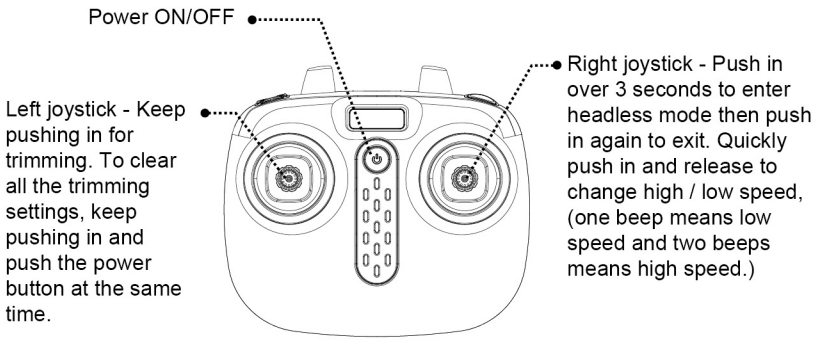
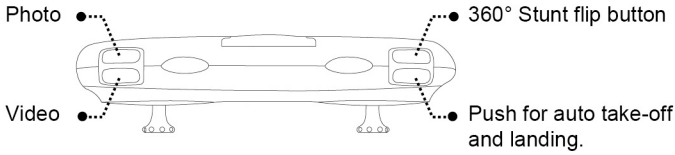
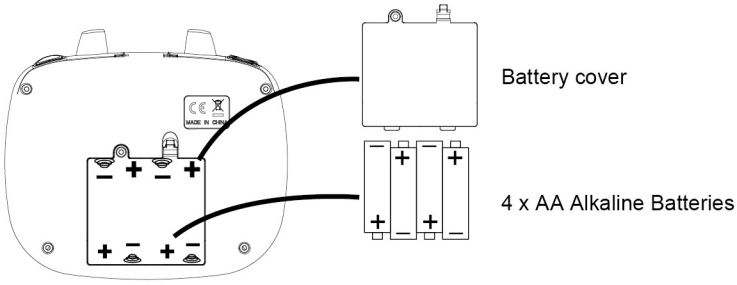
Understanding Your Remote Control

Remote control's button function description:





Battery installation for remote control:



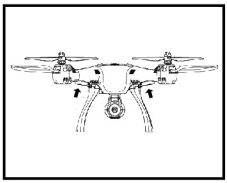
1. Battery Installation Method: Open up the battery cover at the back of the remote control. Correctly place 4 x AA alkaline batteries in the battery box in strict adherence to the polarity instructions (the AA alkaline batteries are not included).

1. During the battery installation, it must be ensured that the polarities of the batteries are matched with that of the battery box. No battery shall be installed with the opposite polarity.
2. Do not use new and old batteries together.
3. Do not use different types of batteries together.
4. Do not use rechargeable batteries.

Product features

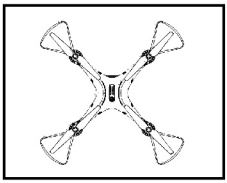
1. Low-voltage Protection:

When the four indicator lights at the bottom of the drone start flashing, it means that the drone's battery power is low. At this time, the drone will initiate the height-limiting function and will descend to a safe altitude.



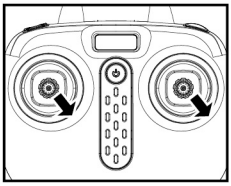
2. Over-current Protection:

If the drone encounters a direct impact from a foreign object,or is obstructed, or if the blades are not rotating, the drone will go into over-current protection mode.



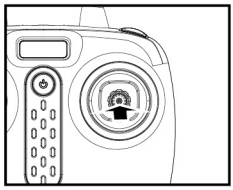
3. Level Calibration Function:

Place the drone on a level surface and at the same time, push both left and right joysticks to the lower right corners for 2 to 3 seconds; the led light indicator on the drone will blink rapidly, and it will return back to the normal status after about 2 to 3 seconds. The level calibration is successful.



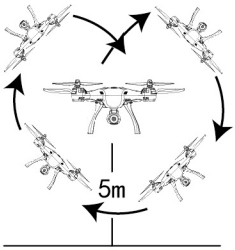
4. Fast/Slow Speed Function:

Slow speed by default when first powered-on. Possible to switch the function mode of fast/slow speed by pressing in on the right joystick for a short time. It is switched into fast speed mode when two “beep” sounds come from the remote control,pressing in on the right joystick for a short time under fast speed mode and then one “beep” sound would come from the remote control, then it is then switched back into slow speed mode.



5. 360° Stunt Flip Function:

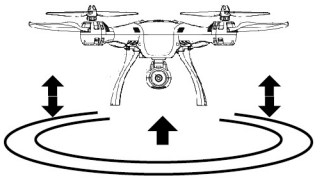
When you are familiar with the basic actions, you can proceed to explore even more exciting stunt actions. Fly the drone to a height of 20 feet above the ground, push the upper right corner button (Stunt Flip Button) on the remote control and simultaneously push the right joystick to the farthest position of Front/Back/Left/Right, the drone will now execute the Front/Back/Left/Right stunt flip action.



Note: Drone will have the best stunt flip action when the batteries are fully charged.

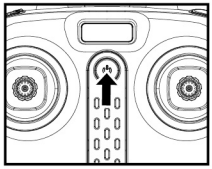
6. Auto Hover Function:

After using the left joystick (throttle) to control the ascending / descending flight of the drone, release the left joystick (accelerator) and the drone will hover at that height when the joystick is released.

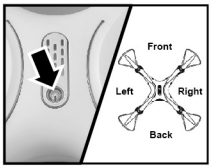


7. Headless function:

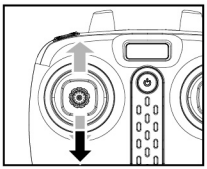
A. Defining forward direction:



1. Push on the power button of the remote control.

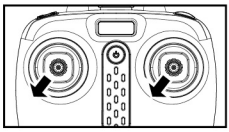


2. After connecting the drone to the power supply, push the switch to “ON” position, and adjust the specified direction of the drone’s head under the headless mode as the new forward direction.



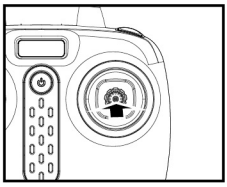
3. Push the left joystick (throttle) on the remote control up to the farthest position and then pull down to the farthest position. When the remote control issues a long beep sound, it means the frequency and defining forward direction functions are completed.

B. Calibration for the definition of the front:



1. When the drone encounters a direct impact with foreign objects in the headless mode, if there is an occurrence of deviation of the defined direction, it is only required to push both the left and right joysticks to the bottom left corners simultaneously after placing the flying direction of the drone in the correction position. When the led light indicator of the drone is in a long “ON” mode after slowly flashing for 3 seconds, it indicates the calibration is complete.

C. Toggling between headless function and normal function:



1. After the drone is matched with the corresponding frequency, the drone would be in normal pattern by default. At this time the indicator light on the drone would be in a state of on for a long time. After pressing in on the right joystick of the remote control for 2 seconds, the remote control would make a sound of “beep, beep, beep” to show that it has entered into a state of headless mode.Pressing in on right joystick for 2 seconds then a long sound of “beep” would be heard to show an exit status.(When under the state of headless mode, four indicator lights on the drone are led lights which flicker once every four seconds)