Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

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C Service suisse d'étalonnage
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Accreditation No.: SCS 108

Client **Sporton (Auden)**

Certificate No: ER3-2358_Jan10

CALIBRATION CERTIFICATE

Object	ER3DV6 - SN:2358
Calibration procedure(s)	QA CAL-02.v5 and QA CAL-25.v2 Calibration procedure for E-field probes optimized for close near field evaluations in air
Calibration date:	January 22, 2010

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-09 (No. 217-01030)	Apr-10
Power sensor E4412A	MY41495277	1-Apr-09 (No. 217-01030)	Apr-10
Power sensor E4412A	MY41498087	1-Apr-09 (No. 217-01030)	Apr-10
Reference 3 dB Attenuator	SN: S5054 (3c)	31-Mar-09 (No. 217-01026)	Mar-10
Reference 20 dB Attenuator	SN: S5086 (20b)	31-Mar-09 (No. 217-01028)	Mar-10
Reference 30 dB Attenuator	SN: S5129 (30b)	31-Mar-09 (No. 217-01027)	Mar-10
Reference Probe ER3DV6	SN: 2328	3-Oct-09 (No. ER3-2328_Oct09)	Oct-10
DAE4	SN: 789	23-Dec-09 (No. DAE4-789_Dec09)	Dec-10

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

	Name	Function	Signature
Calibrated by:	Claudio Leubler	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: January 25, 2010

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Accreditation No.: SCS 108

Glossary:

NORMx,y,z	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1309-2005, " IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 for XY sensors and ϑ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- *NORM(f)x,y,z = NORMx,y,z * frequency_response* (see Frequency Response Chart).
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle*: The angle is assessed using the information gained by determining the *NORMx* (no uncertainty required).

Probe ER3DV6

SN:2358

Manufactured:	July 7, 2005
Last calibrated:	January 14, 2009
Recalibrated:	January 22, 2010

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

ER3DV6 SN:2358 January 22, 2010

DASY - Parameters of Probe: ER3DV6 SN:2358

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu V/(V/m)^2$)	1.71	1.57	1.60	± 10.1%
DCP (mV)[A]	94.0	91.5	96.7	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc[E] (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	± 1.5 %
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

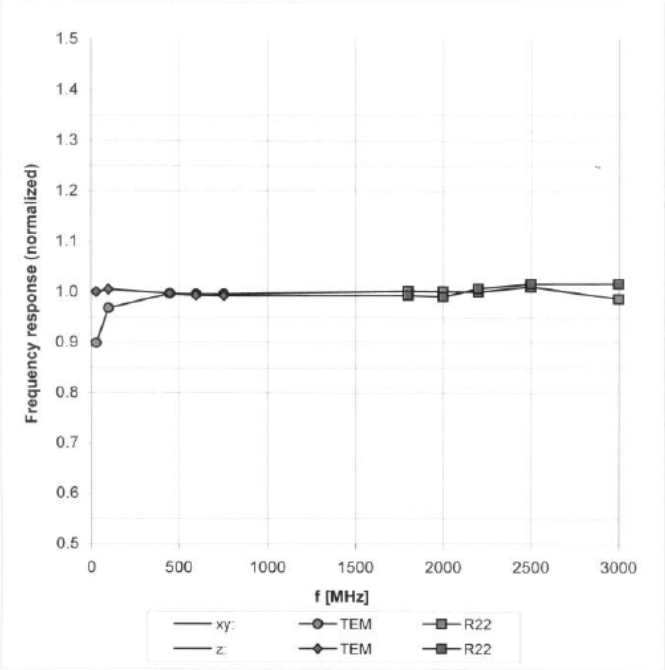
[A] numerical linearization parameter: uncertainty not required

[E] Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

ER3DV6 SN:2358 January 22, 2010

Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)



Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

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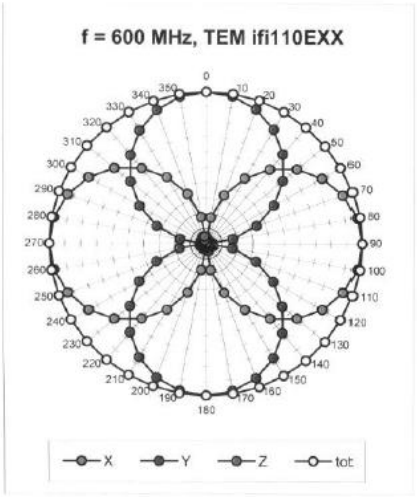
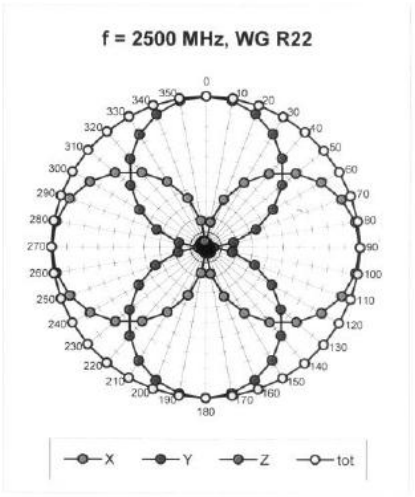
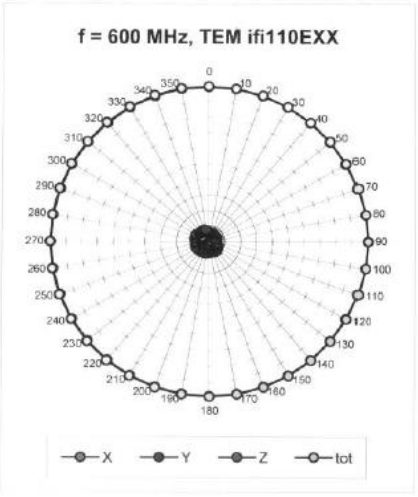
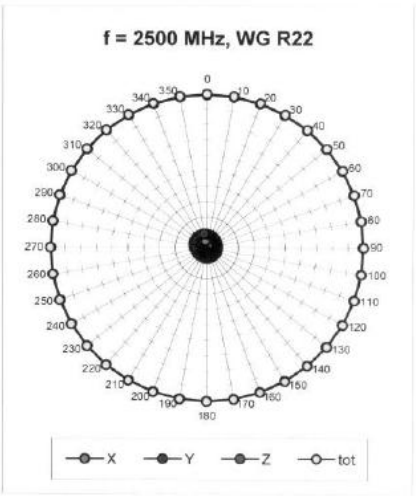
Receiving Pattern (ϕ), ϑ = 0°





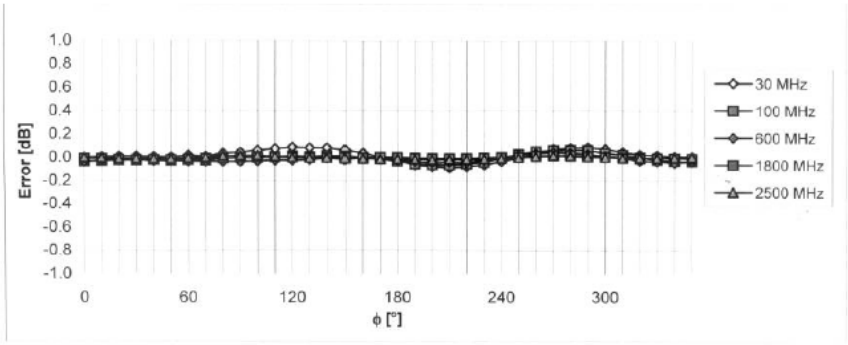
Receiving Pattern (ϕ), ϑ = 90°





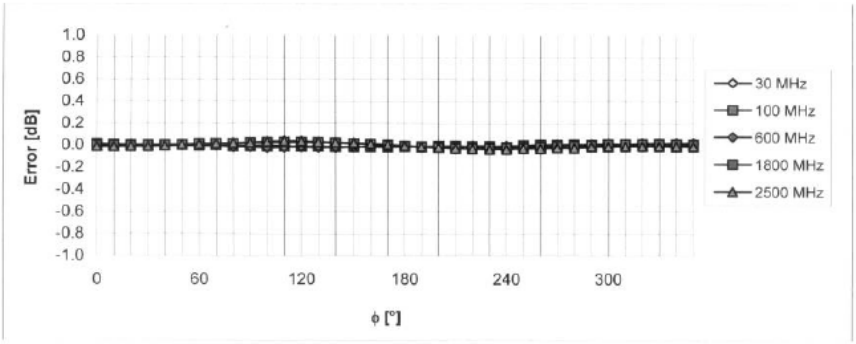
ER3DV6 SN:2358 January 22, 2010

Receiving Pattern (ϕ), ϑ = 0°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Receiving Pattern (ϕ), ϑ = 90°

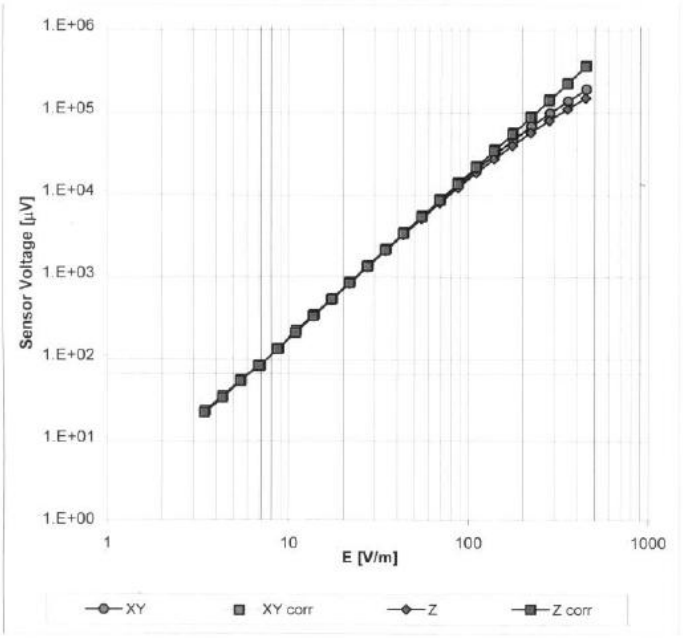


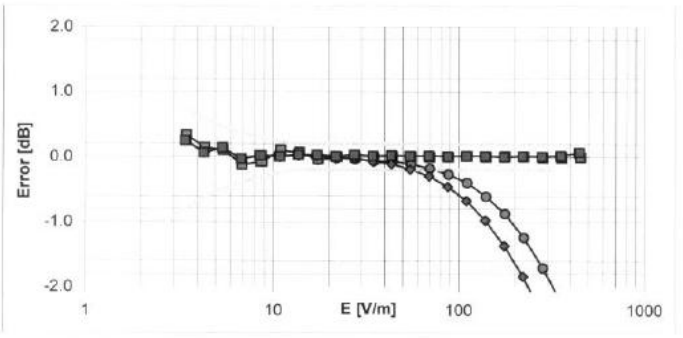
Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

ER3DV6 SN:2358 January 22, 2010

Dynamic Range f(E-field)

(Waveguide R22, f = 1800 MHz)

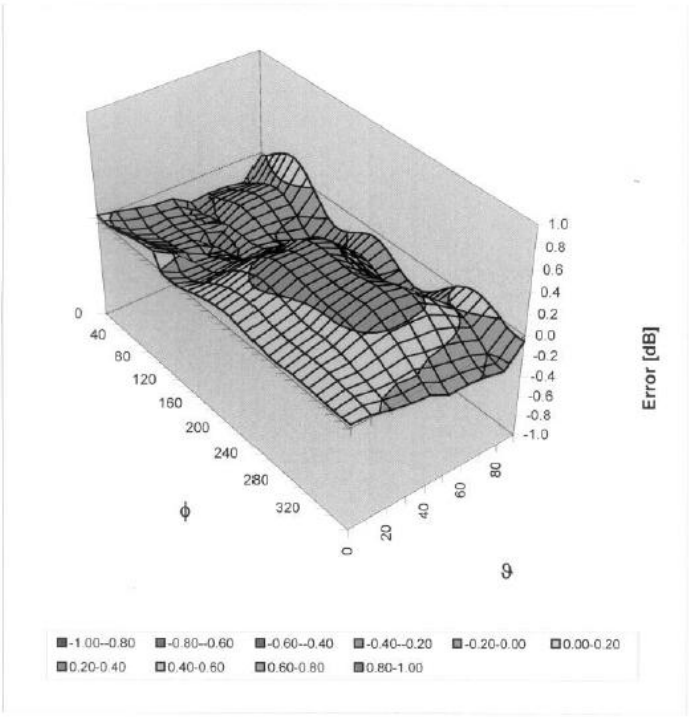




Uncertainty of Linearity Assessment: ± 0.6% (k=2)

ER3DV6 SN:2358 January 22, 2010

Deviation from Isotropy in Air
Error (ϕ, ϑ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

ER3DV6 SN:2358 January 22, 2010

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-242.4
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8.0 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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Accreditation No.: SCS 108

Client Sporton (Auden)

Certificate No: H3-6184_Jan10

CALIBRATION CERTIFICATE

Object	H3DV6 - SN:6184
Calibration procedure(s)	QA CAL-03.v5 and QA CAL-25.v2 Calibration procedure for H-field probes optimized for close near field evaluations in air
Calibration date:	January 22, 2010

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
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Reference 3 dB Attenuator	SN: S5054 (3c)	31-Mar-09 (No. 217-01026)	Mar-10
Reference 20 dB Attenuator	SN: S5086 (20b)	31-Mar-09 (No. 217-01028)	Mar-10
Reference 30 dB Attenuator	SN: S5129 (30b)	31-Mar-09 (No. 217-01027)	Mar-10
Reference Probe H3DV6	SN: 6182	3-Oct-09 (No. H3-6182_Oct09)	Oct-10
DAE4	SN: 789	23-Dec-09 (No. DAE4-789_Dec09)	Dec-10

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

	Name	Function	Signature
Calibrated by:	Claudio Leubler	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: January 25, 2010

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Glossary:

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A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1309-2005, " IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 for XY sensors and ϑ = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- *X,Y,Z(f)_a0a1a2= X,Y,Z_a0a1a2* frequency_response* (see Frequency Response Chart).
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *Ax,y,z; Bx,y,z; Cx,y,z, VRx,y,z: A, B, C* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *Spherical isotropy (3D deviation from isotropy)*: in a locally homogeneous field realized using an open waveguide setup.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle*: The angle is assessed using the information gained by determining the *X_a0a1a2* (no uncertainty required).

Probe H3DV6

SN:6184

Manufactured:	June 8, 2004
Last calibrated:	January 19, 2009
Recalibrated:	January 22, 2010

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

H3DV6 SN:6184 January 22, 2010

DASY - Parameters of Probe: H3DV6 SN:6184

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (A/m / √(μV))	a0	2.47E-3	2.53E-3	2.97E-3	± 5.1%
Norm (A/m / √(μV))	a1	1.05E-5	-6.02E-5	-1.02E-4	± 5.1%
Norm (A/m / √(μV))	a2	6.86E-6	-6.86E-7	6.53E-5	± 5.1%
DCP (mV)[A]		82.6	91.0	83.0	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc[E] (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	± 1.5 %
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

[A] numerical linearization parameter: uncertainty not required

[E] Uncertainty is determined using the maximum deviation from linear response applying recatangular distribution and is expressed for the square of the field value.

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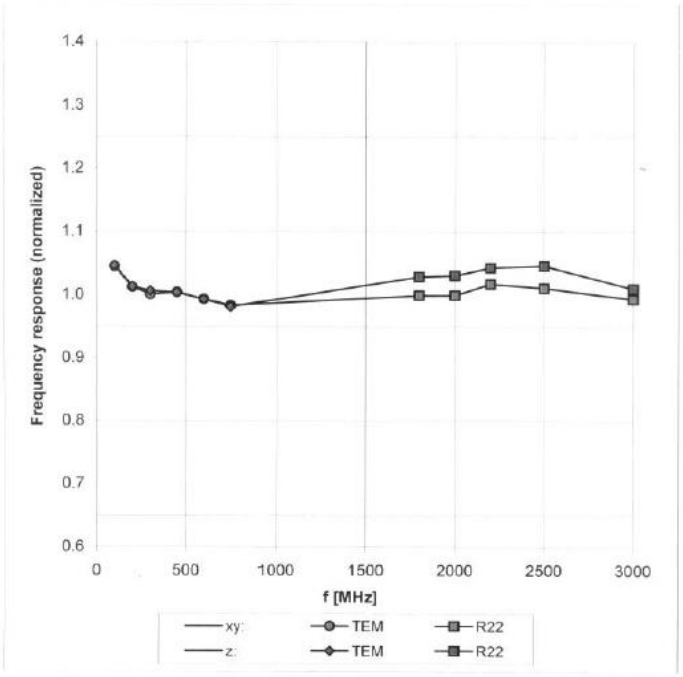
Frequency Response of H-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)

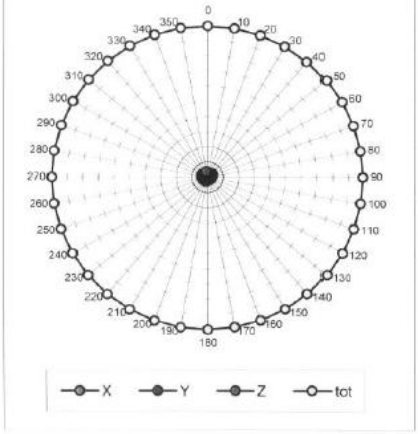


Uncertainty of Frequency Response of H-field: ± 6.3% (k=2)

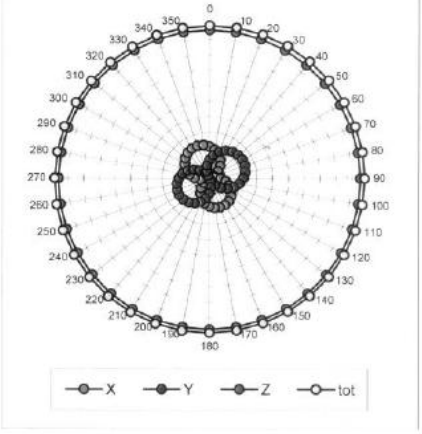
H3DV6 SN:6184 January 22, 2010

Receiving Pattern (ϕ), ϑ = 90°

f = 600 MHz, TEM ifi110EXX

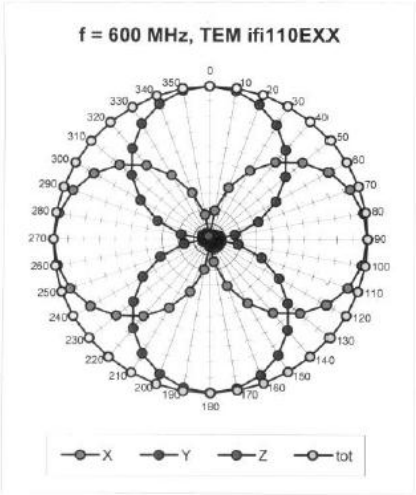


f = 2500 MHz, WG R22

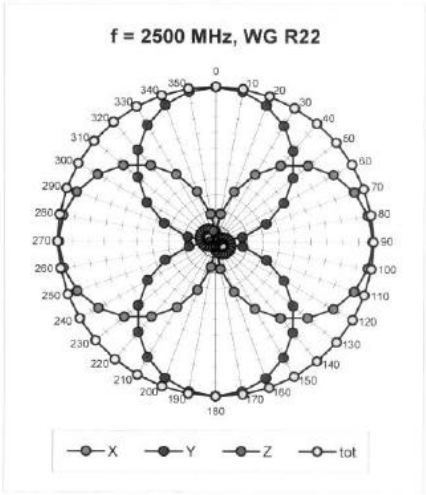


Receiving Pattern (ϕ), ϑ = 0°

f = 600 MHz, TEM ifi110EXX

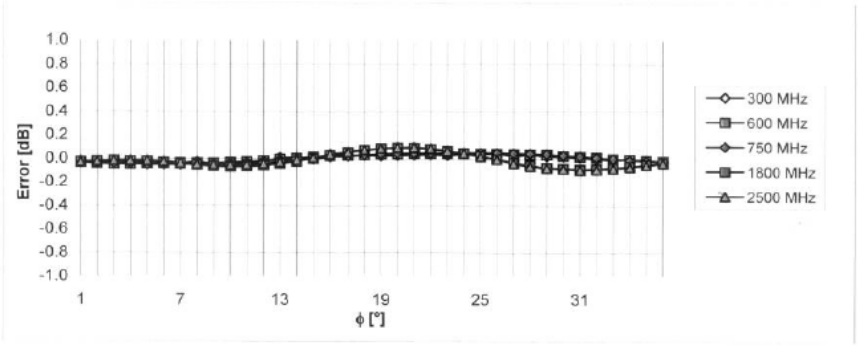


f = 2500 MHz, WG R22



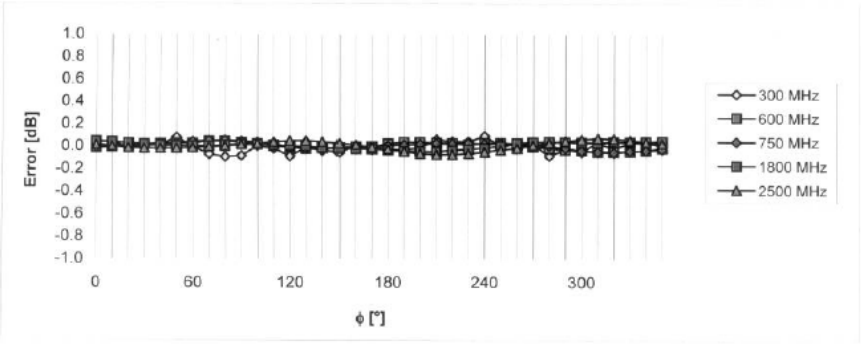
H3DV6 SN:6184 January 22, 2010

Receiving Pattern (ϕ), ϑ = 90°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Receiving Pattern (ϕ), ϑ = 0°

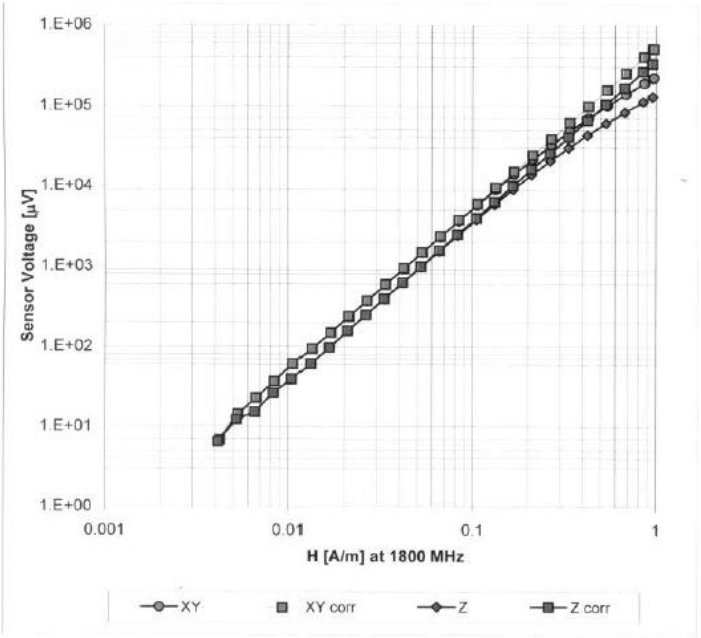


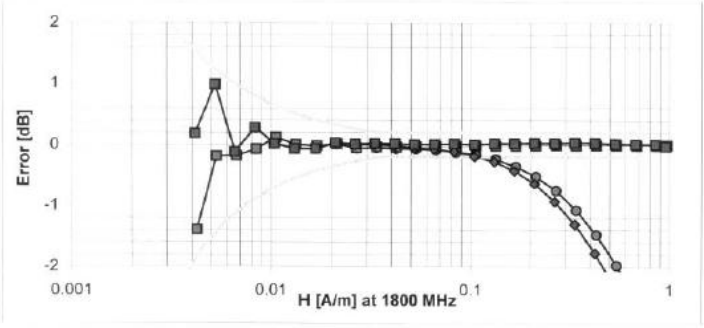
Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

H3DV6 SN:6184 January 22, 2010

Dynamic Range f(H-field)

(Waveguide R22, f = 1800 MHz)

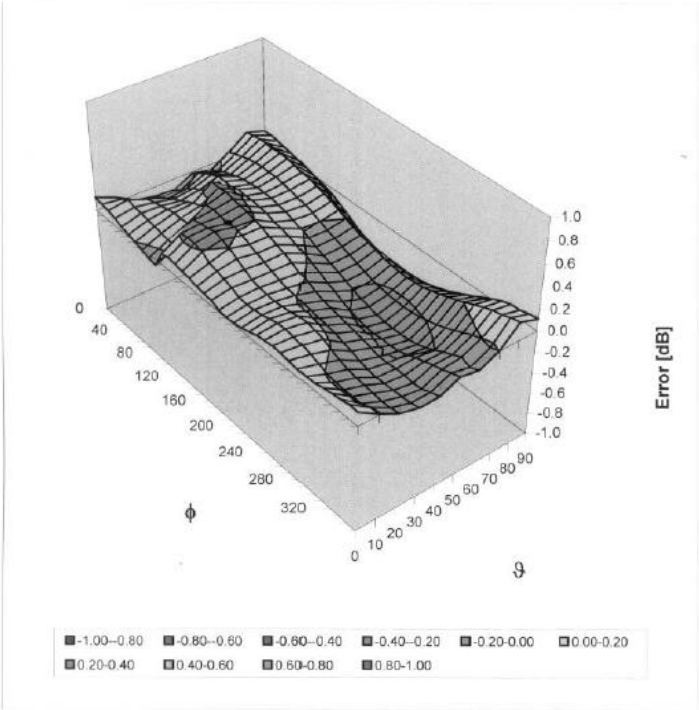




Uncertainty of Linearity Assessment: ± 0.6% (k=2)

H3DV6 SN:6184 January 22, 2010

Deviation from Isotropy in Air
Error (ϕ, ϑ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

H3DV6 SN:6184 January 22, 2010

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-245.3
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6.0 mm
Probe Tip to Sensor X Calibration Point	3 mm
Probe Tip to Sensor Y Calibration Point	3 mm
Probe Tip to Sensor Z Calibration Point	3 mm