Leica TS01



User Manual Version 1.1.9 English







Introduction

Purchase	Congratulations on the purchase of the Leica TS01.				
	This manual contains important safety directions as well as instructions for setting up the product and operating it. Refer to 1 Safety Directions for fur- ther information.				
	Read carefully through the User Manual before you switch on the product.				
		cument is subject to change without prior notice. Ensure ed in accordance with the latest version of this docu-			
-		cument is subject to change without prior notice. Ensure ed in accordance with the latest version of this docu-			
		Updated versions are available for download at the following Internet address: <u>myWorld@Leica Geosystems</u> > myProducts.			
Product identification	The model and serial number of your product are indicated on the type plate Always refer to this information when you need to contact your agency or Leica Geosystems authorised service centre.				
Validity of this manual	This manual applies to the TS01 manual total station.				
Leica Geosystems address book	On the last page of this manual, you can find the address of Leica Geosystems headquarters. For a list of regional contacts, please visit http://leica-geosystems.com/contact-us/sales_support .				
‴world	myWorld@Leica Geosystema fraining material.	stems offers a wide range of services, information and			
	With direct access to n whenever it is convenie	nyWorld, you are able to access all relevant services ent for you.			
	The availability of services depends on the instrument model.				
	Service	Description			
	myProducts	Add all products that you and your company own and explore your world of Leica Geosystems: View detailed information on your products and update your products with the latest software and keep up- to-date with the latest documentation.			
	myService	View the current service status and full service his- tory of your products in Leica Geosystems service centres. Access detailed information on the services performed and download your latest calibration cer- tificates and service reports.			

Service	Description	
mySupport	Create new support requests for your products that will be answered by your local Leica Geosystems Support Team. View the complete history of your support requests and view detailed information on each request in case you want to refer to previous support requests.	
myLearning	Welcome to the home of Leica Geosystems online learning! There are numerous online courses – avail- able to all customers with products that have valid CCPs (Customer Care Packages).	
myTrustedServices	Add your subscriptions and manage users for Leica Geosystems Trusted Services, the secure software services, that assist you to optimise your workflow and increase your efficiency.	
mySmartNet	HxGN SmartNet is the GNSS correction service built on the world's largest reference station network, enabling GNSS-capable devices to quickly determine precise positions in the range of one to two centi- metre accuracy. The service is provided 24/7 by a highly-available infrastructure and professional sup- port team with more than 10 years of experience reliably delivering the service.	
myDownloads	Downloads of software, manuals, tools, training material and news for Leica Geosystems products.	

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1	Safety Directions			
1.1	General	General		
Description	The following directions enable the person responsible for the product, and the person who actually uses the equipment, to anticipate and avoid opera- tional hazards.			
	The person responsible for th these directions and adhere t	e product must ensure that all users understand o them.		
About warning messages		ential part of the safety concept of the instru- hazards or hazardous situations can occur.		
	Warning messages			
		t direct and indirect hazards concerning the use		
	For the users' safety, all safet	y instructions and safety messages shall be !! Therefore, the manual must always be available		
	DANGER , WARNING , CAUTION and NOTICE are standardised signal words fo identifying levels of hazards and risks related to personal injury and property damage. For your safety, it is important to read and fully understand the following table with the different signal words and their definitions! Supple- mentary safety information symbols may be placed within a warning message as well as supplementary text.			
	TypeDescriptionA DANGERIndicates an imminently hazardous situation which, if not avoided, will result in death serious injury.			
	Awarning	Indicates a potentially hazardous situation or an unintended use which, if not avoided, could result in death or serious injury.		
	CAUTION Indicates a potentially hazardous sit or an unintended use which, if not a may result in minor or moderate inju			
	NOTICE	Indicates a potentially hazardous situation or an unintended use which, if not avoided, may result in appreciable material, financial and environmental damage.		
	537	Important paragraphs which must be adhered to in practice as they enable the product to be used in a technically correct and efficient manner.		

1.2	Definition of Use	
Intended use	 Measuring horizontal and vertical angles Measuring distances Recording measurements Visualising the aiming direction and vertical axis Data communication with external appliances Computing with software 	
Reasonably forseeable misuse	Use of the product without instruction Use outside of the intended use and limits Disabling of safety systems Removal of hazard notices Opening the product using tools, for example a screwdriver, unless this is permitted for certain functions Modification or conversion of the product Use after misappropriation Use of products with recognisable damage or defects Use with accessories from other manufacturers without the prior explicit approval of Leica Geosystems Deliberate dazzling of third parties Controlling of machines, moving objects or similar monitoring applications without additional control and safety installations Aiming directly into the sun Inadequate safeguards at the working site	
1.3	Limits of Use	
Environment	 Suitable for use in an atmosphere appropriate for permanent human habitation. Not suitable for use in aggressive or explosive environments. MARNING Working in hazardous areas, or close to electrical installations or similar situations Life Risk. Precautions: Local safety authorities and safety experts must be contacted by the person responsible for the product before working in such conditions. 	
1.4	Responsibilities	
Manufacturer of the product	Leica Geosystems AG, CH-9435 Heerbrugg, hereinafter referred to as Leica Geosystems, is responsible for supplying the product, including the User Manual and original accessories, in a safe condition.	

Person responsible for the product

The person responsible for the product has the following duties:

- To understand the safety instructions on the product and the instructions in the User Manual
- To ensure that it is used in accordance with the instructions
- To be familiar with local regulations relating to safety and accident prevention
- To stop operating the system and inform Leica Geosystems immediately if the product and the application become unsafe
- To ensure that the national laws, regulations and conditions for the operation of the product are respected

1.5 Hazards of Use

NOTICE

Dropping, misusing, modifying, storing the product for long periods or transporting the product

Watch out for erroneous measurement results.

Precautions:

 Periodically carry out test measurements and perform the field adjustments indicated in the User Manual, particularly after the product has been subjected to abnormal use as well as before and after important measurements.

Risk of electrocution

Because of the risk of electrocution, it is dangerous to use poles, levelling staffs and extensions in the vicinity of electrical installations such as power cables or electrical railways.

Precautions:

Keep at a safe distance from electrical installations. If it is essential to work in this environment, first contact the safety authorities responsible for the electrical installations and follow their instructions.



Lightning strike

If the product is used with accessories, for example masts, staffs, poles, you may increase the risk of being struck by lightning.

Precautions:

• Do not use the product in a thunderstorm.

\land WARNING

Distraction/loss of attention

During dynamic applications, for example stakeout procedures, there is a danger of accidents occurring if the user does not pay attention to the environmental conditions around, for example obstacles, excavations or traffic.

Precautions:

 The person responsible for the product must make all users fully aware of the existing dangers.

Inadequate securing of the working site

This can lead to dangerous situations, for example in traffic, on building sites and at industrial installations.

Precautions:

- Always ensure that the working site is adequately secured.
- Adhere to the regulations governing safety, accident prevention and road traffic.

Pointing product toward the sun

Be careful when pointing the product toward the sun, because the telescope functions as a magnifying glass and can injure your eyes and/or cause damage inside the product.

Precautions:

• Do not point the product directly at the sun.

Not properly secured accessories

If the accessories used with the product are not properly secured and the product is subjected to mechanical shock, for example blows or falling, the product may be damaged or people can sustain injury.

- When setting up the product, make sure that the accessories are correctly adapted, fitted, secured, and locked in position.
- Avoid subjecting the product to mechanical stress.

Inappropriate mechanical influences to batteries

During the transport, shipping or disposal of batteries it is possible for inappropriate mechanical influences to constitute a fire hazard.

Precautions:

- Before shipping the product or disposing it, discharge the batteries by the product until they are flat.
- When transporting or shipping batteries, the person in charge of the product must ensure that the applicable national and international rules and regulations are observed.
- Before transportation or shipping, contact your local passenger or freight transport company.

Exposure of batteries to high mechanical stress, high ambient temperatures or immersion into fluids

This can cause leakage, fire or explosion of the batteries.

Precautions:

 Protect the batteries from mechanical influences and high ambient temperatures. Do not drop or immerse batteries into fluids.

Short circuit of battery terminals

If battery terminals are short circuited e.g. by coming in contact with jewellery, keys, metallised paper or other metals, the battery can overheat and cause injury or fire, for example by storing or transporting in pockets.

Precautions:

 Make sure that the battery terminals do not come into contact with metallic objects.

Improper disposal

If the product is improperly disposed of, the following can happen:

- If polymer parts are burnt, poisonous gases are produced which may impair health.
- If batteries are damaged or are heated strongly, they can explode and cause poisoning, burning, corrosion or environmental contamination.
- By disposing of the product irresponsibly you may enable unauthorised persons to use it in contravention of the regulations, exposing themselves and third parties to the risk of severe injury and rendering the environment liable to contamination.
- Improper disposal of silicone oil may cause environmental contamination.
- The product does include parts of Beryllium inside. Any modification of some internal parts can release Beryllium dust or fragments, creating a health hazard.

Precautions:



The product must not be disposed with household waste. Dispose of the product appropriately in accordance with the national regulations in force in your country. Always prevent access to the product by unauthorised personnel.

Product-specific treatment and waste management information can be received from your Leica Geosystems distributor.

Improperly repaired equipment

Risk of injuries to users and equipment destruction due to lack of repair knowledge.

Precautions:

Only authorised Leica Geosystems Service Centres are entitled to repair these products.

1.6	Laser Classification	
1.6.1	General	
General	The following chapters provide instructions and training information about laser safety according to international standard IEC 60825-1 (2014-05) and technical report IEC TP 60825-14 (2004-02). The information enables the	

laser safety according to international standard IEC 60825-1 (2014-05) and technical report IEC TR 60825-14 (2004-02). The information enables the person responsible for the product and the person who actually uses the equipment, to anticipate and avoid operational hazards.

According to IEC TR 60825-14 (2004-02), products classified as laser class 1, class 2 and class 3R do not require:

- laser safety officer involvement,
- protective clothes and eyewear,
- special warning signs in the laser working area

if used and operated as defined in this User Manual due to the low eye hazard level.

	instructions for		could impose more stringent ers than IEC 60825-1 (2014-05)	
1.6.2	Distancer, Measuren	nents with Refle	ctors	
General	The EDM module built in emerges from the telesc		uces a visible laser beam which	
	The laser product descril accordance with: • IEC 60825-1 (2014-		classified as laser class 1 in	
		he eyes provided th	preseeable conditions of operation at the products are used and nual.	
	Description		Value	
	Wavelength		685 nm	
	Pulse duration		6673 ps	
	Pulse repetition freque	псу	75 MHz	
	Maximum average radia	nt power	0.34 mW	
	Beam divergance		1.5 mrad x 3 mrad	
		a	Laser beam	
1.6.3	Distancer, Measuren	nents without Re	flectors	
General	The EDM module built into the product produces a visible laser beam which emerges from the telescope objective.			
	 The laser product described in this section is classified as laser class 3R in accordance with: IEC 60825-1 (2014-05): "Safety of laser products" 			
	lar for deliberate ocular	exposure. The beam ularly under low am	(low eye hazard level), in particu- may cause dazzle, flash-blindness pient light conditions. The risk of ecause of:	

- a) unintentional exposure would rarely reflect worst case conditions of (e.g.) beam alignment with the pupil, worst case accommodation,
- b) inherent safety margin in the maximum permissible exposure to laser radiation (MPE)
- c) natural aversion behaviour for exposure to bright light for the case of visible radiation.

Description	Value
Wavelength	685 nm
Maximum average radiant power	4.8 mW
Pulse duration	6673 ps
Pulse repetition frequency	75 MHz
Beam divergence	0.2 mrad x 0.3 mrad
NOHD (Nominal Ocular Hazard Distance) @ 0.25s	44 m

Class 3R laser products

From a safety perspective, class 3R laser products should be treated as potentially hazardous.

Precautions:

- Prevent direct eye exposure to the beam.
- Do not direct the beam at other people.

ACAUTION

Reflected beams aimed at reflecting surfaces

Potential hazards are not only related to direct beams but also to reflected beams aimed at reflecting surfaces such as prisms, windows, mirrors, metallic surfaces, etc.

- Do not aim at areas that are essentially reflective, such as a mirror, or which could emit unwanted reflections.
- Do not look through or beside the optical sight at prisms or reflecting objects when the laser is switched on, in laser pointer or distance measurement mode. Aiming at prisms is only permitted when looking through the telescope.



1.6.4	Red Laser Pointer			
General	The laser pointer built into the product product which emerges from the telescope objective.	es a visible red laser beam		
	The laser product described in this section is c accordance with:	The laser product described in this section is classified as laser class 3R in accordance with:		
	• IEC 60825-1 (2014-05): "Safety of laser p	roducts"		
	 lar for deliberate ocular exposure. The beam mand after-images, particularly under low ambie injury for laser class 3R products is limited beca a) unintentional exposure would rarely reflect beam alignment with the pupil, worst case b) inherent safety margin in the maximum peration (MPE) c) natural aversion behaviour for exposure to a safety and a safety a safe	beam alignment with the pupil, worst case accommodation,b) inherent safety margin in the maximum permissible exposure to laser radiation (MPE)		
	visible radiation. Description	Value		
	Description	value		
	Wavelength Measurements to prisms and reflectorless	685 nm		
	Maximum average radiant power	4.8 mW		

Description	Value
Pulse duration	6673 ps
Pulse repetition frequency (PRF)	75 MHz
Beam divergence	0.2 mrad x 0.3 mrad
NOHD (Nominal Ocular Hazard Distance) @ 0.25 s	44 m / 144 ft

Class 3R laser products

From a safety perspective, class 3R laser products should be treated as potentially hazardous.

Precautions:

- Prevent direct eye exposure to the beam.
- Do not direct the beam at other people.

Reflected beams aimed at reflecting surfaces

Potential hazards are not only related to direct beams but also to reflected beams aimed at reflecting surfaces such as prisms, windows, mirrors, metallic surfaces, etc.

Precautions:

- Do not aim at areas that are essentially reflective, such as a mirror, or which could emit unwanted reflections.
- Do not look through or beside the optical sight at prisms or reflecting objects when the laser is switched on, in laser pointer or distance measurement mode. Aiming at prisms is only permitted when looking through the telescope.



Labelling



1.6.5 Laser Plummet

General

The laser plummet built into the product produces a visible red laser beam which emerges from the bottom of the product.

The laser product described in this section is classified as laser class 2 in accordance with:

• IEC 60825-1 (2014-05): "Safety of laser products"

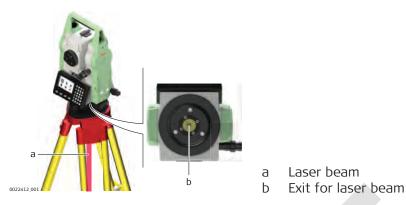
These products are safe for momentary exposures but can be hazardous for deliberate staring into the beam. The beam may cause dazzle, flash-blindness and after-images, particularly under low ambient light conditions.

Description	Value
Wavelength	640 nm
Maximum average radiant power	0.95 mW
Pulse duration	0.1 ms - cw
Pulse repetition frequency (PRF)	1 kHz
Beam divergance	<1.5 mrad

Class 2 laser product

From a safety perspective, class 2 laser products are not inherently safe for the eyes.

- Avoid staring into the beam or viewing it through optical instruments.
- Avoid pointing the beam at other people or at animals.



Electromagnetic Compatibility (EMC)

Description

1.7

The term Electromagnetic Compatibility is taken to mean the capability of the product to function smoothly in an environment where electromagnetic radiation and electrostatic discharges are present, and without causing electromagnetic disturbances to other equipment.

Electromagnetic radiation

Electromagnetic radiation can cause disturbances in other equipment. **Precautions:**

Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that other equipment may be disturbed.

Use of the product with accessories from other manufacturers. For example, field computers, personal computers or other electronic equipment, non-standard cables or external batteries

This may cause disturbances in other equipment.

- Use only the equipment and accessories recommended by Leica Geosystems.
- When combined with the product, other accessories must meet the strict requirements stipulated by the guidelines and standards.
- ➤ When using computers, two-way radios or other electronic equipment, pay attention to the information about electromagnetic compatibility provided by the manufacturer.

Intense electromagnetic radiation. For example, near radio transmitters, transponders, two-way radios or diesel generators

Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that the function of the product may be disturbed in such an electromagnetic environment.

Precautions:

• Check the plausibility of results obtained under these conditions.

Electromagnetic radiation due to improper connection of cables

If the product is operated with connecting cables, attached at only one of their two ends, the permitted level of electromagnetic radiation may be exceeded and the correct functioning of other products may be impaired. For example, external supply cables or interface cables.

Precautions:

While the product is in use, connecting cables, for example product to external battery or product to computer, must be connected at both ends.

Radios or digital cellular phones

Use of product with radio or digital cellular phone devices

Electromagnetic fields can cause disturbances in other equipment, installations, medical devices, for example pacemakers or hearing aids, and aircrafts. Electromagnetic fields can also affect humans and animals.

- Although the product meets the strict regulations and standards which are in force in this respect, Leica Geosystems cannot completely exclude the possibility that other equipment can be disturbed or that humans or animals can be affected.
- Do not operate the product with radio or digital cellular phone devices in the vicinity of filling stations or chemical installations, or in other areas where an explosion hazard exists.
- Do not operate the product with radio or digital cellular phone devices near medical equipment.
- Do not operate the product with radio or digital cellular phone devices in aircrafts.
- Do not operate the product with radio or digital cellular phone devices for long periods with the product immediately next to your body.

Exceeding the RF radiation exposure limits for general population Health risk

- The antennas used for this transmitter must be installed such that a minimum separation distance of at least 23 cm is always maintained between the radiator (antenna) and all persons.
- The antennas used for this transmitter must not be co-located or operated with any other antenna or transmitter.

2	Description of the System			
2.1	System Com	System Components		
Main components		a TS01 instrument with basic field software b Computer with office software c Data transfer		
	Component	Description		
	TS01	TS01 An instrument for measuring, calculating and capturing data. Ideally suited for tasks from simple surveys to complex applications. Equipped with a Basic field software to com- plete these tasks.		
	Basic field software	The firmware package installed on the instrument. Consists of a standard base operating system with additional applications.		
	Office soft- ware An office software consisting of a suite of standard and extended programs for the viewing, exchanging, managing and post processing of data.			
	Data transfer Data can be transferred between a TS01 and a computer USB-stick.			

Container Contents

Container contents

2.2



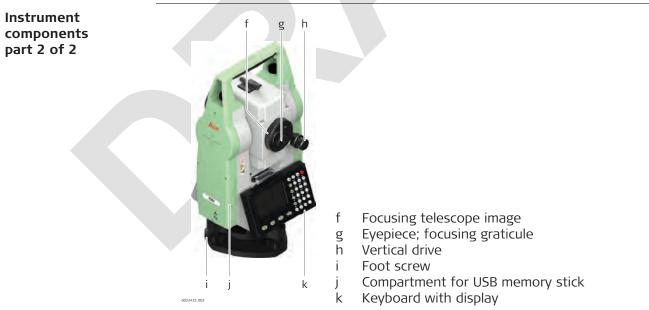
- a Instrument
- b GEB264 battery
- c Tool pouch
- d GKL264 charger
- e GEV289 adapter for charger
- f Manuals
- g Protective cover

2.3 Instrument Components

Instrument components part 1 of 2



- a Battery cover
- b Optical sight
- c Detachable carrying handle with mounting screw
- d Objective with integrated Electronic Distance Measurement (EDM). Exit for EDM laser beam e Horizontal drive



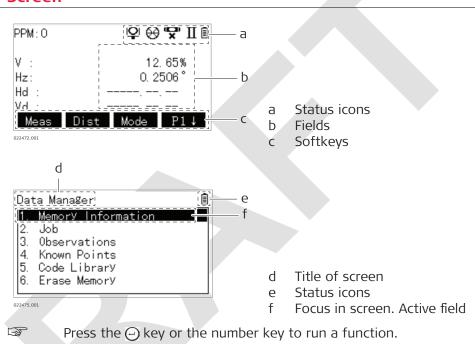
3 3.1	User Interface Keyboard		
Keyboard	(1) (2) (2) (2) (2) (2) (2) (2) (2) (2) (2	a Function keys F1 - F4 b Fixed keys c Short cut key K1, navigation d Short cut key K2, navigation e ESC key f ENTER key g ON/OFF key h Number/letter keys bc d e f	
Keys	Кеу	Description	
		If the instrument is already off: Turns on the instrument when held for 2 s. If the instrument is already on: Turns to Power Options menu when held for 2 s.	
	M	Enter the Main Menu	
	1	Switch between prism and non-prism mode	
		Favourites key Quick-access to measurement supporting functions.	
		Enter the angle survey interface during standard survey	
		Enter the distance measurement panel during standard survey Double click to switch between slope distance and height difference.	
	K	Enter the coordinate measurement panel during standard survey Navigation key, up	
	<u>S0</u>	Enter the set out panel during standard survey Navigation key, down	
	K1	User key 1 Programmable with a function from the K1 Setting menu. Navigation key, left	
	(K2)	User key 2 Programmable with a function from the K2 Setting menu. Navigation key, right	
	\odot	Pressing ESC short: Returns to next higher level. Quits a screen or edit mode without saving changes.	
		Pressing ESC long: Returns to the standard survey screen.	

Кеу	Description
\bigcirc	ENTER key Confirms an entry and continues to the next field.
\odot	Turn the red laser on/off.
$\overline{\mathbf{O}}$	Access the centering/leveling interface.
F1	Function keys that are assigned the variable functions displayed at the bottom of the screen.

3.2

Screen





3.3

Description

Status Icons

The icons provide status information related to basic instrument functions. Depending on the configuration, different icons are displayed.

lcons

	lcon	Description
	<u></u>	Prism mode
	⇔	EDM type for measuring to Round prism.
-	ee MiNi	EDM type for measuring to Mini prism.
-		EDM type for measuring to 360° prism.

lcon	Description
E MiNi	EDM type for measuring to 360° Mini prism.
<u>.</u>	EDM type for measuring to Custom prism.
*	Non prism EDM mode for measuring to all targets.
•	EDM mode for measuring to reflective foils.
.	EDM mode for measuring to reflective foils. Custom defined.
(D) V	Compensator is on.
(D) X	Compensator is off.
Ι	Indicates that telescope position is face I.
Ш	Indicates telescope position in face II.
Ē	The battery symbol indicates the level of the remaining bat- tery capacity in 25% steps.

3.4	Softkeys		
Description	Softkeys are selected using the relevant F1 to F4 function key. This chapter describes the functionality of the common softkeys used by the system. The more specialised softkeys are described with the apps where they appear.		
Common softkey	Кеу	Description	
functions	ОК	If entry screen: Confirms measured or entered values and continues the process. If message screen: Confirms message and continues with selected action or returns to the previous screen to reselect an option.	
	Back	To return to the last active screen.	
	EDM	To view and change EDM settings. Refer to 5.6 EDM Set- tings.	
	Coord	To open the manual coordinate entry screen.	
	Search	To search for an entered point.	
	Value	To display the list of available points.	
	Meas	To start distance and angle measurements and save the measured values.	
	Store	To save the displayed values without executing a distance measurement.	

Кеу	Description
Dist	To execute a distance measurement.
View	To view details about the selected item.
Letter	To change the keypad operation to alphanumerical.
Number	To change the keypad operation to numerical.
P↓	To display the next softkey level.

3.5	Operating Principles			
Turn instrument	Button Description			
on/off		To turn the instrument on or off, use the On/Off key on the keyboard of the instrument.		
Alphanumeric keypad	fields.	nerical keypad is used to enter characters directly into editable		
 Nur the Alp key play For Whe 		c fields : Can only contain numerical values. By pressing a key of ad the number will be displayed. Imeric fields: Can contain numbers and letters. By pressing a ne keypad the first character written above that key will be dis- By pressing several times you can toggle through the characters. hple: $1->S->T->U->1->S$ e alphanumeric mode is active, numbers are not selectable. For T=>U=>V=>T		
Edit fields	Button	Description		
	- B	ESC deletes any change and returns to previous panel.		
	<u>(K1</u>	Moves the cursor to the left		
	<u>(k2</u>)	Moves the cursor to the right.		
3.6	Point Sea	rch		
Description	Pointsearch i storage.	s a function to find measured points or fixpoints in the memory		
		It is possible to limit the point search to a particular job. The search proced- ure always finds fixpoints before measured points that fulfil the same search criteria.		
Direct search	, ,	an actual point number, for example 402, and pressing Search , all the selected job and with the corresponding point number are		
	Кеу	Description		
	Search	To search for matching points within the selected job.		
-				

4	Operation			
4.1	Instrument Setup			
Description	This topic describes an instrument setup over a marked ground point using the laser plummet. It is always possible to set up the instrument without the need for a marked ground point.			
T.	 Important features It is always recommended to shield the instrument from direct sunlight and avoid uneven temperatures around the instrument. The laser plummet described in this topic is built into the vertical axis of the instrument. It projects a red spot onto the ground, making it appre- ciably easier to centre the instrument. The laser plummet cannot be used with a tribrach equipped with an optical plummet. 			
Tripod	FOX.012b			
	 Loosen the clamping screws on the tripod legs, pull out to the required length and tighten the clamps. a In order to guarantee a firm foothold sufficiently press the tripod legs into the ground. b When pressing the legs into the ground. b When pressing the legs into the ground. b When pressing the legs into the ground. 			
	 Careful handling of tripod. Check all screws and bolts for correct fit. During transport, always use the cover supplied. Use the tripod only for surveying tasks. 			

Setup step-by-step		3 2 $4/6$ 7 $4/6$ 5 b 5 b 5 b 5		
	1.	Extend the tripod legs to allow for a comfortable working posture. Position the tripod over the marked ground point, centring it as best as possible.		
	2.	Fasten the tribrach and instrument onto the tripod.		
	3.	Turn on the instrument, and, if tilt correction is set to ON , the laser plummet will be activated automatically, and the Auto-Com-pensator screen appears. Otherwise, press the \textcircled{M} key from within any app and select Level .		
	4.	Move the tripod legs and use the tribrach footscrews (a) to centre the plummet over the ground point (c).		
	5.	Adjust the tripod legs to level the axis level (c).		
	6.	By using the electronic level, turn the tribrach footscrews to pre- cisely level the instrument. Refer to Level up with the electronic level step-by-step.		
	7.	Centre the instrument precisely over the ground point by shifting the tribrach on the tripod plate.		
_	8.	Repeat steps 6. and 7. until the required accuracy is achieved.		
Level up with the electronic level step- by-step		ctronic level can be used to precisely level up the instrument using the ews of the tribrach.		
by step	1.	Turn the instrument until it is parallel to two footscrews.		
	2.	Centre the circular level approximately by turning the footscrews of the tribrach.		
	3.	Turn on the instrument, and, if tilt correction is set to on, the laser plummet will be activated automatically, and the Auto-Compensator screen appears. Otherwise, press the $$ key from within any app and select Level .		
		The bubble of the electronic level and the arrows for the rotating direction of the footscrews only appear if the instrument tilt is inside a certain levelling range.		
	4.	Centre the electronic level of the first axis by turning the two footscrews. The first axis is levelled, when the bubble is exactly in the centre of the first axis.		
	5.	Turn the instrument by 90° so that it is perpendicular to the previous position.		

	6.	Centre the electronic level for the second axis by turning the last footscrew. The second axis is levelled when the bubble is also in the centre of the second axis. This bubble should now be exactly in the centre of the electronic level.		
	7.	Repeat step 5. and step 6. .		
Change the intensity of the laser plummet	External influences and the surface conditions may require the adjustment of the intensity of the laser plummet.			
		Auto-Compensator screen, ac the 🙆 and 🗐 key.	djust the intensity of the laser plummet	
	The las	ser can be adjusted in 20% step	os as required.	
Position over pipes or holes			Under some circumstances the laser dot is not visible, for example over pipes. In this case, using a transpar- ent plate enables the laser dot to be seen and then easily aligned to the centre of the pipe.	

 Batteries Operating Principles The battery must be charged before using it for the first time because it is delivered with an energy content as low as possible The permissible temperature range for charging is from 0 °C to +40 °C/ +32 °F to +104 °F. For optimal charging, we recommend charging the batteries at a low ambient temperature of +10 °C to +20 °C/+50 °F to +68 °F if possible It is normal for the battery to become warm during charging. Using the
 delivered with an energy content as low as possible The permissible temperature range for charging is from 0 °C to +40 °C/ +32 °F to +104 °F. For optimal charging, we recommend charging the batteries at a low ambient temperature of +10 °C to +20 °C/+50 °F to +68 °F if possible
 chargers recommended by Leica Geosystems, it is not possible to charge the battery once the temperature is too high For new batteries or batteries that have been stored for a long time (> three months), it is effectual to make only one charge/discharge cycle For Li-Ion batteries, a single discharging and charging cycle is sufficient. We recommend carrying out the process when the battery capacity indicated on the charger or on a Leica Geosystems product deviates significantly from the actual battery capacity available.
 The batteries can be operated from -20 °C to +55 °C/-4 °F to +131 °F. Low operating temperatures reduce the capacity that can be drawn; high operating temperatures reduce the service life of the battery.

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Change the battery step-by-step	 Face the instrument so that the horizontal drive is at the right side, 			
	where also the battery compartment is located. Press both knobs on the side of the battery compartment to open it.			
	2. Pull out the battery housing.			
	3. Pull the battery out of the battery housing.			
	 4. At the top of the battery is a notch which corresponds to the inner surface of the battery housing. This notch helps you to place the battery correctly. Place the battery into the battery housing, ensuring that the contacts are facing outward. Click the battery into position. 			
	5. Place the battery housing into the battery compartment. Push the battery housing in until it fits completely into the battery compartment.			
	 6. Push the battery compartment back into the instrument. A sound appears when the compartment snaps in its final position. 			
4.3	Data Storage			
Description	An internal memory is included in the instrument. The basic field software stores all data in projects and jobs in a database in the internal memory.			
	Data can be transferred from the internal memory to a computer or other device via an USB stick inserted into the USB host port.			
[3]	Removing the USB stick during operation can cause loss of data. Only remove the USB stick when the TS instrument is switched off.			
4.4	Main Menu			
Main Menu	Press \textcircled{M} on the keyboard to enter the Main Menu .			
	Description of the Main Menu functions			
	Function Description			
	AppsTo select and start apps. Refer to 7 Apps.			

4.2.2

Function	Description
Survey	App to begin measuring. Refer to 4.5 Standard Measure- ments.
Manage	Contains all functions for entering, editing, checking and deleting data in the field. Refer to 9 Data Management.
Transfer	To export and import data. Refer to 10 Data Transfer.
Settings	To change EDM configurations and general instrument set- tings. Refer to 5 Settings.
Tools	 Contains tools to be used for the electronic adjustment of the instrument. Using these tools helps to maintain the measuring accuracy of the instrument. Displays instrument, system and firmware information, as well as settings for the date and time. To load all instrument related firmware as well as licences. Refer to 11 Tools.

4.5	Standard Measurements Overview			
4.5.1				
Access	Select Survey	Select Survey in the Main Menu .		
Standard measure- ment screen	PPM:0	♀ ♀ ♀ ∎ □		
	V : Hz:	12. 65% screen is displayed. 0. 2506 °		
	Hd : Vd : Meas D	 Dist Mode P1↓		

Standard measurement softkeys

Depending on the selected measuring mode and the **Survey** app used, different softkeys are displayed on the standard measurement screen.

The softkeys available in the app **Survey** vary slightly.

Measuring Mode	Softkey	Description
Angle Measurement	Hz=0	Set horizontal angle to 0.
	Lock	Lock the horizontal angle.
	HZ=?	Enter and set a horizontal angle.
	Comp	Enter compensator settings.
	Rmea	Enter angle repeat measurement.
	V %	Toggle between vertical angle unit % and gon/grad/mil depending on the unit settings.
	R/L	Toggle between horizontal angle left and horizontal angle right.

	Measuring Mode	Softkey	Description			
		VA/ZA	Set vertical angle to Horizon = 0°. Set vertical angle to Zenith = 0°.			
	Distance Measurement	Meas	To execute a distance measure- ment and store the displayed val- ues.			
		Dist	To execute a distance measure- ment.			
		Store	To save the displayed values without executing a distance measurment.			
		EDM	Enter EDM settings.			
		OffSet	Enter offset function.			
		SetOut	Enter Set Out app.			
	Coordinate Measurement	Meas	To execute a distance measure- ment and store the displayed val- ues.			
		Dist	To execute a distance measure- ment.			
		Store	To save the displayed values without executing a distance measurment.			
		EDM	Enter EDM settings.			
		hr	Enter target height.			
		hi	Enter station height.			
		STN	Enter station coordinates.			
		Backsight	Enter the back-sight orientation program			
		OffSet	Enter offset function.			
4.5.2	Angle Measurement					
Access	1. Power on to enter	r the standard	survey interface.			
	2. Press 🖉 button of	n the keyboar	d.			
Measure horizontal	1. Align to the first target A.					
and vertical angles between two points	2. Press Hz=0 to set	t the horizonta	al angle to 0°0'0'' .			
betheen the points	3. Press YES .					
	4. Align to the second target B to read the horizontal and vertical angles between B and A.					
Set an angle	By locking the angle					
	1. Rotate the angle l					
	2. Press Lock to fix the horinzontal angle.					
	3. Align to the targe	t.				

4.	Press	YES	to	set	the	horizontal	angle.
----	-------	-----	----	-----	-----	------------	--------

Screen will return to normal measurement mode.

By keyboard input

By keyboard input				
	1. Align to the target.			
	2. Press HZ=? .			
	3. Type in the value for the angle, for example 90.			
	4. Press OK .			
Repeat an angle	1. Press Rmea .			
measurement	2. Press YES .			
	3. Align to the target A.			
	4. Press Hz=0 and YES.			
	5. Align to the target B.			
	6. Press Lock to complete the first observation.			
	7. Align to the target A.			
	8. Press Releas .			
	9. Align to the target B.			
	10. Press Lock to complete the second observation.			
	11. Repeat steps 7. + 8. and 9. + 10. as needed.			
	 Ht:: The cumultative angle The horizontal angle can increase up to 3600°00'00' (3599°59'55" ±5"). Hm:: The average angle 			
	If the difference between the angle and Hm: is bigger than 10", an error message is displayed.			
	12. Press () to quit the remeasuring and to return to the standard measuring mode.			
4.5.3	Distance Measurement			
Access	1. Power on to enter the standard survey interface.			
	2. Press 🙆 button on the keyboard.			
	 Press button on the keyboard again to switch between display views. 			
	 V :: The vertical angle Hz:: The horizontal angle Hd :: The horizontal distance Vd :: The height difference Sd :: The slope distance 			
Measure distance	1. Align to the target.			
	2. Press Meas.			

	3.	To check the slope distance, press letton on the keyboard to switch between display views.
	ß	Press Mode to switch between measuring modes: Standard, Quick, Track, Repeat, Average. The EDM Mode:EDM Mode: remains unchanged. Press () to return to the standard surveing screen.
		Press EDM to change between prism and non-prism mode.
	B	Press m/ft to change between the units meter and feet.
	B	Press OffSet to enter the offset function.
	1. B	Press SetOut to enter the Set Out app.
		Refer to 5 Settings for more information on settings.
4.5.4	Coord	inate Measurement
Access	1.	Power on to enter the standard survey interface.
	2.	Press 😢 button on the keyboard.
Measure coordinates	1.	Align to the target.
	2.	Press Meas . The coordinates are displayed.
		Press Mode to switch between measuring modes: Standard, Quick, Track, Repeat, Average. The EDM Mode:EDM Mode: remains unchanged. Press () to return to the standard surveing screen.
	- B	Press EDM to change between prism and non-prism mode.
	3.	Press P↓ : hr : The height of the prism hi : The height of the instrument STN : The coordinates of the station
	4.	Press P↓ : OffSet to enter offset function. BS to enter the back-sight orientation program. m/ft to toggle between distance unit meter and feet.
4.6	Dista	nce Measurements - Guidelines for Correct Results
Description	by usin objectiv	A is incorporated into the instrument. The distance can be determined g a visible red laser beam which emerges coaxially from the telescope ve. There are two EDM modes: sm measurements
		flectorless measurements

Non-prism

Non-prism measurements	 When a distance measurement is triggered, the EDM measures to the object which is in the beam path at that moment. If a temporary obstruction, for example a passing vehicle, heavy rain, fog or snow is between the instrument and the point to be measured, the EDM may measure to the obstruction. Be sure that the laser beam is not reflected by anything close to the line of sight, for example highly reflective objects. Avoid interrupting the measuring beam while taking Non-Prism measurements or measurements using reflective foils. Do not measure with two instruments to the same target simultaneously.
Prism measurements	 Accurate measurements to prisms should be made in Standard mode. Measurements to strongly reflecting targets such as traffic lights in Prism mode without a prism should be avoided. The measured distances may be wrong or inaccurate. When a distance measurement is triggered, the EDM measures to the object which is in the beam path at that moment. If for example people, cars, animals, or swaying branches cross the laser beam while a measurement is being taken, a fraction of the laser beam is reflected from these objects and may lead to incorrect distance values. In practice, because the measuring time is very short, the user can always find a way of avoiding unwanted objects from interfering in the beam path.

5	Settings				
5.1	Unit Settings				
Access	1. Select Setting from the Main Menu .				
	2. From th	ne Setting men	u, select Unit Setting .		
	3. Press P I to scroll through the screens of available settings.				
Unit Setting	Key Description				
	OK To confirm the entered values and to continue the prod				
	P I To scroll through the screen of available settings.				
	Description of	fields			
	Field	Option	Description		
	AngleUnit:		Sets the units shown for all angular fields. The setting of the angle units can be changed at any time. The current displayed values are converted according to the selec- ted unit.		
		0	Degree decimal. Possible angle values: 0° to 359.999°		
		011	Degree sexagesimal. Possible angle values: 0° to 359°59'59''		
		gon	Gon. Possible angle values: 0 gon to 399.999 gon		
		mil	Mil. Possible angle values: 0 to 6399.99mil.		
	MinRead	5	Sets the number of decimal places shown for all angular fields. This is for data display and does not apply to data export or stor- age.		
		0.0001 0.0005 0.001	Available for AngleUnit:: °.		
		1" 5" 10"	Available for AngleUnit:: ° ' ".		
		0.1mgon 0.5mgon 1 mgon	Available for AngleUnit:: gon .		
		0.01 0.05 0.1	Available for AngleUnit:: mil .		
	Temperature:		Sets the units shown for all temperature fields.		
		°C	Degree Celsius.		
		°F	Degree Fahrenheit.		

	Field	Option	Description
		Option	DescriptionSets the units shown for all pressure fields.
	Pressure:	hPa	Hecto Pascal.
		mbar	Millibar.
			Millimeter mercury.
		mmHg inHg	Inch mercury.
	DistanceUnit:		Sets the units shown for all distance and
	Distanceonit:		coordinate related fields.
		m	Metres [m].
		US-ft	US feet [ft].
		INT-ft	International feet [fi].
		ft-in1/16	US feet-inch-1/16 inch [ft].
	DistanceDec:		Sets the number of decimal places shown for all distance fields. This is for data display and does not apply to data export or stor- age.
		3	Displays distance with three decimals.
		4	Displays distance with four decimals.
Meas. Parameters	Кеу	Description	
		•	
	ОК		he entered values and to continue the process.
	OK Description of	To confirm t	
		To confirm t	
	Description of	To confirm t	he entered values and to continue the process.
	Description of Field Com-	To confirm t fields Option	the entered values and to continue the process. Description
	Description of Field Com-	To confirm t fields Option ON	he entered values and to continue the process. Description To turn the compensator on.

Right	Set horizontal	angle to clockwise direction
	Set horizontal angle to clockwise direction measurement.	
Left	direction meas	angle to counter-clockwise surement. Counter-clockwise displayed but are saved as ctions.
	Sets the vertion	al angle.
Zenith	270° 45° 180°	Zenith=0°; Horizon=90°.
HZO	180° +45° 180° +45° 90°	Zenith=90°; Horizon=0°. Vertical angles are positive above the horizon and neg- ative below it.
Slope %	Slope % +1005 +10	45°=100%; Horizon=0°. Vertical angles are expresse in % with positive above the horizon and negative below it. The % value increases rapidly. % appears on the display above
	Zenith HZO	direction measure directions are clockwise directions Sets the vertice 20° 180° HZO Slope % Slope %

5.3	Display Set	ay Settings			
Access	1. Select	Select Setting from the Main Menu .			
	2. From	From the Setting menu, select Display Setting.			
Display Setting	Кеу	Description	1		
	ОК	To confirm t	he entered values and to continue the process.		
	Description o	iption of fields			
	Field Option		Description		
	Meas. Mode:		Sets which screen is accessed after the instrument is turned on.		
		AGMeas	Startup with angle measuring screen.		
		DTMeas	Startup with distance measuring screen.		
HD&VD/		HD&VD	Horizontal distance to the point. Vertical angle to the point.		
		SD	Slope distance to the point.		

	Field	Option	Description
	COForm:		The order in which grid coordinates are shown in screens.
		NEZ	North is shown first, East second.
		ENZ	East is shown first, North second.
-		_	
5.4	Other Sett	ings	
Access	1. Selec	t Setting from th	ne Main Menu .
-	2. From	the Setting mer	nu, select Other Setting .
Other Setting	Кеу	Description	
	ОК	To confirm the	e entered values and to continue the process.
	₽ŧ	To scroll throu	igh the screen of available settings.
	Description o	of fields	
	Field	Option	Description
	Contrast:	0% to 100%	Sets the display contrast in 10% steps.
	Illumina- tion:	ON or OFF	Sets the screen illumination on or off.
	Reticule:	0% to 100%	Sets the reticle illumination in 10% steps.
	Beep:	ON or OFF	The beep is an acoustic signal after each key stroke.
	Sector Beep:	ON	Sector beep sounds at right angles (0°, 90°, 180°, 270° or 0, 100, 200, 300 gon).
			2 1 1 1 1 1 1 1 1 1 1 1 1 1
			 No beep Fast beep; from 95.0 to 99.5 gon and 105.0 to 100.5 gon. Permanent beep; from 99.5 to 99.995 gon and from 100.5 to 100.005 gon.
		OFF	Sector Beep is deactivated.
5.5	Shortcut K	eys Settings	

Access

Configures the (0) and (0) keys with a function.

When a function is assigned to one of the keys, the function can be started by just one button press.

1. Select **Setting** from the **Main Menu**.

- 2. From the **Setting** menu, select **Shortcut Keys Setting**.
- 3. Select **K1 Setting** or **K2 Setting**.
- 4. Select a function from the list.

EDM Settings

Access

5.6

The settings on this screen define the active EDM, Electronic Distance Measurement. Different settings for measurements are available with reflectorless and prism EDM modes.

- 1. Select **Setting** from the **Main Menu**.
- 2. From the **Setting** menu, select **EDM Setting**.

EDM Settings

Select the options to be changed by the up and down navigation keys, then change by the left and right keys. Enter the corresponding settings through the softkeys. Page down through $\mathbf{P} \mathbf{I}$.

Кеу	Description	
Atmos	To enter atmospheric data ppm.	
PPM	To enter an individual ppm value.	
ОК	To confirm the entered values and to continue the process.	
Scale	To enter projection scale details. Coordinate will be correc- ted by PPM parameters.	
Signal	To view EDM Signal reflection value.	
Reset	To reset all editable fields to their default values.	

Field	Description	Description	
EDM Mode:	Prism	For distance measure	ments using prisms.
	Foil	For distance measured reflective targets.	ments using Retro
	NonPrism	For distance measure	ments without prisms.
Prism Type:	- Carl	The Leica prism const	ant is shown.
	Round		Leica prism constant: 0 mm
	MINI		Leica prism constant: 17.5 mm
	360°	86 64 88 78 78 78	Leica prism constant: 23.1 mm

Field	Description	Description	
	360°MINI		Leica prism cons 30.0 mm
	Foil	\bigcirc	Leica prism cons 34.4 mm
	Custom	The user can define th Constants can be enter Const: . Leica constant = Abso 34.4 mm	red in mm in Leic a
Meas. Mode:	Standard	For distance measurer	nents with prisms.
	Quick	Quick measuring mode higher measuring spee	
	Track	For continuous distant prisms.	e measurements v
	Average	Repeats three measuring mode. The the standard deviation tance are calculated.	average distance a
	Repeat	Repetitive measureme accuracy.	nts with standard
Leica Const:	Editable field	This field displays the selected Prism Type: Where Prism Type: is becomes editable to s stant. Input can only be mad Limit value: -999.9 mm	Custom this field et a user defined c e in mm.
Laser:	OFF	Visible laser beam is d	eactivated.
	ON	Visible laser beam for point is activated.	visualising the targ

EDM Setting - Atmos

This screen enables the entry of atmospheric parameters. Distance measurement is influenced directly by the atmospheric conditions of the air in which the measurements are taken. In order to take these influences into consideration distance measurements are corrected using atmospheric correction parameters.

The refraction correction is taken into account in the calculation of the height differences and the horizontal distance. Refer to 13.6 Scale Correction for the application of the values entered in this screen.

When **PPMO** is selected, the Leica standard atmosphere of 1013mbar and 12°C is applied.

	Description	of fields	
	Field	Option	Description
	Temp:	Editable field	The temperature value can be entered manually.
	Pressure:	Editable field	The atmospheric value can be entered manually. The value for Elev: changes accordingly.
	Elev:	Editable field	The elevation value can be entered manually. The value for Pressure: changes accordingly.
	Ref:	Editable field	The refraction value can be entered manu- ally.
EDM Setting - Input PPM	distance mea	surements are co	of individual scaling factors. Coordinates and rrected with the PPM parameter. Refer to 13.6 ation of the values entered in this screen.
EDM Setting - Projec- tion Scale	This screen enables entry of the scale of projection. Coordinates are corrected with the PPM parameter. Refer to 13.6 Scale Correction for the application of the values entered in this screen.		
EDM Setting - Signal	Enables optim	nal aiming at dista und, indicate the r	al strength (reflection strength) in steps of 1%. ant, barely visible, targets. A percentage bar and reflection strength. The faster the beep the
5.7	Date/Time	Settings	
Access	1. Sele	ct Setting from tl	he Main Menu .
	2. From	n the Setting mer	nu, select Time and Date Setting .
Time and Date Set- tings	Set the current the next digit		of the instrument. Use the $igodot$ key to switch to
5.8	Key Funct	ion Settings	
Access	With the key soft keys can		the assignment of the function to the single
	The customisment and res		its can be saved in the memory of the instru-
	Configure:		
	The assig screen	nment of function	nality to the softkeys in the standard survey
	• The assig		nfiguration to a user ser assignment or of factory default assign-
		ct Setting from t	he Main Menu .
	2. From	n the Setting mer	nu, select Key Function.
	3. Sele	ct:	

	Key distribution	To assign the functionality to the softkeys
	Key function consignment	To save the customsed key assignments in the memory of the instrument. If the general key assignment is changed, the saved key assignment can be restored.
	Key function recovery	To recover a saved user assign- ment or the factory default assignments
Key Function - Key distribution	In the setting panel:	
	a b c [P1P2] Meas ∎ Meas OffSet Mode Mode SetOut EDM ↑ EDM m/ft ↓ hr OK	 a P1 P2 or P1 P2 P3 on the left represent the two or three pages in a screen. b The softkeys on a page, in the order, with the currently assigned functionality c The functions listed on the right can be selected and assigned to the softkeys.
	In the standard surveying panel:	
	V : 12.65% Hz: 0.2506° Hd : Vd : Vd : b c a	a The two or three pages in a screen.b The softkey on a pagec The assigned functionality
	Assign key functions step-by-step 1. In the columns on the lef	
	t, select the softkey to which you hality. hwards in the list and also to the ards in the list. bove, the left cursor is located in . on the position of F1 [Meas]. L softkey function on page 1 can	
	be set.	
	want to assign to a softk	nt, select the functionality which you ey. y to move upwards in the list.
	3. Press the \ominus key to assig	n the functionality.

	4.	Press OK to complete the settings.		
Key Function - Key function consign-	1.	Select Key function consignment from the Key function menu.		
ment	2.	Select Custom 1 or Custom 2 . The current assignment of functionality to the softkeys is saved to the selection.		
	3.	Press YES or \bigcirc to complete.		
Key Function -	1.	Select Key function recovery from the Key function menu.		
Key function recovery	2. Select the saved assigments to recover or Factory Default.			
	3.	Press YES or \bigcirc to complete.		
- 5.9	WiFi Setti	ngs		
517				
Access	1.	Select Setting from the Main Menu.		
	1.	Select Setting from the Main Menu.		
Access	1. 2.	Select Setting from the Main Menu . From the Setting menu, select Wifi Setting .		
Access	1. 2. Key	Select Setting from the Main Menu. From the Setting menu, select Wifi Setting. Description		
Access	1. 2. Key OK	Select Setting from the Main Menu. From the Setting menu, select Wifi Setting. Description To confirm the entered values and to continue the process. Available for WIFI: Enable.		
Access	1. 2. Key OK Select	Select Setting from the Main Menu. From the Setting menu, select Wifi Setting. Description To confirm the entered values and to continue the process. Available for WIFI: Enable. To search and select a Wifi network. Available for WIFI: Enable. to enter the hotspot and password for a known access point to connect to.		
Access	1. 2. Key OK Select Hotspot:	Select Setting from the Main Menu. From the Setting menu, select Wifi Setting. Description To confirm the entered values and to continue the process. Available for WIFI: Enable. To search and select a Wifi network. Available for WIFI: Enable. to enter the hotspot and password for a known access point to connect to.		
Access	1. 2. Key OK Select Hotspot: Description	Select Setting from the Main Menu. From the Setting menu, select Wifi Setting. Description To confirm the entered values and to continue the process. Available for WIFI: Enable. To search and select a Wifi network. Available for WIFI: Enable. to enter the hotspot and password for a known access point to connect to. of fields		

6	Apps - Getting Started				
6.1	Overview				
Description	Apps are predefined programs, that cover a wide spectrum of surveying duties and facilitate daily work in the field. The following apps are available: Survey Set Out OffSet Miss.Line Measure(MLM) Remote Elevation Area Resection Reference Line Road 				
6.2	Starting an App				
Access	1. Select Apps from the Main Menu .				
	2. Press the 🕑 or 🐵 button to scroll through the screen of available apps.				
	3. Press ⊖ or press the number of the app to select the specified app in the Main Menu .				
Pre-settings screens	Description of items in the list				
	The availability of items depends on the app.				
	Item Description				
	Go Starts the selected app.				
	Select Sta- tionTo define the current position of the instrument station. Refer to 6.3 Station Setup.				
•	Select Ori- entationTo define the orientation and horizontal direction of the instrument station. Refer to 6.3 Station Setup.				
	Select JobTo define the job where data will be saved. Refer to 6.5 Setting the Job.				
	Next step				
	Select an item from the list. Press \ominus .				
	OR				
	On the keyboard, press the number of the item in the list.				
6.3	Station Setup				
Description	All measurements and coordinate computations are referenced to the set sta- tion coordinates. The coordinates can be entered manually or selected from the memory.				
	The station coordinates that are set must include:				
	 at least grid coordinates (E, N), and the station height, if required. 				
	······-·				

Z		X Y Z	Directions Easting Northing Height
	STn.X	Stn.X	Station coordinates Easting coordinate of sta-
03	A17.001	Stn.Y	tion Northing coordinate of sta- tion

Station input	Кеу	Description			
	Value	To search for	a point.		
	Coord To open the manual coordinate entry screen.				
	ОК	OK To confirm the entered values and continue in the process.			
	Description of fields				
	Field	Option	Description		
	E :, N :, Z :	Display only	The coordinates of the station.		
	PointID:	Display only	Station name of a previously saved station position.		
	hi:	Editable field	Instrument height The calculation of coordinates is based on plane coordinates (X and Y). Enter the instrument height if necessary.		
6.4	the current station.		p was started, then the last station is set as rent horizontal direction is set as the orienta-		
6.4.1	Overview		···		
Description	All measurements and coordinate computations are referenced to the orienta- tion of the set station. The orientation can be entered manually or determined from points that are either measured or selected from the memory.				
Access	 Select Select Orientationin the Pre-settings screen and choose: Angle Orientation to enter a new bearing. Refer to 6.4.2 Orientation with Angle. Coordinates Orientation to calculate and set the orientation using existing coordinates. Refer to 6.4.3 Orientation with Coordinates. 				
			p was started, then the last station is set as rent horizontal direction is set as the orienta-		

6.4.2	Orientation with Angle			
Access	Select Angle	select Angle Orientation in the Backsight screen.		
Select Orientation	Кеу	Description		
	OK	To confirm the entered values and continue in the process		
	Description of fields			
	Field	Option	Description	
	PointID:	Editable field	Point ID of the backsight point.	
	Hz:	Editable field	The azimuth between survey point and back- sight point.	
6.4.3	Orientation	with Coordina	tes	
Access	Select Coordi	Select Coordinates Orientation in the Backsight screen.		
BS coordinate	Кеу	Description		
	Value	To search for	a point.	
	Coord	To open the m	nanual coordinate entry screen.	
	ОК	To confirm the entered values and continue in the process.		
	Description of fields			
	Field	Option	Description	
	E :, N :, Z :	Display only	The coordinates of the station. The coordinates must be based on plane coordinates (X and Y). Enter the instrument height if necessary.	
	PointID:	Editable field	Point ID of the backsight point.	
	hr	Editable field	Height of the reflector.	
			t in the pointsearch or enter ENZ coordinates ontinue to Backsight Check .	
Backsight Check	Кеу	Description		
	Meas		ice and angle measurements. Ind display azimuth and distance.	
	Coord	To display calc	ulated coordinates.	
	NO	To reject the c	prientation and to return to BS coordinate .	
	YES	To set the orie	entation.	
	Description of	of fields		
	Field	Option	Description	
	Hz:	Display only	Horizontal direction to the target point.	
	CAL. HD:	Display only	Horizontal distance to the target point.	

	Field	Option	Description	
	HD:	Display only	Horizontal distance to the survey point.	
	dHD:	Display only	Horizontal distance difference to the target point.	
			tation and return to the Pre-Settings screen. BS coordinate screen. No changes will be	
-	saved.			
3	If no orientation was set and an app was started, then the current horizontal direction is set as the orientation.			
6.5	Setting th	ne Job		
Description	All data is saved in Jobs, like file directories. Jobs contain measurement data o different types, for example measurements, codes, fixpoints or stations. Jobs are individually manageable and can be exported, edited or deleted separately		easurements, codes, fixpoints or stations. Jobs	
Select Job	Кеу	Description		
	Call	To display the	list of available jobs.	
	New	To create a ne	ew job.	
	ОК	To continue w	ith the selected job.	
	Description of fields			
	Field	Option	Description	
	Job:	Display only	Name of an existing job to be used.	
	User:	Display only	Name of operator, if entered.	
	Date:	Display only	Date the selected job was created.	
	Time:	Display only	Time the selected job was created.	
-				
Job list	Кеу	Description		
	Attrib	To display job and time of th	related information such as creator or date ne creation.	
	Delete	To delete the highlighted job.		
	Select To select the highlighted job as working job.			
Recorded data		s set up, all subseq d job is the active j	juent recorded data will be stored in this job. job.	
_	•	s defined and an ap w default job.	pp was started, then the system automatically	
-				

7	Аррѕ			
7.1	Common Fields			
Description of fields	The following table describes common fields that are found within the firm- ware apps. These fields are described here once and not repeated in the app chapters unless the field has a specific meaning within that app.			
	Field	Description		
	PointID:	Point ID of the point.		
	hr	Height of the reflector.		
	Hz:	Horizontal direction to the point.		
	V :	Vertical angle to the point.		
	Hd :	Horizontal distance to the point.		
	Sd :	Slope distance to the point.		
	Height	Height to the point.		
	Ε:	Easting coordinate of the point.		
	N :	Northing coordinate of the point.		
	Z :	Height coordinate of the point.		
Description		app used for the measurement of an unlimited number of points re-settings for the job, station and orientation prior to beginning		
Access	1. Select Survey from the Main Menu .			
	2. Con	nplete the pre-settings. Refer to 6.2 Starting an App.		
Survey	Кеу	Description		
	Meas	To execute a distance measurement and store the displayed values.		
	Store	To save the displayed values without executing a distance measurment.		
	Dist	To execute a distance measurement.		
	Pŧ	To switch between individual and running point numbers.		
	Code	To add a code to the measured point.		
	OffSet	To apply an offset to the measurement.		
7.3	Set Out			
Description	These prede	n app used to place marks in the field at predetermined points. termined points are the points to be staked. The points to be already exist in a job on the instrument, or be manually entered.		

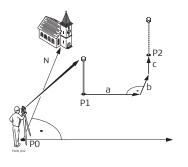
The app can continuously display differences, between current position and desired set out position.

Set out modes

Points can be staked using different modes:

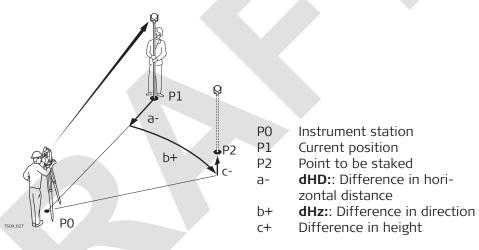
- Cartesian mode: Using coordinates
- Polar mode: Using angle and distance

Cartesian set out mode



Polar set out mode

- P0 Instrument station
- P1 Current position
- P2 Point to be staked
- a **dE::** Difference in Easting coordinate
- b **dN::** Difference in Northing coordinate
 - dZ:: Difference in height



С

Access		1.	Select Apps from the Main Menu.
		2.	Select Set Out.
		3.	Complete app pre-settings. Refer to 6 Apps - Getting Started.
		4.	Select Coordinates Set Out or Angle, Distance Set Out.
	—		
Input		Kay	Description
		Key	Description
		Store	To save the displayed values without executing a distance measurment.
			To save the displayed values without executing a distance

Mode	Field	Description
Cartesian	E :, N :, Z :	Easting, Northing and Height coordinate of the set out point.

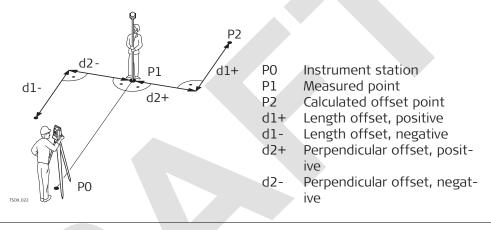
	Mode	Field	Description			
		hr	Height of the reflector.			
	Polar	Dist:	Distance to the set out point.			
		Hz:	Horizontal angle to the set out point.			
		hr	Height of the reflector.			
Next step			ing point with the pointsearch or enter ENZ t. Press OK to continue the set out.			
Compute	Кеу	Description				
	Store	To save the displayed values without executing a distance measurment.				
	Shift	To enter the polar set out screen. To enter the set out screen for coordinates.				
	<>	To switch to the navigation screen or to use horizonal and vertical angle for guidance.				
	HD	To measure a distance.				
	Coord	Coord To measure the coordinates.				
	Description	Description of fields				
	Mode	Field	Description			
	Cartesian	dE:	Easting offset: Positive if set out point is to the right of the measured point.			
		dN:	Northing offset: Positive if set out point is further away than the measured point.			
		dZ:	Height offset: Positive if set out point is higher than the measured point.			
		Hz:	Computed horizontal angle.			
		dHz:	Angle offset: Positive if set out point is to the right of the measured point.			
	Polar	Dist:	Distance to the set out point.			
		Hz:	Horizontal angle to the set out point.			
		hr	Height of the reflector.			
Next step	next set	 Either, press Store to store the set out point and to continue with the next set out point. Or, press () to exit the application. 				
7.4	Target Of	Target Offset				
7.4.1	Overview					
Access	1. Sele	ect Apps from	the Main Menu .			
	2. Sele	ect OffSet .				
		3. Complete app pre-settings. Refer to 6 Apps - Getting Started.				

- 4. Select:
 - Single Distance Offset.
 - Refer to 7.4.2 Distance Offset.
 - Angle Offset. Refer to 7.4.3 Angle Offset.
 - Double Distance Offset.
 - Refer to 7.4.4 Double Distance Offset. **Cylinder Offset**.
 - Refer to 7.4.5 Cylindrical Offset.

7.4.2 Distance Offset

Description

This app calculates the target point coordinates if it is not possible to set up the reflector, or to aim at the target point directly. The offset values (length, traversal and/or height offset) can be entered. The values for the angles and distances are calculated to determine the target point.



Access

Select **Single Distance Offset** from the **OffSet** menu.

Enter offset values	Кеу	Description	
	ок	To confirm the point.	e measurement and to calculate the offset
	Meas		ne distance. angle and distances are displayed as soon as te measurement has been triggered or exists.
	P↓	To scroll down	n and display further fields on the screen.
	Description o	of fields	
	Field	Option	Description
	Hd :	Display only	Horizontal distance to the measured point.
	Hz:	Display only	Horizontal angle to the measured point.
	PointID:	Editable field	The name of the calculated offset point.
	OffSet	Editable field	The offset values are always reset
			to 0 when the app is quit.

	Field	Option	Description
		Left	Perpendicular offset to the left of the meas- ured point.
			The angle between the line con- necting target point and calculated offset point and the line connect- ing instrument station and target point must be 90°.
		Right	Perpendicular offset to the right of the measured point.
			The angle between the line con- necting target point and calculated offset point and the line connect- ing instrument station and target point must be 90°.
		Up	Longitudinal offset. Closer than the meas- ured point.
			The surveying point must be on the line between instrument sta- tion and measured point
		Down	Longitudinal offset. Further away than the measured point.
			The surveying point must be on the line between instrument sta- tion and measured point
	hr	Editable field	Height of the reflector.
7.4.3	Angle Offset		
Description	up the reflector	r, or to aim at th	get point coordinates if it is not possible to set ne target point directly. The offset point and the the same distance to the instrument.
Access	Select Angle O	ffset from the	OffSet menu.
Enter offset values and result			nt to the left or right of the offset point. The trument station must be the same.
	Кеу	Description	
	Meas	To execute a values.	distance measurement and store the displayed
	Dist	To execute a	distance measurement.
Ť	Store	To save the di measurment.	isplayed values without executing a distance
	Shift		ting, Northing and Height or slope distance, and horizontal angle.

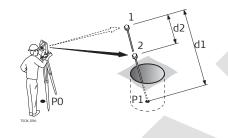
Description of fields			
Field	Option	Description	
PointID:	Editable field	The name of the target point.	
hr	Editable field	Height of the reflector.	
Sd :	Display only	Slope distance to the measured point or cal- culated offset point.	
V :	Display only	Vertical angle to the measured point or cal- culated offset point.	
Hz:	Display only	Horizontal angle to the measured point or calculated offset point.	

Double Distance Offset

7.4.4

Description

This app is used for measurements to a point that is not directly visible, using a special hidden point rod.



- PO Instrument station
- P1 Hidden point
- 1-2 Prisms 1 and 2
- d1 Distance between prism 1 and the hidden point
- d2 Distance between prism 1 and 2

Access

and result

Enter offset values

Select **Double Distance Offset** from the **OffSet** menu.

Кеу	Description
Meas	To measure the distance.
Store	To save the displayed values without executing a distance measurment.
Shift	To display Easting, Northing and Height or slope distance, vertical angle and horizontal angle.

Desemption o		
Field	Option	Description
PointID:	Editable field	The name of the target point.
hr	Editable field	The length of the special hidden point rod.
Sd :	Display only	Slope distance to the measured point or cal- culated offset point.
V :	Display only	Vertical angle to the measured point or cal- culated offset point.
Hz:	Display only	Horizontal angle to the measured point or calculated offset point.
B-C:	Editable field	Spacing between the centres of the prisms 1 and 2.

Next step

Measure to the first and second prisms using **Meas**, enter the distance between the two prisms and the result screen **Double DT Offset** screen is displayed.

7.4.5	Cylindrical	Cylindrical Offset		
Description	radius. The h	orizontal angle to	the centre point of cylindrical objects and their points on both the left and right sides of the listance to the object as well.	
		Hz1 Hz2	P1	
	P1 Ce Hz1 Ho Hz2 Ho d Di R Ra	prizontal angle to	a point on the left side of the object a point on the right side of the object ect in the middle between Hz1 and Hz2	
Access	Select Cylind	er Offset from th	ne OffSet menu.	
Enter offset values	Кеу	Description		
and result	Meas	To execute a c values.	distance measurement and store the displayed	
	ОК	To accept the	measurement.	
	Store	To save the displayed values without executing a distance measurment.		
	END	To exit the app without storing the results.		
	Description of fields			
	Field	Option	Description	
	PointID:	Editable field	The name of the target point.	
	hr	Editable field	The height of the reflector	
	Sd :	Display only	Slope distance to the measured point or cal- culated offset point.	
	V :	Display only	Vertical angle to the measured point or cal- culated offset point.	

	Field	Option	Description		
	Hz:	Display only	Horizontal angle to the measured point or calculated offset point. Measured horizontal direction to the right side of the object. Measured horizontal direction to the left side of the object.		
	Ε:	Display only	Easting coordinate of the centre point.		
	N :	Display only	Northing coordinate of the centre point.		
	Z :	Display only	Height of the point measured with the reflector.		
			This is not the calculated height of the centre point.		
	Radius	Display only	Radius of the cylinder.		
Cylindrical offset measurements step- by-step	1.		e cylinder. to aim in the direction of the centre point of such that horizontal angle is zero.		
	2.	Press Meas for survey	<i>.</i>		
	3.	To repeat the measure Press OK to save the	ement, press Meas again. point.		
	4. Using the vertica lhair, aim at the left side of the object.				
	5.	Press OK for survey.			
	6.	Using the verticalhair,	aim at the right side of the object.		
	7.	Press OK for survey.			
	8.	Check the results.			
	9. Press Store to record the results. Press END to exit the app without storing the results.				
7.5	Missing Line Measurement				
Description	zontal di	stance, height differen	n app used to compute slope distance, hori- ice and azimuth of two target points which are i the memory, or entered using the keypad.		
- Radial method	P FOX.047	N α^{α}	 P0 Instrument station P1-P4 Target points d1 Distance from P1-P2 d2 Distance from P1-P3 d3 Distance from P1-P4 α1 Azimuth from P1-P4 α2 Azimuth from P1-P3 α3 Azimuth from P1-P2 		
Access	1.	Select Apps from the	Main Menu.		

2. Select Miss.Line Measure(MLM).

Missing line measure- ments	After completing the measurements required, the Missing Line result screen will appear.			
Tie distance measure-	Step-by-step			
ments step-by-step	1.	Align to point 1.		
	2.	Press Meas . The distance is displayed.		
	3.	Align to point 2.		
	4.	Press MLM.		
	5.	5. After completing the measurements required, the results screen will appear.		
	Кеу	Description		
	MLM	To calculate the missing line information.		
	NewS	To set point 2 as the starting point of a new line. A new point 2 must be measured.		
	SD	To change to another display view showing slope distance values.		
	Meas	To execute a distance measurement and store the displayed values.		

Description of fields

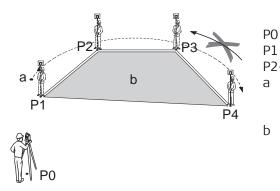
For Meas

Field	Option	Description
Hd :	Display only	Horizontal distance between point 1 and point 2.
V :	Display only	Vertical angle to the point.
Hz:	Display only	Azimuth between point 1 and point 2.
hr	Display only	Height of the reflector.

For MLM

Field	Option	Description
MLM-S	Display only	Slope distance between point 1 and point 2.
Н	Display only	Horizontal distance between point 1 and point 2.
V	Display only	Height difference between point 1 and point 2.
Hd :	Display only	Horizontal distance between point 1 and point 2.
Hz:	Display only	Azimuth between point 1 and point 2.
hr	Display only	Height of the reflector.

Next step	Press ESC to exit the app.			
7.6	Remote Elevation			
Description	Remote Elevation is an app used to compute points directly above the bas prism without a prism at the target point.			directly above the base
	500.050	P2 a d1 P1 P0	P1 Base po P2 Remote d1 Slope di a Height α P2 α Vertical	point
Access	1. Select	Apps from the	Main Menu.	
	2. Select	Remote Elevat	ion.	
Remote height measurement	Measure to the base point.			
	Next step			
	After measurin	g, the results scr	een appears.	
Results	Aim the instrur	nent at the inacc	essible remote point.	
	Description of	f fields		
	Field	Option	Description	
	Ht:	Display only	Calculated difference base point and the re	in height between the emote point.
	Hd :	Display only	Horizontal distance b and target point.	etween station point
	V :	Display only	Vertical angle to the culated offset point.	measured point or cal-
	Hz:	Display only	Horizontal angle to the	ne measured point.
Next step	coordinate	s of the remote	e measurement and re point. the base point again.	cord the calculated
7.7	Area			
Description	connected by s memory, or en	straights. The tar tered via the key	e online areas to a max get points have to be i pad in a clockwise dire ontal plane (2D).	measured, selected from



 P1 Start point
 P2-4 Target points
 a Perimeter, polygonal length from start point to the current measured point.

Instrument station

Calculated area always closed to the start point P1, projected onto the horizontal plane.

Access

1. Select **Apps** from the **Main Menu**.

2. Select Area.

Enter values and results

nd res-	Кеу	Description	
	Value	To select a point from the memory.	
	Meas	To execute a distance measurement and store the displayed values.	
	Coord	To enter point coordinates manually.	
	CAL	To display and record results.	
	Over	To exit the app.	
	P↓	To display the next softkey level.	
	1.	Measure or select existing points to define the area.	
	2.	The 2D can be calculated and displayed once three points have been measured or selected. Press CAL to calculate area and volume and proceed to the results screen.	
	 The result is displayed in square, hectar, acer and feet. View the area in square, hectar, acer and feet. 		
	4.	Press Over to exit the app.	

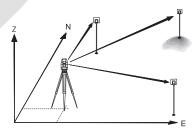
7.8

Resection

1.

Description

Resection is an application used to determine the instruments position from measurements to known points. A minimum of 2 known points and a maximum of 10, can be used to determine the position.



Access

Select Apps from the Main Menu.

2. Select **Resection**.

Enter values

Results

Кеу	Description
Value	To select a point from the memory.
Meas.	A To measure only the angle.
Meas	To execute a distance measurement and store the displayed values. To calculate and display the station coordinates, if at least two points and a distance were measured.
Coord	To enter point coordinates manually.
ОК	To accept the selection.
1.	Press Value to select a point from the memory. OR Press Coord to enter point coordinates manually.
2.	Press OK to accept the selection for the first point.
3.	Repeat 1. and 2. for the following points. At least three points are required.
4.	Before starting the measurements: Press OK to finish the selection and start measuring.
5.	Meas is available after the selection of the second point. Align to the target and press Meas . When distance is surveyed, the angle is surveyed as well.
6.	Press YES to accept the measurement. Press NO to repeat the measurement.
7.	Repeat the measuring steps for all selected points.
8.	Press CAL to calculate and display the station coordinates.
Кеу	Description
AddPT	To add more points and to return to the input screen.
STN	To set as the station point which is not saved.
Store	To save and set as the station point.
Pŧ	To display the next valuesl.

Field	Option	Description
PointID:	Display only	The name of the result point.
hi	Display only	Instrument height
Ε:	Display only	Easting coordinate of the centre point.
N :	Display only	Northing coordinate of the centre point.
Z :	Display only	Height of the point measured with the reflector.
dE:	Display only	Computed residual for the Easting coordin- ate.

Field	Option	Description
dN:	Display only	Computed residual for the Northing coordin- ate.
dZ:	Display only	Computed residual for the Height coordin- ate.

7.9	Reference Line		
7.9.1	Overview		
Description	The Reference Line app can be used to stake out or measure points relative to a line defined by two points.		
	 Reference Line is an application that facilitates the easy stake out or checkin of lines, for example, for buildings, sections of road, or simple excavations. It allows to define a reference line and then complete the following tasks regarding that line: Line & offset Set out points 		
Access	1. Select Apps from the Main Menu .		
	2. Select Reference Line .		
	3. Complete app pre-settings. Refer to 6 Apps - Getting Started.		
Next step	Define the base line for the reference line.		
7.9.2	Defining the Reference Line		
Access	Select Define Reference Line from the Reference Line menu.		
Description	A reference line can be defined by referencing a known base line. The refer- ence line can be offset either longitudinally, in parallel or vertically to the base line, or be rotated around the first base point as required. Furthermore the reference height can be selected as the first point, second point or interpol- ated along the reference line.		
Define the base line	The base line is fixed by two base points. All points can be either measured, manually entered, or selected from the memory.		
	P2 P2 P2 P2 P2 P2 P2 P2 P2 P2		

 α Azimuth

Define the base line by measuring or selecting the start and end points of the line.

Define Ref.(Start Pt) Define Ref.(End Pt)

Determine the reference line by two basis points. All points can be observed, manually entered, or selected from memory.

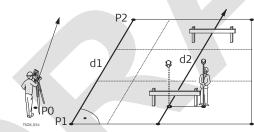
Кеу	Description
Value	To select a point from the memory.
Coord	To enter point coordinates manually.
Meas	To execute a distance measurement and store the displayed values.
Store	To save the displayed values without executing a distance measurment.

Description of fields

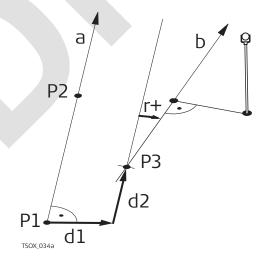
Field	Option	Description
PointID:	Editable field	The name of the result point.
hr	Editable field	Height of the reflector.
Hz:	Display only	Horizontal direction to the point.
Sd :	Display only	Slope distance to the point.

Description

The base line can be offset from, either longitudinally, in parallel or vertically, or be rotated around the first base point. This new line created from the offsets is called the reference line. All measured data refers to the reference line.



- PO Instrument station
- P1 Start point
- P2 End point
- d1 Base line
- d2 Reference line



- P1 Base point
- P2 Base point
- a Base line
- d1 Parallel offset
- d2 Longitudinal offset
- P3 Reference point
- r+ Rotation parameter
- b Reference line

Define Refline(1) Define Refline(2)

Define offset values.			
Кеу	Description		
ОК	To confirm the measured or entered values and continue the process.		
P₽	To display the next softkey level and fields.		

Description of fields

Field	Option	Description
Hz:	Display only	Azimuth of a reference line connecting the start point and the end point.
HD:	Display only	Horizontal distance between the start point and the end point.
VD:	Display only	Vertical distance between the start point and the end point.
Slope:	Display only	Difference in height between the start point and the end point.
L-Offset:	Editable Field	Longitudinal offset of the start point, reference point (P3), of the reference line in the direction of base point 2. Positive values are towards base point 2.
T-Offset:	Editable Field	Parallel offset of the reference line relative to the base line (P1-P2). Positive values are to the right of the base line.
H-Offset:	Editable Field	Height offset of the reference line to the selected reference height. Positive values are higher than the selected reference height.
Rotate:	Editable Field	Rotation of the reference line clockwise around the reference point (P3).

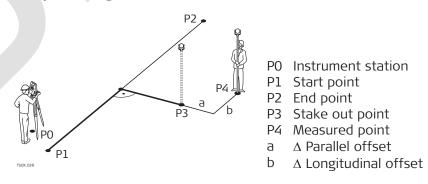
7.9.3

Description

Stakeout

Calculates the difference between a measured point and the calculated point. The orthogonal differences are displayed.

Example orthogonal stakeout



Access

Select Reference Line Setout from the Reference Line menu.

Refline Setout

Enter the stake out elements for the target points to be staked out relative to the reference line.

Decription of fields

Field	Option	Description
T-Offset:	Display only	Perpendicular offset: Positive if stake out point is to the right of the reference line.
L-Offset:	Display only	Longitudinal offset: Positive if stake out point is further away from the reference line.
H-Offset:	Display only	Height offset: Positive if stake out point is higher than the reference line.

Next step

Press **OK** to calculate the coordinates of the stake out point.

The coordinates for the stake out point are displayed.

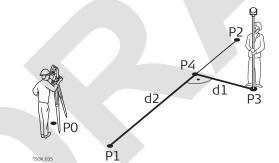
Кеу	Description
SetOut	To start the Set Out app. Refer to 7.3 Set Out.
Store	To save the displayed values without executing a distance measurment.

7.9.4

Measuring to a Reference Line

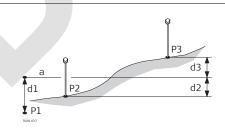
Description

Calculates from measurements or coordinates, longitudinal offsets, parallel offsets and height differences of the target point relative to the reference line.



- PO Instrument station
- P1 Start point
- P2 End point
- P3 Measured point
- P4 Reference point
- d1 Δ Offset
- d2 Δ Line

Example of height difference relative to first reference point

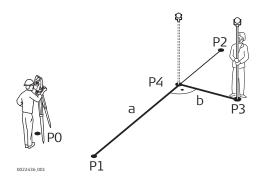


	 P1 Start point P2 Target point P3 Target point a Reference height d1 Height difference between start point and the reference height d2 Height difference between P2 and the reference height d3 Height difference between P3 and the reference height 		
Access	1. Align	to the target point.	
		Refline Measurement from the Reference Line menu.	
	3. A mea	asurement is taken.	
	4. The co	orrdinates and the offset values are displayed.	
 Refline Measurement	Кеу	Description	
	Meas	To execute a distance measurement and store the displayed values.	
	Store	To save the displayed values without executing a distance measurment.	
	P↓	To display the next fields.	
	Description o	f fields	
	Field	Description	
	T-Offset:	Calculated distance perpendicular from the reference line.	
	L-Offset:	Calculated distance longitudinal to the reference line.	
	H-Offset:	Calculated height difference relative to the defined reference height.	
7.9.5	Projections		
Description	Projects a point perpendicular onto a reference line. The initial coordinates of the point can be either measured, manually entered, or selected from the memory.		

Displayed are:

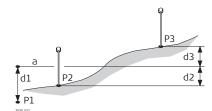
- •
- Coordinates of the projected point on the reference line Offsets between the initial point and the calculated point on the refer-• ence line

Example



- P0 Instrument station
- P1 Start point
- P2 End point
- P3 Initial point
- P4 Point projected on the reference line
- a Δ Longitudinal offset
- b Δ Parallel offset

Example of height difference relative to first reference point



- P1 Start point
- P2 Target point
- P3 Target point
- a Reference height
- d1 Height difference between start point and the reference height
- d2 Height difference between P2 and the reference height
- d3 Height difference between P3 and the reference height

Access

Select **Point Projection** from the **Reference Line** menu.

Point Projection Will project PTCoord	Enter the coordinates of the initial pont.		
will project Preoord	Кеу	Description	
	Value	To select a point from the memory.	
	Meas	To execute a distance measurement and store the displayed values.	
	Store	To save the displayed values without executing a distance measurment.	
	ОК	To confirm the entered values and continue in the process.	
Projection PT data	Кеу	Description	
	SetOut	To start the Set Out app. Refer to 7.3 Set Out.	
	Store	To save the displayed values without executing a distance measurment.	
	₽ ↓	To display the next softkey level and fields.	

	Field D	Description		
	T-Offset:	Calculated distance perpendicular to the reference line. Positive if the initial point is to the right of the reference line.		
	P	Calculated distance longitudinal to the to the reference line. Positive if the initial point is further away from the reference line.		
	h	Calculated height difference relative to the defined reference height. Positive if the initial point is higher than the reference line.		
7.10	Road			
7.10.1	Overview			
Description	 alignment, includir Horizontal alig and exit as we Vertical alignm Import of align Export of align 	used to stake out points or for as-built checks relative to a road , including slopes. It supports the following features: ontal alignments with the elements straight, curve, and spiral (entry xit as well as partial). al alignments t of alignments from the folder \ROAD on the USB memory stick t of alignments into the folder \ROAD on the USB memory stick on, editing and deletion of alignments onboard.		
Access	1. Select Ap	ops from the Main Menu.		
	2. Select Ro	bad.		
	3. Complete	e app pre-settings. Refer to 6 Apps - Getting Started.		
Road menu	The Road app inclu	udes:		
	Menu selection	Description		
	Road Define	To view and enter control points which can be used for station setup and orientation.		
		To define the horizontal and vertical alignments.		
	Road Setout	To stakeout points on the alignment or relative to the alignment.		
		To measure transections.		
		To view results of transection and stakeout.		
	Delete alignmer			

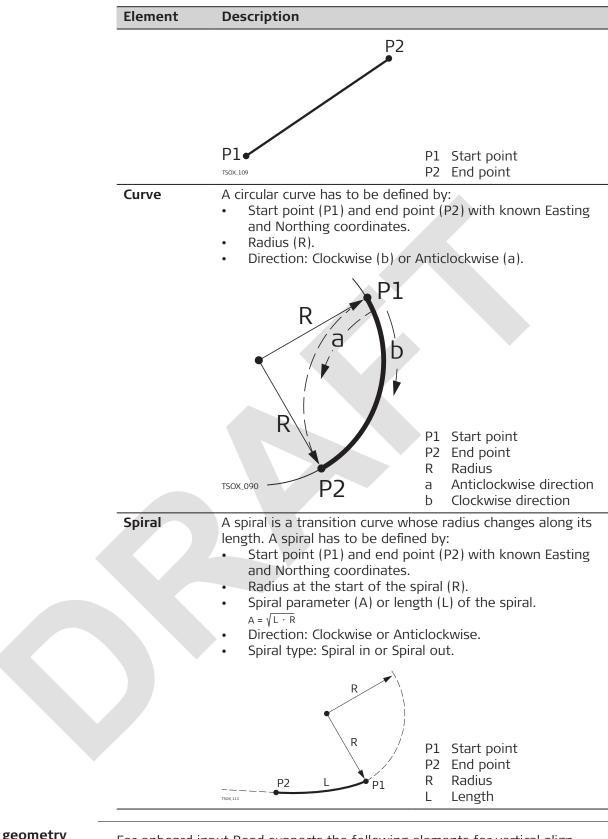
- The alignments must be continuous because geometrical gaps and chainage equations are not supported.
- The created road alignments are permanent and stored even if the app is ٠ closed.
- Road alignments can be deleted onboard. •
- Road alignments can be edited onboard. •

7.10.2 **Basic Terms**

٠

Elements

Elements	d = 155.000	B	Straight
	d = 132.000 d = 122.000 d = 112.000 d = 102.000	A C C C	Spiral Curve Radius Perpendicular offset left Perpendicular offset right Increment Stationing
Terminology	Term	Description	
	Increment direction	The forward direction of the large stake number.	e alignment facing the
	Right and left	Facing to the forward direct	ion of the alignment.
	Larger stake number	Refers to the number in from along the alignment.	nt of the principal point
	Smaller stake num- ber	Refers to the number behind along the alignment.	d the principal point
Horizontal geometry elements	For onboard input Road ments.	l supports the following eleme	ents for horizontal align-
	Element Descr	iption	
	• St	ight has to be defined by: art point (P1) and end point (nd Northing coordinates.	P2) with known Easting



Vertical geometry elements

For onboard input Road supports the following elements for vertical alignments:

	Chai	nage
•	Char	nage

Elevation

-					
7.10.3	Creating a New Alignment				
Description	An alignment is a set of data that can be used to describe and determine the exact location of a road centerline. It describes the whole road in terms of elements of the road, including starting point, straight line, curve and spiral. Create horizontal and vertical road alignment files with the basic field software and upload them onto the instrument. Alternatively, horizontal and vertical road alignments can be created onboard the instrument.				
Access	1. Sele	ct Road Define fr	om the Road menu.		
	 Select: Define H Alignment Select Element or Cross point Edit H Alignment Define V Alignment Edit V Alignment Using a horizontal alignment file is mandatory. 		ent or Cross point nt nent nt nment file is mandatory.		
	Using a vertical alignment file is not mandatory. A height can be defined manually instead.				
Start point	Кеу	Description	Description		
and Exist Element	Back	To return to th	ne last active screen.		
	Straight		aight into a horizontal alignment. ist Element when the start point has been		
	Curve		ve into a horizontal alignment. ist Element when the start point has been		
	Spiral	To insert a spiral into a horizontal alignment. Available in Exist Element when the start point has bee defined.			
	ок	To accept the	selection.		
	Description	of fields			
	For Start point				
	Field	Option	Description		
	Chainage:	Editable field	Stake number of the starting point on road centerline. Characters such as "K", "k" or "+" are not allowed. Example: K2+224.224 must be 2224.224.		
	Ε:	Editable field	Easting of the start point of the horizontal alignment.		
	N :	Editable field	Northing of the start point of the horizontal alignment.		

	Field	Option	Description
	Bearing:	Editable field	The tangential azimuth of the line at the starting point.
	For Straight		
	Field	Option	Description
	Length:	Editable field	The length of the straight element.
	For Curve		
	Field	Option	Description
	Radius:	Editable field	Radius of the curve. Positive when the curve is turning right along the forward direction of the alignment. Negative when the curve is turning left along the forward direction of the alignment.
	Length:	Editable field	Length from the start to the end point of the curve.
	For Spiral		
	Field	Option	Description
	Length:	Editable field	Length of the clothoid element.
	Rs:	Editable field	The entry radius of the spiral. Positive when the spiral is turning right along the forward direction of the alignment. Negative when the spiral is turning left along the forward direction of the alignment.
	Re:	Editable field	The exit radius of the spiral. Positive when the spiral is turning right along the forward direction of the alignment. Negative when the spiral is turning left along the forward direction of the alignment.
Create cross points			n points of two tangents of a symmetric align- to define a complete road alignment.
	P2 *	P4 P5	P1 Start point straight 1 P2 Start point spiral 1 P3 Start point circle P4 Start point spiral 2 P5 Start point straight 2 P6 End point P7 Cross point •P6 a Tangent 1 b Tangent 2
			have to be a straight or rather an end point. Its have to be entered. The first cross point is
		art point of the	
	Кеу	Description	
	Back	To return to th	e last active screen.

Кеу	Description
Store	To save the displayed values without executing a distance measurment.
ОК	To accept the selection.

Description of fields

Field	Option	Description
E :	Editable field	Easting of the point of intersection.
N :	Editable field	Northing of the point of intersection.
Radius:	Editable field	Curvature radius of the circular curve corresponding to the point of intersection. The curvature radius at the end must be input as 0. Positive when right along the forward direction of the alignment. Negative when turning left along the forward direction of the alignment.
A1:	Editable field	The parameter A defining the spiral at the beginning. Positive when the spiral is turning right along the forward direction of the alignment. Negative when the spiral is turning left along the forward direction of the alignment.
A2:	Editable field	The parameter A defining the spiral at the end. Positive when the spiral is turning right along the forward direction of the alignment. Negative when the spiral is turning left along the forward direction of the alignment.

Define V Alignment

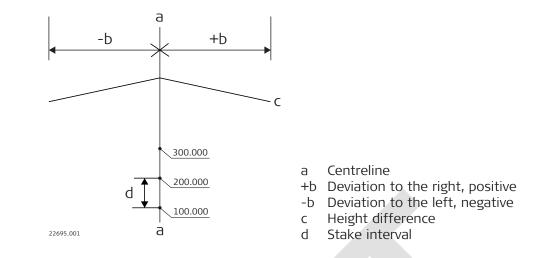
The vertical alignment consists of a set of intersecting points, including chainage, height, and length of an element.

Кеу	Description
Back	To return to the last active screen.
ОК	To save the data entry and proceed to enter the value of the next element.

Field	Option	Description
Chainage:	Editable field	Start chainage of the vertical alignment.
Elevation:	Editable field	The end elevation of the straight.
Length:	Editable field	Using the length of the straight. The length at the start and end of the vertical alignment must be zero.

Example

			P2		P4		
		P1			P3		
		P1	P2	P3	P4		
	Chainage:	0	200	450	600		
	Elevation:	200	425	170	285		
	Length:	0	200	250	150		
Edit horizontal and	Кеу	Description					
vertical alignment	Edit	-	The displayed fields change to editable fields.				
	First	To display the					
	Last	To display the last alignment element.					
	Search						
_	Description c Refer to Start	o f fields pointandExist Ele	ement and D	efine V Alignmer	nt.		
Calculate Coordinate	After the defir calculated.	nition of the aligr	nments, the o	coordinates for s	staking can be		
	S Using	g a horizontal ali <u>s</u>	gnment file is	s mandatory.			
		g a vertical alignn ed manually inst		ot mandatory. A	height can be		
	Кеу	Description					
	ОК	To save the dates.	ata entry and	ry and proceed to calculate the coordin-			
	Description o	of fields					
	Field	Option	Descriptio	on			
	SPACING:	Editable field	Chainage i	ncrement.			
7.10.4	Stake						
Description		nts relative to an ertical alignment			ht difference is		



Access

Selec	t Road	Setout	from	the	Road	menu.

2. Select:

1.

Use Coordinate Data To set out the calculated coordinates.

- Refer to Start Setout. Input Chainage and Offset To set out by stake number and direction.
 - To set out by stake number and dir Refer to Start Setout.

List

Available for Use Coordinate Data.

Select a chainage from the list.

Кеу	Description
Search	To search for a particular chainage.
View	To display chainage and coordinates.
ОК	To accept the selection proceed to set out.

Start Setout

Available for Input Chainage and Offset.

Кеу	Description
Back	To return to the last active screen.
ОК	To accept the selection proceed to set out.

Description of fields

Field	Option	Description
Chainage:	Editable field	The chainage to set out.
SPACING:	Editable field	Chainage increment.
L/R:	Editable field	Offset to left or right. Positive to the right. Negative to the left. Set to zero to set out in the middle.

	Field	Option	Description	
	U/D:	Editable field	Offset to up or down. Positive up. Negative down. Set to zero to set out in the middle.	
Angle SO 1/3	Key	Description		
	hr	To enter a pris	sm height.	
	Meas	To execute a distance measurement and store the displayed values.		
	Store	To save the di measurment.	isplayed values without executing a distance	
	P₽	To display the	next softkey level and fields.	
	Back	To return to t	he last active screen.	
	List	To display the	list of available points.	
	Coord	To display and	d check the coordinates for set out.	
	Description of fields			
	Field	Option	Description	
	Chainage:	Selectable list	Selected chainage to stake out.	
	dHR:	Display only	Perpendicular offset to alignment. The direc- tion is correct when "0" is displayed.	
	dHD:	Display only	Horizontal offset: Positive if the stake out point is further away than the measured point.	
	HDc	Display only	Height difference between the measured point and the defined height.	
7.10.5	Data Transfe	er		
Description		•	and imported from the USB memory stick. red for the transfer.	
Access	Select Data Tr	ansfer from the	e Road menu.	
Road SO-Data trans-	Кеу	Description		
fer	Back	To return to the last active screen.		
	ОК	To select the	file format and continue with the export.	
	Description o	f fields		
	Field	Option	Description	
	Mode:	Selectable list	Select between data import and export.	
	Data type:		Data type to be transferred.	

		Ostion	Description
	Field	Option	Description
		Control point	Available for data import. The calculated coordinate data.
		H Element	Available for data import.
			The horizontal alignment.
		H Cross	Available for data import.
		point	The intersection point
		Control point	Available for data export. The calculated coordinate data.
		Road SO	Available for data export.
		result	The coordinates of the stake out results.
		H alignment	Available for data export. The horizontal alignment.
	Device:	USB	The memory device to which data are expor- ted.
	Overwrite:	Yes	Set for Mode: : Import . Existing data are overwritten. Download existing data first to the USB stick for a backup.
		No	Set for Mode:: Export . Existing data of the same type are not over- written.
_			
13	<i>,</i> .	older on USB st	ick Format
	<i>,</i> .	Folder on USB st	Chainage points:
	<i>.</i>		Chainage points: *.FPT
	<i>.</i>		 Chainage points: *.FPT Alignement definition: *.HLN
	<i>.</i>		 Chainage points: *.FPT Alignement definition: *.HLN Road Set out points:
	Export \	ROAD	 Chainage points: *.FPT Alignement definition: *.HLN Road Set out points: *.STR
τ.ge	Export \		 Chainage points: .FPT Alignement definition: .HLN Road Set out points: .STR Chainage points: .FPT
	Export \	ROAD	 Chainage points: .FPT Alignement definition: .HLN Road Set out points: .STR Chainage points:
Road data format for	Export \	ROAD	 Chainage points: .FPT Alignement definition: .HLN Road Set out points: .STR Chainage points: .FPT Alignement definition:
	Export \\ Import \	ROAD	 Chainage points: .FPT Alignement definition: .HLN Road Set out points: .STR Chainage points: .FPT Alignement definition: .HLN
Road data format for	Export \	ROAD ROAD data must follow	 Chainage points: .FPT Alignement definition: .HLN Road Set out points: .STR Chainage points: .FPT Alignement definition: .HLN the stated standards.
Road data format for	Export \\ Export \\ Import \\ Example control point	ROAD	 Chainage points: .FPT Alignement definition: .HLN Road Set out points: .STR Chainage points: .FPT Alignement definition: .HLN the stated standards.
Road data format for	Export \\ Export \\ Import \\ Example control point chainage,coc	ROAD ROAD data must follow	 Chainage points: *.FPT Alignement definition: *.HLN Road Set out points: *.STR Chainage points: *.FPT Alignement definition: *.HLN the stated standards.
Road data format for	Export \\ Export \\ Import \\ Example control point chainage,coc line_element	ROAD ROAD data must follow : (USB Drive:\Roac ord_n,coord_e,coor	 Chainage points: *.FPT Alignement definition: *.HLN Road Set out points: *.STR Chainage points: *.FPT Alignement definition: *.HLN the stated standards. Alkoad.FPT) rd_h
Road data format for	Export \\ Export \\ Import \\ Example control point chainage,coc line_element	ROAD ROAD data must follow : (USB Drive:\Roac ord_n,coord_e,cool (USB Drive:\Road	 Chainage points: *.FPT Alignement definition: *.HLN Road Set out points: *.STR Chainage points: *.FPT Alignement definition: *.HLN the stated standards.
Road data format for	Export \\ Export \\ Import \\ Example control point chainage,coo line_element type,startpile	ROAD ROAD data must follow : (USB Drive:\Roac ord_n,coord_e,cool (USB Drive:\Road e,coord_n,coord_e,	 Chainage points: .FPT Alignement definition: .HLN Road Set out points: .STR Chainage points: .STR Chainage points: .FPT Alignement definition: .FPT Alignement definition: .HLN the stated standards. the stated standards. Alkoad.FPT) rd_h \Road.HLN) startAZ //start point type:0

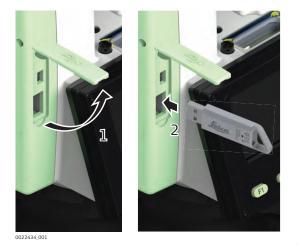
line_crosspoint (USB Drive:\Road\Road.HLN) startpile,coord_n,coord_e //start point coord_n,coord_e,radius,A1,A2 //cross point

8	Coding	Coding		
Description		Codes contain information about recorded points. With the help of coding, points can be assigned to a particular group simplifying later processing.		
Access	Select Data	Select Data Manager from the Main Menu and choose Code Library.		
Code Library	Displayed is	list of existing code names.		
	Кеу	Description		
	Last	Available if a code has been previously used in the job. To select from a list of last used codes. The codes are sorted by time with the most recently used code at the top of the list.		
	Search	To search for a code using the number. After entry, the firmware searches for a matching code name, and displays these.		
	Delete	To delete the selected code.		
	New	To enter a new code.		

9	Data Management			
9.1	Overview			
Access	Select Manage in the Main Menu.			
Data Manager	The Data Manager menu contains all functions for entering, editing, checking and deleting data in the field.			
	Menu item	Description		
	Memory Information	ber of stored	pecific memory information such as the num- stations, fix points and measurement records. n use is shown as well.	
	Job	of data of dif urements or o name and use time of creati	v, create and delete jobs. Jobs are a summary ferent types, for example, fixed points, meas- odes. The job definition consists of the job er. The system generates time and date at the on. etting the Job.	
	Observa- tions	able in the int	elete observation data. Observation data avail- ernal memory can be searched for via a spe- rch, or by viewing all points within a job.	
	Known Points	To view, create, edit and delete known points. Valid fixed points contain at least the point ID and the coordinates E, N or H.		
	Code Library	description ar	e, edit and delete codes. To each code a Id a maximum of 8 attributes with up to 12 ch can be assigned. ding.	
	Erase Memory	of a specific jo	vidual jobs, known points and measurements bb or all jobs in the memory. ng the memory cannot be undone. After ming the message all data is permanently ed.	
9.2	Memory Information			
Access			in the Main Menu .	
Access		_	mation in the Data Manager menu.	
- Memory information	Кеу	Description		
	ОК	To return to the previous screen to reselect an option.		
·	Description of fields			
	Field	Option	Description	
	Job:	Display only	Name of an existing job for which informa- tion from the memory is displayed.	
	Stations:	Display only	The number of stations saved in the selected job.	

	Field	Option	Description		
	Fix:	Display only	The number of known point saved in the selected job.		
	Meas. REC:	Display only	The number of recorded measurements saved in the selected job.		
	Used Mem.:	Display only	The percentage of used memory by this job.		
9.3	Deleting the	e Memory			
Access	1. Select	Data Manager	in the Main Menu.		
	2. Select	Erase Memory	in the Data Manager menu.		
Erase Memory	Кеу	Description			
	Back	To return to t	he last active screen.		
	Delete	To delete the	selected records.		
	Description of	Description of fields			
	Field	Option	Description		
	Data type:	Job	Delete a all data (measurements and known point).		
		Observation	Delete only measurements.		
		Known Point	Delete only fixed point.		
	Job:	Single Job	Delete only one particular job.		
		All jobs	Delete all job at once.		
	SelJob:	Selectable list	Available for Job: : Single Job Displays the selected job.		
9.4	Working wit	th a USB Me	mory Stick		
	Always return t	o the Main Me	nu before removing the USB memory stick.		
3	 Keep the USB memory stick dry. Use it only within the specified temperature range, -40°C to +85°C (-40° to +185°F). Protect the USB memory stick from direct impacts. 				
	Failure to follow these instructions could result in data loss and/or permanent damage to the USB memory stick.				
	Leica industrial	grade USB men	s may be used, Leica Geosystems recommends hory sticks and cannot be held responsible for at may occur when using a non-Leica USB		

Insert a USB memory stick step-by-step



- 1. Open the compartment lid.
- 2. Insert the USB memory stick into the USB host port.

10	Data	Trans	sfer		
10.1	Exporting Data				
Description	Job data can be exported from the internal memory of the instrument. Data are exported to the USB memory stick into the folder \JOBS.				
			stick can be inse transfer.	erted and removed. No additional software is	
Access	1.	Select	Transfer in the	Main Menu.	
	2.				
Data Export	Кеу		Description		
	Back		To return to th	e last active screen.	
	List		To list all jobs	within the internal memory.	
	ОК		To continue wi	th the export.	
	Descrip	tion of	fields		
	Field		Option	Description	
	to:		USB-Stick	The memory device to which data are expor- ted.	
	DataTy	/pe:		Data type to be transferred.	
			Obs.&Fix	Measured points and fixpoints.	
			Observation	Only measured points.	
			Known Point	Only fixpoints.	
	SelJob		Selectable list	Displays the selected job.	
Export data step-by- step	1.	Press (details		Export screen after selecting the export	
	2.	Select	the data format	, enter the file name and press OK .	
		ASCII:		American Standard Code for Information Interchange. Free format. Use and order of vari- ables and delimiter can be defined during import. Continue with step 3	
		IDEX:		The Independent Data Exchange format is a Leica proprietary ASCII format used to exchange data between TPS and GPS instruments and software.	
	3.	A mess	age will display	confirming the successful export of data.	

10.2	Importing	Data	
Description		mported to the internal memory . Data are imported from the fo	
	A USB memor required for t	ry stick can be inserted and rem he transfer.	oved. No additional software is
Importable data formats		ng data, the instrument automa sed on the file extension. The fo	tically stores the file in a direct- llowing data formats can be
	Data Type	File extension	Recognised as
	ASCII	any ASCII file extension e.gtxt	Fixpoints
Access	1. Selec	ct Transfer in the Main Menu .	
_	2. Selec	ct Data Import in the Data Tra	nsfer menu.
Data Import	Key Description		
	Back	To return to the last active s	screen.
	ОК	To select the file format and	continue with the import.
	Description	of fields	
	Field	Option Description	
	From:	USB-Stick Only option	
	to:	Instrument Only option	
	File:	Single File Only option	
Import data step-by- step		s OK in the Data Import screer ne memory device.	n to proceed to the file directory
	2. Selec	ct the file to be imported and pr Files for importing must be p	
	3. Defir	ne the job name for the importe	d file.
	4. Press	s OK to proceed	
		ne the delimiter value, the units	and the data fields of the file
	and	press OK to continue.	

11	Tools			
11.1	Check & Adjust			
11.1.1	Overview			
Description	Leica Geosystems instruments are manufactured, assembled and adjusted to the best possible quality. Quick temperature changes, shock or stress can cause deviations and decrease the instrument accuracy. It is therefore recom- mended to check and adjust the instrument from time to time. This check and adjust can be done in the field by running through specific measurement procedures. The procedures are guided and must be followed carefully and precisely as described in the following chapters. Some other instrument errors and mechanical parts can be adjusted mechanically.			
Electronic calibration	 The following instrument errors can be checked and calibrated electronically: Horizontal collimation error, also called line-of-sight error. Vertical index error. Compensator index error of the electronic level, transversal and longitud- inal. 			
	For determining these errors, it is necessary to measure in both faces, but the procedure can be started in any face.			
Checking parts	 The following instrument parts can be checked: Circular level on the instrument and tribrach. Laser plummet. Screws on the tripod. 			
- 37	 During the manufacturing process, the instrument errors are carefully determined and set to zero. As mentioned, these errors can change and it is highly recommended to redetermine them in the following situations: Before the instrument is used for the first time. Before every high precision survey. After rough or long periods of transport. After long periods of work or storage. If the temperature difference between current environment and the temperature at the last calibration is more than 10°C (18°F). 			
11.1.2	Preparation			
3	Before determining the instrument errors, the instrument has to be levelled using the electronic level. The tribrach, the tripod and the underground should be stable and secure from vibrations or other disturbances.			



ment.

The instrument should be protected from direct sunlight to avoid thermal warming. It is also recommended to avoid strong heat shimmer and air turbulence. The best conditions are early in the morning or with overcast sky.

Before starting to work, the instrument has to become acclimatised to the ambient temperature. Take at least 15 minutes into account or approximately 2 minutes per °C of temperature difference from storage to working environ-

Adjusting Line-of-Sight and Vertical Index Error 11.1.3 The procedures and conditions required to correct line-of-sight and vertical F index errors are the same, therefore the procedure will only be described once. Line-of-sight error The line-of-sight error, or horizontal collimation error is the deviation from the perpendicular between the tilting axis and the line of sight. а **Tilting** axis а Ь Line perpendicular to tilting axis Horizontal collimation, or line-of-sight, error C d Line-of-sight Vertical index error A vertical index error exists, if the 0° mark of the vertical circle reading does not coincide with the mechanical vertical axis of the instrument, also called standing axis. The V index error is a constant error that affects all vertical angle readings. Mechanical vertical axis of the instrument, also а called standing axis Axis perpendicular to the vertical axis. True Ь 90° Vertical angle is reading 90° С Vertical index error d F By determining the vertical index error the electronic level is adjusted automatically.

Access1.Select Tools in the Main Menu.2.Select Check & Adjust in the Tools menu.

F

F

- 3. Select:
 - Hz Collimation, or
 - V-Index.
 - Compensator
 - View Calibration.

Calibration options

Check and adjust step-by-step

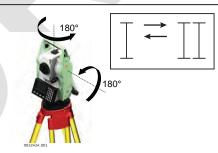
In the **Check & Adjust** screen there are several calibration options.

Menu selection	Description	
Hz Collimation	Refer to Check and adjust step-by-step.	
V-Index	Refer to Check and adjust step-by-step.	
Compensator	Refer to 11.1.4 Adjusting the Compensator.	
View Calibration	Displays the current calibration values and compensator indexes that have been set for HA-Collimation and V-index.	
1. Level the instrument with the electronic level. Refer to 4 Operation Level up with the electronic level step-by-step.		
2.	Aim at a point approximately 100 m from the instrument which is within 5° of the horizontal.	

3. Press **OK** to measure to the target point.

4.

± 5°



Change face and aim at the target point again

For checking the horizontal aim, the difference in Hz and V are displayed.

5.	Press OK to measure to the target point.
	The old and new calculated values are displayed.
6.	Either:
	 Press OK to save the new adjustment data, or
	 Press (5) to exit without saving the new adjustment data.

Messages

11.1.4

The following are important messages or warnings that may appear.

Messages	Description
V not suitable\r\nfor Calib- ration	The vertical angle deviates from the required horizontal / line-of-sight. Aim correctly at the target point. Confirmation of the mes- sage required.
Compensator unstable.\r\nPlease remeasure.	Computed values out of tolerance. The previous values are retained and measurements should be repeated. Confirmation of the message required.
Compensator unstable.\r\nPlease remeasure.	Measurement error appears when, for example, there is an unstable set up. Repeat the process. Confirmation of the message required.

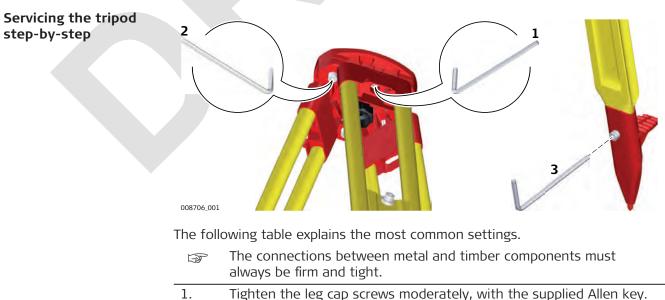
Adjusting the Compensator

Compensator index error	a Mechanical vertical ax instrument, also called ing axis Plumb line C Longitudinal component the compensator inder d Transversal component the compensator inder	d stand- ent (I) of ex error nt (t) of
	The compensator index errors (I, t) occur, if the vertical axis of the ind the plumb line are parallel but the zero points of the compensative do not coincide. The calibration procedure electronically adjust point of the compensator.	itor and the
	A longitudinal component in direction of the telescope and a transv ponent perpendicular to the telescope define the plane of the dual pensator of the instrument.	
	The longitudinal compensator index error (I) has a similar effect as t ndex error and effects all vertical angle readings.	the vertical
	The transversal compensator index error (t) is similar to the tilting a The effect of this error to the horizontal angle readings is 0 at the l and increases with steep sightings.	
Access	1. Select Tools in the Main Menu .	
	2. Select Check & Adjust in the Tools menu.	
×	3. Select Compensator in the Calibration menu.	
Check and adjust	1. Level the instrumentl.	
step-by-step	2. Press OK to measure the first face. No target has to be air	ned at.
	3. OK to release the measurement in the other face.	

- If one or more errors are bigger than the predefined limits, the procedure must be repeated. All measurements of the current run are rejected and are not averaged with the results from previous runs.
- Measure the target. The standard deviations of the determined adjustment errors can be calculated from the second run onwards.

11.1.5	Adjust	ting the Level of the Instrument and Tribrach
Adjust the level step- by-step		
	0022433_001	
	1.	Place and secure the tribrach onto the tripod, and then secure the instrument onto the tribrach.
	2.	Using the tribrach footscrews, level the instrument with the electronic level. To activate the electronic level, turn on the instrument, and press the $$ key from within an app. In some panels, access is possible by pressing the \bigcirc key.
	3.	The bubbles of the instrument and tribrach levels must be centred. If one or both levels are not centred, adjust as follows.
		Instrument : If the bubble extends beyond the centre marking, use the Allen key supplied to centre it with the adjustment screws.
		Tribrach : If the bubble extends beyond the centre marking, adjust it using the adjustment pin with the adjustment screws. Turn the adjustment screws:
		 To the left: and the bubble approaches the screw. To the right: and the bubble goes away from the screw.
	4.	Repeat step 3. on the instrument and tribrach until both levels are centred and no further adjustments are necessary.
1. T	After th	ne adjustment, no adjustment screw should be loose.
11.1.6	Inspec	ting the Laser Plummet of the Instrument
	normal adjustrr	er plummet is located in the vertical axis of the instrument. Under conditions of use, the laser plummet does not need adjusting. If an nent is necessary due to external influences, return the instrument to ca Geosystems authorised service workshop.

plummet step-by-step 360° 0 2.5 mm / 1.5 m 5 3 mm/1.5 m Set up the instrument on the tripod approximately 1.5 m above the 1. ground and level up. 2. To activate the laser plummet, turn on the instrument, and press the (\bigstar) key from within any app and access the level panel. F Inspection of the laser plummet should be carried out on a bright, smooth and horizontal surface, such as a sheet of paper. Mark the centre of the red laser dot on the ground. 3. 4. Turn the instrument slowly through 360°, carefully observing the movement of the red laser dot. F The maximum diameter of the circular movement described by the centre of the laser dot should not exceed 3 mm at a height of 1.5 m. 5. If the centre of the laser dot describes a perceptible circular movement or moves more than 3 mm away from the point which was first marked, an adjustment may be required. Inform your nearest Leica Geosystems authorised service centre. Depending on brightness and surface, the diameter of the laser dot can vary. At 1.5 m, it is about 2.5 mm. Servicing the Tripod 2 1



11.1.7

Inspect the laser

	2.			d joints on the tripod head enough to keep the lifting the tripod off the ground.
	3.	Tighte	n the Allen screv	ws of the tripod legs.
11.2	Syste	m Info	ormation	
Description				displays instrument, system and firmware for the date and time.
	L.S.	ment	type and serial r	trument-related information, such as instru- number, as well as the firmware version and ntacting support.
Access	1.	Select	Tools in the Ma	ain Menu.
	2.	Select	System Inform	nation in the Tools menu.
System information	Кеу		Description	
	Forma	at	lost. N	memory. ivating the format command all data will be lake sure that all important data has been d up before formatting.
	Back		To return to th	ne last active screen.
	Descri	ption of	f fields	
	Field		Option	Description
	First li	ne		Displays the current date and time.
	Туре		Display only	Displays the instrument type.
	SN:		Display only	Displays the serial number of the instrument.
	Firmw	vare:	Display only	Displays the firmware version number installed on the instrument.
	EDM-	FW:	Display only	Displays the version number of the EDM firmware.
11.3	Loadi	ng Firr	nware or Lic	ense
Description				a USB memory stick. This process is described
Access	1.	Select	Tools in the Ma	ain Menu.
	2.	Select	Upload FW in t	he Tools menu.
E.				pply during the system upload process. The apacity before commencing the upload.
Loading firmware or license step-by-step	1.			license files in the root directory of the USB as the extension *.key.
	2.	Insert	the USB stick in	to the instrument.
	3.	Select	Upload FW from	m the Main Menu .

4. Select the type to be loaded from the **Upload FW** menu. Press \bigcirc . OR

On the keyboard, press the number of the item in the list.

- **Mainboard FW**: The firmware installed on the instrument.
- **EDM FW**: The firmware of the EDM.
- **BOOTLOADER FW**: The firmware of the bootloader. The bootloader enables loading the operating system within the memory when the instrument is started.
- **License**: The license key for certain functionality.
- 5. Press **YES** to confirm the warning message.
- 6. Once successfully loaded, the system will shut down and restart again automatically.

12	Care and Transport
12.1	Transport
Transport in the field	 When transporting the equipment in the field, always make sure that you either carry the product in its original container, or carry the tripod with its legs splayed across your shoulder, keeping the attached product upright.
Transport in a road vehicle	Never carry the product loose in a road vehicle, as it can be affected by shock and vibration. Always carry the product in its container and secure it.
	For products for which no container is available use the original packaging or its equivalent.
Shipping	When transporting the product by rail, air or sea, always use the complete original Leica Geosystems packaging, container and cardboard box, or its equi- valent, to protect against shock and vibration.
Shipping, transport of batteries	When transporting or shipping batteries, the person responsible for the product must ensure that the applicable national and international rules and regulations are observed. Before transportation or shipping, contact your local passenger or freight transport company.
Field adjustment	Exposing the product to high mechanical forces, for example through frequent transport or rough handling, or storing the product for a long time may cause deviations and a decrease in the measurement accuracy. Periodically carry out test measurements and perform the field adjustments indicated in the User Manual before using the product.
12.2	Storage
Product	Respect the temperature limits when storing the equipment, particularly in summer if the equipment is inside a vehicle. Refer to 13 Technical Data for information about temperature limits.
Li-Ion batteries	 Refer to 13 Technical Data for information about storage temperature range Remove batteries from the product and the charger before storing After storage recharge batteries before using Protect batteries from damp and wetness. Wet or damp batteries must be dried before storing or use A storage temperature range of 0 °C to +30 °C / +32 °F to +86 °F in a dry environment is recommended to minimize self-discharging of the battery At the recommended storage temperature range, batteries containing a 40% to 50% charge can be stored for up to one year. After this storage period the batteries must be recharged

Cleaning and Drying				
 Blow dust off lenses and prisms. Never touch the glass with your fingers. Use only a clean, soft, lint-free cloth for cleaning. If necessary, moisten the cloth with water or pure alcohol. Do not use other liquids; these may attack the polymer components. 				
Prisms that are cooler than the ambient temperature tend to fog. It is not enough simply to wipe them. Keep them for some time inside your jacket or in the vehicle to allow them to adjust to the ambient temperature.				
Dry the product, the transport container, the foam inserts and the accessories at a temperature not greater than 40 °C /104 °F and clean them. Remove the battery cover and dry the battery compartment. Do not repack until everything is completely dry. Always close the transport container when using in the field.				
Keep plugs clean and dry. Blow away any dirt lodged in the plugs of the connecting cables.				

13	Angle Measurement						
13.1							
Accuracy	Available angular accuracies	Standard deviation Hz, V, ISO17123-3	Display resolution				
	["]	[mgon]	["]	[°]	[mgon]	[mil	
	5	1.5	1	0.0001	0.1	0.01	
13.2	Distance Measu	rement with Reflec	ctors				
Range	Reflector	[m]*	[m]* [ft]*				
	Standard prism (GPR1)	3000		100	00		
	360° prism (GRZ4, GRZ122)	1500		500	0		
	Reflector tape 60 mm x 60 mm						
	Foil mode.	Foil mode, 700 2300		0			
	i on model						
	Mini prism (GMP101)	1200		400		<u></u>	
Accuracy	Mini prism (GMP101) * The distance be above or referring to ate sunlight	e range can vary depend below the specified valu non-extreme conditions slight heat shimmer.	ue. Th 5, visib	n the cond e specifiec ility about	litions and I range val	ue is	
Accuracy	Mini prism (GMP101) * The distance be above or referring to ate sunlight Accuracy refers to me	e range can vary depend below the specified valu non-extreme conditions , slight heat shimmer. easurements to standar	ue. Th 5, visib	n the cond e specifiec ility about ectors.	litions and I range val 20 km, m	ue is oder-	
Accuracy	Mini prism (GMP101) * The distance be above or referring to ate sunlight	e range can vary depend below the specified valu non-extreme conditions , slight heat shimmer. easurements to standar	ue. The s, visib d refle 4 ,	n the cond e specified ility about ectors. Mea	litions and I range val	ue is oder-	
Accuracy	Mini prism (GMP101) * The distance be above or referring to ate sunlight Accuracy refers to me	e range can vary depend below the specified valu non-extreme conditions slight heat shimmer. easurements to standard g mode std. dev. ISO 17123-	ue. The s, visib d refle 4 , rism	n the cond e specified ility about ectors. Mea	litions and I range val 20 km, m asurement	ue is oder-	
Accuracy	Mini prism (GMP101) * The distance be above or referring to ate sunlight Accuracy refers to me Distance measurin	e range can vary depend below the specified valu non-extreme conditions slight heat shimmer. easurements to standar g mode std. dev. ISO 17123- standard pr	ue. The s, visib d refle 4 , rism	n the cond e specifiec ility about ectors. Mea typi	litions and I range val 20 km, m asurement	ue is oder-	
Accuracy	Mini prism (GMP101) * The distance be above or referring to ate sunlight, Accuracy refers to me Distance measurin Standard Quick Beam interruptions, s	e range can vary depend below the specified valu non-extreme conditions slight heat shimmer. easurements to standar g mode std. dev. ISO 17123- standard pr	d refle 4 , rism om	n the cond e specified ility about ectors. Mea typi 1.5 1.1 ing objects	litions and 1 range val 2 20 km, m asurement ical [s]	ue is oder- t time	
Accuracy	Mini prism (GMP101) * The distance be above or referring to ate sunlight, Accuracy refers to me Distance measurin Standard Quick Beam interruptions, s	e range can vary depend below the specified valu non-extreme conditions slight heat shimmer. easurements to standar g mode std. dev. ISO 17123- standard pr 2 mm + 2 pp - severe heat shimmer and	d refle 4 , rism om	n the cond e specified ility about ectors. Mea typi 1.5 1.1 ing objects	litions and 1 range val 2 20 km, m asurement ical [s]	ue is oder- t time	
	Mini prism (GMP101) * The distance be above or referring to ate sunlight, Accuracy refers to me Distance measurin Standard Quick Beam interruptions, s path can result in dev	e range can vary depend below the specified valu non-extreme conditions slight heat shimmer. easurements to standard g mode std. dev. ISO 17123- standard pu 2 mm + 2 pp - severe heat shimmer and viations of the specified	d refle 4 , rism om	n the cond e specified ility about ectors. Mea typi 1.5 1.1 ing objects	litions and 1 range val 2 20 km, m asurement ical [s]	ue is oder- t time	
	Mini prism (GMP101) * The distance be above or referring to ate sunlight, Accuracy refers to me Distance measurin Standard Quick Beam interruptions, s path can result in dev	e range can vary depend below the specified valu non-extreme conditions slight heat shimmer. easurements to standar g mode std. dev. ISO 17123- standard pr 2 mm + 2 pr - severe heat shimmer and viations of the specified Description	d refle d refle d mov accur	n the cond e specified ility about ectors. Mea typi 1.5 1.1 ing objects	litions and 1 range val 2 20 km, m asurement ical [s]	ue is oder- t time	
	Mini prism (GMP101) * The distance be above or referring to ate sunlight, Accuracy refers to me Distance measurin Standard Quick Beam interruptions, s path can result in dev Type Principle	e range can vary depend below the specified valu non-extreme conditions slight heat shimmer. easurements to standard g mode std. dev. ISO 17123- standard pr 2 mm + 2 pp - severe heat shimmer and viations of the specified Description Phase measurement	d refle d refle d mov accur	n the cond e specified ility about ectors. Mea typi 1.5 1.1 ing objects	litions and 1 range val 2 20 km, m asurement ical [s]	ue is oder- t time	

13.3	Distance Measur (Non-Prism mode	ement without Refl e)	ectors
Range	Kodak Gray Card	[m]*	[ft]*
	White side 90% reflective	500	1640
	Grey side 18% reflective	200	820
	be above or referring to r	below the specified value.	g on the conditions and can . The specified range value is <i>v</i> isibility about 20 km, moder-
Accuracy		ISO17123-4	Measure time, typical [s]
	Standard measuring	3 mm + 2 ppm	1.1 in Quick mode 1.4 in Standard mode
	>200m	5 mm + 3 ppm	-
			noving objects within the beam curacy and measurement time.
Laser dot size	Distance [m]	Laser dot size, approx	imately [mm]
	at 50	12 × 24	
Characteristics	Туре	Description	
Characteristics	Type Principle	Description Phase measurement	
Characteristics			
Characteristics	Principle	Phase measurement	
Characteristics	Principle Type	Phase measurement Coaxial, visible red laser 685 nm	75 MHz (74.926925 MHz)
Characteristics	Principle Type Carrier wave Measuring system	Phase measurement Coaxial, visible red laser 685 nm	75 MHz (74.926925 MHz)
	Principle Type Carrier wave Measuring system	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7	75 MHz (74.926925 MHz)
13.4	Principle Type Carrier wave Measuring system General Technica	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ	75 MHz (74.926925 MHz)
13.4	Principle Type Carrier wave Measuring system General Technica Type	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ	75 MHz (74.926925 MHz)
13.4	Principle Type Carrier wave Measuring system General Technica Type All-around rotation	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ Value	75 MHz (74.926925 MHz)
13.4	Principle Type Carrier wave Measuring system General Technica Type All-around rotation Magnification	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ Value 28 x	75 MHz (74.926925 MHz)
13.4	Principle Type Carrier wave Measuring system General Technica Type All-around rotation Magnification Objective diameter	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ Value 28 x 44 mm	75 MHz (74.926925 MHz)
13.4	Principle Type Carrier wave Measuring system General Technica Type All-around rotation Magnification Objective diameter Focusing range	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ Value 28 x 44 mm 1.50 m/4.92 ft 1°30'/1.66 gor	75 MHz (74.926925 MHz)
13.4	Principle Type Carrier wave Measuring system General Technica Type All-around rotation Magnification Objective diameter Focusing range Field of view	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ Value 28 x 44 mm 1.50 m/4.92 ft 1°30'/1.66 gor 2.8 m	75 MHz (74.926925 MHz)
13.4 Telescope	Principle Type Carrier wave Measuring system General Technica Type All-around rotation Magnification Objective diameter Focusing range Field of view Field width at 100 m	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ Value 28 x 44 mm 1.50 m/4.92 ft 1°30'/1.66 gor 2.8 m	75 MHz (74.926925 MHz)
13.4 Telescope Compensation	Principle Type Carrier wave Measuring system General Technica Type All-around rotation Magnification Objective diameter Focusing range Field of view Field width at 100 m Compensator range: ±	Phase measurement Coaxial, visible red laser 685 nm Phase surveying about 7 al Data of the Produ Value 28 x 44 mm 1.50 m/4.92 ft 1°30'/1.66 gor 2.8 m -8' Value	75 MHz (74.926925 MHz)

Control unit	Туре	Description
	Resolution ratio	240 x 128 pixels, greyscale
	Display lightning	Background light available
	Number of keys	28
Instrument ports	Name	Description
	USB device port	Cable connection from USB device to PC fo communication
	WLAN	WLAN connection for Internet access, com munication
	USB host port	Port for USB memory stick for data transfe
nstrument		

dimensions

			T
	Ī		
	359 mm	359 mm	
	35		
100			
165 mm		202 mm	<u>V</u>

W

Weight	Туре	Value	
	Instrument With battery and tribrach	5.9 kg	
Tilting axis height	Туре	Description	
	Without tribrach	196 mm	
	With tribrach (GDF301)	237 mm ± 5 mm	
Recording	Memory Type	Number of measurements	
	Internal memory	50,000	
Laser plummet	Туре	Description	
	Туре	Visible red laser class 2	
	Location	In standing axis of instrument	
	Accuracy	Deviation from plumb line 1.5 mm at 1.5 m instrument height	
	Diameter of laser point	2.5 mm at 1.5 m instrument height	

Internal battery	Туре	Battery	Voltage	Capacity	Operating time, typically*
	GEB264	Li-Ion	7.2 V	4.4 Ah	≤ 24 h
		-	gle measurer tery is not n		C. Operating time may be
Environmental spe-	Temperat	ure			
cifications	Operatin	g temperat	ure [°C]	Stora	ge temperature [°C]
	-20 to +5	0		-30 to	+55
	Protectio	n against w	ater, dust a	and sand	
	IP55 (IEC 60529)				
	Humidity				
	Max 95 %	non conden	sing.		
	The effects of condensation are to be effectively counteracted by periodically drying out the instrument.				
Automatic corrections	The follow	ing automat	ic correction	is are made:	
	Line of sight error				
		al index erro			
	• Comp	Jensalor en	J		
13.5	Conformity to National Regulations				
Labelling GEB264	Li-Ion Ba ➡ 10A Manufact Leica Geo	945125 CC attery: 7.2V 4.4Ah 2INR18/65-2 M	1ade in China .No.: 000001		
	0022591_001				
13.5.1	TS01				
13.5.1.1	EU Declar	ation of Co	nformity		
EU	CE	type TS01		iance with Di	lares that the radio equipment irective 2014/53/EU and other
Europe	(6	(RED) can	be placed o		ropean Directive 2014/53/EU t and be put into service ember state.
	cover		uropean Dire		ational regulations not 53/EU has to be approved prior

Frequency band	Туре	Frequen	cy band [MHz]		
(for EU)	WLAN	2412 - 2472			
	Bluetooth LE	2402 - 2	2402 - 2480		
- Output power	Type Output power [mW]				
(for EU)	WLAN	8.63 (cond.)			
	Bluetooth LE	2.63 (co	nd.)		
Antenna	Туре	Antenna Gain [dBi] Conn		Connector	
(for EU)	WLAN Bluetooth LE	Internal Patch antenna	3 max.	-	
13.5.1.2	FCC Declaration of	Conformity			
	 This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: 1. This device may not cause harmful interference, and 2. This device must accept any interference received, including interference that may cause undesired operation. 				
USA	This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules.				
	These limits are designed to provide reasonable protection against harmful interference in a residential installation.				
	This equipment generates, uses, and can radiate radio frequency energy. If not installed and used in accordance with the instructions, it may cause harmful interference to radio communications.				
	 However, there is no guarantee that interference does not occur in a particular installation. If this equipment does cause harmful interference to radio or television received to which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures: Reorient or relocate the receiving antenna. Increase the separation between the equipment and the receiver. Connect the equipment into an outlet on a circuit different from that to which the receiver is connected. Consult the dealer or an experienced radio/TV technician for help. 			or television recep- f and on, the	
				rent from that to	
	Changes or modificat compliance could void				
FCC Radiation Expos- ure Statement	This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment. This equipment should be installed and operated with minimum distance 20 cm between the radiator and your body. This trans			ed and operated	

mitter must not be co-located or operating in conjunction with any other antenna or transmitter.

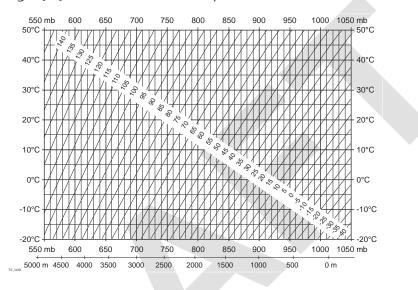
13.5.2	Dangerous Goods Regulations			
Dangerous Goods Regulations	Many products of Leica Geosystems are powered by Lithium batteries. Lithium batteries can be dangerous under certain conditions and can pose a safety hazard. In certain conditions, Lithium batteries can overheat and ignite.			
	When carrying or shipping your Leica product with Lithium batteries onboard a commercial aircraft, you must do so in accordance with the IATA Dangerous Goods Regulations .			
	Leica Geosystems has developed Guidelines on "How to carry Leica products" and "How to ship Leica products" with Lithium batteries. Before any transportation of a Leica product, we ask you to consult these guidelines on our web page (http://www.leica-geosystems.com/dgr) to ensure that you are in			
	accordance with the IATA Dangerous Goods Regulations and that the Leica products can be transported correctly.			
	Damaged or defective batteries are prohibited from being carried or transported onboard any aircraft. Therefore, ensure that the condition of any battery is safe for transportation.			
13.6	Scale Correction			
Use of scale correction	 By entering a scale correction, reductions proportional to distance can be taken into account. Atmospheric correction. Reduction to mean sea level. Projection distortion. 			
Atmospheric correc- tion	The slope distance displayed is correct if the scale correction in ppm, mm/kr which has been entered corresponds to the atmospheric conditions prevailin at the time of the measurement.			
	The atmospheric correction includes:Adjustments for air pressureAir temperature			
	 For highest precision distance measurements, the atmospheric correction should be determined with: An accuracy of 1 ppm Air temperature to 1 °C Air pressure to 3 mbar 			
Formulas	Formula for visible red laser			
	$\Delta D_{1} = 286.338 - \left[\frac{0.29535 \cdot p}{(1 + \alpha \cdot t)} - \frac{4.126 \cdot 10^{-4} \cdot h}{(1 + \alpha \cdot t)} \cdot 10^{X} \right]$			

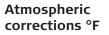
- ΔD_1 Atmospheric correction [ppm]
- p Air pressure [mbar]
- t Air temperature [°C]
- h Relative humidity [%]
- $\alpha = \frac{1}{273.15}$
- x (7.5 * t/(237.3 + t)) + 0.7857

The formula with a relative humidity value of 0% is applied.

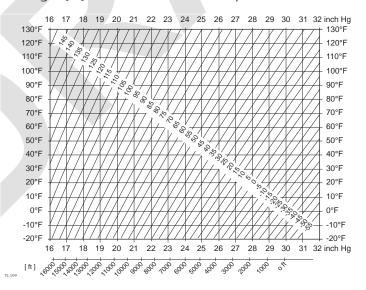


Atmospheric corrections in ppm with temperature [°C], air pressure [mb] and height [m] at 60% relative humidity.





Atmospheric corrections in ppm with temperature [°F], air pressure [inch Hg] and height [ft] at 60% relative humidity.



13.7

Reduction Formulas

Reflector types

The reduction formulas are valid for measurements to all reflector types:

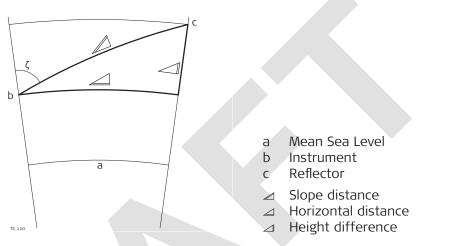
- To prisms
- To reflector tape
- Reflectorless measurements

Slope distance - corrections

Available formats depend on the instrument.

Format	Description
Instrument displayASCII	 Corrections for the atmospheric ppm are applied to the slope distances according to the for- mulas.

Formulas



The instrument calculates the slope distance, horizontal distance, height difference in accordance with the following formulas:

$$= D_0 \cdot (1 + ppm \cdot 10^{-6}) + AC$$

- Displayed slope distance [m]
- D₀ Uncorrected distance [m]
- ppm Atmospheric scale correction [mm/km]
- AC Additive constant of the reflector [m]

 $= Y - A \cdot X \cdot Y$

 $= X + B \cdot Y^2$

- ∠ Horizontal distance [m]
- ⊿ Height difference [m]
- Y ____* sinζ|
- Χ 🛛 🖉 * cosζ
- ζ Vertical circle reading
- A $(1 k / 2) / R = 1.47 * 10^{-7} [m^{-1}]$
- B $(1 k) / (2 * R) = 6.83 * 10^{-8} [m^{-1}]$
- k 0.13 (mean refraction coefficient)
- R 6.378 * 10^6 m (radius of the earth)

Earth curvature (1/R) and mean refraction coefficient (k) are automatically taken into account when calculating the horizontal distance and height difference. The calculated horizontal distance relates to the station height and not to the reflector height.

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Appendix A	Menu Tree
Appendix A Menu tree	Apps Survey Set Out Miss.Line Measure(MLM) Miss.Line Measure(MLM) Resection Resection Reference Line Reference Line Manage Memory Information Memory Information Observations Code Library Erase Memory Transfer Data Export Data Import Setting Shortcut Keys Setting K1 Setting K2 Setting Key distribution Key distribution Key function consignment Key function recovery Hz Collimation Hz Collimation V-Index Compensator View Calibration
	 Wifi Setting Tools Calibration Hz Collimation V-Index Compensator View Calibration

Appendix B	Directory Structure		
Description	On the internal memory, files are stored in certain directories. The following diagram is the default directory structure.		
Directory structure	JOBS 	Files for import/export to/from job	
	SYSTEM	Firmware files	
	ROADS	 Files for import/export to/from the Roads app: Chainage points: *.FPT Alignement definition: *.HLN Road Set out points: *.STR 	

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> Leica Geosystems AG Heinrich-Wild-Strasse 9435 Heerbrugg Switzerland

www.leica-geosystems.com



- when it has to be **right**



