Specific Absorption Rate (SAR) Test Report
for
SOLOMON Technology Corp.
on the
USB GPRS Modem

FCC ID: NIT-SCMI250U
Report No.:   3O1305-F
Date of Testing: Oct. 22, 2003 and Nov. 05, 2003
Date of Report: Nov. 12, 2003
Date of Review: Nov. 13, 2003

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Table of Contents

1. Statement of Compliance

The Specific Absorption Rate (SAR) maximum result found during testing for the SOLOMON Technology Corp. USB GPRS Modem is 0.476 W/Kg in GSM 850 band and 1.26 W/Kg in PCS 1900 band with expanded uncertainty 20.6%. It is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1999 and had been tested in accordance with the measurement methods and procedures specified in OET Bulletin 65 Supplement C (Edition 01-01).

Tested by Kevin Yang   Reviewed by Daniel Lee

Kevin Yang   Dr. C.H. Daniel Lee
Project Leader   SAR Lab. Manager
Nov. 05, 2003   Nov. 13, 2003

2. Administration Data

2.1 Testing Laboratory

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Department :   Antenna Design/SAR
Address :   No.52, Hwa-Ya 1st RD., Hwa Ya Technology Park, Kwei-Shan Hsiang, TaoYuan Hsien, Taiwan, R.O.C.
Telephone Number :   886-3-327-3456
Fax Number :   886-3-327-0973

2.2 Detail of Applicant

Company Name :   SOLOMON Technology Corp..
Address :   No. 42, Sing Shong Rd., Nei Hu Dist., Taipei, Taiwan, R.O.C.
Telephone Number :   886-2-8791-8989
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2.3 Application Detail

Date of reception of application: Oct. 20, 2003
Start of test :   Oct. 22, 2003
End of test :   Nov. 05, 2003

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3. General Information

3.1 Description of Device Under Test (DUT)

DUT Type :	USB GPRS Modem
Brand Name	SOLOMON
Model Name :	SCMi250u
FCC ID	NIT-SCMI250U
Tx Frequency :	824-849MHz (GSM) / 1850-1910MHz (PCS)
Rx Frequency	869-894MHz (GSM) / 1930-1990MHz (PCS)
Antenna Type :	Fixed Monopole
Antenna Gain :	+1 dBi
Type of Modulation :	GMSK
DUT Stage	Identical prototype
Application Type :	Certification
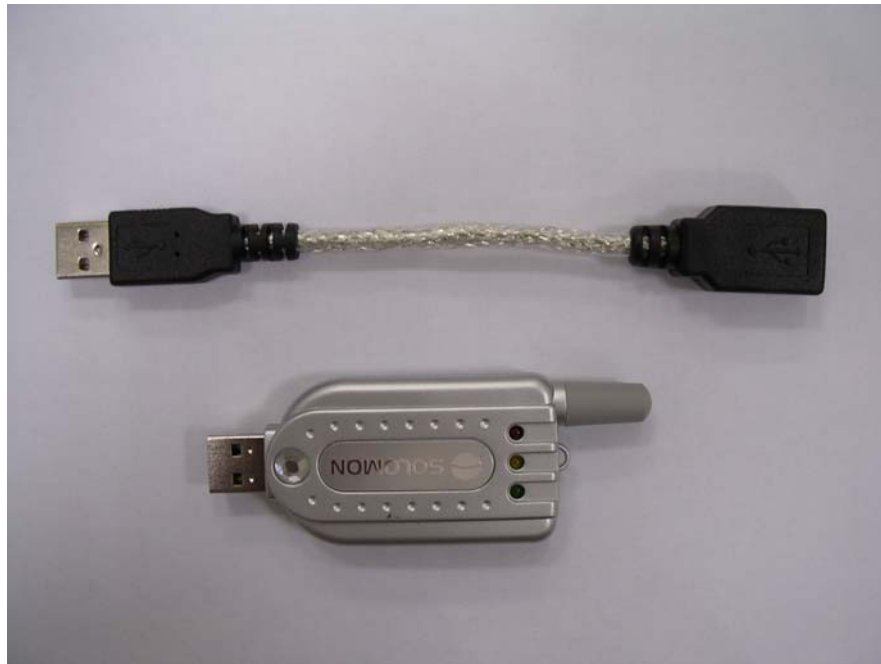
Fig. 3.1. Top view of the DUT
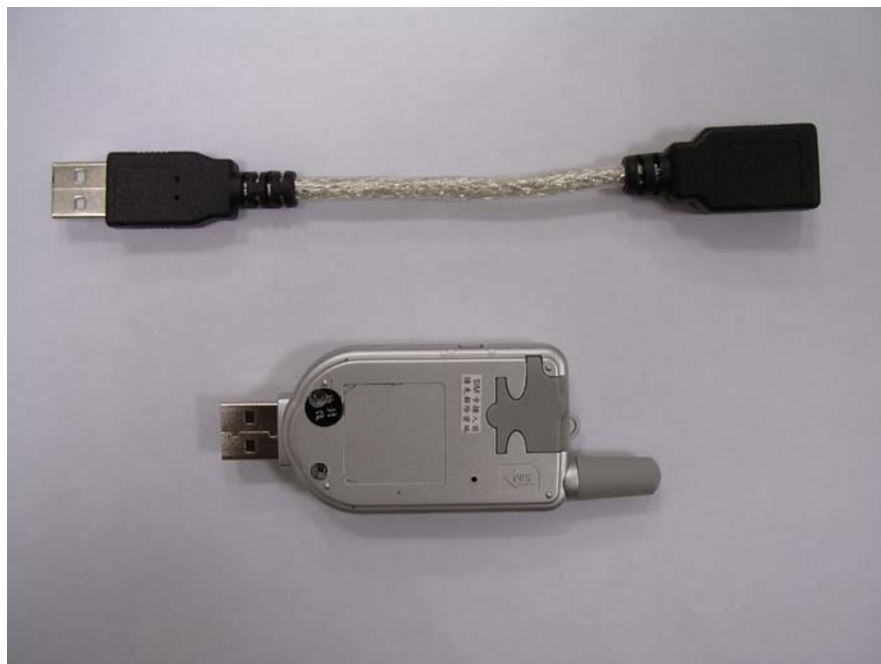
Fig. 3.2 Bottom view of the DUT

3.2 Applied Standards:

The Specific Absorption Rate (SAR) testing specification, method and procedure for this USB GPRS Modem is in accordance with the following standards:

47 CFR Part 2 (2.1093),
IEEE C95.1-1999,
IEEE C95.3-1991,
IEEE P1528 -200X, and
OET Bulletin 65 Supplement C (Edition 01-01)

3.3 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user.

Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

3.4 Test Conditions

3.4.1 Ambient Condition:

Ambient Temperature (^{o}C)	21 ~ 23
Tissue simulating liquid temperature (^{o}C)	21.5
Humidity (%)	40~60

3.4.2 Test Configuration:

The device was controlled by using a base station emulator CMU 200.   Communication between the device and the emulator was established by air link. The distance between the DUT and the antenna of the simulator is larger than 50 cm and the output power radiated from the simulator antenna is at least 30 dB smaller than the output power of DUT.

Measurements were performed on the lowest, middle , and highest channel of both bands for each testing position.   However, if the SAR is 3dB below the SAR limit (1.6 W/kg), only one channel was tested in this position.

The DUT was set from the emulator to radiate maximum output power during all tasting for each band and its crest factor is 8.3.

4.Specific Absorption Rate (SAR)
4.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The FCC recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

4.2. SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density.
ρ). The equation description is as below:

$$\textbf{SAR} = \frac{d}{dt}\left(\frac{dW}{dm}\right) = \frac{d}{dt}\left(\frac{dW}{\rho dv}\right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$\textbf{SAR} = C\frac{\delta T}{\delta t}$$

, where C is the specific head capacity, δT is the temperature rise and δt the exposure duration,

or related to the electrical field in the tissue by

$$\textbf{SAR} = \frac{\sigma |E|^2}{\rho}$$

, where σ is the conductivity of the tissue, ρ is the mass density of the tissue and *E* is the rms electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

5. SAR Measurement Setup

Remote Control Box

PC

Signal lamps

Electro-Optical Converter (EOC)

DAE

E-field probe

Measurement Server

DASY4

Robot

Phantom

Tissue simulating liquid

Light Beam

Robot Controller

(CS7MB-type)
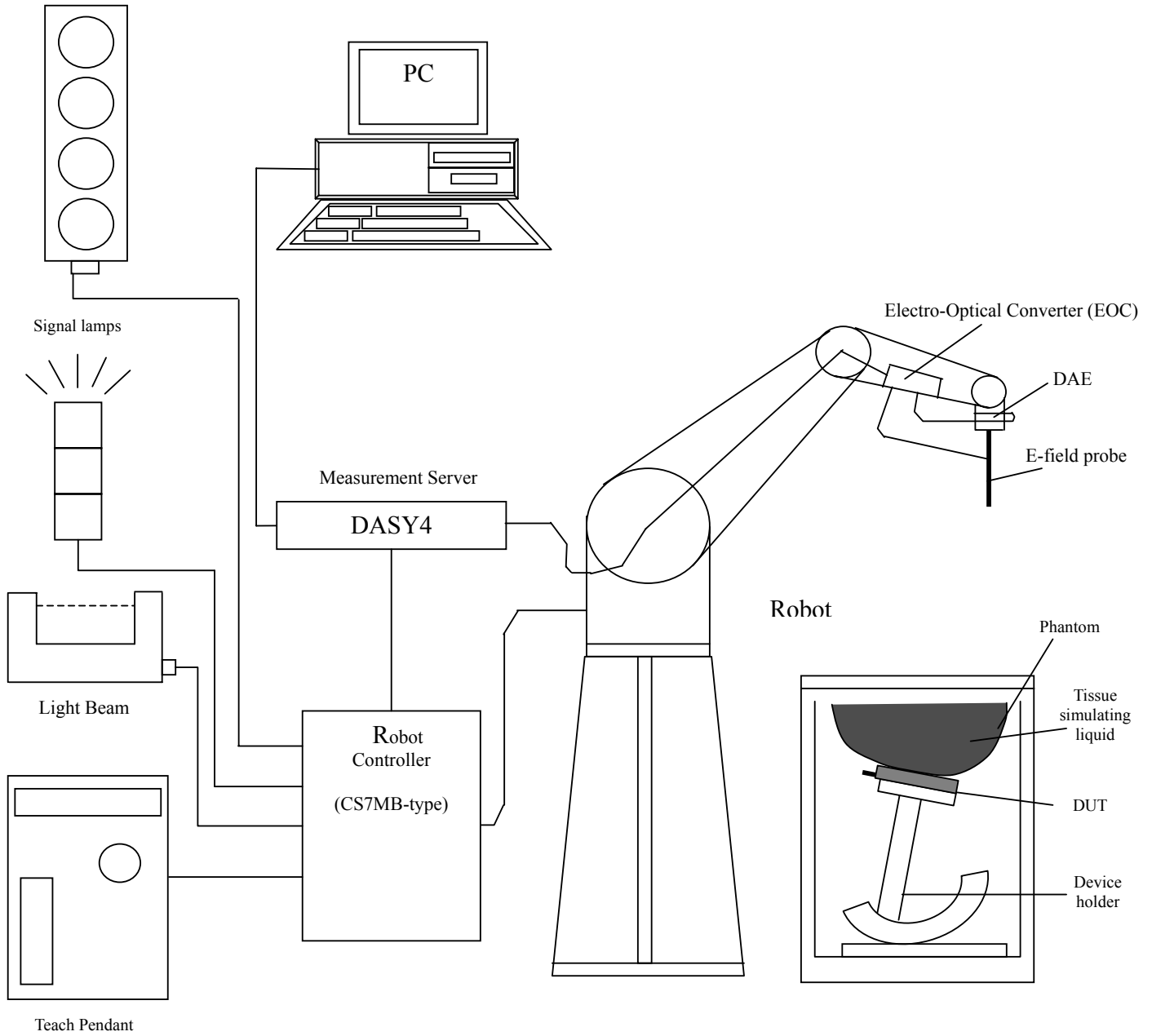
DUT

Device holder

Teach Pendant

Fig. 5.1 DASY4 system

The DASY4 system for performance compliance tests is illustrated above graphically. This system consists of the following items:

➢ A standard high precision 6-axis robot with controller, a teach pendant and software
➢ A data acquisition electronic (DAE) attached to the robot arm extension
➢ A dosimetric probe equipped with an optical surface detector system
➢ The electro-optical converter (ECO) performs the conversion between optical and electrical signals
➢ A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
➢ A probe alignment unit which improves the accuracy of the probe positioning
➢ A computer operating Windows XP
➢ DASY4 software
➢ Remove control with teach pendant and additional circuitry for robot safety such as warming lamps, etc.
➢ The SAM twin phantom
➢ A device holder
➢ Tissue simulating liquid
➢ Dipole for evaluating the proper functioning of the system

Some of the components are described in details in the following sub-sections.

5.1. DASY4 E-Field Probe System

The SAR measurement is conducted with the dosimetric probe ET3DV6 (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

Calibration: Required once a year.

5.1.1. ET3DV6 E-Field Probe Specification

Construction   Symmetrical design with triangular core

Built-in optical fiber for surface detection
system

Built-in shielding against static charges

PEEK enclosure material (resistant to
organic solvents)

Calibration	Simulating tissue at frequencies of 900MHz, 1.8GHz and 2.45GHz for brain and muscle (accuracy ±8%)
Frequency	10 MHz to > 3 GHz
Directivity	± 0.2 dB in brain tissue (rotation around probe axis) ± 0.4 dB in brain tissue (rotation perpendicular to probe axis)
Dynamic Range	5 μ W/g to > 100mW/g; Linearity: ±0.2dB
Surface Detection	± 0.2 mm repeatability in air and clear liquids on reflecting surface
Dimensions	Overall length: 330mm Tip length: 16mm Body diameter: 12mm Tip diameter: 6.8mm Distance from probe tip to dipole centers: 2.7mm
Application	General dosimetry up to 3GHz Compliance tests for mobile phones and Wireless LAN Fast automatic scanning in arbitrary phantoms

Fig. 5.2 Probe setup on robot

5.1.2 ET3DV6 E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than ± 10%. The spherical isotropy shall be evaluated and within ± 0.25dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data are as below:

Sensitivity	EGSM and DCS	X axis : 1.68 µV	Y axis: 1.62 µV	Z axis : 1.71 µV
Diode compression point	EGSM and DCS	X axis : 95 mV	Y axis : 95 mV	Z axis : 95 mV
Conversion factor (Body)		**X axis**	**Y axis**	**Z axis**
	EGSM	6.5	6.5	6.5
	DCS	5.0	5.0	5.0
Boundary effect (Body)		**Alpha**	**Depth**	
	EGSM	0.31	2.92	
	DCS	0.51	2.78	

NOTE:

1. The probe parameters have been calibrated by the SPEAG.
2. For the detailed calibration data is shown in Appendix C.

5.2 DATA Acquisition Electronics (DAE)

The data acquisition electronics (DAE4) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE4 is 200M Ohm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.

Calibration: Required once a year. Calibration data is attached in Appendix C.

5.3 Robot

The DASY4 system uses the high precision robots RX90BL type out of the newer series from Stäubli SA (France). For the 6-axis controller DASYS system, the CS7MB robot controller version from Stäubli is used.   The RX robot series have many features that are important for our application:

➢   High precision (repeatability 0.02 mm)
➢   High reliability (industrial design)
➢   Jerk-free straight movements
➢   Low ELF interference (the closed metallic construction shields against motor control fields)
➢   6-axis controller

5.4 Measurement Server

The DASY4 measurement server is based on a PC/104 CPU board with
166 MHz CPU
32 MB chipset and
64 MB RAM.

Communication with
the DAE4 electronic box
the 16-bit AD-converter system for optical detection and digital I/O interface.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.

Calibration: No calibration required.

5.5 SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

➢   Left head
➢   Right head
➢   Flat phantom

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections.

A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes

in the liquid parameters.

On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

The phantom can be used with the following tissue simulating liquids:
*Water-sugar based liquid
*Glycol based liquids

Fig. 5.3 Top view of twin phantom

Fig. 5.4 Bottom view of twin phantom

5.6 Data Storage and Evaluation

5.6.1 Data Storage

The DASY4 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension .DA4. The postprocessing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a loseless media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

5.6.2 Data Evaluation

The DASY4 postprocessing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software：

Probe parameters：	- Sensitivity	$Norm_i$, a_{i0}, a_{i1}, a_{i2}
	- Conversion factor	$ConvF_i$
	- Diode compression point	dcp_i
Device parameters：	- Frequency	f
	- Crest factor	cf
Media parameters：	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.
The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as：

$$Vi \ = \ U_i + \ U_i^2 \cdot \frac{cf}{dcp_i}$$

with
    V_i = *compensated signal of channel i (i = x, y, z)*
    U_i = *input signal of channel i (i = x, y, z)*
    cf = crest factor of exciting field (DASY parameter)
    dcp_i = *diode compression point (DASY parameter)*

From the compensated input signals, the primary field data for each channel can be evaluated：

E-field probes：$E_i \ = \ \sqrt{\dfrac{V_i}{Norm_i ConvF}}$

H-field probes：$H_i \ = \ \sqrt{V_i}\,\dfrac{a_{i0+}a_{i1}f + a_{i2}f^2}{f}$

with
    V_i = compensated signal of channel i (i = x, y, z)
    $Norm_i$ = sensor sensitivity of channel i (i = x, y, z)
        μ V/(V/m)2 for E-field Probes
    ConvF = sensitivity enhancement in solution
    a_{ij} = sensor sensitivity factors for H-field probes
    f = carrier frequency [GHz]
    E_i = electric field strength of channel i in V/m
    H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude)：

$$E_{tot} \ = \ \sqrt{E_X^2 + E_Y^2 + E_Z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = \ E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with
    SAR = local specific absorption rate in mW/g
    Etot = total field strength in V/m
    σ = conductivity in [mho/m] or [Siemens/m]
    ρ = equivalent tissue density in g/cm3

＊Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^{2}}{3770} \qquad \text{or} \qquad P_{pwe} = H_{tot}^{2} \cdot 37.7$$

with P_{pwe} = equivalent power density of a plane wave in mW/cm^2
                  E_{tot} = total electric field strength in V/m
                  H_{tot} = total magnetic field strength in A/m

5.7. Test Equipment List

Manufacture	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	**Due Date**
SPEAG	Dosimetric E-Filed Probe	ET3DV6	1788	Aug. 29, 2003	Aug. 29, 2004
SPEAG	900MHz System Validation Kit	D900V2	172	Dec. 17, 2002	Dec. 17, 2004
SPEAG	1800MHz System Validation Kit	D1800V2	2d057	Jan. 9, 2003	Jan. 9, 2005
SPEAG	2450MHz System Validation Kit	D2450V2	736	Aug. 26, 2003	Aug. 26, 2004
SPEAG	Data Acquisition Electronics	DAE3	541	Jan. 14, 2003	Jan. 14, 2004
SPEAG	Device Holder	N/A	N/A	NCR	NCR
SPEAG	Phantom	QD 000 P40 C	TP-1150	NCR	NCR
SPEAG	Robot	Staubli RX90BL	F03/5W15A1/A/01	NCR	NCR
SPEAG	Software	DASY4 V4.1 Build 47	N/A	NCR	NCR
SPEAG	Software	SEMCAD V1.6 Build 116	N/A	NCR	NCR
SPEAG	Measurement Server	SE UMS 001 BA	1021	NCR	NCR
Agilent	S-Parameter Network Analyzer	8720ES	US39172472	May 15, 2003	May 15, 2004
Agilent	Dielectric Probe Kit	85070C	US99360094	NCR	NCR
R&S	Power Meter	NRVS	100444	May 28, 2003	May 28, 2004
R&S	Power Sensor	NRV	100057	May 28, 2003	May 28, 2004
R&S	Signal Generator	SMR40	104558402	Nov.8, 2002	Nov. 8, 2003
Agilent	Dual Directional Coupler	778D	50334	NCR	NCR
Agilent	Power Amplifier	8449B	3008A01917	Sep. 16, 2003	Sep. 16, 2004
R & S	Base Station Simulator	CMU200	1100000802	Aug. 12, 2003	Aug. 12, 2004

Table 5.1 Test Equipment List

6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY4, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. The liquid height from the bottom of the phantom body is 15.2 centimeters, which is shown in Fig. 6.1.

The following ingredients for tissue simulating liquid are used:

➢ **Water**: deionized water (pure H_2O), resistivity $\geqq 16M\Omega$ - as basis for the liquid
➢ **Sugar**: refined sugar in crystals, as available in food shops – to reduce relative permittivity
➢ **Salt**: pure NaCl – to increase conductivity
➢ **Cellulose**: Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in water, 20°C), CAS#54290-to increase viscosity and to keep sugar in solution.
➢ **Preservative**: Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS#55965-84-9- to prevent the spread of bacteria and molds.
➢ **DGMBE**: Deithlenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH, CAS#112-34-5 – to reduce relative permittivity.

Table 6.1 gives the recipes for one liter of muscle tissue simulating liquid for frequency bands 850 MHz and 1900 MHz.

Ingredient	MSL-900	MSL-1800
Water	631.68 g	716.56 g
Salt	11.72 g	4.0 g
Preventol D-7	1.2 g	0 g
Sugar	600.0 g	0 g
DGMBE	0 g	300.67 g
Total amount	1 liter	1 liter
Dielectric Parameters at 22°	f= 835 MHz $\varepsilon = 55.2\pm5\%, \sigma = 0.97\pm5\%$ S/m f=900 MHz $\varepsilon = 55.0\pm5\%, \sigma = 1.05\pm5\%$ S/m	f = 1800MHz $\varepsilon = 53.3\pm5\%, \sigma = 1.52\pm5\%$ S/m f= 1900 MHz $\varepsilon = 53.3\pm5\%, \sigma = 1.52\pm5\%$ S/m

Table 6.1

The dielectric parameters of the liquids were verified prior to the SAR evaluation using an Agilent 85070C Dielectric Probe Kit and an Agilent 8720ES Network Analyzer.

Table 6.2 shows the measuring results for muscle simulating liquid in the 850MHz and 1900MHz frequency bands at the temperature = 21.5°C

Bands	Frequency(MHz)	Permittivity (ε)	Conductivity (σ)
GSM band (824~849 MHz)	824.2	55.98	0.9521
	836.4	55.87	0.9634
	848.8	55.75	0.9772
PCS band (1850~1910 MHz)	1850.2	52.54	1.44
	1880	52.43	1.46
	1909.8	52.35	1.48

Table 6.2

The measuring data are consistent with $\varepsilon = 55.2 \pm 5\%$ and $\sigma = 0.97 \pm 5\%$ for GSM band and $\varepsilon = 53.3 \pm 5\%$ and $\sigma = 1.52 \pm 5\%$.

Fig. 6.1

7. Uncertainty Assessment

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 7.1

Uncertainty Distributions	Normal	Rectangular	Triangular	U-shape
Multiplying factor[a]	$1/k$ [b]	$1/\sqrt{3}$	$1/\sqrt{6}$	$1/\sqrt{2}$

(a)   standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b) κ is the coverage factor

Table 7.1

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY4 uncertainty Budget is showed in Table 7.2.

Error Description	Uncertainty Value ± %	Probability Distribution	Divisor	C_i 1g	Standard Unc. (1-g)	v_i or V_{eff}
Measurement System						
Probe Calibration	± 4.8	Normal	1	1	±4.8	∞
Axial Isotropy	± 4.7	Rectangular	√3	$(1-Cp)^{1/2}$	±1.9	∞
Hemispherical Isotropy	± 9.6	Rectangular	√3	$(Cp)^{1/2}$	±3.9	∞
Boundary Effect	± 1.0	Rectangular	√3	1	±0.6	∞
Linearity	± 4.7	Rectangular	√3	1	±2.7	∞
System Detection Limit	± 1.0	Rectangular	√3	1	±0.6	∞
Readout Electronics	± 1.0	Rectangular	1	1	±1.0	∞
Response Time	± 0.8	Normal	√3	1	± 0.5	∞
Integration time	±2.6	Rectangular	√3	1	±1.5	∞
RF Ambient Conditions	± 3.0	Rectangular	√3	1	±1.7	∞
Probe Positioner Mech. Tolerance	± 0.4	Rectangular	√3	1	±0.2	∞
Probe Positioning with respect to Phantom Shell	± 2.9	Rectangular	√3	1	±1.7	∞
Extrapolation and Interpolation Algorithms for Max. SAR Evaluation	± 1.0	Rectangular	√3	1	±0.6	∞
Test sample Related						
Test sample Positioning	±2.9	Normal	1	1	±2.9	145
Device Holder Uncertainty	±3.6	Normal	1	1	±3.6	5
Output Power Variation-SAR drift measurement	±2.5	Rectangular	√3	1	±1.4	∞
Phantom and Tissue parameters						
Phantom uncertainty(Including shap and thickness tolerances)	±4.0	Rectangular	√3	1	±2.3	∞
Liquid Conductivity Target tolerance	±5.0	Rectangular	√3	0.64	±1.8	∞
Liquid Conductivity measurement uncertainty	±2.5	Normal	1	0.64	±1.6	∞
Liquid Permittivity Target tolerance	±5.0	Rectangular	√3	0.6	±1.7	∞
Liquid Permittivity measurement uncertainty	±2.0	Normal	1	0.6	±1.2	∞
Combined standard uncertainty					±10.3	330
Coverage Factor for 95 %		K=2				
Expanded uncertainty (Coverage factor = 2)					**±20.6**	

Table 7.2. Uncertainty Budget of DASY

8. SAR Measurement Evaluation

Each DASY system is equipped with one or more system validation kits.   These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

8.1 Purpose of System Performance check

The system performance check verifies that the system operates within its specifications.   System and operator errors can be detected and corrected.   It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results.   The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time.   The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

8.2 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave which comes from a signal generator with a fixed output power 100 mW (20 dBm) at frequency 900 and 1800 MHz.   The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder.   The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom.   The equipment setup is shown below:
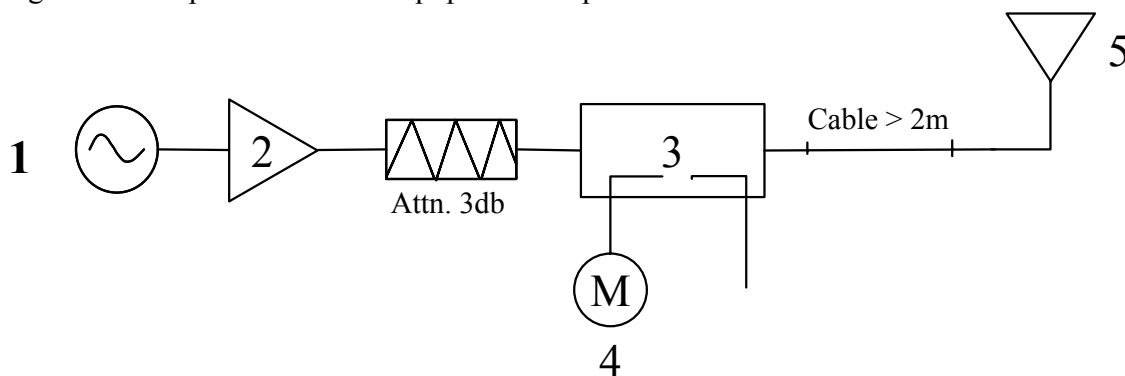

Fig. 8.1

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. 900 MHz or 1800 MHz Dipole

The output power on dipole port must be calibrated to 100 mW (20 dBm) before dipole is connected.

8.3 Validation Results

Comparing to the original SAR value provided by Speag, the validation data should within its specification of 10 %. Table 8.1 shows the target SAR and measured SAR after normalized to 1W input power.

		Target (W/kg)	Measurement data (W/kg)	Variation
GSM band (900 MHz)	SAR (1g)	10.5	11.15	6.2%
	SAR (10g)	6.84	7.1	3.8%
PCS band (1800 MHz)	SAR (1g)	38.8	38.25	1.4%
	SAR (10g)	20.4	20.75	1.7%

Table 8.1

The table above indicates the system performance check can meet the variation criterion.

9. Description for DUT Testing Position

This DUT was tested in 5 different positions. The first one is ''NB Bottom Touch'' in Fig. 9.1. In this position, the bottom of notebook (laptop) is touched with that phantom. The distance between DUT and phantom bottom is one centimeter.

Fig. 9.1

The second position is "DUT with1.5 cm Gap" in Fig. 9.2. In this position, the bottom face of the DUT has 1.5 cm gap with with the flat phantom.

Fig. 9.2

The third one is "DUT Tip with 1.5 cm Gap" in Fig. 9.3. In this position, the antenna of the DUT is normal to the flat phantom and has 1.5 cm gap with it.
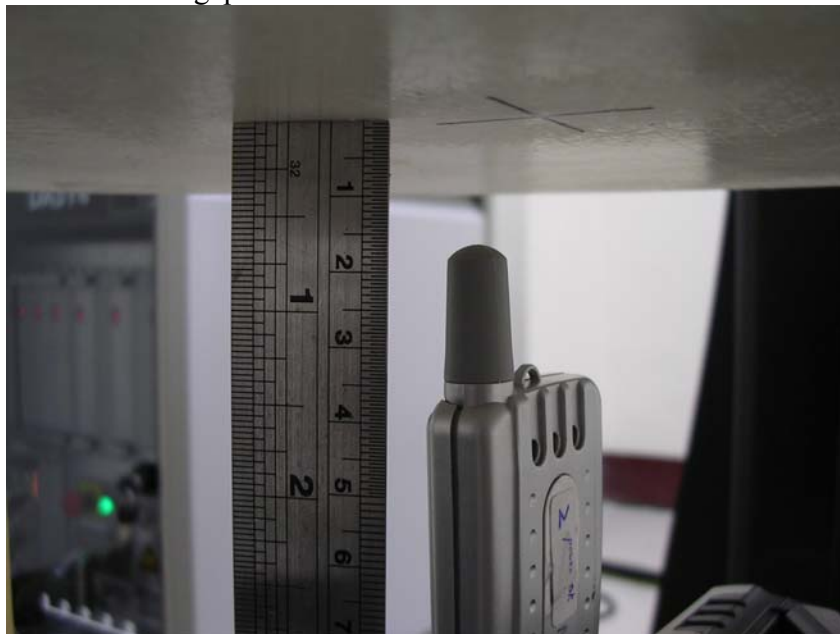
Fig. 9.3

The fourth one is "DUT Plus cable Tip Touch" in Fig. 9.4. In this position, the DUT connects with one USB cable and the antenna of the DUT is normal to the flat phantom and touched with it.

Fig. 9.4

The fifth one is "DUT Plus Cable with 1.5 cm Gap" in Fig. 9.5. In this position, the DUT connects with one USB cable and the antenna of the DUT is parallel with the flat phantom and has 1.5 cm gap with it.
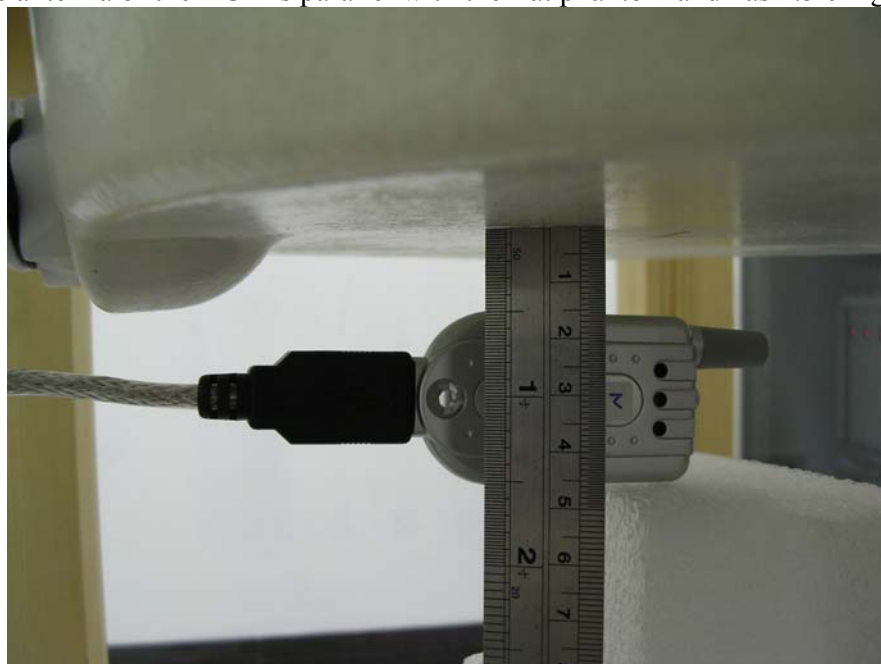
10. Measurement Procedures

The measurement procedures are as follows:

➢ Plugging DUT into the notebook
➢ Linking DUT with base station simulator CMU200 in lowest channel for GSM or PCS band
➢ Setting PCL=7 for GSM and PCL=0 for PCS on CMU200 to allow DUT to radiate maximum output power
➢ Measuring output power through RF cable and power meter
➢ Placing the DUT in the positions described in the last section
➢ Setting scan area, grid size and other setting on the DASY4 software
➢ Taking data for the lowest, middle, and highest channel on each testing position
➢

According to the IEEE P1528 draft standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:
➢ Power reference measurement
➢ Area scan
➢ Zoom scan
➢ Power reference measurement

10.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1528-200X standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY4 software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

Base on the Draft: SCC-34, SC-2, WG-2-Computational Dosimetry, IEEE P1529/D0.0 (Draft Recommended Practice for Determining the Spatial-Peal Specific Absorption Rate (SAR) Associated with the Use of Wireless Handset-Computational techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement.   The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose , the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the postprocessing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

● extraction of the measured data (grid and values) from the Zoom Scan
● calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
● generation of a high-resolution mesh within the measured volume

- interpolation of all measured values form the measurement grid to the high-resolution grid
- extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- calculation of the averaged SAR within masses of 1g and 10g

10.2 Scan Procedures

First **Area Scan** is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an **Area Scan** is defined by the grid extent, grid step size and grid offset.   Next, in order to determine the EM field distribution in a three-dimensional spatial extension, **Zoom Scan** is required. The **Zoom Scan** measures 7x7x7 points with step size 8, 8 and 5 mm.   The **Zoom Scan** is performed around the highest E-field value to determine the averaged SAR-distribution over 1 g.

10.3 SAR Averaged Methods

In DASY4, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method.   The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.
Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface.   The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance.   To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger then 5 mm.

11. SAR Test Results
11.1 N/B Bottom Touch

Bands	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
GSM	128	824.2 (Low)	GMSK	28.3	-	-	-	-
	189	836.4 (Mid)	GMSK	28.4	0.04	0.121	1.6	Pass
	251	848.8 (High)	GMSK	28.5	-	-	-	-
PCS	512	1850.2 (Low)	GMSK	29.2	0.001	1.26	1.6	Pass
	661	1880.0 (Mid)	GMSK	28.9	-0.004	0.838	1.6	Pass
	810	1909.8 (High)	GMSK	28.3	0.06	0.366	1.6	Pass

11.2 DUT with 1.5 cm Gap

Bands	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
GSM	128	824.2 (Low)	GMSK	28.3	0.1	0.0579	1.6	Pass
	189	836.4 (Mid)	GMSK	28.4	-0.08	0.0544	1.6	Pass
	251	848.8 (High)	GMSK	28.5	0.04	0.0539	1.6	Pass
PCS	512	1850.2 (Low)	GMSK	29.2	0.02	0.644	1.6	Pass
	661	1880.0 (Mid)	GMSK	28.9	0.008	0.434	1.6	Pass
	810	1909.8 (High)	GMSK	28.3	0.008	0.186	1.6	Pass

11.3 DUT Tip with 1.5 cm Gap

Bands	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
GSM	128	824.2 (Low)	GMSK	28.3	0.02	0.00399	1.6	Pass
	189	836.4 (Mid)	GMSK	28.4	0.08	0.00444	1.6	Pass
	251	848.8 (High)	GMSK	28.5	0.02	0.0041	1.6	Pass
PCS	512	1850.2 (Low)	GMSK	29.2	0.03	0.0909	1.6	Pass
	661	1880.0 (Mid)	GMSK	28.9	-	-	-	-
	810	1909.8 (High)	GMSK	28.3	-	-	-	-

11.4 DUT Plus Cable Tip Touch

Bands	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
GSM	128	824.2 (Low)	GMSK	28.3	-	-	-	-
	189	836.4 (Mid)	GMSK	28.4	-0.06	0.476	1.6	Pass
	251	848.8 (High)	GMSK	28.5	-	-	-	-
PCS	512	1850.2 (Low)	GMSK	29.2	-	-	-	-
	661	1880.0 (Mid)	GMSK	28.9	-0.04	0.245	1.6	Pass
	810	1909.8 (High)	GMSK	28.3	-	-	-	-

11.5 DUT Plus Cable with 1.5 cm Gap

Bands	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
GSM	128	824.2 (Low)	GMSK	28.3	-	-	-	-
	189	836.4 (Mid)	GMSK	28.4	-0.06	0.126	1.6	Pass
	251	848.8 (High)	GMSK	28.5	-	-	-	-
PCS	512	1850.2 (Low)	GMSK	29.2	-	-	-	-
	661	1880.0 (Mid)	GMSK	28.9	-0.01	0.251	1.6	Pass
	810	1909.8 (High)	GMSK	28.3	-	-	-	-

12.References

[1] FCC 47 CFR Part 2 "Frequency Allocations and Radio Treaty Matters; General Rules and Regulations"

[2] IEEE Std. 1528-200X, Draft CD 1.1 " Recommended Practice for Determining the Spatial-Peak Specific Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques", December 2002

[3] Supplement C (Edition 01-10) to OET Bulletin 65 (Edition 97-01), "Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to RF Emissions", June 2001

[4] IEEE Std. C95.3, "IEEE Recommended Practice for the Meaurement of Potentially Hazardous Electromagnetic Fields-RF and Microwave", 1991

[5] IEEE Std. C95.1, "IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz", 1999

[6] Robert J. Renka, "Multivariate Interpolation Of Large Sets Of Scattered Data", University of Noth Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148

[7] DAYS4 System Handbook

Appendix A – System Performance Check Data

Date/Time: 10/22/03 08:13:20

Test Laboratory: SPORTON

900MHz Diploe System Calbration

DUT: Dipole 900 MHz; Type: D900V2; Serial: D900V2 - SN:172
Program Name: System Performance Check

Communication System: CW; Frequency: 900 MHz;Duty Cycle: 1:1
Medium: MSL850 ($\sigma = 1.1$ mho/m, $\varepsilon_r = 56.363$, $\rho = 1000$ kg/m^3)
Phantom section: Flat Section

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(6.5, 6.5, 6.5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

Pin=100mW;d=15mm/Area Scan (81x141x1): Measurement grid: dx=15mm, dy=15mm
Reference Value = 34.1 V/m
Power Drift = -0.1 dB
Maximum value of SAR = 1.205 mW/g

Pin=100mW;d=15mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 1.62 W/kg
SAR(1 g) = 1.115 mW/g; SAR(10 g) = 0.71 mW/g
Reference Value = 34.1 V/m
Power Drift = -0.1 dB
Maximum value of SAR = 1.205 mW/g

0 dB = 1.205mW/g
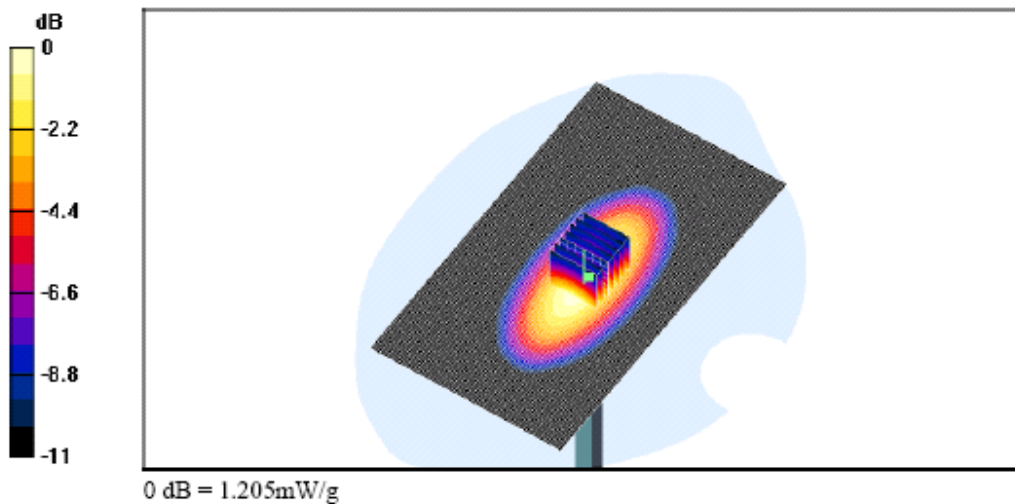
Date/Time: 11/05/03 08:15:04

Test Laboratory: SPORTON

1900MHz Dipole System Calbration

DUT: Dipole 1800 MHz; Type: D1800V2; Serial: D1800V2 - SN:2d057
Program Name: System Performance Check

Communication System: CW; Frequency: 1800 MHz;Duty Cycle: 1:1
Medium: MSL1900 (σ = 1.44 mho/m, ε_r = 51.8561, ρ = 1000 kg/m^3)
Phantom section: Flat Section

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(5, 5, 5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

Pin=100mW;d=10mm/Area Scan (51x51x1): Measurement grid: dx=15mm, dy=15mm
Reference Value = 57.4 V/m
Power Drift = -0.05 dB
Maximum value of SAR = 4.47 mW/g

Pin=100mW;d=10mm/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 6.25 W/kg
SAR(1 g) = 3.825 mW/g; SAR(10 g) = 2.075 mW/g
Reference Value = 57.4 V/m
Power Drift = -0.05 dB
Maximum value of SAR = 4.295 mW/g

0 dB = 4.295mW/g
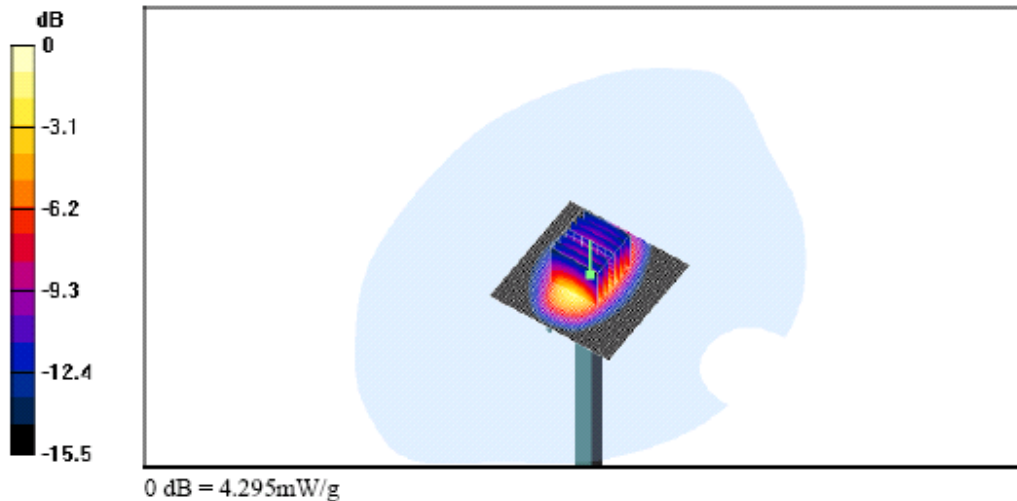
Appendix B - SAR Measurement Data

Date/Time: 10/22/03 14:36:42

Test Laboratory: SPORTON

DUT Plus Cable with 1.5 Gap 850 CH189

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: GSM850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3
Medium: MSL850 (σ = 0.963 mho/m, ε_r = 55.87, ρ = 1000 kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(6.5, 6.5, 6.5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 189 836.4MHz-Middle/Area Scan (81x101x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 11.8 V/m
Power Drift = -0.06 dB
Maximum value of SAR = 0.136 mW/g

**CH 189 836.4MHz-Middle/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm
Peak SAR (extrapolated) = 0.183 W/kg
SAR(1 g) = 0.126 mW/g; SAR(10 g) = 0.084 mW/g
Reference Value = 11.8 V/m
Power Drift = -0.06 dB
Maximum value of SAR = 0.134 mW/g

0 dB = 0.134mW/g
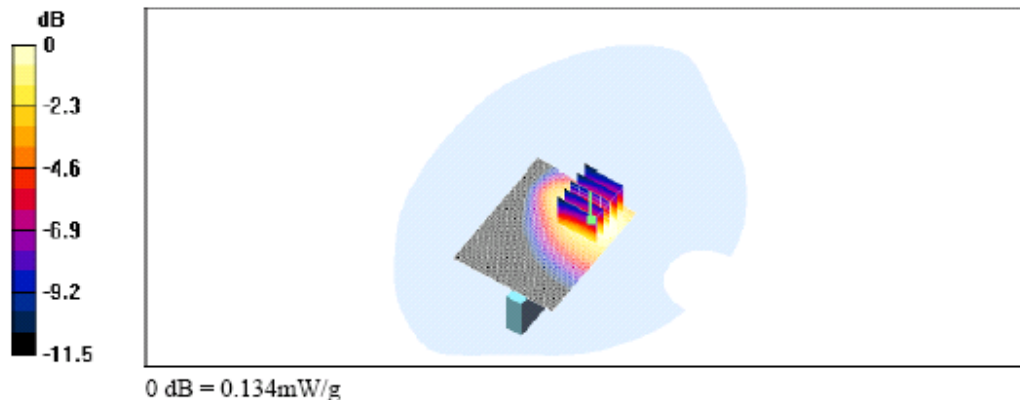
Date/Time: 10/22/03 16:40:32

Test Laboratory: SPORTON

DUT PLUS CABLE Tip Touch 850 CH189

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: GSM850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3

Medium: MSL850 (σ = 0.9634 mho/m, ε_r = 55.87, ρ = 1000 kg/m^3)

Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(6.5, 6.5, 6.5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 189 836.4MHz-Middle/Area Scan (61x61x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 25.4 V/m
Power Drift = -0.06 dB
Maximum value of SAR = 0.516 mW/g

CH 189 836.4MHz-Middle/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Peak SAR (extrapolated) = 2.89 W/kg
SAR(1 g) = 0.476 mW/g; SAR(10 g) = 0.115 mW/g
Reference Value = 25.4 V/m
Power Drift = -0.06 dB
Maximum value of SAR = 0.82 mW/g

0 dB = 0.82mW/g
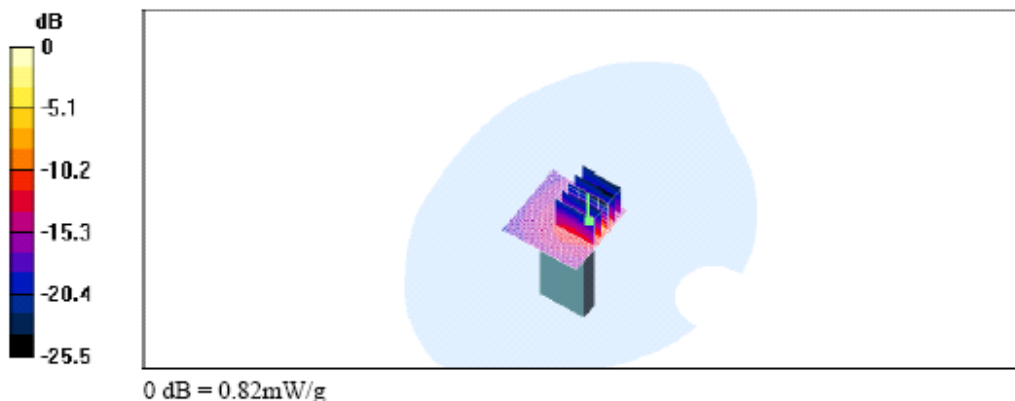
Date/Time: 10/22/03 10:34:28

Test Laboratory: SPORTON

DUT TIP WITH 1.5CM GAP 850 CH 189

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: GSM850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3

Medium: MSL850 (σ = 0.963mho/m, ε_r = 55.87, ρ = 1000 kg/m^3)

Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(6.5, 6.5, 6.5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 189 836.4MHz-Middle/Area Scan (61x61x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 1.99 V/m
Power Drift = 0.08 dB
Maximum value of SAR = 0.00427 mW/g

CH 189 836.4MHz-Middle/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Peak SAR (extrapolated) = 0.0125 W/kg
SAR(1 g) = 0.00444 mW/g; SAR(10 g) = 0.00253 mW/g
Reference Value = 1.99 V/m
Power Drift = 0.08 dB
Maximum value of SAR = 0.00427 mW/g

0 dB = 0.00427mW/g
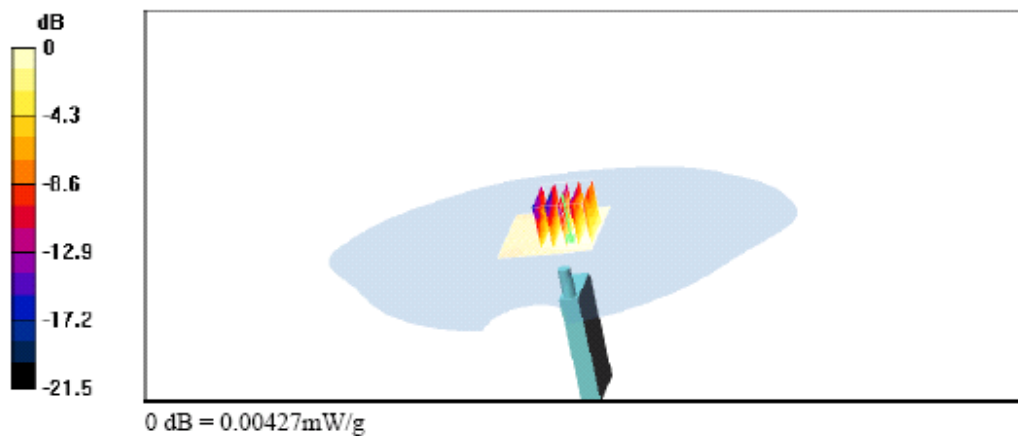
Date/Time: 10/22/03 11:55:42

Test Laboratory: SPORTON

DUT with 1.5cm Gap 850 CH 128

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: GSM850; Frequency: 824.2 MHz;Duty Cycle: 1:8.3
Medium: MSL850 (σ = 0.952 mho/m, ε_r = 55.98, ρ = 1000 kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(6.5, 6.5, 6.5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 128 824.2 MHz-LOW/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 2.75 V/m
Power Drift = 0.1 dB
Maximum value of SAR = 0.0616 mW/g

**CH 128 824.2 MHz-LOW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm
Peak SAR (extrapolated) = 0.0776 W/kg
SAR(1 g) = 0.0579 mW/g; SAR(10 g) = 0.0402 mW/g
Reference Value = 2.75 V/m
Power Drift = 0.1 dB
Maximum value of SAR = 0.0613 mW/g

dB
0
-1.98
-3.96
-5.95
-7.93
-9.91

0 dB = 0.0613mW/g
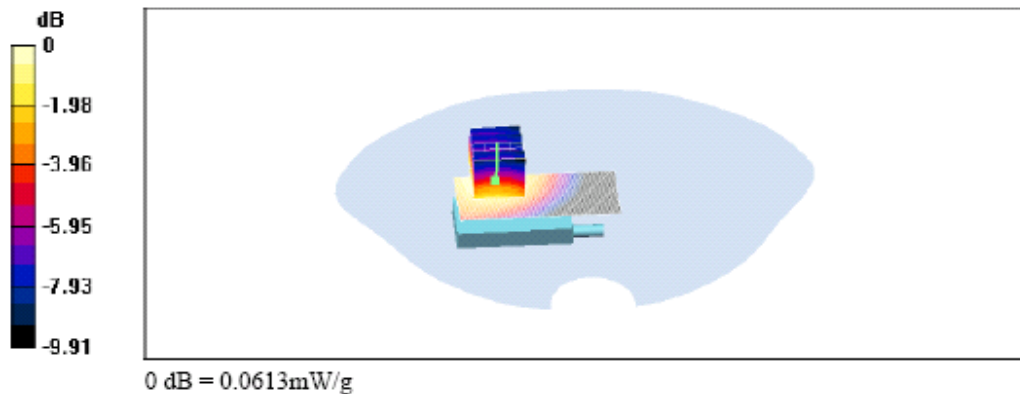
Date/Time: 10/22/03 12:38:02

Test Laboratory: SPORTON

NB Botton Touch 835 Ch 189

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: GSM850; Frequency: 836.4 MHz;Duty Cycle: 1:8.3
Medium: MSL850 (σ = 0.963 mho/m, ε_r = 55.87, ρ = 1000 kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(6.5, 6.5, 6.5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 189 836.4MHz-Middle/Area Scan (51x101x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 6.23 V/m
Power Drift = 0.04 dB
Maximum value of SAR = 0.0915 mW/g

CH 189 836.4MHz-Middle/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm,
dz=5mm
Peak SAR (extrapolated) = 0.201 W/kg
SAR(1 g) = 0.121 mW/g; SAR(10 g) = 0.0711 mW/g
Reference Value = 6.23 V/m
Power Drift = 0.04 dB
Maximum value of SAR = 0.151 mW/g

0 dB = 0.151mW/g
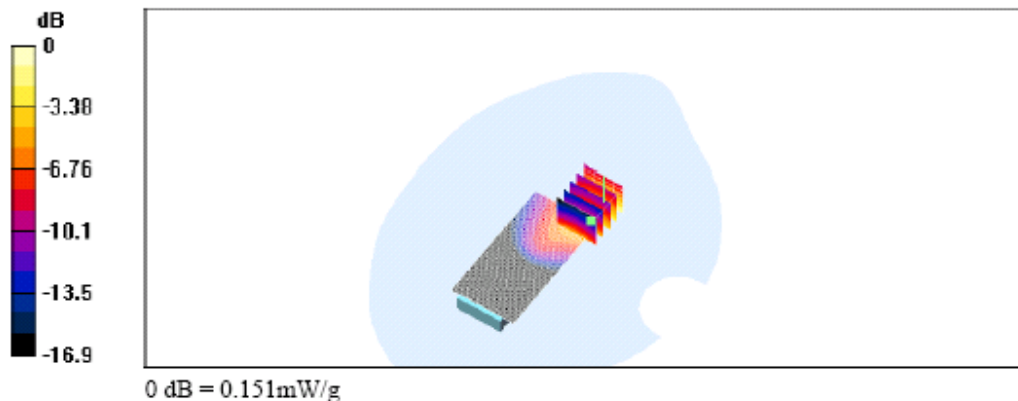
Date/Time: 11/05/03 17:49:36

Test Laboratory: SPORTON

DUT PLUS CABLE 1.5CM GAP 1900 CH 661

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: DCS 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3
Medium: MSL1900 (σ = 1.46 mho/m, ε_r = 52.43, ρ = 1000 kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(5, 5, 5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 661 1880.0MHz-Middle/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 14.5 V/m
Power Drift = -0.01 dB
Maximum value of SAR = 0.275 mW/g

CH 661 1880.0MHz-Middle/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm,
dz=5mm
Peak SAR (extrapolated) = 0.416 W/kg
SAR(1 g) = 0.251 mW/g; SAR(10 g) = 0.142 mW/g
Reference Value = 14.5 V/m
Power Drift = -0.01 dB
Maximum value of SAR = 0.274 mW/g

0 dB = 0.274mW/g
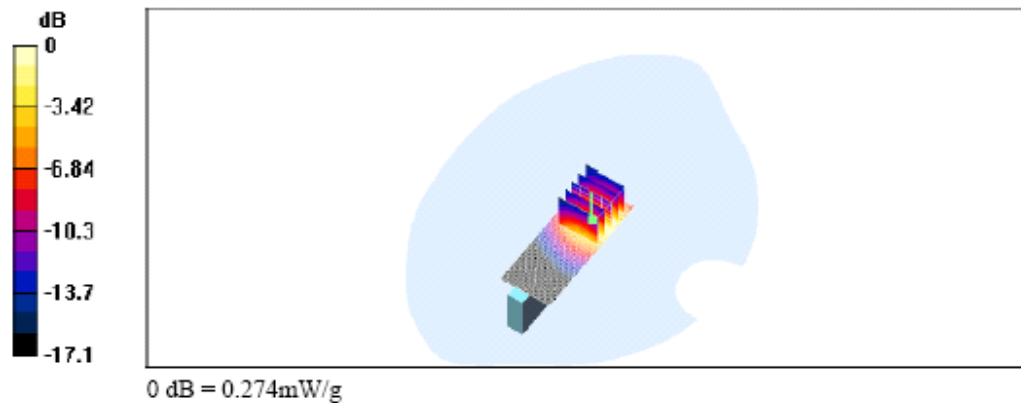
Date/Time: 11/05/03 15:53:12

Test Laboratory: SPORTON

DUT PLUS CABLE TIP TOUCH 1900 CH 661

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: DCS 1900; Frequency: 1880 MHz;Duty Cycle: 1:8.3
Medium: MSL1900 (σ = 1.46 mho/m, ε_r = 52.43, ρ = 1000 kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(5, 5, 5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 661 1880.0MHz-Middle/Area Scan (61x61x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 8.64 V/m
Power Drift = -0.04 dB
Maximum value of SAR = 0.306 mW/g

CH 661 1880.0MHz-Middle/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Peak SAR (extrapolated) = 0.64 W/kg
SAR(1 g) = 0.245 mW/g; SAR(10 g) = 0.129 mW/g
Reference Value = 8.64 V/m
Power Drift = -0.04 dB
Maximum value of SAR = 0.281 mW/g

0 dB = 0.281mW/g
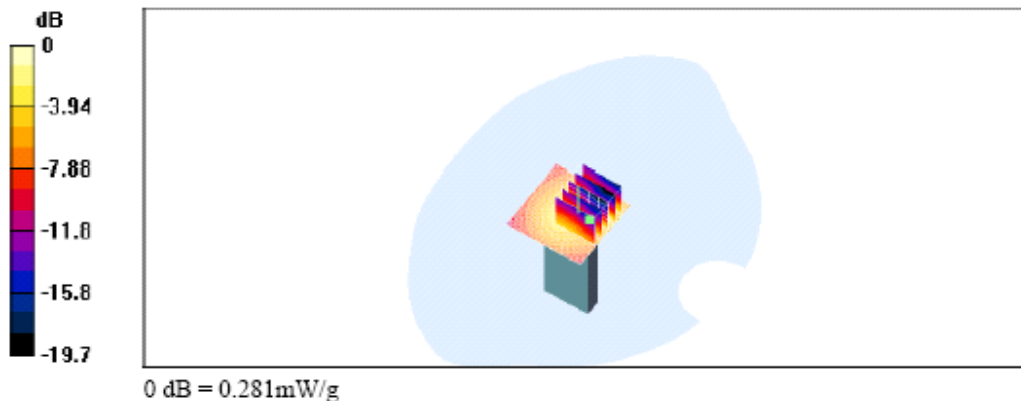
Date/Time: 11/05/03 14:12:28

Test Laboratory: SPORTON

DUT TIP WITH 1.5CM GAP 1900 CH 512

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3
Medium: MSL1900 (σ = 1.44 mho/m, ε_r = 52.54, ρ = 1000 kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(5, 5, 5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 512 1850.2 MHz-LOW/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 5.34 V/m
Power Drift = 0.03 dB
Maximum value of SAR = 0.0981 mW/g

CH 512 1850.2 MHz-LOW/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
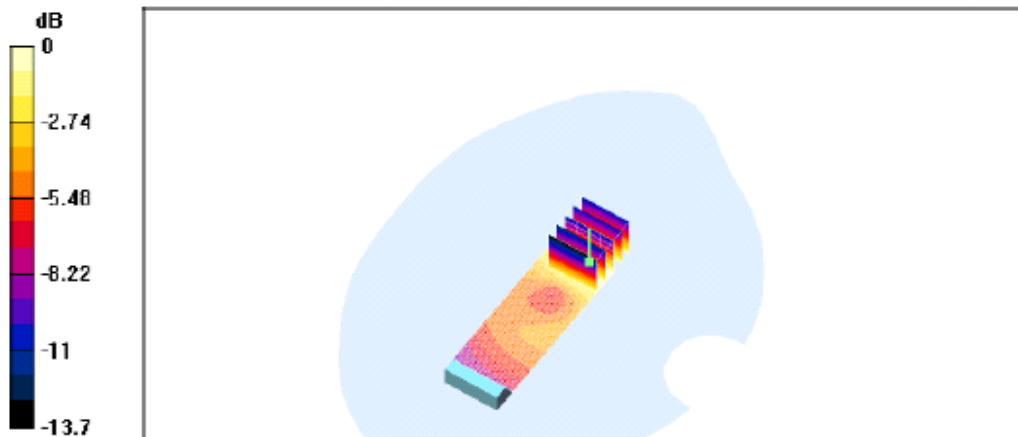Peak SAR (extrapolated) = 0.134 W/kg
SAR(1 g) = 0.0909 mW/g; SAR(10 g) = 0.0596 mW/g
Reference Value = 5.34 V/m
Power Drift = 0.03 dB
Maximum value of SAR = 0.0962 mW/g

0 dB = 0.0962mW/g

Date/Time: 10/23/03 15:31:58

Test Laboratory: SPORTON

DUT with 1.5 CM Gap 1900 Ch 512

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3
Medium: MSL1900 ($\sigma = 1.44$ mho/m, $\varepsilon_r = 52.538$, $\rho = 1000$ kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(5, 5, 5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 512 1850.2 MHz-LOW/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 21.4 V/m
Power Drift = 0.02 dB
Maximum value of SAR = 0.709 mW/g

CH 512 1850.2 MHz-LOW/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm,
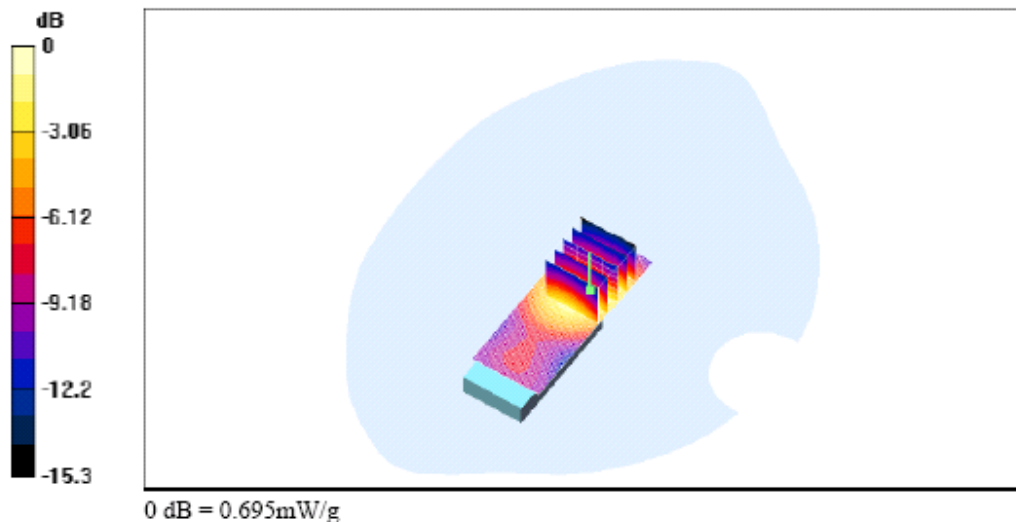dz=5mm
Peak SAR (extrapolated) = 1.02 W/kg
SAR(1 g) = 0.644 mW/g; SAR(10 g) = 0.382 mW/g
Reference Value = 21.4 V/m
Power Drift = 0.02 dB
Maximum value of SAR = 0.695 mW/g

0 dB = 0.695mW/g

Date/Time: 11/05/03 10:26:22

Test Laboratory: SPORTON

NB BTM TOUCH 1900 CH 512

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3
Medium: MSL1900 (σ = 1.44 mho/m, ε_r = 52.54, ρ = 1000 kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(5, 5, 5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 512 1850.2 MHz-LOW/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 30.5 V/m
Power Drift = 0.001 dB
Maximum value of SAR = 1.41 mW/g

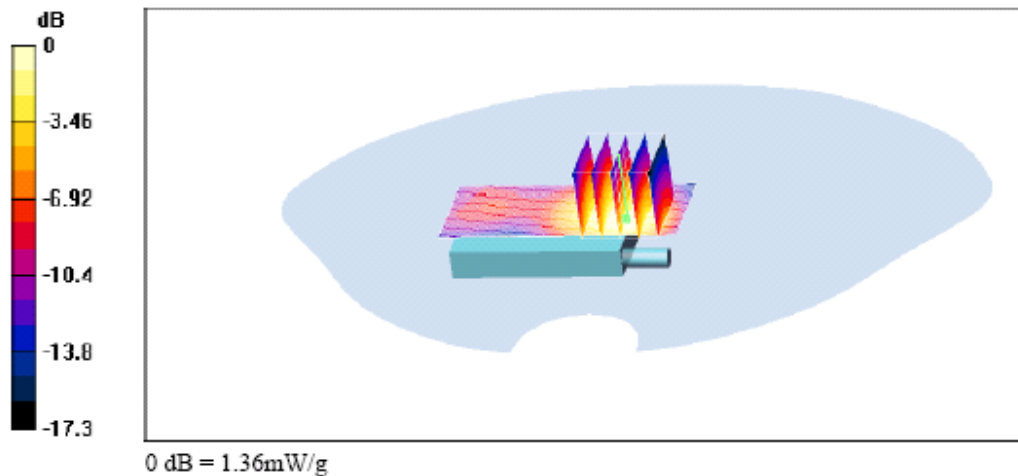**CH 512 1850.2 MHz-LOW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm, dz=5mm
Peak SAR (extrapolated) = 2.07 W/kg
SAR(1 g) = 1.26 mW/g; SAR(10 g) = 0.713 mW/g
Reference Value = 30.5 V/m
Power Drift = 0.001 dB
Maximum value of SAR = 1.36 mW/g

0 dB = 1.36mW/g

Date/Time: 11/05/03 10:26:22

Test Laboratory: SPORTON

NB BTM TOUCH 1900 CH 512

DUT: USB GPRS Modem;Type: SCMi250u

Communication System: DCS 1900; Frequency: 1850.2 MHz;Duty Cycle: 1:8.3
Medium: MSL1900 (σ = 1.44 mho/m, ε_r = 52.54, ρ = 1000 kg/m^3)
Phantom section: Flat Section ;Ambient Temp:21~23C;Liquid Temp=21.5C;Liquid Height=15.2cm

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(5, 5, 5); Calibrated: 8/29/2003
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn541; Calibrated: 1/14/2003
- Phantom: SAM 12; Type: QD 000 P40 C; Serial: TP-1150
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 116

CH 512 1850.2 MHz-LOW/Area Scan (41x101x1): Measurement grid: dx=10mm, dy=10mm
Reference Value = 30.5 V/m
Power Drift = 0.001 dB
Maximum value of SAR = 1.41 mW/g

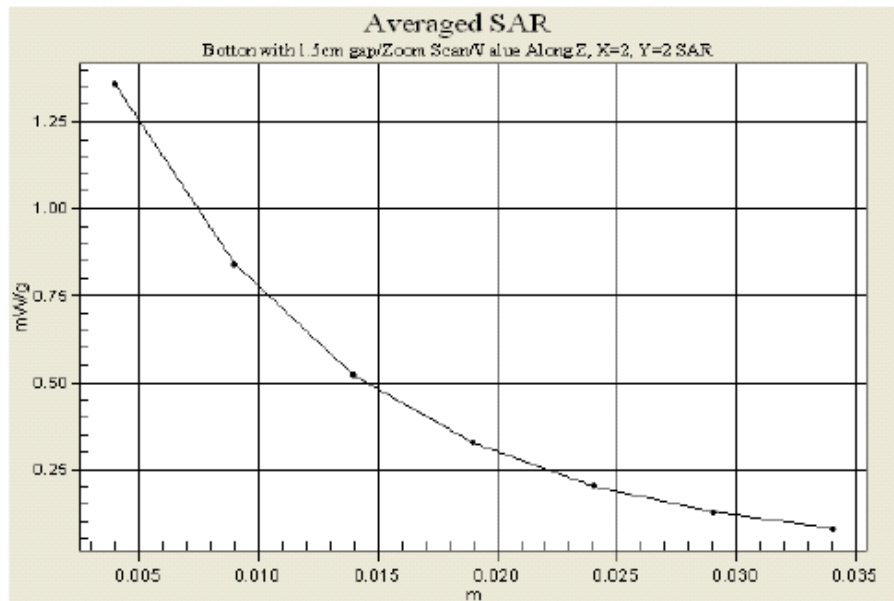**CH 512 1850.2 MHz-LOW/Zoom Scan (5x5x7)/Cube 0:** Measurement grid: dx=8mm, dy=8mm,
dz=5mm
Peak SAR (extrapolated) = 2.07 W/kg
SAR(1 g) = 1.26 mW/g; SAR(10 g) = 0.713 mW/g
Reference Value = 30.5 V/m
Power Drift = 0.001 dB
Maximum value of SAR = 1.36 mW/g

Calibration Laboratory of
Schmid & Partner
  Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

Client   Auden > Sporton Int. Inc.

CALIBRATION CERTIFICATE

Object(s)	ET3DV6 - SN:1788
Calibration procedure(s)	QA CAL-01 v2 Calibration procedure for dosimetric E-field probes
Calibration date:	August 29, 2003
Condition of the calibrated item	In Tolerance (according to the specific calibration document)

This calibration statement documents traceability of M&TE used in the calibration procedures and conformity of the procedures with the ISO/IEC 17025 international standard.

All calibrations have been conducted in the closed laboratory facility: environment temperature 22 +/- 2 degrees Celsius and humidity < 75%.

Calibration Equipment used (M&TE critical for calibration)

Model Type	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
RF generator HP 8684C	US3642U01700	4-Aug-99 (SPEAG, in house check Aug-02)	In house check: Aug-05
Power sensor E4412A	MY41495277	2-Apr-03 (METAS, No 252-0250)	Apr-04
Power sensor HP 8481A	MY41092180	18-Sep-02 (Agilent, No. 20020918)	Sep-03
Power meter EPM E4419B	GB41293874	2-Apr-03 (METAS, No 252-0250)	Apr-04
Network Analyzer HP 8753E	US37390585	18-Oct-01 (Agilent, No. 24BR1033101)	In house check: Oct 03
Fluke Process Calibrator Type 702	SN: 6295803	3-Sep-01 (ELCAL, No.2360)	Sep-03

	Name	Function	Signature
Calibrated by:	Nico Vetteri	Technician	
Approved by:	Katja Pokovic	Laboratory Director	

Date issued: August 28, 2003

This calibration certificate is issued as an intermediate solution until the accreditation process (based on ISO/IEC 17025 International Standard) for Calibration Laboratory of Schmid & Partner Engineering AG is completed.

s p e a g

Probe ET3DV6

SN:1788

Manufactured:	May 28, 2003
Last calibration:	August 29, 2003

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

DASY - Parameters of Probe: ET3DV6 SN:1788

Sensitivity in Free Space

			Diode Compression		
NormX	**1.68** $\mu V/(V/m)^2$		DCP X	**95**	mV
NormY	**1.62** $\mu V/(V/m)^2$		DCP Y	**95**	mV
NormZ	**1.71** $\mu V/(V/m)^2$		DCP Z	**95**	mV

Sensitivity in Tissue Simulating Liquid

Head   900 MHz $\varepsilon_r = 41.5 \pm 5\%$ $\sigma = 0.97 \pm 5\%$ mho/m

Valid for f=800-1000 MHz with Head Tissue Simulating Liquid according to EN 50361, P1528-200X

			Boundary effect:	
ConvF X	**6.6** $\pm 9.5\%$ (k=2)			
ConvF Y	**6.6** $\pm 9.5\%$ (k=2)		Alpha	**0.34**
ConvF Z	**6.6** $\pm 9.5\%$ (k=2)		Depth	**2.48**

Head   1800 MHz $\varepsilon_r = 40.0 \pm 5\%$ $\sigma = 1.40 \pm 5\%$ mho/m

Valid for f=1710-1910 MHz with Head Tissue Simulating Liquid according to EN 50361, P1528-200X

			Boundary effect:	
ConvF X	**5.3** $\pm 9.5\%$ (k=2)			
ConvF Y	**5.3** $\pm 9.5\%$ (k=2)		Alpha	**0.43**
ConvF Z	**5.3** $\pm 9.5\%$ (k=2)		Depth	**2.80**

Boundary Effect

Head   **900 MHz**   **Typical SAR gradient: 5 % per mm**

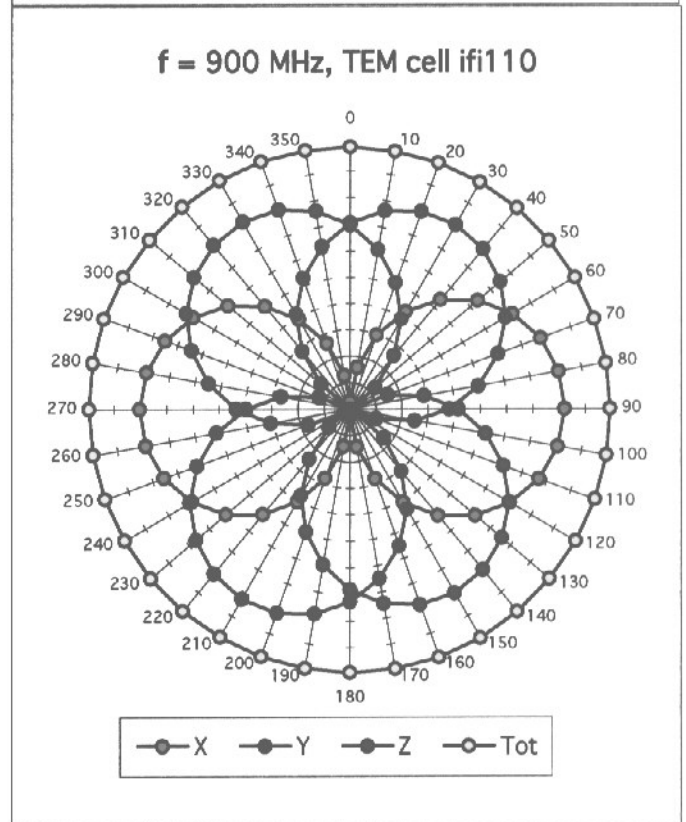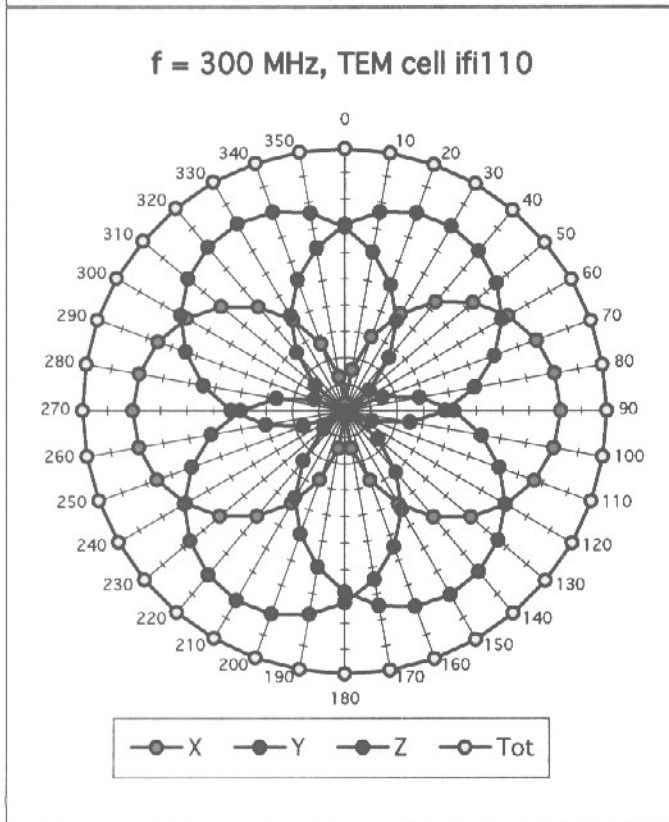|		1 mm	2 mm
Probe Tip to Boundary		1 mm	2 mm
SAR_{be} [%]	Without Correction Algorithm	8.7	5.0
SAR_{be} [%]	With Correction Algorithm	0.3	0.5

Head   **1800 MHz**   **Typical SAR gradient: 10 % per mm**
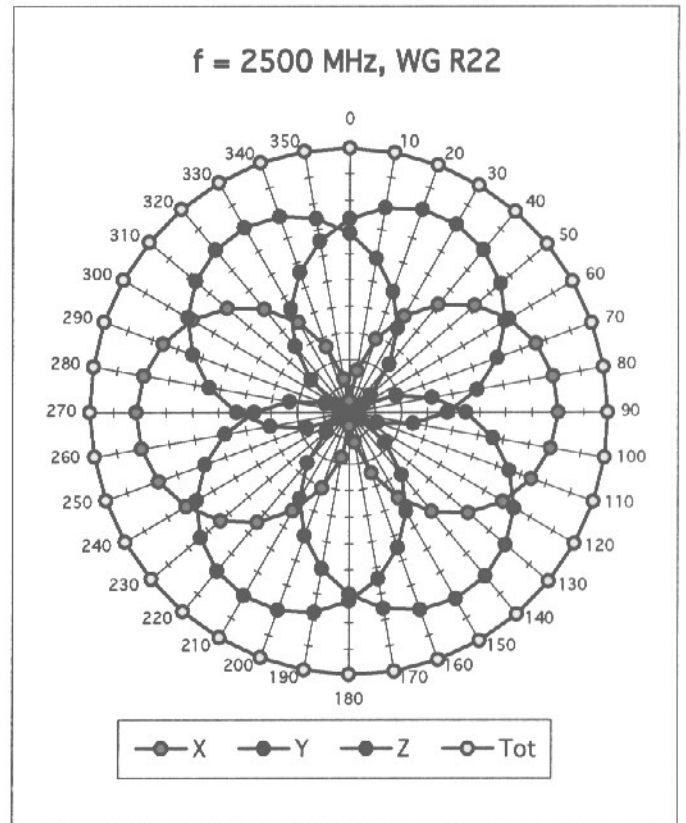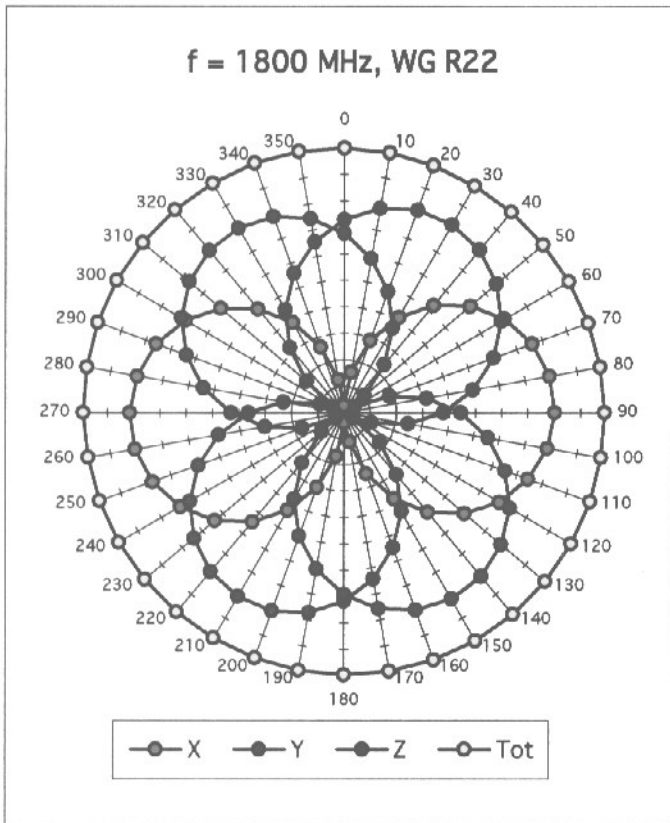
		1 mm	2 mm
Probe Tip to Boundary		1 mm	2 mm
SAR_{be} [%]	Without Correction Algorithm	12.8	8.9
SAR_{be} [%]	With Correction Algorithm	0.3	0.1

Sensor Offset

Probe Tip to Sensor Center	**2.7**	mm
Optical Surface Detection	**1.6 ± 0.2**	mm

Receiving Pattern (φ), θ = 0°

f = 30 MHz, TEM cell ifi110

X — Y — Z — Tot

f = 100 MHz, TEM cell ifi110

X — Y — Z — Tot

f = 300 MHz, TEM cell ifi110

X — Y — Z — Tot

f = 900 MHz, TEM cell ifi110

X — Y — Z — Tot

f = 1800 MHz, WG R22

f = 2500 MHz, WG R22

Isotropy Error (ϕ), $\theta = 0°$