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Testing LaboratoryApplicantCTC advanced GmbH Untertuerkheimer Strasse 6 – 10 66117 Saarbruecken/Germany Phone: + 49 681 5 98 - 0 Fax: + 49 681 5 98 - 9075 Internet: http://www.ctcadvanced.com e-mail: mail@ctcadvanced.comLeica Camera AG Am Leitz-Park 5 35578 Wetzlar/GERMANYContact: Peter Schober e-mail: peter.schober@leica-camera.com Phone: +49 6441 2080-672						
CTC advanced GmbH Leica Camera AG Untertuerkheimer Strasse 6 – 10 Am Leitz-Park 5 66117 Saarbruecken/Germany 35578 Wetzlar/GERMANY Phone: + 49 681 5 98 - 0 Fax: + 49 681 5 98 - 9075 Internet: http://www.ctcadvanced.com e-mail: mail@ctcadvanced.com Phone: + 49 6441 2080-672						
Untertuerkheimer Strasse 6 – 10Am Leitz-Park 566117 Saarbruecken/Germany35578 Wetzlar/GERMANYPhone: + 49 681 5 98 - 035578 Wetzlar/GERMANYFax: + 49 681 5 98 - 9075Contact: Peter SchoberInternet: http://www.ctcadvanced.come-mail: peter.schober@leica-camera.comPhone: + 49 6441 2080-672						
Untertuerkheimer Strasse 6 – 10Am Leitz-Park 566117 Saarbruecken/Germany35578 Wetzlar/GERMANYPhone: + 49 681 5 98 - 035578 Wetzlar/GERMANYFax: + 49 681 5 98 - 9075Contact: Peter SchoberInternet: http://www.ctcadvanced.com e-mail: mail@ctcadvanced.come-mail: phone: +49 6441 2080-672						
For further applied test standards please refer to section 3 of this test report.						
Test Item Kind of test item: Digital Camera Device type: portable device Model name: 6376 S/N serial number: radiated: P 02 conducted: P 10 FCC-ID: FCC-ID: N5A6376 IC: 11245A-6376 Product Marketing Name (PMN): 6376 Hardware Version Identification No. (HVIN): 6376 Hardware status: -/- Software status: -/- Software status: 9.0.0.0 Frequency: see technical details Antenna: Integrated PCB Antenna Battery option: Li-Ion rechargeable Battery Accessories: metal cover, thumb support, handgrip, Hashlight SF 40, Visoflex (see external photos in Annex C) identical prototype Exposure category: general population / uncontrolled environment						

Test Report authorised:

Test performed:

Alexander Hnatovskiy Lab Manager Radio Communications & EMC Marco Scigliano Testing Manager Radio Communications & EMC



1 Table of contents

1	Table of contents2				
2	Genera	Il information	3		
	2.2 / 2.3 S	Notes and disclaimer Application details Statement of compliance Fechnical details	3 3		
3	Test st	andards/ procedures references	5		
	3.1 I	RF exposure limits	6		
4	Summa	ary of Measurement Results	7		
5	Test Er	nvironment	7		
6	Test Se	et-up	8		
-	6.1 6.1 6.1 6.1 6.1 6.1 6.1 6.1 6.1 6.1 6.1	Measurement system .1 System Description .2 Test environment .3 Probe description .4 Phantom description .5 Device holder description .6 Scanning procedure .7 Spatial Peak SAR Evaluation .8 Data Storage and Evaluation .9 Tissue simulating liquids: dielectric properties .10 Tissue simulating liquids: parameters .11 Measurement uncertainty evaluation for SAR test .12 Measurement uncertainty evaluation for System Check .13 System check .14 System check procedure .15 System validation	8 9 10 11 12 13 14 16 17 20 21 21		
7		d Test Results Conducted power measurements WLAN 2450 MHz			
		SAR test results	23		
	7.2 7.2				
8		juipment and ancillaries used for tests			
9		vations			
•	nex A:	System performance check			
	nex B:	DASY5 measurement results			
,		B.1: Liquid depth			
Δnı	nex C:	Photo documentation			
	nex D:	Calibration parameters			
	nex E:	RSS-102 Annex A and B			
	nex F:	Document History			
	Annex G: Further Information				



2 General information

2.1 Notes and disclaimer

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2.2 Application details

Date of receipt of order:	2019-05-20
Date of receipt of test item:	2019-05-30
Start of test:	2019-06-11
End of test:	2019-06-11

2.3 Statement of compliance

The SAR values found for the 6376 Digital Camera are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1 g tissue according to the FCC rule §2.1093, the ANSI/IEEE C 95.1:1992, the NCRP Report Number 86 for uncontrolled environment, according to the Health Canada's Safety Code 6 and the Industry Canada Radio Standards Specification RSS-102 for General Population/Uncontrolled exposure.



2.4 Technical details

Technology	Lowest transmit frequency/MHz	Highest transmit frequency/MHz	Lowest receive Frequency/MHz	Highest receive Frequency/MHz	Kind of modulation	Tested power control level	Test channel low	Test channel middle	Test channel high	Maximum output power/dBm
WLAN	2412	2462	2412	2462	CCK OFDM	max	1	6	11	8.4



3 Test standards/ procedures references

Test Standard	Version	Test Standard Description	
		Recommended Practice for Determining the Peak Spatial- Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques	
RSS-102 Issue 5	2015-03	Radio Frequency Exposure Compliance of Radiocommuni- cation Apparatus (All Frequency Bands)	
Canada's Safety Code No. 6	2015-06	Limits of Human Exposure to Radiofrequency Electromag- netic Fields in the Frequency Range from 3 kHz to 300 GHz	
IEEE Std. C95-3	2002	IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave	
IEEE Std. C95-1	2005	IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.	
IEC 62209-2	2010	Human exposure to radio frequency fields from hand-held and bodymounted wireless communication devices. Human models, instrumentation, and procedures. Procedure to determine the specific absorption rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)	
FCC KDBs:			
KDB 865664D01v01	August 7, 2015	FCC OET SAR measurement requirements 100 MHz to 6 GHz	
KDB 865664D02v01	October 23, 2015	RF Exposure Compliance Reporting and Documentation Considerations	
KDB 447498D01v06	2015 October 23, 2015	Mobile and Portable Devices RF Exposure Procedures and Equipment Authorization Policies	
KDB 648474D04v01	October 23, 2015	SAR Evaluation Considerations for Wireless Handsets	
KDB 248227D01v02	October 23, 2015	SAR Measurement Procedures for 802.11 a/b/g Transmitters	



3.1 RF exposure limits

Human Exposure	Uncontrolled Environment General Population	Controlled Environment Occupational
Spatial Peak SAR* (Brain and Trunk)	1.60 mW/g	8.00 mW/g
Spatial Average SAR** (Whole Body)	0.08 mW/g	0.40 mW/g
Spatial Peak SAR*** (Hands/Feet/Ankle/Wrist)	4.00 mW/g	20.00 mW/g

Table 1: RF exposure limits

The limit applied in this test report is shown in bold letters

Notes:

- The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time
- ** The Spatial Average value of the SAR averaged over the whole body.
- *** The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).



4 Summary of Measurement Results

\square	No deviations from the technical specifications ascertained				
	Deviations from the technical specifications ascertained				
Maximum SAR value (W/kg)					
reported limit					
head for 1g		0.586	1.6		
body worn 0 mm distance for 1g		0.586	1.6		
extremity 0 mm distance for 10g		0.173	4.0		

5 Test Environment

Ambient temperature:	20 – 24 °C
Tissue Simulating liquid:	20 – 24 °C
Relative humidity content:	40 – 50 %

Relative humidity content:	40 – 50 %
Air pressure:	not relevant for this kind of testing
Power supply:	230 V / 50 Hz

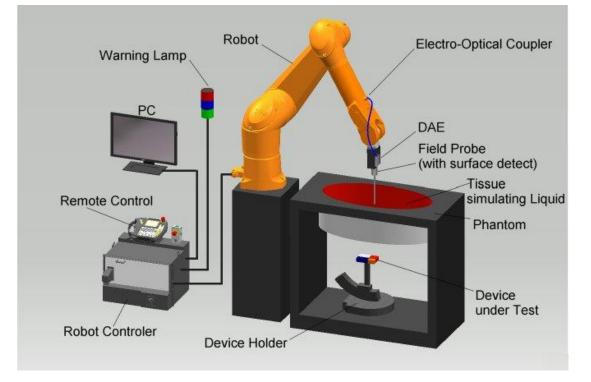
Exact temperature values for each test are shown in the table(s) under 7.1 and/or on the measurement plots.



6 Test Set-up

6.1 Measurement system

6.1.1 System Description



- The DASY system for performing compliance tests consists of the following items:
- A standard high precision 6-axis robot (Stäubli RX/TX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid.
- A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, ADconversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The <u>Electro-Optical Coupler (EOC)</u> performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY measurement server.
- The DASY measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows 7.
- DASY software and SEMCAD data evaluation software.
- Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.
- The generic twin phantom enabling the testing of left-hand and right-hand usage.
- The triple flat and eli phantom for the testing of handheld and body-mounted wireless devices.
- The device holder for handheld mobile phones and mounting device adaptor for laptops
- Tissue simulating liquid mixed according to the given recipes.
- System check dipoles allowing to validate the proper functioning of the system.



6.1.2 Test environment

The DASY measurement system is placed in a laboratory room within an environment which avoids influence on SAR measurements by ambient electromagnetic fields and any reflection from the environment. The pictures at the beginning of the photo documentation show a complete view of the test environment. The system allows the measurement of SAR values larger than 0.005 mW/g.

6.1.3 **Probe description**

isotropic E-Field Prob	Isotropic E-Field Probe ES3DV3 for Dosimetric Measurements					
Technical data according to manufacturer information						
Construction Symmetrical design with triangular core						
	Interleaved sensors					
	Built-in shielding against static charges					
	PEEK enclosure material (resistant to organic solvents,					
	e.g., butyl diglycol)					
Calibration	Calibration certificate in Appendix D					
Frequency	10 MHz to 3 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 3					
	GHz)					
Directivity	± 0.2 dB in HSL (rotation around probe axis)					
	± 0.3 dB in HSL (rotation normal to probe axis)					
Dynamic range	5 μ W/g to > 100 mW/g; Linearity: ± 0.2 dB					
Dimensions	Overall length: 330 mm					
	Tip length: 20 mm					
	Body diameter: 12 mm					
	Tip diameter: 3.9 mm					
	Distance from probe tip to dipole centers: 2.0 mm					
Application	General dosimetry up to 3 GHz					
	Compliance tests of mobile phones					
	Fast automatic scanning in arbitrary phantoms (ES3DV3)					
Isotropic E-Field Probe EX3DV4 for Dosimetric Measurements						
	according to manufacturer information					
Construction	Symmetrical design with triangular core					
	Interleaved sensors					
	Built-in shielding against static charges					
	PEEK enclosure material (resistant to organic solvents, e.g.,					
	DGBE)					
Calibration	ISO/IEC 17025 calibration service available.					
Calibration Frequency	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to					
Frequency	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz)					
	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz) ± 0.3 dB in HSL (rotation around probe axis)					
Frequency Directivity	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz) ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis)					
Frequency	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz) ± 0.3 dB in HSL (rotation around probe axis)					
Frequency Directivity	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz) ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis) 10 µW/g to > 100 mW/g; Linearity: ± 0.2 dB (noise: typically<1					
Frequency Directivity Dynamic range	$\begin{array}{c c} ISO/IEC 17025 \ calibration \ service \ available. \\ \hline 10 \ MHz \ to \ >6 \ GHz \ (dosimetry); \ Linearity: \ \pm \ 0.2 \ dB \ (30 \ MHz \ to \ 6 \ GHz) \\ \hline \pm \ 0.3 \ dB \ in \ HSL \ (rotation \ around \ probe \ axis) \\ \hline \pm \ 0.5 \ dB \ in \ tissue \ material \ (rotation \ normal \ to \ probe \ axis) \\ \hline \pm \ 0.5 \ dB \ in \ tissue \ material \ (rotation \ normal \ to \ probe \ axis) \\ \hline 10 \ \mu W/g \ to \ > \ 100 \ mW/g; \ Linearity: \ \pm \ 0.2 \ dB \ (noise: \ typically<1 \ \mu W/g) \\ \hline Overall \ length: \ 337 \ mm \ (Tip: \ 20mm) \\ \ Tip \ length: \ 2.5 \ mm \ (Body: \ 12mm) \end{array}$					
Frequency Directivity Dynamic range Dimensions	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz) ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis) 10 µW/g to > 100 mW/g; Linearity: ± 0.2 dB (noise: typically<1 µW/g)					
Frequency Directivity Dynamic range	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz) ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis) 10 µW/g to > 100 mW/g; Linearity: ± 0.2 dB (noise: typically<1 µW/g)					
Frequency Directivity Dynamic range Dimensions	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz) ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis) 10 µW/g to > 100 mW/g; Linearity: ± 0.2 dB (noise: typically<1 µW/g)					
Frequency Directivity Dynamic range Dimensions	ISO/IEC 17025 calibration service available. 10 MHz to >6 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 6 GHz) ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis) 10 µW/g to > 100 mW/g; Linearity: ± 0.2 dB (noise: typically<1 µW/g)					



6.1.4 Phantom description

The used SAM Phantom meets the requirements specified in FCC KDB865664 D01 for Specific Absorption Rate (SAR) measurements.

The phantom consists of a fibreglass shell integrated in a wooden table. It allows left-hand and right-hand head as well as body-worn measurements with a maximum liquid depth of 18 cm in head position and 22 cm in planar position (body measurements). The thickness of the Phantom shell is 2 mm +/- 0.1 mm.



-ear reference point right hand side

 \checkmark ear reference point left hand side

reference point flat position



Triple Modular Phantom consists of three identical modules which can be installed and removed separately without emptying the liquid. It includes three reference points for phantom installation. Covers prevent evaporation of the liquid. Phantom material is resistant to DGBE based tissue simulating liquids.



6.1.5 Device holder description

The DASY device holder has two scales for device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The plane between the ear openings and the mouth tip has a rotation angle of 65°. The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. This device holder is used for standard mobile phones or PDA's only. If necessary an additional support of polystyrene material is used.



Larger DUT's (e.g. notebooks) cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values.

Therefore those devices are normally only tested at the flat part of the SAM.



6.1.6 Scanning procedure

- The DASY installation includes predefined files with recommended procedures for measurements and system check. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.
- The "reference" and "drift" measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT's output power and should vary max. +/- 5 %.
- The highest integrated SAR value is the main concern in compliance test applications. These values can mostly be found at the inner surface of the phantom and cannot be measured directly due to the sensor offset in the probe. To extrapolate the surface values, the measurement distances to the surface must be known accurately. A distance error of 0.5mm could produce SAR errors of 6% at 1800 MHz. Using predefined locations for measurements is not accurate enough. Any shift of the phantom (e.g., slight deformations after filling it with liquid) would produce high uncertainties. For an automatic and accurate detection of the phantom surface, the DASY5 system uses the mechanical surface detection. The detection is always at touch, but the probe will move backward from the surface the indicated distance before starting the measurement.
- The "area scan" measures the SAR above the DUT or verification dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The robot performs a stepped movement along one grid axis while the local electrical field strength is measured by the probe. The probe is touching the surface of the SAM during acquisition of measurement values. The scan uses different grid spacings for different frequency measurements. Standard grid spacing for head measurements in frequency ranges ≤ 2GHz is 15 mm in x- and y-dimension. For higher frequencies a finer resolution is needed, thus for the grid spacing is reduced according the following table:

Area scan grid spacing for different frequency ranges				
Frequency range	Grid spacing			
≤ 2 GHz	≤ 15 mm			
2 – 4 GHz	≤ 12 mm			
4 – 6 GHz	≤ 10 mm			

Grid spacing and orientation have no influence on the SAR result. For special applications where the standard scan method does not find the peak SAR within the grid, e.g. mobile phones with flip cover, the grid can be adapted in orientation. Results of this coarse scan are shown in annex B.

• A "zoom scan" measures the field in a volume around the 2D peak SAR value acquired in the previous "coarse" scan. It uses a fine meshed grid where the robot moves the probe in steps along all the 3 axis (x, y and z-axis) starting at the bottom of the Phantom. The grid spacing for the cube measurement is varied according to the measured frequency range, the dimensions are given in the following table:

Zoom scan grid spacing and volume for different frequency ranges							
Frequency range	Grid spacing for x, y axis	Grid spacing for z axis	Minimum zoom scan volume				
≤ 2 GHz	≤ 8 mm	≤ 5 mm	≥ 30 mm				
2 – 3 GHz	≤ 5 mm*	≤ 5 mm	≥ 28 mm				
3 – 4 GHz	≤ 5 mm*	≤ 4 mm	≥ 28 mm				
4 – 5 GHz	≤ 4 mm*	≤ 3 mm	≥ 25 mm				
5 – 6 GHz	≤ 4 mm*	≤ 2 mm	≥ 22 mm				

* When zoom scan is required and the reported SAR from the area scan based 1-g SAR estimation procedures of KDB Publication 447498 is \leq 1.4 W/kg, \leq 8 mm, \leq 7 mm and \leq 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

DASY is also able to perform repeated zoom scans if more than 1 peak is found during area scan. In this document, the evaluated peak 1g and 10g averaged SAR values are shown in the 2D-graphics in annex B. Test results relevant for the specified standard (see section 3) are shown in table form in section 7.



6.1.7 Spatial Peak SAR Evaluation

The spatial peak SAR - value for 1 and 10 g is evaluated after the Cube measurements have been done. The basis of the evaluation are the SAR values measured at the points of the fine cube grid consisting of all points in the three directions x, y and z. The algorithm that finds the maximal averaged volume is separated into three different stages.

- The data between the dipole center of the probe and the surface of the phantom are extrapolated. This data cannot be measured since the center of the dipole is 1 to 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is about 1 mm (see probe calibration sheet). The extrapolated data from a cube measurement can be visualized by selecting 'Graph Evaluated'.
- The maximum interpolated value is searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10 g) are computed using the 3d-spline interpolation algorithm. If the volume cannot be evaluated (i.e., if a part of the grid was cut off by the boundary of the measurement area) the evaluation will be started on the corners of the bottom plane of the cube.
- All neighbouring volumes are evaluated until no neighbouring volume with a higher average value is found.

Extrapolation

The extrapolation is based on a least square algorithm [W. Gander, Computermathematik, p.168-180]. Through the points in the first 3 cm along the z-axis, polynomials of order four are calculated. These polynomials are then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from each other.

Interpolation

The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a knot"-condition [W. Gander, Computermathematik, p.141-150] (x, y and z -direction) [Numerical Recipes in C, Second Edition, p.123ff].

Volume Averaging

At First the size of the cube is calculated. Then the volume is integrated with the trapezoidal algorithm. 8000 points (20x20x20) are interpolated to calculate the average.

Advanced Extrapolation

DASY uses the advanced extrapolation option which is able to compensate boundary effects on E-field probes.



6.1.8 Data Storage and Evaluation

Data Storage

The DASY software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension ".DA4", ".DA5x". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation by SEMCAD

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Normi, a_{i0} , a_{i1} , a_{i2}
	 Conversion factor 	ConvFi
	 Diode compression point 	Dcpi
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics.



If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot cf/dcp_i$$

with	Vi	= compensated signal of channel i	(i = x, y, z)
	Ui	= input signal of channel i	(i = x, y, z)
	cf	= crest factor of exciting field	(DASY parameter)
	dcpi	= diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field p	$E_i = (V_i / Norm_i \cdot ConvF)^{1/2}$							
H-field p	robes:	$H_i = (V_i)^{1/2} \cdot (a_{i0} + a_{i1}f + a_{i2}f^2)/f$						
with	Vi Normi ConvF aij f Ei Hi	 = compensated signal of channel i = sensor sensitivity of channel i [mV/(V/m)²] for E-field Probes = sensitivity enhancement in solution = sensor sensitivity factors for H-field probes = carrier frequency [GHz] = electric field strength of channel i in V/m = magnetic field strength of channel i in A/m 	(i = x, y, z) (i = x, y, z)					

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = (E_x^2 + E_y^2 + E_z^2)^{1/2}$$

The primary field data are used to calculate the derived field units.

$$SAR = (E_{tot}^2 \cdot \sigma) / (\rho \cdot 1000)$$

with	SAR E _{tot}	 local specific absorption rate in mW/g total field strength in V/m
	σ	= conductivity in [mho/m] or [Siemens/m]
	ρ	= equivalent tissue density in g/cm ³

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid. The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = E_{tot}^2 / 3770$$
 or $P_{pwe} = H_{tot}^2 \cdot 37.7$

with

 P_{pwe} = equivalent power density of a plane wave in mW/cm²

E_{tot} = total electric field strength in V/m

H_{tot} = total magnetic field strength in A/m



6.1.9 Tissue simulating liquids: dielectric properties

The following materials are used for producing the tissue-equivalent materials.

(Liquids used for tests described in section 7. are marked with \boxtimes):

Ingredients (% of weight)		Frequency (MHz)													
frequency band	450	750	835	900	1450	1750	1900	2450	5000						
Water	38.56	41.1	41.45	40.92	54.37	55.35	55.19	54.7	64 - 78						
Salt (NaCl)	3.95	1.4	1.45	1.48	0.63	0.38	0.19	0.0	2 - 3						
Sugar	56.32	57.0	56.0	56.5	0.0	0.0	0.0	0.0	0.0						
HEC	0.98	0.2	1.0	1.0	0.0	0.0	0.0	0.0	0.0						
Bactericide	0.19	0.2	0.1	0.1	0.1	0.1	0.1	0.1	0.0						
Tween 20	0.0	0.0	0.0	0.0	44.90	44.17	44.52	45.2	0.0						
Emulsifiers	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	9 - 15						
Mineral Oil	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	11 - 18						

Table 2: Head tissue dielectric properties

Salt: 99+% Pure Sodium Chloride Sugar: 98+% Pure Sucrose

Water: De-ionized, $16M\Omega$ + resistivity HEC: Hydroxyethyl Cellulose

Tween 20: Polyoxyethylene (20) sorbitan monolaurate

6.1.10 Tissue simulating liquids: parameters

	F	Target h	ead tissue	Me		N4			
Liquid HSL	Freq. (MHz)	Permittivity	Conductivity	Permittivity	Dev.	Cond	uctivity	Dev.	Measurement date
TISE	(101112)	Permittivity	(S/m)	Permilivity	%	۳3	(S/m)	%	uale
2450	2412	39.27	1.77	38.4	-2.2	13.11	1.76	-0.4	2019-06-11
	2437	39.22	1.79	38.3	-2.3	13.18	1.79	-0.1	
	2450	39.20	1.80	38.3	-2.3	13.24	1.80	0.2	
	2462	39.18	1.81	38.3	-2.4	13.28	1.82	0.3	

Table 3: Parameter of the head tissue simulating liquid

Note: The dielectric properties have been measured using the contact probe method at 22°C.



6.1.11 Measurement uncertainty evaluation for SAR test

According to IEEE 1528/2003 aSource of uncertainty \pm %Measurement SystemProbe calibration \pm 6.0 %Axial isotropy \pm 4.7 %Hemispherical isotropy \pm 9.6 %Boundary effects \pm 1.0 %Probe linearity \pm 4.7 %System detection limits \pm 1.0 %Readout electronics \pm 0.3 %Response time \pm 0.8 %Integration time \pm 2.6 %RF ambient noise \pm 3.0 %Probe positioner \pm 0.4 %Probe positioning \pm 2.9 %Max.SAR evaluation \pm 1.0 %Power drift \pm 5.0 %Power drift \pm 5.0 %Liquid conductivity (target) \pm 5.0 %Liquid permittivity (meas.) \pm 5.0 %Liquid permittivity (meas.) \pm 5.0 %	DASY5 Uncertainty Budget												
Source of uncertainty \pm %Measurement SystemProbe calibration \pm 6.0 %Axial isotropy \pm 4.7 %Hemispherical isotropy \pm 9.6 %Boundary effects \pm 1.0 %Probe linearity \pm 4.7 %System detection limits \pm 1.0 %Readout electronics \pm 0.3 %Response time \pm 0.8 %Integration time \pm 2.6 %RF ambient noise \pm 3.0 %Probe positioner \pm 0.4 %Probe positioning \pm 2.9 %Max.SAR evaluation \pm 1.0 %Test Sample Related $=$ Device positioning \pm 2.9 %Power drift \pm 5.0 %Phantom and Set-up $=$ Phantom uncertainty \pm 4.0 %Liquid conductivity (target) \pm 5.0 %Liquid permittivity (target) \pm 5.0 %	and IEC 62209-	1 for the	e 300 l	MHz - 3	B GHz rang	е							
Measurement SystemProbe calibration \pm Axial isotropy \pm Hemispherical isotropy \pm Hemispherical isotropy \pm Hemispherical isotropy \pm Boundary effects \pm \pm 1.0Probe linearity \pm \pm 1.0NoReadout electronics \pm \pm 0.3NoResponse time \pm \pm 0.8Integration time \pm \pm 3.0NoRF ambient noise \pm \pm 3.0NoProbe positioner \pm \pm 0.4NoProbe positioning \pm \pm 2.9Max.SAR evaluation \pm \pm 1.0NoTest Sample RelatedDevice positioning \pm \pm 5.0NoPhantom and Set-upPhantom uncertainty \pm \pm 5.0NoLiquid conductivity (target) \pm \pm 5.0NoLiquid permittivity (target) \pm \pm 5.0No	Probability	Divisor	Ci	Ci	Standar	d Uncertainty	v_i^2 or						
Probe calibration \pm 6.0%Axial isotropy \pm 4.7%Hemispherical isotropy \pm 9.6%Boundary effects \pm 1.0%Probe linearity \pm 4.7%System detection limits \pm 1.0%Readout electronics \pm 0.3%Response time \pm 0.8%Integration time \pm 2.6%RF ambient noise \pm 3.0%Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Device positioning \pm 2.9%Device holder uncertainty \pm 3.6%Phantom and Set-up $=$ $=$ $=$ Phantom uncertainty \pm $=$ $=$ Liquid conductivity (target) \pm $=$ $=$ Liquid permittivity (target) \pm $=$ <td>Distribution</td> <td></td> <td>(1g)</td> <td>(10g)</td> <td>± %, (1g)</td> <td>± %, (10g)</td> <td>V_{eff}</td>	Distribution		(1g)	(10g)	± %, (1g)	± %, (10g)	V _{eff}						
Axial isotropy \pm 4.7%Hemispherical isotropy \pm 9.6%Boundary effects \pm 1.0%Probe linearity \pm 4.7%System detection limits \pm 1.0%Readout electronics \pm 0.3%Response time \pm 0.8%Integration time \pm 2.6%RF ambient noise \pm 3.0%Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Device positioning \pm 2.9%Device holder uncertainty \pm 3.6%Power drift \pm 5.0%Liquid conductivity (target) \pm 5.0%Liquid permittivity (target) \pm 5.0%													
Hemispherical isotropy \pm 9.6%Boundary effects \pm 1.0%Probe linearity \pm 4.7%System detection limits \pm 1.0%Readout electronics \pm 0.3%Response time \pm 0.8%Integration time \pm 2.6%RF ambient noise \pm 3.0%Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Device positioning \pm 2.9%Device positioning \pm 2.9%Device positioning \pm 2.9%Device nolder uncertainty \pm 3.6%Phantom and Set-up $=$ $=$ $=$ Phantom uncertainty \pm \pm $=$ Liquid conductivity (target) \pm $=$ $=$ Liquid permittivity (target) \pm $=$	Normal	1	1	1	± 6.0 %		∞						
Boundary effects \pm 1.0%Probe linearity \pm 4.7%System detection limits \pm 1.0%Readout electronics \pm 0.3%Response time \pm 0.8%Integration time \pm 2.6%RF ambient noise \pm 3.0%Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Device positioning \pm 2.9%Device holder uncertainty \pm 3.6%Power drift \pm 5.0%Phantom uncertainty \pm 4.0%Liquid conductivity (target) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	0.7	0.7	± 1.9 %		∞						
Probe linearity \pm 4.7%System detection limits \pm 1.0%Readout electronics \pm 0.3%Response time \pm 0.8%Integration time \pm 2.6%RF ambient noise \pm 3.0%Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Device positioning \pm 2.9%Device positioning \pm 2.9%Device positioning \pm 2.9%Device nolder uncertainty \pm 3.6%Power drift \pm 5.0 %Liquid conductivity (target) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	0.7	0.7	± 3.9 %	± 3.9 %	8						
System detection limits \pm 1.0%Readout electronics \pm 0.3%Response time \pm 0.8%Integration time \pm 2.6%RF ambient noise \pm 3.0%Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Device positioning \pm 2.9%Device positioning \pm 2.9%Device positioning \pm 2.9%Device positioning \pm 2.9%Device nolder uncertainty \pm 3.6%Power drift \pm 5.0 %Phantom and Set-up \pm 5.0%Liquid conductivity (target) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	1	1	± 0.6 %	± 0.6 %	∞						
Readout electronics \pm 0.3%Response time \pm 0.8%Integration time \pm 2.6%RF ambient noise \pm 3.0%RF ambient reflections \pm 3.0%Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Test Sample RelatedDevice positioning \pm 2.9%Device holder uncertainty \pm 3.6%Power drift \pm 5.0%Phantom and Set-upPhantom uncertainty \pm 5.0%Liquid conductivity (target) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	1	1	± 2.7 %	± 2.7 %	∞						
Response time \pm 0.8%Integration time \pm 2.6%RF ambient noise \pm 3.0%RF ambient reflections \pm 3.0%Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Test Sample RelatedDevice positioning \pm 2.9%Device holder uncertainty \pm 3.6%Power drift \pm 5.0%Phantom and Set-upPhantom uncertainty \pm 5.0%Liquid conductivity (target) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	1	1	± 0.6 %	± 0.6 %	8						
Integration time \pm 2.6 $\%$ RF ambient noise \pm 3.0 $\%$ RF ambient reflections \pm 3.0 $\%$ Probe positioner \pm 0.4 $\%$ Probe positioning \pm 2.9 $\%$ Max.SAR evaluation \pm 1.0 $\%$ Test Sample Related $\%$ Device positioning \pm 2.9 $\%$ Device holder uncertainty \pm 3.6 $\%$ Power drift \pm 5.0 $\%$ Phantom and Set-up $\%$ Phantom uncertainty \pm 5.0 $\%$ Liquid conductivity (target) \pm 5.0 $\%$ Liquid permittivity (target) \pm 5.0 $\%$	Normal	1	1	1	± 0.3 %	± 0.3 %	8						
RF ambient noise \pm 3.0 $\%$ RF ambient reflections \pm 3.0 $\%$ Probe positioner \pm 3.0 $\%$ Probe positioning \pm 2.9 $\%$ Max.SAR evaluation \pm 1.0 $\%$ Test Sample Related \bullet Device positioning \pm 2.9 $\%$ Device holder uncertainty \pm 3.6 $\%$ Power drift \pm 5.0 $\%$ Phantom and Set-up \bullet \bullet Phantom uncertainty \pm 5.0 $\%$ Liquid conductivity (target) \pm 5.0 $\%$ Liquid permittivity (target) \pm 5.0 $\%$	Rectangular	√ 3	1	1	± 0.5 %	± 0.5 %	8						
RF ambient reflections \pm 3.0 $\%$ Probe positioner \pm 0.4 $\%$ Probe positioning \pm 2.9 $\%$ Max.SAR evaluation \pm 1.0 $\%$ Test Sample Related \bullet Device positioning \pm 2.9 $\%$ Device holder uncertainty \pm 3.6 $\%$ Power drift \pm 5.0 $\%$ Phantom and Set-up \bullet \bullet Phantom uncertainty \pm 5.0 $\%$ Liquid conductivity (target) \pm 5.0 $\%$ Liquid permittivity (target) \pm 5.0 $\%$	Rectangular	√ 3	1	1	± 1.5 %	± 1.5 %	8						
Probe positioner \pm 0.4%Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Test Sample RelatedDevice positioning \pm 2.9%Device holder uncertainty \pm 3.6%Power drift \pm 5.0%Phantom and Set-upPhantom uncertainty \pm 5.0%Liquid conductivity (target) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	8						
Probe positioning \pm 2.9%Max.SAR evaluation \pm 1.0%Test Sample RelatedDevice positioning \pm 2.9%Device holder uncertainty \pm 3.6%Power drift \pm 5.0%Phantom and Set-upPhantom uncertainty \pm 5.0%Liquid conductivity (target) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	8						
Max.SAR evaluation \pm 1.0%Test Sample Related \pm 2.9%Device positioning \pm 2.9%Device holder uncertainty \pm 3.6%Power drift \pm 5.0 %Phantom and Set-up \pm 5.0 %Phantom uncertainty \pm 4.0 %Liquid conductivity (target) \pm 5.0 %Liquid conductivity (meas.) \pm 5.0 %Liquid permittivity (target) \pm 5.0 %	Rectangular	√ 3	1	1	± 0.2 %	± 0.2 %	8						
Test Sample RelatedDevice positioning \pm 2.9 %Device holder uncertainty \pm 3.6 %Power drift \pm 5.0 %Phantom and Set-upPhantom uncertainty \pm 4.0 %Liquid conductivity (target) \pm 5.0 %Liquid permittivity (target) \pm 5.0 %	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	8						
Device positioning \pm 2.9%Device holder uncertainty \pm 3.6%Power drift \pm 5.0 %Phantom and Set-up \pm 5.0 %Liquid conductivity (target) \pm 5.0 %Liquid conductivity (meas.) \pm 5.0 %Liquid permittivity (target) \pm 5.0 %	Rectangular	√ 3	1	1	± 0.6 %	± 0.6 %	8						
Device holder uncertainty \pm 3.6%Power drift \pm 5.0%Phantom and Set-upPhantom uncertainty \pm 4.0%Liquid conductivity (target) \pm 5.0%Liquid conductivity (meas.) \pm 5.0%Liquid permittivity (target) \pm 5.0%													
Power drift \pm 5.0 %Phantom and Set-up \pm 4.0 %Phantom uncertainty \pm 4.0 %Liquid conductivity (target) \pm 5.0 %Liquid conductivity (meas.) \pm 5.0 %Liquid permittivity (target) \pm 5.0 %	Normal	1	1	1	± 2.9 %	± 2.9 %	145						
Phantom and Set-upPhantom uncertainty \pm 4.0Liquid conductivity (target) \pm 5.0Liquid conductivity (meas.) \pm 5.0Liquid permittivity (target) \pm 5.0%	Normal	1	1	1	± 3.6 %	± 3.6 %	5						
Phantom uncertainty \pm 4.0%Liquid conductivity (target) \pm 5.0%Liquid conductivity (meas.) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	1	1	± 2.9 %	± 2.9 %	8						
Liquid conductivity (target) \pm 5.0%Liquid conductivity (meas.) \pm 5.0%Liquid permittivity (target) \pm 5.0%													
Liquid conductivity (meas.) \pm 5.0%Liquid permittivity (target) \pm 5.0%	Rectangular	√ 3	1	1	± 2.3 %	± 2.3 %	8						
Liquid permittivity (target) ± 5.0 %	Rectangular	√ 3	0.64	0.43	± 1.8 %	± 1.2 %	∞						
	Rectangular	√ 3	0.64	0.43	± 1.8 %	± 1.2 %	8						
Liquid permittivity (mass) + 50 %	Rectangular	√ 3	0.6	0.49	± 1.7 %	± 1.4 %	8						
± 1000 ± 1000 ± 1000	Rectangular	√ 3	0.6	0.49	± 1.7 %	± 1.4 %	∞						
Combined Std.					± 11.1 %	± 10.8 %	387						
Expanded Std.					± 22.1 %	± 21.6 %							

Table 4: Measurement uncertainties

Worst-Case uncertainty budget for DASY5 assessed according to IEEE 1528/2003.

The budget is valid for 2G and 3G communication signals and frequency range 300MHz - 3 GHz. For these conditions it represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



Relative	DASY5 Un	certainty Bu	udget	for S/	AR Te	sts		
According to IEE	E 1528/2013	and IEC62209	/2011 fc	or the	0.3 - 30	GHz range		
Error Description	certainty Val	Probability	Divisor	Ci	Ci	Standard	d Uncertainty	v_i^2 or
End Description	± %	Distribution		(1g)	(10g)	± %, (1g)	± %, (10g)	V _{eff}
Measurement System								
Probe calibration	± 6.0 %	Normal	1	1	1	± 6.0 %	± 6.0 %	∞
Axial isotropy	± 4.7 %	Rectangular	√ 3	0.7	0.7	± 1.9 %		∞
Hemispherical isotropy	± 9.6 %	Rectangular	√ 3	0.7	0.7	± 3.9 %		∞
Boundary effects	± 1.0 %	Rectangular	√ 3	1	1	± 0.6 %		∞
Probe linearity	± 4.7 %	Rectangular	√ 3	1	1	± 2.7 %		∞
System detection limits	± 1.0 %	Rectangular	√ 3	1	1	± 0.6 %		∞
Modulation Response	± 2.4 %	Rectangular	√ 3	1	1	± 1.4 %	± 1.4 %	∞
Readout electronics	± 0.3 %	Normal	1	1	1	± 0.3 %	± 0.3 %	8
Response time	± 0.8 %	Rectangular	√ 3	1	1	± 0.5 %	± 0.5 %	8
Integration time	± 2.6 %	Rectangular	√ 3	1	1	± 1.5 %	± 1.5 %	8
RF ambient noise	± 3.0 %	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	8
RF ambient reflections	± 3.0 %	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	8
Probe positioner	± 0.4 %	Rectangular	√ 3	1	1	± 0.2 %	± 0.2 %	8
Probe positioning	± 2.9 %	Rectangular	√ 3	1	1	± 1.7 %	± 1.7 %	8
Max. SAR evaluation	± 2.0 %	Rectangular	√ 3	1	1	± 1.2 %	± 1.2 %	8
Test Sample Related								
Device positioning	± 2.9 %	Normal	1	1	1	± 2.9 %	± 2.9 %	145
Device holder uncertainty	± 3.6 %	Normal	1	1	1	± 3.6 %	± 3.6 %	5
Power drift	± 5.0 %	Rectangular	√ 3	1	1	± 2.9 %	± 2.9 %	8
Phantom and Set-up								
Phantom uncertainty	± 6.1 %	Rectangular	√ 3	1	1	± 3.5 %	± 3.5 %	8
SAR correction	± 1.9 %	Rectangular	√ 3	1	0.84	± 1.1 %	± 0.9 %	8
Liquid conductivity (meas.)	± 5.0 %	Rectangular	√ 3	0.78	0.71	± 2.3 %	± 2.0 %	8
Liquid permittivity (meas.)	± 5.0 %	Rectangular	√ 3	0.26	0.26	± 0.8 %	± 0.8 %	8
Temp. Unc Conductivity	± 3.4 %	Rectangular	√ 3	0.78	0.71	± 1.5 %	± 1.4 %	8
Temp. Unc Permittivity	± 0.4 %	Rectangular	√ 3	0.23	0.26	± 0.1 %	± 0.1 %	8
Combined Uncertainty						± 11.3 %	± 11.3 %	330
Expanded Std.						± 22.7 %	± 22.5 %	
Uncertainty						± 22.1 %	± 22.5 %	
Table F. Magguramont upon								

Table 5: Measurement uncertainties

Worst-Case uncertainty budget for DASY5 assessed according to IEEE 1528/2013 and IEC 62209-1/2011 standards. The budget is valid for the frequency range 300MHz -3 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



	I	DAS	Y5 (Uncertainty	Budg	et						
According	to IE	C 62	209-	2/2010 for the	e 300 M	Hz - 6	GHz ra	ange	e			
Source of	Un	certa	inty	Probability	Divisor	Ci	Ci	Ś	Standard	d Uno	certainty	v_i^2 or
uncertainty		Value	e	Distribution		(1g)	(10g)	± 9	%, (1g)	±%	%, (10g)	V _{eff}
Measurement System												
Probe calibration	±	6.6	%	Normal	1	1	1	±	6.6 %	±	6.6 %	∞
Axial isotropy	±	4.7	%	Rectangular	√ 3	0.7	0.7	±	1.9 %	±	1.9 %	∞
Hemispherical isotropy	H	9.6	%	Rectangular	√ 3	0.7	0.7	H	3.9 %	±	3.9 %	8
Boundary effects	±	2.0	%	Rectangular	√ 3	1	1	±	1.2 %	±	1.2 %	∞
Probe linearity	±	4.7	%	Rectangular	√ 3	1	1	±	2.7 %	±	2.7 %	∞
System detection limits	+	1.0	%	Rectangular	√ 3	1	1	H	0.6 %	±	0.6 %	8
Modulation Response	±	2.4	%	Rectangular	√ 3	1	1	±	1.4 %	±	1.4 %	∞
Readout electronics	Ħ	0.3	%	Normal	1	1	1	H	0.3 %	±	0.3 %	8
Response time	±	0.8	%	Rectangular	√ 3	1	1	±	0.5 %	±	0.5 %	∞
Integration time	+	2.6	%	Rectangular	√ 3	1	1	H	1.5 %	±	1.5 %	8
RF ambient noise	H	3.0	%	Rectangular	√ 3	1	1	H	1.7 %	±	1.7 %	8
RF ambient reflections	±	3.0	%	Rectangular	√ 3	1	1	±	1.7 %	±	1.7 %	∞
Probe positioner	±	0.8	%	Rectangular	√ 3	1	1	±	0.5 %	±	0.5 %	∞
Probe positioning	+	6.7	%	Rectangular	√ 3	1	1	+	3.9 %	±	3.9 %	∞
Post-processing	±	4.0	%	Rectangular	√ 3	1	1	±	2.3 %	±	2.3 %	∞
Test Sample Related												
Device positioning	±	2.9	%	Normal	1	1	1	±	2.9 %	±	2.9 %	145
Device holder uncertainty	±	3.6	%	Normal	1	1	1	±	3.6 %	±	3.6 %	5
Power drift	±	5.0	%	Rectangular	√ 3	1	1	±	2.9 %	±	2.9 %	∞
Phantom and Set-up												
Phantom uncertainty	±	7.9	%	Rectangular	√ 3	1	1	±	4.6 %	±	4.6 %	∞
SAR correction	±	1.9	%	Rectangular	√ 3	1	0.84	±	1.1 %	±	0.9 %	∞
Liquid conductivity (meas.)	±	5.0	%	Rectangular	√ 3	0.78	0.71	±	2.3 %	±	2.0 %	∞
Liquid permittivity (meas.)	±	5.0	%	Rectangular	√ 3	0.26	0.26	±	0.8 %	±	0.8 %	∞
Temp. Unc Conductivity	±	3.4	%	Rectangular	√ 3	0.78	0.71	±	1.5 %	±	1.4 %	∞
Temp. Unc Permittivity	±	0.4	%	Rectangular	√ 3	0.23	0.26	±	0.1 %	±	0.1 %	∞
Combined Uncertainty								±	12.7 %	±	12.6 %	330
Expanded Std.								±	25.4 %	±	25.3 %	
Uncertainty								_				

Table 6: Measurement uncertainties.

Worst-Case uncertainty budget for DASY5 assessed according to according to IEC 62209-2/2010 standard. The budget is valid for the frequency range 300MHz - 6 GHz and represents a worst-case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.



6.1.12 Measurement uncertainty evaluation for System Check

Uncertainty of	of a	Syster	n Performa	nce C	heck	with	DA	SY5 S	yst	tem	
		for	the 0.3 - 3	GHz r	ange				-		
Source of	Uncertainty		Probability	Divisor	Ci	Ci	Standard		Unc	ertainty	v ² or
uncertainty		Value	Distribution		(1g)	(10g)	±	%, (1g)	± %, (10g)		' V _{eff}
Measurement System											
Probe calibration	±	6.0 %	Normal	1	1	1	±	6.0 %	±	6.0 %	8
Axial isotropy	±	4.7 %	Rectangular	√ 3	0.7	0.7	±	1.9 %	±	1.9 %	8
Hemispherical isotropy	±	0.0 %	Rectangular	√ 3	0.7	0.7	±	0.0 %	±	0.0 %	8
Boundary effects	±	1.0 %	Rectangular	√ 3	1	1	±	0.6 %	±	0.6 %	8
Probe linearity	±	4.7 %	Rectangular	√ 3	1	1	±	2.7 %	±	2.7 %	8
System detection limits	±	1.0 %	Rectangular	√ 3	1	1	±	0.6 %	±	0.6 %	8
Readout electronics	±	0.3 %	Normal	1	1	1	±	0.3 %	±	0.3 %	8
Response time	±	0.0 %	Rectangular	√ 3	1	1	±	0.0 %	±	0.0 %	8
Integration time	±	0.0 %	Rectangular	√ 3	1	1	±	0.0 %	±	0.0 %	8
RF ambient conditions	+	3.0 %	Rectangular	√ 3	1	1	±	1.7 %	±	1.7 %	8
Probe positioner	±	0.4 %	Rectangular	√ 3	1	1	±	0.2 %	±	0.2 %	8
Probe positioning	±	2.9 %	Rectangular	√ 3	1	1	±	1.7 %	±	1.7 %	8
Max. SAR evaluation	±	1.0 %	Rectangular	√ 3	1	1	±	0.6 %	±	0.6 %	8
Test Sample Related											
Dev. of experimental dipole	±	0.0 %	Rectangular	√ 3	1	1	±	0.0 %	±	0.0 %	8
Source to liquid distance	±	2.0 %	Rectangular	√ 3	1	1	±	1.2 %	±	1.2 %	∞
Power drift	±	3.4 %	Rectangular	√ 3	1	1	±	2.0 %	±	2.0 %	8
Phantom and Set-up											
Phantom uncertainty	±	4.0 %	Rectangular	√ 3	1	1	±	2.3 %	±	2.3 %	8
SAR correction	±	1.9 %	Rectangular	√ 3	1	0.84	±	1.1 %	±	0.9 %	8
Liquid conductivity (meas.)	±	5.0 %	Normal	1	0.78	0.71	±	3.9 %	±	3.6 %	8
Liquid permittivity (meas.)	±	5.0 %	Normal	1	0.26	0.26	±	1.3 %		1.3 %	8
Temp. unc Conductivity	±	1.7 %	Rectangular	√ 3	0.78	0.71	±	0.8 %	±	0.7 %	8
Temp. unc Permittivity	±	0.3 %	Rectangular	√ 3	0.23	0.26	±	0.0 %	±	0.0 %	8
Combined Uncertainty							±	9.1 %	±	8.9 %	330
Expanded Std.								18.2 %		17.9 %	
Uncertainty							±	10.2 %	Ľ.	17.9 %	

Table 7: Measurement uncertainties of the System Check with DASY5 (0.3-3GHz)

Note: Worst case probe calibration uncertainty has been applied for all probes used during the measurements.



6.1.13 System check

The system check is performed for verifying the accuracy of the complete measurement system and performance of the software. The system check is performed with tissue equivalent material according to IEEE 1528. The following table shows system check results for all frequency bands and tissue liquids used during the tests (plot(s) see annex A).

	System performence check (1000 mW)													
System validation Kit	Probe	Frequency	Target SAR _{1g} /mW/g (+/-10%)	Target SAR _{10g} /mW/g (+/- 10%)	Measured SAR _{1g} / mW/g	SAR _{1g} dev.	Measured SAR _{10g} / mW/g	SAR _{10g} dev.	Measured date					
D2450V2 S/N: 710	EX3DV4 S/N: 3944	2450 MHz HSL	51.60	24.00	52.00	0.8%	23.90	-0.4%	2019-06-11					

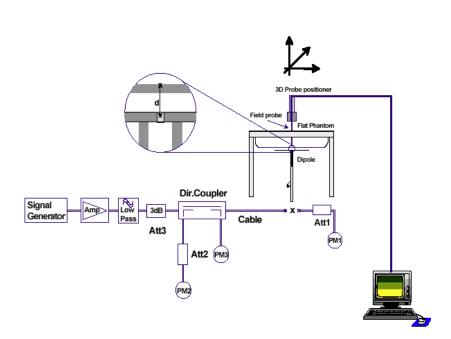
Table 8: Results system check

6.1.14 System check procedure

The system check is performed by using a validation dipole which is positioned parallel to the planar part of the SAM phantom at the reference point. The distance of the dipole to the SAM phantom is determined by a plexiglass spacer. The dipole is connected to the signal source consisting of signal generator and amplifier via a directional coupler, N-connector cable and adaption to SMA. It is fed with a power of 1000 mW for frequencies below 2 GHz or 100 mW for frequencies above 2 GHz. To adjust this power a power meter is used. The power sensor is connected to the cable before the system check to measure the power at this point and do adjustments at the signal generator. At the outputs of the directional coupler both return loss as well as forward power are controlled during the validation to make sure that emitted power at the dipole is kept constant. This can also be checked by the power drift measurement after the test (result on plot).

System check results have to be equal or near the values determined during dipole calibration (target SAR in table above) with the relevant liquids and test system.







6.1.15 System validation

The system validation is performed in a similar way as a system check. It needs to be performed once a SAR measurement system has been established and allows an evaluation of the system accuracy with all components used together with the specified system. It has to be repeated at least once a year or when new system components are used (DAE, probe, phantom, dipole, liquid type).

In addition to the procedure used during system check a system validation also includes checks of probe isotropy, probe modulation factor and RF signal.

The following table lists the system validations relevant for this test report:

Frequency (MHz)	DASY SW	Dipole Type /SN	Probe Type / SN	Calibrated signal type(s)	DAE unit Type / SN	head validation
2450	V52.8.7	D2450V2 / 710	EX3DV4 / 3944	CW	DAE3/ 477	2019-05-22

7 Detailed Test Results

7.1 Conducted power measurements WLAN 2450 MHz

802.	11b	maximum average conducted output power [dBm]						
Band	Ch	1Mbps	2Mbps	5.5Mbps	11Mbps			
2450MHz	1	8.1	8.1	8.1	8.1			
	6	7.5	7.5	7.5	7.5			
	11	7.5	7.5	7.5	7.4			

Table 9: Test results conducted power measurement 802.11b

802.11	9		max	ximum average conducted output power [dBm]					
Band	Ch	6Mbps	9Mbps	12Mbps	18Mbps	24Mbps	36Mbps	48Mbps	54Mbps
2450MHz	1	8.4		8.2	8.1	8.0	7.6	7.6	7.6
	6	7.6		7.4	7.3	7.2	6.9	6.9	6.8
	11	7.6		7.4	7.3	7.2	6.9	6.9	6.8

Table 10: Test results conducted power measurement 802.11g

802.11n H	Г-20		maximum average conducted output power [dBm]									
Band Cł		MCS-0	MCS-1 MCS-2		MCS-3 MCS-4		MCS-5	MCS-6	MCS-7			
Ballu	Ch	6.5Mbps	13Mbps	19.5Mbps	26Mbps	39Mbps	52Mbps	58.5Mbps	65Mbps			
2450MHz	1	8.3	8.0	8.0	8.0	7.9	7.8	7.7	7.7			
	6	7.5	7.2	7.2	7.2	7.0	6.9	6.7	6.9			
	11	7.5	7.1	7.1	7.1	7.0	6.9	6.9	6.9			

Table 11: Test results conducted power measurement 802.11n HT-20



7.2 SAR test results

7.2.1 General description of test procedures

- The DUT is tested using a test software to set test channels and maximum output power to the DUT, as well as for measuring the conducted peak power.
- Test positions as described in the tables above are in accordance with the specified test standard.
- WLAN was tested in 802.11b mode with 1MBit/s.
- Required WLAN test channels were selected according to KDB 248227

7.2.2 Results overview

	measured / extrapolated SAR numbers - WLAN 2450 MHz												
Ch	Freq.	Accessory	Position (<i>mode</i> *)	cond. P _{max} (dBm)		SA	SAR _{1g} (W/kg)			SAR10g (W/kg)			liquid
Cn.	Ch. (MHz)			decl.*	meas.	meas.	extrap.	100% DF	meas.	extrap.	100% DF		(°C)
1	2412		bottom	9.0	8.1	0.000	0.000	0.000	0.000	0.000	0.000	0.00	22.2
1	2412		rear	9.0	8.1	0.146	0.180	0.183	0.055	0.067	0.069	-0.05	22.2
1	2412		rear 30°	9.0	8.1	0.441	0.543	0.554	0.133	0.164	0.167	-0.17	22.2
6	2437		rear 30°	9.0	7.5	0.269	0.380	0.388	0.079	0.111	0.113	0.11	22.2
11	2462		rear 30°	9.0	7.5	0.298	0.421	0.430	0.089	0.125	0.128	-0.19	22.2
1	2412		rear 30° (<i>g-mode</i>)	9.0	8.4	0.484	0.556	0.567	0.144	0.165	0.169	-0.03	22.2
1	2412	metall cover	rear 30°	9.0	8.1	0.456	0.561	0.572	0.138	0.170	0.173	-0.13	22.2
1	2412	thumb support	rear 30°	9.0	8.1	0.431	0.530	0.541	0.131	0.161	0.164	-0.04	22.2
1	2412	handgrip	rear 30°	9.0	8.1	0.394	0.485	0.495	0.116	0.143	0.146	-0.14	22.2
1	2412	flashlight SF 40	rear 30°	9.0	8.1	0.449	0.552	0.564	0.132	0.162	0.166	-0.16	22.2
1	2412	Visoflex	rear 30°	9.0	8.1	0.467	0.575	0.586	0.138	0.170	0.173	0.02	22.2

Table 12: Test results SAR WLAN 2450MHz (see max. SAR plot in Annex B: DASY5 measurement results on page 26 ff.)

*) Mode is only mentioned if it differs from 801.11b mode



8 Test equipment and ancillaries used for tests

To simplify the identification of the test equipment and/or ancillaries which were used, the reporting of the relevant test cases only refer to the test item number as specified in the table below.

Equipment	Туре	Manufacturer	Serial No.	Last Calibration	Frequency (months)
Dosimetric E-Field Probe		Schmid & Partner Engineering AG	3944	May 7, 2019	12
2450 MHz System Validation Dipole	D2450V2	Schmid & Partner Engineering AG	710	November 22, 2018	36
Data acquisition electronics	DAE3V1	Schmid & Partner Engineering AG	477	May 15, 2019	12
Software	DASY52 52.8.7	Schmid & Partner Engineering AG		N/A	
SAM Twin Phantom V5.0	QD 000 P40 C	Schmid & Partner Engineering AG	1813	N/A	
Network Analyser 300 kHz to 6 GHz	8753ES	Agilent Technologies)*	US39174436	December 14, 2017	24
Dielectric Probe Kit	85070C	Hewlett Packard	US99360146	N/A	12
Signal Generator	8665A	Hewlett Packard	2833A00112	December 14, 2017	24
Amplifier	25S1G4 (25 Watt)	Amplifier Reasearch	20452	N/A	
Power Meter	NRP	Rohde & Schwarz	101367	December 11, 2018	24
Power Meter Sensor	NRP Z22	Rohde & Schwarz	100227	December 11, 2018	12
Power Meter Sensor	NRP Z22	Rohde & Schwarz	100234	December 11, 2018	12
Directional Coupler	778D	Hewlett Packard	19171	December 10, 2017	12

)* : Network analyzer probe calibration against air, distilled water and a shorting block performed before measuring liquid parameters.

9 Observations

No observations exceeding those reported with the single test cases have been made.



Annex A: System performance check

Date/Time: 11.06.2019 15:20:02

SystemPerformanceCheck-D2450 HSL 2019-06-11

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 710

Communication System: UID 0, CW (0); Communication System Band: D2450 (2450.0 MHz); Frequency: 2450 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 2450 MHz; σ = 1.804 S/m; ϵ_r = 38.294; ρ = 1000 kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 - SN3944; ConvF(7.77, 7.77, 7.77); Calibrated: 15.05.2019;

- Sensor-Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 26.0

- Electronics: DAE3 Sn477; Calibrated: 07.05.2019

- Phantom: SAM; Type: SAM; Serial: 1043

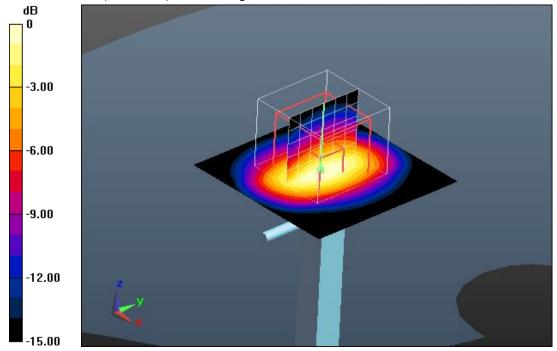
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

HSL2450/d=10mm, Pin=100 mW, dist=1.4mm/Area Scan (51x51x1): Interpolated

grid: dx=1.200 mm, dy=1.200 mm Maximum value of SAR (interpolated) = 9.61 W/kg

HSL2450/d=10mm, Pin=100 mW, dist=1.4mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 71.061 V/m; Power Drift = 0.06 dB Peak SAR (extrapolated) = 10.9 W/kg SAR(1 g) = 5.2 W/kg; SAR(10 g) = 2.39 W/kg Maximum value of SAR (measured) = 8.83 W/kg



0 dB = 8.83 W/kg = 9.46 dBW/kg

Additional information:

ambient temperature: 23.1°C; liquid temperature: 22.2°C



Annex B: DASY5 measurement results

SAR plots for **the highest measured SAR** in each exposure configuration, wireless mode and frequency band combination according to FCC KDB 865664 D02

Date/Time: 11.06.2019 14:15:22

FCC-EN62209-WLAN2450

DUT: LEICA; Type: 6376; Serial: P 02

Communication System: UID 0, WLAN 2450 (0); Communication System Band: 2.4 GHz; Frequency: 2412 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 2412 MHz; σ = 1.76 S/m; ϵ r = 38.4; ρ = 1000 kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 - SN3944; ConvF(7.77, 7.77, 7.77); Calibrated: 15.05.2019;

- Sensor-Surface: 1.4mm (Mechanical Surface Detection (Locations From Previous Scan Used)), Sensor-

Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 26.0

- Electronics: DAE3 Sn477; Calibrated: 07.05.2019

- Phantom: SAM; Type: SAM; Serial: 1043

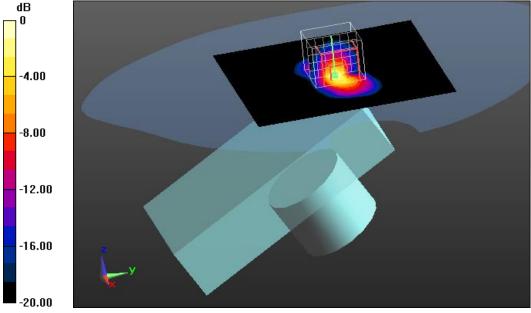
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL2450 - 0 mm/Rear Low (g-mode) 30° tilted (w/o optic)/Area Scan

(101x101x1): Interpolated grid: dx=1.200 mm, dy=1.200 mm Maximum value of SAR (interpolated) = 1.08 W/kg

MSL2450 - 0 mm/Rear Low (g-mode) 30° tilted (w/o optic)/Zoom Scan

(7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 25.424 V/m; Power Drift = -0.03 dB Peak SAR (extrapolated) = 1.74 W/kg SAR(1 g) = 0.484 W/kg; SAR(10 g) = 0.144 W/kg Maximum value of SAR (measured) = 1.15 W/kg



0 dB = 1.15 W/kg = 0.61 dBW/kg

Additional information:

position or distance of DUT to SAM: 0 mm tilted with 30° ambient temperature: 23.1°C; liquid temperature: 22.2°C



FCC-EN62209-WLAN2450

DUT: LEICA; Type: 6376; Serial: P 02

Communication System: UID 0, WLAN 2450 (0); Communication System Band: 2.4 GHz; Frequency: 2412 MHz; Communication System PAR: 0 dB; PMF: 1

Medium parameters used: f = 2412 MHz; σ = 1.76 S/m; ϵ r = 38.4; ρ = 1000 kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5

DASY5 Configuration:

- Probe: EX3DV4 - SN3944; ConvF(7.77, 7.77, 7.77); Calibrated: 15.05.2019;

- Sensor-Surface: 1.4mm (Mechanical Surface Detection (Locations From Previous Scan Used)), Sensor-

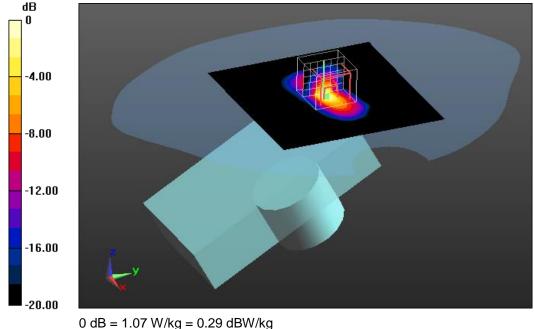
- Surface: 1.4mm (Mechanical Surface Detection), z = 1.0, 26.0
- Electronics: DAE3 Sn477; Calibrated: 07.05.2019
- Phantom: SAM; Type: SAM; Serial: 1043
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

MSL2450 - 0 mm/Rear Low 30° tilted (w/o optic) with Visoflex/Area Scan

(101x101x1): Interpolated grid: dx=1.200 mm, dy=1.200 mm Maximum value of SAR (interpolated) = 0.922 W/kg

MSL2450 - 0 mm/Rear Low 30° tilted (w/o optic) with Visoflex/Zoom Scan 2

(7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm Reference Value = 24.205 V/m; Power Drift = 0.03 dB Peak SAR (extrapolated) = 1.69 W/kg SAR(1 g) = 0.467 W/kg; SAR(10 g) = 0.138 W/kg Maximum value of SAR (measured) = 1.07 W/kg



Additional information:

position or distance of DUT to SAM: 0 mm tilted with 30° with Visoflex attached ambient temperature: 23.1°C; liquid temperature: 22.2°C



Annex B.1: Liquid depth

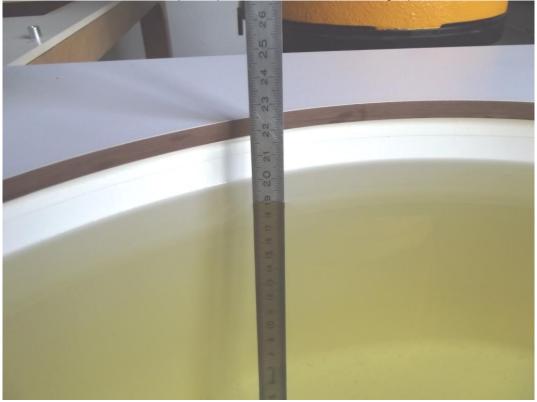


Photo 1: Liquid depth 2450MHz head simulating liquid



Annex C: Photo documentation

Photo documentation is described in the additional document:

Appendix to test report no. 1-7938/19-02-08 Photo documentation

Annex D: Calibration parameters

Calibration parameters are described in the additional document:

Appendix to test report no. 1-7938/19-02-08 Calibration data, Phantom certificate and detail information of the DASY5 System

Annex E: RSS-102 Annex A and B

ICRF documents are described in the additional document:

Appendix to test report no. 1-7938/19-02-08_ICRF RF Technical Brief Cover Sheet acc. To RSS-102 Annex A and Declaration of RX Exposure Compliance Annex B



Annex F: Document History

Version	Applied Changes	Date of Release		
	Initial Release	2019-06-13		

Annex G: Further Information

Glossary

BW	-	Bandwidth
DUT	-	Device under Test
EUT	-	Equipment under Test
FCC	-	Federal Communication Commission
FCC ID	-	Company Identifier at FCC
HW	-	Hardware
IC	-	Industry Canada
Inv. No.	-	Inventory number
N/A	-	not applicable
SAR	-	Specific Absorption Rate
S/N	-	Serial Number
SW	-	Software
UNII	-	Unlicensed National Information Infrastructure