Bluetooth Class 1 OEM Module

Parani-BCD110 Product Datasheet

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Sena Technologies, Inc.



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1. General

The Parani-BCD110 is a Bluetooth Class 1 OEM module for OEM manufacturers who want to implement Bluetooth Class 1 functionality with their products cost effectively and also in timely manner. Users can build their own antenna circuit around the BCD110 to lower the overall cost while benefit from the BCD110's field-proven standard SPP (Serial Port Profile) firmware provided with no additional cost.

The BCD110 supports Class 1 Bluetooth transmission level for longer communication distance typically ranges from 100 m up to 1 km. The BCD110 supports UART, USB, I2C, PCM, PIO interfaces for the communication with the OEM products.

The BCD110 is provided with Bluetooth v2.0 compatible firmware runs internally for SPP (Serial Port Profile) applications by default. The SPP firmware supports up to 4 simultaneous multiple connections and is designed to work out-of-box for real world SPP applications such as POS (Point-of-sales), industrial automation, remote metering and other various applications. Optionally, the BCD110 can be supplied with only software stack up to HCI level so entire Bluetooth stack runs on the host side for the application such as USB dongles for computers, or OEM manufacturers can even develop and embed their own firmware into the BCD110.

The BCD110 is fully qualified with Bluetooth v.2.0+EDR specification so OEM manufacturers can save cost and time for overall OEM product certifications, which makes the BCD110 ideal solution for larger volume and cost sensitive applications.

1.1 Features

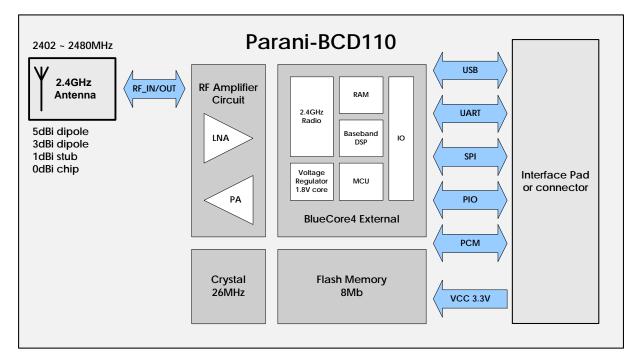
- Bluetooth Class 1
- Fully qualified with Bluetooth v2.0 + EDR specification
- Transmit Power: max. +20dBm
- Receive sensitivity: -90dBm (0.1% BER)
- Size: DIP type 16.8 x 34.6 x 7.5mm with shield can
 - SMD type 14.8 x 34.6 x 3.0mm with shield can
- Extended operating temperature range: -40°C ~ +85°C
- Integrated variable antennas
- Integrated 8Mbit Flash Memory
- USB, Dual UART, I2C, PCM, PIO interfaces
- 802.11 co-existence
- Field-proven SPP (Serial Port Profile) firmware supporting up to 4 simultaneous multiple connections
- RoHS Compliant

1.2 Applications

- High-speed data transceiver systems for long distance communication
- PCs/Personal Digital Assistants (PDA)
- Bluetooth USB dongle
- Bluetooth serial dongle
- Bluetooth access points
- Industrial automation devices
- Remote metering devices
- POS (Point-of-sales) devices



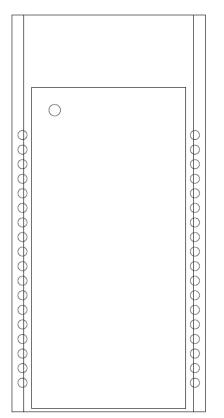
1.3 Device Diagram





1.4 Pin Diagram

| | NAME | DEFINE |
|----|----------|--------------|
| 1 | GND | GND |
| 2 | GND | GND |
| 3 | PVCC | PVCC (+3.3V) |
| 4 | AIO_O | |
| 5 | AIO_1 | |
| 6 | UART_RTS | UART_RTS |
| 7 | UART_RXD | UART_RXD |
| 8 | UART_TXD | UART_TXD |
| 9 | UART_CTS | UART_CTS |
| 10 | USB_DN | USB_DN |
| 11 | USB_DP | USB_DP |
| 12 | PCM_IN | PCM_IN |
| 13 | PCM_SYNC | PCM_SYNC |
| 14 | PCM_CLK | PCM_CLK |
| 15 | PCM_OUT | PCM_OUT |
| 16 | +3V3 | +3V3 |
| 17 | GND | GND |
| 18 | RESETB | RESETB |



| DEFINE | NAME | |
|---------------|----------|----|
| GND | GND | 36 |
| GND | GND | 35 |
| GND | GND | 34 |
| STATUS_LED1 | PI0_11 | 33 |
| STATUS_LED0 | PI0_10 | 32 |
| | PIO_9 | 31 |
| | PIO_8 | 30 |
| UART_DCD | PIO_2 | 29 |
| UART_DTR | PIO_3 | 28 |
| F/C_CTRL | PIO_7 | 27 |
| BT_MODE | PIO_6 | 26 |
| FACTORY RESET | PI0_5 | 25 |
| UART_DSR | PIO_4 | 24 |
| SPI_MOSI | SPI_MOSI | 23 |
| SPI_CSB | SPI_CSB | 22 |
| SPI_CLK | SPI_CLK | 21 |
| SPI_MISO | SPI_MISO | 20 |
| GND | GND | 19 |

Figure 1-2 Pin diagram

1.5 Pin Descriptions

| Function | Pin Name | Pin Number | Description |
|----------------|----------|--------------|---|
| USB Interface | USB_DP | 11 | USB data plus |
| | USB_DN | 10 | USB data minus |
| UART Interface | UART_TXD | 8 | UART data output |
| | UART_RXD | 7 | UART data input |
| | UART_RTS | 6 | UART request to send active low |
| | UART_CTS | 9 | UART clear to send active low |
| PCM Interface | PCM_OUT | 15 | Synchronous data output |
| | PCM_IN | 12 | Synchronous data input |
| | PCM_SYNC | 13 | Synchronous data sync |
| | PCM_CLK | 14 | Synchronous data clock |
| SPI Interface | SPI_MISO | 20 | SPI data output |
| | SPI_MOSI | 23 | SPI data input |
| | SPI_CSB | 22 | Chip select for SPI, active low |
| | SPI_CLK | 21 | SPI clock |
| PIO Interface | PIO_2 | 29 | Programmable input/output line |
| | PIO_3 | 28 | Programmable input/output line |
| | PIO_4 | 24 | Programmable input/output line |
| | PIO_5 | 25 | Programmable input/output line |
| | PIO_6 | 26 | Programmable input/output line |
| | PIO_7 | 27 | Programmable input/output line |
| | PIO_8 | 30 | Programmable input/output line |
| | PIO_9 | 31 | Programmable input/output line |
| | PIO_10 | 32 | Programmable input/output line |
| | PIO_11 | 33 | Programmable input/output line |
| AIO | AIO_0 | 4 | Analogue programmable input/output line |
| | AIO_1 | 5 | Analogue programmable input/output line |
| Power | PVCC | 3 | Power supply for power amplifier, 3.3V |
| | +3V3 | 16 | Power supply for system, 3.3V |
| | GND | 1, 2, 17, 19 | Ground |
| | | 34, 35, 36 | |
| Others | RESETB | 18 | Reset, active low, > 5ms to cause a reset |

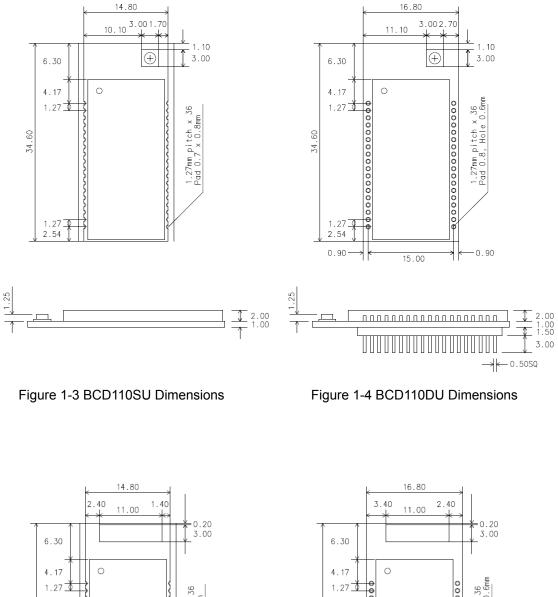
Table 1-1 Pin descriptions

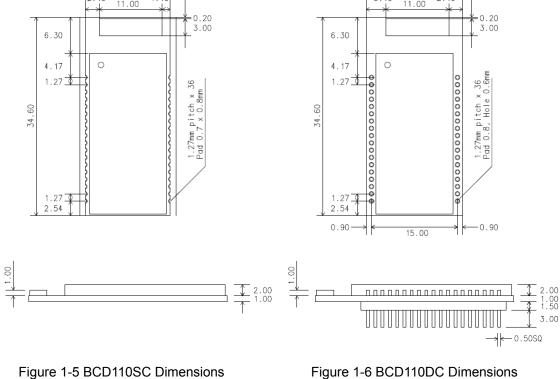
| Function | Pin Name | STATE | | |
|----------|----------|---------------|-----------|--------------------------------|
| | | Define (SPP) | Direction | Pull-up/down |
| USB | USB_DP | - | Input | Weak pull-up |
| | USB_DN | - | Input | Weak pull-up |
| UART | UART_TXD | UART_TXD | Output | Tri-stated with weak pull-up |
| | UART_RXD | UART_RXD | Input | Weak pull-down |
| | UART_RTS | UART_RTS | Output | Tri-stated with weak pull-up |
| | UART_CTS | UART_CTS | Input | Weak pull-down |
| РСМ | PCM_OUT | - | Output | Tri-stated with weak pull-down |
| | PCM_IN | - | Input | Weak pull-down |
| | PCM_SYNC | - | Input | Weak pull-down |
| | PCM_CLK | - | Input | Weak pull-down |
| SPI | SPI_MISO | - | Output | Tri-stated with weak pull-down |
| | SPI_MOSI | - | Input | Weak pull-down |
| | SPI_CSB | - | Input | Weak pull-up |
| | SPI_CLK | - | Input | Weak pull-down |
| PIO | PIO_2 | UART_DCD | Output | Weak pull-down |
| | PIO_3 | UART_DTR | Output | Weak pull-down |
| | PIO_4 | UART_DSR | Input | Weak pull-up |
| | PIO_5 | FACTORY_RESET | Input | Weak pull-up |
| | PIO_6 | BT_MODE | Input | Weak pull-up |
| | PIO_7 | F/C_CTRL | Output | Weak pull-up |
| | PIO_8 | - | Input | Weak pull-down |
| | PIO_9 | - | Input | Weak pull-down |
| | PIO_10 | STATUS_LED0 | Output | Weak pull-down |
| | PIO_11 | STATUS_LED1 | Output | Weak pull-down |
| AIO | AIO_0 | - | Output | Driving low |
| | AIO_1 | - | Output | Driving low |
| Others | RESETB | RESETB | Input | Weak pull-up |

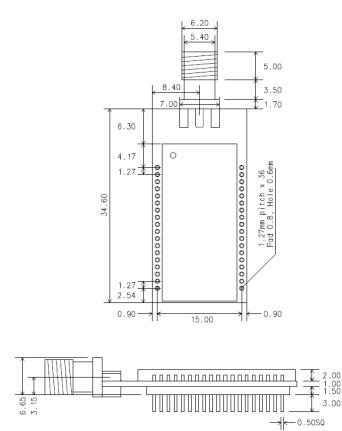
Table 1-2 Pin States on Reset (SPP)

1.6 Dimensions and PCB land pattern

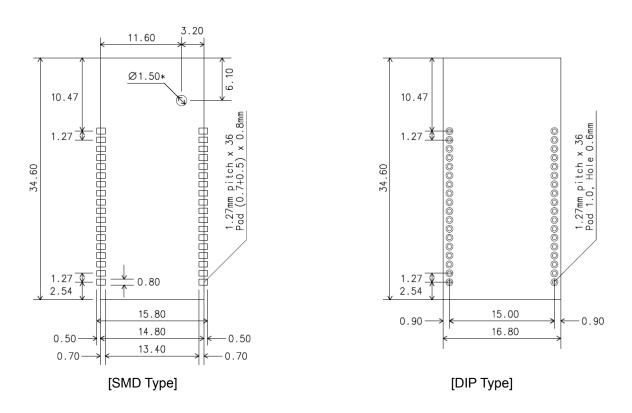
SENA













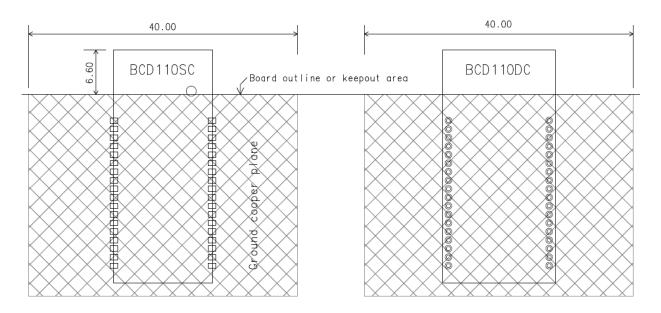


Figure 1-4 Recommended Board Layout

*BCD110SU, DU, DS has no keep-out area.

Model despription

| | | | Antenna | | | |
|-------------------------------|------------------|----------------------|-------------|-------------|-----------|--|
| Model name | Interface | Connector | Туре1 | Туре2 | Туре3 | |
| Parani-BCD110 DU | D IP, pin | U .FL | 5dBi dipole | 3dBi dipole | 1dBi stub | |
| Parani-BCD110 <mark>DS</mark> | D IP, pin | RP <mark>S</mark> MA | 5dBi dipole | 3dBi dipole | 1dBi stub | |
| Parani-BCD110 DC | D IP, pin | CHIP | 0dBi Chip | | | |
| Parani-BCD110 <mark>SU</mark> | SMD, pad | U .FL | 5dBi dipole | 3dBi dipole | 1dBi stub | |
| Parani-BCD110 <mark>SC</mark> | SMD, pad | CHIP | 0dBi Chip | | | |

2. Electrical characteristics

2.1 Absolute maximum ratings

| Ratings | | Min | Max | Unit |
|-------------------------|---------------------|-----------|-----------|------|
| Storage Temperature | | -40 | +85 | °C |
| Operating Temperature | | -40 | +85 | °C |
| Supply voltage | Supply voltage PVCC | | 3.6 | V |
| | +3V3 | -0.4 | 3.6 | V |
| Other terminal voltages | | GND – 0.4 | +3V3 +0.4 | V |

Table 2-1 Absolute maximum ratings

2.2 Recommended operating conditions

| Ratings | | Min | Тур | Max | Unit |
|------------------|--------|-----|-----|-----|------|
| Operating Temper | rature | -40 | 25 | +85 | °C |
| Supply voltage | PVCC | 2.7 | 3.3 | 3.6 | V |
| | +3V3 | 2.7 | 3.3 | 3.6 | V |
| | UART | 3.0 | 3.3 | 3.6 | V |
| | USB | 3.1 | 3.3 | 3.6 | V |
| Supply current | PVCC | 100 | 150 | 200 | mA |
| | +3V3 | 40 | 50 | 100 | mA |

Table 2-2 Recommended operating conditions

* Total current consumption = operating mode: max 100mA, test mode: max. 200mA

2.3 Power Consumptions

| Role | Operation Mode | UART Rate(kbps) | Current | Unit |
|------|---------------------------|-----------------|---------|------|
| - | Inquiry and page Scan | 115.2 | 76 | mA |
| - | Power on (Standby) | 115.2 | 2 | mA |
| | Connectable Mode(Mode3) | 115.2 | 18 | mA |
| | Connected (No data) | 115.2- | 15 | mA |
| | Connected (file transfer) | 115.2 | 45 | mA |
| | Connected (file transfer) | 9.6 | 55 | mA |

Table 2-3 Power consumptions (SPP)

3. **RF** Characteristics

3.1 Basic Data Rate

3.1.1 Transmitter Performance

| RF Characteristics | | Min | Тур | Max | Bluetooth | Unit |
|-------------------------------------|-----------------------------------|------|------|------|---|----------|
| PVCC = 3.3V, 25°C | | | | | Specification | |
| Output power | | 16 | 18 | 19 | ≤ 20 | dBm |
| Power Density | | 16 | 18 | 19 | ≤ 20 | dBm |
| Power Control | | 3 | 4 | 6 | 2 ≤ step ≤ 8 | dB |
| TX Output Spectro | um-Frequency range | 2402 | - | 2480 | 2400 ~2483.5 | MHz |
| TX Output Spectro | um-20dB Bandwidth | - | 900 | - | ≤ 1000 | kHz |
| Adjacent | $F = F_0 \pm 2MHz$ | - | - | -20 | ≤ -20 | dBm |
| Channel Power | $F = F_0 \pm 3MHz$ | - | - | -40 | ≤ -40 | dBm |
| | $F = F_0 \pm > 3MHz$ | - | - | -40 | ≤ -40 | dBm |
| Modulation | $\Delta f1_{avg}$ | 145 | 165 | 175 | 140 ≤ ∆f1 _{avg} ≤ 175 | kHz |
| Characteristics | $\Delta f2_{avg}$ | 115 | 155 | - | ∆f2 _{avg} ≥ 115 | kHz |
| | $\Delta f2_{avg}/\Delta f1_{avg}$ | 0.8 | 0.95 | - | $(\Delta f1_{avg}/\Delta f2_{avg}) \ge 0.8$ | - |
| Initial Carrier Frequency Tolerance | | -20 | - | 20 | ≤ ±75 | kHz |
| Carrier | Drift rate | -20 | - | 20 | ≤ ±20 | kHz/50µs |
| Frequency Drift | 1 slot Freq Drift | -25 | - | 25 | ≤ ±25 | kHz |
| | 5 slot Freq Drift | -40 | - | 40 | ≤ ±40 | kHz |

Table 3-1 Transmitter performance at basic data rate

3.1.2 Transceiver

| RF Characteristics | | Min | Тур | Max | Bluetooth | Unit |
|--------------------|----------------|-----|-----|-----|---------------|------|
| PVCC = 3.3V, 25°C | | | | | Specification | |
| Out of band | 0.030-1.000GHz | -36 | - | - | ≤ -36 | dBm |
| Spurious | 1.000-12.75GHz | -30 | - | - | ≤ -30 | dBm |
| Emissions | 1.800-5.100GHz | -47 | - | - | ≤ -47 | dBm |
| | 5.100-5.300GHz | -47 | - | - | ≤ -47 | dBm |

Table 3-2 Transceiver at basic data rate

3.1.3 Receiver Performance

| RF Characteristics | | Min | Тур | Max | Bluetooth | Unit |
|----------------------|-----------------------|-----|-----|-----|---------------|------|
| Temperature 25°C | | | | | Specification | |
| Sensitivity - Single | e slot packets (0.1%) | - | -90 | -70 | ≤ -70 | dBm |
| Sensitivity - Multi | slot packets (0.1%) | - | -90 | -70 | ≤ -70 | dBm |
| C/I performance | co-channel | - | - | -11 | ≤ -11 | dB |
| at 0.1% BER | $F = F_0 + 1MHz$ | - | - | 0 | ≤ 0 | kHz |
| | $F = F_0 - 1MHz$ | - | - | 0 | ≤ 0 | dB |

| | $F = F_0 + 2MHz$ | - | - | -20 | ≤ -20 | dB |
|---------------------------------|------------------------|-----|---|-----|-------|-----|
| | $F = F_0 - 2MHz$ | - | - | -30 | ≤ -30 | dB |
| | $F = F_0 - 3MHz$ | - | - | -40 | ≤ -40 | dB |
| | $F = F_0 + 5MHz$ | - | - | -40 | ≤ -40 | dB |
| | F = F _{Image} | | - | -9 | ≤ -9 | dB |
| Blocking | 0.030-2.000GHz | -10 | - | - | ≥ -10 | dBm |
| performance | 2.000-2.400GHz | -27 | - | - | ≥ -27 | dBm |
| | 2.500-3.000GHz | -27 | - | - | ≥ -27 | dBm |
| | 3.000-12.75GHz | -10 | - | - | ≥ -10 | dBm |
| Inter-modulation performance | | -39 | - | - | ≥ -39 | dBm |
| Maximum input level at 0.1% BER | | -20 | 0 | - | ≥ -20 | dBm |

 Table 3-3 Receiver Performance at basic data rate

3.2 Enhanced Data Rate

3.2.1 Transmitter performance

| RF Characteristics | | Min | Тур | Max | Bluetooth | Unit | |
|---------------------------------|--|---------------------------------|-----|-----|-----------|------------------------------|-----|
| PVCC = 3.3V, Temperature 25°C | | | | | | Specification | |
| Maximum RF Transmit Power | | | -2 | 2 | - | -6 to +4 | dB |
| Relative Transmit Power | | -4 | - | 1 | -4 to +1 | dB | |
| Carrier | π/4 | ω ₀ | -10 | - | 10 | $\leq \pm 10$ for all blocks | kHz |
| Frequency | DQPSK | ω _i | -75 | - | 75 | ≤ ±75 for all packets | kHz |
| Stability | | ω ₀ + ω _i | -75 | - | 75 | ≤ ±75 for all blocks | kHz |
| | 8DPSK | ω₀ | -10 | - | 10 | ≤ ±10 for all blocks | kHz |
| | | ω _i | -75 | - | 75 | ≤ ±75 for all packets | kHz |
| | | ω ₀ + ω _i | -75 | - | 75 | ≤ ±75 for all blocks | kHz |
| Modulation | π/4 | RMS DEVM | - | - | 20 | ≤ 20 | % |
| Accuracy | DQPSK | 99% DEVM | - | - | 30 | ≤ 30 | % |
| | | Peak DEVM | - | - | 35 | ≤ 35 | % |
| | 8DPSK | RMS DEVM | - | - | 13 | ≤ 13 | % |
| | | 99% DEVM | - | - | 20 | ≤ 20 | % |
| | | Peak DEVM | - | - | 25 | ≤ 25 | % |
| EDR Differential Phase Encoding | | 99 | - | - | ≥ 99 | % | |
| In-band | $F \ge F_0 + 3MHz$ | | - | - | -40 | ≥ -40 | dBm |
| Spurious | F < F ₀ + 3MHz | | - | - | -40 | ≥ -40 | dBm |
| Emissions | $F = F_0 - 3MHz$ | | - | - | -40 | ≥ -40 | dBm |
| (8DPSK) | $F = F_0 - 2MHz$ | | - | - | -20 | ≥ -20 | dBm |
| | $F = F_0 - 1MHz$ $F = F_0 + 1MHz$ $F = F_0 + 2MHz$ $F = F_0 + 3MHz$ | | - | - | -26 | ≥ -26 | dB |
| | | | - | - | -26 | ≥ -26 | dB |
| | | | - | - | -20 | ≥ -20 | dBm |
| | | | - | - | -40 | ≥ -40 | dBm |

Table 3-4 Transmitter performance at enhanced data rate

3.2.2 Receiver performance

| RF Characteristics | | Min | Тур | Max | Bluetooth | Unit | |
|-------------------------------|------------------------|-----------|-----|-----|---------------|-------|-----|
| Temperature 25°C | | | | | Specification | | |
| Sensitivity | | π/4 DQPSK | - | -88 | -70 | ≤ -70 | dBm |
| at 0.01% BER | | 8DPSK | - | -85 | -70 | ≤ -70 | dBm |
| BER floor performance | | | - | - | -60 | ≤ -60 | dBm |
| C/I Performance | | π/4 DQPSK | - | - | 13 | ≤ +13 | dB |
| (co-channel at 0.1% BER) | | 8DPSK | - | - | 21 | ≤ +21 | dB |
| C/I | $F = F_0 + 1MHz$ | π/4 DQPSK | - | - | 0 | ≤ 0 | dB |
| Performance | | 8DPSK | - | - | 5 | ≤ +5 | dB |
| (Adjacent | $F = F_0 - 1MHz$ | π/4 DQPSK | - | - | 0 | ≤ 0 | dB |
| Channel | | 8DPSK | - | - | 5 | ≤ +5 | dB |
| Selectivity) | $F = F_0 + 2MHz$ | π/4 DQPSK | - | - | -30 | ≤ -30 | dB |
| | | 8DPSK | - | - | -25 | ≤ -25 | dB |
| | $F = F_0 - 2MHz$ | π/4 DQPSK | - | - | -20 | ≤ -20 | dB |
| | | 8DPSK | - | - | -13 | ≤ -13 | dB |
| | $F \ge F_0 + 3MHz$ | π/4 DQPSK | - | - | -40 | ≤ -40 | dB |
| | | 8DPSK | - | - | -33 | ≤ -33 | dB |
| | $F \leq F_0 - 5MHz$ | π/4 DQPSK | - | - | -40 | ≤ -40 | dB |
| | | 8DPSK | - | - | -33 | ≤ -33 | dB |
| | F = F _{Image} | π/4 DQPSK | - | - | -7 | ≤ -7 | dB |
| | | 8DPSK | - | - | 0 | ≤ 0 | dB |
| Maximum input level π/4 DQPSK | | -20 | - | - | ≥ -20 | dBm | |
| at 0.1% BER 8DPSK | | 8DPSK | -20 | - | - | ≥ -20 | dBm |

Table 3-5 Receiver performance at enhanced data rate

4. Device Terminal Descriptions

4.1 UART Interface

UART (Universal Asynchronous Receiver and Transmitter) interface provides a simple mechanism for communicating with other serial device using the RS232 protocol. When BCD110 is connected to another digital device, UART_RX and UART_TX transfer data between the two devices. The remaining two signals, UART_CTS, UART_RTS, can be used to implement RS232 hardware flow control where both are active low indicators. All UART connections are implemented using CMOS technology and have signaling levels of 0V and 3.3V

| Parameter | | Possible Values | | | |
|---------------------|---------|---------------------|--|--|--|
| Baud Rate Minimum | | 1200 baud (2%Error) | | | |
| | Maximum | 3M baud (1%Error) | | | |
| Flow Control | | RTS/CTS or None | | | |
| Parity | | None, Odd or Even | | | |
| Number of Stop Bits | | 1 or 2 | | | |
| Bits per Channel | | 8 | | | |

Table 4-1 Possible UART Settings

4.2 USB Interface

BCD110 USB devices contain a full speed (12Mbits/s) USB interface that is capable of driving of a USB cable directly. No external USB transceiver is required. The device operates as a USB peripheral, responding to requests from a master host controller such as a PC. Both the OHCI and the UHCI standards are supported. The set of USB endpoints implemented behave as specified in the USB section of the Bluetooth specification v2.0+EDR or alternatively can appear as a set of endpoints appropriate to USB audio devices such as speakers. As USB is a Master/Slave oriented system (in common with other USB peripherals), BCD110 only supports USB slave operation.

The USB data lines emerge as pins USB_DP and USB_DN. These terminals are connected to the internal USB I/O buffers of the BCD110, therefore, have low output impedance. To match the connection to the characteristic of the USB cable, resistors must be placed in series with USB_DP/USB_DN and the cable. BCD110 features an internal USB pull-up resistor. This pulls the USB_DP pin weakly high when BCD110 is ready to enumerate. It signals to the PC that it is a full speed (12Mbit/s) USB device.

The USB internal pull-up is implemented as a current source, and is compliant with section 7.1.5 of the USB specification v1.2. The internal pull-up pulls USB_DP high to at least 2.8V when loaded with a $15K\Omega\pm5\%$ pull-down resistor (in the hub/host) when VDD_PADS=3.1V. This presents a Thevenin resistance to the host of at least 900 Ω .

4.3 I2C Interface

PIO[8:6] can be used to form a mater I²C interface. The interface is formed using software to drive these lines. Therefore, it is suited only to relatively slow functions such as driving a dot matrix LCD (*Liquid Crystal Display*), keyboard scanner or EEPROM.

Notes:

PIO lines need to be pull-up through 2.2K Ω resistors.

PIO[7:6] dual functions, UART bypass and EEPROM support, therefore, devices using an EEPROM cannot support UART bypass mode.

For connection to EEPROMs, refer to CSR documentation on I²C EEPROM for use with BlueCore. This provides information on the type of devices currently supported.

4.4 PCM CODEC Interface

PCM (*Pulse Code Modulation*) is a standard method used to digitize audio (particularly voice) for transmission over digital communication channels. Through its PCM interface, BCD110 has hardware support for continual transmission and reception of PCM data, thus reducing processor overhead for wireless headset applications. BCD110 offers a bi-directional digital audio interface that route directly into the baseband layer of the on-chip firmware. It does not pass through the HCI protocol layer.

Hardware on BCD110 allows the data to be sent to and received from a SCO connection.

Up to three SCO connections can be supported by the PCM interface at any on time.

BCD110 can operate as PCM interface Master generating an output clock of 128, 256, or 512kHz. When configured as PCM interface slave, it can operate with an input clock up to 2048kHz. BCD110 is compatible with a variety of clock formats, including Long Frame Sync, Short Frame Sync and GCI timing environments.

BCD110 interfaces directly to PCM audio devices including the following:

- Qualcomm MSM 3000 series and MSM 5000 series CDMA baseband devices
- OKI MSM7705 four channel A-raw and u-law CODEC
- Motorola MC145481 8-bit A-law and u-law CODEC
- Motorola MC145483 13-bit linear CODEC
- STW 5093 and 5094 14-bit linear CODECs
- BCD110 is also compatible with the Motorola SSITM interface

4.5 I/O Parallel Ports

PIO lines can be configured through software to have either weak or strong pull-downs. All PIO lines are configured as inputs with weak pull-downs at reset.

Any of the PIO lines can be configured as interrupt request lines or as wake-up lines from sleep modes. PIO_6 or PIO_2 can be configured as a request line for an external clock source. This is useful when the clock to BCD110 is provided from a system ASIC (*Application Specific Integrated Circuit*). Using PSKEY_CLOCK_REQUEST_ENABLE (0x246), this terminal can be configured to be low when BCD110 is in Deep Sleep and high when a clock is required. The clock must be supplied within 4ms of the rising edge of PIO_6 or PIO_2 to avoid losing timing accuracy in certain Bluetooth operating modes. BCD110 has three general purpose analogue interface pins, AIO_0 and AIO_1. These are used to access internal circuitry and control signals. One pin is allocated to decoupling for the on-chip band gap reference voltage, the other two may be configured to provide additional functionality.

4.6 Reset Interface

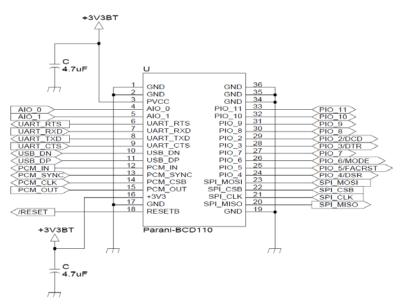
BCD110 may be reset from several sources: RESETB pin, power on reset, a UART break character or via a software configured watchdog timer.

The RESETB pin is an active low reset and is internally filtered using the internal low frequency clock oscillator. A reset will be performed between 1.5 and 4.0ms following RESETB being active. It is recommended that RESETB be applied for a period greater than 5ms.

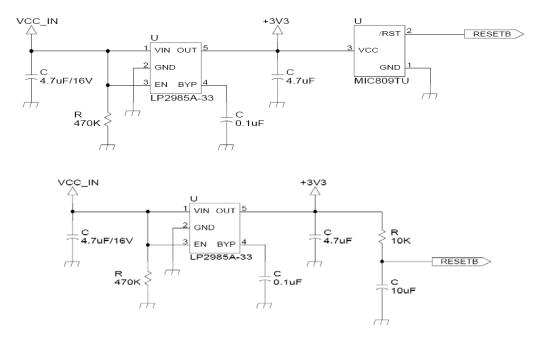
The power on reset occurs when the VDD_CORE supply falls below typically 1.5V and is released when VDD_CORE rises above typically 1.6V.

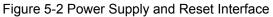
At reset the digital I/O pins are set to inputs for bi-directional pins and outputs are tri-state. The PIOs have weak pull-downs.

5. Application Schematic

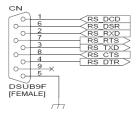


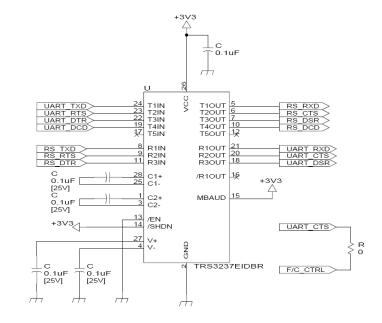


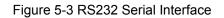












MICOM Parani-BCD100 TXD UART_RXD 8 RXD UART_TXD 9 RTS UART_CTS стѕ 6 UART_RTS 29 DTR UART_DSR 28 DSR UART_DTR 24 UART_DCD DCD

[When TTL level of MICOM is 3.3V]

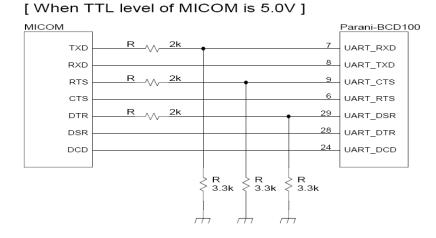
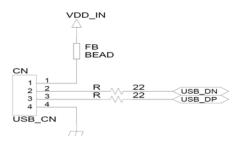
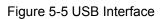
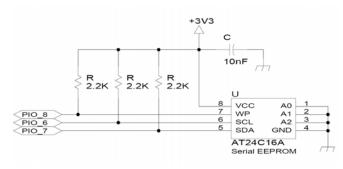
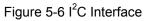


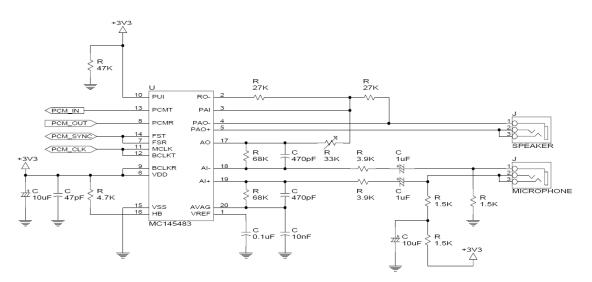
Figure 5-4 MICOM UART Interface













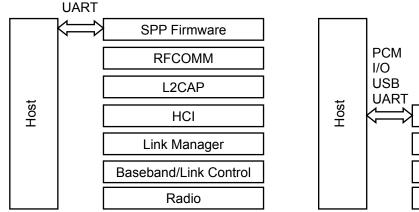
6. Software Stack

BCD110 is provided with Bluetooth v2.0 compatible firmware runs internally for SPP (Serial Port Profile) applications by default. The firmware is designed to work out-of-box for real world SPP applications such as POS (Point-of-sales), industrial automation, remote metering and other various applications.

The SPP firmware can be configured and controlled by typical AT commands. Users can easily configure BCD110 by using a terminal program such as HyperTerminal and can use Bluetooth wireless communication without modifying user's existing serial communication program. In addition to the basic AT commands, BCD110 provides some expanded AT commands for various functions. User friendly ParaniWizard and ParaniWIN are also provided for easy setup on Microsoft Windows. To run AT commands on the BCD110, the BCD110 should be connected to the serial port of the user's own board or equivalent to carry the BCD110.

The SPP firmware provided with the BCD110 is identical to the firmware of the Parani-ESD100V2 and Parani-ESD110V2. To shorten the overall development cycle or for quick verification during or before own development work, users might want to try ESD100V2/110V2 starter kits first for convenience. Also, please refer to the ESD100V2/110V2 user's manual for overall concept, configuration and complete AT commands list of the SPP firmware. The ESD100V2/110V2 user's manual can be downloaded from Sena support home page at http://www.sena.com/support/downloads/.

Optionally, the BCD110 can be supplied with only software stack up to HCI level so users can develop and embed their own firmware version into the BCD110 or entire Bluetooth stack runs on the host side for the application such as USB dongle for computers. Regarding these custom firmware options, please contact a Sena representative for more detail.



Baseband/Link Control Radio

HCI

Link Manager

Figure 6-1 SPP Firmware Bluetooth software stack

Figure 6-2 HCI firmware Bluetooth Software Stack

SENA

7. Solder Profiles

The soldering profile depends on various parameters necessitating a set up for each application. The data here is given only for guidance on solder re-flow. There are four zones:

- **Preheat Zone** This zone raises the temperature at a controlled rate, typically 1-2.5°C /s
- Equilibrium Zone This zone brings the board to a uniform temperature and also activates the flux. The duration in this zone (typically 2-3 minutes) will need to be adjusted to optimize the out gassing of the flux.
- **Reflow Zone** The peak temperature should be high enough to achieve good wetting but not so high as to cause component discoloration or damage. Excessive soldering time can lead to intermetallic growth which can result in a brittle joint.
- **Cooling Zone** The cooling rate should be fast, to keep the solder grains small which will give a longer lasting joint. Typical rates will be 2-5°C/s

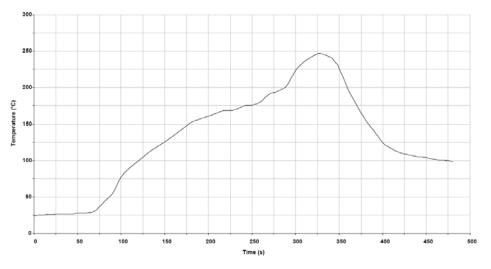


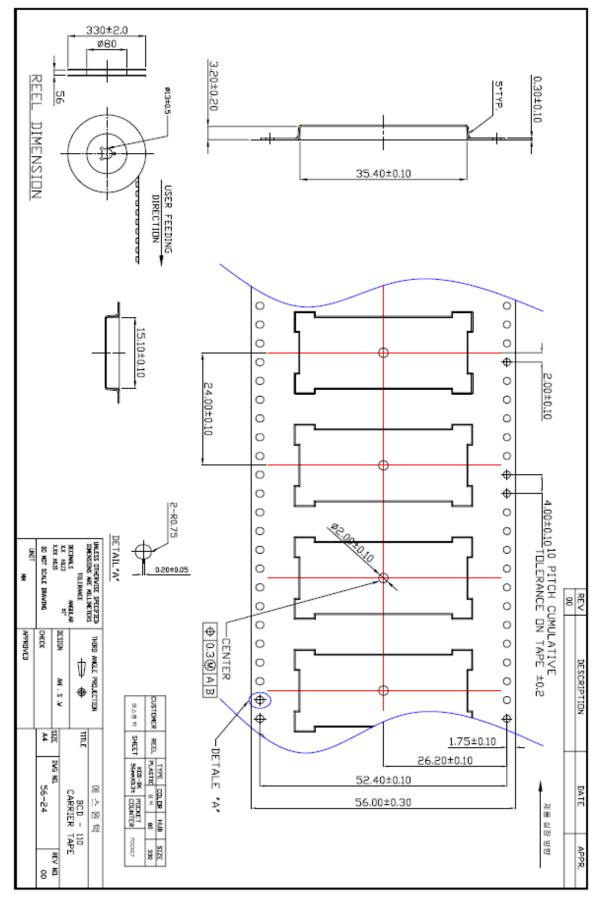
Figure 7-1 Typical Lead-Free Re-flow Solder Profile

Key features of the profile:

- Initial Ramp = 1-2.5°C/sec to 175°C±25°C equilibrium
- Equilibrium time = 60 to 180 seconds
- Ramp to Maximum temperature (245°C) = 3°C/sec max.
- Time above liquids temperature (217°C): 45~90 seconds
- Device absolute maximum reflow temperature: 260°C

The BCD110 will withstand the specified profile up to two reflows to a maximum temperature of 260°C

8. Packaging Information







TBD

Figure 8-2 Reel Information

9. Certificate Information

9.1 FCC

FCC Rule: Part 15 Subpart C Section 15.247 FCCID: S7AIW02

9.1.1 FCC Compliance Statement

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) This device must accept any interference received,

Including interference that may cause undesired operation

Information to User

This equipment has been tested and found to comply with limits for a Class B digital device, Pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation.

This equipment generate, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications.

However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by on or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver-Connect the equipment into an outlet a circuit different form that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

9.1.2 RF Exposure Statement

The equipment complies with FCC RF radiation exposure limits set forth for an uncontrolled environment. This device and its antenna must not be co-located or operation in conjunction with any other antenna or transmitter.

9.1.3 Do not

Any changes or modifications to the equipment not expressly approved by the party responsible for compliance could void user's authority to operate the equipment.

To comply with FCC RF exposure compliance requirements, the antenna used for this transmitter must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operate in conjunction with any other antenna or transmitter."

As such, the radio component of this device is intended only for OEM integrators under the following two conditions: The antenna must be installed such that 20 cm is maintained between the antenna and users. The transmitter module may not be co-located with any other transmitter or antenna.

As long as the two conditions above are met, further transmitter testing will not be required. However, the OEM integrator is still responsible for testing their end product for any additional compliance requirements required with this module installed (e.g., digital device emissions, PC peripheral requirements).

In the event that these conditions cannot be met (for example, co-location with another transmitter), then the FCC authorization is no longer considered valid and the FCC ID cannot be used on the final product. In these circumstances, the OEM integrator will be responsible for re-evaluating the end product (including the transmitter) and obtaining a separate FCC authorization.

End Product Labeling

The final end product must be labeled in a visible area with the following :

"Contains Transmitter Module FCC ID: S7AIW02".

The radio component is an integral part of the Parani-BCD110DU and cannot be removed.



9.2 CE

€€1177

Declare under our own responsibility that the product Bluetooth Module Brand name: SENA Model No.: Parani-BCD110DU / Parani-BCD110DC / Parani-BCD110DS Parani-BCD110SU / Parani-BCD110SC To which this declaration refers conforms with the relevant standards or other standardizing documents EN 60950-1 ETSI EN 301 489-1 ETSI EN 301 489-17 ETSI EN 300 328 According to the regulations in **Directive 1999/5/EC**

9.3 IC

"This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device."

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes : (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Radio Cert. No.: IC: 8154A-IW02

9.4 KC

Type Registration Certification No: KCC-CRM-SNA-IW02

9.5 TELEC

Technical Regulations for Specified Radio Equipment Article 2, Section 1 (19) Certification No:

9.6 SIG

QDID: B016862 Model Name: Parani-BCD110 Core Version: 2.0+EDR Product Type: End Product Declared Specifications: Baseband Conformance, Radio, Service Discovery Protocol, Logical Link Control and Adaption Protocol, Generic Access Profile, Link Manager, RFCOMM, Serial Port Profile, Host Controller Interface, Summary ICS, Product Type