

SAR TEST REPORT

REPORT NO.: SA950109L04G

MODEL NO.: HERM100

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TESTED: Sep. 05 ~ Sep. 10, 2006

ISSUED: Sep. 07, 2006

APPLICANT: High Tech Computer Corp.

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No.: 2177-0



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1. CERTIFICATION

PRODUCT: Pocket PC Phone

MODEL: HERM100

APPLICANT: High Tech Computer Corp.

TESTED: Sep. 05 ~ Sep. 10, 2006

TEST SAMPLE: ENGINEERING SAMPLE

STANDARDS: FCC Part 2 (Section 2.1093), RSS-102,

FCC OET Bulletin 65, Supplement C (01-01)

IEEE 1528-2003

The above equipment have been tested by **Advance Data Technology Corporation**, and found compliance with the requirement of the above standards. The test record, data evaluation & Equipment Under Test (EUT) configurations represented herein are true and accurate accounts of the measurements of the sample's EMC characteristics under the conditions specified in this report.

PREPARED BY :_______ , DATE: ____ Sep. 07, 2006

Stephanie Hung

ACCEPTANCE : Sep. 07, 2006

Responsible for RF Stanely Hsu

APPROVED BY: Jay Jay , DATE: Sep. 07, 2006

Gary Chang / Supervisor



2. GENERAL INFORMATION

2.1 GENERAL DESCRIPTION OF EUT

PRODUCT	Pocket PC Phone
MODEL NO.	HERM100
FCC ID	NM8HERM100
POWER SUPPLY	3.7Vdc from rechargeable lithium battery 5.0Vdc from power adapter 5.0Vdc from host equipment
CLASSIFICATION	Portable device, production unit
MODULATION TYPE	Mobile phone: GMSK, 8PSK for GSM, GPRS, E-GPRS QPSK, BPSK for WCDMA, HSDPA Wireless LAN: CCK, DQPSK, DBPSK for DSSS 64QAM, 16QAM, QPSK, BPSK for OFDM Bluetooth: GFSK for FHSS
FREQUENCY RANGE	Tx Frequency: 824.2MHz ~ 848.8MHz (for GSM850, WCDMA850) 1850.2MHz ~ 1909.8MHz (for PCS1900, WCDMA1900) 2400.0MHz ~ 2483.5 MHz (for Wireless LAN, Bluetooth) Rx Frequency: 869.2MHz ~ 893.8MHz (for GSM850, WCDMA850) 1930.2MHz ~ 1989.8MHz (for PCS1900, WCDMA1900) 2400.0MHz ~ 2483.5 MHz (for Wireless LAN, Bluetooth)
MAX. AVERAGE SAR (1g)	Head: 0.348W/kg (for GSM850) 0.593W/kg (for PCS1900) 1.020W/kg (for WCDMA1900) 0.00297W/kg (for Bluetooth) Body: 0.599W/kg (for GSM850) 0.443W/kg (for PCS1900) 0.682W/kg (for WCDMA1900) 0.156W/kg (for Wireless LAN)



ANTENNA TYPE	For GSM850, PCS1900, Wireless LAN, Bluetooth: PIFA antenna with -1.0dBi gain For WCDMA850, WCDMA1900: Monopole antenna with -1.0dBi gain
DATA CABLE	1.2m shielded USB cable without core1.7m non-shielded cable for earphone
I/O PORTS	Refer to user's manual
ASSOCIATED DEVICES	Earphone

NOTE:

- 1. This report is issued as a supplementary report of SA950109L04. This report shall be combined together with its original report.
- 2. RF output power is the same as the original test report. Channel frequencies under test and its conducted output power listed as below:

FOR GSM850					
	LOW	MIDDLE	HIGH		
CHANNEL	128	190	251		
FREQUECY	824.2MHz	836.6MHz	848.8MHz		
POWER	1.832W	1.683W	1.449W		

FOR PCS1900					
	LOW	MIDDLE	HIGH		
CHANNEL	512	661	810		
FREQUECY	1850.2MHz	1880.0MHz	1909.8MHz		
POWER	0.708W	0.830W	0.883W		

FOR WCDMA850					
	LOW	MIDDLE	HIGH		
CHANNEL	4132	4182	4233		
FREQUECY	826.4MHz	836.4MHz	846.6MHz		
POWER	0.222W	0.209W	0.206W		

FOR WCDMA1900					
OHANNE	LOW	MIDDLE	HIGH		
CHANNEL	9262	9400	9538		
FREQUECY	1852.4MHz	1880.0MHz	1907.6M		
POWER	0.226W	0.225W	0.228W		

FOR WIRELESS LAN (DSSS)					
	LOW	MIDDLE	HIGH		
CHANNEL	1	6	11		
FREQUECY	2412.0MHz	2437.0MHz	2462.0MHz		
POWER	31.769mW	35.645mW	39.902mW		

FOR WIRELESS LAN (OFDM)					
	LOW	MIDDLE	HIGH		
CHANNEL	1	6	11		
FREQUECY	2412.0MHz	2437.0MHz	2462.0MHz		
POWER	44.668mW	50.466mW	50.119mW		

FOR BLUETOOTH					
	LOW	MIDDLE	HIGH		
CHANNEL	0	39	78		
FREQUECY	2402.0MHz	2441.0MHz	2480.0MHz		
POWER	0.912mW	0.881mW	1.000mW		

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3. This report is prepared for FCC class II permissive change. Difference compared with the original report is listed as below, therefore radiated emission measurements has been re-tested.

ITEM	ORIGINAL DESCRIPTION	ITEM	CLASS II CHANGE DESCRIPTION
1	with Video telephone, with CCD camera	1	with Video telephone, without CCD camera
2	without Video telephone, without CCD camera	2	without Video telephone, with CCD camera

4. The EUT is a GSM850/PCS1900/ WCDMA850/WCDMA1900 Pocket PC Phone with wireless LAN and bluetooth functions. The communicated functions of EUT listed as below:

		GSM850MHz	PCS1900MHz	WCDMA850MHz	WCDMA1900MHz	
	GPRS	√	√			With 802.11b/g
2G	Edge	$\sqrt{}$	$\sqrt{}$			& bluetooth
3G	HSDPA			\checkmark	\checkmark	

5. IMEI code: 35771900******.6. Software version: 0.90.00.

7. The EUT was operated with following power adapters:

ADAPTER 1:	ADAPTER 1:					
BRAND:	PHIHONG					
MODEL:	PSAA05A-050					
INPUT:	100-240Vac, 50-60Hz, 0.2A					
OUTPUT:	5.15Vdc, 1A					
POWER LINE:	DC 1.8m non-shielded cable without core					

ADAPTER 2:	ADAPTER 2:				
BRAND:	TPT				
MODEL:	JHA050100UU05				
INPUT:	100-240Vac, 50-60Hz, 0.3A				
OUTPUT:	5.0Vdc, 1.0A, 5W				
POWER LINE:	DC 1.8m non-shielded cable without core				

ADAPTER 3:				
BRAND:	Delta			
MODEL:	ADP-5FH B			
INPUT:	100-240Vac, 50-60Hz, 0.2A			
OUTPUT:	5.0Vdc, 1A			
POWER LINE:	DC 1.8m non-shielded cable without core			



8. The EUT has one lithium battery listed as below:

STANDARD BATTERY:			
MODEL:	MODEL: PA16A		
RATING:	3.7Vdc, 1350mAh		

9. IMEI Code: 357719 00*****.

10. Software version: 0.90.00.

11. The above EUT information was declared by manufacturer and for more detailed features description, please refer to the manufacturer's specifications or User's Manual.

2.2 GENERAL DESCRIPTION OF APPLIED STANDARDS

According to the specifications of the manufacturer, this product must comply with the requirements of the following standards:

FCC 47 CFR Part 2 (2.1093)

FCC OET Bulletin 65, Supplement C (01-01)

RSS-102

IEEE 1528-2003

All test items have been performed and recorded as per the above standards.

2.3 GENERAL INOFRMATION OF THE SAR SYSTEM

DASY4 (software 4.7 Build 44) consists of high precision robot, probe alignment sensor, phantom, robot controller, controlled measurement server and near-field probe. The robot includes six axes that can move to the precision position of the DASY4 software defined. The DASY4 software can define the area that is detected by the probe. The robot is connected to controlled box. Controlled measurement server is connected to the controlled robot box. The DAE includes amplifier, signal multiplexing, AD converter, offset measurement and surface detection. It is connected to the Electro-optical coupler (ECO). The ECO performs the conversion form the optical into digital electric signal of the DAE and transfers data to the PC.



ET3DV6 ISOTROPIC E-FIELD PROBE

CONSTRUCTION Symmetrical design with triangular core.

Built-in optical fiber for surface detection system.

Built-in shielding against static charges.

PEEK enclosure material (resistant to organic solvents, e.g.,

glycolether).

FREQUENCY 10MHz to 3GHz; Linearity: ± 0.2dB (30MHz to 3GHz)

DYNAMIC RANGE 5μ W/g to > 100mW/g; Linearity: \pm 0.2dB

OPTICAL SURFACE DETECTION

± 0.2mm repeatability in air and clear liquids over diffuse

reflecting surfaces

DIMENSIONS Overall length: 330mm (Tip Length: 16.0mm)

Tip diameter: 6.8mm (Body diameter: 12.0mm)
Distance from probe tip to dipole centers: 2.7mm

APPLICATION General dosimetric measurements up to 3GHz

Compliance tests of GSM Tri-band Digital Mobile Phones Fast automatic scanning in arbitrary phantoms (ET3DV6)

NOTE: 1. The Probe parameters have been calibrated by the SPEAG. Please reference "APPENDIX D" for the Calibration Certification Report.

- 2. For frequencies above 800MHz, calibration in a rectangular wave-guide is used, because wave-guide size is manageable.
- 3. For frequencies below 800MHz, temperature transfer calibration is used because the wave-guide size becomes relatively large.

TWIN SAM V4.0

CONSTRUCTION The shell corresponds to the specifications of the Specific

Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-2003, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three

points with the robot.

SHELL THICKNESS 2 ± 0.2mm

FILLING VOLUME Approx. 25liters

DIMENSIONS Height: 810mm; Length: 1000mm; Width: 500mm



SYSTEM VALIDATION KITS:

CONSTRUCTION Symmetrical dipole with I/4 balun

Enables measurement of feedpoint impedance with NWA Matched for use near flat phantoms filled with brain simulating

solutions

Includes distance holder and tripod adaptor

CALIBRATION Calibrated SAR value for specified position and input power at

the flat phantom in brain simulating solutions

FREQUENCY 900, 1800, 1900, 2450MHz

RETURN LOSS > 20dB at specified validation position

POWER CAPABILITY > 100W (f < 1GHz); > 40W (f > 1GHz)

OPTIONS Dipoles for other frequencies or solutions and other calibration

conditions upon request

DEVICE HOLDER FOR SAM TWIN PHANTOM

CONSTRUCTION The device holder for the GSM900/DCS1800/PCS1900

GSM/GPRS/CDMA Mobile Phone device is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles. The holder has been made out of

low-loss POM material having the following dielectric

parameters: relative permittivity ε =3 and loss tangent δ =0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered. The device holder for the portable device makes up of the polyethylene foam. The dielectric parameters of

material close to the dielectric parameters of the air.



DATA ACQUISITION ELECTRONICS

CONSTRUCTION

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplex, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe is mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.

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2.4 GENERAL DESCRIPTION OF THE SPATIAL PEAK SAR EVALUATION

The DASY4 post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the micro-volt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Norm_i, a_{i0}, a_{i1}, a_{i2}

- Conversion factor ConvF_i

- Diode compression point dcp_i

Device parameters: - Frequency F

- Crest factor Cf

Media parameters: - Conductivity σ

- Density ρ

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \bullet \frac{cf}{dcp_i}$$

 V_i =compensated signal of channel i (i = x, y, z)

 U_i =input signal of channel I (i = x, y, z)

Cf =crest factor of exciting field (DASY parameter)
dcp_i =diode compression point (DASY parameter)



From the compensated input signals the primary field data for each channel can be evaluated:

E-fieldprobes:
$$E_i = \sqrt{\frac{V_1}{Norm_i \cdot ConvF}}$$

H-fieldprobes:
$$H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

 V_i =compensated signal of channel I (i = x, y, z)

Norm_i = sensor sensitivity of channel i μ V/(V/m)2 for E- (i = x, y, z)

field Probes

ConvF = sensitivity enhancement in solution

a_{ii} = sensor sensitivity factors for H-field probes

F = carrier frequency [GHz]

E_i = electric field strength of channel i in V/m H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1'000}$$

SAR = local specific absorption rate in mW/g

 E_{tot} = total field strength in V/m

 σ = conductivity in [mho/m] or [Siemens/m]

ρ = equivalent tissue density in g/cm3



Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid. The entire evaluation of the spatial peak values is performed within the Post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- 1. The extraction of the measured data (grid and values) from the Zoom Scan
- 2. The calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- 3. The generation of a high-resolution mesh within the measured volume
- 4. The interpolation of all measured values from the measurement grid to the high-resolution grid
- 5. The extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- 6. The calculation of the averaged SAR within masses of 1g and 10g.

The probe is calibrated at the center of the dipole sensors that is located 1 to 2.7mm away from the probe tip. During measurements, the probe stops shortly above the phantom surface, depending on the probe and the surface detecting system. Both distances are included as parameters in the probe configuration file. The software always knows exactly how far away the measured point is from the surface. As the probe cannot directly measure at the surface, the values between the deepest measured point and the surface must be extrapolated. The angle between the probe axis and the surface normal line is less than 30 degree.

In the Area Scan, the gradient of the interpolation function is evaluated to find all the extreme of the SAR distribution. The uncertainty on the locations of the extreme is less than 1/20 of the grid size. Only local maximum within -2dB of the global maximum are searched and passed for the Cube Scan measurement. In the Cube Scan, the interpolation function is used to extrapolate the Peak SAR from the lowest measurement points to the inner phantom surface (the extrapolation distance). The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1g and 10g cubes, the extrapolation distance should not be larger than 5mm.



The maximum search is automatically performed after each area scan measurement. It is based on splines in two or three dimensions. The procedure can find the maximum for most SAR distributions even with relatively large grid spacing. After the area scanning measurement, the probe is automatically moved to a position at the interpolated maximum. The following scan can directly use this position for reference, e.g., for a finer resolution grid or the cube evaluations. The 1g and 10g peak evaluations are only available for the predefined cube 7 x 7 x 7 scans. The routines are verified and optimized for the grid dimensions used in these cube measurements. The measured volume of 30 x 30 x 30mm contains about 30g of tissue. The first procedure is an extrapolation (incl. boundary correction) to get the points between the lowest measured plane and the surface. The next step uses 3D interpolation to get all points within the measured volume in a 1mm grid (42875 points). In the last step, a 1g cube is placed numerically into the volume and its averaged SAR is calculated. This cube is the moved around until the highest averaged SAR is found. If the highest SAR is found at the edge of the measured volume, the system will issue a warning: higher SAR values might be found outside of the measured volume. In that case the cube measurement can be repeated, using the new interpolated maximum as the center.



3. DESCRIPTION OF SUPPORT UNITS

The EUT has been tested as an independent unit together with other necessary accessories or support units. The following support units or accessories were used to form a representative test configuration during the tests.

NO.	PRODUCT	BRAND	MODEL NO.	SERIAL NO.	CALIBRATED UNTIL
1	NJZ-2000 (GSM+WCDMA simulator)	JRC	NJZ-2000	ET00054	Sep. 05, 2007
2	Universal Radio Communication Tester	R&S	CMU200	104958	Apr. 11, 2007

NO.	SIGNAL CABLE DESCRIPTION OF THE ABOVE SUPPORT UNITS			
1	NA			
2	NA			

NOTE: All power cords of the above support units are non shielded (1.8m).



4. DESCRIPTION OF TEST POSITION

4.1 DESCRIPTION OF TEST POSITION

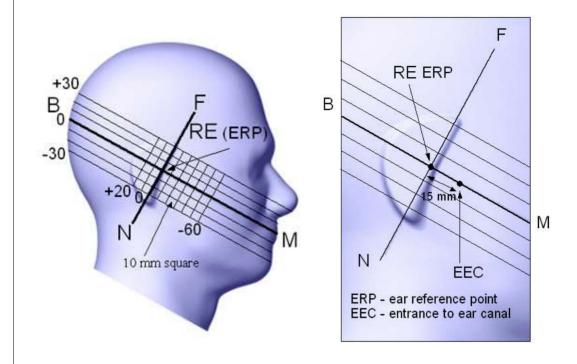
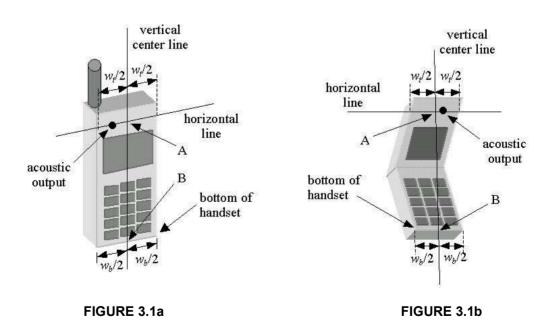


FIGURE 3.1

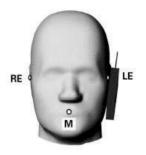


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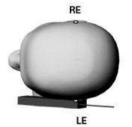


4.1.1 TOUCH/CHEEK TEST POSITION

The head position in Figure 3.1, the ear reference points ERP are 15mm above entrance to ear canal along the B-M line. The line N-F (Neck-Front) is perpendicular to the B-M (Back Mouth) line. The handset device in Figure 3.1a and 3.1b, The vertical centerline pass through two points on the front side of handset: the midpoint of the width wt of the handset at the level of the acoustic output (point A) and the midpoint of the width Wb of the bottom of the handset (point B). The vertical centerline is perpendicular to the horizontal line and pass through the center of the acoustic output. The point A touches the ERP and the vertical centerline of the handset is parallel to the B-M line. While maintaining the point A contact with the ear(ERP), rotate the handset about the line NF until any point on handset is in contact with the cheek of the phantom







TOUCH/CHEEK POSITION FIGURE

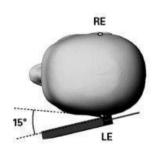


4.1.2 TILT TEST POSITION

Adjust the device in the cheek position. While maintaining a point of the handset contact in the ear, move the bottom of the handset away from the mouth by an angle of 15 degrees.







TILT POSITION FIGURE

4.1.3 BODY-WORN CONFIGURATION

The handset device attached the belt clip or the holster. The keypad face of the handset is against with the bottom of the flat phantom face and the bottom of the keypad face contact to the bottom of the flat phantom.

When multiple accessories that do not contain metallic components are supplied with the device, the device may be tested with only the accessory that dictates the closest spacing to the body. When multiple accessories that contain metallic components are supplied with the device, the device must be tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (e.g., the same metallic belt-clip used with different holsters with no other metallic components), only accessory that dictates the closest spacing to the body must be tested.



4.2 DESCRIPTION OF TEST MODE

The tested channel of each test item is selected from the worst case of original report.

The EUT of this mode is with Video telephone, without CCD camera:

TEST MODE	COMMUNICATION MODE	MODULATION TECHNOLOGY	ASSESSMENT POSTITION	TESTED CHANNEL
1	CCMOEO	GSM	A / Cheek	Н
2	GSM850	GPRS	С	Н
3	D004000	GSM	B / Tilt	L
4	PCS1900	GPRS	С	L
5		WCDMA	A / Cheek	L, M, H
6		WCDMA	A / Tilt	L, M, H
7	WCDMA1900	WCDMA	B / Cheek	L, M, H
8		WCDMA	B / Tilt	L, M, H
13		WCDMA	С	L, M, H
15	802.11b	DSSS	С	L
16	Bluetooth	FHSS	A / Cheek	М

NOTE: Assessment position A: Right head position, B: Left head position, C: Body position, please refer to appendix E for the photo.

The EUT of this mode is without Video telephone, with CCD camera:

TEST MODE	COMMUNICATION MODE	MODULATION TECHNOLOGY	ASSESSMENT POSTITION	TESTED CHANNEL
9		WCDMA	A / Cheek	L, M, H
10		WCDMA	A / Tilt	L, M, H
11	WCDMA1900	WCDMA	B / Cheek	L, M, H
12		WCDMA	B / Tilt	L, M, H
14		WCDMA	С	L, M, H

NOTE: Assessment position A: Right head position, B: Left head position, C: Body position, please refer to appendix E for the photo.



4.3 SUMMARY OF TEST RESULTS

The EUT of this mode is with Video telephone, without CCD camera:

The Lot of this mode is with vides telephone; without Gob cumera.						
COMMUNICATION MODE	GSM	1 850	PCS1900			
		MEASURED VALUE OF 1g SAR (W/kg)				
CHANNEL	HEAD BODY (RIGHT / CHEEK)		HEAD (LEFT / TILT)	BODY		
LOW			0.593	0.443		
MIDDLE	-	-	-	-		
HIGH	0.348	0.599	-	-		

COMMUNICATIO -N MODE	WCDMA 1900					
		MEASURED VALUE OF 1g SAR (W/kg)				
	HEAD / RIGHT HEAD / LEFT				DODY	
CHANNEL	CHEEK	TILT	CHEEK	TILT	BODY	
LOW	0.644	1.020	0.710	0.945	0.682	
MIDDLE	0.593	0.922	0.634	0.850	0.585	
HIGH	0.630	0.985	0.647	0.849	0.577	

NOTE: The worst value has been marked by boldface.

COMMUNICATION MODE	802.11b	BLUETOOTH			
	MEASURED VALUE	MEASURED VALUE OF 1g SAR (W/kg)			
CHANNEL	BODY	HEAD (RIGHT / TILT)			
LOW	0.156	-			
MIDDLE	-	0.00297			
HIGH	-	-			



The EUT of this mode is without Video telephone, with CCD camera:

COMMUNICATIO -N MODE	WCDMA 1900					
		MEASURED VALUE OF 1g SAR (W/kg)				
	HEAD / RIGHT HEAD / LEFT				BODY	
CHANNEL	CHEEK	TILT	CHEEK	TILT	BODY	
LOW	0.586	0.929	0.645	0.859	0.607	
MIDDLE	0.609	0.947	0.651	0.872	0.593	
HIGH	0.613	0.960	0.630	0.827	0.546	



5. TEST RESULTS

5.1 TEST PROCEDURES

The EUT (Pocket PC Phone) makes a phone call to the GSM base station. Establish the simulation communication configuration rather the actual communication. Then the EUT could continuous the transmission mode. Adjust the PCL of the base station could controlled the EUT to transmitted the maximum output power. The base station also could control the transmission channel. The SAR value was calculated via the 3D spline interpolation algorithm that has been implemented in the software of DASY4 SAR measurement system manufactured and calibrated by SPEAG. According to the IEEE 1528, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Verification of the power reference measurement
- Area scan
- Zoom scan
- Power reference measurement

The area scan with 15mm x 15mm grid was performed for the highest spatial SAR location. Consist of 11×13 points while the scan size is the 150mm x 180mm. The zoom scan with 30mm x 30mm x 30mm volume was performed for SAR value averaged over 1g and 10g spatial volumes.



In the zoom scan, the distance between the measurement point at the probe sensor location (geometric center behind the probe tip) and the phantom surface is 4.0mm and maintained at a constant distance of ± 1.0 mm during a zoom scan to determine peak SAR locations. The distance is 4mm between the first measurement point and the bottom surface of the phantom. The secondary measurement point to the bottom surface of the phantom is with 9mm separation distance. The cube size is 7 x 7 x 7 points consist of 343 points and the grid space is 5mm.

The measurement time is 0.5s at each point of the zoom scan. The probe boundary effect compensation shall be applied during the SAR test. Because of the tip of the probe to the Phantom surface separated distances are longer than half a tip probe diameter.

In the area scan, the separation distance is 4mm between the each measurement point and the phantom surface. The scan size shall be included the transmission portion of the EUT. The measurement time is the same as the zoom scan. At last the reference power drift shall be less than $\pm 5\%$.



5.2 MEASURED SAR RESULTS

GSM850 BAND HEAD POSITION

ENVIR	RONMEN DITION			Air Temperature:22.8°C, Liquid Temperature:21.9°C Humidity:55%RH							
TESTI	ED BY		Sam O	nn		DATE		Sep. 05,	2006		
	FREQ.		LATION	CONDUCTED POWER (W)		POWER	DEVICE USE	TEST	MEASURED		
CHAN.	(MHz)	TECHN	IOLOGY	BEGIN TEST	AFTER TEST	DRIFT (%)	POWER	MODE ITEM	1g SAR (W/kg)		
251	251 848.8 GSM			1.449	1.436	-0.92	Standard Battery	1	0.348		

GSM850 BAND BODY POSITION

	RONMEN DITION			nperature:: ty:57%RH		id Te	empera	nture:21.1°C	;		
TEST	ED BY		Sam O	nn			DATE		Sep. 05, 2006		
CHAN.	FREQ.	MODU	LATION	CONDUCTE	CONDUCTED POWER (W)			DEVICE USE	TEST MODE	MEASURED 1g SAR	
CHAN.	(MHz)	TECHN	IOLOGY	BEGIN TEST	AFTER TEST		FT (%)	POWER	ITEM	(W/kg)	
251	848.8 (High) GPRS			1.406	1.387	i	1.36	Standard Battery	2	0.599	

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



PCS1900 BAND HEAD POSITION

ENVIF	RONMEN DITION			Air Temperature:22.5°C, Liquid Temperature:21.3°C Humidity:60%RH							
TEST	TESTED BY			Sam Onn					Sep. 06,	2006	
CHAN.	FREQ.		LATION	CONDUCTED	POWER (W)		WER	DEVICE USE	TEST MODE	MEASURED 1g SAR	
	(MHz)	TECHN	IOLOGY	BEGIN TEST	AFTER TEST		FT (%)	POWER	ITEM	(W/kg)	
512	1850.2 (Low)	G	SM	0.708	0.700		1.15	Standard Battery	3	0.593	

PCS1900 BAND BODY POSITION

ENVIR	RONMEN DITION			Air Temperature:22.7°C, Liquid Temperature:21.7°C Humidity:63%RH							
TESTI	ED BY		Sam O	nn		DATE		Sep. 06, 2006			
	FREQ.	MODU	LATION	CONDUCTED	POWER (W)	POWER	DEVICE USE	TEST	MEASURED		
CHAN.	(MHz)	TECHN	IOLOGY	BEGIN TEST	AFTER TEST	DRIFT (%)	POWER	MODE ITEM	1g SAR (W/kg)		
512	512 1850.2 GPRS			0.690	0.679	-153	Standard Battery	4	0.443		

- 1. Test configuration of each mode is described in section 3.
- $2. \quad \text{In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.} \\$
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



WCDMA1900 BAND RIGHT HEAD POSITION

ENVIR	RONMEN DITION	TAL		nperature:2 ty:60%RH		id Te	empera	iture:21.3°C	;		
TESTI	ED BY		Sam Onn				DATE		Sep. 06, 2006		
	FREQ. MODUL		LATION	CONDUCTED PO		POWER		DEVICE USE	TEST	MEASURED	
CHAN.	(MHz)	TECHNOLOGY		BEGIN TEST	AFTER TEST		FT (%)	POWER	MODE ITEM	1g SAR (W/kg)	
9262	1852.4 (Low)	wc	DMA	0.226	0.225	-1	0.37	Standard Battery	5	0.644	
9400	1880.0 (Mid.)	wc	DMA	0.225	0.224	1	0.58	Standard Battery	5	0.593	
9538	1907.6 (High)	wc	DMA	0.228	0.226	1	0.78	Standard Battery	5	0.630	
9262	1852.4 (Low)	wc	DMA	0.226	0.224	-1	0.97	Standard Battery	6	1.020	
9400	1880.0 (Mid.)	wc	DMA	0.225	0.223	-1	0.69	Standard Battery	6	0.922	
9538	1907.6 (High)	wc	DMA	0.228	0.226	-1	0.92	Standard Battery	6	0.985	

- 1. Test configuration of each mode is described in section 3.
- $2. \quad \text{In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.} \\$
- ${\it 3.} \quad {\it Please see} \ the \ {\it Appendix} \ {\it A for the data, and Appendix E} \ for \ the \ photo \ of \ the \ test \ configuration.$
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



WCDMA1900 BAND LEFT HEAD POSITION

ENVIR	RONMEN	TAL		nperature:2 ty:60%RH	•	id Te	empera	ture:21.3°C	;		
TESTI	TESTED BY			nn		DATE			Sep. 06, 2006		
	FREQ.	MODU	LATION	CONDUCTED	CONDUCTED POWER (W)		WER	DEVICE USE	TEST	MEASURED	
CHAN.	(MHz)	TECHNOLOGY		BEGIN TEST	AFTER TEST	DRII	FT (%)	POWER	MODE ITEM	1g SAR (W/kg)	
9262	1852.4 (Low)	wc	DMA	0.226	0.224	-(0.76	Standard Battery	7	0.710	
9400	1880.0 (Mid.)	wc	DMA	0.225	0.223	-(0.87	Standard Battery	7	0.634	
9538	1907.6 (High)	wc	DMA	0.228	0.226	-(0.96	Standard Battery	7	0.647	
9262	1852.4 (Low)	wc	DMA	0.226	0.225	-(0.63	Standard Battery	8	0.945	
9400	1880.0 (Mid.)	wc	DMA	0.225	0.223	-(0.75	Standard Battery	8	0.850	
9538	1907.6 (High)	wc	DMA	0.228	0.225		1.15	Standard Battery	8	0.849	

- 1. Test configuration of each mode is described in section 3.
- $2. \quad \text{In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.} \\$
- ${\it 3.} \quad {\it Please see} \ the \ {\it Appendix} \ {\it A for the data, and Appendix E} \ for \ the \ photo \ of \ the \ test \ configuration.$
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



WCDMA1900 BAND RIGHT HEAD POSITION

ENVIR	RONMEN	TAL		nperature:2 ty:60%RH	•	id Te	empera	iture:21.3°C	;	
TESTI	TESTED BY			nn		DATE			Sep. 09,	2006
	FREQ.	MODU	LATION	CONDUCTED POWER (W)		PO	WER	DEVICE USE	TEST	MEASURED
CHAN.	(MHz)	TECHNOLOGY		BEGIN TEST	AFTER TEST	DRI	FT (%)	POWER	MODE ITEM	1g SAR (W/kg)
9262	1852.4 (Low)	wc	DMA	0.226	0.225	-1	0.36	Standard Battery	9	0.586
9400	1880.0 (Mid.)	wc	DMA	0.225	0.224	-1	0.48	Standard Battery	9	0.609
9538	1907.6 (High)	wc	DMA	0.228	0.227	1	0.46	Standard Battery	9	0.613
9262	1852.4 (Low)	wc	DMA	0.226	0.225	-1	0.41	Standard Battery	10	0.939
9400	1880.0 (Mid.)	wc	DMA	0.225	0.224	-1	0.58	Standard Battery	10	0.947
9538	1907.6 (High)	wc	DMA	0.228	0.226	-1	0.66	Standard Battery	10	0.960

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



WCDMA1900 BAND LEFT HEAD POSITION

ENVIR	RONMEN	TAL		nperature:2 ty:60%RH	•	id Te	empera	ture:21.3°C	;	
TESTI	TESTED BY			nn		DATE			Sep. 09,	2006
	FREQ.	MODU	LATION	CONDUCTED PO		POWER		DEVICE USE	TEST	MEASURED
CHAN.	(MHz)	TECHNOLOGY		BEGIN TEST	AFTER TEST	DRI	FT (%)	POWER	MODE ITEM	1g SAR (W/kg)
9262	1852.4 (Low)	wc	DMA	0.226	0.225	-1	0.31	Standard Battery	11	0.645
9400	1880.0 (Mid.)	wc	DMA	0.225	0.224	-1	0.63	Standard Battery	11	0.651
9538	1907.6 (High)	wc	DMA	0.228	0.226	-1	0.75	Standard Battery	11	0.630
9262	1852.4 (Low)	wc	DMA	0.226	0.224	-1	0.82	Standard Battery	12	0.859
9400	1880.0 (Mid.)	WCDMA		0.225	0.223	-1	0.93	Standard Battery	12	0.872
9538	1907.6 (High)	wc	DMA	0.228	0.226	*	1.08	Standard Battery	12	0.827

- 1. Test configuration of each mode is described in section 3.
- $2. \quad \text{In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.} \\$
- ${\it 3.} \quad {\it Please see} \ the \ {\it Appendix} \ {\it A for the data, and Appendix E} \ for \ the \ photo \ of \ the \ test \ configuration.$
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



WCDMA1900 BAND BODY POSITION

	RONMEN DITION		Air Temperature:22.7°C, Liquid Temperature:21.7°C Humidity:63%RH								
TESTI	ED BY		Sam Onn				DATE		Sep. 07, 2006		
CHAN	FREQ. MODU		LATION	CONDUCTED	POWER (W)	PO	WER	DEVICE USE	TEST	MEASURED	
CHAN.	(MHz)	TECHN	IOLOGY	BEGIN TEST	AFTER TEST	DRIFT (%)		POWER	MODE ITEM	1g SAR (W/kg)	
9262	1852.4 (Low)	wc	DMA	0.226	0.225	-(0.25	Standard Battery	13	0.682	
9400	1880.0 (Mid.)	wc	DMA	0.225	0.224	-(0.37	Standard Battery	13	0.585	
9538	1907.6 (High)	wc	DMA	0.228	0.226	-(0.69	Standard Battery	13	0.577	

- 1. Test configuration of each mode is described in section 3.
- 2. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



WCDMA1900 BAND BODY POSITION

ENVIR	RONMEN DITION	TAL	Air Temperature:22.7°C, Liquid Temperature:21.7°C Humidity:63%RH									
TEST	ED BY		Sam O	nn		DATE			Sep. 10,	2006		
CUAN	CUAN FREQ. MODU		LATION	CONDUCTED	POWER (W)	PO	WER	DEVICE USE	TEST	MEASURED		
CHAN.	(MHz)	TECHN	IOLOGY	BEGIN TEST	AFTER TEST	DRIFT (%)		POWER	MODE ITEM	1g SAR (W/kg)		
9262	1852.4 (Low)	wc	DMA	0.226	0.225	-().64	Standard Battery	14	0.607		
9400	1880.0 (Mid.)	wc	DMA	0.225	0.223	-().86	Standard Battery	14	0.593		
9538	1907.6 (High)	wc	DMA	0.228	0.226	-().79	Standard Battery	14	0.546		

- 5. Test configuration of each mode is described in section 3.
- 6. In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.
- 7. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 8. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



802.11b BAND BODY POSITION

ENVIF	RONMEN DITION			Air Temperature:22.6°C, Liquid Temperature:21.7°C Humidity:61%RH							
TEST	ED BY		Sam O	nn			DATE		Sep. 05, 2006		
CHAN	FREQ.	MODU	CONDUCTE (m)		ED POWER NW)	PO	WER	DEVICE USE	TEST	MEASURED	
CHAN.	(MHz)	TECHN	IOLOGY	BEGIN TEST AFTER TEST			FT (%)	POWER	MODE ITEM	1g SAR (W/kg)	
1	2412.0 (Low)	DS	SSS	31.769	31.556	-1	0.67	Standard Battery	15	0.156	

BLUETOOTH BAND HEAD POSITION

ENVIF	RONMEN DITION		Air Temperature:22.3°C, Liquid Temperature:21.2°C Humidity:63%RH							
TESTI	ED BY		Sam O	nn		DATE		Sep. 05, 2006		
	FREQ.	MODU	LATION	CONDUCTED POWER (W)		POWER	DEVICE USE	TEST	MEASURED	
CHAN.	(MHz)	TECHN	IOLOGY	BEGIN TEST	AFTER TEST	DRIFT (%)	POWER	MODE ITEM	1g SAR (W/kg)	
39	2441.0 (Mid.)	FH	ISS	0.881	0.873	-0.91	Standard Battery	16	0.00297	

- 1. Test configuration of each mode is described in section 3.
- $2. \quad \text{In this testing, the limit for General Population Spatial Peak averaged over 1g, 1.6W/kg, is applied.} \\$
- 3. Please see the Appendix A for the data, and Appendix E for the photo of the test configuration.
- 4. The variation of the EUT conducted power measured before and after SAR testing should not over 5%.



5.3 SAR LIMITS

	SAR (W/kg)	
HUMAN EXPOSURE	(General Population / Uncontrolled Exposure Environment)	(Occupational / controlled Exposure Environment)
Spatial Average (whole body)	0.08	0.4
Spatial Peak (averaged over 1 g)	1.6	8.0
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

NOTE: 1. This limits accord to 47 CFR 2.1093 – Safety Limit.

2. The EUT property been complied with the partial body exposure limit under the general population environment.



5.4 RECIPES FOR TISSUE SIMULATING LIQUIDS

For the measurement of the field distribution inside the SAM phantom, the phantom must be filled with 25 litters of tissue simulation liquid.

The following ingredients are used:

• WATER- Deionized water (pure H20), resistivity _16 M - as basis for the liquid

• **SUGAR-** Refined sugar in crystals, as available in food shops - to reduce relative

permittivity

• SALT- Pure NaCl - to increase conductivity

• **CELLULOSE-** Hydroxyethyl-cellulose, medium viscosity (75-125mPa.s, 2% in water,

20_C),

CAS # 54290 - to increase viscosity and to keep sugar in solution

• PRESERVATIVE- Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS # 55965-84-9 - to

prevent the spread of bacteria and molds

• **DGMBE-** Diethylenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH,

CAS # 112-34-5 - to reduce relative permittivity

THE RECIPES FOR 900MHz SIMULATING LIQUID TABLE

INGREDIENT	HEAD SIMULATING LIQUID 900MHz (HSL-900)	MUSCLE SIMULATING LIQUID 900MHz (MSL-900)
Water	40.28%	50.07%
Cellulose	02.41%	NA
Salt	01.38%	0.94%
Preventtol D-7	00.18%	0.09%
Sugar	57.97%	48.2%
Dielectric Parameters at 22°C	f = 900MHz $ε = 41.5 \pm 5\%$ $σ = 0.97 \pm 5\%$ S/m	f= 900MHz ε= 55.0 ± 5% σ = 1.05 ± 5% S/m



THE RECIPES FOR 1900MHz SIMULATING LIQUID TABLE

INGREDIENT	HEAD SIMULATING LIQUID 1900MHz (HSL-1900)	MUSCLE SIMULATING LIQUID 1900MHz (MSL-1900)
Water	55.24%	70.16%
DGMBE	44.45%	29.44%
Salt	0.306%	00.39%
Dielectric Parameters at 22°C	f= 1900MHz ε= 40.0 ± 5% σ = 1.40 ± 5% S/m	f= 1900MHz ε= 53.3 \pm 5% σ= 1.52 \pm 5% S/m

THE RECIPES FOR 2450MHz SIMULATING LIQUID TABLE

INGREDIENT	HEAD SIMULATING LIQUID 2450MHz (HSL-2450)	MUSCLE SIMULATING LIQUID 2450MHz (MSL-2450)
Water	45%	69.83%
DGMBE	55%	30.17%
Salt	NA	NA
Dielectric Parameters at 22℃	f= 2450MHz ε= 39.2 ± 5% σ = 1.80 ± 5% S/m	f= 2450MHz ε= 52.7 ± 5% σ= 1.95 ± 5% S/m



Testing the liquids using the Agilent Network Analyzer E8358A and Agilent Dielectric Probe Kit 85070D. The testing procedure is following as

- 1. Turn Network Analyzer on and allow at least 30 min. warm up.
- 2. Mount dielectric probe kit so that interconnecting cable to Network Analyzer will not be moved during measurements or calibration.
- 3. Pour de-ionized water and measure water temperature (±1°).
- 4. Set water temperature in Agilent-Software (Calibration Setup).
- 5. Perform calibration.
- 6. Validate calibration with dielectric material of known properties (e.g. polished ceramic slab with >8mm thickness ϵ '=10.0, ϵ "=0.0). If measured parameters do not fit within tolerance, repeat calibration (±0.2 for ϵ ': ±0.1 for ϵ ").
- 7. Conductivity can be calculated from ε'' by $\sigma = \omega \varepsilon_0 \varepsilon'' = \varepsilon'' f [GHz] / 18.$
- 8. Measure liquid shortly after calibration. Repeat calibration every hour.
- 9. Stir the liquid to be measured. Take a sample (~50ml) with a syringe from the center of the liquid container.
- 10. Pour the liquid into a small glass flask. Hold the syringe at the bottom of the flask to avoid air bubbles.
- 11. Put the dielectric probe in the glass flask. Check that there are no air bubbles in front of the opening in the dielectric probe kit.
- 12. Perform measurements.
- 13. Adjust medium parameters in DASY4 for the frequencies necessary for the measurements ('Setup Config', select medium (e.g. Brain 900MHz) and press 'Option'-button.

Select the current medium for the frequency of the validation (e.g. Setup Medium Brain 900MHz).



FOR GSM850 BAND SIMULATING LIQUID

LIQUID T	TYPE	HSL-850		MSL-850	
SIMULATING LIQUID TEMP.		21	1.9	21.1	
TESTED	DATE	Sep. 0	5, 2006	Sep. 0	5, 2006
TESTED	BY	Sam	Onn	Sam	n Onn
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE
824.2		41.556	41.500	55.242	54.600
835.0	Permitivity	41.500	41.400	55.200	54.100
836.6	(ε)	41.500	41.400	55.195	54.100
848.8		41.500	41.300	55.157	53.900
824.2	0	0.899	0.890	0.969	0.930
835.0	Conductivity	0.900	0.900	0.970	0.940
836.6	(σ) S/m	0.901	0.900	0.972	0.940
848.8	0/111	0.914 0.900		0.987	0.950
Dielectric Parameters Required at 22℃		f= 900MHz ε= 41.5 ± 5% σ= 0.97 ± 5% S/m		ε= 55.	0MHz 0 ± 5% ± 5% S/m



FOR PCS1900 BAND SIMULATING LIQUID

LIQUID T	YPE	HSL-	-1900	MSL	-1900
SIMULATING LIQUID TEMP.		21	1.3	21.7	
TESTED	DATE	Sep. 0	6, 2006	Sep. 0	6, 2006
TESTED	BY	Sam	Onn	Sam	ı Onn
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE
1850.2		40.0	40.9	53.3	54.5
1880.0	Permitivity	40.0	40.8	53.3	54.4
1900.0	(ε)	40.0	40.7	53.3	54.4
1909.8		40.0	40.7	53.3	54.4
1850.2	O a ra al constitucito c	1.40	1.35	1.52	1.50
1880.0	Conductivity	1.40	1.38	1.52	1.54
1900.0	(σ) S/m	1.40	1.41	1.52	1.57
1909.8	0/111	1.40	1.42	1.52	1.58
Dielectric Parameters Required at 22℃		f= 1900MHz ε= 40.0 ± 5% σ= 1.40 ± 5% S/m		ε= 53.	00MHz 3 ± 5% ± 5% S/m



FOR WCDMA1900 BAND SIMULATING LIQUID

LIQUID T	YPE	HSL-	-1900	MSL-1900	
SIMULAT	TING LIQUID	2′	1.3	21.7	
TESTED	DATE	Sep. 0	6, 2006	Sep. 0	6, 2006
TESTED	BY	Sam	Onn	Sam	Onn
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE
1852.4		40.0	40.9	53.3	54.5
1880.0	Permitivity	40.0	40.8	53.3	54.4
1900.0	(ε)	40.0	40.7	53.3	54.4
1907.6		40.0	40.7	53.3	54.4
1852.4	0	1.40	1.35	1.52	1.50
1880.0	Conductivity	1.40	1.38	1.52	1.54
1900.0	(σ) S/m	1.40	1.41	1.52	1.57
1907.6	3/111	1.40 1.42		1.52	1.58
Dielectric Parameters Required at 22℃		ε= 40.	00MHz 0 ± 5% ± 5% S/m	ε= 53.	00MHz 3 ± 5% ± 5% S/m

Note: The EUT of this mode is with Video telephone, without CCD camera:



FOR WCDMA1900 BAND SIMULATING LIQUID

LIQUID T	YPE	HSL-	-1900	MSL-1900	
SIMULATING LIQUID TEMP.		21	1.0	21.5	
TESTED	DATE	Sep. 09	9, 2006	Sep. 1	0, 2006
TESTED	BY	Sam	Onn	Sam	Onn
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE
1852.4		40.0	41.4	53.3	54.4
1880.0	Permitivity	40.0	41.3	53.3	54.2
1900.0	(ε)	40.0	41.2	53.3	54.2
1907.6		40.0	41.1	53.3	54.1
1852.4	O a ra al constitucito c	1.40	1.36	1.52	1.51
1880.0	Conductivity (σ)	1.40	1.39	1.52	1.55
1900.0	(♂) S/m	1.40	1.42	1.52	1.58
1907.6	O/III	1.40 1.43		1.52	1.59
Dielectric Parameters Required at 22℃		f= 1900MHz ε= 40.0 ± 5% σ= 1.40 ± 5% S/m		ε= 53.	00MHz 3 ± 5% ± 5% S/m

Note: The EUT of this mode is without Video telephone, with CCD camera:



FOR 2.4GHz BAND SIMULATING LIQUID

LIQUID T	YPE	HSL-	-2450	MSL-2450	
SIMULAT	TING LIQUID	NA		21.7	
TEST DA	ATE .	N	IA	Sep. 0	5, 2006
TESTED	BY	N	IA	Sam	Onn
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE
2412.0		NA	NA	52.75	52.80
2437.0	Permitivity	NA	NA	52.71	52.70
2450.0	(ε)	NA	NA	52.70	52.70
2462.0		NA	NA	52.68	52.60
2412.0	O a ra di catin situ s	NA	NA	1.913	1.940
2437.0	Conductivity (σ)	NA	NA	1.937	1.980
2450.0	S/m	NA	NA	1.950	2.00
2462.0	O/III	NA NA		1.967	2.01
Dielectric Parameters Required at 22℃		f= 2450MHz ε= 39.2 ± 5% σ= 1.80 ± 5% S/m		ε= 52.	50MHz 7 ± 5% ± 5% S/m



FOR BLUETOOTH BAND SIMULATING LIQUID

LIQUID T	YPE	HSL-2450		MSL-2450	
SIMULAT	EIMULATING LIQUID 21.2		1.2	NA	
TEST DA	ATE .	Sep. 0	5, 2006	1	NA .
TESTED	BY	Sam	ı Onn	١	NA .
FREQ. (MHz)	LIQUID PARAMETER	STANDARD VALUE	MEASUREMENT VALUE	STANDARD VALUE	MEASUREMENT VALUE
2402.0		39.28	40.00	NA	NA
2441.0	Permitivity	39.21	39.80	NA	NA
2450.0	(ε)	39.20	39.80	NA	NA
2480.0		39.16	39.70	NA	NA
2402.0	O a ra di catin situ s	1.757	1.790	NA	NA
2441.0	Conductivity	1.792	1.840	NA	NA
2450.0	(σ) S/m	1.800	1.850	NA	NA
2480.0	0/111	1.832 1.890		NA	NA
Dielectric Parameters Required at 22℃		f= 2450MHz ε= 39.2 ± 5% σ= 1.80 ± 5% S/m		ε= 52	50MHz .7 ± 5% ± 5% S/m



5.5 TEST EQUIPMENT FOR TISSUE PROPERTY

ITEM	NAME	BAND	TYPE	SERIES NO.	CALIBRATED UNTIL
1	Network Analyzer	Agilent	E8358A	US41480538	Oct. 27, 2006
2	Dielectric Probe	Agilent	85070D	US01440176	NA

NOTE:

- 1. Before testing the measurement, all test equipment shall have 30 min warm up.
- 2. The tolerance (k=1) specified by Agilent for general dielectric measurements, deriving from inaccuracies in the calibration data, analyzer drift, and random errors, are usually ±2.5% and ±5% for measured permittivity and conductivity, respectively. However, the tolerances for the conductivity is smaller for material with large loss tangents, i.e., less than ±2.5% (k=1). It can be substantially smaller if more accurate methods are applied.



6. SYSTEM VALIDATION

The system validation was performed in the flat phantom with equipment listed in the following table. Since the SAR value is calculated from the measured electric field, dielectric constant and conductivity of the body tissue and the SAR is proportional to the square of the electric field. So, the SAR value will be also proportional to the RF power input to the system validation dipole under the same test environment. In our system validation test, 250mW RF input power was used.

6.1 TEST EQUIPMENT

ITEM	NAME	BAND	TYPE	SERIES NO.	CALIBRATED UNTIL
1	SAM Phantom	S&P	QD000 P40 CA	PT-1150	NA
2	Signal Generator	Anritsu	68247B	984703	Dec. 07, 2006
3	E-Field Probe	S&P	ET3DV6	1687	Sep. 14, 2006
4	DAE	S&P	DAE3 V1	579	Mar. 14, 2007
5	Robot Positioner	Staubli Unimation	NIΔ		NA
		S&P	D835V2	4d021	May 22, 2007
6	Validation Dipole	S&P	D1900V2	5d036	Apr. 27, 2007
		S&P	D2450V2	737	Apr. 26, 2007

NOTE: 1. Before starting the measurement, all test equipment shall be warmed up for 30min.

^{2.} System validation was performed to check the condition during each test. According to this situation, calibrated period for the validation dipole back to the original factory is one year, and the others will be two.



6.2 TEST PROCEDURE

Before you start the system performance check, need only to tell the system with which components (probe, medium, and device) are performing the system performance check; the system will take care of all parameters. The dipole must be placed beneath the flat phantom section of the SAM Twin Phantom with the correct distance holder in place. The distance holder should touch the phantom surface with a light pressure at the reference marking (little cross) and be oriented parallel to the long side of the phantom. Accurate positioning is not necessary, since the system will search for the peak SAR location, except that the dipole arms should be parallel to the surface. The device holder for Tri-Band GSM900/DCS1800/PCS1900 GSM/GPRS/CDMA Mobile Phones can be left in place but should be rotated away from the dipole.

- 1.The "Power Reference Measurement" and "Power Drift Measurement" jobs are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the amplifier output power. If it is too high (above ±0.1 dB), the system performance check should be repeated; some amplifiers have very high drift during warm-up. A stable amplifier gives drift results in the DASY system below ±0.02 dB.
- 2.The "Surface Check" job tests the optical surface detection system of the DASY system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above ± 0.1 mm). In that case it is better to abort the system performance check and stir the liquid. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within $\pm 30^{\circ}$.) However, varying breaking indices of different liquid compositions might also influence the distance. If the indicated difference varies from the actual setting, the probe parameter "optical surface



- 3. The "Area Scan" job measures the SAR above the dipole on a plane parallel to the surface. It is used to locate the approximate location of the peak SAR. The proposed scan uses large grid spacing for faster measurement; due to the symmetric field, the peak detection is reliable. If a finer graphic is desired, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result.
- 4. The "Zoom Scan" job measures the field in a volume around the peak SAR value assessed in the previous "Area Scan" job (for more information see the application note on SAR evaluation).

About the validation dipole positioning uncertainty, the constant and low loss dielectric spacer is used to establish the correct distance between the top surface of the dipole and the bottom surface of the phantom, the error component introduced by the uncertainty of the distance between the liquid (i.e., phantom shell) and the validation dipole in the DASY4 system is less than ±0.1mm.

$$SAR_{tolerance}[\%] = 100 \times (\frac{(a+d)^2}{a^2} - 1)$$

As the closest distance is 10mm, the resulting tolerance SAR_{tolerance}[%] is <2%.



6.3 VALIDATION RESULTS

	SYSTEM VALIDATION TEST OF SIMULATING LIQUID								
FREQUENCY (MHz)	REQUIRED SAR (mW/g)	MEASURED SAR (mW/g)	DEVIATION (%)	SEPARATION DISTANCE	TESTED DATE				
HSL835	2.31 (1g)	2.35	1.73	15mm	Sep. 05, 2006				
MSL835	2.45 (1g)	2.33	-4.90	15mm	Sep. 05, 2006				
HSL1900	9.61 (1g)	9.52	-0.94	10mm	Sep. 06, 2006				
MSL1900	9.96 (1g)	9.77	-1.91	10mm	Sep. 06, 2006				
HSL2450	13.30 (1g)	13.50	1.50	10mm	Sep. 05, 2006				
MSL2450	13.90 (1g)	13.90	0	10mm	Sep. 05, 2006				
TESTED BY	BY Sam Onn								

NOTE: 1. Please sees Appendix for the photo of system validation test.

2. The EUT of this mode is with Video telephone, without CCD camera.

SYSTEM VALIDATION TEST OF SIMULATING LIQUID							
FREQUENCY (MHz)	REQUIRED SAR (mW/g)	MEASURED SAR (mW/g)	DEVIATION (%)	SEPARATION DISTANCE	TESTED DATE		
HSL1900	9.61 (1g)	9.49	-1.25	10mm	Sep. 09, 2006		
MSL1900	9.96 (1g)	9.74	-2.21	10mm	Sep. 10, 2006		
TESTED BY	Sam Onn						

NOTE: 1. Please sees Appendix for the photo of system validation test.

2. The EUT of this mode is without Video telephone, with CCD camera.



6.4 SYSTEM VALIDATION UNCERTAINTIES

In the table below, the system validation uncertainty with respect to the analytically assessed SAR value of a dipole source as given in the IEEE 1528 standard is given. This uncertainty is smaller than the expected uncertainty for mobile phone measurements due to the simplified setup and the symmetric field distribution.

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(0	C _i)	Uncei	dard rtainty %)	(v _i)
	(= /3)			(1g)	(10g)	(1g)	(10g)	
		Measuremen	t System					
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	8
Axial Isotropy	4.7	Rectangular	√3	1	1	2.7	2.7	~
Hemispherical Isotropy	0	Rectangular	√3	1	1	0	0	∞
Boundary effect	1.0	Rectangular	√3	1	1	0.6	0.6	8
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	~
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	~
Response Time	0	Rectangular	√3	1	1	0	0	∞
Integration Time	0	Rectangular	√3	1	1	0	0	8
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	∞
Probe Positioner	0.4	Rectangular	√3	1	1	0.2	0.2	∞
Probe positioning	2.9	Rectangular	√3	1	1	1.7	1.7	~
Algorithms for Max. SAR Evaluation	1.0	Rectangular	√3	1	1	0.6	0.6	8
		Dipol	е					
Dipole Axis to Liquid Distance	2.0	Rectangular	√3	1	1	1.2	1.2	8
Input power and SAR drift measurement	4.7	Rectangular	√3	1	1	2.7	2.7	8
	ı	Phantom and Tiss	ue Paramet	ters				
Phantom Uncertainty	4.0	Rectangular	√3	1	1	2.3	2.3	~
Liquid Conductivity (target)	5.0	Rectangular	√3	0.64	0.43	1.8	1.2	8
Liquid Conductivity (measurement)	2.5	Normal	1	0.64	0.43	1.6	1.1	8
Liquid Permittivity (target)	5.0	Rectangular	√3	0.6	0.49	1.7	1.4	8
Liquid Permittivity (measurement)	2.5	Normal	1	0.6	0.49	1.5	1.2	8
Combined Standard Uncertainty							8.1	∞
	Coverag	e Factor for 95%				kp=2		
	Expanded	Uncertainty (K=2)				16.8	16.2	

NOTE: About the system validation uncertainty assessment, please reference the section 7.



7. MEASUREMENT SAR PROCEDURE UNCERTAINTIES

The assessment of spatial peak SAR of the hand handheld devices is according to IEEE 1528. All testing situation shall be met below these requirements.

- The system is used by an experienced engineer who follows the manual and the guidelines taught during the training provided by SPEAG.
- The probe has been calibrated within the requested period and the stated uncertainty for the relevant frequency bands does not exceed 4.8% (k=1).
- The validation dipole has been calibrated within the requested period and the system performance check has been successful.
- The DAE unit has been calibrated within the within the requested period.
- The minimum distance between the probe sensor and inner phantom shell is selected to be between 4 and 5mm.
- The operational mode of the DUT is CW, CDMA, FDMA or TDMA (GSM, DCS, PCS, IS136 and PDC) and the measurement/integration time per point is >500 ms.
- The dielectric parameters of the liquid have been assessed using Agilent 85070D dielectric probe kit or a more accurate method.
- The dielectric parameters are within 5% of the target values.
- The DUT has been positioned as described in section 3.

7.1 PROBE CALIBRATION UNCERTAINTY

SPEAG conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528, EN50361, IEC 62209, etc.) under ISO17025. The uncertainties are stated on the calibration certificate. For the most relevant frequency bands, these values do not exceed 4.8% (k=1). If evaluations of other bands are performed for which the uncertainty exceeds these values, the uncertainty tables given in the summary have to be revised accordingly.



7.2 ISOTROPY UNCERTAINTY

The axial isotropy tolerance accounts for probe rotation around its axis while the hemispherical isotropy error includes all probe orientations and field polarizations. These parameters are assessed by SPEAG during initial calibration. In 2001, SPEAG further tightened its quality controls and warrants that the maximal deviation from axial isotropy is ± 0.20 dB, while the maximum deviation of hemispherical isotropy is ± 0.40 dB, corresponding to $\pm 4.7\%$ and $\pm 9.6\%$, respectively. A weighting factor of cp equal to 0.5 can be applied, since the axis of the probe deviates less than 30 degrees from the normal surface orientation.

7.3 BOUNDARY EFFECT UNCERTAINTY

The effect can be estimated according to the following error approximation formula

$$SAR_{tolerance} [\%] = SAR_{be} [\%] \times \frac{(d_{be} + d_{step})^2}{2d_{step}} \frac{e^{-\frac{d_{be}}{\delta/2}}}{\delta/2}$$

$$d_{be} + d_{step} < 10mm$$

The parameter d_{be} is the distance in mm between the surface and the closest measurement point used in the averaging process; d_{step} is the separation distance in mm between the first and second measurement points; δ is the minimum penetration depth in mm within the head tissue equivalent liquids (i.e., δ = 13.95 mm at 3GHz); SAR_{be} is the deviation between the measured SAR value at the distance d_{be} from the boundary and the wave-guide analytical value SAR_{ref}.DASY4 applies a boundary effect compensation algorithm according to IEEE 1528, which is possible since the axis of the probe never deviates more than 30 degrees from the normal surface orientation. SAR_{be}[%] is assessed during the calibration process and SPEAG warrants that the uncertainty at distances larger than 4mm is always less than 1%.In summary, the worst case boundary effect SAR tolerance[%] for scanning distances larger than 4mm is < \pm 0.8%.



7.4 PROBE LINEARITY UNCERTAINTY

Field probe linearity uncertainty includes errors from the assessment and compensation of the diode compression effects for CW and pulsed signals with known duty cycles. This error is assessed using the procedure described in IEEE 1528. For SPEAG field probes, the measured difference between CW and pulsed signals, with pulse frequencies between 10 Hz and 1 kHz and duty cycles between 1 and 100, is $< \pm 0.20$ dB ($< \pm 4.7\%$).

7.5 READOUT ELECTRONICS UNCERTAINTY

All uncertainties related to the probe readout electronics (DAE unit), including the gain and linearity of the instrumentation amplifier, its loading effect on the probe, and accuracy of the signal conversion algorithm, have been assessed accordingly to IEEE 1528. The combination (root-sum-square RSS method) of these components results in an overall maximum error of ±1.0%.

7.6 RESPONSE TIME UNCERTAINTY

The time response of the field probes is assessed by exposing the probe to a well-controlled electric field producing SAR larger than 2.0 W/kg at the tissue medium surface. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/of switch of the power source. Analytically, it can be expressed as:

$$SAR_{tolerance} [\%] = 100 \times (\frac{T_m}{T_m + \tau e^{-T_m/\tau} - \tau} - 1)$$

where Tm is 500 ms, i.e., the time between measurement samples, and $_{\rm T}$ the time constant. The response time $_{\rm T}$ of SPEAG's probes is <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.



7.7 INTEGRATION TIME UNCERTAINTY

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization and can be assessed as follows

$$SAR_{tolerance} [\%] = 100 \times \sum_{all sub-frames} \frac{t_{frame}}{t_{\text{int egration}}} \frac{slot_{idle}}{slot_{total}}$$

The tolerances for the different systems are given in Table 7.1, whereby the worst-case $SAR_{tolerance}$ is 2.6%.

System	SAR _{tolerance} %
CW	0
CDMA*	0
WCDMA*	0
FDMA	0
IS-136	2.6
PDC	2.6
GSM/DCS/PCS	1.7
DECT	1.9
Worst-Case	2.6

TABLE 7.1



7.8 PROBE POSITIONER MECHANICAL TOLERANCE

The mechanical tolerance of the field probe positioner can introduce probe positioning uncertainties. The resulting SAR uncertainty is assessed by comparing the SAR obtained according to the specifications of the probe positioner with respect to the actual position defined by the geometric enter of the probe sensors. The tolerance is determined as:

$$SAR_{tolerance}[\%] = 100 \times \frac{d_{ph}}{\delta/2}$$

The specified repeatability of the RX robot family used in DASY4 systems is $\pm 25 \,\mu\text{m}$. The absolute accuracy for short distance movements is better than $\pm 0.1 \,\text{mm}$, i.e., the SAR_{tolerance}[%] is better than 1.5% (rectangular).

7.9 PROBE POSITIONING

The probe positioning procedures affect the tolerance of the separation distance between the probe tip and the phantom surface as:

$$SAR_{tolerance}[\%] = 100 \times \frac{d_{ph}}{\delta/2}$$

where d_{ph} is the maximum deviation of the distance between the probe tip and the phantom surface. The optical surface detection has a precision of better than 0.2 mm, resulting in an SAR_{tolerance}[%] of <2.9% (rectangular distribution). Since the mechanical detection provides better accuracy, 2.9% is a worst-case figure for DASY4 system.



7.10 PHANTOM UNCERTAINTY

The SAR measurement uncertainty due to SPEAG phantom shell production tolerances has been evaluated using

$$SAR_{tolerance}[\%] \cong 100 \times \frac{2d}{a},$$
 $d << a$

For a maximum deviation d of the inner and outer shell of the phantom from that specified in the CAD file of ± 0.2 mm, and a 10mm spacing a between source and tissue liquid, the calculated phantom uncertainty is $\pm 4.0\%$.



7.11 DASY4 UNCERTAINTY BUDGET

Error Description	Tolerance (±%)	Probability Distribution	Divisor	(C _i)		Standard Uncertainty (±%)		(V _i)
	` ,			(1g)	(10g)	(1g)	(10g)	
Measurement Equipment								
Probe Calibration	4.8	Normal	1	1	1	4.8	4.8	∞
Axial Isotropy	4.7	Rectangular	√3	1	1	1.9	1.9	∞
Hemispherical Isotropy	9.6	Rectangular	√3	1	1	3.9	3.9	∞
Boundary effect	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Linearity	4.7	Rectangular	√3	1	1	2.7	2.7	∞
System Detection Limit	1.0	Rectangular	√3	1	1	0.6	0.6	∞
Readout Electronics	1.0	Normal	1	1	1	1.0	1.0	∞
Response Time	0.8	Normal	1	1	1	0.8	0.8	∞
Integration Time	2.6	Normal	1	1	1	2.6	2.6	∞
Noise	0.0	Normal	1	0	0	0	0	∞
Mechanical Constraints								
Scanning System	0.4	Rectangular	√3	1	1	0.2	0.2	∞
Phantom Shell	4.0	Rectangular	√3	1	1	2.3	2.3	∞
Probe Positioning	2.9	Rectangular	√3	1	1	1.7	1.7	∞
Device Positioning	2.9	Normal	1	1	1	2.9	2.9	875
Physical Parameters								
Liquid Conductivity (target)	5.0	Rectangular	√3	0.7	0.5	2	1.4	∞
Liquid Conductivity (measurement)	4.3	Rectangular	√3	0.7	0.5	1.7	1.2	8
Liquid Permittivity (target)	5.0	Rectangular	√3	0.6	0.5	1.7	1.4	~
Liquid Permittivity (measurement)	4.3	Rectangular	√3	0.6	0.5	1.5	1.2	8
Power Drift	5	Rectangular	√3	1	1	2.9	2.9	∞
RF Ambient Conditions	3.0	Rectangular	√3	1	1	1.7	1.7	∞
Post-Processing								
Extrapolation and Integration	1	Rectangular	√3	1	1	0.6	0.6	∞
Combined Standard Uncertainty						9.9	9.7	
Coverage Factor for 95%							kp=2	
Expanded Uncertainty (K=2)						19.9	19.3	

TABLE 7.2

The table 7.2: Worst-Case uncertainty budget for DASY4 assessed according to IEEE 1528. The budget is valid for the frequency range 300MHz ~ 3GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



8. INFORMATION ON THE TESTING LABORATORIES

We, ADT Corp., were founded in 1988 to provide our best service in EMC, Radio, Telecom and Safety consultation. Our laboratories are accredited and approved by the following approval agencies according to ISO/IEC 17025.

USA FCC, UL, A2LA TUV Rheinland

JAPAN VCCI NORWAY NEMKO

CANADA INDUSTRY CANADA, CSA

R.O.C. CNLA, BSMI, DGT

NETHERLANDS Telefication

SINGAPORE PSB , GOST-ASIA (MOU)

RUSSIA CERTIS (MOU)

Copies of accreditation certificates of our laboratories obtained from approval agencies can be downloaded from our web site:

<u>www.adt.com.tw/index.5/phtml</u>. If you have any comments, please feel free to contact us at the following:

Linko EMC/RF Lab:Hsin Chu EMC/RF Lab:Tel: 886-2-26052180Tel: 886-3-5935343Fax: 886-2-26051924Fax: 886-3-5935342

Hwa Ya EMC/RF/Safety/TelecomLinko RF Lab.Lab:Tel: 886-3-3270910Tel: 886-3-3183232Fax: 886-3-3270892

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Web Site: www.adt.com.tw

The address and road map of all our labs can be found in our web site also.