SAR TEST REPORT

Test item	:	MP3 player
Model No.	:	D3
Order No.	:	1008-00780
Date of receipt	:	2010-08-27
Test duration	:	2011-01-28
Date of issue	:	2011-02-08
Use of report	:	FCC Original Grant

Applicant : COWON SYSTEMS, Inc

6th FL. COWON TOWER, 689-3, Yeoksam-Dong, Gangnam-Gu, Seoul, 135-080, Korea

Test laboratory : Digital EMC Co., Ltd.

683-3, Yubang-Dong, Cheoin-Gu, Yongin-Si, Kyunggi-Do, 449-080, Korea

Test specification : §2.1093, FCC/OET Bulletin 65 Supplement C[July 2001]

Test environment : See appended test report

Test result : ☒ Pass ☐ Fail

The test results presented in this test report are limited only to the sample supplied by applicant and
the use of this test report is inhibited other than its purpose. This test report shall not be reproduced except in full,
without the written approval of DIGITAL EMC CO., LTD.
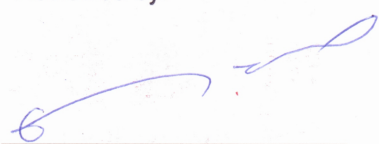
Tested by: Witnessed by: Reviewed by:

_____ _____ _____
Engineer N/A Manager
S.K.Ryu W.J. Lee

CONTENTS

1. DESCRIPTION OF DEVICE

Environmental evaluation measurements of specific absorption rate (SAR) distributions in emulated human head and body tissues exposed to radio frequency (RF) radiation from wireless portable devices for compliance with the rules and regulations of the U.S. Federal Communications Commission (FCC).

General Information

Equipment type	MP3 player
FCC ID:	SXV-D3
Equipment model name	D3
Equipment add model name	N/A
Equipment serial no.	Identical prototype
Mode(s) of Operation	W-LAN(802.11b)
TX Frequency Range	2412 ~ 2462 MHz(802.11b)
RX Frequency Range	2412 ~ 2462 MHz(802.11b)
Max. SAR Measurement	**0.804** mW/g W-LAN(802.11b) Body SAR
FCC Equipment Class	Digital Transmission System (DTS)
Date(s) of Tests	2011-01-28
Antenna Type	Chip Antenna

2. INTROCUCTION

The FCC has adopted the guidelines for evaluating the environmental effects of radio frequency radiation in ET Docket 93-62 on Aug. 6, 1996 to protect the public and workers from the potential hazards of RF emissions due to FCC-regulated portable devices. The safety limits used for the environmental evaluation measurements are based on the criteria published by the American National Standards Institute (ANSI) for localized specific absorption rate (SAR) in IEEE/ANSI C95.1-2005 Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz. 1992 by the Institute of Electrical and Electronics Engineers, Inc., New York, New York 10017. The measurement procedure described in IEEE/ANSI C95.3-1992 Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields - RF and Microwave is used for guidance in measuring SAR due to the RF radiation exposure from the Equipment under Test (EUT). These criteria for SAR evaluation are similar to those recommended by the National Council on Radiation Protection and Measurements (NCRP) in Biological Effects and Exposure Criteria for Radio frequency Electromagnetic Fields," NCRP Report No. 86 NCRP, 1986, Bethesda, MD 20814. SAR is a measure of the rate of energy absorption due to exposure to an RF transmitting source. SAR values have been related to threshold levels for potential biological hazards.

SAR Definition

Specific Absorption Rate (SAR) is defined as the time derivative (rate) of the incremental energy (dU)absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (ρ) It is also defined as the rate of RF energy absorption per unit mass at a point in an absorbing body (see Fig. 2.1)

$$S\ A\ R\ =\ \frac{d}{d\,t}\left(\frac{d\,U}{d\,m}\right)\ =\ \frac{d}{d\,t}\left(\frac{d\,U}{\rho\,d\,v}\right)$$

Figure 2.1 SAR Mathematical Equation

SAR is expressed in units of Watts per Kilogram (W/kg).

$$SAR = \frac{\sigma \cdot E^2}{\rho}$$

Where:

σ = conductivity of the tissue - simulating material (S/m)

ρ = mass density of the tissue-simulating material (kg/m3)

E   = Total RMS electric field strength (V/m)

NOTE: The primary factors that control rate of energy absorption were found to be the wavelength of the incident field in relations to the dimensions and geometry of the irradiated organism, the orientation of the organism in relation to the polarity of field vectors, the presence of reflecting surfaces, and whether conductive contact is made by the organism with a ground plane.

Automated TEST SYSTEM SPECIFICATIONS

Positioner

Robot:	Stäubli Unimation Corp. Robot Model: RX60L
Repeatability:	0.02 mm
No. of axis:	6

Data Acquisition Electronic (DAE) System
Cell Controller

Processor:	Pentium 4 CPU
Clock Speed:	3 GHz
Operating System:	Window 2000
Data Card:	DASY4 PC-Board

Data Converter

Features:	Signal, multiplexer, A/D converter. & control logic
Software:	DASY4
Connecting Lines:	Optical downlink for data and status info
	Optical uplink for commands and clock

PC Interface Card

Function:	24 bit (64 MHz) DSP for real time processing
	Link to DAE 4
	16 bit A/D converter for surface detection system
	serial link to robot
	direct emergency stop output for robot

E-Field Probes

Model:	ES3DV3 S/N: 3123
Construction:	Triangular core fiber optic detection system
Frequency:	10 MHz to 4 GHz
Linearity:	±0.2dB (30MHz to 4GHz)

Phantom

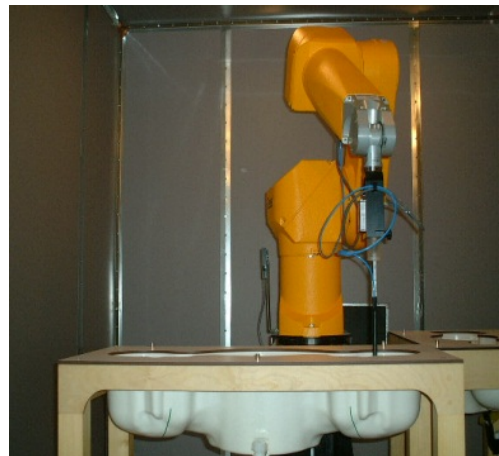|	
Phantom:	SAM Twin Phantom (V4.0)
Shell Material:	Composite
Thickness:	2.0 ± 0.2 mm

Figure 2.2 DASY4 Test System

3. DESCRIPTION OF TEST EQUIPMENT

3.1 SAR MEASUREMENT SETUP

Robotic System

These measurements are performed using the DASY4 automated dos imetric assessment system. The DASY4 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, Pentium III computer, near-field probe, probe alignment sensor, and the generic twin phantom containing the brain equivalent material. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF) (see Fig. 3.1).

System Hardware

A cell controller system contains the power supply, robot controller teach pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the Micron Pentium IV 500 MHz computer with Windows NT system and SAR Measurement Software DASY4, A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot.   A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC).   The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.
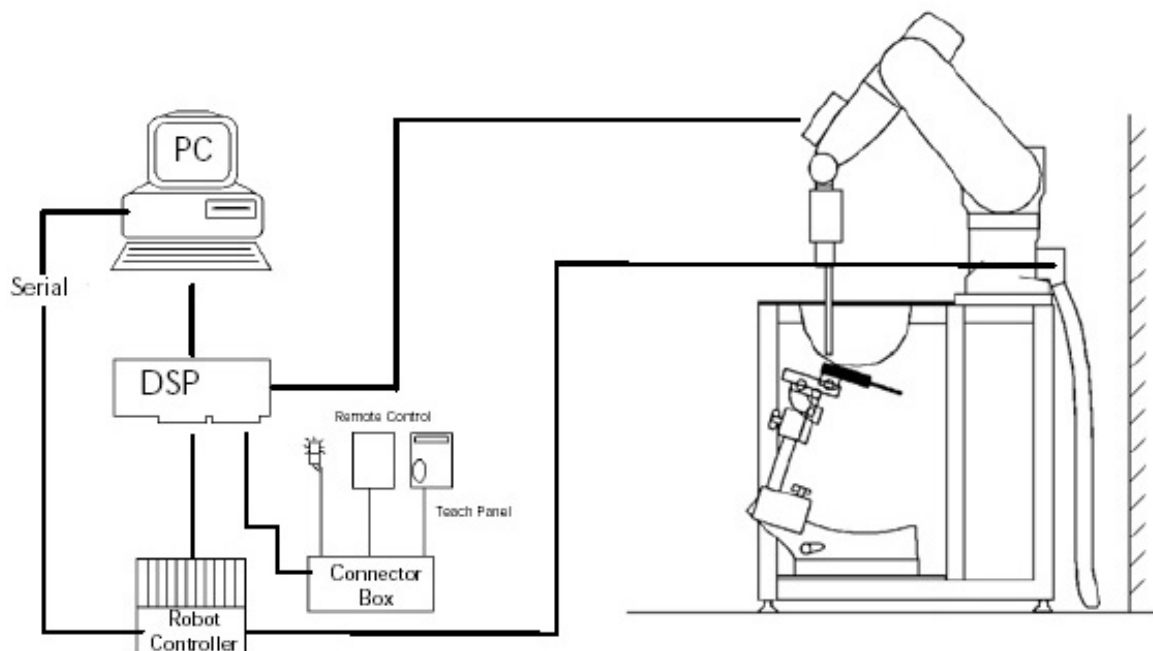

Figure 3.1 SAR Measurement System Setup

System Electronics

The DAE4 consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit.   Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer. The system is described in detail in.

3.2 Probe Measurement System

The SAR measurements were conducted with the dosimetric probe ES3DV3, designed in the classical triangular configuration (see Fig. 3.2) and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi fiber line ending at the front of the probe tip. (see Fig. 3.3) It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped at reaching the maximum.

DAE System

Probe Specifications

Calibration: In air from 10 MHz to 4 GHz
                     In brain and muscle simulating tissue at Frequencies of 835 MHz, 1750 MHz, 1900 MHz, 2450 MHz

Frequency: 10 MHz to 4 GHz

Linearity: ±0.2dB (30 MHz to 4 GHz)

Dynamic: 5 µW/g to > 100 mW/g

A - BEAM

Figure 3.2 Triangular Probe Configurations

Range: Linearity: ±0.2dB

Dimensions: Overall length: 337 mm

Tip length: 10 mm

Body diameter: 10 mm

Tip diameter: 4 mm

Distance from probe tip to sensor center: 2 mm

Application: SAR Dosimetry Testing
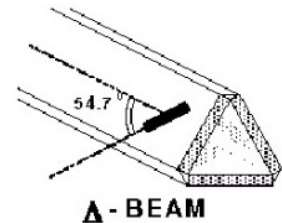   Compliance tests of mobile phones

Figure 3.3 Probe Thick-Film Technique

3.3 Probe Calibration Process

Dosimetric Assessment Procedure

Each probe is calibrated according to a dosimetric assessment procedure described in with accuracy better than +/-10%. The spherical isotropy was evaluated with the procedure described in and found to be better than +/-0.25dB. The sensitivity parameters (Norm X, Norm Y, Norm Z), the diode compression parameter (DCP) and the conversion factor (Conv F) of the probe is tested.

Free Space Assessment

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies below 1 GHz, and in a waveguide above 1GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/cm^2.

Temperature Assessment *

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium, correlates to temperature rise in a dielectric medium. For temperature correlation calibration a RF transparent the rmistor based temperature probe is used in conjunction with the E-field probe

$$ SAR = C\frac{\Delta T}{\Delta t} $$

$$ SAR = \frac{|E|^2 \cdot \sigma}{\rho} $$

where:

Δt = exposure time (30 seconds),

C = heat capacity of tissue (brain or muscle),

ΔT = temperature increase due to RF exposure.

where:

σ = simulated tissue conductivity,

ρ = Tissue density (1.25 g/cm^3 for brain tissue)

SAR is proportional to ΔT / Δt , the initial rate of tissue
heating, before thermal diffusion takes place.
Now it's possible to quantify the electric field in the simulated tissue by
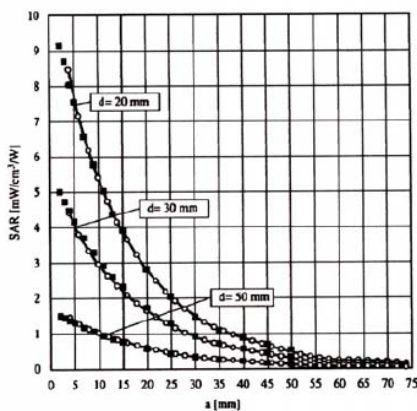equating the thermally derived SAR to the E- field;

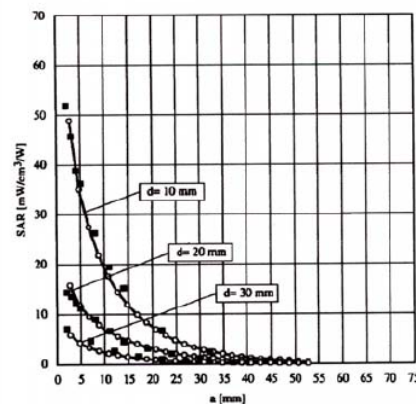

**Figure 3.4 E-Field and Temperature
Measurements at 900MHz**

**Figure 3.5 E-Field and Temperature
Measurements at 1800MHz**

Data Extrapolation

The DASY4 software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given like below;

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with V_i = compensated signal of channel i   (i=x,y,z)
U_i = input signal of channel i   (i=x,y,z)
cf   = crest factor of exciting field   (DASY parameter)
dcp_i = diode compression point   (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes:

$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

with V_i = compensated signal of channel i (i = x,y,z)
$Norm_i$ = sensor sensitivity of channel i   (i = x,y,z)
$\mu V/(V/m)^2$ for E-field probes
ConvF = sensitivity of enhancement in solution
E_i = electric field strength of channel i in V/m

The RSS value of the field components gives the total field strength (Hermetian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with   SAR   = local specific absorption rate in W/g
E_{tot} = total field strength in V/m
σ = conductivity in [mho/m] or [Siemens/m]
ρ = equivalent tissue density in g/cm³

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770}$$

with P_{pwe} = equivalent power density of a plane wave in W/cm²
E_{tot} = total electric field strength in V/m

3.4 SAM PHANTOM

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a wooden table.   The shape of the shell is based on data from an anatomical study designed to determine the maximum exposure in at least 90% of all users.   It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region.   A cover prevents the evaporation of the liquid. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. (see Fig. 3.6)

<u>Phantom Specification</u>

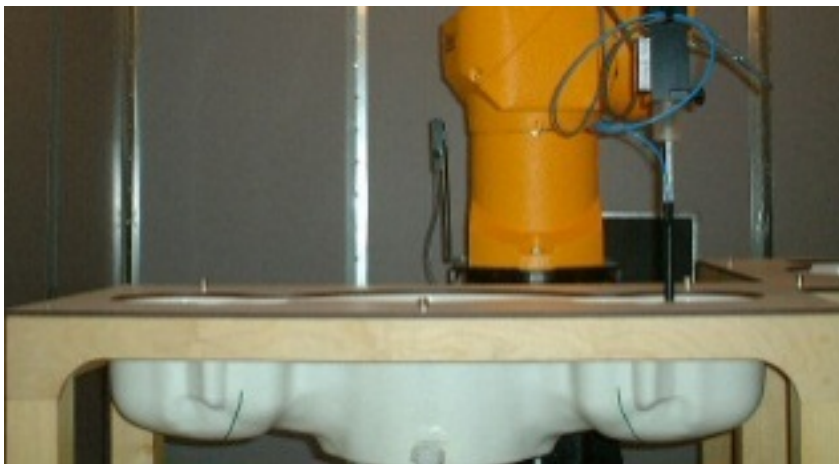|	
Phantom:	SAM Twin Phantom (V4.0)
Shell Material:	Vivac Composite
Thickness:	2.0 ± 0.2 mm

Figure 3.6 SAM Twin Phantom

3.5 Device Holder for Transmitters

In combination with the SAM Twin Phantom V4.0 the Mounting Device (see Fig. 3.7), enables the rotation of the mounted transmitter in spherical coordinates whereby the rotation point is the ear opening.   The devices can be easily, accurately, and repeat ably be positioned according to the FCC, CENELEC, IEC and IEEE specifications.   The device holder can be locked at different phantom locations (left head, right head, flat phantom).

Note: A simulating human hand is not used due to the complex anatomical and geometrical structure of the hand that may produce infinite number of configurations.   To produce the worst-case condition (the hand absorbs antenna output power), the hand is omitted during the tests.

Figure 3.7 Mounting Device

3.6 Brain & Muscle Simulating Mixture Characterization

Simulated Tissue

The brain and muscle mixtures consist of a viscous gel using hydrox-ethyl cellulose (HEC) gelling agent and saline solution (see Table 3.1). Preservation with a bacteriacide is added and visual inspection is made to make sure air bubbles are not trapped during the mixing process. The mixture is calibrated to obtain proper dielectric constant (permittivity) and conductivity of the desired tissue. The mixture characterizations used for the brain and muscle tissue simulating liquids are according to the data by C. Gabriel and G. Harts grove.

Table 3.1 Composition of the Tissue Equivalent Matter

INGREDIENTS	835MHz Brain	835MHz Muscle	1800MHz Brain	1800MHz Muscle	1900MHz Brain	1900MHz Muscle	2450MHz Brain	2450MHz Muscle
WATER	40.19%	50.75%	55.24%	69.04%	55.24%	70.23%	71.88%	73.4%
SUGAR	57.90%	48.21%	-	-	-	-	-	-
SALT	1.48%	0.94%	0.31%	2.72%	0.31%	0.29%	0.16%	0.06%
DGBE	-	-	44.45%	28.24%	44.45%	29.48%	7.99%	26.54%
Triton X-100	-	-	-	-	-	-	19.97%	-
BACTERIACIDE	0.18%	0.10%	-	-	-	-	-	-
HEC	0.25%	-	-	-	-	-	-	-
Dielectric Constant Target	41.5	55.2	40	53.3	40	53.3	39.2	52.7
Conductivity Target (S/m)	0.9	0.97	1.4	1.52	1.4	1.52	1.8	1.95

Salt: 99 % Pure Sodium Chloride Sugar: 98 % Pure Sucrose

Water: De-ionized, 16M resistivity HEC: Hydroxyethyl Cellulose

DGBE: 99 % Di(ethylene glycol) butyl ether,[2-(2-butoxyethoxy) ethanol]

Triton X-100(ultra pure): Polyethylene glycol mono [4-(1,1,3,3-tetramethylbutyl)phenyl]

4. SAR MEASUREMENT PROCEDURE

The evaluation was performed using the following procedure:

1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing.   This fixed location point was measured and used as a reference value.

2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9mm from the Inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 15 mm x 15 mm.

Sample SAR Area Scan

3. Based on the area scan data, the area of the maximum absorption was determined by sp line interpolation.   Around this point, a volume of 32 mm x32 mm x 30 mm (fine resolution volume scan, zoom scan) was assessed by measuring 5 x 5 x 7 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure (see Sample Sar Area Scan):

    a. The data at the surface was extrapolated, since the center of the dipoles is 2.5 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2mm. The extrapolation was based on a least square algorithm. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.

    b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional sp lines with the "Not a knot" condition (in x, y, and z directions). The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10x 10) were interpolated to calculate the average.

    c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

4. The SAR reference value, at the same location as step 1, was re-measured. If the value changed by more than 5%, the evaluation is repeated.
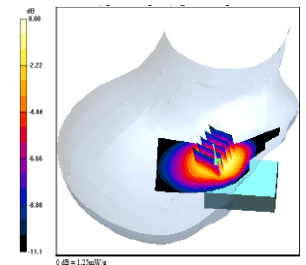
Specific Anthropomorphic Mannequin (SAM) Specifications

The phantom for handset SAR assessment testing is a low-loss dielectric shell, with shape and dimensions derived from the anthropometric data of the 90th percentile adult male head dimensions as tabulated by the US Army.   The SAM Twin Phantom shell is bisected along the mid-sagittal plane into right and left halves (see Fig. 4.1).   The perimeter side walls of each phantom halves are extended to allow filling with liquid to a depth that is sufficient to minimized reflections from the upper surface.   The liquid depth is maintained at a minimum depth of 15cm to minimize reflections from the upper surface.

Figure 4.1 Sam Twin Phantom shell

5. DEFINITION OF REFERENCE POINTS

EAR Reference Point

Figure 5.1 shows the front, back and side views of the SAM Twin Phantom.   The point"M" is the reference point for the center of the mouth, "LE" is the left ear reference point(ERP), and "RE" is the right ERP.   The ERPs are 15mm posterior to the entrance to the Ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 5.5.   The plane Passing, through the two ear canals and M is defined as the Reference Plane.   The line N-F (Neck- Front) is perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 5.2).   Line B-M is perpendicular to the N-F line. Both N-F and B-M lines are marked on the external phantom shell to facilitate handset positioning.

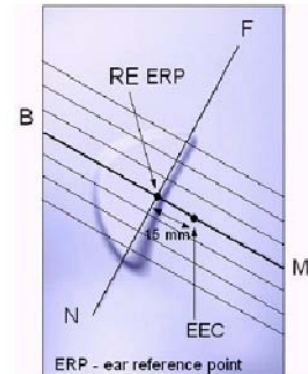**Figure 5.1 Front, back and side view of SAM Twin Phantom**

Figure 5.2 Close-up side view of ERPs

Handset Reference Points

Two imaginary lines on the handset were established: the vertical centerline and the horizontal line.   The test device was placed in a normal operating position with the "test device reference point" located along the "vertical centerline" on the front of the device aligned to the "ear reference point"   (See Fig. 5.3).   The "test device reference point" was than located at the same level as the center of the ear reference point.   The test device was positioned so that the "vertical centerline" was bisecting the front surface of the handset at it's top and bottom edges, positioning the "ear reference point" on the outer surface of the both the left and right head phantoms on the ear reference point.
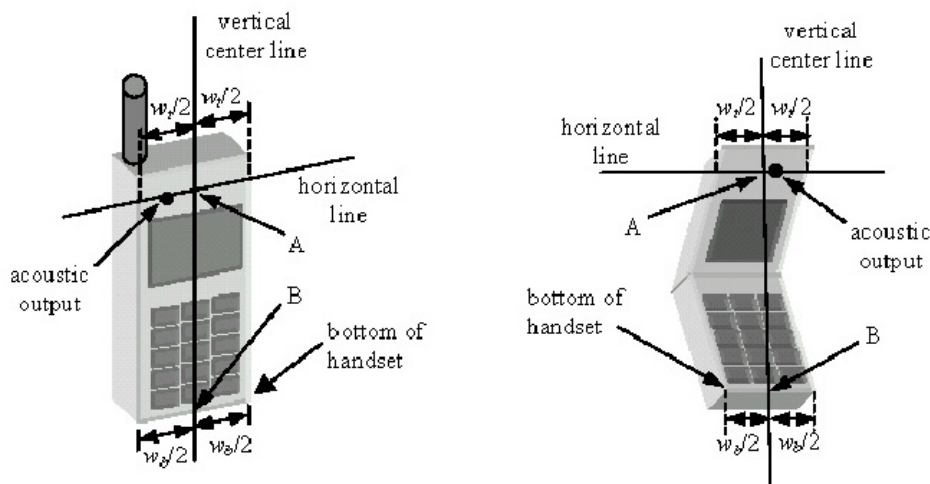
Figure 5.3 Handset Vertical Center & Horizontal Line Reference Points

5.1 TEST CONFIGURATION POSITIONS

Positioning for Cheek/Touch

1. The test device was positioned with the handset close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 5.4), such that the plane defined by the vertical center line and the horizontal line of the phone is approximately parallel to the sagittal plane of the phantom.
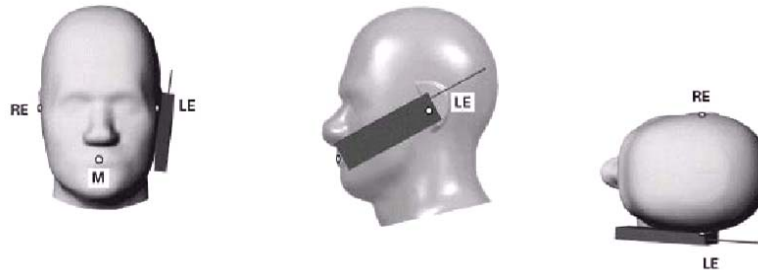

Figure 5.4 Front, Side and Top View of Cheek/Touch Position

2. The handset was translated towards the phantom along the line passing through RE & LE until the handset touches the ear.

3. While maintaining the handset in this plane, the handset was rotated around the LE-RE line until the vertical centerline was in the plane normal to MB-NF including the line MB (reference plane).

4. The phone was hen rotated around the vertical centerline until the phone (horizontal line) was symmetrical was respect to the line NF.

5. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE, and maintaining the phone contact with the ear, the handset was rotated about the line NF until any point on the handset made contact with a phantom point below the ear (cheek).   (See Figure 5.5)
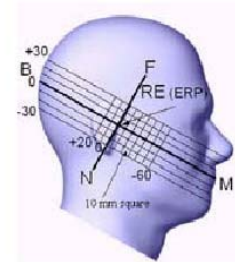

Figure 5.5 Side view w/ relevant markings

Positioning for Ear / 15 ° Tilt

With the test device aligned in the "Cheek/Touch Position":

1. While maintaining the orientation of the phone, the phone was retracted parallel to the reference plane far enough to enable a rotation of the phone by 15degree.

2. The phone was then rotated around the horizontal line by 15 degree.

3. While maintaining the orientation of the phone, the phone was moved parallel to the reference plane until any part of the phone touches the head. (In this position, point A was located on the line RE-LE). The tilted position is obtained when the contact is on the pinna.   If the contact was at any location other than the pinna, the angle of the phone would then be reduced.   The tilted position was obtained when any part of the phone was in contact of the ear as well as a second part of the phone was in contact with the head (see Figure 5.6).
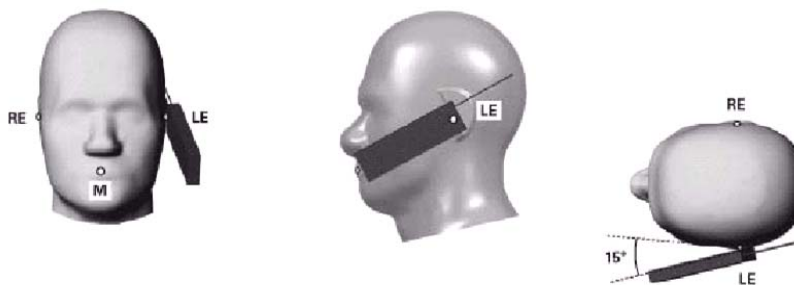

Figure 5.6 Front, Side and Top View of Ear/15° Tilt Position

Body Holster /Belt Clip Configurations

Body-worn operating configurations are tested with the belt-clips and holsters attacked to 3the device and positioned against a flat phantom in a normal use configuration (see Figure 5.7).   A device with a headset output is tested with a headset connected to the device.   Body dielectric parameters are used.

Figure 5.7 Body Belt Clip & Holster Configurations

Accessories for Body-worn operation configurations are divided into two categories: those that do not contain metallic components and those that contain metallic components.   When multiple accessories that do not contain metallic components are supplied with the device, the device is tested with only the accessory that dictates the closest spacing to the body.   Then multiple accessories that contain metallic components are supplied with the device, the device is tested with each accessory that contains a unique metallic component.   If multiple accessories share an identical metallic component (i.e. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that dictates the closest spacing to the body is tested.

Body-worn accessories may not always be supplied or available as options for some Devices intended to be authorized for body-worn use.   In this case, a test configuration where a separation distances between the back of the device and the flat phantom is used. All test position spacing is documented.

Transmitters that are designed to operate in front of a person's face, as in push-to-talk configurations, are tested for SAR compliance with the front of the device positioned to face the flat phantom.   For devices that are carried next to the body such as a shoulder, waist or chest-worn transmitters, SAR compliance is tested with the accessories, including headsets and microphones, attached to the device and positioned against a flat phantom in a normal use configuration.

In all cases SAR measurements are performed to investigate the worst-case positioning. Worst-case positioning is then documented and used to perform Body SAR testing.

In order for users to be aware of the body-worn operating requirements for meeting RF exposure compliance, operating instructions and cautions statements are included in the user's manual.

6. ANSI / IEEE C95.1-2005 RF EXPOSURE LIMITS

Uncontrolled Environment

UNCONTROLLED ENVIRONMENTS are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

Controlled Environment

CONTROLLED ENVIRONMENTS are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are employment, which have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

Table 6.1.SAR Human Exposure Specified in ANSI/IEEE C95.1-2005

	HUMAN EXPOSURE LIMITS	
	General Public Exposure (W/kg) or (mW/g)	Occupational Exposure (W/kg) or (mW/g)
Whole-Body average SAR (W/kg)	0.08	0.40
Localized SAR (head and trunk) (W/kg)	1.60	8.00
Localized SAR (limbs) (W/kg)	4.00	20.0

NOTES:
* The Spatial Peak value of the SAR averaged over any 1 g of tissue
  (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
** The Spatial Average value of the SAR averaged over the whole-body.
*** The Spatial Peak value of the SAR averaged over any 10 g of tissue
  (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e.as a result of employment or occupation).

7. IEEE P1528 –MEASUREMENT UNCERTAINTIES

Error Description	Uncertaint value ±%	Probability Distribution	Divisor	(Ci) 1g	Standard (1g)	vi 2 or Veff
Measurement System						
Probe calibration	± 4.8	Normal	1	1	± 4.8 %	∞
Axial isotropy	± 4.7	Rectangular	√3	0.7	± 1.9 %	∞
Hemispherical isotropy	± 9.6	Rectangular	√3	0.7	± 3.9 %	∞
Boundary Effects	± 1.0	Rectangular	√3	1	± 0.6 %	∞
Probe Linearity	± 4.7	Rectangular	√3	1	± 2.7 %	∞
Detection limits	± 1.0	Rectangular	√3	1	± 0.6 %	∞
Readout Electronics	± 1.0	Normal	1	1	± 1.0 %	∞
Response time	± 0.8	Rectangular	√3	1	± 0.5 %	∞
Integration time	± 2.6	Rectangular	√3	1	± 1.5 %	∞
RF Ambient Conditions	± 3.0	Rectangular	√3	1	± 1.7 %	∞
Probe Positioner	± 0.4	Rectangular	√3	1	± 0.2 %	∞
Probe Positioning	± 2.9	Rectangular	√3	1	± 1.7 %	∞
Algorithms for Max. SAR Eval.	± 1.0	Rectangular	√3	1	± 0.6 %	∞
Test Sample Related						
Device Positioning	± 2.9	Normal	1	1	± 2.9 %	145
Device Holder	± 3.6	Normal	1	1	± 3.6 %	5
Power Drift	± 5.0	Rectangular	√3	1	± 2.9 %	∞
Physical Parameters						
Phantom Shell	± 4.0	Rectangular	√3	1	± 2.3 %	∞
Liquid conductivity (Target)	± 5.0	Rectangular	√3	0.64	± 1.8 %	∞
Liquid conductivity (Meas.)	± 2.5	Normal	1	0.64	± 1.6 %	∞
Liquid permittivity (Target)	± 5.0	Rectangular	√3	0.6	± 1.7 %	∞
Liquid permittivity (Meas.)	± 2.5	Normal	1	0.6	± 1.5 %	∞
CombinedStandard Uncertainty					**± 10.3 %**	330
Expanded Uncertainty (k=2)					**± 20.6 %**	

The above measurement uncertainties are according to IEEE P1528 (2003)

8. SYSTEM VERIFICATION

Tissue Verification

Table 8.1 Simulated Tissue Verification

MEASURED TISSUE PARAMETERS							
Date(s)	Target Frequency	Dielectric constant: ε			Conductivity: σ		
		Target	Measured	Deviation (%)	Target	Measured	Deviation (%)
January 28, 2011	2450 MHz Muscle	52.7	53.0	0.57	1.950	1.910	-2.05

Test System Validation

Prior to assessment, the system is verified to the ±10% of the specifications at 2450 MHz by using the system validation kit(s).   (Graphic Plots Attached)

Table 8.2 System Validation

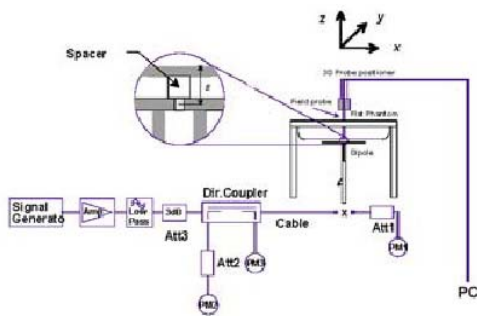| SYSTEM DIPOLE VALIDATION TARGET & MEASURED (2450 MHz values are normalized to a forward power of 1/4 W)					
Date(s)	System Validation Kit:	Target Frequency	Targeted SAR$_{1g}$ (mW/g)	Measured SAR$_{1g}$ (mW/g)	Deviation (%)
January 28, 2011	D-2450V2, S/N: 726	2450 MHz Muscle	12.83	13.2	2.88

Figure 8.1 Dipole Validation Test Setup

9. Configuring 802.11 a/b/g Transmitters for SAR Measurement

SAR Testing with IEEE 802.11 a/b/g Transmitters

Normal network operating configurations are not suitable for measuring the SAR of 802.11 a/b/g transmitters. Unpredictable in network traffic and antenna diversity conditions can introduce undesirable variations in SAR results. The SAR for these devices should be measured using chipset based test mode software to ensure the results are consistent and reliable.

General Device Setup

Chipset based test mode software is hardware dependent and generally varies among manufacturers. The device operating parameters established in test mode for SAR measurements must be identical to those programmed in production units, including output power levels, amplifier gain settings and other RF performance tuning parameters. The test frequencies should correspond to actual channel frequencies defined for domestic use. SAR for devices with switched diversity should be measured with only one antenna transmitting at a time during each SAR measurement, according to a fixed modulation and data rate. The same data pattern should be sued for all measurements.

Frequency Channel Configurations

802.11 a/b/g and 4.9 GHz operation modes are tested independently according to the service requirements in each frequency band. 802.11 b/g modes are tested on channels 1. 6 and 11. 802.11a is tested for UNII operations on channels 36 and 48 in the 5.15-5.25 GHz Band; channels 52 and 64 in the 5.25-5.35 GHz band; channels 104, 116, 124 and 136 in the 5.470-5.725 GHz BAND; and channel 149 and 161 in the 5.8 GHz band. When 5.8 GHz § 15.247 is also available, channels 149, 157 and 165 should be tested of the UNII channels. 4.9 GHz is tested on channels 1., 10 and 5 or 6, whichever has the higher output power, for 5MHz channels; channels 11, 15 and 19 for 10MHz channels; and channels 21 and 25 for 20MHz channels. These are referred to as the "default test channels". 802.11g mode was evaluated only if the output power was 0.25 dB higher than the 802.11b mode.

Table 10.1 802.11 Test channels per FCC Requirements

Mode		GHz	Channel	Turbo Channel	"Default Test Channels"		
					§15.247		UNII
					802.11b	802.11g	
802.11 b/g		2.412	1#		√	▽	
		2.437	6	6	√	▽	
		2.462	11#		√	▽	
802.11a	UNII	5.18	36				√
		5.20	40	42 (5.21 GHz)			*
		5.22	44				*
		5.24	48	50 (5.25 GHz)			√
		5.26	52				√
		5.28	56	58 (5.29 GHz)			*
		5.30	60				*
		5.32	64				√
		5.500	100				*
		5.520	104				√
		5.540	108				*
		5.560	112	Unknown			*
		5.580	116				√
		5.600	120				*
		5.620	124				√
		5.640	128				*
		5.660	132				*
		5.680	136				√
		5.700	140				*
	UNII or §15.247	5.745	149		√		√
		5.765	153	152 (5.76 GHz)		*	*
		5.785	157		√		*
		5.805	161	160 (5.80 GHz)		*	√
	§15.247	5.825	165		√		

10. SAR TEST DATA SUMMARY AND POWER TABLE

See Measurement Result Data Pages

Procedures Used To Establish Test Signal

This device was tested WLAN test program to control DUT. The channel was selected at Low, Middle, and High channel. The output power level was set to rated max output power using the WLAN test program. This output power level was measured and recorded on the report as a begin power.

Device Test Conditions

The EUT is battery operated. Each SAR measurement was taken with a fully charged battery.
In order to verify that the device was tested at full power, conducted output power measurements were performed before and after each SAR measurement to confirm the output power.   If a conducted power deviation of more than 5% occurred, the test was repeated.

Max. Power Output Table for D3 (W-LAN)

Mode	Frequency (MHz)	Channel No.	Output Power (dBm) Using the Average Power Meter
802.11b	2412	1	15.51
	2437	6	15.32
	2462	11	15.50
802.11g	2412	1	12.86
	2437	6	12.73
	2462	11	13.01

※ **SAR is not required for 802.11g channels when the maximum average output power is less than $^1/_4$ dB higher than that measured on the corresponding 802.11b channels.**

Max. Power Output Table for D3 (Bluetooth)

Frequency	Channel No.	Measured Data (dBm)	(mW)
2402	0	-0.285	0.936
2441	39	0.469	1.114
2480	78	0.593	1.146

※ **Bluetooth is not performed because of the output power is $\leq$ 60/f$_{(GHz)}$ mW.**

11. SAR TEST DATA SUMMARY

11.1 Measurement Results (W-LAN (802.11b) Body SAR)

FREQUENCY		Begin Power	Drift Power	Mode	Device Test Position	Antenna Position	SAR
MHz	Ch	(dBm)	(dB)				(W/kg)
2412	**1**	**15.51**	**-0.255**	**802.11b**	**0 mm [Rear]**	**Internal**	**0.804**
2437	6	15.32	-0.047	802.11b	0 mm [Rear]	Internal	0.619
2462	11	15.50	0.345	802.11b	0 mm [Rear]	Internal	0.459
2437	6	15.32	0.349	802.11b	0 mm [Front]	Internal	0.070
ANSI / IEEE C95.1 2005 – SAFETY LIMIT Spatial Peak Uncontrolled Exposure/ General Population Exposure							Body 1.6 W/kg (mW/g) averaged over 1 gram

NOTE:

1. The test data reported are the worst-case SAR value with the antenna-body position set in a typical configuration. Test procedures used are according to FCC/OET Bulletin 65, Supp.C [July 2001].

2. All modes of operation were investigated, and worst-case results are reported.

3. Prior to testing the conducted output power was measured.

4. The EUT is tested 2nd hot-spot peak, if it is less than 2dB below the highest peak.

5. Battery is fully charged for all readings.

6. Test Signal Call Mode   ▣ Continuous Tx On   □ Manu.Test Codes   □ Base Station Simulator

7. Tissue parameters and temperatures are listed on the SAR plots.

8. Liquid tissue depth is 15.0cm.±0.1

9. Justification for reduced test configurations: per FCC/OET Supplement C (July, 2001), if the SAR measured at the middle channel for each test configuration (Left, right, cheek/touch, tilt/ear, extended and retracted) is at least 3.0 dB lower than the SAR limit, testing at the high and low channels is optional for such test configuration(s).

12. SAR TEST EQUOPMENT

	Type	Manufacturer	Model	Cal.Date (dd/mm/yy)	Next.Cal.Date (dd/mm/yy)	S/N
☒	SEMITEC Engineering	SEMITEC	N/A	N/A	N/A	Shield Room
☒	Robot	SCHMID	RX90BL	N/A	N/A	F02/5Q85A1/A/01
☒	Robot Controller	SCHMID	CS7MB	N/A	N/A	F02/5Q85A1/C/01
☒	Joystick	SCHMID	N/A	N/A	N/A	D221340031
☒	Hicron Computer Pentium Celeron 1.1GHz Window2000	N/A	N/A	N/A	N/A	N/A
☒	Probe Alignment Unit LB	N/A	N/A	N/A	N/A	321
☒	Mounting Device	SCHMID	Holder	N/A	N/A	N/A
☒	Sam Phantom	SCHMID	TP1223	N/A	N/A	N/A
☒	Sam Phantom	SCHMID	TP1224	N/A	N/A	N/A
☐	Head/Body Equivalent Matter(450MHz)	N/A	N/A	01/01/11	01/01/12	N/A
☐	Head/Body Equivalent Matter(835MHz)	N/A	N/A	01/01/11	01/01/12	N/A
☐	Head/Body Equivalent Matter(1800MHz)	N/A	N/A	01/01/11	01/01/12	N/A
☐	Head/Body Equivalent Matter(1900MHz)	N/A	N/A	01/01/11	01/01/12	N/A
☒	Head/Body Equivalent Matter(2450MHz)	N/A	N/A	01/01/11	01/01/12	N/A
☒	Data Acquisition Electronics	SCHMID	DAE4	29/04/10	29/04/11	911
☐	Data Acquisition Electronics	SCHMID	DAE3V1	23/11/10	23/11/11	520
☒	Dosimetric E-Field Probe	SCHMID	ES3DV3	22/11/10	22/11/11	3123
☐	Dosimetric E-Field Probe	SCHMID	EX3DV4	26/01/10	26/01/11	3643
☐	Dosimetric E-Field Probe	SCHMID	ET3DV6	06/07/10	06/07/11	1703
☐	Dummy Probe	N/A	N/A	N/A	N/A	N/A
☐	835MHz System Validation Dipole	SCHMID	D835V2	22/03/10	22/03/12	464
☐	1800MHz System Validation Dipole	SCHMID	D1800V2	16/07/10	16/07/12	2d047
☐	1900MHz System Validation Dipole	SCHMID	D1900V2	23/03/10	23/03/12	5d029
☒	2450MHz System Validation Dipole	SCHMID	D2450V2	18/03/10	18/03/12	726
☐	2600MHz System Validation Dipole	SCHMID	D2600V2	27/05/10	27/05/12	1016
☐	3500MHz System Validation Dipole	SCHMID	D3500V2	27/05/10	27/05/12	1018
☒	Network Analyzer	HP	8753D	12/03/10	12/03/11	3410J01204
☒	Signal Generator	HP	ESG-3000A	01/07/10	01/07/11	US37230529
☒	Amplifier	EMPOWER	BBS3Q7ELU	04/10/10	04/10/11	1020
☒	Power Meter	HP	EPM-442A	12/03/10	12/03/11	GB37170267
☒	Power Sensor	HP	8481A	12/03/10	12/03/11	3318A96566
☒	Power Sensor	HP	8481A	12/03/10	12/03/11	3318A90918
☐	Dual Directional Coupler	Agilent	778D-012	11/01/11	11/01/12	50228
☒	Directional Coupler	HP	773D	01/07/10	01/07/11	2389A00640
☐	Low Pass Filter 1.5GHz	Micro LAB	LA-15N	11/01/11	11/01/12	N/A
☒	Low Pass Filter 3.0GHz	Micro LAB	LA-30N	04/10/10	04/10/11	N/A
☒	Attenuators(3dB)	Agilent	8491B	01/07/10	01/07/11	MY39260700
☒	Attenuators(10dB)	WEINSCHEL	23-10-34	11/01/11	11/01/12	BP4387
☐	Step Attenuator	HP	8494A	04/10/10	04/10/11	3308A33341
☒	Dielectric Probe kit	Agilent	85070D	N/A	N/A	US01440118
☐	8960 Series 10 Wireless Comms. Test Set	Agilent	E5515C	02/07/10	02/07/11	GB43461134

NOTE: The E-field probe was calibrated by SPEAG, by temperature measurement procedure. Dipole Validation measurement is performed by Digital EMC before each test. The brain simulating material is calibrated by Digital EMC using the dielectric probe system and network analyzer to determine the conductivity and permittivity (dielectric constant) of the brain-equivalent material.

13. CONCLUSION

Measurement Conclusion

The SAR measurement indicates that the EUT complies with the RF radiation exposure limits of the FCC. These measurements are taken to simulate the RF effects exposure under the worst-case conditions. Precise laboratory measures were taken to assure repeatability of the tests. The tested device complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role impossible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease).

Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables.

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