SAR EVALUATION REPORT

For

Motion Computing, Inc.

8601 Ranch Road 2222 Building II,

Austin, TX 78730, USA

FCC ID: Q3QIHWM6235ANH
IC: 4587A-IM6235AN

Report Type:	Product Type:
CIIPC	WLAN Module with Tablet PC

Prepared By: Ricky Wang

Report Number: R1212071-FCC-SAR

Report Date: 2013-01-02

Reviewed By: Quinn Jiang
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<table>
<tr><th colspan="4">Summary of Test Results</th></tr>
<tr><td>Rule Part(s):</td><td colspan="3">FCC §2.1093, IC RSS-102, Issue 4</td></tr>
<tr><td>Test Procedure(s):</td><td colspan="3">FCC OET Bulletin 65-C; IEEE 1528, RSS-102</td></tr>
<tr><td>Device Category:
Exposure Category:</td><td colspan="3">Portable Device
General Population/Uncontrolled Exposure</td></tr>
<tr><td>Device Type:</td><td colspan="3">Portable Device</td></tr>
<tr><td>Modulation Type:</td><td colspan="3">GMSK/WCDMA
CCK, DQPSK,DBPSK for DSSS
64QAM, 16QAM, QPSK, BPSK for OFDM</td></tr>
<tr><td>TX Frequency Range:</td><td colspan="3">Bluetooth (FHSS): 2402-2480 MHz
Bluetooth (BLE): 2402-2480 MHz
802.11 b/g/n20/n40: 2412-2462 MHz/2422-2452 MHz
802.11 a/n20/n40: 5180-5240 MHz/5190-5230 MHz
802.11 a/n20/n40: 5260-5320 MHz/5270-5310 MHz
802.11 a/n20/n40: 5500-5700 MHz/5510-5670 MHz
802.11 a/n20/n40: 5745-5825 MHz/5755-5795 MHz</td></tr>
<tr><td rowspan="2">Maximum Conducted Power Tested:</td><td colspan="2">Bluetooth : 6.74 dBm
802.11b/g/n20/n40:16.91 dBm</td><td>2.4 GHz</td></tr>
<tr><td colspan="2">802.11 a/n20/n40 5180-5240 MHz: 16.48 dBm
802.11 a/n20/n40 5260-5320 MHz: 16.61 dBm
802.11 a/n20/n40 5500-5700 MHz: 16.50 dBm
802.11 a/n20/n40 5745-5825 MHz: 23.93 dBm</td><td>5 GHz</td></tr>
<tr><td>Antenna Type(s) Tested:</td><td colspan="3">Internal Antenna</td></tr>
<tr><td>Body-Worn Accessories:</td><td colspan="3">None</td></tr>
<tr><td>Face-Head Accessories:</td><td colspan="3">None</td></tr>
<tr><td>Battery Type (s) Tested:</td><td colspan="3">Li-Ion: 14.8V/2900mAh</td></tr>
<tr><td rowspan="4">Max. SAR Level (s) Measured:</td><td>Level (W/Kg)</td><td>Position</td><td>Operational Mode</td></tr>
<tr><td>0.074</td><td>Back Touch</td><td>2.4 GHz</td></tr>
<tr><td>Level (W/Kg)</td><td>Position</td><td>Operational Mode</td></tr>
<tr><td>0.168</td><td>Back Touch</td><td>5 GHz</td></tr>
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1 General Description

1.1 Product Description for Equipment Under Test (EUT)

This test and measurement report was prepared on behalf of *Motion Computing, Inc.*, and their product, FCC ID: *Q3QIHWM6235ANH*, IC: *4587A-IM6235AN*, model: N6235, or the "EUT" as referred to in this report, is a WLAN/Bluetooth combo module which built into Motion Tablet PC with WWAN and GPS Functionalities. Based on the declaration by the manufacture, there’re no simultaneous transmissions between WWAN and WLAN + BT radios.

The current Motion Tablet PC J3600, model: T008 is an update version from previous motion tablet PC J3500. The changes made to the current J3600 from the previous J3500 were the WLAN+BT combo card with new antenna type. The WWAN portion remains the same. Therefore, SAR measurement is only required for WLAN.

1.2 EUT Technical Specification

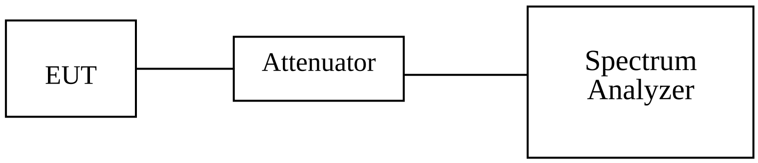
Item	Description	
Modulation	CCK, DQPSK,DBPSK for DSSS 64QAM, 16QAM, QPSK, BPSK for OFDM GFSK, QPSK, BPSK for FHSS	
Frequency Range	Bluetooth (FHSS): 2402-2480 MHz Bluetooth (BLE): 2402-2480 MHz 802.11 b/g/n20/n40: 2412-2462 MHz 802.11 a/n20/n40 5180-5240 MHz 802.11 a/n20/n40 5260-5320 MHz 802.11 a/n20/n40 5500-5700 MHz 802.11 a/n20/n40 5745-5825 MHz	
Maximum Conducted Power Tested:	Bluetooth: 6.74 dBm 802.11b/g/n20/n40: 16.91 dBm	2.4 GHz
	802.11 a/n20/n40 5180-5240 MHz: 16.48 dBm 802.11 a/n20/n40 5260-5320 MHz: 16.61 dBm 802.11 a/n20/n40 5500-5700 MHz: 16.50 dBm 802.11 a/n20/n40 5745-5825 MHz: 23.93 dBm	5 GHz
Dimensions (L*W*H)	Tablet PC: 320mm (L) x 230mm (W) x 20 mm (H)	
Power Source	Li-Ion: 14.8V/2000mAh	
Weight	1750g (Tablet PC with battery)	
Normal Operation	Body-worn	

The test data gathered are from typical production sample, Sample ID: R1212071 provided by BACL.

2 Conducted Power Measurement

Test Block Diagram and Procedure

The RF output of the transmitter was connected to the input of the spectrum analyzer through sufficient attenuation.



Conducted Output Power Results

Modulation	Frequency	Output Power Conducted (dBm)		
		Main Antenna	Aux Antenna	Combined Power
802.11b	2412	16.80	16.20	/
	2437	16.91	14.60	/
	2462	16.87	15.40	/
802.11g	2412	12.94	12.30	/
	2437	15.60	15.60	/
	2462	13.34	12.40	/
802.11n20	2412	12.12	11.10	/
	2437	15.63	15.64	/
	2462	11.50	11.24	/
802.11n20 MIMO	2412	11.89	11.84	14.88
	2437	13.32	13.45	16.34
	2462	10.78	10.68	13.74
802.11n40	2422	9.16	8.37	/
	2437	12.00	12.00	/
	2452	9.00	9.10	/
802.11n40 MIMO	2422	6.88	7.32	10.12
	2437	11.99	12.64	15.34
	2452	6.78	7.14	9.97

Modulation	Frequency	Output Power Conducted (dBm)		
		Main Antenna	Aux Antenna	Combined Power
802.11a	5180	16.45	16.40	/
	5200	16.44	16.47	/
	5240	16.48	16.34	/
802.11n 20	5180	16.07	16.40	/
	5200	16.16	16.35	/
	5240	16.00	16.39	/
802.11n 20 MIMO	5180	13.34	13.40	16.38
	5200	13.44	13.41	16.44
	5240	13.31	12.90	16.12
802.11n40	5190	13.03	13.20	/
	5230	16.04	16.28	/
802.11n40 MIMO	5190	10.16	11.06	13.64
	5230	13.61	13.61	16.62

Modulation	Frequency	Output Power Conducted (dBm)		
		Main Antenna	Aux Antenna	Combined Power
802.11a	5260	15.87	15.41	/
	5300	16.42	15.39	/
	5320	16.35	16.03	/
802.11n 20	5260	16.25	15.31	/
	5300	16.61	15.31	/
	5320	16.51	15.65	/
802.11n 20 MIMO	5260	13.06	12.51	15.80
	5300	13.46	12.81	16.16
	5320	13.10	13.20	16.16
802.11n40	5270	16.09	15.26	/
	5310	11.50	12.40	/
802.11n40 MIMO	5270	12.81	12.77	15.80
	5310	12.58	12.48	15.54

Modulation	Frequency	Output Power Conducted (dBm)		
		Main Antenna	Aux Antenna	Combined Power
802.11a	5500	16.30	15.63	/
	5580	16.50	15.68	/
	5700	16.43	15.60	/
802.11n 20	5500	16.25	15.52	/
	5580	16.46	15.60	/
	5700	16.11	15.51	/
802.11n 20 MIMO	5500	12.86	13.23	16.06
	5580	12.74	13.23	16.00
	5700	12.64	12.43	15.55
802.11n40	5510	15.58	14.75	/
	5550	16.45	15.65	/
	5670	16.22	15.51	/
802.11n40 MIMO	5510	13.44	13.21	16.34
	5550	13.24	13.20	16.23
	5670	12.94	12.85	15.91

Modulation	Frequency	Output Power Conducted (dBm)		
		Main Antenna	Aux Antenna	Combined Power
802.11a	5745	14.68	16.16	/
	5785	14.21	15.95	/
	5825	14.23	16.03	/
802.11n 20	5745	14.87	16.03	/
	5785	14.42	16.17	/
	5825	14.41	15.91	/
802.11n 20 MIMO	5745	10.25	10.48	13.38
	5785	10.66	10.48	13.58
	5825	10.31	10.66	13.50
802.11n40	5755	19.90	20.00	/
	5795	19.80	20.00	/
802.11n40 MIMO	5755	20.86	20.98	23.93
	5795	20.77	20.65	23.72

Bluetooth Output Power

Mode	Channel	Frequency (MHz)	Conducted Output Power (dBm)
BDR (GFSK)	Low	2402	6.02
	Middle	2440	6.56
	High	2480	6.74
EDR (π/4-DQPSK)	Low	2402	3.06
	Middle	2440	3.86
	High	2480	3.74
EDR (8DPSK)	Low	2402	2.92
	Middle	2440	3.96
	High	2480	3.78
BLE	Low	2402	6.32
	Middle	2440	6.66
	High	2480	6.74

Note*: 802.11 n20/n40 contains both SISO and MIMO functionality.

3 SAR Measurement Results

This page summarizes the results of the performed dosimetric evaluation. The plots with the corresponding SAR distributions, which reveal information about the location of the maximum SAR with respect to the device, could be found in Appendix E.

3.1 Test Environmental Conditions

Temperature:	22 °C
Relative Humidity:	53 %
ATM Pressure:	101.8kPa

Testing was performed by Ricky Wang on 2012-12-14 - 2012-12-18 in SAR chamber.

2.4 GHz Band									
Radio Mode	**EUT Position**	**Frequency (MHz)**	**Test Type**	**Antenna Type**	**Antenna**	**Phantom**	**SAR Value (W/kg) 1g Tissue**	**Limit (W/kg) 1g Tissue**	**Plot #**
802.11b	Back side Touch (Mid CH)	2437	Body	Integral	Main	Flat	0.073	1.6	1
802.11n20	Back side Touch (Mid CH)	2437	Body	Integral	Aux	Flat	0.059	1.6	2
802.11n20 MIMO	Back side Touch (Mid CH)	2437	Body	Integral	Aux+ Main	Flat	0.074	1.6	3
802.11n40	Back side Touch (Mid CH)	2437	Body	Integral	Aux	Flat	0.019	1.6	4
802.11n40 MIMO	Back side Touch (Mid CH)	2437	Body	Integral	Aux+ Main	Flat	0.048	1.6	5

5 GHz Band									
Radio Mode	**EUT Position**	**Frequency (MHz)**	**Test Type**	**Antenna Type**	**Antenna**	**Phantom**	**SAR Value (W/kg) 1g Tissue**	**Limit (W/kg) 1g Tissue**	**Plot #**
802.11a	Back side Touch (Mid CH)	5200	Body	Integral	Aux	Twin	0.168	1.6	6
	Back side Touch (Mid CH)	5300	Body	Integral	Main	Twin	0.145	1.6	7
	Back side Touch (Mid CH)	5580	Body	Integral	Main	Twin	0.135	1.6	8
	Back side Touch (Low CH)	5745	Body	Integral	Aux	Twin	0.098	1.6	9
802.11n20	Back side Touch (Mid CH)	5200	Body	Integral	Aux	Twin	0.101	1.6	10
	Back side Touch (Mid CH)	5300	Body	Integral	Main	Twin	0.145	1.6	11
	Back side Touch (Mid CH)	5580	Body	Integral	Main	Twin	0.086	1.6	12
	Back side Touch (Mid CH)	5785	Body	Integral	Aux	Twin	0.090	1.6	13
802.11n20 MIMO	Back side Touch (Mid CH)	5200	Body	Integral	Aux+ Main	Twin	0.066	1.6	14
	Back side Touch (Mid CH)	5300	Body	Integral	Aux+ Main	Twin	0.081	1.6	15
	Back side Touch (Low CH)	5500	Body	Integral	Aux+ Main	Twin	0.123	1.6	16
	Back side Touch (Mid CH)	5785	Body	Integral	Aux+ Main	Twin	No Value	1.6	-*

Note*: *The SAR values of back side touch at 5785MHz (802.11n20 MIMO) is on the noise floor.*

5 GHz Band									
Radio Mode	**EUT Position**	**Frequency (MHz)**	**Test Type**	**Antenna Type**	**Antenna**	**Phantom**	**SAR Value (W/kg) 1g Tissue**	**Limit (W/kg) 1g Tissue**	**Plot #**
802.11n40	Back side Touch (High CH)	5230	Body	Integral	Aux	Twin	0.084	1.6	17
	Back side Touch (Low CH)	5270	Body	Integral	Main	Twin	0.167	1.6	18
	Back side Touch (Mid CH)	5550	Body	Integral	Main	Twin	0.120	1.6	19
	Back side Touch (High CH)	5795	Body	Integral	Aux	Twin	0.108	1.6	20
802.11n40 MIMO	Back side Touch (High CH)	5230	Body	Integral	Aux+ Main	Twin	0.056	1.6	21
	Back side Touch (Low CH)	5270	Body	Integral	Aux+ Main	Twin	0.00161	1.6	22
	Back side Touch (Low CH)	5510	Body	Integral	Aux+ Main	Twin	0.067	1.6	23
	Back side Touch (Low CH)	5755	Body	Integral	Aux+ Main	Twin	0.123	1.6	24

Note

1. *For the right/left side touch to phantom position, the SAR measurements were on the noise floor; therefore, right/left side touch to phantom SAR are not listed.*
2. *According To KDB 248227, SAR is not required for 802.11g channels when the maximum average output power is less than1/4dB than that measured on the corresponding 802.11b channels.*

Based on the manufacturer's statement, the tablet computer (Motion Computing J3600, model: T008) only supports 3 screen orientations:

a. Landscape mode (fig. 1)
b. Portrait mode-right (fig. 2)
c. Portrait mode-left (fig. 3)

The J3600 (model: T008) tablet PC does not support the orientation that places the top of the product (RF antenna) against the body.

Fig.1:

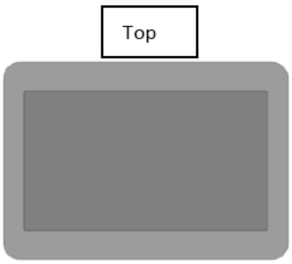
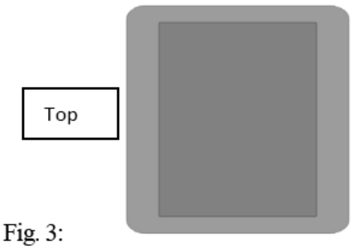


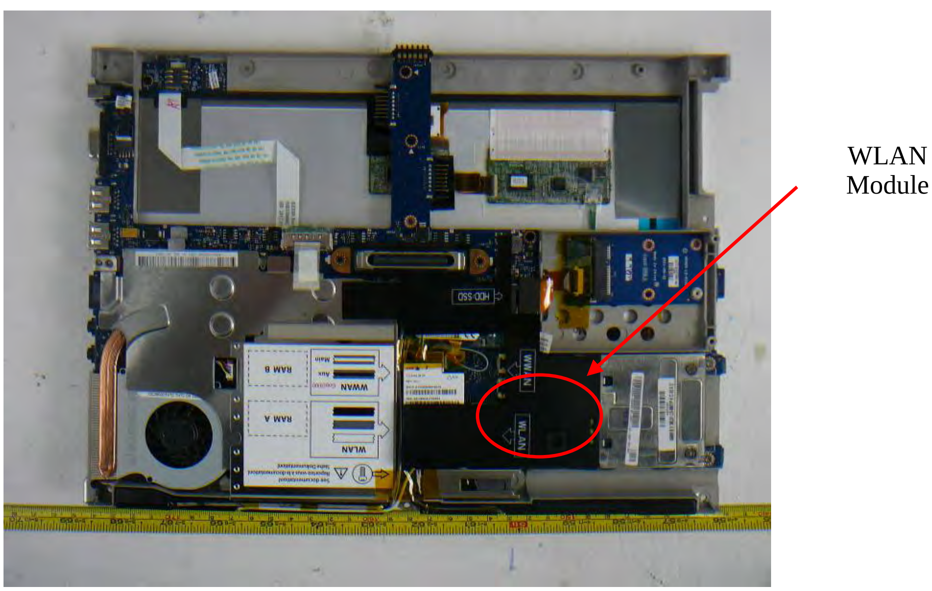
Fig. 2:

Fig. 3:

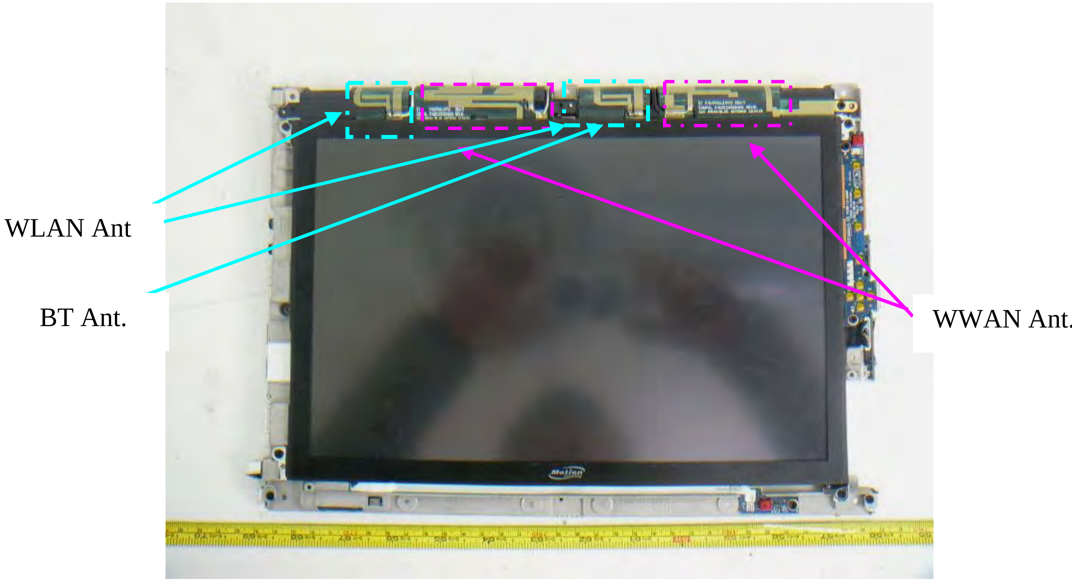


The Motion Computing J3600 tablet PC (Model: T008) contains at most three radio modules inside, namely Bluetooth, WLAN and WWAN radios, each internal radio has individual registration identifiers. Based on the manufacturer's statement, WLAN and WWAN radio modules are not allowed to transmit simultaneously. The manufacturer has embedded a software tool that notifies the user that the two radios are not allowed to transmit at the same time, please refer to the statement with this filing.

Back View



Front View



Note:

1. *According to KDB 447498, Bluetooth Power (conducted) ≤10mw, the standalone SAR is not required for Bluetooth. The maximum conducted BT power is 4.72 mW (6.74 dBm); therefore, standalone SAR is not required for FCC*
2. *According to RSS 102 section 2.5.1, if the output power (conducted or radiated) power is ≤ 20 mW, Standalone SAR is not required. The max EIRP of BT is 10.5mW (6.74 +3.47 (ant gain)). Therefore, Stand alone SAR is not required for IC.*

5 Test Facility

The test site used by BACL Corp. to collect radiated and conducted emissions measurement data is located at its facility in Sunnyvale, California, USA.

The test site at BACL Corp. has been fully described in reports submitted to the Federal Communication Commission (FCC) and Voluntary Control Council for Interference (VCCI). The details of these reports have been found to be in compliance with the requirements of Section 2.948 of the FCC Rules on February 11 and December 10, 1997, and Article 8 of the VCCI regulations on December 25, 1997. The test site also complies with the test methods and procedures set forth in CISPR 22:2008 §10.4 for measurements below 1 GHz and §10.6 for measurements above 1 GHz as well as ANSI C63.4-2003, ANSI C63.4-2009, TIA/EIA-603 & CISPR 24:2010.

The Federal Communications Commission and Voluntary Control Council for Interference have the reports on file and they are listed under FCC registration number: 90464 and VCCI Registration No.: A-0027. The test site has been approved by the FCC and VCCI for public use and is listed in the FCC Public Access Link (PAL) database.

Additionally, BACL Corp. is an American Association for laboratory Accreditation (A2LA) accredited laboratory (Lab Code 3297-02). The current scope of accreditations can be found at

http://www.a2la.org/scopepdf/3297-02.pdf?CFID=1132286&CFTOKEN=e42a3240dac3f6ba-6DE17DCB-1851-9E57-477422F667031258&jsessionid=8430d44f1f47cf2996124343c704b367816b

6 Reference, Standards and Guidelines

FCC:

The Report and Order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mW/g as recommended by the ANSI/IEEE standard C95.1-1992 [6] for an uncontrolled environment (Paragraph 65). According to the Supplement C of OET Bulletin 65 “Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under “worst-case” conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

This report describes the methodology and results of experiments performed on wireless data terminal. The objective was to determine if there is RF radiation and if radiation is found, what is the extent of radiation with respect to safety limits. SAR (Specific Absorption Rate) is the measure of RF exposure determined by the amount of RF energy absorbed by human body (or its parts) – to determine how the RF energy couples to the body or head which is a primary health concern for body worn devices. The limit below which the exposure to RF is considered safe by regulatory bodies in North America is 1.6 mW/g average over 1 gram of tissue mass.

CE:

The CE requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 2 mW/g as recommended by the EN50360 for an uncontrolled environment. According to the Standard, the device should be evaluated at maximum output power (radiated from the antenna) under “worst-case” conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

This report describes the methodology and results of experiments performed on wireless data terminal. The objective was to determine if there is RF radiation and if radiation is found, what is the extent of radiation with respect to safety limits? SAR (Specific Absorption Rate) is the measure of RF exposure determined by the amount of RF energy absorbed by human body (or its parts) – to determine how the RF energy couples to the body or head which is a primary health concern for body worn devices. The limit below which the exposure to RF is considered safe by regulatory bodies in Europe is 2 mW/g average over 10 gram of tissue mass.

The test configurations were laid out on a specially designed test fixture to ensure the reproducibility of measurements. Each configuration was scanned for SAR. Analysis of each scan was carried out to characterize the above effects in the device.

6.1 SAR Limits

FCC Limit (1g Tissue)

EXPOSURE LIMITS	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)
Spatial Average (averaged over the whole body)	0.08	0.4
Spatial Peak (averaged over any 1 g of tissue)	1.60	8.0
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

CE Limit (10g Tissue)

EXPOSURE LIMITS	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)
Spatial Average (averaged over the whole body)	0.08	0.4
Spatial Peak (averaged over any 1 g of tissue)	2.0	10
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

Population/Uncontrolled Environments are defined as locations where there is the exposure of individual who have no knowledge or control of their exposure.

Occupational/Controlled Environments are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure (i.e. as a result of employment or occupation).

General Population/Uncontrolled environments Spatial Peak limit 1.6 W/kg (FCC) & 2 W/kg (CE) applied to the EUT.

7 Equipment List and Calibration

7.1 Equipments List & Calibration Info

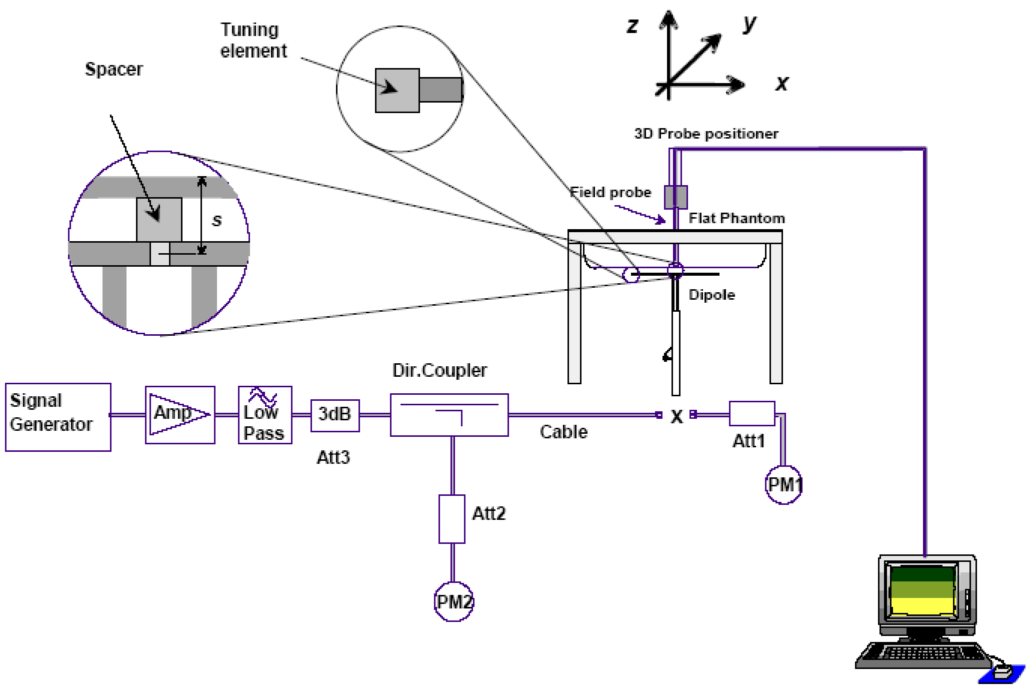
Type/Model	Cal. Due Date	S/N
DASY4 Professional Dosimetric System	N/A	N/A
Robot RX60L	N/A	CS7MBSP / 467
Robot Controller	N/A	F01/5J72A1/A/01
Dell Computer Dimension 3000	N/A	N/A
SPEAG EDC3	N/A	N/A
SPEAG DAE3	2014-03-16	456
DASY4 Measurement Server	N/A	1176
Schmid & Partner ET3DV6	2013-08-25	1604
SPEAG E-Field Probe EX3DV4	2013-08-25	3619
Antenna, Dipole, D-2450-S-1	2014-07-25	BCL-141
Antenna, Dipole, D5100V2	2014-08-23	1001
SPEAG Flat Phantom	N/A	1004
Brain Equivalent Matter (2450 MHz)	Each Time	N/A
Muscle Equivalent Matter (2450 MHz)	Each Time	N/A
Brain Equivalent Matter (5200 MHz)	Each Time	N/A
Muscle Equivalent Matter (5200 MHz)	Each Time	N/A
Brain Equivalent Matter (5600 MHz)	Each Time	N/A
Muscle Equivalent Matter (5600 MHz)	Each Time	N/A
Brain Equivalent Matter (5800 MHz)	Each Time	N/A
Muscle Equivalent Matter (5800 MHz)	Each Time	N/A
Agilent, Spectrum Analyzer E4440A	2013-05-10	MY44303352
Microwave Amp. 8349A	N/A	2644A02662
Power Meter Agilent E4419B	2013-09-01	MY4121511
Power Sensor Agilent E4412A	N/A	N/A
Dielectric Probe Kit HP85070A	N/A	US99360201
HP, Signal Generator, 83650B	2013-06-21	3614A00276
Amplifier, ST181-20	N/A	E012-0101
Antenna, Horn DRH-118	N/A	A052704

8 SAR Measurement System Verification

8.1 System Accuracy Verification

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of ±10%. The validation results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

8.2 System Setup Block Diagram



8.3 Liquid and System Validation

Date	Simulant	Freq. [MHz]	Parameters	Liquid Temp [°C]	Target Value	Measured Value	Deviation [%]	Limits [%]
2012-12-14	Body	2450	εr	22	52.7	50.7	-3.80	± 5
			σ	22	1.95	2.02	3.59	± 5
			1g SAR	22	53.115	52.6	-0.97	± 10

Date	Simulant	Freq. [MHz]	Parameters	Liquid Temp [°C]	Target Value	Measured Value	Deviation [%]	Limits [%]
2012-12-14	Body	5200	εr	22	49.0	47.9	-2.24	± 5
			σ	22	5.3	5.3	0.00	± 5
			1g SAR	22	74.9	77.6	3.60	± 10

Date	Simulant	Freq. [MHz]	Parameters	Liquid Temp [ºC]	Target Value	Measured Value	Deviation [%]	Limits [%]
2012-12-14	Body	5500	εr	22	48.6	47.0	-3.29	± 5
			σ	22	5.65	5.7	0.88	± 5
			1g SAR	22	79.3	81.0	2.14	± 10

Date	Simulant	Freq. [MHz]	Parameters	Liquid Temp [ºC]	Target Value	Measured Value	Deviation [%]	Limits [%]
2012-12-14	Body	5800	εr	22	48.2	46.5	-3.52	± 5
			σ	22	6.0	6.0	0	± 5
			1g SAR	22	74.2	76.2	2.70	± 10

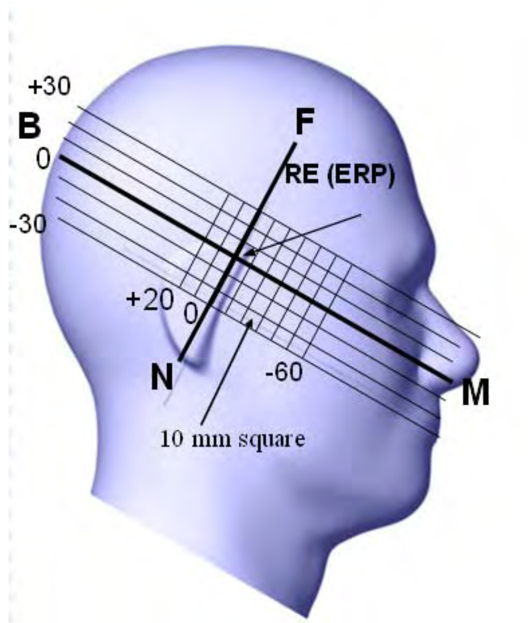
εr = relative permittivity, σ = conductivity and ρ=1000 kg/m3

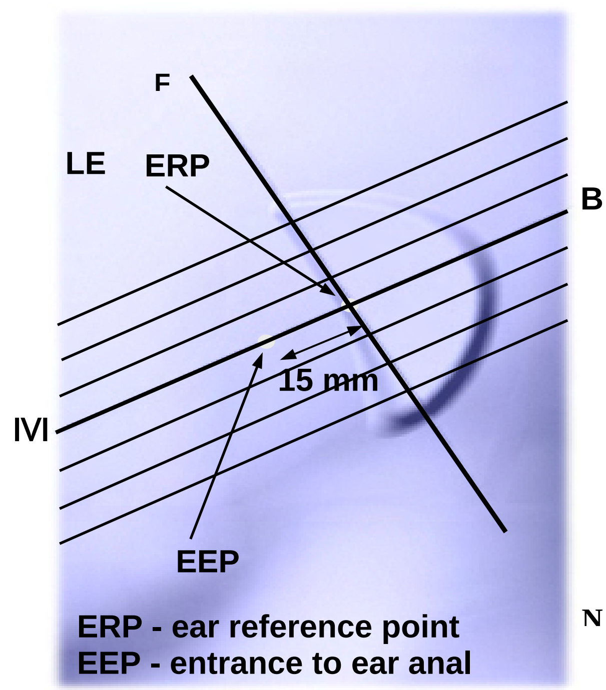
9 EUT Test Strategy and Methodology

9.1 Test Positions for Device Operating Next to a Person's Ear

This category includes most wireless handsets with fixed, retractable or internal antennas located toward the top half of the device, with or without a foldout, sliding or similar keypad cover. The handset should have its earpiece located within the upper ¼ of the device, either along the centerline or off-centered, as perceived by its users. This type of handset should be positioned in a normal operating position with the "test device reference point" located along the "vertical centerline" on the front of the device aligned to the "ear reference point". The "test device reference point" should be located at the same level as the center of the earpiece region. The "vertical centerline" should bisect the front surface of the handset at its top and bottom edges. An "ear reference point" is located on the outer surface of the head phantom on each ear spacer. It is located 1.5 cm above the center of the ear canal entrance in the "phantom reference plane" defined by the three lines joining the center of each "ear reference point" (left and right) and the tip of the mouth.

A handset should be initially positioned with the earpiece region pressed against the ear spacer of a head phantom. For the SCC-34/SC-2 head phantom, the device should be positioned parallel to the "N-F" line defined along the base of the ear spacer that contains the "ear reference point". For interim head phantoms, the device should be positioned parallel to the cheek for maximum RF energy coupling. The "test device reference point" is aligned to the "ear reference point" on the head phantom and the "vertical centerline" is aligned to the "phantom reference plane". This is called the "initial ear position". While maintaining these three alignments, the body of the handset is gradually adjusted to each of the following positions for evaluating SAR:





9.2 Cheek/Touch Position

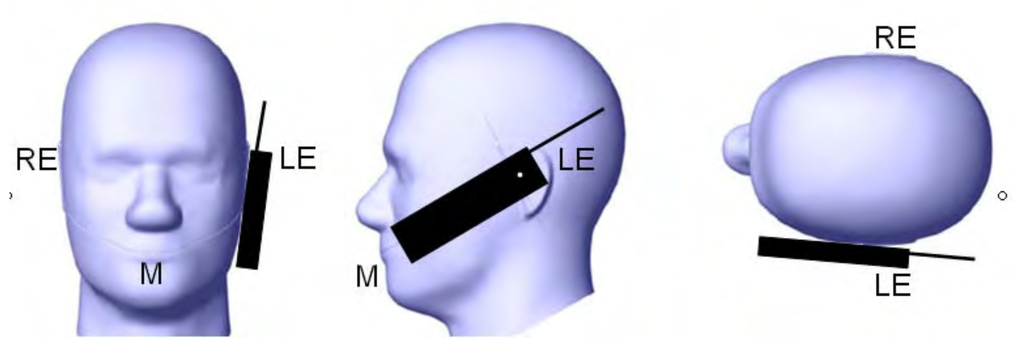
The device is brought toward the mouth of the head phantom by pivoting against the “ear reference point” or along the “N-F” line for the SCC-34/SC-2 head phantom.

This test position is established:

- When any point on the display, keypad or mouthpiece portions of the handset is in contact with the phantom.
- (or) When any portion of a foldout, sliding or similar keypad cover opened to its intended self-adjusting normal use position is in contact with the cheek or mouth of the phantom.

For existing head phantoms – when the handset loses contact with the phantom at the pivoting point, rotation should continue until the device touches the cheek of the phantom or breaks its last contact from the ear spacer.

Cheek /Touch Position



9.3 Ear/Tilt Position

With the handset aligned in the “Cheek/Touch Position”:

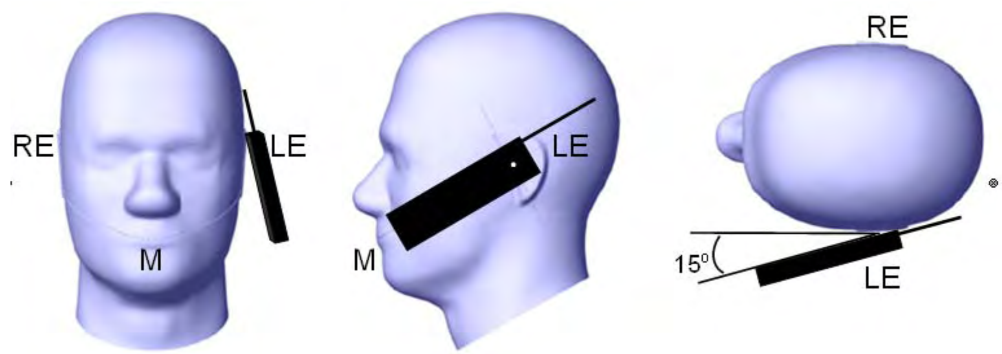
1) If the earpiece of the handset is not in full contact with the phantom’s ear spacer (in the “Cheek/Touch position”) and the peak SAR location for the “Cheek/Touch” position is located at the ear spacer region or corresponds to the earpiece region of the handset, the device should be returned to the “initial ear position” by rotating it away from the mouth until the earpiece is in full contact with the ear spacer.

2) (otherwise) The handset should be moved (translated) away from the cheek perpendicular to the line passes through both “ear reference points” (note: one of these ear reference points may not physically exist on a split head model) for approximate 2-3 cm. While it is in this position, the device handset is tilted away from the mouth with respect to the “test device reference point” until the inside angle between the vertical centerline on the front surface of the phone and the horizontal line passing through the ear reference point is by 15 80°. After the tilt, it is then moved (translated) back toward the head perpendicular to the line passes through both “ear reference points” until the device touches the phantom or the ear spacer. If the antenna touches the head first, the positioning process should be repeated with a tilt angle less than 15 80° so that the device and its antenna would touch the phantom simultaneously. This test position may require a device holder or positioner to achieve the translation and tilting with acceptable positioning repeatability.

If a device is also designed to transmit with its keypad cover closed for operating in the head position, such positions should also be considered in the SAR evaluation. The device should be tested on the left and right side of the head phantom in the “Cheek/Touch” and “Ear/Tilt” positions. When applicable, each configuration should be tested with the antenna in its fully extended and fully retracted positions.

These test configurations should be tested at the high, middle and low frequency channels of each operating mode; for example, AMPS, CDMA, and TDMA. If the SAR measured at the middle channel for each test configuration (left, right, Cheek/Touch, Tile/Ear, extended and retracted) is at least 2.0 dB lower than the SAR limit, testing at the high and low channels is optional for such test configuration(s). If the transmission band of the test device is less than 10 MHz, testing at the high and low frequency channels is optional.

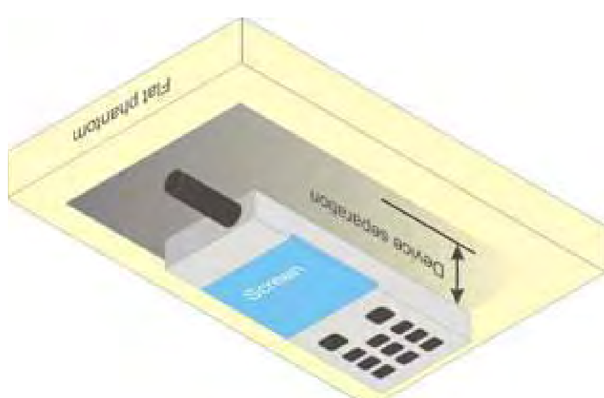
Ear /Tilt 15º Position



9.4 Test positions for body-worn and other configurations

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a headset output should be tested with a headset connected to the device. When multiple accessories that do not contain metallic components are supplied with the device, the device may be tested with only the accessory that dictates the closest spacing to the body. When multiple accessories that contain metallic components are supplied with the device, the device must be tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (e.g., the same metallic belt-clip used with different holsters with no other metallic components), only the accessory that dictates the closest spacing to the body must be tested.

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. Other separation distances may be used, but they should not exceed 2.5 cm. In these cases, the device may use body-worn accessories that provide a separation distance greater than that tested for the device provided however that the accessory contains no metallic components.



9.5 SAR Evaluation Procedure

The evaluation was performed with the following procedure:

Step 1: Measurement of the SAR value at a fixed location above the ear point or central position was used as a reference value for assessing the power drop. The SAR at this point is measured at the start of the test and then again at the end of the testing.

Step 2: The SAR distribution at the exposed side of the head was measured at a distance of 4 mm from the inner surface of the shell. The area covered the entire dimension of the head or EUT and the horizontal grid spacing was 15 mm x 15 mm. Based on these data, the area of the maximum absorption was determined by line interpolation. The first Area Scan covers the entire dimension of the EUT to ensure that the hotspot was correctly identified.

Step 3: Around this point, a volume of 30 mm x 30 mm x 21 mm was assessed by measuring 5 x 5 x 7 points. On the basis of this data set, the spatial peak SAR value was evaluated under the following procedure:

1. The data at the surface were extrapolated, since the center of the dipoles is 1.2 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.3 mm. The extrapolation was based on a least square algorithm. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.

2. The maximum interpolated value was searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g or 10 g) were computed by the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one dimensional splines with the “Not a knot"-condition (in x, y and z-directions). The volume was integrated with the trapezoidal-algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the averages.

3. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

Step 4: Re-measurement of the SAR value at the same location as in Step 1. If the value changed by more than 5%, the evaluation was repeated.

9.6 Test Methodology

The tests documented in this report were performed in accordance with FCC OET Bulletin 65 Supplement C 01 01, IC RSS 102 Issue 4 and following specific FCC Test Procedures.

- KDB 941225 D01 SAR test for 3G devices v02
- KDB 941225 D03 SAR Test Reduction GSM/GPRS/EDGE v01
- KDB 648474 D01 SAR Handsets Multi Xmitter and Ant, v01r05
- KDB 248227 D01 SAR meas for 802 11 abg v01r02

10 DASY4 SAR Evaluation Procedure

10.1 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method. The Minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. By default, the Minimum distance of probe sensors to surface is 4mm. This distance can be modified by the user, but cannot be smaller than the Distance of sensor calibration points to probe tip as defined in the probe properties (for example, 2.7mm for an ET3DV6 probe type).

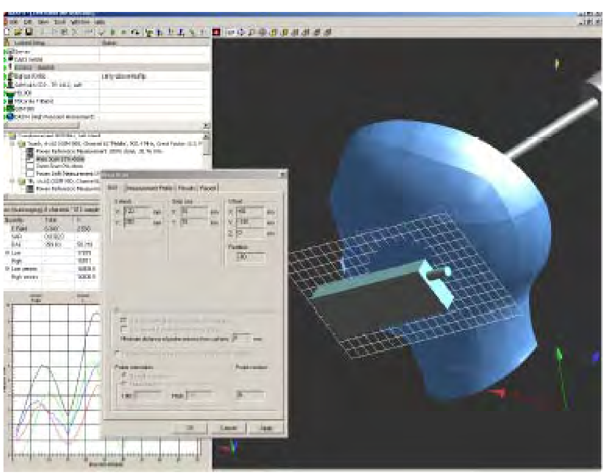
10.2 Area Scan

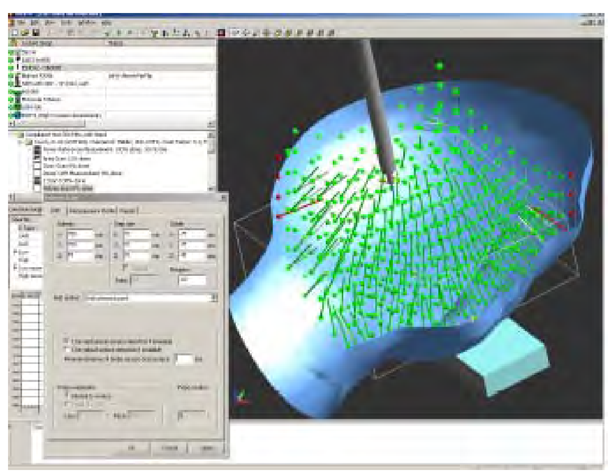
The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in DASY4 software can find the maximum locations even in relatively coarse grids.

The scanning area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom. When the Area Scan's property sheet is brought-up, grid settings can be edited by a user.

When an Area Scan has measured all reachable points, it computes the field maxima found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE 1528-2003, EN 50361 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan). If only one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of Zoom Scans has to be increased accordingly.

After measurement is completed, all maxima and their coordinates are listed in the Results property page. The maximum selected in the list is highlighted in the 3-D view. For the secondary maxima returned from an Area Scan, the user can specify a lower limit (peak SAR value), in addition to the Find secondary maxima within x dB condition. Only the primary maximum and any secondary maxima within x dB from the primary maximum and above this limit will be measured.





10.3 Zoom Scan

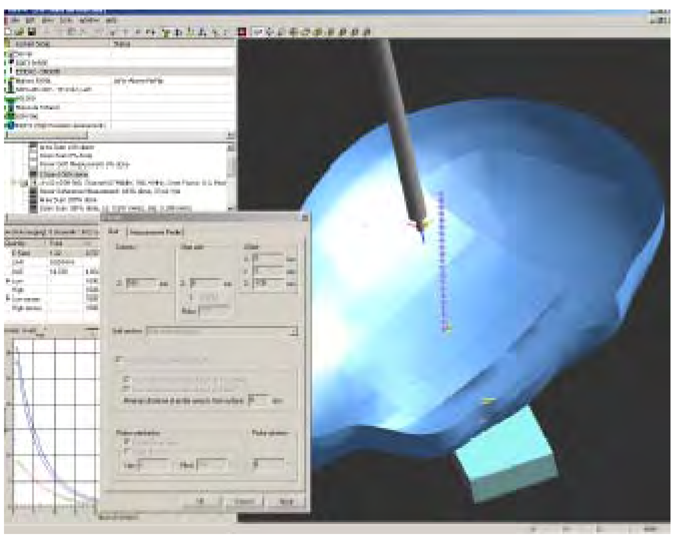
Zoom Scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default Zoom Scan measures 5 x 5 x 7 points within a cube whose base faces are centered around the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1 g and 10 g and displays these values next to the job’s label.

10.4 Power drift measurement

The Power Drift Measurement job measures the field at the same location as the most recent power reference measurement job within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the last Power Reference Measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

10.5 Z-Scan

The Z Scan job measures points along a vertical straight line. The line runs along the Z axis of a one-dimensional grid. A user can anchor the grid to the section reference point, to any defined user point or to the current probe location. As with any other grids, the local Z axis of the anchor location establishes the Z axis of the grid.



11 Appendix A – Measurement Uncertainty

The uncertainty budget has been determined for the DASY4 measurement system and is given in the following Table.

300 MHz to 3 GHz

SASY4 Uncertainty Budget According to IEEE 1528								
Error Description	Uncertainty Value	Prob. Dist.	Div.	(c i) 1g	(c i) 10g	Std. Unc. (1g)	Std. Unc. (10g)	(v i) veff
Measurement System								
Probe Calibration	± 6.0 %	N	1	1	1	± 6.0 %	± 6.0 %	∝
Axial Isotropy	± 4.7 %	R	$\sqrt{3}$	0.7	0.7	± 1.9 %	± 1.9 %	∝
Hemispherical Isotropy	± 9.6 %	R	$\sqrt{3}$	0.7	0.7	± 3.9 %	± 3.9 %	∝
Boundary Effects	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	∝
Linearity	± 4.7 %	R	$\sqrt{3}$	1	1	± 2.7 %	± 2.7 %	∝
System Detection Limits	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	∝
Readout Electronics	± 0.3 %	N	1	1	1	± 0.3 %	± 0.3 %	∝
Response Time	± 0.8 %	R	$\sqrt{3}$	1	1	± 0.5 %	± 0.5 %	∝
Integration Time	± 2.6 %	R	$\sqrt{3}$	1	1	± 1.5 %	± 1.5 %	∝
RF Ambient Conditions	± 3.0 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	∝
Probe Positioner	± 0.4 %	R	$\sqrt{3}$	1	1	± 0.2 %	± 0.2 %	∝
Probe Positioning	± 2.9 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	∝
Max. SAR Eval.	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	∝
Test Sample Related								
Device Positioning	± 2.9 %	N	1	1	1	± 2.9 %	± 2.9 %	∝
Device Holder	± 3.6 %	N	1	1	1	± 3.6 %	± 2.6 %	∝
Power Drift	± 5.0 %	R		1	1	± 2.9 %	± 2.9 %	∝
Phantom and Setup								
Phantom Uncertainty	± 4.0 %	R	$\sqrt{3}$	1	1	± 2.3 %	± 2.3 %	∝
Liquid Conductivity (Target)	± 5.0 %	R	$\sqrt{3}$	0.64	0.43	± 1.8 %	± 1.2 %	∝
Liquid Conductivity (meas.)	± 2.5 %	N	1	0.64	0.43	± 1.6 %	± 1.1 %	∝
Liquid Permittivity (Target)	± 5.0 %	R	$\sqrt{3}$	0.6	0.49	± 1.7 %	± 1.4 %	∝
Liquid Permittivity (Target)	± 2.5 %	N	1	0.6	0.49	± 1.5 %	± 1.0 %	∝
Combined Std. Uncertainty	-	-	-	-	-	± 10.8 %	± 10.3 %	330
Expanded STD Uncertainty	-	-	-	-	-	± 21.6 %	± 20.6 %	-

3 GHz to 6 GHz

SASY4 Uncertainty Budget
According to IEEE 1528

Error Description	Uncertainty Value	Prob. Dist.	Div.	(c i) 1g	(c i) 10g	Std. Unc. (1g)	Std. Unc. (10g)	(v i) veff
Measurement System								
Probe Calibration	± 6.55 %	N	1	1	1	± 6.55 %	± 6.55 %	∝
Axial Isotropy	± 4.7 %	R	$\sqrt{3}$	0.7	0.7	± 1.9 %	± 1.9 %	∝
Hemispherical Isotropy	± 9.6 %	R	$\sqrt{3}$	0.7	0.7	± 3.9 %	± 3.9 %	∝
Boundary Effects	± 2.0 %	R	$\sqrt{3}$	1	1	± 1.2 %	± 1.2 %	∝
Linearity	± 4.7 %	R	$\sqrt{3}$	1	1	± 2.7 %	± 2.7 %	∝
System Detection Limits	± 1.0 %	R	$\sqrt{3}$	1	1	± 0.6 %	± 0.6 %	∝
Readout Electronics	± 0.3 %	N	1	1	1	± 0.3 %	± 0.3 %	∝
Response Time	± 0.8 %	R	$\sqrt{3}$	1	1	± 0.5 %	± 0.5 %	∝
Integration Time	± 2.6 %	R	$\sqrt{3}$	1	1	± 1.5 %	± 1.5 %	∝
RF Ambient Conditions	± 3.0 %	R	$\sqrt{3}$	1	1	± 1.7 %	± 1.7 %	∝
Probe Positioner	± 0.8 %	R	$\sqrt{3}$	1	1	± 0.5 %	± 0.5 %	∝
Probe Positioning	± 9.9 %	R	$\sqrt{3}$	1	1	± 5.7 %	± 5.7 %	∝
Max. SAR Eval.	± 4.0 %	R	$\sqrt{3}$	1	1	± 2.3 %	± 2.3 %	∝
Test Sample Related								
Device Positioning	± 2.9 %	N	1	1	1	± 2.9 %	± 2.9 %	∝
Device Holder	± 3.6 %	N	1	1	1	± 3.6 %	± 2.6 %	∝
Power Drift	± 5.0 %	R		1	1	± 2.9 %	± 2.9 %	∝
Phantom and Setup								
Phantom Uncertainty	± 4.0 %	R	$\sqrt{3}$	1	1	± 2.3 %	± 2.3 %	∝
Liquid Conductivity (Target)	± 5.0 %	R	$\sqrt{3}$	0.64	0.43	± 1.8 %	± 1.2 %	∝
Liquid Conductivity (meas.)	± 2.5 %	N	1	0.64	0.43	± 1.6 %	± 1.1 %	∝
Liquid Permittivity (Target)	± 5.0 %	R	$\sqrt{3}$	0.6	0.49	± 1.7 %	± 1.4 %	∝
Liquid Permittivity (Target)	± 2.5 %	N	1	0.6	0.49	± 1.5 %	± 1.0 %	∝
Combined Std. Uncertainty	-	-	-	-	-	± 12.7 %	± 12.2 %	330
Expanded STD Uncertainty	-	-	-	-	-	± 25.4 %	± 24.4 %	-

12 Description of Test System

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG) which is the fourth generation of the system shown in the figure hereinafter:

The system is based on a high precision robot (working range greater than 0.9m), which positions the probes with a positional repeatability of better than ±0.02mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit.

The SAR measurements were conducted with the dosimetric probe ET3DV6 SN: 1604 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure with accuracy of better than ±10%. The spherical isotropy was evaluated with the procedure and found to be better than ±0.25dB.

The phantom used was the Generic Twin Phantom”. The ear was simulated as a spacer of 4 mm thickness between the earpiece of the phone and the tissue simulating liquid. The Tissue simulation liquid used for each test is in according with the FCC OET65 supplement C as listed below.

Ingredients (% by weight)	Frequency (MHz)									
	450		835		915		1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0
Triton x-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78

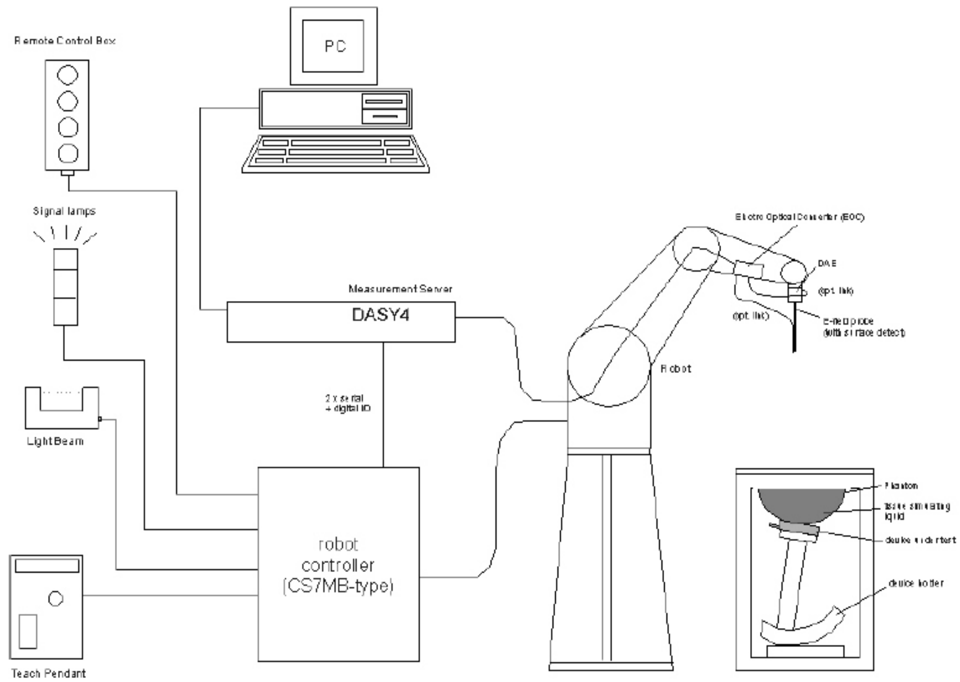
12.1 IEEE SCC-34/SC-2 P1528 Recommended Tissue Dielectric Parameters

Frequency (MHz)	Head Tissue		Body Tissue	
	εr	Ơ (S/m)	εr	Ơ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

12.2 DAY4 users Manual Recommended Tissue Dielectric Parameters

Frequency (MHz)	Head Tissue		Body Tissue	
	εr	Ơ (S/m)	εr	Ơ (S/m)
5200	36.0	4.66	49.0	5.30
5500	35.6	4.96	48.6	5.65

12.3 Measurement System Diagram



The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).

- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.

- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.

- The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.

- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.

- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.

- A computer operating Windows 2000 or Windows XP.

• DASY4 software.

• Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.

• The SAM twin phantom enabling testing left-hand and right-hand usage.

• The device holder for handheld mobile phones.

• Tissue simulating liquid mixed according to the given recipes.

• Validation dipole kits allowing system validation.

12.4 System Components

• DASY4 Measurement Server
• Data Acquisition Electronics
• Probes
• Light Beam Unit
• Medium
• SAM Twin Phantom
• Device Holder for SAM Twin Phantom
• System Validation Kits
• Robot

12.5 DASY4 Measurement Server

The DASY4 measurement server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chip disk and 64MB RAM. The necessary circuits for communication with either the DAE4 (or DAE3) electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pin out and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server.

12.6 Data Acquisition Electronics

The data acquisition electronics DAE3 consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

12.7 Probes

The DASY system can support many different probe types.

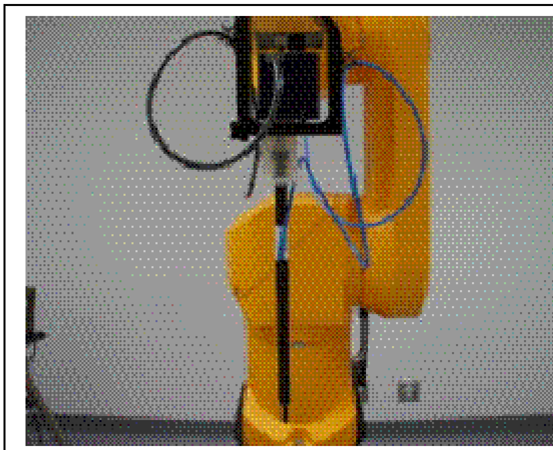
Dosimetric Probes: These probes are specially designed and calibrated for use in liquids with high permittivities. They should not be used in air, since the spherical isotropy in air is poor (±2 dB). The dosimetric probes have special calibrations in various liquids at different frequencies.

Free Space Probes: These are electric and magnetic field probes specially designed for measurements in free space. The z-sensor is aligned to the probe axis and the rotation angle of the x-sensor is specified. This allows the DASY system to automatically align the probe to the measurement grid for field component measurement. The free space probes are generally not calibrated in liquid. (The H-field probes can be used in liquids without any change of parameters.)

Temperature Probes: Small and sensitive temperature probes for general use. They use a completely different parameter set and different evaluation procedures. Temperature rise features allow direct SAR evaluations with these probes.

12.8 ET3DV6 Probe Specification

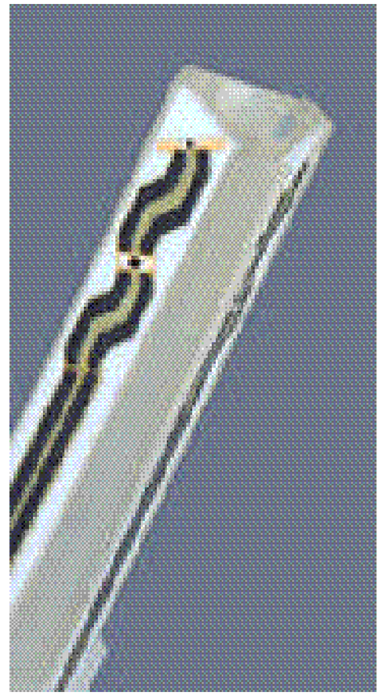
Construction Symmetrical design with triangular core
Built-in optical fiber for surface detection System
Built-in shielding against static charges
Calibration In air from 10 MHz to 2.5 GHz
In brain and muscle simulating tissue at
Frequencies of 450 MHz, 900 MHz and
1.8 GHz (accuracy ± 8%)
Frequency 10 MHz to > 6 GHz; Linearity: ± 0.2 dB
(30 MHz to 3 GHz)
Directivity ± 0.2 dB in brain tissue (rotation around
probe axis)
± 0.4 dB in brain tissue (rotation normal probe axis)
Dynamic 5 mW/g to > 100 mW/g;
Range Linearity: ± 0.2 dB
Surface ± 0.2 mm repeatability in air and clear liquids
Detection over diffuse reflecting surfaces.
Dimensions Overall length: 330 mm
Tip length: 16 mm



Photograph of the probe

Body diameter: 12 mm
Tip diameter: 6.8 mm
Distance from probe tip to dipole centers: 2.7 mm
Application General dosimetric up to 3 GHz
Compliance tests of mobile phones
Fast automatic scanning in arbitrary phantoms

The SAR measurements were conducted with the dosimetric probe ET3DV6 designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multi-fiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY3 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped when reaching the maximum.



Inside view of ET3DV6 E-field Probe

12.9 E-Field Probe Calibration Process

Each probe is calibrated according to a dosimetric assessment procedure described in [6] with accuracy better than +/- 10%. The spherical isotropy was evaluated with the procedure described in [7] and found to be better than +/-0.25dB. The sensitivity parameters (NormX, NormY, NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested.

The free space E-field from amplified probe outputs is determined in a test chamber. This is performed in a TEM cell for frequencies bellow 1 GHz, and in a waveguide above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The measured free space E-field in the medium correlates to temperature rise in dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

12.10 Data Evaluation

The DASY4 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Normi, ai0, ai1, ai2
	- Conversion factor	ConvFi
	- Diode compression point	dcpi
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

With Vi = compensated signal of channel i (i =x, y, z)
Ui = input signal of channel i (i =x, y, z)
cf = crest factor of exciting field (DASY parameter)
dcp_i = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$\text{E-fieldprobes}: \qquad E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

$$\text{H-fieldprobes}: \qquad H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1} f + a_{i2} f^2}{f}$$

With Vi = compensated signal of channel i (i =x, y, z)
$Norm_i$ = sensor sensitivity of channel i (i =x, y, z)
μV/ $(V/m)^2$ for E-field probes
ConF = sensitivity enhancement in solution
a_{ij} = sensor sensitivity factors for H-field probes
f = carrier frequency [GHz]
Ei = electric field strenggy of channel i in V/m
H_i = diode compression point (DASY parameter)

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$$

With SAR = local specific absorption rate in mW/g
E_{tot} = total field strength in V/m
σ = conductivity in [mho/meter] or [Siemens/meter]
ρ = equivalent tissue density in g/cm^3

Note that the density is normally set to 1, to account for actual brain density rather than the density of the simulation liquid.

12.11 Light Beam Unit

The light beam switch allows automatic “tooling” of the probe. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, so that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.

12.12 Medium

Parameters

The parameters of the tissue simulating liquid strongly influence the SAR in the liquid. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE 1528-2003).

Parameter measurements

Several measurement systems are available for measuring the dielectric parameters of liquids:

- The open coax test method (e.g., HP85070 dielectric probe kit) is easy to use, but has only moderate acuracy. It is calibrated with open, short, and deionized water and the calibrations a critical process.

- The transmission line method (e.g., model 1500T from DAMASKOS, INC.) measures the transmission and reflection in a liquid filled high precision line. It needs standard two port calibration and is probably more accurate than the open coax method.

- The reflection line method measures the reflection in a liquid filled shorted precision lined.The method is not suitable for these liquids because of its low sensitivity.

- The slotted line method scans the field magnitude and phase along a liquid filled line. The evaluation is straight forward and only needs a simple response calibration. The method is very accurate, but can only be used in high loss liquids and at frequencies above 100 to 200MHz. Cleaning the line can be tedious.

12.13 SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left hand
- Right hand
- Flat phantom

The phantom table comes in two sizes: A 100 x 50 x 85 cm (L x W x H) table for use with free standing robots (DASY4 professional system option) or as a second phantom and a 100 x 75 x 85 cm(L x W x H) table with reinforcements for table mounted robots (DASY4 compact system option) .
The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids) A white cover is provided to tap the phantom during o_-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

The phantom can be used with the following tissue simulating liquids:

• Water-sugar based liquids can be left permanently in the phantom. Always cover the liquid if the system is not used, otherwise the parameters will change due to water evaporation.

• Glycol based liquids should be used with care. As glycol is a softener for most plastics, the liquid should be taken out of the phantom and the phantom should be dried when the system is not used (desirable at least once a week).

• Do not use other organic solvents without previously testing the phantom's compatibility.

12.14 Device Holder for SAM Twin Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source in 5mm distance, a positioning uncertainty of ±0.5mm would produce a SAR uncertainty of ±20%. An accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions, in which the devices must be measured, are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point ERP). Thus the device needs no repositioning when changing the angles.


The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity "=3 and loss tangent _=0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

12.15 System Validation Kits

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. For that purpose a well defined SAR distribution in the flat section of the SAM twin phantom is produced.

System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder. Dipoles are available for the variety of frequencies between 300MHz and 6 GHz (dipoles for other frequencies or media and other calibration conditions are available upon request).

The dipoles are highly symmetric and matched at the center frequency for the specified liquid and distance to the flat phantom (or flat section of the SAM-twin phantom). The accurate distance between the liquid surface and the dipole center is achieved with a distance holder that snaps on the dipole.

12.16 Robot

The DASY4 system uses the high precision industrial robots RX60L, RX90 and RX90L, as well as the RX60BL and RX90BL types out of the newer series from Stäubli SA (France). The RX robot series offers many features that are important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance-free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchronous motors; no stepper motors)
- Low ELF interference (the closed metallic construction shields against motor control fields)

For the newly delivered DASY4 systems as well as for the older DASY3 systems delivered since 1999, the CS7MB robot controller version from Stäubli is used. Previously delivered systems have either a CS7 or CS7M controller; the differences to the CS7MB are mainly in the hardware, but some procedures in the robot software from Stäubli are also not completely the same. The following descriptions about robot hard- and software correspond to CS7MB controller with software version 13.1 (edit S5). The actual commands, procedures and configurations, also including details in hardware, might differ if an older robot controller is in use. In this case please also refer to the Stäubli manuals for further information.

13 Appendix B – Probe Calibration Certificates

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

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Accreditation No.: **SCS 108**

Client **BACL**

Certificate No: **ET3-1604_Aug12**

CALIBRATION CERTIFICATE

Object: ET3DV6 - SN:1604

Calibration procedure(s): QA CAL-01.v8, QA CAL-12.v7, QA CAL-23.v4, QA CAL-25.v4
Calibration procedure for dosimetric E-field probes

Calibration date: August 24, 2012

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	29-Mar-12 (No. 217-01508)	Apr-13
Power sensor E4412A	MY41498087	29-Mar-12 (No. 217-01508)	Apr-13
Reference 3 dB Attenuator	SN: S5054 (3c)	27-Mar-12 (No. 217-01531)	Apr-13
Reference 20 dB Attenuator	SN: S5086 (20b)	27-Mar-12 (No. 217-01529)	Apr-13
Reference 30 dB Attenuator	SN: S5129 (30b)	27-Mar-12 (No. 217-01532)	Apr-13
Reference Probe ES3DV2	SN: 3013	29-Dec-11 (No. ES3-3013_Dec11)	Dec-12
DAE4	SN: 660	20-Jun-12 (No. DAE4-660_Jun12)	Jun-13
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-11)	In house check: Apr-13
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-11)	In house check: Oct-12

	Name	Function	Signature
Calibrated by:	Jeton Kastrati	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: August 25, 2012

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: ET3-1604_Aug12 Page 1 of 11

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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not affect the E^2-field uncertainty inside TSL (see below *ConvF*).
- *NORM(f)x,y,z = NORMx,y,z * frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *PAR:* PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- *Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z*: *A, B, C* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *ConvF and Boundary Effect Parameters:* Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z * ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- *Spherical isotropy (3D deviation from isotropy)*: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Probe ET3DV6

SN:1604

Manufactured: July 30, 2001
Calibrated: August 24, 2012

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

ET3DV6– SN:1604 August 24, 2012

DASY/EASY - Parameters of Probe: ET3DV6 - SN:1604

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (µV/(V/m)^2)[A]	1.90	1.83	1.92	± 10.1 %
DCP (mV)[B]	96.0	94.1	96.0	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc[E] (k=2)
0	CW	0.00	X	0.00	0.00	1.00	148.8	±2.7 %
			Y	0.00	0.00	1.00	143.4	
			Z	0.00	0.00	1.00	150.1	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

[A] The uncertainties of NormX,Y,Z do not affect the E^2-field uncertainty inside TSL (see Pages 5 and 6).
[B] Numerical linearization parameter: uncertainty not required.
[E] Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

DASY/EASY - Parameters of Probe: ET3DV6 - SN:1604

Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) [C]	Relative Permittivity [F]	Conductivity (S/m) [F]	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
300	45.3	0.87	8.14	8.14	8.14	0.30	1.55	± 13.4 %
450	43.5	0.87	7.31	7.31	7.31	0.22	2.30	± 13.4 %
835	41.5	0.90	6.37	6.37	6.37	0.35	3.00	± 12.0 %
900	41.5	0.97	6.21	6.21	6.21	0.34	3.00	± 12.0 %
1810	40.0	1.40	5.22	5.22	5.22	0.75	2.08	± 12.0 %
1900	40.0	1.40	5.14	5.14	5.14	0.80	1.96	± 12.0 %
2450	39.2	1.80	4.46	4.46	4.46	0.80	1.64	± 12.0 %

[C] Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.
[F] At frequencies below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

DASY/EASY - Parameters of Probe: ET3DV6 - SN:1604

Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) [C]	Relative Permittivity [F]	Conductivity (S/m) [F]	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
300	58.2	0.92	7.67	7.67	7.67	0.28	2.35	± 13.4 %
450	56.7	0.94	7.70	7.70	7.70	0.14	2.22	± 13.4 %
835	55.2	0.97	6.28	6.28	6.28	0.44	2.37	± 12.0 %
900	55.0	1.05	6.25	6.25	6.25	0.40	2.56	± 12.0 %
1810	53.3	1.52	4.75	4.75	4.75	0.80	2.38	± 12.0 %
1900	53.3	1.52	4.60	4.60	4.60	0.80	2.35	± 12.0 %
2450	52.7	1.95	4.11	4.11	4.11	0.61	1.13	± 12.0 %

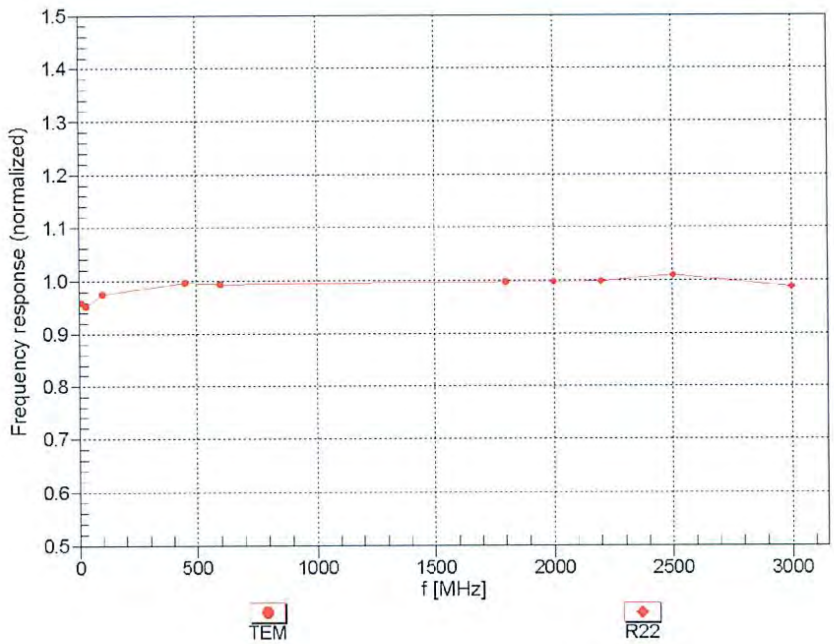
[C] Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

[F] At frequencies below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

ET3DV6– SN:1604 August 24, 2012

Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)



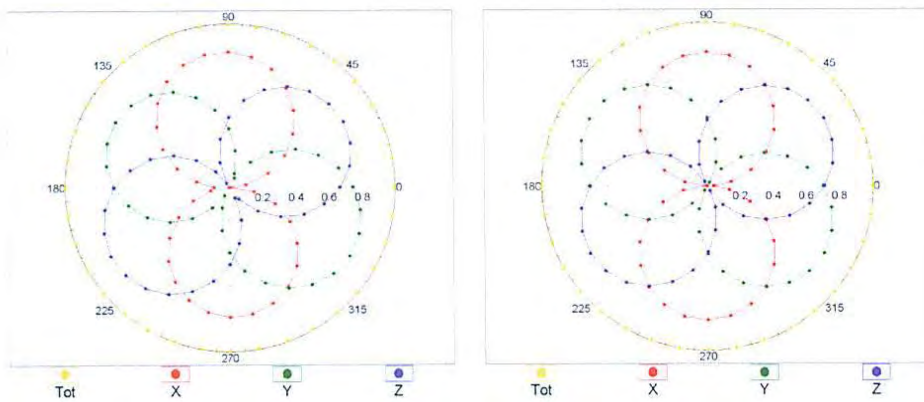
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

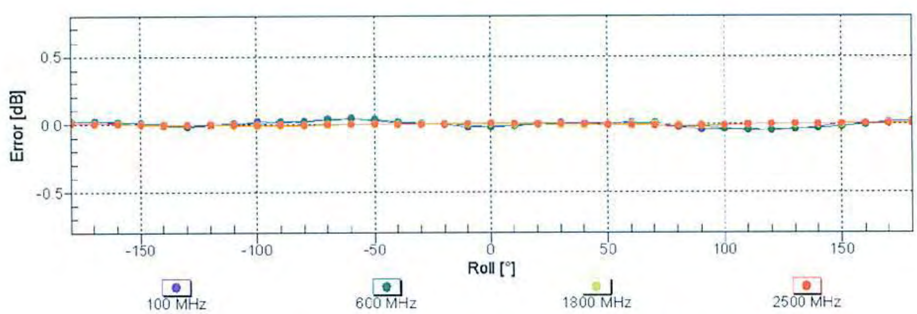
Certificate No: ET3-1604_Aug12 Page 7 of 11

ET3DV6– SN:1604 August 24, 2012

Receiving Pattern (ϕ), ϑ = 0°

f=600 MHz,TEM f=1800 MHz,R22





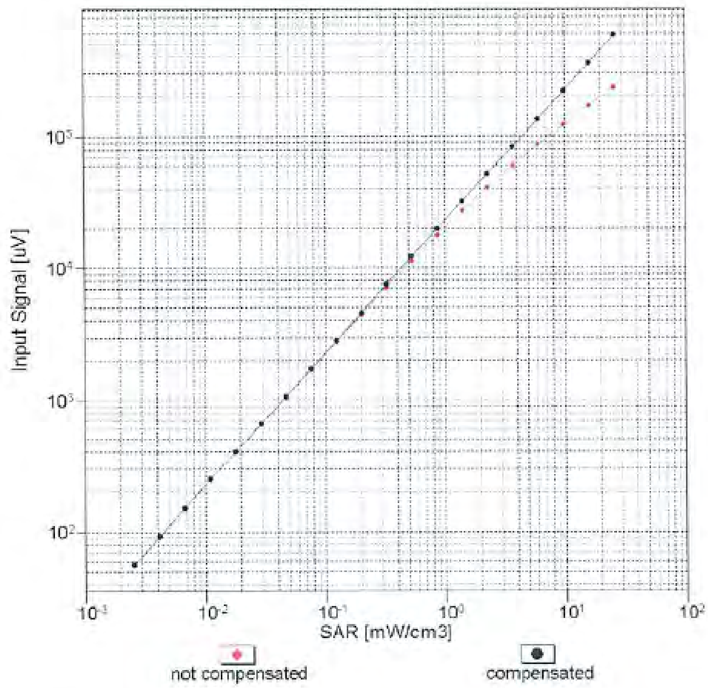
Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

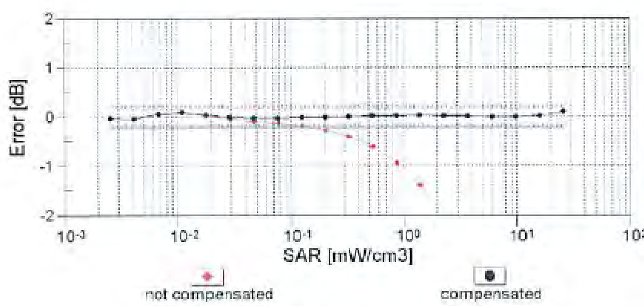
Certificate No: ET3-1604_Aug12 Page 8 of 11

ET3DV6– SN:1604 August 24, 2012

Dynamic Range f(SAR_{head})

(TEM cell , f = 900 MHz)





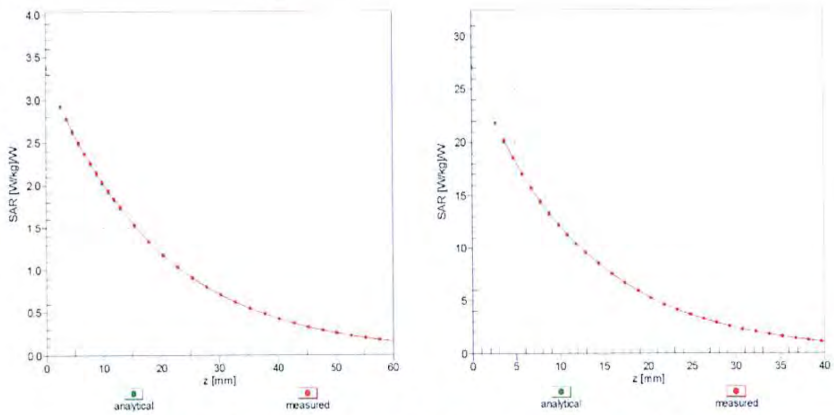
Uncertainty of Linearity Assessment: ± 0.6% (k=2)

Certificate No: ET3-1604_Aug12 Page 9 of 11

ET3DV6– SN:1604 August 24, 2012

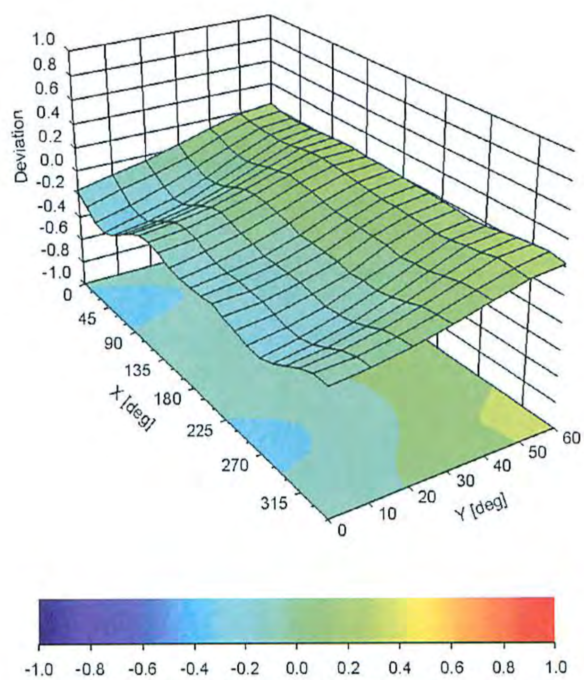
Conversion Factor Assessment

f = 835 MHz,WGLS R9 (H_convF) f = 1810 MHz,WGLS R22 (H_convF)



Deviation from Isotropy in Liquid

Error (ϕ, ϑ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Certificate No: ET3-1604_Aug12 Page 10 of 11

DASY/EASY - Parameters of Probe: ET3DV6 - SN:1604

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	60.3
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	enabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	6.8 mm
Probe Tip to Sensor X Calibration Point	2.7 mm
Probe Tip to Sensor Y Calibration Point	2.7 mm
Probe Tip to Sensor Z Calibration Point	2.7 mm
Recommended Measurement Distance from Surface	4 mm

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Accreditation No.: **SCS 108**

Client **BACL**

Certificate No: **EX3-3619_Aug12**

CALIBRATION CERTIFICATE

Object	EX3DV4 - SN:3619
Calibration procedure(s)	QA CAL-01.v8, QA CAL-14.v3, QA CAL-23.v4, QA CAL-25.v4 Calibration procedure for dosimetric E-field probes
Calibration date:	August 27, 2012

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	29-Mar-12 (No. 217-01508)	Apr-13
Power sensor E4412A	MY41498087	29-Mar-12 (No. 217-01508)	Apr-13
Reference 3 dB Attenuator	SN: S5054 (3c)	27-Mar-12 (No. 217-01531)	Apr-13
Reference 20 dB Attenuator	SN: S5086 (20b)	27-Mar-12 (No. 217-01529)	Apr-13
Reference 30 dB Attenuator	SN: S5129 (30b)	27-Mar-12 (No. 217-01532)	Apr-13
Reference Probe ES3DV2	SN: 3013	29-Dec-11 (No. ES3-3013_Dec11)	Dec-12
DAE4	SN: 660	20-Jun-12 (No. DAE4-660_Jun12)	Jun-13
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-11)	In house check: Apr-13
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-11)	In house check: Oct-12

	Name	Function	Signature
Calibrated by:	Jeton Kastrati	Laboratory Technicien	
Approved by:	Katja Pokovic	Technical Manager	

Issued: August 27, 2012

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: EX3-3619_Aug12 Page 1 of 11

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not affect the E^2-field uncertainty inside TSL (see below *ConvF*).
- *NORM(f)x,y,z = NORMx,y,z * frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *PAR:* PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- *Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z*: *A, B, C* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *ConvF and Boundary Effect Parameters:* Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z * ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- *Spherical isotropy (3D deviation from isotropy)*: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

Probe EX3DV4

SN:3619

Manufactured: July 3, 2007
Calibrated: August 27, 2012

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3619

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (µV/(V/m)^2)[A]	0.43	0.38	0.41	± 10.1 %
DCP (mV)[B]	94.8	102.0	94.5	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc[E] (k=2)
0	CW	0.00	X	0.00	0.00	1.00	151.8	±3.0 %
			Y	0.00	0.00	1.00	173.5	
			Z	0.00	0.00	1.00	146.6	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

[A] The uncertainties of NormX,Y,Z do not affect the E^2-field uncertainty inside TSL (see Pages 5 and 6).
[B] Numerical linearization parameter: uncertainty not required.
[E] Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3619

Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) [C]	Relative Permittivity [F]	Conductivity (S/m) [F]	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
5200	36.0	4.66	4.70	4.70	4.70	0.25	1.80	± 13.1 %
5600	35.5	5.07	4.31	4.31	4.31	030	1.80	± 13.1 %
5800	35.3	5.27	4.14	4.14	4.14	0.35	1.80	± 13.1 %

[C] Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.
[F] At frequencies below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3619

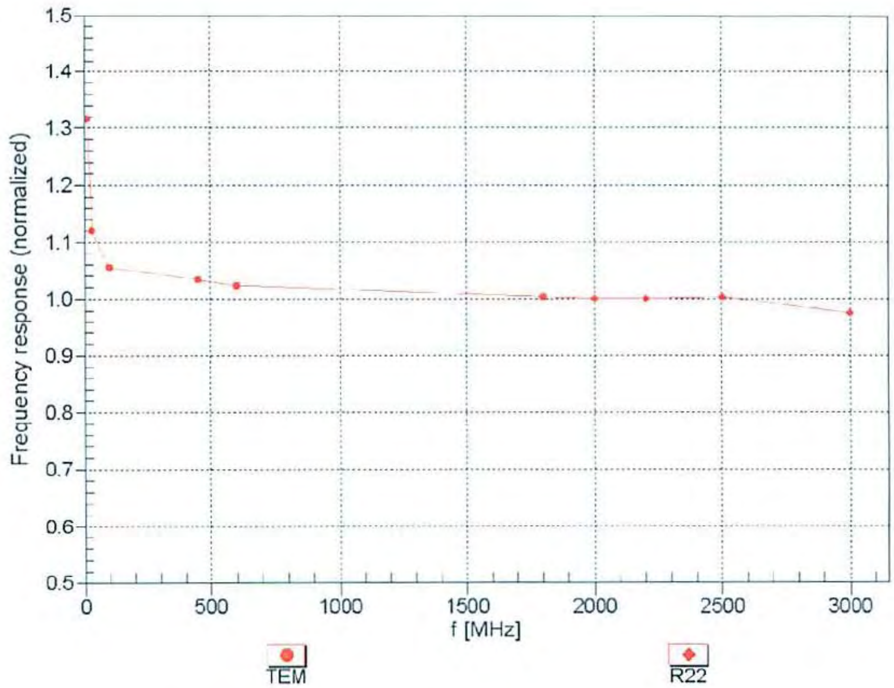
Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) [C]	Relative Permittivity [F]	Conductivity (S/m) [F]	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
5200	49.0	5.30	4.17	4.17	4.17	0.35	1.90	± 13.1 %
5600	48.5	5.77	3.72	3.72	3.72	0.30	1.90	± 13.1 %
5800	48.2	6.00	4.14	4.14	4.14	0.35	1.90	± 13.1 %

[C] Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.
[F] At frequencies below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

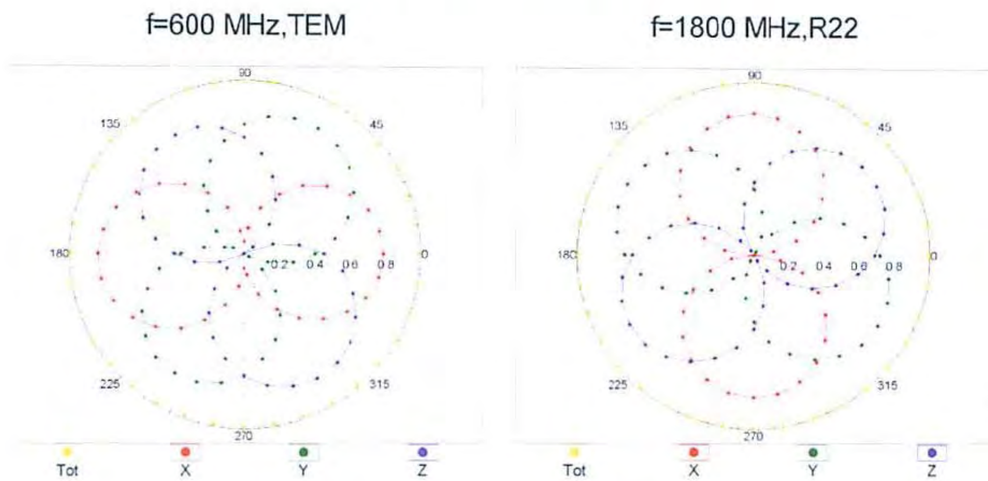
Frequency Response of E-Field

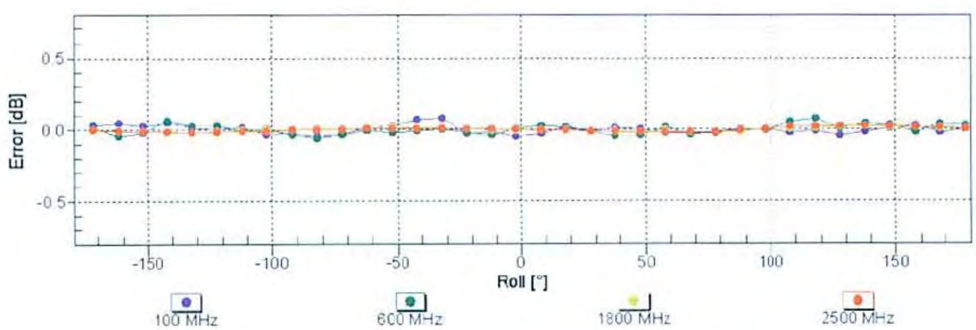
(TEM-Cell:ifi110 EXX, Waveguide: R22)



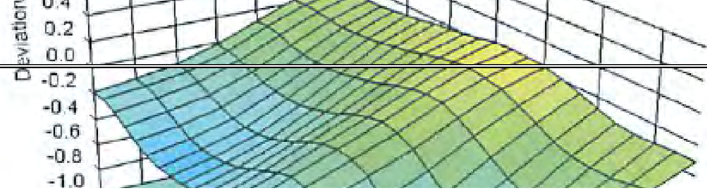
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

Receiving Pattern (ϕ), $\vartheta = 0°$

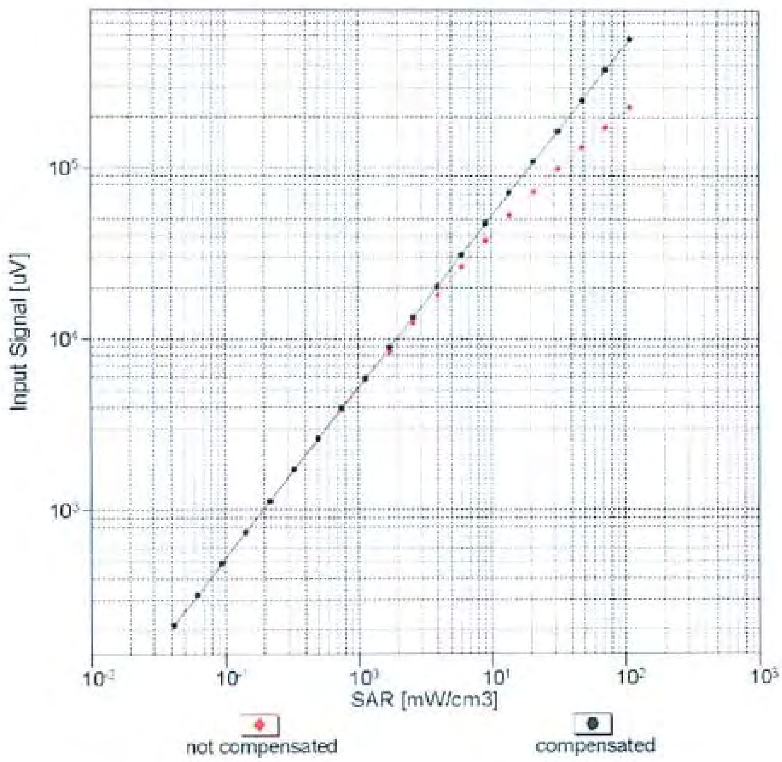


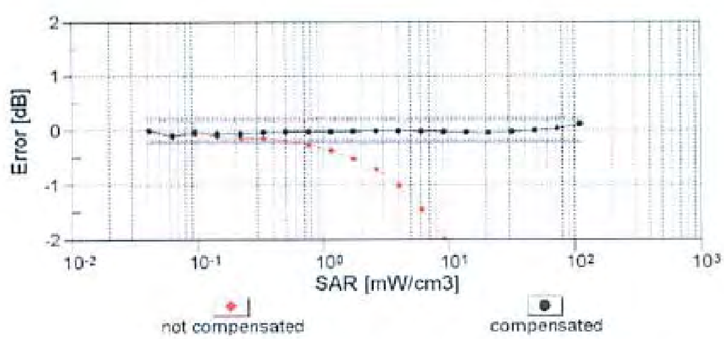


Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)



Dynamic Range f(SAR$_{head}$)
(TEM cell , f = 900 MHz)



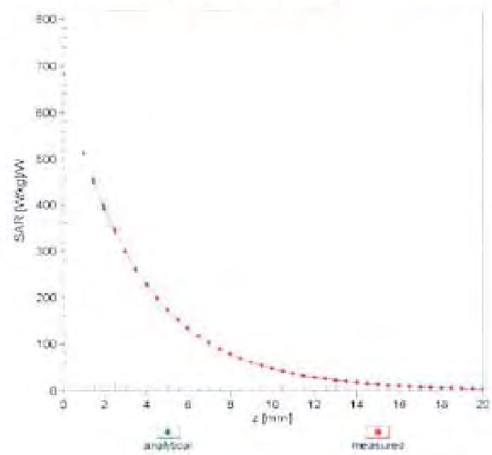


Uncertainty of Linearity Assessment: ± 0.6% (k=2)

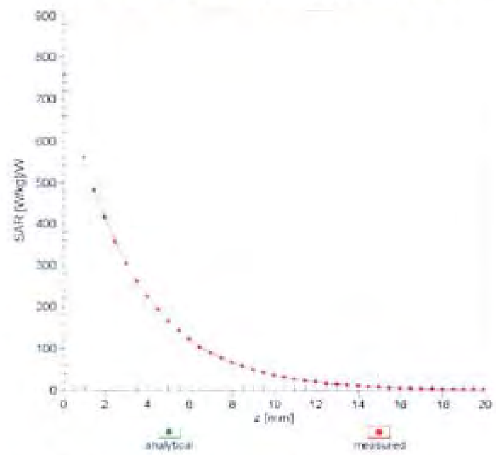
EX3DV4– SN:3619 August 27, 2012

Conversion Factor Assessment

f = 5200 MHz,WGLS R58 (H_convF)-SCS

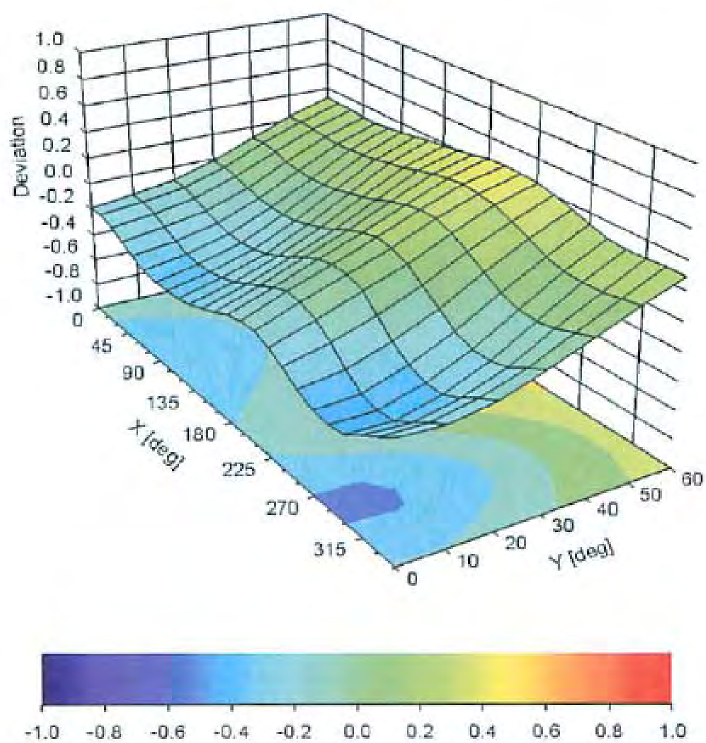


f = 5800 MHz,WGLS R58 (H_convF)-SCS



Deviation from Isotropy in Liquid

Error (ϕ, ϑ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Certificate No: EX3-3619_Aug12 Page 10 of 11

DASY/EASY - Parameters of Probe: EX3DV4 - SN:3619

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	28
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	2 mm

14 Appendix C – Dipole Calibration Certificates

NCL CALIBRATION LABORATORIES

Calibration File No: DC-1285
Project Number: BACL-dipole-cal-5612

CERTIFICATE OF CALIBRATION

It is certified that the equipment identified below has been calibrated in the **NCL CALIBRATION LABORATORIES** by qualified personnel following recognized procedures and using transfer standards traceable to NRC/NIST.

BACL Validation Dipole (Head & Body)

Manufacturer: APREL Laboratories
Part number: D-2450-S-1
Frequency: 2450 MHz
Serial No: BCL-141

Customer: Bay Area Compliance Laboratory

Calibrated: 25th July 2011
Released on: 27th July 2011

This Calibration Certificate is Incomplete Unless Accompanied with the Calibration Results Summary

Released By: ______________________

NCL CALIBRATION LABORATORIES

Suite 102, 303 Terry Fox Dr.
Kanata, ONTARIO
CANADA K2K 3J1

Division of APREL Lab.
TEL: (613) 435-8300
FAX: (613) 432-8306

8.19.2011

NCL Calibration Laboratories
Division of APREL Laboratories.

Conditions

Dipole BCL-141 was received from customer in good condition for re-calibration, SMA connector required cleaning prior to calibration.

Ambient Temperature of the Laboratory: 22 °C +/- 0.5°C
Temperature of the Tissue: 21 °C +/- 0.5°C

We the undersigned attest that to the best of our knowledge the calibration of this device has been accurately conducted and that all information contained within this report has been reviewed for accuracy.

Stuart Nicol

C. Teodorian

Primary Measurement Standards		
Instrument	**Serial Number**	**Cal due date**
Power meter Anritsu MA2408A	245025437	Nov.4, 2011
Power Sensor Anritsu MA2481D	103555	Nov 4, 2011
Attenuator HP 8495A (70dB) 1	944A10711	Sept. 14, 2011
Network Analyzer Anritsu MT8801C	MB11855	Feb. 8, 2012
Secondary Measurement Standards		
Signal Generator Agilent E4438C	-506 MY55182336	June 7, 2012

This page has been reviewed for content and attested to by signature within this document.

NCL Calibration Laboratories
Division of APREL Laboratories.

Calibration Results Summary

The following results relate the Calibrated Dipole and should be used as a quick reference for the user.

Mechanical Dimensions

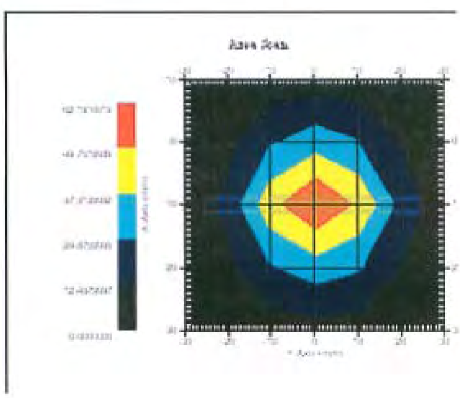
Length: 51.5 mm
Height: 30.4 mm

Electrical Specification 2450MHz

Tissue Type	Return Loss:	SWR:	Impedance:
Head	-29.565	1.076u	52.887
Body	-25.834	1.111u	55.110

System Validation Results

Tissue	Frequency	1 Gram	10 Gram	Peak
Head	2450MHz	54.075	24.19	113.98
Body	2450MHz	53.115	24.011	109.960



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NCL Calibration Laboratories

Division of APREL Laboratories.

Introduction

This Calibration Report has been produced in line with the SSI Dipole Calibration Procedure SSI-TP-018-ALSAS. The results contained within this report are for Validation Dipole BCL-141. The calibration routine consisted of a three-step process. Step 1 was a mechanical verification of the dipole to ensure that it meets the mechanical specifications. Step 2 was an Electrical Calibration for the Validation Dipole, where the SWR, Impedance, and the Return loss were assessed. Step 3 involved a System Validation using the ALSAS-10U, along with APREL E-020 130 MHz to 26 GHz E-Field Probe Serial Number 212.

References

SSI-TP-018-ALSAS Dipole Calibration Procedure
SSI-TP-016 Tissue Calibration Procedure
IEEE 1528 "Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques"

Conditions

Dipole BCL-141 was received from customer in good condition for re-calibration, SMA connector required cleaning prior to calibration.

Ambient Temperature of the Laboratory:	22 °C +/- 0.5°C
Temperature of the Tissue:	20 °C +/- 0.5°C

Dipole Calibration uncertainty

The calibration uncertainty for the dipole is made up of various parameters presented below.

Mechanical	1%
Positioning Error	1.22%
Electrical	1.7%
Tissue	2.2%
Dipole Validation	2.2%
TOTAL	**8.32% (16.64% K=2)**

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NCL Calibration Laboratories

Division of APREL Laboratories.

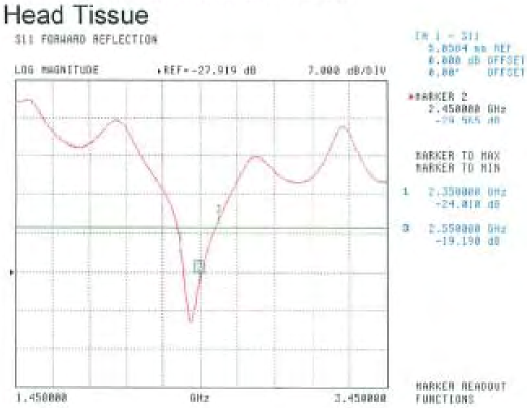
Tissue Type	Measured Epsilon	Measured Sigma
Head	38.06	1.86
Body	50.22	2.03

Electrical Calibration

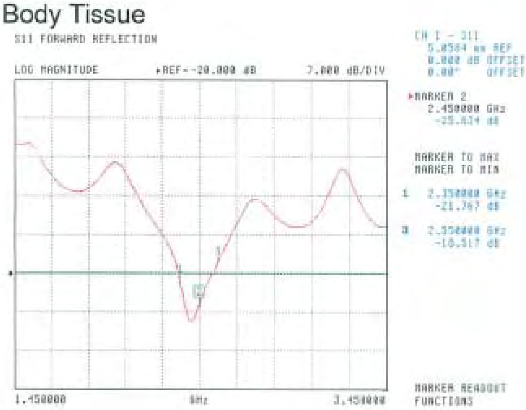
The Following Graphs are the results as displayed on the Vector Network Analyzer.

S11 Parameter Return Loss

Head Tissue



Body Tissue



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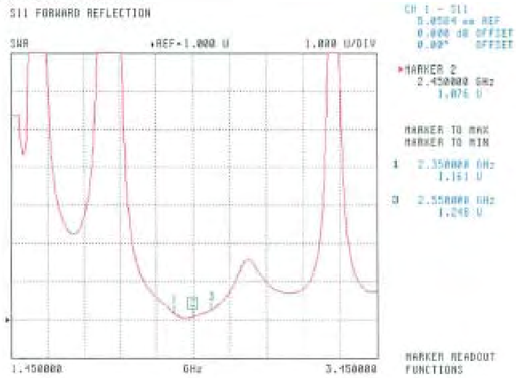
NCL Calibration Laboratories

Division of APREL Laboratories.

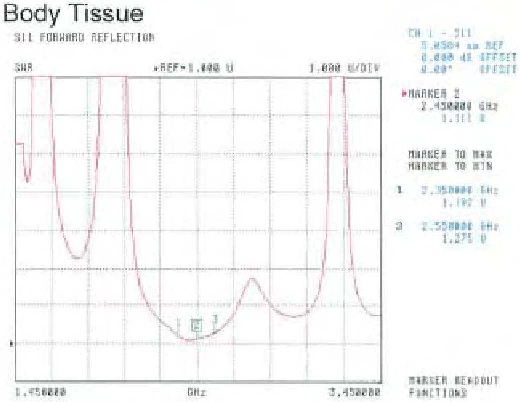
Tissue Type	Measured Epsilon	Measured Sigma
Head	38.06	1.86
Body	50.22	2.03

SWR

Head Tissue



Body Tissue



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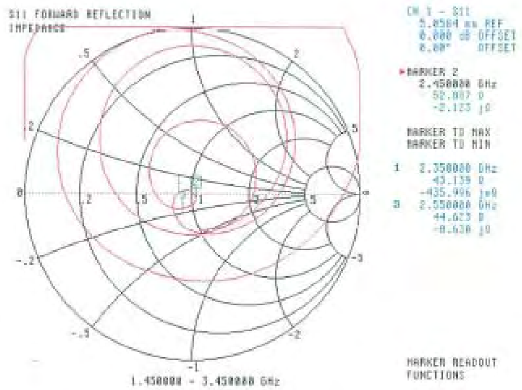
NCL Calibration Laboratories
Division of APREL Laboratories.

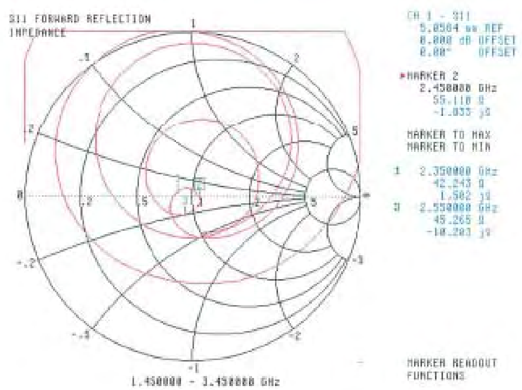
Tissue Type	Measured Epsilon	Measured Sigma
Head	38.06	1.86
Body	50.22	2.03

Smith Chart Dipole Impedance

Head Tissue



Body Tissue



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NCL Calibration Laboratories
Division of APREL Laboratories.

Test Equipment

The test equipment used during Probe Calibration, manufacturer, model number and, current calibration status are listed and located on the main APREL server R:\NCL\Calibration Equipment\Instrument List

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **BACL**

Certificate No: **D5GHz-1001_Aug11**

CALIBRATION CERTIFICATE

Object	D5GHzV2 - SN: 1001
Calibration procedure(s)	QA CAL-22.v1 Calibration procedure for dipole validation kits between 3-6 GHz
Calibration date:	August 23, 2011

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	06-Oct-10 (No. 217-01266)	Oct-11
Power sensor HP 8481A	US37292783	06-Oct-10 (No. 217-01266)	Oct-11
Reference 20 dB Attenuator	SN: 5086 (20g)	29-Mar-11 (No. 217-01368)	Apr-12
Type-N mismatch combination	SN: 5047.2 / 06327	29-Mar-11 (No. 217-01371)	Apr-12
Reference Probe EX3DV4	SN: 3503	04-Mar-11 (No. EX3-3503_Mar11)	Mar-12
DAE4	SN: 601	04-Jul-11 (No. DAE4-601_Jul11)	Jul-12

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (in house check Oct-09)	In house check: Oct-11
RF generator R&S SMT-06	100005	04-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (in house check Oct-10)	In house check: Oct-11

	Name	Function	Signature
Calibrated by:	Claudio Leubler	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: August 23, 2011

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

Additional Documentation:

d) DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- *Measurement Conditions:* Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- *Antenna Parameters with TSL:* The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- *Feed Point Impedance and Return Loss:* These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- *SAR measured:* SAR measured at the stated antenna input power.
- *SAR normalized:* SAR as measured, normalized to an input power of 1 W at the antenna connector.
- *SAR for nominal TSL parameters:* The measured TSL parameters are used to calculate the nominal SAR result.

Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.6.2
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V5.0	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy = 4.0 mm, dz = 1.4 mm	Graded Ratio = 1.4 (Z direction)
Frequency	5200 MHz ± 1 MHz 5500 MHz ± 1 MHz 5800 MHz ± 1 MHz	

Head TSL parameters at 5200 MHz

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	36.0	4.66 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	35.7 ± 6 %	4.49 mho/m ± 6 %
Head TSL temperature change during test	< 0.5 °C	----	----

SAR result with Head TSL at 5200 MHz

SAR averaged over 1 cm^3 (1 g) of Head TSL	Condition	
SAR measured	100 mW input power	7.70 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	**76.8 mW /g ± 17.0 % (k=2)**

SAR averaged over 10 cm^3 (10 g) of Head TSL	condition	
SAR measured	100 mW input power	2.21 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	**22.0 mW /g ± 16.5 % (k=2)**

Head TSL parameters at 5500 MHz

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	35.6	4.96 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	35.3 ± 6 %	4.79 mho/m ± 6 %
Head TSL temperature change during test	< 0.5 °C	----	----

SAR result with Head TSL at 5500 MHz

SAR averaged over 1 cm^3 (1 g) of Head TSL	Condition	
SAR measured	100 mW input power	7.96 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	**79.4 mW / g ± 17.0 % (k=2)**

SAR averaged over 10 cm^3 (10 g) of Head TSL	condition	
SAR measured	100 mW input power	2.27 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	**22.6 mW / g ± 16.5 % (k=2)**

Head TSL parameters at 5800 MHz

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	35.3	5.27 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	34.8 ± 6 %	5.09 mho/m ± 6 %
Head TSL temperature change during test	< 0.5 °C	----	----

SAR result with Head TSL at 5800 MHz

SAR averaged over 1 cm^3 (1 g) of Head TSL	Condition	
SAR measured	100 mW input power	7.23 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	**72.0 mW / g ± 17.0 % (k=2)**

SAR averaged over 10 cm^3 (10 g) of Head TSL	condition	
SAR measured	100 mW input power	2.05 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	**20.4 mW / g ± 16.5 % (k=2)**

Body TSL parameters at 5200 MHz

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	49.0	5.30 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	48.8 ± 6 %	5.45 mho/m ± 6 %
Body TSL temperature change during test	< 0.5 °C	----	----

SAR result with Body TSL at 5200 MHz

SAR averaged over 1 cm^3 (1 g) of Body TSL	Condition	
SAR measured	100 mW input power	7.50 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	**74.9 mW / g ± 18.1 % (k=2)**

SAR averaged over 10 cm^3 (10 g) of Body TSL	condition	
SAR measured	100 mW input power	2.10 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	**21.0 mW / g ± 17.6 % (k=2)**

Body TSL parameters at 5500 MHz

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	48.6	5.65 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	48.3 ± 6 %	5.86 mho/m ± 6 %
Body TSL temperature change during test	< 0.5 °C	----	----

SAR result with Body TSL at 5500 MHz

SAR averaged over 1 cm^3 (1 g) of Body TSL	Condition	
SAR measured	100 mW input power	7.94 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	**79.3 mW / g ± 18.1 % (k=2)**

SAR averaged over 10 cm^3 (10 g) of Body TSL	condition	
SAR measured	100 mW input power	2.21 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	**22.1 mW / g ± 17.6 % (k=2)**

Body TSL parameters at 5800 MHz

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	48.2	6.00 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	47.7 ± 6 %	6.27 mho/m ± 6 %
Body TSL temperature change during test	< 0.5 °C	----	----

SAR result with Body TSL at 5800 MHz

SAR averaged over 1 cm^3 (1 g) of Body TSL	Condition	
SAR measured	100 mW input power	7.43 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	**74.2 mW / g ± 18.1 % (k=2)**

SAR averaged over 10 cm^3 (10 g) of Body TSL	condition	
SAR measured	100 mW input power	2.06 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	**20.6 mW / g ± 17.6 % (k=2)**

Appendix

Antenna Parameters with Head TSL at 5200 MHz

Impedance, transformed to feed point	51.4 Ω - 10.1 jΩ
Return Loss	- 20.0 dB

Antenna Parameters with Head TSL at 5500 MHz

Impedance, transformed to feed point	51.3 Ω - 2.1 jΩ
Return Loss	- 32.3 dB

Antenna Parameters with Head TSL at 5800 MHz

Impedance, transformed to feed point	56.7 Ω - 0.3 jΩ
Return Loss	- 24.1 dB

Antenna Parameters with Body TSL at 5200 MHz

Impedance, transformed to feed point	49.5 Ω - 9.6 jΩ
Return Loss	- 20.4 dB

Antenna Parameters with Body TSL at 5500 MHz

Impedance, transformed to feed point	49.3 Ω - 1.6 jΩ
Return Loss	- 35.2 dB

Antenna Parameters with Body TSL at 5800 MHz

Impedance, transformed to feed point	54.8 Ω + 1.8 jΩ
Return Loss	- 26.2 dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.202 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.
No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
Manufactured on	April 02, 2003

DASY5 Validation Report for Head TSL

Date: 22.08.2011

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 5GHz; Type: D5GHz; Serial: D5GHzV2 - SN: 1001

Communication System: CW; Frequency: 5200 MHz, Frequency: 5500 MHz, Frequency: 5800 MHz
Medium parameters used: f = 5200 MHz; σ = 4.49 mho/m; ε_r = 35.7; ρ = 1000 kg/m^3 ,
Medium parameters used: f = 5500 MHz; σ = 4.79 mho/m; ε_r = 35.3; ρ = 1000 kg/m^3 ,
Medium parameters used: f = 5800 MHz; σ = 5.09 mho/m; ε_r = 34.8; ρ = 1000 kg/m^3
Phantom section: Flat Section
Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

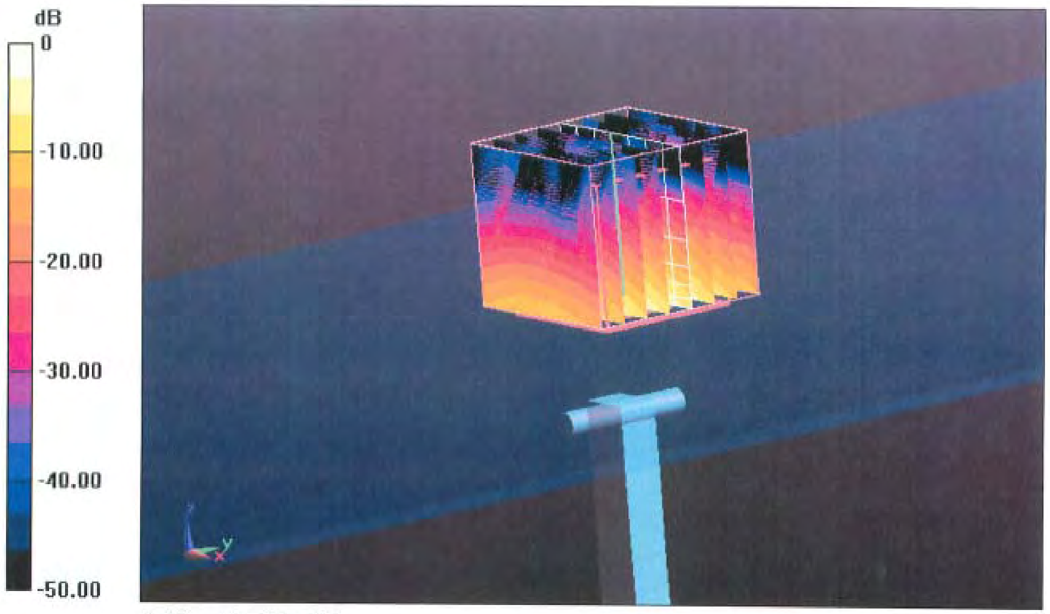
DASY52 Configuration:

- Probe: EX3DV4 - SN3503; ConvF(5.41, 5.41, 5.41), ConvF(4.91, 4.91, 4.91), ConvF(4.81, 4.81, 4.81); Calibrated: 04.03.2011
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 04.07.2011
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001
- DASY52 52.6.2(482); SEMCAD X 14.4.5(3634)

Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, f=5200 MHz/Zoom Scan, dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm
Reference Value = 64.587 V/m; Power Drift = -0.0082 dB
Peak SAR (extrapolated) = 28.409 W/kg
SAR(1 g) = 7.7 mW/g; SAR(10 g) = 2.21 mW/g
Maximum value of SAR (measured) = 17.676 mW/g

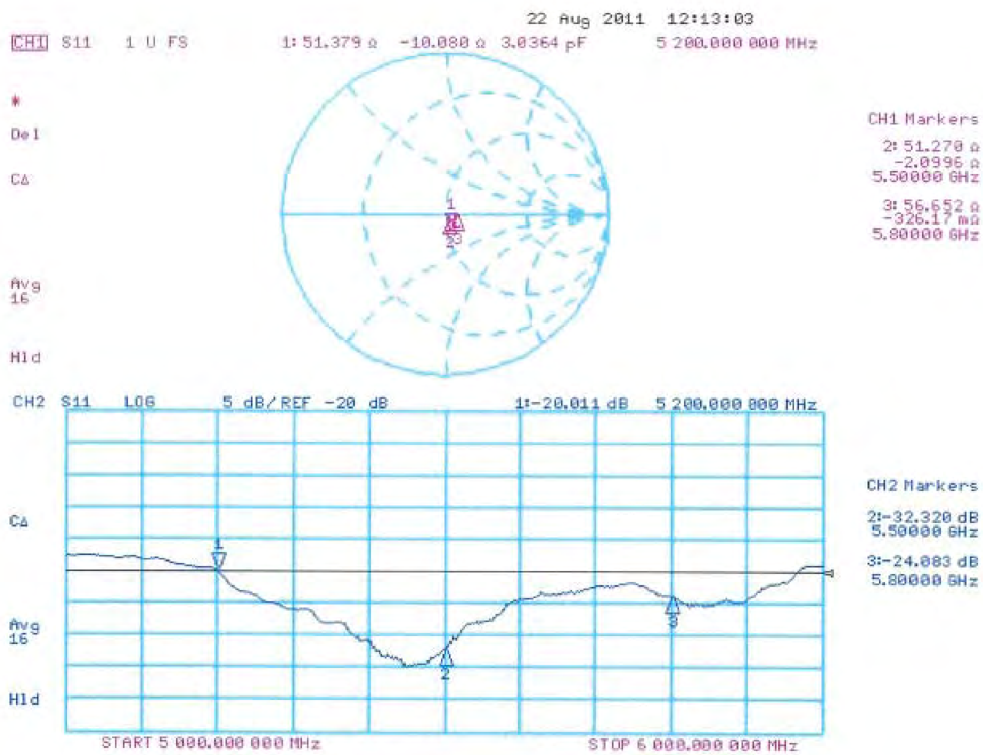
Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, f=5500 MHz/Zoom Scan, dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm
Reference Value = 60.924 V/m; Power Drift = 0.06 dB
Peak SAR (extrapolated) = 31.429 W/kg
SAR(1 g) = 7.96 mW/g; SAR(10 g) = 2.27 mW/g
Maximum value of SAR (measured) = 19.046 mW/g

Dipole Calibration for Head Tissue/Pin=100mW, dist=10mm, f=5800 MHz/Zoom Scan, dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm
Reference Value = 57.308 V/m; Power Drift = 0.08 dB
Peak SAR (extrapolated) = 30.086 W/kg
SAR(1 g) = 7.23 mW/g; SAR(10 g) = 2.05 mW/g
Maximum value of SAR (measured) = 17.772 mW/g



0 dB = 17.770mW/g

Impedance Measurement Plot for Head TSL



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DASY5 Validation Report for Body TSL

Date: 23.08.2011

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 5GHz; Type: D5GHz; Serial: D5GHzV2 - SN: 1001

Communication System: CW; Frequency: 5200 MHz, Frequency: 5500 MHz, Frequency: 5800 MHz
Medium parameters used: f = 5200 MHz; σ = 5.45 mho/m; ε_r = 48.8; ρ = 1000 kg/m^3 ,
Medium parameters used: f = 5500 MHz; σ = 5.86 mho/m; ε_r = 48.3; ρ = 1000 kg/m^3 ,
Medium parameters used: f = 5800 MHz; σ = 6.27 mho/m; ε_r = 47.7; ρ = 1000 kg/m^3
Phantom section: Flat Section
Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

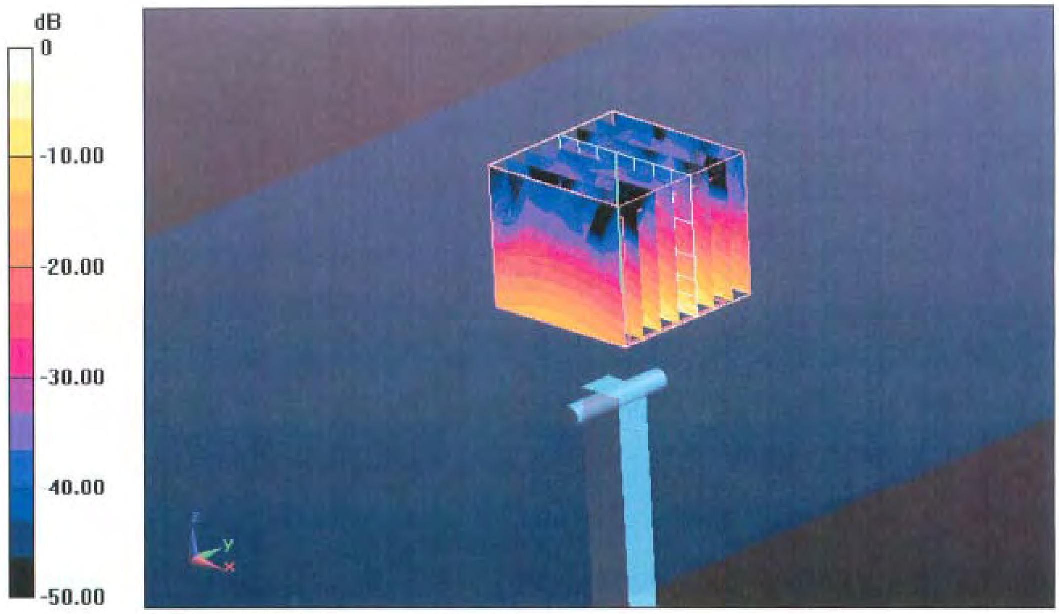
DASY52 Configuration:

- Probe: EX3DV4 - SN3503; ConvF(4.91, 4.91, 4.91), ConvF(4.43, 4.43, 4.43), ConvF(4.38, 4.38, 4.38); Calibrated: 04.03.2011
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 04.07.2011
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1002
- DASY52 52.6.2(482); SEMCAD X 14.4.5(3634)

Dipole Calibration for Body Tissue/Pin=100mW, dist=10mm, f=5200 MHz/Zoom Scan, dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm
Reference Value = 58.015 V/m; Power Drift = -0.02 dB
Peak SAR (extrapolated) = 29.052 W/kg
SAR(1 g) = 7.5 mW/g; SAR(10 g) = 2.1 mW/g
Maximum value of SAR (measured) = 17.252 mW/g

Dipole Calibration for Body Tissue/Pin=100mW, dist=10mm, f=5500 MHz/Zoom Scan, dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm
Reference Value = 57.704 V/m; Power Drift = -0.04 dB
Peak SAR (extrapolated) = 33.735 W/kg
SAR(1 g) = 7.94 mW/g; SAR(10 g) = 2.21 mW/g
Maximum value of SAR (measured) = 19.001 mW/g

Dipole Calibration for Body Tissue/Pin=100mW, dist=10mm, f=5800 MHz/Zoom Scan, dist=1.4mm (8x8x7)/Cube 0: Measurement grid: dx=4mm, dy=4mm, dz=1.4mm
Reference Value = 54.075 V/m; Power Drift = -0.03 dB
Peak SAR (extrapolated) = 34.299 W/kg
SAR(1 g) = 7.43 mW/g; SAR(10 g) = 2.06 mW/g
Maximum value of SAR (measured) = 18.305 mW/g



0 dB = 18.300mW/g

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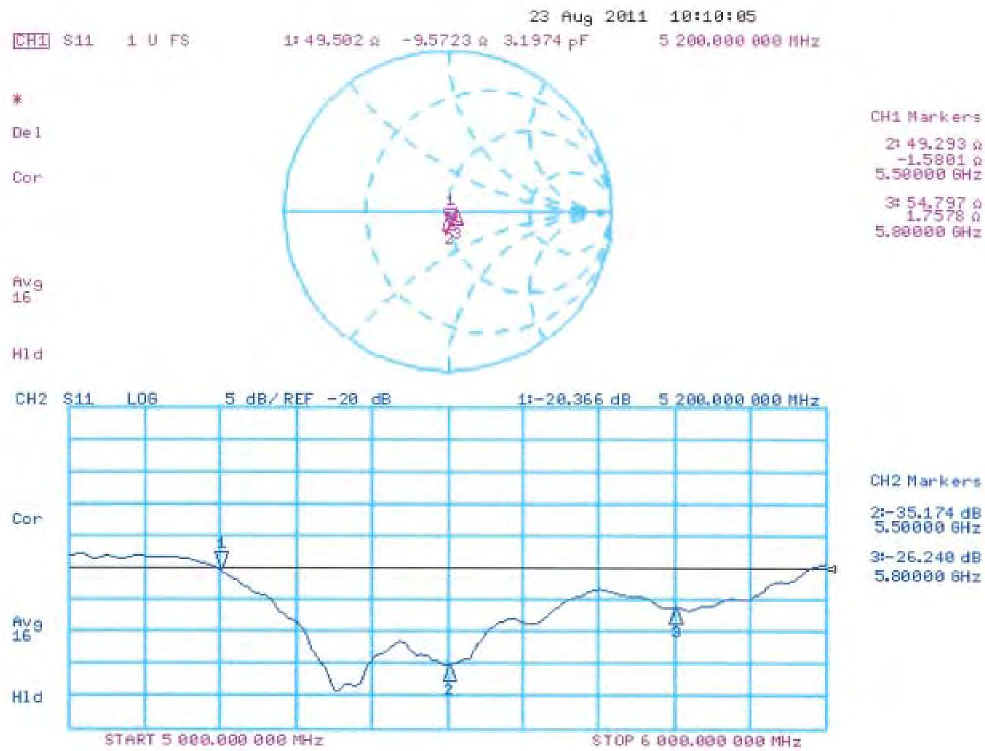
Impedance Measurement Plot for Body TSL



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15 Appendix D - Test System Verifications Scans

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

System Performance Test (2450 MHz Body)

DUT: Dipole 2450 MHz; Type: D-2450-S-1; Serial: SN: BCL-141

Communication System: CW; Frequency: 2450 MHz;Duty Cycle: 1:1
Medium parameters used: f = 2450 MHz; σ = 2.02 mho/m; ε_r = 50.7; ρ = 1000 kg/m^3
Phantom section: Flat Section

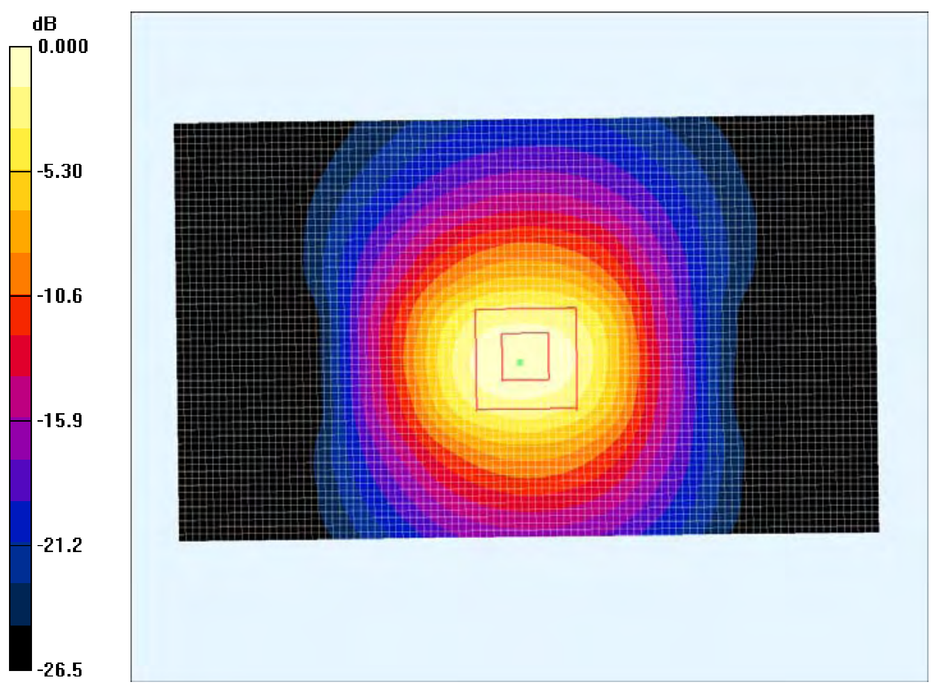
DASY4 Configuration:

- Probe: ET3DV6 - SN1604; ConvF(4.11, 4.11, 4.11); Calibrated: 8/24/2012
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: Flat Phantom 4.4; Type: Flat Phantom 4.4; Serial:
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

d =10 mm, Pin = 0.5W /Area Scan (61x101x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 27.7 mW/g

d =10 mm, Pin = 0.5W /Zoom Scan (8x8x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 116.9 V/m; Power Drift = 0.141 dB
Peak SAR (extrapolated) = 73.7 W/kg

SAR (1 g) = 26.3 mW/g; SAR (10 g) = 11.7 mW/g
Maximum value of SAR (measured) = 27.9 mW/g



0 dB = 27.9mW/g

2450 MHz System Validation with Body Tissue

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

System Performance Test (5200 MHz Body)

DUT: D5100V2; Type: D5100; Serial: SN: 1001

Communication System: CW; Frequency: 5200 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5200 MHz; σ = 5.3 mho/m; ε_r = 47.9; ρ = 1000 kg/m^3
Phantom section: Flat Section

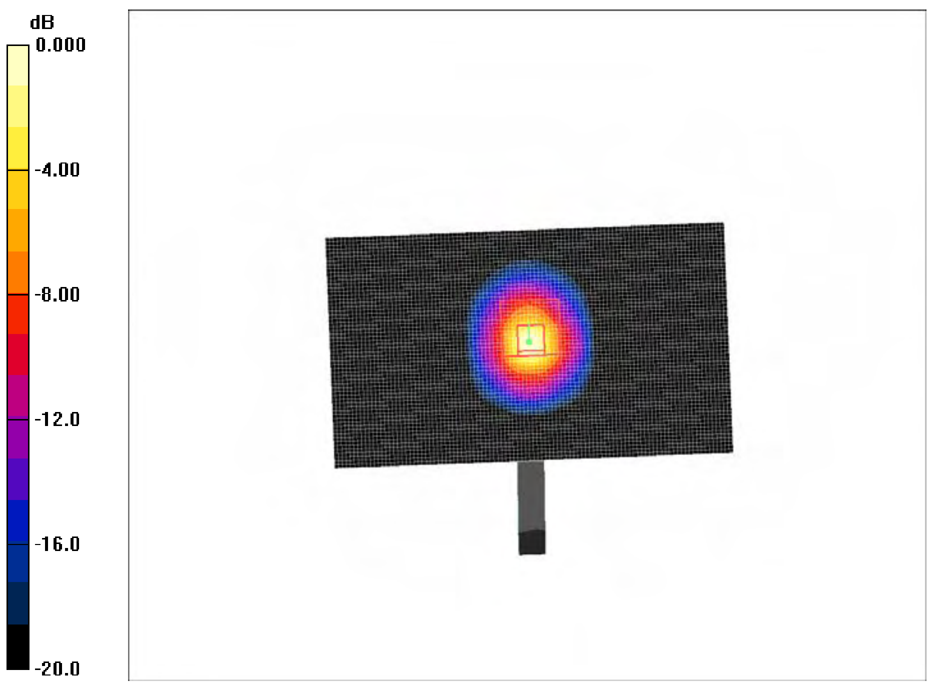
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

d =10 mm, Pin = 0.5W 2/Area Scan (81x131x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 92.2 mW/g

d =10 mm, Pin = 0.5W 2/Zoom Scan (11x11x8)/Cube 0: Measurement grid: dx=3mm, dy=3mm, dz=3mm
Reference Value = 86.3 V/m; Power Drift = 0.211 dB
Peak SAR (extrapolated) = 201.5 W/kg

SAR (1 g) = 38.8 mW/g; SAR (10 g) = 10.3 mW/g
Maximum value of SAR (measured) = 75.3 mW/g



0 dB = 75.3mW/g

5200 MHz System Validation with Body Tissue

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

System Performance Test (5500 MHz Body)

DUT: D5GHzV2; Type: 5GHz; Serial: SN: 1001

Communication System: CW; Frequency: 5500 MHz; Duty Cycle: 1:1
Medium parameters used: f = 5500 MHz; σ = 5.7 mho/m; ε_r = 47.0; ρ = 1000 kg/m^3
Phantom section: Flat Section

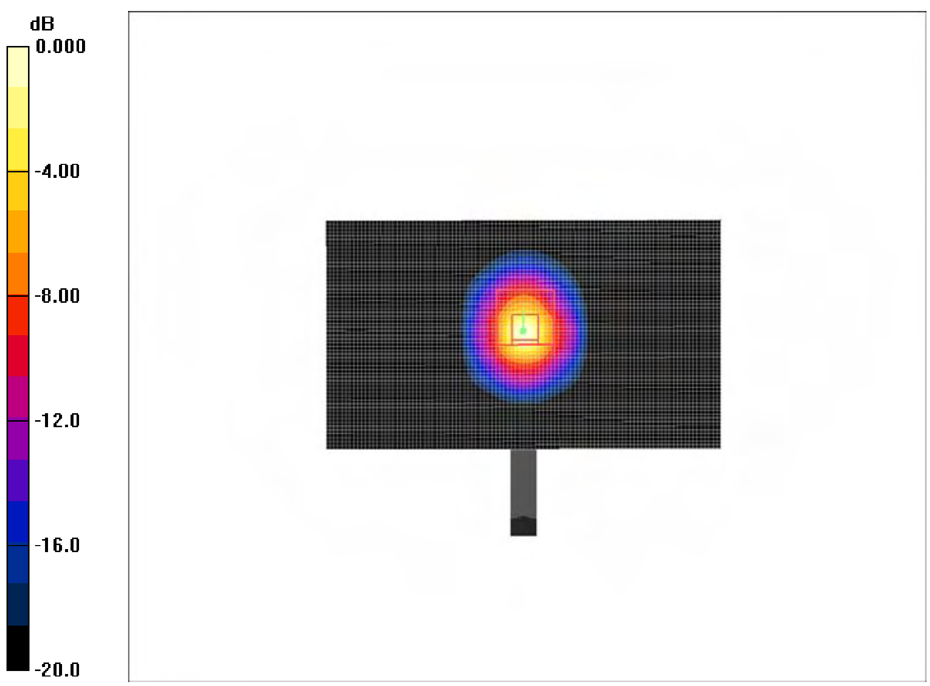
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(3.72, 3.72, 3.72); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

d =10 mm, Pin = 0.5W /Area Scan (101x151x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 116.5 mW/g

d =10 mm, Pin = 0.5W /Zoom Scan (7x7x8)/Cube 0: Measurement grid: dx=3mm, dy=3mm, dz=3mm
Reference Value = 88.3 V/m; Power Drift = 0.109 dB
Peak SAR (extrapolated) = 289.2 W/kg

SAR (1 g) = 40.5 mW/g; SAR (10 g) = 11.6 mW/g
Maximum value of SAR (measured) = 95.6 mW/g



0 dB = 95.6mW/g

5500 MHz System Validation with Body Tissue

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

System Performance Test (5800 MHz Body)

DUT: D5GHzV2; Type: 5GHz; Serial: SN: 1001

Communication System: CW; Frequency: 5800 MHz; Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5800 MHz; σ = 6.0 mho/m; ε_r = 46.5; ρ = 1000 kg/m^3
Phantom section: Flat Section

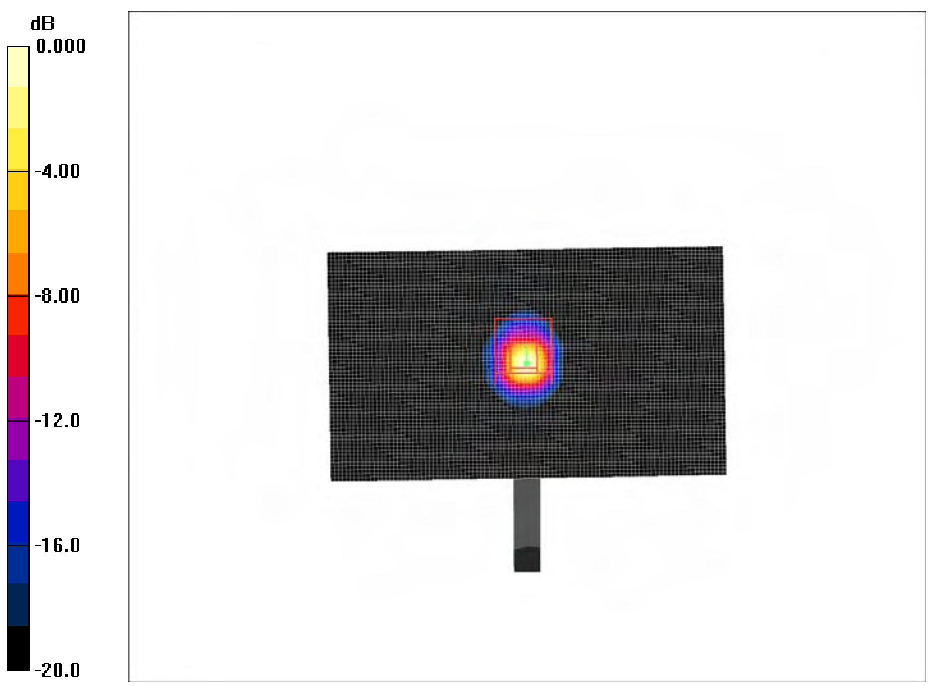
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.14, 4.14, 4.14); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

d =10 mm, Pin = 0.5W /Area Scan (101x151x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 89.5 mW/g

d =10 mm, Pin = 0.5W /Zoom Scan (7x7x8)/Cube 0: Measurement grid: dx=3mm, dy=3mm, dz=3mm
Reference Value = 74.2 V/m; Power Drift = 0.133 dB
Peak SAR (extrapolated) = 312.5 W/kg

SAR (1 g) = 38.1 mW/g; SAR (10 g) = 10.8 mW/g
Maximum value of SAR (measured) = 74.2 mW/g



0 dB = 74.2mW/g

5800 MHz System Validation with Body Tissue

16 Appendix E – EUT Scan Results

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A (Middle Channel)

DUT: Motion Computing, Inc.; Type: Tablet; Serial: R1212071

Communication System: 802.11b; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 2437 MHz; σ = 2.01 mho/m; ε_r = 50.7; ρ = 1000 kg/m^3
Phantom section: Flat Section

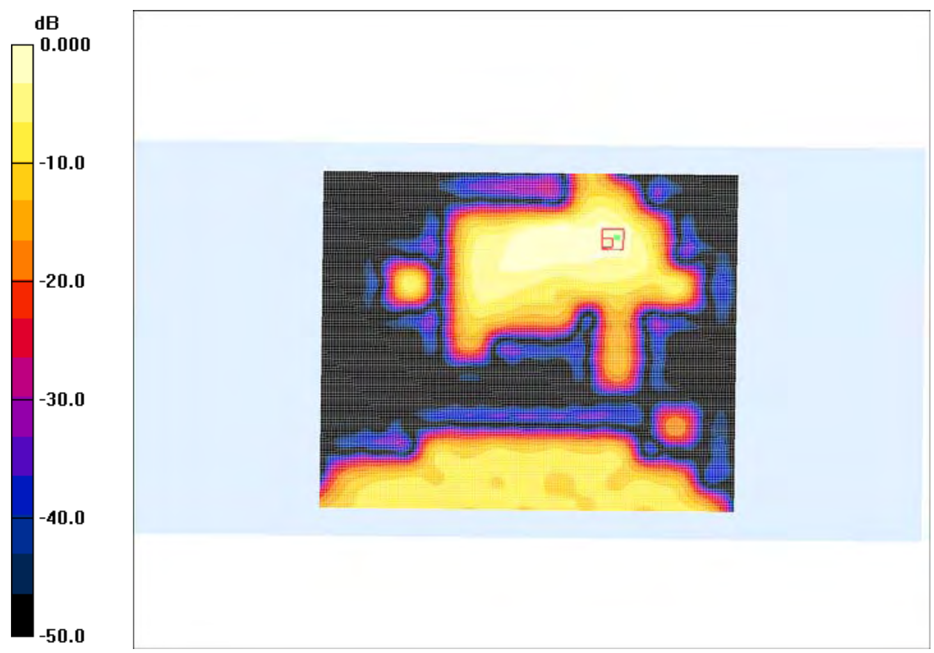
DASY4 Configuration:

- Probe: ET3DV6 - SN1604; ConvF(4.11, 4.11, 4.11); Calibrated: 8/24/2012
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: Flat Phantom 4.4; Type: Flat Phantom 4.4; Serial:
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x141x1): Measurement grid: dx=30mm, dy=30mm
Maximum value of SAR (interpolated) = 0.112 mW/g

Back Side Touch to the Phantom/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 0.947 V/m; Power Drift = -3.43 dB
Peak SAR (extrapolated) = 0.187 W/kg

SAR (1 g) = 0.073 mW/g; SAR (10 g) = 0.039 mW/g
Maximum value of SAR (measured) = 0.076 mW/g



0 dB = 0.076mW/g

#1

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - B (Middle Channel)

DUT: Motion Computing, Inc.; Type: Tablet; Serial: R1212071

Communication System: 802.11n20; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 2437 MHz; σ = 2.01 mho/m; ε_r = 50.7; ρ = 1000 kg/m^3
Phantom section: Flat Section

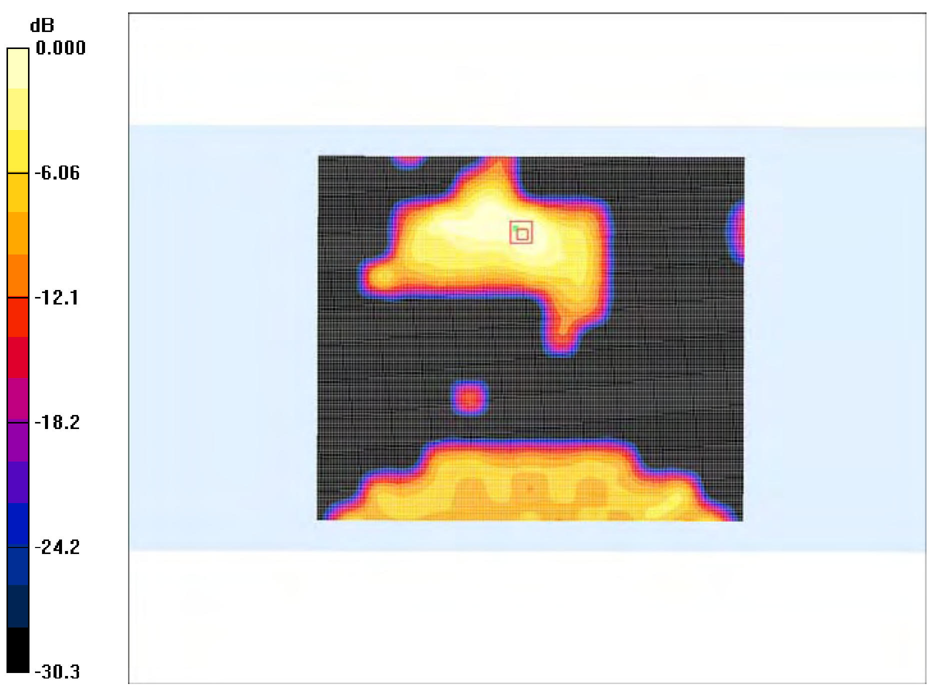
DASY4 Configuration:

- Probe: ET3DV6 - SN1604; ConvF(4.11, 4.11, 4.11); Calibrated: 8/24/2012
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: Flat Phantom 4.4; Type: Flat Phantom 4.4; Serial:
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x141x1): Measurement grid: dx=30mm, dy=30mm
Maximum value of SAR (interpolated) = 0.070 mW/g

Back Side Touch to the Phantom/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 0.896 V/m; Power Drift = -4.35 dB
Peak SAR (extrapolated) = 0.162 W/kg

SAR (1 g) = 0.059 mW/g; SAR (10 g) = 0.031 mW/g
Maximum value of SAR (measured) = 0.060 mW/g



0 dB = 0.060mW/g

#2

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom A + B (Middle Channel)

DUT: Motion Computing, Inc.; Type: Tablet; Serial: R1212071

Communication System: 802.11n20; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 2437 MHz; σ = 2.01 mho/m; ε_r = 50.7; ρ = 1000 kg/m^3
Phantom section: Flat Section

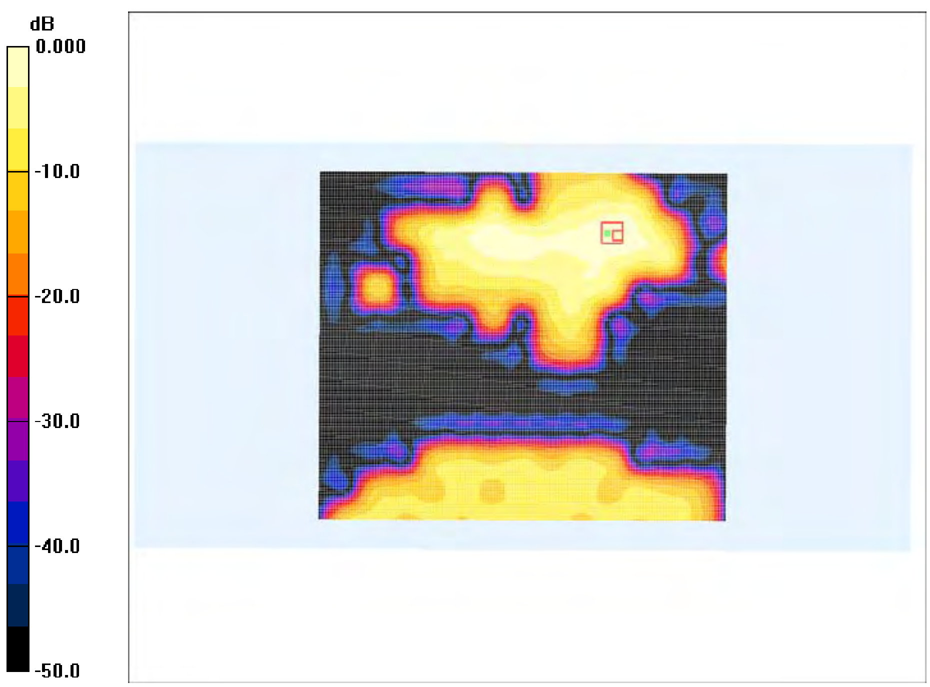
DASY4 Configuration:

- Probe: ET3DV6 - SN1604; ConvF(4.11, 4.11, 4.11); Calibrated: 8/24/2012
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: Flat Phantom 4.4; Type: Flat Phantom 4.4; Serial:
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x141x1): Measurement grid: dx=30mm, dy=30mm
Maximum value of SAR (interpolated) = 0.080 mW/g

Back Side Touch to the Phantom/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 1.49 V/m; Power Drift = -2.37 dB
Peak SAR (extrapolated) = 0.181 W/kg

SAR (1 g) = 0.074 mW/g; SAR (10 g) = 0.038 mW/g
Maximum value of SAR (measured) = 0.079 mW/g



0 dB = 0.079mW/g

#3

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - B (Middle Channel)

DUT: Motion Computing, Inc.; Type: Tablet; Serial: R1212071

Communication System: 802.11n40; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 2437 MHz; σ = 2.01 mho/m; ε_r = 50.7; ρ = 1000 kg/m^3
Phantom section: Flat Section

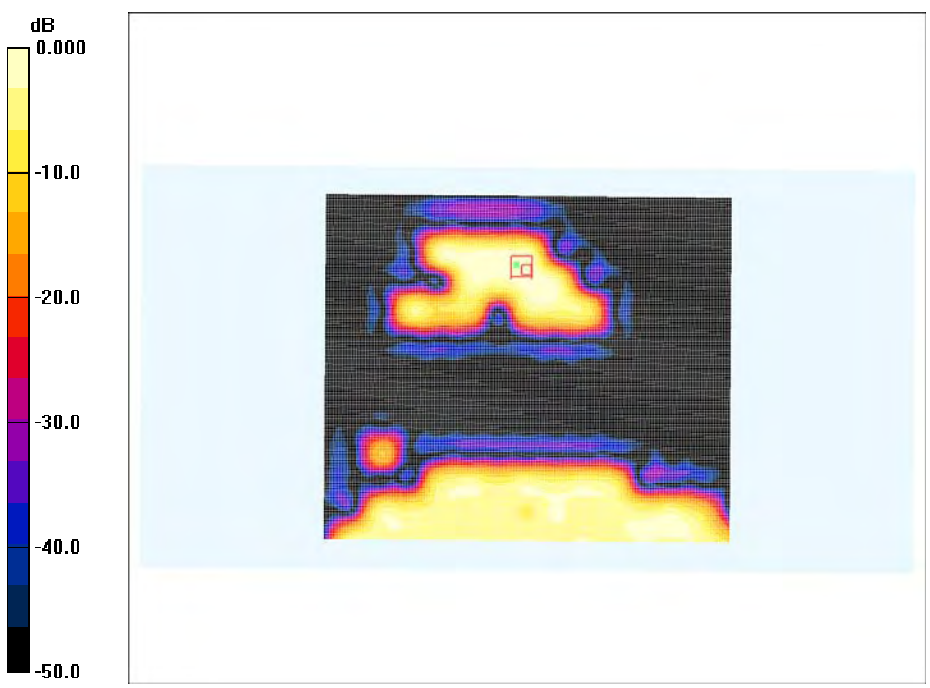
DASY4 Configuration:

- Probe: ET3DV6 - SN1604; ConvF(4.11, 4.11, 4.11); Calibrated: 8/24/2012
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: Flat Phantom 4.4; Type: Flat Phantom 4.4; Serial:
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x141x1): Measurement grid: dx=30mm, dy=30mm
Maximum value of SAR (interpolated) = 0.049 mW/g

Back Side Touch to the Phantom/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 0.625 V/m; Power Drift = -5.86 dB
Peak SAR (extrapolated) = 0.049 W/kg

SAR (1 g) = 0.019 mW/g; SAR (10 g) = 0.00912 mW/g
Maximum value of SAR (measured) = 0.024 mW/g



0 dB = 0.024mW/g

#4

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A + B (Middle Channel)

DUT: Motion Computing, Inc.; Type: Tablet; Serial: R1212071

Communication System: 802.11n40; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 2437 MHz; σ = 2.01 mho/m; ε_r = 50.7; ρ = 1000 kg/m^3
Phantom section: Flat Section

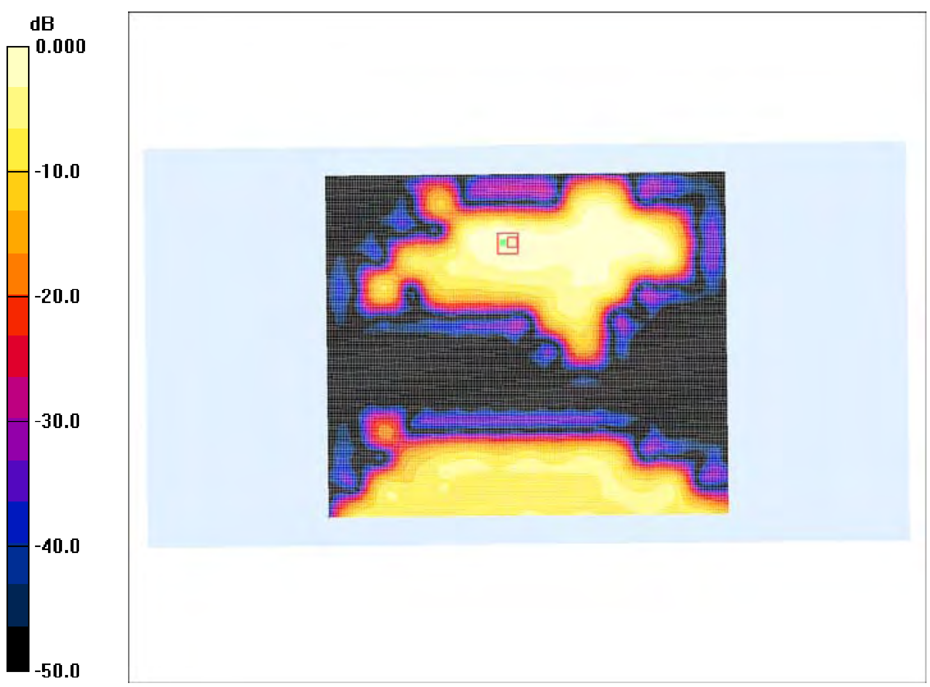
DASY4 Configuration:

- Probe: ET3DV6 - SN1604; ConvF(4.11, 4.11, 4.11); Calibrated: 8/24/2012
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: Flat Phantom 4.4; Type: Flat Phantom 4.4; Serial:
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x141x1): Measurement grid: dx=30mm, dy=30mm
Maximum value of SAR (interpolated) = 0.082 mW/g

Back Side Touch to the Phantom/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 0.948 V/m; Power Drift = -9.67 dB
Peak SAR (extrapolated) = 0.143 W/kg

SAR (1 g) = 0.048 mW/g; SAR (10 g) = 0.024 mW/g
Maximum value of SAR (measured) = 0.053 mW/g



0 dB = 0.053mW/g

#5

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - B (Middle Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11a; Frequency: 5200 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5200 MHz; σ = 5.3 mho/m; ε_r = 47.9; ρ = 1000 kg/m^3
Phantom section: Flat Section

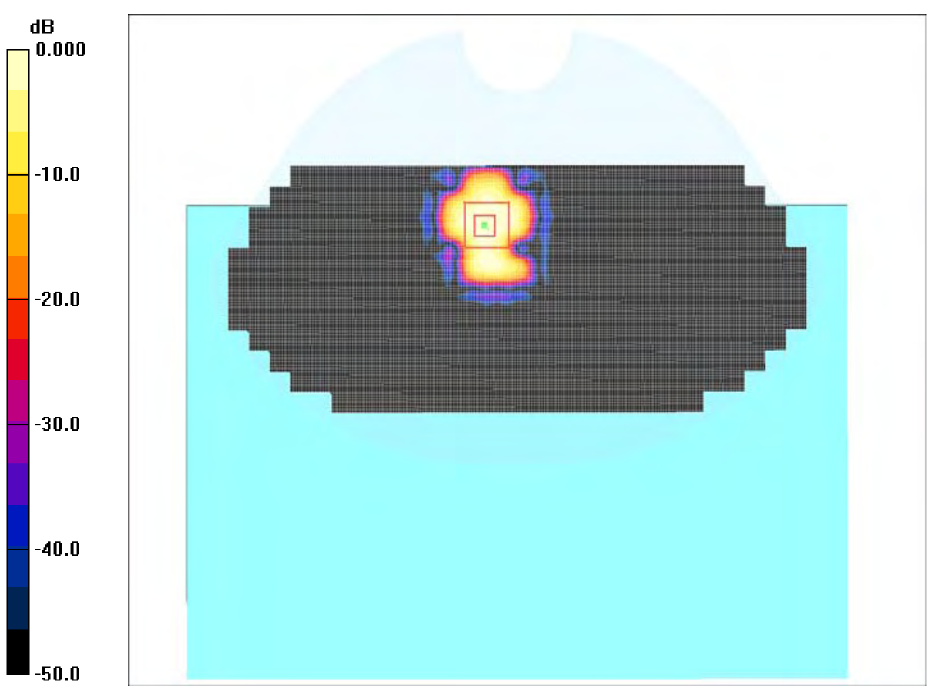
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.486 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 1.19 V/m; Power Drift = 0.171 dB
Peak SAR (extrapolated) = 0.620 W/kg

SAR (1 g) = 0.168 mW/g; SAR (10 g) = 0.054 mW/g
Maximum value of SAR (measured) = 0.404 mW/g



0 dB = 0.404mW/g

#6

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A (Middle Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11a; Frequency: 5300 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5300 MHz; σ = 5.4 mho/m; ε_r = 47.5; ρ = 1000 kg/m^3
Phantom section: Flat Section

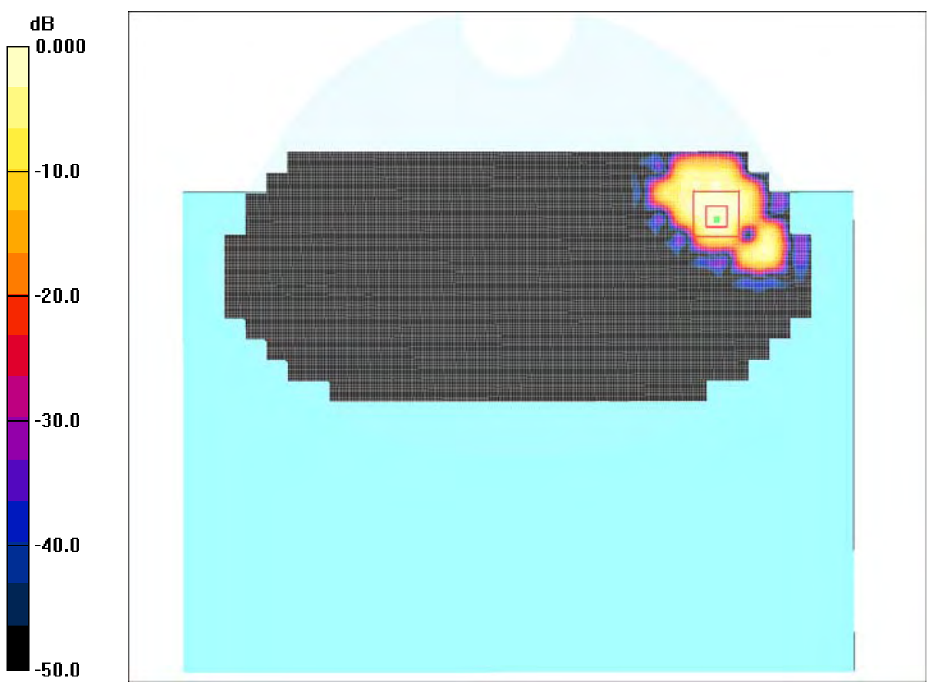
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.410 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 1.01V/m; Power Drift = 0.164 dB
Peak SAR (extrapolated) = 0.534 W/kg

SAR (1 g) = 0.145 mW/g; SAR (10 g) = 0.046 mW/g
Maximum value of SAR (measured) = 0.339 mW/g



0 dB = 0.339mW/g

#7

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A (Middle Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11a; Frequency: 5580 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5580 MHz; σ = 5.86 mho/m; ε_r = 46.8; ρ = 1000 kg/m^3
Phantom section: Flat Section

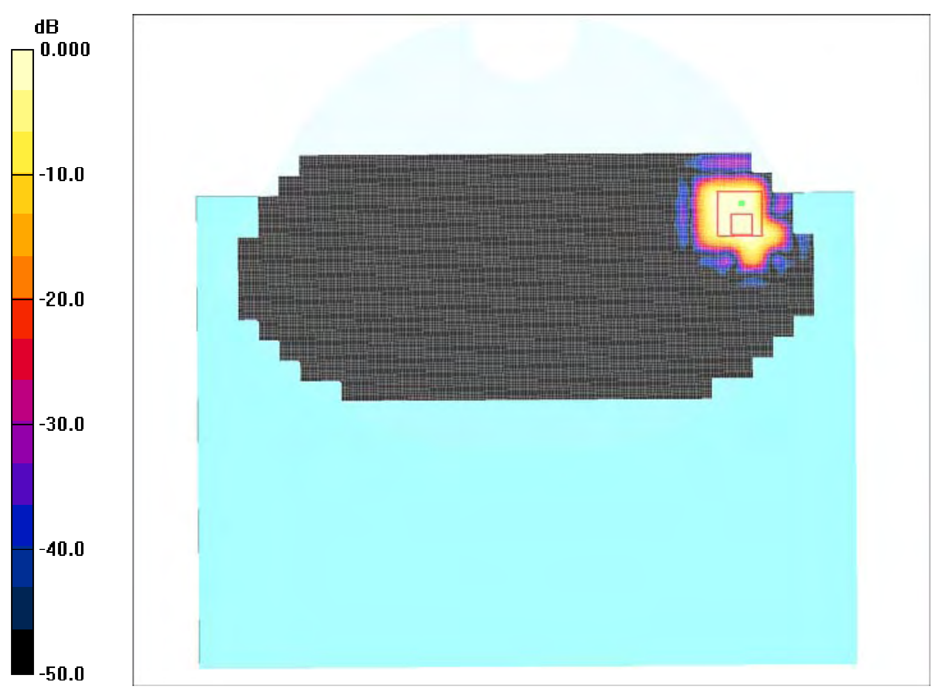
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(3.72, 3.72, 3.72); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.704 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 1.07 V/m; Power Drift = 0.158 dB
Peak SAR (extrapolated) = 0.764 W/kg

SAR (1 g) = 0.135 mW/g; SAR (10 g) = 0.048 mW/g
Maximum value of SAR (measured) = 0.318 mW/g



0 dB = 0.318mW/g

#8

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - B (Low Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11a; Frequency: 5745 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5745 MHz; σ = 6 mho/m; ε_r = 46.6; ρ = 1000 kg/m^3
Phantom section: Flat Section

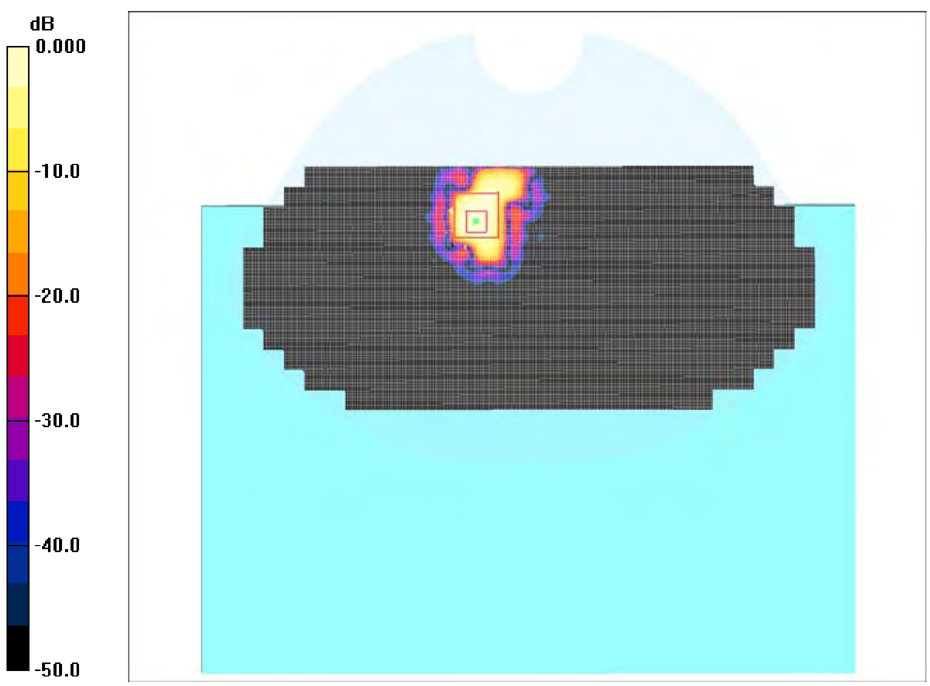
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.14, 4.14, 4.14); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.242 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.97V/m; Power Drift = 0.149 dB
Peak SAR (extrapolated) = 0.760 W/kg

SAR (1 g) = 0.098 mW/g; SAR (10 g) = 0.034 mW/g
Maximum value of SAR (measured) = 0.223 mW/g



0 dB = 0.223mW/g

#9

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - B (Middle Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n20; Frequency: 5200 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5200 MHz; σ = 5.3 mho/m; ε_r = 47.9; ρ = 1000 kg/m^3
Phantom section: Flat Section

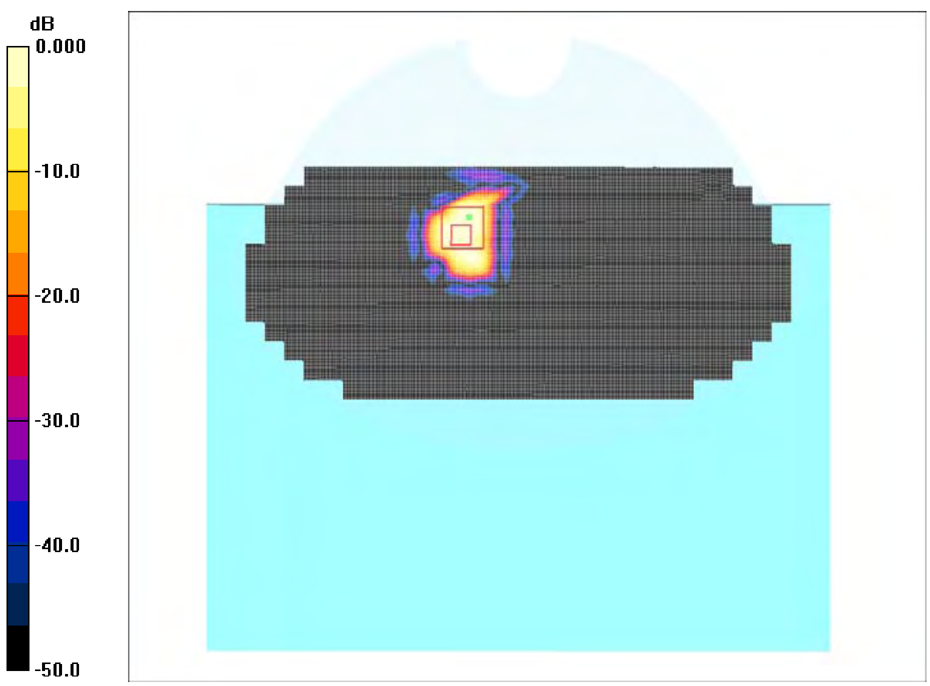
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom /Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.362 mW/g

Back Side Touch to the Phantom /Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 1.01 V/m; Power Drift = 0.144 dB
Peak SAR (extrapolated) = 0.476 W/kg

SAR (1 g) = 0.101 mW/g; SAR (10 g) = 0.031 mW/g
Maximum value of SAR (measured) = 0.236 mW/g



0 dB = 0.236mW/g

#10

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A (Middle Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n20; Frequency: 5300 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5300 MHz; σ = 5.4 mho/m; ε_r = 47.5; ρ = 1000 kg/m^3
Phantom section: Flat Section

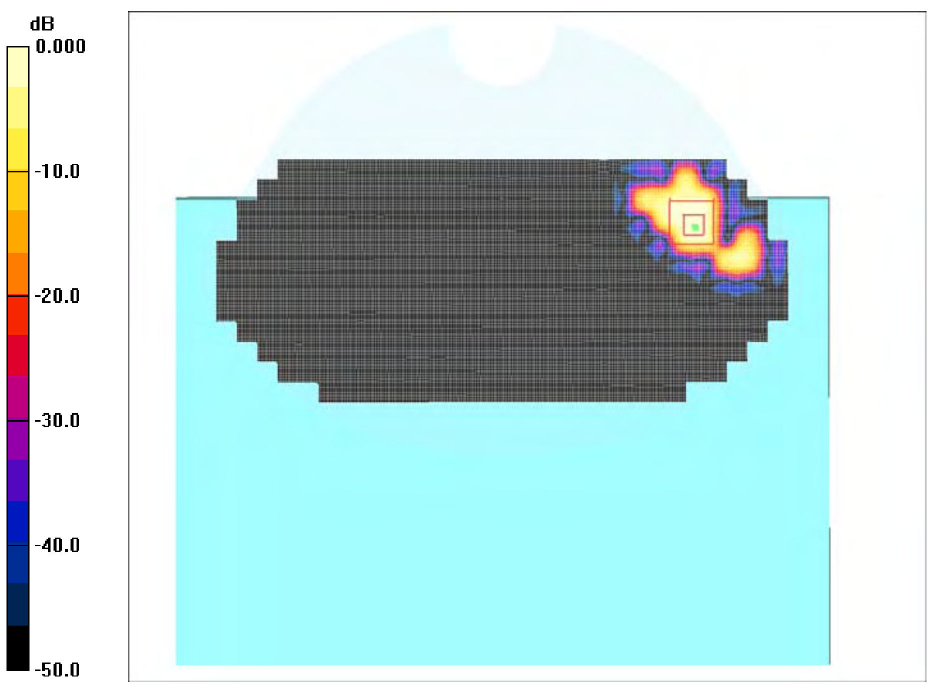
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.574 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.96V/m; Power Drift = 0.155 dB
Peak SAR (extrapolated) = 1.21 W/kg

SAR (1 g) = 0.145 mW/g; SAR (10 g) = 0.043 mW/g
Maximum value of SAR (measured) = 0.300 mW/g



0 dB = 0.300mW/g

#11

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)
Back Side Touch to the Phantom - A (Middle Channel)
DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n20; Frequency: 5580 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5580 MHz; σ = 5.86 mho/m; ε_r = 46.8; ρ = 1000 kg/m^3
Phantom section: Flat Section

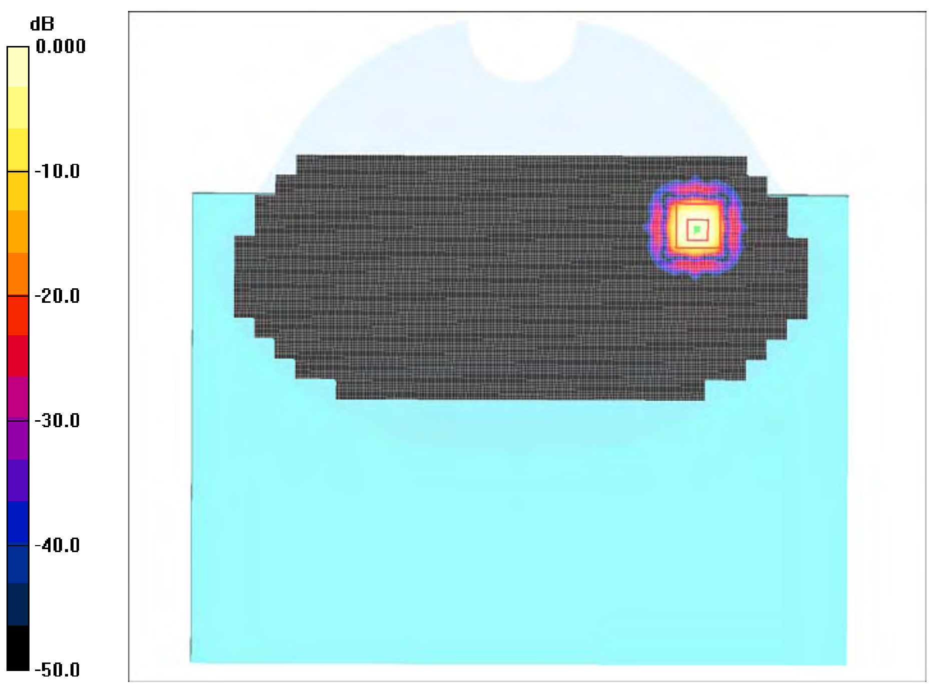
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(3.72, 3.72, 3.72); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.203 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.88 V/m; Power Drift = 0.141 dB
Peak SAR (extrapolated) = 0.744 W/kg

SAR (1 g) = 0.086 mW/g; SAR (10 g) = 0.026 mW/g
Maximum value of SAR (measured) = 0.177 mW/g



0 dB = 0.177mW/g

#12

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - B (Middle Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n20; Frequency: 5785 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5785 MHz; σ = 6.07 mho/m; ε_r = 46.5; ρ = 1000 kg/m^3
Phantom section: Flat Section

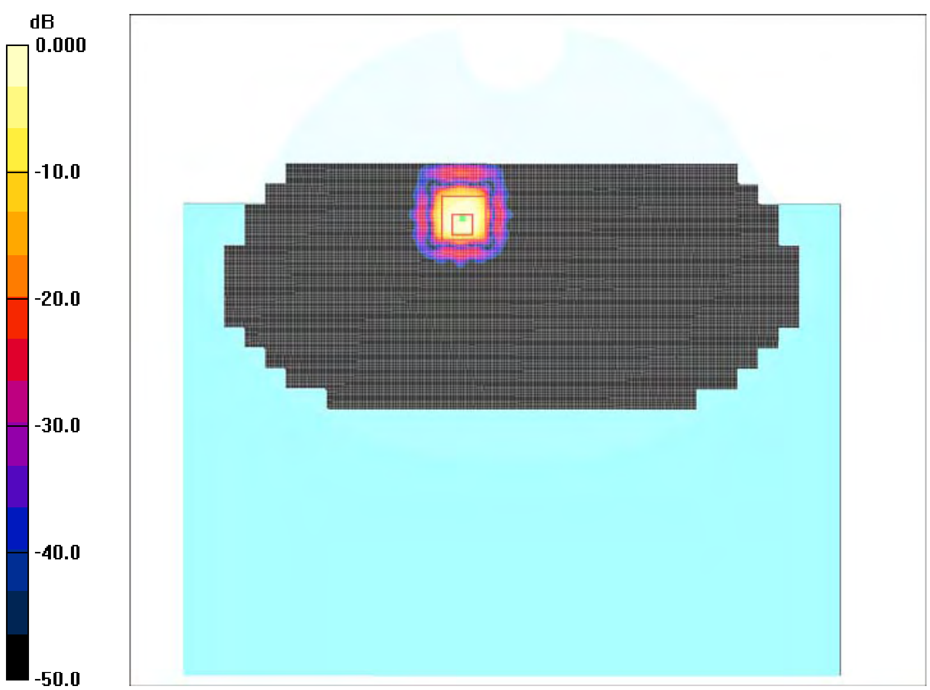
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.14, 4.14, 4.14); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.215 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.84V/m; Power Drift = 0.142dB
Peak SAR (extrapolated) = 0.722 W/kg

SAR (1 g) = 0.090 mW/g; SAR (10 g) = 0.029 mW/g
Maximum value of SAR (measured) = 0.196 mW/g



0 dB = 0.196mW/g

#13

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A + B (Middle Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n20; Frequency: 5200 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5200 MHz; σ = 5.3 mho/m; ε_r = 47.9; ρ = 1000 kg/m^3
Phantom section: Flat Section

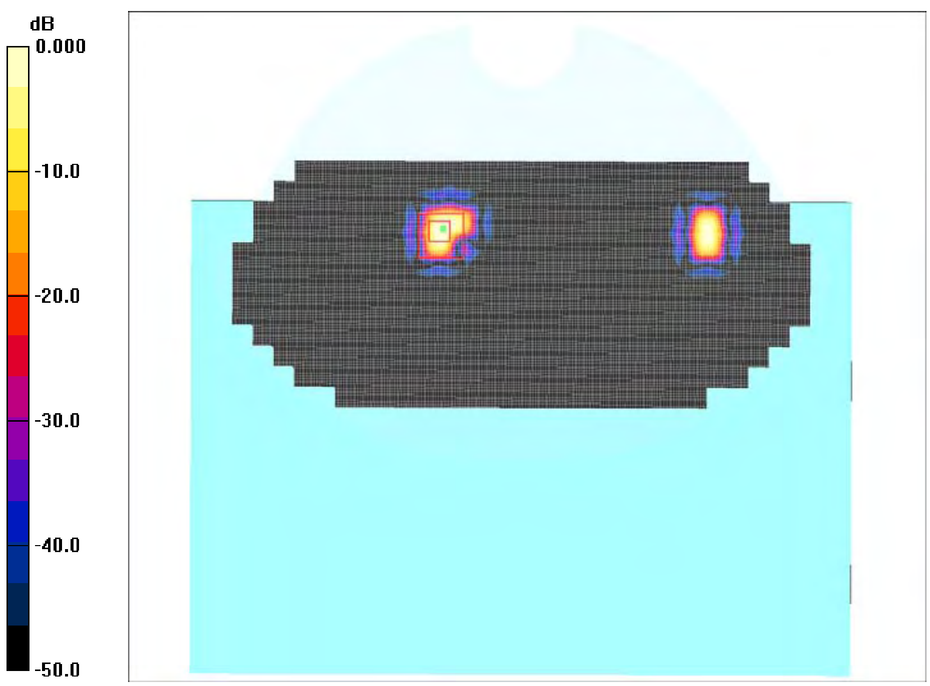
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.220 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.79V/m; Power Drift = 0.131 dB
Peak SAR (extrapolated) = 0.661 W/kg

SAR (1 g) = 0.066 mW/g; SAR (10 g) = 0.013 mW/g
Maximum value of SAR (measured) = 0.141 mW/g



0 dB = 0.141mW/g

#14

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)
Back Side Touch to the Phantom - A + B (Middle Channel)
DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11 n20; Frequency: 5300 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5300 MHz; σ = 5.4 mho/m; ε_r = 47.5; ρ = 1000 kg/m^3
Phantom section: Flat Section

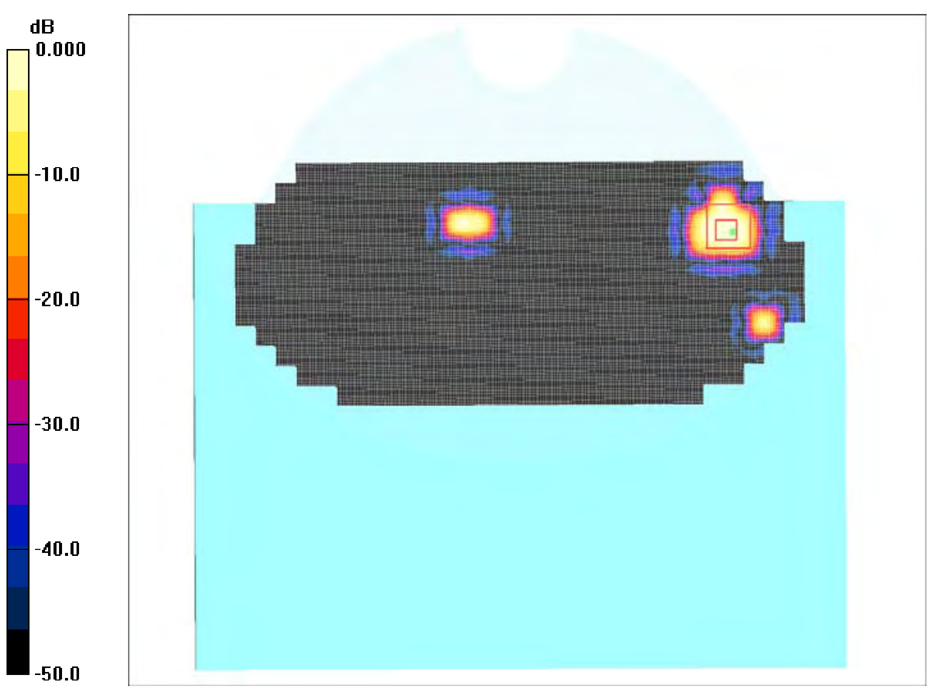
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.477 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.89V/m; Power Drift = 0.150 dB
Peak SAR (extrapolated) = 0.594 W/kg

SAR (1 g) = 0.081 mW/g; SAR (10 g) = 0.026 mW/g
Maximum value of SAR (measured) = 0.185 mW/g



0 dB = 0.185mW/g

#15

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A + B (Low Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n20; Frequency: 5500 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5500 MHz; σ = 5.7 mho/m; ε_r = 47; ρ = 1000 kg/m^3
Phantom section: Flat Section

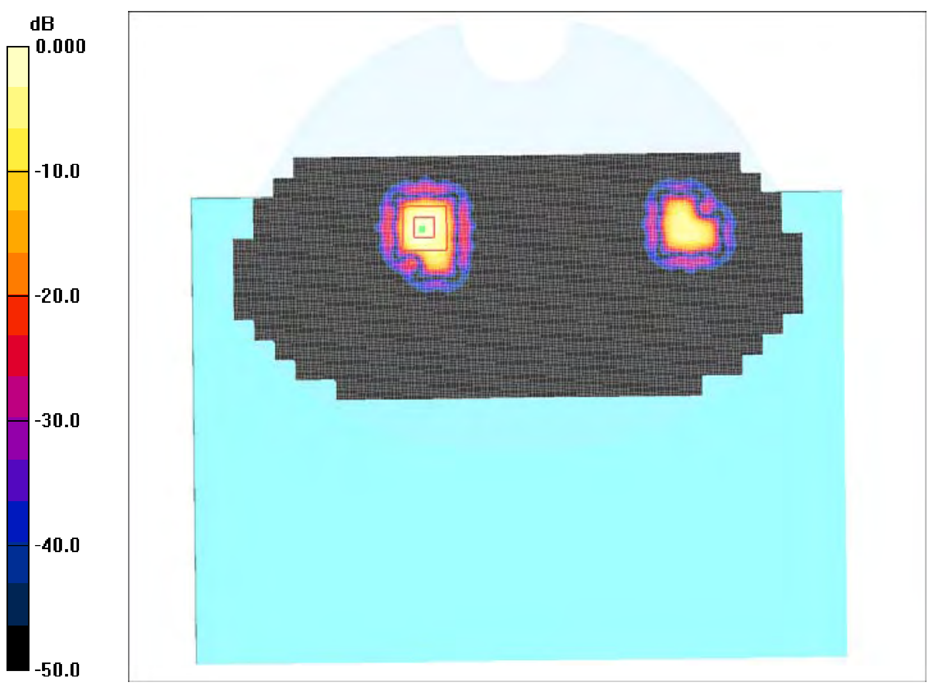
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(3.72, 3.72, 3.72); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.277 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 1.15 V/m; Power Drift = -8.47 dB
Peak SAR (extrapolated) = 0.885 W/kg

SAR (1 g) = 0.123 mW/g; SAR (10 g) = 0.035 mW/g
Maximum value of SAR (measured) = 0.289 mW/g



0 dB = 0.289mW/g

#16

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - B (High Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n40; Frequency: 5230 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5230 MHz; σ = 5.36 mho/m; ε_r = 48.3; ρ = 1000 kg/m^3
Phantom section: Flat Section

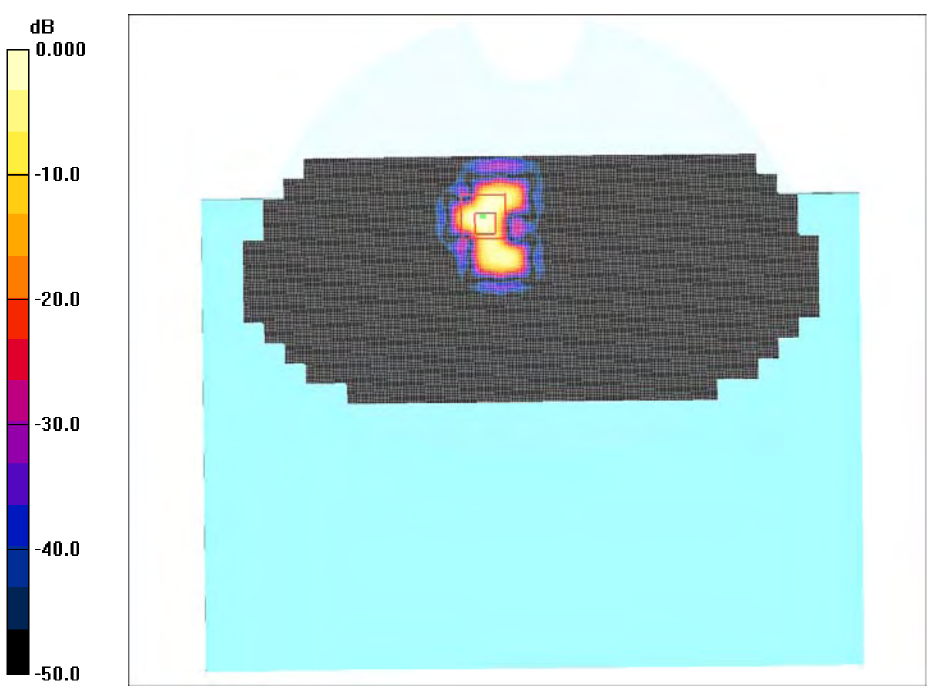
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.247 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 1.02V/m; Power Drift = -10.9 dB
Peak SAR (extrapolated) = 0.527 W/kg

SAR (1 g) = 0.084 mW/g; SAR (10 g) = 0.025 mW/g
Maximum value of SAR (measured) = 0.193 mW/g



0 dB = 0.193mW/g

#17

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A (Low Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11 n40; Frequency: 5270 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5270 MHz; σ = 5.4 mho/m; ε_r = 47.6; ρ = 1000 kg/m^3
Phantom section: Flat Section

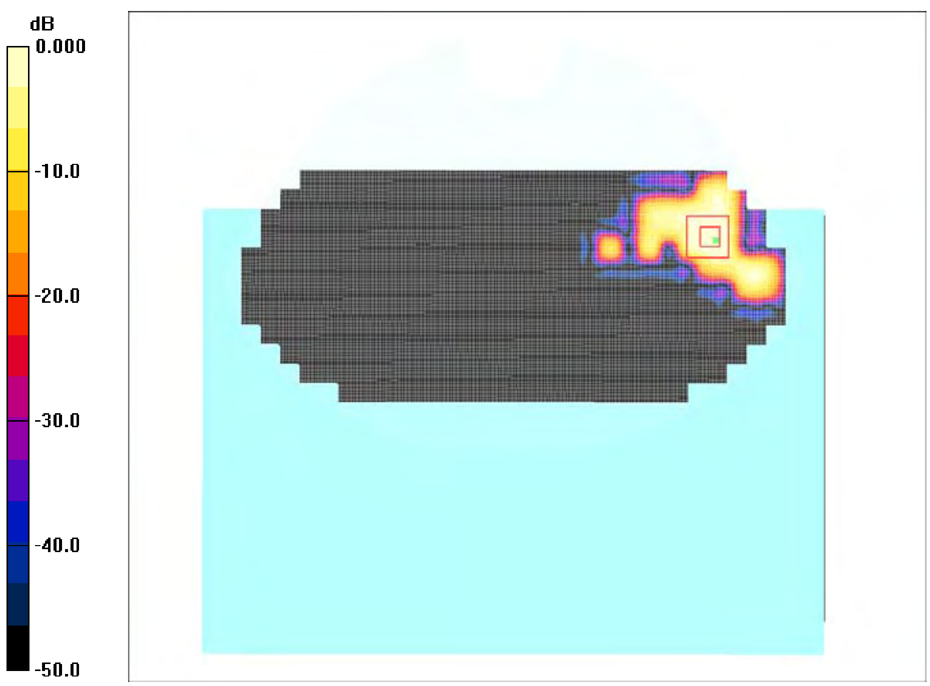
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.463 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 1.17V/m; Power Drift = -8.87 dB
Peak SAR (extrapolated) = 1.61 W/kg

SAR (1 g) = 0.167 mW/g; SAR (10 g) = 0.032 mW/g
Maximum value of SAR (measured) = 0.329 mW/g



0 dB = 0.329mW/g

#18

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A (Middle Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n40; Frequency: 5550 MHz;Duty Cycle: 1:1
Medium parameters used: f = 5550 MHz; σ = 5.8 mho/m; ε_r = 46.9; ρ = 1000 kg/m^3
Phantom section: Flat Section

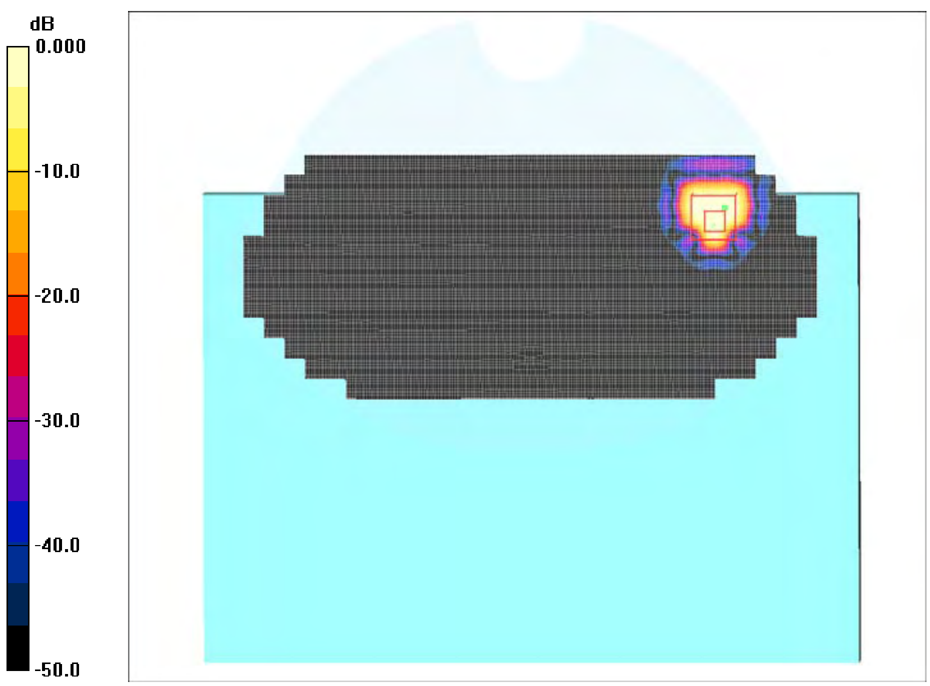
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(3.72, 3.72, 3.72); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.535 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.772 V/m; Power Drift = -3.32 dB
Peak SAR (extrapolated) = 0.951 W/kg

SAR (1 g) = 0.120 mW/g; SAR (10 g) = 0.040 mW/g
Maximum value of SAR (measured) = 0.254 mW/g



0 dB = 0.254mW/g

#19

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - B (High Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n40; Frequency: 5795 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5795 MHz; σ = 6.09 mho/m; ε_r = 46.5; ρ = 1000 kg/m^3
Phantom section: Flat Section

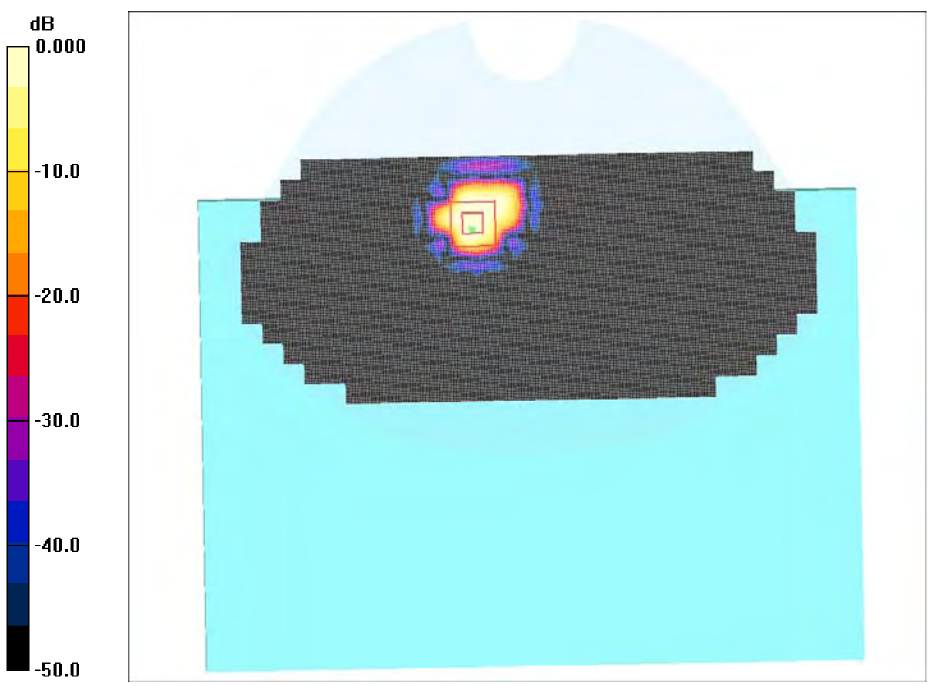
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.14, 4.14, 4.14); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.381 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.798 V/m; Power Drift = -3.85 dB
Peak SAR (extrapolated) = 0.866 W/kg

SAR (1 g) = 0.108 mW/g; SAR (10 g) = 0.035 mW/g
Maximum value of SAR (measured) = 0.237 mW/g



0 dB = 0.237mW/g

#20

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A + B (High Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n40; Frequency: 5230 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5230 MHz; σ = 5.36 mho/m; ε_r = 48.3; ρ = 1000 kg/m^3
Phantom section: Flat Section

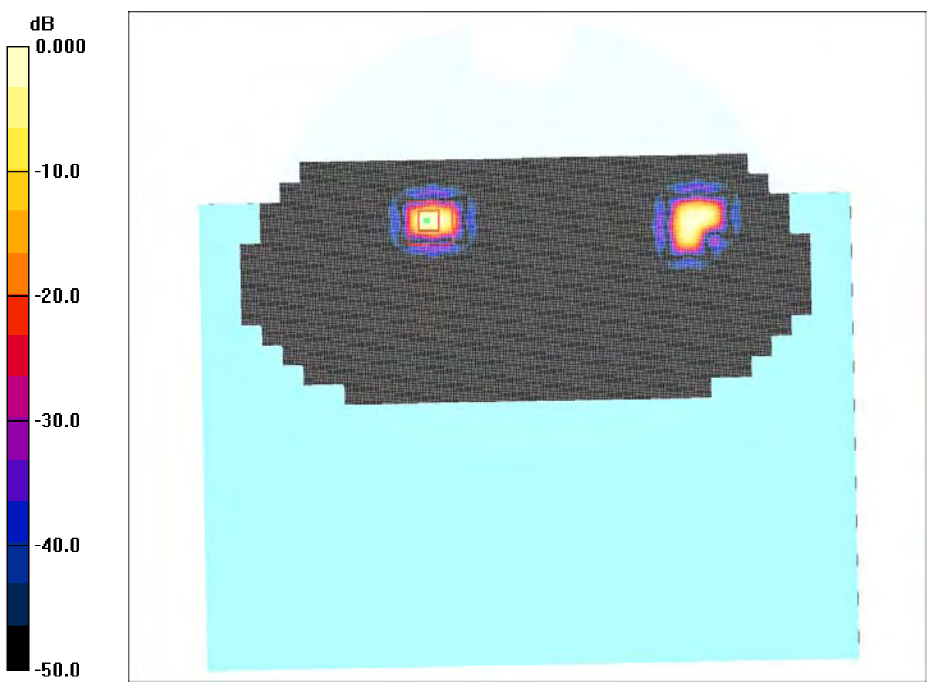
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.162 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.659V/m; Power Drift = -7.62 dB
Peak SAR (extrapolated) = 0.502 W/kg

SAR (1 g) = 0.056 mW/g; SAR (10 g) = 0.011 mW/g
Maximum value of SAR (measured) = 0.131 mW/g



0 dB = 0.131mW/g

#21

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A + B (Low Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11 n40; Frequency: 5270 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5270 MHz; σ = 5.4 mho/m; ε_r = 47.6; ρ = 1000 kg/m^3
Phantom section: Flat Section

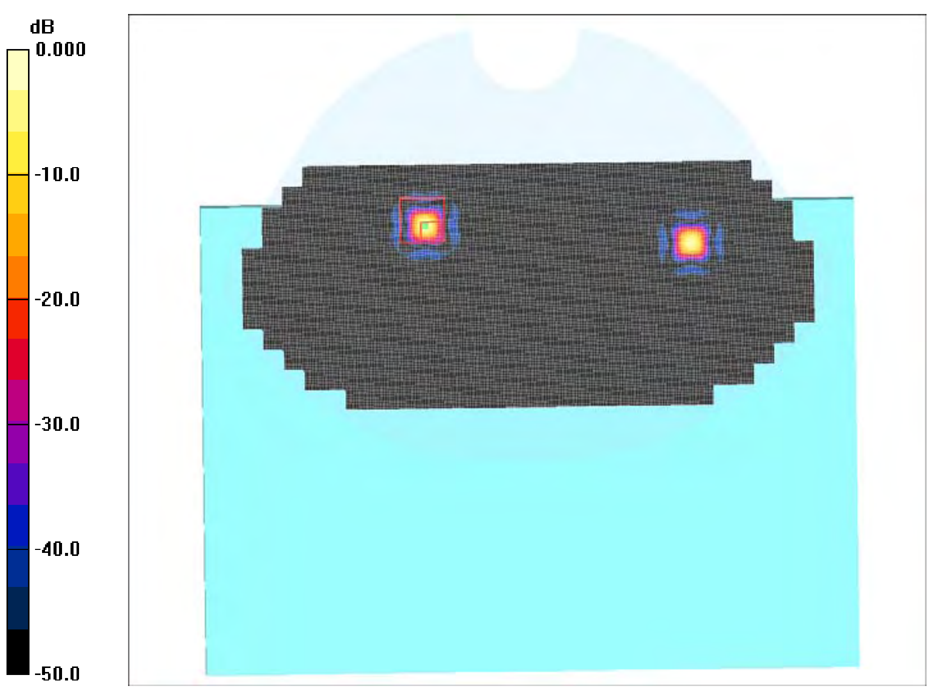
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.17, 4.17, 4.17); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.065 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.359 V/m; Power Drift = -9.92 dB
Peak SAR (extrapolated) = 0.336 W/kg

SAR (1 g) = 0.00161 mW/g; SAR (10 g) = 0.000314 mW/g
Maximum value of SAR (measured) = 0.133 mW/g



0 dB = 0.133mW/g

#22

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A + B (Low Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n40; Frequency: 5510 MHz;Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5510 MHz; σ = 5.72 mho/m; ε_r = 47; ρ = 1000 kg/m^3
Phantom section: Flat Section

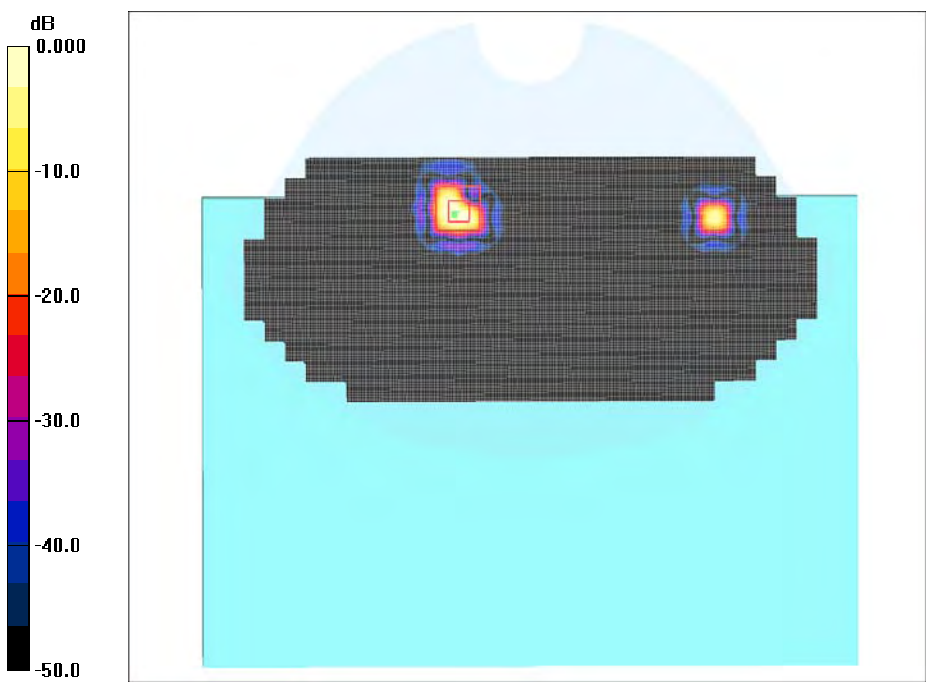
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(3.72, 3.72, 3.72); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.258 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.567 V/m; Power Drift = -7.28 dB
Peak SAR (extrapolated) = 0.645 W/kg

SAR (1 g) = 0.067 mW/g; SAR (10 g) = 0.016 mW/g
Maximum value of SAR (measured) = 0.132 mW/g



0 dB = 0.132mW/g

#23

Test Laboratory: Bay Area Compliance Lab Corp. (BACL)

Back Side Touch to the Phantom - A + B (Low Channel)

DUT: Motion Computing; Type: tablet; Serial: R1212071

Communication System: 802.11n40; Frequency: 5755 MHz; Duty Cycle: 1:1
Medium parameters used (interpolated): f = 5755 MHz; σ = 6.01 mho/m; ε_r = 46.6; ρ = 1000 kg/m^3
Phantom section: Flat Section

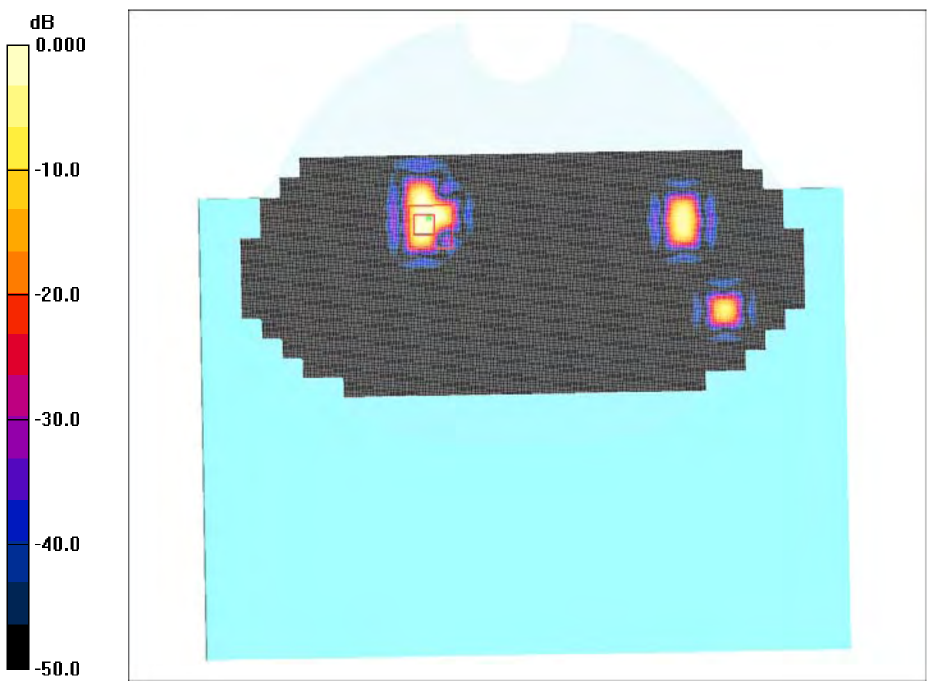
DASY4 Configuration:

- Probe: EX3DV4 - SN3619; ConvF(4.14, 4.14, 4.14); Calibrated: 8/27/2012
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn456; Calibrated: 3/16/2012
- Phantom: SAM with CRP; Type: Twin SAM; Serial: TP-1032
- Measurement SW: DASY4, V4.7 Build 80; Postprocessing SW: SEMCAD, V1.8 Build 186

Back Side Touch to the Phantom/Area Scan (121x301x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 0.331 mW/g

Back Side Touch to the Phantom/Zoom Scan (10x10x8)/Cube 0: Measurement grid: dx=3.33mm, dy=3.33mm, dz=3mm
Reference Value = 0.889V/m; Power Drift = -2.61 dB
Peak SAR (extrapolated) = 1.18 W/kg

SAR (1 g) = 0.123 mW/g; SAR (10 g) = 0.023 mW/g
Maximum value of SAR (measured) = 0.241 mW/g



0 dB = 0.241mW/g

#24

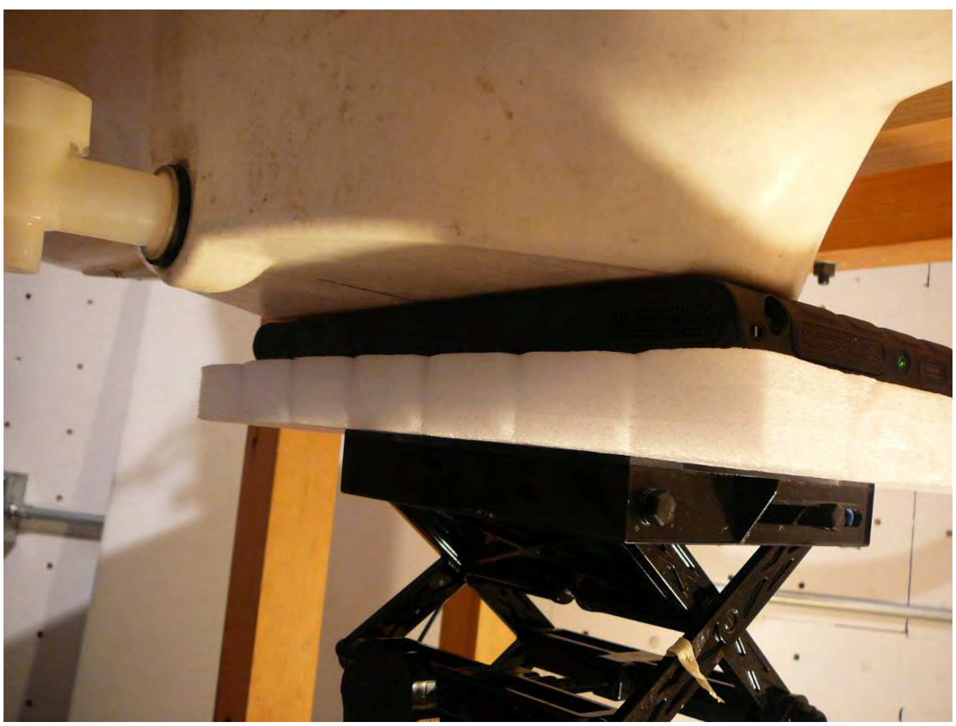
17 Appendix F – Test Setup Photos

17.1 Tablet PC Back Side Touch to the Flat Phantom Setup Photo

17.2 Tablet PC Right Side Touch to the Flat Phantom Setup Photo

17.3 Tablet PC Left Side Touch to the Flat Phantom Setup Photo

17.4 Tablet PC Back Side Touch to the Twin Phantom Flat part Setup Photo

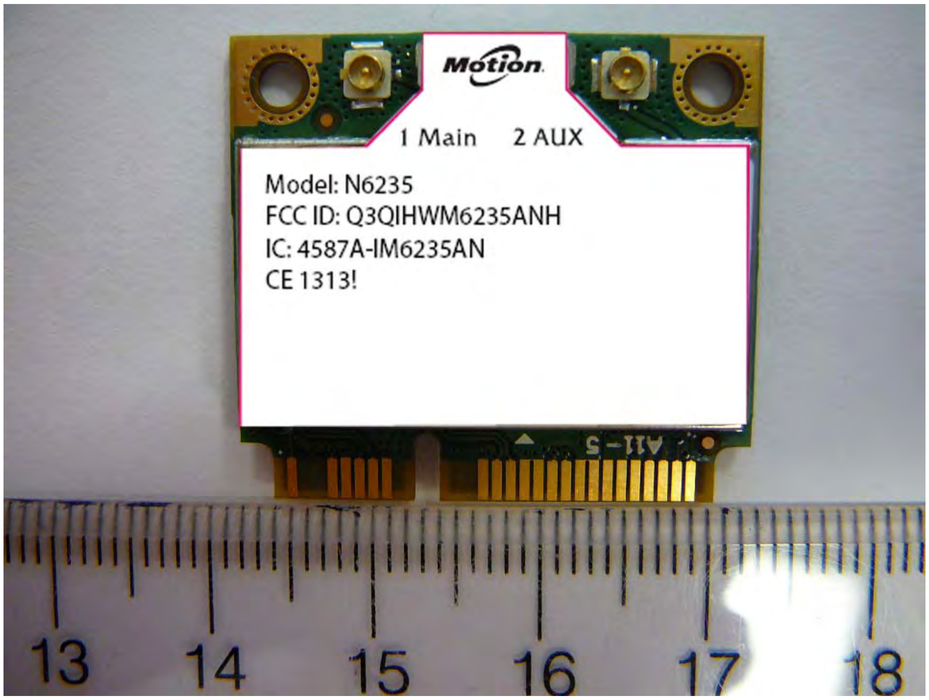


17.5 Tablet PC Right Side Touch to the Twin Phantom Flat part Setup Photo

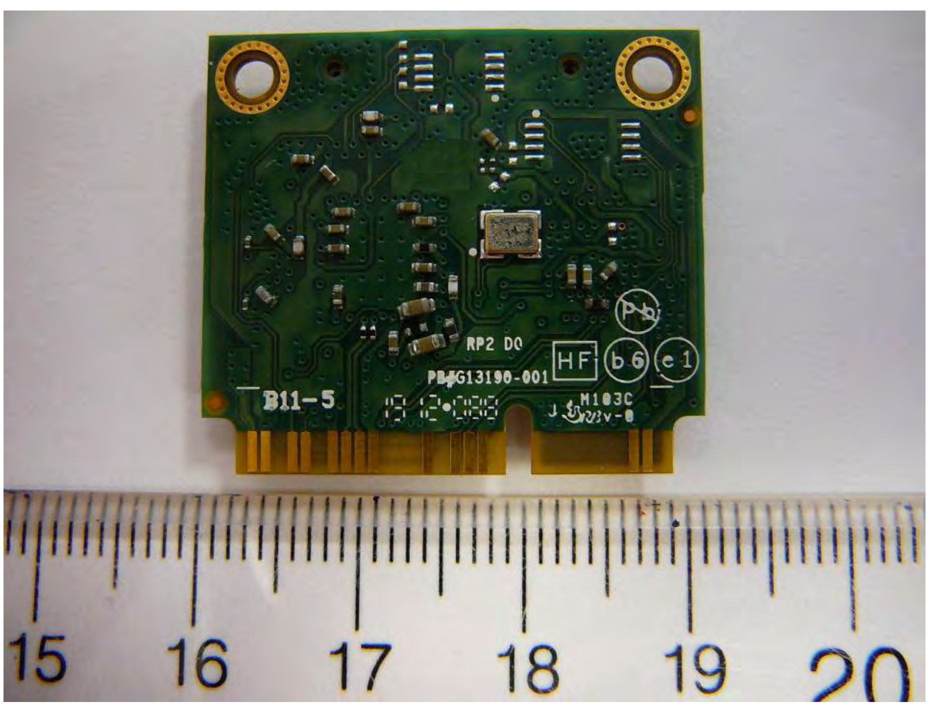
17.6 Tablet PC Left Side Touch to the Twin Phantom Flat part Setup Photo

18 Appendix G – EUT Photos

18.1 EUT – Front View



18.2 EUT – Rear View



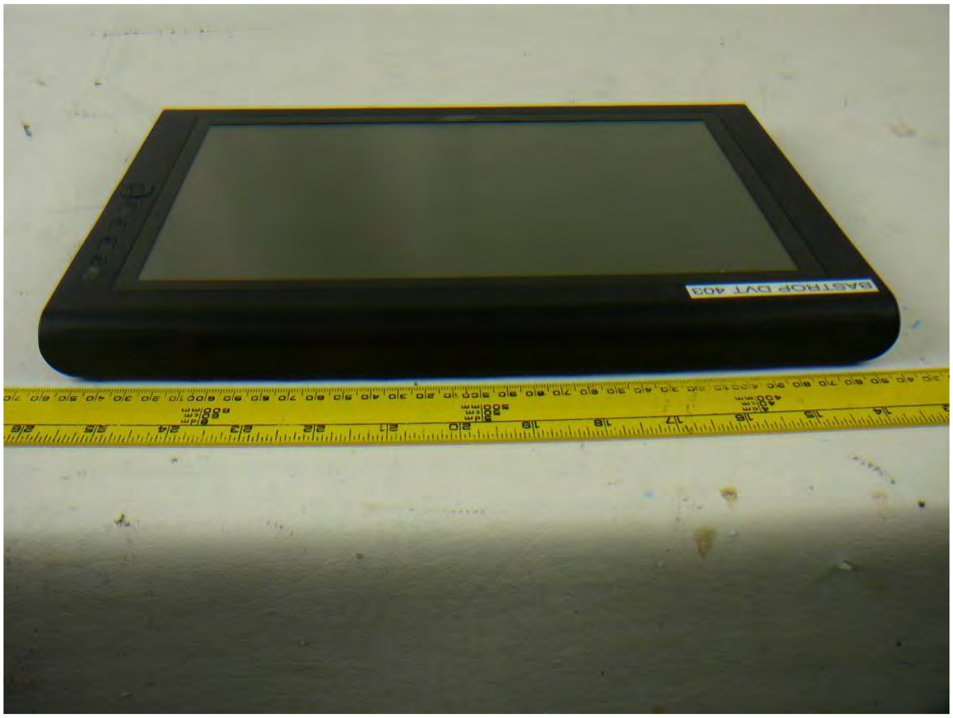
18.3 Motion T008 Tablet – Top View

18.4 Motion T008 Tablet – Front View

18.5 Motion T008 Tablet – Left Side View

18.6 Motion T008 Tablet – Right Side View

18.7 Motion T008 Tablet – Rear Side View



18.8 Motion T008 Tablet – Bottom Side View

18.9 Motion T008 Tablet – Open Chassis

18.10 Motion T008 Tablet – Battery View

19 Appendix H - Informative References

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