

Approved

**Company Internal** REPORT Prepared (also subject responsible if other) No LD/SEMC/BGLIM Hamid Kami Shirazi BGLI07:491 Checked Rev Reference Date 070923 LD/SEMC/BGLIMC Peter Lindeborg 070920 А File

# **Report issued by Accredited SAR Laboratory**

### For

# PY7A1052051 (W908i)

Date of test:	20 <sup>th</sup> - 22 <sup>nd</sup> Aug. and 3 <sup>rd</sup> - 6 <sup>th</sup> Sept. 2007
Laboratory:	SAR Test Laboratory Sony Ericsson Mobile Communications AB Nya Vattentornet SE-221 82 LUND, Sweden
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Testing Approval	Peter Lindeborg peter.lindeborg@sonyericsson.com PL LL +46462126180

#### Statement of Compliance

Sony Ericsson Mobile Communications AB declares under its sole responsibility that the product

#### Sony Ericsson Type AAB-1052051-BV; FCC ID: PY7A1052051; IC:4170B-A1052051

to which this declaration relates, is in conformity with the appropriate RF exposure standards recommendations and guidelines. It also declares that the product was tested in accordance with the appropriate measurement standards, guidelines and recommended practices. Any deviations from these standards, guidelines and recommended practices are noted below: (None)

This laboratory is accredited to ISO/IEC 17025 (SWEDAC accreditation no. 1847).



Laboratories are accredited by the Swedish Board for Accreditation and Conformity Assessment (SWEDAC) under the terms of Swedish legislation. The accredited laboratory activities meet the requirements in SS-EN ISO/IEC 17025 (2005). This report may not be reproduced other than in full, except with the prior written approval of the issuing laboratory.

The results and statements contained herein relate only to the items tested. The names of individuals involved may be mentioned only in connection with the statements or results from this report.

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#### Table of contents 1

2	2 INTRODUCTION	2
3	3 DEVICE UNDER TEST	2
	<ul><li>3.1 ANTENNA DESCRIPTION</li><li>3.2 DEVICE DESCRIPTION</li></ul>	2
4	4 TEST EQUIPMENT	2
	<ul><li>4.1 Dosimetric system</li><li>4.2 Additional equipment</li></ul>	2
5	5 ELECTRICAL PARAMETERS ON THE TISSUE SIMULATING LIQUID	5
6	6 SYSTEM ACCURACY VERIFICATION	2
7	7 SAR MEASUREMENT UNCERTAINTY	2
8	8 TEST RESULTS	
9	9 REFERENCES	9
1	10 APPENDIX	10
	10.1 Photographs of the device under test	
	10.2       Device position on SAM Twins Phantom         10.3       Attachments	



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LD/SEMC/BGLIM Hamid Kami Shirazi		BGLI07:491		
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LD/SEMC/BGLIMC Peter Lindeborg	070923	070920	А	File

# 2 Introduction

In this test report, compliance of the Sony Ericsson PY7A1052051 (W908i) portable telephone with RF safety guidelines is demonstrated. The applicable RF safety guidelines and the SAR measurement specifications used for the test are described in the SAR Measurement Specifications of Wireless Handsets [1].

# 3 Device under Test

### 3.1 Antenna Description

Туре	Internal antenna	Internal antenna		
Location	Inside, rear, at top	Inside, rear, at top		
Dimensions	Max length	40mm		
Dimensions	Max width	18mm		
Configuration	PIFA			

### 3.2 Device description

Device model	PY7A1052	2051(W908	Bi)			
Serial number (EUT #)	CB5A0DZ					
Mode	GSM1900		-	GSM850		
Crest Factor	8.3			8.3		
Multiple Access Scheme	TDMA			TDMA		
Maximum Output Power Setting	Ch512	Ch661	Ch810	Ch128	Ch190	Ch251
(dBm)	30.2	30.2	30.2	32.4	32.4	32.4
Factory Tolerance in Power Setting		±0.5dB			±0.5dB	
Maximum Peak Output Power (dBm)	30.7	30.7	30.7	32.9	32.9	32.9
Data and connectivity		GPRS Cla	iss: 10 ;	Capability	Class: B	
Maximum Output Power Setting	Ch512	Ch661	Ch810	Ch128	Ch190	Ch251
(dBm)	28.2	28.2	28.2	31.2	31.2	31.2
Factory Tolerance in Power Setting		±0.5dB		±0.5dB		
Maximum Peak Output Power (dBm)	28.7	28.7	28.7	31.7	31.7	31.7
Data and connectivity			EGPRS C	lass: 10		
Maximum Output Power Setting	Ch512	Ch661	Ch810	Ch128	Ch190	Ch251
(dBm)	26.5	26.5	26.5	27.5	27.5	27.5
Factory Tolerance in Power Setting		±0.5dB			±0.5dB	
Maximum Peak Output Power (dBm)	27.0	27.0	27.0	28.0	28.0	28.0
Transmitting Frequency Range(MHz)	185	50.2 – 1909	9.8	8	24.2 – 848	.8
Prototype or Production Unit	Preproduction (HW-FP2)					
Device Category	Portable					
RF exposure environment	General p	opulation	/ uncontro	olled		



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LD/SEMC/BGLIM Hamid Kami Shirazi		BGL107:491		
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#### 4 **Test equipment**

#### 4.1 **Dosimetric system**

SAR measurements were made using the DASY4 professional system (software version 4.7, Build 53) with SAM twin phantom, manufactured by Schmid & Partner Engineering AG (SPEAG). The list of calibrated equipment is given below.

Description	Serial Number	Due Date
DASY DAE4	428	Jan 2008
DASY DAE4	640	Jan 2008
E-field probe ET3DV6	1815	Jan 2008
E-field probe ES3DV3	3062	Jan 2008
Dipole Validation Kit, D835V2	484	May 2008
Dipole Validation Kit, D1900V2	5d002	Jan 2009

#### **Additional equipment** 4.2

Description	Inventory Number	Due Date
Signal generator R&S SML03	INV 20007667	March 2008
Power meter R&S NRVZ	INV 20007669	March 2008
Power sensor R&S NRV-Z5	INV 20007672	March 2008
Power sensor R&S NRV-Z5	INV 20007673	March 2008
Network analyzer HP8753C	INV421671	March 2008
S-parameter test set HP85047A	INV 421670	March 2008
Dielectric probe kit HP8507D	INV 200 000 53	Self calibrated
CMU200	INV 20002149	March 2008
Thermometer Fluke 51	INV 2071	March 2008
Signal generator ESG-D4000A	INV 462935	March 2008
Directional coupler HP778D	INV 2903	March 2008
Power meter R&S NRVD	INV 20007668	March 2008
Power sensor R&S NRV-Z5	INV 20007670	March 2008
Power sensor R&S NRV-Z5	INV 20007671	March 2008
Termination 65N50-0-11	INV 2903	March 2008
Network analyzer HP8753C	INV421671	March 2008
S-parameter test set HP85047A	INV 421670	March 2008
Dielectric probe kit HP85070D	INV 20000053	Self calibrated



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LD/SEMC/BGLIM Hamid Kami Shirazi		BGL107:491		
Approved	Checked	Date	Rev	Reference
LD/SEMC/BGLIMC Peter Lindeborg	070923	070920	А	File

#### Electrical parameters on the tissue simulating liquid 5

Prior to conducting SAR measurements, the relative permittivity,  $\epsilon$ r, and the conductivity,  $\sigma$ , of the tissue simulating liquids were measured with the dielectric probe kit. These values are shown in the table below. The mass density, p, entered into the DASY4 software is also given. Recommended limits for permittivity  $\varepsilon r$ , conductivity  $\sigma$  and mass density  $\rho$  are also shown.

f	Tissue	Limits / Measured	Dielectric I	Parameters	Density
(MHz)	type	Limits / Measured	٤r	σ (S/m)	ρ (g/cm <sup>3</sup> )
		Measured, 03/09/2007	38.9	1.47	1.00
1900	Head	Measured, 04/09/2007	38.9	1.47	1.00
		Recommended	40.0	1.40	1.00
	Body	Measured, 05/09/2007	51.1	1.57	1.00
		Recommended	53.3	1.52	1.00
	Head	Measured, 20/08/2007	40.5	0.87	1.00
850	neau	Recommended	41.5	0.90	1.00
	Body	Measured, 06/09/2007	53.3	1.00	1.00
	Bouy	Recommended	55.2	0.97	1.00

#### System accuracy verification 6

A system accuracy verification of the DASY4 was performed using the dipole validation kit listed in section 4.1. Measurement made in ambient temperature 20-24 °C and humidity 40-60 %. The obtained results are displayed in the table below.

RF noise had been measured in liquid when all RF equipment in lab was switched off. Measured value was 0.00002mW/g in 1g mass

f	Tissue	Measured / Reference	SAR (W/kg)	Dielectric F	Parameters	Density	Liquid
(MHz)	type	Measured / Reference	1g/10g	٤r	σ (S/m)	<b>ρ</b> (g/cm <sup>3</sup> )	T(°C)
		Measured, 03/09/2007	38.6/20.1	38.5	1.45	1.00	20.5
	Head	Measured, 04/09/2007	38.6/19.8	38.9	1.47	1.00	20.5
1900		Reference	37.4/19.8	40.0	1.40	1.00	22.2
	Body	Measured, 05/09/2007	39.1/20.6	51.1	1.57	1.00	21.5
		Reference	38.6/20.6	53.3	1.52	1.00	22.2
	Head	Measured, 20/08/2007	9.17/6.02	40.5	0.87	1.00	21.3
850		Reference	9.20/6.00	41.5	0.90	1.00	22.2
	Body	Measured, 06/09/2007	10.1/6.62	53.3	1.00	1.00	22.4
	Бойу	Reference	9.48/6.29	53.3	0.97	1.00	22.2



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Prepared (also subject responsible if other)		No.		
LD/SEMC/BGLIM Hamid Kami Shirazi		BGLI07:491		
Approved	Checked	Date	Rev	Reference
LD/SEMC/BGLIMC Peter Lindeborg	070923	070920	А	File

#### 7 SAR measurement uncertainty

# SAR measurement uncertainty evaluation for Sonyericsson PY7A1052051 (W908i) phone According to IEEE 1528

Uncertainty Component	Uncer. (%)	Prob Dist.	Div.	Ci	SAR 1g mass
Measurement System					
Probe Calibration	±5.9	Ν	1	1	±5.9
Axial Isotropy	±4.7	R	√3	0.7	±1.9
Spherical Isotropy	±9.6	R	√3	0.7	±3.9
Boundary effect	±1.0	R	√3	1	±0.6
Probe linearity	±4.7	R	√3	1	±2.7
Detection limit	±1.0	R	√3	1	±0.6
Readout electronics	±0.3	Ν	1	1	±0.3
Response time	±0.8	R	√3	1	±0.5
Integration time	±2.6	R	√3	1	±1.5
RF Ambient Conditions	±3.0	R	√3	1	±1.7
Mech. Constraints of robot	±0.4	R	√3	1	±0.2
Probe positioning	±2.9	R	√3	1	±1.7
Extrapolation, interpolation and integration	±1.0	R	√3	1	±0.6
Measurement System Uncertainty					±8.4
Test Sample Related					
Device positioning	±3.5	Ν	1	1	±3.5
Device holder uncertainty	±3.5	Ν	1	1	±3.5
Power drift	±5	R	√3	1	±2.9
Test Sample Related Uncertainty					±5.5
Phantom and Tissue Parameters					
Phantom uncertainty	±4.0	R	√3	1	±2.3
Liquid conductivity (measurement)	±2.5	R	1	0.64	±1.6
Liquid conductivity (target)	±5.0	R	√3	0.64	±1.8
Liquid Permittivity (measurement)	±2.5	R	1	0.6	±1.5
Liquid Permittivity (target)	±5.0	R	√3	0.6	±1.7
Phantom and Tissue Parameters Uncertainty	Phantom and Tissue Parameters Uncertainty				±4.0
Combined standard uncertainty					±10.8
Extended standard uncertainty (k=2)					<u>+21.6</u>



		Company Inter REPORT	Internal		
Prepared (also subject responsible if other)		No.			
LD/SEMC/BGLIM Hamid Kami Shirazi		BGL107:491			
Approved	Checked	Date	Rev	Reference	
LD/SEMC/BGLIMC Peter Lindeborg	070923	070920	А	File	

### 8 Test results

The measured 1-gram averaged SAR values of the device towards head and body are provided in tables 1 and 2. The ambient humidity and temperature of test facility were 40%-60% and 20°C–24°C respectively. The depth of tissue simulating liquids for 850MHz head and body are 15.3cm and 15.2cm for 1900MHz and 15.3 and 15 for 850MHz respectively. A base station simulator was used to control the device during the SAR measurement. The phone was supplied with fully charged battery for each measurement.

For head measurement, the device was tested on the right-hand side and the left-hand side of phantom in two phone positions, cheek (touch) and tilt (cheek + 15deg). The device slider was close state in all measurements and open state only in the worst cases.

For body measurement DUT was tested on the antenna (rear) and Front towards flat section of phantom with 15mm distance in both speech and Data (GPRS and EGPRS) mode. EGPRS have measured only in the worst case of GPRS channel. For all modes, the device was tested at the lowest, middle and highest frequencies in the transmission band. For Hands free use Sony Ericsson head set (HPB-60) and for Bluetooth DUT was pared with Sony Ericsson HBH-610 Bluetooth accessory and measured on worst case speech mode and for body.

		Power	Phone	Liqui	SAR (V	V/kg)	
Mode	Channel	(dB)	Position	dt	Right-hand	Left-hand	
		(ub)	rosition	(°C)	1g mass	1g mass	
	128	33.0	Cheek/Close	21.3	0.33	0.33	
	120	55.0	Tilt/close	21.3	-	-	
GSM			Cheek/Close	21.3	0.33	0.35	
850	190	33.1	Tilt/close	21.3	0.22	0.20	
Head			Cheek/Open	21.3	-	0.23	
neau	251 33.1	Cheek/Close	21.3	0.37	0.34		
		251	33.1	Tilt/close	21.3	-	-
			Cheek/Open	21.3	0.33	-	
			Cheek/Close	20.5	0.67	0.92	
	512	30.7	Tilt/close	20.5	0.31	0.28	
GSM			Cheek/Open	20.5	0.41	0.38	
1900	661	30.7	Cheek/Close	20.5	0.56	0.66	
Head	<b>1</b> 001 30.7	Tilt/close	20.5	0.25	0.21		
	810	30.7	Cheek/Close	20.5	0.49	0.57	
	010 30.7	Tilt/close	20.5	-	-		

Table1: SAR measurement result for Sony Ericsson PY7A1052051 (W908i) telephone at highest possible output power. The phone has measured towards head.



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Mode	Channel	Power (dBm)	Phone Position	Liquid T ( °C)	SAR (W/kg) in 1 g mass
		33.0	Antenna to phantom BT	22.4	0.29
	128	31.7	Antenna to phantom GPRS2TX	22.4	0.48
	190	33.1	Antenna to phantom BT	22.4	0.31
GSM	190	31.7	Antenna to phantom GPRS2TX	22.4	0.41
850		33.1	Antenna to phantom BT	22.4	0.36
Body		31.6	Antenna to phantom GPRS2TX	22.4	0.48
	251	28.0	Antenna to phantom EGPRS2TX	22.4	0.21
		33.1	Antenna to phantom PHF	22.4	0.32
		31.6	Front to phantom GPRS2TX	22.4	0.30
		30.6	Antenna to phantom BT	21.5	0.30
	512	28.8	Antenna to phantom GPRS2TX	21.5	0.40
		26.9	Antenna to phantom EGPRS2TX	21.5	0.18
GSM		28.8	Front to phantom GPRS2TX	21.5	0.21
1900		30.6	Antenna to phantom PHF	21.5	0.30
Body	661	30.7	Antenna to phantom BT	21.5	0.21
	001	28.8	Antenna to phantom GPRS2TX	21.5	0.31
	810	30.6	Antenna to phantom BT	21.5	0.19
	610	28.8	Antenna to phantom GPRS2TX	21.5	0.30

Table2: SAR measurement result for Sony Ericsson PY7A1052051 (W908i) telephone at highest possible output power. The phone has measured towards the Body.



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LD/SEMC/BGLIM Hamid Kami Shirazi		BGLI07:491			
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# 9 References

[1] R.Plicanic, "SAR Measurement Specification of Wireless Handsets", Sony Ericsson SAR Test Laboratory internal document GUG/N 03:141

[2] FCC, "Evaluating Compliance with FCC Guidelines for Human Exposure to Radio Frequency Electromagnetic Fields: Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radio Frequency Emissions," Supplement C (Edition 01-01) to OET Bulletin 65 (Edition 97-01).

[3] IEEE, "Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques," STD 1528-2003, June, 2003.

[4] IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for handheld mobile wireless devices in the frequency range of 300 MHz to 3 GHz", February 2005.



		Company Inte REPORT	ernal		
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10 Appendix

# 10.1 Photographs of the device under test



Close state



Front and rear



**Rear with Battery** 



Close state

Sides



System connector



Open state



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10.2 Device position on SAM Twins Phantom





Close state





Open state

Close state

Device position towards the head: Cheek (touch) phone position









Device position towards the head: Tilt (cheek+15deg) phone position

Open stat

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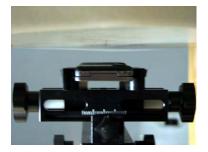
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Device position towards the body: Phone on 15mm distance against Phantom

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# 10.3 Attachment

- Probe & Dipole Calibration
- Measurement plots and system validation

Date/Time: 2007-08-20 09:36:10

Test Laboratory: Sony Ericsson Mobile Communications **DUT: Dipole 835 MHz; Type: D835V2; Serial: D835V2 - SN: 484** Communication System: CW; Frequency: 835 MHz;Duty Cycle: 1:1 Medium parameters used: f = 835 MHz;  $\sigma$  = 0.869 mho/m;  $\epsilon_r$  = 40.5;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ES3DV3 - SN3062; ConvF(6.06, 6.06, 6.06); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE4 Sn640; Calibrated: 2007-01-19

- Phantom: SAM 5; Type: SAM; Serial: 1352

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

d=15mm, Pin=100mW/Area Scan (81x111x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.998 mW/g

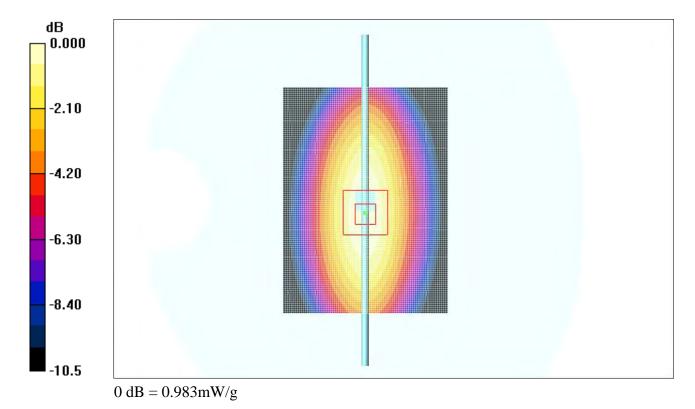
**d=15mm, Pin=100mW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 34.3 V/m; Power Drift = -0.035 dB

Peak SAR (extrapolated) = 1.34 W/kg

SAR(1 g) = 0.917 mW/g; SAR(10 g) = 0.602 mW/g

Maximum value of SAR (measured) = 0.983 mW/g



Date/Time: 2007-08-20 11:03:13

Test Laboratory: Sony Ericsson Mobile Communications **DUT:** (AAC-1052051-BV) (closed); #8734 Communication System: GSM835MHz; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 836.4 MHz;  $\sigma = 0.871$  mho/m;  $\varepsilon_r = 40.5$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

### DASY4 Configuration:

- Probe: ES3DV3 - SN3062; ConvF(6.06, 6.06, 6.06); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn640; Calibrated: 2007-01-19
- Phantom: SAM 5; Type: SAM; Serial: 1352
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Left Tilt/Area Scan (71x111x1): Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.216 mW/g

Left Tilt/Zoom Scan (6x6x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 10.6 V/m; Power Drift = 0.019 dB

Peak SAR (extrapolated) = 0.254 W/kg

### SAR(1 g) = 0.204 mW/g; SAR(10 g) = 0.153 mW/g;

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.211 mW/g



Date/Time: 2007-08-20 15:37:52

Test Laboratory: Sony Ericsson Mobile Communications **DUT:** (AAC-1052051-BV) (closed); #8734 Communication System: GSM835MHz; Frequency: 836.4 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 836.4 MHz;  $\sigma = 0.871$  mho/m;  $\varepsilon_r = 40.5$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ES3DV3 - SN3062; ConvF(6.06, 6.06, 6.06); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE4 Sn640; Calibrated: 2007-01-19

- Phantom: SAM 5; Type: SAM; Serial: 1352

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**Right Tilt/Area Scan (71x111x1):** Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.234 mW/g

Right Tilt/Zoom Scan (6x6x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

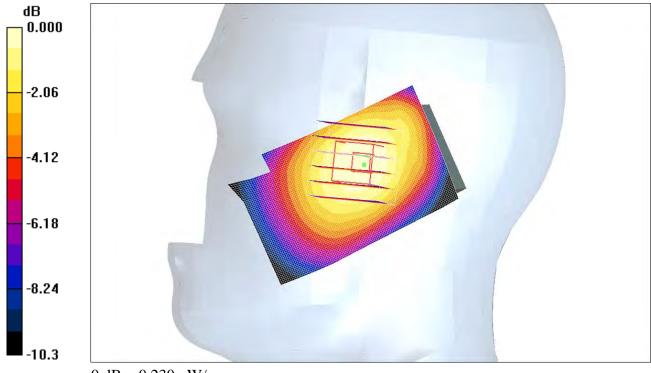
Reference Value = 11.5 V/m; Power Drift = 0.032 dB

Peak SAR (extrapolated) = 0.277 W/kg

SAR(1 g) = 0.222 mW/g; SAR(10 g) = 0.166 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.230 mW/g



 $0 \, dB = 0.230 \, mW/g$ 

Date/Time: 2007-08-20 16:24:41

Test Laboratory: Sony Ericsson Mobile Communications **DUT:** (AAC-1052051-BV) (closed); #8734 Communication System: GSM835MHz; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 0.883$  mho/m;  $\varepsilon_r = 40.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Right Section

### DASY4 Configuration:

- Probe: ES3DV3 - SN3062; ConvF(6.06, 6.06, 6.06); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn640; Calibrated: 2007-01-19
- Phantom: SAM 5; Type: SAM; Serial: 1352
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Right Cheek/Area Scan (71x111x1): Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.391 mW/g

Right Cheek/Zoom Scan (6x6x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

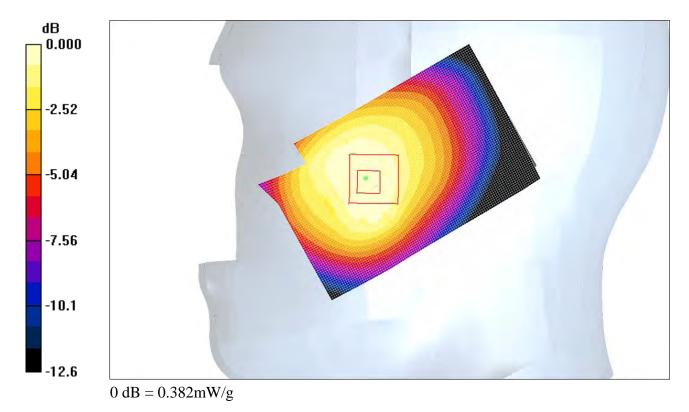
Reference Value = 6.78 V/m; Power Drift = -0.039 dB

Peak SAR (extrapolated) = 0.479 W/kg

### SAR(1 g) = 0.369 mW/g; SAR(10 g) = 0.273 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.382 mW/g



# Test Laboratory: Sony Ericsson Mobile Communications DUT: (AAC-1052051-BV) (closed); #8734

Communication System: GSM835MHz; Frequency: 836.4 MHz; Duty Cycle: 1:8.3

Medium parameters used (interpolated): f = 836.4 MHz;  $\sigma = 0.871 \text{ mho/m}$ ;  $\varepsilon_r = 40.5$ ;  $\rho = 1000 \text{ kg/m}^3$ Phantom section: Left Section

**DASY4** Configuration:

- Probe: ES3DV3 SN3062; ConvF(6.06, 6.06, 6.06); Calibrated: 2007-01-16
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn640; Calibrated: 2007-01-19
- Phantom: SAM 5; Type: SAM; Serial: 1352
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Left Cheek/Area Scan (71x111x1): Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.398 mW/g

Left Cheek/Zoom Scan (6x6x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

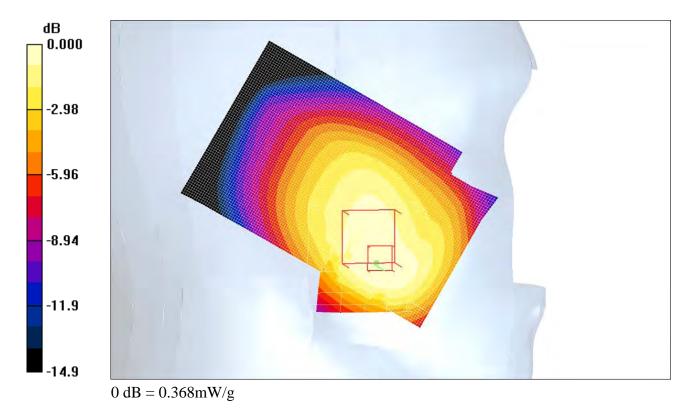
Reference Value = 5.20 V/m; Power Drift = 0.123 dB

Peak SAR (extrapolated) = 0.554 W/kg

SAR(1 g) = 0.349 mW/g; SAR(10 g) = 0.233 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.368 mW/g



Date/Time: 2007-08-20 16:48:08

### Test Laboratory: Sony Ericsson Mobile Communications DUT: (AAC-1052051-BV) (open); Program Name: SAR measurement on the head

Communication System: GSM835MHz; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma$  = 0.883 mho/m;  $\epsilon_r$  = 40.3;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ES3DV3 - SN3062; ConvF(6.06, 6.06, 6.06); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn640; Calibrated: 2007-01-19
- Phantom: SAM 5; Type: SAM; Serial: 1352

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Right Cheek/Area Scan (71x111x1): Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.346 mW/g

Right Cheek/Zoom Scan (6x6x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

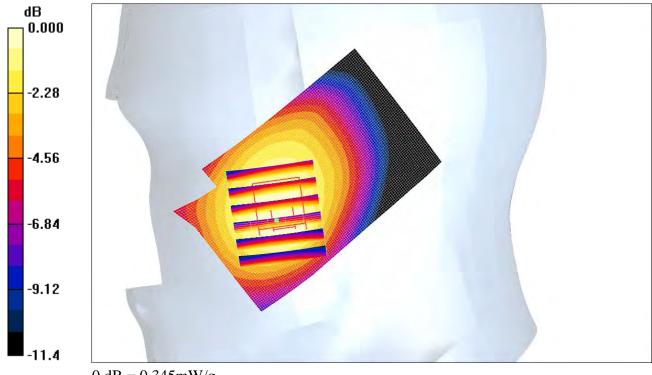
Reference Value = 5.75 V/m; Power Drift = 0.040 dB

Peak SAR (extrapolated) = 0.472 W/kg

SAR(1 g) = 0.327 mW/g; SAR(10 g) = 0.239 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.345 mW/g



 $0 \ dB = 0.345 mW/g$ 

Date/Time: 2007-08-20 13:41:54

### Test Laboratory: Sony Ericsson Mobile Communications DUT: (AAC-1052051-BV) (open); Program Name: SAR measurement on the head

Communication System: GSM835MHz; Frequency: 824.2 MHz;Duty Cycle: 1:8.3 Medium parameters used: f = 825 MHz;  $\sigma = 0.86$  mho/m;  $\varepsilon_r = 40.6$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ES3DV3 - SN3062; ConvF(6.06, 6.06, 6.06); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn640; Calibrated: 2007-01-19
- Phantom: SAM 5; Type: SAM; Serial: 1352

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Left Cheek/Area Scan (71x111x1): Measurement grid: dx=10mm, dy=10mm

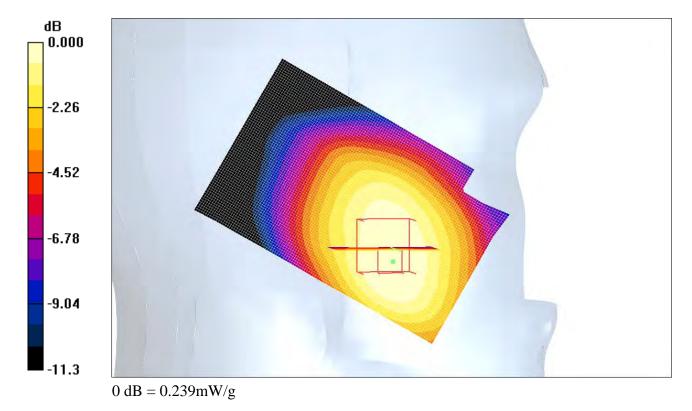
Maximum value of SAR (interpolated) = 0.251 mW/g

**Left Cheek/Zoom Scan (6x6x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm Reference Value = 4.42 V/m; Power Drift = 0.015 dB

Peak SAR (extrapolated) = 0.315 W/kg

SAR(1 g) = 0.232 mW/g; SAR(10 g) = 0.174 mW/g

Maximum value of SAR (measured) = 0.239 mW/g



Test Laboratory: Sony Ericsson Mobile Communications

DUT: Dipole 835 MHz; Type: D835V2; Serial: D835V2 - SN: 484

Communication System: CW; Frequency: 835 MHz;Duty Cycle: 1:1

Medium parameters used: f = 835 MHz;  $\sigma = 0.869$  mho/m;  $\varepsilon_r = 40.5$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ES3DV3 - SN3062; ConvF(6.06, 6.06, 6.06); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE4 Sn640; Calibrated: 2007-01-19
- Phantom: SAM 5; Type: SAM; Serial: 1352

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

d=15mm, Pin=100mW/Area Scan (81x111x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 0.998 mW/g

**d=15mm, Pin=100mW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

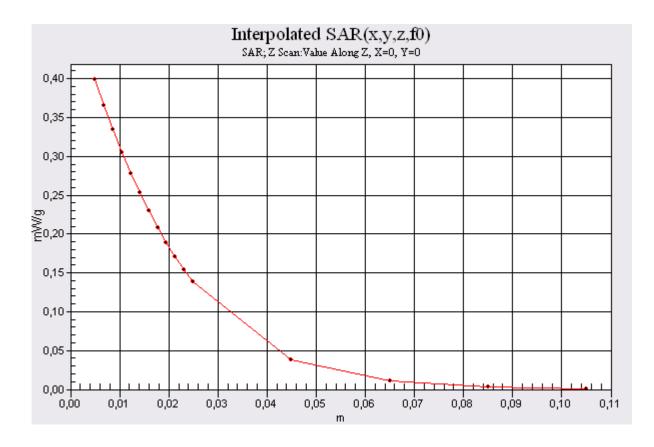
Reference Value = 34.3 V/m; Power Drift = -0.035 dB

Peak SAR (extrapolated) = 1.34 W/kg

SAR(1 g) = 0.917 mW/g; SAR(10 g) = 0.602 mW/g

Maximum value of SAR (measured) = 0.983 mW/g

**d=15mm, Pin=100mW/Z Scan (1x1x16):** Measurement grid: dx=20mm, dy=20mm, dz=20mm Maximum value of SAR (interpolated) = 0.399 mW/g



Date/Time: 2007-09-06 08:27:09

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: Dipole 835 MHz; Type: D835V2; Serial: D835V2 - SN:484** Communication System: CW; Frequency: 835 MHz;Duty Cycle: 1:1 Medium parameters used: f = 835 MHz;  $\sigma = 0.996$  mho/m;  $\varepsilon_r = 53.3$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section

Thantom section. That Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(6.86, 6.86, 6.86); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 3; Type: SAM; Serial: 1137

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

d=15mm, Pin=100mW 2/Area Scan (61x121x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 1.09 mW/g

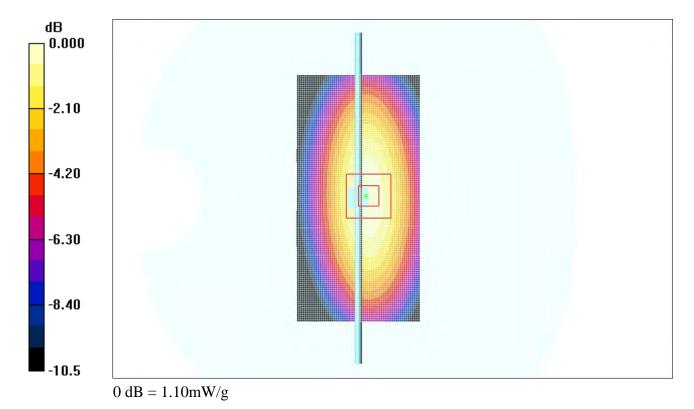
**d=15mm, Pin=100mW 2/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 33.2 V/m; Power Drift = 0.057 dB

Peak SAR (extrapolated) = 1.49 W/kg

SAR(1 g) = 1.01 mW/g; SAR(10 g) = 0.662 mW/g

Maximum value of SAR (measured) = 1.10 mW/g



Date/Time: 2007-09-06 10:05:04

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: GSM850 ; Frequency: 848.8 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 1.01$  mho/m;  $\varepsilon_r = 53.2$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(6.86, 6.86, 6.86); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 3; Type: SAM; Serial: 1137

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=15mm,Back,High ,Speech;HandsFree/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.343 mW/g

d=15mm,Back,High,Speech;HandsFree/Zoom Scan (5x5x7)/Cube 0: Measurement grid:

dx=8mm, dy=8mm, dz=5mm

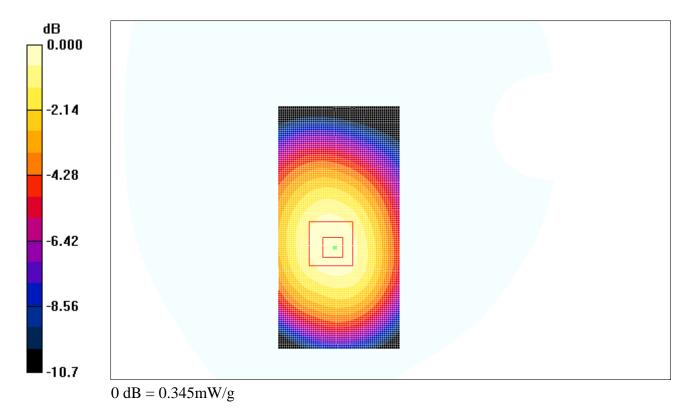
Reference Value = 6.96 V/m; Power Drift = 0.002 dB

Peak SAR (extrapolated) = 0.444 W/kg

SAR(1 g) = 0.324 mW/g; SAR(10 g) = 0.228 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.345 mW/g



Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: GSM850 GPRS2TX; Frequency: 848.8 MHz;Duty Cycle: 1:4.15 Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 1.01$  mho/m;  $\varepsilon_r = 53.2$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(6.86, 6.86, 6.86); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 3; Type: SAM; Serial: 1137

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=15mm,Back,High ,Data/Area Scan (41x81x1):** Measurement grid: dx=15mm, dy=15mm Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.517 mW/g

d=15mm,Back,High ,Data/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm,

dy=8mm, dz=5mm

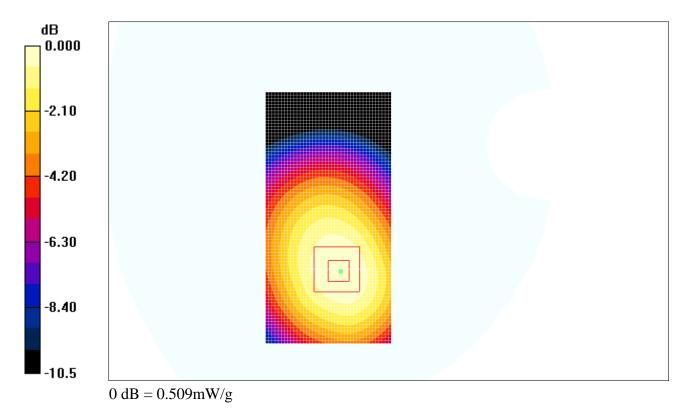
Reference Value = 9.54 V/m; Power Drift = -0.048 dB

Peak SAR (extrapolated) = 0.641 W/kg

SAR(1 g) = 0.482 mW/g; SAR(10 g) = 0.344 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.509 mW/g



Test Laboratory: Sony Ericsson Mobile Communications AB **DUT:** #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK Communication System: GSM850 GPRS2TX; Frequency: 848.8 MHz;Duty Cycle: 1:4.15 Medium parameters used (interpolated): f = 848.8 MHz;  $\sigma = 1.01$  mho/m;  $\varepsilon_r = 53.2$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(6.86, 6.86, 6.86); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 3; Type: SAM; Serial: 1137

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=15mm,Front,High ,Data/Area Scan (41x81x1):** Measurement grid: dx=15mm, dy=15mm Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.320 mW/g

d=15mm,Front,High ,Data/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm,

dy=8mm, dz=5mm

Reference Value = 8.01 V/m; Power Drift = -0.011 dB

Peak SAR (extrapolated) = 0.411 W/kg

SAR(1 g) = 0.302 mW/g; SAR(10 g) = 0.215 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.321 mW/g



Date/Time: 2007-09-06 08:27:09

Test Laboratory: Sony Ericsson Mobile Communications AB

DUT: Dipole 835 MHz; Type: D835V2; Serial: D835V2 - SN:484

Communication System: CW; Frequency: 835 MHz; Duty Cycle: 1:1

Medium parameters used: f = 835 MHz;  $\sigma = 0.996$  mho/m;  $\varepsilon_r = 53.3$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(6.86, 6.86, 6.86); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn428; Calibrated: 2007-01-18
- Phantom: SAM 3; Type: SAM; Serial: 1137

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

d=15mm, Pin=100mW 2/Area Scan (61x121x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 1.09 mW/g

**d=15mm, Pin=100mW 2/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

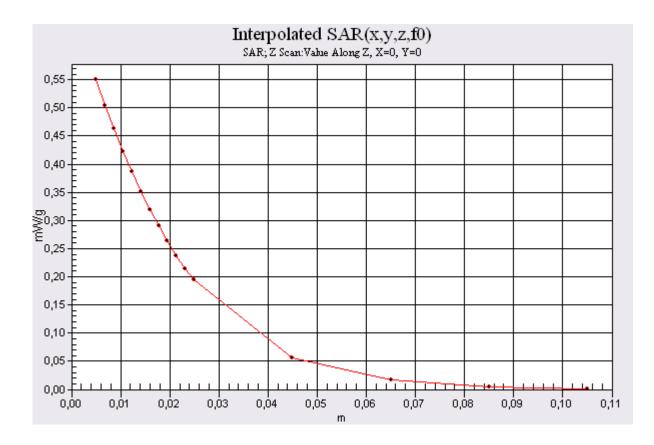
Reference Value = 33.2 V/m; Power Drift = 0.057 dB

Peak SAR (extrapolated) = 1.49 W/kg

SAR(1 g) = 1.01 mW/g; SAR(10 g) = 0.662 mW/g

Maximum value of SAR (measured) = 1.10 mW/g

**d=15mm, Pin=100mW 2/Z Scan (1x1x16):** Measurement grid: dx=20mm, dy=20mm, dz=20mm Maximum value of SAR (interpolated) = 0.551 mW/g



Date/Time: 2007-09-03 14:10:43

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: Dipole 1900 MHz; Type: D1900V2; Serial: SN:5d002** Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.47 mho/m;  $\epsilon_r$  = 38.9;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

d=10mm, Pin=100mW/Area Scan (61x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 4.44 mW/g

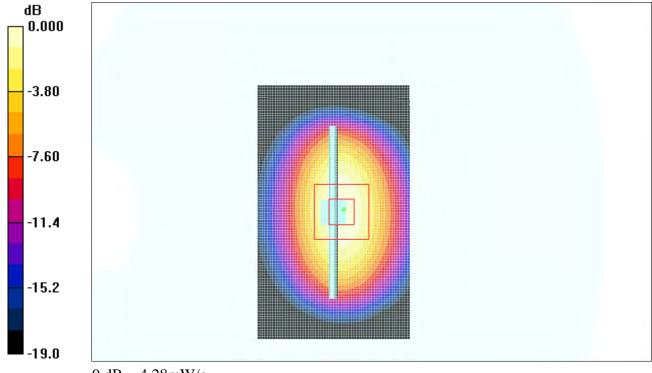
**d=10mm, Pin=100mW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 56.0 V/m; Power Drift = 0.091 dB

Peak SAR (extrapolated) = 6.71 W/kg

SAR(1 g) = 3.86 mW/g; SAR(10 g) = 2.01 mW/g

Maximum value of SAR (measured) = 4.28 mW/g



 $0 \, dB = 4.28 mW/g$ 

Date/Time: 2007-09-04 08:44:41

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: Dipole 1900 MHz; Type: D1900V2; Serial: SN:5d002** Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.47 mho/m;  $\epsilon_r$  = 38.9;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

d=10mm, Pin=100mW/Area Scan (61x101x1): Measurement grid: dx=10mm, dy=10mm

Maximum value of SAR (interpolated) = 4.41 mW/g

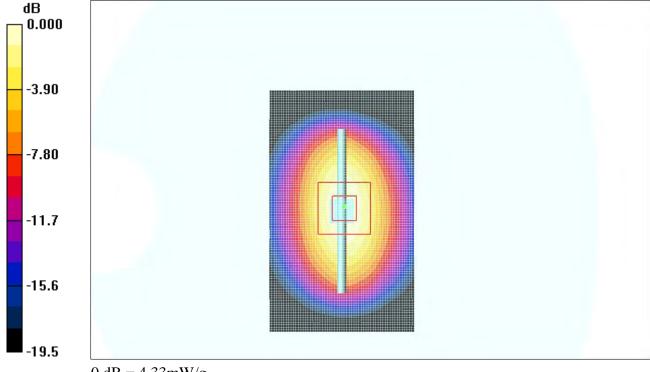
**d=10mm, Pin=100mW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

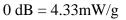
Reference Value = 57.7 V/m; Power Drift = 0.021 dB

Peak SAR (extrapolated) = 6.81 W/kg

SAR(1 g) = 3.86 mW/g; SAR(10 g) = 1.98 mW/g

Maximum value of SAR (measured) = 4.33 mW/g





Date/Time: 2007-09-03 14:39:52

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.44$  mho/m;  $\varepsilon_r = 39.1$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**Touch position - Low/Area Scan (61x111x1):** Measurement grid: dx=10mm, dy=10mm Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAD (intermelated) 0.764 mW/z

Maximum value of SAR (interpolated) = 0.764 mW/g

**Touch position - Low/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

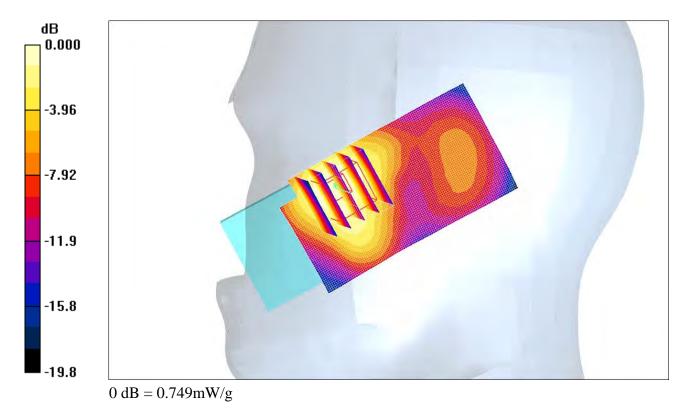
Reference Value = 10.6 V/m; Power Drift = -0.035 dB

Peak SAR (extrapolated) = 1.10 W/kg

SAR(1 g) = 0.685 mW/g; SAR(10 g) = 0.403 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.749 mW/g



Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK(open State)** Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.44$  mho/m;  $\varepsilon_r = 39.1$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18
- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**Touch position - Low/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.427 mW/g

**Touch position - Low/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

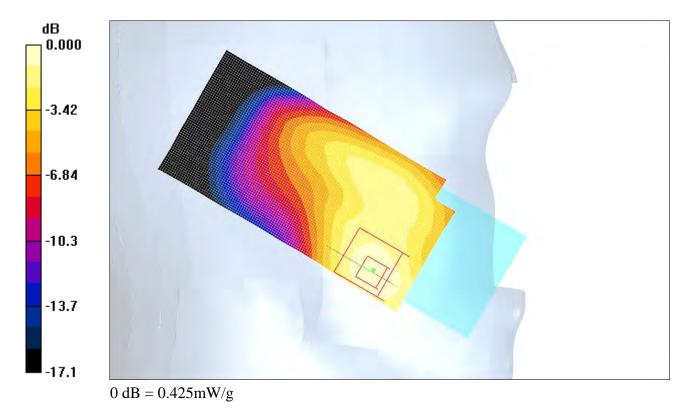
Reference Value = 4.68 V/m; Power Drift = -0.183 dB

Peak SAR (extrapolated) = 0.602 W/kg

SAR(1 g) = 0.380 mW/g; SAR(10 g) = 0.226 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.425 mW/g



Date/Time: 2007-09-04 11:17:58

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.44$  mho/m;  $\varepsilon_r = 39.1$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**Touch position - Low/Area Scan (61x121x1):** Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 1.06 mW/g

**Touch position - Low/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

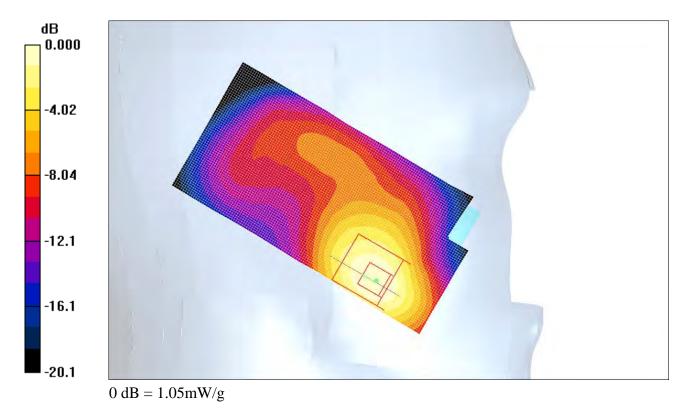
Reference Value = 9.47 V/m; Power Drift = -0.017 dB

Peak SAR (extrapolated) = 1.66 W/kg

SAR(1 g) = 0.922 mW/g; SAR(10 g) = 0.482 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 1.05 mW/g



# Test Laboratory: Sony Ericsson Mobile Communications AB DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK(open state)

Communication System: DCS 1900; Frequency: 1850.2 MHz; Duty Cycle: 1:8.3

Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.44 \text{ mho/m}$ ;  $\varepsilon_r = 39.1$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**Touch position - Low/Area Scan (61x111x1):** Measurement grid: dx=10mm, dy=10mm Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.455 mW/g

**Touch position - Low/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

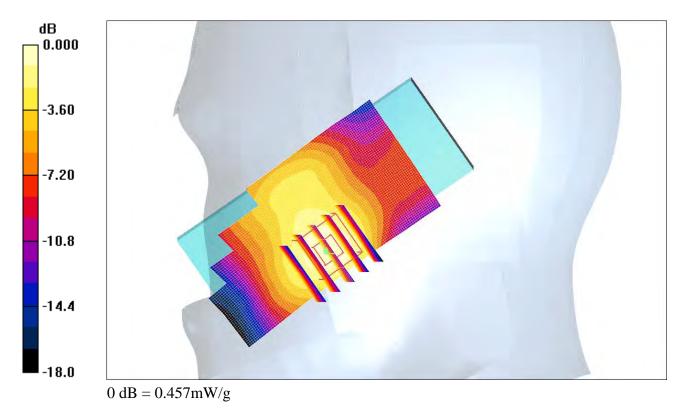
Reference Value = 6.97 V/m; Power Drift = 0.001 dB

Peak SAR (extrapolated) = 0.618 W/kg

SAR(1 g) = 0.413 mW/g; SAR(10 g) = 0.249 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.457 mW/g



Date/Time: 2007-09-04 13:22:51

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.44$  mho/m;  $\varepsilon_r = 39.1$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Left Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18
- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Tilt position - Low/Area Scan (61x131x1): Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.323 mW/g

**Tilt position - Low/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

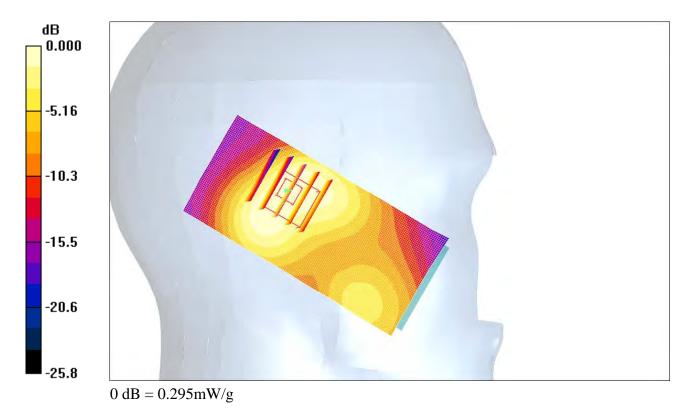
Reference Value = 15.2 V/m; Power Drift = -0.011 dB

Peak SAR (extrapolated) = 0.447 W/kg

SAR(1 g) = 0.276 mW/g; SAR(10 g) = 0.170 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.295 mW/g



Date/Time: 2007-09-04 09:49:57

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.44$  mho/m;  $\varepsilon_r = 39.1$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Right Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

Tilt position - Low/Area Scan (61x121x1): Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.345 mW/g

**Tilt position - Low/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

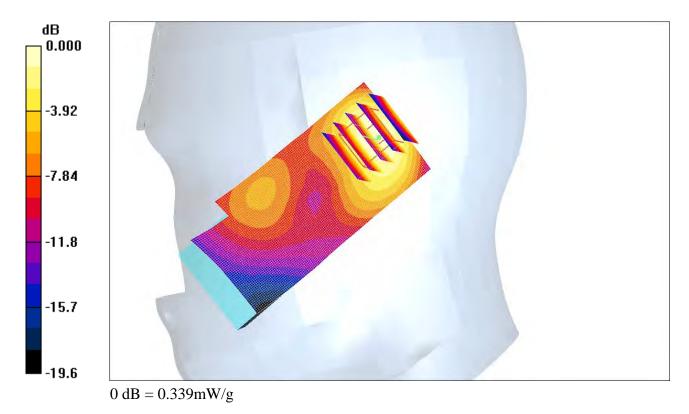
Reference Value = 15.9 V/m; Power Drift = 0.004 dB

Peak SAR (extrapolated) = 0.454 W/kg

SAR(1 g) = 0.308 mW/g; SAR(10 g) = 0.179 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.339 mW/g



Date/Time: 2007-09-03 14:10:43

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: Dipole 1900 MHz; Type: D1900V2; Serial: SN:5d002** Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.47 mho/m;  $\varepsilon_r$  = 38.9;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(5.21, 5.21, 5.21); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)Sensor-Surface: 0mm (Fix Surface)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=10mm, Pin=100mW/Area Scan (61x101x1):** Measurement grid: dx=10mm, dy=10mm Maximum value of SAR (interpolated) = 4.44 mW/g

 $d_{-10}mm Din_{-10}mW/7 com Scon (5x5x7)/Cube 0. Me$ 

**d=10mm, Pin=100mW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

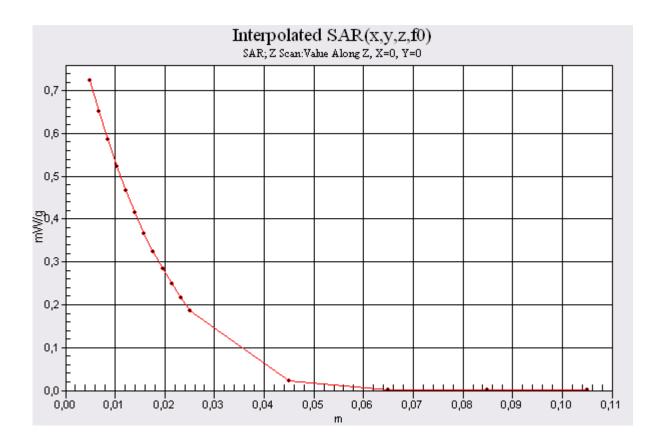
Reference Value = 56.0 V/m; Power Drift = 0.091 dB

Peak SAR (extrapolated) = 6.71 W/kg

SAR(1 g) = 3.86 mW/g; SAR(10 g) = 2.01 mW/g

Maximum value of SAR (measured) = 4.28 mW/g

**d=10mm, Pin=100mW/Z Scan (1x1x16):** Measurement grid: dx=20mm, dy=20mm, dz=20mm Maximum value of SAR (interpolated) = 0.724 mW/g



Date/Time: 2007-09-05 08:29:27

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: Dipole 1900 MHz; Type: D1900V2; Serial: SN:5d002** Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.57 mho/m;  $\varepsilon_r$  = 51.1;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(4.75, 4.75, 4.75); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=10mm, Pin=100mW 070905/Area Scan (71x101x1):** Measurement grid: dx=10mm, dv=10mm

Maximum value of SAR (interpolated) = 4.50 mW/g

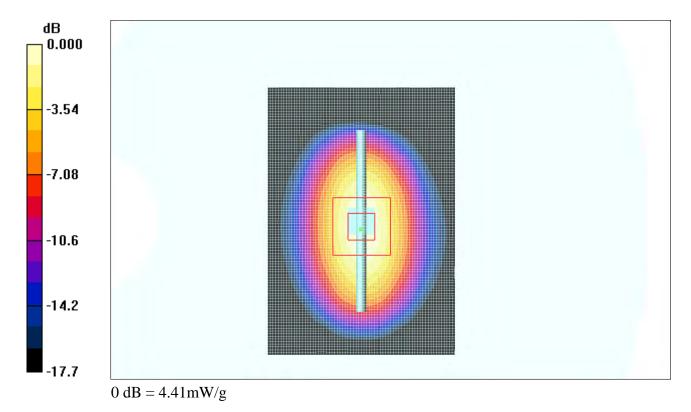
**d=10mm, Pin=100mW 070905/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 56.8 V/m; Power Drift = 0.005 dB

Peak SAR (extrapolated) = 6.64 W/kg

SAR(1 g) = 3.91 mW/g; SAR(10 g) = 2.06 mW/g

Maximum value of SAR (measured) = 4.41 mW/g



Date/Time: 2007-09-04 16:36:42

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3 Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.51$  mho/m;  $\varepsilon_r = 51.2$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(4.75, 4.75, 4.75); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=15mm,Back,Low ,Speech;PHF/Area Scan (61x111x1):** Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.328 mW/g

**d=15mm,Back,Low ,Speech;PHF/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm

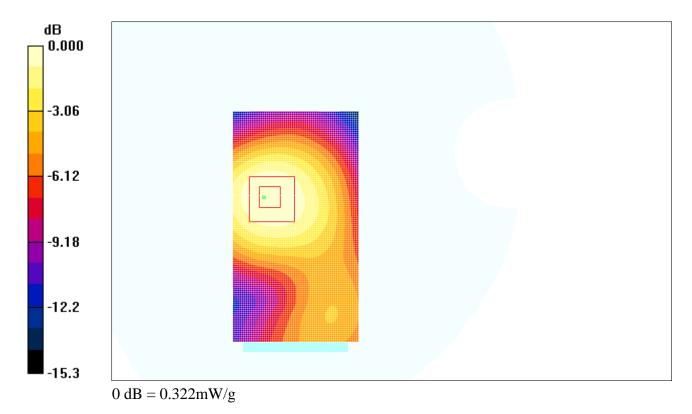
Reference Value = 10.4 V/m; Power Drift = -0.065 dB

Peak SAR (extrapolated) = 0.456 W/kg

SAR(1 g) = 0.304 mW/g; SAR(10 g) = 0.191 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.322 mW/g



Date/Time: 2007-09-05 11:04:44

Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: GSM1900 GPRS2TX; Frequency: 1850.2 MHz;Duty Cycle: 1:4.15 Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.51$  mho/m;  $\epsilon_r = 51.2$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(4.75, 4.75, 4.75); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=15mm,Back,Low;GPRS2TX 2/Area Scan 2 (71x121x1):** Measurement grid: dx=10mm, dy=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.439 mW/g

d=15mm,Back,Low;GPRS2TX 2/Zoom Scan 2 (5x5x7)/Cube 0: Measurement grid:

dx=8mm, dy=8mm, dz=5mm

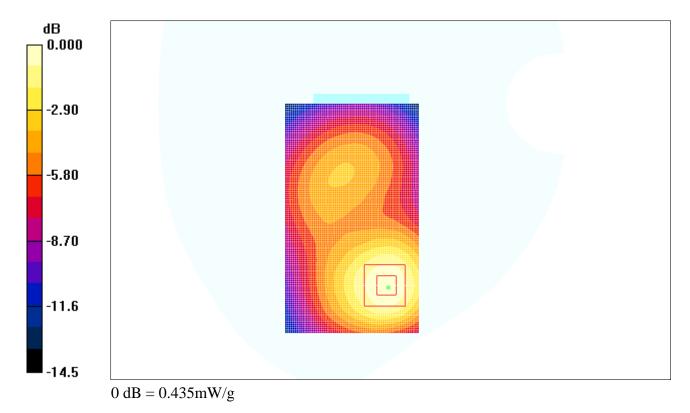
Reference Value = 5.98 V/m; Power Drift = -0.125 dB

Peak SAR (extrapolated) = 0.606 W/kg

SAR(1 g) = 0.397 mW/g; SAR(10 g) = 0.240 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.435 mW/g



Test Laboratory: Sony Ericsson Mobile Communications AB **DUT: #8734; Type: AAC-1052051-BV; Serial: CB5A0DZKHK** Communication System: GSM1900 GPRS2TX; Frequency: 1850.2 MHz;Duty Cycle: 1:4.15 Medium parameters used (interpolated): f = 1850.2 MHz;  $\sigma = 1.51$  mho/m;  $\varepsilon_r = 51.2$ ;  $\rho = 1000$  kg/m<sup>3</sup> Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(4.75, 4.75, 4.75); Calibrated: 2007-01-16

- Sensor-Surface: 4mm (Mechanical Surface Detection)

- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=15mm,front,Low;GPRS2TX/Area Scan (71x121x1):** Measurement grid: dx=10mm, dv=10mm

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (interpolated) = 0.229 mW/g

**d=15mm,front,Low;GPRS2TX/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dv=8mm, dz=5mm

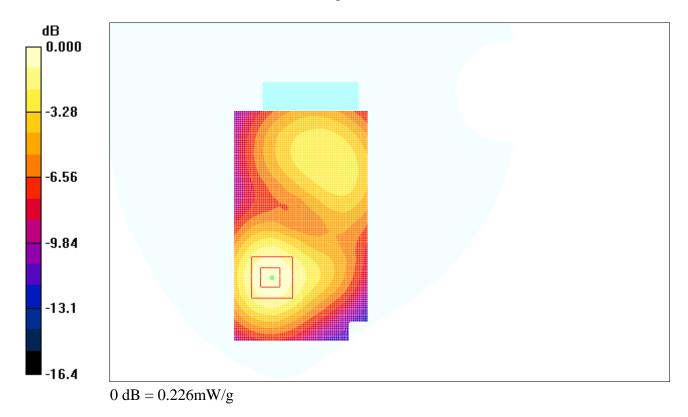
Reference Value = 5.43 V/m; Power Drift = -0.106 dB

Peak SAR (extrapolated) = 0.326 W/kg

SAR(1 g) = 0.205 mW/g; SAR(10 g) = 0.122 mW/g

Info: Interpolated medium parameters used for SAR evaluation.

Maximum value of SAR (measured) = 0.226 mW/g



Test Laboratory: Sony Ericsson Mobile Communications AB

#### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: SN:5d002

Communication System: CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.57 mho/m;  $\varepsilon_r$  = 51.1;  $\rho$  = 1000 kg/m<sup>3</sup>

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1815; ConvF(4.75, 4.75, 4.75); Calibrated: 2007-01-16

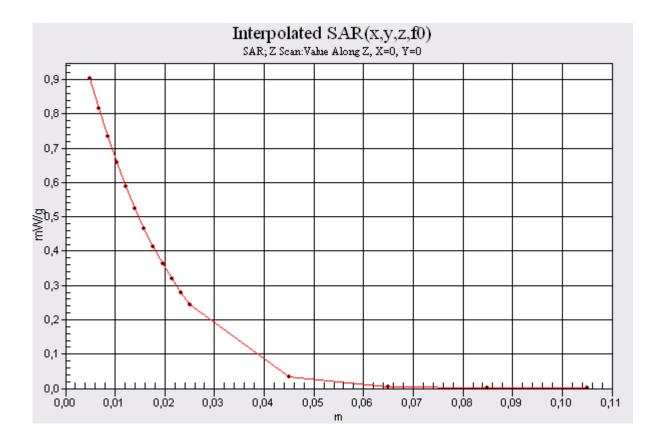
- Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn428; Calibrated: 2007-01-18

- Phantom: SAM 4; Type: SAM; Serial: 1053

- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

**d=10mm, Pin=100mW 070905/Z Scan (1x1x16):** Measurement grid: dx=20mm, dy=20mm, dz=20mm

Maximum value of SAR (interpolated) = 0.903 mW/g



#### **Calibration Laboratory of** Schmid & Partner **Engineering AG** Zeughausstrasse 43, 8004 Zurich, Switzerland

10/20/20/20/20/20/2010/01





Schweizerischer Kalibrierdienst

- Service suisse d'étalonnage
- С Servizio svizzero di taratura S
  - Swiss Calibration Service

Accredited by the Swiss Federal Office of Metrology and Accreditation The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

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Accreditation No.: SCS 108

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#### Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





S Schweizerischer Kalibrierdienst

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- C Servizio svizzero di taratura
- S Swiss Calibration Service

Accreditation No.: SCS 108

Accredited by the Swiss Federal Office of Metrology and Accreditation The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

#### Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
Polarization φ	φ rotation around probe axis
Polarization 9	9 rotation around an axis that is in the plane normal to probe axis (at
	measurement center), i.e., $\vartheta = 0$ is normal to probe axis

#### **Calibration is Performed According to the Following Standards:**

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001

#### Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization θ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E<sup>2</sup>-field uncertainty inside TSL (see below *ConvF*).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z* \* *ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

# Probe ES3DV3

# SN:3062

Manufactured: Last calibrated: Recalibrated:

January 30, 2004 January 20, 2006 January 16, 2007

#### Calibrated for DASY Systems

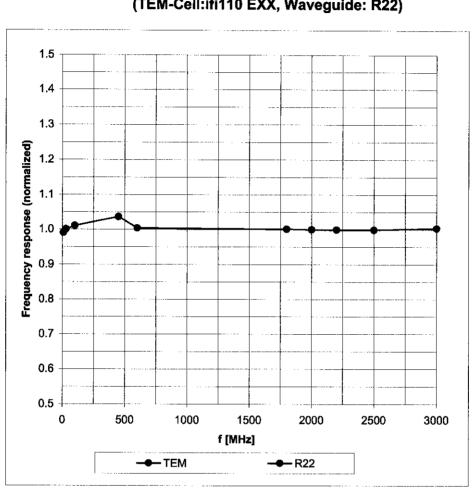
(Note: non-compatible with DASY2 system!)

# DASY - Parameters of Probe: ES3DV3 SN:3062

Sens	Sensitivity in Free Space <sup>A</sup> Diode Compression <sup>B</sup>					
	NormX NormY NormZ	1.1	8 ± 10.1% 9 ± 10.1% 0 ± 10.1%	μV/(V/m) <sup>2</sup> μV/(V/m) <sup>2</sup> μV/(V/m) <sup>2</sup>	DCP X DCP Y DCP Z	95 m∨ 96 m∨ 95 m∨
Sens	Sensitivity in Tissue Simulating Liquid (Conversion Factors)					
Please	see Page 8.					
Boun	dary Effect	:				
TSL	9	00 MHz	Typical SA	NR gradient: 5 %	per mm	
	Sensor Cente SAR <sub>be</sub> [%] SAR <sub>be</sub> [%]	Without	m Surface Di Correction A prrection Algo	lgorithm	<b>3.0 mm</b> 3.2 0.0	<b>4.0 mm</b> 1.2 0.7
TSL	. 17	50 MHz	Typical SA	AR gradient: 10 %	per mm	
	Sensor Cente SAR <sub>be</sub> [%] SAR <sub>be</sub> [%]	Without	m Surface Di Correction A prrection Algo	lgorithm	<b>3.0 mm</b> 4.0 0.2	<b>4.0 mm</b> 1.9 0.2
Sens	or Offset					
	Probe Tip to S	Sensor Cen	ter		<b>2.0</b> mm	
The		rtainty of		nt is stated as	the standard	man de inter alt
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.						

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

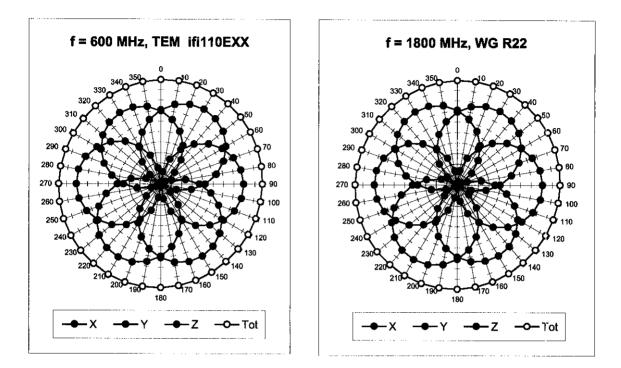
<sup>B</sup> Numerical linearization parameter: uncertainty not required.



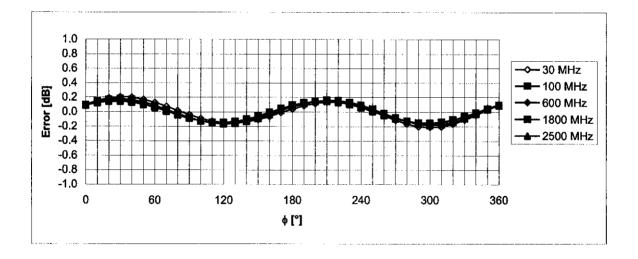
### **Frequency Response of E-Field**

(TEM-Cell:ifi110 EXX, Waveguide: R22)

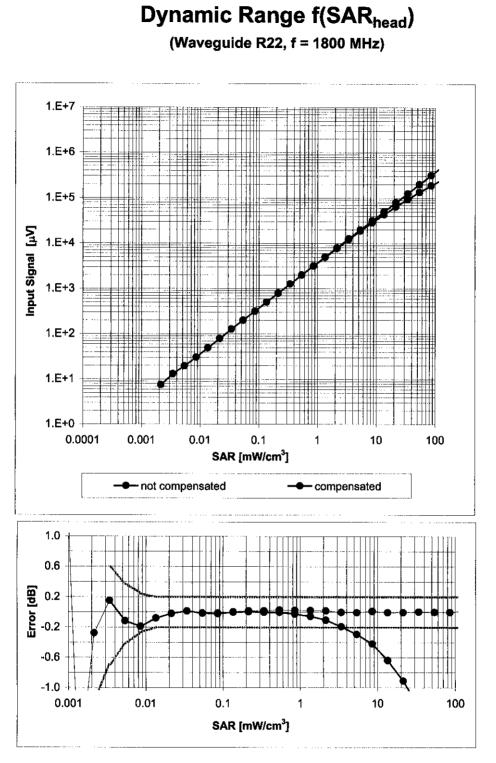
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)



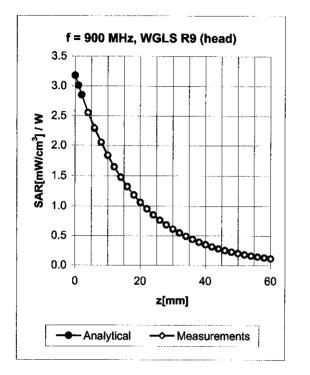
## **Receiving Pattern (** $\phi$ **),** $\vartheta$ = 0°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)

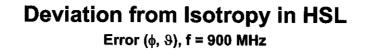


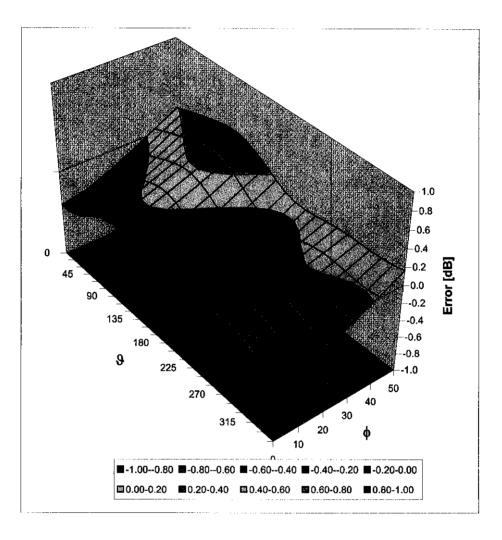
### **Conversion Factor Assessment**

	30.0					
	25.0				_	
w / [נ	20.0					
[mW/cn	20.0	<del>م</del>				
SAR	10.0	90				
	5.0 -		00000	40		
	0.0			~00000		000
	0		20	40		60
			z[n	nm]		

f [MHz]	Validity [MHz] <sup>C</sup>	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
835	± 50 / ± 100	Head	41.5 ± 5%	0.90 ± 5%	1.00	1.11	6.06 ± 11.0% (k=2)
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	1.00	1.15	5.99 ± 11.0% (k=2)
1750	± 50 / ± 100	Head	40.1 ± 5%	1.37 ± 5%	0.85	1.21	4.84 ± 11.0% (k=2)
1900	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.86	1.19	4.73 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.67	1.40	4.34 ± 11.8% (k=2)
835	± 50 / ± 100	Body	55.2 ± 5%	0.97 ± 5%	0.98	1.15	6.13 ± 11.0% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	1.00	1.14	5.84 ± 11.0% (k=2)
1750	± 50 / ± 100	Body	53.4 ± 5%	1.49 ± 5%	0.80	1.29	4.72 ± 11.0% (k=2)
1900	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.71	1.35	4.53 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.86	1.10	4.09 ± 11.8% (k=2)

<sup>C</sup> The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.





Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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- S **Swiss Calibration Service**

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Client	Son Medications		Certificates	
Object		ETBDV8-SN 1	<b>615</b>	
Calibratic	on procedure(s)	OA CAL-01 v6 Calibration proci	edure for dosimetric E-field probe	
Calibratio	on date:	<b>January 16, 200</b>		
Condition	of the calibrated item			
			ional standards, which realize the physical us probability are given on the following pages a	
Ali calibra	ations have been conduct	ted in the closed laborate	ry facility: environment temperature (22 $\pm$ 3)°	'C and humidity < 70%.
Calibratio	on Equipment used (M&T	E critical for calibration)		
Primary S	Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power m	eter E4419B	GB41293874	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Power se	nsor E4412A	MY41495277	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Power se	nsor E4412A	MY41498087	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Referenc	e 3 dB Attenuator	SN: S5054 (3c)	10-Aug-06 (METAS, No. 217-00592)	Aug-07
Referenc	e 20 dB Attenuator	SN: S5086 (20b)	4-Apr-06 (METAS, No. 251-00558)	Apr-07
Referenc	e 30 dB Attenuator	SN: S5129 (30b)	10-Aug-06 (METAS, No. 217-00593)	Aug-07
Referenc	e Probe ES3DV2	SN: 3013	4-Jan-07 (SPEAG, No. ES3-3013_Jan07	) Jan-08
DAE4		SN: 654	21-Jun-06 (SPEAG, No. DAE4-654_Jun0	6) Jun-07
Seconda	ry Standards	ID #	Check Date (in house)	Scheduled Check
RF gener	rator HP 8648C	US3642U01700	4-Aug-99 (SPEAG, in house check Nov-0	05) In house check: Nov-07
Network	Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Oct-0	06) In house check: Oct-07
-		Name	Function	Signature
Calibrate	d by:	Kalja Pokovic	Technical Measoer	AL- 14
Approved	i by:	Niels Kutier	Quality Manager	X / X Konger
This calit	pration certificate shall no	t be reproduced except in	n full without written approval of the laborator	issued: January 16, 2007 v.
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#### **Calibration Laboratory of**

Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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Accreditation No.: SCS 108

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#### Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
Polarization $\phi$	φ rotation around probe axis
Polarization 9	9 rotation around an axis that is in the plane normal to probe axis (at
	measurement center), i.e., $\vartheta = 0$ is normal to probe axis

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001

#### Methods Applied and Interpretation of Parameters:

- NORMx, y,z: Assessed for E-field polarization θ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx, y,z are only intermediate values, i.e., the uncertainties of NORMx, y,z does not effect the E<sup>2</sup>-field uncertainty inside TSL (see below *ConvF*).
- NORM(f)x,y,z = NORMx,y,z \* frequency\_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z* \* *ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

# Probe ET3DV6

# SN:1815

Manufactured: Last calibrated: Recalibrated:

February 27, 2004 January 20, 2006 January 16, 2007

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

# DASY - Parameters of Probe: ET3DV6 SN:1815

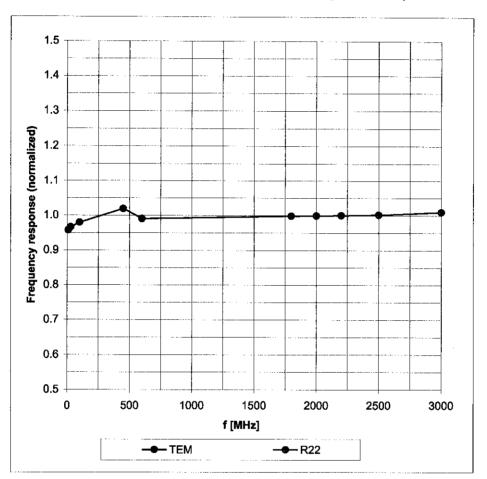
Sens	itivity in Fre	e Spac	e <sup>A</sup>		Diode	Compression <sup>B</sup>
	NormX	1.9	<b>3</b> ± 10.1%	μV/(V/m) <sup>2</sup>	DCP X	<b>90</b> mV
	NormY	1.9	<b>7</b> ± 10.1%	μV/(V/m) <sup>2</sup>	DCP Y	<b>93</b> mV
	NormZ	2.0	<b>7</b> ± 10.1%	μ <b>V/(V/m)</b> ²	DCP Z	96 mV
Sens	itivity in Tis	sue Sim	ulating Li	quid (Conver	sion Factor	s)
Please	see Page 8.					
Boun	idary Effect					
TSL	9	00 MHz	Typical SA	R gradient: 5 % j	oer mm	
	Sensor Cente SAR <sub>be</sub> [%] SAR <sub>be</sub> [%]	Without	om Surface Di Correction A prrection Algo	Igorithm	<b>3.7 mm</b> 5.0 0.0	<b>4.7 mm</b> 2.3 0.0
TSL	17	50 MHz	Typical SA	R gradient: 10 %	per mm	
	Sensor Cente	r to Phanto	m Surface Di	stance	3.7 mm	4.7 mm
	SAR <sub>be</sub> [%]	Without	Correction A	lgorithm	6.8	3.9
	SAR <sub>be</sub> [%]	With Co	prrection Algo	rithm	0.1	0.3
Sens	or Offset					
	Probe Tip to S	Sensor Cen	ter		<b>2.7</b> mm	

# The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

<sup>A</sup> The uncertainties of NormX,Y,Z do not affect the E<sup>2</sup>-field uncertainty inside TSL (see Page 8).

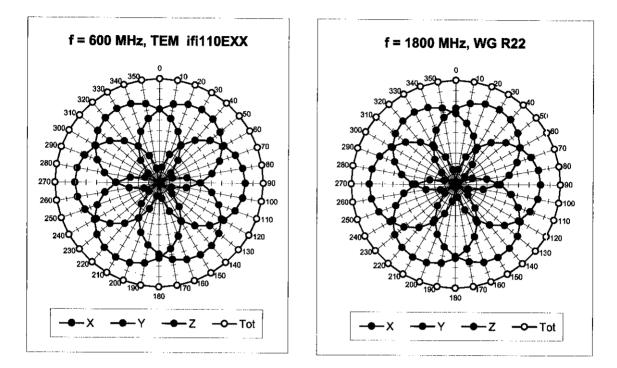
<sup>B</sup> Numerical linearization parameter: uncertainty not required.

## **Frequency Response of E-Field**

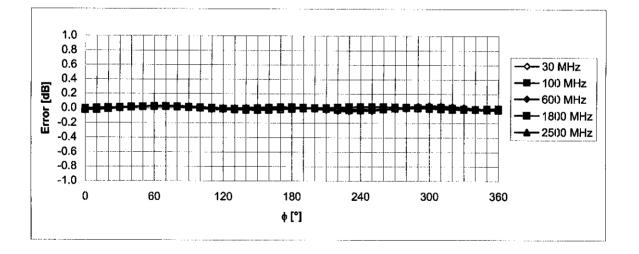


(TEM-Cell:ifi110 EXX, Waveguide: R22)

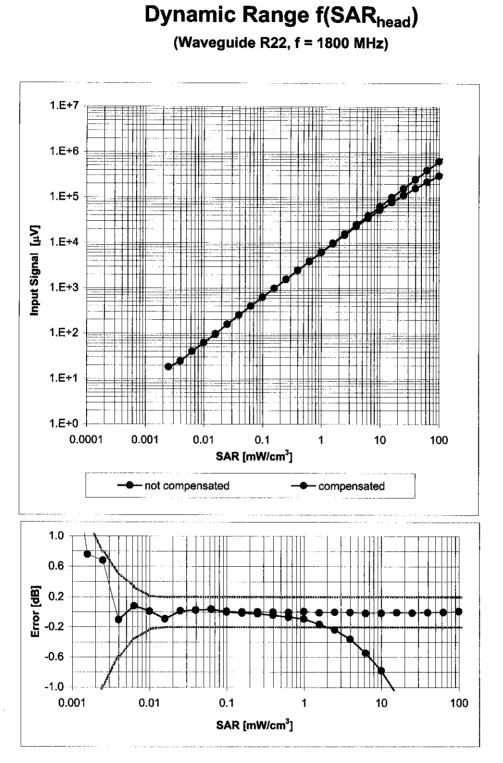
Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)



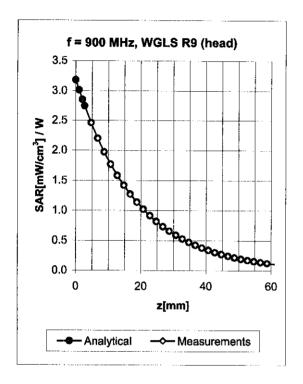
# Receiving Pattern ( $\phi$ ), $\vartheta = 0^{\circ}$



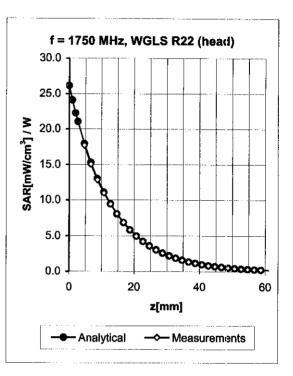
Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)



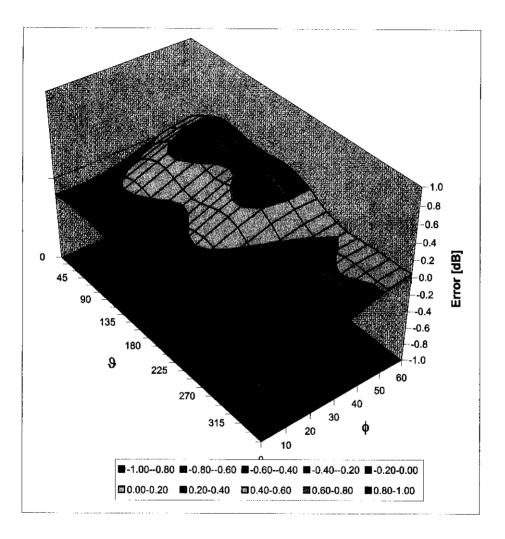
# **Conversion Factor Assessment**



f [MHz]	Validity [MHz] <sup>c</sup>	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
835	± 50 / ± 100	Head	41.5 ± 5%	0.90 ± 5%	0.27	2.57	6.79 ± 11.0% (k=2)
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.28	2.64	6.73 ± 11.0% (k=2)
1750	± 50 / ± 100	Head	40.1 ± 5%	1.37 ± 5%	0.48	2.54	5.36 ± 11.0% (k=2)
1900	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.52	2.59	5.21 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.65	2.05	4.71 ± 11.8% (k=2)
835	± 50 / ± 100	Body	55.2 ± 5%	0.97 ± 5%	0.25	2.85	6.86 ± 11.0% (k=2)
<del>9</del> 00	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	0.28	2.87	6.50 ± 11.0% (k=2)
1750	± 50 / ± 100	Body	53.4 ± 5%	1.49 ± 5%	0.50	2.87	4.97 ± 11.0% (k=2)
1900	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.65	2.45	4.75 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.66	1.82	4.16 ± 11.8% (k=2)

<sup>c</sup> The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

### Deviation from Isotropy in HSL Error ( $\phi$ , $\vartheta$ ), f = 900 MHz



#### Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)



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Accreditation No.: SCS 108

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Client	Sony Ellesop	n <b>Lund</b>		Clerificate No.	
S. I.					
Object		DISSIV	N: 464		
Calibrati	on procedure(s)	2013月20日13月20日開始中国13月20日20日1月20日 2013月20日13月20日開始中国13月20日13月20日20日13月20日 2013月20日13月20日13月20日13月20日13月20日20日13月20日 2013月20日13月20日13月20日13月20日13月20日13月20日13月20日13月20日13月20日13月	ncceciure ionclipol	e validation tite	つけはは、は、は、「「、「、」」、「、」、「、」、「、」、「、」、「、」、「、」、「
Calibrati	on date:	January 15,	2007		

Condition of the calibrated item

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

In Tolerance

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	03-Oct-06 (METAS, No. 217-00608)	Oct-07
Power sensor HP 8481A	US37292783	03-Oct-06 (METAS, No. 217-00608)	Oct-07
Reference 20 dB Attenuator	SN: 5086 (20g)	10-Aug-06 (METAS, No 217-00591)	Aug-07
Reference 10 dB Attenuator	SN: 5047.2 (10r)	10-Aug-06 (METAS, No 217-00591)	Aug-07
Reference Probe ET3DV6 (HF)	SN 1507	19-Oct-06 (SPEAG, No. ET3-1507_Oct06)	Oct-07
DAE4	SN 907	20-Jul-06 (SPEAG, No. DAE4-907_Jul06)	Jul-07
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (SPEAG, in house check Oct-05)	In house check: Oct-07
RF generator Agilent E4421B	MY41000675	11-May-05 (SPEAG, in house check Nov-05)	In house check: Nov-07
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (SPEAG, in house check Oct-06)	In house check: Oct-07
	Name	Function	Signature
Calibrated by:	Marcel Fiehr	Laboratory Technician	Nall
Approved by:	Kata Pokovic	Technical'Manager	in the second
			Issued: January 16, 2007
This calibration certificate shall no	t be reproduced except in	full without written approval of the laboratory.	

Calibration Laboratory of Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland

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  - Swiss Callbration Service

Accreditation No.: SCS 108

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#### Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

#### **Additional Documentation:**

d) DASY4 System Handbook

#### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

#### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY4	V4.7
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V4.9	
Distance Dipole Center - TSL	15 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	and the second
Frequency	835 MHz ± 1 MHz	

#### Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	41.5	0.90 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	40.2 ± 6 %	0.88 mho/m ± 6 %
Head TSL temperature during test	(22.1 ± 0.2) °C		

#### SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	2.31 mW / g
SAR normalized	normalized to 1W	9.24 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	9.20 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	condition	······································
SAR measured	250 mW input power	1.51 mW / g
SAR normalized	normalized to 1W	6.04 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	6.00 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### **Body TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	55.2	0.97 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	54.1 ± 6 %	1.01 mho/m ± 6 %
Body TSL temperature during test	(21.9 ± 0.2) °C		

#### SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	condition	
SAR measured	250 mW input power	2.47 mW / g
SAR normalized	normalized to 1W	9.88 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	9.48 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	
SAR measured	250 mW input power	1.62 mW / g
SAR normalized	normalized to 1W	6.48 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	6.29 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### Appendix

#### **Antenna Parameters with Head TSL**

Impedance, transformed to feed point	52.4 Ω - 3.2 jΩ
Return Loss	- 28.1 dB

#### Antenna Parameters with Body TSL

Impedance, transformed to feed point	48.2 Ω - 4.8 jΩ
Return Loss	- 25.6 dB

#### **General Antenna Parameters and Design**

Electrical Delay (one direction)	4.005
	1.395 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

#### **Additional EUT Data**

Manufactured by	SPEAG
Manufactured on	April 23, 2003

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 835 MHz; Type: D835V2; Serial: D835V2 - SN: 484

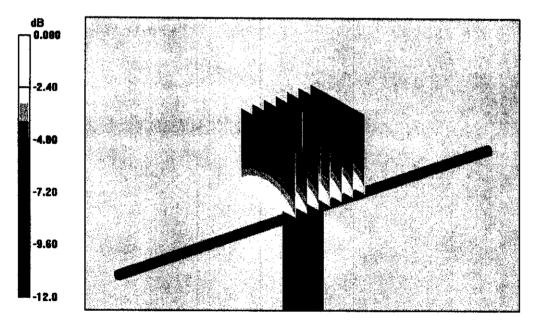
Communication System: CW; Frequency: 835 MHz;Duty Cycle: 1:1 Medium: HSL 900 MHz; Medium parameters used: f = 835 MHz;  $\sigma$  = 0.88 mho/m;  $\epsilon_r$  = 40.3;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

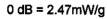
#### DASY4 Configuration:

- Probe: ET3DV6 SN1507 (HF); ConvF(6.09, 6.09, 6.09); Calibrated: 19.10.2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn907; Calibrated: 20.07.2006
- Phantom: Flat Phantom 4.9L; Type: QD000P49AA; ;
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

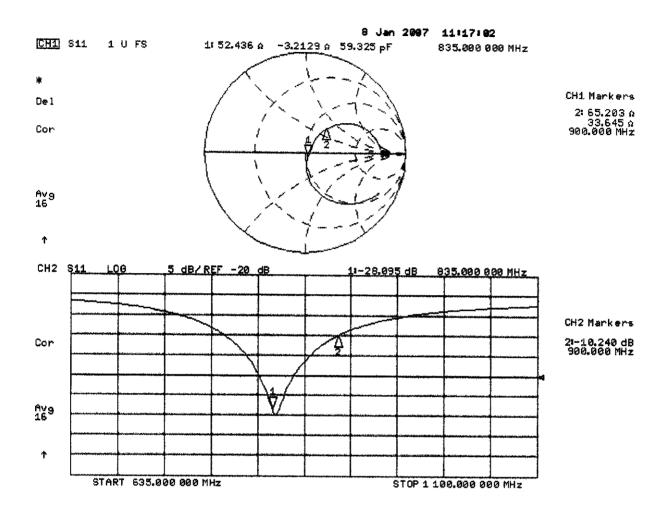
# Pin = 250 mW; d = 15 mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 55.7 V/m; Power Drift = -0.006 dB Peak SAR (extrapolated) = 3.40 W/kg SAR(1 g) = 2.31 mW/g; SAR(10 g) = 1.51 mW/g Maximum value of SAR (measured) = 2.47 mW/g





#### Impedance Measurement Plot for Head TSL



Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 835 MHz; Type: D835V2; Serial: D835V2 - SN:484

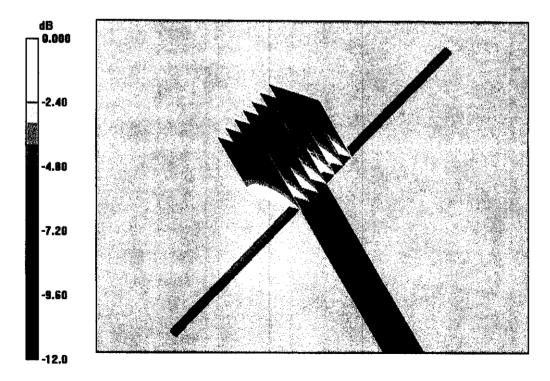
Communication System: CW; Frequency: 835 MHz;Duty Cycle: 1:1 Medium: MSL900; Medium parameters used: f = 835 MHz;  $\sigma$  = 1.01 mho/m;  $\epsilon_r$  = 54.1;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

#### DASY4 Configuration:

- Probe: ET3DV6 SN1507 (HF); ConvF(5.75, 5.75, 5.75); Calibrated: 19.10.2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn907; Calibrated: 20.07.2006
- Phantom: Flat Phantom 4.9L; Type: QD000P49AA; ;
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

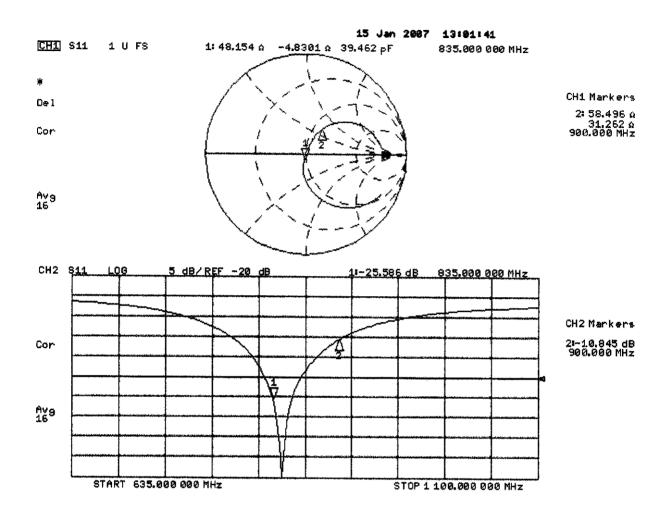
# **Unnamed procedure/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 53.8 V/m; Power Drift = 0.018 dB Peak SAR (extrapolated) = 3.55 W/kg SAR(1 g) = 2.47 mW/g; SAR(10 g) = 1.62 mW/g Maximum value of SAR (measured) = 2.66 mW/g





#### Impedance Measurement Plot for Body TSL



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Swiss Calibration Service

Accreditation No.: SCS 108

Object D1900V2 - SN: 5d002 OA CALLORIVO Calibration procedure(s) Calibration procedure for diople validation kit January 16, 2007 Calibration date: In Tolerance Condition of the calibrated item This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%. Calibration Equipment used (M&TE critical for calibration) ID # Scheduled Calibration **Primary Standards** Cal Date (Calibrated by, Certificate No.) Power meter EPM-442A GB37480704 03-Oct-06 (METAS, No. 217-00608) Oct-07 Power sensor HP 8481A US37292783 Oct-07 03-Oct-06 (METAS, No. 217-00608) Reference 20 dB Attenuator SN: 5086 (20g) 10-Aug-06 (METAS, No 217-00591) Aug-07 Reference 10 dB Attenuator SN: 5047.2 (10r) 10-Aug-06 (METAS, No 217-00591) Aug-07 Reference Probe ET3DV6 SN: 1507 19-Oct-06 (SPEAG, No. ET3-1507 Oct06) Oct-07 Reference Probe ES3DV3 SN: 3025 19-Oct-06 (SPEAG, No. ES3-3025\_Oct06) Oct-07 DAE4 SN 907 20-Jul-06 (SPEAG, No. DAE4-907\_Jul06) Jul-07 ID# Scheduled Check Secondary Standards Check Date (in house) Power sensor HP 8481A MY41092317 18-Oct-02 (SPEAG, in house check Oct-05) In house check: Oct-07 RF generator Agilent E4421B MY41000675 11-May-05 (SPEAG, in house check Nov-05) In house check: Nov-07 Network Analyzer HP 8753E US37390585 S4206 18-Oct-01 (SPEAG, in house check Oct-06) In house check: Oct-07 Name Function Signature Laboratory Technicia Calibrated by: mical Manapor Approved by: Katle Pokovic Issued: January 17, 2007 This calibration certificate shall not be reproduced except in full without written approval of the laboratory. Page 1 of 9 Certificate No: D1900V2-5d002 Jan07

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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#### Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

#### Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

#### Additional Documentation:

d) DASY4 System Handbook

#### Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end • of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power. •
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

#### **Measurement Conditions**

DASY system configuration, as far as not given on page 1.

DASY Version	DASY4	V4.7
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V5.0	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	1900 MHz ± 1 MHz	

Head TSL parameters The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	40.0	1.40 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	38.8 ± 6 %	1.43 mho/m ± 6 %
Head TSL temperature during test	(22.0 ± 0.2) °C		

#### SAR result with Head TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Head TSL	condition	
SAR measured	250 mW input power	9.61 mW / g
SAR normalized	normalized to 1W	38.4 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	37.4 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	5.04 mW / g
SAR normalized	normalized to 1W	20.2 mW / g
SAR for nominal Head TSL parameters <sup>1</sup>	normalized to 1W	19.8 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>1</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### **Body TSL parameters**

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	53.3	1.52 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	51.9 ± 6 %	1.55 mho/m ± 6 %
Body TSL temperature during test	(21.1 ± 0.2) °C		

#### SAR result with Body TSL

SAR averaged over 1 cm <sup>3</sup> (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	9.94 mW / g
SAR normalized	normalized to 1W	39.8 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	38.6 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm <sup>3</sup> (10 g) of Body TSL	condition	
SAR measured	250 mW input power	5.24 mW / g
SAR normalized	normalized to 1W	21.0 mW / g
SAR for nominal Body TSL parameters <sup>2</sup>	normalized to 1W	20.6 mW / g ± 16.5 % (k=2)

<sup>&</sup>lt;sup>2</sup> Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

#### Appendix

#### Antenna Parameters with Head TSL

Impedance, transformed to feed point	51.8 Ω - 0.3 jΩ
Return Loss	- 34.9 dB

#### Antenna Parameters with Body TSL

Impedance, transformed to feed point	48.2 Ω + 2.3 jΩ
Return Loss	- 30.5 dB

#### **General Antenna Parameters and Design**

Electrical Delay (one direction)	1.177 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

#### **Additional EUT Data**

Manufactured by	SPEAG
Manufactured on	February 14, 2002

#### DASY4 Validation Report for Head TSL

Test Laboratory: SPEAG, Zurich, Switzerland

#### DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d002

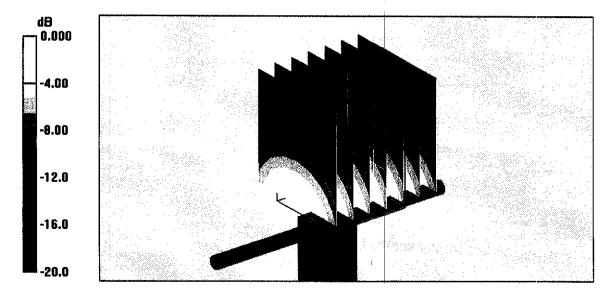
Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium: HSL U10 BB; Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.43 mho/m;  $\epsilon_{\rm f}$  = 38.8;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ET3DV6 SN1507 (HF); ConvF(4.97, 4.97, 4.97); Calibrated: 19.10.2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn907; Calibrated: 20.07.2006
- Phantom: Flat Phantom 4.9L; Type: QD000P49AA; ;
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

#### Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

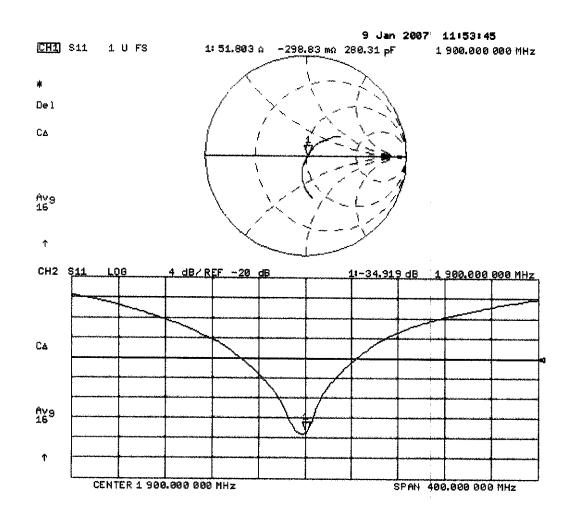
Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 91.7 V/m; Power Drift = 0.033 dB Peak SAR (extrapolated) = 17.0 W/kg SAR(1 g) = 9.61 mW/g; SAR(10 g) = 5.04 mW/g Maximum value of SAR (measured) = 11.0 mW/g



0 dB = 11.0mW/g

# Impedance Measurement Plot for Head TSL

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Test Laboratory: SPEAG, Zurich, Switzerland

# DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d002

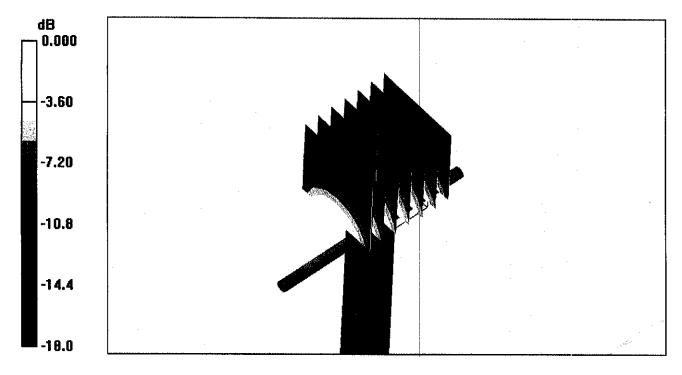
Communication System: CW; Frequency: 1900 MHz;Duty Cycle: 1:1 Medium: MSL U10 BB; Medium parameters used: f = 1900 MHz;  $\sigma$  = 1.55 mho/m;  $\epsilon_r$  = 52.1;  $\rho$  = 1000 kg/m<sup>3</sup> Phantom section: Flat Section Measurement Standard: DASY4 (High Precision Assessment)

**DASY4** Configuration:

- Probe: ET3DV6 SN1507 (HF); ConvF(4.43, 4.43, 4.43); Calibrated: 19.10.2006
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn907; Calibrated: 20.07.2006
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; ;
- Measurement SW: DASY4, V4.7 Build 53; Postprocessing SW: SEMCAD, V1.8 Build 172

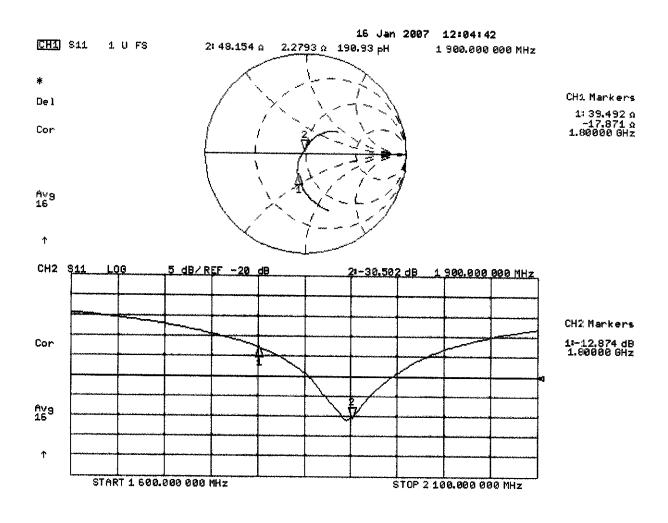
# Pin = 250 mW; d = 10 mm 2/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 85.8 V/m; Power Drift = 0.053 dB Peak SAR (extrapolated) = 17.0 W/kg SAR(1 g) = 9.94 mW/g; SAR(10 g) = 5.24 mW/g Maximum value of SAR (measured) = 11.3 mW/g



0 dB = 11.3mW/g

# Impedance Measurement Plot for Body TSL





Prepared (also subject responsible if other)

LD/SEMC/BGUG/NM Ramadan Plicanic

LD/SEMC/BGUG/NMC Mats Hansson

Company Internal INSTRUCTION No. GUG/N 03:141 Date Rev 060220 E

Reference File

## Sony Ericsson SAR Measurement Specification of Wireless Terminals

Checked

#### Contents

1	Introduction and scope	2
2	References	
3	Physical quantities, units and constants	
4	Definitions	
5	Measurement system specifications	
5.1	General	
5.2	Phantom	
5.3	SAR measurement equipment	
5.4	Scanning system	
5.5	Wireless device holder	
5.6	Other equipment	
6	Protocol for SAR assessment	7
6.1	Measurement preparation	7
6.2	Tests to be performed	
6.3	Measurement procedure	7
6.4	Post processing	8
7	Measurement uncertainty	
Annex A	Tissue simulating material preparation	
Annex B	Dielectric property measurements	12
Annex C	SAR measurement procedure	13
Annex D	Measurement system performance check and validation	15
Annex E	Uncertainty budgets for 1g and 10g SAR assessments with DASY3	17



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### 1. Introduction and scope

It is a Sony Ericsson policy that all RF transmitting product models shall comply with relevant recommendations, standards and regulations on human exposure to electromagnetic fields. In the reference section below, the most important RF safety guidelines are listed [9-13]. If no national standard or regulation is available in a country, the international recommendation from ICNIRP [9] shall be applied.

The RF safety guidelines specify *basic restrictions* and *reference levels*. In the frequency range of interest for mobile communications, the basic restrictions are expressed as Specific Absorption Rate (SAR) limits and the reference levels as field strength or power density limits. The reference levels are provided for the purpose of simple measurements of compliance with the basic restrictions, and they are primarily applicable in the far-field region of a RF source. Measured values greater than the reference levels do not necessarily mean that the basic restrictions are exceeded.

In the near-field region of mobile communication devices (handsets), field strength values exceeding the reference levels may be observed. Compliance with the basic SAR restrictions has therefore to be verified. SAR (W/kg) is a measure of the rate of RF energy absorption in tissue. The localized SAR limits depend on whether the device is classified for use by the general public (uncontrolled environment) or workers (controlled environment). Mobile communication equipment are usually used by the general public and should consequently be in compliance with the general public limits, which are 2.0 W/kg averaged in 10 gram of tissue in the ICNIRP guidelines [9] and 1.6 W/kg averaged in 1 gram in the ANSI/IEEE standard [10]. Because of the lower limit and the smaller averaging mass, the ANSI/IEEE limit is slightly more conservative than the ICNIRP limit. The averaging times are also different, 6 minutes in the ICNIRP recommendations and 30 minutes in the IEEE guidelines.

This document describes the SAR measurement procedures used by the SAR testing laboratories of Sony Ericsson. SAR measurement standardization is currently evolving. Many standards and guidelines have recently been released [1, 2 and 5] or are in progress (e.g. [3, 4]). Sony Ericsson is firmly committed to using the latest technology and the latest standards to ensure that the SAR measurements are of the highest quality.

### 2. References

#### SAR measurement standards and guidelines

The following standards and guidelines are used as a basis for the SAR measurement specification described herein. Although these documents are well harmonized, some differences exist. References [1] and [2] are approved European standards, [5] is IEEE standard, [3] and [4] draft measurement standards and references [6] are published guidelines. This measurement specification closely conforms to these documents.

- [1] European Standard EN 50360, "Product standard to demonstrate the compliance of mobile phones with the basic restrictions related to human exposure to electromagnetic fields (300 MHz 3 GHz)", CENELEC, July 2001.
- [2] European Standard EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz 3 GHz)", CENELEC, July 2001.
- [3] IEC 62209\_Part1 (CD), "Procedure to determine the Specific Absorption Rate (SAR) for hand-held mobile wireless devices in the frequency range of 300 MHz to 3 GHz", IEC, February 2005
- [4] IEC 62209 Part 2, "Evaluation of Human Exposure to Radio Frequency Fields from Handheld and Body-Mounted Wireless Communication Devices in the Frequency Range of 30 MHz to 6 GHz: Human models, Instrumentation, and Procedures, Part 2: Procedure to measure the Specific Absorption Rate (SAR) for two-way radios, palmtop terminals, laptop terminals, desktop terminals, and body-mounted devices including accessories and multiple transmitters", Draft Version 0.6, October 2002
- [5] Standard 1528-2003, "Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques", IEEE, June, 2003,
- [6] Supplement C (Edition 01-01) to OET Bulletin 65 (Edition 97-01), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields: Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", FCC, June 2001.



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[7] Radiocommunications (Electromagnetic Radiation Human Exposure) Standard 2003, Australian Communications Authority (ACA), February 2003.

[8] ARIB Standard STD-T56, "Method of Measuring the Specific Absorption Rate from Portable Wireless Terminals", 2<sup>nd</sup> Edition, Association of Radio Industries and Businesses, January 24<sup>th</sup>, 2002. (Translation by Asia Technical Translation Pty Ltd 10/04/02).

#### Other references

- [9] ICNIRP, "Guidelines for limiting exposure to time-varying electric, magnetic, and electromagnetic fields (up to 300 GHz)", International Commission on Non-Ionizing Radiation Protection (ICNIRP), Health Physics, vol. 74, pp 494-522, April 1998.
- [10] ANSI/IEEE C95.1-1992, "Safety levels with respect to human exposure to radio frequency electromagnetic fields, 3 kHz to 300 GHz", The Institute of Electrical and Electronics Engineers Inc., New York, 1992.
- [11] CENELEC ENV 50166-2, "Human exposure to electromagnetic fields: High-frequency (10 kHz 300 GHz)", European Prestandard, European Committee for Electrotechnical Standardization (CENELEC), January 1995.
- [12] MPT, "Radio-radiation protection guidelines for human exposure to electromagnetic fields", Telecommunications Technology Council, Ministry of Posts and Telecommunications, Japan, April 1997.
- [13] AS/NZS 2772.1(Int):1998, Interim Australian/New Zealand Standard, "Radiofrequency fields, Part 1: Maximum exposure levels 3 kHz to 300 GHz", Standards Australia/Standards New Zealand, 1998.
- [14] FCC Report and Order, ET Docket 93-62, FCC 96-326, Federal Communications Commission (FCC), August 1996.
- [15] Safety code 6, Canadian Standard, Health Canada, 1999.
- [16] Thomas Schmid, Oliver Egger, Niels Kuster, "Automated E-field scanning system for dosimetric assessments", IEEE Transactions on Microwave Theory and Techniques, vol. 44, pp. 105-113, January 1996.
- [17] Schmid & Partner Engineering AG, "DASY3 User Manual", August 1999 Edition, Zurich, Switzerland.
- [18] Klaus Meier, Michael Burkhardt, Thomas Schmid and Niels Kuster, "Broadband calibration of E-field probes in lossy media", *IEEE transactions on Microwave Theory and Techniques*, vol. 44, no. 10, pp. 1954-1962, October 1996.
- [19] K. Pokovic, T Schmid and N. Kuster, "E-field Probe with Improved Isotropy in Brain Simulating Liquids", *Proceedings ELMAR*, Zadar, Croatia, June 23-25, 1996.
- [20] NIS 81, "The treatment of uncertainty in EMC measurements", Technical Report, NAMAS Executive, National Physical Laboratory, Teddington, Middlesex, England, Edition 1, May 1994.
- [21] Barry N. Taylor and Christ E. Kuyatt, "Guidelines for evaluating and expressing the uncertainty of NIST measurement results", NIST Technical Report 1297, National Institute of Standards and Technology, September 1994.
- [22] T. Schmid and N. Kuster, "Preliminary uncertainty budget for SAR evaluations with DASY3," contribution to IEEE Standards Coordinating Committee 34, Subcommittee 2, July, 1998.
- [23] ISO/IEC Guide Expres (1995-01), "Guide to the expression of uncertainty in measurement (1995)", Ed. 1.0 English, 1995.
- [24] HP 8752C Network analyzer User's guide. Hewlett Packard part number 08752-90157.
- [25] HP 85070D Dielectric probe kit manual, Hewlett Packard part number 85070-90009.
- [26] M. Siegbahn, "A SAR test procedure for wireless devices with simultaneous multi-band transmission", EAB/TF-02:118, Rev. A, November 19, 2002



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### 3. Physical quantities, units and constants

The physical quantities, units and constants given in section 3 of [2] and section 4 of [3] are applicable for this procedure document.

### 4. Definitions

The definitions given in section 4 of [2], section 3 of [3] and section 2 of [4] apply.

### 5. Measurement system specifications

Requirements and recommendations are listed in section 5 of [2] and [3] and in sections 3, 4 of 5 of [4].

### 5.1 General

Requirements and recommendations are listed in section 5.1 of [2] and [3] and in section 5.6.1.1 of [4].

Tests are performed using a miniature electric field probe that is positioned by a robot whose movements are software controlled. The probes are positioned to measure the internal electric field of a liquid-filled phantom representing the human head while the phantom is exposed to electromagnetic energy from a wireless device. The software processes the electric field data to determine the SAR distribution and the highest mass-averaged SAR.

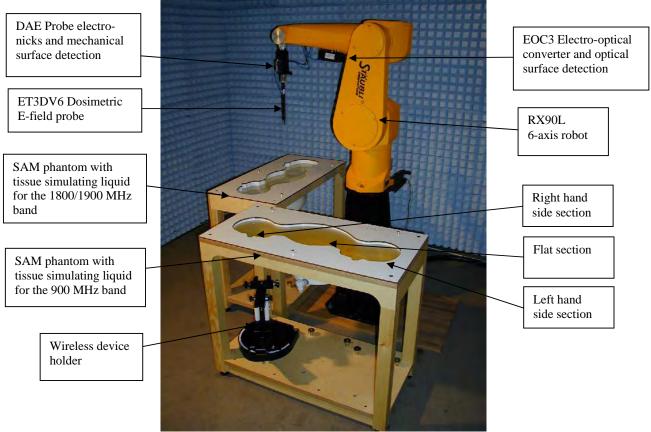


Figure 5.1 SAR measurement system



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The SAR measurement system used in the Sony Ericsson SAR testing laboratories is the DASY near-field scanner manufactured by Schmid & Partner Engineering AG (SPEAG). The system is based on the E-field probe technique and includes a high precision 6-axis robot, liquid-filled plastic phantoms and miniature electric field probes [16, 17]. The specifications of the system are further described below. Figure 5.1 is a picture of the SAR measurement system.

The Ericsson SAR testing laboratories conform to the following environmental conditions:

- Measurements are conducted in a metal screen room, which is designed to provide shielding from external radiofrequency signals and to prevent devices under test from interfering with local wireless networks.
- The ambient temperature is kept in the range 20 25°C (this simultaneously satisfies several recommendations and requirements [2-5], which are 15 30°C, 18 25°C and 20 26°C, respectively).
- The relative humidity of the laboratory is kept within 30 70% [5].
- During measurements, the temperature of the liquid is kept within ±2 °C of the temperature at which the dielectric parameters were measured [2-4].
- The ambient noise level is kept low so that the 1-gram averaged SAR is below 12 mW/kg when the device under test (DUT) is turned off (this simultaneously satisfies the requirements of [2] and [4]).

### 5.2 Phantom

Phantom requirements and specifications are provided in section 5.2 of [2] and [3] and in section 4 of [4 and 5].

The phantom used is an implementation of the Specific Anthropomorphic Mannequin (SAM) model [2-5]. It consists of three measurement areas or sections, one section corresponding to right hand side use and an identical but mirrored section for the left-hand side. In the middle of the phantom there is a flat section for tests of mobile phones when worn on the body. The flat section is also used for system validation.

The phantom shell was manufactured by SPEAG to meet stringent shape, thickness and material requirements [2-5]. The length and width of the flat section are at least 0.75  $\lambda_0$  and 0.6  $\lambda_0$  respectively at frequencies of 824 MHz and above ( $\lambda_0$  = wavelength in air).

The phantom is filled with a tissue simulating liquid to a depth of at least 15 cm at each ear reference point [2-5]. The dielectric properties of the liquid conform to all the tabulated values [2-5]. Liquids are prepared according to Annex A and dielectric properties are measured according to Annex B.

#### 5.3 SAR measurement equipment

Measurement equipment requirements and specifications are provided in section 5.3 of [2] and [3] and in section 3 of [4 and 5].

The Dosimetric Assessment System (DASY) Professional by Schmid & Partner Engineering AG consists of the dosimetric probe ET3DV6 connected to the readout electronics DAE3 which is attached to the tool joint of a Stäubli RX90L 6-axis high precision robot. The measurement signal is transferred via a fiber optical link from the DAE3 to the electro-optical converter EOC3 that is connected to the ISA type PC card in the system computer.

The dosimetric probe is sensitive to E-fields and incorporates three dipoles arranged so that the overall response is close to isotropic [14, 15]. The probe sensors are covered by an outer protective shell made of plastic, which is resistant to organic solvents i.e. glycol. In the center line of the probe an optical fiber for surface detection is located. The table below summarizes the technical data of this probe. The E-fields probes have been calibrated once per year and after calibration Technical Lead Engineer or Technical Engineer are responsible to change correction factor in DASY system software for each probes. Other probe parameters are provided in the uncertainty budget in Section 7.

The DAE probe electronics incorporates one measurement amplifier for each sensor dipole and a mechanical surface detection system that automatically stops the robot in a probe collision emergency. The fiber optical surface detection system is located



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Prepared (also subject responsible if other)		No.			
LD/SEMC/BGUG/NM Ramadan Plicanic		GUG/N 03:141			
Approved	Checked	Date	Rev	Reference	
LD/SEMC/BGUG/NMC Mats Hansson		060220	Е	File	

in the EOC. Either the mechanical or the optical surface detection system is used for controlling the distance between the probe and the inner surface of the phantom shell.

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Data
30 MHz – 3 GHz
$\pm 0.2 \text{ dB}$
5 $\mu$ W/kg - >100 W/kg
6.8 mm
2.7 mm
3 mm
$\pm 0.2 \text{ mm}$

Table 5.1 The technical data for the SAR probe ET3DV6.

Property	Data
Frequency range	10 MHz – 6 GHz
Linearity	$\pm 0.2 \text{ dB}$
Dynamic Range	5 $\mu$ W/kg - >100 W/kg
Tip diameter (including protective cover)	4 mm
Distance from probe tip to sensors	2 mm
Length of sensor dipoles	2 mm
Optical surface detection repeatability	$\pm 0.2 \text{ mm}$

Table 5.2 The technical data for the SAR probe ES3DV3

The data acquisition electronic have been calibrated once per year and after calibration Technical Lead Engineer or Technical Engineer are responsible to change correction factor in DASY system software for each DAE. System performance check is conducted for the complete system for each relevant tissue equivalent liquid at the appropriate frequency.

### 5.4 Scanning system

Requirements and recommendations are listed in section 5.4 of [2] and [3] and in section 5.5 of [4 and 5].

The robotic scanning system works in such a way that the system identifies the measurement areas in the phantom shell by three reference points located on the phantom table and a laser beam on the robot stand which determines the alignment of the probe. The coordinates of the three reference point are entered into the system by manually steering the robotic arm so that the probe tip is above each of these points. Measurement grids can then be defined in each of the available measurement sections of the phantom, the right ear section, the left ear section and in the middle of the shell, the flat section. The robotic arm automatically positions the probe in the selected measurement grid and the distance from the probe tip to the inner surface of the phantom shell is controlled by either a mechanical or an optical surface detection system. The measurement grids are defined so that the whole tested device is covered. During the measurement the local SAR results can be continuously monitored.

### 5.5 Wireless device holder

Requirements and recommendations are listed in section 5.5 of [2] and [3] and in section 4.1.4 of [4 and 5].

The wireless device holder is a positioning system that allows for very accurate and repeatable device positioning [17]. Tilt and rotation angles have a positioning repeatability better than 1°. Care is taken at the laboratory to ensure that the wireless



	INSTRUCTION		
	No.		
	GUG/N 03:141		
Checked	Date	Rev	Reference
	060220	Е	File
	Checked	INSTRUCTION No. GUG/N 03:141 Checked Date	No. GUG/N 03:141 Checked Date Rev

device is placed in the holder in such a way that the holder has a minimal effect on the measured results. Test personnel are trained on proper positioning techniques.

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### 5.6 Other equipment

Requirements and recommendations are listed in section 5.6 of [2] and [3] and in section 5.5 of [4 and 5].

The measurement system also includes dipole antennas for system performance checking and system validation procedures at frequency bands of interest. The dipole antennas conform to the specifications of Annex G of [3] and Annex F of [4]. These dipole antennas are checked yearly according to the following items:

- dipole arms are parallel to a flat surface with a tolerance of 2°.
- return loss at the center frequency is below -20 dB while the dipole is positioned under the flat phantom according to Section 7 of [4].
- current distribution along the dipole is symmetric within 5%, as measured using an H-field probe.
- SAR is measured in a flat phantom and compared with reference SAR values in Table D.1 of [3] or in Table 7.1 of [4 and 5].

SAR measurement system performance check is described in detail in Annex D.

#### 6 Protocol for SAR assessment

Requirements and recommendations are listed in section 6 of [2] and [3] and in section 5 of [4 and 5].

This section presents an overview of the process of assessing SAR for a wireless terminal in Sony Ericsson SAR testing laboratories, the setup of the tested device and the measurement system, which tests are performed and how the test results are processed.

### 6.1 Measurement preparation

Requirements and recommendations are listed in section 6.1 of [2] and [3] and in section 5.4 and 5.6 of [4 and 5].

Prior to conducting SAR measurements of the DUT, the dielectric properties of the tissue simulating liquid are measured (see Annex B). System performance check (see Annex D) is performed prior to the SAR measurements or when any part of the SAR testing system has been altered, which includes change of probe and calibration of tissue simulating liquid etc.

For SAR compliance measurements, the peak output power level of the mobile phone is set to the maximum power level of that device with a digital radio tester acting as a base station. The peak power level is measured with either a power meter, a sensor suitable for the carrier frequency and the duty cycle, or a digital radio tester.

Tests are conducted for each of the test configurations of the DUT (operational modes, test frequencies, and configurations).

If the device is intended to be used next to the ear, it is positioned next to the SAM head phantom in the "cheek" and "tilt" positions on both the left and right sides of the phantom according to section 5.4 of [4 and 5].

If the device is intended to be used while placed against the body, the phone is tested on the flat section of the phantom. The device, with its original carry case(s) and with hands-free accessories, shall be positioned on the phantom simulating the intended use position, i.e. with the case placed against the phantom shell. Alternatively, the device can be placed against the phantom using a spacer that separates the device from the phantom by the minimum distance allowable using all carry cases. Additional guidance given in [5] on conducting body-worn measurements should be followed.



		INSTRUCTION		
Prepared (also subject responsible if other)		No.		
LD/SEMC/BGUG/NM Ramadan Plicanic		GUG/N 03:14	l	
Approved	Checked	Date	Rev	Reference
LD/SEMC/BGUG/NMC Mats Hansson		060220	Е	File

### 6.2 Tests to be performed

Requirements and recommendations are listed in section 6.2 of [2] and [3] and in section 5.6 of [4 and 5].

A wireless handset can have many test conditions (operational modes, test frequencies, configurations and test positions against the phantom). At a minimum, the steps outlined in the above listed sections are followed to determine the maximum spatial-averaged SAR of the device.

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### 6.3 Measurement procedure

Requirements and recommendations are listed in section 6.3 of [2] and [3] and in section 5.6 of [4 and 5]. The measurement procedure is described in detail in Annex C. The measurement procedure can be summarized in the following steps:

- 1. Setup of DASY: liquid parameters, test device properties, probe, DAE and measurement areas are specified in the system configuration setting.
- 2. Setup of the device: positioning on the phantom, output power level and test channel are selected and checked.
- 3. SAR measurement, the following measurement jobs are conducted:
  - Reference measurement where the robot moves the probe to a fixed reference position in the tissue liquid and the E-field is recorded.
  - Coarse SAR scan with grid covering the whole device for finding maximum.
  - Fine cubical SAR scan around maximum for obtaining mass averaged SAR.
  - Second reference measurement for checking device output power drift. Repeat the SAR measurement if the drift is higher than ±5% (±0.21dB).
  - Surface checks (optional) where the robot repeatedly moves the probe to the phantom surface at a specified point to check the repeatability of the mechanical and optical surface detection are conducted before the reference measurements if needed. If the repeatability is greater than ±0.1 mm, the system should be inspected (e.g. check for air bubbles trapped under the probe) and the surface check procedure should be repeated.

#### 6.4 **Post processing**

Requirements and recommendations are listed in section 6.4 of [2] and [3] and in section 5.5 of [4 and 5]. The specific absorption rate (SAR) is calculated from the recorded E-fields by the following expression:

$$SAR = \sigma \frac{E^2}{\rho}$$

where  $\sigma$  is the measured electric conductivity (S/m) of the liquid, *E* is the measured root-mean-squared E field (V/m), and  $\rho$  is the chosen tissue density ( $\rho = 1000 \text{ kg/m}^3 = 1 \text{ g/cm}^3$  should always be used [2,4 and 5]). The SAR distribution of the tested device is determined by a coarse scan where the probe is moved in a coarse grid following the inner surface of the phantom. The size of the scanned region should be large enough to guarantee that all possible SAR peaks are included. The distance between adjacent measured points should be 10 - 20 mm [2-5]. Spline interpolation is then used to determine the point of maximum SAR.

The mass averaged SAR is determined by a fine cubical scan, a measurement taken on a fine grid around the position of the maximum SAR. The grid typically consists of 5x5x7 points with 8 mm between the individual points [2] and thus contains about 27 grams of tissue. Numerical extrapolation is then used to determine the SAR values between measurement points in the cube and in the small region between the cube and the inner surface of the phantom where the E-field sensors cannot be positioned. The extrapolation distance is the sum of the probe tip - sensor offset, the surface detection distance and the grid offset. The extrapolation is based on fourth-order polynomial functions. Next, a 3D-spline interpolation algorithm is used to interpolate the measured data to a 1g cube (20x20x20=8000 points) over which the SAR is averaged. The cube is shifted throughout the fine scan area until the highest averaged SAR is found. The same procedure is repeated for the 10 gram cube



		Company Inter		
Prepared (also subject responsible if other)		No.		
LD/SEMC/BGUG/NM Ramadan Plicanic		GUG/N 03:141		
Approved	Checked	Date	Rev	Reference
LD/SEMC/BGUG/NMC Mats Hansson		060220	Е	File

(also 20x20x20=8000 points). If the 1g and 10g maximum SAR is found when the averaging cube is touching any side of the measurement grid a message "Maximum outside" is given and a second fine scan has to be conducted. This in order to assess the absolute maximum mass averaged SAR.

### 7 Measurement uncertainty

Requirements and recommendations are listed in section 7 of [2] and [3] and in sections 3 and 4 of [4 and 5].

The measurement uncertainty of the DASY has been determined according to the NIS81 [18] and NIST1297 documents [19]. The total uncertainty of the SAR assessment is composed of two main factors: measurement uncertainty and source uncertainty. Each of these uncertainties consists of a number of individual factors. A detailed breakdown of uncertainties, according to T. Schmid *et. al.* [20], is provided in Annex E. The combined uncertainty (k=1) of the 1g SAR assessment is  $\pm 13.6\%$  and for 10g SAR assessments  $\pm 13.3\%$ . The extended uncertainties (k=2) is  $\pm 27.1\%$  and  $\pm 26.6\%$  for 1g and 10g assessments, respectively [21].



		Company Interr		
Prepared (also subject responsible if other)		No.		
LD/SEMC/BGUG/NM Ramadan Plicanic		GUG/N 03:141		
Approved	Checked	Date	Rev	Reference
LD/SEMC/BGUG/NMC Mats Hansson		060220	Е	File

### Annex A Tissue simulating material preparation

This section describes the preparation procedure for the tissue simulating liquids used in SAR testing.

#### A.1 Liquid parameters

The liquids prepared for the SAR testing meet both the requirements of [2] in table 1 and the requirements of [3] and [4 and 5] in table 2. The parameters below are applicable to average head tissue simulating material. Since dielectric parameters for average body tissue have not yet been developed, liquids meeting the below stated data are also used for measurements of body SAR. The parameters for a liquid used in SAR measurements has to be within  $\pm 5\%$  of the target values.

Frequency (MHz)	٤ <sub>r</sub>	σ (S/m)
300	45	0.85
450	44	0.88
900	42	0.99
1450	41	1.20
1800	40	1.38
2450	39	1.84
3000	39	2.40

Table A.1. The dielectric properties of tissue simulating material given in [2].

Frequency (MHz)	٤r	σ (S/m)
300	45.3	0.87
450	43.5	0.87
835	41.5	0.90
900	41.5	0.97
1450	40.5	1.20
1800	40.0	1.40
1900	40.0	1.40
2000	40.0	1.40
2450	39.2	1.80
3000	38.5	2.40

Table A.2. The dielectric properties of tissue simulating material given in [3], [5] and [6].

A.2 Liquid recipes	
Ingredients	
Water	distilled water
Sugar	as available in food shops
Salt	as available in food shops (Note, no iodine!)
Cellulose	HEC Hydroxyethyl-cellulose (Optional ingredient)
Preservative	Preventol D7 Bayer AG or Sodium Nitrate
DGBE	Diethyleneglycolbutyl ether (CAS No. 112-34-5)

**Note 1:** It is important to follow the instructions provided in the Material Safety Data Sheet (MSDS) for any material, or any local regulations. It is also important to have material handling procedures (including procedures for handling, storage and disposal).



		Company Interr		
Prepared (also subject responsible if other)		No.		
LD/SEMC/BGUG/NM Ramadan Plicanic		GUG/N 03:141		
Approved	Checked	Date	Rev	Reference
LD/SEMC/BGUG/NMC Mats Hansson		060220	E	File

**Note 2:** Similar materials can also be substituted for the ones above (e.g. deionized water instead of distilled water). The specifications of the materials (e.g. purity) are not critical (although they may change the recipes below), because the after the tissue simulating liquid is made, its dielectric parameters must be verified to be within the target ranges.

#### **Preparation equipment**

- Balance (range: 0-6000 g, accuracy:  $\pm 0.1$ g)
- Stirrer with hotplate
- Jars and beakers
- Mixing spoon

#### Liquids for the 835 MHz and 900 MHz

	835 MHz and 900 MHz head	
Ingredient	weight (%)	weight (g)
Distilled water	40.29	532.63
HEC	0.24	3.20
NaCl	1.40	18.29
Preservative	0.18	2.4
Sugar	57.90	765.49
Total amount		1322.00
Goal		
Frequency (MHz)	835	900
<b>Relative Permittivity</b>	41.5	41.5
Conductivity	0.90	0.97

	835 MHz and 900 MHz body	
Ingredient	weight (%)	weight (g)
Distilled water	50.75	633.91
HEC	-	0.00
NaCl	0.94	11.76
Preservative	0.10	1.2
Sugar	48.21	602.12
Total amount		1249.00
Goal		
Frequency (MHz)	835	900
Relative Permittivity	55.2	55.0
Conductivity	0.97	1.05

Liquids for the 1800 MHz and 1900 MHz

	1800 MHz and 1900 MHz head	
Ingredient	weight (%)	weight (g)



	Company Interna	al
	No.	
	GUG/N 03:141	
Checked	Date	Rev
	060220	E
	Checked	No. GUG/N 03:141 Checked Date

Distilled water	55.24	552.42
DGBE	44.45	444.52
NaCl (Salt)	0.31	3.06
Total amount		1000.00
Goal		
Frequency (MHz)	1800	1900
<b>Relative Permittivity</b>	40.0	40.0
Conductivity	1.40	1.40

	1800 MHz and 1900 MHz body	
Ingredient	weight (%)	weight (g)
Distilled water	70.17	701.66
DGBE	29.44	294.42
NaCl (Salt)	0.39	3.92
Total amount		1000.00
Goal		
Frequency (MHz)	1800	1900
Relative Permittivity	53.3	533
Conductivity	1.52	1.52

#### Liquids for the 2450 MHz

	2450 MHz head	
Ingredient	weight (%)	weight (g)
Distilled water	55.0	550.00
DGBE	45.0	450.00
Total amount		1000.00
Goal		
Frequency (MHz)	2450	
<b>Relative Permittivity</b>	39.2	
Conductivity	1.80	

	2450 MHz body	
Ingredient	weight (%)	weight (g)
Distilled water	68.64	686.64
DGBE	31.37	313.65
Total amount		1000.00
Goal		
Frequency (MHz)	2450	
Relative Permittivity	52.7	
Conductivity	1.95	

## A.2 Preparation procedure

### Sugar-based liquids

Add the water to a large container. Begin heating and stirring.

- Add the cellulose, preservative and salt (if required). While keeping the container covered, leave the solution on the heating plate until the mixture becomes sufficiently transparent and homogeneous. The temperature of the mixture should be hot enough to aid in mixing the ingredients but cool enough to prevent a significant amount of water evaporation.
- Add the sugar. Hand stirring may be necessary at the beginning until the sugar is sufficiently dissolved.

Reference File



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Keep the liquid hot and the container covered until the solids are dissolved and the liquid is homogenous.

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Turn the hotplate off and allow the liquid to cool off to room temperature prior to performing dielectric measurements.

#### Alcohol-based liquids

- 1. Add all the ingredients in a large container.
- 2. Stir until the liquids are solved.

#### A.3 Tissue liquid maintenance

In order to keep the dielectric parameters of the tissue simulating liquids within their target ranges, ingredients may be added to adjust the parameters. For example, one can add water to increase the permittivity, sugar to reduce the permittivity or salt to increase the conductivity. Parameters should each be within a  $\pm 5\%$  range of target values.

A batch of tissue simulating liquid may last several months or more but regular maintenance is necessary in order to keep the dielectric properties within target ranges. The electrical parameters of the tissue simulating liquids are assessed prior to SAR compliance testing and checked that they are within tolerance of the specified values (see tables above). The parameters are subject to small variations due to evaporation, and ingredients have to be added on a regular basis in order to adjust the parameters. The amount of ingredient to add depends on the parameter deviations and the total liquid volume and is therefore not easily calculated. However, based on experience, for sugar-salt-water liquids a rule of thumb can be applied: to a 25-liter liquid with a permittivity deviation of about -7% and a conductivity deviation around -3% to -7%, 200 - 400 grams of water should be added. It is recommended that a batch be disposed of and replaced with a new batch when it becomes difficult to keep its dielectric parameters within the ranges specified.



		Company Internal INSTRUCTION			
Prepared (also subject responsible if other)		No.			
LD/SEMC/BGUG/NM Ramadan Plicani	с	GUG/N 03:1	41		
Approved	Checked	Date	Rev	Reference	
LD/SEMC/BGUG/NMC Mats Hansson		060220	E	File	

### Annex B: Dielectric property measurements

This annex describes the procedures used to measure the dielectric properties of the tissue simulating liquid.

#### B.1 Equipment

- HP network analyzer, models in the HP8753 series, HP8752C or similar
- HP dielectric probe kit HP85070 of versions A, B, C or D [25]
- HP 85070 software (any software version)
- PC using GPIB card [24] for communication with network analyzer
- Syringe
- Small glass jars for liquid samples
- Thermometer

#### B.2 Procedure for testing tissue simulating liquid

- 1. Turn the NWA (Network analyzer) on and allow it to warm up.
- 2. Start the PC and run the HP 85070 software.
- 3. Mount dielectric probe kit so that interconnecting cable to NWA will not be moved during measurement or calibration.
- 4. Perform calibration according to the HP85070 manual [25]. In short the following steps are covered:
  - Inspect the probe and ensure that it is properly cleaned.
  - Pour distilled water in a sample container and measure the water temperature.
  - Set start and stop frequency, frequency step and water temperature.
  - Perform calibration measurement with probe in air, connected to short circuiting block and in distilled water. Assure proper contact which requires attaching the block firmly. Monitor the polar chart on the network analyzer to assure good contact as explained in the manual.
- 5. Assure that the probe is thoroughly cleaned before performing the measurement.
- 6. Inspect the liquid for in homogeneities. Surface bubbles can be moved to one side, but if there are numerous bubbles throughout the liquid (e.g. as happens after a new liquid has been poured into a phantom), wait until the bubbles have floated to the surface before proceeding. Also remove any debris or lumps in the liquid.
- 7. Stir the liquid to be measured.
- 8. Measure the temperature of the tissue simulating liquid in the phantom. Save value for reference, SAR measurements are only conducted for temperatures  $\pm 2^{\circ}$ C from this reference temperature.
- 9. Extract a sample (approximately 50 ml or more).
- 10. Measure liquid shortly after calibration of the network analyzer and at most within an hour of this calibration. It is also important to measure the liquid sample soon after extracting it so that evaporation and temperature variation do not affect the results.
- 11. Immerse the dielectric probe in the liquid sample. Check that there are no air bubbles in front of the opening in the dielectric probe kit.
- 12. Perform measurements. Repeat measurement five times to increase reliability and use average value for comparison with target value. If a single measurement deviates substantially from the rest then redo that measurement to reject possible artifact. The accuracy specified by the dielectric probe kit manufacturer [23] is  $\pm 5\%$  for the dielectric constant  $\epsilon'$  and  $\pm 0.05$  for the loss tangent  $\epsilon''/\epsilon'$ .
- 13. Conductivity  $\sigma$  can be calculated from  $\mathcal{E}''$  according to

$$\sigma = \omega \varepsilon_o \varepsilon'' \cong \varepsilon'' f (GHz)/18$$

- 14. Clean the probe thoroughly after use.
- 15. Pour the sample back into the phantom.



Company Internal INSTRUCTION				
Prepared (also subject responsible if other)		No.		
LD/SEMC/BGUG/NM Ramadan Plicanic		GUG/N 03:1-	41	
Approved	Checked	Date	Rev	Reference
LD/SEMC/BGUG/NMC Mats Hansson		060220	Е	File

### Annex C: SAR measurement procedure

This section gives a step-by-step procedure for measuring the DUT. The instructions of this section are only valid under the assumption that the measurement equipment is calibrated. More information is found in the user manual for the measurement system [13].

#### C.1 Initial setup

- 1. Ensure that the computer, robot controller and DAE are turned on, and that the DASY software is running.
- 2. Press the robot button on the toolbar to set up the communications between the software and the robot. Go through the self-check procedure in the software to ensure that the system is properly running and set up for measurement.
- 3. Choose the appropriate test configuration in the "Setup" menu. NOTE, check that the medium parameters in the "options" window are equal to those measured previously with the dielectric probe kit for the liquid in the phantom.
- 5. Remove the plastic cover on the phantom.
- 6. Verify that the system knows the reference points on the phantom. Check the distance between the reference points and the probe tip with the plastic spacer. If it does not accurately locate one or more of the points, install the reference points. Should the installation fail to give results within the tolerances set out in the factory settings for the phantom, the procedure will give an error and the user will have to reinstall the reference points. Afterwards, move the probe to the resting point above the flat section.
- 7. Stir the liquid in the phantom to ensure that it is homogeneous. Surface bubbles can be moved to one side, but if there are numerous bubbles throughout the liquid (e.g. as happens after a new liquid has been poured into a phantom), wait until the bubbles have floated to the surface before proceeding. Also remove any debris or lumps in the liquid.
- 8. Measure the temperature of the tissue simulating liquid in the phantom. The liquid temperature has to be within  $\pm 2$  °C of the temperature recorded when the electrical parameters were measured.

#### C.2 Measurement procedure

The following steps should be carried out for each of the test conditions described in Section 6.2.

- 1. Open the appropriate predefined measurement file or prepare a new measurement file by selecting jobs from the menu. The measurement file contains the following jobs: reference measurement, drift measurement, coarse scan covering the whole device, two cubical fine scans and a final drift measurement. The recording time for the coarse and fine scans is 1 second, which gives sufficient accuracy, but for reference/drift measurements 4 seconds giving increased noise-reduction. Additionally, a surface check can be inserted before the reference/drift measurements. During this check, the robot repeatedly moves the probe to the phantom surface at a specified point to check the repeatability of the mechanical and optical surface detection. If the repeatability is worse than ±0.1 mm, the system should be inspected (e.g. check for air bubbles trapped under the probe) and the surface check procedure should be repeated. Save the measurement file under an appropriate name.
- 2. Move the probe so that the tip is below the surface of the liquid in the selected measurement section. Stir the liquid again to remove any bubbles trapped under the probe tip.
- 3. Power on the DUT and set it to transmit at full power in one of the operational configurations (as described in Section 6.1). Check the signal with the spectrum analyzer.
- 4. Position the DUT against the phantom in one of the required test positions (as described in Section 6.1).
- 5. Select and start the first five measurement jobs; reference measurement, 3-minute time sweep, drift measurement, the coarse and one fine scan). Note the time sweep can be omitted once the device has warmed up.



	Company Internal INSTRUCTION			
	No.			
	GUG/N 03:141			
Checked	Date	Rev	Reference	
	060220	Е	File	
	Checked	INSTRUCTION No. GUG/N 03:141 Checked Date	INSTRUCTION No. GUG/N 03:141 Checked Date Rev	

- 6. Check the measured fine scan when the measurement jobs have been completed. If the maximum SAR has been found within the measured grid (no system message "Maximum outside") delete the second fine scan in the file and proceed with the final drift measurement. Otherwise, measure both the second fine scan and the drift measurement. Additionally, check for local maxima of at least 50% of maximum SAR.
- Check the system drift. If the measurement data is not within ±5% (±0.21 dB), check the DUT and change battery if necessary, check the DASY and repeat the measurement. If the drift cannot be maintained within 5%, add the drift to the measured SAR value.
- 8. Save the measurement data and enter it into the laboratory log.

#### C.3 Post measurement procedure

When the SAR measurements are finished, do the following:

- 1. Power off the DUT.
- 2. Move the probe to the resting point and clean it with water.
- 3. Put the plastic cover on the phantom.



		Company In INSTRUCTI		
Prepared (also subject responsible if other)		No.		
LD/SEMC/BGUG/NM Ramadan Plicanic		GUG/N 03:1	41	
Approved	Checked	Date	Rev	Reference
LD/SEMC/BGUG/NMC Mats Hansson		060220	Е	File

### Annex D: Measurement system performance check and validation

#### D.1 General

Measurement system validation consists of three procedures:

- 1. System performance checking
- 2. System validation
- 3. Inter laboratory comparison

These three procedures are defined in section 7 of [4 and 5]. System performance checking and inter laboratory comparison are also described in Annex D of [2] (they are called Simplified performance checking and system validation, respectively) and in Annex D of [3].

System performance checking is conducted prior to the SAR testing of a wireless device with a reference dipole antenna and the flat section of the SAM phantom. The results are compared to reference data provided by the system manufacturer, Schmid & Partner Engineering AG. The DASY3 manufacturer conducts system validation. Inter laboratory comparison between the Ericsson SAR testing laboratories is conducted according to a separate procedure.

#### D.2 System performance check procedure

System performance check is conducted according to the following steps.

#### Setup of the dipole antenna

- 1. Turn on the signal generator, power meter and power amplifier (if used). Allow them sufficient time to warm up, to reduce drift.
- 2. Position the dipole antenna under the flat phantom and adjust the height of the stand until the specified spacer is touching the shell of the flat phantom. The center of the dipole antenna should be positioned under the middle of the flat phantom, as indicated by a mark on the flat phantom.
- 3. Connect one end of the coax line to the power meter sensor and the other end to the output of the signal generator. If the power amplifier is used, connect it between the signal generator and the power meter sensor.
- 4. Set the signal generator to transmit in CW mode and ensure that any signal modulation is turned off. This ensures that the power amplifier will transmit a pure sinusoid.
- 5. Set the frequency of the signal generator to the resonant frequency of the dipole antenna.
- 6. Set the output power of the signal generator (and optionally adjust the gain of the power amplifier) so that the same amount of power as used by the system manufacturer at calibration is delivered to the power meter.
- 7. Disconnect the coax line from the power meter and connect it to the dipole antenna.

#### Setup of the DASY

- 1. Mount the 3D electric field probe, as shown in the SPEAG manual.
- 2. Remove the plastic cover on the phantom.
- 3. Power up the DAE. The LED indicates that the power is on.
- 4. Power up the computer.
- 5. Turn on the robot controller
- 6. Start the DASY software on the computer.



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JG/N 03:141				
	Rev	Reference		
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5	STRUĆTION IG/N 03:141	STRUCTION IG/N 03:141 Rev		

- 7. Choose the appropriate measurement configuration in the "Setup" menu of the software for the dipole measurement. Record the dielectric constant and conductivity of the liquid in the program.
- 8. Press the robot button on the toolbar to set up the communications between the software and the robot. Go through the self-check procedure in the software to ensure that the system is properly running and set up for measurement.
- 9. Verify that the robot knows the reference points on the phantom. Check the distance between the reference points and the probe tip with the plastic spacer. If it does not accurately locate one or more of the reference points to within ±5 mm, install the reference points. Should the installation fail to give results within the tolerances set out in the factory settings for the phantom, the procedure will give an error and the user will have to reinstall the reference points. Afterward, move the probe to the resting point above the flat section.
- 10. Measure the temperature of the tissue simulating liquid in the phantom. The liquid temperature has to be within  $\pm 2$  °C of the temperature recorded when the electrical parameters were measured.

#### Measurement procedure

- 1. Open a measurement file. Select the predefined dipole test provided by SPEAG. This file includes all of the necessary measurements for the dipole test. Rename the file with an appropriate name and save it in the appropriate directory.
- 2. Tell the robot to move the probe tip below the surface of the liquid. Stir the liquid again to remove any bubbles trapped under the probe tip.
- 3. Select and start the measurement jobs in the file. These include the reference check, coarse scan, fine scan, and drift measurements.

#### Analysis of measured data

- 1. Normalize the measurement data to 1 Watt and compare the one-gram and ten-gram averaged peak SAR values to the standard values provided in the reference documents. If they do not agree within ±10%, check the system parameters (e.g. antenna output power, dielectric parameters of the tissue simulating liquid, homogeneity of the liquid) and repeat the measurement.
- 2. Also check that the distribution of measured SAR agrees with that provided in the reference data. The peak SAR should be located over the center of the dipole, and the SAR should monotonically decrease away from this point. If the SAR distribution does not compare well with the reference data, repeat the measurement.
- 3. Make sure that the drift measurement is within  $\pm 5\%$  ( $\pm 0.2$  dB). If not, check the system parameters and repeat the measurement.
- 4. Save the measurement data and enter it into the logbook.
- 5. Move the probe out of the liquid and clean it with warm water.



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## Annex E Uncertainty budgets for 1g and 10g SAR assessments with DASY

### E.1 Uncertainty budget for measurements of 1g mass averaged SAR

Error description	Uncertainty (%)	Distrib.	Divisor	c <sub>i</sub> 1g	Standard unc 1g (%)	v <sub>i</sub> <sup>2</sup> or v <sub>eff</sub>
Measurement system						
Probe calibration	± 4.4	Normal	1	1	± 4.4	$\infty$
Axial isotropy	± 4.7	Rectang.	$\sqrt{3}$	$(1-c_p)^{1/2}$	± 1.9	$\infty$
Spherical isotropy	± 9.6	Rectang.	$\sqrt{3}$	$(c_p)^{1/2}$	± 3.9	$\infty$
Spatial resolution	$\pm 0.0$	Rectang.	√3	1	$\pm 0.0$	$\infty$
Boundary effects	± 5.5	Rectang.	√3	1	± 3.2	$\infty$
Probe linearity	± 4.7	Rectang.	√3	1	± 2.7	$\infty$
Detection limit	$\pm 1.0$	Rectang.	√3	1	$\pm 0.6$	$\infty$
Readout electronics	$\pm 1.0$	Normal	1	1	$\pm 1.0$	$\infty$
Response time	$\pm 0.8$	Rectang.	√3	1	$\pm 0.5$	$\infty$
Integration time	± 1.4	Rectang.	√3	1	$\pm 0.8$	$\infty$
RF ambient conditions	± 3.0	Rectang.	$\sqrt{3}$	1	± 1.7	$\infty$
Mech. Constraints of robot	$\pm 0.4$	Rectang.	√3	1	$\pm 0.2$	$\infty$
Probe positioning	± 2.9	Rectang.	√3	1	± 1.7	$\infty$
Extrap. and integration	± 3.9	Rectang.	√3	1	± 2.3	$\infty$
Test sample related						
Device positioning	± 6.0	Normal	0.89	1	± 6.7	12
Device holder uncertainty	± 5.0	Normal	0.84	1	± 5.9	8
Power drift	± 5.0	Rectang.	√3	1	± 2.9	$\infty$
Phantom and setup						
Phantom uncertainty	$\pm 4.0$	Rectang.	√3	1	± 2.3	$\infty$
Liquid conductivity (target)	± 5.0	Rectang.	√3	0.6	± 1.7	$\infty$
Liquid conductivity (meas)	$\pm 10.0$	Rectang.	$\sqrt{3}$	0.6	± 3.5	$\infty$
Liquid permittivity (target)	± 5.0	Rectang.	$\sqrt{3}$	0.6	± 1.7	$\infty$
Liquid permittivity (meas)	± 5.0	Rectang.	√3	0.6	± 1.7	~
Combined standard uncertain	nty				± 13.6	
Extended standard uncertain	ty (k=2)				± 27.1	



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Error description	Uncertainty (%)	Distrib.	Divisor	c <sub>i</sub> 10g	Standard unc 10g (%)	v <sub>i</sub> <sup>2</sup> or v <sub>eff</sub>
Measurement system						
Probe calibration	± 4.4	Normal	1	1	± 4.4	×
Axial isotropy	± 4.7	Rectang.	$\sqrt{3}$	$(1-c_p)^{1/2}$	± 1.9	8
Spherical isotropy	± 9.6	Rectang.	$\sqrt{3}$	$(c_p)^{1/2}$	± 3.9	8
Spatial resolution	$\pm 0.0$	Rectang.	$\sqrt{3}$	1	$\pm 0.0$	8
Boundary effects	± 5.5	Rectang.	$\sqrt{3}$	1	± 3.2	8
Probe linearity	± 4.7	Rectang.	$\sqrt{3}$	1	$\pm 2.7$	8
Detection limit	$\pm 1.0$	Rectang.	√3	1	$\pm 0.6$	8
Readout electronics	$\pm 1.0$	Normal	1	1	$\pm 1.0$	8
Response time	$\pm 0.8$	Rectang.	√3	1	$\pm 0.5$	8
Integration time	± 1.4	Rectang.	√3	1	$\pm 0.8$	8
RF ambient conditions	± 3.0	Rectang.	√3	1	± 1.7	8
Mech. Constraints of robot	$\pm 0.4$	Rectang.	√3	1	$\pm 0.2$	8
Probe positioning	± 2.9	Rectang.	√3	1	± 1.7	8
Extrap. and integration	± 3.9	Rectang.	√3	1	± 2.3	8
Test sample related						
Device positioning	± 6.0	Normal	0.89	1	± 6.7	12
Device holder uncertainty	± 5.0	Normal	0.84	1	± 5.9	8
Power drift	± 5.0	Rectang.	√3	1	± 2.9	8
Phantom and setup						
Phantom uncertainty	± 4.0	Rectang.	√3	1	± 2.3	8
Liquid conductivity (target)	± 5.0	Rectang.	√3	0.6	± 1.4	x
Liquid conductivity (meas)	± 10.0	Rectang.	√3	0.6	± 2.9	00
Liquid permittivity (target)	± 5.0	Rectang.	√3	0.6	± 1.4	00
Liquid permittivity (meas)	± 5.0	Rectang.	√3	0.6	± 1.4	×
Combined standard uncertain	nty				± 13.3	
Extended standard uncertain	ty (k=2)				± 26.6	

### E.2 Uncertainty budget for measurements of 10g mass averaged SAR