



<b>SAR TEST REPORT</b> <b>FCC 47 CFR Part 2.1093</b> <b>Industry Canada RSS-102</b> <b>RF-Exposure evaluation of portable equipment</b>	
<b>Report Reference No.</b> .....	G0M-1309-3226-TFC093S-V01
<b>Testing Laboratory</b> .....	Eurofins Product Service GmbH
Address .....	Storkower Str. 38c 15526 Reichenwalde Germany
Accreditation .....	<div style="display: flex; justify-content: center; align-items: center;">   </div> <p style="text-align: center; font-size: small;">                     A2LA Accredited Testing Laboratory, Certificate No.: 1983.01                      FCC Filed Test Laboratory, Reg.-No.: 96970                      IC OATS Filing assigned code: 3470A                 </p>
<b>Applicant's name</b> .....	Biotronik SE & Co. KG
Address .....	Woermannkehre 1 12359 Berlin GERMANY
<b>Test specification:</b>	
Standard.....	FCC 47 CFR Part 2 §2.1093 FCC OET Bulletin 65 Supplement C 01-01 IEEE Std. 1528 - 2003 IC RSS-102 Issue 4 Safety Code 6 (2009)
Non-standard test method.....	None
Test scope.....	complete Radio compliance test
<b>Equipment under test (EUT):</b>	
Product description	Telemonitoring System
Model No.	CardioMessenger Smart 3G
Hardware version	CardioMessenger Smart 3G mit LP, Best.LP1/TelexSmart3G, LP, Best.LP1/TelexSmart3G_JP Rev. Dx
Firmware / Software version	SMARTAPP 1.x
	FCC-ID: QRICMSMART                      IC: 4708A-CMSMART
<b>Test result</b>	<b>Passed</b>

**Possible test case verdicts:**

- neither assessed nor tested .....: N/N
- required by standard but not appl. to test object.....: N/A
- required by standard but not tested.....: N/T
- not required by standard for the test object .....: N/R
- test object does meet the requirement.....: P (Pass)
- test object does not meet the requirement.....: F (Fail)

**Testing:**

Date of receipt of test item .....: 2013-11-19

Date (s) of performance of tests .....: 2013-11-27 - 2013-12-05

Compiled by ..... : Christian Weber

Tested by (+ signature).....: Burkhard Pudell *i.v. Pudell*

(Testing Manager) .....

Approved by (+ signature) .....: Christian Weber *C. Locher*

(Test Lab Manager) .....

Date of issue .....: 2013-12-17

Total number of pages.....: 122

**General remarks:**

**The test results presented in this report relate only to the object tested.**

**The results contained in this report reflect the results for this particular model and serial number. It is the responsibility of the manufacturer to ensure that all production models meet the intent of the requirements detailed within this report.**

This report shall not be reproduced, except in full, without the written approval of the Issuing testing laboratory.

**Additional comments:**


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Test Report No.: G0M-1309-3226-TFC093S-V01

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Eurofins Product Service GmbH  
 Storkower Str. 38c, D-15526 Reichenwalde, Germany

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## Version History

Version	Issue Date	Remarks	Revised by
01	2013-12-17	Initial Release	

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## 1 Equipment (Test item) Description

<b>Description</b>	Telemonitoring System	
<b>Model</b>	CardioMessenger Smart 3G	
<b>Serial number</b>	None	
<b>Hardware version</b>	CardioMessenger Smart 3G mit LP, Best.LP1/TelexSmart3G, LP, Best.LP1/TelexSmart3G_JP Rev. Dx	
<b>Software / Firmware version</b>	SMARTAPP 1.x	
<b>FCC-ID</b>	QRICMSMART	
<b>IC</b>	4708A-CMSMART	
<b>Equipment type</b>	End product	
<b>Prototype or production unit</b>	Identical Prototype	
<b>Device category</b>	Handset	
<b>Environment</b>	General public	
<b>Radio technologies</b>	MedRadio GSM/GRPS850, Power Class 4, Multislot Class 8 EGPRS850, Power Class E2, Multislot Class 8 GSM/GRPS1900, Power Class 1, Multislot Class 8 EGPRS1900, Power Class E2, Multislot Class 8 WCDMA FDDII, Power Class 3 WCDMA FDDIV, Power Class 3 WCDMA FDDV, Power Class 3 HSDPA HSUPA	
<b>Operating frequency ranges</b>	MedRadio : 402 MHz – 405 MHz GRPS / EGPRS 850 : 824 MHz - 849 MHz GRPS / EGPRS 1900 : 1850 MHz - 1910 MHz WCDMA FDDII : 1850 MHz - 1910 MHz WCDMA FDDIV : 1710 MHz - 1755 MHz WCDMA FDDV : 824 MHz - 849 MHz	
<b>Antenna MedRadio</b>	Type	integrated
	Model	pcb antenna
	Manufacturer	Biotronik SE & Co. KG
	Gain	-5 dBi
<b>Antenna GPRS / EGPRS / WCDMA</b>	Type	integrated
	Model	pcb antenna
	Manufacturer	Biotronik SE & Co. KG
	Gain	GSM 850 = 1.6 dBi GPRS 1900 = 2.4 dBi FDDV = 1.6 dBi FDDII = 2.4 dBi FDDIV = 3.2 dBi

<b>Power supply</b>	V <sub>NOM</sub>	3.7 VDC (Lithium Battery)
<b>AC/DC-Adaptor</b>	Model	N/A
	Vendor	N/A
	Input	N/A
	Output	N/A
<b>Accessories</b>	None	
<b>Manufacturer</b>	Biotronik SE & Co. KG Woermannkehre 1 12359 Berlin Germany	

1.1 Equipment photos





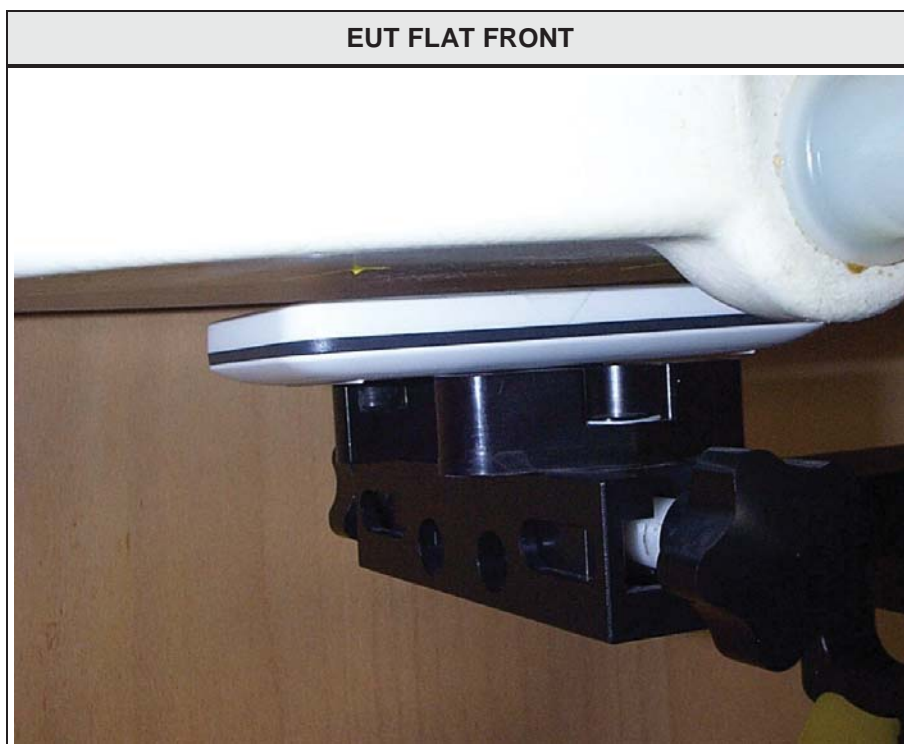
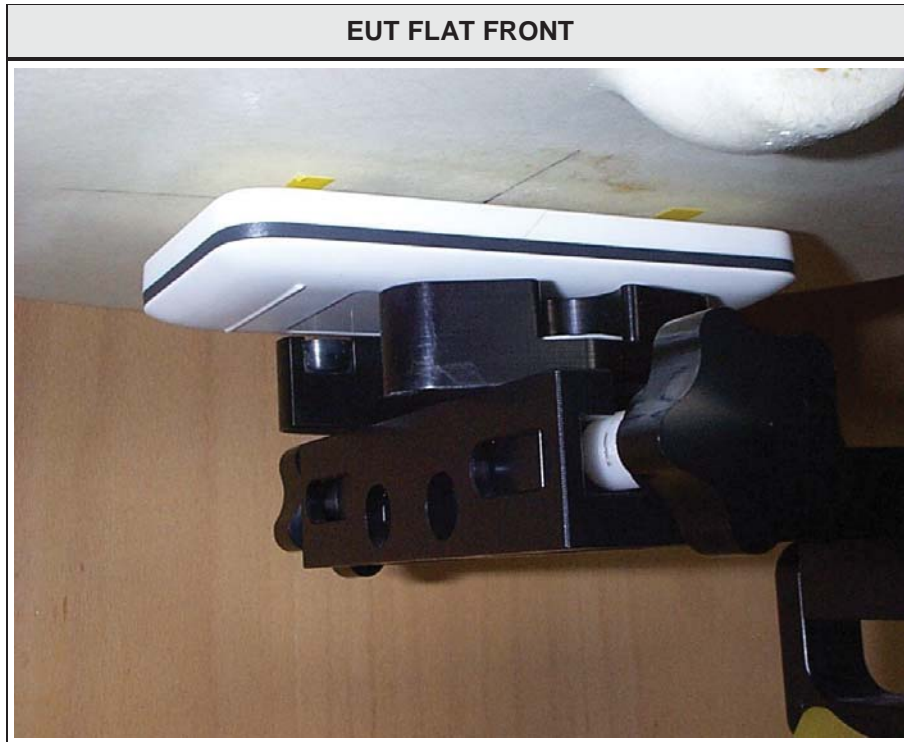
EUT SIDE VIEW



EUT ID



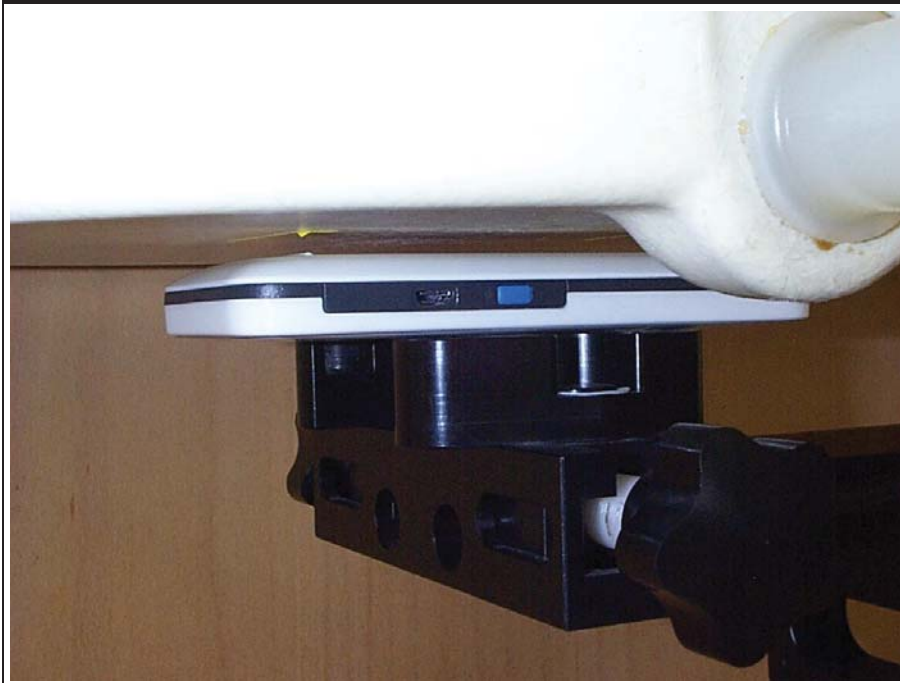
1.2 Equipment setup photos



EUT FLAT BACK



EUT FLAT BACK



### 1.3 Reference Documents

Document
KDB Publication 447498 D01 v05r01 : Mobile and Portable Device RF Exposure Procedures and Equipment Authorization Polices
KDB Publication 648474 D04 v01r01 : SAR Evaluation Considerations for Wireless Handsets
KDB Publication 865664 D01 v01r01 : SAR measurement procedures for devices operating between 100 MHz to 6 GHz
KDB Publication 941225 D01 v02: SAR Measurement Procedures for 3G Devices
KDB Publication 941225 D02 v02r01: 3GPP R6 HSPA and R7 HSPA+ SAR Guidance
KDB Publication 941225 D03 v01: Recommended SAR Test Reduction Procedures for GSM/GPRS/EDGE
KDB Publication 941225 D05 v02r01: SAR Test Consideration for LTE Devices
KDB Publication 248227 D01 v01r02 : SAR Measurement Procedures for 802.11 a/b/g Transmitters
KDB Publication 450824 D02 v01r01 : Dipole Requirements for SAR System Validation and Verification

**1.4 Supporting Equipment Used During Testing**

Product Type*	Device	Manufacturer	Model No.	Comments
None				
<p><b>*Note:</b> Use the following abbreviations:</p> <p style="padding-left: 40px;">AE : Auxiliary/Associated Equipment, or</p> <p style="padding-left: 40px;">SIM : Simulator (Not Subjected to Test)</p> <p style="padding-left: 40px;">CABL : Connecting cables</p>				

**1.5 Supported standalone operating modes**

<b>Mode</b>	<b>Modulation</b>	<b>Frequency range</b>	<b>Max. Duty cycle</b>
MedRadio	FSK	402.45 – 404.85 MHz	100 %
GSM/GPRS850	GMSK	824.2 - 848.8 MHz	12.5 %
EGPRS850	GMSK, 8-PSK	824.2 - 848.8 MHz	12.5 %
GSM/GPRS1900	GMSK	1850.2 - 1909.8 MHz	12.5 %
EGPRS1900	GMSK, 8-PSK	1850.2 - 1909.8 MHz	12.5 %
UMTS FDDII	QPSK	1852.4 - 1907.6 MHz	100 %
UMTS FDDIV	QPSK	1712.4 – 1752.6 MHz	100 %
UMTS FDDV	QPSK	826.4 - 846.6 MHz	100 %

## 1.6 Conducted Power Values

### MedRadio

MedRadio		
Channel	Frequency [MHz]	Source-based time averaged Power [dBm]
8	402.45	-10.9
0	403.65	-12.0
7	404.85	-12.5

### GPRS/EGPRS

GSM850																
Band	Mode	Channel	Frequency [MHz]	Coding	Traffic Mode	Number Timeslots	Power Level	Power TS 1 [dBm]	Power TS 2 [dBm]	Power TS 3 [dBm]	Power TS 4 [dBm]	Power TS 5 [dBm]	Power TS 6 [dBm]	Power TS 7 [dBm]	Power TS 8 [dBm]	Source-based time average Power [dBm]
850	GSM	128	824,2	FR V1	FR V1	1	PCL 5									
850	GSM	190	836,6	FR V1	FR V1	1	PCL 5									
850	GSM	251	848,0	FR V1	FR V1	1	PCL 5									
850	GPRS	128	824,2	CS1	Test Mode A	1	GAMMA 3	31,35								22,32
850	GPRS	188	836,2	CS1	Test Mode A	1	GAMMA 3	31,53								22,50
850	GPRS	251	848,0	CS1	Test Mode A	1	GAMMA 3	31,60								22,57
850	GPRS	128	824,2	CS1	Test Mode A	2	GAMMA 3									
850	GPRS	188	836,2	CS1	Test Mode A	2	GAMMA 3									
850	GPRS	251	848,0	CS1	Test Mode A	2	GAMMA 3									
850	GPRS	128	824,2	CS1	Test Mode A	3	GAMMA 3									
850	GPRS	190	836,6	CS1	Test Mode A	3	GAMMA 3									
850	GPRS	251	848,0	CS1	Test Mode A	3	GAMMA 3									
850	GPRS	128	824,2	CS1	Test Mode A	4	GAMMA 3									
850	GPRS	190	836,6	CS1	Test Mode A	4	GAMMA 3									
850	GPRS	251	848,0	CS1	Test Mode A	4	GAMMA 3									
850	EGPRS	128	824,2	MCS1	Test Mode A	1	GAMMA 3									
850	EGPRS	190	836,6	MCS1	Test Mode A	1	GAMMA 3									
850	EGPRS	251	848,0	MCS1	Test Mode A	1	GAMMA 3									
850	EGPRS	128	824,2	MCS1	Test Mode A	2	GAMMA 3									
850	EGPRS	190	836,6	MCS1	Test Mode A	2	GAMMA 3									
850	EGPRS	251	848,0	MCS1	Test Mode A	2	GAMMA 3									
850	EGPRS	128	824,2	MCS1	Test Mode A	3	GAMMA 3									
850	EGPRS	190	836,6	MCS1	Test Mode A	3	GAMMA 3									
850	EGPRS	251	848,0	MCS1	Test Mode A	3	GAMMA 3									
850	EGPRS	128	824,2	MCS1	Test Mode A	4	GAMMA 3									
850	EGPRS	190	836,6	MCS1	Test Mode A	4	GAMMA 3									
850	EGPRS	251	848,0	MCS1	Test Mode A	4	GAMMA 3									
850	EGPRS	128	824,2	MCS5	Test Mode A	1	GAMMA 6	26,14								17,11
850	EGPRS	188	836,2	MCS5	Test Mode A	1	GAMMA 6	26,16								17,13
850	EGPRS	251	848,0	MCS5	Test Mode A	1	GAMMA 6	26,14								17,11
850	EGPRS	128	824,2	MCS5	Test Mode A	2	GAMMA 6									
850	EGPRS	188	836,2	MCS5	Test Mode A	2	GAMMA 6									
850	EGPRS	251	848,0	MCS5	Test Mode A	2	GAMMA 6									
850	EGPRS	128	824,2	MCS5	Test Mode A	3	GAMMA 6									
850	EGPRS	190	836,6	MCS5	Test Mode A	3	GAMMA 6									
850	EGPRS	251	848,0	MCS5	Test Mode A	3	GAMMA 6									
850	EGPRS	128	824,2	MCS5	Test Mode A	4	GAMMA 6									
850	EGPRS	190	836,6	MCS5	Test Mode A	4	GAMMA 6									
850	EGPRS	251	848,0	MCS5	Test Mode A	4	GAMMA 6									

GSM1900																
Band	Mode	Channel	Frequency [MHz]	Coding	Traffic Mode	Number Timeslots	Power Level	Power TS 1 [dBm]	Power TS 2 [dBm]	Power TS 3 [dBm]	Power TS 4 [dBm]	Power TS 5 [dBm]	Power TS 6 [dBm]	Power TS 7 [dBm]	Power TS 8 [dBm]	Source-based time average Power [dBm]
1900	GSM	512	1850,2	FR V1	FR V1	1	PCL 0									
1900	GSM	661	1880,0	FR V1	FR V1	1	PCL 0									
1900	GSM	810	1909,8	FR V1	FR V1	1	PCL 0									
1900	GPRS	512	1850,2	CS1	Test Mode A	1	GAMMA 3	29,30								20,27
1900	GPRS	661	1880,0	CS1	Test Mode A	1	GAMMA 3	29,11								20,08
1900	GPRS	810	1909,8	CS1	Test Mode A	1	GAMMA 3	28,85								19,82
1900	GPRS	512	1850,2	CS1	Test Mode A	2	GAMMA 3									
1900	GPRS	661	1880,0	CS1	Test Mode A	2	GAMMA 3									
1900	GPRS	810	1909,8	CS1	Test Mode A	2	GAMMA 3									
1900	GPRS	512	1850,2	CS1	Test Mode A	3	GAMMA 3									
1900	GPRS	661	1880,0	CS1	Test Mode A	3	GAMMA 3									
1900	GPRS	810	1909,8	CS1	Test Mode A	3	GAMMA 3									
1900	GPRS	512	1850,2	CS1	Test Mode A	4	GAMMA 3									
1900	GPRS	661	1880,0	CS1	Test Mode A	4	GAMMA 3									
1900	GPRS	810	1909,8	CS1	Test Mode A	4	GAMMA 3									
1900	EGPRS	512	1850,2	MCS1	Test Mode A	1	GAMMA 3									
1900	EGPRS	661	1880,0	MCS1	Test Mode A	1	GAMMA 3									
1900	EGPRS	810	1909,8	MCS1	Test Mode A	1	GAMMA 3									
1900	EGPRS	512	1850,2	MCS1	Test Mode A	2	GAMMA 3									
1900	EGPRS	661	1880,0	MCS1	Test Mode A	2	GAMMA 3									
1900	EGPRS	810	1909,8	MCS1	Test Mode A	2	GAMMA 3									
1900	EGPRS	512	1850,2	MCS1	Test Mode A	3	GAMMA 3									
1900	EGPRS	661	1880,0	MCS1	Test Mode A	3	GAMMA 3									
1900	EGPRS	810	1909,8	MCS1	Test Mode A	3	GAMMA 3									
1900	EGPRS	512	1850,2	MCS1	Test Mode A	4	GAMMA 3									
1900	EGPRS	661	1880,0	MCS1	Test Mode A	4	GAMMA 3									
1900	EGPRS	810	1909,8	MCS1	Test Mode A	4	GAMMA 3									
1900	EGPRS	512	1850,2	MCS5	Test Mode A	1	GAMMA 5	24,53								15,50
1900	EGPRS	661	1880,0	MCS5	Test Mode A	1	GAMMA 5	24,54								15,51
1900	EGPRS	810	1909,8	MCS5	Test Mode A	1	GAMMA 5	24,56								15,53
1900	EGPRS	512	1850,2	MCS5	Test Mode A	2	GAMMA 5									
1900	EGPRS	661	1880,0	MCS5	Test Mode A	2	GAMMA 5									
1900	EGPRS	810	1909,8	MCS5	Test Mode A	2	GAMMA 5									
1900	EGPRS	512	1850,2	MCS5	Test Mode A	3	GAMMA 5									
1900	EGPRS	661	1880,0	MCS5	Test Mode A	3	GAMMA 5									
1900	EGPRS	810	1909,8	MCS5	Test Mode A	3	GAMMA 5									
1900	EGPRS	512	1850,2	MCS5	Test Mode A	4	GAMMA 5									
1900	EGPRS	661	1880,0	MCS5	Test Mode A	4	GAMMA 5									
1900	EGPRS	810	1909,8	MCS5	Test Mode A	4	GAMMA 5									

WCDMA/HSDPA/HSUPA

The conducted power values for the various operating modes of the Wireless LAN transmitter were measured according to KDB 941225 D01 v02:

W-CDMA FDD V														
Uplink UARFCN	Uplink Frequency [MHz]	Source-based time averaged Power [dBm]												
		RMC 12.2 kbps	RMC 64 kbps	RMC 144 kbps	RMC 384 kbps	HSDPA Subtest 1	HSDPA Subtest 2	HSDPA Subtest 3	HSDPA Subtest 4	HSUPA Subtest 1	HSUPA Subtest 2	HSUPA Subtest 3	HSUPA Subtest 4	HSUPA Subtest 5
						$B_c=2 / B_d=15$	$B_c=11 / B_d=15$	$B_c=15 / B_d=8$	$B_c=15 / B_d=4$	$B_c=10 / B_d=15$ $\Delta E-DPCCH=6$ AG Index = 20 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=6 / B_d=15$ $\Delta E-DPCCH=8$ AG Index = 12 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=15 / B_d=9$ $\Delta E-DPCCH=8$ AG Index = 15 No. E-TFCIs = 2 E-TFCI = 11, 92	$B_c=2 / B_d=15$ $\Delta E-DPCCH=5$ AG Index = 17 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=14 / B_d=15$ $\Delta E-DPCCH=7$ AG Index = 21 No. E-TFCIs = 5 E-TFCI = 11, 67
4133	826,6	22,40	22,25	22,20	21,93	22,97	23,08	22,57	22,51	22,95	21,67	21,23	21,30	22,99
4175	835,0	<b>22,46</b>	22,20	22,18	22,27	<b>23,16</b>	23,12	22,74	22,55	22,95	21,42	21,15	21,45	23,02
4232	846,4	<b>22,46</b>	22,33	22,10	22,13	22,96	23,00	22,49	22,50	<b>23,21</b>	21,39	21,21	21,72	23,18

W-CDMA FDD II														
Uplink UARFCN	Uplink Frequency [MHz]	Source-based time averaged Power [dBm]												
		RMC 12.2 kbps	RMC 64 kbps	RMC 144 kbps	RMC 384 kbps	HSDPA Subtest 1	HSDPA Subtest 2	HSDPA Subtest 3	HSDPA Subtest 4	HSUPA Subtest 1	HSUPA Subtest 2	HSUPA Subtest 3	HSUPA Subtest 4	HSUPA Subtest 5
						$B_c=2 / B_d=15$	$B_c=11 / B_d=15$	$B_c=15 / B_d=8$	$B_c=15 / B_d=4$	$B_c=10 / B_d=15$ $\Delta E-DPCCH=6$ AG Index = 20 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=6 / B_d=15$ $\Delta E-DPCCH=8$ AG Index = 12 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=15 / B_d=9$ $\Delta E-DPCCH=8$ AG Index = 15 No. E-TFCIs = 2 E-TFCI = 11, 92	$B_c=2 / B_d=15$ $\Delta E-DPCCH=5$ AG Index = 17 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=14 / B_d=15$ $\Delta E-DPCCH=7$ AG Index = 21 No. E-TFCIs = 5 E-TFCI = 11, 67
9263	1852,6	22,12	22,05	22,11	22,10	22,55	22,60	22,04	22,12	22,52	21,23	19,89	21,69	22,73
9400	1880,0	<b>22,77</b>	22,57	22,68	22,57	<b>23,23</b>	23,25	22,67	22,83	22,93	21,47	21,05	22,28	<b>23,33</b>
9537	1907,4	22,28	22,28	22,30	22,27	22,93	22,82	22,31	22,33	22,27	21,26	19,76	22,05	22,67

W-CDMA FDD IV														
Uplink UARFCN	Uplink Frequency [MHz]	Source-based time averaged Power [dBm]												
		RMC 12.2 kbps	RMC 64 kbps	RMC 144 kbps	RMC 384 kbps	HSDPA Subtest 1	HSDPA Subtest 2	HSDPA Subtest 3	HSDPA Subtest 4	HSUPA Subtest 1	HSUPA Subtest 2	HSUPA Subtest 3	HSUPA Subtest 4	HSUPA Subtest 5
						$B_c=2 / B_d=15$	$B_c=11 / B_d=15$	$B_c=15 / B_d=8$	$B_c=15 / B_d=4$	$B_c=10 / B_d=15$ $\Delta E-DPCCH=6$ AG Index = 20 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=6 / B_d=15$ $\Delta E-DPCCH=8$ AG Index = 12 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=15 / B_d=9$ $\Delta E-DPCCH=8$ AG Index = 15 No. E-TFCIs = 2 E-TFCI = 11, 92	$B_c=2 / B_d=15$ $\Delta E-DPCCH=5$ AG Index = 17 No. E-TFCIs = 5 E-TFCI = 11, 67	$B_c=14 / B_d=15$ $\Delta E-DPCCH=7$ AG Index = 21 No. E-TFCIs = 5 E-TFCI = 11, 67
1313	1712,6	22,02	21,94	22,00	21,99	22,49	22,54	21,98	22,06	22,46	21,17	19,83	21,63	22,67
1413	1732,6	<b>22,66</b>	22,46	22,57	22,46	<b>23,17</b>	23,15	22,61	22,77	22,87	21,41	20,99	22,22	<b>23,27</b>
1512	1752,4	22,17	22,17	22,19	22,16	22,87	22,76	22,25	22,27	22,21	21,20	19,70	22,00	22,61



## 1.1 Standalone Operational Mode Test Exclusion

### MedRadio

According to KDB 447498 D01 v05 for standalone SAR evaluation the test exclusion power condition is given by

$$\frac{\text{max Power, mW}}{\text{test distance, mm}} \cdot \sqrt{f_{\text{GHz}}} \leq 3.0$$

With the maximum source-base time averaged conducted power level of -10.9 dBm the test exclusion condition gives (test distance 5 mm for distances  $\leq$  5 mm)

$$\frac{\text{max Power, mW}}{\text{test distance, mm}} \cdot \sqrt{f_{\text{GHz}}} = \frac{0.081}{5} \cdot \sqrt{0.405} = 0.0 \leq 3.0$$

Hence the test exclusion condition for the MedRadio transmitter for standalone operation is fulfilled.

### GRPS/EGRPS

The conducted output power is higher than the test exclusion power value

### WCDMA/HSDPA/HSUPA

The conducted output power is higher than the test exclusion power value

## 1.2 Supported concurrent (multi-transmitter) operating modes

The ability of all other transmitters to transmit simultaneously is given in the following table:

	<b>MedRadio</b>	<b>GPRS/EGRPS</b>	<b>HSDPA/HSUPA</b>
<b>MedRadio</b>	N/A	Yes	Yes
<b>GPRS/EGRPS</b>	Yes	N/A	N/A
<b>HSDPA/HSUPA</b>	Yes	N/A	N/A



### 1.3 Supported use cases

Use case	Distance to human body	corresponding test configuration
EUT placed against human body	5 mm	body-worn device

**1.4 Radio Test Modes**

Mode	Settings
GPRS850	Mode = GSM 850 Modulation = GMSK Duty cycle = 12.5% (1 Timeslot) Power level = maximum (GAMMA 3) Antenna = integrated
GRPS1900	Mode = GSM 1900 Modulation = GMSK Duty cycle = 12.5% (1 Timeslot) Power level = maximum (GAMMA 3) Antenna = integrated
FDDV	Mode = HSDPA Subtest 1 Modulation = QPSK Duty cycle = 100% Power level = maximum (TPC all 1) Antenna = integrated
FDDII	Mode = HSDPA Subtest 1 Modulation = QPSK Duty cycle = 100% Power level = maximum (TPC all 1) Antenna = integrated
FDDIV	Mode = HSDPA Subtest 1 Modulation = QPSK Duty cycle = 100% Power level = maximum (TPC all 1) Antenna = integrated

1.5 Test Positions

Position	Description
FRONT-5MM	<p data-bbox="416 434 783 468">EUT touching the human body</p> 
BACK-5MM	<p data-bbox="416 1072 783 1106">EUT touching the human body</p> 

## 1.6 Test Equipment Used During Testing

SAR Measurement					
Description	Manufacturer	Model	Identifier	Cal. Date	Cal. Due
Stäubli Robot	Stäubli	RX90B L	EF00271	functional test	functional test
Stäubli Robot Controller	Stäubli	CS7MB	EF00272	functional test	functional test
DASY 5 Measurement Server	Schmid & Partner		EF00273	functional test	functional test
Control Pendant	Stäubli		EF00274	functional test	functional test
Dell Computer	Schmid & Partner	Intel	EF00275	functional test	functional test
Data Acquisition Electronics	Schmid & Partner	DAE3V1	EF00276	2013-09	2014-09
Dosimetric E-Field Probe	Schmid & Partner	ET3DV6	EF00279	2013-09	2014-09
Dosimetric E-Field Probe	Schmid & Partner	EX3DV4	EF00826	2013-09	2014-09
System Validation Kit	Schmid & Partner	D300V3	EF00299	2012-09	2015-09
System Validation Kit	Schmid & Partner	D450V3	EF00300	2012-09	2015-09
System Validation Kit	Schmid & Partner	D900V2	EF00281	2012-09	2015-09
System Validation Kit	Schmid & Partner	D1800V2	EF00282	2012-09	2015-09
System Validation Kit	Schmid & Partner	D1900V2	EF00283	2012-09	2015-09
System Validation Kit	Schmid & Partner	D2450V2	EF00284	2012-09	2015-09
System Validation Kit	Schmid & Partner	D5GHZV2	EF00827	2012-11	2015-11
Flat phantom	Schmid & Partner	V 4.4	EF00328	no calibration required	no calibration required
Oval flat phantom	Schmid & Partner	ELI 4	EF00289	functional test	functional test
Mounting Device	Schmid & Partner	V 3.1	EF00287	functional test	functional test
Millivoltmeter	Rohde & Schwarz	URV 5	EF00126	2013-08	2016-08
Power sensor	Rohde & Schwarz	NRV-Z2	EF00125	2013-04	2015-04
RF signal generator	Rohde & Schwarz	SMP 02	EF00165	2013-05	2015-05
Insertion unit	Rohde & Schwarz	URV5-Z4	EF00322	2013-08	2014-08
Directional Coupler	HP	HP 87300B	EF00288	functional test	functional test
Radio Communication Tester	Rohde & Schwarz	CMD65	EF00625	ICO (initial calibration only)	ICO (initial calibration only)
Universal Radio Communication Tester	Rohde & Schwarz	CMU 200	EF00304	2013-05	2014-05
Network Analyzer 300 kHz to 3 GHz	Agilent	8752C	EF00140	2013-06	2014-06
Dielectric Probe Kit	Agilent	85070C	EF00291	functional test	functional test

## 2 Result Summary

OET Bulletin 65 Supplement C, RSS-102					
Product Specific Standard Section	Requirement – Test	Reference Method	Maximum SAR [W/kg]	Result	Remarks
OET Bulletin 65 Suppl. C Section 2 RSS-102 Section 3	Single-band conformity	KDB Publication 447498 KDB Publication 248227 KDB Publication 865664	1.31	PASS	
OET Bulletin 65 Suppl. C Section 2 RSS-102 Section 3	Multi-band conformity	KDB Publication 447498 KDB Publication 648474 KDB Publication 865664	1.31	PASS	
<b>Remarks:</b>					

### 3 Definitions

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy ( $dW$ ) absorbed by (dissipated in) an incremental mass ( $dm$ ) contained in a volume element ( $dV$ ) of a given density ( $\rho_t$ ), expressed in watts per kilogram (W/kg)

$$\text{SAR} = d/dt (dW/dm) = d/dt (dW/\rho_t dV) = \sigma/\rho_t |E_t|^2$$

where

$$dW/dt = \int_V E \cdot J \, dV = \int_V \sigma E^2 \, dV$$

#### 3.1 Controlled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category and the general population/uncontrolled exposure limits apply to these devices.

#### 3.2 Uncontrolled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on the risk of potential exposure and instructions on methods to minimize such exposure risks.

#### 3.3 Localized SAR

Compliance with the localized SAR limits is demonstrated using the head and trunk limit because this SAR limit is only half the limbs limit value. The values are obtained by SAR measurements according to EN 62209-2.

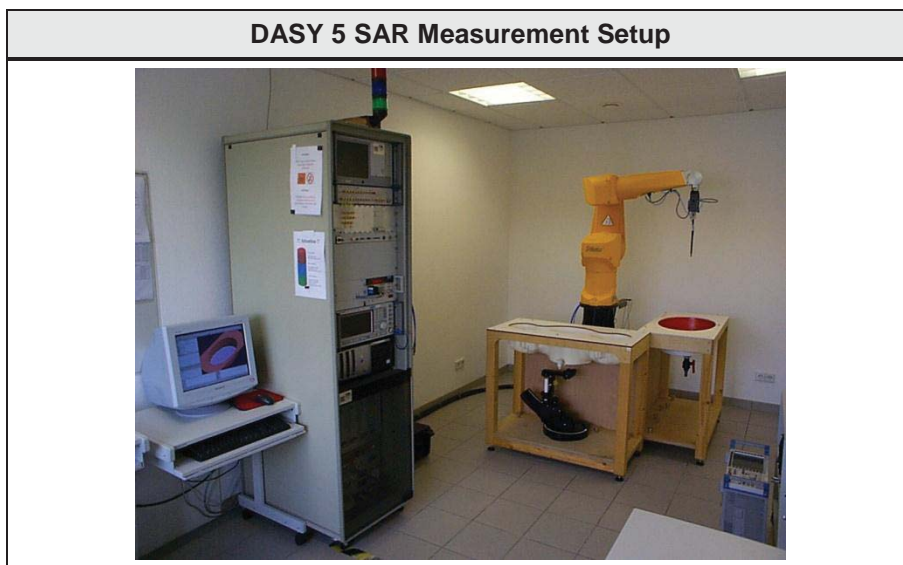


## 4 Localized SAR Measurement Equipment

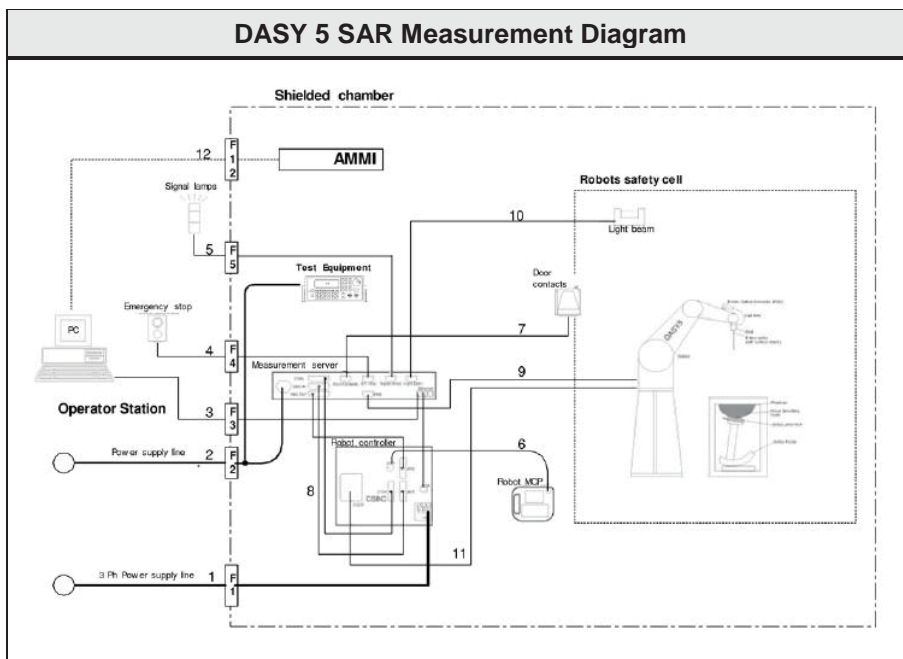
The measurements were performed with Dasy5 automated near-field scanning system comprised of high precision robot, robot controller, computer, e-field probe, probe alignment unit, phantoms, non-conductive phone positioned and software extension.

### 4.1 Complete SAR DASY5 Measurement System

Measurements are performed using the DASY5 automated assessment system made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland.



The following Diagram show the elements involved in the measurement setup.



The DASY5 system for performing compliance tests consists of the following items:

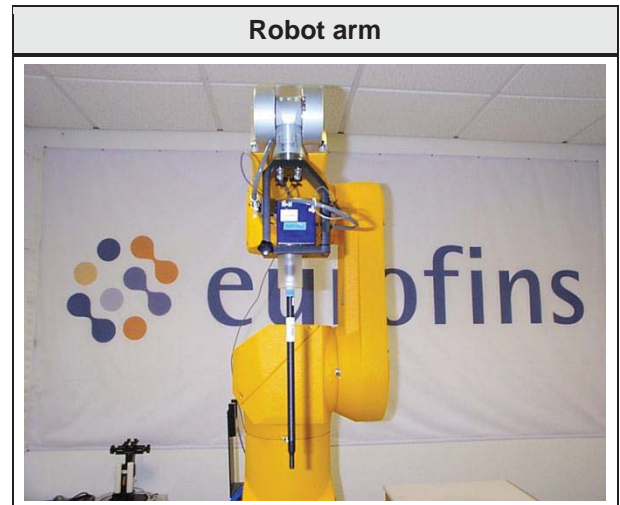
<b>DASY5 SAR Measurement System</b>	
Device	Description:
RX90BL	A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software.
Probe Alignment Unit	A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
Teach Pendant	The Manual Control Pendant (MCP), also called the manual teach pendant, is the user interface to the robot. In DASY, it is used for certain installation and teach procedures
Signal Lamps	External warning lamp which indicates when the robot arm is powered-on and if the robot is under software control or in manual mode (controlled with the teach pendant).
DAE	The data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
E-Field Probes	Isotropic E-Field probe optimized and calibrated for E-field measurements in free space.
EOC	The electro-optical converter (EOC) performs the conversion between optical and electrical signals
Measurement Server	The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
Control Computer	A computer operating Windows 2000 or Windows NT with DASY 4 Software.
Control Software	DASY4 and SEMCAD post processing Software
SAM Twin Phantom	The SAM twin phantom enabling testing left-hand and right-hand usage.
Flat Phantom	Flat Phantom (only for body-mounted transceivers operating below 800 MHz).
Tissue simulating liquid	Tissue simulating liquid mixed according to the given recipes.
Device Holder	The device holder for handheld mobile phones.
System Validation Dipoles	System validation dipoles allowing to validate the proper functioning of the system.

#### 4.2 Robot Arm

The DASY5 system uses the high precision robots RX90BL type out of the newer series from Stäubli SA (France).

The RX robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller



#### 4.3 Data Acquisition Electronics

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 is 200M Ohm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.



#### 4.4 Isotropic E-Field Probe $\leq 3$ GHz

##### Probe Specifications

###### **Construction:**

One dipole parallel, two dipoles normal to probe axis built-in shielding against static charges.

###### **Calibration:**

In air from 10 MHz to 2.5 GHz,  
In brain and muscle simulating tissue at  
Frequencies of 835MHz, 900MHz, 1800MHz,  
1900 MHz and 2450 MHz

###### **Frequency:**

10MHz to > 3GHz,  
Linearity  $\pm 0.2$ dB (30MHz to 3GHz)

###### **Directivity:**

$\pm 0.2$ dB in HSL (rotation around probe axis)  
 $\pm 0.4$ dB in HSL (rotation normal to probe axis)

###### **Dynamic Range:**

5 $\mu$ W/g to > 100mW/g

###### **Linearity:**

$\pm 0.2$ dB

###### **Dimensions:**

Overall Length: 330mm (Tip: 16mm),  
Tip Diameter: 6.8mm (Body: 12mm),  
Distance from probe tip to dipole centers: 2.7mm

###### **Application:**

General dosimetry up to 3 GHz  
Compliance tests of mobile phones  
Fast automatic scanning in arbitrary phantoms



#### 4.5 Isotropic E-Field Probe $\leq 6$ GHz

##### Probe Specifications

###### **Construction:**

One dipole parallel, two dipoles normal to probe axis built-in shielding against static charges.

###### **Calibration:**

In air from 10 MHz to 6 GHz,  
In brain and muscle simulating tissue at  
Frequencies of 5200, 5500, 5800

###### **Frequency:**

10MHz to 6GHz,  
Linearity  $\pm 0.2$ dB (30MHz to 6GHz)

###### **Directivity:**

$\pm 0.3$ dB in HSL (rotation around probe axis)  
 $\pm 0.5$ dB in tissue material (rotation normal to probe axis)

###### **Dynamic Range:**

10 $\mu$ W/g to > 100mW/g

###### **Linearity:**

$\pm 0.2$ dB

###### **Dimensions:**

Overall Length: 337mm (Tip: 20mm),  
Tip Diameter: 2.5mm (Body: 12mm),  
Distance from probe tip to dipole centers: 1mm

###### **Application:**



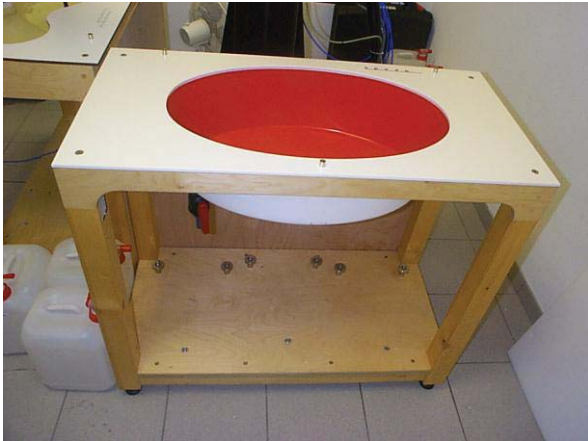

General dosimetry up to 6 GHz  
Compliance tests of mobile phones  
Fast automatic scanning in arbitrary phantoms



#### 4.6 Test phantom and positioner

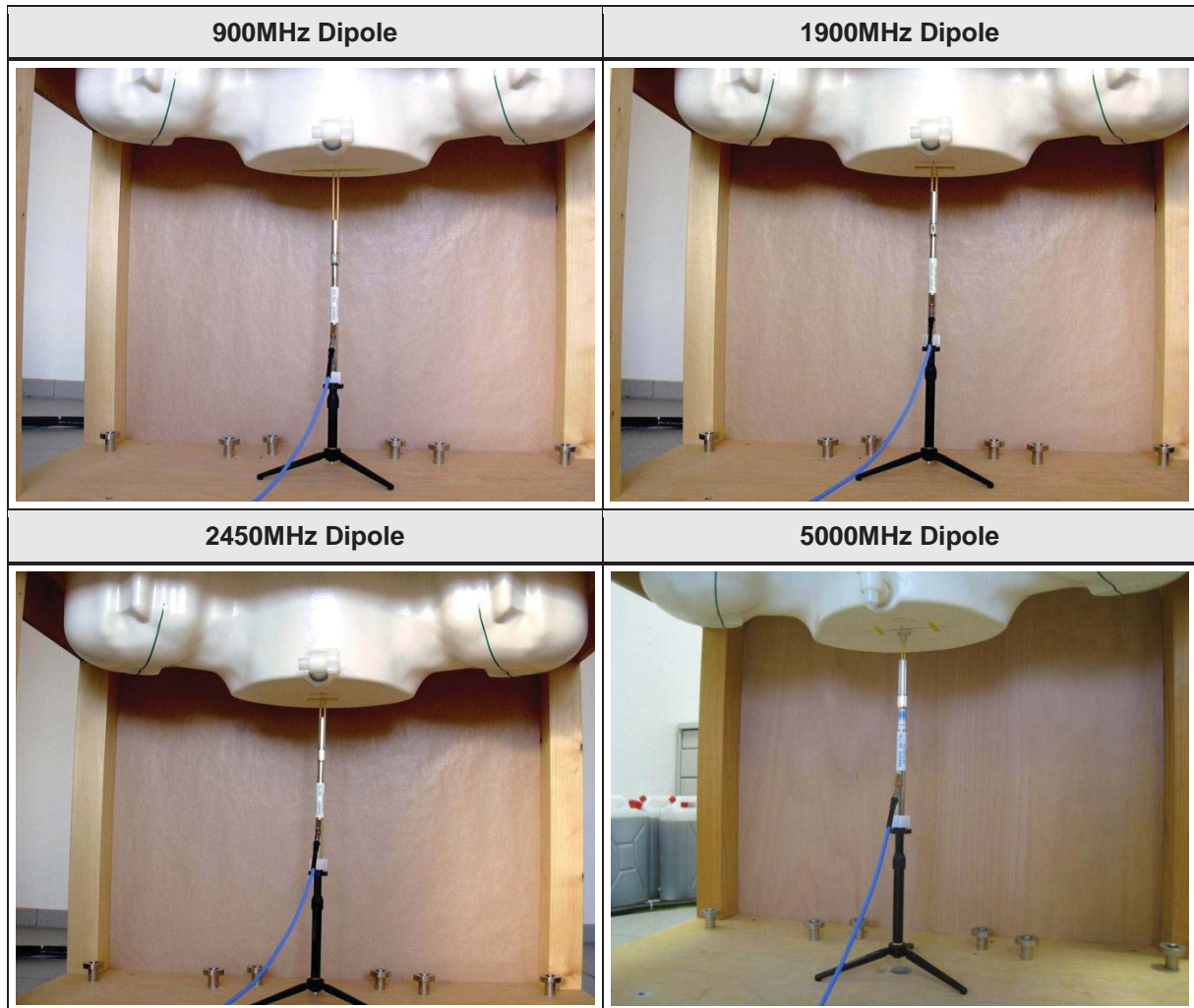
The positioner and test phantoms are manufactured by SPEAG. The test phantoms are used for all tests i.e. for both validation testing and device testing. The positioner and test phantom conforms to the requirements of EN 62209 and IEEE 1528.

The SPEAG device holder was used to position the test device in all tests whilst a tripod was used to position the validation dipoles in the test arch.

Probe Positioner	SAM Twin Phantom
	
ELI4 phantom	Flat phantom
	

#### 4.7 System Validation Dipoles

A set of calibration dipoles (D900V2, D1900V2, D2450V2, D5GHzV2) is included as a part of the SAR measurement setup. These are used for the validation of the test setup after its installation and prior to the EUT measurements. The calibration dipole is placed in the position normally occupied by the EUT. All calibration dipoles have the same height which allows an exact fitting below the center point of the test phantom. The dipole center is 10mm below the surface of the test phantom.



## 5 Single-band SAR Measurement

After successful completion of the tissue and system verification the SAR values of the EUT are measured according to the following description.

### 5.1 General measurement description

The measurement is performed for each frequency band of the device. If the width of the transmit frequency band exceeds 1% of its center frequency, then the channels at the lowest and highest frequencies should also be tested. Furthermore, if the width of the transmit band exceeds 10% of its center frequency the following formula is used to determine the number of channels:

$$N_C = 2 \cdot \text{roundup}[10 \cdot (f_{\text{high}} - f_{\text{low}}) / f_c] + 1$$

First the device is tested on the center channel of each frequency band used by the device. An operation mode and configuration with maximum transmit power is established. If battery operated equipment is used, the batteries are fully charged.

SAR measurements are performed using the steps outlined in the next section for all relevant operational modes, EUT configurations and measurement positions.

For the condition (position, configuration, operational mode) that provides the highest spatial-average SAR value on the center channel, the other channels are also tested.

Additionally all other conditions where the spatial-average SAR value is within 3dB of the SAR limit are also tested on all determined test frequencies.

### 5.2 SAR measurement description

First the local SAR value at a test point within 10mm or less in normal direction from the inner surface of the phantom is measured. This SAR value is used to determine the measurement drift during SAR measurement.

Next an area scan is performed over an area larger than the projection of the EUT with antenna on the surface of the phantom with a spatial grid step of 10mm.

From the scanned SAR distribution the position of maximum SAR value is identified as well as any local SAR maxima within 2dB of the maximum value that are not within the zoom scan volume. (The additional peaks are only measured when the primary peak is within 2dB of the SAR limit.)

The zoom-scan volume constructed on the peak SAR position is scanned with a grid step of 5mm. The measured data are extracted and the local SAR value for each measurement point is calculated. The measured values are interpolated over a fine-mesh within the scan volume and the average SAR value over 10g mass is calculated.

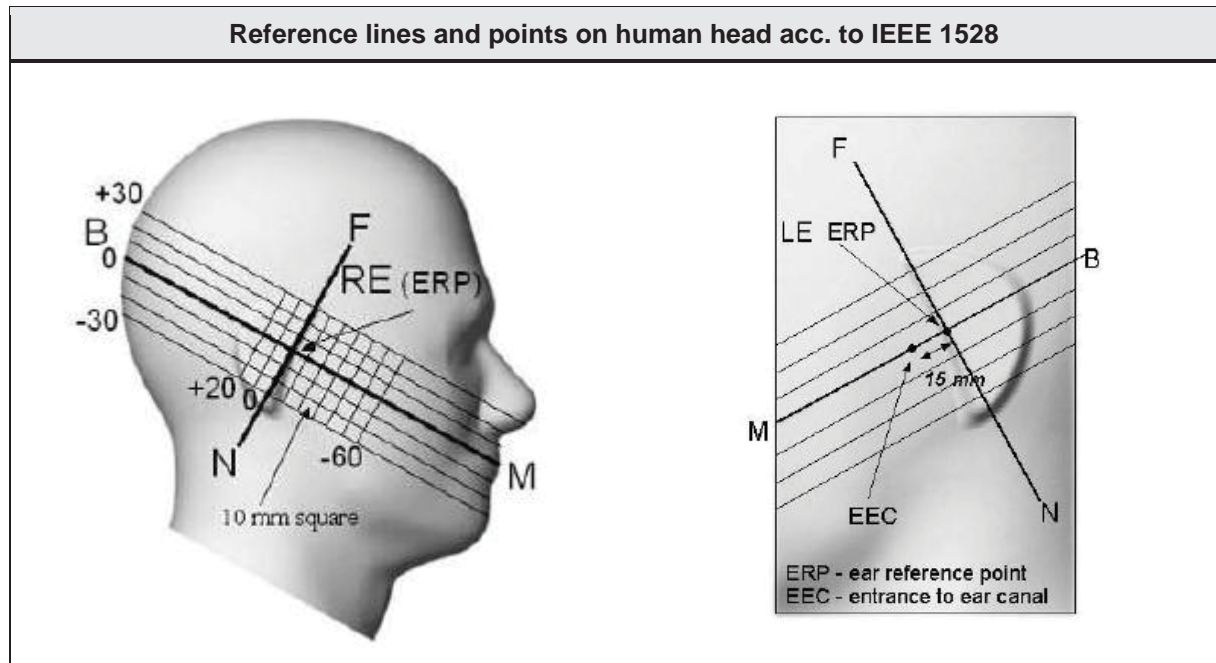
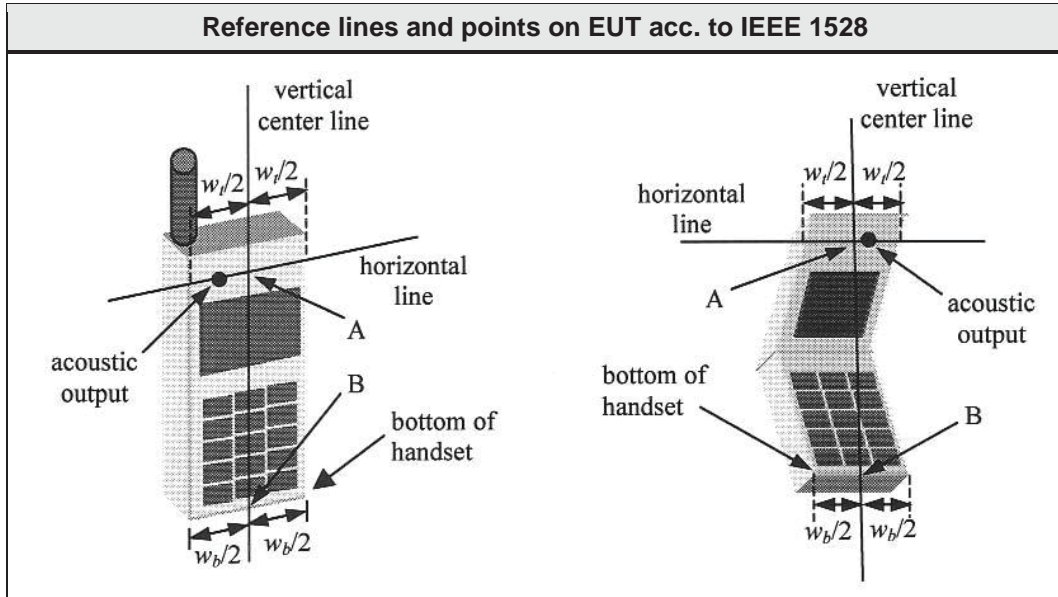
At the end of the measurement the reference point measured at the beginning of the measurement is measured again and from the difference the drift is calculated.



### 5.3 Reference lines and points for Handsets

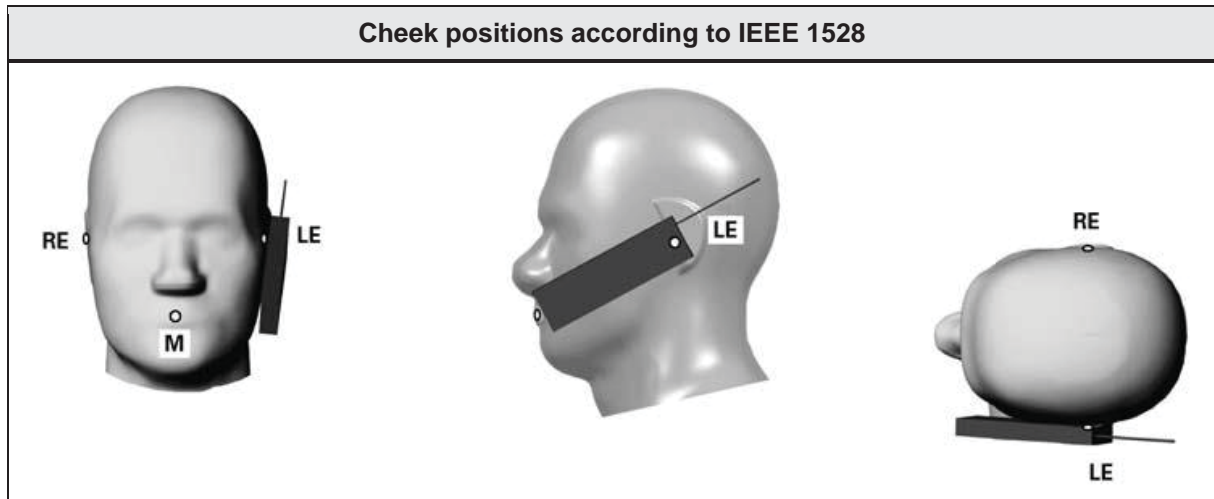
For all measurement positions of the EUT, the EUT has to be placed in a specific orientation with respect to the phantom. The orientation of the EUT relative to the phantom is defined by reference lines and points.

According to IEEE 1528, the reference lines and points shall be positioned at the EUT as shown in the following figure.



#### 5.4 Test positions relative to the Head

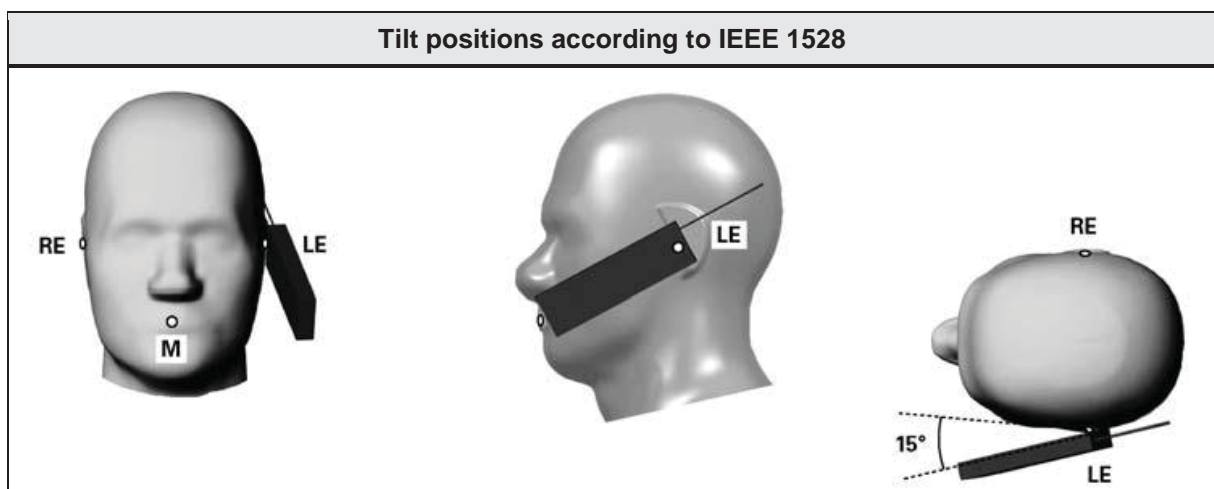
##### Cheek position



The handset is positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure), such that the plane defined by the vertical centerline and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom. Next the handset is translated towards the phantom along the line passing through RE and LE until handset point A touches the pinna at the ERP.

While the handset is maintained in this plane, it is rotated around the LE-RE line until the vertical centerline is in the plane normal to the plane containing B-M and N-F lines, i.e., the Reference Plane. Then it is rotated around the vertical centerline until the handset (horizontal line) is parallel to the N-F line. While the vertical centerline is maintained in the Reference Plane, point A is kept on the line passing through RE and LE, and the handset is maintained in contact with the pinna, the handset is rotated about the N-F line until any point on the handset is in contact with a phantom point below the pinna on the cheek.

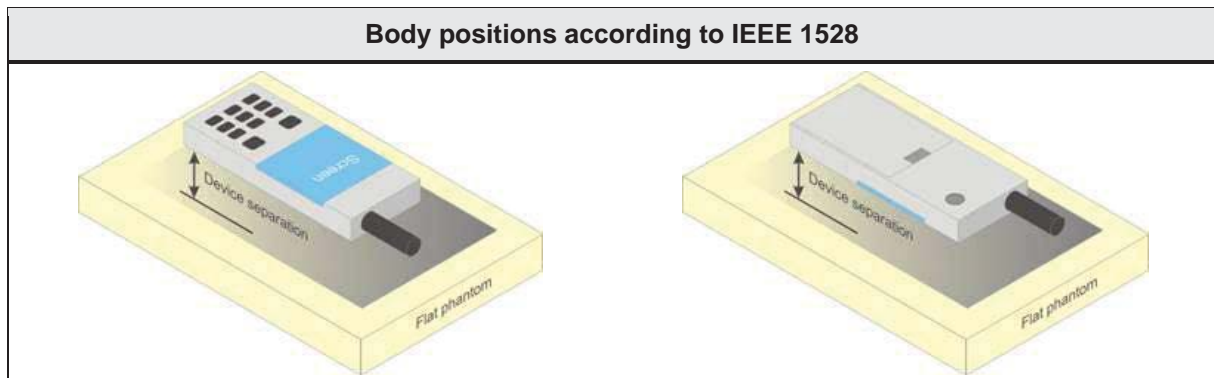
##### Tilt position



First the EUT is placed in the cheek position. Next the handset is moved away from the pinna along the line passing through RE and LE far enough to allow a rotation of the handset away from the cheek by 15°. Then the handset is rotated around the horizontal line by 15°.

The handset is moved towards the phantom on the line passing through RE and LE until any part of the handset touches the ear. The tilt position is obtained when the contact point is on the pinna. See Figure. If contact occurs at any location other than the pinna, e.g., the antenna at the back of the phantom head, the angle of the handset should be reduced. In this case, the tilt position is obtained if any point on the handset is in contact with the pinna and a second point on the handset is in contact with the phantom, e.g., the antenna with the back of the head

### 5.5 Test positions relative to the human body



In body worn configuration the device is positioned parallel to the phantom surface with either top or bottom side of the EUT facing against the phantom.

The separation distance of the EUT is selected according to the use case of the EUT (e.g. with belt clip or holster).

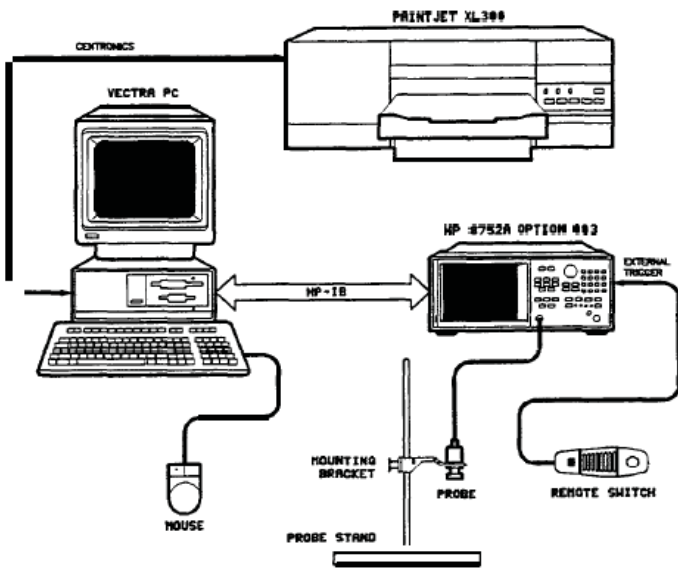
## 5.6 Measurement Uncertainty

Measurement Uncertainty according to IEEE 1528							
Error Description	Uncertainty Value	Probability Distribution	Div.	c <sub>i</sub> (1g)	c <sub>i</sub> (10g)	Std. Unc. 1g	Std. Unc. 10g
<b>Measurement System</b>							
Probe Calibration	±6.55%	N	1	1	1	±6.55%	±6.55%
Axial Isotropy	±4.7%	R	$\sqrt{3}$	0.7	0.7	±1.9%	±1.9%
Hemispherical Isotropy	±9.6%	R	$\sqrt{3}$	0.7	0.7	±3.9%	±3.9%
Linearity	±4.7%	R	$\sqrt{3}$	1	1	±2.7%	±2.7%
Modulation Response	±2.4%	R	$\sqrt{3}$	1	1	±1.4%	±1.4%
System Detection Limits	±1.0%	R	$\sqrt{3}$	1	1	±0.6%	±0.6%
Boundary effects	±2.0%	R	$\sqrt{3}$	1	1	±1.2%	±1.2%
Readout Electronics	±0.3%	N	1	1	1	±0.3%	±0.3%
Response Time	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
Integration Time	±2.6%	R	$\sqrt{3}$	1	1	±1.5%	±1.5%
RF Ambient Noise	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
RF Ambient Reflections	±3.0%	R	$\sqrt{3}$	1	1	±1.7%	±1.7%
Probe Positioner	±0.8%	R	$\sqrt{3}$	1	1	±0.5%	±0.5%
Probe Positioning	±6.7%	R	$\sqrt{3}$	1	1	±3.9%	±3.9%
Post processing	±4.0%	R	$\sqrt{3}$	1	1	±2.3%	±2.3%
<b>Test Sample Related</b>							
Device Holder	±3.6%	N	1	1	1	±3.6%	±3.6%
Test Sample Positioning	±2.9%	N	1	1	1	±2.9%	±2.9%
Power Scaling	±0%	R	$\sqrt{3}$	1	1	±0%	±0%
Power Drift	±5.0%	R	$\sqrt{3}$	1	1	±2.9%	±2.9%
<b>Phantom and Setup Related</b>							
Phantom Uncertainty	±7.9%	R	$\sqrt{3}$	1	1	±4.6%	±4.6%
SAR correction	±1.9%	R	$\sqrt{3}$	1	0.84	±1.1%	±0.9%
Liquid conductivity (measured)	±2.5%	N	1	0.78	0.71	±2.0%	±1.8%
Liquid permittivity (measured)	±2.5%	N	1	0.26	0.26	±0.1%	±0.1%
Temperature uncertainty - Conductivity	±5.2%	R	$\sqrt{3}$	0.78	0.71	±2.3%	±2.1%
Temperature uncertainty - Permittivity	±0.8%	R	$\sqrt{3}$	0.23	0.26	±0.1%	±0.1%
Combined Standard Uncertainty						±12.8%	±12.7%
<b>Expanded Standard Uncertainty</b>						<b>±25.6%</b>	<b>±25.4%</b>

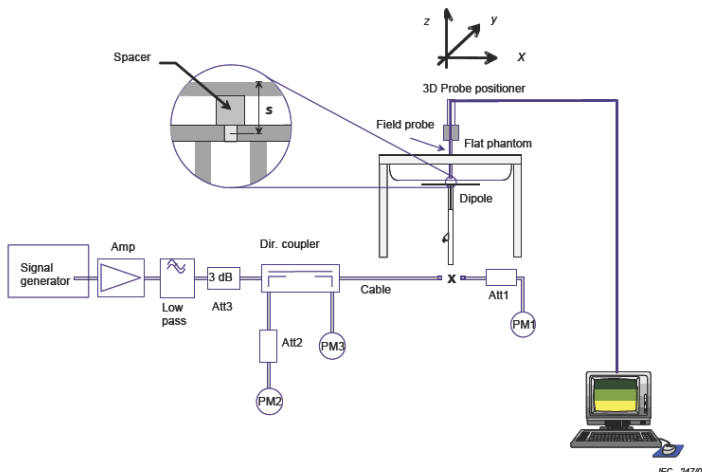
## 6 Test Conditions and Results

### 6.1 Test Conditions and Results – Tissue Validation

Tissue Validation acc. to FCC OET Bulletin 65 Suppl. C / IC RSS-102					Verdict: PASS
Test according to measurement reference		Reference Method			
		OET Bulletin 65 Supplement C			
Target Values					
Frequency [MHz]	Head		Body		Permitted tolerance [%]
	Relative dielectric constant $\epsilon_r$	Conductivity $\sigma$ [S/m]	Relative dielectric constant $\epsilon_r$	Conductivity $\sigma$ [S/m]	
150	52.3	0.76	61.9	0.80	$\leq \pm 5$
300	45.3	0.87	58.2	0.92	$\leq \pm 5$
450	43.5	0.87	56.7	0.94	$\leq \pm 5$
835	41.5	0.90	55.2	0.97	$\leq \pm 5$
900	41.5	0.97	55.0	1.05	$\leq \pm 5$
915	41.5	0.98	55.0	1.06	$\leq \pm 5$
1450	40.5	1.20	54.0	1.30	$\leq \pm 5$
1610	40.3	1.29	53.8	1.40	$\leq \pm 5$
1800 – 2000	40.0	1.40	53.3	1.52	$\leq \pm 5$
2450	39.2	1.80	52.7	1.95	$\leq \pm 5$
3000	38.5	2.40	52.0	2.73	$\leq \pm 5$
5200	36.0	4.66	49.0	5.30	$\leq \pm 5$
5500	35.6	4.96	48.6	5.65	$\leq \pm 5$
5800	35.3	5.27	48.2	6.00	$\leq \pm 5$

Test setup							
							
Test procedure							
<ol style="list-style-type: none"> <li>1. The dielectric probe kit is calibrated using the standards air, short circuit and deionized water</li> <li>2. The tissue simulating liquid is measured using the dielectric probe</li> <li>3. Target values are compared to the measurement values and deviations are determined</li> </ol>							
Test results							
Frequency [MHz]	Tissue	Measured $\epsilon_r$	Target $\epsilon_r$	Delta $\epsilon_r$ [%]	Measured $\sigma$ [S/m]	Target $\sigma$ [S/m]	Delta $\sigma$ [%]
900	Body	54.42	55.0	-01.05	1.03	1.05	-01.90
1800	Body	54.28	53.3	01.84	1.58	1.51	04.64
1900	Body	51.87	53.3	-02.68	1.56	1.52	02.63
Comments:							

6.2 Test Conditions and Results – System Validation

System Validation acc. to FCC OET Bulletin 65 Suppl. C / IC RSS-102		Verdict: PASS
Test according to measurement reference	Reference Method	
	OET Bulletin 65 Supplement C / IEEE 1528	
Test frequency range	Tested frequencies	
	2450 MHz , 5200 MHz	
Test mode	unmodulated CW	
Target Values		
Frequency [MHz]	Target SAR value [W/kg (1g)]	Permitted tolerance [%]
900	2.76 @ 250mW	≤ ±10
1800	9.75 @ 250mW	≤ ±10
1900	10.2 @ 250mW	≤ ±10
The target reference values are taken from the calibration sheets (see annex)		
Test setup		
		
Test procedure		
<ol style="list-style-type: none"> <li>1. The dipole antenna input power is set to 250mW</li> <li>2. The reference dipole is positioned under the phantom</li> <li>3. With the dipole antenna powered the SAR value is measured</li> <li>4. The measured SAR values are compared to the target SAR values</li> </ol>		

<b>Test results</b>				
Frequency [MHz]	Input power [mW]	Measured SAR value [W/kg (1g)]	Target SAR value [W/kg (1g)]	Delta [%]
900	250	2.80	2.76	01.45
900	250	2.98	2.76	07.97
1800	250	10.3	9.75	05.64
1900	250	10.50	10.20	02.94
Comments:				



## 6.3 Test Conditions and Results – Standalone SAR Measurement

Standalone SAR acc. to FCC OET Bulletin 65 Suppl. C / IC RSS-102				Verdict: PASS		
Test according to measurement reference		Reference Method				
		FCC OET Bulletin 65 Supplement C / IC RSS-102 Issue 4				
Room temperature		22.0 – 22.6 °C				
Liquid depth		15.5 cm				
Environment		general public				
Limits						
Region		Occupational SAR values [W/kg]		General public SAR values [W/kg]		
Whole body average SAR		0.4		0.08		
Localized SAR (Head and trunk) SAR averaging mass = 10g		8		1.6		
Localized SAR (Limbs) SAR averaging mass = 10g		20		4		
Test results						
Mode	Position	Channel	Frequency [MHz]	Drift [dB]	Average SAR [W/kg (1g)]	SAR Limit [W/kg (1g)]
GPRS850	FRONT-5MM	128	824.2	0.02	1.02	1.6
GPRS850	FRONT-5MM	188	836.2	-0.08	1.05	1.6
GPRS850	FRONT-5MM	251	848.8	-0.08	1.02	1.6
GPRS850	BACK-5MM	128	824.2	-0.07	1.05	1.6
GPRS850	BACK-5MM	188	836.2	0.10	1.04	1.6
GPRS850	BACK-5MM	251	848.8	-0.12	1.03	1.6
GPRS1900	FRONT-5MM	512	1850.2	-0.02	1.17	1.6
GPRS1900	FRONT-5MM	661	1880.0	0.04	1.03	1.6
GPRS1900	FRONT-5MM	810	1909.8	0.00	0.93	1.6
GPRS1900	BACK-5MM	512	1850.2	0.02	1.26	1.6
GPRS1900	BACK-5MM	661	1880.0	0.07	1.16	1.6
GPRS1900	BACK-5MM	810	1909.8	0.00	1.03	1.6

FDDII	FRONT-5MM	9263	1852.6	0.00	1.08	1.6
FDDII	FRONT-5MM	9400	1880.0	-0.01	1.08	1.6
FDDII	FRONT-5MM	9537	1907.4	-0.02	1.02	1.6
FDDII	BACK-5MM	9263	1852.6	-0.02	1.31	1.6
FDDII	BACK-5MM	9400	1880.0	0.61	1.26	1.6
FDDII	BACK-5MM	9537	1907.4	-0.11	1.18	1.6
FDDIV	FRONT-5MM	1313	1712.6	0.03	1.11	1.6
FDDIV	FRONT-5MM	1450	1740	0.01	1.21	1.6
FDDIV	FRONT-5MM	1512	1752.4	0.03	1.25	1.6
FDDIV	BACK-5MM	1313	1712.6	-0.03	1.14	1.6
FDDIV	BACK-5MM	1450	1740	0.06	1.23	1.6
FDDIV	BACK-5MM	1512	1752.4	0.02	1.29	1.6
FDDV	FRONT-5MM	4133	826.6	0.04	0.89	1.6
FDDV	FRONT-5MM	4175	835	-0.05	0.88	1.6
FDDV	FRONT-5MM	4232	846.4	-0.06	0.89	1.6
FDDV	BACK-5MM	4133	826.6	-0.01	0.91	1.6
FDDV	BACK-5MM	4175	835	-0.08	0.89	1.6
FDDV	BACK-5MM	4232	846.4	-0.07	0.93	1.6
<b>Overall maximum SAR value [W/kg (1g)]</b>					<b>1.31</b>	<b>1.6</b>
Comments:						

6.4 Test Conditions and Results – Multi-band SAR Assessment

Multi-band SAR Assessment acc. KDB 447498		Verdict: PASS	
Test according to measurement reference	Reference Method		
	KDB 447498		
Environment	general public		
Limits			
Region	Occupational SAR values [W/kg]	General public SAR values [W/kg]	
Whole body average SAR	0.4	0.08	
Localized SAR (Head and trunk) SAR averaging mass = 1g	8	1.6	
Localized SAR (Limbs) SAR averaging mass = 1g	20	4	
Multi-band transmission capabilities			
	MedRadio	GRPS/EGRPS	HSDPA/HSUPA
MedRadio	N/A	Yes	Yes
GRPS/EGRPS	Yes	N/A	N/A
HSDPA/HSUPA	Yes	N/A	N/A
<p>The SAR Value for MedRadio is estimated according to KDB 447498</p> $\frac{\text{max Power, mW}}{\text{test distance, mm}} \cdot \frac{\sqrt{f_{\text{GHz}}}}{7.5}$ $\frac{\text{max Power, mW}}{\text{test distance, mm}} \cdot \frac{\sqrt{f_{\text{GHz}}}}{7.5} = \frac{0.08}{5} \cdot \frac{\sqrt{0.40485}}{7.5} = 0.0 \frac{W}{kg}$ <p>The estimated SAR Value when rounded to 1 decimal is 0. So the MedRadio transmitter does not contribute to the SAR-Values of the standalone transmission modes. For that reason no further multi-transmitter SAR-Evaluation is performed and the highest SAR-Value measured for the standalone operating modes is also the highest SAR-Value for multi-band operation.</p>			

**ANNEX A Calibration Documents**



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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **Eurofins**

Certificate No: **DAE3-522\_Sep13**

## CALIBRATION CERTIFICATE

Object **DAE3 - SD 000 D03 AA - SN: 522**

Calibration procedure(s) **QA CAL-06.v26  
Calibration procedure for the data acquisition electronics (DAE)**

Calibration date: **September 11, 2013**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature ( $22 \pm 3$ )°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	02-Oct-12 (No:12728)	Oct-13
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	07-Jan-13 (in house check)	In house check: Jan-14
Calibrator Box V2.1	SE UMS 006 AA 1002	07-Jan-13 (in house check)	In house check: Jan-14

Calibrated by:	Name <b>R.Mayoraz</b>	Function Technician	Signature <i>R. Mayoraz</i>
Approved by:	<b>Fin Bomholt</b>	Deputy Technical Manager	<i>F. Bomholt</i>

Issued: September 11, 2013

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



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Accreditation No.: **SCS 108**

## Glossary

**DAE** data acquisition electronics  
**Connector angle** information used in DASY system to align probe sensor X to the robot coordinate system.

## Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
  - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
  - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
  - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.
  - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - *Input resistance:* Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
  - *Power consumption:* Typical value for information. Supply currents in various operating modes.

## DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 $\mu$ V, full range = -100...+300 mV

Low Range: 1LSB = 61nV, full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.235 $\pm$ 0.02% (k=2)	403.905 $\pm$ 0.02% (k=2)	404.733 $\pm$ 0.02% (k=2)
Low Range	3.96415 $\pm$ 1.50% (k=2)	3.95903 $\pm$ 1.50% (k=2)	3.97308 $\pm$ 1.50% (k=2)

## Connector Angle

Connector Angle to be used in DASY system	57.0 $^{\circ}$ $\pm$ 1 $^{\circ}$
---	------------------------------------

## Appendix

### 1. DC Voltage Linearity

High Range	Reading ( $\mu\text{V}$ )	Difference ( $\mu\text{V}$ )	Error (%)
Channel X + Input	199994.84	-1.61	-0.00
Channel X + Input	20002.41	2.31	0.01
Channel X - Input	-19996.48	4.99	-0.02
Channel Y + Input	199996.01	-0.32	-0.00
Channel Y + Input	20000.12	0.00	0.00
Channel Y - Input	-19996.80	4.74	-0.02
Channel Z + Input	199996.36	-0.14	-0.00
Channel Z + Input	19999.47	-0.63	-0.00
Channel Z - Input	-20000.32	1.29	-0.01

Low Range	Reading ( $\mu\text{V}$ )	Difference ( $\mu\text{V}$ )	Error (%)
Channel X + Input	2000.73	0.37	0.02
Channel X + Input	202.12	1.52	0.76
Channel X - Input	-198.07	1.15	-0.58
Channel Y + Input	2000.27	-0.12	-0.01
Channel Y + Input	200.27	-0.32	-0.16
Channel Y - Input	-199.53	-0.32	0.16
Channel Z + Input	2000.40	0.21	0.01
Channel Z + Input	199.46	-1.06	-0.53
Channel Z - Input	-200.31	-0.98	0.49

### 2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading ( $\mu\text{V}$ )	Low Range Average Reading ( $\mu\text{V}$ )
Channel X	200	-3.46	-5.15
	- 200	6.33	5.03
Channel Y	200	-0.62	-0.84
	- 200	-1.40	-1.23
Channel Z	200	17.02	16.63
	- 200	-16.85	-17.55

### 3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X ( $\mu\text{V}$ )	Channel Y ( $\mu\text{V}$ )	Channel Z ( $\mu\text{V}$ )
Channel X	200	-	-2.55	-1.42
Channel Y	200	7.66	-	-0.32
Channel Z	200	6.37	4.74	-



#### 4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15741	16839
Channel Y	15715	14908
Channel Z	16057	16580

#### 5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10MΩ

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	1.14	-0.51	2.54	0.62
Channel Y	-0.99	-2.51	0.31	0.52
Channel Z	0.68	-0.45	2.23	0.54

#### 6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

#### 7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

#### 8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

#### 9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9



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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **Eurofins**

Certificate No: **ET3-1711\_Sep13**

**CALIBRATION CERTIFICATE**

Object: **ET3DV6 - SN:1711**

Calibration procedure(s): **QA CAL-01.v9, QA CAL-12.v8, QA CAL-23.v5, QA CAL-25.v6  
Calibration procedure for dosimetric E-field probes**

Calibration date: **September 18, 2013**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).  
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	04-Apr-13 (No. 217-01733)	Apr-14
Power sensor E4412A	MY41498087	04-Apr-13 (No. 217-01733)	Apr-14
Reference 3 dB Attenuator	SN: S5054 (3c)	04-Apr-13 (No. 217-01737)	Apr-14
Reference 20 dB Attenuator	SN: S5277 (20x)	04-Apr-13 (No. 217-01735)	Apr-14
Reference 30 dB Attenuator	SN: S5129 (30b)	04-Apr-13 (No. 217-01738)	Apr-14
Reference Probe ES3DV2	SN: 3013	28-Dec-12 (No. ES3-3013_Dec12)	Dec-13
DAE4	SN: 660	4-Sep-13 (No. DAE4-660_Sep13)	Apr-14
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-13)	In house check: Apr-15
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-12)	In house check: Oct-13

Calibrated by:	Name <b>Jeton Kastrati</b>	Function <b>Laboratory Technician</b>	Signature 
Approved by:	Name <b>Katja Pokovic</b>	Function <b>Technical Manager</b>	

Issued: September 18, 2013

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### Glossary:

TSL	tissue simulating liquid
NORM <sub>x,y,z</sub>	sensitivity in free space
ConvF	sensitivity in TSL / NORM <sub>x,y,z</sub>
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization $\varphi$	$\varphi$ rotation around probe axis
Polarization $\vartheta$	$\vartheta$ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis

### Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

### Methods Applied and Interpretation of Parameters:

- NORM<sub>x,y,z</sub>**: Assessed for E-field polarization  $\vartheta = 0$  ( $f \leq 900$  MHz in TEM-cell;  $f > 1800$  MHz: R22 waveguide). NORM<sub>x,y,z</sub> are only intermediate values, i.e., the uncertainties of NORM<sub>x,y,z</sub> does not affect the E<sup>2</sup>-field uncertainty inside TSL (see below *ConvF*).
- NORM(f)<sub>x,y,z</sub>** = NORM<sub>x,y,z</sub> \* *frequency\_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- DCP<sub>x,y,z</sub>**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR**: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- A<sub>x,y,z</sub>; B<sub>x,y,z</sub>; C<sub>x,y,z</sub>; D<sub>x,y,z</sub>; VR<sub>x,y,z</sub>; A, B, C, D** are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for  $f \leq 800$  MHz) and inside waveguide using analytical field distributions based on power measurements for  $f > 800$  MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM<sub>x,y,z</sub> \* *ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from  $\pm 50$  MHz to  $\pm 100$  MHz.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

# Probe ET3DV6

## SN:1711

Manufactured: August 7, 2002  
Calibrated: September 18, 2013

Calibrated for DASY/EASY Systems  
(Note: non-compatible with DASY2 system!)

# DASY/EASY - Parameters of Probe: ET3DV6 - SN:1711

## Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ( $\mu\text{V}/(\text{V}/\text{m})^2$ ) <sup>A</sup>	1.89	1.86	2.06	± 10.1 %
DCP (mV) <sup>B</sup>	96.7	98.1	98.0	

## Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Unc <sup>E</sup> (k=2)
0	CW	X	0.0	0.0	1.0	0.00	148.0	±2.7 %
		Y	0.0	0.0	1.0		154.3	
		Z	0.0	0.0	1.0		153.5	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Pages 5 and 6).

<sup>B</sup> Numerical linearization parameter: uncertainty not required.

<sup>E</sup> Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

## DASY/EASY - Parameters of Probe: ET3DV6 - SN:1711

### Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
450	43.5	0.87	7.37	7.37	7.37	0.26	2.45	± 13.4 %
900	41.5	0.97	6.19	6.19	6.19	0.43	2.27	± 12.0 %
1810	40.0	1.40	5.37	5.37	5.37	0.76	2.28	± 12.0 %
1950	40.0	1.40	5.16	5.16	5.16	0.80	2.19	± 12.0 %
2450	39.2	1.80	4.58	4.58	4.58	0.80	1.85	± 12.0 %

<sup>C</sup> Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

## DASY/EASY - Parameters of Probe: ET3DV6 - SN:1711

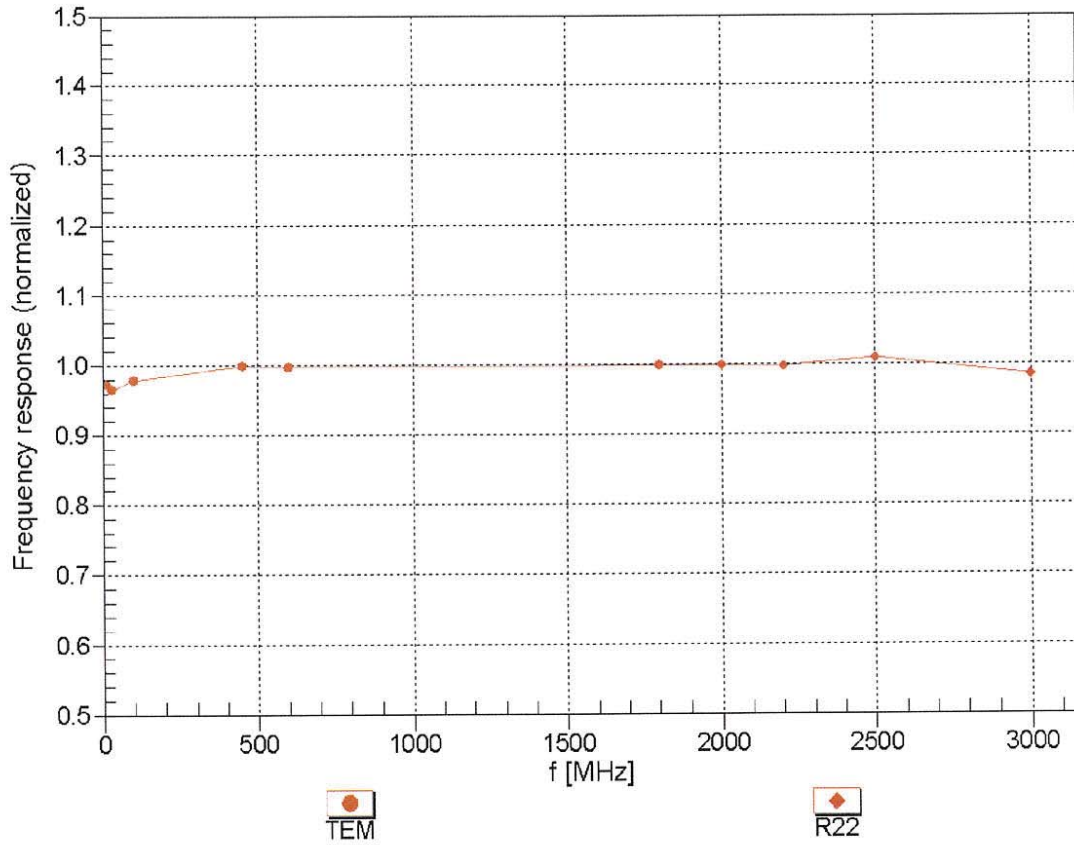
### Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
450	56.7	0.94	7.59	7.59	7.59	0.16	2.30	± 13.4 %
900	55.0	1.05	5.99	5.99	5.99	0.32	2.91	± 12.0 %
1810	53.3	1.52	4.69	4.69	4.69	0.80	2.34	± 12.0 %
1950	53.3	1.52	4.68	4.68	4.68	0.80	2.27	± 12.0 %
2450	52.7	1.95	4.05	4.05	4.05	0.67	1.27	± 12.0 %

<sup>C</sup> Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

### Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field:  $\pm 6.3\%$  (k=2)



# Probe ET3DV6

## SN:1711

Manufactured: August 7, 2002  
Calibrated: September 18, 2013

Calibrated for DASY/EASY Systems  
(Note: non-compatible with DASY2 system!)

# DASY/EASY - Parameters of Probe: ET3DV6 - SN:1711

## Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ( $\mu\text{V}/(\text{V}/\text{m})^2$ ) <sup>A</sup>	1.89	1.86	2.06	± 10.1 %
DCP (mV) <sup>B</sup>	96.7	98.1	98.0	

## Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Unc <sup>E</sup> (k=2)
0	CW	X	0.0	0.0	1.0	0.00	148.0	±2.7 %
		Y	0.0	0.0	1.0		154.3	
		Z	0.0	0.0	1.0		153.5	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Pages 5 and 6).

<sup>B</sup> Numerical linearization parameter: uncertainty not required.

<sup>E</sup> Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

## DASY/EASY - Parameters of Probe: ET3DV6 - SN:1711

### Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
450	43.5	0.87	7.37	7.37	7.37	0.26	2.45	± 13.4 %
900	41.5	0.97	6.19	6.19	6.19	0.43	2.27	± 12.0 %
1810	40.0	1.40	5.37	5.37	5.37	0.76	2.28	± 12.0 %
1950	40.0	1.40	5.16	5.16	5.16	0.80	2.19	± 12.0 %
2450	39.2	1.80	4.58	4.58	4.58	0.80	1.85	± 12.0 %

<sup>C</sup> Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

## DASY/EASY - Parameters of Probe: ET3DV6 - SN:1711

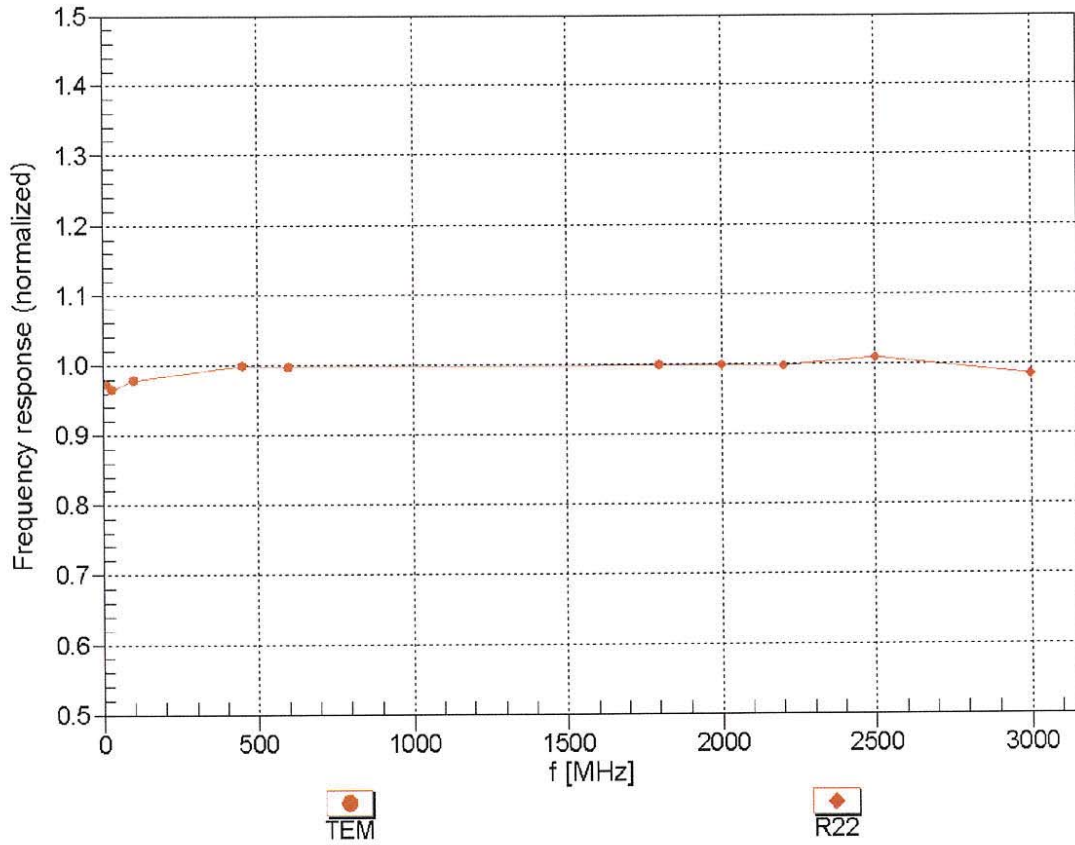
### Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) <sup>C</sup>	Relative Permittivity <sup>F</sup>	Conductivity (S/m) <sup>F</sup>	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
450	56.7	0.94	7.59	7.59	7.59	0.16	2.30	± 13.4 %
900	55.0	1.05	5.99	5.99	5.99	0.32	2.91	± 12.0 %
1810	53.3	1.52	4.69	4.69	4.69	0.80	2.34	± 12.0 %
1950	53.3	1.52	4.68	4.68	4.68	0.80	2.27	± 12.0 %
2450	52.7	1.95	4.05	4.05	4.05	0.67	1.27	± 12.0 %

<sup>C</sup> Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

<sup>F</sup> At frequencies below 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters ( $\epsilon$  and  $\sigma$ ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

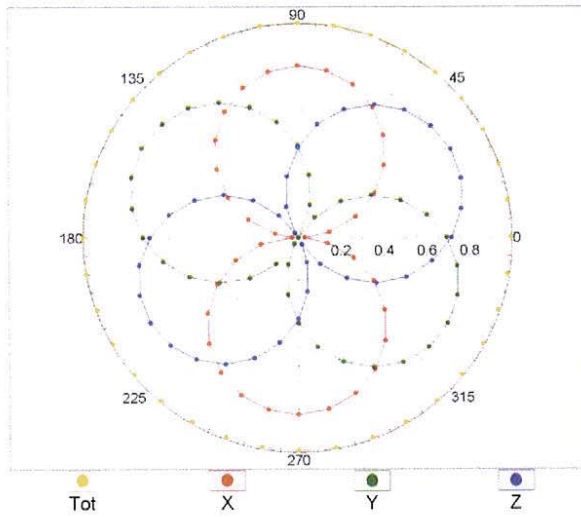
### Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



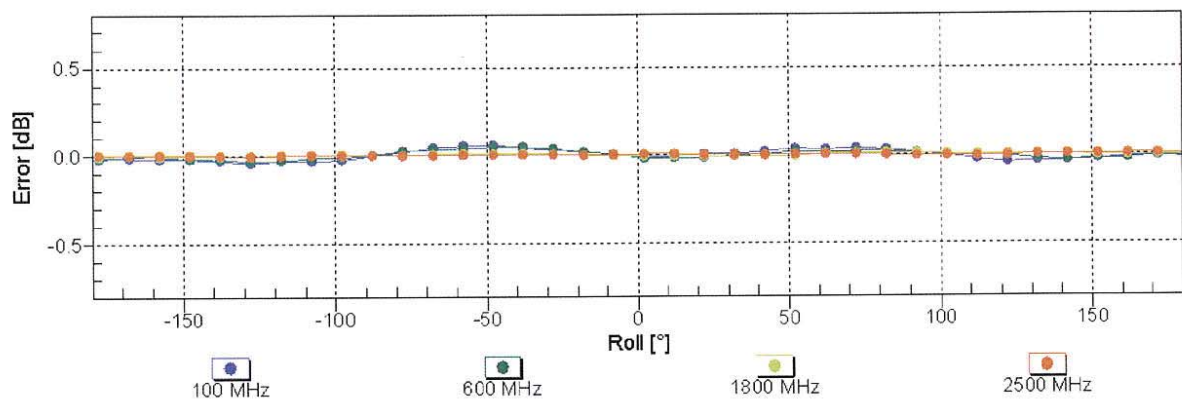
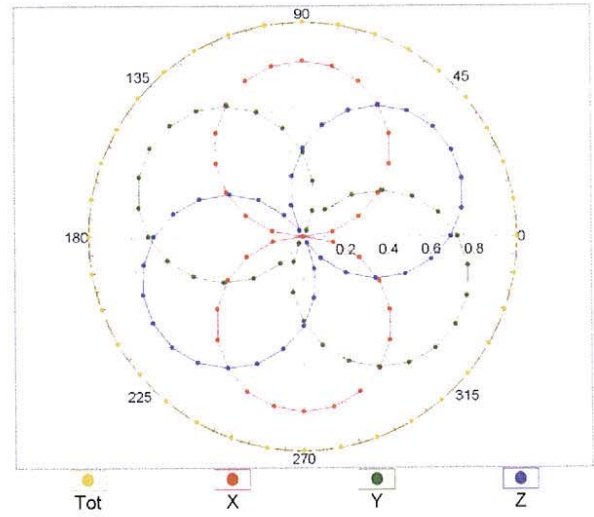
Uncertainty of Frequency Response of E-field:  $\pm 6.3\%$  (k=2)

## Receiving Pattern ( $\phi$ ), $\theta = 0^\circ$

f=600 MHz,TEM



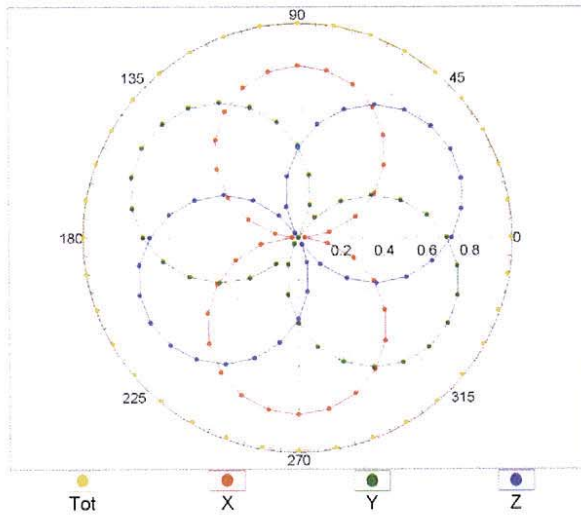
f=1800 MHz,R22



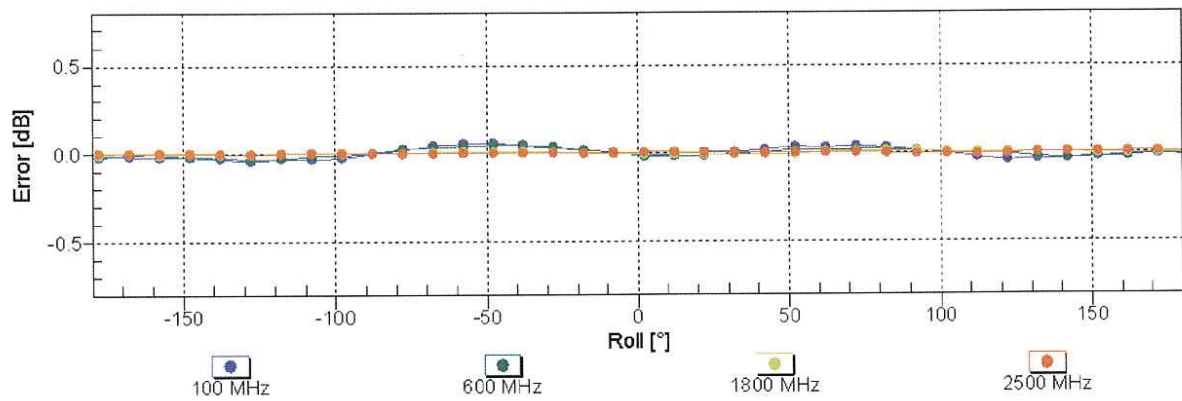
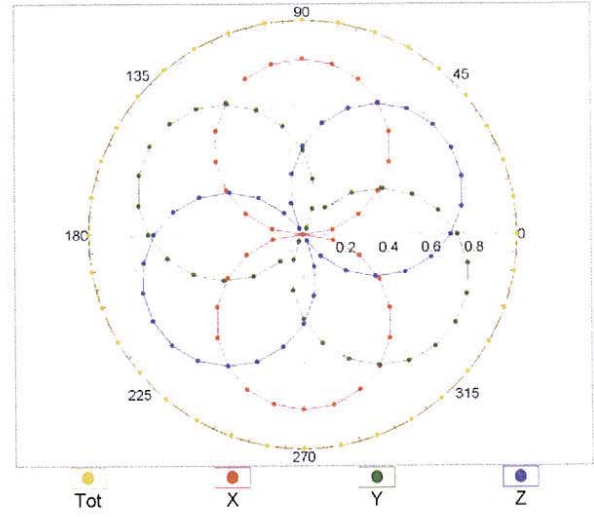
**Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  (k=2)**

## Receiving Pattern ( $\phi$ ), $\theta = 0^\circ$

f=600 MHz,TEM

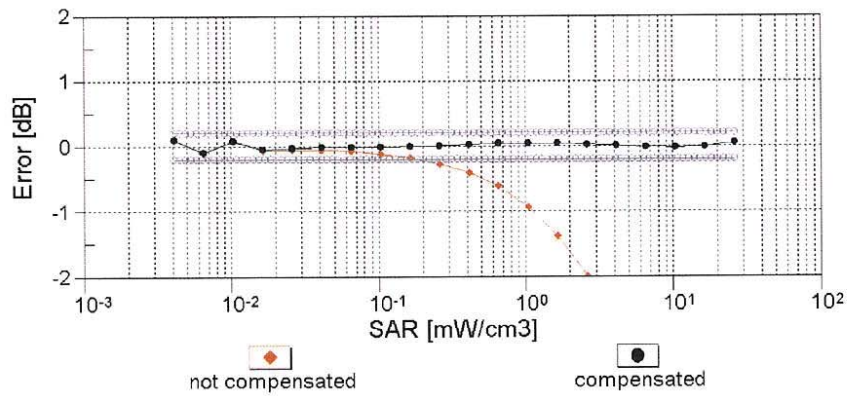
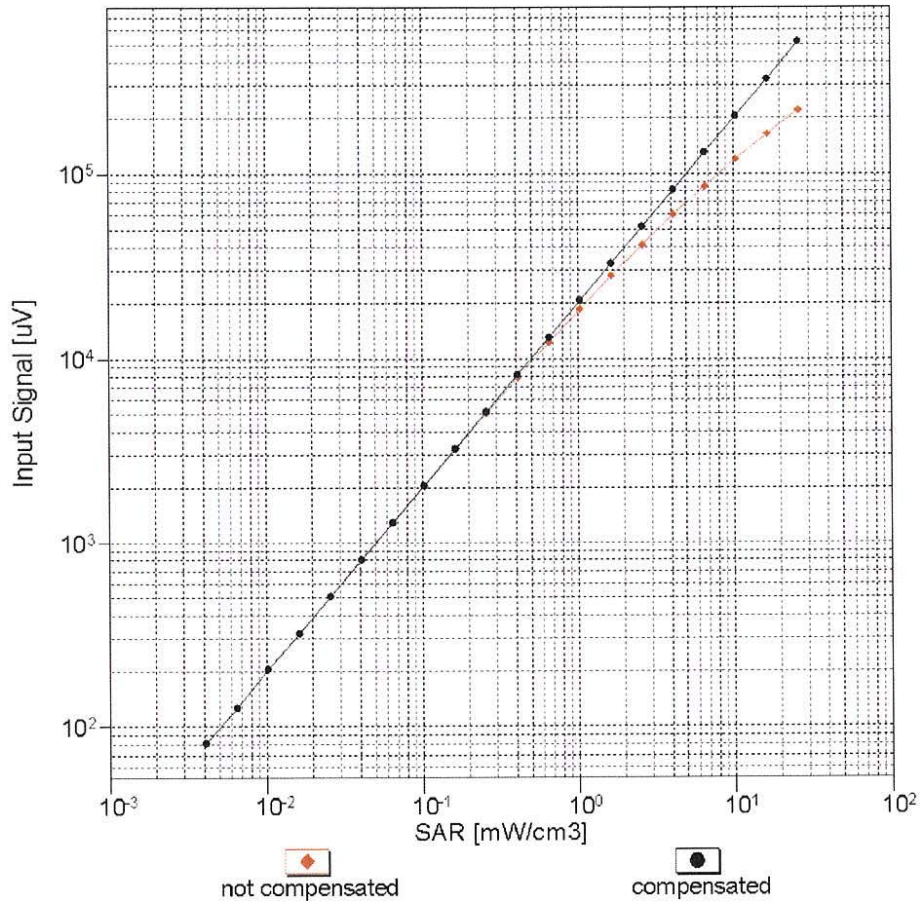


f=1800 MHz,R22



**Uncertainty of Axial Isotropy Assessment:  $\pm 0.5\%$  (k=2)**

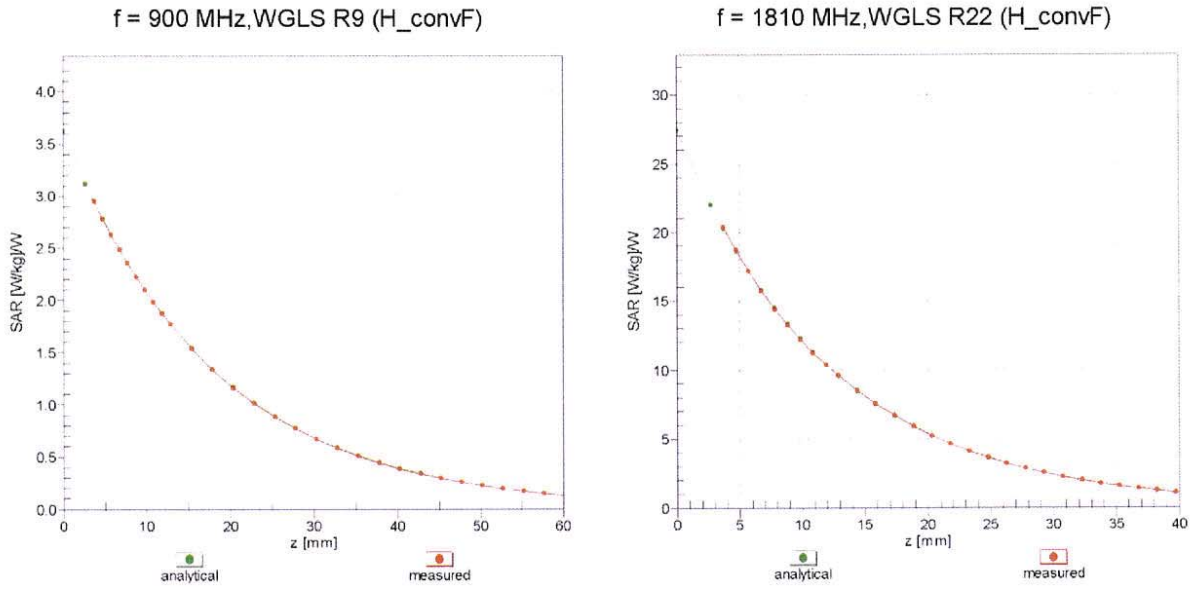
## Dynamic Range $f(SAR_{head})$ (TEM cell , $f = 900$ MHz)



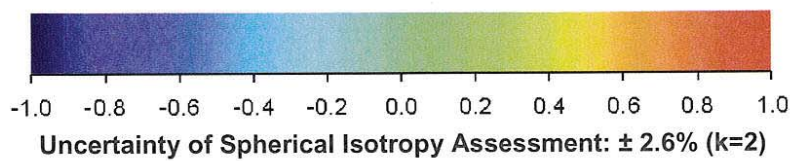
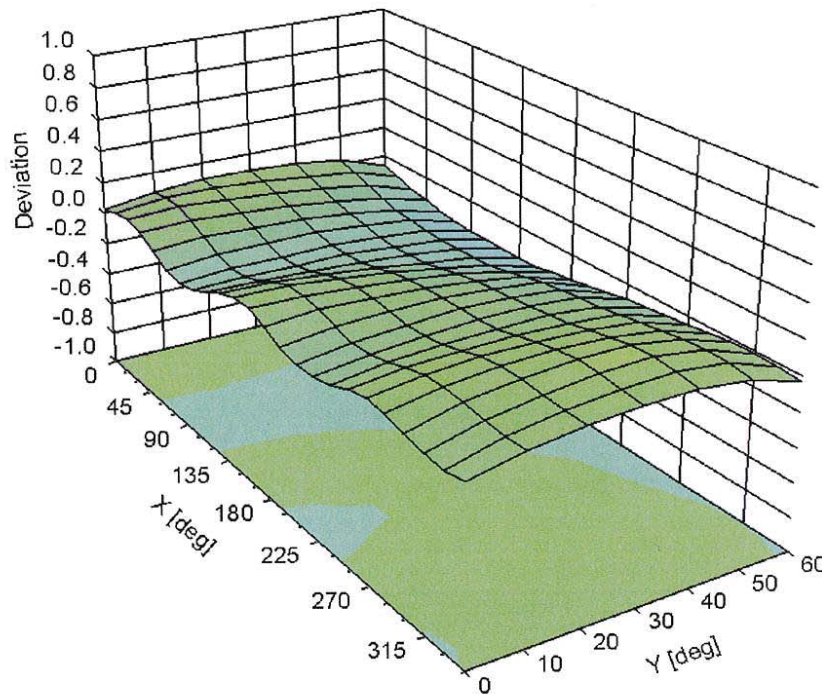
**Uncertainty of Linearity Assessment:  $\pm 0.6\%$  ( $k=2$ )**



# Conversion Factor Assessment



## Deviation from Isotropy in Liquid Error ( $\phi, \vartheta$ ), f = 900 MHz



## DASY/EASY - Parameters of Probe: ET3DV6 - SN:1711

### Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	-107.8
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	enabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	6.8 mm
Probe Tip to Sensor X Calibration Point	2.7 mm
Probe Tip to Sensor Y Calibration Point	2.7 mm
Probe Tip to Sensor Z Calibration Point	2.7 mm
Recommended Measurement Distance from Surface	4 mm