

## **LINX TECHNOLOGIES DUTY CYCLE EXPLANATION**

This device transmits at a 9600 baud rate and can have a maximum 8 data bits high. Based on this calculation, the maximum calculated duty cycle using the formula on page 2 would be 48.3%. Plots of the duty cycle are given showing that the actual measured duty cycle is less than or equal to 48.3% (See the duty cycle plot exhibits, which are separate from this exhibit). However, per the FCC response, the maximum calculated duty is to be used for the purposes of testing.

# MS Series Encoder Data Structure

The MS Series encoder is designed to securely register button presses or switch closures over a wireless link for remote control applications. It will turn eight parallel input lines into a secure, encoded serial bit stream output. It will turn eight parallel input lines into a secure, encoded serial bit stream output.

The MS Series algorithm is designed to create a data stream with a 50% duty cycle by using the same number of high bits and low bits. Two wait times reduce this duty cycle to just below 50%.

## Logic State Description:

1 = HIGH  
0 = LOW

Total bits, including start and stop bits = 80

Total 1's = 40

Total 0's = 40

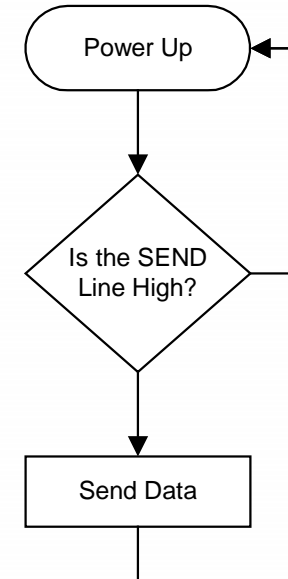
## Value for each bit per baud rate:

2400bps = 417uS or 1.18% of duty cycle

9600bps = 104uS or 1.01% of duty cycle

19200bps = 52uS or 0.85% of duty cycle

28800bps = 35uS or 0.74% of duty cycle



Wait Time	Processing Time		Wait Time	Wake	Noise Filter	Error Check	ADDR-H	ADDR-M	ADDR-L	Data Byte	Error Check
680uS	11111111	00000000	465uS	1010	800uS	0 01101000 1	0 10101010 1	0 01010101 1	0 00000000 1	0 11111111 1	0 11101010 1

$$\begin{aligned}
 \text{Duty Cycle} &= \frac{\text{Time High}}{\text{Total Time}} \longrightarrow \frac{40 \text{ bits} + 800\text{uS}}{80 \text{ bits} + 680\text{uS} + 465\text{uS} + 800\text{uS}} \longrightarrow \frac{(40 \times 104\text{uS}) + 800\text{uS}}{(80 \times 104\text{uS}) + 1,945\text{uS}} = \frac{4,960\text{uS}}{10,265\text{uS}} = 48.3\%
 \end{aligned}$$