

Annex E

Appendix to Test Report No.: 1-4254/12-27-02



Testing Laboratory

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Accredited Test Laboratory:

The testing laboratory (area of testing) is accredited according to DIN EN ISO/IEC 17025 (2005) by the Deutsche Akkreditierungsstelle GmbH (DAkkS)

The accreditation is valid for the scope of testing procedures as stated in the accreditation certificate with the registration number: D-PL-12076-01-01

Appendix with Calibration data, Phantom certificate and system validation information

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2 Calibration report "Probe ER3DV6"

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland



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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **Cetecom**

Certificate No: **ER3-2262_Jan12**

CALIBRATION CERTIFICATE

Object **ER3DV6 - SN:2262**

Calibration procedure(s) **QA CAL-02.v6, QA CAL-25.v4
Calibration procedure for E-field probes optimized for close near field
evaluations in air**

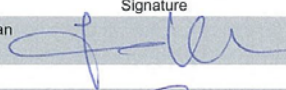

Calibration date: **January 9, 2012**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^\circ\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID | Cal Date (Certificate No.) | Scheduled Calibration |
|----------------------------|-----------------|-----------------------------------|------------------------|
| Power meter E4419B | GB41293874 | 31-Mar-11 (No. 217-01372) | Apr-12 |
| Power sensor E4412A | MY41498087 | 31-Mar-11 (No. 217-01372) | Apr-12 |
| Reference 3 dB Attenuator | SN: S5054 (3c) | 29-Mar-11 (No. 217-01369) | Apr-12 |
| Reference 20 dB Attenuator | SN: S5086 (20b) | 29-Mar-11 (No. 217-01367) | Apr-12 |
| Reference 30 dB Attenuator | SN: S5129 (30b) | 29-Mar-11 (No. 217-01370) | Apr-12 |
| Reference Probe ER3DV6 | SN: 2328 | 11-Oct-11 (No. ER3-2328_Oct11) | Oct-12 |
| DAE4 | SN: 789 | 6-Apr-11 (No. DAE4-789_Apr11) | Apr-12 |
| | | | |
| Secondary Standards | ID | Check Date (in house) | Scheduled Check |
| RF generator HP 8648C | US3642U01700 | 4-Aug-99 (in house check Apr-11) | In house check: Apr-13 |
| Network Analyzer HP 8753E | US37390585 | 18-Oct-01 (in house check Oct-11) | In house check: Oct-12 |

| | Name | Function | Signature |
|---|----------------|-----------------------|---|
| Calibrated by: | Jeton Kastrati | Laboratory Technician |  |
| Approved by: | Katja Pokovic | Technical Manager |  |
| | | | Issued: January 12, 2012 |
| This calibration certificate shall not be reproduced except in full without written approval of the laboratory. | | | |

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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

| | |
|--------------------------|---|
| NORM _{x,y,z} | sensitivity in free space |
| DCP | diode compression point |
| CF | crest factor (1/duty_cycle) of the RF signal |
| A, B, C | modulation dependent linearization parameters |
| Polarization ϕ | ϕ rotation around probe axis |
| Polarization ϑ | ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis |
| Connector Angle | information used in DASY system to align probe sensor X to the robot coordinate system |

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- *NORM_{x,y,z}*: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- *NORM(f)_{x,y,z}* = *NORM_{x,y,z}* * *frequency_response* (see Frequency Response Chart).
- *DCP_{x,y,z}*: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *PAR*: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- *A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}*: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- *Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle*: The angle is assessed using the information gained by determining the *NORM_x* (no uncertainty required).

ER3DV6 – SN:2262

January 9, 2012

Probe ER3DV6

SN:2262

Manufactured: May 18, 2001
Calibrated: January 9, 2012

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

ER3DV6– SN:2262

January 9, 2012

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2262

Basic Calibration Parameters

| | Sensor X | Sensor Y | Sensor Z | Unc (k=2) |
|--|----------|----------|----------|---------------|
| Norm ($\mu\text{V}/(\text{V}/\text{m})^2$) | 1.52 | 1.34 | 1.62 | $\pm 10.1 \%$ |
| DCP (mV) ^B | 100.7 | 99.9 | 97.6 | |

Modulation Calibration Parameters

| UID | Communication System Name | PAR | | A dB | B dB | C dB | VR mV | Unc ^E (k=2) |
|-------|---------------------------|------|---|---------|---------|---------|----------|---------------------------|
| 10000 | CW | 0.00 | X | 0.00 | 0.00 | 1.00 | 105.9 | $\pm 2.7 \%$ |
| | | | Y | 0.00 | 0.00 | 1.00 | 103.2 | |
| | | | Z | 0.00 | 0.00 | 1.00 | 99.8 | |

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

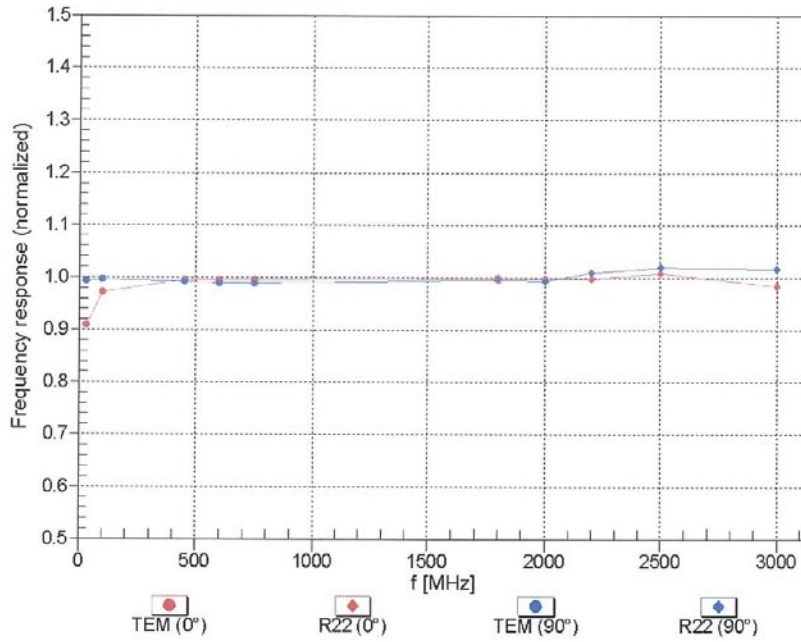
^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

ER3DV6-SN:2262

January 9, 2012

Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)

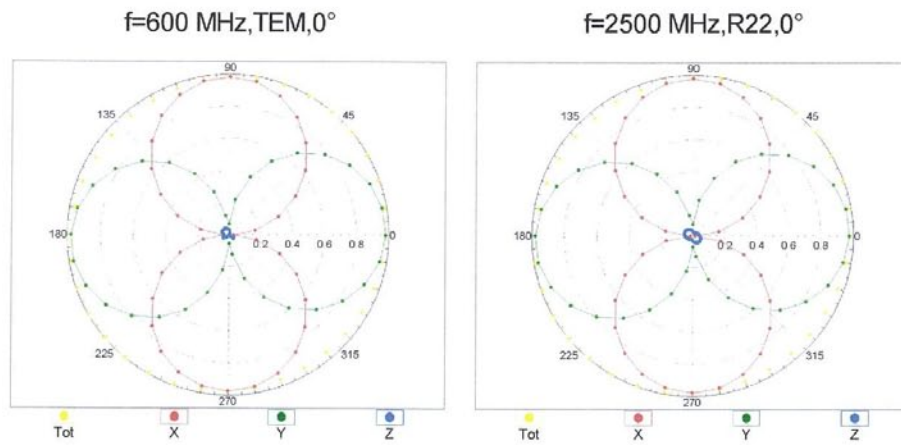


Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ (k=2)

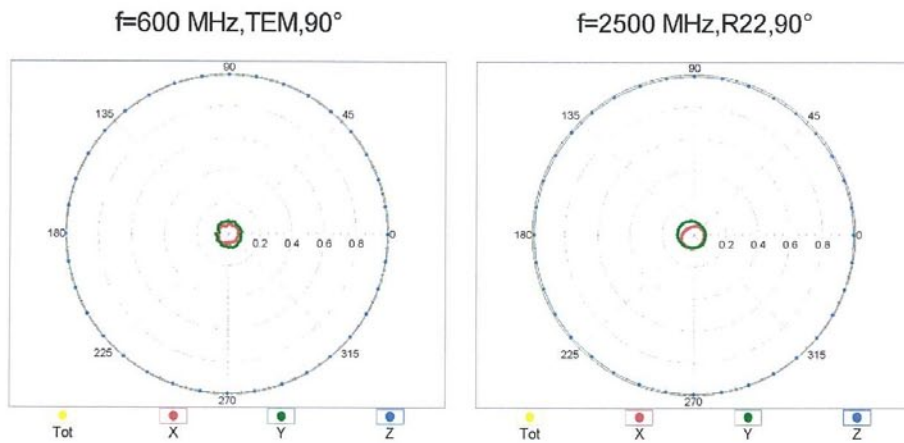
ER3DV6- SN:2262

January 9, 2012

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



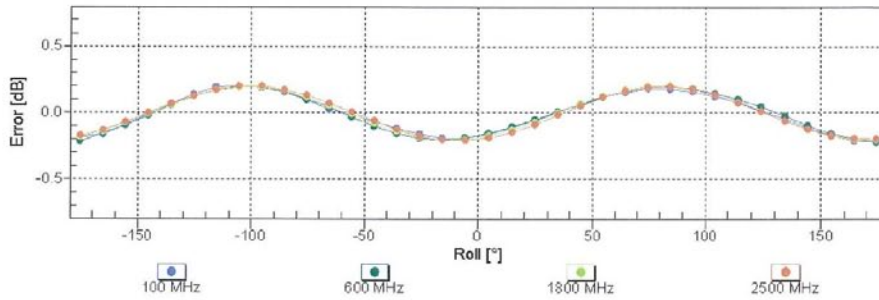
Receiving Pattern (ϕ), $\vartheta = 90^\circ$



ER3DV6-SN:2262

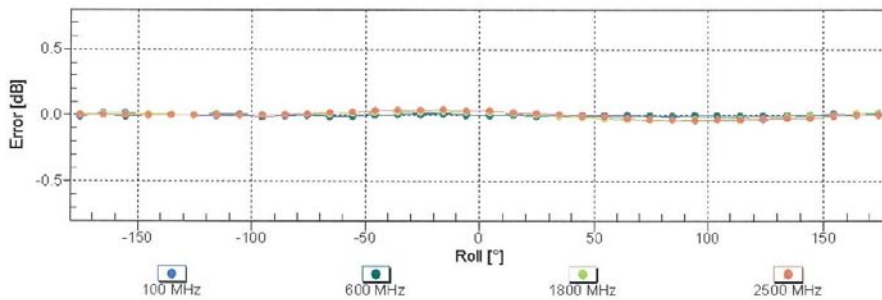
January 9, 2012

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\vartheta = 90^\circ$

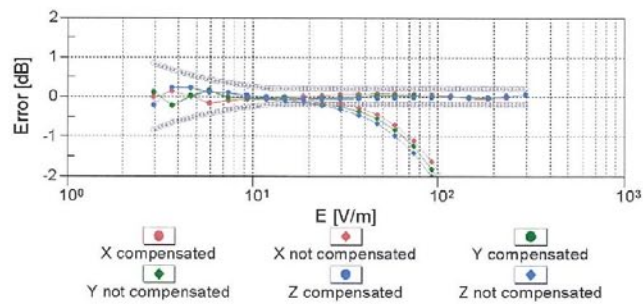
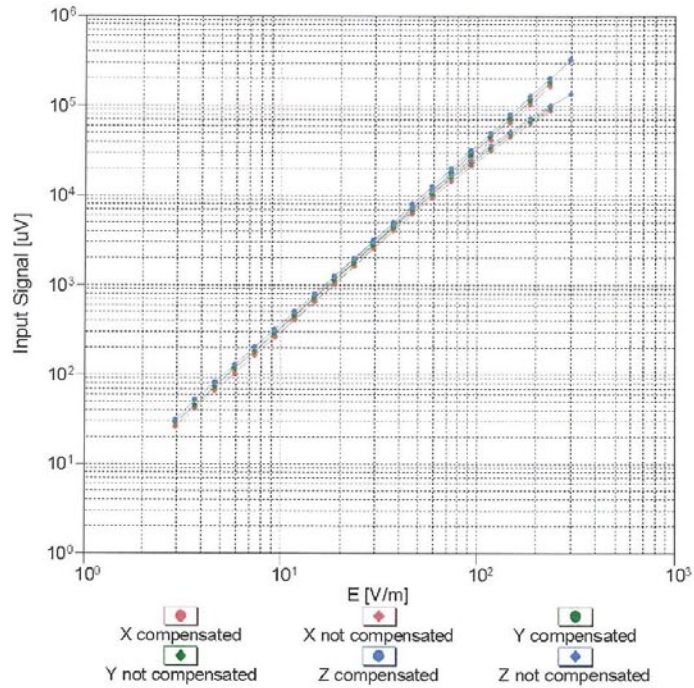


Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

ER3DV6– SN:2262

January 9, 2012

Dynamic Range f(E-field) (TEM cell , f = 900 MHz)

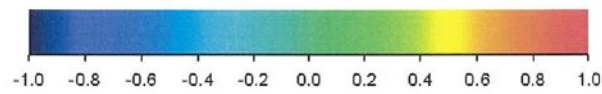
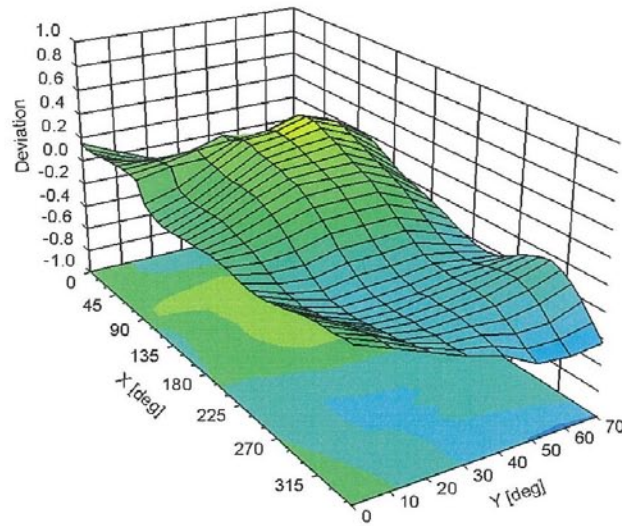


Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

ER3DV6-SN:2262

January 9, 2012

Deviation from Isotropy in Air Error (ϕ , θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

ER3DV6- SN:2262

January 9, 2012

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2262**Other Probe Parameters**

| | |
|---|-------------|
| Sensor Arrangement | Rectangular |
| Connector Angle (°) | 34.4 |
| Mechanical Surface Detection Mode | enabled |
| Optical Surface Detection Mode | disabled |
| Probe Overall Length | 337 mm |
| Probe Body Diameter | 10 mm |
| Tip Length | 10 mm |
| Tip Diameter | 8 mm |
| Probe Tip to Sensor X Calibration Point | 2.5 mm |
| Probe Tip to Sensor Y Calibration Point | 2.5 mm |
| Probe Tip to Sensor Z Calibration Point | 2.5 mm |

3 Calibration report "Probe H3DV6"

Calibration Laboratory of
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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client **Cetecom**

Certificate No: H3-6086_Jan12

CALIBRATION CERTIFICATE

Object **H3DV6 - SN:6086**

Calibration procedure(s) **QA CAL-03.v6, QA CAL-25.v4
Calibration procedure for H-field probes optimized for close near field
evaluations in air**

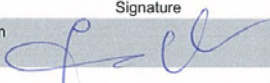

Calibration date: **January 14, 2012**

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All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID | Cal Date (Certificate No.) | Scheduled Calibration |
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| Reference 3 dB Attenuator | SN: S5054 (3c) | 29-Mar-11 (No. 217-01369) | Apr-12 |
| Reference 20 dB Attenuator | SN: S5086 (20b) | 29-Mar-11 (No. 217-01367) | Apr-12 |
| Reference 30 dB Attenuator | SN: S5129 (30b) | 29-Mar-11 (No. 217-01370) | Apr-12 |
| Reference Probe H3DV6 | SN: 6182 | 11-Oct-11 (No. H3-6182_Oct11) | Oct-12 |
| DAE4 | SN: 789 | 6-Apr-11 (No. DAE4-789_Apr11) | Apr-12 |
| Secondary Standards | ID | Check Date (in house) | Scheduled Check |
| RF generator HP 8648C | US3642U01700 | 4-Aug-99 (in house check Apr-11) | In house check: Apr-13 |
| Network Analyzer HP 8753E | US37390585 | 18-Oct-01 (in house check Oct-11) | In house check: Oct-12 |

| | Name | Function | Signature |
|----------------|----------------|-----------------------|--|
| Calibrated by: | Jeton Kastrati | Laboratory Technician |  |
| Approved by: | Katja Pokovic | Technical Manager |  |

Issued: January 17, 2012

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Accreditation No.: **SCS 108**

Glossary:

| | |
|--------------------------|---|
| NORM _{x,y,z} | sensitivity in free space |
| DCP | diode compression point |
| CF | crest factor (1/duty_cycle) of the RF signal |
| A, B, C | modulation dependent linearization parameters |
| Polarization φ | φ rotation around probe axis |
| Polarization ϑ | ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis |
| Connector Angle | information used in DASY system to align probe sensor X to the robot coordinate system |

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- *NORM_{x,y,z}*: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- *X, Y, Z(f)_a0a1a2 = X, Y, Z_a0a1a2* frequency_response* (see Frequency Response Chart).
- *DCP_{x,y,z}*: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *PAR*: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- *A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}; A, B, C* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle*: The angle is assessed using the information gained by determining the *X_a0a1a2* (no uncertainty required).

H3DV6 – SN:6086

January 14, 2012

Probe H3DV6

SN:6086

Manufactured: June 1, 2001
Calibrated: January 14, 2012

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

H3DV6– SN:6086

January 14, 2012

DASY/EASY - Parameters of Probe: H3DV6 - SN:6086

Basic Calibration Parameters

| | | Sensor X | Sensor Y | Sensor Z | Unc (k=2) |
|----------------------------------|----|------------|------------|------------|--------------|
| Norm (A/m / $\sqrt{\text{mV}}$) | a0 | 2.92E-003 | 2.77E-003 | 3.01E-003 | $\pm 5.1 \%$ |
| Norm (A/m / $\sqrt{\text{mV}}$) | a1 | -1.03E-004 | -1.08E-004 | -2.84E-004 | $\pm 5.1 \%$ |
| Norm (A/m / $\sqrt{\text{mV}}$) | a2 | -3.36E-005 | -1.31E-005 | -3.75E-006 | $\pm 5.1 \%$ |
| DGP (mV) ^B | | 89.7 | 91.7 | 92.2 | |

Modulation Calibration Parameters

| UID | Communication System Name | PAR | | A dB | B dB | C dB | VR mV | Unc ^E (k=2) |
|-------|---------------------------|------|---|---------|---------|---------|----------|---------------------------|
| 10000 | CW | 0.00 | X | 0.00 | 0.00 | 1.00 | 88.2 | $\pm 2.2 \%$ |
| | | | Y | 0.00 | 0.00 | 1.00 | 94.1 | |
| | | | Z | 0.00 | 0.00 | 1.00 | 103.0 | |

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

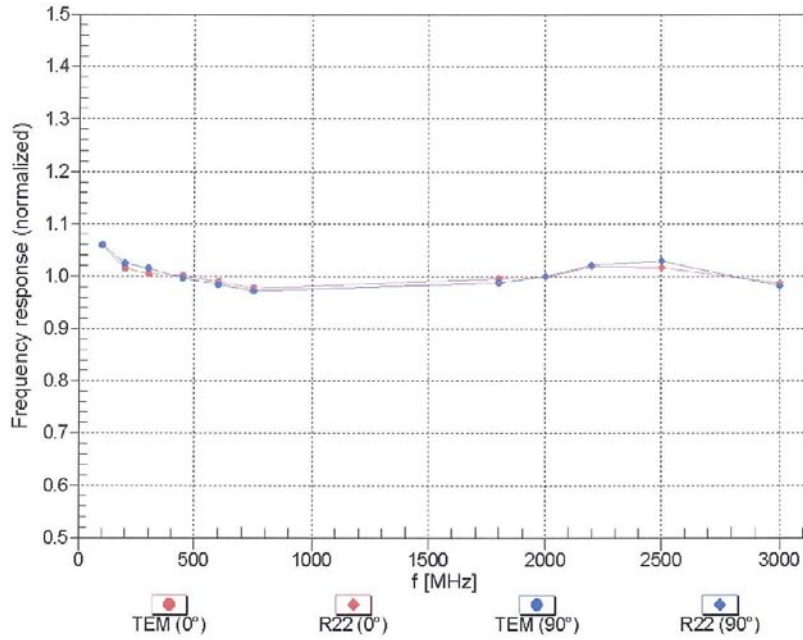
^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

H3DV6-SN:6086

January 14, 2012

Frequency Response of H-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)

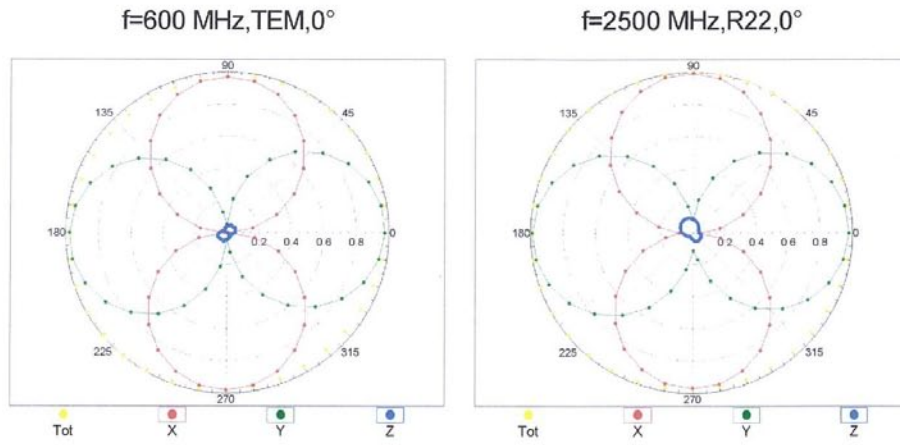


Uncertainty of Frequency Response of H-field: $\pm 6.3\%$ (k=2)

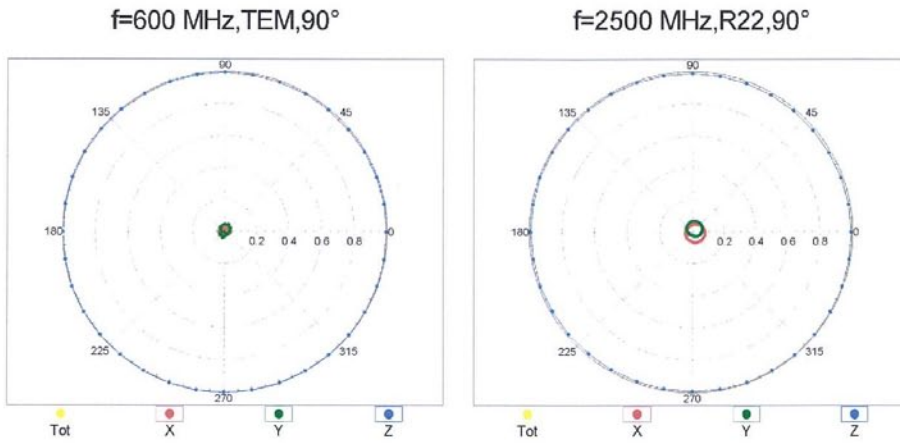
H3DV6- SN:6086

January 14, 2012

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



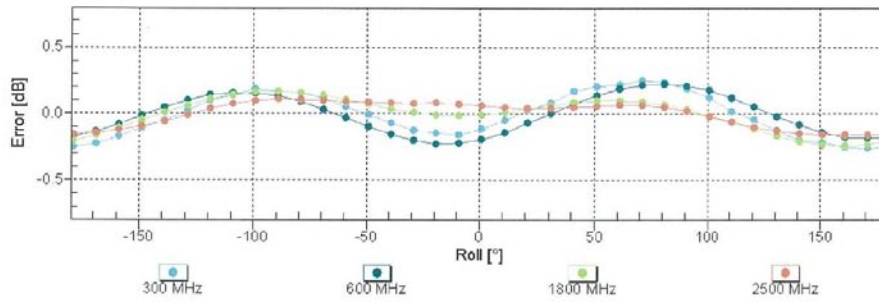
Receiving Pattern (ϕ), $\vartheta = 90^\circ$



H3DV6– SN:6086

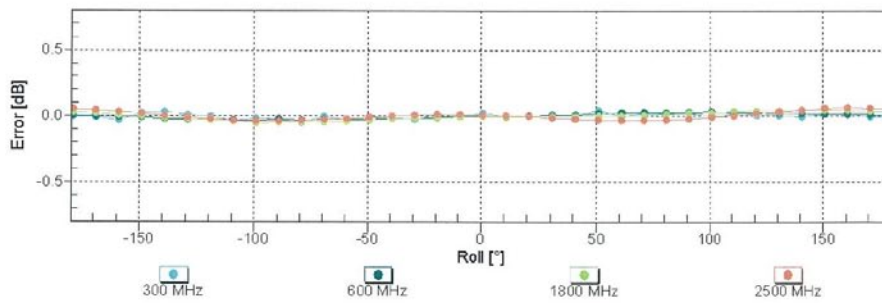
January 14, 2012

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\vartheta = 90^\circ$

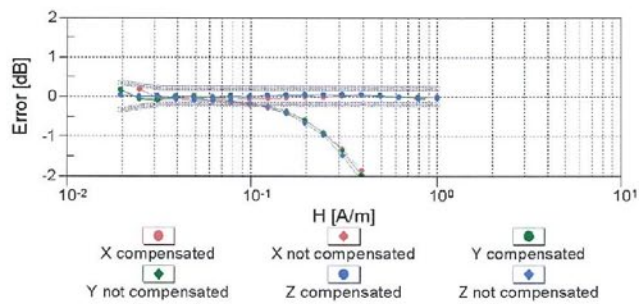
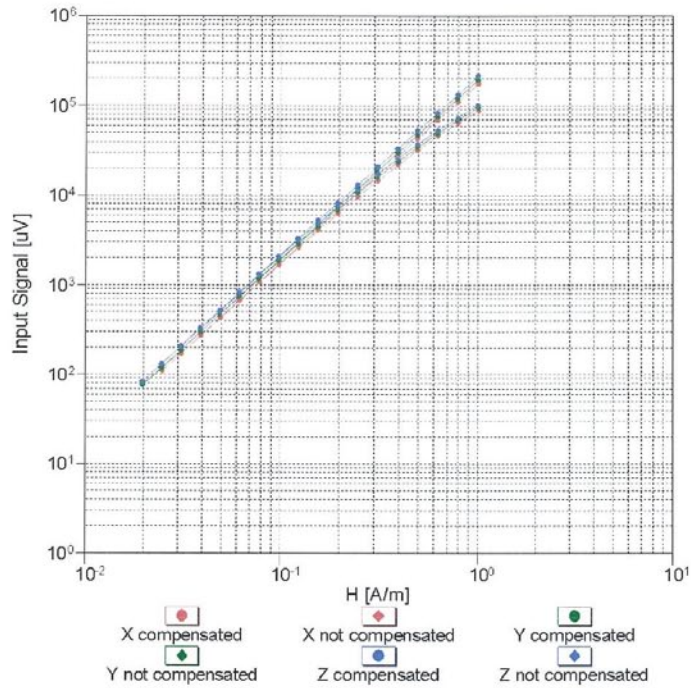


Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

H3DV6– SN:6086

January 14, 2012

Dynamic Range f(H-field) (TEM cell, f = 900 MHz)

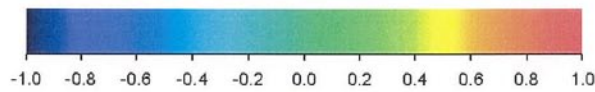
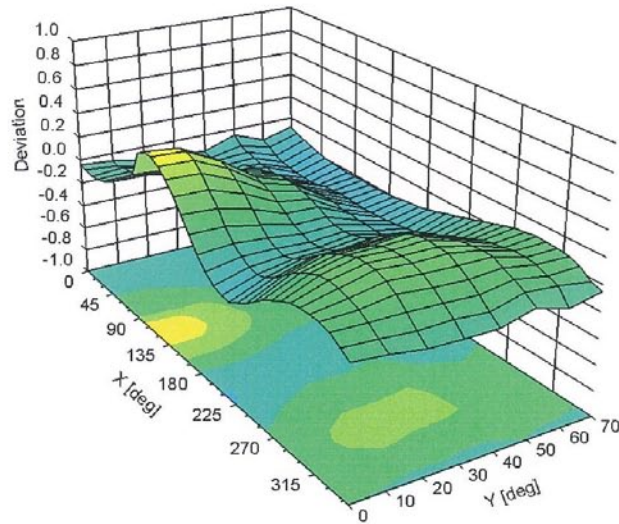


Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

H3DV6- SN:6086

January 14, 2012

Deviation from Isotropy in Air Error (ϕ , θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

H3DV6- SN:6086

January 14, 2012

DASY/EASY - Parameters of Probe: H3DV6 - SN:6086**Other Probe Parameters**

| | |
|---|-------------|
| Sensor Arrangement | Rectangular |
| Connector Angle (°) | -149.1 |
| Mechanical Surface Detection Mode | enabled |
| Optical Surface Detection Mode | disabled |
| Probe Overall Length | 337 mm |
| Probe Body Diameter | 10 mm |
| Tip Length | 20 mm |
| Tip Diameter | 6 mm |
| Probe Tip to Sensor X Calibration Point | 3 mm |
| Probe Tip to Sensor Y Calibration Point | 3 mm |
| Probe Tip to Sensor Z Calibration Point | 3 mm |

4 Calibration report "835 MHz HAC System validation dipole"

**Calibration Laboratory of
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Accreditation No.: **SCS 108**

Client **Cetecom**

Certificate No: **CD835V3-1027_May12**

CALIBRATION CERTIFICATE

Object **CD835V3 - SN: 1027**

Calibration procedure(s) **QA CAL-20.v6
Calibration procedure for dipoles in air**

Calibration date: **May 08, 2012**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID # | Cal Date (Certificate No.) | Scheduled Calibration |
|---------------------------|----------------|-----------------------------------|------------------------|
| Power meter EPM-442A | GB37480704 | 05-Oct-11 (No. 217-01451) | Oct-12 |
| Power sensor HP 8481A | US37292783 | 05-Oct-11 (No. 217-01451) | Oct-12 |
| Probe ER3DV6 | SN: 2336 | 29-Dec-11 (No. ER3-2336_Dec11) | Dec-12 |
| Probe H3DV6 | SN: 6065 | 29-Dec-11 (No. H3-6065_Dec11) | Dec-12 |
| DAE4 | SN: 781 | 25-Apr-12 (No. DAE4-781_Apr12) | Apr-13 |
| Secondary Standards | ID # | Check Date (in house) | Scheduled Check |
| Power meter Agilent 4419B | SN: GB42420191 | 09-Oct-09 (in house check Oct-11) | In house check: Oct-12 |
| Power sensor HP 8482H | SN: 3318A09450 | 09-Oct-09 (in house check Oct-11) | In house check: Oct-12 |
| Power sensor HP 8482A | SN: US37295597 | 09-Oct-09 (in house check Oct-11) | In house check: Oct-12 |
| Network Analyzer HP 8753E | US37390585 | 18-Oct-01 (in house check Oct-11) | In house check: Oct-12 |
| RF generator E4433B | MY 41000675 | 03-Nov-04 (in house check Oct-11) | In house check: Oct-13 |

Calibrated by: **Claudio Leubler** **Laboratory Technician**

Approved by: **Fin Bomholt** **R&D Director**

Issued: May 9, 2012

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C Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

References

- [1] ANSI-C63.19-2007
American National Standard for Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.
- [2] ANSI-C63.19-2011
American National Standard, Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.

Methods Applied and Interpretation of Parameters:

- **Coordinate System:** y-axis is in the direction of the dipole arms. z-axis is from the basis of the antenna (mounted on the table) towards its feed point between the two dipole arms. x-axis is normal to the other axes. In coincidence with the standards [1], the measurement planes (probe sensor center) are selected to be at a distance of 10 mm (15 mm for [2]) above the top metal edge of the dipole arms.
- **Measurement Conditions:** Further details are available from the hardcopies at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated. The forward power to the dipole connector is set with a calibrated power meter connected and monitored with an auxiliary power meter connected to a directional coupler. While the dipole under test is connected, the forward power is adjusted to the same level.
- **Antenna Positioning:** The dipole is mounted on a HAC Test Arch phantom using the matching dipole positioner with the arms horizontal and the feeding cable coming from the floor. The measurements are performed in a shielded room with absorbers around the setup to reduce the reflections. It is verified before the mounting of the dipole under the Test Arch phantom, that its arms are perfectly in a line. It is installed on the HAC dipole positioner with its arms parallel below the dielectric reference wire and able to move elastically in vertical direction without changing its relative position to the top center of the Test Arch phantom. The vertical distance to the probe is adjusted after dipole mounting with a DASY5 Surface Check job. Before the measurement, the distance between phantom surface and probe tip is verified. The proper measurement distance is selected by choosing the matching section of the HAC Test Arch phantom with the proper device reference point (upper surface of the dipole) and the matching grid reference point (tip of the probe) considering the probe sensor offset. The vertical distance to the probe is essential for the accuracy.
- **Feed Point Impedance and Return Loss:** These parameters are measured using a HP 8753E Vector Network Analyzer. The impedance is specified at the SMA connector of the dipole. The influence of reflections was eliminated by applying the averaging function while moving the dipole in the air, at least 70cm away from any obstacles.
- **E-field distribution:** E field is measured in the x-y-plane with an isotropic ER3D-field probe with 100 mW forward power to the antenna feed point. In accordance with [1] and [2], the scan area is 20mm wide, its length exceeds the dipole arm length (180 or 90mm). The sensor center is 10 mm (15 mm for [2]) (in z) above the metal top of the dipole arms. Two 3D maxima are available near the end of the dipole arms. Assuming the dipole arms are perfectly in one line, the average of these two maxima (in subgrid 2 and subgrid 8) is determined to compensate for any non-parallelity to the measurement plane as well as the sensor displacement. The E-field value stated as calibration value represents the maximum of the interpolated 3D-E-field, in the plane above the dipole surface.
- **H-field distribution:** H-field is measured with an isotropic H-field probe with 100mW forward power to the antenna feed point, in the x-y-plane. The scan area and sensor distance is equivalent to the E-field scan. The maximum of the field is available at the center (subgrid 5) above the feed point. The H-field value stated as calibration value represents the maximum of the interpolated H-field, 10mm above the dipole surface at the feed point.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Measurement Conditions

DASY system configuration, as far as not given on page 1.

| | | |
|---|------------------------|---------|
| DASY Version | DASY5 | V52.8.1 |
| Extrapolation | Advanced Extrapolation | |
| Phantom | HAC Test Arch | |
| Distance Dipole Top - Probe Center | 10mm 15mm | |
| Scan resolution | dx, dy = 5 mm | |
| Frequency | 835 MHz \pm 1 MHz | |
| Input power drift | < 0.05 dB | |

Maximum Field values at 835 MHz

| H-field 10 mm above dipole surface | condition | interpolated maximum |
|---|--------------------|---|
| Maximum measured | 100 mW input power | 0.458 A / m \pm 8.2 % (k=2) |

| E-field 10 mm above dipole surface | condition | Interpolated maximum |
|---|--------------------|--|
| Maximum measured above high end | 100 mW input power | 169.2 V / m |
| Maximum measured above low end | 100 mW input power | 162.4 V / m |
| Averaged maximum above arm | 100 mW input power | 165.8 V / m \pm 12.8 % (k=2) |

| E-field 15 mm above dipole surface | condition | Interpolated maximum |
|---|--------------------|--|
| Maximum measured above high end | 100 mW input power | 108.4 V / m |
| Maximum measured above low end | 100 mW input power | 106.0 V / m |
| Averaged maximum above arm | 100 mW input power | 107.2 V / m \pm 12.8 % (k=2) |

Appendix

Antenna Parameters

| Frequency | Return Loss | Impedance |
|-----------|-------------|---------------------------------|
| 800 MHz | 16.0 dB | 41.9 Ω - 12.3 j Ω |
| 835 MHz | 23.9 dB | 49.1 Ω + 6.3 j Ω |
| 900 MHz | 17.7 dB | 58.4 Ω - 11.4 j Ω |
| 950 MHz | 18.0 dB | 50.0 Ω + 12.7 j Ω |
| 960 MHz | 13.4 dB | 58.7 Ω + 22.1 j Ω |

3.2 Antenna Design and Handling

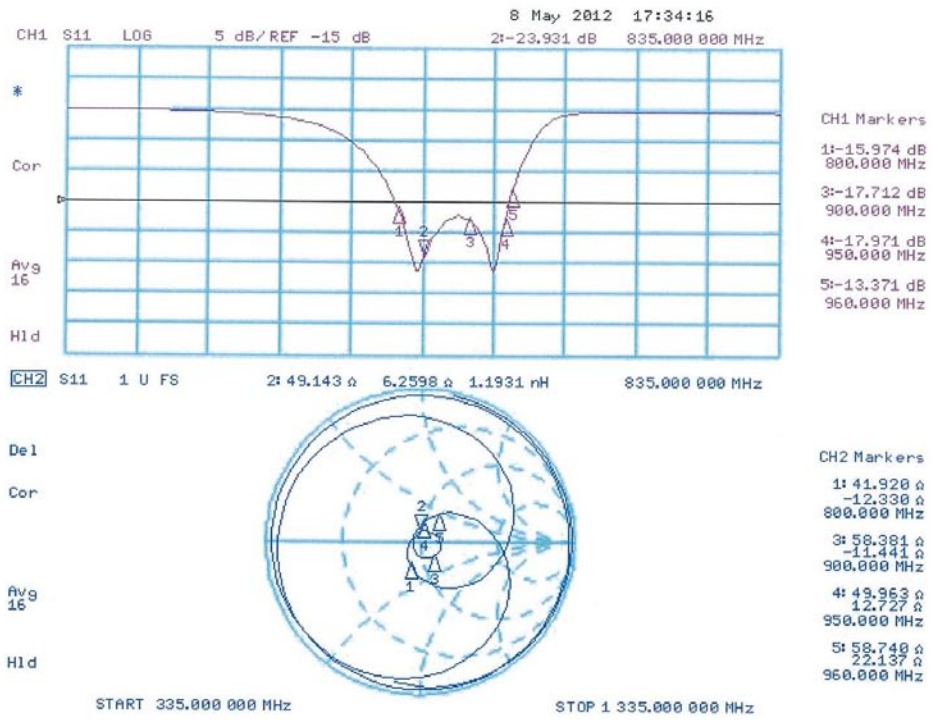
The calibration dipole has a symmetric geometry with a built-in two stub matching network, which leads to the enhanced bandwidth.

The dipole is built of standard semirigid coaxial cable. The internal matching line is open ended. The antenna is therefore open for DC signals.

Do not apply force to dipole arms, as they are liable to bend. The soldered connections near the feedpoint may be damaged. After excessive mechanical stress or overheating, check the impedance characteristics to ensure that the internal matching network is not affected.

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

Impedance Measurement Plot



DASY4 H-field Result

Date: 08.05.2012

Test Laboratory: SPEAG Lab2

DUT: HAC-Dipole 835 MHz; Type: CD835V3; Serial: CD835V3 - SN: 1027

Communication System: CW; Frequency: 835 MHz
 Medium parameters used: $\sigma = 0$ mho/m, $\epsilon_r = 1$; $\rho = 1$ kg/m³
 Phantom section: RF Section
 Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY52 Configuration:

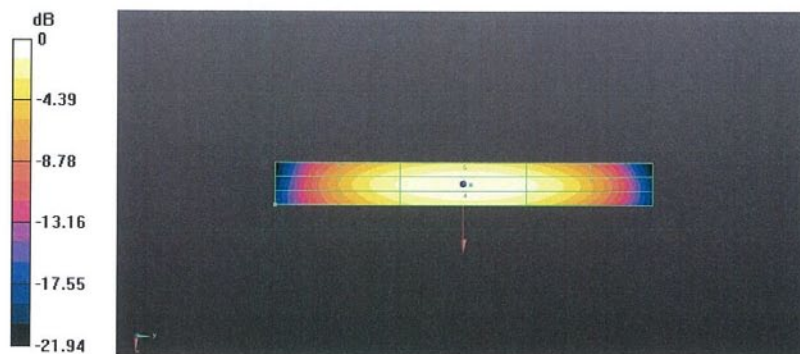
- Probe: H3DV6 - SN6065; ; Calibrated: 29.12.2011
- Sensor-Surface: (Fix Surface)
- Electronics: DAE4 Sn781; Calibrated: 25.04.2012
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA; Serial: 1070
- DASY52 52.8.1(838); SEMCAD X 14.6.5(6469)

Dipole H-Field measurement @ 835MHz/H-Scan - 835MHz d=10mm/Hearing Aid Compatibility Test (41x361x1):

Measurement grid: dx=5mm, dy=5mm
 Device Reference Point: 0, 0, -6.3 mm
 Reference Value = 0.4870 A/m; Power Drift = 0.00 dB
 PMR not calibrated. PMF = 1.000 is applied.
 H-field emissions = 0.4580 A/m
Near-field category: M4 (AWF 0 dB)

PMF scaled H-field

| | | |
|-----------|-----------|-----------|
| Grid 1 M4 | Grid 2 M4 | Grid 3 M4 |
| 0.380 A/m | 0.396 A/m | 0.372 A/m |
| Grid 4 M4 | Grid 5 M4 | Grid 6 M4 |
| 0.440 A/m | 0.458 A/m | 0.429 A/m |
| Grid 7 M4 | Grid 8 M4 | Grid 9 M4 |
| 0.396 A/m | 0.412 A/m | 0.381 A/m |



0 dB = 0.458 A/m = -6.78 dB A/m

5 Calibration report "1880 MHz HAC System validation dipole"

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: SCS 108

Client **Cetecom**

Certificate No: CD1880V3-1021_May12

CALIBRATION CERTIFICATE

Object CD1880V3 - SN: 1021

Calibration procedure(s) QA CAL-20.v6
Calibration procedure for dipoles in air

Calibration date: May 08, 2012


This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID # | Cal Date (Certificate No.) | Scheduled Calibration |
|---------------------------|----------------|-----------------------------------|------------------------|
| Power meter EPM-442A | GB37480704 | 05-Oct-11 (No. 217-01451) | Oct-12 |
| Power sensor HP 8481A | US37292783 | 05-Oct-11 (No. 217-01451) | Oct-12 |
| Probe ER3DV6 | SN: 2336 | 29-Dec-11 (No. ER3-2336_Dec11) | Dec-12 |
| Probe H3DV6 | SN: 6065 | 29-Dec-11 (No. H3-6065_Dec11) | Dec-12 |
| DAE4 | SN: 781 | 25-Apr-12 (No. DAE4-781_Apr12) | Apr-13 |
| Secondary Standards | ID # | Check Date (in house) | Scheduled Check |
| Power meter Agilent 4419B | SN: GB42420191 | 09-Oct-09 (in house check Oct-11) | In house check: Oct-12 |
| Power sensor HP 8482H | SN: 3318A09450 | 09-Oct-09 (in house check Oct-11) | In house check: Oct-12 |
| Power sensor HP 8482A | SN: US37295597 | 09-Oct-09 (in house check Oct-11) | In house check: Oct-12 |
| Network Analyzer HP 8753E | US37390585 | 18-Oct-01 (in house check Oct-11) | In house check: Oct-12 |
| RF generator E4433B | MY 41000675 | 03-Nov-04 (in house check Oct-11) | In house check: Oct-13 |

Calibrated by: Name Claudio Leubler Function Laboratory Technician Signature 

Approved by: Name Fin Bomholt Function R&D Director Signature 

Issued: May 9, 2012

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: **SCS 108**

References

- [1] ANSI-C63.19-2007
American National Standard for Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.
- [2] ANSI-C63.19-2011
American National Standard, Methods of Measurement of Compatibility between Wireless Communications Devices and Hearing Aids.

Methods Applied and Interpretation of Parameters:

- *Coordinate System:* y-axis is in the direction of the dipole arms. z-axis is from the basis of the antenna (mounted on the table) towards its feed point between the two dipole arms. x-axis is normal to the other axes. In coincidence with the standards [1], the measurement planes (probe sensor center) are selected to be at a distance of 10 mm (15 mm for [2]) above the top metal edge of the dipole arms.
- *Measurement Conditions:* Further details are available from the hardcopies at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated. The forward power to the dipole connector is set with a calibrated power meter connected and monitored with an auxiliary power meter connected to a directional coupler. While the dipole under test is connected, the forward power is adjusted to the same level.
- *Antenna Positioning:* The dipole is mounted on a HAC Test Arch phantom using the matching dipole positioner with the arms horizontal and the feeding cable coming from the floor. The measurements are performed in a shielded room with absorbers around the setup to reduce the reflections. It is verified before the mounting of the dipole under the Test Arch phantom, that its arms are perfectly in a line. It is installed on the HAC dipole positioner with its arms parallel below the dielectric reference wire and able to move elastically in vertical direction without changing its relative position to the top center of the Test Arch phantom. The vertical distance to the probe is adjusted after dipole mounting with a DASY5 Surface Check job. Before the measurement, the distance between phantom surface and probe tip is verified. The proper measurement distance is selected by choosing the matching section of the HAC Test Arch phantom with the proper device reference point (upper surface of the dipole) and the matching grid reference point (tip of the probe) considering the probe sensor offset. The vertical distance to the probe is essential for the accuracy.
- *Feed Point Impedance and Return Loss:* These parameters are measured using a HP 8753E Vector Network Analyzer. The impedance is specified at the SMA connector of the dipole. The influence of reflections was eliminated by applying the averaging function while moving the dipole in the air, at least 70cm away from any obstacles.
- *E-field distribution:* E field is measured in the x-y-plane with an isotropic ER3D-field probe with 100 mW forward power to the antenna feed point. In accordance with [1] and [2], the scan area is 20mm wide, its length exceeds the dipole arm length (180 or 90mm). The sensor center is 10 mm (15 mm for [2]) (in z) above the metal top of the dipole arms. Two 3D maxima are available near the end of the dipole arms. Assuming the dipole arms are perfectly in one line, the average of these two maxima (in subgrid 2 and subgrid 8) is determined to compensate for any non-parallelity to the measurement plane as well as the sensor displacement. The E-field value stated as calibration value represents the maximum of the interpolated 3D-E-field, in the plane above the dipole surface.
- *H-field distribution:* H-field is measured with an isotropic H-field probe with 100mW forward power to the antenna feed point, in the x-y-plane. The scan area and sensor distance is equivalent to the E-field scan. The maximum of the field is available at the center (subgrid 5) above the feed point. The H-field value stated as calibration value represents the maximum of the interpolated H-field, 10mm above the dipole surface at the feed point.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Measurement Conditions

DASY system configuration, as far as not given on page 1.

| | | |
|---|--|---------|
| DASY Version | DASY5 | V52.8.1 |
| Extrapolation | Advanced Extrapolation | |
| Phantom | HAC Test Arch | |
| Distance Dipole Top - Probe Center | 10mm 15mm | |
| Scan resolution | dx, dy = 5 mm | |
| Frequency | 1730 MHz \pm 1 MHz 1880 MHz \pm 1 MHz | |
| Input power drift | < 0.05 dB | |

Maximum Field values at 1730 MHz

| H-field 10 mm above dipole surface | condition | interpolated maximum |
|------------------------------------|--------------------|-------------------------------|
| Maximum measured | 100 mW input power | 0.487 A / m \pm 8.2 % (k=2) |

| E-field 10 mm above dipole surface | condition | Interpolated maximum |
|------------------------------------|--------------------|--------------------------------|
| Maximum measured above high end | 100 mW input power | 155.9 V / m |
| Maximum measured above low end | 100 mW input power | 149.2 V / m |
| Averaged maximum above arm | 100 mW input power | 152.6 V / m \pm 12.8 % (k=2) |

| E-field 15 mm above dipole surface | condition | Interpolated maximum |
|------------------------------------|--------------------|-------------------------------|
| Maximum measured above high end | 100 mW input power | 97.4 V / m |
| Maximum measured above low end | 100 mW input power | 96.9 V / m |
| Averaged maximum above arm | 100 mW input power | 97.2 V / m \pm 12.8 % (k=2) |

Maximum Field values at 1880 MHz

| H-field 10 mm above dipole surface | condition | interpolated maximum |
|------------------------------------|--------------------|-------------------------------|
| Maximum measured | 100 mW input power | 0.459 A / m \pm 8.2 % (k=2) |

| E-field 10 mm above dipole surface | condition | Interpolated maximum |
|------------------------------------|--------------------|--------------------------------|
| Maximum measured above high end | 100 mW input power | 139.8 V / m |
| Maximum measured above low end | 100 mW input power | 139.7 V / m |
| Averaged maximum above arm | 100 mW input power | 139.8 V / m \pm 12.8 % (k=2) |

| E-field 15 mm above dipole surface | condition | Interpolated maximum |
|------------------------------------|--------------------|-------------------------------|
| Maximum measured above high end | 100 mW input power | 91.0 V / m |
| Maximum measured above low end | 100 mW input power | 87.6 V / m |
| Averaged maximum above arm | 100 mW input power | 89.3 V / m \pm 12.8 % (k=2) |

Appendix

Antenna Parameters

Nominal Frequencies

| Frequency | Return Loss | Impedance |
|-----------|-------------|-------------------------------|
| 1730 MHz | 31.3 dB | 52.8 Ω + 0.1 $j\Omega$ |
| 1880 MHz | 19.8 dB | 47.9 Ω + 9.8 $j\Omega$ |
| 1900 MHz | 20.9 dB | 50.4 Ω + 9.1 $j\Omega$ |
| 1950 MHz | 26.4 dB | 52.2 Ω + 4.4 $j\Omega$ |
| 2000 MHz | 20.2 dB | 43.8 Ω + 6.7 $j\Omega$ |

3.2 Antenna Design and Handling

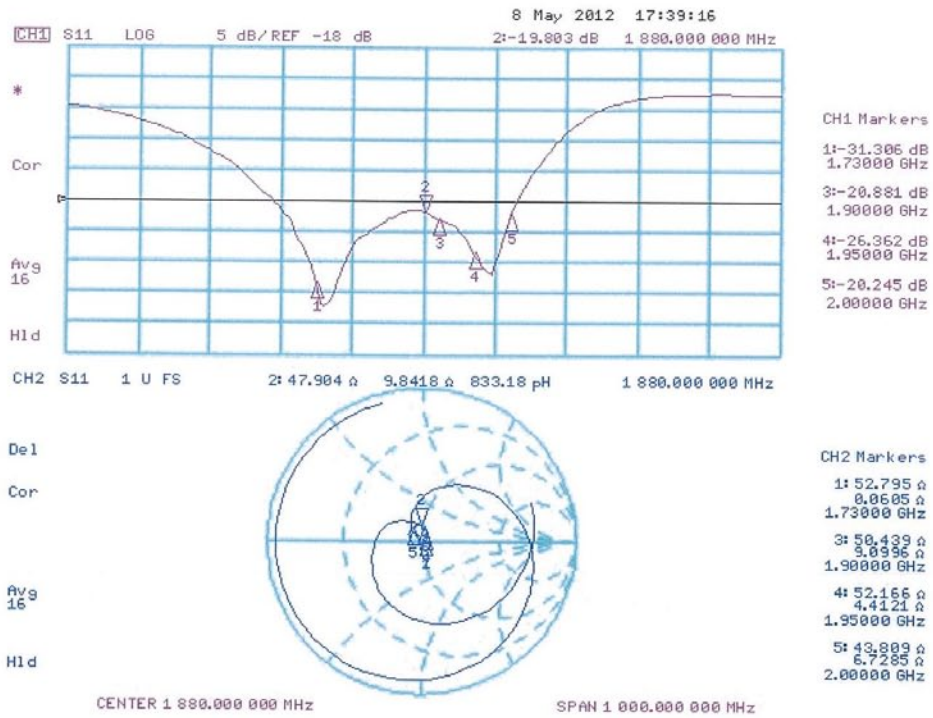
The calibration dipole has a symmetric geometry with a built-in two stub matching network, which leads to the enhanced bandwidth.

The dipole is built of standard semirigid coaxial cable. The internal matching line is open ended. The antenna is therefore open for DC signals.

Do not apply force to dipole arms, as they are liable to bend. The soldered connections near the feedpoint may be damaged. After excessive mechanical stress or overheating, check the impedance characteristics to ensure that the internal matching network is not affected.

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

Impedance Measurement Plot



DASY5 H-field Result

Date: 08.05.2012

Test Laboratory: SPEAG Lab2

DUT: HAC Dipole 1880 MHz; Type: CD1880V3; Serial: CD1880V3 - SN: 1021

Communication System: CW; Frequency: 1880 MHz, Frequency: 1730 MHz
 Medium parameters used: $\sigma = 0$ mho/m, $\epsilon_r = 1$; $\rho = 1$ kg/m³
 Phantom section: RF Section
 Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY52 Configuration:

- Probe: H3DV6 - SN6065; ; Calibrated: 29.12.2011
- Sensor-Surface: (Fix Surface)
- Electronics: DAE4 Sn781; Calibrated: 25.04.2012
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA; Serial: 1070
- DASY52 52.8.1(838); SEMCAD X 14.6.5(6469)

Dipole H-Field measurement @ 1880MHz/H-Scan - 1880MHz d=10mm/Hearing Aid Compatibility Test (41x181x1):

Measurement grid: dx=5mm, dy=5mm

Device Reference Point: 0, 0, -6.3 mm

Reference Value = 0.4850 A/m; Power Drift = 0.02 dB

PMR not calibrated. PMF = 1.000 is applied.

H-field emissions = 0.4591 A/m

Near-field category: M2 (AWF 0 dB)

PMF scaled H-field

| | | |
|-----------|-----------|-----------|
| Grid 1 M2 | Grid 2 M2 | Grid 3 M2 |
| 0.402 A/m | 0.416 A/m | 0.393 A/m |
| Grid 4 M2 | Grid 5 M2 | Grid 6 M2 |
| 0.443 A/m | 0.459 A/m | 0.433 A/m |
| Grid 7 M2 | Grid 8 M2 | Grid 9 M2 |
| 0.405 A/m | 0.423 A/m | 0.397 A/m |

6 Calibration certificate of Data Acquisition Unit (DAE)

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland



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C Service suisse d'étalonnage
S Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client **Cetecom**

Certificate No: DAE3-413_Jan12

CALIBRATION CERTIFICATE

Object **DAE3 - SD 000 D03 AA - SN: 413**

Calibration procedure(s) **QA CAL-06.v24
Calibration procedure for the data acquisition electronics (DAE)**


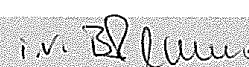
Calibration date: **January 12, 2012**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^\circ\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

| Primary Standards | ID # | Cal Date (Certificate No.) | Scheduled Calibration |
|-------------------------------|--------------------|----------------------------|------------------------|
| Keithley Multimeter Type 2001 | SN: 0810278 | 28-Sep-11 (No:11450) | Sep-12 |
| Secondary Standards | ID # | Check Date (in house) | Scheduled Check |
| Calibrator Box V2.1 | SE UWS 053 AA 1001 | 05-Jan-12 (in house check) | In house check: Jan-13 |

| | Name | Function | Signature |
|----------------|-------------------|--------------|---|
| Calibrated by: | Dominique Steffen | Technician |  |
| Approved by: | Fin Bomholt | R&D Director |  |

Issued: January 13, 2012

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

7 Certificate of "SAM Twin Phantom V4.0/V4.0C"

Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland, Phone +41 1 245 97 00, Fax +41 1 245 97 79

Certificate of conformity / First Article Inspection

| | |
|-----------------------|--|
| Item | SAM Twin Phantom V4.0 |
| Type No | QD 000 P40 BA |
| Series No | TP-1002 and higher |
| Manufacturer / Origin | Untersee Composites Hauptstr. 69 CH-8559 Fruthwilen Switzerland |

Tests

The series production process used allows the limitation to test of first articles. Complete tests were made on the pre-series Type No. QD 000 P40 AA, Serial No. TP-1001 and on the series first article Type No. QD 000 P40 BA, Serial No. TP-1006. Certain parameters have been retested using further series units (called samples).

| Test | Requirement | Details | Units tested |
|----------------------|---|--|-----------------------------|
| Shape | Compliance with the geometry according to the CAD model. | IT'IS CAD File (*) | First article, Samples |
| Material thickness | Compliant with the requirements according to the standards | 2mm +/- 0.2mm in specific areas | First article, Samples |
| Material parameters | Dielectric parameters for required frequencies | 200 MHz – 3 GHz Relative permittivity < 5 Loss tangent < 0.05. | Material sample TP 104-5 |
| Material resistivity | The material has been tested to be compatible with the liquids defined in the standards | Liquid type HSL 1800 and others according to the standard. | Pre-series, First article |

Standards

- [1] CENELEC EN 50361
- [2] IEEE P1528-200x draft 6.5
- [3] IEC PT 62209 draft 0.9
- (*) The IT'IS CAD file is derived from [2] and is also within the tolerance requirements of the shapes of [1] and [3].

Conformity

Based on the sample tests above, we certify that this item is in compliance with the uncertainty requirements of SAR measurements specified in standard [1] and draft standards [2] and [3].

Date 18.11.2001

Signature / Stamp  Schmid & Partner Engineering AG 
 Zeughausstrasse 43, CH-8004 Zurich
 Tel. +41 1 245 97 00, Fax +41 1 245 97 79

8 Application Note System Performance Check

8.1 Purpose of system performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check is performed prior to any usage of the system in order to guarantee reproducible results.

The measurement of the Specific Absorption Rate (SAR) is a complicated task and the result depends on the proper functioning of many components and the correct settings of many parameters. Faulty results due to drift, failures or incorrect parameters might not be recognized, since they often look similar in distribution to the correct ones. The Dosimetric Assessment System DASY4 incorporates a system performance check procedure to test the proper functioning of the system. The system performance check uses normal SAR measurements in a simplified setup (the flat section of the SAM Twin Phantom) with a well characterized source (a matched dipole at a specified distance). This setup was selected to give a high sensitivity to all parameters that might fail or vary over time (e.g., probe, liquid parameters, and software settings) and a low sensitivity to external effects inherent in the system (e.g., positioning uncertainty of the device holder). The system performance check does not replace the calibration of the components. The accuracy of the system performance check is not sufficient for calibration purposes. It is possible to calculate the field quite accurately in this simple setup; however, due to the open field situation some factors (e.g., laboratory reflections) cannot be accounted for. Calibrations in the flat phantom are possible with transfer calibration methods, using either temperature probes or calibrated E-field probes. The system performance check also does not test the system performance for arbitrary field situations encountered during real measurements of mobile phones. These checks are performed at SPEAG by testing the components under various conditions (e.g., spherical isotropy measurements in liquid, linearity measurements, temperature variations, etc.), the results of which are used for an error estimation of the system. The system performance check will indicate situations where the system uncertainty is exceeded due to drift or failure.

8.2 System Performance check procedure

Preparation

The conductivity should be measured before the validation and the measured liquid parameters must be entered in the software. If the measured values differ from targeted values in the dipole document, the liquid composition should be adjusted. If the validation is performed with slightly different (measured) liquid parameters, the expected SAR will also be different. See the application note about SAR sensitivities for an estimate of possible SAR deviations. Note that the liquid parameters are temperature dependent with approximately – 0.5% decrease in permittivity and + 1% increase in conductivity for a temperature decrease of 1° C. The dipole must be placed beneath the flat phantom section of the Generic Twin Phantom with the correct distance holder in place. The distance holder should touch the phantom surface with a light pressure at the reference marking (little hole) and be oriented parallel to the long side of the phantom. Accurate positioning is not necessary, since the system will search for the peak SAR location, except that the dipole arms should be parallel to the surface. The device holder for mobile phones can be left in place but should be rotated away from the dipole. The forward power into the dipole at the dipole SMA connector should be determined as accurately as possible. See section 4 for a description of the recommended setup to measure the dipole input power. The actual dipole input power level can be between 20mW and several watts. The result can later be normalized to any power level. It is strongly recommended to note the actually used power level in the „comment“-window of the measurement file; otherwise you lose this crucial information for later reference.

System Performance Check

The DASY4 installation includes predefined files with recommended procedures for measurements and validation. They are read-only document files and destined as fully defined but unmeasured masks, so you must save the finished validation under a different name. The validation document requires the Generic Twin Phantom, so this phantom must be properly installed in your system. (You can create your own measurement procedures by opening a new document or editing an existing document file). Before you start the validation, you just have to tell the system with which components (probe, medium, and device) you are performing the validation; the system will take care of all parameters. After the validation, which will take about 20 minutes, the results of each task are displayed in the document window. Selecting all measured tasks and opening the predefined "validation" graphic format displays all necessary information for validation. A description of the different measurement tasks in the predefined document is given below, together with the information that can be deduced from their results:

- The „reference“ and „drift“ measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the amplifier output power. If it is too high (above $\pm 0.1\text{dB}$) the validation should be repeated; some amplifiers have very high drift during warm-up. A stable amplifier gives drift results in the DASY4 system below $\pm 0.02\text{ dB}$.
- The „surface check“ measurement tests the optical surface detection system of the DASY4 system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above $\pm 0.1\text{mm}$). In that case it is better to abort the validation and stir the liquid. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within $\pm 30^\circ$.) However, varying breaking indices of different liquid compositions might also influence the distance. If the indicated difference varies from the actual setting, the probe parameter „optical surface distance“ should be changed in the probe settings (see manual). For more information see the application note about SAR evaluation.
- The „area scan“ measures the SAR above the dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The proposed scan uses large grid spacing for faster measurement; due to the symmetric field the peak detection is reliable. If a finer graphic is desired, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result.
- The zoom scan job measures the field in a volume around the peak SAR value assessed in the previous „area“ scan (for more information see the application note on SAR evaluation).

If the validation measurements give reasonable results, the peak 1g and 10g spatial SAR values averaged between the two cubes and normalized to 1W dipole input power give the reference data for comparisons. The next section analyzes the expected uncertainties of these values. Section 6 describes some additional checks for further information or troubleshooting.

8.3 Uncertainty Budget

Please note that in the following Tables, the tolerance of the following uncertainty components depends on the actual equipment and setup at the user location and need to be either assessed or verified on-site by the end user of the DASY4 system:

- RF ambient conditions
- Dipole Axis to Liquid Distance
- Input power and SAR drift measurement
- Liquid permittivity - measurement uncertainty
- Liquid conductivity - measurement uncertainty

Note: All errors are given in percent of SAR, so 0.1 dB corresponds to 2.3%. The field error would be half of that. The liquid parameter assessment give the targeted values from the dipole document. All errors are given in percent of SAR, so 0.1dB corresponds to 2.3%. The field error would be half of that.

System validation

In the table below, the system validation uncertainty with respect to the analytically assessed SAR value of a dipole source as given in the P1528 standard is given. This uncertainty is smaller than the expected uncertainty for mobile phone measurements due to the simplified setup and the symmetric field distribution.

| Error Sources | Uncertainty Value | Probability Distribution | Divisor | c_i 1g | c_i 10g | Standard Uncertainty 1g | Standard Uncertainty 10g | v_i^2 or v_{eff} |
|----------------------------------|-------------------|--------------------------|---------|----------|-----------|-------------------------|--------------------------|----------------------|
| Measurement System | | | | | | | | |
| Probe calibration | ± 4.8% | Normal | 1 | 1 | 1 | ± 4.8% | ± 4.8% | ∞ |
| Axial isotropy | ± 4.7% | Rectangular | √3 | 0.7 | 0.7 | ± 1.9% | ± 1.9% | ∞ |
| Hemispherical isotropy | ± 0.0% | Rectangular | √3 | 0.7 | 0.7 | ± 0.0% | ± 3.9% | ∞ |
| Boundary effects | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Probe linearity | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | ∞ |
| System detection limits | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Readout electronics | ± 1.0% | Normal | 1 | 1 | 1 | ± 1.0% | ± 1.0% | ∞ |
| Response time | ± 0.0% | Rectangular | √3 | 1 | 1 | ± 0.0% | ± 0.0% | ∞ |
| Integration time | ± 0.0% | Rectangular | √3 | 1 | 1 | ± 0.0% | ± 0.0% | ∞ |
| RF ambient conditions | ± 3.0% | Rectangular | √3 | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Probe positioner | ± 0.4% | Rectangular | √3 | 1 | 1 | ± 0.2% | ± 0.2% | ∞ |
| Probe positioning | ± 2.9% | Rectangular | √3 | 1 | 1 | ± 1.7% | ± 1.7% | ∞ |
| Max. SAR evaluation | ± 1.0% | Rectangular | √3 | 1 | 1 | ± 0.6% | ± 0.6% | ∞ |
| Test Sample Related | | | | | | | | |
| Dipole axis to liquid distance | ± 2.0% | Normal | 1 | 1 | 1 | ± 1.2% | ± 1.2% | ∞ |
| Power drift | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | ∞ |
| Phantom and Set-up | | | | | | | | |
| Phantom uncertainty | ± 4.0% | Rectangular | √3 | 1 | 1 | ± 2.3% | ± 2.3% | ∞ |
| Liquid conductivity (target) | ± 5.0% | Rectangular | √3 | 0.64 | 0.43 | ± 1.8% | ± 1.2% | ∞ |
| Liquid conductivity (meas.) | ± 2.5% | Normal | 1 | 0.64 | 0.43 | ± 1.6% | ± 1.1% | ∞ |
| Liquid permittivity (target) | ± 5.0% | Rectangular | √3 | 0.6 | 0.49 | ± 1.7% | ± 1.4% | ∞ |
| Liquid permittivity (meas.) | ± 2.5% | Normal | 1 | 0.6 | 0.49 | ± 1.5% | ± 1.2% | ∞ |
| Combined Uncertainty | | | | | | ± 8.4% | ± 8.1% | |
| Expanded Std. Uncertainty | | | | | | ± 16.8% | ± 16.2% | |

Performance check repeatability

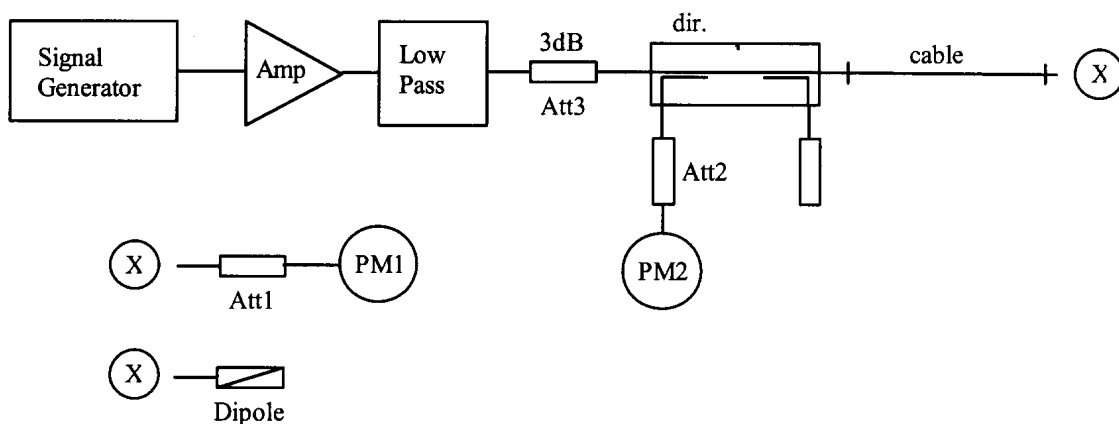
The repeatability check of the validation is insensitive to external effects and gives an indication of the variations in the DASY4 measurement system, provided that the same power reading setup is used for all validations. The repeatability estimate is given in the following table:

| Error Sources | Uncertainty Value | Probability Distribution | Divisor | c_i 1g | c_i 10g | Standard Uncertainty 1g | Standard Uncertainty 10g | v_i^2 or v_{eff} |
|----------------------------------|-------------------|--------------------------|---------|----------|-----------|-------------------------|--------------------------|----------------------|
| Measurement System | | | | | | | | |
| Probe calibration | ± 4.8% | Normal | 1 | 1 | 1 | 0 | 0 | ∞ |
| Axial isotropy | ± 4.7% | Rectangular | √3 | 0.7 | 0.7 | 0 | 0 | ∞ |
| Hemispherical isotropy | ± 0.0% | Rectangular | √3 | 0.7 | 0.7 | 0 | 0 | ∞ |
| Boundary effects | ± 1.0% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| Probe linearity | ± 4.7% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| System detection limits | ± 1.0% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| Readout electronics | ± 1.0% | Normal | 1 | 1 | 1 | 0 | 0 | ∞ |
| Response time | ± 0.0% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| Integration time | ± 0.0% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| RF ambient conditions | ± 3.0% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| Probe positioner | ± 0.4% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| Probe positioning | ± 2.9% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| Max. SAR evaluation | ± 1.0% | Rectangular | √3 | 1 | 1 | 0 | 0 | ∞ |
| Test Sample Related | | | | | | | | |
| Dipole axis to liquid distance | ± 2.0% | Normal | 1 | 1 | 1 | ± 1.2% | ± 1.2% | ∞ |
| Power drift | ± 4.7% | Rectangular | √3 | 1 | 1 | ± 2.7% | ± 2.7% | ∞ |
| Phantom and Set-up | | | | | | | | |
| Phantom uncertainty | ± 4.0% | Rectangular | √3 | 1 | 1 | ± 2.3% | ± 2.3% | ∞ |
| Liquid conductivity (target) | ± 5.0% | Rectangular | √3 | 0.64 | 0.43 | ± 1.8% | ± 1.2% | ∞ |
| Liquid conductivity (meas.) | ± 2.5% | Normal | 1 | 0.64 | 0.43 | ± 1.6% | ± 1.1% | ∞ |
| Liquid permittivity (target) | ± 5.0% | Rectangular | √3 | 0.6 | 0.49 | ± 1.7% | ± 1.4% | ∞ |
| Liquid permittivity (meas.) | ± 2.5% | Normal | 1 | 0.6 | 0.49 | ± 1.5% | ± 1.2% | ∞ |
| Combined Uncertainty | | | | | | ± 5.3% | ± 4.9% | |
| Expanded Std. Uncertainty | | | | | | ± 10.6% | ± 9.7% | |

The expected repeatability deviation is low. Excessive drift (e.g., drift in liquid parameters), partial system failures or incorrect parameter settings (e.g., wrong probe or device settings) will lead to unexpectedly high repeatability deviations. The repeatability gives an indication that the system operates within its initial specifications. Excessive drift, system failure and operator errors are easily detected.

8.4 Power set-up for validation

The uncertainty of the dipole input power is a significant contribution to the absolute uncertainty and the expected deviation in interlaboratory comparisons. The values in Section 2 for a typical and a sophisticated setup are just average values. Refer to the manual of the power meter and the detector head for the evaluation of the uncertainty in your system. The uncertainty also depends on the source matching and the general setup. Below follows the description of a recommended setup and procedures to increase the accuracy of the power reading:



The figure shows the recommended setup. The PM1 (incl. Att1) measures the forward power at the location of the validation dipole connector. The signal generator is adjusted for the desired forward power at the dipole connector and the power meter PM2 is read at that level. After connecting the cable to the dipole, the signal generator is readjusted for the same reading at power meter PM2. If the signal generator does not allow a setting in 0.01dB steps, the remaining difference at PM2 must be noted and considered in the normalization of the validation results. The requirements for the components are:

- The signal generator and amplifier should be stable (after warm-up). The forward power to the dipole should be above 10mW to avoid the influence of measurement noise. If the signal generator can deliver 15dBm or more, an amplifier is not necessary. Some high power amplifiers should not be operated at a level far below their maximum output power level (e.g. a 100W power amplifier operated at 250mW output can be quite noisy). An attenuator between the signal generator and amplifier is recommended to protect the amplifier input.
- The low pass filter after the amplifier reduces the effect of harmonics and noise from the amplifier. For most amplifiers in normal operation the filter is not necessary.
- The attenuator after the amplifier improves the source matching and the accuracy of the power head. (See power meter manual.) It can also be used also to make the amplifier operate at its optimal output level for noise and stability. In a setup without directional coupler, this attenuator should be at least 10dB.
- The directional coupler (recommended ³ 20dB) is used to monitor the forward power and adjust the signal generator output for constant forward power. A medium quality coupler is sufficient because the loads (dipole and power head) are well matched. (If the setup is used for reflective loads, a high quality coupler with respect to directivity and output matching is necessary to avoid additional errors.)
- The power meter PM2 should have a low drift and a resolution of 0.01dBm, but otherwise its accuracy has no impact on the power setting. Calibration is not required.
- The cable between the coupler and dipole must be of high quality, without large attenuation and phase changes when it is moved. Otherwise, the power meter head PM1 should be brought to the location of the dipole for measuring.
- The power meter PM1 and attenuator Att1 must be high quality components. They should be calibrated, preferably together. The attenuator (³10dB) improves the accuracy of the power reading. (Some higher power heads come with a built-in calibrated attenuator.) The exact attenuation of the attenuator at the frequency used must be known; many attenuators are up to 0.2dB off from the specified value.

- Use the same power level for the power setup with power meter PM1 as for the actual measurement to avoid linearity and range switching errors in the power meter PM2. If the validation is performed at various power levels, do the power setting procedure at each level.
- The dipole must be connected directly to the cable at location "X". If the power meter has a different connector system, use high quality couplers. Preferably, use the couplers at the attenuator Att1 and calibrate the attenuator with the coupler.
- Always remember: We are measuring power, so 1% is equivalent to 0.04dB.

8.5 Laboratory reflection

In near-field situations, the absorption is predominantly caused by induction effects from the magnetic near-field. The absorption from reflected fields in the laboratory is negligible. On the other hand, the magnetic field around the dipole depends on the currents and therefore on the feed point impedance. The feed point impedance of the dipole is mainly determined from the proximity of the absorbing phantom, but reflections in the laboratory can change the impedance slightly. A 1% increase in the real part of the feed point impedance will produce approximately a 1% decrease in the SAR for the same forward power. The possible influence of laboratory reflections should be investigated during installation. The validation setup is suitable for this check, since the validation is sensitive to laboratory reflections. The same tests can be performed with a mobile phone, but most phones are less sensitive to reflections due to the shorter distance to the phantom. The fastest way to check for reflection effects is to position the probe in the phantom above the feed point and start a continuous field measurement in the DASY4 multi-meter window. Placing absorbers in front of possible reflectors (e.g. on the ground near the dipole or in front of a metallic robot socket) will reveal their influence immediately. A 10dB absorber (e.g. ferrite tiles or flat absorber mats) is probably sufficient, as the influence of the reflections is small anyway. If you place the absorber too near the dipole, the absorber itself will interact with the reactive near-field. Instead of measuring the SAR, it is also possible to monitor the dipole impedance with a network analyzer for reflection effects. The network analyzer must be calibrated at the SMA connector and the electrical delay (two times the forward delay in the dipole document) must be set in the NWA for comparisons with the reflection data in the dipole document. If the absorber has a significant influence on the results, the absorber should be left in place for validation or measurements. The reference data in the dipole document are produced in a low reflection environment.

8.6 Additional system checks

While the validation gives a good check of the DASY4 system components, it does not include all parameters necessary for real phone measurements (e.g. device modulation or device positioning). For system validation (repeatability) or comparisons between laboratories a reference device can be useful. This can be any mobile phone with a stable output power (preferably a device whose output power can be set through the keyboard). For comparisons, the same device should be sent around, since the SAR variations between samples can be large. Several measurement possibilities in the DASY software allow additional tests of the performance of the DASY system and components. These tests can be useful to localize component failures:

- The validation can be performed at different power levels to check the noise level or the correct compensation of the diode compression in the probe.
- If a pulsed signal with high peak power levels is fed to the dipole, the performance of the diode compression compensation can be tested. The correct crest factor parameter in the DASY software must be set (see manual). The system should give the same SAR output for the same averaged input power.
- The probe isotropy can be checked with a 1D-probe rotation scan above the feed point. The automatic probe alignment procedure must be passed through for accurate probe rotation movements (optional DASY4 feature with a robot-mounted light beam unit). Otherwise the probe tip might move on a small circle during rotation, producing some additional isotropy errors in gradient fields.