SAR TEST REPORT

No. I16Z42314-SEM02

For

Lenovo(Shanghai) Electronics Technology Co., Ltd.

Portable Tablet Computer

Model Name: Lenovo TB-X304F

With

Hardware Version: LenovoPad_TB-304F

Software Version: TB-X304F_RF01_170104

FCC ID: O57TBX304F

Issued Date: 2017-3-23

Note:

The test results in this test report relate only to the devices specified in this report. This report shall not be reproduced except in full without the written approval of CTTL.

Test Laboratory:

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REPORT HISTORY

Report Number	Revision	Issue Date	Description
I16Z42314-SEM02	Rev.0	2017-3-23	Initial creation of test report

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1 Test Laboratory

1.1 Testing Location

Company Name:	CTTL(Shouxiang)
Address:	No. 51 Shouxiang Science Building, Xueyuan Road, Haidian District, Beijing, P. R. China100191

1.2 Testing Environment

Temperature:	18°C~25°C,
Relative humidity:	30%~ 70%
Ground system resistance:	< 0.5 Ω
Ambient noise & Reflection:	< 0.012 W/kg

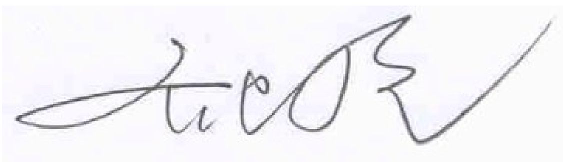
1.3 Project Data

Project Leader:	Qi Dianyuan
Test Engineer:	Lin Xiaojun
Testing Start Date:	March 20, 2017
Testing End Date:	March 20, 2017

1.4 Signature

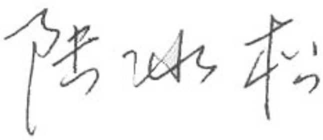
Lin Xiaojun

(Prepared this test report)



Qi Dianyuan

(Reviewed this test report)



Lu Bingsong

Deputy Director of the laboratory

(Approved this test report)

2 Statement of Compliance

The maximum results of SAR found during testing for Lenovo(Shanghai) Electronics Technology Co., Ltd. Portable Tablet Computer Lenovo TB-X304F is as follows:

Table 2.1: Highest Reported SAR(1g)

Exposure Configuration	Technology Band	Highest Reported SAR 1g(W/Kg)	Equipment Class
Body (Separation Distance 0mm)	WLAN 2.4 GHz	1.46	DTS

The SAR values found for the Mobile Phone are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1g tissue according to the ANSI C95.1-1992.

For body worn operation, this device has been tested and meets FCC RF exposure guidelines when used with any accessory that contains no metal and which provides a minimum separation distance of 0 mm between this device and the body of the user. Use of other accessories may not ensure compliance with FCC RF exposure guidelines.

The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power output.

The measurement together with the test system set-up is described in annex C of this test report. A detailed description of the equipment under test can be found in chapter 4 of this test report.

The highest reported SAR value is obtained at the case of **(Table 2.1),** and the values are**: 1.46 W/kg(1g).**

3 Client Information

3.1 Applicant Information

Company Name:	Lenovo(Shanghai) Electronics Technology Co., Ltd.
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3.2 Manufacturer Information

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Postal Code:	/
Country:	China
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Fax:	+86-21-50807240

4 Equipment Under Test (EUT) and Ancillary Equipment (AE)

4.1 About EUT

Description:	Portable Tablet Computer
Model name:	Lenovo TB-X304F
Operating mode(s):	BT, WLAN
Tx Frequency:	2402 – 2480 MHz (Bluetooth)
	2412 – 2462 MHz (Wi-Fi 2.4G)
Test device Production information:	Production unit
Device type:	Portable device
Antenna type:	Integrated antenna
Hotspot mode:	Support

4.2 Internal Identification of EUT used during the test

EUT ID	SN	HW Version	SW Version
1	d7010903587	LenovoPad_TB-304F	TB-X304F_RF01_170104
2	d7010903501	LenovoPad_TB-304F	TB-X304F_RF01_170104
3	d7010903661	LenovoPad_TB-304F	TB-X304F_RF01_170104

*EUT ID: is used to identify the test sample in the lab internally.

Note: It is performed to test SAR with the EUT1&2&3 and conducted power with the EUT1.

4.3 Internal Identification of AE used during the test

AE ID	Description	Model	SN	Manufacturer
AE1	Battery	L16D2P31	/	SCUD(Fujian） Electronics Co., Ltd.
AE2	Battery	L16D2P31	/	Celxpert+coslight

There are three kinds of combination modes to be tested and the detail information is as follows:

SKU1-1			SKU1-2			SKU6		
Material description	Model	Supplier	Material description	Model	Supplier	Material description	©Model	Supplier
PCB	A6000A_MB _V4_PCBA	RED BOARD LTD	PCB	A6000A_MB _V4_PCBA	HUAXIN	PCB	A6000A_MB _V4_PCBA	HUAXIN
LPDDR3 Emcp	KMQE10013 M-B318	2+16 Samsung	LPDDR3 Emcp	KMQE10013 M-B318	2+16 Samsung	LPDDR3 Emcp	H9TQ26ADF TBCUR-KUM	3+32 Hynix
Motor	HZF-Z04B-R L10B20-90	HONGZHIFA	Motor	HZF-Z04B-R L10B20-90	HONGZHIFA	Motor	CY0408L-02 1HB-015	KUNWANG
Battery	16D2P31	SCUD ©(FUJIAN)	Battery	16D2P31	SCUD ©(FUJIAN)	Battery	16D2P31	Celxpert
speakerBo x1	HQZA6000A JA_08	KEYSOUND	speakerBo x1	HQZA6000A JA_08	KEYSOUND	speakerBo x1	XHB171218B 08-01-B-RH	HAOSHENG
speakerBo x2	HQZA6000A JA_09	KEYSOUND	speakerBo x2	HQZA6000A JA_09	KEYSOUND	speakerBo x2	XHB171218B 08-02-B1F-R H	HAOSHENG
LCM	P101DCA-A B0	Innolux	LCM	P101DCA-A B0	Innolux	LCM	TV101WXM- NL1-39P0	BOE
Camera_ Back	F5695AV	Q-tech	Camera_ Back	F5695AV	Q-tech	Camera_ Back	F5V08B	Sunny
Camera_ ©©©Front	K7P2-A6000 FHQ	Kingcom	Camera_ ©©Front	K7P2-A6000 FHQ	Kingcom	Camera_ Front	BLX2375H-A 6000-F	BO LI XIN

We'll perform the SAR measurement with SKU1-2 and retest on highest value point with SKU1-1 and SKU6.

5 TEST METHODOLOGY

5.1 Applicable Limit Regulations

ANSI C95.1–1992 IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

It specifies the maximum exposure limit of **1.6 W/kg** as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

5.2 Applicable Measurement Standards

IEEE 1528–2013 Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques.

KDB616217 D04 SAR for laptop and tablets v01r02 SAR Evaluation Considerations for Laptop, Notebook, Notebook and Tablet Computers.

KDB248227 D01 802.11 Wi-Fi SAR v02r02: SAR GUIDANCE FOR IEEE 802.11 (Wi-Fi) TRANSMITTERS

KDB865664 D01SAR measurement 100 MHz to 6 GHz v01r04 SAR Measurement Requirements for 100 MHz to 6 GHz.

KDB865664 D02RF Exposure Reporting v01r02 RF Exposure Compliance Reporting and Documentation Considerations

6 Specific Absorption Rate (SAR)

6.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

6.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt}\left(\frac{dW}{dm}\right) = \frac{d}{dt}\left(\frac{dW}{\rho dv}\right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = c\left(\frac{\delta T}{\delta t}\right)$$

Where: C is the specific head capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

7 Tissue Simulating Liquids

7.1 Targets for tissue simulating liquid

Table 7.1: Targets for tissue simulating liquid

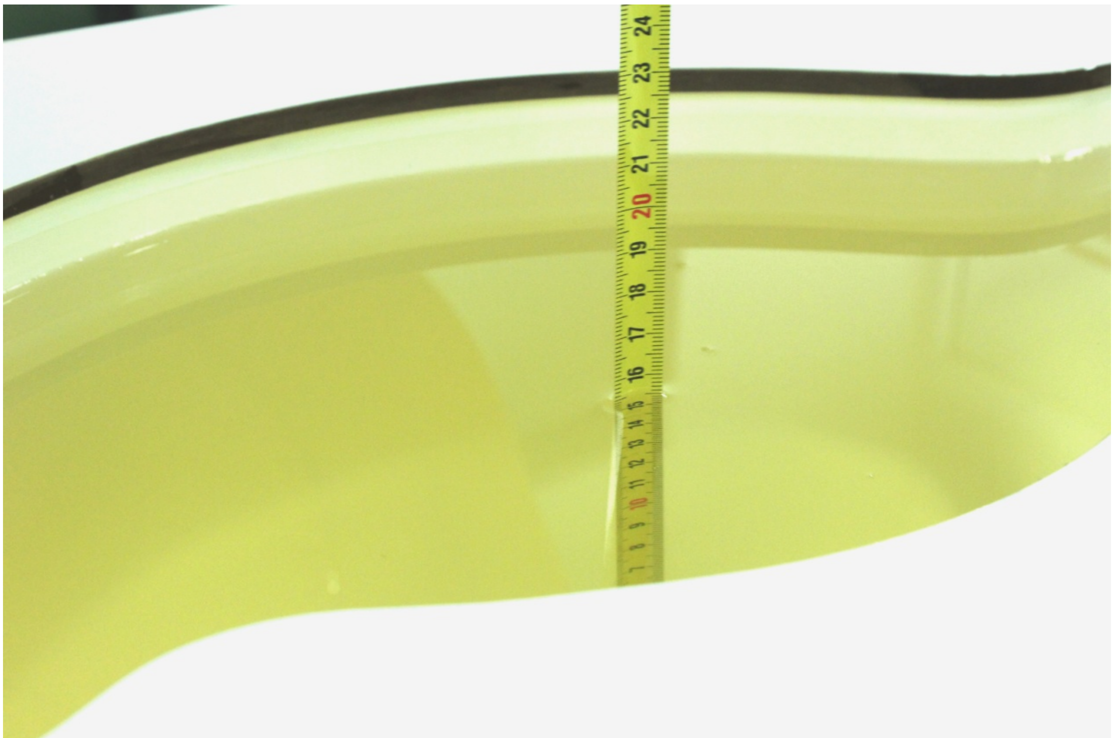
Frequency(MHz)	Liquid Type	Conductivity(σ)	± 5% Range	Permittivity(ε)	± 5% Range
2450	Body	1.95	1.85～2.05	52.7	50.1～55.3

7.2 Dielectric Performance

Table 7.2: Dielectric Performance of Tissue Simulating Liquid

Measurement Date yyyy/mm/dd	Frequency	Type	Permittivity ε	Drift (%)	Conductivity σ (S/m)	Drift (%)
2017/3/20	2450 MHz	Body	52.17	-1.01	1.89	-3.08

Note: The liquid temperature is 22.0℃

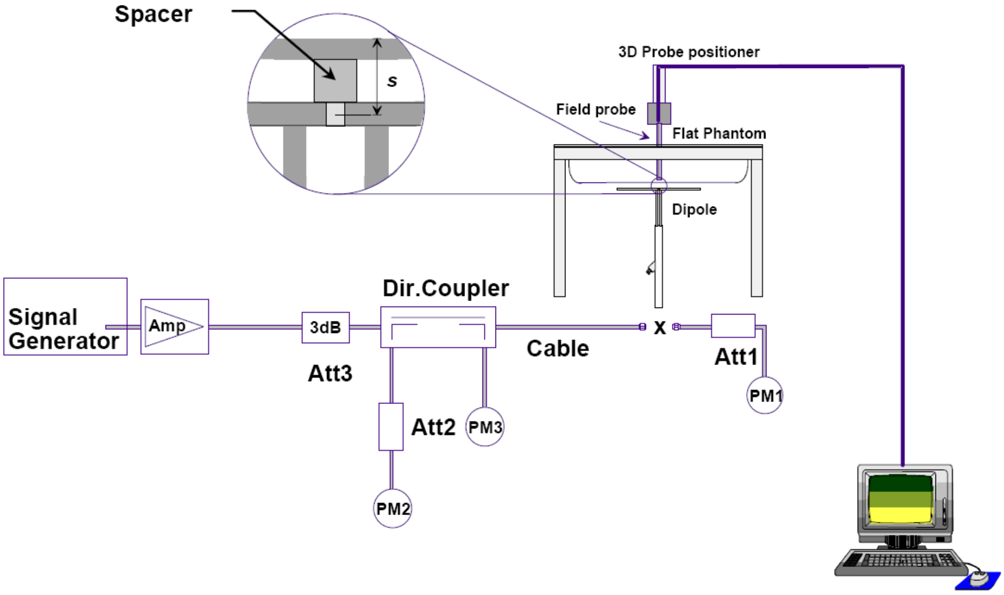


Picture 7-1 Liquid depth in the Flat Phantom (2450MHz)

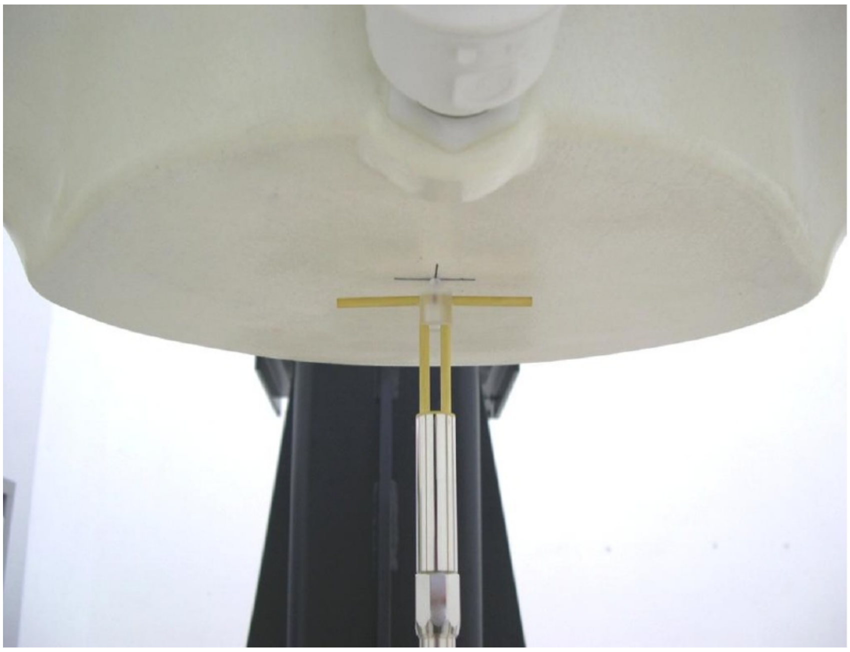
8 System verification

8.1 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



Picture 8.1 System Setup for System Evaluation



Picture 8.2 Photo of Dipole Setup

8.2 System Verification

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device.

The system verification results are required that the area scan estimated 1-g SAR is within 3% of the zoom scan 1-g SAR. The details are presented in annex B.

Table 8.1: System Verification of Body

Measurement Date (yyyy-mm-dd)	Frequency	Target value (W/kg)		Measured value (W/kg)		Deviation	
		10 g Average	1 g Average	10 g Average	1 g Average	10 g Average	1 g Average
2017-3-20	2450 MHz	24.1	51.2	24.60	52.80	2.07%	3.12%

9 Measurement Procedures

9.1 Tests to be performed

In order to determine the highest value of the peak spatial-average SAR of a handset, all device positions, configurations and operational modes shall be tested for each frequency band according to steps 1 to 3 below. A flowchart of the test process is shown in picture 9.1.

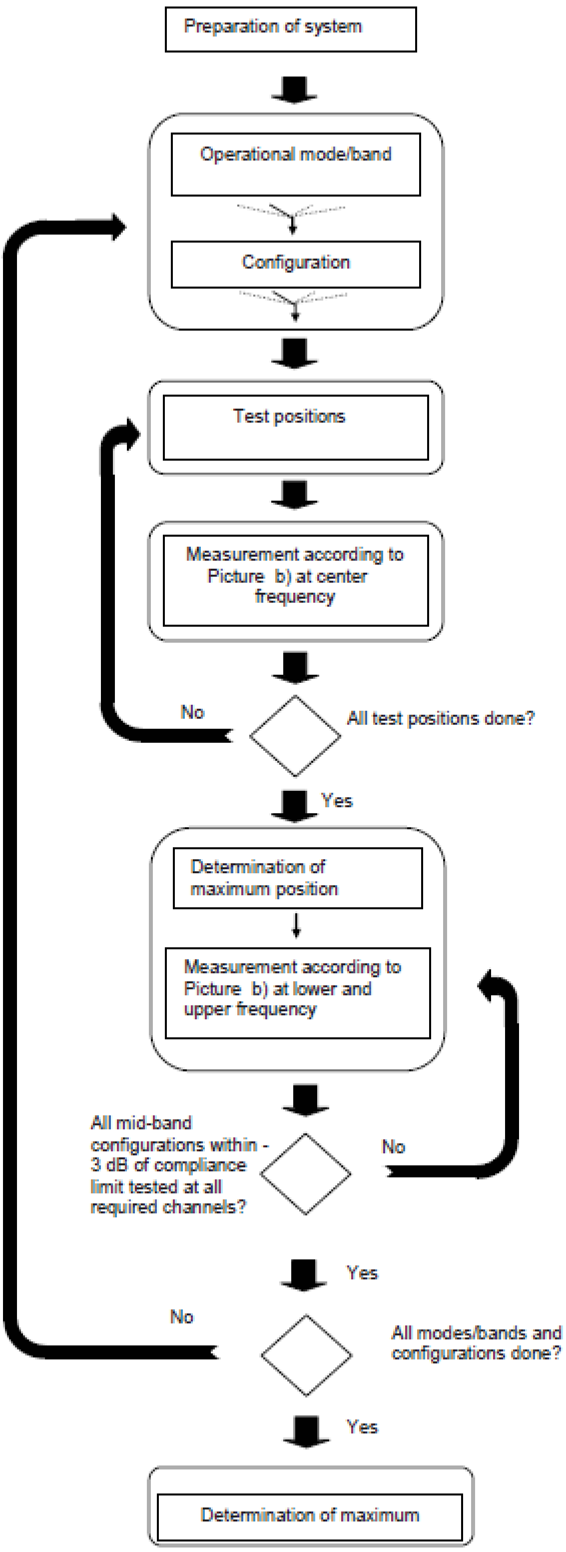
Step 1: The tests described in 9.2 shall be performed at the channel that is closest to the center of the transmit frequency band (f_c) for:

a) all device positions (cheek and tilt, for both left and right sides of the SAM phantom, as described in annex D),
b) all configurations for each device position in a), e.g., antenna extended and retracted, and
c) all operational modes, e.g., analogue and digital, for each device position in a) and configuration in b) in each frequency band.

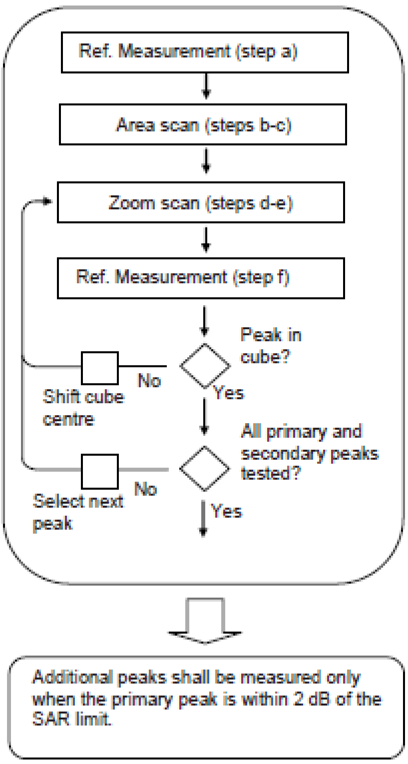
If more than three frequencies need to be tested according to 11.1 (i.e., N_c > 3), then all frequencies, configurations and modes shall be tested for all of the above test conditions.

Step 2: For the condition providing highest peak spatial-average SAR determined in Step 1, perform all tests described in 9.2 at all other test frequencies, i.e., lowest and highest frequencies. In addition, for all other conditions (device position, configuration and operational mode) where the peak spatial-average SAR value determined in Step 1 is within 3 dB of the applicable SAR limit, it is recommended that all other test frequencies shall be tested as well.

Step 3: Examine all data to determine the highest value of the peak spatial-average SAR found in Steps 1 to 2.



Picture a – Tests to be performed



Picture b – General procedure

Picture 9.1Block diagram of the tests to be performed

9.2 General Measurement Procedure

The area and zoom scan resolutions specified in the table below must be applied to the SAR measurements and fully documented in SAR reports to qualify for TCB approval. Probe boundary effect error compensation is required for measurements with the probe tip closer than half a probe tip diameter to the phantom surface. Both the probe tip diameter and sensor offset distance must satisfy measurement protocols; to ensure probe boundary effect errors are minimized and the higher fields closest to the phantom surface can be correctly measured and extrapolated to the phantom surface for computing 1-g SAR. Tolerances of the post-processing algorithms must be verified by the test laboratory for the scan resolutions used in the SAR measurements, according to the reference distribution functions specified in IEEE Std 1528-2003. The results should be documented as part of the system validation records and may be requested to support test results when all the measurement parameters in the following table are not satisfied.

			≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface			5 ± 1 mm	$\frac{1}{2}\cdot\delta\cdot\ln(2) \pm 0.5$ mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location			30° ± 1°	20° ± 1°
Maximum area scan spatial resolution: Δx_{Area}, Δy_{Area}			≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
			When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	
Maximum zoom scan spatial resolution: Δx_{Zoom}, Δy_{Zoom}			≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$		≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
	graded grid	$\Delta z_{Zoom}(1)$: between 1st two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		$\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq 1.5\cdot\Delta z_{Zoom}(n-1)$	
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

* When zoom scan is required and the *reported* SAR from the area scan based *1-g SAR estimation* procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

9.3 Bluetooth & Wi-Fi Measurement Procedures for SAR

Normal network operating configurations are not suitable for measuring the SAR of 802.11 transmitters in general. Unpredictable fluctuations in network traffic and antenna diversity conditions can introduce undesirable variations in SAR results. The SAR for these devices should be measured using chipset based test mode software to ensure that the results are consistent and reliable.

Chipset based test mode software is hardware dependent and generally varies among manufacturers. The device operating parameters established in a test mode for SAR measurements must be identical to those programmed in production units, including output power levels, amplifier gain settings and other RF performance tuning parameters. The test frequencies should correspond to actual channel frequencies defined for domestic use. SAR for devices with switched diversity should be measured with only one antenna transmitting at a time during each SAR measurement, according to a fixed modulation and data rate. The same data pattern should be used for all measurements.

9.4 Power Drift

To control the output power stability during the SAR test, DASY4 system calculates the power drift by measuring the E-field at the same location at the beginning and at the end of the measurement for each test position. These drift values can be found in section12 labeled as: (Power Drift [dB]). This ensures that the power drift during one measurement is within 5%.

10 Conducted Output Power

The output power of BT antenna is as following:

Mode	Conducted Power (dBm)			Tune up
	Channel 0 (2402MHz)	Channel 39 (2441MHz)	Channel 78(2480MHz)	
GFSK	4.35	4.10	4.21	5
EDR2M-4_DQPSK	4.83	4.81	4.92	5
EDR3M-8DPSK	3.79	3.83	3.93	5

The average conducted power for Wi-Fi is as following:

802.11b (dBm)

Channel\data rate	1Mbps	2Mbps	5.5Mbps	11Mbps
1	15.76	15.58	15.37	15.12
6	15.51	/	/	/
11	15.64	/	/	/
Tune up	16	16	16	16

802.11g (dBm)

Channel\data rate	6Mbps	9Mbps	12Mbps	18Mbps	24Mbps	36Mbps	48Mbps	54Mbps
1	15.63	15.22	15.02	14.65	14.28	13.71	13.22	13.03
6	15.35	/	/	/	/	/	/	/
11	15.57	/	/	/	/	/	/	/
Tune up	16	16	16	16	16	14	14	14

802.11n (dBm) - HT20 (2.4G)

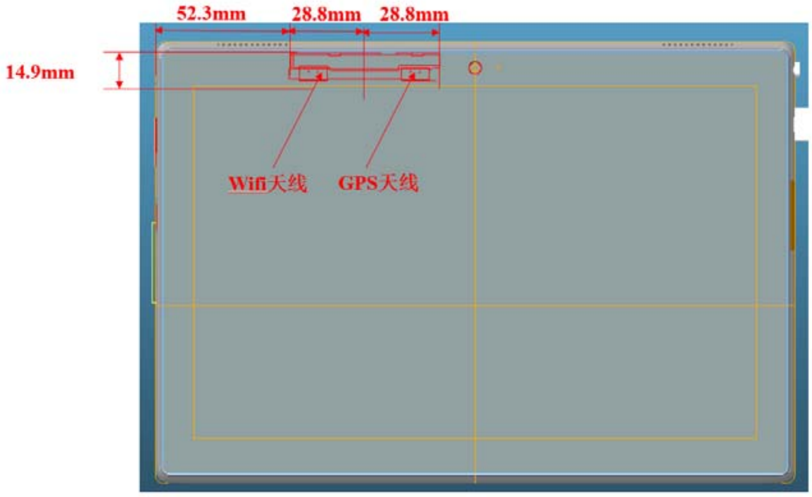
Channel\data rate	MCS0	MCS1	MCS2	MCS3	MCS4	MCS5	MCS6	MCS7
1	15.44	15.04	14.68	14.31	13.78	13.33	13.15	12.96
6	15.04	/	/	/	/	/	/	/
11	15.41	/	/	/	/	/	/	/
Tune up	16	16	16	16	14	14	14	14

802.11n (dBm) – HT40 (2.4G)

Channel\data rate	MCS0	MCS1	MCS2	MCS3	MCS4	MCS5	MCS6	MCS7
3	14.36	/	/	/	/	/	/	/
6	14.30	/	/	/	/	/	/	/
9	14.57	13.88	13.32	12.86	12.13	11.68	11.50	11.30
Tune up	15	15	15	14	13	13	13	13

11 Standalone SAR Considerations

11.1 Transmit Antenna Separation Distances



Picture 11.1 Antenna Locations

11.2 SAR Measurement Positions

According to the KDB941225 D06 Hot Spot SAR v01, the edges with less than 2.5 cm distance to the antennas need to be tested for SAR.

SAR measurement positions						
Mode	Front	Rear	Left edge	Right edge	Top edge	Bottom edge
WLAN	No	Yes	No	No	Yes	No

11.3 Standalone SAR Test Exclusion Considerations

Standalone 1-g head or body SAR evaluation by measurement or numerical simulation is not required when the corresponding SAR Exclusion Threshold condition, listed below, is satisfied. The 1-g SAR test exclusion threshold for 100 MHz to 6 GHz at test separation distances≤ 50 mm are determined by:

[(max. power of channel, including tune-up tolerance, mW)/(min. test separation distance, mm)] · [√f(GHz)] ≤ 3.0 for 1-g SAR, where

- f(GHz) is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation
- The result is rounded to one decimal place for comparison

Table 11.1: Standalone SAR test exclusion considerations

Band/Mode	**F(GHz)**	**Position**	**SAR test exclusion threshold (mW)**	**RF output power**		**SAR test exclusion**
				dBm	**mW**	
Bluetooth	2.441	Body	19.2	5	3.16	Yes
WLAN 802.11 b	2.45	Body	19.17	16	39.81	No

12 SAR Test Result

It is determined by user manual for the distance between the EUT and the phantom bottom.
The distance is 0 mm and just applied to the condition of body worn accessory.
The calculated SAR is obtained by the following formula:

$$\text{Reported SAR} = \text{Measured SAR} \times 10^{(P_{Target} - P_{Measured})/10}$$

Where P_{Target} is the power of manufacturing upper limit;
$P_{Measured}$ is the measured power in chapter 10.

We'll perform the SAR measurement with SKU1-2 and retest on highest value point with SKU1-1 and SKU6.

Table 12-1: SAR Values (WLAN - Body) – 802.11b 1Mbps

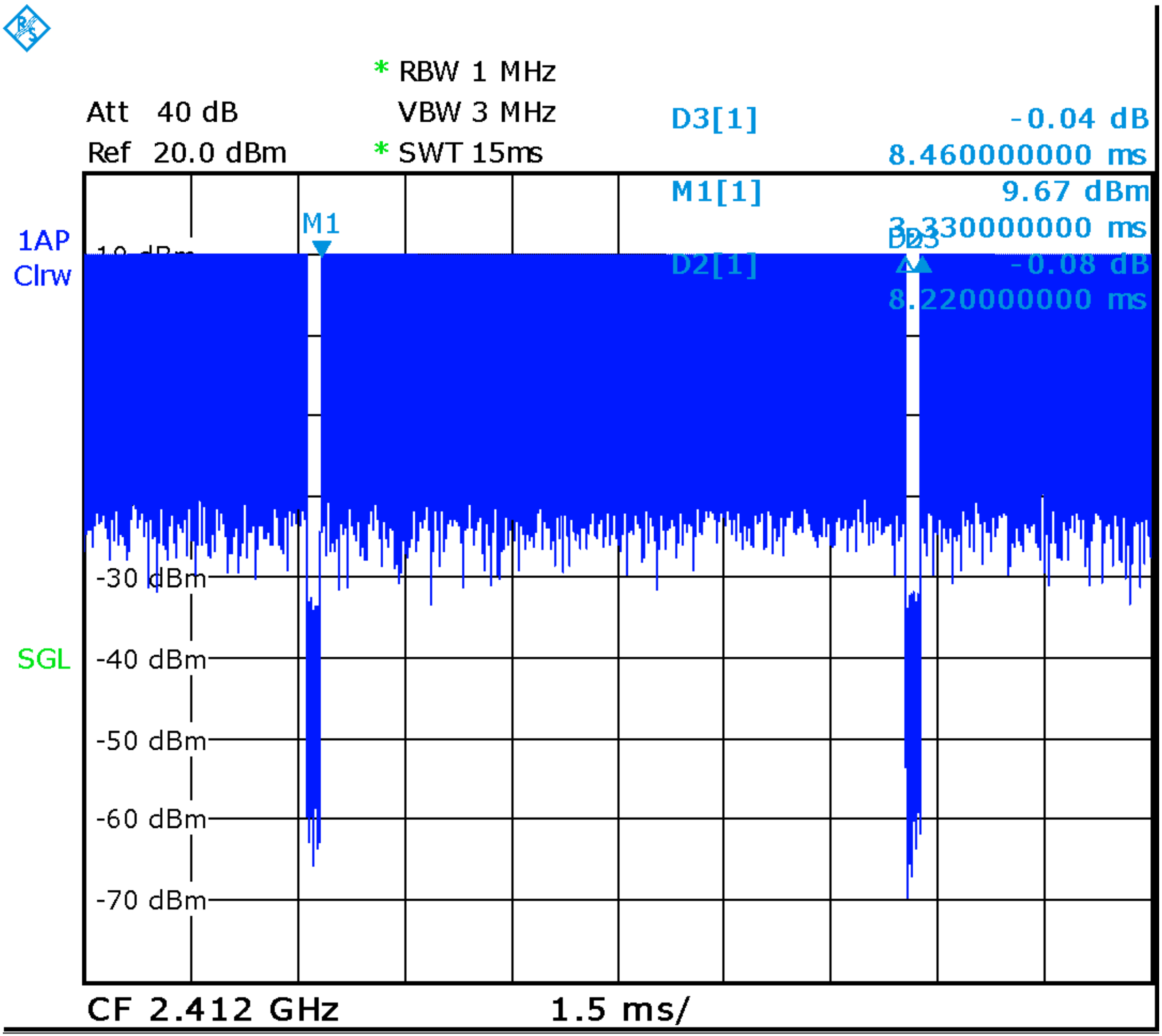
Ambient Temperature: 22.5 °C Liquid Temperature: 22.0°C												
Frequency		Test Position	Mode	Figure No.	Note	Conducted Power (dBm)	Max. tune-up Power (dBm)	Measured SAR(10g) (W/kg)	Reported SAR(10g) (W/kg)	Measured SAR(1g) (W/kg)	Reported SAR(1g) (W/kg)	Power Drift (dB)
MHz	Ch.											
2462	11	Rear	802.11b	/	SKU1-2	15.64	16	0.446	**0.48**	1.11	**1.20**	-0.06
2437	6	Rear	802.11b	/	SKU1-2	15.51	16	0.398	**0.45**	0.969	**1.08**	-0.05
2412	1	Rear	802.11b	/	SKU1-2	15.76	16	0.418	**0.44**	0.977	**1.03**	-0.09
2437	6	Top	802.11b	/	SKU1-2	15.51	16	0.087	**0.10**	0.185	**0.21**	0.06
2462	11	Rear	802.11b	/	SKU1-1	15.64	16	0.408	**0.44**	0.995	**1.08**	0.02
2437	6	Rear	802.11b	/	SKU1-1	15.51	16	0.357	**0.40**	0.875	**0.98**	0.05
2412	1	Rear	802.11b	/	SKU1-1	15.76	16	0.388	**0.41**	0.951	**1.01**	0.08
2462	11	Rear	802.11b	Fig.1	SKU6	15.64	16	0.519	**0.56**	1.31	**1.42**	0.10
2437	6	Rear	802.11b	/	SKU6	15.51	16	0.431	**0.48**	1.15	**1.29**	-0.01
2412	1	Rear	802.11b	/	SKU6	15.76	16	0.489	**0.52**	1.26	**1.33**	0.03
2462	11	Rear	802.11g	/	SKU6	15.57	16	0.504	**0.56**	1.28	**1.41**	0.09
2437	6	Rear	802.11g	/	SKU6	15.35	16	0.449	**0.52**	1.19	**1.38**	-0.05
2412	1	Rear	802.11g	/	SKU6	15.63	16	0.437	**0.48**	1.15	**1.25**	0.06

Note1: The distance between the EUT and the phantom bottom is 0mm.
Note2: The mode of 802.11g is performed for SKU6, because the reported SAR of 802.11b for SKU6 is higher than 1.2W/kg.

According to the KDB248227 D01, The reported SAR must be scaled to 100% transmission duty factor to determine compliance at the maximum tune-up tolerance limit. The scaled reported SAR is presented as below.

Table 12-2: SAR Values (WLAN - Body) – 802.11b 1Mbps (Scaled Reported SAR)

Ambient Temperature: 22.5 °C Liquid Temperature: 22.0°C						
Frequency		Test Position	Actual duty factor	maximum duty factor	Reported SAR (1g)(W/kg)	Scaled reported SAR (1g)(W/kg)
MHz	Ch.					
2462	11	Rear	97.16%	100%	**1.42**	**1.46**



Picture 12.1 Duty factor plot

13 SAR Measurement Variability

SAR measurement variability must be assessed for each frequency band, which is determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media are required for SAR measurements in a frequency band, the variability measurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium.

The following procedures are applied to determine if repeated measurements are required.

1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps2) through 4) do not apply.

2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.

3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45W/kg (~ 10% from the 1-g SAR limit).

4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

Table 13.1: SAR Measurement Variability for Body WLAN (1g)

Frequency		Test Position	Spacing (mm)	Original SAR (W/kg)	First Repeated SAR (W/kg)	The Ratio	Second Repeated SAR (W/kg)	The Ratio
Ch.	MHz							
11	2462	Rear	0	1.31	1.29	1.02	/	/

14 Measurement Uncertainty

No.	Error Description	Type	Uncertainty value	Probably Distribution	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	Degree of freedom
Measurement system										
1	Probe calibration	B	6.0	N	1	1	1	6.0	6.0	∞
2	Isotropy	B	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	∞
3	Boundary effect	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
4	Linearity	B	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
5	Detection limit	B	1.0	N	1	1	1	0.6	0.6	∞
6	Readout electronics	B	0.3	R	$\sqrt{3}$	1	1	0.3	0.3	∞
7	Response time	B	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
8	Integration time	B	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	∞
9	RF ambient conditions-noise	B	0	R	$\sqrt{3}$	1	1	0	0	∞
10	RFambient conditions-reflection	B	0	R	$\sqrt{3}$	1	1	0	0	∞
11	Probe positioned mech. restrictions	B	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	∞
12	Probe positioning with respect to phantom shell	B	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞
13	Post-processing	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
Test sample related										
14	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	71
15	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
16	Drift of output power	B	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
Phantom and set-up										
17	Phantom uncertainty	B	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞
18	Liquid conductivity (target)	B	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
19	Liquid conductivity (meas.)	A	2.06	N	1	0.64	0.43	1.32	0.89	43
20	Liquid permittivity (target)	B	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞
21	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	1.0	0.8	521

Combined standard uncertainty	$u_c^{'} = \sqrt{\sum_{i=1}^{21} c_i^2 u_i^2}$					9.55	9.43	257
Expanded uncertainty (confidence interval of 95 %)	$u_e = 2u_c$					19.1	18.9	

15 MAIN TEST INSTRUMENTS

Table 15.1: List of Main Instruments

No.	Name	Type	Serial Number	Calibration Date	Valid Period
01	Network analyzer	E5071C	MY46110673	January 13, 2017	One year
02	Dielectric Probe Kit	85070E	Agilent	No Calibration Requested	
03	Power meter	NRVD	102083	September 22, 2016	One year
04	Power sensor	NRV-Z5	100595		
05	Signal Generator	E4438C	MY49071430	January 13, 2017	One Year
06	Amplifier	60S1G4	0331848	No Calibration Requested	
07	Directional Coupler	778D	MY48220584	No Calibration Requested	
08	E-field Probe	SPEAG EX3DV4	3846	January 13,2017	One year
09	DAE	SPEAG DAE4	1331	January 19, 2017	One year
10	Dipole Validation Kit	SPEAG D2450V2	853	July 25, 2016	One year

END OF REPORT BODY

ANNEX A Graph Results

WLAN_CH11 Rear
Date: 2017-3-20
Electronics: DAE4 Sn1331
Medium: Body 2450 MHz
Medium parameters used (interpolated): f = 2462 MHz; σ = 1.918 mho/m; εr = 52.161; ρ = 1000 kg/m^3
Ambient Temperature: 22.5^{o}C, Liquid Temperature: 22.0^{o}C
Communication System: WLAN 2462 MHz Duty Cycle: 1:1
Probe: EX3DV4 – SN3846 ConvF(7.31,7.31,7.31)

Area Scan (121x111x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm
Maximum value of SAR (interpolated) = 1.86 W/kg

Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 9.360 V/m; Power Drift = 0.10 dB
Peak SAR (extrapolated) = 3.48 W/kg
SAR(1 g) = 1.31 W/kg; SAR(10 g) = 0.519 W/kg
Maximum value of SAR (measured) = 1.91 W/kg

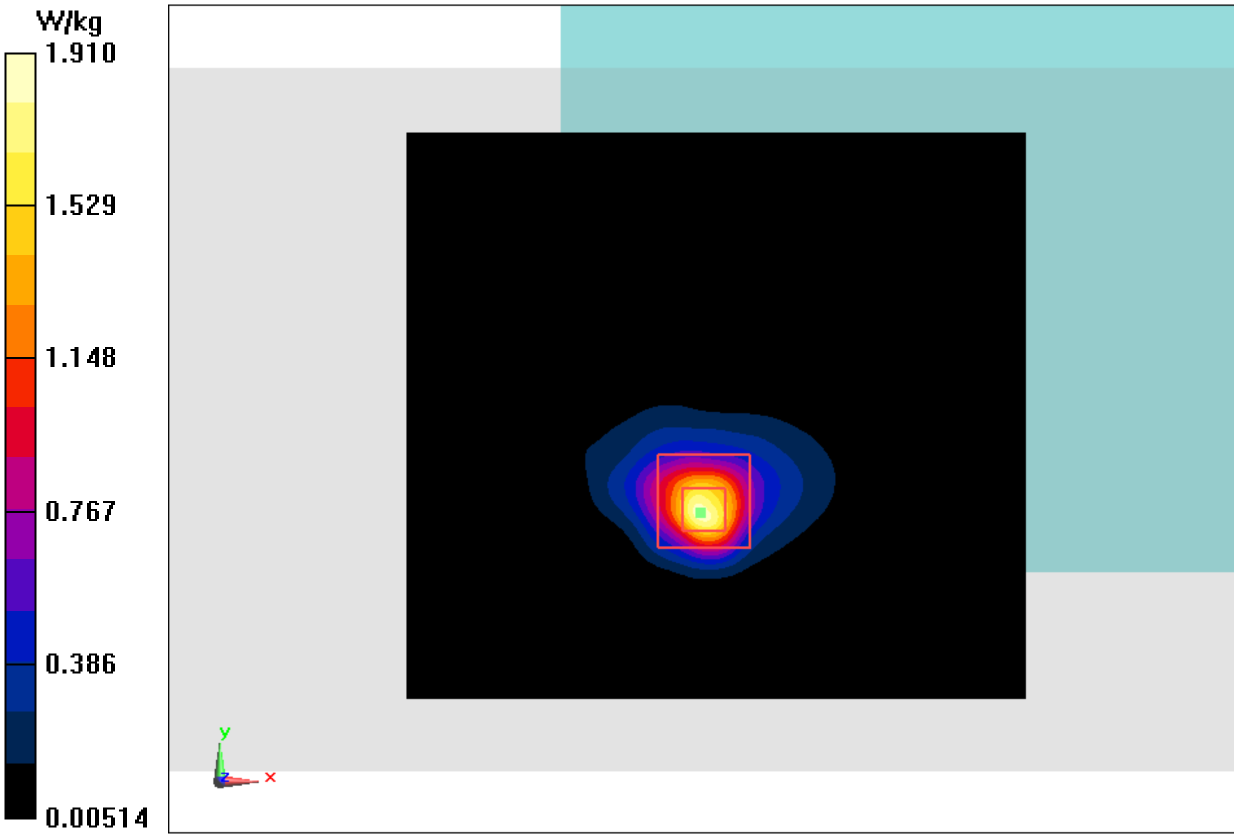


Figure 1

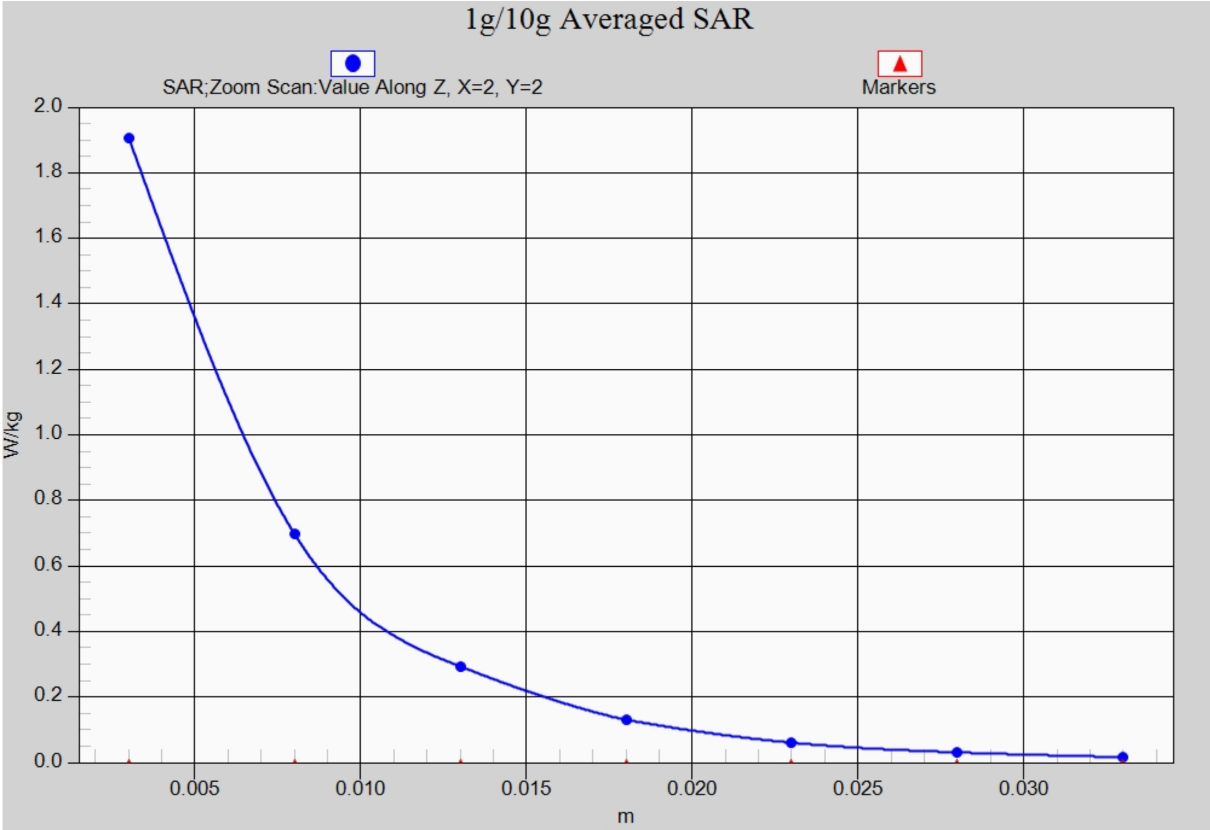

1g/10g Averaged SAR
SAR;Zoom Scan:Value Along Z, X=2, Y=2
Markers
2.0
1.8
1.6
1.4
1.2
1.0
0.8
0.6
0.4
0.2
0.0
W/kg
0.005
0.010
0.015
0.020
0.025
0.030
m

Figure 1-1

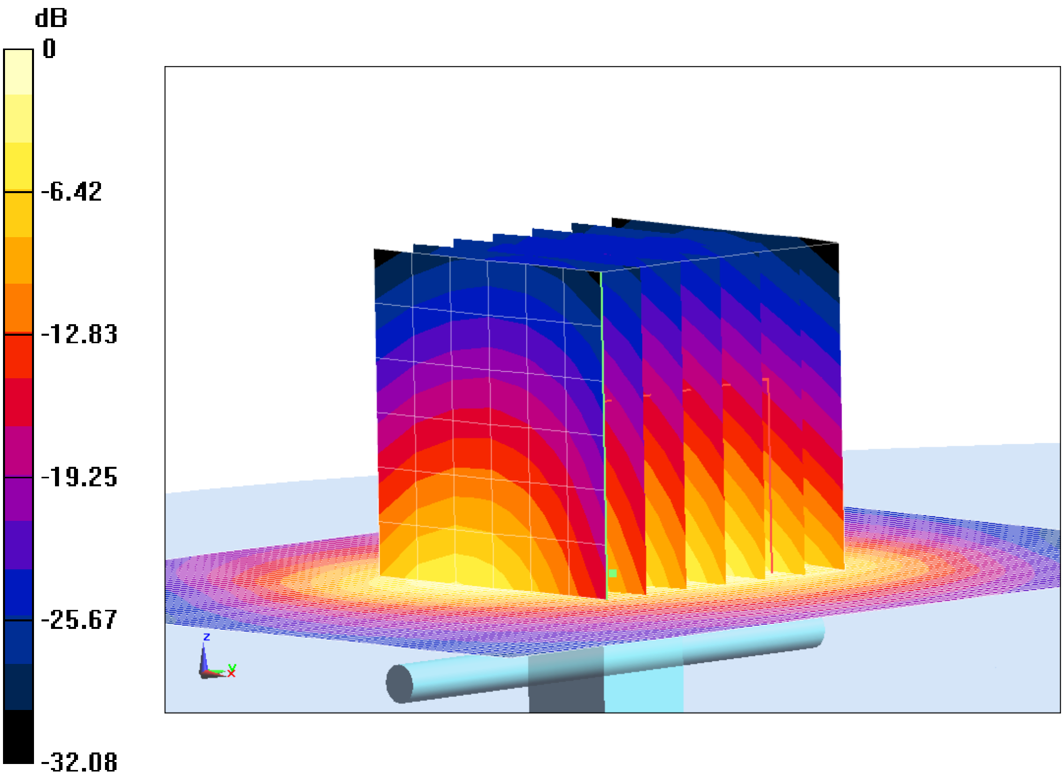
ANNEX B SystemVerification Results

2450 MHz

Date: 2017-3-20
Electronics: DAE4 Sn1331
Medium: Body2450 MHz
Medium parameters used: f = 2450 MHz; σ =1.89 mho/m; ε_r = 52.17; ρ = 1000 kg/m^3
Ambient Temperature: 22.5^{o}C Liquid Temperature: 22.0^{o}C
Communication System: CW Frequency: 2450 MHz Duty Cycle: 1:1
Probe: EX3DV4 – SN7307 ConvF(7.31,7.31,7.31)

System Validation /Area Scan (81x191x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm
Maximum value of SAR (interpolated) = 21.5 W/kg

System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value =104.6 V/m; Power Drift = 0.11 dB
Peak SAR (extrapolated) = 26.12 W/kg
SAR(1 g) = 13.2 W/kg; SAR(10 g) = 6.15 W/kg
Maximum value of SAR (measured) = 21.3 W/kg



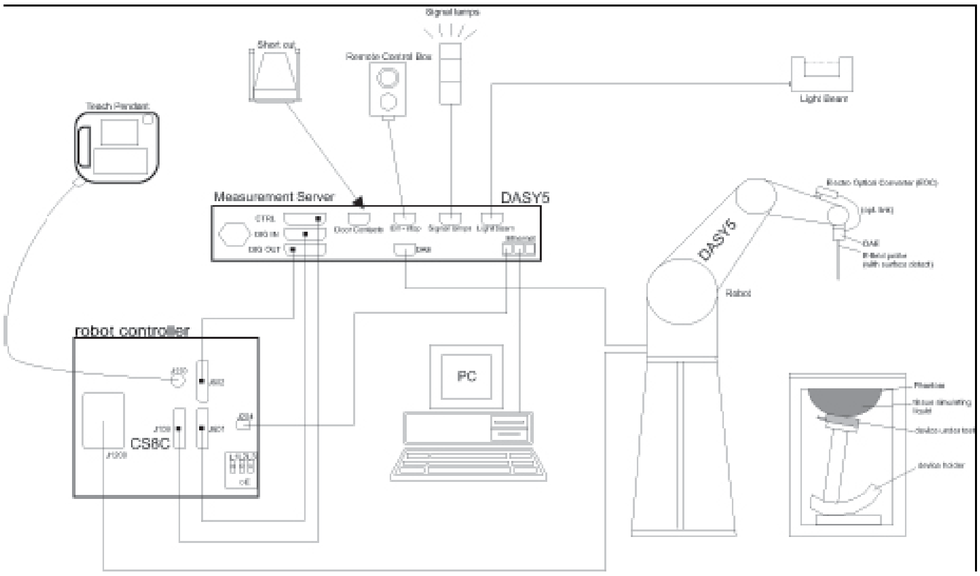
0 dB = 21.3 W/kg = 13.28 dB W/kg

Fig.B.1 validation 2450 MHz 250mW

ANNEX C SAR Measurement Setup

C.1 Measurement Set-up

The Dasy4 or DASY5 system for performing compliance tests is illustrated above graphically. This system consists of the following items:



Picture C.1 SAR Lab Test Measurement Set-up

- A standard high precision 6-axis robot (StäubliTX=RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY4 or DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as
- warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

C.2 Dasy4 or DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 or DASY5 software reads the reflection durning a software approach and looks for the maximum using 2nd ord curve fitting. The approach is stopped at reaching the maximum.

Picture C.2 Near-field Probe

Probe Specifications:

Model: ES3DV3, EX3DV4

Frequency Range: 10MHz — 6.0GHz(EX3DV4)
10MHz — 4GHz(ES3DV3)

Calibration: In head and body simulating tissue at Frequencies from 835 up to 5800MHz

Linearity: ± 0.2 dB(30 MHz to 6 GHz) for EX3DV4
± 0.2 dB(30 MHz to 4 GHz) for ES3DV3

Dynamic Range: 10 mW/kg — 100W/kg

Probe Length: 330 mm

Probe Tip Length: 20 mm

Body Diameter: 12 mm

Tip Diameter: 2.5 mm (3.9 mm for ES3DV3)

Tip-Center: 1 mm (2.0mm for ES3DV3)

Application: SAR Dosimetry Testing
Compliance tests of mobile phones
Dosimetry in strong gradient fields

Picture C.3 E-field Probe

C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm^2) using an RF Signal generator, TEM cell, and RF Power Meter.

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/ cm^2.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C\frac{\Delta T}{\Delta t}$$

Where:

Δt = Exposure time (30 seconds),

C = Heat capacity of tissue (brain or muscle),

ΔT = Temperature increase due to RF exposure.

$$SAR = \frac{|E|^2 \cdot \sigma}{\rho}$$

Where:

σ = Simulated tissue conductivity,

ρ = Tissue density (kg/m^3).

C.4 Other Test Equipment

C.4.1 Data Acquisition Electronics(DAE)

The data acquisition electronics consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.

PictureC.4: DAE

C.4.2 Robot

The SPEAG DASY system uses the high precision robots (DASY4: RX90XL; DASY5: RX160L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchron motors; no stepper motors)
- Low ELF interference (motor control fields shielded via the closed metallic construction shields)

Picture C.5 DASY 4

Picture C.6 DASY 5

C.4.3 Measurement Server

The Measurement server is based on a PC/104 CPU broad with CPU (dasy4: 166 MHz, Intel Pentium; DASY5: 400 MHz, Intel Celeron), chip disk (DASY4: 32 MB; DASY5: 128MB), RAM (DASY4: 64 MB, DASY5: 128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O broad, which is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.

Picture C.7 Server for DASY 4

Picture C.8 Server for DASY 5

C.4.4 Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ±0.5mm would produce a SAR uncertainty of ±20%. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

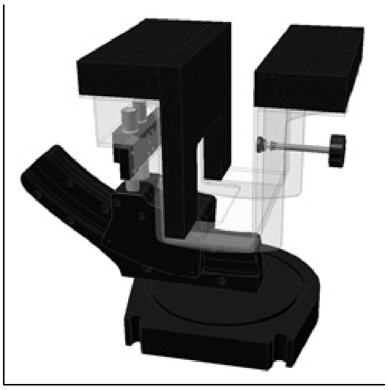
The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity ε=3 and loss tangent δ=0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.

Picture C.9-1: Device Holder



Picture C.9-2: Laptop Extension Kit

C.4.5 Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to
Represent the 90th percentile of the population. The phantom enables the dissymmetric evaluation of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

Shell Thickness: 2 ± 0. 2 mm
Filling Volume: Approx. 25 liters
Dimensions: 810 x l000 x 500 mm (H x L x W)
Available: Special

Picture C.10: SAM Twin Phantom

ANNEX D Position of the wireless device in relation to the phantom

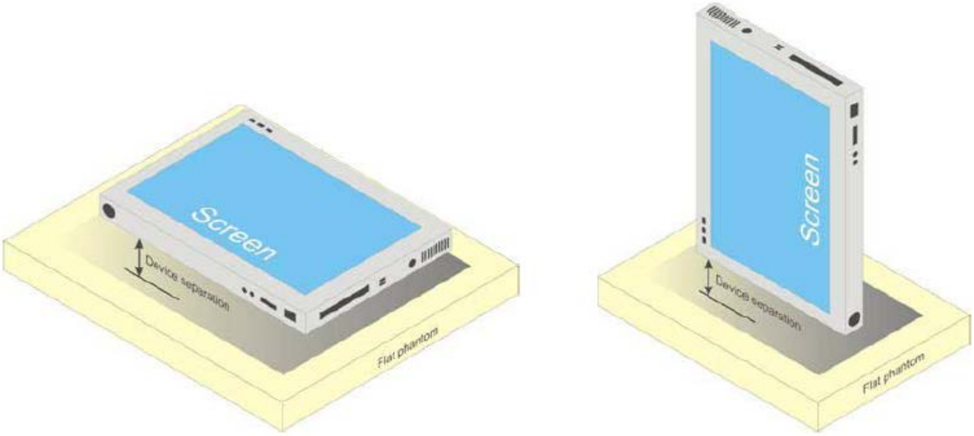
D.1 Body-supported device

Other devices that fall into this category include tablet type portable computers and credit card transaction authorisation terminals, point-of-sale and/or inventory terminals. Where these devices may be torso or limb-supported, the same principles for body-supported devices are applied.
The example in Picture D.1 shows a tablet form factor portable computer for which SAR should be separately assessed with

a) each surface and

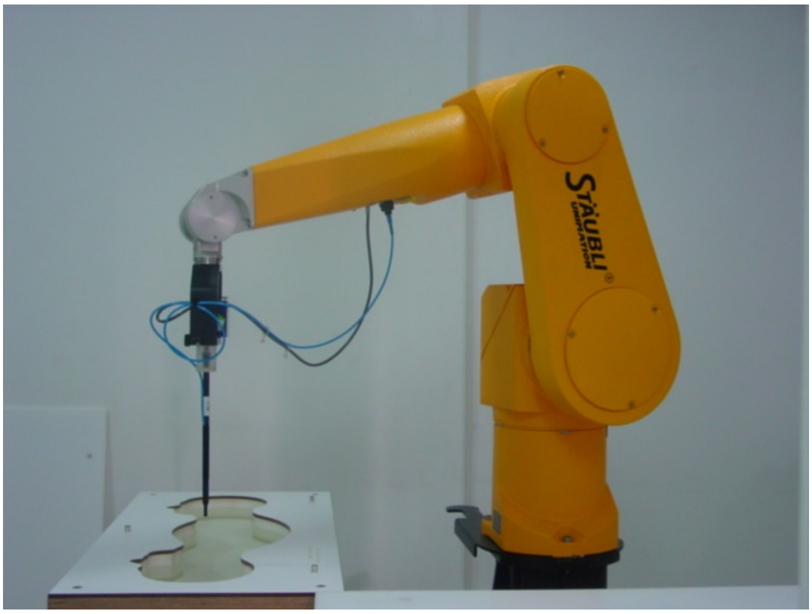
b) the separation distances

positioned against the flat phantom that correspond to the intended use as specified by the manufacturer. If the intended use is not specified in the user instructions, the device shall be tested directly against the flat phantom in all usable orientations.



Picture D.1 Tablet form factor portable computer

D.2 DUT Setup Photos



Picture D.2

ANNEX E Equivalent Media Recipes

The liquid used for the frequency range of 800-3000 MHz consisted of water, sugar, salt, preventol, glycol monobutyl and Cellulose. The liquid has been previously proven to be suited for worst-case. The Table E.1 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

TableE.1: Composition of the Tissue Equivalent Matter

Frequency (MHz)	835Head	835Body	1900 Head	1900 Body	2450 Head	2450 Body	5800 Head	5800 Body
Ingredients (% by weight)								
Water	41.45	52.5	55.242	69.91	58.79	72.60	65.53	65.53
Sugar	56.0	45.0	\	\	\	\	\	\
Salt	1.45	1.4	0.306	0.13	0.06	0.18	\	\
Preventol	0.1	0.1	\	\	\	\	\	\
Cellulose	1.0	1.0	\	\	\	\	\	\
Glycol Monobutyl	\	\	44.452	29.96	41.15	27.22	\	\
Diethylenglycol monohexylether	\	\	\	\	\	\	17.24	17.24
Triton X-100	\	\	\	\	\	\	17.24	17.24
Dielectric Parameters Target Value	ε=41.5 σ=0.90	ε=55.2 σ=0.97	ε=40.0 σ=1.40	ε=53.3 σ=1.52	ε=39.2 σ=1.80	ε=52.7 σ=1.95	ε=35.3 σ=5.27	ε=48.2 σ=6.00

Note: There are a little adjustment respectively for 750, 1750, 2600, 5200, 5300 and 5600 based on the recipe of closest frequency in table E.1.

ANNEX F System Validation

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components.

Table F.1: System Validation for 3846

Probe SN.	Liquid name	Validation date	Frequency point	Status (OK or Not)
3846	Head 750MHz	Jan.19,2017	750 MHz	OK
3846	Head 850MHz	Jan.19,2017	850 MHz	OK
3846	Head 900MHz	Jan.18,2017	900 MHz	OK
3846	Head 1750MHz	Jan.17,2017	1750 MHz	OK
3846	Head 1810MHz	Jan.17,2017	1810 MHz	OK
3846	Head 1900MHz	Jan.16,2017	1900 MHz	OK
3846	Head 1950MHz	Jan.16,2017	1950 MHz	OK
3846	Head 2000MHz	Jan.16,2017	2000 MHz	OK
3846	Head 2100MHz	Jan.16,2017	2100 MHz	OK
3846	Head 2300MHz	Jan.15,2017	2300 MHz	OK
3846	Head 2450MHz	Jan.15,2017	2450 MHz	OK
3846	Head 2550MHz	Jan.15,2017	2550 MHz	OK
3846	Head 2600MHz	Jan.15,2017	2600 MHz	OK
3846	Head 3500MHz	Jan.14,2017	3500 MHz	OK
3846	Head 3700MHz	Jan.14,2017	3700 MHz	OK
3846	Head 5200MHz	Jan.13,2017	5200 MHz	OK
3846	Head 5500MHz	Jan.13,2017	5500 MHz	OK
3846	Head 5800MHz	Jan.13,2017	5800 MHz	OK
3846	Body 750MHz	Jan.19,2017	750 MHz	OK
3846	Body 850MHz	Jan.19,2017	850 MHz	OK
3846	Body 900MHz	Jan.18,2017	900 MHz	OK
3846	Body 1750MHz	Jan.17,2017	1750 MHz	OK
3846	Body 1810MHz	Jan.17,2017	1810 MHz	OK
3846	Body 1900MHz	Jan.16,2017	1900 MHz	OK
3846	Body 1950MHz	Jan.16,2017	1950 MHz	OK
3846	Body 2000MHz	Jan.16,2017	2000 MHz	OK
3846	Body 2100MHz	Jan.16,2017	2100 MHz	OK
3846	Body 2300MHz	Jan.15,2017	2300 MHz	OK
3846	Body 2450MHz	Jan.15,2017	2450 MHz	OK
3846	Body 2550MHz	Jan.15,2017	2550 MHz	OK
3846	Body 2600MHz	Jan.15,2017	2600 MHz	OK
3846	Body 3500MHz	Jan.14,2017	3500 MHz	OK
3846	Body 3700MHz	Jan.14,2017	3700 MHz	OK
3846	Body 5200MHz	Jan.13,2017	5200 MHz	OK
3846	Body 5500MHz	Jan.13,2017	5500 MHz	OK
3846	Body 5800MHz	Jan.13,2017	5800 MHz	OK

ANNEX G Probe Calibration Certificate

Probe 3846 Calibration Certificate

In Collaboration with
s p e a g
CALIBRATION LABORATORY

中国认可
国际互认
校准
CALIBRATION
CNAS L0570

Add: No.51 Xueyuan Road, Haidian District, Beijing, 100191, China
Tel: +86-10-62304633-2218 Fax: +86-10-62304633-2209
E-mail: cttl@chinattl.com Http://www.chinattl.cn

Client CTTL Certificate No: Z16-97251

CALIBRATION CERTIFICATE

Object	EX3DV4 - SN:3846
Calibration Procedure(s)	FD-Z11-004-01 Calibration Procedures for Dosimetric E-field Probes
Calibration date:	January 13, 2017

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)℃ and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	27-Jun-16 (CTTL, No.J16X04777)	Jun-17
Power sensor NRP-Z91	101547	27-Jun-16 (CTTL, No.J16X04777)	Jun-17
Power sensor NRP-Z91	101548	27-Jun-16 (CTTL, No.J16X04777)	Jun-17
Reference10dBAttenuator	18N50W-10dB	13-Mar-16(CTTL,No.J16X01547)	Mar-18
Reference20dBAttenuator	18N50W-20dB	13-Mar-16(CTTL, No.J16X01548)	Mar-18
Reference Probe EX3DV4	SN 7433	26-Sep-16(SPEAG,No.EX3-7433_Sep16)	Sep-17
DAE4	SN 1331	21-Jan-16(SPEAG, No.DAE4-1331_Jan16)	Jan -17
Secondary Standards	**ID #**	**Cal Date(Calibrated by, Certificate No.)**	**Scheduled Calibration**
SignalGeneratorMG3700A	6201052605	27-Jun-16 (CTTL, No.J16X04776)	Jun-17
Network Analyzer E5071C	MY46110673	26-Jan-16 (CTTL, No.J16X00894)	Jan -17

	Name	Function	Signature
Calibrated by:	Yu Zongying	SAR Test Engineer	[signature]
Reviewed by:	Qi Dianyuan	SAR Project Leader	[signature]
Approved by:	Lu Bingsong	Deputy Director of the laboratory	[signature]

Issued: January 14, 2017

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Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A,B,C,D	modulation dependent linearization parameters
Polarization Φ	Φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i θ=0 is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013

b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005

c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010

d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E^2-field uncertainty inside TSL (see below ConvF).
- *NORM(f)x,y,z = NORMx,y,z* frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.
- *Ax,y,z; Bx,y,z; Cx,y,z; VRx,y,z:*A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- *ConvF and Boundary Effect Parameters:* Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from±50MHz to±100MHz.
- *Spherical isotropy (3D deviation from isotropy):* in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- *Sensor Offset:* The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle:* The angle is assessed using the information gained by determining the *NORMx* (no uncertainty required).

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Probe EX3DV4

SN: 3846

Calibrated: January 13, 2017

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)