C.2 Dasy4 or DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 or DASY5 software reads the reflection durning a software approach and looks for the maximum using 2nd ord curve fitting. The approach is stopped at reaching the maximum.

Probe Specifications:

Picture C.2 Near-field Probe

Model:	**ES3DV3, EX3DV4**
Frequency	**10MHz — 6.0GHz(EX3DV4)**
Range:	**10MHz — 4GHz(ES3DV3)**
Calibration:	**In head and body simulating tissue at Frequencies from 835 up to 5800MHz**
Linearity:	**± 0.2 dB(30 MHz to 6 GHz) for EX3DV4 ± 0.2 dB(30 MHz to 4 GHz) for ES3DV3**
Dynamic Range:	**10 mW/kg — 100W/kg**
Probe Length:	**330 mm**
Probe Tip Length:	**20 mm**
Body Diameter:	**12 mm**
Tip Diameter:	**2.5 mm (3.9 mm for ES3DV3)**
Tip-Center:	**1 mm (2.0mm for ES3DV3)**
Application:	**SAR Dosimetry Testing Compliance tests of mobile phones Dosimetry in strong gradient fields**

Picture C.3 E-field Probe

C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm^2) using an RF Signal generator, TEM cell, and RF Power Meter.

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed

in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/ cm^2.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C\frac{\Delta T}{\Delta t}$$

Where:

Δt = Exposure time (30 seconds),

C = Heat capacity of tissue (brain or muscle),

ΔT = Temperature increase due to RF exposure.

$$SAR = \frac{|E|^2 \cdot \sigma}{\rho}$$

Where:

σ = Simulated tissue conductivity,

ρ = Tissue density (kg/m^3).

C.4 Other Test Equipment

C.4.1 Data Acquisition Electronics(DAE)

The data acquisition electronics consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.
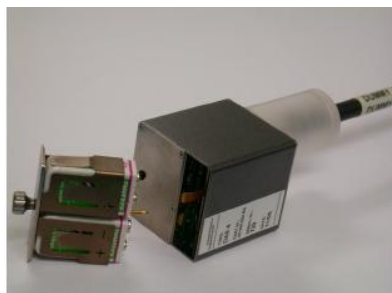
PictureC.4: DAE

C.4.2 Robot

The SPEAG DASY system uses the high precision robots (DASY4: RX90XL; DASY5: RX160L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

➢ High precision (repeatability 0.02mm)
➢ High reliability (industrial design)
➢ Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
➢ Jerk-free straight movements (brushless synchron motors; no stepper motors)
➢ Low ELF interference (motor control fields shielded via the closed metallic construction shields)

Picture C.6 DASY 5

C.4.3 Measurement Server

The Measurement server is based on a PC/104 CPU broad with CPU (dasy4: 166 MHz, Intel Pentium; DASY5: 400 MHz, Intel Celeron), chipdisk (DASY4: 32 MB; DASY5: 128MB), RAM (DASY4: 64 MB, DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O broad, which is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.

Picture C.7 Server for DASY 4

Picture C.8 Server for DASY 5

C.4.4 Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ±0.5mm would produce a SAR uncertainty of ±20%. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss

POM material having the following dielectric

parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.

Picture C.9-1: Device Holder Kit

Picture C.9-2: Laptop Extension

C.4.5 Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to

Represent the 90th percentile of the population. The phantom enables the dissymmetric evaluation of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

Shell Thickness: 2 ± 0. 2 mm

 Filling Volume: Approx. 25 liters

 Dimensions: 810 x l000 x 500 mm (H x L x W)

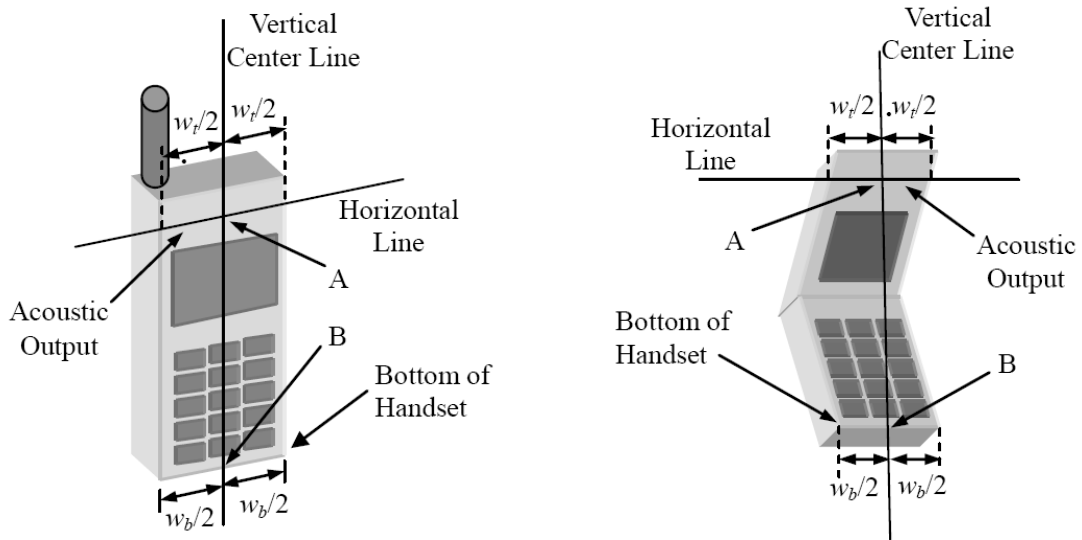 Available: Special

Picture C.10: SAM Twin Phantom

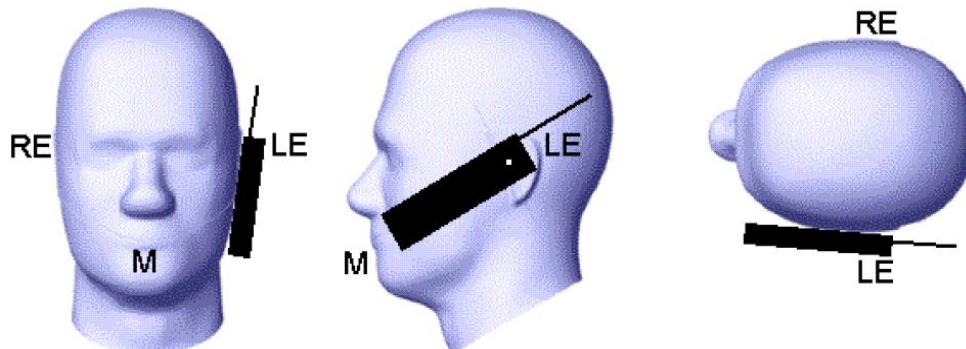## ANNEX D   Position of the wireless device in relation to the phantom

D.1 General considerations

This standard specifies two handset test positions against the head phantom – the "cheek" position and the "tilt" position.


| W_t | Width of the handset at the level of the acoustic |

| W_b | Width of the bottom of the handset |

| A | Midpoint of the width W_t of the handset at the level of the acoustic output |

| B | Midpoint of the width W_b of the bottom of the handset |

Picture D.1-a Typical "fixed" case handset   Picture D.1-b Typical "clam-shell" case handset


Picture D.2 Cheek position of the wireless device on the left side of SAM
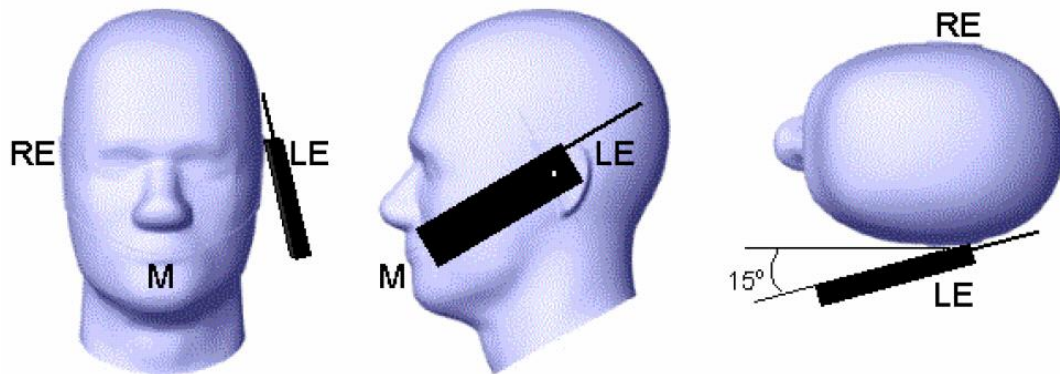
Picture D.3 Tilt position of the wireless device on the left side of SAM

D.2 Body-worn device

A typical example of a body-worn device is a mobile phone, wireless enabled PDA or other battery operated wireless device with the ability to transmit while mounted on a person's body using a carry accessory approved by the wireless device manufacturer.
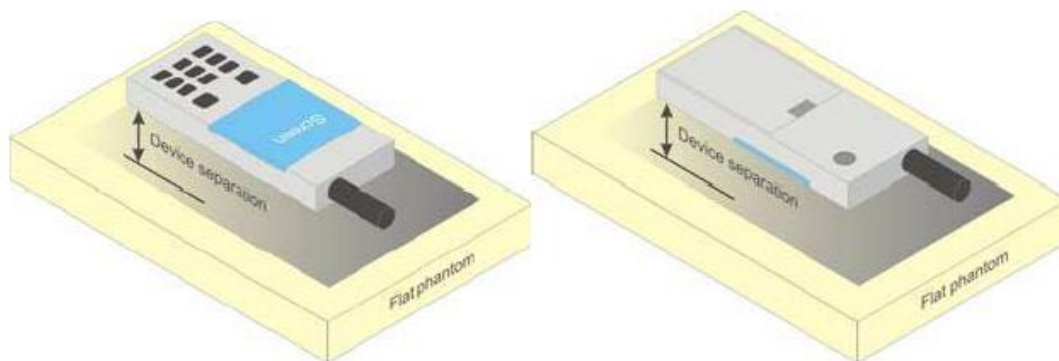

Picture D.4 Test positions for body-worn devices

D.3 Desktop device

A typical example of a desktop device is a wireless enabled desktop computer placed on a table or desk when used.

The DUT shall be positioned at the distance and in the orientation to the phantom that corresponds to the intended use as specified by the manufacturer in the user instructions. For devices that employ an external antenna with variable positions, tests shall be performed for all antenna positions specified. Picture 8.5 show positions for desktop device SAR tests. If the intended use is not specified, the device shall be tested directly against the flat phantom.
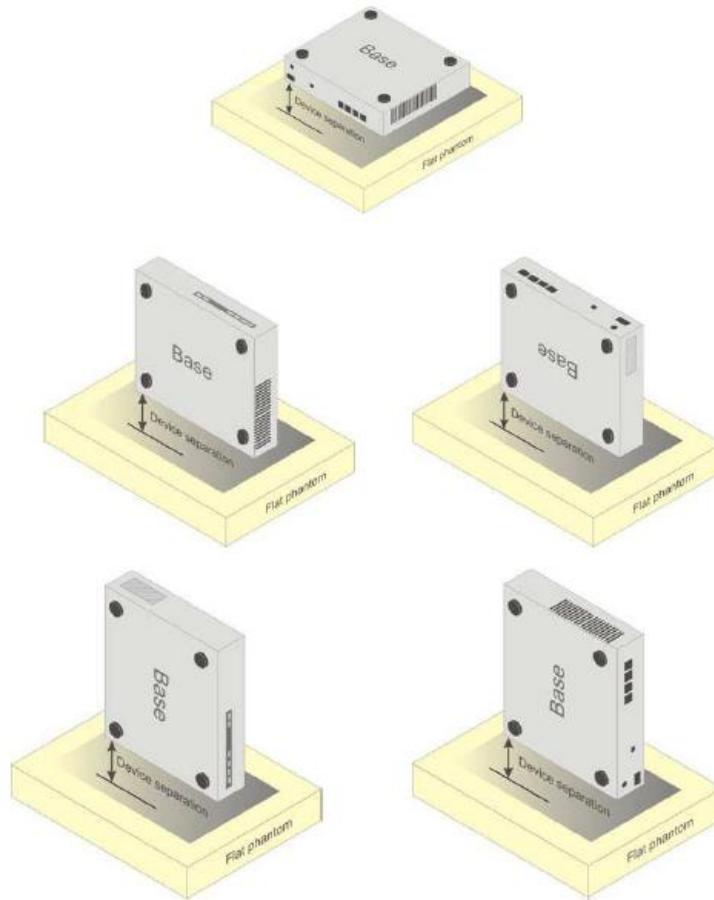
Picture D.5 Test positions for desktop devices

D.4 DUT Setup Photos

Picture D.6

ANNEX E   Equivalent Media Recipes

The liquid used for the frequency range of 800-3000 MHz consisted of water, sugar, salt, preventol, glycol monobutyl and Cellulose. The liquid has been previously proven to be suited for worst-case. The Table E.1 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

Table E.1: Composition of the Tissue Equivalent Matter

Frequency (MHz)	835 Head	835 Body	1900 Head	1900 Body	2450 Head	2450 Body	5800 Head	5800 Body
Ingredients (% by weight)								
Water	41.45	52.5	55.242	69.91	58.79	72.60	65.53	65.53
Sugar	56.0	45.0	\	\	\	\	\	\
Salt	1.45	1.4	0.306	0.13	0.06	0.18	\	\
Preventol	0.1	0.1	\	\	\	\	\	\
Cellulose	1.0	1.0	\	\	\	\	\	\
Glycol Monobutyl	\	\	44.452	29.96	41.15	27.22	\	\
Diethylenglycol monohexylether	\	\	\	\	\	\	17.24	17.24
Triton X-100	\	\	\	\	\	\	17.24	17.24
Dielectric Parameters Target Value	$\varepsilon=41.5$ $\sigma=0.90$	$\varepsilon=55.2$ $\sigma=0.97$	$\varepsilon=40.0$ $\sigma=1.40$	$\varepsilon=53.3$ $\sigma=1.52$	$\varepsilon=39.2$ $\sigma=1.80$	$\varepsilon=52.7$ $\sigma=1.95$	$\varepsilon=35.3$ $\sigma=5.27$	$\varepsilon=48.2$ $\sigma=6.00$

ANNEX F   System Validation

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components.

Table F.1: System Validation

Probe SN.	Liquid name	Validation date	Frequency point	Status (OK or Not)
3151	Head 850MHz	June 12, 2015	850 MHz	OK
3151	Head 1750MHz	June 12, 2015	1750 MHz	OK
3151	Head 1810MHz	June 12, 2015	1810 MHz	OK
3151	Head 1900MHz	June 12, 2015	1900 MHz	OK
3151	Head 2450MHz	June 12, 2015	2450 MHz	OK
3151	Head 2550MHz	June 12, 2015	2550 MHz	OK

ANNEX G   Probe Calibration Certificate

Probe ES3DV3-SN:3151 Calibration Certificate

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Client	CTTL(South Branch)	Certificate No: Z14-97077

CALIBRATION CERTIFICATE

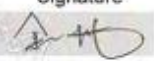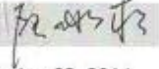|	
Object	ES3DV3 - SN:3151
Calibration Procedure(s)	TMC-OS-E-02-195 Calibration Procedures for Dosimetric E-field Probes
Calibration date:	September 01, 2014

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards		ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter	NRP2	101919	01-Jul-14 (CTTL, No.J14X02146)	Jun-15
Power sensor	NRP-Z91	101547	01-Jul-14 (CTTL, No.J14X02146)	Jun-15
Power sensor	NRP-Z91	101548	01-Jul-14 (CTTL, No.J14X02146)	Jun-15
Reference10dBAttenuator		BT0520	12-Dec-12(TMC,No.JZ12-867)	Dec-14
Reference20dBAttenuator		BT0267	12-Dec-12(TMC,No.JZ12-866)	Dec-14
Reference Probe EX3DV4		SN 3846	03-Sep-13(SPEAG,No.EX3-3846_Sep13)	Sep-14
DAE4		SN 1331	23-Jan-14 (SPEAG, DAE4-1331_Jan14)	Jan -15
Secondary Standards		ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
SignalGeneratorMG3700A		6201052605	01-Jul-14 (CTTL, No.J14X02145)	Jun-15
Network Analyzer E5071C		MY46110673	15-Feb-14 (TMC, No.JZ14-781)	Feb-15

	Name	Function	Signature
Calibrated by:	Yu Zongying	SAR Test Engineer	
Reviewed by:	Qi Dianyuan	SAR Project Leader	
Approved by:	Lu Bingsong	Deputy Director of the laboratory	

Issued: September 02, 2014

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A,B,C,D	modulation dependent linearization parameters
Polarization Φ	Φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i θ=0 is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013

b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z*: Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E^2-field uncertainty inside TSL (see below ConvF).

- *NORM(f)x,y,z = NORMx,y,z* frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.

- *DCPx,y,z*: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.

- *PAR*: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.

- *Ax,y,z; Bx,y,z; Cx,y,z; VRx,y,z*: A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.

- *ConvF and Boundary Effect Parameters*: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from±50MHz to±100MHz.

- *Spherical isotropy (3D deviation from isotropy)*: in a field of low gradients realized using a flat phantom exposed by a patch antenna.

- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

- *Connector Angle*: The angle is assessed using the information gained by determining the *NORMx* (no uncertainty required).

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Probe ES3DV3

SN: 3151

Calibrated: September 01, 2014

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

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DASY – Parameters of Probe: ES3DV3 - SN: 3151

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm(μV/(V/m)^2)^A	1.11	1.20	1.14	±10.8%
DCP(mV)^B	103.4	103.3	102.9	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB√μV	C	D dB	VR mV	Unc^E (k=2)
0	CW	X	0.0	0.0	1.0	0.00	264.1	±2.3%
		Y	0.0	0.0	1.0		275.7	
		Z	0.0	0.0	1.0		268.7	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

^{A} The uncertainties of Norm X, Y, Z do not affect the E^2-field uncertainty inside TSL (see Page 5 and Page 6).
^{B} Numerical linearization parameter: uncertainty not required.
^{E} Uncertainly is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

DASY – Parameters of Probe: ES3DV3 - SN: 3151

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Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz]^C	Relative Permittivity ^{F}	Conductivity (S/m) ^{F}	ConvF X	ConvF Y	ConvF Z	Alpha^G	Depth^G (mm)	Unct. (k=2)
850	41.5	0.92	6.04	6.04	6.04	0.41	1.49	±12%
900	41.5	0.97	6.17	6.17	6.17	0.38	1.55	±12%
1810	40.0	1.40	5.44	5.44	5.44	0.57	1.49	±12%
1900	40.0	1.40	5.16	5.16	5.16	0.74	1.25	±12%
2000	40.0	1.40	5.23	5.23	5.23	0.50	1.57	±12%
2100	39.8	1.49	5.25	5.25	5.25	0.74	1.24	±12%
2300	39.5	1.67	4.91	4.91	4.91	0.73	1.21	±12%
2450	39.2	1.80	4.71	4.71	4.71	0.82	1.16	±12%
2600	39.0	1.96	4.57	4.57	4.57	0.89	1.14	±12%

^{C} Frequency validity of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.
^{F} At frequency below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.
^{G} Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

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DASY – Parameters of Probe: ES3DV3 - SN: 3151

Calibration Parameter Determined in Body Tissue Simulating Media

f [MHz]^C	Relative Permittivity ^{F}	Conductivity (S/m) ^{F}	ConvF X	ConvF Y	ConvF Z	Alpha^G	Depth^G (mm)	Unct. (k=2)
850	55.2	0.99	6.14	6.14	6.14	0.34	1.78	±12%
900	55.0	1.05	6.08	6.08	6.08	0.51	1.43	±12%
1810	53.3	1.52	5.03	5.03	5.03	0.52	1.54	±12%
1900	53.3	1.52	4.77	4.77	4.77	0.48	1.66	±12%
2000	53.3	1.52	5.00	5.00	5.00	0.68	1.33	±12%
2100	53.2	1.62	5.04	5.04	5.04	0.73	1.32	±12%
2300	52.9	1.81	4.56	4.56	4.56	0.58	1.57	±12%
2450	52.7	1.95	4.42	4.42	4.42	0.67	1.39	±12%
2600	52.5	2.16	4.26	4.26	4.26	0.69	1.37	±12%

^{C} Frequency validity of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.
^{F} At frequency below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.
^{G} Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

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Frequency Response of E-Field
### (TEM-Cell: ifi110 EXX, Waveguide: R22)

TEM   f [MHz]   R22
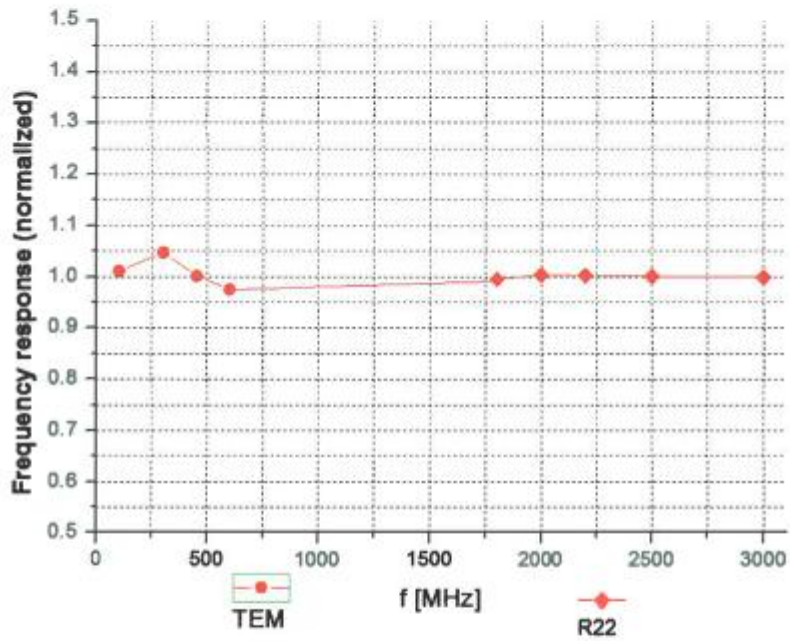
Uncertainty of Frequency Response of E-field: ±7.5% (k=2)

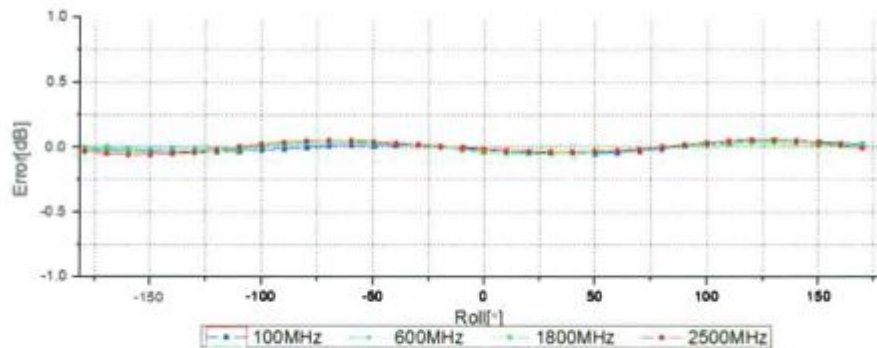Certificate No: Z14-97077   Page 7 of 11

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Receiving Pattern (Φ), θ=0°

f=600 MHz, TEM
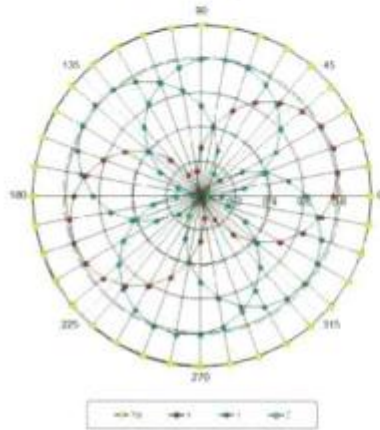
f=1800 MHz, R22

Uncertainty of Axial Isotropy Assessment: ±0.9% (k=2)

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Dynamic Range f(SAR_head)
(TEM cell, f = 900 MHz)
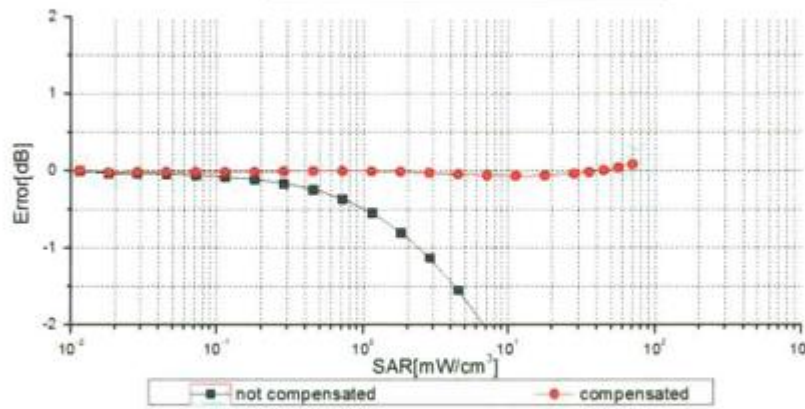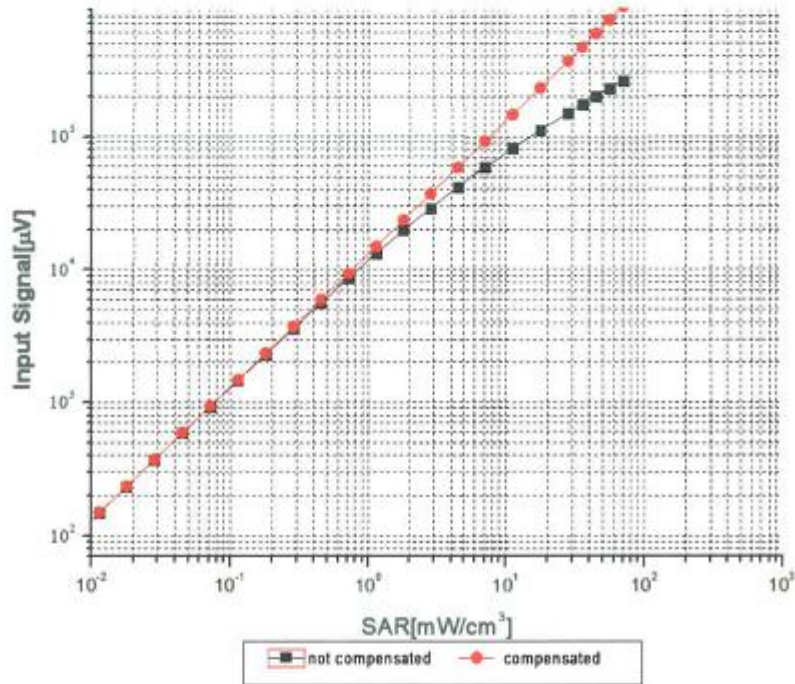
Uncertainty of Linearity Assessment: ±0.9% (k=2)
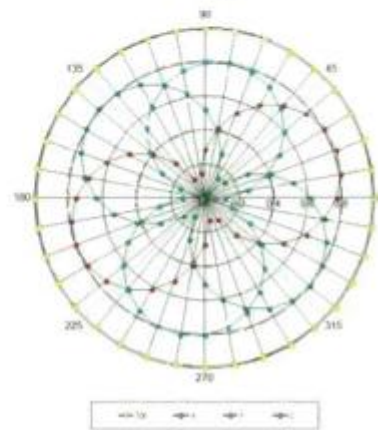
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Conversion Factor Assessment

f=900 MHz, WGLS R9(H_convF)

f=1810 MHz, WGLS R22(H_convF)

Deviation from Isotropy in Liquid

Uncertainty of Spherical Isotropy Assessment: ±2.8% (K=2)

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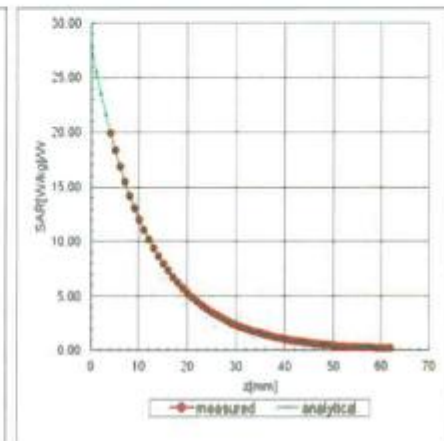**s p e a g**
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DASY - Parameters of Probe: ES3DV3 - SN: 3151

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	85.2
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disable
Probe Overall Length	337mm
Probe Body Diameter	10mm
Tip Length	10mm
Tip Diameter	4mm
Probe Tip to Sensor X Calibration Point	2mm
Probe Tip to Sensor Y Calibration Point	2mm
Probe Tip to Sensor Z Calibration Point	2mm
Recommended Measurement Distance from Surface	3mm

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ANNEX H   DIPOLE CALIBRATION CERTIFICATE

850 MHz Dipole Calibration Certificate

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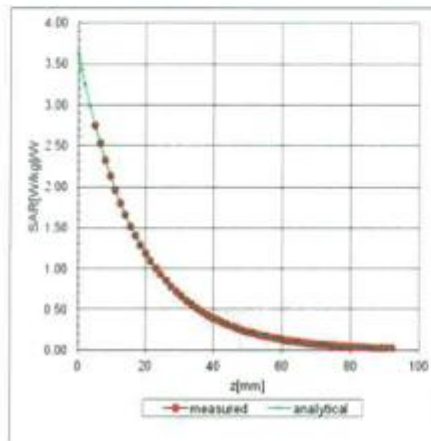
受控文件

ilac-MRA CNAS
CALIBRATION
No. L0570

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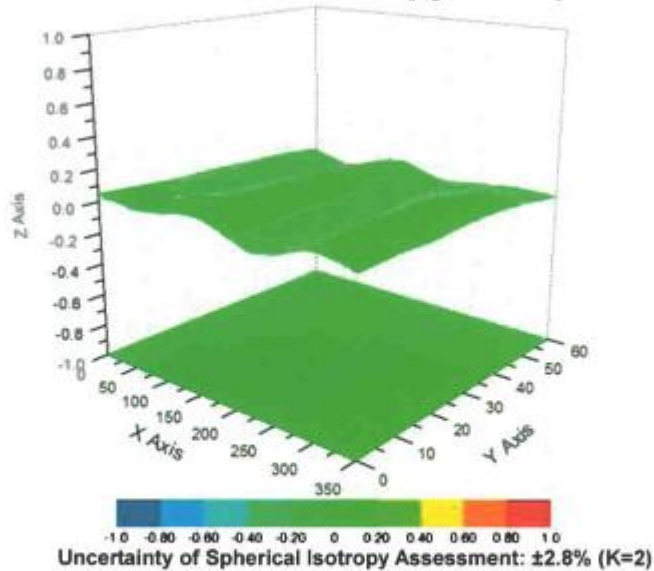E-mail: cttl@chinattl.com   Http://www.chinattl.cn

| Client | CTTL(South Branch) | | Certificate No: | Z14-97127 |

CALIBRATION CERTIFICATE

Object	D835V2 - SN: 4d057
Calibration Procedure(s)	TMC-OS-E-02-194 Calibration Procedures for dipole validation kits
Calibration date:	November 4, 2014

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)℃ and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	01-Jul-14 (CTTL, No.J14X02146)	Jun-15
Power sensor NRP-Z91	101547	01-Jul-14 (CTTL, No.J14X02146)	Jun-15
Reference Probe EX3DV4	SN 3617	28-Aug-14(SPEAG,No.EX3-3617_Aug14)	Aug-15
DAE4	SN 1331	23-Jan-14 (SPEAG, DAE4-1331_Jan14)	Jan-15
Secondary Standards	**ID #**	**Cal Date(Calibrated by, Certificate No.)**	**Scheduled Calibration**
SignalGeneratorMG3700A	6201052605	01-Jul-14 (CTTL, No.J14X02145)	Jun-15
Network Analyzer E5071C	MY4614d0573	15-Feb-14 (TMC, No.JZ14-781)	Feb-15

	Name	Function	Signature
Calibrated by:	Zhao Jing	SAR Test Engineer	
Reviewed by:	Qi Dianyuan	SAR Project Leader	
Approved by:	Lu Bingsong	Deputy Director of the laboratory	

Issued: November 6, 2014

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORMx,y,z
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:
a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) For hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
c) KDB865664, SAR Measurement Requirements for 100 MHz to 6 GHz

Additional Documentation:
d) DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:
- *Measurement Conditions:* Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- *Antenna Parameters with TSL:* The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- *Feed Point Impedance and Return Loss:* These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- *SAR measured:* SAR measured at the stated antenna input power.
- *SAR normalized:* SAR as measured, normalized to an input power of 1 W at the antenna connector.
- *SAR for nominal TSL parameters:* The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY52	52.8.8.1222
Extrapolation	Advanced Extrapolation	
Phantom	Triple Flat Phantom 5.1C	
Distance Dipole Center - TSL	15 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	835 MHz ± 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	41.5	0.90 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	40.8 ± 6 %	0.92 mho/m ± 6 %
Head TSL temperature change during test	<1.0 °C	----	----

SAR result with Head TSL

SAR averaged over 1 cm^3 (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	2.41 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	**9.48 mW /g ± 20.8 % (k=2)**
SAR averaged over 10 cm^3 (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	1.57 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	**6.20 mW /g ± 20.4 % (k=2)**

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	55.2	0.97 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	55.3 ± 6 %	0.99 mho/m ± 6 %
Body TSL temperature change during test	<1.0 °C	----	----

SAR result with Head TSL

SAR averaged over 1 cm^3 (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	2.42 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	**9.53 mW /g ± 20.8 % (k=2)**
SAR averaged over 10 cm^3 (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	1.61 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	**6.36 mW /g ± 20.4 % (k=2)**

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