

SGS TESTING KOREA

TEST – REPORT

SAR Compliance Test Report

Test report no.:

STROS-05-005

SAR



Report File No. : STROS-05-005

Date of Issue : 5 MAY 2005

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1 General Information

1.1 Notes

The purpose of conformity testing is to increase the probability of adherence to the essential requirements or conformity specifications, as appropriate. The complexity of the technical specifications, however, means that full and thorough testing is impractical for both technical and economic reasons. Furthermore, there is no guarantee that a test sample which has passed all the relevant tests conforms to a specification. The existence of the tests nevertheless provides the confidence that the test sample possesses the qualities as maintained and that its performance generally conforms to representative cases of communications equipment.

The test results of this test report relate exclusively to the item tested as specified in 1.5. The test report may only be reproduced or published in full. Reproduction or publication of extracts from the report requires the prior written approval of the SGS Testing Korea.

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualification of all persons taking them.

Tester:

03.MAY.2005

Elvin Lee

Date

Name

Signature

Technical responsibility for area of testing:

05.MAY.2005

James Kwon

Date

Name

Signature

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1.2 Location of Testing laboratory

SGS Testing Korea Co., Ltd.

18-34, Sanbon-dong, Gunpo-si, Gyeonggi-do
Korea

Telephone : +82 31 428 5700

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1.3 Details of approval holder

Name Entel UK Ltd.

Address 4 Elstree Gate, Elstree Way
Borehamwood, Herts. WD6 1JD

Country United Kingdom

Telephone +44 208 236 0032

Fax +44 208 236 0082

Contact Metin Pallenberg

E-Mail sales@entel.co.uk**1.4 Manufacturer: (if applicable)**

Name :

Street :

Town :

Country :

1.5 Test item

FCC ID :	RV6HT780
Description of test item :	UHF Transceiver
Type identification :	HT780
Serial number :without;	Identical prototype
Device category :	PCF (Licensed Portable Transmitter Held To Face)

Technical data

Tx Frequency range :	440 – 470 MHz
Rx Frequency range :	440 – 470 MHz
Max. Conducted RF output power :	4.0 W
Power supply :	7.4 V DC rechargeable battery
Antenna Tx :	external
Antenna Rx :	external
Antenna type :	Whip
Antenna Additional information :	Tx and Rx. antenna are the same.

1.6 Test Results

Max. SAR Measurement :	6.7W/kg (averaged over 1 gram)
------------------------	--------------------------------

This EUT has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528-200X(Draft 6.5, January 2002).

1.7 Test standards

Standards :	- IEEE Std. 1528-200X (Draft 6.5, January 2002)
FCC Rule Part(s) :	-FCC OET Bulletin 65, Supplement C, Edition 01-01

2 Technical test

2.1 Summary of test results

Classification

Uncontrolled environment/general population	
Controlled exposure/occupational environment	X

Applicable Configuration

Handset (Head)	
Handset (Held to face)	X
Handset (Body)	
Headset (Head)	
Body Worn Equipment	X

EUT complies with the RF radiation exposure limits of the FCC as shown by the SAR measurement results. These measurements are taken to simulate the RF effects exposure under worst-case conditions. The EUT complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interaction, environmental conditions, and physiological variables. [1]

2.2 Test environment

Room temperature : 22.0–22.3°C
 Liquid temperature : 22.0-22.1°C
 Relative humidity content : 47%
 Details of power supply : 7.4 V DC

2.3 Test equipment utilized

Type / Model	Calib. Date	S/N
Staubli Robot / RX90BL	N/A	F03/5W05A1/A/01
Staubli Robot Controller / RX90B L	N/A	F03/5W05A1/C/01
Staubli Manual Control Operator	N/A	D22134006 1
PC / IBM NetVista 2.66	N/A	99LA523
OS / Windows 2000	N/A	-
SPEAG DAE / DAE3	April 2005	567
SPEAG E-Field Probe / ET3DV6	April 2005	1782
SPEAG Dummy Probe	N/A	-
SPEAG SAM Phantom	N/A	TP-1300, TP-1299
SPEAG Flat Phantom	N/A	1003, 1005
SPEAG Validation Dipole D450V2	July 2005	1015
SPEAG Validation Dipole D835V2	June 2005	490
SPEAG Validation Dipole D900V2	June 2005	188
SPEAG Validation Dipole D1800V2	June 2005	2d074
SPEAG Validation Dipole D1900V2	June 2005	5d033
SPEAG Validation Dipole D2450V2	July 2005	734
Dipole Antenna/ VHAP/UHAP	May 2005	958
Mounting Device	N/A	-

2.4 Definitions

2.4.1 SAR

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (ρ), expressed in watts per kilogram (W/kg)

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho_i dV} \right) = \frac{\sigma}{\rho} |E_t|^2$$

where:

$$\frac{dW}{dt} = \int_V E \cdot J dV = \int_V \sigma E^2 dV$$

2.4.2 Uncontrolled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category, and the general population/uncontrolled exposure limits apply to these devices. [2]

2.4.3 Controlled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on the risk of potential exposure and instructions on methods to minimize such exposure risks. [2] Push-to-talk applications (PTT) operating in front of a person's face and certain body worn configurations as occupational/controlled exposure. The consideration of a 50% duty factor for PTT simplex radio-carrying typical voice traffic is possible.

2.5 Measurement System Description

2.5.1 System Setup

Measurements are performed using the DASY4 automated dosimetric assessment system (figure 1) made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland.

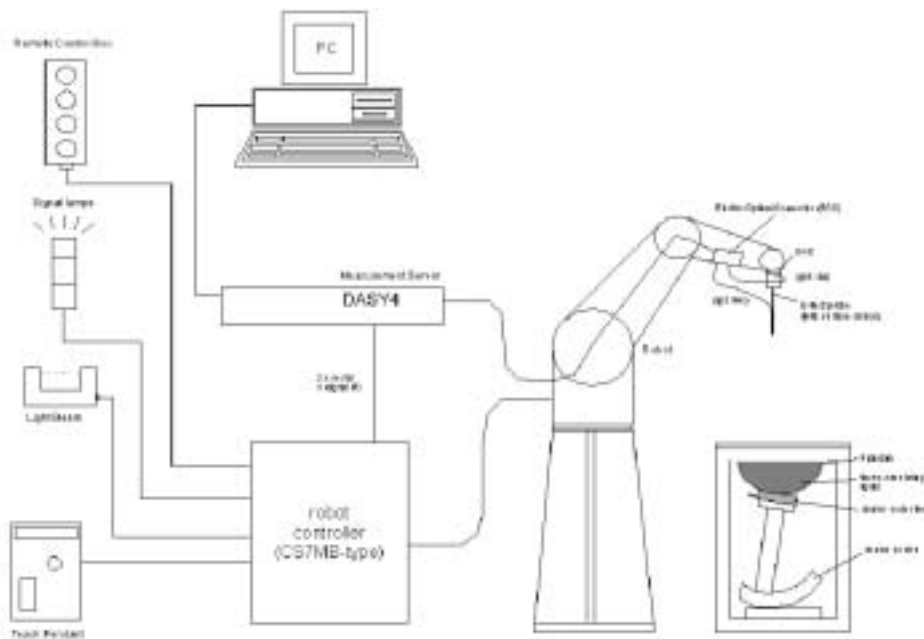


Figure1

The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Staubli RX family) with controller, teach pendant and software.
- An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- An unit to operate the optical surface detector which is connected to the EOC.
- The Electro-optical converter (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the measurement server.
- The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows NT.
- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.

- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes (see Application Notes).
- System validation dipoles allowing to validate the proper functioning of the system.

2.5.2 Phantom Description



(figure 2.1)

The SAM twin phantom V4.0 (figure 2.1) is a fiberglass shell phantom with 2 mm shell thickness. It has three measurement areas:

- Left hand
- Right hand
- Flat phantom

The phantoms are integrated in a wooden table.

The bottom plate of the table contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used(e.g., for different liquids).

A cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible.

On the phantoms top, three reference markers are provided to identify the phantom positions with respect to the robot.



(figure 2.2)

The FLATPHANTOM V4 (figure 2.2) is a phantom for dosimetric evaluations of body mounted usage and system performance check for the frequency up to 3 GHz.

2.5.3 Tissue Simulating Liquids

The parameters of the tissue simulating liquid strongly influence the SAR. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE P1528-200X).

Tissue dielectric properties

Frequency (MHz)	Head		Body	
	Relative Dielectric Constant (ϵ_r)	Conductivity(σ) (S/m)	Relative Dielectric Constant (ϵ_r)	Conductivity(σ) (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
1450	40.5	1.20	54.0	1.30
1800	40.0	1.40	53.3	1.52
1900	40.0	1.40	53.3	1.52
2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73

2.5.4 Device Holder

The DASY device holder (figure 3.1) is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The rotation center for both scales is the ear opening. Thus the device needs no repositioning when changing the angles.



Figure 3.1

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon_r = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the results could thus be lowered.

2.5.5 Probes

The SAR measurements were conducted with the dosimetric probe ET3DV6 (figure 4), designed in the classical triangular configuration and optimized for dosimetric evaluation. [3] The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped at reaching the maximum.



Figure 4

Probe Specifications

Calibration:	In air from 10 MHz to 2.5 GHz In brain and muscle simulating tissue at Frequencies of 150 MHz, 300 MHz, 450 MHz, 835 MHz, 900 MHz, 1800 MHz, 1900 MHz and 2450 MHz Calibration certificates please find attached.
Frequency:	10 MHz to > 3 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity:	± 0.2 dB in HSL (rotation around probe axis) ± 0.4 dB in HSL (rotation normal probe axis)
Dynamic Range:	5 μ W/g to > 100 mW/g;
Linearity:	± 0.2 dB
Dimensions:	Overall length: 330mm Tip length: 16mm Body diameter: 12mm Tip diameter: 6.8mm Distance from probe tip to dipole centers: 2.7 mm
Application:	General dosimetry up to 3 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms

Positioner

Robot: Staubli Animation Corp. Robot Model: RX90B L
 Repeatability: 0.02 mm
 No. of axis: 6

Data Acquisition Electronic(DAE) System
Cell Controller

Processor: Pentium IV
 Clock Speed: 2.0 GHz
 Operating System: Windows 2000
 Data Card: DASY4 PC-Board
 Data Converter
 Features: Signal Amplifier, multiplexer, A/D converter, & control logic
 Software: DASY4 software
 Connecting Lines: Optical downlink for data and status info.
 Optical uplink for commands and clock
 PC Interface Card
 Function: 24 bit (64 MHz) DSP for real time processing
 Link to DAE3
 16 bit A/D converter for surface detection system
 serial link to robot
 direct emergency stop output for robot

E-Field Probes

Model: ET3DV6 / SN1782
 Construction: Triangular core fiber optic detection system
 Frequency: 10 MHz to 6 GHz
 Linearity: ± 0.2 dB (30 MHz to 3 GHz)

Phantom

Phantom: SAM Twin Phantom(V4.0)
 Shell Material: Fiberglass
 Thickness: 2.0 ± 0.2 mm

Phantom

Phantom: Flat Phantom (V4.4)
 Shell Material: Fiberglass
 Thickness: $6 \text{ mm} \pm 0.2 \text{ mm}$

2.7 Measurement Procedure

The evaluation was performed using the following procedure:

1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value.
2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 10mm x 10mm.
3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 30mm x 30mm x 30mm (fine resolution volume scan, zoom scan) was assessed by measuring 5 x 5 x 5 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure:
 - a. The data at the surface was extrapolated, since the center of the dipoles is 2.7mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
 - b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions) [4] [5]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
 - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
4. The SAR reference value, at the same location as procedure #1, was remeasured. If the value changed by more than 5%, the evaluation is repeated.

2.8 Reference Positions for Handheld Radio Transmitters

In general handheld radio transmitters like PMR/SMR devices are used in held to face position or with a speaker/microphone combination as body-worn configuration.

1.8.1 Held to face position

For held to face position the flat section of a SAM Phantom or a flat phantom is used. The center of the radiating structure is to set on the middle position of the flat phantom. The distance between sample and flat phantom is 2.5 cm, similar to the real using. For the measurement head tissue simulating liquid is used.

1.8.2 Belt Clip/Holster Configuration

Test configurations for body-worn operated EUTs are carried out while the belt-clip and/or holster is attached to the EUT and placed against a flat phantom in a regular configuration. An EUT with a headset output is tested with a headset connected to the device.

Body dielectric parameters are used.

There are two categories for accessories for body-worn operation configurations:

1. accessories not containing metallic components
2. accessories containing metallic components.

When the EUT is equipped with accessories not containing metallic components the tests are done with the accessory that dictates the closest spacing to the body. For accessories containing metallic parts a test with each one is implemented. If the multiple accessories share an identical metallic component (e.g. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that has the closest spacing to the body is tested.

In case that a EUT authorized to be body-worn is not supplied or has no options to be operated with any accessories, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters operating in front of a person's face (e.g. push-to-talk configurations) are tested for SAR compliance with the front of the device positioned to face the flat platform. SAR Compliance tests for shoulder, waist or chest-worn transmitters are carried out with the accessories including headsets and microphones attached to the device and placed against a flat phantom in a regular configuration.

The SAR measurements are performed to investigate the worst-case positioning. This is documented and used to perform Body SAR testing. [2]. Body tissue simulating liquid is used.

1.9 Measurement uncertainty

The uncertainty budget has been determined for the DASY4 system performance check according to IEEE Str. 1528-200X, (draft), April 2002.

Error Description	Uncertainty value $\pm\%$	Probability distribution	Divisor	c_i 1g	Standard unc. (1g)	v_i or v_{eff}
Measurement System						
Probe Calibration	± 4.8	normal	1	1	± 4.8	∞
Axial Isotropy	± 4.7	rectangular	$\sqrt{3}$	$(1/\sqrt{3})^{1/2}$	± 1.9	∞
Hemispherical Isotropy	± 9.6	rectangular	$\sqrt{3}$	$(\sqrt{3})^{1/2}$	± 3.9	∞
Boundary effects	± 1.0	rectangular	$\sqrt{3}$	1	± 0.6	∞
Linearity	± 4.7	rectangular	$\sqrt{3}$	1	± 2.7	∞
System Detection limits	± 1.0	rectangular	$\sqrt{3}$	1	± 0.6	∞
Readout Electronics	± 1.0	normal	1	1	± 1.0	∞
Response time	± 0.8	rectangular	$\sqrt{3}$	1	± 0.5	∞
Integration time	± 2.6	rectangular	$\sqrt{3}$	1	± 1.5	∞
RF Ambient Conditions	± 3.0	rectangular	$\sqrt{3}$	1	± 1.7	∞
Probe Positioner Mechanical Tolerance	± 0.4	rectangular	$\sqrt{3}$	1	± 0.2	∞
Probe Positioning with respect to Phantom Shell	± 2.9	rectangular	$\sqrt{3}$	1	± 1.7	∞
Extrapolation, Interpolation and Integration Algorithms for Max. SAR Evaluation	± 1.0	rectangular	$\sqrt{3}$	1	± 0.6	∞
Test Sample Related						
Test Sample Positioning	± 2.9	normal	1	1	± 2.9	145
Device Holder Uncertainty	± 3.6	normal	1	1	± 3.6	5
Output Power Variation – SAR drift measurement	± 5.0	rectangular	$\sqrt{3}$	1	± 2.9	∞
Phantom and Tissue Parameters						
Phantom Uncertainty (shape and thickness tolerances)	± 4.0	rectangular	$\sqrt{3}$	1	± 2.3	∞
Liquid conductivity Target - tolerance	± 5.0	rectangular	$\sqrt{3}$	0.64	± 1.8	∞
Liquid conductivity – measurement uncertainty	± 2.5	normal	1	0.64	± 1.6	∞
Liquid permittivity Target - tolerance	± 5.0	rectangular	$\sqrt{3}$	0.6	± 1.7	∞
Liquid permittivity – measurement uncertainty	± 2.5	normal	1	0.6	± 1.5	∞
Combined Standard Uncertainty						
					± 10.3	330
Coverage Factor for 95%		k = 2				
Expanded Standard Uncertainty					± 20.6	



3. Tissue and System Verification

3.1 Tissue Verification

Dielectric parameters of the simulating liquids were verified using a Dielectric Probe Kit Agilent 85070D to a tolerance of $\pm 5\%$.

Room Temperature: 22.0 -22.3°C

	Measured Tissue Parameters	
	450 MHz Head	
	Target	Measured
Date		17.06.2004
Liquid Temperature: °C		22.1
Dielectric Constant: ϵ	43.5	44.78
Conductivity: σ	0.87	0.879

Room Temperature: 22.1 -22.3°C

	Measured Tissue Parameters	
	450 MHz Body	
	Target	Measured
Date		18.06.2004
Liquid Temperature: °C		22.2
Dielectric Constant: ϵ	56.7	57.90
Conductivity: σ	0.94	0.956



3.2 System Verification

Prior to the assessment, the system was verified by using a 300 MHz validation dipole. Power level of 250mW was supplied to the dipole antenna placed under the flat section of SAM Phantom.

The system was verified to a tolerance of $\pm 10\%$

Room Temperature: 22.0-22.3°C

Liquid Temperature: 22.0-22.1°C

Liquid Depth: >15cm

System Dipole Validation Target & Measurement					
Date	System Validation Kit:	Liquid	Targeted SAR 1g(mW/g)	Measured SAR 1g(mW/g)	Deviation (%)
29.04.2005	D450V2	450 MHz Head	5.24	5.6	-6.4

Comment: Please find attached the measurement plots.

4. Test Results

Procedures Used To Establish Test Signal

The EUT was placed into simulated call mode (e.g. AMPS, Cellular CDMA & PCS CDMA modes) using manufacturers test codes. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [2]. The actual transmission is activated through a base station simulator or similar when test modes are not available or inappropriate for testing the EUT.

The EUT is rechargeable battery operated. The battery used for the SAR measurements was completely charged. The device was tested at full power verified by implementing conducted output power measurements. For confirming of the output power it was tested before and after each SAR measurement. The test was repeated if a conducted power deviation of more than 5% occurred.

Mixture Type: 450 MHz Head

Date: 29.04.2005

Liquid Temperature: 22.0-22.1°C

Room Temperature: 22.0 – 22.3°C

Frequency			Power Drift dBm	Antenna Pos.	Phantom Section	Test Position –25 mm	SAR (W/kg) 1g	
MHz	Channel	Modulation					Measured SAR values	
							100% Duty Cycle	50% Duty Cycle
440	Low	CW	-0.20	Fixed	Flat	Front	2.190	1.095
450	Middle	CW	-0.18	Fixed	Flat	Front	5.950	2.975
470	High	CW	-0.18	Fixed	Flat	Front	4.440	2.220

1. The SAR values found were below the maximum limit of 8.0 w/kg (controlled exposure):
2. The highest face-held SAR value found was 2.22 W/kg (50% duty cycle)
3. The EUT was tested for face-held SAR with a 2.5 cm separation distance between the front of the EUT and the outer surface of the planar phantom.

Mixture Type: 450 MHz Muscle

Date: 27.05.2005

Liquid Temperature: 22.1 – 22.2°C

Room Temperature: 22.1 – 22.3 °C

Frequency			Power Drift dBm	Antenna Pos.	Phantom Section	Test Position –10 mm	SAR (W/kg) 1g	
MHz	Channel	Modulation					Measured SAR values	
							100% Duty Cycle	50% Duty Cycle
440	Low	CW	-0.14	Fixed	Flat	Back	8.57	4.29
450	Middle	CW	-0.16	Fixed	Flat	Back	12.80	6.40
470	High	CW	-0.29	Fixed	Flat	Back	13.40	6.70

1. The SAR values found were below the maximum limit of 8.0 w/kg (controlled exposure):
2. The highest body-worn SAR value found was 6.7 W/kg (50% duty cycle)
3. The EUT was tested for body-worn SAR with the attached belt-clip providing a 1.0 cm separation distance between the front of the EUT and the outer surface of the planar phantom.

Limits:

Exposure Limits	SAR (W/kg)	
	Uncontrolled Exposure/General Population Environment	Controlled Exposure/Occupational Environment
Spatial Average SAR (averaged over the whole body)	0.08	0.40
Spatial Peak SAR (averaged over any 1g of tissue)	1.60	8.00
Spatial Peak SAR (Hands, Feet, Ankles, Wrist) (averaged over any 10g of tissue)	4.00	20.00

Notes:

1. Test data represent the worst case SAR value and test procedure used are according to OET Bulletin 65, Supplement C (01-01).
2. All Modes of operation were investigated.

5. References

- [1] ANSI/IEEE C95.3 – 1991, IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic fields, 300 KHz to 100 GHz, New York: IEEE, Aug. 1992.
- [2] Federal Communications Commission, OET Bulletin 65 (Edition 97-01), Supplement C (Edition 01-01), Evaluating Compliance with FCC Guidelines for Human Exposure to Radio frequency Electromagnetic Fields, July 2001.
- [3] T. Schmid, O. Egger, N. Kuster, Automated E-field scanning system for dosimetric assessments, IEEE Transaction on Microwave Theory and Techniques, vol. 44, Jan. 1996, pp. 105-113.
- [4] W. Gander, Computer mathematics, Birkhaeuser, Basel, 1992.
- [5] W.H. Press, S.A Teukolsky, W.T. Vetterling, and B.P. Flannery, Numerical Recipes in C, The Art of Scientific Computing, Second edition, Cambridge University Press, 1992.
- [6] IEEE Standards Coordinating Committee 34 – IEEE Std. 1528-200X (Draft 6.1 – January 2002), Draft Recommended Practice for Determining the Peak Spatial-Average Absorption Rate (SAR in the Human Body Due to Wireless Communications Devices: Experimental Techniques).
- [7] DASY4 Dosimetric Assessment System Manual; Draft; September 6, 2002; Schmid & Partner Engineering AG.



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6. Appendix

1. Appendix A Calibration Certificate
2. Appendix B Measurement Plots
3. Appendix C Pictures

SGS Testing Korea Co., Ltd.

18-34, Sanbon-dong, Gunpo-si, Gyeonggi-do, Korea, 435-041

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<http://www.sgstesting.co.kr>

Appendix A

Calibration Certificate

Client **SGS KES (Dymstec)**

CALIBRATION CERTIFICATE

Object(s) **ET3DV6 - SN:1782**

Calibration procedure(s) **QA CAL-01.v2**
Calibration procedure for dosimetric E-field probes

Calibration date: **April 28, 2005**

Condition of the calibrated item **In Tolerance (according to the specific calibration document)**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 +/- 2 degrees Celsius and humidity < 75%.

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter EPM E442	GB37480704	6-Nov-04 (METAS, No. 252-0254)	Nov-05
Power sensor HP 8481A	US37292783	6-Nov-04 (METAS, No. 252-0254)	Nov-05
Fluke Process Calibrator Type 702	SN: 6295803	8-Sep-04 (Sintrel SCS No. E-030020)	Sep-05
Power sensor HP 8481A	MY41092180	18-Sep-02 (SPEAG, in house check Oct-03)	In house check: Oct-05
RF generator HP 8684C	US3642U01700	4-Aug-99 (SPEAG, in house check Aug-02)	In house check: Aug-05
Network Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Oct-03)	In house check: Oct-05

Calibrated by: Name Function
 Nico Vetterli Technician

Signature

F. Brinkhoff

Approved by: Katja Pokovic Laboratory Director

Katja Pokovic

Date issued: April 28, 2005

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

Probe ET3DV6

SN:1782

Manufactured:	April 15, 2003
Last calibrated:	July 28, 2003
Recalibrated:	April 28, 2005

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: ET3DV6 SN:1782**Sensitivity in Free Space****Diode Compression^A**

NormX	2.03 $\mu\text{V}/(\text{V}/\text{m})^2$	DCP X	94	mV
NormY	1.72 $\mu\text{V}/(\text{V}/\text{m})^2$	DCP Y	94	mV
NormZ	1.89 $\mu\text{V}/(\text{V}/\text{m})^2$	DCP Z	94	mV

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 7.

Boundary Effect**Head 900 MHz Typical SAR gradient: 5 % per mm**

Sensor Center to Phantom Surface Distance		3.7 mm	4.7 mm
SAR _{be} [%]	Without Correction Algorithm	8.0	4.0
SAR _{be} [%]	With Correction Algorithm	0.0	0.1

Head 1800 MHz Typical SAR gradient: 10 % per mm

Sensor Center to Phantom Surface Distance		3.7 mm	4.7 mm
SAR _{be} [%]	Without Correction Algorithm	12.7	8.5
SAR _{be} [%]	With Correction Algorithm	0.2	0.1

Sensor Offset

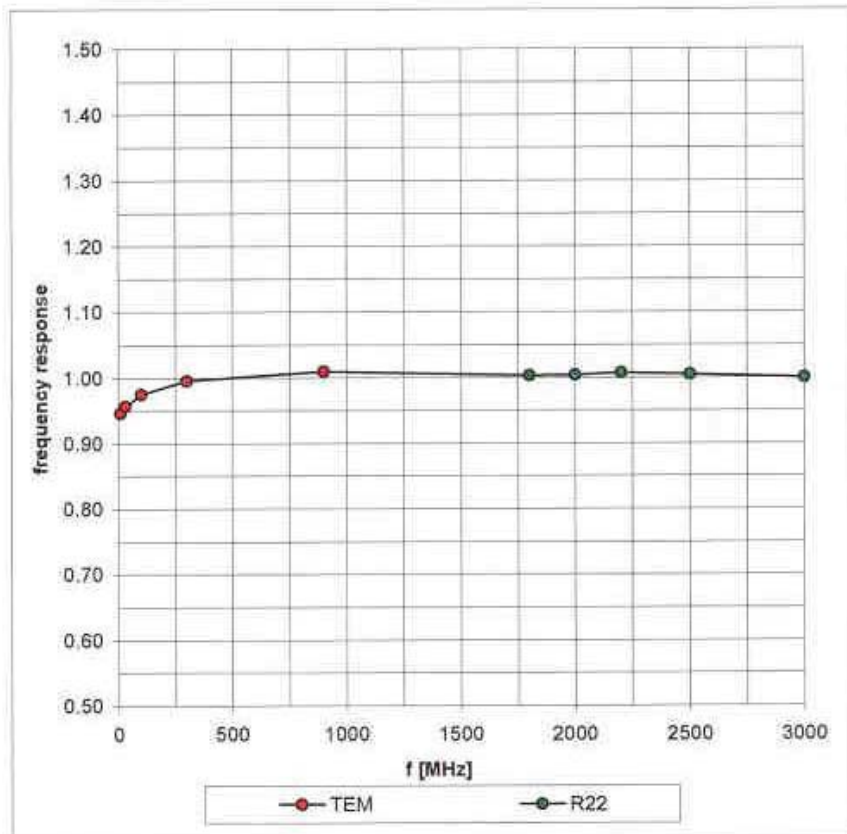
Probe Tip to Sensor Center	2.7 mm
Optical Surface Detection	in tolerance

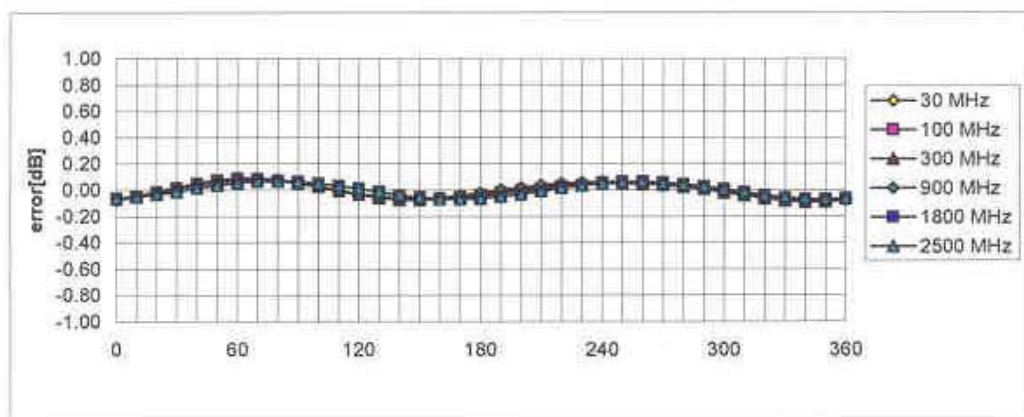
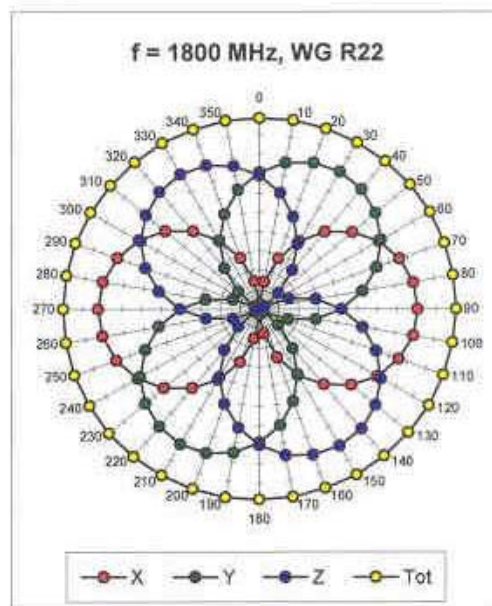
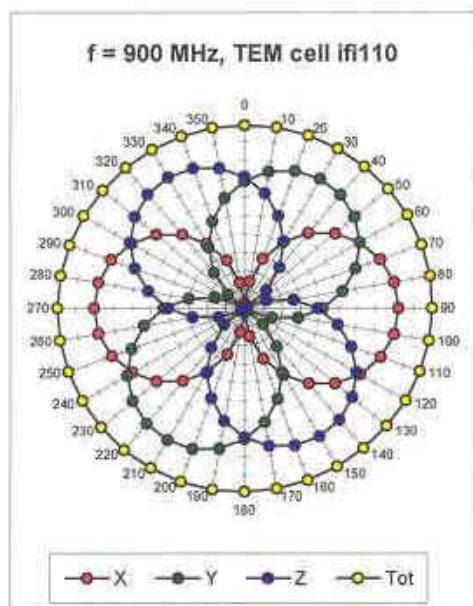
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A numerical linearization parameter; uncertainty not required

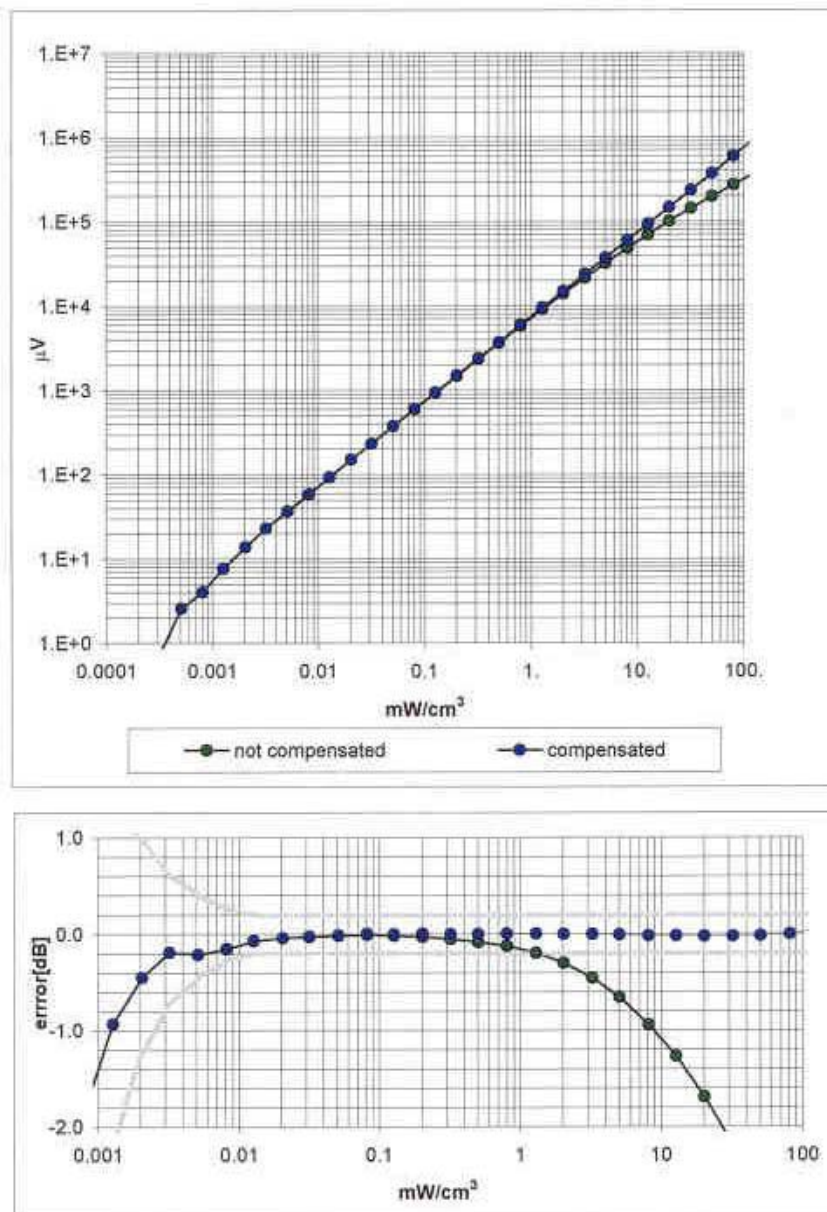
Frequency Response of E-Field

(TEM-Cell:ifi110, Waveguide R22)



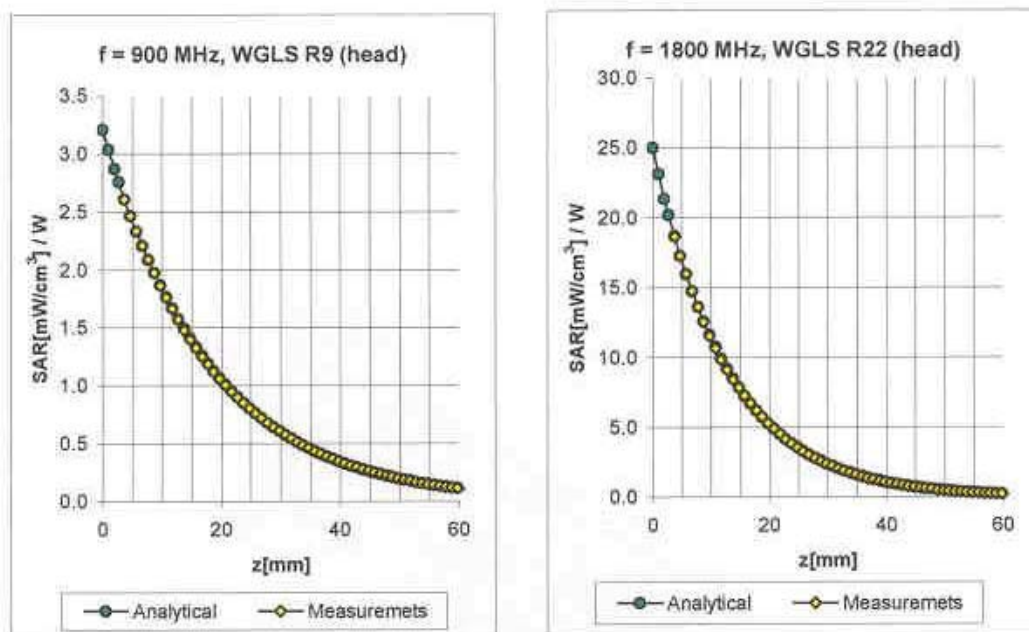
Receiving Pattern (ϕ) , $\theta = 0^\circ$ Axial Isotropy Error $< \pm 0.2 \text{ dB}$

Dynamic Range f(SAR_{head}) (Waveguide R22)



Probe Linearity $< \pm 0.2$ dB

Conversion Factor Assessment

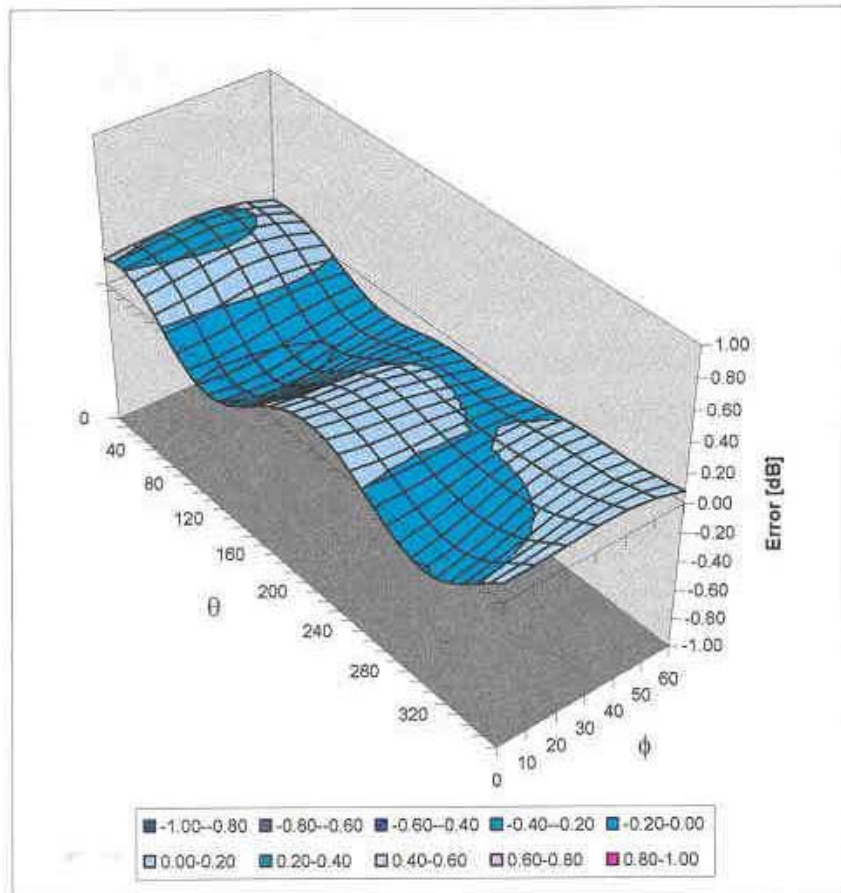


f [MHz]	Validity [MHz] ^a	Tissue	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
900	800-1000	Head	41.5 ± 5%	0.97 ± 5%	0.76	1.59	6.45 ± 11.3% (k=2)
1800	1710-1910	Head	40.0 ± 5%	1.40 ± 5%	0.47	2.62	5.07 ± 11.7% (k=2)
2450	2400-2500	Head	39.2 ± 5%	1.80 ± 5%	0.89	1.98	4.36 ± 9.7% (k=2)
835	785-885	Body	55.2 ± 5%	0.97 ± 5%	0.46	2.19	6.14 ± 9.7% (k=2)
900	850-950	Body	55.0 ± 5%	1.05 ± 5%	0.44	2.31	5.93 ± 9.7% (k=2)
1800	1710-1890	Body	53.3 ± 5%	1.52 ± 5%	0.52	2.80	4.55 ± 10.9% (k=2)
1900	1805-1995	Body	53.3 ± 5%	1.52 ± 5%	0.56	2.86	4.40 ± 11.1% (k=2)
2450	2400-2500	Body	52.7 ± 5%	1.95 ± 5%	1.01	1.71	4.22 ± 9.7% (k=2)

^a The total standard uncertainty is calculated as root-sum-square of standard uncertainty of the Conversion Factor at calibration frequency and the standard uncertainty for the indicated frequency band.

Deviation from Isotropy in HSL

Error (θ, ϕ), $f = 900$ MHz



Spherical Isotropy Error $< \pm 0.4$ dB

Client **SGS KES (Dymstec)**

CALIBRATION CERTIFICATE

Object(s) **DAE3 - SD 000 D03 AA - SN: 567**

Calibration procedure(s) **QA CAL-06.v7
Calibration procedure for the data acquisition unit (DAE)**

Calibration date: **30.04.2005**

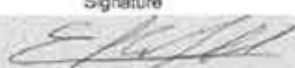
Condition of the calibrated item **In Tolerance (according to the specific calibration document)**

This calibration statement documents traceability of M&TE used in the calibration procedures and conformity of the procedures with the ISO/IEC 17025 international standard.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 +/- 2 degrees Celsius and humidity < 75%.

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date	Scheduled Calibration
Fluke Process Calibrator Type 702	SN: 6295803	8-Sep-04	Sep-05

	Name	Function	Signature
Calibrated by:	Eric Hainfeld	Technician	

Approved by:	Fin Bornholt	R&D Director	
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Date issued: 30.04.2005

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

1. DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 μ V, full range = -100...+300 mV

Low Range: 1LSB = 61nV, full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.815	404.585	404.668
Low Range	3.95105	3.95178	3.94235
Connector Angle to be used	in DASY System 83 °		

High Range	Input (μ V)	Reading (μ V)	Error (%)
Channel X + Input	200000	200000	0.00
Channel X + Input	20000	19998.36	-0.01
Channel X - Input	20000	-19996.24	-0.02
Channel Y + Input	200000	200000.1	0.00
Channel Y + Input	20000	19997.34	-0.01
Channel Y - Input	20000	-19994.76	-0.03
Channel Z + Input	200000	199999.7	0.00
Channel Z + Input	20000	19995.08	-0.02
Channel Z - Input	20000	-19995.66	-0.02

Low Range	Input (μ V)	Reading (μ V)	Error (%)
Channel X + Input	2000	2000	0.00
Channel X + Input	200	199.41	-0.30
Channel X - Input	200	-200.38	0.19
Channel Y + Input	2000	2000.1	0.00
Channel Y + Input	200	198.84	-0.58
Channel Y - Input	200	-201.23	0.61
Channel Z + Input	2000	2000	0.00
Channel Z + Input	200	199.06	-0.47
Channel Z - Input	200	-201.56	0.78

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Reading (μ V)	Low Range Reading (μ V)
Channel X	200	2.82	2.30
	- 200	-0.12	-0.99
Channel Y	200	0.18	-0.05
	- 200	-1.64	-1.75
Channel Z	200	3.51	4.59
	- 200	-6.09	-6.64

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μ V)	Channel Y (μ V)	Channel Z (μ V)
Channel X	200	-	3.51	0.44
Channel Y	200	2.07	-	4.53
Channel Z	200	-0.98	1.54	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16381	16315
Channel Y	16208	16160
Channel Z	15912	15782

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

	Average (μ V)	min. Offset (μ V)	max. Offset (μ V)	Std. Deviation (μ V)
Channel X	0.36	-0.68	1.66	0.50
Channel Y	-1.49	-2.46	-0.11	0.38
Channel Z	-0.47	-1.74	0.63	0.42

6. Input Offset Current

Nominal input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.2001	201.9
Channel Y	0.2001	201.6
Channel Z	0.2000	200.0

8. Low Battery Alarm Voltage

typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption

typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9

Appendix B

Measurement Plots

Test Laboratory: SGS Testing Korea

HT780_450MHz_Valid_Head_250mW

DUT: Dipole 450 MHz; Type: D450V2; Serial: D450V2 - SN:1015

Communication System: CW; Frequency: 450 MHz; Duty Cycle: 1:1

Medium: HSL 450MHz Medium parameters used: $f = 450 \text{ MHz}$; $s = 0.879 \text{ mho/m}$; $\epsilon_r = 44.8$; $\rho =$

1000 kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1782; ConvF(7.6, 7.6, 7.6); Calibrated: 2005-04-28
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn567; Calibrated: 2005-04-30
- Phantom: SAM_TP-1300; Type: SAM MIC #2000-93; Serial: TP-1300
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

450MHz Validation APR 2005/Area Scan (61x121x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Reference Value = 42.3 V/m ; Power Drift = -0.0 dB

Maximum value of SAR (interpolated) = 1.49 mW/g

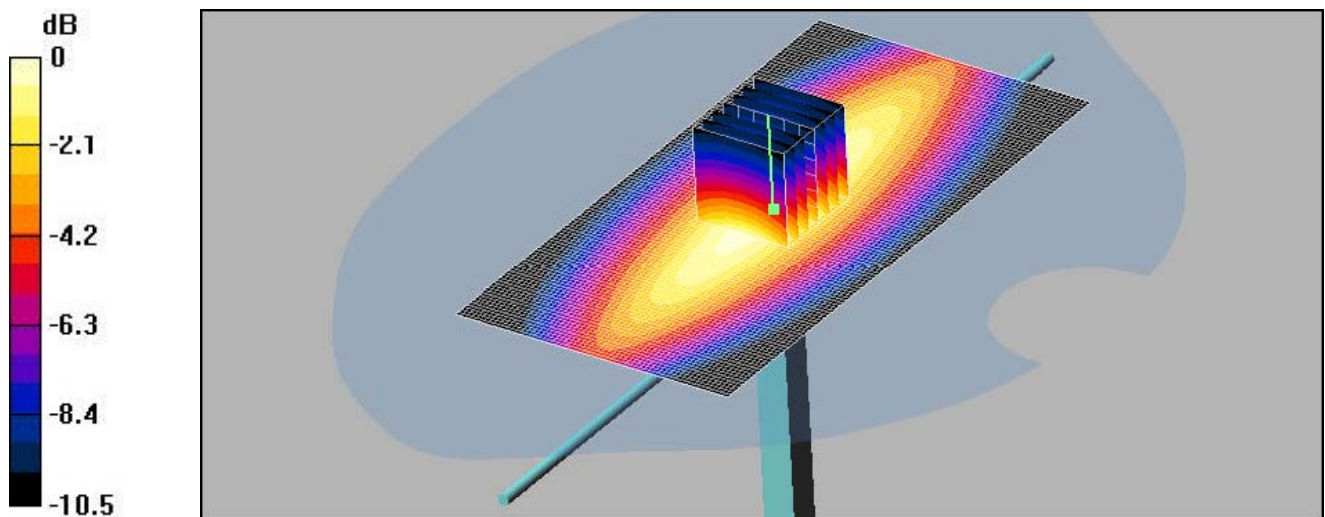
450MHz Validation APR 2005/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 42.3 V/m ; Power Drift = -0.0 dB

Maximum value of SAR (measured) = 1.48 mW/g

Peak SAR (extrapolated) = 2.59 W/kg

SAR(1 g) = 1.4 mW/g ; SAR(10 g) = 0.869 mW/g



0 dB = 1.48mW/g

Test Laboratory: SGS Testing Korea

HT780_low_440MHz_Head

DUT: HT780; Type: UHF; Serial: none

Communication System: CW; Frequency: 440 MHz; Duty Cycle: 1:1

Medium: HSL 450MHz Medium parameters used: $f = 440 \text{ MHz}$; $s = 0.839 \text{ mho/m}$; $\epsilon_r = 45.6$; $\rho =$

1000 kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1782; ConvF(7.6, 7.6, 7.6); Calibrated: 2005-04-28
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn567; Calibrated: 2005-04-30
- Phantom: SAM_TP-1300; Type: SAM MIC #2000-93; Serial: TP-1300
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

440MHz/Area Scan (61x161x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Reference Value = 52.9 V/m; Power Drift = -0.2 dB

Maximum value of SAR (interpolated) = 2.33 mW/g

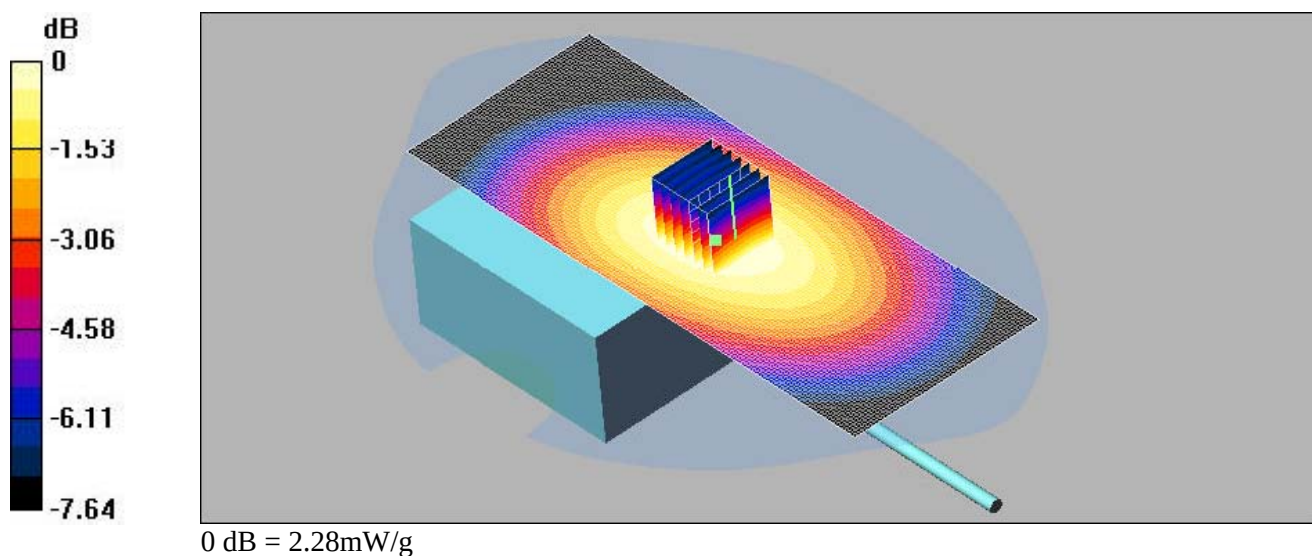
440MHz/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 52.9 V/m; Power Drift = -0.2 dB

Maximum value of SAR (measured) = 2.28 mW/g

Peak SAR (extrapolated) = 3.31 W/kg

SAR(1 g) = 2.19 mW/g; SAR(10 g) = 1.62 mW/g



Test Laboratory: SGS Testing Korea

HT780_Mid_450MHz_Head

DUT: HT780; Type: UHF; Serial: none

Communication System: CW; Frequency: 450 MHz; Duty Cycle: 1:1

Medium: HSL 450MHz Medium parameters used: $f = 450 \text{ MHz}$; $s = 0.879 \text{ mho/m}$; $\epsilon_r = 44.8$; $\rho =$

1000 kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1782; ConvF(7.6, 7.6, 7.6); Calibrated: 2005-04-28
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn567; Calibrated: 2005-04-30
- Phantom: SAM_TP-1300; Type: SAM MIC #2000-93; Serial: TP-1300
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

450MHz/Area Scan (61x161x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Reference Value = 91.4 V/m ; Power Drift = -0.18 dB

Maximum value of SAR (interpolated) = 7.02 mW/g

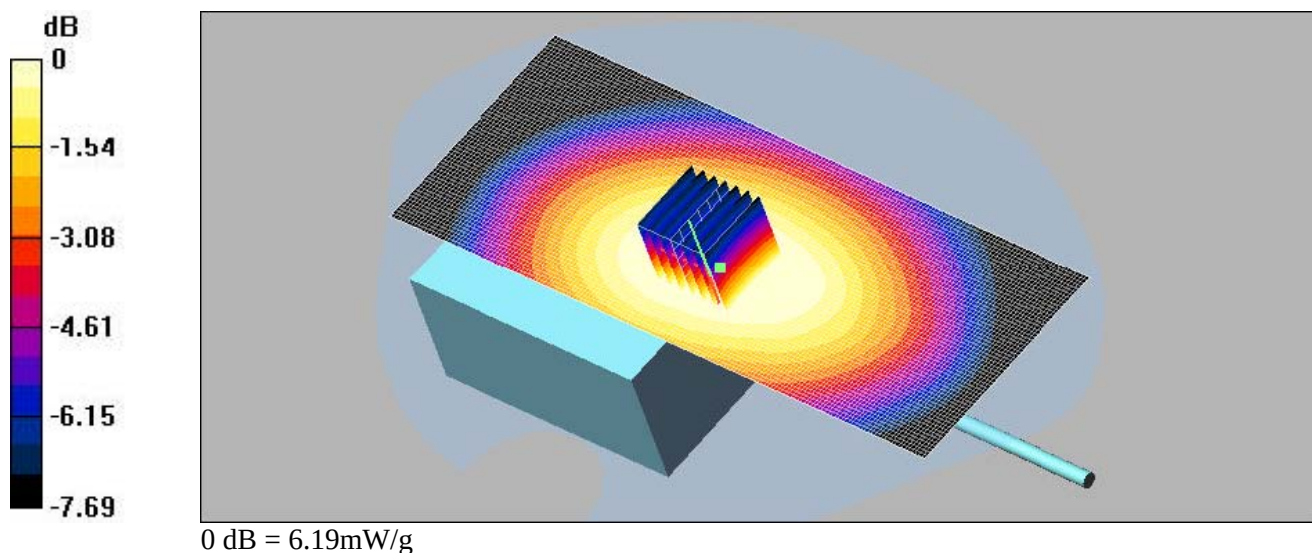
450MHz/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 91.4 V/m ; Power Drift = -0.18 dB

Maximum value of SAR (measured) = 6.19 mW/g

Peak SAR (extrapolated) = 9.01 W/kg

SAR(1 g) = 5.95 mW/g ; SAR(10 g) = 4.36 mW/g



Test Laboratory: SGS Testing Korea

HT780_high_470MHz_Head

DUT: HT780; Type: UHF; Serial: none

Communication System: CW; Frequency: 470 MHz; Duty Cycle: 1:1

Medium: HSL 450MHz Medium parameters used: $f = 440 \text{ MHz}$; $s = 0.903 \text{ mho/m}$; $\epsilon_r = 43.1$; $\rho =$

1000 kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1782; ConvF(7.6, 7.6, 7.6); Calibrated: 2005-04-28
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn567; Calibrated: 2005-04-30
- Phantom: SAM_TP-1300; Type: SAM MIC #2000-93; Serial: TP-1300
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

470MHz/Area Scan (61x161x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Reference Value = 79.9 V/m ; Power Drift = -0.18 dB

Maximum value of SAR (interpolated) = 5.36 mW/g

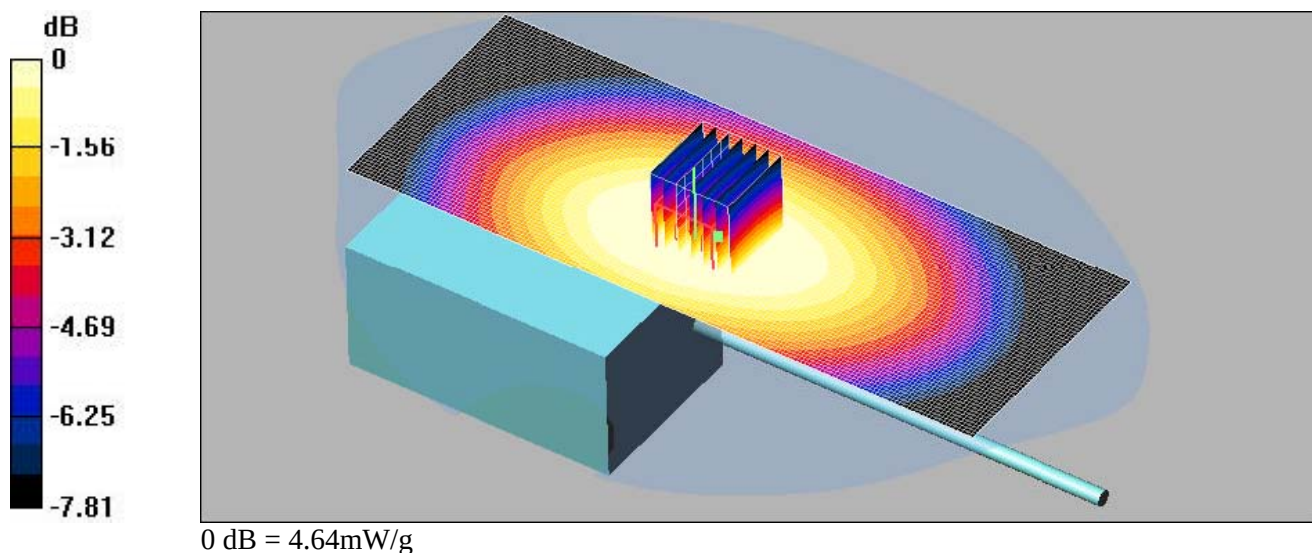
470MHz/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 79.9 V/m ; Power Drift = -0.18 dB

Maximum value of SAR (measured) = 4.64 mW/g

Peak SAR (extrapolated) = 6.71 W/kg

SAR(1 g) = 4.44 mW/g ; SAR(10 g) = 3.25 mW/g



Test Laboratory: SGS Testing Korea

HT780_Low_440MHz_Muscle

DUT: HT780; Type: UHF; Serial: none

Communication System: CW; Frequency: 440 MHz; Duty Cycle: 1:1

Medium: M450 Medium parameters used: $f = 440 \text{ MHz}$; $s = 0.919 \text{ mho/m}$; $\epsilon_r = 58.5$; $\rho = 1000$

kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1782; ConvF(7.4, 7.4, 7.4); Calibrated: 2005-04-28
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn567; Calibrated: 2005-04-30
- Phantom: SAM_TP-1300; Type: SAM MIC #2000-93; Serial: TP-1300
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

440MHz/Area Scan (61x161x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Reference Value = 92.1 V/m ; Power Drift = -0.14 dB

Maximum value of SAR (interpolated) = 9.34 mW/g

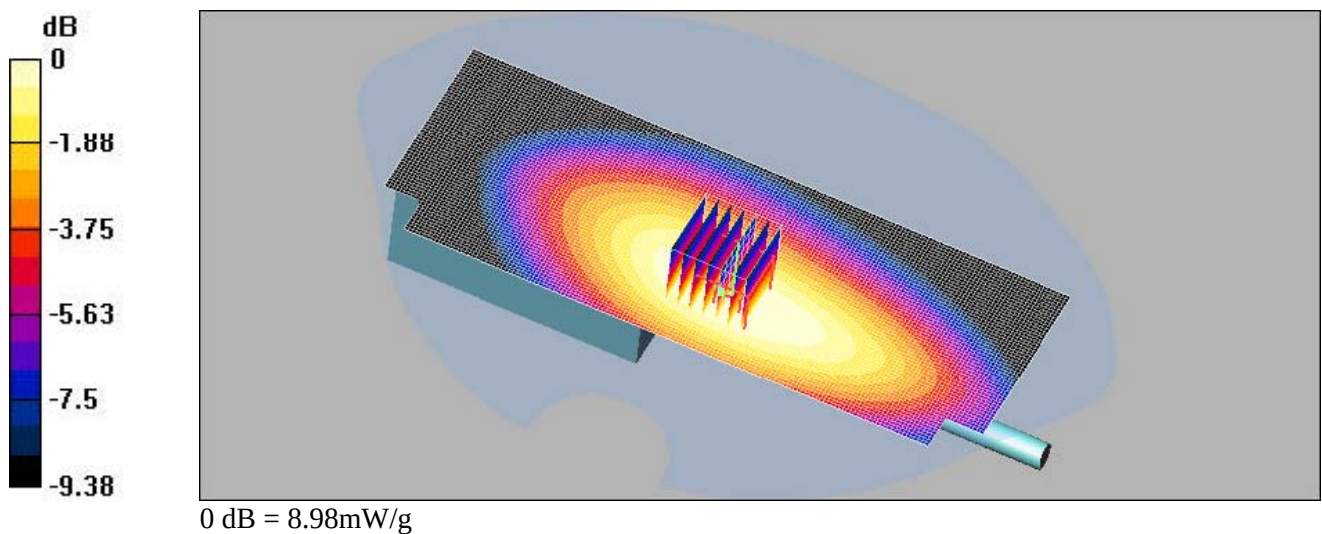
440MHz/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 92.1 V/m ; Power Drift = -0.14 dB

Maximum value of SAR (measured) = 8.98 mW/g

Peak SAR (extrapolated) = 14.1 W/kg

SAR(1 g) = 8.57 mW/g ; SAR(10 g) = 5.86 mW/g



Test Laboratory: SGS Testing Korea

HT780_Mid_450MHz_Muscle

DUT: HT780; Type: UHF; Serial: none

Communication System: CW; Frequency: 450 MHz; Duty Cycle: 1:1

Medium: M450 Medium parameters used: $f = 450 \text{ MHz}$; $s = 0.956 \text{ mho/m}$; $\epsilon_r = 57.9$; $\rho = 1000$

kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1782; ConvF(7.4, 7.4, 7.4); Calibrated: 2005-04-28
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn567; Calibrated: 2005-04-30
- Phantom: SAM_TP-1300; Type: SAM MIC #2000-93; Serial: TP-1300
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

450MHz 2 2/Area Scan (61x161x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Reference Value = 110.9 V/m ; Power Drift = -0.16 dB

Maximum value of SAR (interpolated) = 14.5 mW/g

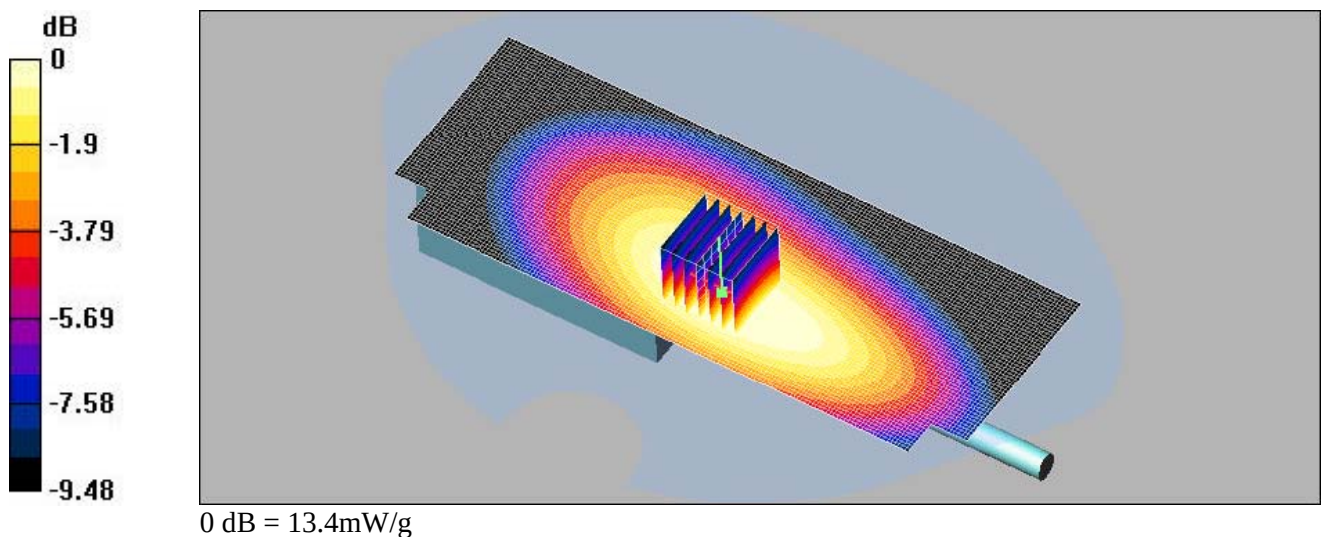
450MHz 2 2/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 110.9 V/m ; Power Drift = -0.16 dB

Maximum value of SAR (measured) = 13.4 mW/g

Peak SAR (extrapolated) = 21.1 W/kg

SAR(1 g) = 12.8 mW/g ; SAR(10 g) = 8.71 mW/g



Test Laboratory: SGS Testing Korea

HT780_High_470MHz_Muscle

DUT:HT780; Type: UHF; Serial: none

Communication System: CW; Frequency: 470 MHz; Duty Cycle: 1:1

Medium: M450 Medium parameters used: $f = 470 \text{ MHz}$; $s = 0.984 \text{ mho/m}$; $\epsilon_r = 57.4$; $\rho = 1000$

kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1782; ConvF(7.4, 7.4, 7.4); Calibrated: 2005-04-28
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn567; Calibrated: 2005-04-30
- Phantom: SAM_TP-1300; Type: SAM MIC #2000-93; Serial: TP-1300
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

470MHz 2 2 2 2 2/Area Scan (61x161x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Reference Value = 118.9 V/m ; Power Drift = -0.29 dB

Maximum value of SAR (interpolated) = 15.8 mW/g

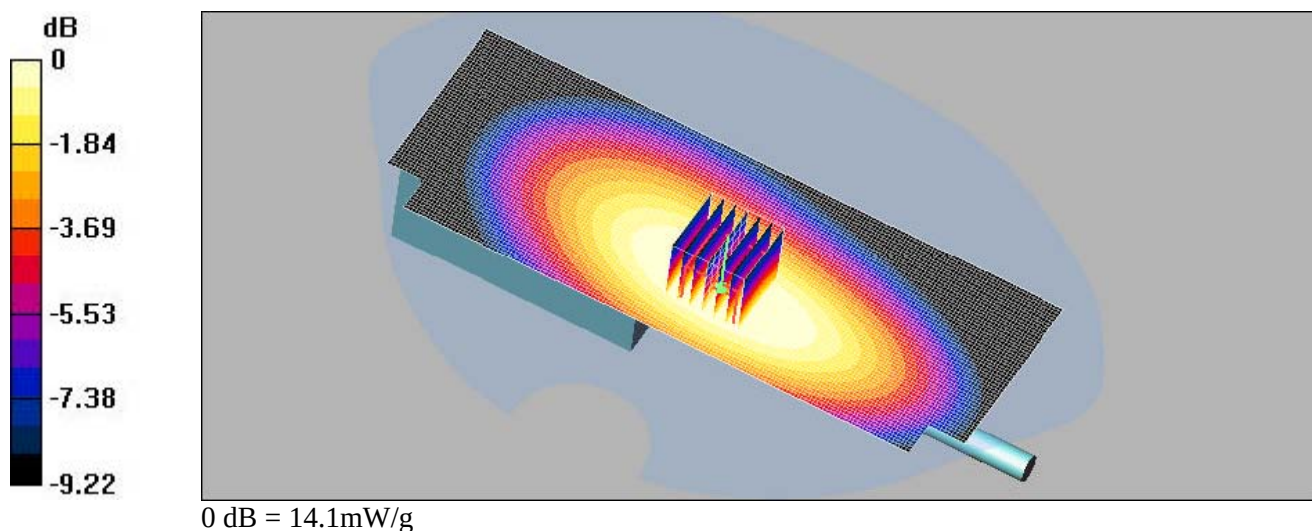
470MHz 2 2 2 2 2/Zoom Scan (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$ Reference

Value = 118.9 V/m ; Power Drift = -0.29 dB

Maximum value of SAR (measured) = 14.1 mW/g

Peak SAR (extrapolated) = 21.9 W/kg

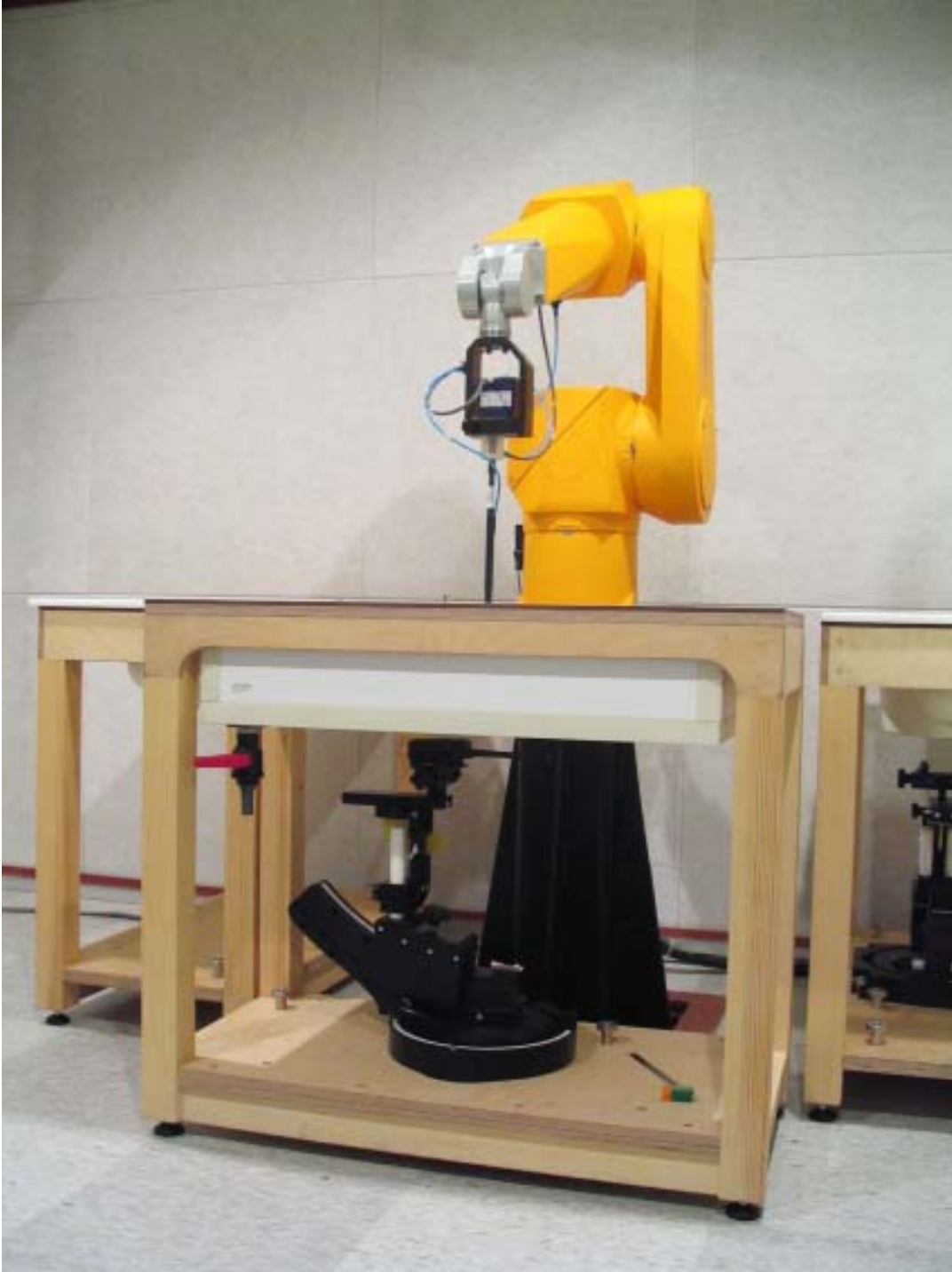
SAR(1 g) = 13.4 mW/g ; SAR(10 g) = 9.18 mW/g



Appendix C

Pictures

SAR System in SGS Testing Korea



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