

No. 2013SAR00064

For

TCT Mobile Limited

GSM/GPRS quadband mobile phone

Mode Name: Tigris 3SIM

Marketing Name: ALCATEL 3000H

With

Hardware Version: PIO

Software Version: VB20

FCC ID: RAD395

Issued Date: 2013-05-10



Note:

The test results in this test report relate only to the devices specified in this report. This report shall not be reproduced except in full without the written approval of TMC Beijing.

Test Laboratory:

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Revision Version

Report Number	Revision	Date	Memo
2013SAR00064	00	2013-05-10	Initial creation of test report



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1 Test Laboratory

1.1 Testing Location

Company Name: TMC Beijing, Telecommunication Metrology Center of MIIT Address: No 52, Huayuan beilu, Haidian District, Beijing,P.R.China

Postal Code: 100191

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1.2 Testing Environment

Temperature: $18^{\circ}\text{C} \sim 25^{\circ}\text{C}$, Relative humidity: $30\% \sim 70\%$ Ground system resistance: $< 0.5 \ \Omega$

Ambient noise & Reflection: < 0.012 W/kg

1.3 Project Data

Project Leader: Qi Dianyuan
Test Engineer: Lin Xiaojun
Testing Start Date: April 11, 2013
Testing End Date: April 27, 2013

1.4 Signature

Lin Xiaojun

(Prepared this test report)

Qi Dianyuan

(Reviewed this test report)

Xiao Li

Deputy Director of the laboratory (Approved this test report)



2 Statement of Compliance

This EUT is a variant product and the report of original sample is No.2013SAR00060. According to the client request, we quote the test results of report, No.2013SAR00060, from table 12.2 to 12.13. The results of spot check are presented in the annex I.

The maximum r esults of S pecific A bsorption R ate (SAR) found during t esting for TCT M obile Limited GSM/GPRS quadband mobile phone Tigris 3SIM / ALCATEL 3000H are as follows:

Table 2.1: Highest Reported SAR (1g)

Exposure Configuration	Technology Band	Highest Reported SAR 1g (W/Kg)	Equipment Class	
Head	GSM 850	0.77	PCE	
(Separation Distance 0mm)	PCS 1900	1.01	POE	
Body-worn	GSM 850	1.16	PCE	
(Separation Distance 10mm)	PCS 1900	0.76	PCE	

The SAR values found for the Mobile Phone are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1g tissue according to the ANSI C95.1-1999.

For body worn operation, this device has been tested and meets FCC RF exposure guidelines when used with any accessory that contains no metal and which provides a minimum separation distance of 10 mm between this device and the body of the user. Use of other accessories may not ensure compliance with FCC RF exposure guidelines.

The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power output.

The measurement together with the test system set-up is described in annex C of this test report. A detailed description of the equipment under test can be found in chapter 4 of this test report. The highest reported SAR value is obtained at the case of (Table 2.1), and the values are: 1.16 W/kg (1g).



3 Client Information

3.1 Applicant Information

Company Name:	TCT Mobile Limited
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3.2 Manufacturer Information

Company Name:	TCT Mobile Limited
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Postal Code:	201203
Country:	P.R.China
Contact:	Gong Zhizhou
Email:	zhizhou.gong@jrdcom.com
Telephone:	0086-21-61460890
Fax:	0086-21-61460602



4 Equipment Under Test (EUT) and Ancillary Equipment (AE)

4.1 About EUT

Description:	GSM/GPRS quadband mobile phone	
Model name:	Tigris 3SIM	
Marketing name:	ALCATEL 3000H	
Operating mode(s):	GSM 850/900/1800/1900	
Tootod Ty Fraguency:	825 – 848.8 MHz (GSM 850)	
Tested Tx Frequency:	1850.2 – 1910 MHz (GSM 1900)	
GPRS Multislot Class:	12	
GPRS capability Class:	В	
Release Version:	GSM: Rel5	
Release version.	GPRS: Rel6	
Test device Production information:	Production unit	
Device type:	Portable device	
Antenna type:	Integrated antenna	
Accessories/Body-worn configurations:	Headset	
Form factor:	10.7cm × 5.8 cm	

4.2 Internal Identification of EUT used during the test

EUT ID*	IMEI	HW Version	SW Version	
EUT1	860518020006821	PIO	VB20	

^{*}EUT ID: is used to identify the test sample in the lab internally.

4.3 Internal Identification of AE used during the test

AE ID*	Description	Model	SN	Manufacturer
AE1	Battery	CAB22D0000C1	1	BYD
AE2	Battery	CAB30M0000C2	1	BAK
AE3	Headset	CCB3160A15C1	1	Shunda
AE4	Headset	CCB3160A15C2	/	Shunda
AE5	Headset	CCB3160A11C1	/	Juwei
AE6	Headset	CCB3160A11C2	1	Shunda

^{*}AE ID: is used to identify the test sample in the lab internally.

Note: AE3 is same as AE5, so they can use the same results. AE4 is same as AE6, so they can use the same results.



5 TEST METHODOLOGY

5.1 Applicable Limit Regulations

ANSI C95.1–1999: IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

It specifies the maximum exposure limit of **1.6 W/kg** as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

5.2 Applicable Measurement Standards

IEEE 1528–2003: Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques.

OET Bulletin 65 (Edition 97-01) and Supplement C(Edition 01-01): Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits.

KDB447498 D01: General RF Exposure Guidance v05: Mobile and Portable Devices RF Exposure Procedures and Equipment Authorization Policies.

865664 D01 SAR measurement 100 MHz to 6 GHz v01: SAR Measurement Requirements for 100 MHz to 6 GHz

865664 D02 SAR Reporting v01: RF Exposure Compliance Reporting and Documentation Considerations



6 Specific Absorption Rate (SAR)

6.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a b iological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, oc cupational/controlled and ge neral po pulation/uncontrolled, ba sed on a per ility to exercise control over his or her exposure. In general, awareness and ab occupational/controlled exposure limits are higher than the limits general population/uncontrolled.

6.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt}(\frac{dW}{dm}) = \frac{d}{dt}(\frac{dW}{\rho dv})$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = c(\frac{\delta T}{\delta t})$$

Where: C is the specific head capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of tissue and E is the RMS electrical field strength.

However for evaluating SAR of I ow power transmitter, electrical field measurement is typically applied.



7 Tissue Simulating Liquids

7.1 Targets for tissue simulating liquid

Table 7.1: Targets for tissue simulating liquid

				~ :	
Frequency (MHz)	Liquid Type	Conductivity (σ)	± 5% Range	Permittivity (ε)	± 5% Range
835	Head	0.90	0.86~0.95	41.5	39.4~43.6
835	Body	0.97	0.92~1.02	55.2	52.4~58.0
1900	Head	1.40	1.33~1.47	40.0	38.0~42.0
1900	Body	1.52	1.44~1.60	53.3	50.6~56.0

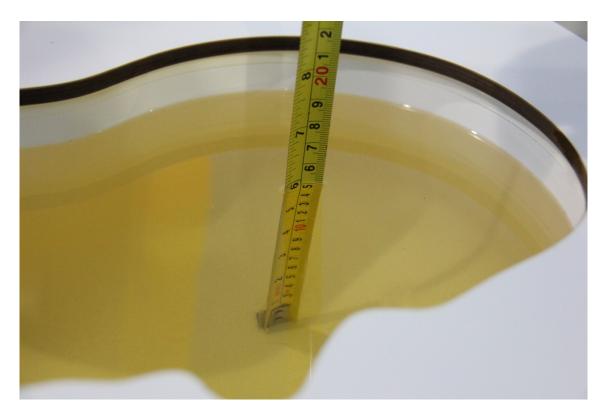
7.2 Dielectric Performance

Table 7.2: Dielectric Performance of Tissue Simulating Liquid

Measurement Date	Туре	Frequency	Permittivity	Drift	Conductivity	Drift	
(yyyy-mm-dd)			ε	(%)	σ (S/m)	(%)	
2012 04 11	Head	835 MHz	42.01	1.23	0.908	0.89	
2013-04-11	Body	835 MHz	55.92	1.30	0.984	1.44	
2013-04-12	Head	1900 MHz	40.61	1.53	1.415	1.07	
	Body	1900 MHz	52.94	-0.68	1.541	1.38	
2013-04-26	Head	835 MHz	40.88	-1.49	0.917	1.89	
2013-04-20	Body	835 MHz	55.01	-0.34	0.979	0.93	
2013-04-27	Head	1900 MHz	39.41	-1.48	1.422	1.57	
	Body	1900 MHz	52.43	-1.63	1.538	1.18	

Note: The liquid temperature is 22.0 $^{\circ}\mathrm{C}$



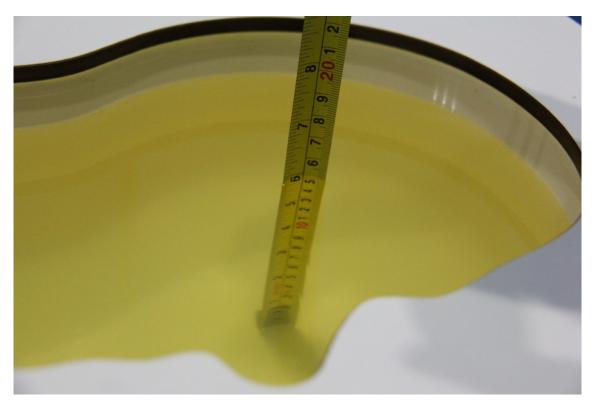


Picture 7-1: Liquid depth in the Head Phantom (835 MHz)

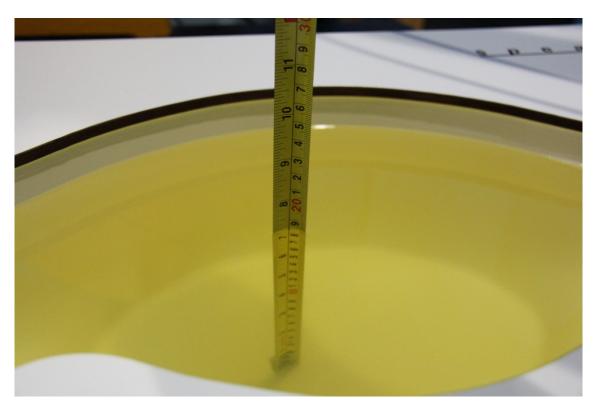


Picture 7-2: Liquid depth in the Flat Phantom (835 MHz)





Picture 7-3: Liquid depth in the Head Phantom (1900 MHz)



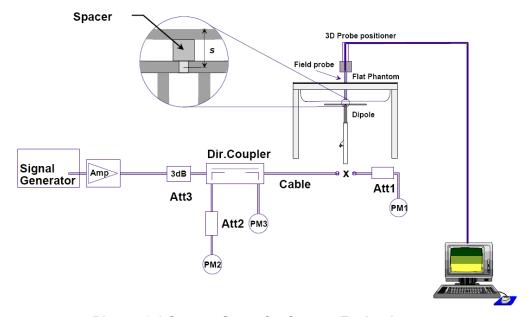
Picture 7-4 Liquid depth in the Flat Phantom (1900MHz)



8 System verification

8.1 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



Picture 8.1 System Setup for System Evaluation



Picture 8.2 Photo of Dipole Setup



8.2 System Verification

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device.

The system verification results are required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR. The details are presented in annex B.

Table 8.1: System Verification of Head

Measurement		Target value (W/kg)		Measured value (W/kg)		Deviation	
Date	Frequency	10 g	1 g	10 g	1 g	10 g	1 g
(yyyy-mm-dd)		Average	Average	Average	Average	Average	Average
2013-04-11	835 MHz	6.07	9.30	6.04	9.40	-0.49%	1.08%
2013-04-12	1900 MHz	20.6	39.1	20.20	38.48	-1.94%	-1.59%
2013-04-26	835 MHz	6.07	9.30	5.96	9.20	-1.81%	-1.08%
2013-04-27	1900 MHz	20.6	39.1	20.12	38.36	-2.33%	-1.89%

Table 8.2: System Verification of Body

Measurement		Target val	ue (W/kg)	Measured v	value (W/kg)	Deviation		
Date	Frequency	10 g	1 g	10 g	1 g	10 g	1 g	
(yyyy-mm-dd)		Average	Average	Average	Average	Average	Average	
2013-04-11	835 MHz	6.20	9.36	6.20	9.24	0.00%	-1.28%	
2013-04-12	1900 MHz	21.3	39.9	21.36	40.40	0.28%	1.25%	
2013-04-26	835 MHz	6.20	9.36	6.28	9.44	1.29%	0.85%	
2013-04-27	1900 MHz	21.3	39.9	21.52	40.80	1.03%	2.26%	



9 Measurement Procedures

9.1 Tests to be performed

In order to determine the highest value of the peak spatial-average SAR of a handset, all device positions, configurations and operational modes shall be tested for each frequency band according to steps 1 to 3 below. A flowchart of the test process is shown in picture 9.1.

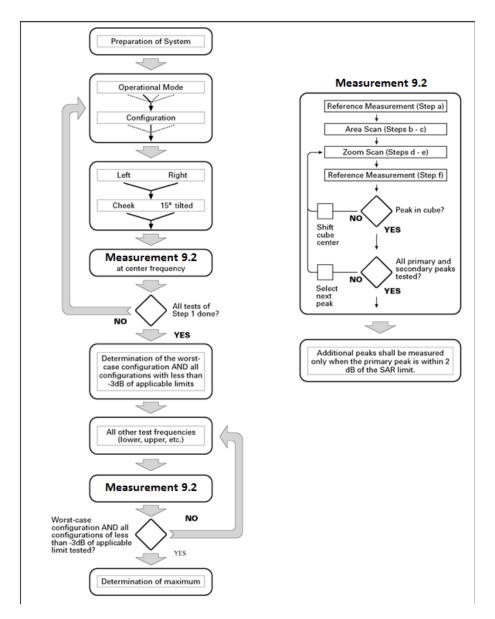
- **Step 1**: The tests described in 9.2 shall be performed at the channel that is closest to the centre of the transmit frequency band (f_c) for:
- a) all device positions (cheek and tilt, for both left and right sides of the SAM phantom, as described in annex D),
- b) all configurations for each device position in a), e.g., antenna extended and retracted, and c) all operational modes, e.g., analogue and digital, for each device position in a) and configuration in b) in each frequency band.

If more than three frequencies need to be tested according to 11.1 (i.e., $N_c > 3$), then all frequencies, configurations and modes shall be tested for all of the above test conditions.

Step 2: For the condition providing highest peak spatial-average SAR determined in Step 1, perform all tests described in 9.2 at all other test frequencies, i.e., lowest and highest frequencies. In addition, for all other conditions (device position, configuration and operational mode) where the peak spatial-average SAR value determined in Step 1 is within 3 dB of the applicable SAR limit, it is recommended that all other test frequencies shall be tested as well.

Step 3: Examine all data to determine the highest value of the peak spatial-average SAR found in Steps 1 to 2.





Picture 9.1 Block diagram of the tests to be performed

9.2 General Measurement Procedure

The area and zoom scan resolutions specified in the table below must be applied to the SAR measurements and fully documented in SAR reports to qualify for TCB approval. Probe boundary effect error compensation is required for measurements with the probe tip closer than half a probe tip diameter to the phantom surface. Both the probe tip diameter and sensor offset distance must satisfy measurement protocols; to ensure probe boundary effect errors are minimized and the higher fields closest to the phantom surface can be correctly measured and extrapolated to the phantom surface for computing 1-g SAR. Tolerances of the post-processing algorithms must be verified by the test laboratory for the scan resolutions used in the SAR measurements, according to the reference distribution functions specified in IEEE Std 1528-2003. The results should be documented as part of the system validation records and may be requested to support test results when all the measurement parameters in the following table are not satisfied.



			≤ 3 GHz	> 3 GHz	
Maximum distance from (geometric center of pro		•	In turface $5 \pm 1 \text{ mm}$ $\frac{1}{2} \cdot 5 \cdot \ln(2) \pm 0.5 \text{ mm}$ Solution of the surface $30^{\circ} \pm 1^{\circ}$ $20^{\circ} \pm 1^{\circ}$ $ \leq 2 \text{ GHz} : \leq 15 \text{ mm} \qquad 3 - 4 \text{ GHz} : \leq 12 \text{ mm}$ $ 2 - 3 \text{ GHz} : \leq 12 \text{ mm} \qquad 4 - 6 \text{ GHz} : \leq 10 \text{ mm}$ When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be \leq the corresponding x or y dimension of the test device with at least one measurement point on the test device. $ \leq 2 \text{ GHz} : \leq 8 \text{ mm} \qquad 3 - 4 \text{ GHz} : \leq 5 \text{ mm}^* $ $ 2 - 3 \text{ GHz} : \leq 5 \text{ mm}^* \qquad 4 - 6 \text{ GHz} : \leq 4 \text{ mm}^* $ $ \leq 5 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 4 \text{ mm} $ $ \leq 5 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 2 \text{ mm} $ The element 1^{st} and $1 - 4 \text{ GHz} : \leq 2 \text{ mm} $ $ \leq 4 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 2 \text{ mm} $ $ \leq 4 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 2 \text{ mm} $ $ \leq 4 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 2 \text{ mm} $ $ \leq 4 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 2 \text{ mm} $ $ \leq 4 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 2 \text{ mm} $ $ \leq 4 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 2 \text{ mm} $ $ \leq 4 \text{ mm} \qquad 4 - 5 \text{ GHz} : \leq 2 \text{ mm} $		
Maximum probe angle f normal at the measurem			30° ± 1°	20° ± 1°	
				_	
Maximum area scan spa	tial resolutio	on: Δx _{Area} , Δy _{Area}	measurement plane orientation, measurement resolution must b dimension of the test device wit	is smaller than the above, the e the corresponding x or y	
Maximum zoom scan sp	atial resolu	ion: Δx _{Zoom} , Δy _{Zoom}		_	
	uniform g	nid: Δz _{Zoom} (n)	≤ 5 mm	4 – 5 GHz: ≤ 3 mm	
Maximum zoom scan spatial resolution, normal to phantom surface	graded	Δz _{Zoom} (1): between 1 st two points closest to phantom surface	≤ 4 mm	4 – 5 GHz: ≤ 2.5 mm	
surace	grid	Δz _{Zoom} (n>1): between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$		
Minimum zoom scan volume	x, y, z	1	≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm	

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details

9.3 Power Drift

To control the output power stability during the SAR test, DASY4 system calculates the power drift by measuring the E-field at the same location at the beginning and at the end of the measurement for each test position. These drift values can be found in Table 12.2 to Table 12.13 labeled as: (Power Drift [dB]). This ensures that the power drift during one measurement is within 5%.

When zoom scan is required and the <u>reported</u> SAR from the area scan based 1-g SAR estimation procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.



10 Area Scan Based 1-g SAR

10.1 Requirement of KDB

According to the KDB447498 D01 v05, when the implementation is based the specific polynomial fit algorithm as presented at the 29th Bioelectromagnetics Society meeting (2007) and the estimated 1-g SAR is \leq 1.2 W/kg, a zoom scan measurement is not required provided it is also not needed for any other purpose; for example, if the peak SAR location required for simultaneous transmission SAR test exclusion can be determined accurately by the SAR system or manually to discriminate between distinctive peaks and scattered noisy SAR distributions from area scans.

There must not be any warning or alert messages due to various measurement concerns identified by the SAR system; for example, noise in measurements, peaks too close to scan boundary, peaks are too sharp, spatial resolution and uncertainty issues etc. The SAR system verification must also demonstrate that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR (See Annex B). When all the SAR results for each exposure condition in a frequency band and wireless mode are based on estimated 1-g SAR, the 1-g SAR for the highest SAR configuration must be determined by a zoom scan.

10.2 Fast SAR Algorithms

The approach is based on the area scan measurement applying a frequency dependent attenuation parameter. This attenuation parameter was empirically determined by analyzing a large number of phones. The MOTOROLA FAST SAR was developed and validated by the MOTOROLA Research Group in Ft. Lauderdale.

In the initial study, an approximation algorithm based on Linear fit was developed. The accuracy of the algorithm has been demonstrated across a broad frequency range (136-2450 MHz) and for both 1- and 10-g averaged SAR using a sample of 264 SAR measurements from 55 wireless handsets. For the sample size studied, the root-mean-squared errors of the algorithm are 1.2% and 5.8% for 1- and 10-g averaged SAR, respectively. The paper describing the algorithm in detail is expected to be published in August 2004 within the Special Issue of Transactions on MTT.

In the second step, the same research group optimized the fitting algorithm to an Polynomial fit whereby the frequency validity was extended to cover the range 30-6000MHz. Details of this study can be found in the BEMS 2007 Proceedings.

Both algorithms are implemented in DASY software.



11 Conducted Output Power

11.1 Manufacturing tolerance

Table 11.1: GSM Speech

	GSM 850									
Channel	Channel 251	Channel 190	Channel 128							
Target (dBm)	32.3	32.3	32.3							
Tolerance \pm (dB)	1	1	1							
	GSM	1 1900								
Channel	Channel 810	Channel 661	Channel 512							
Target (dBm)	29.3	29.3	29.3							
Tolerance \pm (dB)	1	1	1							

Table 11.2: GPRS

		Table 11.2: GPR	3	
		GSM 850 GPRS (GN	MSK)	
	Channel	251	190	128
1 Tyelet	Target (dBm)	32.3	32.3	32.3
1 Txslot	Tolerance \pm (dB)	1	1	1
2 Txslots	Target (dBm)	29.5	29.5	29.5
2 TXSIOIS	Tolerance \pm (dB)	1	1	1
2Tvolete	Target (dBm)	27.5	27.5	27.5
3Txslots	Tolerance \pm (dB)	1	1	1
4 Tyoloto	Target (dBm)	26.5	26.5	26.5
4 Txslots	Tolerance \pm (dB)	1	1	1
		GSM 1900 GPRS (GI	MSK)	
	Channel	810	661	512
1 Txslot	Target (dBm)	29.3	29.3	29.3
1 1 XSIOL	Tolerance \pm (dB)	1	1	1
2 Typloto	Target (dBm)	27	27	27
2 Txslots	Tolerance \pm (dB)	1	1	1
2Tvoloto	Target (dBm)	25	25	25
3Txslots	Tolerance \pm (dB)	1	1	1
4 Txslots	Target (dBm)	24	24	24
4 1 XSIU(S	Tolerance \pm (dB)	1	1	1



11.2 GSM Measurement result

During the process of testing, the EUT was controlled via Agilent Digital Radio Communication tester (E5515C) to ensure the maximum power transmission and proper modulation. This result contains conducted output power for the EUT. In all cases, the measured peak output power should be greater and within 5% than EMI measurement.

Table 11.3: The conducted power measurement results for GSM850/1900

	•								
GSM — 850MHz —	Conducted Power (dBm)								
	Channel 251(848.8MHz)	Channel 190(836.6MHz)	Channel 128(824.2MHz)						
	32.26	32.24	32.22						
CCM	Conducted Power (dBm)								
GSM 1900MHz	Channel 810(1909.8MHz)	Channel 661(1880MHz)	Channel 512(1850.2MHz)						
I 900IVITZ	29.23	29.19	29.14						

Table 11.4: The conducted power measurement results for GPRS

GSM 850	Measi	ıred Power	(dBm)	calculation	Avera	ged Power	(dBm)	
GPRS (GMSK)	251	190	128		251	190	128	
1 Txslot	32.27	32.25	32.21	-9.03dB	23.24	23.22	23.18	
2 Txslots	29.45	29.44	29.48	-6.02dB	23.43	23.42	23.46	
3Txslots	27.41	27.43	27.48	-4.26dB	23.15	23.17	23.22	
4 Txslots	26.48	26.53	26.62	-3.01dB	23.47	23.52	23.61	
PCS1900	Measi	ured Power	(dBm)	calculation	Averaged Power (dBm)			
GPRS (GMSK)	810	661	512		810	661	512	
1 Txslot	29.24	29.20	29.14	-9.03dB	20.21	20.17	20.11	
2 Txslots	27.07	27.03	26.98	-6.02dB	21.05	21.01	20.96	
3Txslots	25.24	25.18	25.10	-4.26dB	20.98	20.92	20.84	

NOTES:

To average the power, the division factor is as follows:

1TX-slot = 1 transmit time slot out of 8 time slots=> conducted power divided by (8/1) => -9.03dB

2TX-slots = 2 transmit time slots out of 8 time slots=> conducted power divided by (8/2) => -6.02dB

3TX-slots = 3 transmit time slots out of 8 time slots=> conducted power divided by (8/3) => -4.26dB

4TX-slots = 4 transmit time slots out of 8 time slots=> conducted power divided by (8/4) => -3.01dB

According to the conducted power as above, the body measurements are performed with 4Txslots for GPRS.

¹⁾ Division Factors



12 SAR Test Result

It is determined by user manual for the distance between the EUT and the phantom bottom.

The distance is 10mm and just applied to the condition of body worn accessory.

It is performed for all SAR measurements with area scan based 1-g SAR estimation (Fast SAR). A zoom scan measurement is added when the estimated 1-g SAR is the highest measured SAR in each exposure configuration, wireless mode and frequency band combination or more than 1.2W/kg.

The calculated SAR is obtained by the following formula:

Reported SAR = Measured SAR $\times 10^{(P_{Target}-P_{Measured})/10}$

Where P_{Target} is the power of manufacturing upper limit;

P_{Measured} is the measured power in chapter 11.

Table 12.1: Duty Cycle

Mode	Duty Cycle
Speech for GSM850/1900	1:8.3
GPRS for GSM850/1900	1:2

12.1 The evaluation of multi-batteries

We'll perform the head measurement in all bands with the primary battery depending on the evaluation of multi-batteries and retest on highest value point with other batteries. Then, repeat the measurement in the Body test.

Table 12.2: The evaluation of multi-batteries for Head Test

Freque	ency	Side	Test	Patton, Type	SAR(1g)	Power	
MHz	Ch.	Side	Position	Battery Type	(W/kg)	Drift(dB)	
1880	661	Right	Touch	CAB22D0000C1	0.783	0.14	
1880	661	Right	Touch	CAB30M0000C2	0.741	0.04	

Note: According to the values in the above table, the battery, CAB22D0000C1, is the primary battery. We'll perform the head measurement with this battery and retest on highest value point with others.

Table 12.3: The evaluation of multi-batteries for Body Test

Freq	uency	Mode	Test	Spacing	Pottony Typo	SAR(1g)	Power
MHz	Ch.	wode	Position	(mm)	Battery Type	(W/kg)	Drift(dB)
848.8	251	GPRS	Rear	10	CAB22D0000C1	0.918	-0.06
848.8	251	GPRS	Rear	10	CAB30M0000C2	0.917	-0.05

Note: According to the values in the above table, the battery, CAB22D0000C1, is the primary battery. We'll perform the Body measurement with this battery and retest on highest value point with others.



12.2 SAR results for Fast SAR

Table 12.4: SAR Values (GSM 850 MHz Band - Head) with battery CAB22D0000C1

				Ambient	Temperature:	22.5°C L	iquid Tempera	ture: 22.0 °C			
Frequ	ency		Test	Figure	Conducted	Max. tune-up	Measured	Reported	Measured	Reported	Power
	1	Side			Power		SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)	Drift
MHz	Ch.		Position	No.	(dBm)	Power (dBm)	(W/kg)	(W/kg)	(W/kg)	(W/kg)	(dB)
848.8	251	Left	Touch	/	32.26	33.3	0.344	0.44	0.467	0.59	-0.04
836.6	190	Left	Touch	Fig.1	32.24	33.3	0.447	0.57	0.604	0.77	-0.08
824.2	128	Left	Touch	/	32.22	33.3	0.331	0.42	0.446	0.57	-0.07
848.8	251	Left	Tilt	/	32.26	33.3	0.200	0.25	0.290	0.37	-0.03
836.6	190	Left	Tilt	/	32.24	33.3	0.199	0.25	0.288	0.37	0.01
824.2	128	Left	Tilt	/	32.22	33.3	0.195	0.25	0.281	0.36	-0.02
848.8	251	Right	Touch	/	32.26	33.3	0.396	0.50	0.547	0.70	-0.11
836.6	190	Right	Touch	/	32.24	33.3	0.370	0.47	0.510	0.65	-0.17
824.2	128	Right	Touch	/	32.22	33.3	0.368	0.47	0.506	0.65	-0.04
848.8	251	Right	Tilt	1	32.26	33.3	0.190	0.24	0.277	0.35	-0.03
836.6	190	Right	Tilt	1	32.24	33.3	0.180	0.23	0.261	0.33	-0.00
824.2	128	Right	Tilt	1	32.22	33.3	0.185	0.24	0.270	0.35	-0.00

Table 12.5: SAR Values (GSM 850 MHz Band - Body) with battery CAB22D0000C1

	Ambient Temperature: 22.5 °C Liquid Temperature: 22.0 °C												
Frequ	requency Mode Te		Test	Test Figure		Max. tune-up	Measured	Reported	Measured	Reported	Power		
		(number of		•	Power	•	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)	Drift		
MHz	Ch.	timeslots)	Position	No.	(dBm)	Power (dBm)	(W/kg)	(W/kg)	(W/kg)	(W/kg)	(dB)		
848.8	251	GPRS (4)	Front	1	26.48	27.5	0.505	0.64	0.682	0.86	0.03		
836.6	190	GPRS (4)	Front	/	26.53	27.5	0.442	0.55	0.641	0.80	-0.00		
824.2	128	GPRS (4)	Front	/	26.62	27.5	0.581	0.71	0.401	0.49	0.06		
848.8	251	GPRS (4)	Rear	Fig.2	26.48	27.5	0.648	0.82	0.918	1.16	-0.06		
836.6	190	GPRS (4)	Rear	/	26.53	27.5	0.597	0.75	0.847	1.06	-0.02		
824.2	128	GPRS (4)	Rear	/	26.62	27.5	0.526	0.64	0.772	0.95	-0.02		
848.8	251	Chaach	Rear	,	32.26	33.3	0.349	0.44	0.511	0.65	0.04		
048.8	201	Speech	Headset1	/	32.20	აა.ა	0.349	0.44	0.511	0.00	0.04		
040 0	251	Speech	Rear	,	22.26	22.2	0.254	0.45	0.524	0.67	0.02		
848.8	201	Speech	Headset2	/	32.26	33.3	0.354	0.45	0.524	0.67	0.03		

Note1: The distance between the EUT and the phantom bottom is 10mm.

Note2: The type of Headset1 is CCB3160A15C1, the type of Headset2 is CCB3160A15C2.



Table 12.6: SAR Values (GSM 1900 MHz Band - Head) with battery CAB22D0000C1

				Ambient	Temperature:	22.6 °C L	iquid Tempera	ture: 22.1 °C			
Freque	ency		Test	Eiguro	Conducted	May tupo up	Measured	Reported	Measured	Reported	Power
	_	Side	Position	Figure	Power	Max. tune-up	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)	Drift
MHz	Ch.		Position	No.	(dBm)	Power (dBm)	(W/kg)	(W/kg)	(W/kg)	(W/kg)	(dB)
1909.8	810	Left	Touch	/	29.23	30.3	0.218	0.28	0.383	0.49	-0.14
1880	661	Left	Touch	/	29.19	30.3	0.253	0.33	0.432	0.56	0.09
1850.2	512	Left	Touch	/	29.14	30.3	0.287	0.37	0.472	0.62	-0.11
1909.8	810	Left	Tilt	/	29.23	30.3	0.101	0.13	0.174	0.22	0.03
1880	661	Left	Tilt	/	29.19	30.3	0.133	0.17	0.227	0.29	0.09
1850.2	512	Left	Tilt	/	29.14	30.3	0.132	0.17	0.224	0.29	0.05
1909.8	810	Right	Touch	/	29.23	30.3	0.352	0.45	0.658	0.84	-0.19
1880	661	Right	Touch	Fig.3	29.19	30.3	0.437	0.56	0.783	1.01	0.14
1850.2	512	Right	Touch	/	29.14	30.3	0.389	0.51	0.718	0.94	-0.11
1909.8	810	Right	Tilt	/	29.23	30.3	0.098	0.13	0.165	0.21	-0.01
1880	661	Right	Tilt	1	29.19	30.3	0.133	0.17	0.224	0.29	-0.03
1850.2	512	Right	Tilt	1	29.14	30.3	0.141	0.18	0.237	0.31	-0.08

Table 12.7: SAR Values (GSM 1900 MHz Band - Body) with battery CAB22D0000C1

			Ambi	ent Tempe	erature: 22.6 °C	C Liquid To	emperature: 2	22.1°C			
Freque	ency	Mode (number of	Test	Figure	Conducted Power	Max. tune-up	Measured SAR(10g)	Reported SAR(10g)	Measured SAR(1g)	Reported SAR(1g)	Power Drift
MHz	Ch.	timeslots)	Position	No.	(dBm)	Power (dBm)	(W/kg)	(W/kg)	(W/kg)	(W/kg)	(dB)
1909.8	810	GPRS (4)	Front	1	24.23	25	0.240	0.29	0.404	0.48	-0.00
1880	661	GPRS (4)	Front	/	24.17	25	0.294	0.36	0.477	0.58	0.02
1850.2	512	GPRS (4)	Front	/	24.10	25	0.284	0.35	0.475	0.58	-0.04
1909.8	810	GPRS (4)	Rear	/	24.23	25	0.300	0.36	0.529	0.63	0.02
1880	661	GPRS (4)	Rear	Fig.4	24.17	25	0.375	0.45	0.624	0.76	0.01
1850.2	512	GPRS (4)	Rear	/	24.10	25	0.286	0.35	0.499	0.61	-0.01
1880	661	Speech	Rear Headset1	1	29.19	30.3	0.294	0.38	0.513	0.66	0.04
1880	661	Speech	Rear Headset2	/	29.19	30.3	0.283	0.37	0.472	0.61	0.03

Note1: The distance between the EUT and the phantom bottom is 10mm.

Note2: The type of Headset1 is CCB3160A15C1, the type of Headset2 is CCB3160A15C2.



Table 12.8: SAR Values (GSM 1900 MHz Band - Head) with battery CAB30M0000C2

				Ambient	Temperature:	22.6 °C L	iquid Tempera	ture: 22.1 °C			
Freque	ency	Cido	Test	Figure	Conducted Power	Max. tune-up	Measured	Reported	Measured	Reported	Power Drift
MHz	Ch.	Side	Position	No.	(dBm)	Power (dBm)	SAR(10g) (W/kg)	SAR(10g) (W/kg)	SAR(1g) (W/kg)	SAR(1g) (W/kg)	(dB)
1880	661	Right	Touch	1	29.19	30.3	0.417	0.54	0.741	0.96	0.04

Table 12.9: SAR Values (GSM 850 MHz Band - Body) with battery CAB30M0000C2

			Aı	mbient Te	mperature: 22	5°C Liqui	id Temperature	e: 22.0 °C			
Frequ	encv	Mode	Test	Figure	Conducted	Max. tune-up	Measured	Reported	Measured	Reported	Power
	,	(number of			Power		SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)	Drift
MHz	Ch.	timeslots)	Position	No.	(dBm)	Power (dBm)	(W/kg)	(W/kg)	(W/kg)	(W/kg)	(dB)
848.8	251	GPRS (4)	Rear	1	26.48	27.5	0.645	0.82	0.917	1.16	-0.05

Note1: The distance between the EUT and the phantom bottom is 10mm.



12.3 SAR results for Standard procedure

There is zoom scan measurement to be added for the highest measured SAR in each exposure configuration/band.

Table 12.10: SAR Values (GSM 850 MHz Band - Head) with battery CAB22D0000C1

				Ambient	Temperature	: 22.5°C L	iquid Tempera	ture: 22.0 °C			
Frequ	ency		Test	Figure	Conducted	Max. tune-up	Measured	Reported	Measured	Reported	Power
		Side			Power	· ·	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)	Drift
MHz	Ch.		Position	No.	(dBm)	Power (dBm)	(W/kg)	(W/kg)	(W/kg)	(W/kg)	(dB)
836.6	190	Left	Touch	Fig.1	32.24	33.3	0.447	0.57	0.604	0.77	-0.08

Table 12.11: SAR Values (GSM 850 MHz Band - Body) with battery CAB22D0000C1

			A	mbient Te	mperature: 22	5°C Liqui	id Temperature	e: 22.0 °C			
Frequ	encv	Mode	Test	Liguro	Conducted	May tune un	Measured	Reported	Measured	Reported	Power
		(number of		Figure	Power	Max. tune-up	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)	Drift
MHz	Ch.	timeslots)	Position	No.	(dBm)	Power (dBm)	(W/kg)	(W/kg)	(W/kg)	(W/kg)	(dB)
848.8	251	GPRS (4)	Rear	Fig.2	26.48	27.5	0.648	0.82	0.918	1.16	-0.06

Note1: The distance between the EUT and the phantom bottom is 10mm.

Table 12.12: SAR Values (GSM 1900 MHz Band - Head) with battery CAB22D0000C1

				Ambient	Temperature:	22.6 °C L	iquid Tempera	ture: 22.1 °C			
Freque	ency		Test	Figure	Conducted	Max. tune-up	Measured	Reported	Measured	Reported	Power
NAL 1-	Ch	Side	Position	No.	Power	Power (dBm)	SAR(10g)	SAR(10g)	SAR(1g)	SAR(1g)	Drift
MHz	Ch.				(dBm)	,	(W/kg)	(W/kg)	(W/kg)	(W/kg)	(dB)
1880	661	Right	Touch	Fig.3	29.19	30.3	0.437	0.56	0.783	1.01	0.14

Table 12.13: SAR Values (GSM 1900 MHz Band - Body) with battery CAB22D0000C1

			Ambie	ent Tempe	erature: 22.6°	C Liquid T	emperature: 2	22.1°C			
Frequ MHz	ency Ch.	Mode (number of timeslots)	Test Position	Figure No.	Conducted Power (dBm)	Max. tune-up Power (dBm)	Measured SAR(10g) (W/kg)	Reported SAR(10g) (W/kg)	Measured SAR(1g) (W/kg)	Reported SAR(1g) (W/kg)	Power Drift (dB)
1880	661	GPRS (4)	Rear	Fig.4	24.17	25	0.375	0.45	0.624	0.76	0.01

Note1: The distance between the EUT and the phantom bottom is 10mm.



13 SAR Measurement Variability

SAR measurement variability must be assessed for each frequency band, which is determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media are required for SAR measurements in a frequency band, the variability measurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium.

The following procedures are applied to determine if repeated measurements are required.

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps 2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg (~ 10% from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

Table 13.1: SAR Measurement Variability for Body GSM 850 (1g)

Freque	ency	Test	Spacing	Original	First	The	Second
MHz	Ch.	Position	(mm)	SAR (W/kg)	Repeated SAR (W/kg)	Ratio	Repeated SAR (W/kg)
848.8	251	Rear	10	0.918	0.917	1.00	1



14 Measurement Uncertainty

14.1 Measurement Uncertainty for Normal SAR Tests (300MHz~3GHz)

i Measurement Oi	icerta	inity for No	milai SAR	resis	(SUUI	VITZ~	ЗОПА)	
Error Description	Type	Uncertainty	Probably	Div.	(Ci)	(Ci)	Std.	Std.	Degree
		value	Distribution		1g	10g	Unc.	Unc.	of
							(1g)	(10g)	freedo
									m
surement system									
Probe calibration	В	5.5	N	1	1	1	5.5	5.5	∞
Isotropy	В	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	∞
Boundary effect	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
Linearity	В	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
Detection limit	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	∞
Response time	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	∞
RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	0	0	∞
RF ambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	0	0	∞
Probe positioned mech. restrictions	В	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	∞
Probe positioning with respect to phantom shell	В	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞
Post-processing	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
		Test	sample related	i					
Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71
Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
		Phan	tom and set-u	p					
Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞
Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
Liquid conductivity (meas.)	A	2.06	N	1	0.64	0.43	1.32	0.89	43
Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞
Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521
	Error Description Surement system Probe calibration Isotropy Boundary effect Linearity Detection limit Readout electronics Response time Integration time RF ambient conditions-noise RF ambient conditions-reflection Probe positioned mech. restrictions Probe positioning with respect to phantom shell Post-processing Test sample positioning with respect to phantom shell Post-processing Test sample positioning Device holder uncertainty Drift of output power Phantom uncertainty Liquid conductivity (target) Liquid permittivity (target) Liquid permittivity (target)	Error Description Surement system Probe calibration Bushing probe cal	Surement system Probe calibration B 5.5 Isotropy B 4.7 Boundary effect B 1.0 Linearity B 4.7 Detection limit B 1.0 Readout electronics B 0.3 Response time B 0.8 Integration time B 2.6 RF ambient conditions-noise B 0.8 RF ambient conditions-reflection B 0.4 Probe positioned mech. restrictions B 0.4 Probe positioning with respect to phantom shell B 0.9 Post-processing B 1.0 Test sample positioning B 1.0 Test sample positioning B 1.0 Probe positioning B 1.0 Test sample positioning B 1.0 Test sample positioning B 1.0 Probe positioning B 1.0 Test sample positioning B 1.0 Liquid conductivity (arget) B 1.0 Liquid conductivity (target) B 1.0 Liquid permittivity (target) B 1.0	Error Description Type Uncertainty value Distribution Surement system Probe calibration B 5.5 N Isotropy B 4.7 R Boundary effect B 1.0 R Linearity B 4.7 R Detection limit B 1.0 R Readout electronics B 0.3 R Response time B 0.8 R Integration time B 2.6 R RF ambient conditions-noise B 0.3 R RF ambient conditions-reflection B 0.4 R Probe positioned mech. restrictions B 0.4 R Probe positioning with respect to phantom shell Post-processing B 1.0 R Test sample positioning B 1.0 R Test sample related b 1.0 R Test sample positioning B 1.0 R Test sample related b 1.	Error Description Type Uncertainty value Probably Distribution Div.	Error Description Type Uncertainty value Probably Distribution Ig Ig	Type Uncertainty Probably Distribution Div. C(i) 10g 10g	Type	Probe Prob



Combined standard uncertainty	$u_{c}' = \sqrt{\sum_{i=1}^{21} c_{i}^{2} u_{i}^{2}}$			9.25	9.12	257
Expanded uncertainty (confidence interval of 95 %)	$u_e = 2u_c$			18.5	18.2	

14.2 Measurement Uncertainty for Normal SAR Tests (3~6GHz)

14.	<u> 2 Measurement Ui</u>	ncerta	iinty for No	rmai SAR	iests	(3~6)	ظHZ)			
No.	Error Description	Type	Uncertainty	Probably	Div.	(Ci)	(Ci)	Std.	Std.	Degree
			value	Distribution		1g	10g	Unc.	Unc.	of
								(1g)	(10g)	freedo
										m
Mea	surement system									
1	Probe calibration	В	6.5	N	1	1	1	6.5	6.5	8
2	Isotropy	В	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	8
3	Boundary effect	В	2.0	R	$\sqrt{3}$	1	1	1.2	1.2	8
4	Linearity	В	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	8
5	Detection limit	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	8
6	Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	8
7	Response time	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	8
8	Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	8
9	RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	0	0	8
10	RF ambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	0	0	8
11	Probe positioned mech. restrictions	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	8
12	Probe positioning with respect to phantom shell	В	6.7	R	$\sqrt{3}$	1	1	3.9	3.9	8
13	Post-processing	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	8
			Test	sample related	ì					
14	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71
15	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
16	Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	8
			Phan	tom and set-u	p					
17	Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	8
18	Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	8
19	Liquid conductivity (meas.)	A	2.06	N	1	0.64	0.43	1.32	0.89	43



20	Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞
21	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521
(Combined standard uncertainty	$u_c^{'} =$	$\sqrt{\sum_{i=1}^{21} c_i^2 u_i^2}$					10.8	10.7	257
_	inded uncertainty fidence interval of	ı	$u_e = 2u_c$					21.6	21.4	

14.3 Measurement Uncertainty for Fast SAR Tests (300MHz~3GHz)

No.	Error Description	Type		Probably	Div.	(Ci)	(Ci)	Std.	Std.	Degree	
			value	Distribution		1g	10g	Unc.	Unc.	of	
								(1g)	(10g)	freedo	
										m	
Mea	Measurement system										
1	Probe calibration	В	5.5	N	1	1	1	5.5	5.5	∞	
2	Isotropy	В	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	∞	
3	Boundary effect	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞	
4	Linearity	В	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞	
5	Detection limit	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞	
6	Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	∞	
7	Response time	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞	
8	Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	∞	
9	RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	0	0	∞	
10	RF ambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	0	0	∞	
11	Probe positioned mech. Restrictions	В	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	∞	
12	Probe positioning with respect to phantom shell	В	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	88	
13	Post-processing	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞	
14	Fast SAR z-Approximation	В	7.0	R	$\sqrt{3}$	1	1	4.0	4.0	∞	
Test sample related											
15	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71	
16	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5	
17	Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞	



	Phantom and set-up									
18	Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	8
19	Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	8
20	Liquid conductivity (meas.)	A	2.06	N	1	0.64	0.43	1.32	0.89	43
21	Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	8
22	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521
(Combined standard uncertainty	$u_c^{'} =$	$\sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$					10.1	9.95	257
Expanded uncertainty (confidence interval of 95 %)		ı	$u_e = 2u_c$					20.2	19.9	

14.4 Measurement Uncertainty for Fast SAR Tests (3~6GHz)

No.	Error Description	Type	Uncertainty	Probably	Div.	(Ci)	(Ci)	Std.	Std.	Degree	
			value	Distribution		1g	10g	Unc.	Unc.	of	
								(1g)	(10g)	freedo	
										m	
Mea	Measurement system										
1	Probe calibration	В	6.5	N	1	1	1	6.5	6.5	8	
2	Isotropy	В	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	8	
3	Boundary effect	В	2.0	R	$\sqrt{3}$	1	1	1.2	1.2	8	
4	Linearity	В	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	8	
5	Detection limit	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	8	
6	Readout electronics	В	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	8	
7	Response time	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	8	
8	Integration time	В	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	8	
9	RF ambient conditions-noise	В	0	R	$\sqrt{3}$	1	1	0	0	8	
10	RF ambient conditions-reflection	В	0	R	$\sqrt{3}$	1	1	0	0	8	
11	Probe positioned mech. Restrictions	В	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	8	
12	Probe positioning with respect to phantom shell	В	6.7	R	$\sqrt{3}$	1	1	3.9	3.9	&	
13	Post-processing	В	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	8	
14	Fast SAR z-Approximation	В	14.0	R	$\sqrt{3}$	1	1	8.1	8.1	∞	



	Test sample related									
15	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71
16	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
17	Drift of output power	В	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	8
			Phan	tom and set-uj	p					
18	Phantom uncertainty	В	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	8
19	Liquid conductivity (target)	В	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	8
20	Liquid conductivity (meas.)	A	2.06	N	1	0.64	0.43	1.32	0.89	43
21	Liquid permittivity (target)	В	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	8
22	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521
Combined standard uncertainty		$u_c^{'} =$	$\sqrt{\sum_{i=1}^{22} c_i^2 u_i^2}$					13.3	13.2	257
_	nded uncertainty idence interval of	ι	$u_e = 2u_c$					26.6	26.4	

15 MAIN TEST INSTRUMENTS

Table 15.1: List of Main Instruments

No.	Name	Туре	Serial Number	Calibration Date	Valid Period	
01	Network analyzer	E5071C	MY46110673	February 15, 2013	One year	
02	Power meter	NRVD	102083	Contombor 11, 2012	One year	
03	Power sensor	NRV-Z5	100542	September 11, 2012	One year	
04	Signal Generator	E4438C	MY49070393	November 13, 2012	One Year	
05	Amplifier	60S1G4	0331848	No Calibration Requested		
06	BTS	E5515C	MY48363198	July 11, 2012	One year	
07	E-field Probe	SPEAG ES3DV3	3149	April 24, 2012	One year	
08	E-field Probe	SPEAG EX3DV4	3846	December 20, 2012	One year	
09	DAE	SPEAG DAE4	771	November 20, 2012	One year	
10	Dipole Validation Kit	SPEAG D835V2	443	May 03, 2012	One year	
11	Dipole Validation Kit	SPEAG D1900V2	541	May 09, 2012	One year	

^{***}END OF REPORT BODY***



ANNEX A G raph Results

850 Left Cheek Middle

Date: 2013-4-11

Electronics: DAE4 Sn771 Medium: Head 850 MHz

Medium parameters used (interpolated): f = 836.6 MHz; $\sigma = 0.91$ mho/m; $\epsilon r = 41.991$; $\rho =$

 1000 kg/m^3

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C

Communication System: GSM 850 Frequency: 836.6 MHz Duty Cycle: 1:8.3

Probe: ES3DV3 - SN3149 ConvF(6.26, 6.26, 6.26)

Cheek Middle/Area Scan (61x91x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.634 W/kg

Cheek Middle/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 9.117 V/m; Power Drift = -0.08 dB

Peak SAR (extrapolated) = 0.744 W/kg

SAR(1 g) = 0.604 W/kg; SAR(10 g) = 0.447 W/kg

Maximum value of SAR (measured) = 0.642 W/kg

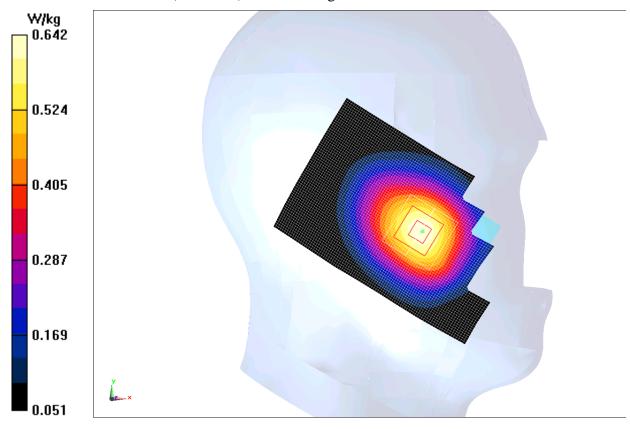


Fig.1 850MHz CH190



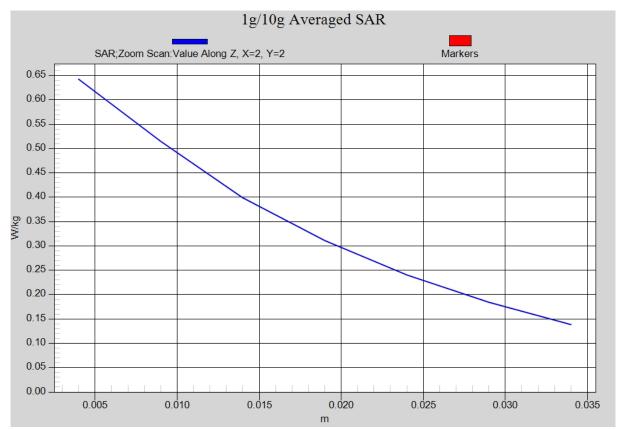


Fig. 1-1 Z-Scan at power reference point (850 MHz CH190)



850 Body Rear High

Date: 2013-4-11

Electronics: DAE4 Sn771 Medium: Body 850 MHz

Medium parameters used (interpolated): f = 848.8 MHz; $\sigma = 0.997$ mho/m; $\epsilon r = 56.019$; $\rho =$

 1000 kg/m^3

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C

Communication System: GSM 850 GPRS Frequency: 848.8 MHz Duty Cycle: 1:2

Probe: ES3DV3 - SN3149 ConvF(6.14, 6.14, 6.14)

Rear High/Area Scan (61x101x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.963 W/kg

Rear High/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 24.587 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 1.24 W/kg

SAR(1 g) = 0.918 W/kg; SAR(10 g) = 0.648 W/kg

Maximum value of SAR (measured) = 0.974 W/kg

Rear High/Zoom Scan (7x7x7)/Cube 1: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 24.587 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 1.17 W/kg

SAR(1 g) = 0.762 W/kg; SAR(10 g) = 0.512 W/kg

Maximum value of SAR (measured) = 0.843 W/kg

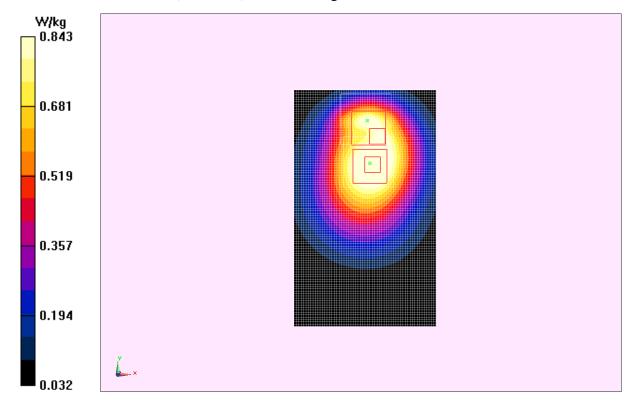


Fig.2 850 MHz CH251



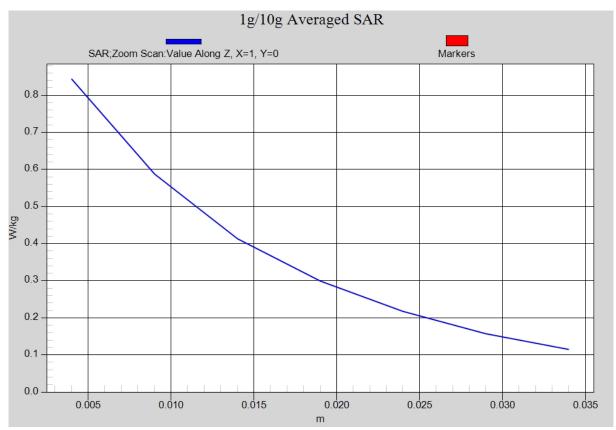


Fig. 2-1 Z-Scan at power reference point (850 MHz CH251)



1900 Right Cheek Middle

Date: 2013-4-12

Electronics: DAE4 Sn771 Medium: Head 1900 MHz

Medium parameters used: f = 1880 MHz; $\sigma = 1.399 \text{ mho/m}$; $\epsilon r = 40.618$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C

Communication System: GSM 1900MHz Frequency: 1880 MHz Duty Cycle: 1:8.3

Probe: ES3DV3 - SN3149 ConvF(5.19, 5.19, 5.19)

Cheek Middle/Area Scan (61x91x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 0.896 W/kg

Cheek Middle/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 8.485 V/m; Power Drift = 0.14 dB

Peak SAR (extrapolated) = 1.30 W/kg

SAR(1 g) = 0.783 W/kg; SAR(10 g) = 0.437 W/kg

Maximum value of SAR (measured) = 0.868 W/kg

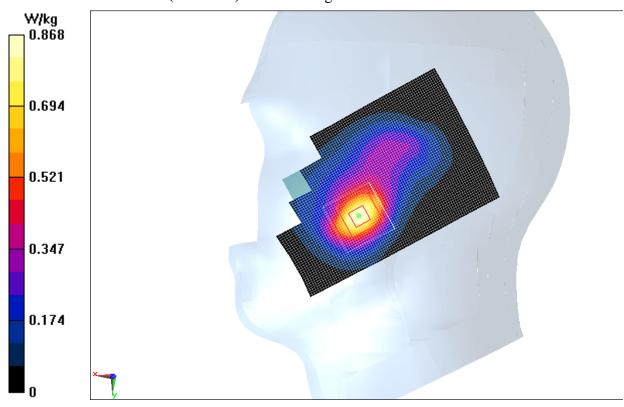


Fig.3 1900 MHz CH661



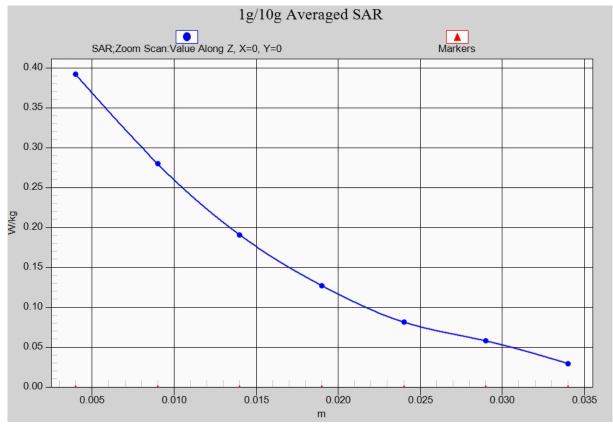


Fig. 3-1 Z-Scan at power reference point (1900 MHz CH661)



1900 Body Rear Middle

Date: 2013-4-12

Electronics: DAE4 Sn771 Medium: Body 1900 MHz

Medium parameters used: f = 1880 MHz; $\sigma = 1.515 \text{ mho/m}$; $\epsilon r = 52.972$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C

Communication System: GSM 1900MHz GPRS Frequency: 1880 MHz Duty Cycle: 1:2

Probe: ES3DV3 - SN3149 ConvF(4.64, 4.64, 4.64)

Rear Middle/Area Scan (61x101x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm Maximum value of SAR (interpolated) = 0.711 W/kg

Rear Middle/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 19.406 V/m; Power Drift = 0.01 dB

Peak SAR (extrapolated) = 0.993 W/kg

SAR(1 g) = 0.624 W/kg; SAR(10 g) = 0.375 W/kg

Maximum value of SAR (measured) = 0.662 W/kg

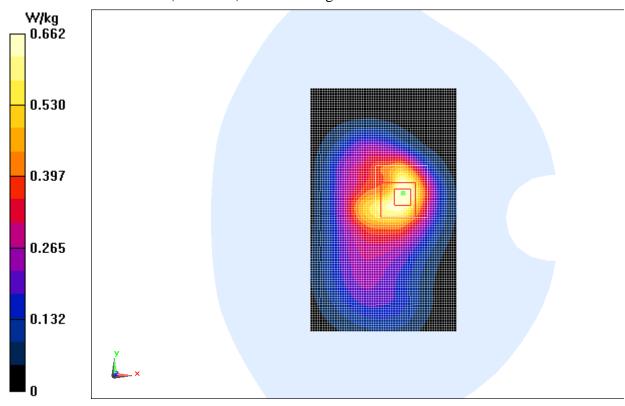


Fig.4 1900 MHz CH661



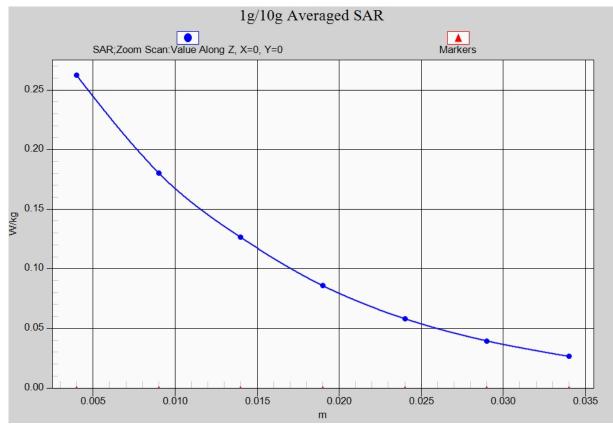


Fig.4-1 Z-Scan at power reference point (1900 MHz CH661)



ANNEX B System Verification Results

835MHz

Date: 2013-4-11

Electronics: DAE4 Sn771 Medium: Head 850 MHz

Medium parameters used: f = 835 MHz; $\sigma = 0.908$ mho/m; $\varepsilon_r = 42.01$; $\rho = 1000$ kg/m³

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C Communication System: CW Frequency: 835 MHz Duty Cycle: 1:1

Probe: ES3DV3 - SN3149 ConvF(6.26, 6.26, 6.26)

System Validation /Area Scan (81x161x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 51.953 V/m; Power Drift = 0.11 dB

Fast SAR: SAR(1 g) = 2.34 W/kg; SAR(10 g) = 1.51 W/kg

Maximum value of SAR (interpolated) = 2.54 W/kg

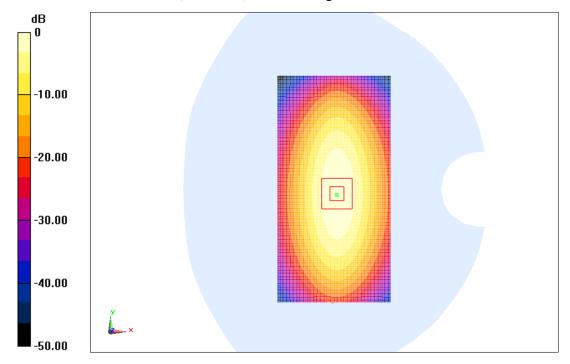
System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 51.953 V/m; Power Drift = 0.11 dB

Peak SAR (extrapolated) = 3.487 W/kg

SAR(1 g) = 2.35 W/kg; SAR(10 g) = 1.51 W/kg

Maximum value of SAR (measured) = 2.54 W/kg



0 dB = 2.54 W/kg = 8.10 dB W/kg

Fig.B.1 validation 835MHz 250mW



Date: 2013-4-11

Electronics: DAE4 Sn771 Medium: Body 850 MHz

Medium parameters used: f = 835 MHz; $\sigma = 0.984$ mho/m; $\varepsilon_r = 55.92$; $\rho = 1000$ kg/m³

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C Communication System: CW Frequency: 835 MHz Duty Cycle: 1:1

Probe: ES3DV3 - SN3149 ConvF(6.14, 6.14, 6.14)

System Validation /Area Scan (81x171x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 45.038 V/m; Power Drift = -0.07 dB

Fast SAR: SAR(1 g) = 2.29 W/kg; SAR(10 g) = 1.53 W/kg

Maximum value of SAR (interpolated) = 2.50 W/kg

System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm,

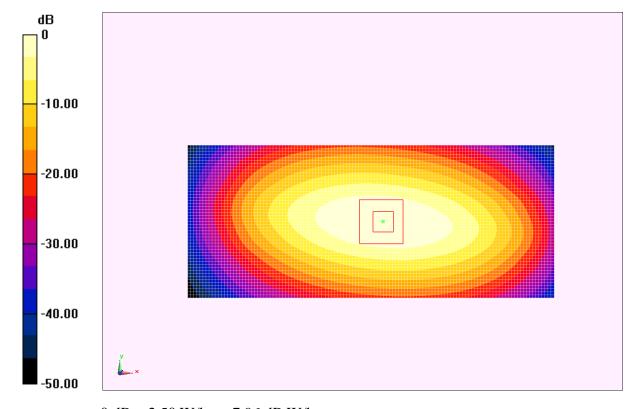
dy=5mm, dz=5mm

Reference Value = 45.038 V/m; Power Drift = -0.07 dB

Peak SAR (extrapolated) = 3.503 W/kg

SAR(1 g) = 2.31 W/kg; SAR(10 g) = 1.55 W/kg

Maximum value of SAR (measured) = 2.51 W/kg



0 dB = 2.50 W/kg = 7.96 dB W/kg

Fig.B.2 validation 835MHz 250mW



Date: 2013-4-12

Electronics: DAE4 Sn771 Medium: Head 1900 MHz

Medium parameters used: f = 1900 MHz; $\sigma = 1.415 \text{ mho/m}$; $\varepsilon_r = 40.61$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C Communication System: CW Frequency: 1900 MHz Duty Cycle: 1:1

Probe: ES3DV3 - SN3149 ConvF(5.19, 5.19, 5.19)

System Validation/Area Scan (81x121x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 94.295 V/m; Power Drift = 0.06 dB

Fast SAR: SAR(1 g) = 9.69 W/kg; SAR(10 g) = 5.10 W/kg

Maximum value of SAR (interpolated) = 11.1 W/kg

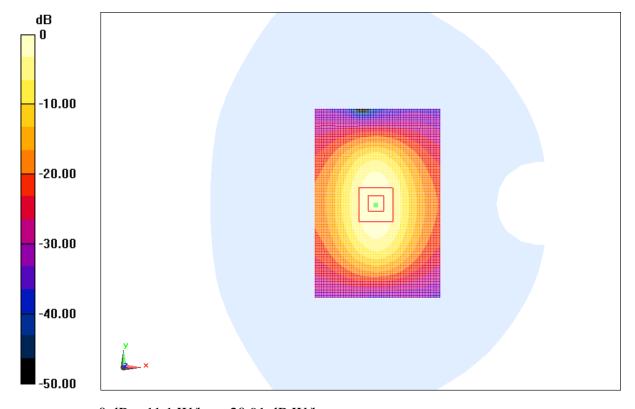
System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 94.295 V/m; Power Drift = 0.06 dB

Peak SAR (extrapolated) = 17.941 W/kg

SAR(1 g) = 9.62 W/kg; SAR(10 g) = 5.05 W/kg

Maximum value of SAR (measured) = 11.0 W/kg



0 dB = 11.1 W/kg = 20.91 dB W/kg

Fig.B.3 validation 1900MHz 250mW



Date: 2013-4-12

Electronics: DAE4 Sn771 Medium: Body 1900 MHz

Medium parameters used: f = 1900 MHz; $\sigma = 1.541 \text{ mho/m}$; $\varepsilon_r = 52.94$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C Communication System: CW Frequency: 1900 MHz Duty Cycle: 1:1

Probe: ES3DV3 - SN3149 ConvF(4.64, 4.64, 4.64)

System Validation/Area Scan (81x121x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 85.076 V/m; Power Drift = -0.06 dB

Fast SAR: SAR(1 g) = 10.0 W/kg; SAR(10 g) = 5.26 W/kg

Maximum value of SAR (interpolated) = 11.5 W/kg

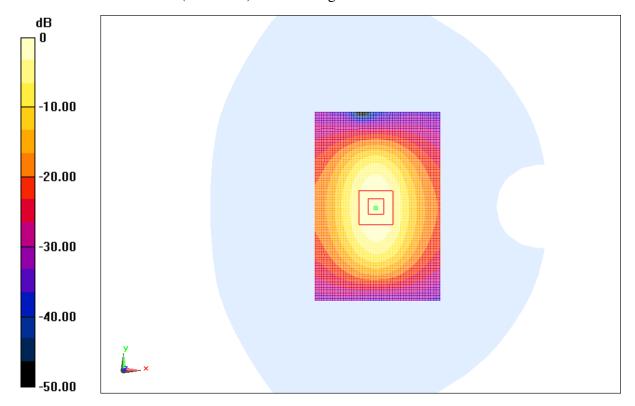
System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 85.076 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 16.6 W/kg

SAR(1 g) = 10.1 W/kg; SAR(10 g) = 5.34 W/kg

Maximum value of SAR (measured) = 11.6 W/kg



0 dB = 11.5 W/kg = 21.21 dB W/kg

Fig.B.4 validation 1900MHz 250mW



Date: 2013-4-26

Electronics: DAE4 Sn771 Medium: Head 850 MHz

Medium parameters used: f = 835 MHz; $\sigma = 0.917$ mho/m; $\varepsilon_r = 40.88$; $\rho = 1000$ kg/m³

Ambient Temperature: 22.8°C Liquid Temperature: 22.3°C Communication System: CW Frequency: 835 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(9.18, 9.18, 9.18)

System Validation /Area Scan (81x161x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 50.748 V/m; Power Drift = -0.08 dB

Fast SAR: SAR(1 g) = 2.31 W/kg; SAR(10 g) = 1.50 W/kg

Maximum value of SAR (interpolated) = 2.49 W/kg

System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm,

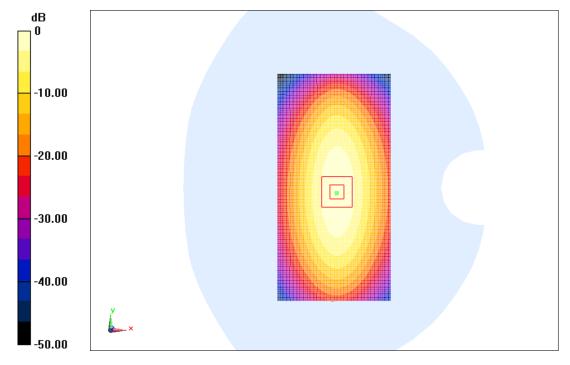
dy=5mm, dz=5mm

Reference Value = 50.748 V/m; Power Drift = -0.08 dB

Peak SAR (extrapolated) = 3.435 W/kg

SAR(1 g) = 2.30 W/kg; SAR(10 g) = 1.49 W/kg

Maximum value of SAR (measured) = 2.49 W/kg



0 dB = 2.49 W/kg = 7.92 dB W/kg

Fig.B.5 validation 835MHz 250mW



Date: 2013-4-26

Electronics: DAE4 Sn771 Medium: Body 850 MHz

Medium parameters used: f = 835 MHz; $\sigma = 0.979$ mho/m; $\varepsilon_r = 55.01$; $\rho = 1000$ kg/m³

Ambient Temperature: 22.8°C Liquid Temperature: 22.3°C Communication System: CW Frequency: 835 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(9.04, 9.04, 9.04)

System Validation /Area Scan (81x171x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 45.969 V/m; Power Drift = -0.10 dB

Fast SAR: SAR(1 g) = 2.34 W/kg; SAR(10 g) = 1.55 W/kg

Maximum value of SAR (interpolated) = 2.55 W/kg

System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm,

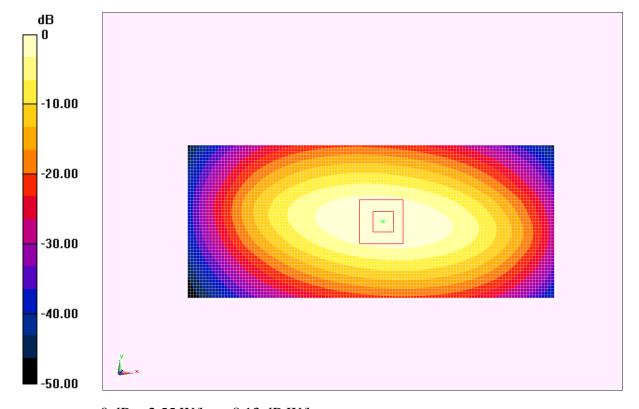
dy=5mm, dz=5mm

Reference Value = 45.969 V/m; Power Drift = -0.10 dB

Peak SAR (extrapolated) = 3.551 W/kg

SAR(1 g) = 2.36 W/kg; SAR(10 g) = 1.57 W/kg

Maximum value of SAR (measured) = 2.56 W/kg



0 dB = 2.55 W/kg = 8.13 dB W/kg

Fig.B.6 validation 835MHz 250mW



Date: 2013-4-27

Electronics: DAE4 Sn771 Medium: Head 1900 MHz

Medium parameters used: f = 1900 MHz; $\sigma = 1.422 \text{ mho/m}$; $\varepsilon_r = 39.41$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C Communication System: CW Frequency: 1900 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(8.01, 8.01, 8.01)

System Validation/Area Scan (81x121x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 93.711 V/m; Power Drift = 0.07 dB

Fast SAR: SAR(1 g) = 9.67 W/kg; SAR(10 g) = 5.09 W/kg

Maximum value of SAR (interpolated) = 11.1 W/kg

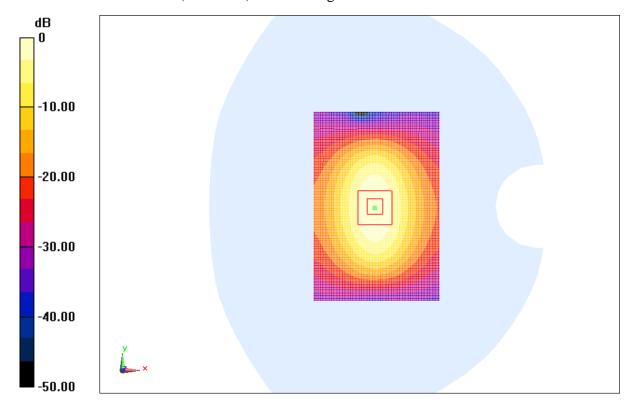
System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 93.711 V/m; Power Drift = 0.07 dB

Peak SAR (extrapolated) = 17.919 W/kg

SAR(1 g) = 9.59 W/kg; SAR(10 g) = 5.03 W/kg

Maximum value of SAR (measured) = 11.0 W/kg



0 dB = 11.1 W/kg = 20.91 dB W/kg

Fig.B.7 validation 1900MHz 250mW



Date: 2013-4-27

Electronics: DAE4 Sn771 Medium: Body 1900 MHz

Medium parameters used: f = 1900 MHz; $\sigma = 1.538 \text{ mho/m}$; $\varepsilon_r = 52.43$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C Communication System: CW Frequency: 1900 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(7.37, 7.37, 7.37)

System Validation/Area Scan (81x121x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 86.586 V/m; Power Drift = 0.05 dB

Fast SAR: SAR(1 g) = 10.1 W/kg; SAR(10 g) = 5.29 W/kg

Maximum value of SAR (interpolated) = 11.6 W/kg

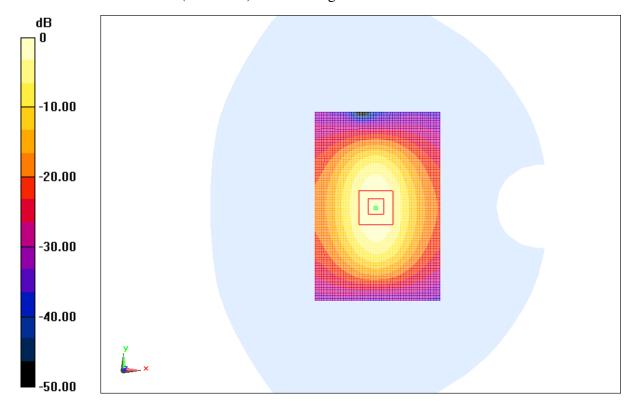
System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 86.586 V/m; Power Drift = 0.05 dB

Peak SAR (extrapolated) = 16.7 W/kg

SAR(1 g) = 10.2 W/kg; SAR(10 g) = 5.38 W/kg

Maximum value of SAR (measured) = 11.7 W/kg



0 dB = 11.6 W/kg = 21.29 dB W/kg

Fig.B.8 validation 1900MHz 250mW



The SAR system verification must be required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR.

Table B.1 Comparison between area scan and zoom scan for system verification

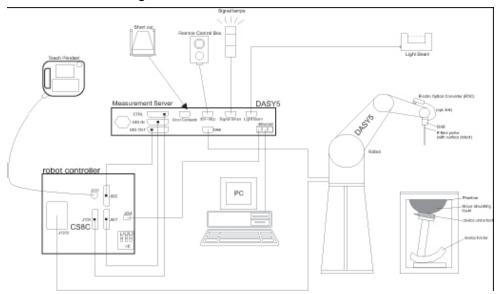
Band	Position	Area scan (1g)	Zoom scan (1g)	Drift (%)
835	Head	2.34	2.35	-0.43
835	Body	2.29	2.31	-0.87
1900	Head	9.69	9.62	0.73
1900	Body	10.0	10.1	-0.99
835	Head	2.31	2.30	0.43
835	Body	2.34	2.36	-0.85
1900	Head	9.67	9.59	0.83
1900	Body	10.1	10.2	-0.98



ANNEX C SAR Measurement Setup

C.1 Measurement Set-up

The Dasy4 or DASY5 system for performing compliance tests is illustrated above graphically. This system consists of the following items:



Picture C.1 SAR Lab Test Measurement Set-up

- A standard high precision 6-axis robot (Stäubli TX=RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc.
 The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals
 for the digital communication to the DAE. To use optical surface detection, a special version of
 the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY4 or DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as
- warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.



C.2 Dasy4 or DASY5 E-field Probe System

The S AR m easurements w ere c onducted w ith t he dos imetric pr obe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom's urface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The D ASY4 or D ASY5 software reads the reflection during a software approach and looks for the maximum using 2nd ord curve fitting. The approach is stopped at reaching the maximum.

Probe Specifications:

Model: E S3DV3, EX3DV4

Frequency 10MHz — 6.0GHz(EX3DV4) Range: 10MHz — 4GHz(ES3DV3)

Calibration: In head and body simulating tissue at

Frequencies from 835 up to 5800MHz

Linearity: ± 0.2 dB(30 MHz to 6 GHz) for EX3DV4

± 0.2 dB(30 MHz to 4 GHz) for ES3DV3

Dynamic Range: 10 mW/kg — 100W/kg

Probe Length: 330 mm

Probe Tip

Length: 20 mm Body Diameter: 12 mm

Tip Diameter: 2.5 mm (3.9 mm for ES3DV3)
Tip-Center: 1 mm (2.0mm for ES3DV3)
Application: SAR Dosimetry Testing

Compliance tests of mobile phones

Dosimetry in strong gradient fields



Picture C.2 Near-field Probe



Picture C.3 E-field Probe

C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm²) using an RF Signal generator, TEM cell, and RF Power Meter.

The f ree s pace E -field f rom a mplified pr obe out puts i s det ermined i n a t est c hamber. T his calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed



in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/ cm².

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated br ain t issue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a R F transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where:

 Δt = Exposure time (30 seconds),

C = Heat capacity of tissue (brain or muscle),

 ΔT = Temperature increase due to RF exposure.

$$SAR = \frac{\left|E\right|^2 \cdot \sigma}{\rho}$$

Where:

 σ = Simulated tissue conductivity,

 ρ = Tissue density (kg/m³).

C.4 Other Test Equipment

C.4.1 Data Acquisition Electronics(DAE)

The data acquisition electronics consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



PictureC.4: DAE



C.4.2 Robot

The SPEAG DASY system uses the high precision robots (DASY4: RX90XL; DASY5: RX160L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchron motors; no stepper motors)
- Low ELF interference (motor control fields shielded via the closed metallic construction shields)





Picture C.5 DASY 4

Picture C.6 DASY 5

C.4.3 Measurement Server

The Measurement server is based on a P C/104 CPU broad with CPU (dasy4: 166 M Hz, I ntel Pentium; D ASY5: 400 M Hz, I ntel C eleron), c hipdisk (DASY4: 32 M B; D ASY5: 128M B), R AM (DASY4: 64 M B, DASY5: 128M B). T he n ecessary c ircuits for communication with the D AE electronic box, as well as the 16 bit AD converters ystem for optical detection and digital I/O interface are contained on the DASY I/O broad, which is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, c ontrols r obot m ovements and hand less afety oper ation. The P C operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices f rom any of her supplier could seriously damage the measurement server.







Picture C.7 Server for DASY 4

Picture C.8 Server for DASY 5

C.4.4 Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ± 0.5 mm would produce a SAR uncertainty of $\pm 20\%$. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss

POM material having the following dielectric

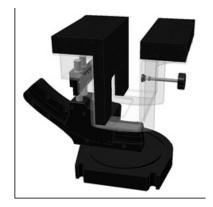
parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.



Picture C.9-1: Device Holder



Picture C.9-2: Laptop Extension Kit

C.4.5 Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to

Represent the 90th percentile of the population. The phantom enables the dissymmetric evaluation



of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

Shell Thickness: 2 ± 0. 2 mm Filling Volume: Approx. 25 liters

Dimensions: 810 x 1000 x 500 mm (H x L x W)

Available: Special



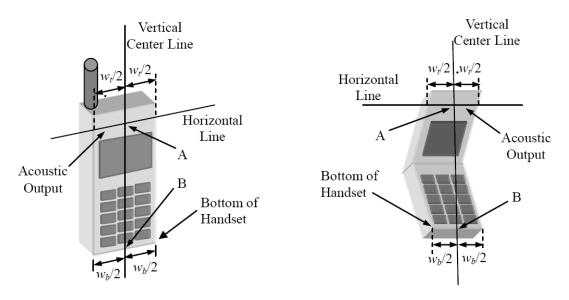
Picture C.10: SAM Twin Phantom



ANNEX D Position of the wireless device in relation to the phantom

D.1 General considerations

This standard specifies two handset test positions against the head phantom – the "cheek" position and the "tilt" position.



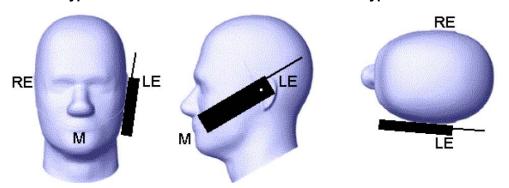
 W_t Width of the handset at the level of the acoustic

 W_b Width of the bottom of the handset

A Midpoint of the width w_t of the handset at the level of the acoustic output

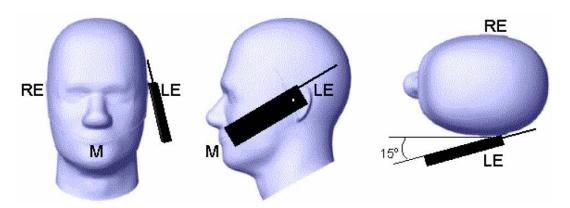
B Midpoint of the width W_b of the bottom of the handset

Picture D.1-a Typical "fixed" case handset
Picture D.1-b Typical "clam-shell" case handset



Picture D.2 Cheek position of the wireless device on the left side of SAM

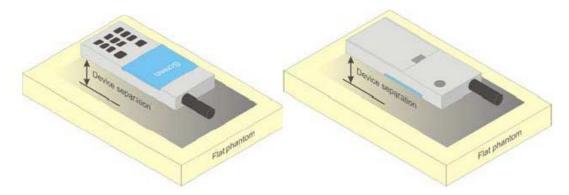




Picture D.3 Tilt position of the wireless device on the left side of SAM

D.2 Body-worn device

A typical example of a body-worn device is a mobile phone, wireless enabled PDA or other battery operated wireless device with the ability to transmit while mounted on a person's body using a carry accessory approved by the wireless device manufacturer.



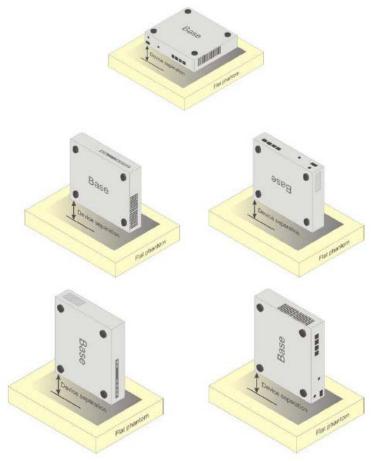
Picture D.4 Test positions for body-worn devices

D.3 Desktop device

A typical example of a desktop device is a wireless enabled desktop computer placed on a table or desk when used.

The DUT shall be positioned at the distance and in the orientation to the phantom that corresponds to the intended use as specified by the manufacturer in the user instructions. For devices that employ an external antenna with variable positions, tests shall be performed for all antenna positions specified. Picture 8.5 show positions for desktop device SAR tests. If the intended use is not specified, the device shall be tested directly against the flat phantom.





Picture D.5 Test positions for desktop devices

D.4 DUT Setup Photos



Picture D.6



ANNEX E Equivalent Media Recipes

The liquid used for the frequency range of 800-3000 MHz consisted of water, sugar, salt, preventol, glycol monobutyl and Cellulose. The liquid has been previously proven to be suited for worst-case. The Table E.1 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

Table E.1: Composition of the Tissue Equivalent Matter

			-						
Frequency	835	835	1900	1900	2450	2450	5800	5800	
(MHz)	Head	Body	Head	Body	Head	Body	Head	Body	
Ingredients (% by weight)									
Water	41.45	52.5	55.242	69.91	58.79	72.60	65.53	65.53	
Sugar	56.0	45.0	\	\	\	\	\	\	
Salt	1.45	1.4	0.306	0.13	0.06	0.18	\	\	
Preventol	0.1	0.1	\	\	\	\	1	\	
Cellulose	1.0	1.0	\	\	\	\	1	\	
Glycol	,	\	44.452	29.96	41.15	27.22	,	,	
Monobutyl	١	١	44.452	29.90	41.15	21.22	\	\	
Diethylenglycol	\	\	\	\	\	,	17.24	17.24	
monohexylether	١	١	\	١	١	\	17.24	17.24	
Triton X-100	\	\	\	\	\	\	17.24	17.24	
Dielectric	ε=41.5	ε=55.2	ε=40.0	ε=53.3	ε=39.2	ε=52.7	ε=35.3	ε=48.2	
Parameters	$\sigma = 0.90$	σ=0.97	$\sigma = 1.40$	σ=1.52	σ=1.80	σ=1.95	σ=5.27	σ=6.00	
Target Value	0-0.90	0-0.97	0-1.40	0-1.32	0-1.00	0-1.95	0-3.27	0-0.00	



ANNEX F S ystem Validation

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components.

Table F.1: System Validation with probe 3149

	Table 1.1. System Validation With probe 0140								
Probe SN.	Liquid name	Validation date	Frequency point	Status (OK or Not)					
3149	Head 750MHz	Sep. 17, 2012	750 MHz	OK					
3149	Head 850MHz	Sep. 17, 2012	850 MHz	OK					
3149	Head 900MHz	Sep. 17, 2012	900 MHz	OK					
3149	Head 1800MHz	Sep. 18, 2012	1800 MHz	OK					
3149	Head 1900MHz	Sep. 18, 2012	1900 MHz	OK					
3149	Head 2000MHz	Sep. 18, 2012	2000 MHz	OK					
3149	Head 2100MHz	Sep. 18, 2012	2100 MHz	OK					
3149	Head 2450MHz	Sep. 19, 2012	2450 MHz	OK					
3149	Head 2550MHz	Sep. 19, 2012	2550 MHz	OK					
3149	Head 2600MHz	Sep. 19, 2012	2600 MHz	OK					
3149	Body 750MHz	Sep. 20, 2012	750 MHz	OK					
3149	Body 850MHz	Sep. 20, 2012	850 MHz	OK					
3149	Body 900MHz	Sep. 20, 2012	900 MHz	OK					
3149	Body 1800MHz	Sep. 21, 2012	1800 MHz	OK					
3149	Body 1900MHz	Sep. 21, 2012	1900 MHz	OK					
3149	Body 2000MHz	Sep. 21, 2012	2000 MHz	OK					
3149	Body 2100MHz	Sep. 21, 2012	2100 MHz	OK					
3149	Body 2450MHz	Sep. 22, 2012	2450 MHz	OK					
3149	Body 2550MHz	Sep. 22, 2012	2550 MHz	OK					
3149	Body 2600MHz	Sep. 22, 2012	2600 MHz	OK					



Table F.2: System Validation with probe 3846

Probe SN.	Liquid nama	Validation data	Eroquonov point	Status (OK or Not)
	Liquid name	Validation date	Frequency point	Status (OK or Not)
3846	Head 750MHz	Mar. 06, 2013	750 MHz	OK
3846	Head 850MHz	Mar. 06, 2013	850 MHz	OK
3846	Head 900MHz	Mar. 01, 2013	900 MHz	OK
3846	Head 1750MHz	Mar. 03, 2013	1750 MHz	OK
3846	Head 1810MHz	Mar. 03, 2013	1810 MHz	OK
3846	Head 1900MHz	Mar. 07, 2013	1900 MHz	OK
3846	Head 1950MHz	Mar. 04, 2013	1950 MHz	OK
3846	Head 2000MHz	Mar. 04, 2013	2000 MHz	OK
3846	Head 2100MHz	Mar. 05, 2013	2100 MHz	OK
3846	Head 2300MHz	Mar. 05, 2013	2300 MHz	OK
3846	Head 2450MHz	Mar. 02, 2013	2450 MHz	OK
3846	Head 2550MHz	Mar. 08, 2013	2550 MHz	OK
3846	Head 2600MHz	Mar. 08, 2013	2600 MHz	OK
3846	Head 3500MHz	Mar. 09, 2013	3500 MHz	OK
3846	Head 3700MHz	Mar. 09, 2013	3700 MHz	OK
3846	Head 5200MHz	Mar. 10, 2013	5200 MHz	OK
3846	Head 5500MHz	Mar. 10, 2013	5500 MHz	OK
3846	Head 5800MHz	Mar. 10, 2013	5800 MHz	OK
3846	Body 750MHz	Mar. 06, 2013	750 MHz	OK
3846	Body 850MHz	Mar. 06, 2013	850 MHz	OK
3846	Body 900MHz	Mar. 01, 2013	900 MHz	OK
3846	Body 1750MHz	Mar. 03, 2013	1750 MHz	OK
3846	Body 1810MHz	Mar. 03, 2013	1810 MHz	OK
3846	Body 1900MHz	Mar. 07, 2013	1900 MHz	OK
3846	Body 1950MHz	Mar. 04, 2013	1950 MHz	OK
3846	Body 2000MHz	Mar. 04, 2013	2000 MHz	OK
3846	Body 2100MHz	Mar. 05, 2013	2100 MHz	OK
3846	Body 2300MHz	Mar. 05, 2013	2300 MHz	OK
3846	Body 2450MHz	Mar. 02, 2013	2450 MHz	OK
3846	Body 2550MHz	Mar. 08, 2013	2550 MHz	OK
3846	Body 2600MHz	Mar. 08, 2013	2600 MHz	OK
3846	Body 3500MHz	Mar. 09, 2013	3500 MHz	OK
3846	Body 3700MHz	Mar. 09, 2013	3700 MHz	OK
3846	Body 5200MHz	Mar. 10, 2013	5200 MHz	OK
3846	Body 5500MHz	Mar. 10, 2013	5500 MHz	OK
3846	Body 5800MHz	Mar. 10, 2013	5800 MHz	OK
	,	1 '		= * *



ANNEX G Probe Calibration Certificate

Probe 3149 Calibration Certificate

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S

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Accreditation No.: SCS 108

Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Client

TMC Beijing

Certificate No: ES3-3149_Apr12

CALIBRATION CERTIFICATE

Object

ES3DV3 - SN:3149

Calibration procedure(s)

QA CAL-01.v8, QA CAL-23.v4, QA CAL-25.v4 Calibration procedure for dosimetric E-field probes

Calibration date:

April 24, 2012

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

ID	Cal Date (Certificate No.)	Scheduled Calibration
GB41293874	29-Mar-12 (No. 217-01508)	Apr-13
MY41498087	29-Mar-12 (No. 217-01508)	Apr-13
SN: S5054 (3c)	27-Mar-12 (No. 217-01531)	Apr-13
SN: S5086 (20b)	27-Mar-12 (No. 217-01529)	Apr-13
SN: S5129 (30b)	27-Mar-12 (No. 217-01532)	Apr-13
SN: 3013	29-Dec-11 (No. ES3-3013_Dec11)	Dec-12
SN: 660	10-Jan-12 (No. DAE4-660_Jan12)	Jan-13
ID	Check Date (in house)	Scheduled Check
US3642U01700	4-Aug-99 (in house check Apr-11)	In house check: Apr-13
US37390585	18-Oct-01 (in house check Oct-11)	In house check; Oct-12
	GB41293874 MY41498087 SN: S5054 (3c) SN: S5086 (20b) SN: S5129 (30b) SN: 3013 SN: 660	GB41293874 29-Mar-12 (No. 217-01508) MY41498087 29-Mar-12 (No. 217-01508) SN: S5054 (3c) 27-Mar-12 (No. 217-01531) SN: S5086 (20b) 27-Mar-12 (No. 217-01529) SN: S5129 (30b) 27-Mar-12 (No. 217-01532) SN: 3013 29-Dec-11 (No. ES3-3013_Dec11) SN: 660 10-Jan-12 (No. DAE4-660_Jan12) ID Check Date (in house) US3642U01700 4-Aug-99 (in house check Apr-11)

Calibrated by:

Name
Function
Signature

Laboratory Technician

Approved by:

Katja Pokovic
Technical Manager

Issued: April 24, 2012

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
Servizio svizzero di taratura
Swiss Calibration Service

Accreditation No.: SCS 108

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Glossary:

TSL tissue simulating liquid
NORMx,y,z sensitivity in free space
ConvF sensitivity in TSL / NORMx,y,z
DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A, B, C modulation dependent linearization parameters

Polarization φ φ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., $\vartheta = 0$ is normal to probe axis

Calibration is Performed According to the Following Standards:

 IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003

b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization § = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
 NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not affect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)x,y,z = NORMx,y,z * frequency_response (see Frequency Response Chart). This linearization is
 implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included
 in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C are numerical linearization parameters assessed based on the data of
 power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the
 maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.



ES3DV3 - SN:3149

April 24, 2012

Probe ES3DV3

SN:3149

Manufactured: Calibrated:

June 12, 2007 April 24, 2012

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)



ES3DV3-SN:3149 April 24, 2012

DASY/EASY - Parameters of Probe: ES3DV3 - SN:3149

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (µV/(V/m) ²) ^A	1.21	1.24	1.24	± 10.1 %
DCP (mV) ^B	101.1	100.9	100.5	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc ^E (k=2)
0	CW	0.00	X	0.00	0.00	1.00	112.7	±2.2 %
			Y	0.00	0.00	1.00	114.2	
			Z	0.00	0.00	1.00	118.9	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

A The uncertainties of NormX,Y,Z do not affect the E²-field uncertainty inside TSL (see Pages 5 and 6).

B Numerical linearization parameter: uncertainty not required.

E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.



ES3DV3-SN:3149 April 24, 2012

DASY/EASY - Parameters of Probe: ES3DV3 - SN:3149

Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) ^C	Relative Permittivity ^F	Conductivity (S/m) F	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
750	41.9	0.89	6.50	6.50	6.50	0.24	2.36	± 12.0 %
850	41.5	0.92	6.26	6.26	6.26	0.25	2.14	± 12.0 %
900	41.5	0.97	6.17	6.17	6.17	0.21	2.55	± 12.0 %
1800	40.0	1.40	5.23	5.23	5.23	0.43	1.64	± 12.0 %
1900	40.0	1.40	5.19	5.19	5.19	0.45	1.64	± 12.0 %
2000	40.0	1.40	5.11	5.11	5.11	0.52	1.46	± 12.0 %
2100	39.8	1.49	5.12	5.12	5.12	0.49	1.52	± 12.0 %
2450	39.2	1.80	4.49	4.49	4.49	0.71	1.37	± 12.0 %
2550	39.1	1.91	4.34	4.34	4.34	0.69	1.26	± 12.0 %
2600	39.0	1.96	4.26	4.26	4.26	0.55	1.29	± 12.0 %

 $^{^{}c}$ Frequency validity of \pm 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to \pm 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. † At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to \pm 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to \pm 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.



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DASY/EASY - Parameters of Probe: ES3DV3 - SN:3149

Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) ^c	Relative Permittivity F	Conductivity (S/m) F	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
750	55.5	0.96	6.29	6.29	6.29	0.43	1.56	± 12.0 %
850	55.2	0.99	6.14	6.14	6.14	0.41	1.63	± 12.0 %
900	55.0	1.05	6.16	6.16	6.16	0.63	1.30	± 12.0 %
1800	53.3	1.52	4.84	4.84	4.84	0.28	2.97	± 12.0 %
1900	53.3	1.52	4.64	4.64	4.64	0.34	2.25	± 12.0 %
2000	53.3	1.52	4.63	4.63	4.63	0.35	2.21	± 12.0 %
2100	53.2	1.62	4.91	4.91	4.91	0.36	2.20	± 12.0 %
2450	52.7	1.95	4.15	4.15	4.15	0.80	0.61	± 12.0 %
2550	52.6	2.09	4.07	4.07	4.07	0.80	0.50	± 12.0 %
2600	52.5	2.16	3.99	3.99	3.99	0.80	0.51	± 12.0 %

 $^{^{}c}$ Frequency validity of \pm 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to \pm 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

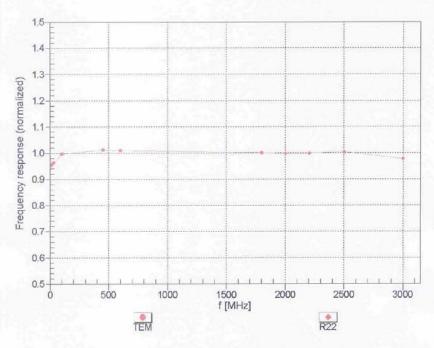
F At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to \pm 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to \pm 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.



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Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)