

ETS PRODUCT SERVICE AG

TEST - REPORT

SAR Compliance Test Report

Test report no.:

G0M20703-1223-S-8

SAR





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1 General Information

1.1 Notes

The purpose of conformity testing is to increase the probability of adherence to the essential requirements or conformity specifications, as appropriate.

The complexity of the technical specifications, however, means that full and thorough testing is impractical for both technical and economic reasons.

Furthermore, there is no guarantee that a test sample which has passed all the relevant tests conforms to a specification.

The existence of the tests nevertheless provides the confidence that the test sample possesses the qualities as maintained and that is performance generally conforms to representative cases of communications equipment.

The test results of this test report relate exclusively to the item tested as specified in 1.5.

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I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualification of all persons taking them.

Tester:

19.03.2007 Mr. Cersovsky

Date ETS-Lab. Name Signature

Technical responsibility for area of testing:

19.03.2007

N. Kaspar

Date

ETS

Name

Signature



1.2 Testing laboratory

1.2.1 Location

ETS PRODUCT SERVICE AG

Storkower Straße 38c

D-15526 Reichenwalde b. Berlin

Germany

Telephone: +49 33631 888 00 Fax: +49 33631 888 660

1.2.2 Details of accreditation status

ACCREDITED TESTING LABORATORY

DAR-REGISTRATION NUMBER: DAT-P-201/96

FCC FILED TEST LABORATORY REG. No. 96970

BLUETOOTH QUALIFICATION TEST FACILITY (BQTF)

ACCREDITED BY BLUETOOTH QUALIFICATION REVIEW BOARD

INDUSTRY CANADA FILED TEST LABORATORY REG. No. IC 3470

A2LA ACCREDITED Certificate Number #1983.01

Statement: The tests documented within this report are carried out in accordance with the scope of

accreditation of test laboratory ETS Product Service AG

1.3 Details of approval holder

Name : KIRK telecom A/S Street : Langmarksvej 34 Town : DK-8700 Horsens

Country : Denmark

Telephone : +45 7628 1280 Fax : +45 7560 2851

Contact : Mr. Henrik Birch Rasmussen

E-Mail : hbr@kirktelecom.dk



1.4 Manufacturer: (if applicable)

Name Street Town Country

1.5 **Application details**

Date of receipt of application : 03.03.2007 Date of receipt of test item : 03.03.2007 Date of test : 19.03.2007

1.6 **Test item**

FCC ID : PXAPP5I80-1G9

Description of test item : KIRK UPCS (DECT based) Handset (PP)

Type identification : PP5I80 1G9

Brand Name : Brand Name: Kirk telecom A/S

Serial number : without; Identical prototype

Device category : PUE (Part 15 unlicensed PCS portable TX held to ear)

Technical data

TX Frequency range : 1921.536 - 1928.448 MHz

Max. Conducted RF output power: UPCS 20,73 dBm (118,3 mW)

: 3.6 V DC Power supply Antenna Tx : integral Antenna RX : integral

Additional information : ./.



1.7 Test Results

Max. SAR Measurement (Head) : 0.011 W/kg (averaged over 1 gram)
Max. SAR Measurement (Body : 0.019 W/kg (averaged over 1 gram)

This EUT has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528-2003, December 2003.

1.8 Test standards

Standards : - Radiocommunications (Electromagnetic Radiation - Human

Exposure) Standard 2003

- IEEE Std. 1528-2003, December 2003

FCC Rule Part(s) : - FCC OET Bulletin 65, Supplement C, Edition 01-01



2 Technical test

2.1 Summary of test results

Applicable Configuration

Handset (Head)	X
Handset (Body)	X
Headset (Head)	
Body Worn Equipment	

EUT complies with the RF radiation exposure limits of the FCC as shown by the SAR measurement results. These measurements are taken to simulate the RF effects exposure under worst-case conditions. The EUT complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables. [1]

In case of multiple hotspots the secondary hotspots within 2dB of the maximum SAR value will be recorded and displayed in the measurement plots. The secondary hotspots with a peak SAR value below 0.5 W/kg will not be measured by the system, due to the high margin to the limits.

2.2 Test environment

Room temperature : 22.1 -22.6 ° C

Liquid temperature : 22.0 -22.3 ° C

Relative humidity content : 20 ... 75 %

Air pressure : 86 ... 103 k P a

Details of power supply : 3.6 V DC



2.3 Test equipment utilized

No.	Measurement device:	Type:	Manufacturer:
ETS 0449	Stäubli Robot	RX90B L	Stäubli
ETS 0450	Stäubli Robot Controller	CS/MBs&p	Stäubli
ETS 0451	DASY 4 Measurement Server		Schmid & Partner
ETS 0452	Control Pendant		Stäubli
ETS 0453	Compaq Computer	Pentium IV, 2 GHz,	Schmid & Partner
ETS 0454	Dabu Acquisition Electronics	DAE3V1	Schmid & Partner
ETS 0455	Dummy Probe		Schmid & Partner
ETS 0456	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner
ETS 0457	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner
ETS 0458	Dosimetric H-Field Probe	H3DV6	Schmid & Partner
ETS 0459	System Validation Kit	D900V2	Schmid & Partner
ETS 0460	System Validation Kit	D1800V2	Schmid & Partner
ETS 0461	System Validation Kit	D1900V2	Schmid & Partner
ETS 0462	System Validation Kit	D2450V2	Schmid & Partner
ETS 0463	Probe Alignment Unit	LBV2	Schmid & Partner
ETS 0464	SAM Twin phantom	V 4.0	Schmid & Partner
ETS 0465	Mounting Device	V 3.1	Schmid & Partner
ETS 0224a	Millivoltmeter	URV 5	Rohde & Schwarz
ETS 0219	Power sensor	NRV-Z2	Rohde & Schwarz
ETS 0268	RF signal generator	SMP 02	Rohde & Schwarz
ETS 0322	Insertion unit	URV5-Z4	Rohde & Schwarz
ETS 0466	Directional Coupler	HP 87300B	HP
ETS0231	Radio Communication Tester	CMD65	Rohde & Schwarz
ETS 0467	Universal Radio Communication Tester	CMU 200	Rohde & Schwarz
ETS 0468	Network Analyzer 300 kHz to 3 GHz	8753C	Agilent
ETS 0469	Dielectric Probe Kit	85070C	Agilent



2.4 Definitions

2.4.1 SAR

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (ρ_t) , expressed in watts per kilogram (W/kg)

SAR =
$$\frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho_t dV} \right) = \frac{\sigma}{\rho_t} |E_t|^2$$

where:

$$\frac{dW}{dt} = \int_{V} E \cdot J \, dV = \int_{V} \sigma E^2 dV$$

2.4.2 Uncontrolled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category, and the general population/uncontrolled exposure limits apply to these devices. [2]

2.4.3 Controlled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on the risk of potential exposure risks. [2]



2.5 Measurement System Description

2.5.1 System Setup

Measurements are performed using the DASY4 automated dosimetric assessment system (figure 1) made by Schmid & Partner Engineering AG (SPEAG)in Zurich, Switzerland.



The DASY4 system for performing compliance tests consists of the following it Figure 1

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- An unit to operate the optical surface detector which is connected to the EOC.
- The Electro-optical converter (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the measurement server.
- The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows NT.
- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes (see Application Notes).
- System validation dipoles allowing to validate the proper functioning of the system.



2.5.2 Phantom Description



(Figure 2.1)

The SAM twin phantom V4.0 (figure 2.1) is a fiberglass shell phantom with 2 mm shell thickness. It has three measurement areas:

- Left hand
- Right hand
- Flat phantom



(Figure 2.2)

The FLATPHANTOM V4 (figure 2.2) is a phantom for dosimetric evaluations of body mounted usage and system performance check for the frequency up to 3 GHz.



(Figure 2.3)

The Oval flat phantom (ELI 4) (figure 2.3) is a fiberglass shell phantom with 2 mm thickness.

The phantom is integrated in a wooden table.

The bottom plate of the table contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids).

A cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible.

On the phantom top, three reference markers are provided to identify the phantom positions with respect to the robot.



2.5.3 Tissue Simulating Liquids

The parameters of the tissue simulating liquid strongly influence the SAR. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE P1528-2003, December 2003).

Tissue dielectric properties

	Не	ead	В	ody
Frequency (MHz)	Relative Dielectric Constant (ε _r)	Conductivity (σ) (S/m)	Relative Dielectric Constant (ε _r)	Conductivity (σ) (S/m)
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
1450	40.5	1.20	54.0	1.30
1800	40.0	1.40	53.3	1.52
1900	40.0	1.40	53.3	1.52
2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73



2.5.4 Device Holder

The DASY device holder (figure 3.1 and 3.2) is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The rotation centers for both scales is the ear opening. Thus the device needs no repositioning when changing the angles.



Figure 3.1 Figure 3.2

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\varepsilon = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



2.5.5 Probes

The SAR measurements were conducted with the dosimetric probe ET3DV6 (figure 4), designed in the classical triangular configuration and optimized for dosimetric evaluation. [3] The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped at reaching the maximum.

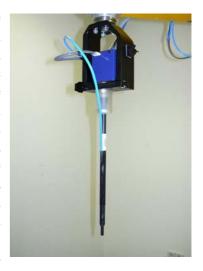


Figure 4

Probe Specifications

Calibration: In air from 10 MHz to 2.5 GHz

In brain and muscle simulating tissue at Frequencies of 835 MHz,

900 MHz, 1800 MHz, 1900 MHz and 2450 MHz

Calibration certificates please find attached.

Frequency: 10 MHz to > 3 GHz; Linearity: $\pm 0.2 \text{ dB}$ (30 MHz to 3 GHz)

Directivity: $\pm 0.2 \text{ dB}$ in HSL (rotation around probe axis)

 \pm 0.4 dB in HSL (rotation normal probe axis)

Dynamic Range: $5 \mu \text{W/g to} > 100 \text{ mW/g}$;

Linearity: $\pm 0.2 \text{ dB}$

Dimensions: Overall length: 330 m

Tip length: 16 mm Body diameter: 12 mm Tip diameter: 6.8 mm

Distance from probe tip to dipole centers: 2.7 mm

Application: General dosimetry up to 3 GHz

Compliance tests of mobile phones

Fast automatic scanning in arbitrary phantoms



2.6 Test System Specification

Positioner

Robot: Stäubli Animation Corp. Robot Model: RX90B L

Repeatability: 0.02 mm

No. of axis: 6

Data Acquisition Electronic (DAE) System

Cell Controller

Processor: Pentium IV 2.0 GHz Clock Speed:

Windows 2000 Operating System: DASY4 PC-Board Data Card:

Data Converter

Features: Signal Amplifier, multiplexer, A/D converter, & control logic

DASY4 software Software:

Connecting Lines: Optical downlink for data and status info.

Optical uplink for commands and clock

PC Interface Card

Function: 24 bit (64 MHz) DSP for real time processing

Link to DAE3

16 bit A/D converter for surface detection system

serial link to robot

direct emergency stop output for robot

E-Field Probes

ET3DV6 SN1711 Model:

Triangular core fiber optic detection system Construction:

10 MHz to 6 GHz Frequency:

Linearity: \pm 0.2 dB (30MHz to 3 GHz)

Phantom

Phantom 1: Oval flat phantom (ELI 4)

Shell Material: **Fiberglass** $2.0 \pm 0.2 \text{ mm}$ Thickness:

Phantom 2: Flat Phantom (V4.4)

Fiberglass Shell Material: $6.0 \pm 0.2 \text{ mm}$ Thickness:

Phantom 3: SAM Twin Phantom (V4.0)

Shell Material: **Fiberglass** Thickness: $2.0 \pm 0.2 \text{ mm}$



2.7 Measurement Procedure

The evaluation was performed using the following procedure:

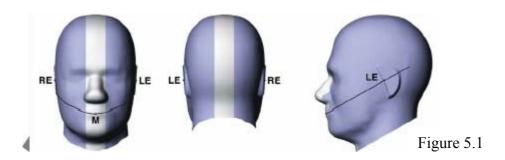
- 1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value
- 2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 10mm x 10mm.
- 3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 30mm x 30mm x 30mm (fine resolution volume scan, zoom scan) was assessed by measuring 5 x 5 x 5 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure:
 - a. The data at the surface was extrapolated, since the center of the dipoles is 2.7mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
 - b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions) [4] [5]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
 - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
- 4. The SAR reference value, at the same location as procedure #1, was re-measured. If the value changed by more than 5 %, the evaluation is repeated.



2.8 Reference Points

2.8.1 Ear Reference Points

Figure 5.1 shows the front, back and side vies of SAM. The point "M" is the reference point for the center of mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15 mm posterior to the entrance to ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 5.2. The plane passing through the two ear reference points and M is defined as the Reference Plane. The line N-F (Neck-Front) perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 5.3). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines should be marked on the external phantom shell to facilitate handset positioning. Posterior to the N-F line, the thickness of the N-F line, the ear is truncated as illustrated in Figure 5.2. The ear truncation is introduced to avoid the handset from touching the ear lobe, which can cause unstable handset positioning at the cheek. [6]



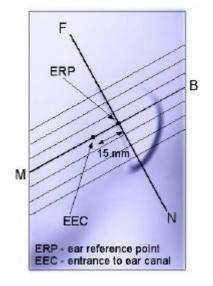
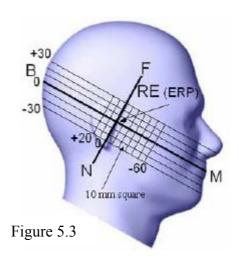


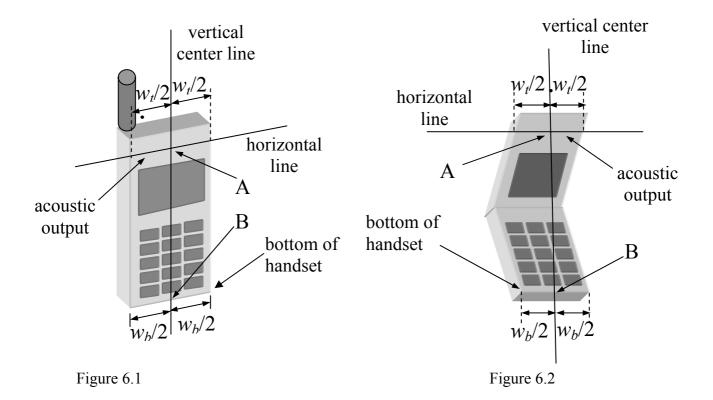
Figure 5.2





2.8.2 Handset Reference Points

Two imaginary lines on the handset were defined: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width w_t of the handset at the level of the acoustic output (point A on Figures 6.1 and 6.2), and the midpoint of the width wb of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 6.1). The two lines intersect at point A. For many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. The vertical centerline is not necessarily parallel to the front face of the handset (see Figure 6.2), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets. [6]





2.9 Test Positions

2.9.1 "Cheek" / "Touch" Position

The EUT was positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.

The EUT was translated towards the phantom along the line passing through RE and LE until the handset touches the pinna.

While maintaining the handset in this plane, the EUT was rotated it around the LE-RE line until the vertical centerline was in the plane normal to MB-NF including the line MB (called the reference plane).

The EUT was rotated around the vertical centerline until the handset (horizontal line) was symmetrical with respect to the line NF.

While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, the EUT was rotated about the line NF until any point on the handset was in contact with a phantom point below the pinna (cheek). [6] See Figure 7.



Figure 7



2.9.2 "Tilted" Position

The EUT was in "cheek position".

While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.

The EUT was rotated around the horizontal line by 15 degrees.

While maintaining the orientation of the handset, the EUT was moved towards the phantom on a line passing through RE and LE until any part of the handset touched the ear. The tilted position is obtained when the contact is on the pinna. If the contact was at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset would be reduced. In this case, the tilted position is obtained if any part of the handset was in contact with the pinna as well as a second part of the handset was in contact with the phantom (e.g., the antenna with the back of the head). [6] See Figure 8.



Figure 8



2.9.3 Belt Clip/Holster Configuration

Test configurations for body-worn operated EUTs are carried out while the belt-clip and/or holster is attached to the EUT and placed against a flat phantom in a regular configuration (see Figure 9). An EUT with a headset output is tested with a headset connected to the device.

Body dielectric parameters are used.

There are two categories for accessories for body-worn operation configurations:

- 1. accessories not containing metallic components
- 2. accessories containing metallic components.

When the EUT is equipped with accessories not containing metallic components the tests are done with the accessory that dictates the closest spacing to the body. For accessories containing metallic parts a test with each one is implemented. If the multiple accessories share an identical metallic component (e.g. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that has the closest spacing to the body is tested.

In case that a EUT authorized to be body-worn is not supplied or has no options to be operated with any accessories, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters operating in front of a person's face (e.g. push-to-talk configurations) are tested for SAR compliance with the front of the device positioned to face the flat platform. SAR Compliance tests for shoulder, waist or chest-worn transmitters are carried out with the accessories including headsets and microphones attached to the device and placed against a flat phantom in a regular configuration.

The SAR measurements are performed to investigate the worst-case positioning. This is documented and used to perform Body SAR testing. [2].



Figure 9



2.9.4 Headset Configuration

Headsets which have their radiating structure in close proximity to the head are measured according to the following conditions.

- Head tissue liquid is used.
- The EUT is positioned on the surface of the head of phantom according the picture below. Right and left position is tested according to the normal use (see figure 10).
- Additional metallic parts like clips or others are subject of testing, too.



Figure 10

Headsets which have their radiating structure in close proximity to the body are tested as body worn equipment.



2.10 Measurement uncertainty

The uncertainty budget has been determined for the DASY4 system performance check according to IEEE Std. 1528-2003 December 2003.

	Tol.	Prob.	Div.	$(^{c}i^{)1}$	Std. unc.	$(v_i)^{2}$
Error Description	(± %)	dist.		(1g)	(1g) (± %)	•
Measurement System						
Probe Calibration	4.8	N	1	1	4.8	∞
Axial Isotropy	4.7	R	√3	0.7	1.9	∞
Hemispherical Isotropy	9.6	R	$\sqrt{3}$	0.7	3.9	∞
Boundary Effects	1.0	R	√3	1	0.6	∞
Linearity	4.7	R	√3	1	2.7	∞
System Detection Limit	1.0	R	$\sqrt{3}$	1	0.6	∞
Readout Electronics	1.0	N	1	1	1.0	∞
Response Time	0.8	R	√3	1	0.5	∞
Integration Time	2.6	R	√3	1	1.5	∞
RF Ambient Conditions	3.0	R	√3	1	1.7	∞
Probe Positioner	0.4	R	√3	1	0.2	∞
Probe Positioning	2.9	R	√3	1	1.7	∞
Algorithms for Max. SAR Eval.	1.0	R	√3	1	0.6	∞
Test Sample Related						
Device Positioning	2.9	N	1	1	2.9	145
Device Holder	3.6	N	1	1	3.6	5
Power Drift	5.0	R	√3	1	2.9	∞
Phantom and Setup						
Phantom Uncertainty	4.0	R	√3	1	2.3	∞
Liquid Conductivity (target)	5.0	R.	√3	0.64	1.8	∞
Liquid Conductivity (meas.)	2.6	N	1	0.64	1.7	∞
Liquid Permittivity (target)	5.0	R	√3	0.6	1.7	∞
Liquid Permittivity (meas.)	3.8	N	1	0.6	2.3	∞
Combined Standard Uncertainty					10.4	330
Expanded Uncertainty kp=2						
Coverage Factor for 95%					20.8	

The budget is valid for the frequency range 300 MHz - 3 GHz and represent a worst case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



3. Tissue and System Verification

3.1 Tissue Verification

Dielectric parameters of the simulating liquids were verified using a Dielectric Probe Kit Agilent 85070D to a tolerance of \pm 5 %.

Room Temperature: 22.1 -22.6 ° C

	Measured Tissue Parameters 1900 MHz Brain		
	Target	Measured 19.03.2007	
Date		22.1 ° C	
Liquid Temperature:		22.1 ° C	
Dielectric Constant: ε	40.0	39.9	
Conductivity: σ	1.40	1.42	

Room Temperature: 22.1 -22.6 ° C

	Measured Tissue Parameters 1900 MHz Muscle		
	Target	Measured 19.03.2007	
Date		22,1 ° C	
Liquid Temperature:		22,1 ° C	
Dielectric Constant: ε	53.3	51.9	
Conductivity: σ	1.52	1.58	



3.2 System Verification

Prior to the assessment, the system was verified by using a 1900 MHz validation dipole. Power level of 250 mW was supplied to the dipole antenna placed under the flat section of SAM Phantom. This system validation is valid for a frequency range of 900 ± 100 MHz.

The system was verified to a tolerance of \pm 10 %.

Liquid Temperature: $22.0 - 22.3 \,^{\circ}$ CRoom Temperature: $22.1 - 22.6 \,^{\circ}$ CLiquid Depth: $> 15.5 \,^{\circ}$ cm

System Dipole Validation Target & Measurement						
Date	System Validation Kit:	Liquid	Targeted SAR 1g (mW/g)	Measured SAR 1g (mW/g)	Deviation (%)	
19.03.2007	D1900V2 SN5d025	1900 MHz Head	40,4	41,6	2,97	
19.03.2007	D1900V2 SN5d025	1900 MHz Muscle	45,6	42,8	-6,14	

Comment: Please find attached the measurement plots.



Room Temperature: 22.1 -22.6 °C

4. Test Results

Procedures Used To Establish Test Signal

The EUT was placed into simulated call mode (e.g. AMPS, Cellular CDMA & PCS CDMA modes) using manufacturers test codes. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [2]. The actual transmission is activated through a base station simulator or similar when test modes are not available or inappropriate for testing the EUT.

The EUT is rechargeable battery operated. The battery used for the SAR measurements was completely charged. The device was tested at full power verified by implementing conducted output power measurements. For confirming of the output power it was tested before and after each SAR measurement. The test was repeated if a conducted power deviation of more than 5 % occurred.

Mixture Type: 1900 MHz Head Date: 19.03.2007 Liquid Temperature: 22.0 -22.3 ° C

	Freque	ncy	Power	Antenna Pos.	Phantom	Test	SAR
MHz	Channel	Modulation	Drift dBm		Section	Position	(W/kg)
1924.99	2	DECT (UPCS)	-0.001	Integral	Left Ear	Cheek	0.010
1924.99	2	DECT (UPCS)	-0,039	Integral	Left Ear	Tilt	0.00814
1921.54	4	DECT (UPCS)	-0.023	Integral	Right Ear	Cheek	0.010
1924.99	2	DECT (UPCS)	0.073	Integral	Right Ear	Cheek	0.011
1924.99	2	DECT (UPCS)	-0.068	Integral	Right Ear	Tilt	0.0099
1928.45	0	DECT (UPCS)	0.077	Integral	Right Ear	Cheek	0.011



Mixture Type: 1900 MHz Muscle

Date: 19.03.2007

Liquid Temperature: 22.0 -22.3 °C Room Temperature: 22.1 -22.6 °C

Antenna: 0

	Freque	ncy	Power	Antenna Pos.	Phantom	Test	SAR
MHz	Channel	Modulation	Drift dBm		Section	Position	(W/kg)
1921.54	4	DECT (UPCS)	-0.031	Integral	Flat	Front	0.019
1924.99	2	DECT (UPCS)	-0.023	Integral	Flat	Front	0.018
1924.99	2	DECT (UPCS)	0.098	Integral	Flat	Back	0.00611
1928.45	0	DECT (UPCS)	0.047	Integral	Flat	Front	0.00859

Note: Device positioning: spacing from flat phantom was adjusted at 0 cm.

Limits:

	SAR (W/kg)						
Exposure Limits		lled Exposure ation Enviro		Controlled Exposure/Occupational Environment			
Region	Australia	US	EU	Australia	US	EU	
Spatial Average SAR (averaged over the whole body)	0.08	0.08	0.08	0.40	0.40	0.40	
Spatial Peak SAR (averaged over any 1 g of tissue)	2.00	1.60	2.00	10.0	8.00	10.0	
Spatial Peak SAR (Hands, Feet, Ankles, Wrist) (averaged over any 10 g of tissue)	4.00	4.00	4.00	20.0	20.0	20.0	

Notes:

- 1. Test data represent the worst case SAR value and test procedure used are according to OET Bulletin 65, Supplement C (01-01).
- 2. All modes of operation were investigated.



5. References

- [1] ANSI/IEEE C95.3 1991, *IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic fields, 300 kHz to 100 GHz*, New York: IEEE, Aug. 1992
- [2] Federal Communications Commission, OET Bulletin 65 (Edition 97-01), Supplement C (Edition 01-01), Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields, July 2001.
- [3] T. Schmid, O. Egger, N. Kuster, *Automated E-field scanning system for dosimetric assessments*, IEEE Transaction on Microwave Theory and Techniques, vol. 44, Jan. 1996, pp. 105-113.
- [4] W. Gander, Computermathematics, Birkhaeuser, Basel, 1992.
- [5] W.H. Press, S.A. Teukolsky, W.T. Vetterling, and B.P. Flannery, *Numerical Recipes in C*, The Art of Scientific Computing, Second edition, Cambridge University Press, 1992.
- [6] IEEE Standards Coordinating Committee 34 IEEE Std. 1528-2003, December 2003, Recommended Practice for Determining the Peak Spatial-Average Absorption Rate (SAR in the Human Body Due to Wireless Communications Devices: Experimental Techniques.
- [7] DASY4 Dosimetric Assessment System Manual; Draft; September 6, 2002; Schmid & Partner Engineering AG



6. Appendix

1. Appendix A Calibration Certificate D1900V2 SN5d025

ET3DV6 SN1711 DAE3V1-522

2. Appendix B Measurement Plots

3. Appendix C Pictures



Appendix A

Calibration Certificate

Note:

The calibration cycle for SAR field probes and related equipment is determined to one year. According to ETS 's internal quality management instruction based on EN 17025 the calibration cycle for other test equipment is determined to 2 years. Additionally, ETS has prolonged the calibration interval for SPEAG System Validation Dipoles by two additional years. These QM procedures are acknowledged by the accreditation bodies mentioned on page 3 of this report during several accreditation audits.

Calibration Laboratory of

Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland





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Issued: September 28, 2006

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C

S

Client

Dr. Genz

Cardinate No. D2450V2-722_Sep.06

SISTEM TO THE STATE OF THE STAT Object QA CAL-05.NB Calibration procedure(s) Calibration procedure for dipo Calibration date: In Tolerance Condition of the calibrated item This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%. Calibration Equipment used (M&TE critical for calibration) Scheduled Calibration ID# Cal Date (Calibrated by, Certificate No.) **Primary Standards** Power meter EPM-442A GB37480704 04-Oct-05 (METAS, No. 251-00516) Oct-06 Power sensor HP 8481A US37292783 04-Oct-05 (METAS, No. 251-00516) Oct-06 10-Aug-06 (METAS, No 217-00591) Aug-07 Reference 20 dB Attenuator SN: 5086 (20g) Aug-07 Reference 10 dB Attenuator SN: 5047.2 (10r) 10-Aug-06 (METAS, No 217-00591) Reference Probe ES3DV2 SN 3025 28-Oct-05 (SPEAG, No. ES3-3025_Oct05) Oct-06 DAE4 SN 601 15-Dec-05 (SPEAG, No. DAE4-601_Dec05) Dec-06 Secondary Standards ID# Check Date (in house) Scheduled Check MY41092317 18-Oct-02 (SPEAG, in house check Oct-05) In house check: Oct-07 Power sensor HP 8481A In house check: Nov-07 RF generator Agilent E4421B MY41000675 11-May-05 (SPEAG, in house check Nov-05) Network Analyzer HP 8753E US37390585 S4206 18-Oct-01 (SPEAG, in house check Nov-05) In house check: Nov-06 **Function** Signature Name

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Claudio Leuble

Calibrated by:

Approved by:

Calibration Laboratory of

Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland





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Glossary:

TSL tissue simulating liquid

ConvF sensitivity in TSL / NORM x,y,z N/A not applicable or not measured

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz 3 GHz), July 2001
- c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

Additional Documentation:

d) DASY4 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions: Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL: The dipole is mounted with the spacer to position its feed
 point exactly below the center marking of the flat phantom section, with the arms oriented
 parallel to the body axis.
- Feed Point Impedance and Return Loss: These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay: One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured: SAR measured at the stated antenna input power.
- SAR normalized: SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters: The measured TSL parameters are used to calculate the nominal SAR result.

Certificate No: D2450V2-722_Sep06 Page 2 of 9

Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	SY Version DASY4		
Extrapolation	Advanced Extrapolation		
Phantom	Modular Flat Phantom V5.0		
Distance Dipole Center - TSL	10 mm	with Spacer	
Zoom Scan Resolution	dx, dy, dz = 5 mm		
Frequency	2450 MHz ± 1 MHz		

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	37.8 ± 6 %	1.77 mho/m ± 6 %
Head TSL temperature during test	(22.0 ± 0.2) °C	Mile Annual Spin Annual Sp	

SAR result with Head TSL

SAR averaged over 1 cm³ (1 g) of Head TSL	condition	
SAR measured	250 mW input power	13.6 mW / g
SAR normalized	normalized to 1W	54.4 mW / g
SAR for nominal Head TSL parameters ¹	normalized to 1W	53.8 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm³ (10 g) of Head TSL	condition	
SAR measured	250 mW input power	6.31 mW/g
SAR normalized	normalized to 1W	25.2 mW / g
SAR for nominal Head TSL parameters ¹	normalized to 1W	25.0 mW / g ± 16.5 % (k=2)

Certificate No: D2450V2-722_Sep06 Page 3 of 9

¹ Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	52.1 ± 6 %	1.97 mho/m ± 6 %
Body TSL temperature during test	(21.6 ± 0.2) °C		

SAR result with Body TSL

SAR averaged over 1 cm³ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	13.8 mW/g
SAR normalized	normalized to 1W	55.2 mW / g
SAR for nominal Body TSL parameters ²	normalized to 1W	54.5 mW / g ± 17.0 % (k=2)

SAR averaged over 10 cm³ (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	6.39 mW / g
SAR normalized	normalized to 1W	25.6 mW / g
SAR for nominal Body TSL parameters ²	normalized to 1W	25.4 mW / g ± 16.5 % (k=2)

Certificate No: D2450V2-722_Sep06

² Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

Appendix

Antenna Parameters with Head TSL

Impedance, transformed to feed point	50.4 Ω + 6.4 jΩ
Return Loss	– 24.0 dB

Antenna Parameters with Body TSL

Impedance, transformed to feed point	46.5 Ω + 6.3 jΩ
Return Loss	– 22.6 dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.153 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
Manufactured on	October 16, 2002

Certificate No: D2450V2-722_Sep06 Page 5 of 9

DASY4 Validation Report for Head TSL

Date/Time: 27.09.2006 11:58:51

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN722

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: HSL U10 BB;

Medium parameters used: f = 2450 MHz; $\sigma = 1.77$ mho/m; $\epsilon_r = 37.8$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

Probe: ES3DV2 - SN3025 (HF); ConvF(4.4, 4.4, 4.4); Calibrated: 28.10.2005

• Sensor-Surface: 4mm (Mechanical Surface Detection)

Electronics: DAE4 Sn601; Calibrated: 15.12.2005

• Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; ;

Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

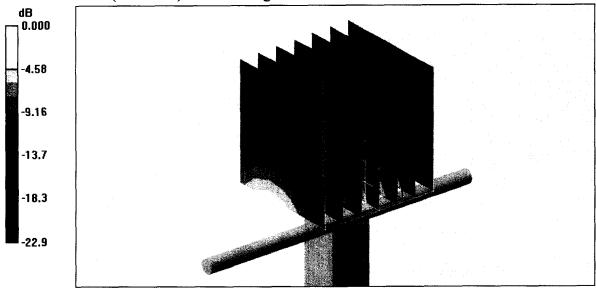
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 90.6 V/m; Power Drift = -0.016 dB

Peak SAR (extrapolated) = 28.4 W/kg

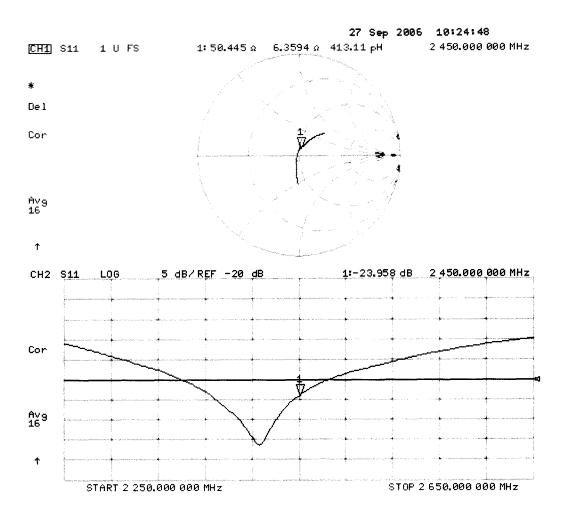
SAR(1 g) = 13.6 mW/g; SAR(10 g) = 6.31 mW/g

Maximum value of SAR (measured) = 15.2 mW/g



0 dB = 15.2 mW/g

Impedance Measurement Plot for Head TSL



DASY4 Validation Report for Body TSL

Date/Time: 27.09.2006 14:44:54

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN722

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: MSL U10 BB;

Medium parameters used: f = 2450 MHz; $\sigma = 1.97$ mho/m; $\varepsilon_r = 52.2$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

Probe: ES3DV2 - SN3025 (HF); ConvF(4.06, 4.06, 4.06); Calibrated: 28.10.2005

• Sensor-Surface: 4mm (Mechanical Surface Detection)

Electronics: DAE4 Sn601; Calibrated: 15.12.2005

Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA;;

Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:

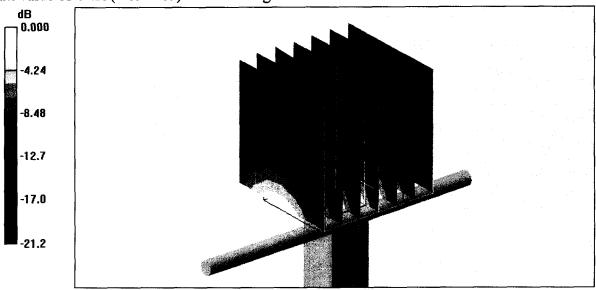
Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 89.4 V/m; Power Drift = 0.005 dB

Peak SAR (extrapolated) = 29.3 W/kg

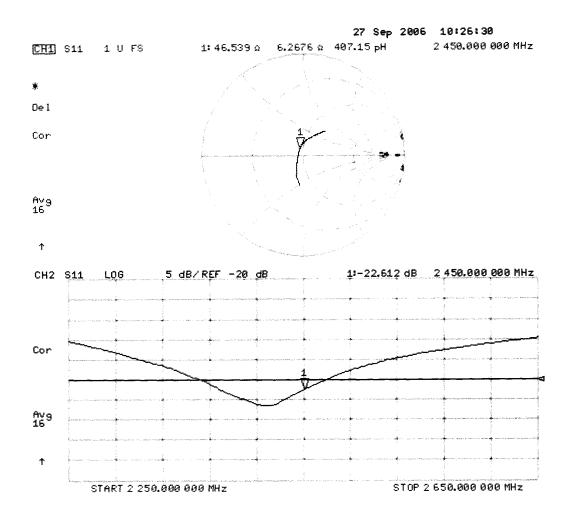
SAR(1 g) = 13.8 mW/g; SAR(10 g) = 6.39 mW/g

Maximum value of SAR (measured) = 15.7 mW/g



0 dB = 15.7 mW/g

Impedance Measurement Plot for Body TSL



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Object QA CAL-01.v5 and QA CAL-12. Calibration procedure for desima Calibration procedure(s) Calibration date: Condition of the calibrated item This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate. All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%. Calibration Equipment used (M&TE critical for calibration) **Scheduled Calibration Primary Standards** Cal Date (Calibrated by, Certificate No.) Apr-07 Power meter E4419B GB41293874 5-Apr-06 (METAS, No. 251-00557) Power sensor E4412A MY41495277 5-Apr-06 (METAS, No. 251-00557) Apr-07 Apr-07 Power sensor E4412A MY41498087 5-Apr-06 (METAS, No. 251-00557) Aug-07 Reference 3 dB Attenuator SN: S5054 (3c) 10-Aug-06 (METAS, No. 217-00592) Apr-07 Reference 20 dB Attenuator SN: S5086 (20b) 4-Apr-06 (METAS, No. 251-00558) Reference 30 dB Attenuator SN: S5129 (30b) 10-Aug-06 (METAS, No. 217-00593) Aug-07 Jan-07 Reference Probe ES3DV2 SN: 3013 2-Jan-06 (SPEAG, No. ES3-3013_Jan06) SN: 654 21-Jun-06 (SPEAG, No. DAE4-654_Jun06) Jun-07 DAE4 Scheduled Check Secondary Standards Check Date (in house) in house check: Nov-07 RF generator HP 8648C US3642U01700 4-Aug-99 (SPEAG, in house check Nov-05) Network Analyzer HP 8753E US37390585 18-Oct-01 (SPEAG, in house check Nov-05) In house check: Nov 06 Name **Function** Signature Calibrated by: Approved by: Issued: October 16, 2006

Certificate No: ET3-1711_Oct06

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Glossary:

TSL tissue simulating liquid NORMx,y,z sensitivity in free space

ConF sensitivity in TSL / NORMx,y,z
DCP diode compression point

Polarization φ φ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at

measurement center), i.e., $\vartheta = 0$ is normal to probe axis

Calibration is Performed According to the Following Standards:

- a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
- b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz 3 GHz), July 2001

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization 9 = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E^2 -field uncertainty inside TSL (see below *ConvF*).
- NORM(f)x,y,z = NORMx,y,z * frequency_response (see Frequency Response Chart). This
 linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of
 the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

October 16, 2006

Probe ET3DV6

SN:1711

Manufactured:

August 7, 2002

Last calibrated:

November 21, 2005

Repaired:

September 28, 2006

Recalibrated:

October 16, 2006

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

ET3DV6 SN:1711 October 16, 2006

DASY - Parameters of Probe: ET3DV6 SN:1711

Sensitivity in Free Space ^A			Diode C	ompression ^B	ł
NormX	1.94 ± 10.1%	μ V/(V/m) ²	DCP X	93 mV	
NormY	1.84 ± 10.1%	μ V/(V/m) ²	DCP Y	95 mV	
NormZ	2.04 ± 10.1%	μV/(V/m) ²	DCP Z	94 mV	

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

Boundary Effect

TSL	900 MHz	Typical SAR	gradient: 5 %	per mm

Sensor Center t	o Phantom Surface Distance	3.7 mm	4.7 mm
SAR _{be} [%]	Without Correction Algorithm	8.5	4.7
SAR _{be} [%]	With Correction Algorithm	0.1	0.1

TSL 1810 MHz Typical SAR gradient: 10 % per mm

Sensor Center t	o Phantom Surface Distance	3.7 mm	4.7 mm
SAR _{be} [%]	Without Correction Algorithm	7.2	3.8
SAR _{be} [%]	With Correction Algorithm	0.2	0.1

Sensor Offset

Probe Tip to Sensor Center 2.7 mm

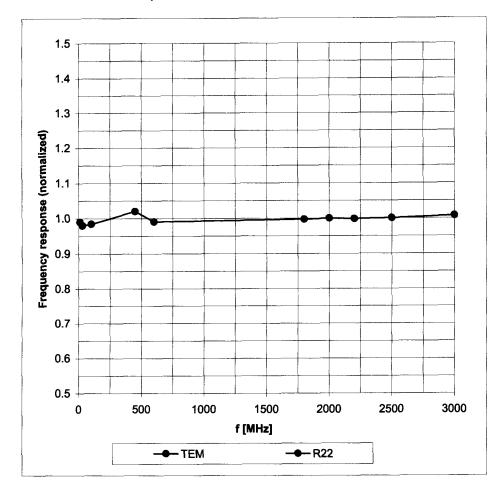
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A The uncertainties of NormX,Y,Z do not affect the E²-field uncertainty inside TSL (see Page 8).

^B Numerical linearization parameter: uncertainty not required.

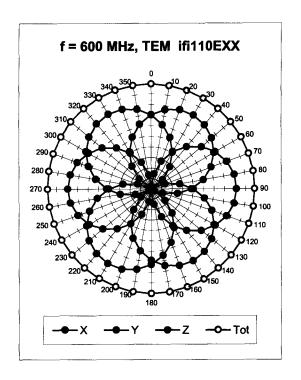
Frequency Response of E-Field

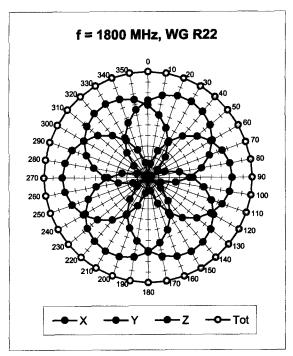
(TEM-Cell:ifi110 EXX, Waveguide: R22)

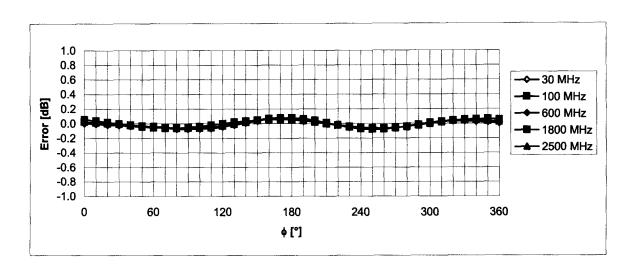


Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

Receiving Pattern (ϕ), θ = 0°



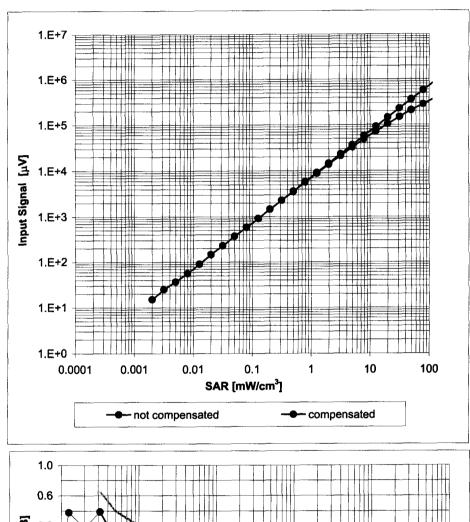


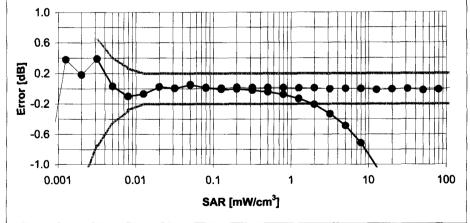


Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Dynamic Range f(SAR_{head})

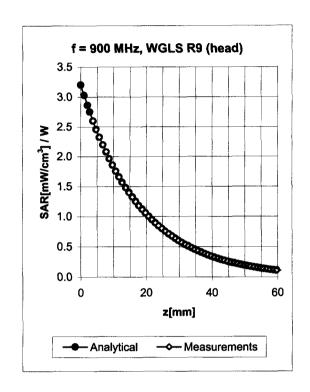
(Waveguide R22, f = 1800 MHz)

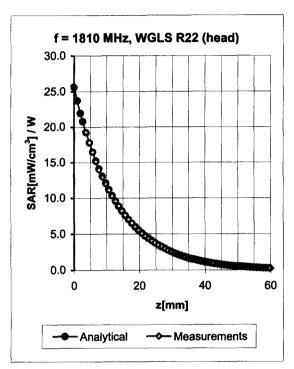




Uncertainty of Linearity Assessment: ± 0.6% (k=2)

Conversion Factor Assessment



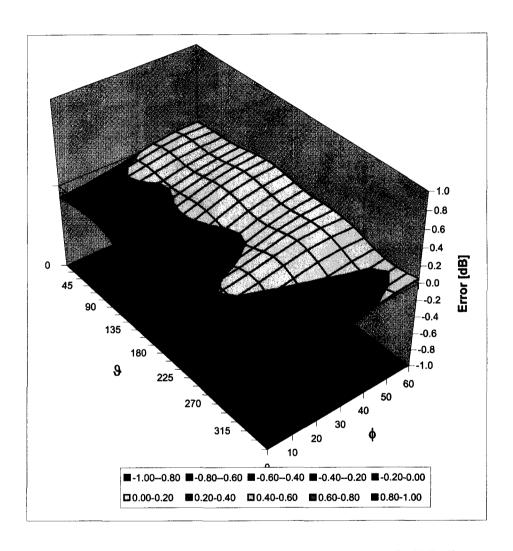


f [MHz]	Validity [MHz] ^c	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
450	± 50 / ± 100	Head	43.5 ± 5%	0.87 ± 5%	0.36	1.84	6.99 ± 13.3% (k=2)
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.55	1.90	6.38 ± 11.0% (k=2)
1810	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.49	2.67	5.16 ± 11.0% (k=2)
1950	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.58	2.45	4.89 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.65	2.07	4.52 ± 11.8% (k=2)
450	± 50 / ± 100	Body	56.7 ± 5%	0.94 ± 5%	0.30	1.90	7.72 ± 13.3% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	0.51	2.05	6.11 ± 11.0% (k=2)
1810	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.63	2.57	4.57 ± 11.0% (k=2)
1950	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.72	2.42	4.42 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.64	1.92	4.06 ± 11.8% (k=2)

^c The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

Deviation from Isotropy in HSL

Error (ϕ, ϑ) , f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





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Client

ETS

Certificate No: DAE3-522_Sep06

Accreditation No.: SCS 108

CALIBRATION C	ERTIFICATE		
Object	DAE3 - SD 000 D	03 AA - SN: 522	
Calibration procedure(s)	QA CAL-06.v12 Calibration proces	lure for the data acquisition electro	nics (DAE)
Calibration date:	September 21, 20	06	
Condition of the calibrated item	In Tolerance		
		onal standards, which realize the physical units on obability are given on the following pages and ar	
All calibrations have been conducted	ed in the closed laboratory	r facility: environment temperature (22 ± 3)°C an	d humidity < 70%.
Calibration Equipment used (M&TE	E critical for calibration)		
Primary Standards	ID#	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Fluke Process Calibrator Type 702	SN: 6295803	7-Oct-05 (Sintrel, No.E-050073)	Oct-06
Secondary Standards	ID#	Check Date (in house)	Scheduled Check
Calibrator Box V1.1	SE UMS 006 AB 1002	15-Jun-06 (SPEAG, in house check)	In house check Jun-07
Calibrated by:	Name Daniel Steinacher	Function Technician	Signature Skinada
Approved by:	Fin Bomholt	R&D Director 7.2	Esterado Esnhell

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: DAE3-522_Sep06

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Accreditation No.: SCS 108

Glossary

DAE

data acquisition electronics

Connector angle

information used in DASY system to align probe sensor X to the robot

coordinate system.

Methods Applied and Interpretation of Parameters

- DC Voltage Measurement: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- Connector angle: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters contain technical information as a result from the performance test and require no uncertainty.
- DC Voltage Measurement Linearity: Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
- Common mode sensitivity: Influence of a positive or negative common mode voltage on the differential measurement.
- Channel separation: Influence of a voltage on the neighbor channels not subject to an input voltage.
- AD Converter Values with inputs shorted: Values on the internal AD converter corresponding to zero input voltage
- Input Offset Measurement: Output voltage and statistical results over a large number of zero voltage measurements.
- Input Offset Current: Typical value for information; Maximum channel input offset current, not considering the input resistance.
- Input resistance: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
- Low Battery Alarm Voltage: Typical value for information. Below this voltage, a battery alarm signal is generated.
- Power consumption: Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: $1LSB = 6.1 \mu V$, full range = -100...+300 mVLow Range: 1LSB = 61 nV, full range = -1......+3 mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	Х	Y	Z
High Range	404.296 ± 0.1% (k=2)	403.959 ± 0.1% (k=2)	404.794 ± 0.1% (k=2)
Low Range	3.95220 ± 0.7% (k=2)	3.93931 ± 0.7% (k=2)	3.94312 ± 0.7% (k=2)

Connector Angle

Connector Angle to be used in DASY system	59°±1°

Certificate No: DAE3-522_Sep06 Page 3 of 5

Appendix

1. DC Voltage Linearity

High Range		Input (μV)	Reading (μV)	Error (%)
Channel X	+ Input	200000	200000.1	0.00
Channel X	+ Input	20000	20004.16	0.02
Channel X	- Input	20000	-19999.50	0.00
Channel Y	+ Input	200000	200000.2	0.00
Channel Y	+ Input	20000	20004.75	0.02
Channel Y	- Input	20000	-19999.93	0.00
Channel Z	+ Input	200000	199999.7	0.00
Channel Z	+ Input	20000	20002.63	0.01
Channel Z	- Input	20000	-20001.06	0.01

Low Range		Input (μV)	Reading (μV)	Error (%)
Channel X +	Input	2000	1999.9	0.00
Channel X +	Input	200	199.36	-0.32
Channel X - I	nput	200	-200.02	0.01
Channel Y +	Input	2000	2000.1	0.00
Channel Y +	Input	200	199.32	-0.34
Channel Y - I	nput	200	-200.30	0.15
Channel Z +	Input	2000	1999.9	0.00
Channel Z +	Input	200	199.77	-0.12
Channel Z - I	nput	200	-200.39	0.19

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-4.35	-5.20
	- 200	6.12	5.53
Channel Y	200	0.14	0.72
	- 200	-0.21	-2.36
Channel Z	200	16.34	16.58
	- 200	-17.88	-18.43

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	_	3.41	-0.46
Channel Y	200	0.54	-	3.51
Channel Z	200	-2.42	-0.05	<u>-</u>

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4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15736	16552
Channel Y	15745	15304
Channel Z	16042	16452

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10MΩ

TIPUL TOWNS	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	1.32	-0.10	4.21	0.65
Channel Y	-1.99	-4.00	-0.76	0.64
Channel Z	-0.69	-1.56	0.68	0.54

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.2000	199.0
Channel Y	0.2000	199.7
Channel Z	0.2001	196.7

8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9