

Raymarine SmartController User Guide



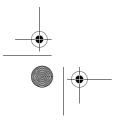
Welcome to the SmartController

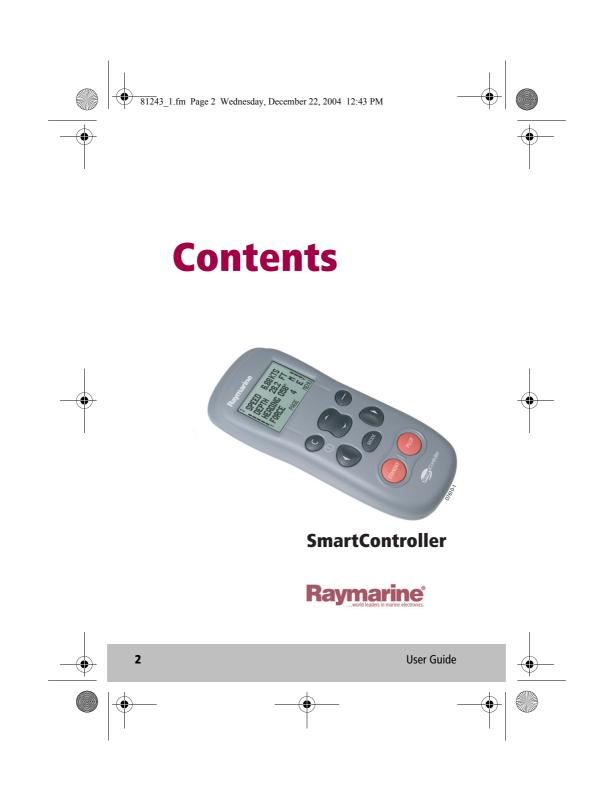
Handbooks can be such daunting things, can't they? Please don't worry, we have made this guide as simple as possible.

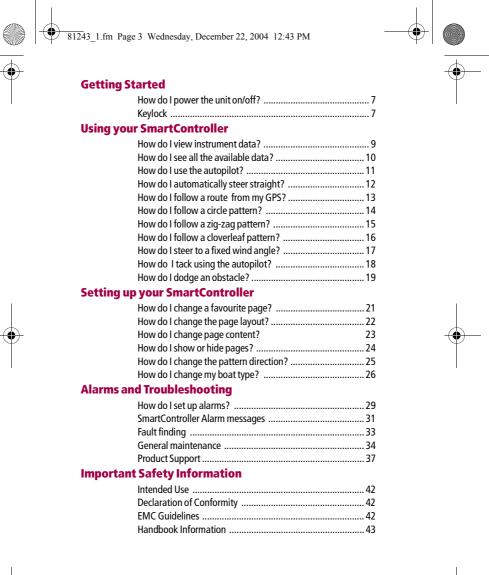
Your guide contains an explanation on how to use your SmartController, so finding your way around will become second nature.

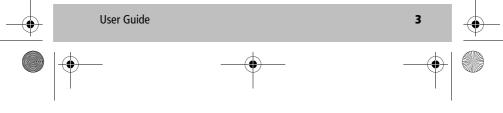
If all you want to do is power up and get going, that's fine. But if you want to know more about what your SmartController will do for you, you'll find it here.

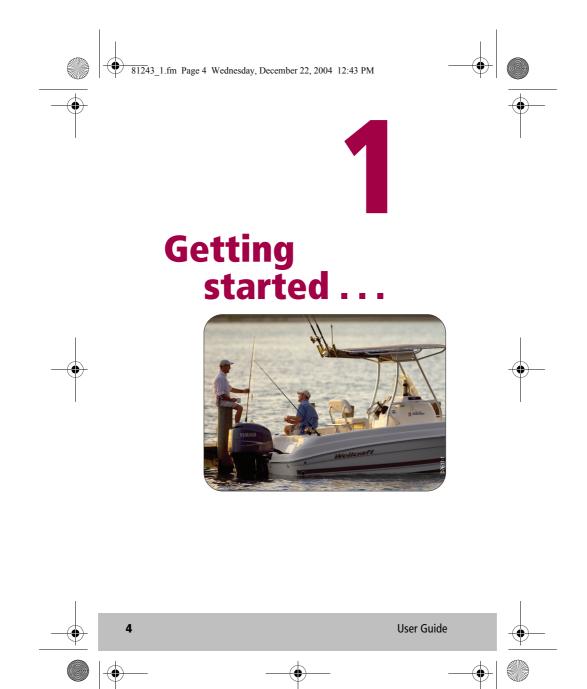
Document Number: 81243-1 Date: December 2004













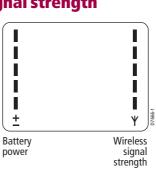
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81243_1.fm Page 5 Wednesday, December 22, 2004 12:43 PM

Battery power and signal strength

The battery power (5 levels) are indicated on the left hand side of the display. Your SmartController will sound an alarm when battery power is running low.

Wireless signal strength is shown similarly on the right hand side of the display.



Charging the SmartController

Before using the SmartController for the first time, you will need to charge the unit.

To charge the SmartController, simply place it into the cradle, pull open the rubber cover on the base and connect the charging cable.

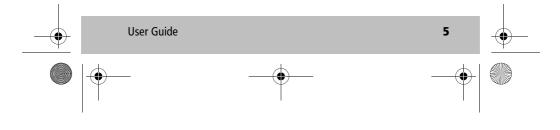
CAUTION:

Do not use any other cable to charge the unit.

The battery power indicator will flash during charging. The recommended charge time is approximately five hours. Once fully charged the battery indicator will stop flashing.

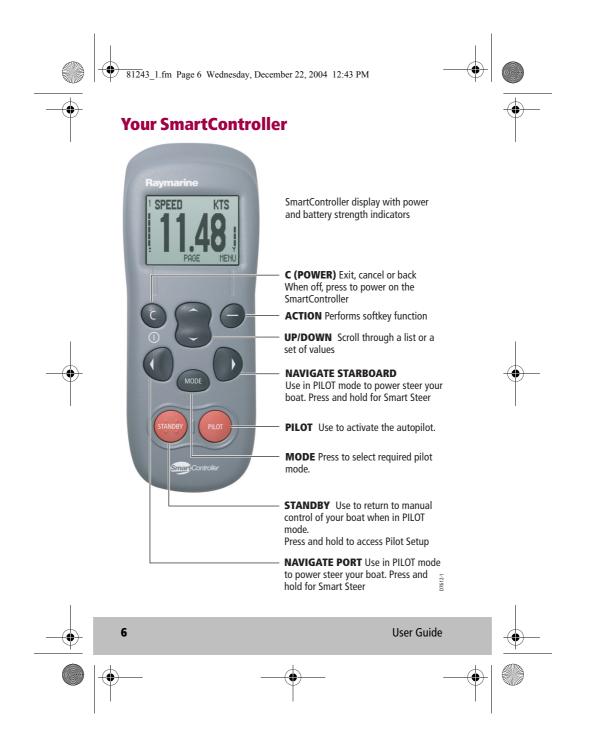
The SmartController can also be charged whenever you wish without affecting performance.













81243_1.fm Page 7 Wednesday, December 22, 2004 12:43 PM

How do I power the unit on/off?

Power on

Press and hold the **C** button. The handset will beep, the display will show the first instrument data page and you're ready to go.

Power off

Press and hold the **C** button for 3 seconds. The display will countdown to zero and will then go blank.

Note: You cannot power off the handset when the autopilot is in control of your boat.

Keylock

When using your SmartController, you can temporarily lock the autopilot keys to ensure that it is not accidentally operated. Access to the instrument pages is unaffected by the keylock.

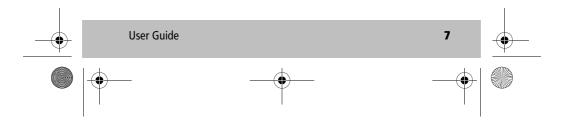
How do I activate the keylock?

Press and hold the **mode** button until you see the "KEYLOCK ACTIVE" message. A key symbol will also be displayed on the instrument data pages.

Note: You cannot activate keylock when the autopilot is in control of your boat.

How do I turn off the keylock?

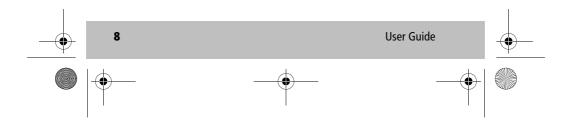
Press **mode** followed by **unlock**. A "KEYLOCK OFF" message will be displayed.

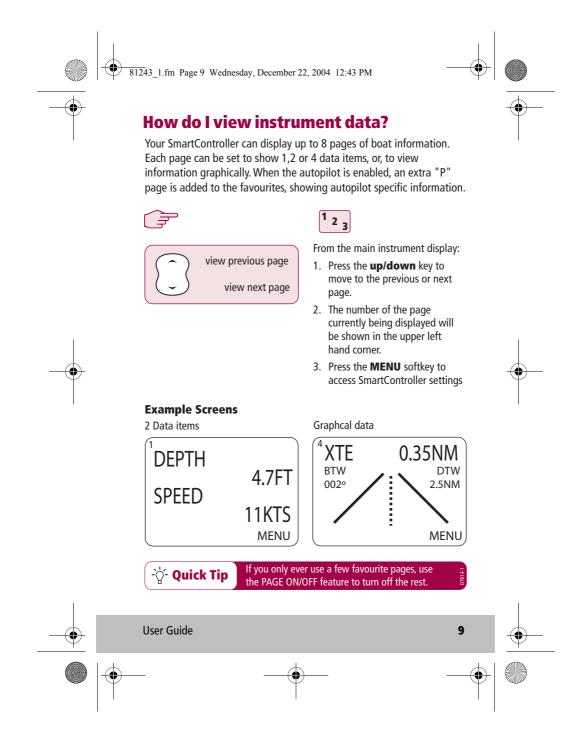


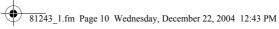












How do I see all the available data?

You can display all the available SeaTalk data in a list for reference. This is particularly useful when checking the availability of data, or when wishing to see an infrequently used reading.

$\overline{\bigcirc}$	MENU
	SHOW ALL DATA
$\overline{\bigcirc}$	SELECT
	Scroll through data list

Example Screen

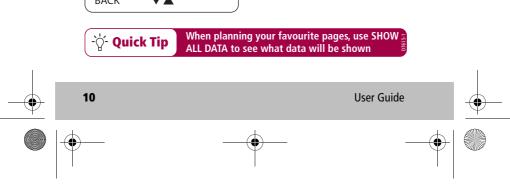
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ALL DATA		
DEPTH	4.7 FT	
SPEED	11 KTS	
SOG	9.7 KTS	
VMG W	KTS	
BACK	▼▲	

¹ _{2 3}

From the main instrument display:

- 1. Press the MENU softkey to display the main menu.
- 2. Using the up/down key, scroll to "SHOW ALL DATA" and press the SELECT softkey.
- All of the available SeaTalk data will be displayed with its present value. Use the up/down key to scroll through the data. Where the is no data present, "- - -" will be displayed.



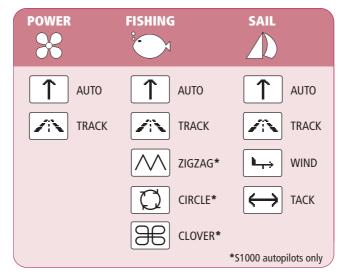


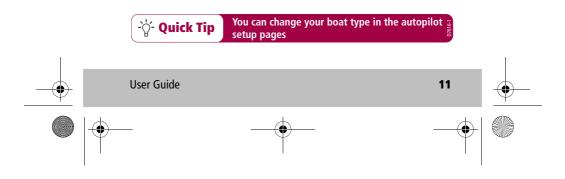
• 81243_1.fm Page 11 Wednesday, December 22, 2004 12:43 PM

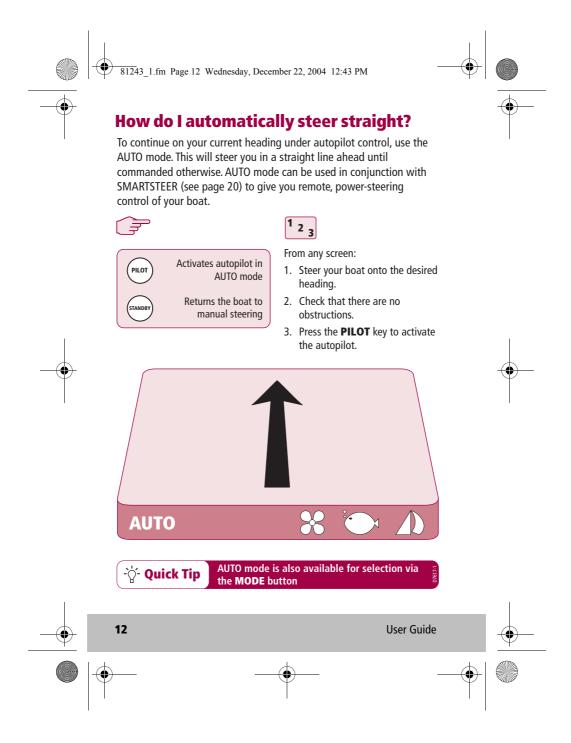
How do I use the autopilot?

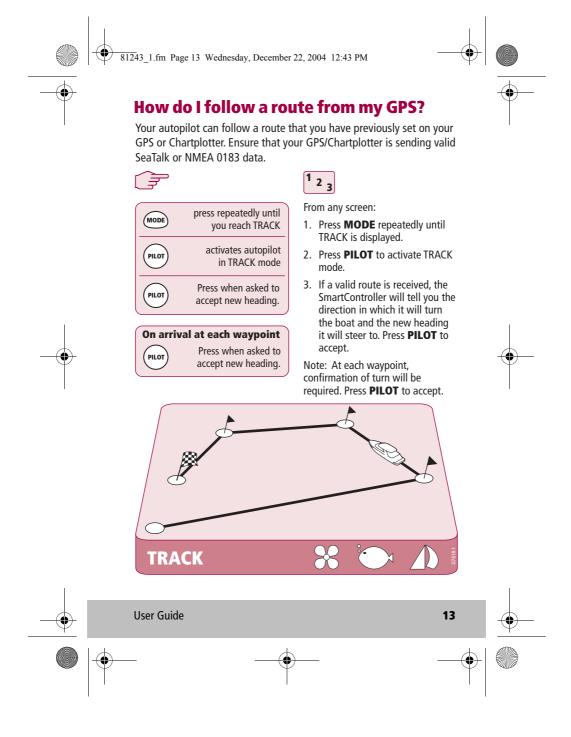
Your autopilot can steer your boat according to one of its preset modes. The modes that are available are dependant on your boat and autopilot type. Each of these are explained on the following pages. ¢

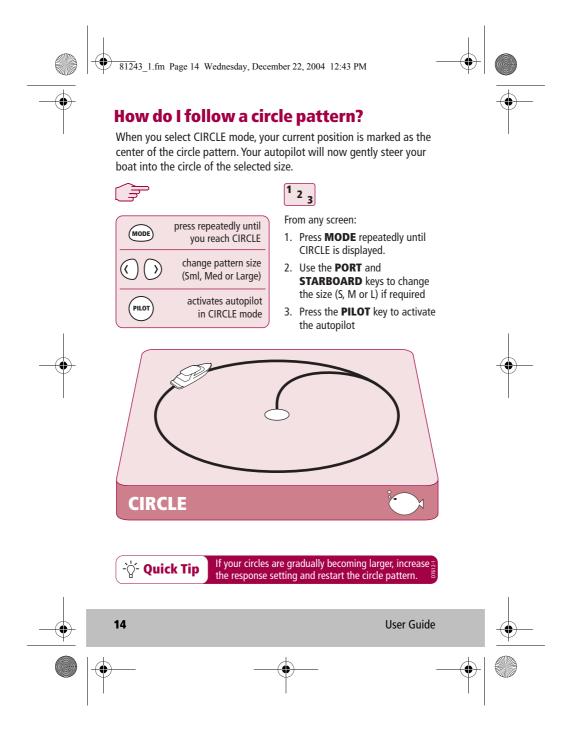
Available modes

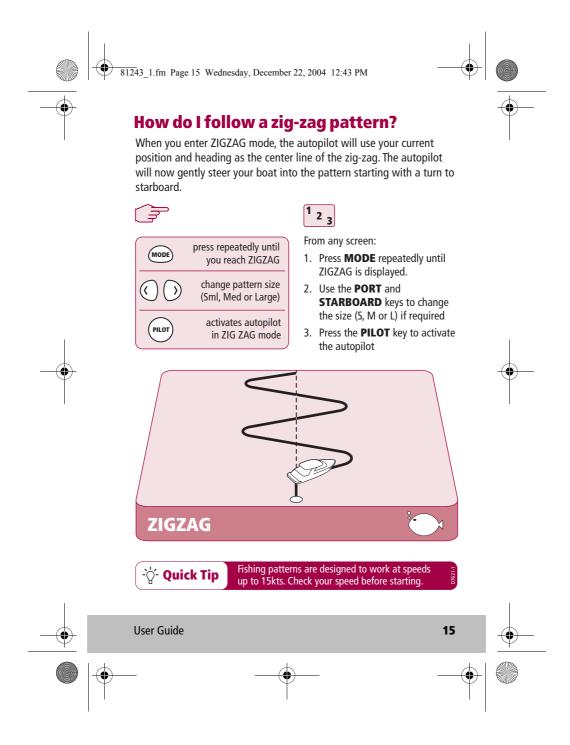


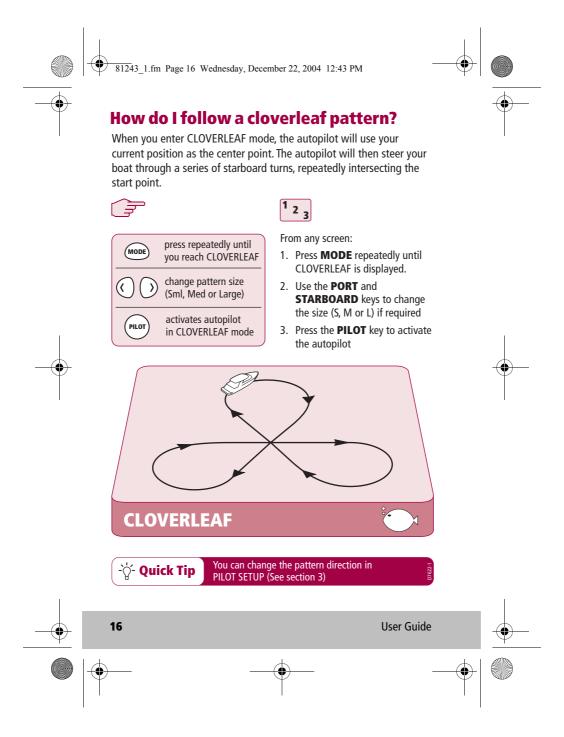


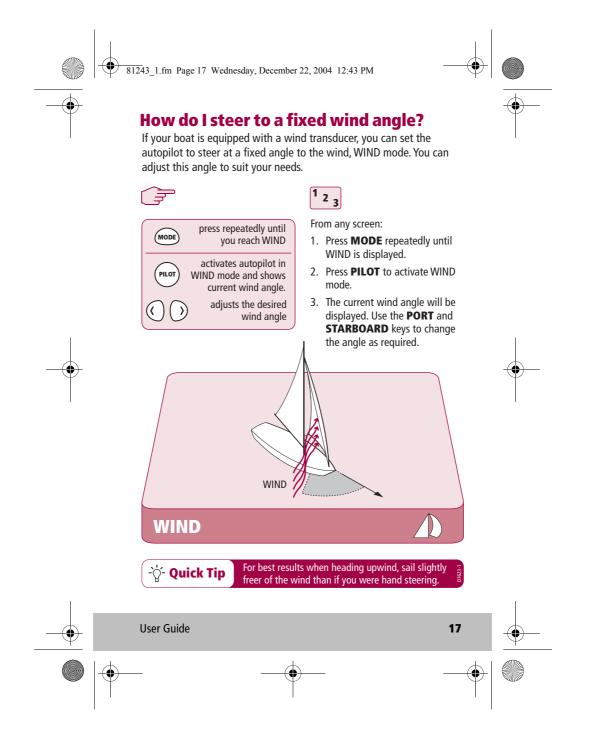


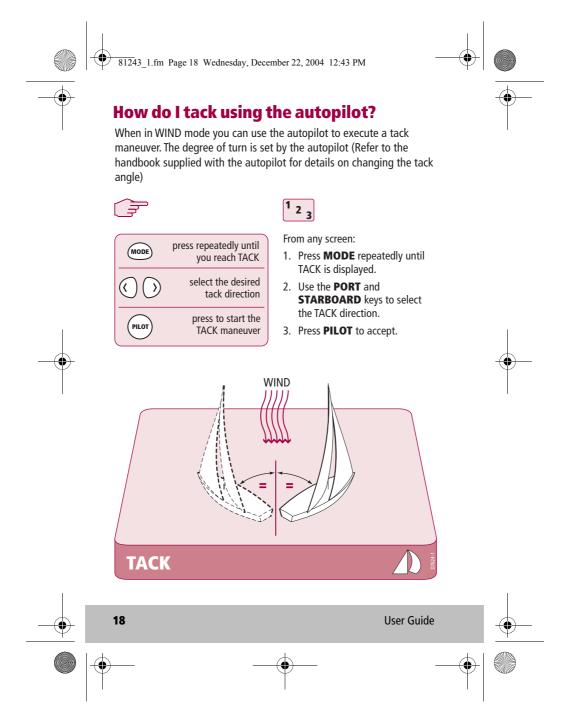


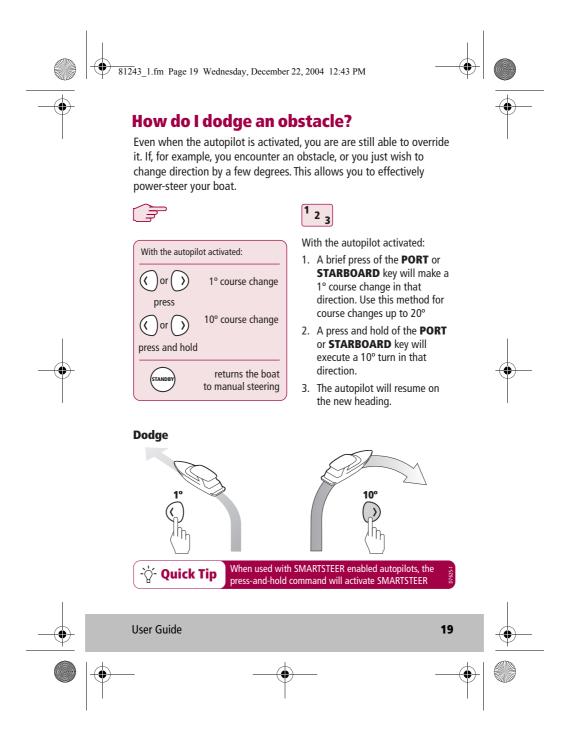


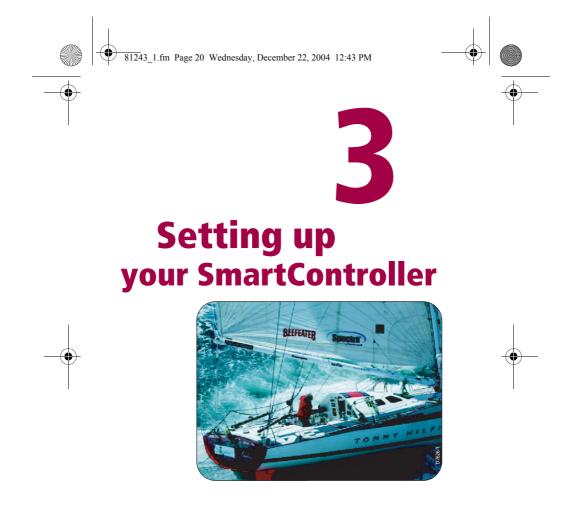


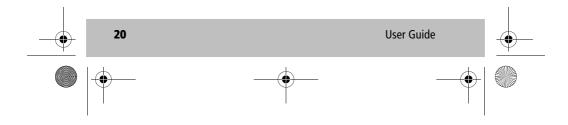


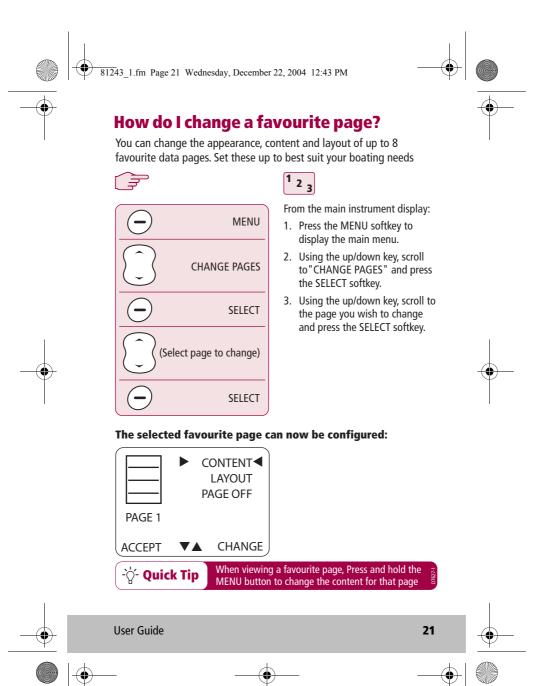


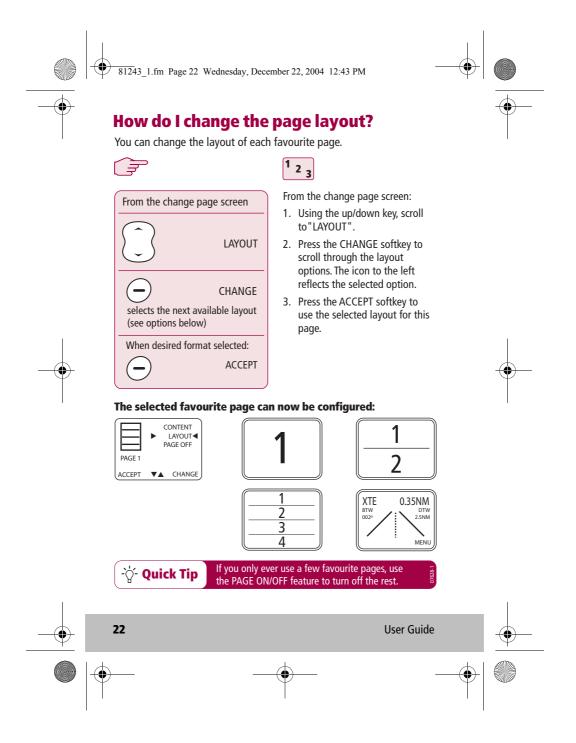


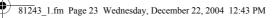








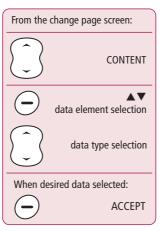




How do I change page content?

You can change the content of each favourite page.





Example screen:

-☆- Quick Tip

User Guide

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DEPTH		4.7FT
SPEED		11KTS
HEADIN	G	227M
AWS		2.3KTS
ACCEPT	DATA	▼▲

From the change page screen:

¹ ₂ ₃

- Using the up/down key, scroll to "CONTENT" and press the CHANGE softkey. The current data type(s) will be displayed.
- 2. The selected data element will be shown with a black background. Where you have more than one piece of data displayed, use the softkey to select the data element you wish to change.
- Use the up/down control to scroll through the available data types for your current selection. When complete, press the ACCEPT softkey to save your changes and return to the change page screen.

23

If you only ever use a few favourite pages, use

the PAGE ON/OFF feature to turn off the rest.



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) 81243_1.fm Page 24 Wednesday, December 22, 2004 12:43 PM

How do I show or hide pages?

Use as many or as few data pages as you like The page on/off option allows you to only display those data pages you really want to see.

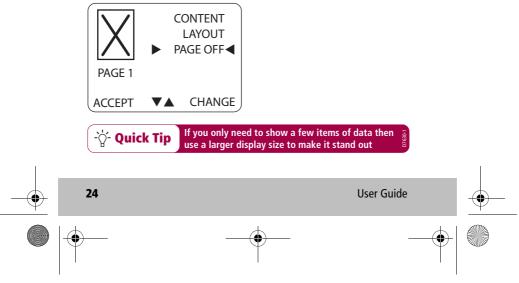
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From the cl	nange page screen:
	PAGE ON/OFF
$\overline{\bigcirc}$	CHANGE
	Toggles Page On/Off

¹ ₂ ₃

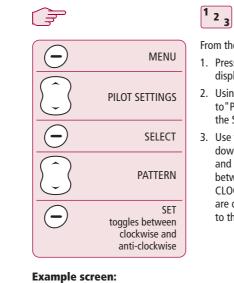
From the change page screen:

- 1. Using the up/down key, scroll to "PAGE ON" or "PAGE OFF"
- 2. The label displayed indicated the current status of the selected page. This will also be represented graphically in the icon.
- 3. Press the CHANGE softkey to toggle the setting from ON to OFF and vice-versa.

Example screen:







From the main instrument display:

- 1. Press the MENU softkey to display the main menu.
- 2. Using the up/down key, scroll to "PILOT SETTINGS" and press the SELECT softkey.
- Use the up/down key to scroll down to the "PATTERN" option and press SET to switch between CLOCKWISE and ANTI-CLOCKWISE patterns. When you are done, press BACK to return to the main menu.

PILOT SETTINGS AUTOLEARN START FISHING **BOAT TYPE** PILOT ENABLED SETTINGS CHANGE ► PATTERN BACK SET Turns to starboard (clockwise) is the default -☆- Quick Tip pattern direction. User Guide 25 -

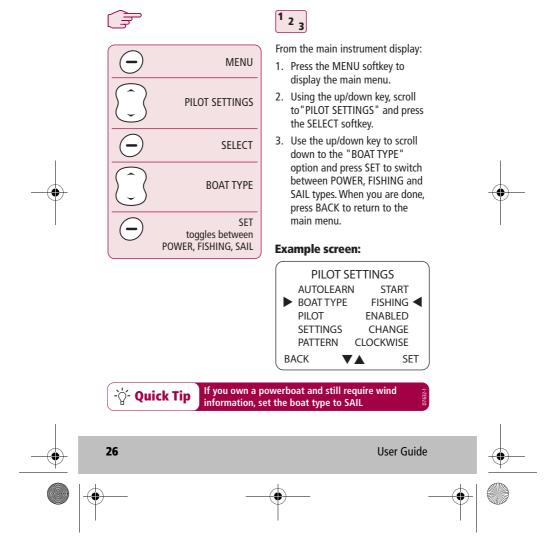


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81243_1.fm Page 26 Wednesday, December 22, 2004 12:43 PM

How do I change my boat type?

Your SmartController can be set to suit the type of vessel to which it is fitted. This ensures that the user interface will offer you the most relevant features.





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81243_1.fm Page 27 Wednesday, December 22, 2004 12:43 PM

How do I adjust the handset settings?

Your SmartController can be set to display information appropriate to your current location, in the format you require. The User Settings menu allows you to set this up.

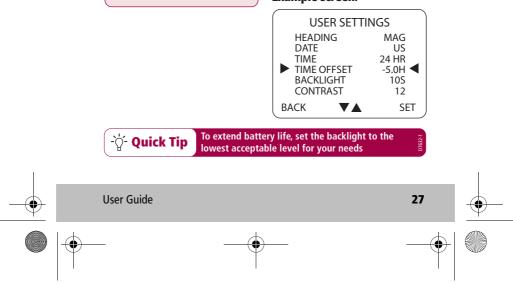
\bigcirc	MENU
	USER SETTINGS
$\overline{\bigcirc}$	SELECT
	(User Setting)
Θ	SET (to adjust)

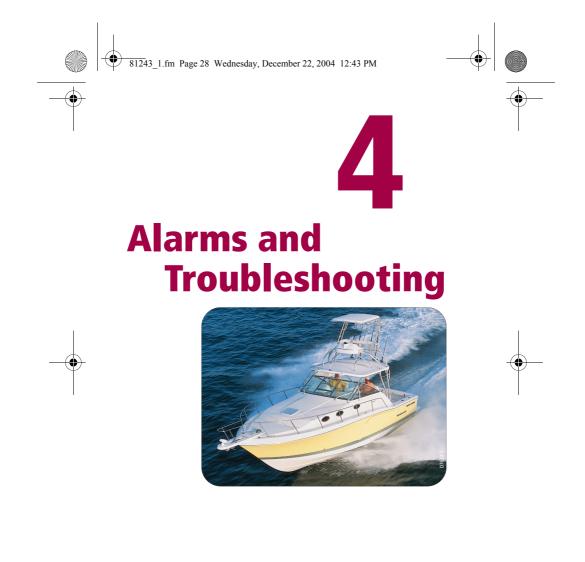
¹ ₂ ₃

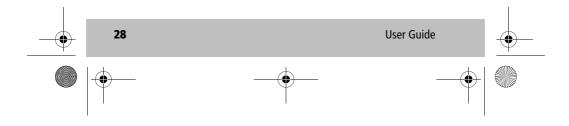
From the main instrument display:

- Press the MENU softkey to display the main menu and using the up/down key, scroll to "USER SETTINGS" and press the SELECT softkey.
- Use the up/down key to scroll to the item you wish to change. Press SET to adjust a user setting value.
- 3. When you are done, press BACK to return to the main menu.

Example screen:









How do I set up alarms?

You can configure which alarms to you want the SmartController to report.

F	
Θ	MENU
	ALARMS
$\overline{\bigcirc}$	SELECT
	(Select alarm to configure)
$\overline{\bigcirc}$	SELECT

¹ ₂ ₃

From the main instrument display:

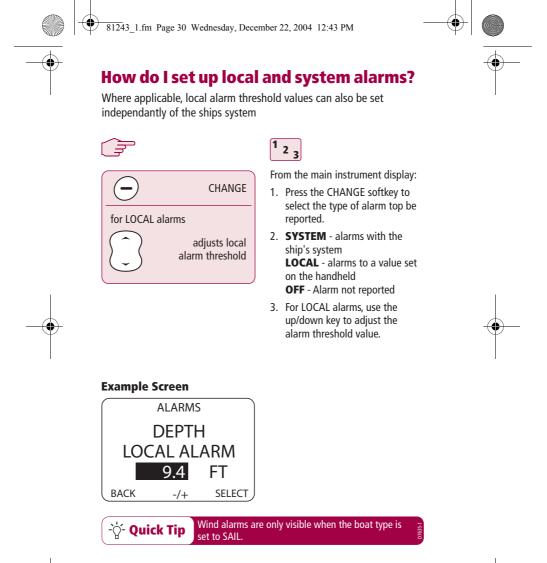
- 1. Press the MENU softkey to display the main menu.
- Using the up/down key, scroll to "ALARMS" and press the SELECT softkey.
- Using the up/down key, scroll to the alarm you wish to change and press the SELECT softkey.

Example Screen

	ALARM	S
► DEPTH	1	LOCAL ◀
WP AR	RIVAL	SYSTEM
LOST F	IX	SYSTEM
PILOT		SYSTEM
HIGH WIND		OFF
LOW W	VIND	OFF
BACK	▼▲	SELECT

-\'d'- Quick Tip Wind alarms are only visible when the boat type is set to SAIL.





User Guide

30

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81243_1.fm Page 31 Wednesday, December 22, 2004 12:43 PM

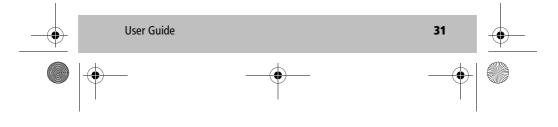
SmartController Alarm messages

When the SmartController detects a fault or failure on the system, it will activate one of the alarm messages listed in the following table.

Unless otherwise stated, you should respond to the alarm by pressing **standby** to clear the alarm and return to manual control, before you attempt to resolve the problem.

In some situations, the SmartController will raise more than one alarm. When you have dealt with the first alarm, it will display the next alarm.

ALARM MESSAGE	POSSIBLE CAUSE and SOLUTION
CHECK PILOT	See the main autopilot display head for infor- mation on this alarm.
CURRENT LIMIT	Serious drive failure – the drive is taking too much current due to short-circuit or jamming. Check the drive unit.
DRIVE STOPPED	The autopilot is unable to turn the rudder (this occurs if the weather load on helm is too high, or if the rudder position sensor has passed beyond the preset rudder limits or rudder end- stops). Check drive and rudder position sensor.
LARGE XTE	This alarm will sound when you are more than 0.3nm from your planned track. The alarm will also state if you are to the PORT or STARBOARD of the track,
LRN FAIL 1, 2 or 4	AutoLearn not completed successfully. Failure codes: 1 = AutoLearn has not been carried out 2 = AutoLearn failed, usually due to manual interruption 4 = AutoLearn failed, probably due to drive or compass failure Repeat the AutoLearn procedure.



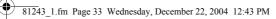
 81243_1.fm Page 32 Wednesday, December 22, 2004 12:43 PM

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POSSIBLE CAUSE and SOLUTION
Motor cables are connected to power terminals (and power cables are connected to motor ter- minals) at course computer. Turn off power and swap over connections.
The autopilot is in Track mode and: • the autopilot is not receiving SeaTalk naviga- tion data, or • your GPS is receiving a low strength signal, this will clear when the signal improves Note: The autopilot stops adjusting the heading as soon as it loses data.
The autopilot is not receiving valid COG data from your GPS system. Check the connections and that your GPS unit is setup to send out COG data.
Your GPS is receiving a low strength signal, this will clear when the signal improves
The controller is not receiving data from the autopilot. Check connections and check course computer is switched on.
This alarm sounds if you have been off course from the locked heading for more than 20 sec- onds. It also states if you are to the PORT or STARBOARD of the intended heading.
GyroPlus yaw sensor has failed. Call a Rayma- rine service agent.
This sounds on the completion of a track. Press PILOT to continue on the same heading or STANDBY for manual control.
The ships battery voltage has dropped below acceptable limits, replace the batteries.
You have arrived at a waypoint on your route. The autopilot is now requestiong permission to turn onto the next leg, press PILOT to accept.

 32
 User Guide

 Image: Second second





All Raymarine products are designed to provide many years of trouble-free operation. We also put them through comprehensive testing and quality assurance procedures before shipping.

If a fault occurs with your SmartController, use the fault finding tables in this section to help identify the problem and provide a solution. If you cannot resolve the problem yourself, refer to the product support information.

SYMPTOM	POSSIBLE CAUSE and SOLUTION
Display is blank	No power – press C to power up the SmartController or charge the batteries.
Autopilot not responding.	Drive the boat for 30 seconds at above 2.5kts and retry. Check autopilot connections.
Boat turns slowly and takes a long time to come onto course	Rudder gain too low. Complete AutoLearn or increase gain setting.
Boat overshoots when turning onto a new course	Rudder gain too high. Complete AutoLearn or decrease gain setting.
Position information not received	Navigator not transmitting the correct position data.
The pilot will not auto advance to the next waypoint.	No bearing to waypoint information received from the navigator.





81243_1.fm Page 34 Wednesday, December 22, 2004 12:43 PM

General maintenance

Routine checks

The SmartController does NOT contain any user-serviceable parts. If you remove the main cover you will invalidate the warranty. It should be serviced only by authorized Raymarine service technician.

As a result, user maintenance is limited to the following checks

- make sure all cable connectors are firmly attached
- examine for signs of wear or damage replace any damaged cables

Cleaning the SmartController

Take care when cleaning the display. Avoid wiping the display screen with a dry cloth as this could scratch the screen coating. If necessary, only use a mild detergent.

Never use chemical or abrasive materials to clean the controller. If it is dirty, wipe it with a clean, damp cloth.

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Dealer Maintenance Procedures This section includes procedures that have a significant impact on autopilot operation and can affect your boat's safety. You will not need to follow

these procedures in normal operation. We therefore recommend that these are only performed by authorised service personnel.

Accessing the dealer calibration area.

From the MAIN MENU mode, press and hold SELECT for 5 seconds until the dealer calibration screen is displayed:

Use the up/down key to scroll through the various calibration options.









81243 1.fm Page 35 Wednesday, December 22, 2004 12:43 PM

Hardware and Software version numbers

Use this option to display the current hardware revision and the software version numbers for the SmartController. At VERSION, press the SELECT key to display the information.

Self test

Press SELECT to start the unit test sequence and then follow the on-screen instructions. This will test the display, buzzer and button functions.

Diagnostics

Press **PILOT** to display the the status of the wireless link.

Handset Registration

Raymarine wireless systems require each wireless controller to be "registered" to a basestation. This registration process is to prevent unauthorised control of your boat by another wireless user.

Note: There may be instances where you want to move your controller to another boat and use it with another system. In this case, you will need to de-register from the current system and register with the new system. You can do this using the REGISTRATION function.

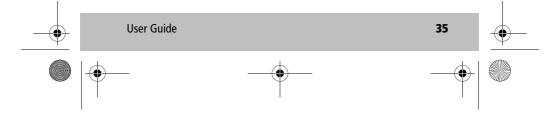
Note: For best results always perform registration and de-registration with the handset close to the basestation.

To register a handset

At REGISTRATION, press **SELECT**.

If the SmartController is not registered, then the display will read HANDSET NOT REGISTERED. Press REG to start the registration process.

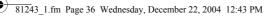












The SmartController will now search for the basestation, you can press **EXIT** at any time to stop the search. When a basestation is found by the SmartController, check that the yellow registration light on the basestation is on. This ensures that the handset and basestation are matched correctly.

If the yellow light is on, press **ACCEPT** to complete the registration, the display will read REGISTER SUCCESSFUL. Otherwise, press **REJECT** and re-start the registration procedure

To de-register a handset

At REGISTRATION, press SELECT.

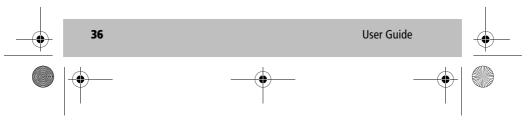
If the SmartController is already registered, then the display will read REGISTERED TO BASESTATION. Press **DEREG** to continue, or **EXIT** to cancel the operation.

The SmartController will attempt to commuicate with the basestation and de-register. When complete, the display will read HANDSET NOT REGISTERED.

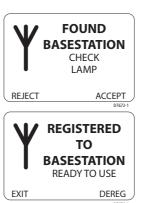
If the SmartController cannot communicate with the basestation then a "BASE NOT FOUND" message will be displayed. It is still possible to deregister the SmartController at this point by pressing **SELECT**. To leave without de-registering, press **EXIT**.

Factory Reset

This option will clear all settings from the SmartController. Press and hold the **SELECT** key for 2 seconds to activate the reset.



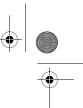








81243_1.fm Page 37 Wednesday, December 22, 2004 12:43 PM



Note: A reset does not alter the registration status of the SmartController

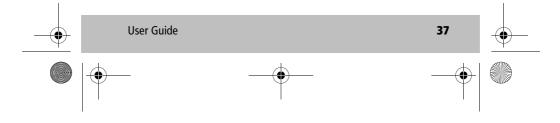
Product Support

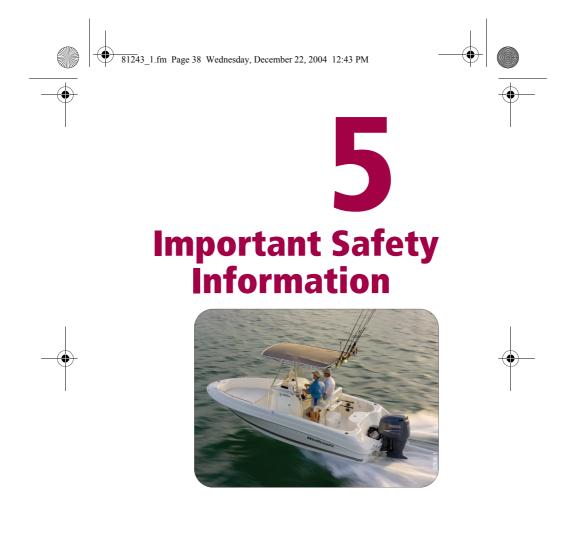
Raymarine products are supported by a worldwide network of distributors and Authorized Service Representatives. If you encounter any difficulties with this product, please contact either your national distributor, service representative, or the Raymarine Technical Services Call Center. Refer to the back cover or www.raymarine.com for contact details.

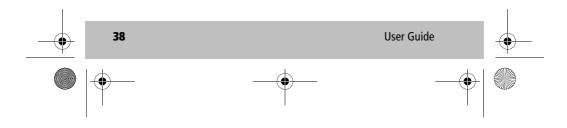
If you cannot trace or rectify the fault, contact your nearest Raymarine dealer or Service Center, specifying:

The SmartController serial numbers:

- the controller serial number is printed on its rear cover
- the controller software version numbers









81243 1.fm Page 39 Wednesday, December 22, 2004 12:43 PM

Safety Notices

Product installation

This equipment must be installed and operated in accordance with the instructions contained in this handbook. Failure to do so could result in poor product performance, personal injury and/or damage to your boat.

Before installing the SmartController and basestation, check that they are the correct voltage for your boat's supply.

As correct performance of the boat's steering is critical for safety, we STRONGLY RECOMMEND that an Authorized Raymarine Service Representative fits this product.

WARNING: Electrical safety

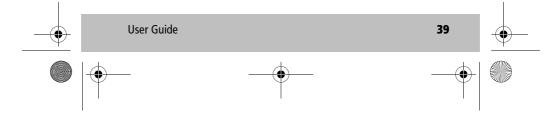
Make sure the power supply is switched off before you make any electrical connections.

WARNING: Calibration

We supply this product calibrated to default settings that should provide initial stable performance for most boats. To ensure optimum performance on your boat, you must complete the AutoLearn procedure as described in your autopilot handbook.

WARNING: Navigation aid

Although we have designed this product to be accurate and reliable, many factors can affect its performance. As a result, it should only be used as an aid to navigation and should never replace common sense and navigational judgement. Always maintain a permanent watch so you can respond to situations as they develop.











81243 1.fm Page 40 Wednesday, December 22, 2004 12:43 PM

WARNING: Autopilot controller If the wireless controller is your only method of operating the autopilot, ensure that your system includes a readily accessible method of switching off the autopilot power supply.

Your SmartController will add a new dimension to your boating enjoyment. However, it is the skipper's responsibility to ensure the safety of the boat at all times by following these basic rules:

- Ensure that someone is present at the helm AT ALL TIMES, to take manual control in an emergency.
- Make sure that all members of crew know how to disengage the autopilot.
- Regularly check for other boats and any obstacles to navigation

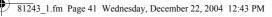
 no matter how clear the sea may appear, a dangerous situation can develop rapidly.
- Maintain an accurate record of the boat's position by using either a navigation aid or visual bearings.
- Maintain a continuous plot of your boat's position on a current chart. Ensure that the locked autopilot heading will steer the boat clear of all obstacles. Make proper allowance for tidal set – the autopilot cannot.
- Even when your autopilot is locked onto the desired track using a navigation aid, always maintain a log and make regular positional plots. Navigation signals can produce significant errors under some circumstances and the autopilot will not be able to detect these errors.

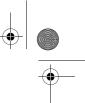
General Care and Safety

Do not leave the controller in places where the temperature could exceed $60^{\circ}C$ (140°F).

Do not attempt to dismantle the SmartController or any of its accessories.







Only use with the lanyard supplied with your SmartController or a spare supplied by Raymarine.

Switch off your SmartController system at a refuelling point, even if you are not refuelling your own vessel.

The operation of some medical electronic devices such as hearing aids and pacemakers, may be affected if a controller is used next to them. Observe the manufacturers recommendations for such devices.

Radio frequency energy

Your SmartController and base station both low- power radio transmitters and receivers. When they are turned on, they intermittently receive and transmit radio frequency (RF) energy (radio waves).

Exposure to radio frequency energy

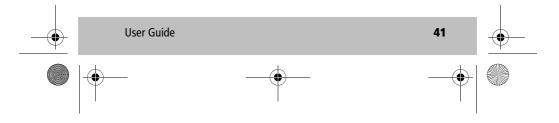
The SmartController is designed not to exceed the limits for exposure to RF energy set by national authorities and international health agencies These limits establish permitted levels of radio wave exposure for the general population. An example of a radio frequency exposure guideline and standard that the SmartController is designed to conform to is :

BS EN 50371:2002 - Generic standard to demonstrate the compliance of low-power electronic and electrical apparatus with the basic restrictions related to human exposure to electromagnetic fields.

FCC Information

These devices comply with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) these devices may not cause harmful interference and (2) these devices must accept interference received, including interference that may cause undesired operation.

Changes or modifications to this equipment not expressly approved in writing by Raymarine could violate compliance with FCC rules and void the user's authority to operate the equipment.





81243_1.fm Page 42 Wednesday, December 22, 2004 12:43 PM

Disposal

Disposal of this product, at the end of its useful life, should be in accordance with local regulations.

Do not incinerate or mutilate the integral battery pack.

Intended Use

The Smart Controller and Base Station are part of a Raymarine autopilot and instrumentation system intended for use on leisure vessels and small workboats

Declaration of Conformity

Hereby Raymarine UK Ltd, declare that the SmartController and Basestation are in compliance with the essential requirements and other relevant provisions of the Directive 1999/5/EC

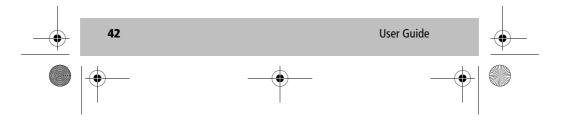
The original Declaration of Conformity certificate may be viewed on the relevant product page at www.raymarine.com

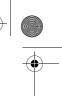
EMC Guidelines

All Raymarine equipment and accessories are designed to the best industry standards for use in the recreational marine environment. Their design and manufacture conforms to the appropriate Electromagnetic Compatibility (EMC) standards, but correct installation is required to ensure that performance is not compromised.

Connections to other equipment

If your Raymarine equipment is to be connected to other equipment using a cable not supplied by Raymarine, a suppression ferrite MUST always be attached to the cable near to the Raymarine unit.







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81243_1.fm Page 43 Wednesday, December 22, 2004 12:43 PM

Handbook Information

To the best of our knowledge, the information in this handbook was correct when it went to press. However, Raymarine cannot accept liability for any inaccuracies or omissions it may contain. In addition, our policy of continuous product improvement may change specifications without notice. As a result, Raymarine cannot accept liability for any differences between the product and the handbook.

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