

## TEST REPORT

Test Report No.: 1-5031/22-01-02



Deutsche  
Akkreditierungsstelle  
D-PL-12076-01-01

### Testing Laboratory

#### CTC advanced GmbH

Untertuerkheimer Strasse 6 – 10

66117 Saarbruecken/Germany

Phone: + 49 681 5 98 - 0

Fax: + 49 681 5 98 - 9075

Internet: <https://www.ctcadvanced.com>

e-mail: [mail@ctcadvanced.com](mailto:mail@ctcadvanced.com)

#### Accredited Test Laboratory:

The testing laboratory (area of testing) is accredited according to DIN EN ISO/IEC 17025 (2018-03) by the Deutsche Akkreditierungsstelle GmbH (DAkKS)

The accreditation is valid for the scope of testing procedures as stated in the accreditation certificate with the registration number: D-PL-12076-01-01.

### Applicant

#### Molex Technologies GmbH

Mizarstraße 3

12529 Schönefeld/GERMANY

Phone: +49 3377 316 0

Contact: Ines Baufeld

e-mail: [ines.baufeld@molex.com](mailto:ines.baufeld@molex.com)

### Manufacturer

#### Molex Technologies GmbH

Mizarstraße 3

12529 Schönefeld/GERMANY

### Test Standard/s

NONE

Tested according manufacturer requirements.

### Test Item

Kind of test item: Wireless Charger  
 Device type: portable device  
**Model name:** **WCH-304**  
 S/N serial number: "DUT 1 SAR"  
 FCC-ID: RK7WCH-304  
 ISED: 4774A-WCH304  
 Hardware status: H11  
 Software status: T032  
 Frequency: 127.55 kHz Charging frequency  
 Antenna: 3 Integrated coils,  
 Power supply: 12V DC supply  
 Accessories: --  
 Test sample status: identical prototype  
 Exposure category: general population / uncontrolled environment



This test report is electronically signed and valid without handwritten signature. For verification of the electronic signatures, the public keys can be requested at the testing laboratory.

### Test Report authorised:

Thomas Vogler  
Lab Manager  
Radio Labs

### Test performed:

Marco Scigliano  
Testing Manager  
Radio Labs

**1 Table of contents**

|                 |   |           |
|-----------------|---|-----------|
| <b>1</b>        | <b>Table of contents.....</b>                               | <b>2</b>  |
| <b>2</b>        | <b>General information .....</b>                            | <b>3</b>  |
| 2.1             | Notes and disclaimer .....                                  | 3         |
| 2.2             | Application details .....                                   | 3         |
| <b>3</b>        | <b>Test Environment .....</b>                               | <b>3</b>  |
| <b>4</b>        | <b>Test Set-up.....</b>                                     | <b>4</b>  |
| 4.1             | Measurement system.....                                     | 4         |
| 4.1.1           | Broadband Electromagnetic Field Test system.....            | 4         |
| 4.1.2           | Test equipment list .....                                   | 5         |
| 4.1.3           | Uncertainties.....  | 6         |
| 4.1.3.1         | Typical uncertainty of MAGPy-H3D probe .....                | 6         |
| 4.1.4           | Validation procedure.....                                   | 7         |
| 4.1.5           | Definition of test position and distances .....             | 7         |
| 4.1.6           | Measurement with MAGPy-H3D probe / DASY 8 WPT-System.....   | 7         |
| 4.2             | Test results – Line scan at defined middle of the coil..... | 8         |
| 4.3             | Test results – Line scan at found max. position .....       | 10        |
| <b>Annex A:</b> | <b>Photo documentation .....</b>                            | <b>12</b> |
| <b>Annex B:</b> | <b>Document History .....</b>                               | <b>16</b> |
| <b>Annex C:</b> | <b>Further Information .....</b>                            | <b>16</b> |

## 2 General information

### 2.1 Notes and disclaimer

The test results of this test report relate exclusively to the test item specified in this test report. CTC advanced GmbH does not assume responsibility for any conclusions and generalisations drawn from the test results with regard to other specimens or samples of the type of the equipment represented by the test item. The test report may only be reproduced or published in full. Reproduction or publication of extracts from the report requires the prior written approval of CTC advanced GmbH.

This test report is electronically signed and valid without handwriting signature. For verification of the electronic signatures, the public keys can be requested at the testing laboratory.

The testing service provided by CTC advanced GmbH has been rendered under the current "General Terms and Conditions for CTC advanced GmbH".

CTC advanced GmbH will not be liable for any loss or damage resulting from false, inaccurate, inappropriate or incomplete product information provided by the customer.

Under no circumstances does the CTC advanced GmbH test report include any endorsement or warranty regarding the functionality, quality or performance of any other product or service provided.

Under no circumstances does the CTC advanced GmbH test report include or imply any product or service warranties from CTC advanced GmbH, including, without limitation, any implied warranties of merchantability, fitness for purpose, or non-infringement, all of which are expressly disclaimed by CTC advanced GmbH.

All rights and remedies regarding vendor's products and services for which CTC advanced GmbH has prepared this test report shall be provided by the party offering such products or services and not by CTC advanced GmbH.

In no case this test report can be considered as a Letter of Approval.

### 2.2 Application details

|                               |            |
|-------------------------------|------------|
| Date of receipt of order:     | 2022-10-10 |
| Date of receipt of test item: | 2022-10-10 |
| Start of test:                | 2022-10-20 |
| End of test:                  | 2022-10-25 |

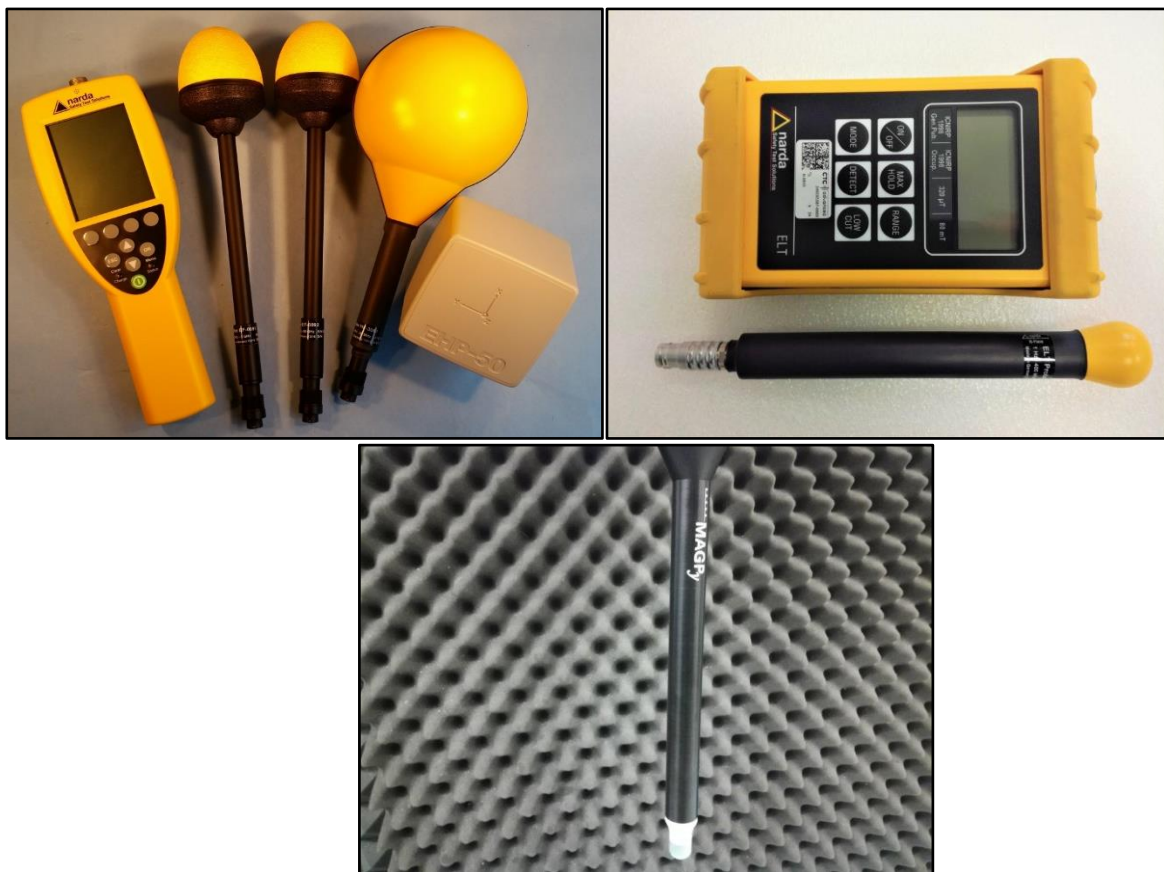
## 3 Test Environment

|                            |                                       |
|----------------------------|---------------------------------------|
| Ambient temperature:       | 20 – 24 °C                            |
| Relative humidity content: | 40 – 50 %                             |
| Air pressure:              | not relevant for this kind of testing |
| Power supply:              | 230 V / 50 Hz                         |

## 4 Test Set-up

### 4.1 Measurement system

#### 4.1.1 Broadband Electromagnetic Field Test system



A state of the art Broadband Electromagnetic Field Test system was used. The probes of the system are fitted with three sensors which measure the field strength of the X, Y and Z plane directions separately. The field strength is calculated by the instrument's processor by summing the squares of the three measured values.

The frequency range 5 Hz to 60 GHz is covered.

Depending on the used probe type Electric and Magnetic Field or Electric Field only is detectable.

- |                            |                   |                             |
|----------------------------|-------------------|-----------------------------|
| • EHP-50D                  | 5 Hz to 100 kHz   | Electric and Magnetic Field |
| • EHP-50F                  | 5 Hz to 400 kHz   | Electric and Magnetic Field |
| • HF 3061                  | 300 kHz to 30 MHz | Magnetic Field              |
| • EF 0691                  | 100 kHz to 6 GHz  | Electric Field              |
| • EF 6092                  | 100 MHz to 60 GHz | Electric Field              |
| • ELT 400 3cm <sup>2</sup> | 1 Hz to 400 kHz   | Magnetic Field              |
| • MAGPy-H3D                | 3 kHz to 10 MHz   | Magnetic Field              |

#### 4.1.2 Test equipment list

|                                     | Manufacturer | Device  | Type                     | Serial number | Last Calibration |
|-------------------------------------|--------------|---|--------------------------|---------------|------------------|
| <input type="checkbox"/>            | Narda        | Electric and Magnetic Field Meter                     | NBM-550                  | F-0319        | 2021-03-10       |
| <input type="checkbox"/>            | Narda        | Electric and Magnetic Field Meter                     | NBM-520                  | D-1234        | 2019-05-15       |
| <input type="checkbox"/>            | Narda        | Electric and Magnetic Field Meter                     | ELT 400                  | N-0915        | 2021-07-26       |
| <input type="checkbox"/>            | Narda        | Electric Field Probe (100 kHz - 6 GHz)                | EF 0691                  | G-0027        | 2021-03-10       |
| <input type="checkbox"/>            | Narda        | Electric Field Probe (100 MHz - 60 GHz)               | EF 6092                  | A-0071        | 2019-05-15       |
| <input type="checkbox"/>            | Narda        | Magnetic Field Probe (300 kHz to 30 MHz)              | HF 3061                  | D-0404        | 2021-02-23       |
| <input type="checkbox"/>            | Narda        | Electric and Magnetic Field Analyser (5 Hz – 100 kHz) | EHP-50D                  | 230WX50108    | 2021-03-03       |
| <input type="checkbox"/>            | Narda        | Electric and Magnetic Field Analyser (5 Hz – 400 kHz) | EHP-50F                  | 000WX60907    | 2020-10-14       |
| <input type="checkbox"/>            | Narda        | Magnetic Field Probe (1 Hz – 400 kHz)                 | B-Field 3cm <sup>2</sup> | C-0393        | 2021-07-26       |
| <input checked="" type="checkbox"/> | SPEAG        | MAGPy Field Probe                                     | MAGPy-H3D/DAS            | 1013/1023     | 2021-06-20       |

 Devices used during the test

 Devices not used during the test

### 4.1.3 Uncertainties

The probe uncertainties stated by the manufacturer are considered to be the main relevant and dominant issues.

#### 4.1.3.1 Typical uncertainty of MAGPy-H3D probe

Uncertainty Table for MAGPy-H3D

Uncertainty Budgets

##### 6.1.1 Preliminary Uncertainty Budget of the MAGPy-H3D Probe

| Uncertainty Source                | Tolerance (dB) | Distr. | Div.       | ci | Std.Unc. (dB) |
|-----------------------------------|----------------|--------|------------|----|---------------|
| <b>Probe uncertainty</b>          |                |        |            |    |               |
| Amplitude calibration uncertainty | 0.47           | norm   | 1          | 1  | 0.47          |
| Probe anisotropy                  | 0.5            | rect   | $\sqrt{3}$ | 1  | 0.29          |
| Probe dynamic linearity           | 0.15           | rect   | $\sqrt{3}$ | 1  | 0.09          |
| Probe frequency domain response   | 0.25           | rect   | $\sqrt{3}$ | 1  | 0.14          |
| Gradient uncertainty              | 0.1            | rect   | $\sqrt{3}$ | 1  | 0.06          |
| Parasitic E-field sensitivity     | 0.1            | rect   | $\sqrt{3}$ | 1  | 0.06          |
| Detection limit                   | 0.15           | rect   | $\sqrt{3}$ | 1  | 0.09          |
| Readout electronics               | 0              | norm   | 1          | 1  | 0             |
| Probe positioning                 | 0.19           | norm   | 1          | 1  | 0.19          |
| Repeatability                     | 0.1            | norm   | 1          | 1  | 0.10          |
| Combined uncertainty (k=1)        |                |        |            |    | 0.63          |
| Expanded uncertainty (k=2)        |                |        |            |    | 1.24          |

#### 4.1.4 Validation procedure

Before performing the tests the empty test chamber was checked for system immanent frequency responses. The following background signal level was detected. All levels are small enough to allow accurate proof of the limits to be considered.

| Probe     | Frequency Range | Magnetic Flux Density (B) in $\mu\text{T}$ | Magnetical Field Strength in A/m | Electrical Field Strength in V/m | Remark |
|-----------|-----------------|--|----------------------------------|----------------------------------|--------|
| MAGPy-H3D | 3 kHz – 10 MHz  | 0.023                                      | 0.018                            | --                               |        |

#### 4.1.5 Definition of test position and distances

In absence of an equipment specific regulation with given test distances, all not further noted test positions were measured in "touched" mode, the probe radome touching the DUT at the defined test position. Due to the mechanical concept of the used probe a distance between DUT surface and electrical centre of the probe antennas remains.

| Probe type | Maximum distance (cm) |                  |
|------------|-----------------------|------------------|
|            | Magnetic Field        | Electrical Field |
| MAGPy-H3D  | 0.7                   | --               |

#### 4.1.6 Measurement with MAGPy-H3D probe / DASY 8 WPT-System

The DASY8 WPT-System is a complete high precision robot-based evaluation platform for demonstrating compliance of wireless power transfer (WPT) devices according to IEC PAS 63184:2021(Chapter 8 "Measurement and numerical combination methods") and enables fully automated compliance testing.

It is composed of the isotropic probe MAGPy-H3D, the reference amplitude and phase probe (MAGPy-RA $\phi$ ), and the data acquisition system (MAGPy-DAS) mounted to the DASY8 robot via the emergency stop (MAGPy-ES). The induced electric (E-) fields and specific absorption rate (SAR) are assessed with Sim4Life's Quasi-Static EM Solver (P-EM-QS) using only the measured data. The dedicated graphical user interface (GUI) fully automates the testing workflow.

This allows for Laboratory evaluation of WPT devices and any other local electromagnetic source not requiring magnetic (H-) field volume scans exceeding 2000 x 1000 x 1500 mm:

- Evaluation of H-field (3 kHz – 10 MHz)
- Demonstration of compliance (3 kHz and 4 MHz) according to IEC PAS 63184:2021

#### NOTE:

For this report the DASY8 WPT system was only used for its advanced positioning possibilities and accuracy to perform basic H-field measurements in the close range of the EUT. Thus for no further complex system check procedures needed to be applied. The system noise level was measured before conducting the H-field measurements on the EUT.

## 4.2 Test results – Line scan at defined middle of the coil

STEP 1:

Defined start position on the surface of the EUT. (Start position)

STEP 2:

Line measurement from the surface of the EUT to a sufficient height (perpendicular).

TEST RESULTS:

| distance<br>between<br>sensor and<br>EUT-surface<br>[mm] | H - field<br>[A/m] | $H_{\text{Previous}}/H_{\text{Actual}} < 6\text{dB}^{(1)}$ | $H_{\text{Max}} > 10 \cdot H_{\text{Actual}}^{(2)}$ |
|--|--------------------|--|---|
| 7*   | 1547.06            | --   | --  |
| 8  | 1431.28            | TRUE   | FALSE   |
| 9  | 1325.11            | TRUE   | FALSE   |
| 10   | 1222.15            | TRUE   | FALSE   |
| 11   | 1138.80            | TRUE   | FALSE   |
| 12   | 1055.42            | TRUE   | FALSE   |
| 13   | 979.86             | TRUE   | FALSE   |
| 14   | 910.91             | TRUE   | FALSE   |
| 15   | 845.95             | TRUE   | FALSE   |
| 16   | 782.31             | TRUE   | FALSE   |
| 17   | 726.98             | TRUE   | FALSE   |
| 18   | 677.11             | TRUE   | FALSE   |
| 19   | 630.53             | TRUE   | FALSE   |
| 20   | 587.05             | TRUE   | FALSE   |
| 21   | 546.92             | TRUE   | FALSE   |
| 22   | 510.17             | TRUE   | FALSE   |
| 23   | 475.85             | TRUE   | FALSE   |
| 24   | 444.44             | TRUE   | FALSE   |
| 25   | 415.65             | TRUE   | FALSE   |
| 26   | 388.68             | TRUE   | FALSE   |
| 27   | 363.99             | TRUE   | FALSE   |
| 28   | 341.27             | TRUE   | FALSE   |
| 29   | 319.66             | TRUE   | FALSE   |
| 30   | 300.18             | TRUE   | FALSE   |
| 31   | 281.84             | TRUE   | FALSE   |
| 32   | 265.11             | TRUE   | FALSE   |
| 33   | 249.358            | TRUE   | FALSE   |
| 34   | 234.749            | TRUE   | FALSE   |
| 35   | 221.190            | TRUE   | FALSE   |
| 36   | 208.494            | TRUE   | FALSE   |
| 37   | 196.811            | TRUE   | FALSE   |
| 38   | 185.954            | TRUE   | FALSE   |
| 39   | 175.806            | TRUE   | FALSE   |
| 40   | 166.357            | TRUE   | FALSE   |



| distance between sensor and EUT-surface [mm] | H - field [A/m] | $H_{\text{Previous}}/H_{\text{Actual}} < 6\text{dB}^{1)}$ | $H_{\text{Max}} > 10 \cdot H_{\text{Actual}}^{2)}$ |
|--|-----------------|---|--|
| 41   | 157.405         | TRUE  | FALSE  |
| 42   | 149.182         | TRUE  | TRUE   |
| 43   | 141.358         | TRUE  | TRUE   |
| 44   | 134.085         | TRUE  | TRUE   |
| 45   | 127.297         | TRUE  | TRUE   |
| 46   | 120.900         | TRUE  | TRUE   |
| 47   | 114.895         | TRUE  | TRUE   |
| 48   | 109.237         | TRUE  | TRUE   |
| 49   | 104.014         | TRUE  | TRUE   |
| 50   | 99.009          | TRUE  | TRUE   |
| 51   | 94.394          | TRUE  | TRUE   |
| 52   | 90.003          | TRUE  | TRUE   |
| 53   | 85.816          | TRUE  | TRUE   |
| 54   | 81.973          | TRUE  | TRUE   |
| 55   | 78.258          | TRUE  | TRUE   |
| 56   | 74.833          | TRUE  | TRUE   |
| 57   | 71.486          | TRUE  | TRUE   |
| 58   | 68.405          | TRUE  | TRUE   |
| 59   | 65.474          | TRUE  | TRUE   |
| 60   | 62.653          | TRUE  | TRUE   |
| 61   | 60.044          | TRUE  | TRUE   |
| 62   | 57.549          | TRUE  | TRUE   |
| 63   | 55.216          | TRUE  | TRUE   |
| 64   | 52.981          | TRUE  | TRUE   |
| 65   | 50.908          | TRUE  | TRUE   |
| 66   | 48.882          | TRUE  | TRUE   |
| 67   | 46.974          | TRUE  | TRUE   |
| 68   | 45.160          | TRUE  | TRUE   |
| 69   | 43.431          | TRUE  | TRUE   |
| 70   | 41.794          | TRUE  | TRUE   |
| 71   | 40.238          | TRUE  | TRUE   |
| 72   | 38.770          | TRUE  | TRUE   |
| 73   | 37.346          | TRUE  | TRUE   |
| 74   | 36.003          | TRUE  | TRUE   |

<sup>1)</sup> The column shows if the deviation from the actual measurement point to the previous measured one is less than 6dB.

<sup>2)</sup> The column shows if ten times the actual value is less than the highest measured H-field.

\*)MAGPy probe touching the surface of the EUT

**NOTE:** For test positions see photo documentation (Annex A).

### 4.3 Test results – Line scan at found max. position

STEP 1:

Determination of max position on the surface of the EUT. (Found max. position)

STEP 2:

Line measurement from the surface of the EUT to a sufficient height (perpendicular).

TEST RESULTS:

| distance between sensor and EUT-surface [mm] | H - field [A/m] | $H_{\text{Previous}}/H_{\text{Actual}} < 6\text{dB}^{(1)}$ | $H_{\text{Max}} > 10 \cdot H_{\text{Actual}}^{(2)}$ |
|--|-----------------|--|---|
| 7*   | 1578.79         | --   | --  |
| 8  | 1442.28         | TRUE   | FALSE   |
| 9  | 1334.63         | TRUE   | FALSE   |
| 10   | 1230.56         | TRUE   | FALSE   |
| 11   | 1131.85         | TRUE   | FALSE   |
| 12   | 1047.08         | TRUE   | FALSE   |
| 13   | 968.27          | TRUE   | FALSE   |
| 14   | 897.28          | TRUE   | FALSE   |
| 15   | 831.67          | TRUE   | FALSE   |
| 16   | 770.84          | TRUE   | FALSE   |
| 17   | 715.59          | TRUE   | FALSE   |
| 18   | 664.96          | TRUE   | FALSE   |
| 19   | 619.03          | TRUE   | FALSE   |
| 20   | 575.82          | TRUE   | FALSE   |
| 21   | 535.96          | TRUE   | FALSE   |
| 22   | 498.36          | TRUE   | FALSE   |
| 23   | 465.51          | TRUE   | FALSE   |
| 24   | 434.48          | TRUE   | FALSE   |
| 25   | 405.81          | TRUE   | FALSE   |
| 26   | 379.03          | TRUE   | FALSE   |
| 27   | 355.28          | TRUE   | FALSE   |
| 28   | 332.77          | TRUE   | FALSE   |
| 29   | 312.01          | TRUE   | FALSE   |
| 30   | 292.75          | TRUE   | FALSE   |
| 31   | 274.82          | TRUE   | FALSE   |
| 32   | 258.45          | TRUE   | FALSE   |
| 33   | 243.046         | TRUE   | FALSE   |
| 34   | 228.628         | TRUE   | FALSE   |
| 35   | 214.802         | TRUE   | FALSE   |
| 36   | 203.211         | TRUE   | FALSE   |
| 37   | 191.902         | TRUE   | FALSE   |
| 38   | 181.087         | TRUE   | FALSE   |
| 39   | 171.357         | TRUE   | FALSE   |
| 40   | 161.935         | TRUE   | FALSE   |

| distance between sensor and EUT-surface [mm] | H - field [A/m] | $H_{\text{Previous}}/H_{\text{Actual}} < 6\text{dB}^{1)}$ | $H_{\text{Max}} > 10 \cdot H_{\text{Actual}}^{2)}$ |
|--|-----------------|---|--|
| 41   | 153.191         | TRUE  | TRUE   |
| 42   | 145.290         | TRUE  | TRUE   |
| 43   | 137.680         | TRUE  | TRUE   |
| 44   | 130.812         | TRUE  | TRUE   |
| 45   | 124.049         | TRUE  | TRUE   |
| 46   | 117.901         | TRUE  | TRUE   |
| 47   | 111.978         | TRUE  | TRUE   |
| 48   | 106.587         | TRUE  | TRUE   |
| 49   | 101.443         | TRUE  | TRUE   |
| 50   | 96.675          | TRUE  | TRUE   |
| 51   | 92.083          | TRUE  | TRUE   |
| 52   | 87.656          | TRUE  | TRUE   |
| 53   | 83.814          | TRUE  | TRUE   |
| 54   | 79.925          | TRUE  | TRUE   |
| 55   | 76.390          | TRUE  | TRUE   |
| 56   | 72.997          | TRUE  | TRUE   |
| 57   | 69.799          | TRUE  | TRUE   |
| 58   | 66.763          | TRUE  | TRUE   |
| 59   | 63.879          | TRUE  | TRUE   |
| 60   | 61.178          | TRUE  | TRUE   |
| 61   | 58.592          | TRUE  | TRUE   |
| 62   | 56.195          | TRUE  | TRUE   |
| 63   | 53.902          | TRUE  | TRUE   |
| 64   | 51.750          | TRUE  | TRUE   |
| 65   | 49.639          | TRUE  | TRUE   |
| 66   | 47.678          | TRUE  | TRUE   |
| 67   | 45.868          | TRUE  | TRUE   |
| 68   | 44.045          | TRUE  | TRUE   |
| 69   | 42.430          | TRUE  | TRUE   |
| 70   | 40.740          | TRUE  | TRUE   |
| 71   | 39.286          | TRUE  | TRUE   |
| 72   | 37.820          | TRUE  | TRUE   |
| 73   | 36.461          | TRUE  | TRUE   |
| 74   | 35.130          | TRUE  | TRUE   |

<sup>1)</sup> The column shows if the deviation from the actual measurement point to the previous measured one is less than 6dB.

<sup>2)</sup> The column shows if ten times the actual value is less than the highest measured H-field.

\*)MAGPy probe touching the surface of the EUT

**NOTE:** For test positions see photo documentation (Annex A).

## Annex A: Photo documentation

Photo 1: DASY 8 WPT set up



Photo 2: EUT on test bank

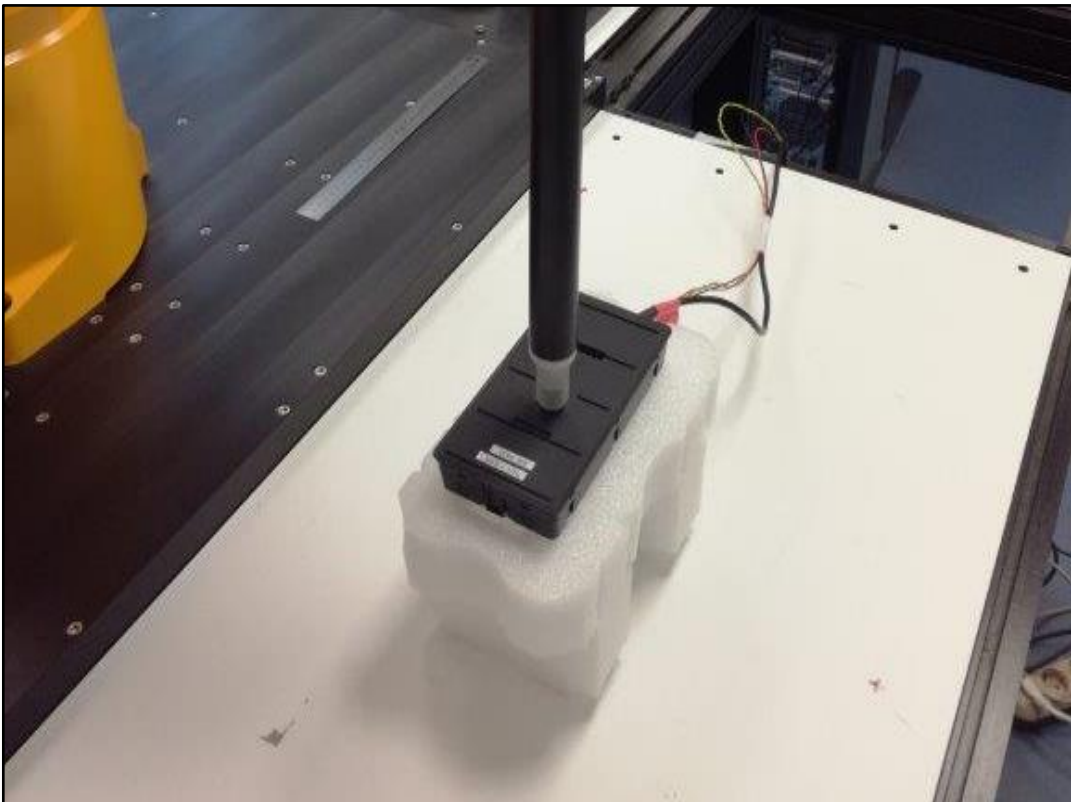


Photo 3: System Orientation

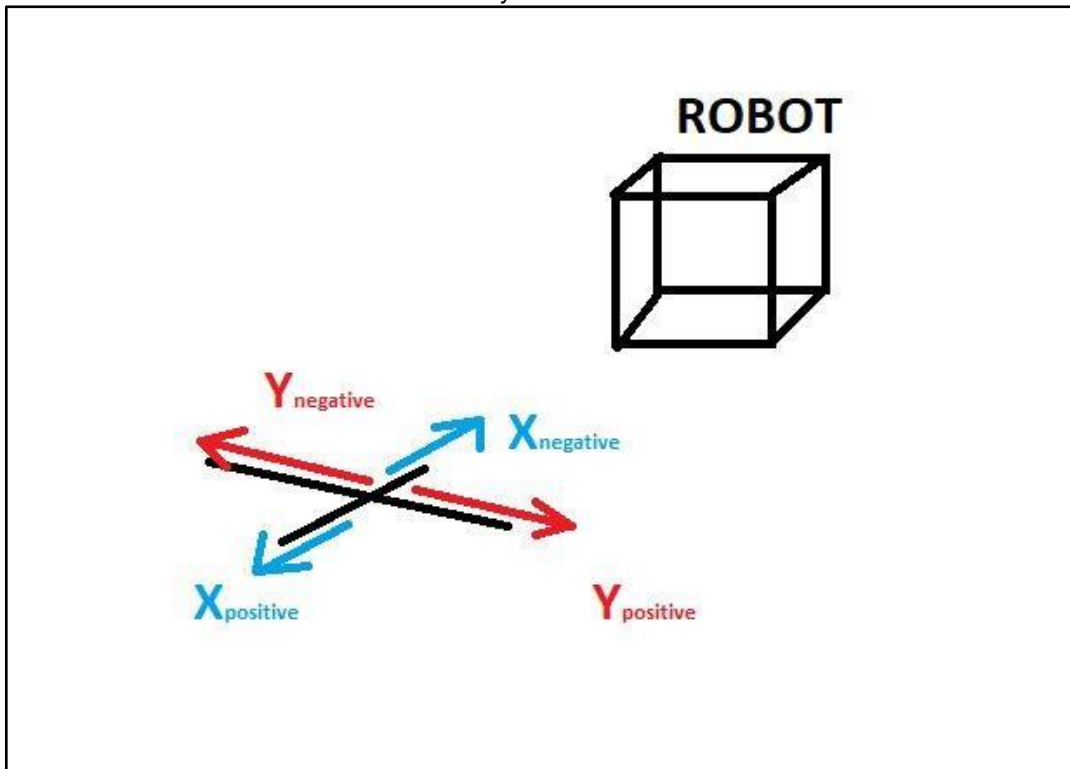


Photo 4: EUT – Top side view





Photo 5: Test pictures - Setting distance to EUT (touch - top side)  
[Offset caused by Battery symbol]

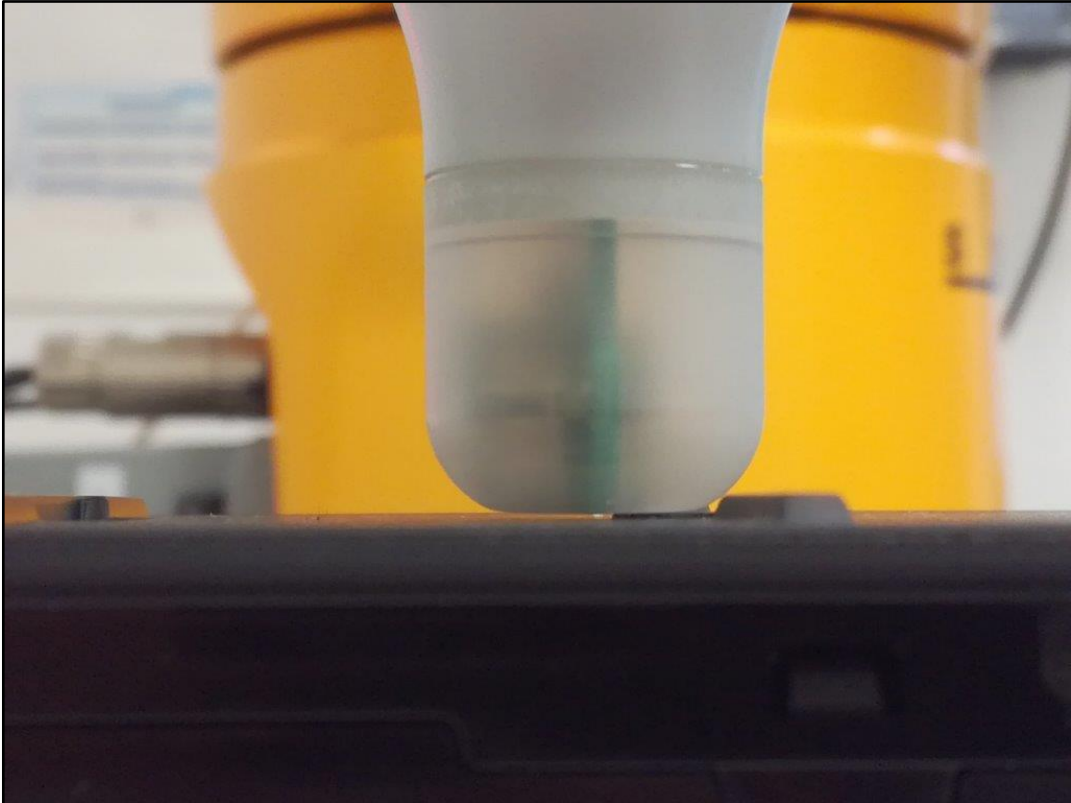


Photo 6: Test pictures – Start position (Coil 3 centre – top side)

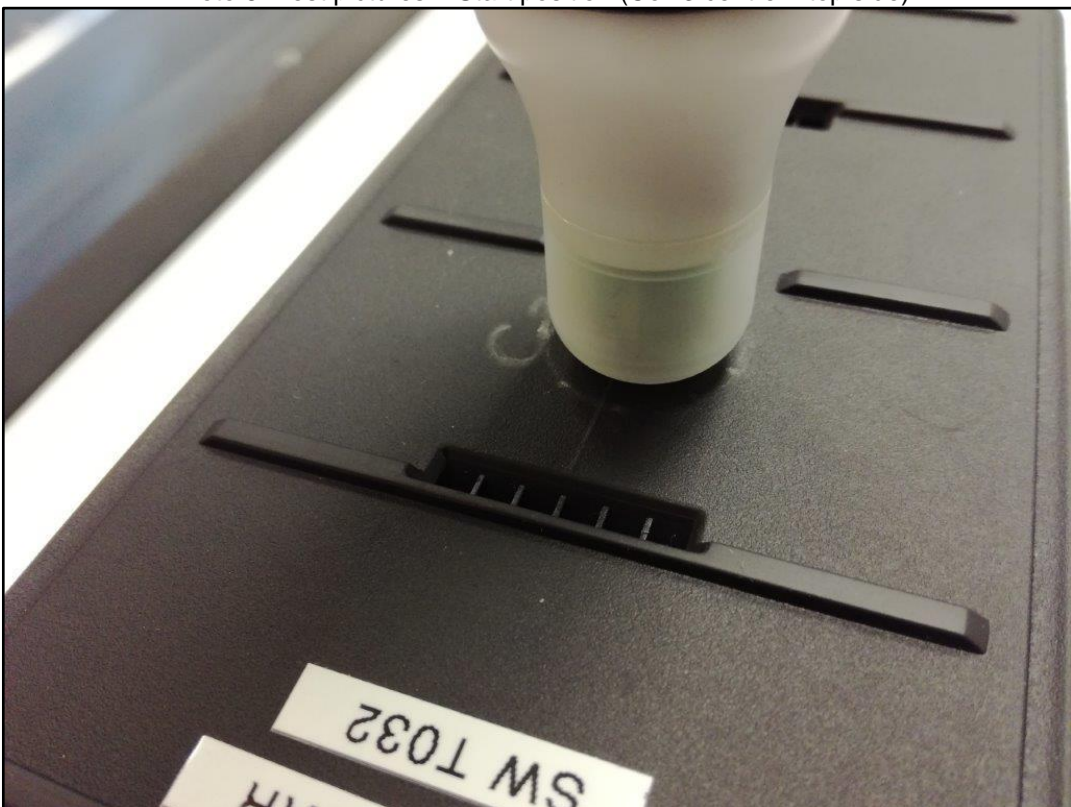
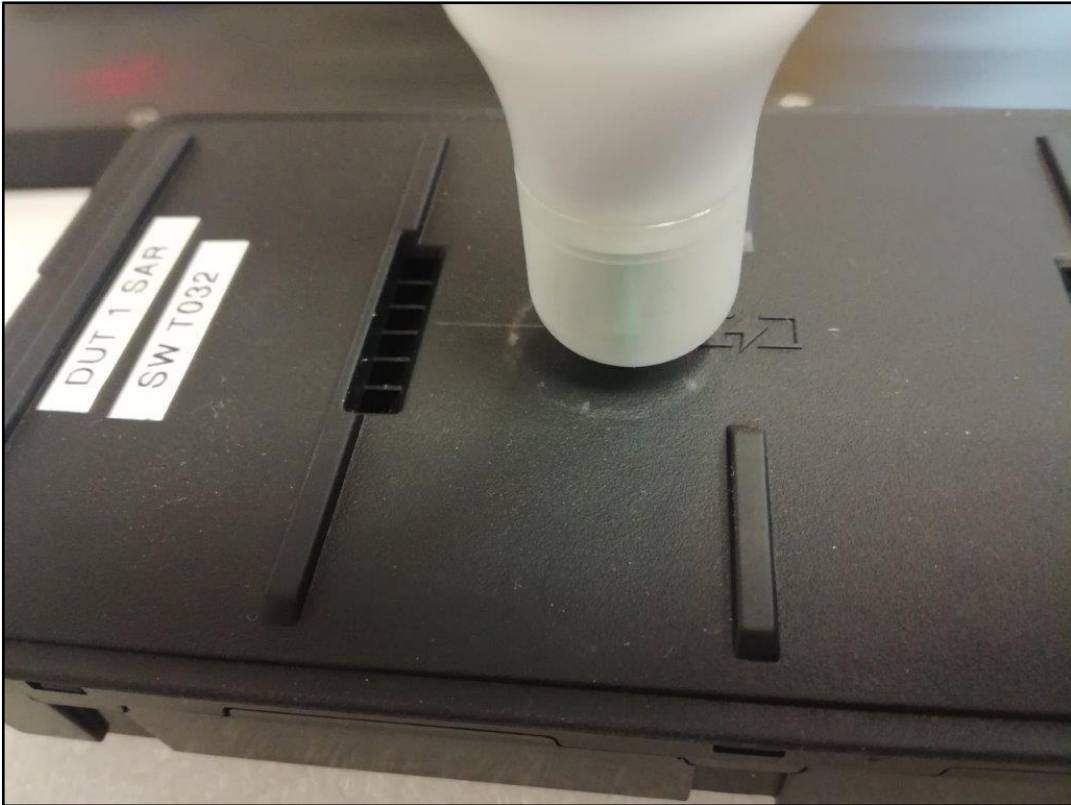


Photo 7: Test pictures – Found max. position (Coil 3 – top side)



**Annex B: Document History**

| Version | Applied Changes | Date of Release |
|---------|-----------------|-----------------|
|         | Initial Release | 2023-03-01      |
|         |                 |                 |

**Annex C: Further Information****Glossary**

|          |   |                                 |
|----------|---|---------------------------------|
| BW       | - | Bandwidth                       |
| DTS      | - | Distributed Transmission System |
| DUT      | - | Device under Test               |
| EUT      | - | Equipment under Test            |
| HW       | - | Hardware                        |
| Inv. No. | - | Inventory number                |
| N/A      | - | not applicable                  |
| S/N      | - | Serial Number                   |
| SW       | - | Software                        |