid for the frequency range 300 MHz - 3 GHz and represent a worst case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



#### 3 Tissue and System Verification

#### 3.1 Tissue Verification

Dielectric parameters of the simulating liquids were verified using a Dielectric Probe Kit Agilent 85070D to a tolerance of  $\pm$  5 %.

#### Room Temperature: 22.1 - 22.6 ° C

		Measured Tissue Parameters					
	900 M	Hz Head	1900 MHz Head				
	Target	Measured	Target	Measured			
Date:		31.03.2010		29.03.2010			
Liquid Temperature: °C		22,1		22,0			
Dielectric Constant: ε	41,5	40,5	40,0	39,9			
Conductivity: σ	0,97	0.944	1,40	1,42			

Room Temperature: 22.1 - 22.6 ° C

	Measured Tissue Parameters					
	900 MH	z Muscle	1900 MHz Muscle			
	Target Measured		Target	Measured		
Date:		30.03.2010		01.04.2010		
Liquid Temperature: ° C		22,1		22,1		
Dielectric Constant: ε	55,0	54,1	53,3	51,9		
Conductivity: σ	1,05	1,01	1,52	1,58		



#### 3.2 System Verification

Prior to the assessment, the system was verified by using a 1900 MHz validation dipole. Power level of 250 mW was supplied to the dipole antenna placed under the flat section of SAM Phantom. This system validation is valid for a frequency range of 1900  $\pm$  100 MHz.

The system was verified to a tolerance of  $\pm$  10 %.

Liquid Temperature:	22.0 - 22.3 ° C
Room Temperature:	22.1 - 22.6 ° C
Liquid Depth:	>15.5 cm

System Dipole Validation Target & Measurement						
Date	System Validation Kit:	Liquid	Targeted SAR 1 g (mW/g)	Measured SAR 1 g (mW/g)	Deviation (%)	
31.03.2010	D900V2 SN164	900 MHz Head	10,2	10,12	-0,78	
30.03.2010	D900V2 SN164	900 MHz Muscle	11,2	11,16	-0,35	
29.03.2010	D1900V2 SN5d025	1900 MHz Head	40,4	41,6	2,97	
01.04.2010	D1900V2 SN5d025	1900 MHz Muscle	45,6	42,4	-7,02	

Comment: Please find attached the measurement plots.



#### 4 Test Results

#### Procedures Used To Establish Test Signal

The EUT was placed into simulated call mode (e.g. AMPS, Cellular CDMA & PCS CDMA modes) using manufacturers test codes. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [2]. The actual transmission is activated through a base station simulator or similar when test modes are not available or inappropriate for testing the EUT.

The EUT is rechargeable battery operated. The battery used for the SAR measurements was completely charged. The device was tested at full power verified by implementing conducted output power measurements. For confirming of the output power it was tested before and after each SAR measurement. The test was repeated if a conducted power deviation of more than 5 % occurred.

Frequency band:	GSM 850
Mixture Type:	900 MHz Head
Date:	31.03.2010
Liquid Temperature:	22.0 - 22.3 ° C

Room Temperature: 22.1 - 22.6 °C

	Frequency			Antenna	Phantom	Test Position	SAR
MHz	Channel	Modulation	dBm	Pos.	Section	0 mm	(W/kg)
824,2	128	GSM	-0.113	Integral	Left Ear	Cheek	0.038
836,4	189	GSM	-0.170	Integral	Left Ear	Cheek	0.050
848,8	251	GSM	-0.129	Integral	Left Ear	Cheek	0.066
848,8	251	GSM	-0.093	Integral	Left Ear	Tilt	0.020
836,4	189	GSM	-0.151	Integral	Right Ear	Cheek	0.051
848,8	251	GSM	-0.146	Integral	Right Ear	Cheek	0.062
848,8	251	GSM	-0.178	Integral	Right Ear	Tilt	0.015

Mixture Type:	900 MHz Muscle
Date:	30.03.2010
Liquid Temperature:	22.0 - 22.3 ° C

Room Temperature: 22.1 - 22.6 ° C

	Frequency		Frequency		Frequency		Power Drift	Antenna	Phantom	Test Position	SAR
MHz	Channel	Modulation	dBm	Pos.	Section	0 mm	(W/kg)				
824,2	128	GPRS	-0.121	Integral	Flat	Front / 0mm	0.028				
836,4	189	GPRS	-0.146	Integral	Flat	Back / 5mm	0.00118				
836,4	189	GPRS	-0.169	Integral	Flat	Front / 0mm	0.030				
848,8	251	GPRS	-0.151	Integral	Flat	Front / 0mm	0.045				



Frequency band:	PCS 1900
Mixture Type:	1900 MHz Head
Date:	29.03.2010
Liquid Temperature:	22.0 - 22.3 ° C

Room Temperature: 22.1 - 22.6 °C

	Frequency		Power Drift	Antenna	Phantom	Test Position	SAR
MHz	Channel	Modulation	dBm	Pos.	Section	0 mm	(W/kg)
1880,0	661	GSM	-0.188	Integral	Left Ear	Cheek	0.427
1909,8	810	GSM	-0.173	Integral	Left Ear	Cheek	0.579
1909,8	810	GSM	-0.130	Integral	Left Ear	Tilted	0.280
1850,2	512	GSM	-0.158	Integral	Right Ear	Cheek	0.457
1880,0	661	GSM	-0.139	Integral	Right Ear	Cheek	0.540
1909,8	810	GSM	-0.008	Integral	Right Ear	Cheek	0.755
1909,8	810	GSM	-0.142	Integral	Right Ear	Tilted	0.403

Note: Upper and lower frequencies were measured at the worst position.

Mixture Type:	
Date:	
Liquid Temperature:	

1900 MHz Muscle 01.04.2010 22.0 - 22.3 ° C

Room Temperature: 22.1 - 22.6 ° C

Frequency		Power Drift Antenna		Phantom	Test Position	SAR	
MHz	Channel	Modulation	dBm	Pos.	Section		(W/kg)
1850,2	512	GPRS	-0.149	Integral	Flat	Front / 0mm	0.248
1880,0	661	GPRS	-0.190	Integral	Flat	Front / 0mm	0.389
1909.8	810	GPRS	-0.094	Integral	Flat	Back / 5mm	0.229
1909.8	810	GPRS	-0.184	Integral	Flat	Front / 0mm	0.455



Limits:

	SAR (W/kg)					
Exposure Limits	Uncontrolled Exposure/General Population Environment			Controlled Exposure/Occupational Environment		
Region	Australia	US	EU	Australia	US	EU
Spatial Average SAR (averaged over the whole body)	0.08	0.08	0.08	0.40	0.40	0.40
Spatial Peak SAR (averaged over any 1 g of tissue)	2.00	1.60	2.00	10.0	8.00	10.0
Spatial Peak SAR (Hands, Feet, Ankles, Wrist) (averaged over any 10 g of tissue)	4.00	4.00	4.00	20.0	20.0	20.0

Notes:

- 1. Test data represent the worst case SAR value and test procedure used are according to OET Bulletin 65, Supplement C (01-01).
- 2. All modes of operation were investigated.



#### 5 References

- [1] ANSI/IEEE C95.3 1991, *IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic fields, 300 kHz to 100 GHz,* New York: IEEE, Aug. 1992
- [2] Federal Communications Commission, OET Bulletin 65 (Edition 97-01), Supplement C (Edition 01-01), *Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields*, July 2001.
- [3] T. Schmid, O. Egger, N. Kuster, *Automated E-field scanning system for dosimetric assessments,* IEEE Transaction on Microwave Theory and Techniques, vol. 44, Jan. 1996, pp. 105-113.
- [4] W. Gander, *Computer mathematics*, Birkhaeuser, Basel, 1992.
- [5] W.H. Press, S.A. Teukolsky, W.T. Vetterling, and B.P. Flannery, *Numerical Recipes in C*, The Art of Scientific Computing, Second edition, Cambridge University Press, 1992.
- [6] IEEE Standards Coordinating Committee 34 IEEE Std. 1528-2003, December 2003 Recommended Practice for Determining the Peak Spatial-Average Absorption Rate (SAR in the Human Body Due to Wireless Communications Devices: Experimental Techniques.
- [7] DASY4 *Dosimetric Assessment System Manual*; Draft; September 6, 2002; Schmid & Partner Engineering AG



Annex A

#### **Calibration Certificate**

Note:

The calibration cycle for SAR field probes and related equipment is determined to one year. According to Eurofins's internal quality management instruction based on EN 17025 the calibration cycle for other test equipment is determined to 2 years. Additionally, Eurofins has prolonged the calibration interval for SPEAG System Validation Dipoles by two additional years. These QM procedures are acknowledged by the accreditation bodies mentioned on page 3 of this report during several accreditation audits.

#### Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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CALIBRATION CERTIFICATE

#### Client Eurofins

Certificate No: D900V2-164\_Sep09

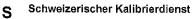
#### Object D900V2 - SN: 164 QA CAL-05.v7 Calibration procedure(s) Calibration procedure for dipole validation kits Calibration date: September 14, 2009 Condition of the calibrated item In Tolerance This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility; environment temperature (22 ± 3)°C and humidity < 70%. Calibration Equipment used (M&TE critical for calibration) Primary Standards ID # Cal Date (Certificate No.) Scheduled Calibration Power meter EPM-442A GB37480704 08-Oct-08 (No. 217-00898) Oct-09 Power sensor HP 8481A US37292783 08-Oct-08 (No. 217-00898) Oct-09 Reference 20 dB Attenuator SN: 5086 (20g) 31-Mar-09 (No. 217-01025) Mar-10 Type-N mismatch combination SN: 5047.2 / 06327 31-Mar-09 (No. 217-01029) Mar-10 Reference Probe ES3DV3 SN: 3205 26-Jun-09 (No. ES3-3205 Jun09) Jun-10 DAE4 SN: 601 07-Mar-09 (No. DAE4-601\_Mar09) Mar-10 Secondary Standards ID # Check Date (in house) Scheduled Check MY41092317 Power sensor HP 8481A 18-Oct-02 (in house check Oct-07) In house check: Oct-09 RF generator R&S SMT-06 100005 4-Aug-99 (in house check Oct-07) In house check: Oct-09 Network Analyzer HP 8753E US37390585 S4206 18-Oct-01 (in house check Oct-08) In house check: Oct-09 Name Eunction Signature Calibrated by: Jeton Kastrati Laboratory Technician Approved by: Katja Pokovic Technical Manager Issued: September 15, 2009

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

#### Calibration Laboratory of

Schmid & Partner **Engineering AG** Zeughausstrasse 43, 8004 Zurich, Switzerland





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#### **Glossary:**

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

#### Additional Documentation:

d) DASY4/5 System Handbook

#### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

#### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V5.0
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V4.9	
Distance Dipole Center - TSL	15 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	900 MHz ± 1 MHz	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,

## Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	41.5	0.97 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	40.4 ± 6 %	0.96 mho/m ± 6 %
Head TSL temperature during test	(21.7 ± 0.2) °C		

#### SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	2.79 mW / g
SAR normalized	normalized to 1W	11.2 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	11.2 mW /g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	condition	· <u></u>
SAR measured	250 mW input power	1.78 mW / g
SAR normalized	normalized to 1W	7.12 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	7.13 mW /g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

Body TSL parameters The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	55.0	1.05 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	52.7 ± 6 %	1.06 mho/m ± 6 %
Body TSL temperature during test	(22.0 ± 0.2) °C		

#### SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	2.84 mW / g
SAR normalized	normalized to 1W	11.4 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	11.2 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	· · · · · · · · · · · · · · · · · · ·
SAR measured	250 mW input power	1.83 mW / g
SAR normalized	normalized to 1W	7.32 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	7.24 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### Appendix

#### Antenna Parameters with Head TSL

Impedance, transformed to feed point	50.1 Ω - 7.4 jΩ
Return Loss	- 22.7 dB

#### Antenna Parameters with Body TSL

Impedance, transformed to feed point	46.0 Ω - 8.7 jΩ
Return Loss	- 20.0 dB

#### **General Antenna Parameters and Design**

Electrical Delay (one direction)	1.410 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

#### Additional EUT Data

Manufactured by	SPEAG
Manufactured on	May 16, 2002

#### **DASY5 Validation Report for Head TSL**

#### Date/Time: 14.09.2009 09:39:14

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 900 MHz; Type: D900V2; Serial: D900V2 - SN:164

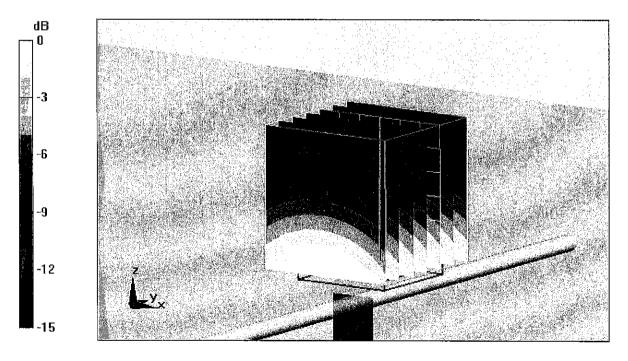
Communication System: CW-900; Frequency: 900 MHz; Duty Cycle: 1:1 Medium: HSL 900 MHz Medium parameters used: f = 900 MHz;  $\sigma = 0.96$  mho/m;  $\epsilon_r = 40.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Probe: ES3DV3 SN3205; ConvF(5.88, 5.88, 5.88); Calibrated: 26.06.2009
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 07.03.2009
- Phantom: Flat Phantom 4.9L; Type: QD000P49AA; Serial: 1001
- Measurement SW: DASY 5, V5.0 Build 120; SEMCAD X Version 13.4 Build 45

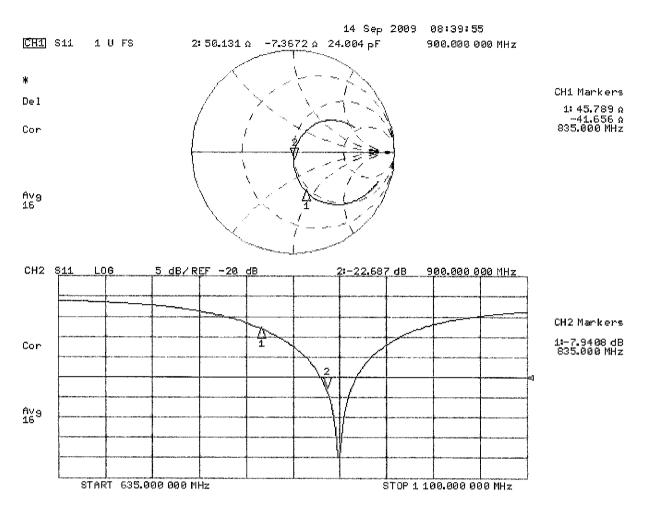
## Pin=250mW; dip=15mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 59.9 V/m; Power Drift = -0.013 dB Peak SAR (extrapolated) = 4.23 W/kg SAR(1 g) = 2.79 mW/g; SAR(10 g) = 1.78 mW/g Maximum value of SAR (measured) = 3.28 mW/g



 $<sup>0 \,</sup> dB = 3.28 \, mW/g$ 

#### Impedance Measurement Plot for Head TSL



#### **DASY5 Validation Report for Body**

#### Date/Time: 14.09.2009 10:47:13

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 900 MHz; Type: D900V2; Serial: D900V2 - SN:164

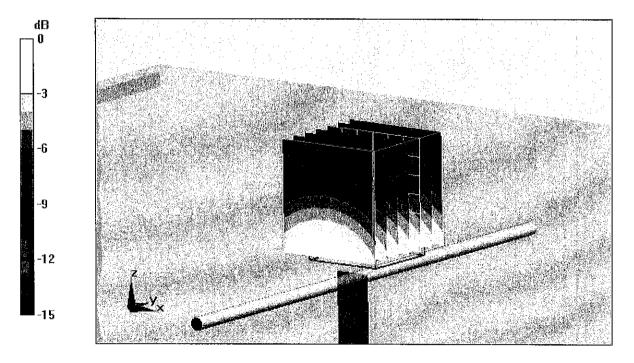
Communication System: CW-900; Frequency: 900 MHz; Duty Cycle: 1:1 Medium: MSL900 Medium parameters used: f = 900 MHz;  $\sigma = 1.06$  mho/m;  $\epsilon_r = 52.7$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Probe: ES3DV3 SN3205; ConvF(5.81, 5.81, 5.81); Calibrated: 26.06.2009
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 07.03.2009
- Phantom: Flat Phantom 4.9L; Type: QD000P49AA; Serial: 1001
- Measurement SW: DASY 5, V5.0 Build 120; SEMCAD X Version 13.4 Build 45

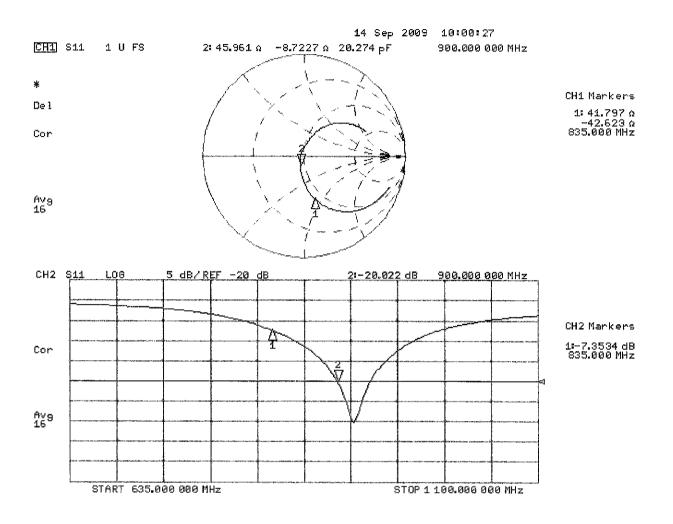
# Pin=250mW; dip=15mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 57.7 V/m; Power Drift = 0.00836 dBPeak SAR (extrapolated) = 4.23 W/kgSAR(1 g) = 2.84 mW/g; SAR(10 g) = 1.83 mW/gMaximum value of SAR (measured) = 3.31 mW/g



 $0 \, dB = 3.31 \, mW/g$ 

#### Impedance Measurement Plot for Body TSL



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#### **Eurofins** Client

Certificate No: D1900V2-5d025-Sep09

## **CALIBRATION CERTIFICATE**

Object	D1900V2 - SN: 5d025			
Calibration procedure(s)	QA CAL-05.v7 Calibration proce	dure for dipole validation kits	· .	
Calibration date:	September 15, 20	009		
Condition of the calibrated item	In Tolerance			
The measurements and the uncert	This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^{\circ}$ C and humidity < 70%.			
Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration	
Power meter EPM-442A	GB37480704	08-Oct-08 (No. 217-00898)	Oct-09	
Power sensor HP 8481A	US37292783	08-Oct-08 (No. 217-00898)	Oct-09	
Reference 20 dB Attenuator	SN: 5086 (20g)	31-Mar-09 (No. 217-01025)	Mar-10	
Type-N mismatch combination	SN: 5047.2 / 06327	31-Mar-09 (No. 217-01029)	Mar-10	
Reference Probe ES3DV3	SN: 3205	26-Jun-09 (No. ES3-3205_Jun09)	Jun-10	
DAE4	SN: 601	07-Mar-09 (No. DAE4-601_Mar09)	Mar-10	
Secondary Standards	ID#	Check Date (in house)	Scheduled Check	
Power sensor HP 8481A	MY41092317	18-Oct-02 (in house check Oct-07)	In house check: Oct-09	
RF generator R&S SMT-06	100005	4-Aug-99 (in house check Oct-07)	In house check: Oct-09	
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (in house check Oct-08)	In house check: Oct-09	
	Name	Function	Signature	
Calibrated by:	Jeton Kastrati	Laboratory Technician	7 11	
Approved by:	Katja Pokovic	Technical Manager	All the	
This calibration certificate shall not	t be reproduced except in	full without written approval of the laboratory.	Issued: September 16, 2009	

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Accreditation No.: SCS 108

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#### Glossarv:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361. "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields: Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions". Supplement C (Edition 01-01) to Bulletin 65

#### Additional Documentation:

d) DASY4/5 System Handbook

#### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

#### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V5.0
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V5.0	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	1900 MHz ± 1 MHz	

Head TSL parameters The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	40.0	1.40 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	40.8 ± 6 %	1.45 mho/m ± 6 %
Head TSL temperature during test	(21.5 ± 0.2) °C		

#### SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	condition	
SAR measured	250 mW input power	10.3 mW / g
SAR normalized	normalized to 1W	41.2 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	40.6 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	5.39 mW / g
SAR normalized	normalized to 1W	21.6 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	21.4 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### **Body TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	53.3	1.52 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	53.9 ± 6 %	1.57 mho/m ± 6 %
Body TSL temperature during test	(22.0 ± 0.2) °C		

#### SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	9.94 mW / g
SAR normalized	normalized to 1W	39.8 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	39.1 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	
SAR measured	250 mW input power	5.23 mW / g
SAR normalized	normalized to 1W	20.9 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	20.8 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### Appendix

#### Antenna Parameters with Head TSL

Impedance, transformed to feed point	50.3 Ω + 5.9 jΩ
Return Loss	- 24.6 dB

#### Antenna Parameters with Body TSL

Impedance, transformed to feed point	45.2 Ω + 5.5 jΩ
Return Loss	- 22.3 dB

#### General Antenna Parameters and Design

Electrical Delay (one direction)	1.202 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

#### Additional EUT Data

Manufactured by	SPEAG
Manufactured on	July 29, 2002

#### **DASY5 Validation Report for Head TSL**

#### Date/Time: 15.09.2009 14:19:40

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d025

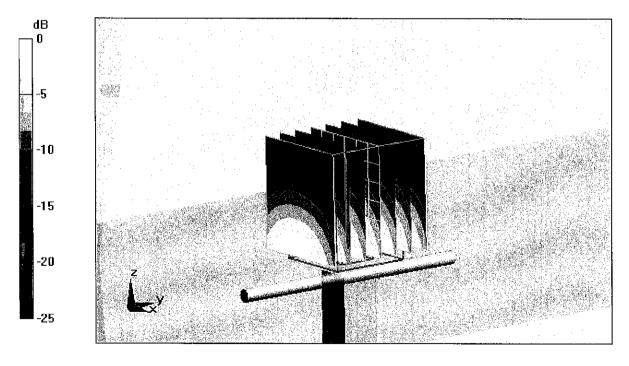
Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1 Medium: HSL U11 BB Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.45 mho/m;  $\epsilon_r$  = 40.9;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

- Probe: ES3DV3 SN3205; ConvF(5.09, 5.09, 5.09); Calibrated: 26.06.2009
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 07.03.2009
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001
- Measurement SW: DASY 5, V5.0 Build 120; SEMCAD X Version 13.4 Build 45

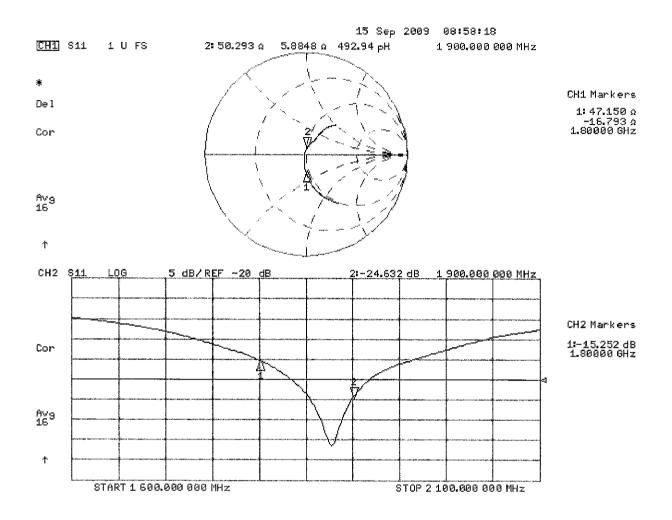
#### Pin = 250 mW; dip = 10 mm/Zoom Scan (dist=3.0 mm, probe 0deg) (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mmReference Value = 97 V/m; Power Drift = 0.025 dB Peak SAR (extrapolated) = 18.8 W/kg **SAR(1 g) = 10.3 mW/g; SAR(10 g) = 5.39 mW/g** Maximum value of SAR (measured) = 12.7 mW/g



0 dB = 12.7 mW/g

#### Impedance Measurement Plot for Head TSL



#### **DASY5 Validation Report for Body TSL**

#### Date/Time: 15.09.2009 12:45:32

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d025

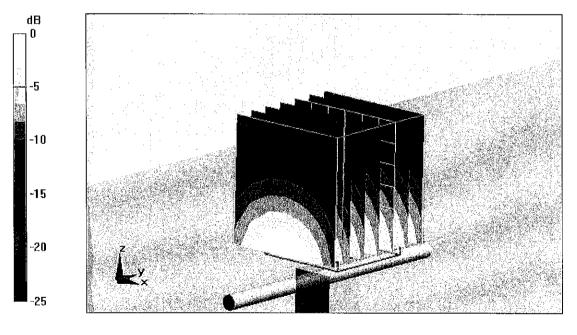
Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1 Medium: MSL U10 BB Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.57 mho/m;  $\epsilon_r$  = 53.9;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY5 (IEEE/IEC)

#### DASY5 Configuration:

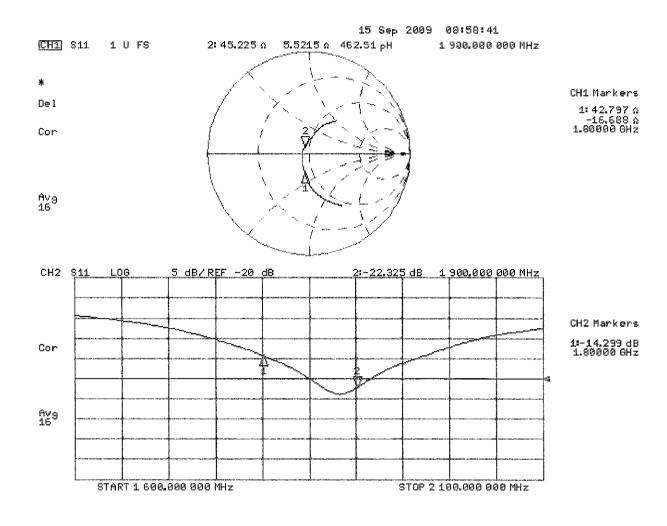
- Probe: ES3DV3 SN3205; ConvF(4.59, 4.59, 4.59); Calibrated: 26.06.2009
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 07.03.2009
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1001
- Measurement SW: DASY 5, V5.0 Build 120; SEMCAD X Version 13.4 Build 45

#### Pin = 250 mW; dip = 10 mm/Zoom Scan (dist=3.0mm, probe 0deg) (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 94.1 V/m; Power Drift = 0.00862 dB Peak SAR (extrapolated) = 16.9 W/kg **SAR(1 g) = 9.94 mW/g; SAR(10 g) = 5.23 mW/g** Maximum value of SAR (measured) = 12.5 mW/g



 $0 \, dB = 12.5 \, mW/g$ 



#### Impedance Measurement Plot for Body TSL

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S

Client Eurofins			Certificate No: DA	E3-522_Sep09
CALERATION	EBILECATE		1993 <b>9</b> 93 - 1993 - 1993	
Object	DAE3 - SD 000 D(	)3 AA - SN: 522	, <b>1</b> 7 - 16	
Calibration procedure(s)	QA CAL-06:v20 Calibration proced	ure for the data acc	uisition electroni	cs (DAE)
Calibration date:	September 11, 20	09		
Condition of the calibrated item	In Tolerance			
This calibration certificate docum The measurements and the unce	•			
All calibrations have been conduc	cted in the closed laboratory	facility: environment tempe	erature (22 ± 3)°C and	humidity < 70%.
Calibration Equipment used (M&	TE critical for calibration)			
   Primary Standards	ID #	Cal Date (Certificate No.)		Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	30-Sep-08 (No: 7670)		Sep-09
Secondary Standards	ID #	Check Date (in house)		Scheduled Check
Calibrator Box V1.1	SE UMS 006 AB 1004	05-Jun-09 (in house chec	k)	In house check: Jun-10
Calibrated by:	Name Dominique Staffen	Function Technician		Signature
Approved by:	Fin-Bomholt	, R&D Directo		i. V. Blue
This calibration certificate shall n	ot be reproduced except in t	fuli without written approval	of the laboratory.	Issued: September 11, 2009

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#### Glossary

DAE Connector angle

#### data acquisition electronics

information used in DASY system to align probe sensor X to the robot coordinate system.

#### Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
  - Channel separation: Influence of a voltage on the neighbor channels not subject to an . input voltage.
  - AD Converter Values with inputs shorted: Values on the internal AD converter • corresponding to zero input voltage
  - Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
  - Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - Input resistance: DAE input resistance at the connector, during internal auto-zeroing • and during measurement.
  - Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
  - *Power consumption:* Typical value for information. Supply currents in various operating modes.

#### DC Voltage Measurement A/D - Converter Resolution nominal

A/D - Converter Resc	nution nominal			
High Range:	1LSB =	6.1µV,	full range =	-100+300 mV
Low Range:	1LSB =	61nV,	full range =	<b>-1</b> +3mV
DASY measurement	parameters: Aut	o Zero Time: 3	sec; Measuring t	ime: 3 sec

Calibration Factors	x	Y	Z
High Range	404.267 ± 0.1% (k=2)	403.935 ± 0.1% (k=2)	$404.757 \pm 0.1\%$ (k=2)
Low Range	3.96803 ± 0.7% (k=2)	3.96066 ± 0.7% (k=2)	3.97594 ± 0.7% (k=2)

#### **Connector Angle**

Connector Angle to be used in DASY system	58.5°±1°
	1 00.0 II

#### Appendix

#### 1. DC Voltage Linearity

High Range		Reading (μV)	Difference (µV)	Error (%)
Channel X	+ Input	199998.6	-2.60	-0.00
Channel X	+ Input	20001.59	0.69	0.00
Channel X	- Input	-19995.96	3.44	-0.02
Channel Y	+ Input	200009.2	-0.68	-0.00
Channel Y	+ Input	19998.42	-1.58	-0.01
Channel Y	- Input	-19998.42	0.88	-0.00
Channel Z	+ Input	200004.8	-4.55	-0.00
Channel Z	+ Input	19996.32	-3.28	-0.02
Channel Z	- input	-19999.65	0.00	0.00

Low Range		Reading (μV)	Difference (µV)	Error (%)
Channel X	+ Input	1998.4	-1.49	-0.07
Channel X	+ Input	198.87	-1.03	-0.52
Channel X	- Input	-201.97	-1.87	0.94
Channel Y	+ Input	2000.2	0.29	0.01
Channel Y	+ Input	197.51	-2.49	-1.24
Channel Y	- Input	-201.79	-1.79	0.89
Channel Z	+ Input	1999.7	-0.29	-0.01
Channel Z	+ Input	198.23	-1.87	-0.93
Channel Z	- Input	-202.49	-2.49	1,25

2. Common mode sensitivity DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (µV)
Channel X	200	-2.99	-4.10
	- 200	5.34	3.71
Channel Y	200	-0.76	-0.83
	- 200	0.13	0.03
Channel Z	200	16.10	16.06
	- 200	-17.39	-17.89

#### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Υ (μV)	Channel Ζ (μV)
Channel X	200	-	1.72	-0.87
Channel Y	200	2.21	-	2.42
Channel Z	200	1.86	0.10	-

#### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15737	16238
Channel Y	15733	16377
Channel Z	16058	16346

#### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec Input  $10M\Omega$ 

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	0.42	-1.29	1.94	0.70
Channel Y	-1.21	-2.94	0.12	0.56
Channel Z	-0.45	-2.05	0.91	0.52

#### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

#### 7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.2000	200.1
Channel Y	0.2001	200.9
Channel Z	0.2001	198.1

#### 8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

#### 9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9

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Client	Eurofins			Certificate Not ET	8-1711_Sep09
CALI	BRATION C	ERTIFICAT			
Object		ET3DV6 - SN:17	11		
Calibratior	ı procedure(s)		QA CAL-12 v5, QA CA adure for dosimetric E-		CAL-25)v2
Calibration	ı date:	Séptémber 15, 2	2009		
Condition	of the calibrated item	In Tolerance			
			tional standards, which realize probability are given on the follo		
All calibrat	ions have been conduct	ed in the closed laborate	ory facility: environment temper	ature (22 ± 3)°C and h	umidity < 70%.
Calibratior	n Equipment used (M&TE	E critical for calibration)			
Primary St	landards	ID #	Cal Date (Certificate No.)		Scheduled Calibration
	ter E4419B	GB41293874	1-Apr-09 (No. 217-01030)		Apr-10
Power ser	nsor E4412A	MY41495277	1-Apr-09 (No. 217-01030)		Apr-10
Power ser	nsor E4412A	MY41498087	1-Apr-09 (No. 217-01030)		Apr-10
Reference	3 dB Attenuator	SN: S5054 (3c)	31-Mar-09 (No. 217-01026	)	Mar-10
Reference	20 dB Attenuator	SN: S5086 (20b)	31-Mar-09 (No. 217-01028	)	Mar-10
Reference	a 30 dB Attenuator	SN: S5129 (30b)	31-Mar-09 (No. 217-01027	)	Mar-10
Reference	Probe ES3DV2	SN: 3013	2-Jan-09 (No. ES3-3013_J	lan09)	Jan-10
DAE4		SN: 660	9-Sep-08 (No. DAE4-660_	Sep08)	Sep-09
Secondar	y Standards	ID #	Check Date (in house)		Scheduled Check
	ator HP 8648C	US3642U01700	4-Aug-99 (in house check	 በ	In house check: Oct-09
-	nalyzer HP 8753E	U\$37390585	18-Oct-01 (in house check	,	In house check: Oct-09
		0007000000		00-00	III IIUuse Gieun, Ool-Va
		Name	Function		Signature
Calibrated	by:	Jeton Kastrati	Laboratory Te	chnician A	- U-
Approved	by:	Katja Pokovio	Technical Mar	iager	Her llif-
					Issued: September 16, 2009
This calib	ration certificate shall no	t be reproduced except i	in full without written approval c	of the laboratory.	

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#### Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
Polarization φ	$\varphi$ rotation around probe axis
Polarization 9	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at
	measurement center), i.e., $\vartheta$ = 0 is normal to probe axis

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

#### Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization θ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E<sup>2</sup>-field uncertainty inside TSL (see below *ConvF*).
- *NORM(f)x,y,z* = *NORMx,y,z* \* *frequency\_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z* \* *ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

# Probe ET3DV6

# SN:1711

Manufactured: Last calibrated: Recalibrated:

August 7, 2002 September 17, 2008 September 15, 2009

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

#### DASY - Parameters of Probe: ET3DV6 SN:1711

Sensitivity in Fr	Diode C	ompression <sup>B</sup>		
NormX	<b>1.95</b> ± 10.1%	$\mu$ V/(V/m) <sup>2</sup>	DCP X	<b>92</b> mV
NormY	<b>1.90</b> ± 10.1%	μ <b>V/(V/m)<sup>2</sup></b>	DCP Y	<b>93</b> mV
NormZ	<b>2.08 ±</b> 10.1%	μV/(V/m)²	DCP Z	<b>92</b> m∨

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

#### Please see Page 8.

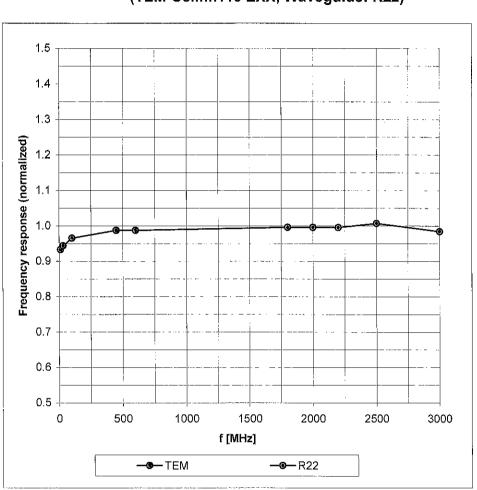
#### **Boundary Effect**

TSL	90	0 MHz	Typical SAR gradient: 5 % pe	r mm	
	SAR <sub>be</sub> [%]	Without	m Surface Distance Correction Algorithm	<b>3.7 mm</b> 9.6	<b>4.7 mm</b> 5.8
TSL	SAR <sub>be</sub> [%] <b>181</b>	With Co 0 MHz	rrection Algorithm Typical SAR gradient: 10 % p	0.7 <b>er mm</b>	0.3
	Sensor Center SAR <sub>be</sub> [%] SAR <sub>be</sub> [%]	Without	m Surface Distance Correction Algorithm rrection Algorithm	<b>3.7 mm</b> 10.0 0.9	<b>4.7 mm</b> 5.6 0.5
Sensor Offset Probe Tip to Sensor Center 2.7 mm					

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

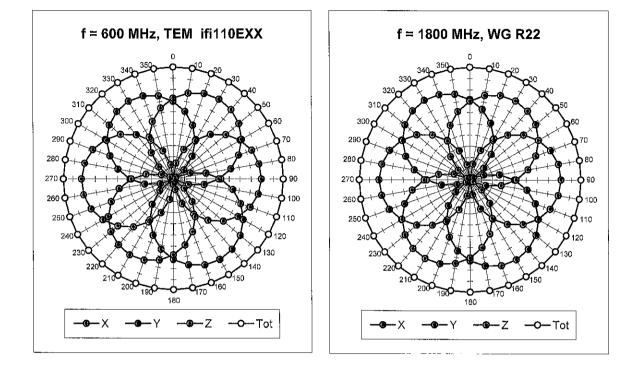
<sup>B</sup> Numerical linearization parameter: uncertainty not required.



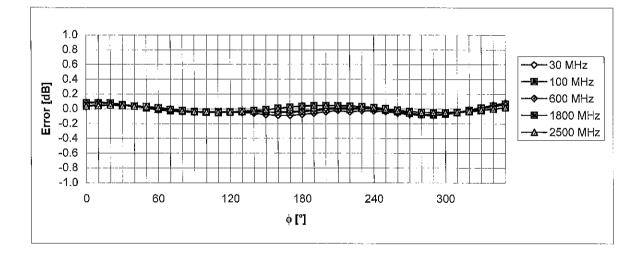
## **Frequency Response of E-Field**

(TEM-Cell:ifi110 EXX, Waveguide: R22)

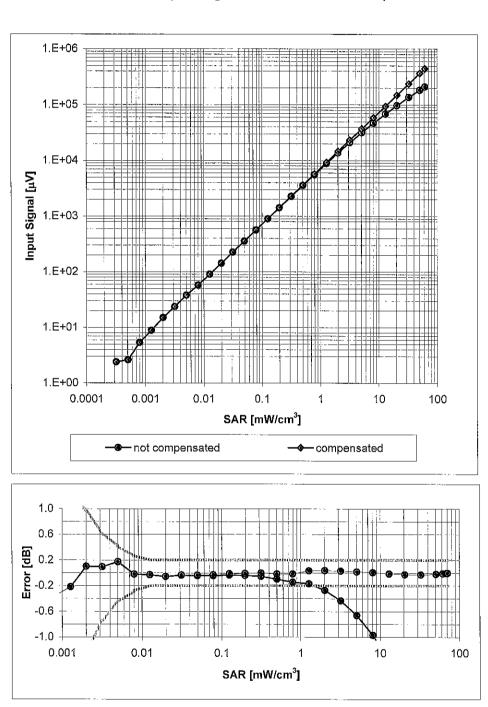
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)



## **Receiving Pattern (** $\phi$ **),** $\vartheta$ = 0°

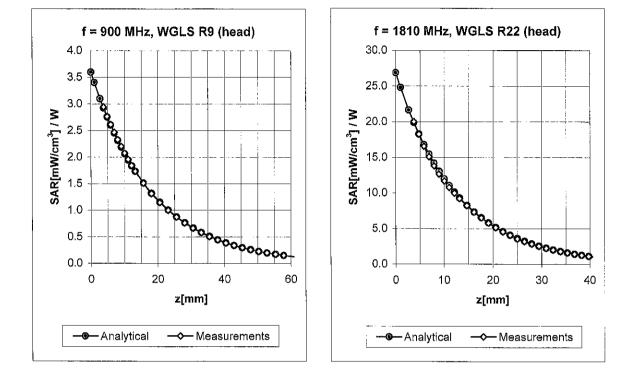


Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)



### Dynamic Range f(SAR<sub>head</sub>) (Waveguide R22, f = 1800 MHz)

Uncertainty of Linearity Assessment: ± 0.6% (k=2)



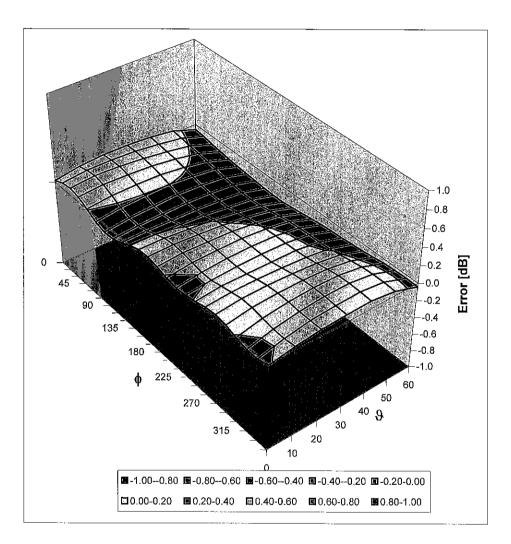
### **Conversion Factor Assessment**

f [MHz]	Validity [MHz] <sup>C</sup>	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
450	± 50 / ± 100	Head	43.5 ± 5%	0.87 ± 5%	0.27	1.88	7.12 ± 13.3% (k=2)
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.38	2.43	6.04 ± 11.0% (k=2)
1810	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.55	2.66	5.09 ± 11.0% (k=2)
1950	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.74	2,17	4.89 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.99	1.74	4.38 ± 11.0% (k=2)
450	± 50 / ± 100	Body	56.7 ± 5%	0.94 ± 5%	0.20	1.95	7.68 ± 13.3% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 <b>±</b> 5%	0.35	2.69	5.85 ± 11.0% (k=2)
1810	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.71	2.99	4.60 ± 11.0% (k=2)
1950	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.96	2.37	4.58 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.99	1.33	4.07 ± 11.0% (k=2)

 $^{\rm c}$  The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

## **Deviation from Isotropy in HSL**

Error (φ, ϑ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)



**Eurofins Product Service** 

Annex B

**Measurement Plots** 

Test Report No.: G0M21003-2994-S-8

#### Dipol Valid.900 (h)\_250mW\_SAM\_31.03.2010

#### DUT: Dipole 900 MHz; Type: D900V2; Serial: 164

Communication System: CW; Frequency: 900 MHz;Duty Cycle: 1:1

Medium: Head 900 MHz Medium parameters used: f = 900 MHz;  $\sigma = 0.944$  mho/m;  $\varepsilon_r = 40.5$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

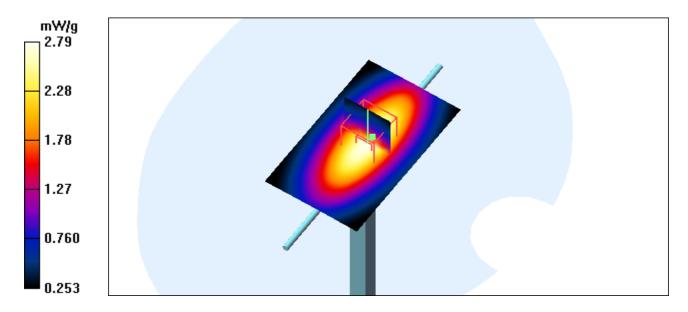
#### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Dipol 900 (250mW)/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 2.80 mW/g

**Dipol 900 (250mW)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 56.1 V/m; Power Drift = -0.003 dBPeak SAR (extrapolated) = 3.67 W/kgSAR(1 g) = 2.53 mW/g; SAR(10 g) = 1.68 mW/gMaximum value of SAR (measured) = 2.79 mW/g



#### Dipol Valid.900 (m)\_250mW\_SAM\_30.03.2010

#### DUT: Dipole 900 MHz; Type: D900V2; Serial: 164

Communication System: CW; Frequency: 900 MHz;Duty Cycle: 1:1

Medium: Muscle 900 MHz Medium parameters used: f = 900 MHz;  $\sigma = 1.01$  mho/m;  $\varepsilon_r = 54.1$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

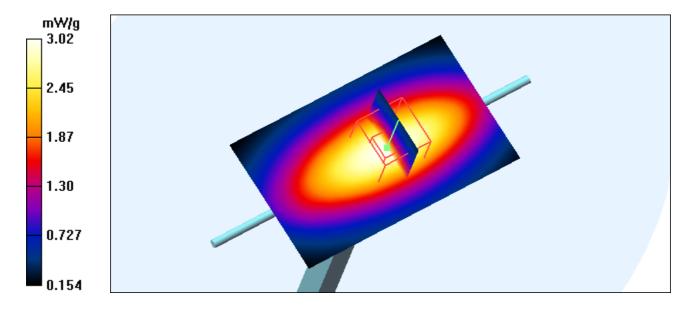
#### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.85, 5.85, 5.85); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Dipol 900 (250mW)/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 3.02 mW/g

**Dipol 900 (250mW)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 57.0 V/m; Power Drift = 0.012 dB Peak SAR (extrapolated) = 3.97 W/kg SAR(1 g) = 2.79 mW/g; SAR(10 g) = 1.84 mW/g Maximum value of SAR (measured) = 3.01 mW/g



#### Dipol Valid.1900 (h)\_250mW\_SAM\_29.03.2010

#### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: 5d025

Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1

Medium: Head 1900 MHz Medium parameters used: f = 1900 MHz;  $\sigma = 1.42$  mho/m;  $\varepsilon_r = 39.9$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Flat Section

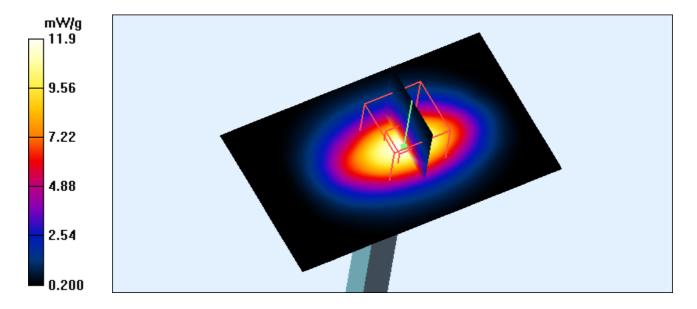
#### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Dipol 1900 (250mW)/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 12.1 mW/g

**Dipol 1900 (250mW)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 05.3 V/m: Power Drift = 0.025 dP

Reference Value = 95.3 V/m; Power Drift = -0.035 dB Peak SAR (extrapolated) = 17.7 W/kg SAR(1 g) = 10.4 mW/g; SAR(10 g) = 5.44 mW/g Maximum value of SAR (measured) = 11.9 mW/g



#### Dipol Valid.1900 (m)\_250mW\_SAM\_01.04.2010

#### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: 5d025

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: Muscle 1900 MHz Medium parameters used: f = 1900 MHz;  $\sigma = 1.58$  mho/m;  $\varepsilon_r = 51.9$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

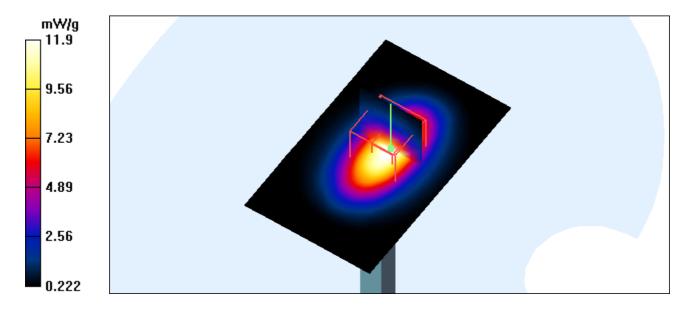
DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.6, 4.6, 4.6); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Dipol 1900 (250mW)/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 12.6 mW/g

**Dipol 1900 (250mW)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 93.8 V/m; Power Drift = -0.017 dBPeak SAR (extrapolated) = 15.6 W/kg SAR(1 g) = 10.6 mW/g; SAR(10 g) = 5.56 mW/g Maximum value of SAR (measured) = 11.9 mW/g



#### 850\_ch\_128\_left\_cheek

#### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

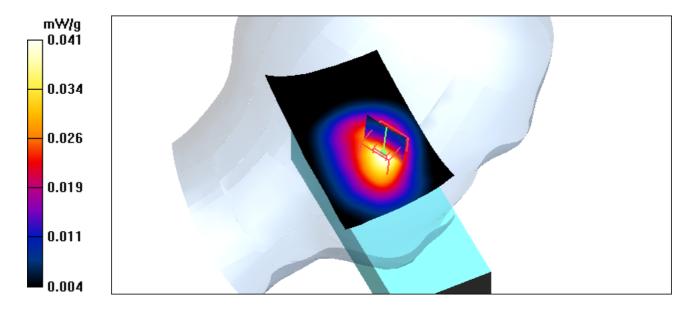
Communication System: GSM 850; Frequency: 824.2 MHz;Duty Cycle: 1:8.3 Medium: Head 900 MHz Medium parameters used (interpolated): f = 824.2 MHz;  $\sigma = 0.874$  mho/m;  $\varepsilon_r = 41.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.043 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 4.33 V/m; Power Drift = -0.113 dB Peak SAR (extrapolated) = 0.053 W/kg SAR(1 g) = 0.038 mW/g; SAR(10 g) = 0.026 mW/g Maximum value of SAR (measured) = 0.041 mW/g



#### 850\_ch\_189\_left\_cheek

#### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Head 900 MHz Medium parameters used: f = 836.512 MHz;  $\sigma = 0.89$  mho/m;  $\epsilon_r = 41.1$ ;  $\rho$ 

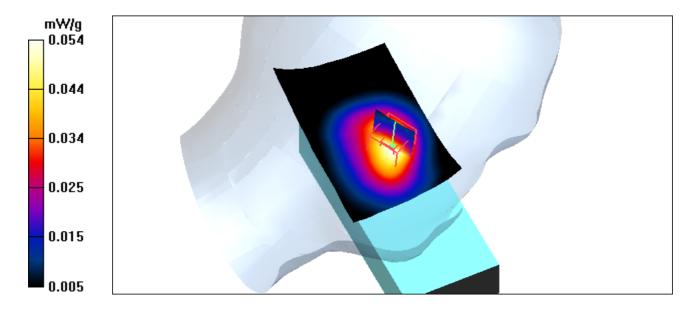
=  $1000 \text{ kg/m}^3$ Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.054 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 4.86 V/m; Power Drift = -0.170 dB Peak SAR (extrapolated) = 0.069 W/kg **SAR(1 g) = 0.050 mW/g; SAR(10 g) = 0.034 mW/g Maximum value of SAR (measured) = 0.054 mW/g** 



#### 850\_ch\_251\_left\_cheek

#### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

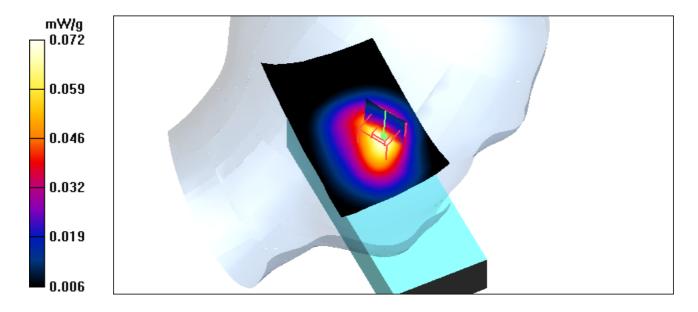
Communication System: GSM 850; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium: Head 900 MHz Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 0.904$  mho/m;  $\varepsilon_r = 40.9$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.071 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 5.30 V/m; Power Drift = -0.129 dB Peak SAR (extrapolated) = 0.094 W/kg **SAR(1 g) = 0.066 mW/g; SAR(10 g) = 0.044 mW/g** Maximum value of SAR (measured) = 0.072 mW/g



#### 850\_ch\_251\_left\_tilted

#### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

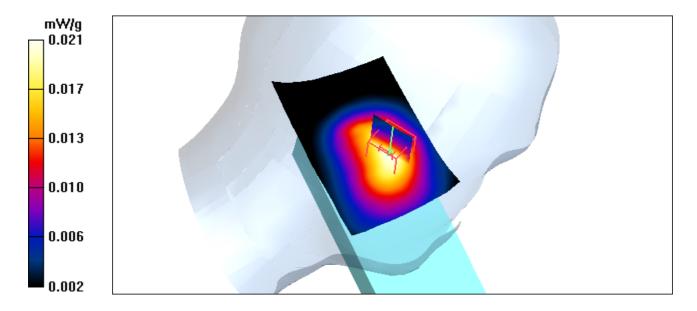
Communication System: GSM 850; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium: Head 900 MHz Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 0.904$  mho/m;  $\varepsilon_r = 40.9$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.021 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 3.81 V/m; Power Drift = -0.093 dB Peak SAR (extrapolated) = 0.026 W/kg SAR(1 g) = 0.020 mW/g; SAR(10 g) = 0.014 mW/g Maximum value of SAR (measured) = 0.021 mW/g



#### 850\_ch\_189\_right\_cheek

#### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

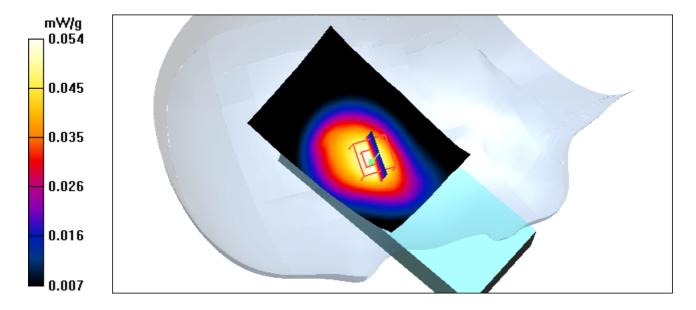
Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Head 900 MHz Medium parameters used (interpolated): f = 836.512 MHz;  $\sigma = 0.89$  mho/m;  $\varepsilon_r = 41.1$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.055 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 5.80 V/m; Power Drift = -0.151 dB Peak SAR (extrapolated) = 0.064 W/kg **SAR(1 g) = 0.051 mW/g; SAR(10 g) = 0.037 mW/g Maximum value of SAR (measured) = 0.054 mW/g** 



# 850\_ch\_251\_right\_cheek

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 850; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium: Head 900 MHz Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 0.904$  mho/m;  $\varepsilon_r = 40.9$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Pight Section

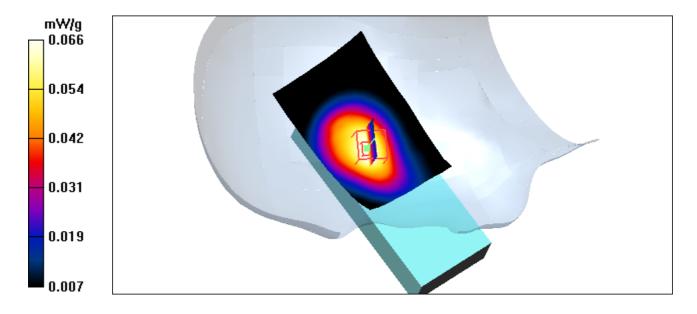
Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.067 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 6.46 V/m; Power Drift = -0.146 dB Peak SAR (extrapolated) = 0.079 W/kg **SAR(1 g) = 0.062 mW/g; SAR(10 g) = 0.045 mW/g Maximum value of SAR (measured) = 0.066 mW/g** 



# 850\_ch\_251\_right\_tilted

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 850; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium: Head 900 MHz Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 0.904$  mho/m;  $\varepsilon_r = 40.9$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phontom section: Bight Section

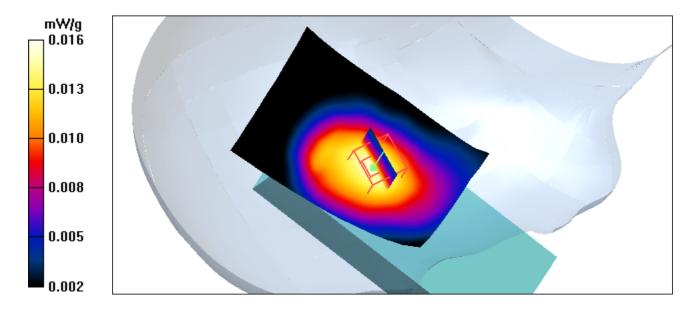
Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.015 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 3.64 V/m; Power Drift = -0.178 dB Peak SAR (extrapolated) = 0.019 W/kg SAR(1 g) = 0.015 mW/g; SAR(10 g) = 0.011 mW/g Maximum value of SAR (measured) = 0.016 mW/g



# 850\_ch\_128\_flat\_front\_0mm gprs-1slot

## DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 850; Frequency: 824.2 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 824.2 MHz;  $\sigma = 0.927$  mho/m;  $\epsilon_r = 54.9$ ;  $\rho$ 

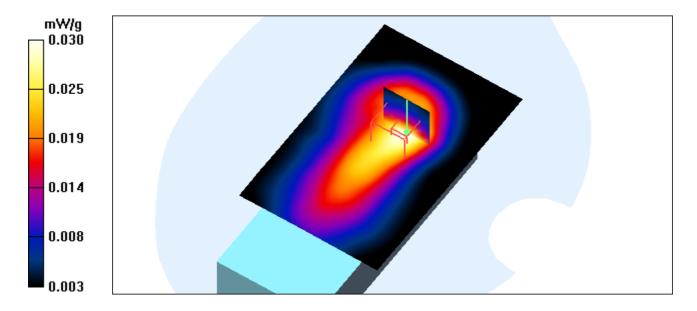
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.85, 5.85, 5.85); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (141x91x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.030 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 5.52 V/m; Power Drift = -0.121 dB Peak SAR (extrapolated) = 0.040 W/kg SAR(1 g) = 0.028 mW/g; SAR(10 g) = 0.019 mW/g Maximum value of SAR (measured) = 0.030 mW/g



## 850\_ch\_189\_flat\_back\_5mm gprs-1slot

## DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\varepsilon_r = 54.8$ ;  $\rho$ 

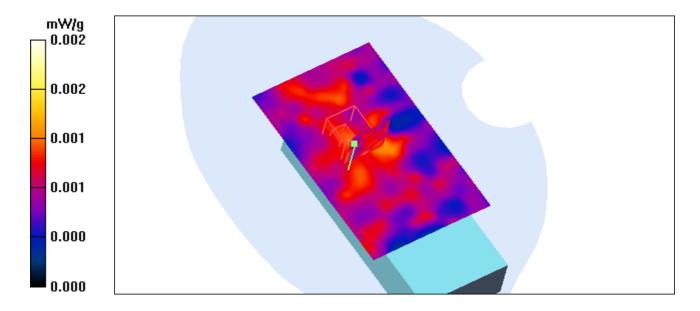
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.85, 5.85, 5.85); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (141x91x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.001 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 1.07 V/m; Power Drift = -0.146 dB Peak SAR (extrapolated) = 0.002 W/kg **SAR(1 g) = 0.00118 mW/g; SAR(10 g) = 0.00104 mW/g Maximum value of SAR (measured) = 0.001 mW/g** 



## 850\_ch\_189\_flat\_front\_0mm gprs-1slot

## DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\varepsilon_r = 54.8$ ;  $\rho$ 

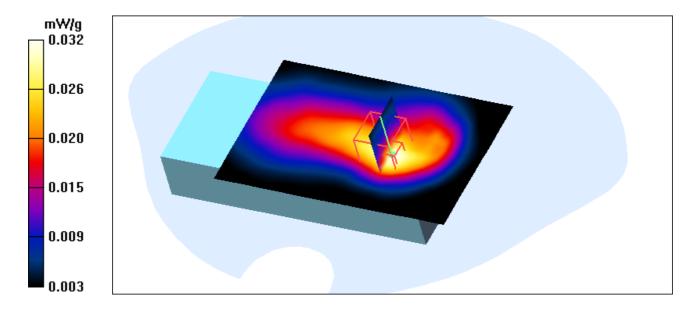
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.85, 5.85, 5.85); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (141x91x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.032 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 5.51 V/m; Power Drift = -0.169 dB Peak SAR (extrapolated) = 0.046 W/kg **SAR(1 g) = 0.030 mW/g; SAR(10 g) = 0.020 mW/g Maximum value of SAR (measured) = 0.032 mW/g** 



# 850\_ch\_251\_flat\_front\_0mm gprs-1slot

## DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium: Muscle 900 MHz Medium parameters used: f = 836.4 MHz;  $\sigma = 0.936$  mho/m;  $\varepsilon_r = 54.8$ ;  $\rho$ 

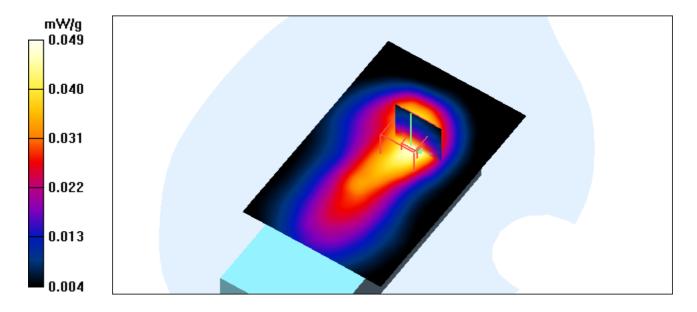
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.85, 5.85, 5.85); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (141x91x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.047 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 6.61 V/m; Power Drift = -0.151 dB Peak SAR (extrapolated) = 0.067 W/kg **SAR(1 g) = 0.045 mW/g; SAR(10 g) = 0.029 mW/g Maximum value of SAR (measured) = 0.049 mW/g** 



# 850\_Z - axis\_scan

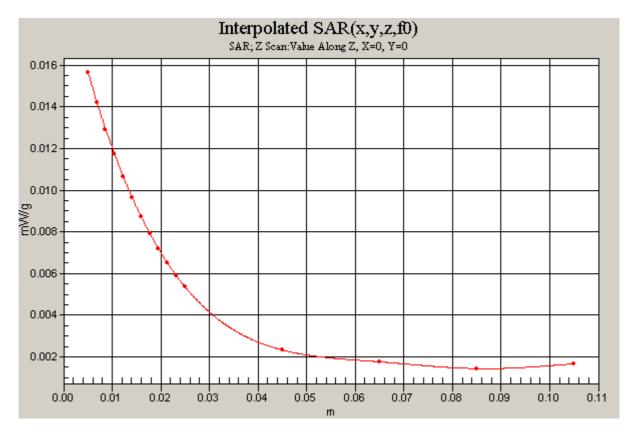
## DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 850; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium: Head 900 MHz Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 0.904$  mho/m;  $\varepsilon_r = 40.9$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(6.04, 6.04, 6.04); Calibrated: 9/15/2009
- Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Z Scan (1x1x16):** Measurement grid: dx=20mm, dy=20mm, dz=20mm Maximum value of SAR (interpolated) = 0.016 mW/g



# 1900\_ch\_661\_left\_cheek

## DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.4$  mho/m;  $\epsilon_r = 39.9$ ;  $\rho =$ 

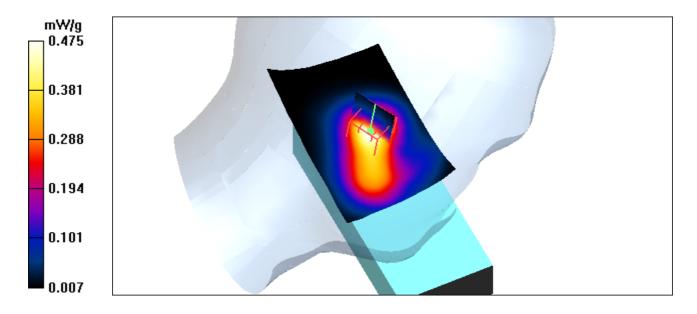
1000 kg/m<sup>3</sup> Phantom section: Left Section

#### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.480 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 13.3 V/m; Power Drift = -0.188 dB Peak SAR (extrapolated) = 0.662 W/kg SAR(1 g) = 0.427 mW/g; SAR(10 g) = 0.243 mW/g Maximum value of SAR (measured) = 0.475 mW/g



# 1900\_ch\_810\_left\_cheek

## DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.43$  mho/m;  $\varepsilon_r = 39.8$ ;  $\rho$ 

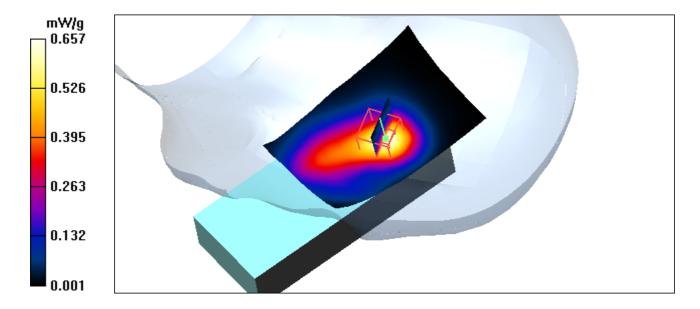
= 1000 kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.649 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 15.6 V/m; Power Drift = -0.173 dB Peak SAR (extrapolated) = 0.894 W/kg **SAR(1 g) = 0.579 mW/g; SAR(10 g) = 0.330 mW/g** Maximum value of SAR (measured) = 0.657 mW/g



# 1900\_ch\_810\_left\_tilted

## DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.43$  mho/m;  $\varepsilon_r = 39.8$ ;  $\rho$ 

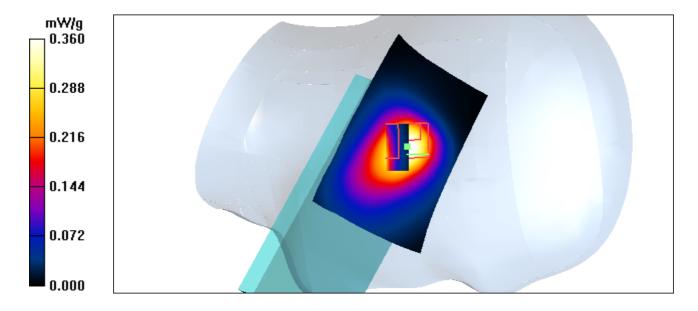
= 1000 kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.394 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 13.1 V/m; Power Drift = -0.130 dB Peak SAR (extrapolated) = 0.646 W/kg SAR(1 g) = 0.280 mW/g; SAR(10 g) = 0.121 mW/g Maximum value of SAR (measured) = 0.360 mW/g



# 1900\_ch\_512\_right\_cheek

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1850.2 MHz;  $\sigma = 1.37$  mho/m;  $\epsilon_r = 39.9$ ;  $\rho$ 

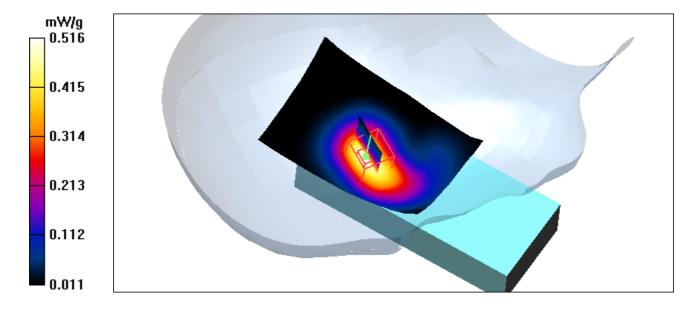
= 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.513 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 12.0 V/m; Power Drift = -0.158 dB Peak SAR (extrapolated) = 0.675 W/kg SAR(1 g) = 0.457 mW/g; SAR(10 g) = 0.274 mW/g Maximum value of SAR (measured) = 0.516 mW/g



# 1900\_ch\_661\_right\_cheek

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.4$  mho/m;  $\epsilon_r = 39.9$ ;  $\rho =$ 

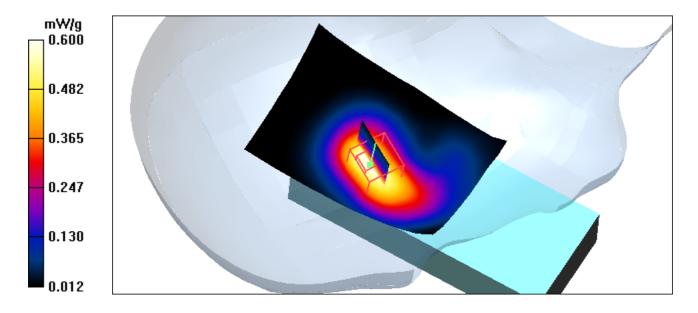
1000 kg/m<sup>3</sup> Phantom section: Right Section

#### DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.601 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 14.4 V/m; Power Drift = -0.139 dB Peak SAR (extrapolated) = 0.812 W/kg SAR(1 g) = 0.540 mW/g; SAR(10 g) = 0.322 mW/g Maximum value of SAR (measured) = 0.600 mW/g



# 1900\_ch\_810\_right\_cheek

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.43$  mho/m;  $\varepsilon_r = 39.8$ ;  $\rho$ 

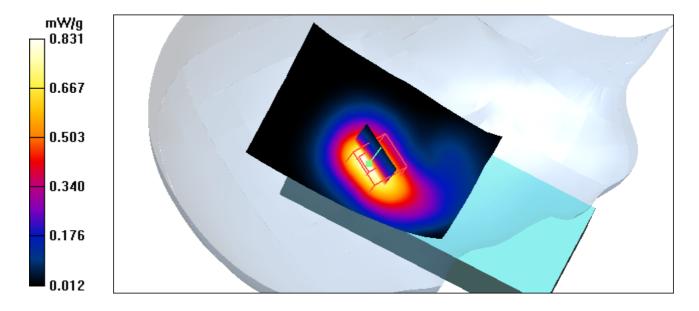
 $= 1000 \text{ kg/m}^3$ Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.839 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 15.0 V/m; Power Drift = -0.008 dB Peak SAR (extrapolated) = 1.15 W/kg SAR(1 g) = 0.755 mW/g; SAR(10 g) = 0.441 mW/g Maximum value of SAR (measured) = 0.831 mW/g



# 1900\_ch\_810\_right\_tilted

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.43$  mho/m;  $\varepsilon_r = 39.8$ ;  $\rho$ 

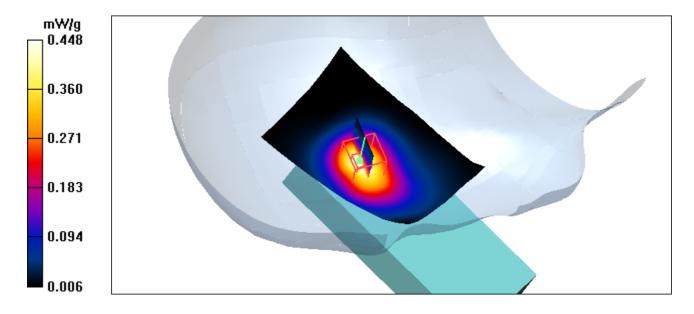
= 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (121x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.443 mW/g

**Pegasus/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 12.6 V/m; Power Drift = -0.142 dB Peak SAR (extrapolated) = 0.623 W/kg **SAR(1 g) = 0.403 mW/g; SAR(10 g) = 0.236 mW/g** Maximum value of SAR (measured) = 0.448 mW/g



# 1900\_ch\_512\_flat\_front\_0mm gprs-1slot

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium: Muscle 1900 MHz Medium parameters used: f = 1850.2 MHz;  $\sigma = 1.51$  mho/m;  $\varepsilon_r = 52$ ;  $\rho$ 

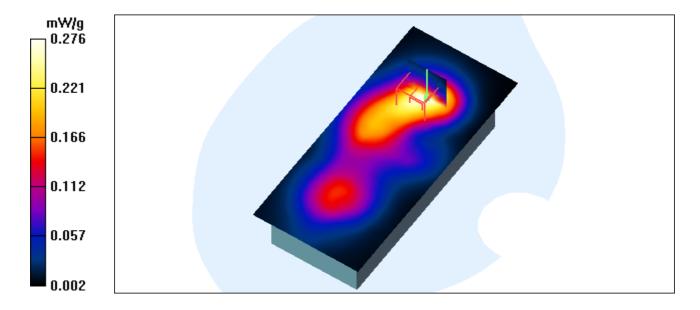
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.6, 4.6, 4.6); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (181x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.277 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 9.61 V/m; Power Drift = -0.149 dB Peak SAR (extrapolated) = 0.379 W/kg SAR(1 g) = 0.248 mW/g; SAR(10 g) = 0.146 mW/g Maximum value of SAR (measured) = 0.276 mW/g



# 1900\_ch\_661\_flat\_front\_0mm gprs-1slot

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3 Medium: Muscle 1900 MHz Medium parameters used: f = 1880 MHz;  $\sigma = 1.55$  mho/m;  $\varepsilon_r = 51.9$ ;  $\rho$ 

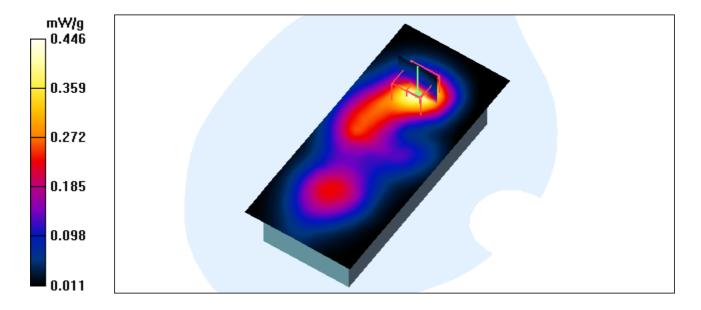
= 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.6, 4.6, 4.6); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (181x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.434 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 11.2 V/m; Power Drift = -0.190 dB Peak SAR (extrapolated) = 0.536 W/kg SAR(1 g) = 0.389 mW/g; SAR(10 g) = 0.231 mW/g Maximum value of SAR (measured) = 0.446 mW/g



# 1900\_ch\_810\_flat\_back\_5mm gprs-1slot

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:8.3 Medium: Muscle 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.59$  mho/m;  $\varepsilon_r = 51.9$ ;

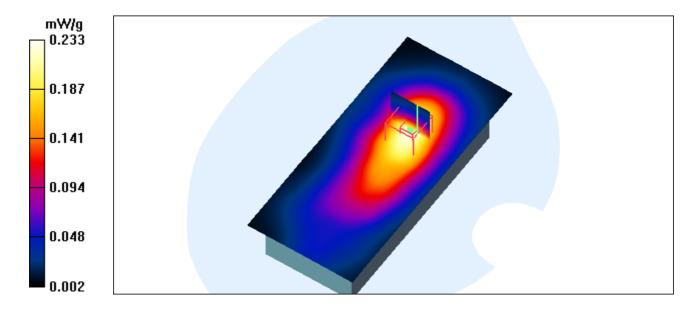
 $\rho = 1000 \text{ kg/m}^3$ Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.6, 4.6, 4.6); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (181x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.233 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 11.3 V/m; Power Drift = -0.094 dB Peak SAR (extrapolated) = 0.366 W/kg SAR(1 g) = 0.229 mW/g; SAR(10 g) = 0.142 mW/g Maximum value of SAR (measured) = 0.233 mW/g



# 1900\_ch\_810\_flat\_front\_0mm gprs-1slot

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:8.3 Medium: Muscle 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.59$  mho/m;  $\varepsilon_r = 51.9$ ;

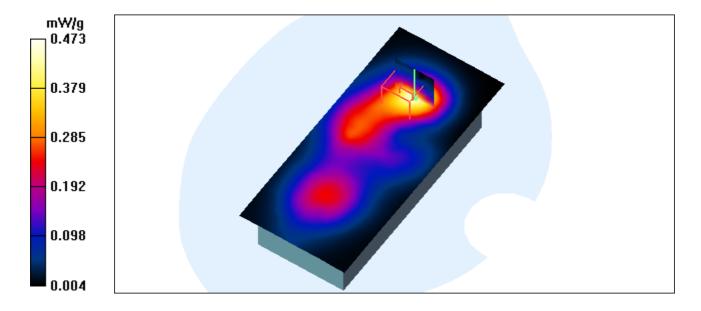
 $\rho = 1000 \text{ kg/m}^3$ Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(4.6, 4.6, 4.6); Calibrated: 9/15/2009
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Area Scan (181x81x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 0.477 mW/g

Pegasus/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 11.2 V/m; Power Drift = -0.184 dB Peak SAR (extrapolated) = 0.987 W/kg SAR(1 g) = 0.455 mW/g; SAR(10 g) = 0.240 mW/g Maximum value of SAR (measured) = 0.473 mW/g



# 1900\_Z - axis\_scan

### DUT: GSM/GPRS mobile phone with GPS; Type: Pegasus; Serial: -

Communication System: GSM 1900; Frequency: 1909.8 MHz;Duty Cycle: 1:8.3 Medium: Head 1900 MHz Medium parameters used: f = 1909.8 MHz;  $\sigma = 1.43$  mho/m;  $\epsilon_r = 39.8$ ;  $\rho$ 

 $= 1000 \text{ kg/m}^3$ Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 SN1711; ConvF(5.09, 5.09, 5.09); Calibrated: 9/15/2009
- Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2009
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.7 Build 71; Postprocessing SW: SEMCAD, V1.8 Build 184

**Pegasus/Z Scan (1x1x16):** Measurement grid: dx=20mm, dy=20mm, dz=20mm Maximum value of SAR (interpolated) = 0.119 mW/g

