

WCDMA 1900 Body Rear Low

Date: 2013-7-4

Electronics: DAE4 Sn771 Medium: Body 1900 MHz

Medium parameters used (interpolated): f = 1852.4 MHz; $\sigma = 1.491$ mho/m; $\epsilon r = 51.94$; $\rho =$

 1000 kg/m^3

Ambient Temperature: 22.7°C Liquid Temperature: 22.2°C

Communication System: WCDMA 1900 Frequency: 1852.4 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(7.37, 7.37, 7.37)

Rear Low/Area Scan (61x111x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 1.15 W/kg

Rear Low/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 12.929 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 1.68 W/kg

SAR(1 g) = 1.04 W/kg; SAR(10 g) = 0.611 W/kg

Maximum value of SAR (measured) = 1.14 W/kg

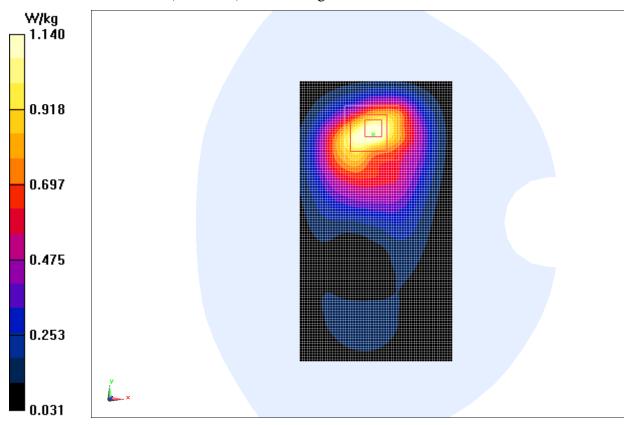


Fig.8 WCDMA1900 CH9262



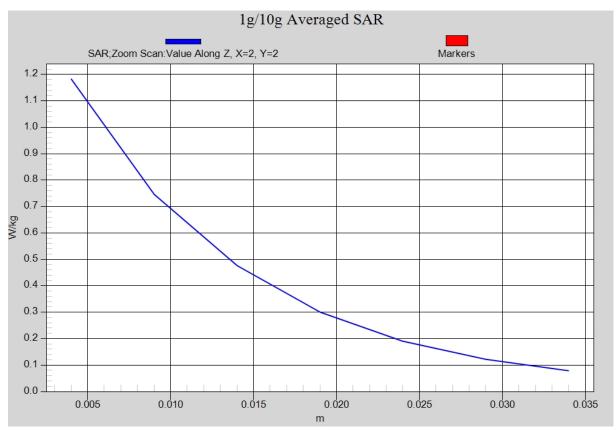


Fig. 8-1 Z-Scan at power reference point (WCDMA1900 CH9262)



Wifi 802.11b Right Cheek Channel 6

Date: 2013-7-5

Electronics: DAE4 Sn771 Medium: Head 2450 MHz

Medium parameters used (interpolated): f = 2437 MHz; $\sigma = 1.812$ mho/m; $\varepsilon_r = 39.79$; $\rho = 1000$

 kg/m^3

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C

Communication System: WLan 2450 Frequency: 2437 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(7.13, 7.13, 7.13)

Cheek/Area Scan (71x131x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.0426 W/kg

Cheek/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.752 V/m; Power Drift = 0.16 dB

Peak SAR (extrapolated) = 0.0820 W/kg

SAR(1 g) = 0.039 W/kg; SAR(10 g) = 0.020 W/kgMaximum value of SAR (measured) = 0.0427 W/kg

0.034 0.026 0.017 0.00854

Fig.9 2450 MHz CH6



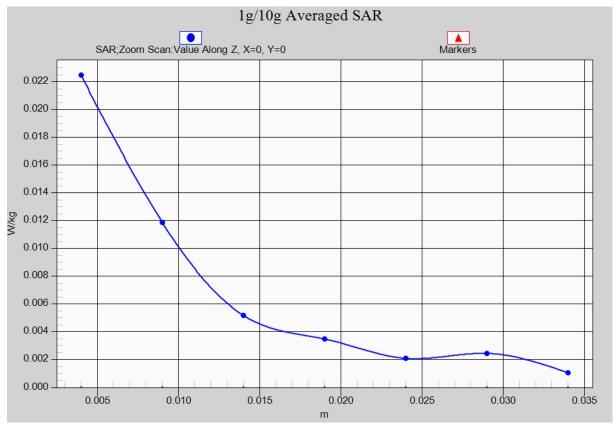


Fig. 9-1 Z-Scan at power reference point (2450 MHz CH6)



Wifi 802.11b Body Rear Channel 6

Date: 2013-7-5

Electronics: DAE4 Sn771 Medium: Body 2450 MHz

Medium parameters used (interpolated): f = 2437 MHz; $\sigma = 1.947$ mho/m; $\varepsilon_r = 52.287$; $\rho =$

 1000 kg/m^3

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C

Communication System: WLan 2450 Frequency: 2437 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(7.00, 7.00, 7.00)

Rear Middle/Area Scan (91x171x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.0355 W/kg

Rear Middle/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.214 V/m; Power Drift = 0.17 dB

Peak SAR (extrapolated) = 0.0540 W/kg

SAR(1 g) = 0.030 W/kg; SAR(10 g) = 0.015 W/kg

Maximum value of SAR (measured) = 0.0341 W/kg

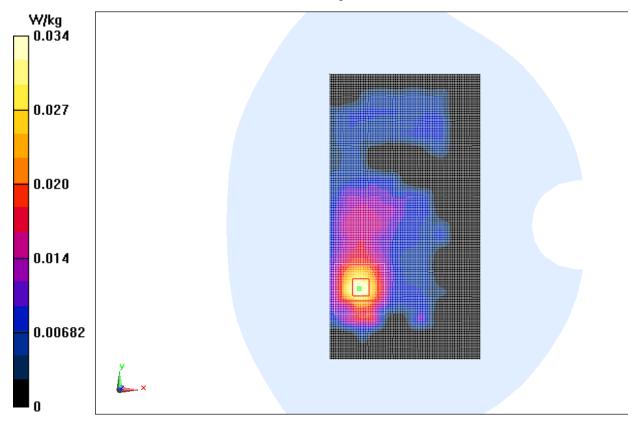


Fig.10 2450 MHz CH6



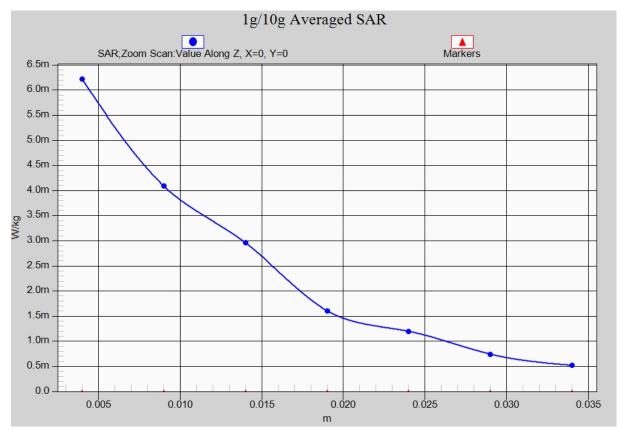


Fig. 10-1 Z-Scan at power reference point (2450 MHz CH6)



ANNEX B System Verification Results

835MHz

Date: 2013-7-3

Electronics: DAE4 Sn771 Medium: Head 850 MHz

Medium parameters used: f = 835 MHz; $\sigma = 0.911$ mho/m; $\varepsilon_r = 42.18$; $\rho = 1000$ kg/m³

Ambient Temperature: 22.7°C Liquid Temperature: 22.2°C Communication System: CW Frequency: 835 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(9.18, 9.18, 9.18)

System Validation /Area Scan (81x161x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 51.539 V/m; Power Drift = -0.10 dB

Fast SAR: SAR(1 g) = 2.28 W/kg; SAR(10 g) = 1.49 W/kg

Maximum value of SAR (interpolated) = 2.48 W/kg

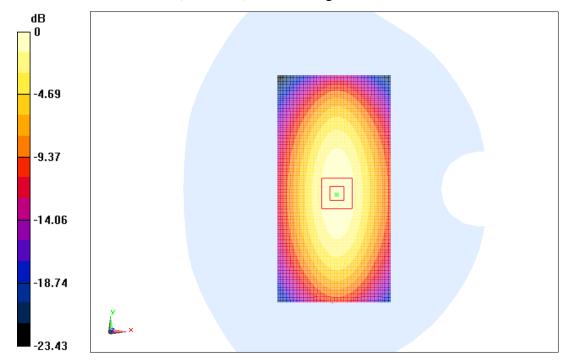
System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 51.539 V/m; Power Drift = -0.10 dB

Peak SAR (extrapolated) = 3.429 W/kg

SAR(1 g) = 2.30 W/kg; SAR(10 g) = 1.50 W/kg

Maximum value of SAR (measured) = 2.49 W/kg



0 dB = 2.48 W/kg = 7.89 dB W/kg

Fig.B.1 validation 835MHz 250mW



Date: 2013-7-3

Electronics: DAE4 Sn771 Medium: Body 850 MHz

Medium parameters used: f = 835 MHz; $\sigma = 0.963$ mho/m; $\varepsilon_r = 54.37$; $\rho = 1000$ kg/m³

Ambient Temperature: 22.7°C Liquid Temperature: 22.2°C Communication System: CW Frequency: 835 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(9.04, 9.04, 9.04)

System Validation /Area Scan (81x171x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 44.505 V/m; Power Drift = -0.08 dB

Fast SAR: SAR(1 g) = 2.26 W/kg; SAR(10 g) = 1.50 W/kg

Maximum value of SAR (interpolated) = 2.47 W/kg

System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm,

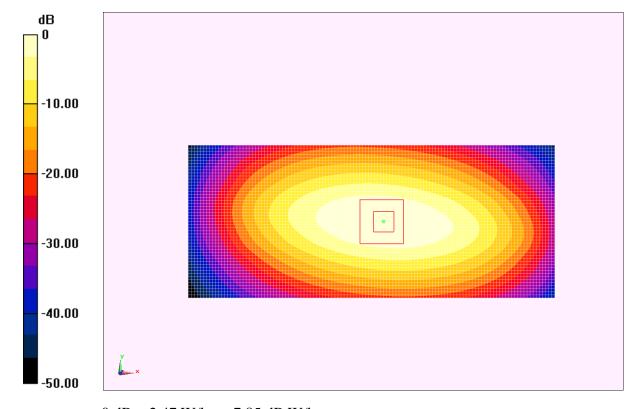
dy=5mm, dz=5mm

Reference Value = 44.505 V/m; Power Drift = -0.08 dB

Peak SAR (extrapolated) = 3.48 W/kg

SAR(1 g) = 2.28 W/kg; SAR(10 g) = 1.52 W/kg

Maximum value of SAR (measured) = 2.48 W/kg



0 dB = 2.47 W/kg = 7.85 dB W/kg

Fig.B.2 validation 835MHz 250mW



Date: 2013-7-4

Electronics: DAE4 Sn771 Medium: Head 1900 MHz

Medium parameters used: f = 1900 MHz; $\sigma = 1.417 \text{ mho/m}$; $\varepsilon_r = 38.86$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.7°C Liquid Temperature: 22.2°C Communication System: CW Frequency: 1900 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(8.01, 8.01, 8.01)

System Validation/Area Scan (81x121x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 94.421 V/m; Power Drift = -0.06 dB

Fast SAR: SAR(1 g) = 9.69 W/kg; SAR(10 g) = 5.12 W/kg

Maximum value of SAR (interpolated) = 11.1 W/kg

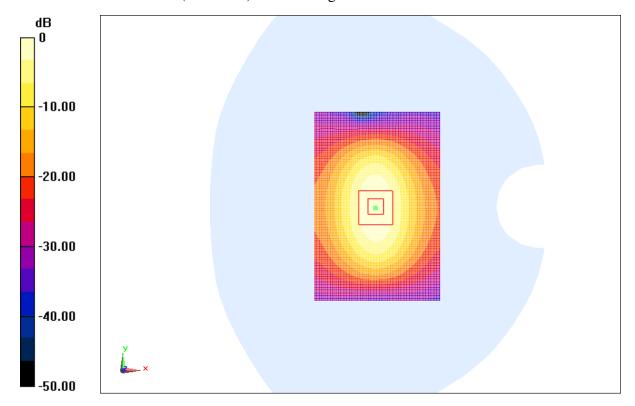
System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 94.421 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 17.922 W/kg

SAR(1 g) = 9.60 W/kg; SAR(10 g) = 5.05 W/kg

Maximum value of SAR (measured) = 11.0 W/kg



0 dB = 11.1 W/kg = 20.91 dB W/kg

Fig.B.3 validation 1900MHz 250mW



Date: 2013-7-4

Electronics: DAE4 Sn771 Medium: Body 1900 MHz

Medium parameters used: f = 1900 MHz; $\sigma = 1.539 \text{ mho/m}$; $\varepsilon_r = 51.75$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.7°C Liquid Temperature: 22.2°C Communication System: CW Frequency: 1900 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(7.37, 7.37, 7.37)

System Validation/Area Scan (81x121x1): Measurement grid: dx=10mm, dy=10mm

Reference Value = 83.673 V/m; Power Drift = -0.05 dB

Fast SAR: SAR(1 g) = 10.1 W/kg; SAR(10 g) = 5.33 W/kg

Maximum value of SAR (interpolated) = 11.6 W/kg

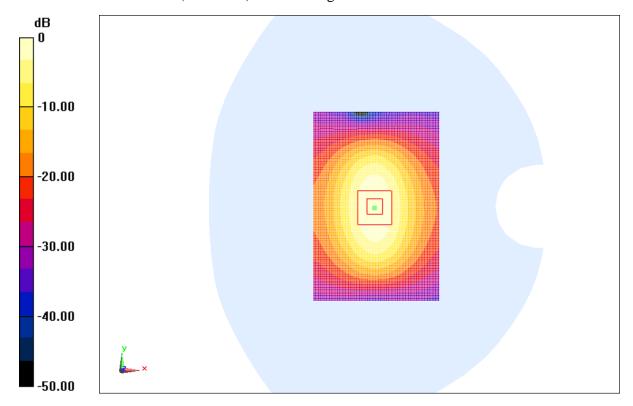
System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 83.673 V/m; Power Drift = -0.05 dB

Peak SAR (extrapolated) = 16.692 W/kg

SAR(1 g) = 10.2 W/kg; SAR(10 g) = 5.41 W/kg

Maximum value of SAR (measured) = 11.7 W/kg



0 dB = 11.6 W/kg = 21.29 dB W/kg

Fig.B.4 validation 1900MHz 250mW



Date: 2013-7-5

Electronics: DAE4 Sn771 Medium: Head 2450 MHz

Medium parameters used: f = 2450 MHz; $\sigma = 1.825 \text{ mho/m}$; $\varepsilon_r = 39.73$; $\rho = 1000 \text{ kg/m}^3$

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C Communication System: CW Frequency: 2450 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(7.13, 7.13, 7.13)

System Validation /Area Scan (81x101x1): Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 14.8 W/kg

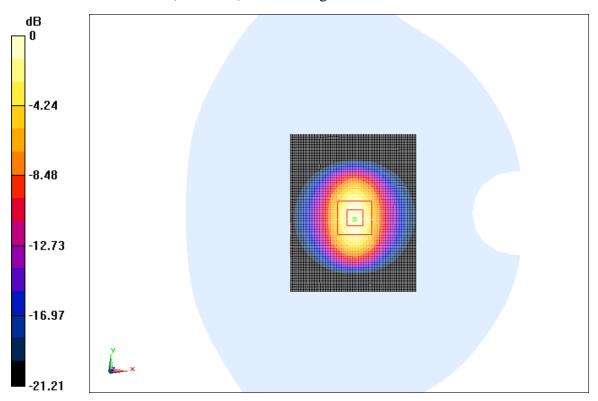
System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 92.945 V/m; Power Drift = -0.05 dB

Peak SAR (extrapolated) = 25.91 W/kg

SAR(1 g) = 12.8 W/kg; SAR(10 g) = 5.95 W/kg

Maximum value of SAR (measured) = 14.7 W/kg



0 dB = 14.8 W/kg = 23.40 dB W/kg

Fig.B.5 validation 2450MHz 250mW



Date: 2013-7-5

Electronics: DAE4 Sn771 Medium: Body 2450 MHz

Medium parameters used: f = 2450 MHz; $\sigma = 1.961$ mho/m; $\varepsilon_r = 52.24$; $\rho = 1000$ kg/m³

Ambient Temperature: 22.6°C Liquid Temperature: 22.1°C Communication System: CW Frequency: 2450 MHz Duty Cycle: 1:1

Probe: EX3DV4 - SN3846 ConvF(7.00, 7.00, 7.00)

System Validation/Area Scan (81x101x1): Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 14.9 W/kg

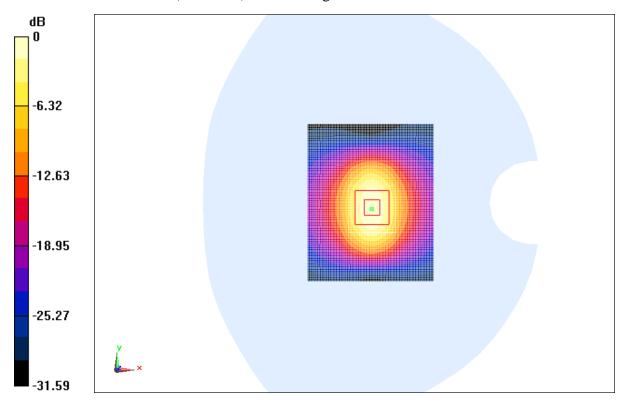
System Validation/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 96.875 V/m; Power Drift = -0.07 dB

Peak SAR (extrapolated) = 26.01 W/kg

SAR(1 g) = 12.9 W/kg; SAR(10 g) = 6.02 W/kg

Maximum value of SAR (measured) = 14.8 W/kg



0 dB = 14.9 W/kg = 23.46 dB W/kg

Fig.B.6 validation 2450MHz 250mW



The SAR system verification must be required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR.

Table B.1 Comparison between area scan and zoom scan for system verification

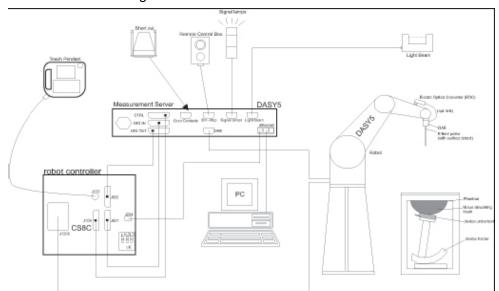
Band	Position	Area scan (1g)	Zoom scan (1g)	Drift (%)
835	Head	2.28	2.30	-0.87
835	Body	2.26	2.28	-0.88
1900	Head	9.69	9.60	0.94
1900	Body	10.1	10.2	-0.98



ANNEX C SAR Measurement Setup

C.1 Measurement Set-up

The Dasy4 or DASY5 system for performing compliance tests is illustrated above graphically. This system consists of the following items:



Picture C.1 SAR Lab Test Measurement Set-up

- A standard high precision 6-axis robot (Stäubli TX=RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc.
 The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals
 for the digital communication to the DAE. To use optical surface detection, a special version of
 the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY4 or DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as
- warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.



C.2 Dasy4 or DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 or DASY5 software reads the reflection durning a software approach and looks for the maximum using 2nd ord curve fitting. The approach is stopped at reaching the maximum.

Probe Specifications:

Model: ES3DV3, EX3DV4

Frequency 10MHz — 6.0GHz(EX3DV4) Range: 10MHz — 4GHz(ES3DV3)

Calibration: In head and body simulating tissue at

Frequencies from 835 up to 5800MHz

Linearity: $\pm 0.2 dB(30 MHz to 6 GHz) for EX3DV4$

± 0.2 dB(30 MHz to 4 GHz) for ES3DV3

Dynamic Range: 10 mW/kg — 100W/kg

Probe Length: 330 mm

Probe Tip

Length: 20 mm Body Diameter: 12 mm

Tip Diameter: 2.5 mm (3.9 mm for ES3DV3)
Tip-Center: 1 mm (2.0mm for ES3DV3)
Application: SAR Dosimetry Testing

Compliance tests of mobile phones

Dosimetry in strong gradient fields



Picture C.2 Near-field Probe



Picture C.3 E-field Probe

C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm²) using an RF Signal generator, TEM cell, and RF Power Meter.

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed



in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/ cm².

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C \frac{\Delta T}{\Delta t}$$

Where:

 $\Delta t = \text{Exposure time (30 seconds)},$

C = Heat capacity of tissue (brain or muscle),

 ΔT = Temperature increase due to RF exposure.

$$SAR = \frac{\left|E\right|^2 \cdot \sigma}{\rho}$$

Where:

 σ = Simulated tissue conductivity,

 ρ = Tissue density (kg/m³).

C.4 Other Test Equipment

C.4.1 Data Acquisition Electronics(DAE)

The data acquisition electronics consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



PictureC.4: DAE



C.4.2 Robot

The SPEAG DASY system uses the high precision robots (DASY4: RX90XL; DASY5: RX160L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability 0.02mm)
- > High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchron motors; no stepper motors)
- > Low ELF interference (motor control fields shielded via the closed metallic construction shields)





Picture C.5 DASY 4

Picture C.6 DASY 5

C.4.3 Measurement Server

The Measurement server is based on a PC/104 CPU broad with CPU (dasy4: 166 MHz, Intel Pentium; DASY5: 400 MHz, Intel Celeron), chipdisk (DASY4: 32 MB; DASY5: 128MB), RAM (DASY4: 64 MB, DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O broad, which is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.







Picture C.7 Server for DASY 4

Picture C.8 Server for DASY 5

C.4.4 Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ±0.5mm would produce a SAR uncertainty of ±20%. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss

POM material having the following dielectric

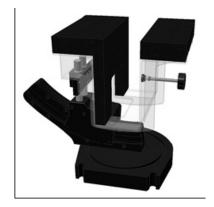
parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.



Picture C.9-1: Device Holder



Picture C.9-2: Laptop Extension Kit

C.4.5 Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to

Represent the 90th percentile of the population. The phantom enables the dissymmetric evaluation



of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

Shell Thickness: $2 \pm 0.2 \text{ mm}$ Filling Volume: Approx. 25 liters

Dimensions: 810 x 1000 x 500 mm (H x L x W)

Available: Special



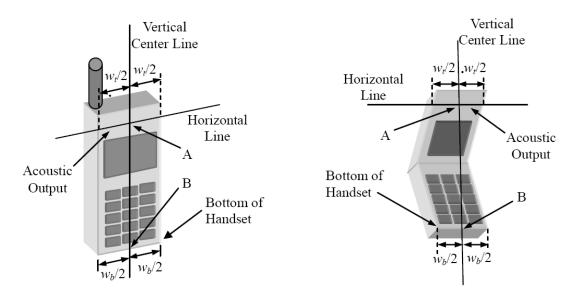
Picture C.10: SAM Twin Phantom



ANNEX D Position of the wireless device in relation to the phantom

D.1 General considerations

This standard specifies two handset test positions against the head phantom – the "cheek" position and the "tilt" position.



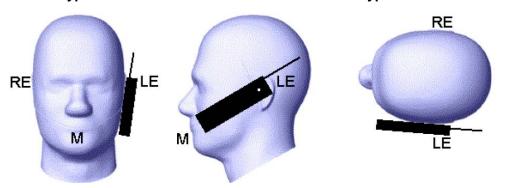
 W_t Width of the handset at the level of the acoustic

 W_b Width of the bottom of the handset

A Midpoint of the width w_t of the handset at the level of the acoustic output

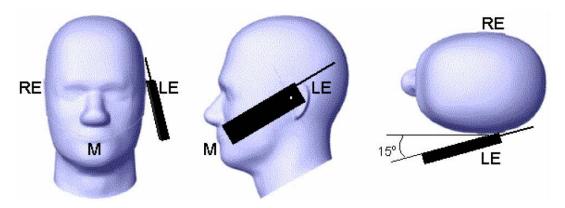
B Midpoint of the width W_b of the bottom of the handset

Picture D.1-a Typical "fixed" case handset Picture D.1-b Typical "clam-shell" case handset



Picture D.2 Cheek position of the wireless device on the left side of SAM

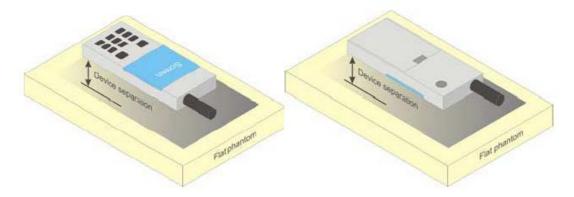




Picture D.3 Tilt position of the wireless device on the left side of SAM

D.2 Body-worn device

A typical example of a body-worn device is a mobile phone, wireless enabled PDA or other battery operated wireless device with the ability to transmit while mounted on a person's body using a carry accessory approved by the wireless device manufacturer.



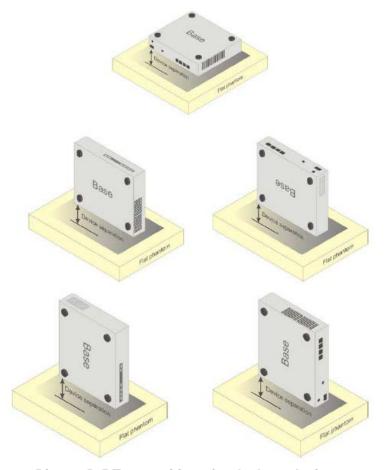
Picture D.4 Test positions for body-worn devices

D.3 Desktop device

A typical example of a desktop device is a wireless enabled desktop computer placed on a table or desk when used.

The DUT shall be positioned at the distance and in the orientation to the phantom that corresponds to the intended use as specified by the manufacturer in the user instructions. For devices that employ an external antenna with variable positions, tests shall be performed for all antenna positions specified. Picture 8.5 show positions for desktop device SAR tests. If the intended use is not specified, the device shall be tested directly against the flat phantom.





Picture D.5 Test positions for desktop devices

D.4 DUT Setup Photos



Picture D.6



ANNEX E Equivalent Media Recipes

The liquid used for the frequency range of 800-3000 MHz consisted of water, sugar, salt, preventol, glycol monobutyl and Cellulose. The liquid has been previously proven to be suited for worst-case. The Table E.1 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

Table E.1: Composition of the Tissue Equivalent Matter

			<u>- </u>		-					
Frequency	835	835	1900	1900	2450	2450	5800	5800		
(MHz)	Head	Body	Head	Body	Head	Body	Head	Body		
Ingredients (% by weight)										
Water	41.45	52.5	55.242	69.91	58.79	72.60	65.53	65.53		
Sugar	56.0	45.0	\	\	\	\	\	\		
Salt	1.45	1.4	0.306	0.13	0.06	0.18	\	\		
Preventol	0.1	0.1	\	\	\	\	\	\		
Cellulose	1.0	1.0	\	\	\	\	\	\		
Glycol	\	\	44.452	29.96	41.15	27.22	\	,		
Monobutyl	\	\	44.432	29.90	41.13	21.22	\	\		
Diethylenglycol	\	\	\	\	\	1	17.24	17.24		
monohexylether	\	\	\	\	\	\	17.24	17.24		
Triton X-100	\	\	\	\	\	\	17.24	17.24		
Dielectric	ε=41.5	ε=55.2	ε=40.0	ε=53.3	ε=39.2	ε=52.7	ε=35.3	ε=48.2		
Parameters		σ=0.97								
Target Value	σ=0.90	0-0.97	σ=1.40	σ=1.52	σ=1.80	σ=1.95	σ=5.27	σ=6.00		



ANNEX F System Validation

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components.

Table F.1: System Validation

Table F.1: System validation									
Probe SN.	Liquid name	Validation date	Frequency point	Status (OK or Not)					
3846	Head 750MHz	Mar. 06, 2013	750 MHz	OK					
3846	Head 850MHz	Mar. 06, 2013	850 MHz	OK					
3846	Head 900MHz	Mar. 01, 2013	900 MHz	OK					
3846	Head 1750MHz	Mar. 03, 2013	1750 MHz	OK					
3846	Head 1810MHz	Mar. 03, 2013	1810 MHz	OK					
3846	Head 1900MHz	Mar. 07, 2013	1900 MHz	OK					
3846	Head 1950MHz	Mar. 04, 2013	1950 MHz	OK					
3846	Head 2000MHz	Mar. 04, 2013	2000 MHz	OK					
3846	Head 2100MHz	Mar. 05, 2013	2100 MHz	OK					
3846	Head 2300MHz	Mar. 05, 2013	2300 MHz	OK					
3846	Head 2450MHz	Mar. 02, 2013	2450 MHz	OK					
3846	Head 2550MHz	Mar. 08, 2013	2550 MHz	OK					
3846	Head 2600MHz	Mar. 08, 2013	2600 MHz	OK					
3846	Head 3500MHz	Mar. 09, 2013	3500 MHz	OK					
3846	Head 3700MHz	Mar. 09, 2013	3700 MHz	OK					
3846	Head 5200MHz	Mar. 10, 2013	5200 MHz	OK					
3846	Head 5500MHz	Mar. 10, 2013	5500 MHz	OK					
3846	Head 5800MHz	Mar. 10, 2013	5800 MHz	OK					
3846	Body 750MHz	Mar. 06, 2013	750 MHz	OK					
3846	Body 850MHz	Mar. 06, 2013	850 MHz	OK					
3846	Body 900MHz	Mar. 01, 2013	900 MHz	OK					
3846	Body 1750MHz	Mar. 03, 2013	1750 MHz	OK					
3846	Body 1810MHz	Mar. 03, 2013	1810 MHz	OK					
3846	Body 1900MHz	Mar. 07, 2013	1900 MHz	OK					
3846	Body 1950MHz	Mar. 04, 2013	1950 MHz	OK					
3846	Body 2000MHz	Mar. 04, 2013	2000 MHz	OK					
3846	Body 2100MHz	Mar. 05, 2013	2100 MHz	OK					
3846	Body 2300MHz	Mar. 05, 2013	2300 MHz	OK					
3846	Body 2450MHz	Mar. 02, 2013	2450 MHz	OK					
3846	Body 2550MHz	Mar. 08, 2013	2550 MHz	OK					
3846	Body 2600MHz	Mar. 08, 2013	2600 MHz	OK					
3846	Body 3500MHz	Mar. 09, 2013	3500 MHz	OK					
3846	Body 3700MHz	Mar. 09, 2013	3700 MHz	OK					
3846	Body 5200MHz	Mar. 10, 2013	5200 MHz	OK					
3846	Body 5500MHz	Mar. 10, 2013	5500 MHz	OK					
3846	Body 5800MHz	Mar. 10, 2013	5800 MHz	OK					



ANNEX G Probe Calibration Certificate

Probe 3846 Calibration Certificate

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Client

TMC Beijing (Auden)

Certificate No: EX3-3846_Dec12

Accreditation No.: SCS 108

S

C

S

CALIBRATION CERTIFICATE

Object

EX3DV4 - SN:3846

Calibration procedure(s)

QA CAL-01.v8, QA CAL-14.v3, QA CAL-23.v4, QA CAL-25.v4

Calibration procedure for dosimetric E-field probes

Calibration date:

December 20, 2012

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID .	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	29-Mar-12 (No. 217-01508)	Apr-13
Power sensor E4412A	MY41498087	29-Mar-12 (No. 217-01508)	Apr-13
Reference 3 dB Attenuator	SN: S5054 (3c)	27-Mar-12 (No. 217-01531)	Apr-13
Reference 20 dB Attenuator	SN: S5086 (20b)	27-Mar-12 (No. 217-01529)	Apr-13
Reference 30 dB Attenuator	SN: S5129 (30b)	27-Mar-12 (No. 217-01532)	Apr-13
Reference Probe ES3DV2	SN: 3013	29-Dec-11 (No. ES3-3013_Dec11)	Dec-12
DAE4	SN: 660	20-Jun-12 (No. DAE4-660_Jun12)	Jun-13
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-11)	In house check: Apr-13
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-12)	In house check: Oct-13

Calibrated by:

Name
Function
Signature
Laboratory Technician

Approved by:

Katja Pokovic
Technical Manager

Issued: December 20, 2012

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



Calibration Laboratory of Schmid & Partner





Schweizerischer Kalibrierdienst S Service suisse d'étalonnage C Servizio svizzero di taratura S Swiss Calibration Service

Accreditation No.: SCS 108

Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland

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Glossary:

TSL tissue simulating liquid NORMx,y,z sensitivity in free space ConvF sensitivity in TSL / NORMx,y,z DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A.B.C modulation dependent linearization parameters

Polarization o φ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 9 = 0 is normal to probe axis

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003

IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not affect the E2-field uncertainty inside TSL (see below ConvF).
- $NORM(f)x,y,z = NORMx,y,z * frequency_response$ (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z; A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from \pm 50 MHz to \pm 100
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.



EX3DV4 - SN:3846

December 20, 2012

Probe EX3DV4

SN:3846

Manufactured: Calibrated:

October 25, 2011 December 20, 2012

Calibrated for DASY/EASY Systems (Note: non-compatible with DASY2 system!)



EX3DV4-SN:3846

December 20, 2012

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3846

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm $(\mu V/(V/m)^2)^A$	0.49	0.44	0.46	± 10.1 %
DCP (mV) ^B	98.5	98.3	99.4	- 1011 70

Modulation Calibration Parameters

UID	Communication System Name	PAR	3.1	A dB	B dB	C dB	VR mV	Unc [±] (k=2)
0	CW	CW 0.00	X	0.0	0.0	1.0	120.0	±1.9 %
			Y	0.0	0.0	1.0	110.6	
			Z	0.0	0.0	1.0	115.4	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

A The uncertainties of NomX,Y,Z do not affect the E²-field uncertainty inside TSL (see Pages 5 and 6).

a Numerical linearization parameter: uncertainty not required.

Uncertainty is determined using the max, deviation from linear response applying rectangular distribution and is expressed for the square of the field value. field value.



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DASY/EASY - Parameters of Probe: EX3DV4 - SN:3846

Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) ^C	Relative Permittivity F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
750	41.9	0.89	9.53	9.53	9.53	0.55	0.72	± 12.0 %
850	41.5	0.92	9.18	9.18	9.18	0.80	0.59	± 12.0 %
900	41.5	0.97	9.01	9.01	9.01	0.55	0.71	± 12.0 %
1750	40.1	1.37	8.39	8.39	8.39	0.46	0.78	± 12.0 %
1810	40.0	1.40	8.20	8.20	8.20	0.43	0.83	± 12.0 %
1900	40.0	1.40	8.01	8.01	8.01	0.46	0.75	± 12.0 %
1950	40.0	1.40	7.73	7.73	7.73	0.33	0.90	± 12.0 %
2000	40.0	1.40	7.94	7.94	7.94	0.65	0.64	± 12.0 %
2100	39.8	1.49	8.06	8.06	8.06	0.65	0.63	± 12.0 %
2300	39.5	1.67	7.56	7.56	7.56	0.49	0.71	± 12.0 %
2450	39.2	1.80	7.13	7.13	7.13	0.51	0.74	± 12.0 %
2550	39.1	1.91	6.78	6.78	6.78	0.42	0.81	± 12.0 %
2600	39.0	1.96	7.00	7.00	7.00	0.42	0.86	± 12.0 %
3500	37.9	2.91	6.63	6.63	6.63	0.35	1.20	± 13.1 %
3700	37.7	3.12	6.55	6.55	6.55	0.32	1.10	± 13.1 %
5200	36.0	4.66	4.68	4.68	4.68	0.40	1.80	± 13.1 %
5500	35.6	4.96	4.43	4.43	4.43	0.40	1.80	± 13.1 %
5800	35.3	5.27	4.28	4.28	4.28	0.45	1.80	± 13.1 %

[©] Frequency validity of \pm 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to \pm 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

F At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to \pm 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to \pm 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.



EX3DV4-SN:3846

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DASY/EASY - Parameters of Probe: EX3DV4 - SN:3846

Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) ^C	Relative Permittivity F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
750	55.5	0.96	9.28	9.28	9.28	0.44	0.85	± 12.0 %
850	55.2	0.99	9.04	9.04	9.04	0.28	1.12	± 12.0 %
900	55.0	1.05	9.01	9.01	9.01	0.59	0.76	± 12.0 %
1750	53.4	1.49	7.63	7.63	7.63	0.33	0.96	± 12.0 %
1810	53.3	1.52	7.50	7.50	7.50	0.46	0.77	± 12.0 %
1900	53.3	1.52	7.37	7.37	7.37	0.54	0.73	± 12.0 %
1950	53.3	1.52	7.56	7.56	7.56	0.45	0.77	± 12.0 %
2000	53.3	1.52	7.50	7.50	7.50	0.37	0.90	± 12.0 %
2100	53.2	1.62	7.64	7.64	7.64	0.35	0.90	± 12.0 %
2300	52.9	1.81	7.20	7.20	7.20	0.61	0.67	± 12.0 %
2450	52.7	1.95	7.00	7.00	7.00	0.76	0.56	± 12.0 %
2550	52.6	2.09	6.89	6.89	6.89	0.80	0.50	± 12.0 %
2600	52.5	2.16	6.72	6.72	6.72	0.80	0.50	± 12.0 %
3500	51.3	3.31	6.39	6.39	6.39	0.45	1.04	± 13.1 %
3700	51.0	3.55	6.17	6.17	6.17	0.53	0.92	± 13.1 %
5200	49.0	5.30	4.37	4.37	4.37	0.45	1.90	± 13.1 %
5500	48.6	5.65	3.89	3.89	3.89	0.50	1.90	± 13.1 %
5800	48.2	6.00	3.92	3.92	3.92	0.50	1.90	± 13.1 %

^C Frequency validity of \pm 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to \pm 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

F At frequencies below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to \pm 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to \pm 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.