
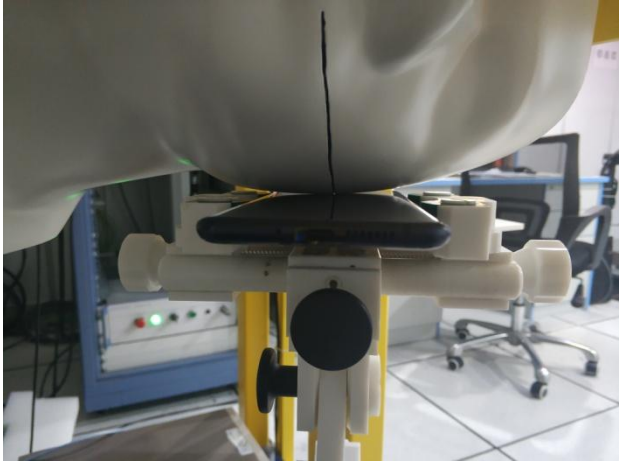

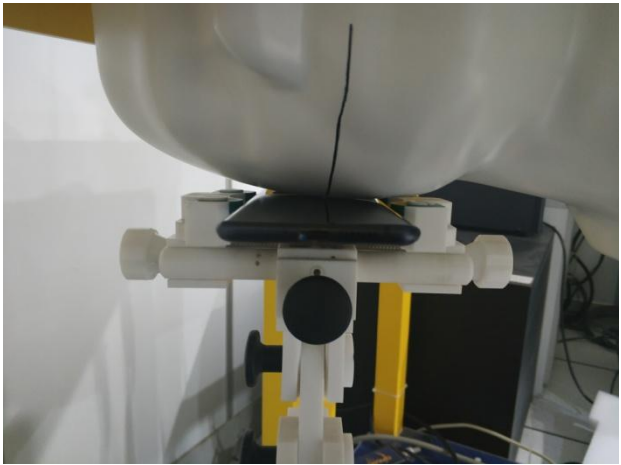
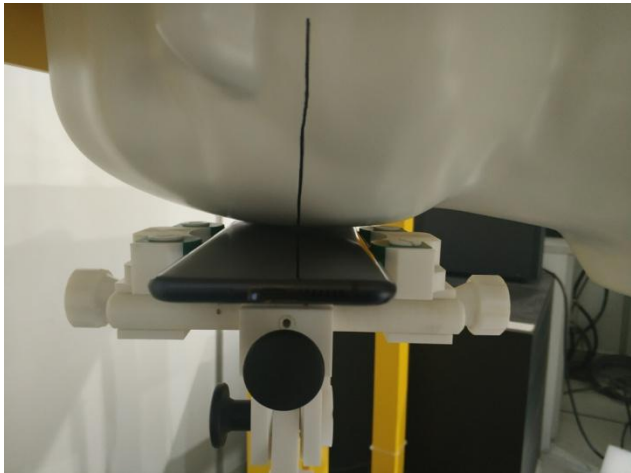


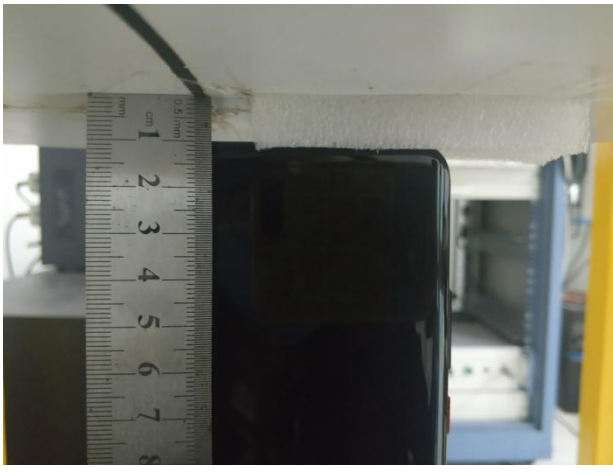

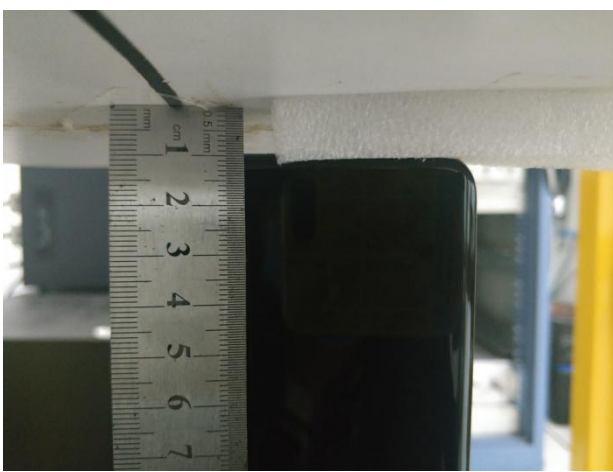


Appendix D: SAR Test Setup

<p>Photo 1: Measurement System SATIMO</p>	<p>Photo 2: Left Cheek</p>
 A photograph showing a white KUKA robotic arm mounted on a yellow stand in a laboratory setting. The arm is positioned over a white mannequin head. Various electronic equipment and cables are visible on a table in the background.	 A close-up photograph of the left cheek area of a white mannequin head. The head is mounted on a white and yellow mechanical fixture. A black circular sensor or probe is visible on the fixture.
<p>Photo 3: Left Tilt 15°</p>	<p>Photo 4: Right Cheek</p>
 A close-up photograph of the left cheek area of a white mannequin head, tilted at a 15-degree angle. The head is mounted on a white and yellow mechanical fixture.	 A close-up photograph of the right cheek area of a white mannequin head. The head is mounted on a white and yellow mechanical fixture.
<p>Photo 5: Right Tilt 15°</p>	<p>Photo 6: Face upward 10mm</p>
 A close-up photograph of the right cheek area of a white mannequin head, tilted at a 15-degree angle. The head is mounted on a white and yellow mechanical fixture.	 A close-up photograph of the face area of a white mannequin head, tilted upwards. A vertical ruler is placed next to the head to indicate a 10mm distance.

<p>Photo 7: Back Upward 10mm</p>	<p>Photo 8: Edge A 10mm</p>
	
<p>Photo 9: Edge B 10mm</p>	<p>Photo 10: Edge C 10mm</p>
	
<p>Photo 11: Edge D 10mm</p>	<p>Photo 12: Liquid deep(15cm)</p>
