

Applicant:	Kyocera
FCC ID:	OVFS13503CB
Report #:	CT-S1350-13E-0411-R0

EXHIBIT 12 APPENDIX A: HAC RF PROBE CALIBRATION CERTIFICATE

Total pages including cover page = 21

Calibration Laboratory of

Schmid & Partner

Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland





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Client

Kyocera USA

Certificate No: ER3-2341 Jul10

Accreditation No.: SCS 108

CALIBRATION CERTIFICATE

Object ER3DV6 - SN:2341

Calibration procedure(s) QA CAL-02,v5 and QA CAL-25.v2

Calibration procedure for E-field probes optimized for close near field

evaluations in air

Calibration date: July 12, 2010

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID#	Cal Date (Certificate No.)	Scheduled Calibration	
Power meter E4419B	GB41293874	1-Apr-10 (No. 217-01136)	Арг-11	
Power sensor E4412A	MY41495277	1-Apr-10 (No. 217-01136)	Apr-11	
Power sensor E4412A	MY41498087	1-Apr-10 (No. 217-01136)	Apr-11	
Reference 3 dB Attenuator	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11	
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11	
Reference 30 dB Attenuator	SN: S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11	
Reference Probe ER3DV6	SN: 2328	3-Oct-09 (No. ER3-2328 Oct09)	Oct-10	
DAE4	SN: 789	23-Dec-09 (No. DAE4-789_Dec09)	Dec-10	
Secondary Standards	ID#	Check Date (in house)	Scheduled Check	
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11	
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10	
***	Name	Function	Signature	
Calibrated by:	Katja Pokovic	Technical Manager		
Approved by:	Alia File.		X	
Approved by:	Niels Kuster	r Quality Manager		
			V./53	

Issued: July 14, 2010

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Glossary:

NORMx,y,z sensitivity in free space DCP diode compression point

CF crest factor (1/duty_cycle) of the RF signal A, B, C modulation dependent linearization parameters

Polarization φ φ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 9 = 0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORMx, y, z: Assessed for E-field polarization θ = 0 for XY sensors and θ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- NORM(f)x, y, z = NORMx, y, z * frequency response (see Frequency Response Chart).
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

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Probe ER3DV6

SN:2341

Manufactured: June 15, 2004 Last calibrated: March 10, 2009 Recalibrated: July 12, 2010

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

Certificate No: ER3-2341 Jul10 Page 3 of 10

DASY/EASY - Parameters of Probe: ER3DV6 SN:2341

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm $(\mu V/(V/m)^2)$	1.68	1.76	1.72	± 10.1%
DCP (mV) ^A	92.2	94.3	97.3	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	С	VR mV	Unc ^E (k=2)
10000	cw	0.00	×	0.00	0.00	1.00	300	± 1.5 %
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

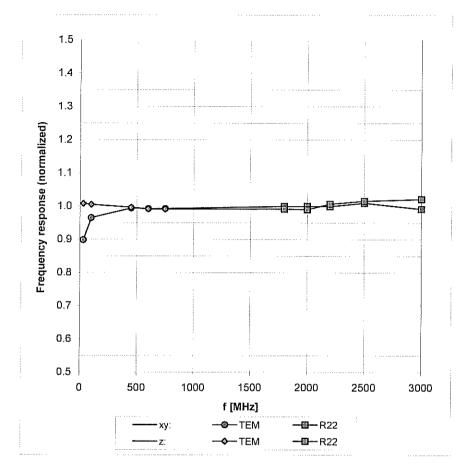
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A numerical linearization parameter: uncertainty not required

E Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

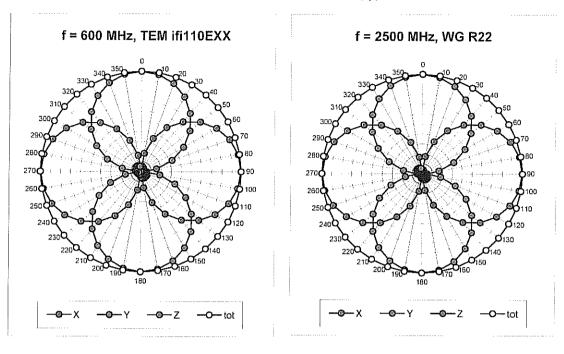
Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)

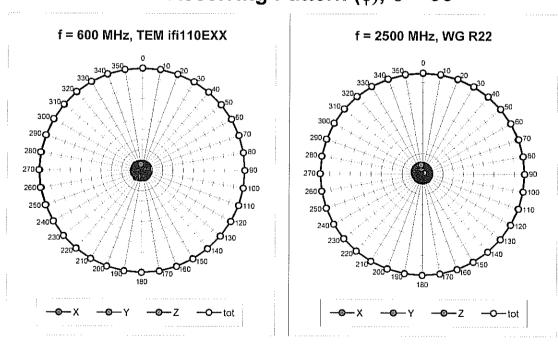


Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

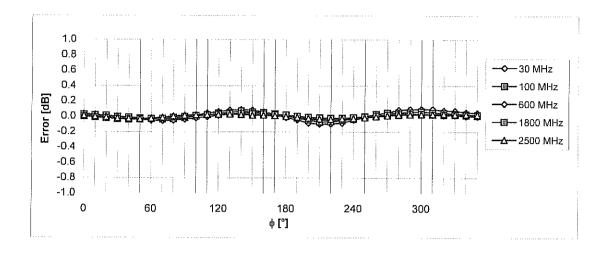
Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$



Receiving Pattern (ϕ), ϑ = 90°

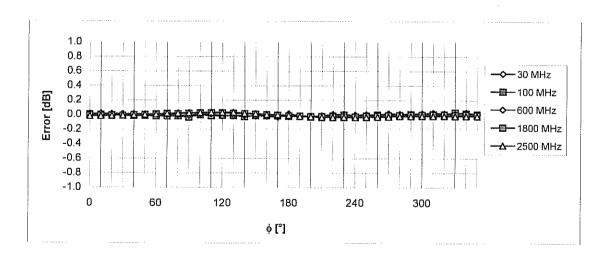


Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

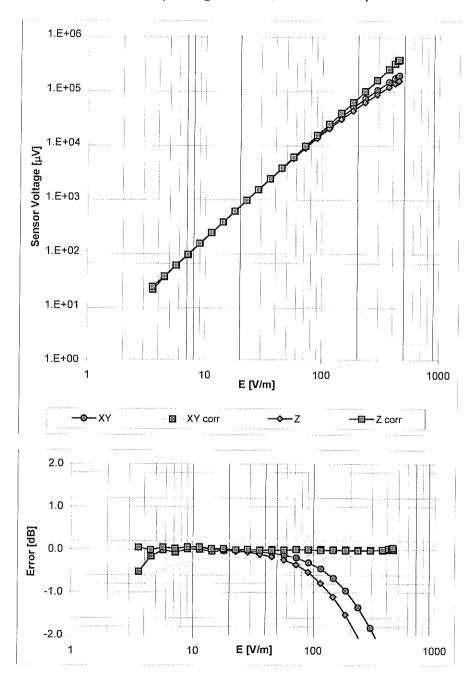
Receiving Pattern (ϕ), $\vartheta = 90^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

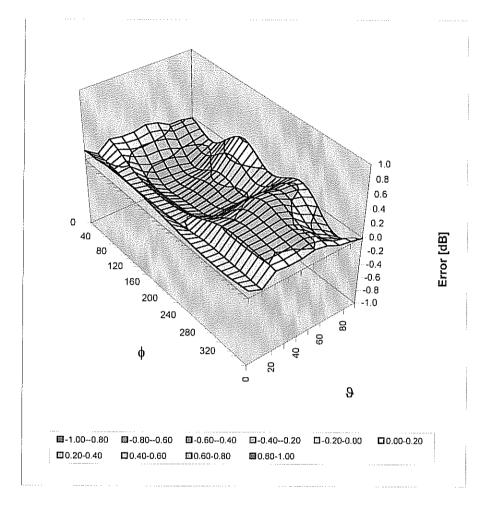
Dynamic Range f(E-field)

(Waveguide R22, f = 1800 MHz)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)

Deviation from Isotropy in Air Error (ϕ, ϑ) , f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-238.6
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8.0 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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Client

Kyocera USA

Certificate No: H3-6029 Jul10

Accreditation No.: SCS 108

CALIBRATION CERTIFICATE

Object H3DV5 - SN:6029

Calibration procedure(s) QA CAL-03.v5 and QA CAL-25.v2

Calibration procedure for H-field probes optimized for close near field

evaluations in air

Calibration date: July 16, 2010

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID#	Cal Date (Certificate No.)	Scheduled Calibration	
Power meter E4419B	GB41293874	1-Apr-10 (No. 217-01136)	Apr-11	
Power sensor E4412A	MY41495277	1-Apr-10 (No. 217-01136)	Apr-11	
Power sensor E4412A	MY41498087	1-Apr-10 (No. 217-01136)	Apr-11	
Reference 3 dB Attenuator	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11	
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11	
Reference 30 dB Attenuator	SN: S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11	
Reference Probe H3DV6	SN: 6182	3-Oct-09 (No. H3-6182_Oct09)	Oct-10	
DAE4	SN: 789	23-Dec-09 (No. DAE4-789_Dec09)	Dec-10	
Secondary Standards	ID#	Check Date (in house)	Scheduled Check	
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11	
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10	
	Name	Function	Signature	
Calibrated by:	Jeton Kastrati	Laboratory Technician	1 _ /	
Approved by:	Kalja Pokovic	Technical Manager	1 72 in	
			JES AS	

Issued: July 16, 2010

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Glossary:

NORMx,y,z sensitivity in free space diode compression point

CF crest factor (1/duty_cycle) of the RF signal modulation dependent linearization parameters

Polarization φ φ rotation around probe axis

Polarization 9 9 rotation around an axis that is in the plane normal to probe axis (at measurement center).

i.e., 9 = 0 is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORMx,y,z: Assessed for E-field polarization θ = 0 for XY sensors and θ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- X,Y,Z(f)_a0a1a2= X,Y,Z_a0a1a2* frequency_response (see Frequency Response Chart).
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the X_a0a1a2 (no uncertainty required).

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Probe H3DV5

SN:6029

Manufactured: May 5, 1998 Last calibrated: June 22, 2009 Recalibrated: July 16, 2010

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

Certificate No: H3-6029_Jul10 Page 3 of 10

DASY/EASY - Parameters of Probe: H3DV5 SN:6029

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (A/m / √(μV))	a0	2.77E-3	2.70E-3	2.89E-3	± 5.1%
Norm (A/m / √(μV))	a1	-4.95E-5	1.89E-5	7.91E-5	± 5.1%
Norm (A/m / √(μV))	a2	-4.80E-5	-6.37E-5	9.65E-5	± 5.1%
DCP (mV) ^A		81.5	94.5	82.6	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	С	VR mV	Unc ^E (k=2)
10000	cw	0.00	х	0.00	0.00	1.00	300	± 1.5 %
			Υ	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

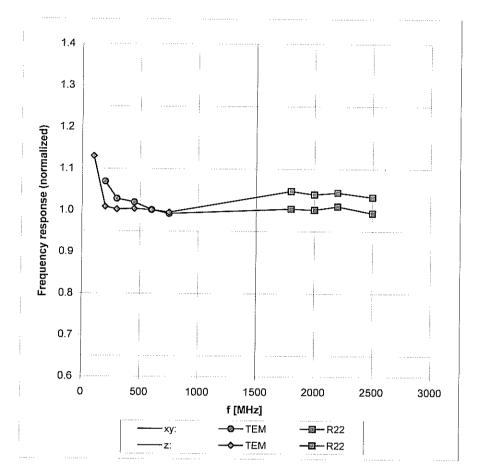
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A numerical linearization parameter: uncertainty not required

E Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

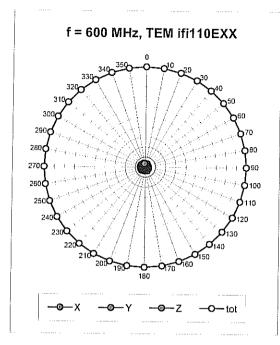
Frequency Response of H-Field

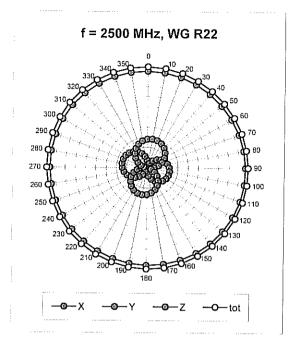
(TEM-Cell:ifi110 EXX, Waveguide R22)



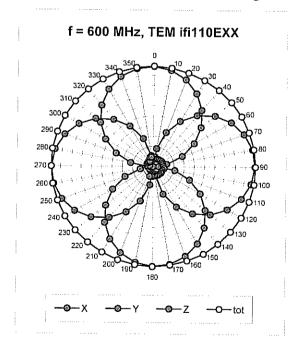
Uncertainty of Frequency Response of H-field: ± 6.3% (k=2)

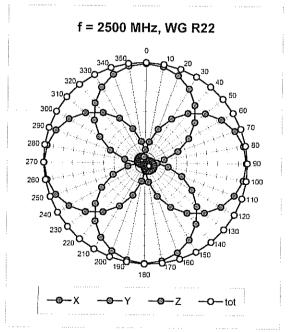
Receiving Pattern (ϕ), $\vartheta = 90^{\circ}$



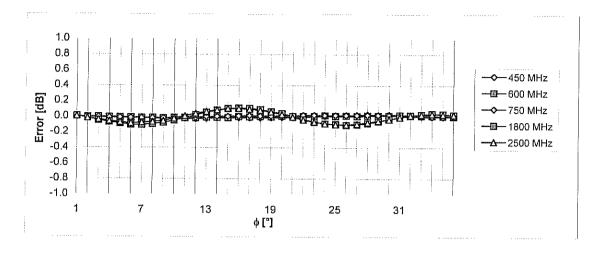


Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$



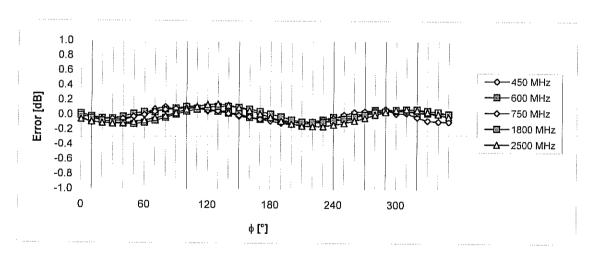


Receiving Pattern (ϕ), θ = 90°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

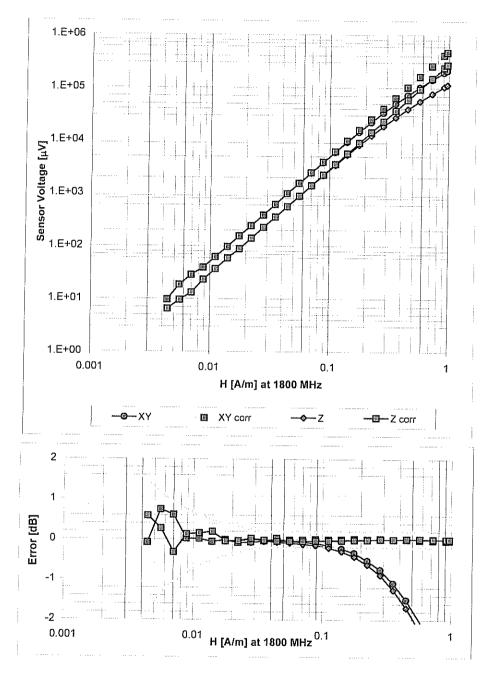
Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

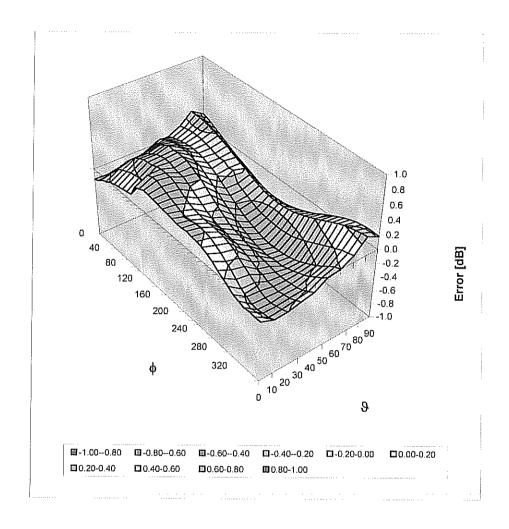
Dynamic Range f(H-field)

(Waveguide R22, f = 1800 MHz)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)

Deviation from Isotropy in Air Error (ϕ, ϑ) , f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-196.4
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6.0 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm