

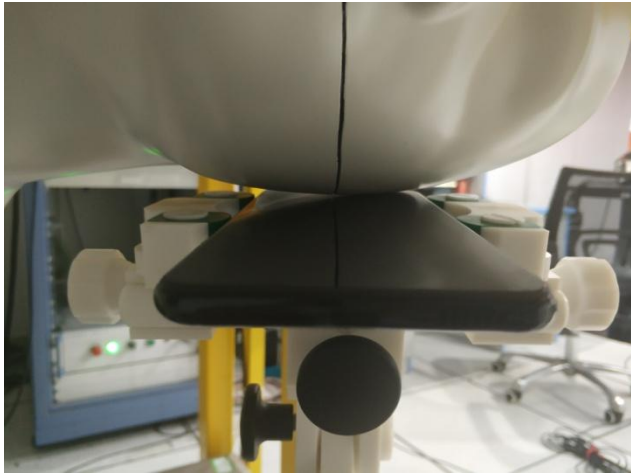
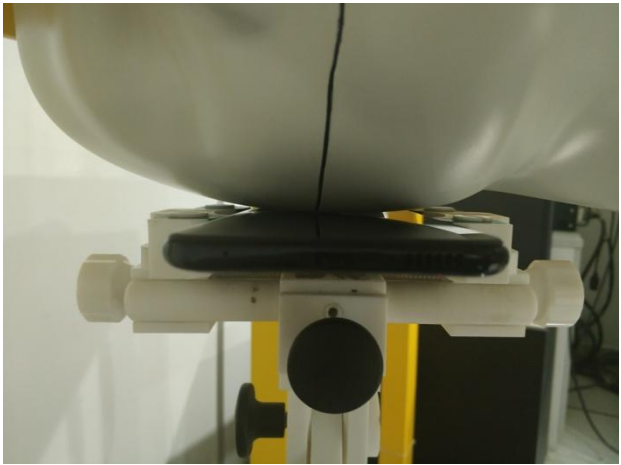
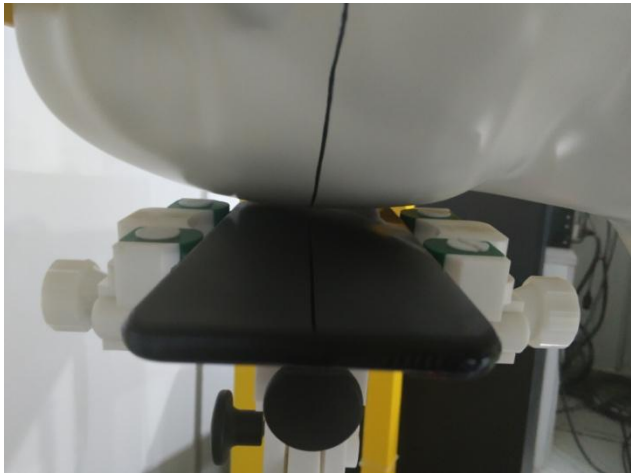


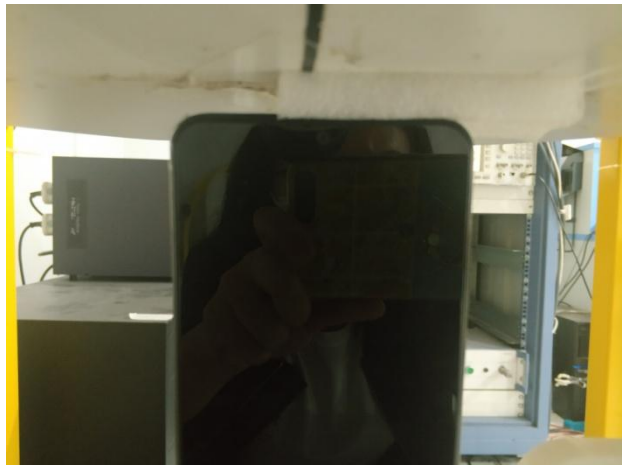
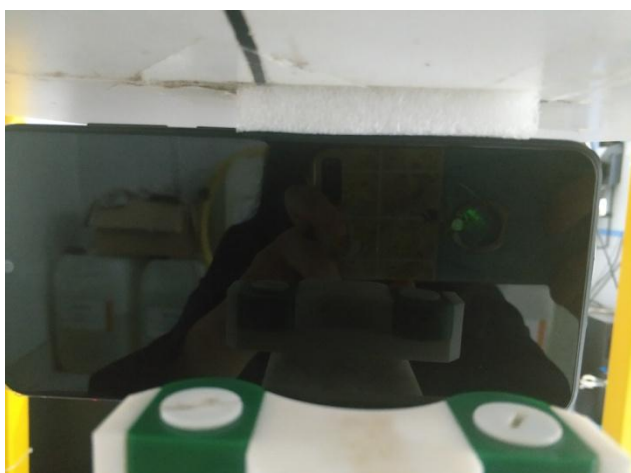



Appendix D: SAR Test Setup

<p>Photo 1: Measurement System SATIMO</p>	<p>Photo 2: Left Cheek</p>
 <p>A photograph showing a white KUKA robotic arm mounted on a table in a laboratory setting. The arm is holding a probe over a white mannequin head. Various electronic equipment and cables are visible in the background.</p>	 <p>A close-up photograph of the left cheek area of the white mannequin head, showing the black probe tip in contact with the surface.</p>
<p>Photo 3: Left Tilt 15 °</p>	<p>Photo 4: Right Cheek</p>
 <p>A close-up photograph of the left cheek area of the white mannequin head, showing the black probe tip in contact with the surface. The head is tilted to the left.</p>	 <p>A close-up photograph of the right cheek area of the white mannequin head, showing the black probe tip in contact with the surface.</p>
<p>Photo 5: Right Tilt 15 °</p>	<p>Photo 6: Face upward 10mm</p>
 <p>A close-up photograph of the right cheek area of the white mannequin head, showing the black probe tip in contact with the surface. The head is tilted to the right.</p>	 <p>A close-up photograph of the white mannequin head with a ruler placed vertically next to it to indicate a height of 10mm.</p>

<p>Photo 7: Back Upward 10mm</p>	<p>Photo 8: Edge A 10mm</p>
	
<p>Photo 9: Edge B 10mm</p>	<p>Photo 10: Edge C 10mm</p>
	
<p>Photo 11: Edge D 10mm</p>	<p>Photo 12: Liquid deep(15cm)</p>
