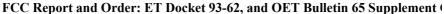
#### **ANSI/IEEE Std. C95.1-1992**

in accordance with the requirements of





# **FCC TEST REPORT**

For

# ASUSTeK COMPUTER INC.

**Pocket PC** 

**Trade Name: ASUS** 

Model: A730

Prepared for

ASUSTeK COMPUTER INC. 4Fl, No. 150, Li-Te Rd., Peitou, Taipei, Taiwan.

Prepared by

Compliance Certification Services Inc. No. 81-1, Lane 210, Bade Rd. 2, Luchu Hsiang, Taoyuan Hsien, (338) Taiwan, R.O.C.

TEL: 886-3-324-0332 FAX: 886-3-324-5235





# **CERTIFICATE OF COMPLIANCE (SAR EVALUATION)**

Date of Test: June 15, 2004

**Applicant:** ASUSTeK COMPUTER INC.

4Fl, No. 150, Li-Te Rd., Peitou,

Taipei, Taiwan.

**Model Number / Trade Name:** A730 / ASUS

**Device Category:** PORTABLE DEVICES

**Exposure Category:** GENERAL POPULATION/UNCONTROLLED EXPOSURE

**Test Sample is a:** Production unit

**Modulation type:** 802.11b

Direct Sequence Spread Spectrum

Tx Frequency:  $2412 \sim 2462 \text{ MHz}$ 

**Max. O/P Power:** 15.59 dBm

(Conducted/Peak)

Max. SAR (1g): 0.130W/kg
Application Type: Certification

FCC Rule Part(s): 15C



Note: This Report is only applicable for 802.11b/g.

This wireless portable device has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC OET 65 Supplement C (released on 6/29/2001 see Test Report).

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.

Approved by:

Reviewed by:

Harris W. Lai

**Executive Vice President** 

Compliance Certification Services Inc.

James Lee Section Manager

Compliance Certification Services Inc.

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#### 1. EUT DESCRIPTION

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**Application Type:** Certification

FCC Rule Part(s): 15C

**Antennas:** PIFA Ant.





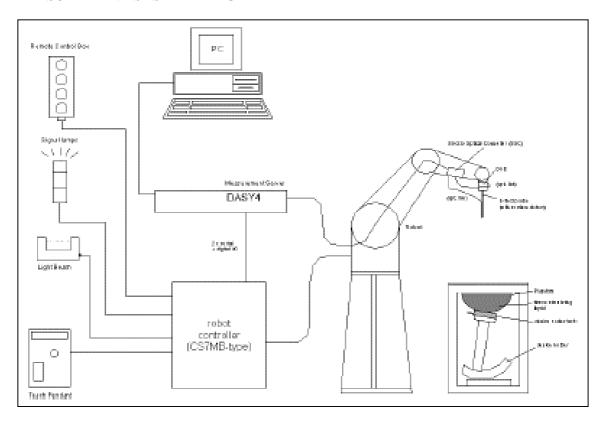
#### 2. REQUIREMENTS FOR COMPLIANCE TESTING DEFINED BY THE FCC

The US Federal Communications Commission has released the report and order "Guidelines for Evaluating the Environmental Effects of RF Radiation", ET Docket No. 93-62 in August 1996 [1]. The order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 mW/g for an uncontrolled environment and 8.0 mW/g for an occupational/controlled environment as recommended by the ANSI/IEEE standard C95.1-1992 [6]. According to the Supplement C of OET Bulletin 65 "Evaluating Compliance with FCC Guide-lines for Human Exposure to Radio frequency Electromagnetic Fields", released on Jun 29, 2001 by the FCC, the device should be evaluated at maximum output power (radiated from the antenna) under "worst-case" conditions for normal or intended use, incorporating normal antenna operating positions, device peak performance frequencies and positions for maximum RF energy coupling.

#### 3. DOSIMETRIC ASSESSMENT SYSTEM

These measurements were performed with the automated near-field scanning system DASY4 from Schmid & Partner Engineering AG (SPEAG). The system is based on a high precision robot (working range greater than 0.9 m) which positions the probes with a positional repeatability of better than  $\pm 0.02$  mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit. The SAR measurements were conducted with the dosimetric probe ES3DV2-SN: 3023 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure with accuracy of better than  $\pm 10\%$ . The spherical isotropy was evaluated with the procedure and found to be better than  $\pm 0.25$  dB. The phantom used was the SAM Twin Phantom as described in FCC supplement C, IEEE P1528 and EN50361.

#### 3.1 MEASUREMENT SYSTEM DIAGRAM



#### The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (St aubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing,
  AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit
  is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the
  EOC.
- The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows XP.
- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing validating the proper functioning of the system.

#### 3.2 SYSTEM COMPONENTS

#### **DASY4 Measurement Server**



The DASY4 measurement server is based on a PC/104 CPU board with a 166MHz low-power Pentium, 32MB chip disk and 64MB RAM. The necessary circuits for communication with either the DAE3 electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY4 I/O-board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation.

The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pinout and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server. Calibration: No calibration required.

#### **Data Acquisition Electronics (DAE)**

The data acquisition electronics (DAE3) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE3 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



#### ES3DV2 Isotropic E-Field Probe for Dosimetric Measurements

**Construction:** Symmetrical design with triangular core Interleaved sensors

Built-in shielding against static charges PEEK enclosure material

(resistant to organic solvents, e.g., glycolether)

Calibration: Basic Broad Band Calibration in air: 10-2500 MHz. Conversion

Factors (CF) for HSL 900 and HSL 1800 CF-Calibration for

other liquids and frequencies upon request.

Frequency: 10 MHz to > 6 GHz; Linearity:  $\pm$  0.2 dB **Directivity:**  $\pm$  0.2 dB in HSL (rotation around probe axis);

 $\pm$  0.3 dB in tissue material (rotation normal to probe axis)

**Dynamic Range:**  $5 \mu \text{W/g to} > 100 \text{ mW/g; Linearity:} \pm 0.2 \text{ dB}$  **Dimensions:** Overall length: 330 mm (Tip: 20 mm) Tip diameter: 3.9 mm (Body: 12 mm)

Distance from probe tip to dipole centers: 2.7 mm

**Application:** General dosimetry up to 6 GHz

Dosimetry in strong gradient fields Compliance tests of mobile phones



E-Field probe



#### SAM Phantom (V4.0)

**Construction:** The shell corresponds to the specifications of the

Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528-200X, CENELEC 50361 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

**Shell Thickness:**  $2 \pm 0.2 \text{ mm}$ 

Filling Volume: Approx. 25 liters

**Dimensions:** Height: 810mm; Length: 1000mm; Width:

500mm



#### **Device Holder for SAM Twin Phantom**

**Construction:** In combination with the Twin SAM Phantom V4.0 or Twin SAM, the

Mounting Device (made from POM) enables the rotation of the mounted transmitter in spherical coordinates, whereby the rotation point is the ear opening. The devices can be easily and accurately positioned according to IEC, IEEE, CENELEC, FCC or other specifications. The device holder can be locked at different phantom locations (left head, right head, and flat phantom).



#### **System Validation Kits**

**Construction:** Symmetrical dipole with 1/4 balun Enables measurement of feedpoint

impedance with NWA Matched for use near flat phantoms filled with brain

simulating solutions Includes distance holder and tripod adaptor.

**Frequency:** 450, 900, 1800, 2450, 5800 MHz

**Return loss:** > 20 dB at specified validation position

Power capability:  $> 100 \mathrm{~W}$  (f  $< 1\mathrm{GHz}$ );  $> 40 \mathrm{~W}$  (f  $> 1\mathrm{GHz}$ )

**Dimensions:** 450V2: dipole length: 270 mm; overall height: 330 mm

D900V2: dipole length: 149 mm; overall height: 330 mm D1800V2: dipole length: 72 mm; overall height: 300 mm

D2450V2: dipole length: 51.5 mm; overall height: 300 mm D5GHzV2: dipole

length: 25.5 mm; overall height: 290 mm



#### 4. EVALUATION PROCEDURES

#### **DATA EVALUATION**

The DASY4 post processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters: - Sensitivity Norm<sub>i</sub>,  $a_{i0}$ ,  $a_{i1}$ ,  $a_{i2}$ 

- Conversion factor  $ConvF_i$ - Diode compression point  $dcp_i$ 

Device parameters: - Frequency f

- Crest factor *cf* 

Media parameters: - Conductivity  $\sigma$ 

- Density ho

These parameters must be set correctly in the software. They can be found in the component documents or be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with  $V_i$  = Compensated signal of channel i (i = x, y, z) $U_i$  = Input signal of channel i (i = x, y, z)

 $U_i$  = Input signal of channel i (i = x, y, z) cf = Crest factor of exciting field (DASY parameter)  $dcp_i$  = Diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes:  $E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$ 

H-field probes:  $H_i = \sqrt{Vi} \cdot \frac{a_{i10} + a_{i11}f + a_{i12}f^2}{f}$ 

with  $V_i$  = Compensated signal of channel i (i = x, y, z)

 $Norm_i$  = Sensor sensitivity of channel i (i = x, y, z)

 $\mu V/(V/m)^2$  for E0field Probes

ConvF = Sensitivity enhancement in solution

*aij* = Sensor sensitivity factors for H-field probes

f = Carrier frequency (GHz)

Ei = Electric field strength of channel i in V/m

Hi = Magnetic field strength of channel i in A/m



The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

 $E_{tot}$  = total field strength in V/m

 $\sigma$  = conductivity in [mho/m] or [Siemens/m]

 $\rho$  = equivalent tissue density in g/cm<sup>3</sup>

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770}$$
 or  $P_{pwe} = H_{tot}^2 \cdot 37.7$ 

with  $P_{pwe}$  = Equivalent power density of a plane wave in mW/cm<sup>2</sup>

 $E_{tot}$  = total electric field strength in V/m

 $H_{tot}$  = total magnetic field strength in A/m

#### **SAR MEASUREMENT PROCEDURES**

The procedure for assessing the peak spatial-average SAR value consists of the following steps:

#### • Power Reference Measurement

The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

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#### Area Scan

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in DASY4 software can find the maximum locations even in relatively coarse grids. The scan area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom. When the area scan's property sheet is brought-up, grid was at to **15 mm by 15 mm** and can be edited by a user.

#### Zoom Scan

Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures **5x5x7** points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more then one maximum, the number of Zoom Scans has to be enlarged accordingly (The default number inserted is 1).

#### • Power Drift measurement

The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have DASY4 software stop the measurements if this limit is exceeded.

#### • Z-Scan

The Z Scan job measures points along a vertical straight line. The line runs along the Z-axis of a one-dimensional grid. A user can anchor the grid to the current probe location. As with any other grids, the local Z-axis of the anchor location establishes the Z-axis of the grid.



## 5. MEASUREMENT UNCERTAINTY

| Un                               | CERTAINTY B             | UDGE ACCORI              | DING TO IE  | EEE P152          | 8                       |                    |
|----------------------------------|-------------------------|--------------------------|-------------|-------------------|-------------------------|--------------------|
| Error Description                | Uncertainty<br>Value ±% | Probability distribution | Divisor     | C <sub>1</sub> 1g | Standard<br>unc.(1g) ±% | $V_1$ or $V_{eff}$ |
| Measurement System               |                         |                          |             |                   |                         |                    |
| Probe calibration                | ±4.8                    | normal                   | 1           | 1                 | ±4.8                    | 8                  |
| Axial isotropy of probe          | ±4.6                    | rectangular              | $\sqrt{3}$  | $(1-Cp)^{1/2}$    | ±1.9                    | 8                  |
| Sph. Isotropy of probe           | ±9.7                    | rectangular              | √3          | $(Cp)^{1/2}$      | ±3.9                    | 8                  |
| Probe linearity                  | ±4.5                    | rectangular              | √3          | 1                 | ±2.7                    | 8                  |
| Detection Limit                  | ±0.9                    | rectangular              | $\sqrt{3}$  | 1                 | ±0.6                    | 8                  |
| Boundary effects                 | ±8.5                    | rectangular              | $\sqrt{3}$  | 1                 | ±4.8                    | 8                  |
| Readoutelectronics               | ±1.0                    | normal                   | 1           | 1                 | ±1.0                    | 8                  |
| Response time                    | ±0.9                    | rectangular              | $\sqrt{3}$  | 1                 | ±0.5                    | 8                  |
| Integration time                 | ±1.2                    | rectangular              | $\sqrt{3}$  | 1                 | ±0.8                    | 8                  |
| Mech Constrains of robot         | ±0.5                    | rectangular              | $\sqrt{3}$  | 1                 | ±0.2                    | 8                  |
| Probe positioning                | ±2.7                    | rectangular              | $\sqrt{3}$  | 1                 | ±1.7                    | 8                  |
| Extrap. And integration          | ±4.0                    | rectangular              | $\sqrt{3}$  | 1                 | ±2.3                    | 8                  |
| RF ambient conditiona            | ±0.54                   | rectangular              | $\sqrt{3}$  | 1                 | ±0.43                   | ∞                  |
| Test Sample Related              |                         |                          |             |                   |                         |                    |
| Device positioning               | ±2.2                    | normal                   | 1           | 1                 | ±2.23                   | 11                 |
| Device holder uncertainty        | ±5                      | normal                   | 1           | 1                 | ±5.0                    | 7                  |
| Power drift                      | ±5                      | rectangular              | $\sqrt{3}$  | 1                 | ±2.9                    | 8                  |
| Phantom and Set up               |                         |                          |             |                   |                         |                    |
| Phantom uncertainty              | <u>±</u> 4              | rectangular              | $\sqrt{3}$  | 1                 | ±2.3                    | 8                  |
| Liquid conductivity              | ±5                      | rectangular              | $\sqrt{3}$  | 0.6               | ±1.7                    | 8                  |
| Liquid conductivity              | ±5                      | rectangular              | $\sqrt{3}$  | 0.6               | ±3.5/1.7                | 8                  |
| Liquid permittivity              | ±5                      | rectangular              | $\sqrt{3}$  | 0.6               | ±1.7                    | 8                  |
| Liquid permittivity              | ±5                      | rectangular              | $\sqrt{3}$  | 0.6               | ±1.7                    | 8                  |
| Combined Standard<br>Uncertainty |                         |                          |             |                   | ±12.14/11.76            |                    |
| Coverage Factor for 95%          |                         | kp=2                     |             |                   |                         |                    |
| Expanded Standard<br>Uncertainty |                         |                          | - 4- IEEE I |                   | ±24.29/23.51            |                    |

Table: Worst-case uncertainty for DASY4 assessed according to IEEE P1528.

The budge is valid for the frequency range 300 MHz to 6G Hz and represents a worst-case analysis.

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#### 6. EXPOSURE LIMIT

(A).Limits for Occupational/Controlled Exposure (W/kg)

Hands, Wrists, Feet and Ankles Whole-Body Partial-Body

0.4 8.0 2.0

(B). Limits for General Population/Uncontrolled Exposure (W/kg)

Partial-Body Whole-Body Hands, Wrists, Feet and Ankles

0.08 16

NOTE: Whole-Body SAR is averaged over the entire body, partial-body SAR is averaged over any

1 gram of tissue defined as a tissue volume in the shape of a cube. SAR for hands, wrists, feet and ankles is averaged over any 10 grams of tissue defined as a tissue volume in the

shape of a cube.

#### **Population/Uncontrolled Environments:**

are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

#### **Occupational/Controlled Environments:**

are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

# **NOTE** GENERAL POPULATION/UNCONTROLLED EXPOSURE PARTIAL BODY LIMIT 1.6 W/kg

#### 7. TYPICAL COMPOSITION OF INGREDIENTS FOR LIQUID TISSUE PHANTOMS

The following tissue formulations are provided for reference only as some of the parameters have not been thoroughly verified. The composition of ingredients may be modified accordingly to achieve the desired target tissue parameters required for routine SAR evaluation.

| Ingredients         |       | Frequency (MHz) |       |      |       |       |       |      |      |      |
|---------------------|-------|-----------------|-------|------|-------|-------|-------|------|------|------|
| (% by weight)       | 45    | 50              | 83    | 35   | 91    | 15    | 19    | 00   | 24   | 50   |
| Tissue Type         | Head  | Body            | Head  | Body | Head  | Body  | Head  | Body | Head | Body |
| Water               | 38.56 | 51.16           | 41.45 | 52.4 | 41.05 | 56.0  | 54.9  | 40.4 | 62.7 | 73.2 |
| Salt (NaCl)         | 3.95  | 1.49            | 1.45  | 1.4  | 1.35  | 0.76  | 0.18  | 0.5  | 0.5  | 0.04 |
| Sugar               | 56.32 | 46.78           | 56.0  | 45.0 | 56.5  | 41.76 | 0.0   | 58.0 | 0.0  | 0.0  |
| HEC                 | 0.98  | 0.52            | 1.0   | 1.0  | 1.0   | 1.21  | 0.0   | 1.0  | 0.0  | 0.0  |
| Bactericide         | 0.19  | 0.05            | 0.1   | 0.1  | 0.1   | 0.27  | 0.0   | 0.1  | 0.0  | 0.0  |
| Triton X-100        | 0.0   | 0.0             | 0.0   | 0.0  | 0.0   | 0.0   | 0.0   | 0.0  | 36.8 | 0.0  |
| DGBE                | 0.0   | 0.0             | 0.0   | 0.0  | 0.0   | 0.0   | 44.92 | 0.0  | 0.0  | 26.7 |
| Dielectric Constant | 43.42 | 58.0            | 42.54 | 56.1 | 42.0  | 56.8  | 39.9  | 54.0 | 39.8 | 52.5 |
| Conductivity (S/m)  | 0.85  | 0.83            | 0.91  | 0.95 | 1.0   | 1.07  | 1.42  | 1.45 | 1.88 | 1.78 |

Salt: 99<sup>+</sup>% Pure Sodium Chloride Sugar: 98<sup>+</sup>% Pure Sucrose Water: De-ionized,  $16 \text{ M}\Omega^+$  resistivity HEC: Hydroxyethyl Cellulose DGBE: 99<sup>+</sup>% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]

Triton X-100 (ultra pure): Polyethylene glycol mono [4-(1, 1, 3, 3-tetramethylbutyl)phenyl]ether

#### 8. MEASUREMENT RESULTS

#### 8.1 SYSTEM PERFORMANCE CHECK

The system performance check is performed prior to any usage of the system in order to guarantee reproducible results. The system performance check verifies that the system operates within its specifications. The system performance check results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

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#### SYSTEM PERFORMANCE CHECK MEASUREMENT CONDITIONS

- The measurements were performed in the flat section of the SAM twin phantom filled with Body simulating liquid of the following parameters.
- The DASY4 system with an E-fileld probe ES3DV2 SN: 3023 was used for the measurements.
- The dipole was mounted on the small tripod so that the dipole feed point was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10 mm (above 1 GHz) from dipole center to the simulating liquid surface.
- The coarse grid with a grid spacing of 10mm was aligned with the dipole.
- Special 5x5x7 fine cube was chosen for cube integration (dx=dy= 7.5 mm, dz= 3 mm).
- Distance between probe sensors and phantom surface was set to 3.0 mm.
- The dipole input power (forward power) was 250 mW±3%.
- The results are normalized to 1 W input power.

#### **Reference SAR values**

The reference SAR values were using measurement results indicated in the dipole calibration document (see table below)

| Frequency (MHz) | 1g SAR | 10g SAR | Local SAR at Surface<br>(Above Feed Point) | Local SAR at Surface (y = 2cm offset from feed point) |
|-----------------|--------|---------|--|---|
| 900             | 10.3   | 6.57    | 16.4                                       | 5.4   |
| 1800            | 38.2   | 20.3    | 69.5                                       | 6.8   |
| 2450(Body)      | 53.2   | 24.3    | 104.2                                      | 7.7   |

# SYSTEM PERFORMANCE CHECK RESULTS

**Dipole:** D2450V2 SN: 728 **Date:** June 15, 2004

**Ambient condition:** Temperature 24.5°C; Relative humidity: 53%

| Body Simulating Liquid |             |             | Parameters Target M |        | Measured | Deviation[%] | Limited[%] |  |
|------------------------|-------------|-------------|---------------------|--------|----------|--------------|------------|--|
| f(MHz)                 | Temp. [°C]  | Depth [cm]  | Parameters          | Target | Measured | Deviation[%] | Limited[%] |  |
|                        | 23.50 15.00 |             | Permitivity:        | 52.70  | 51.00    | -3.23        | ± 5        |  |
| 2450.00                |             | 23.50 15.00 | Conductivity:       | 1.95   | 1.98     | 1.54         | ± 5        |  |
|                        |             |             | 1g SAR:             | 53.20  | 54.00    | 1.50         | ± 5        |  |

## 8.2 TEST LIQUID CONFIRMATION

#### SIMULATING LIQUIDS PARAMETER CHECK

The simulating liquids should be checked at the beginning of a series of SAR measurements to determine of the dielectric parameters are within the tolerances of the specified target values

Date of Issue: June 18, 2004

The relative permittivity and conductivity of the tissue material should be within  $\pm$  5% of the values given in the table below. 5% may not be easily achieved at certain frequencies. Under such circumstances, 10% tolerance may be used until more precise tissue recipes are available

#### IEEE SCC-34/SC-2 P1528 RECOMMENDED TISSUE DIELECTRIC PARAMETERS

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations and extrapolated according to the head parameters specified in P1528

| Target Frequency | Н    | ead     | Bo                | dy     |
|------------------|------|---------|-------------------|--------|
| (MHz)            | ٤r   | σ (S/m) | $\epsilon_{ m r}$ | σ(S/m) |
| 150              | 52.3 | 0.76    | 61.9              | 0.80   |
| 300              | 45.3 | 0.87    | 58.2              | 0.92   |
| 450              | 43.5 | 0.87    | 56.7              | 0.94   |
| 835              | 41.5 | 0.90    | 55.2              | 0.97   |
| 900              | 41.5 | 0.97    | 55.0              | 1.05   |
| 915              | 41.5 | 0.98    | 55.0              | 1.06   |
| 1450             | 40.5 | 1.20    | 54.0              | 1.30   |
| 1610             | 40.3 | 1.29    | 53.8              | 1.40   |
| 1800-2000        | 40.0 | 1.40    | 53.3              | 1.52   |
| 2450             | 39.2 | 1.80    | 52.7              | 1.95   |
| 3000             | 38.5 | 2.40    | 52.0              | 2.73   |
| 5800             | 45.3 | 5.27    | 48.2              | 6.00   |

#### SIMULATING LIQUIDS PARAMETER CHECK RESULTS

**Ambient condition**: Temperature: 24.5°C; Relative humidity: 53% **Date:** June 15, 2004

| Body    | Body Simulating Liquid |            |               | Target | Measured | Deviation[%]  | Limitad[0/.1 |  |
|---------|------------------------|------------|---------------|--------|----------|---------------|--------------|--|
| f (MHz) | Temp. [°C]             | Depth (cm) | Parameters    | Target | Measured | Deviation[/0] | Limited[70]  |  |
| 2450.00 | 23.50                  | 15.00      | Permitivity:  | 52.70  | 51.00    | -3.23         | ± 5          |  |
| 2430.00 | 23.30                  | 13.00      | Conductivity: | 1.95   | 1.98     | 1.54          | ± 5          |  |

## 8.3 EUT TUNE-UP PROCEDURES

The following procedure had been used to prepare the EUT for the SAR test.

- The client supplied a special driver to program the EUT, allowing it to continually transmit the specified maximum power and change the channel frequency.
- o The conducted power was measured at the high, middle and low channel frequency before and after the SAR measurement.
- o The output power(dBm) we measured before SAR test in different transition rate and channel

#### IEEE802.11b:

| 111111111111111111111111111111111111111 | LD.   |       |       |       |
|---|-------|-------|-------|-------|
| Rate<br>CH                              | 1M    | 2M    | 5.5M  | 11M   |
| 1                                       | 15.27 | 15.37 | 15.47 | 15.59 |
| 6                                       | 14.56 | 14.66 | 14.76 | 14.86 |
| 11                                      | 13.74 | 13.84 | 13.94 | 14.04 |

#### 8.4 SAR MEASUREMENTS RESULTS

#### **EUT Setup Configuration 1**



802.11b (DSSS): Duty Cycle =100 %, Crest Factor: 1. Depth of liquid: 15.0 cm

| G []      | Antenna Channel |         | Frequency | *Conducted | Power_dBm | Liquid       | SAR    | Limit  |
|-----------|-----------------|---------|-----------|------------|-----------|--------------|--------|--------|
| Sep. [mm] | Antenna         | Channel | [MHz]     | Before     | After     | Temp<br>[°C] | (W/kg) | (W/kg) |
| 0         | Main            | 1       | 2412      | 15.59      | 15.58     | 23.5         | 0.102  | 1.6    |
| 0         | Main            | 6       | 2437      | 14.86      | 14.85     | 23.5         | 0.130  | 1.6    |
| 0         | Main            | 11      | 2462      | 14.04      | 14.03     | 23.5         | 0.046  | 1.6    |

802.11b (DSSS) with Bluetooth: Duty Cycle =100 %, Crest Factor: 1. Depth of liquid: 15.0 cm Liquid \*Conducted Power\_dBm SAR Limit Frequency Channel Temp Sep. [mm] Antenna [MHz] (W/kg) (W/kg) Before After [°C] 15.59 Main 6 2437 15.58 23.5 0.090 1.6

#### Notes:

- 1. \*: Peak power.
- 2. Bottom face in parallel with flat phantom.
- 3. See attachment for the result presentation in plot format.

# **EUT Setup Configuration 2**



| 802.11b (DSSS): Duty Cycle = 100 %, Crest Factor: 1. | Depth of liquid: 15.0 cm |
|--|--------------------------|
|--|--------------------------|

| Sep. [mm] | Antenna | Channel | Frequency | *Conducted | Power_dBm | Liquid<br>Temp | SAR    | Limit  |
|-----------|---------|---------|-----------|------------|-----------|----------------|--------|--------|
| Sep. [mm] | Antenna | Chamici | [MHz]     | Before     | After     | [°C]           | (W/kg) | (W/kg) |
| 15        | Main    | 1       | 2412      | 15.59      | 15.58     | 23.5           | 0.075  | 1.6    |
| 15        | Main    | 6       | 2437      | 14.86      | 14.85     | 23.5           | 0.052  | 1.6    |
| 15        | Main    | 11      | 2462      | 14.04      | 14.03     | 23.5           | 0.044  | 1.6    |

## Notes:

- 1. \*: Peak power.
- 2. Host device perpendicular to flat phantom.
- 3. See attachment for the result presentation in plot format.

# 9. EUT PHOTOS









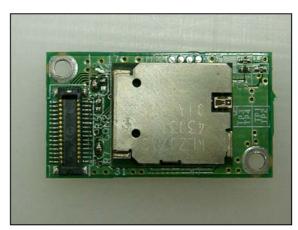




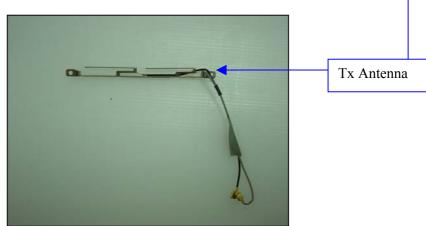












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# 10. EQUIPMENT LIST & CALIBRATION STATUS

| Name of Equipment                       | Manufacturer    | Type/Model  | Serial Number   | Calibration Due |
|---|-----------------|-------------|-----------------|-----------------|
| S-Parameter Network Analyzer            | Agilent         | E8358A      | US40260243      | 05/24/05        |
| Electronic Probe kit                    | Hewlett Packard | 85070D      | N/A             | N/A             |
| Power Meter                             | Boonton         | 4531        | 13061           | 07/13/04        |
| Power Sensor                            | Boonton         | 56218       | 2240            | 07/13/04        |
| Thermometer                             | Amarell         | 4046        | 25060           | 10/02/14        |
| Thermometer                             | Amarell         | 4046        | 25058           | 12/03/14        |
| Universal Radio Communication<br>Tester | Rohde & Schwarz | CMU 200     | 1100.0008.02    | N/A             |
| Signal Generator                        | Agilent         | 83630B      | 3844A01022      | 01/14/05        |
| Amplifier                               | Mini-Circuit    | ZHL-1724HLN | N/A             | N/A             |
| DC Power generator                      | ABM             | 8301HD      | N/A             | N/A             |
| Data Acquisition Electronics (DAE)      | SPEAG           | DAE3        | 427             | 03/15/05        |
| Dosimetric E-Field Probe                | SPEAG           | ES3DV2      | 3023            | 09/22/04        |
| 900 MHz System Validation Dipole        | SPEAG           | D900V2      | 179             | 05/12/06        |
| 1800 MHz System Validation Dipole       | SPEAG           | D1800V2     | 2d062           | 03/17/06        |
| 2450 MHz System Validation Dipole       | SPEAG           | D2450V2     | 728             | 03/22/06        |
| Probe Alignment Unit                    | SPEAG           | LB (V2)     | 348             | N/A             |
| Robot                                   | Staubli         | RX90B L     | F02/5T69A1/A/01 | N/A             |
| SAM Twin Phantom V4.0                   | SPEAG           | N/A         | N/A             | N/A             |
| Devices Holder                          | SPEAG           | N/A         | N/A             | N/A             |
| Head 835 MHz                            | CCS             | H835A       | N/A             | N/A             |
| Muscle 835 MHz                          | CCS             | M835A       | N/A             | N/A             |
| Head 900 MHz                            | CCS             | H900A       | N/A             | N/A             |
| Muscle 900 MHz                          | CCS             | M900A       | N/A             | N/A             |
| Head 1800 MHz                           | CCS             | H1800A      | N/A             | N/A             |
| Muscle 1800 MHz                         | CCS             | M1800A      | N/A             | N/A             |
| Head 1900 MHz                           | CCS             | H1900A      | N/A             | N/A             |
| Muscle 1900 MHz                         | CCS             | M1900A      | N/A             | N/A             |
| Head 2450 MHz                           | CCS             | H2450A      | N/A             | N/A             |
| Muscle 2450 MHz                         | CCS             | M2450A      | N/A             | N/A             |

#### 11. FACILITIES

| All measurement facilities used to collect the measurement data are located at             |
|--|
| No. 81-1, Lane 210, Bade Rd. 2, Luchu Hsiang, Taoyuan Hsien, Taiwan, R.O.C.                |
| No. 11, Wu-Kung 6 Rd, Wu-Ku Hsiang, Wu-Ku Industrial District, Taipei Hsien, (248) Taiwan. |
| No. 199, Chunghsen Road, Hsintien City, Taipei Hsien, Taiwan, R.O.C.                       |

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# 13. ATTACHMENTS

| Exhibit | Content                        |
|---------|--------------------------------|
| 1       | System Performance Check Plots |
| 2       | SAR Test Plots                 |

# **END OF REPORT**

Date/Time: 06/15/04 09:52:35

Test Laboratory: Compliance Certification Services Inc.

#### D2450V2 SN 728

# **DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:728**

Communication System: CW2450; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2450 MHz;  $\sigma = 1.98 \text{ mho/m}$ ;  $\epsilon_r = 51$ ;  $\rho = 1000 \text{ kg/m}^3$ 

Air Temperature:24.5 deg C;Liquid Temperature:23.5 deg C

Phantom section: Flat Section

# DASY4 Configuration:

- Probe: ES3DV2 SN3023; ConvF(4.1, 4.1, 4.1); Calibrated: 9/23/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn427; Calibrated: 3/15/2004
- Phantom: SAM 34; Type: SAM V4.0; Serial: TP-1150
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

# Pin=250mW,d=10mm/Area Scan (6x6x1): Measurement grid: dx=15mm,

dy=15mm

Reference Value = 89.5 V/m; Power Drift = -0.1 dB

Maximum value of SAR (measured) = 9.5 mW/g

# Pin=250mW,d=10mm/Z Scan (1x1x21): Measurement grid: dx=20mm,

dy=20mm, dz=5mm

Reference Value = 89.5 V/m; Power Drift = -0.1 dB

Maximum value of SAR (measured) = 15.8 mW/g

# Pin=250mW,d=10mm/Zoom Scan (5x5x7)/Cube 0: Measurement grid:

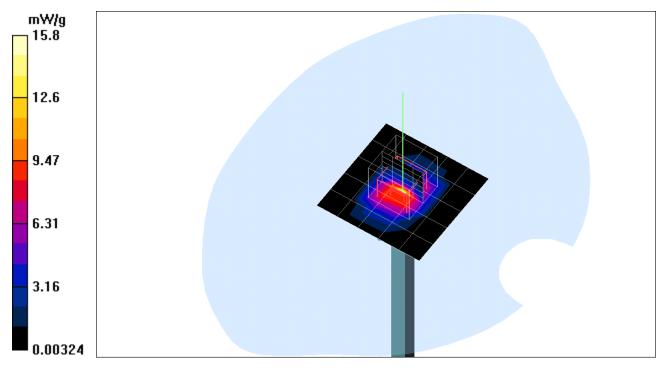
dx=7.5mm, dy=7.5mm, dz=5mm

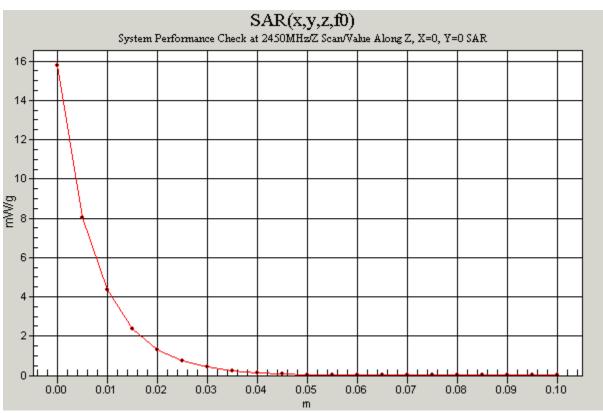
Reference Value = 89.5 V/m; Power Drift = -0.1 dB

Maximum value of SAR (measured) = 15.6 mW/g

Peak SAR (extrapolated) = 27.1 W/kg

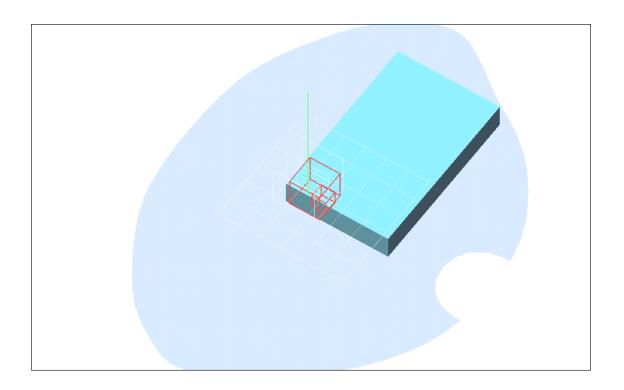
SAR(1 g) = 13.5 mW/g; SAR(10 g) = 6.31 mW/g





Test Laboratory: Compliance Certification Services Inc.

# **Test Configuration-1**



Test Laboratory: Compliance Certification Services Inc.

## Touch mode

# DUT: Pocket PC; Type: A730; Serial: N/A

Communication System: IEEE802.11b; Frequency: 2412 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2412 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Air Temperature:24.5 deg C;Liquid Temperature:23.5 deg C

Phantom section: Flat Section

# DASY4 Configuration:

- Probe: ES3DV2 SN3023; ConvF(4.1, 4.1, 4.1); Calibrated: 9/23/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn427; Calibrated: 3/15/2004
- Phantom: SAM 34; Type: SAM V4.0; Serial: TP-1150
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

# Low Rate=11M bit/Area Scan (8x11x1): Measurement grid: dx=15mm,

dy=15mm

Reference Value = 3.69 V/m; Power Drift = 0.4 dB

Maximum value of SAR (measured) = 0.096 mW/g

# Low Rate=11M bit/Z Scan (1x1x21): Measurement grid: dx=20mm, dy=20mm,

dz=5mm

Reference Value = 3.69 V/m; Power Drift = 0.3 dB

Maximum value of SAR (measured) = 0.086 mW/g

# Low Rate=11M bit/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=7.5mm,

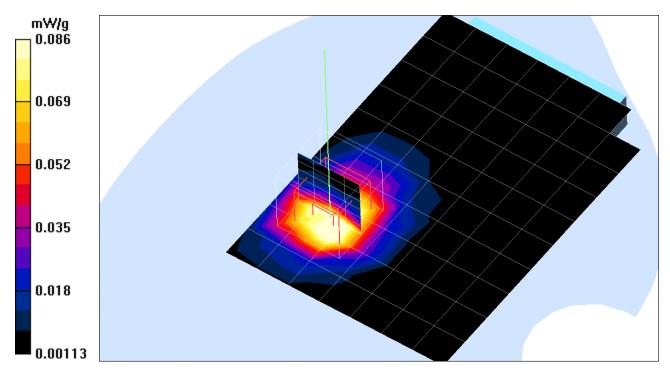
dy=7.5mm, dz=5mm

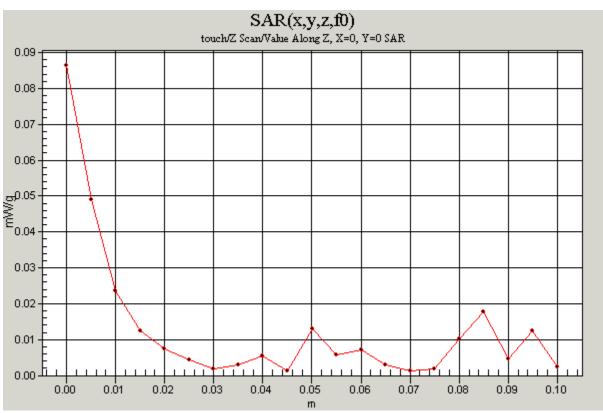
Reference Value = 3.69 V/m; Power Drift = 0.4 dB

Maximum value of SAR (measured) = 0.111 mW/g

Peak SAR (extrapolated) = 0.184 W/kg

SAR(1 g) = 0.102 mW/g; SAR(10 g) = 0.055 mW/g





Test Laboratory: Compliance Certification Services Inc.

## Touch mode

# DUT: Pocket PC; Type: A730; Serial: N/A

Communication System: IEEE802.11b; Frequency: 2437 MHz; Duty Cycle: 1:1 Medium parameters used: f = 2437 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Air Temperature:24.5 deg C;Liquid Temperature:23.5 deg C

Phantom section: Flat Section

# DASY4 Configuration:

- Probe: ES3DV2 SN3023; ConvF(4.1, 4.1, 4.1); Calibrated: 9/23/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn427; Calibrated: 3/15/2004
- Phantom: SAM 34; Type: SAM V4.0; Serial: TP-1150
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

mid Rate=11M bit/Area Scan (7x7x1): Measurement grid: dx=15mm, dy=15mm Reference Value = 3.19 V/m; Power Drift = 0.2 dB Maximum value of SAR (measured) = 0.091 mW/g

mid Rate=11M bit/Z Scan (1x1x21): Measurement grid: dx=20mm, dy=20mm, dz=5mm

Reference Value = 3.19 V/m; Power Drift = 0.2 dB Maximum value of SAR (measured) = 0.095 mW/g

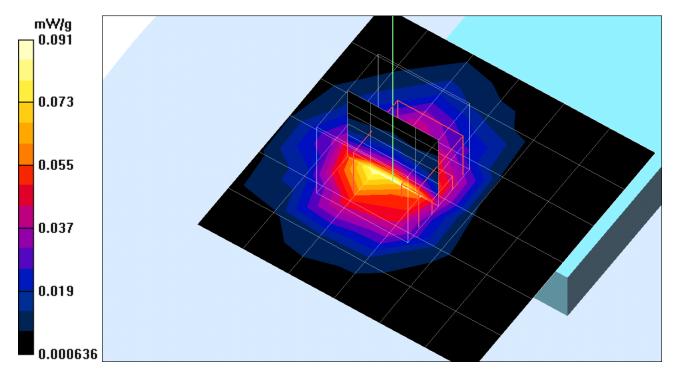
# mid Rate=11M bit/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=7.5mm, dy=7.5mm, dz=5mm

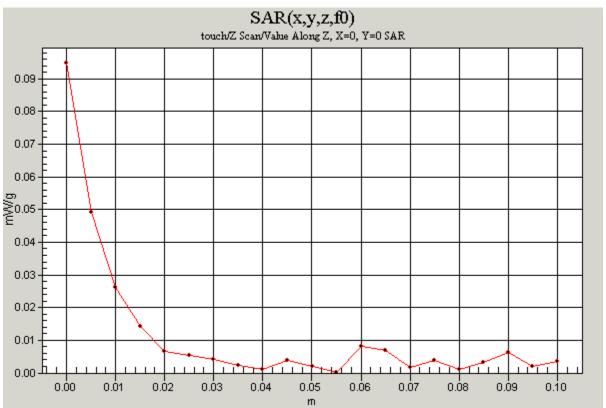
Reference Value = 3.19 V/m; Power Drift = 0.2 dB

Maximum value of SAR (measured) = 0.091 mW/g

Peak SAR (extrapolated) = 98.9 W/kg

SAR(1 g) = 0.130 mW/g; SAR(10 g) = 0.049 mW/g





Test Laboratory: Compliance Certification Services Inc.

# Touch mode

# DUT: Pocket PC; Type: A730; Serial: N/A

Communication System: IEEE802.11b; Frequency: 2462 MHz; Duty Cycle: 1:1 Medium parameters used: f = 2462 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Air Temperature:24.5 deg C;Liquid Temperature:23.5 deg C

Phantom section: Flat Section

# DASY4 Configuration:

- Probe: ES3DV2 SN3023; ConvF(4.1, 4.1, 4.1); Calibrated: 9/23/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn427; Calibrated: 3/15/2004
- Phantom: SAM 34; Type: SAM V4.0; Serial: TP-1150
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

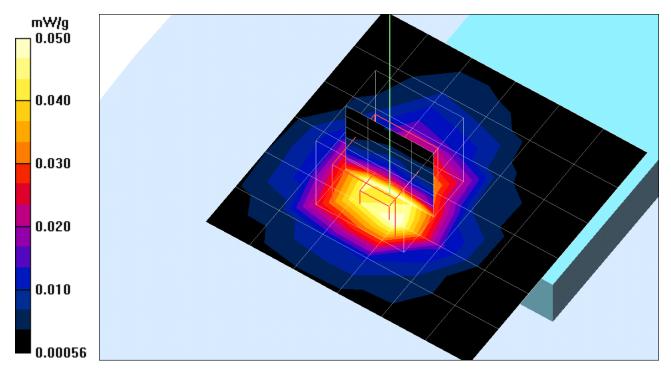
**High Rate=11M bit/Area Scan (7x7x1):** Measurement grid: dx=15mm, dy=15mm Reference Value = 3.38 V/m; Power Drift = -0.1 dB Maximum value of SAR (measured) = 0.050 mW/g

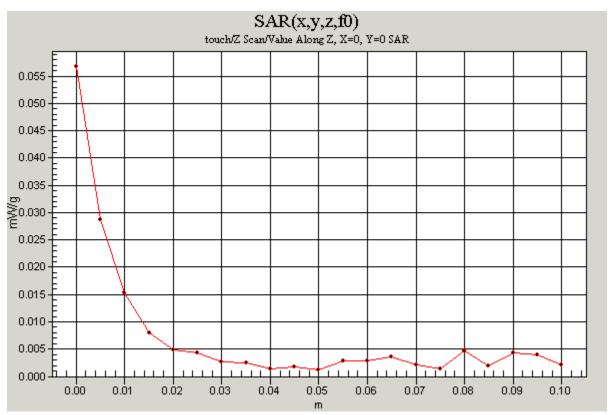
# **High Rate=11M bit/Z Scan (1x1x21):** Measurement grid: dx=20mm, dy=20mm, dz=5mm

Reference Value = 3.38 V/m; Power Drift = -0.0 dB Maximum value of SAR (measured) = 0.057 mW/g

# **High Rate=11M bit/Zoom Scan (5x5x7)/Cube 0:** Measurement grid:

dx=7.5mm, dy=7.5mm, dz=5mm Reference Value = 3.38 V/m; Power Drift = -0.1 dB Maximum value of SAR (measured) = 0.054 mW/g Peak SAR (extrapolated) = 0.064 W/kg SAR(1 g) = 0.046 mW/g; SAR(10 g) = 0.024 mW/g





Test Laboratory: Compliance Certification Services Inc.

## Touch mode

# DUT: Pocket PC; Type: A730; Serial: N/A

Communication System: IEEE802.11b; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2437 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51$ ;  $\rho = 1000$  kg/m<sup>3</sup> Air

Temperature:24.5 deg C;Liquid Temperature:23.5 deg C

Phantom section: Flat Section

# DASY4 Configuration:

- Probe: ES3DV2 SN3023; ConvF(4.1, 4.1, 4.1); Calibrated: 9/23/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn427; Calibrated: 3/15/2004
- Phantom: SAM 34; Type: SAM V4.0; Serial: TP-1150
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

# mid Rate=11M bit 2 Co-location Wiless+BT/Area Scan (7x7x1):

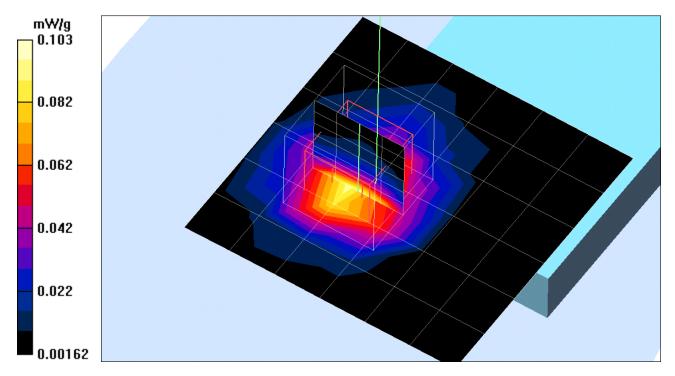
Measurement grid: dx=15mm, dy=15mm Reference Value = 2.73 V/m; Power Drift = -0.9 dB Maximum value of SAR (measured) = 0.103 mW/g

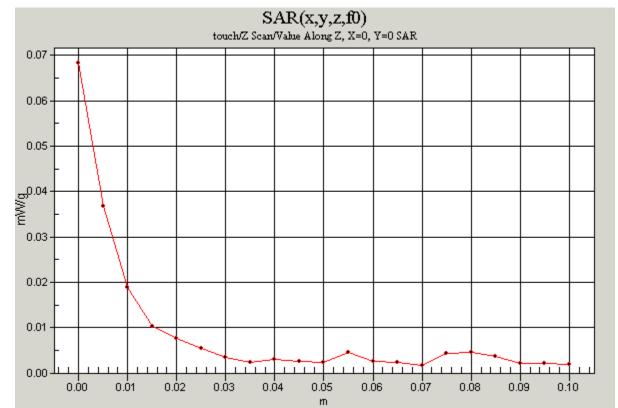
# mid Rate=11M bit 2 Co-location Wiless+BT/Z Scan (1x1x21): Measurement

grid: dx=20mm, dy=20mm, dz=5mm Reference Value = 2.73 V/m; Power Drift = -0.1 dB Maximum value of SAR (measured) = 0.068 mW/g

# mid Rate=11M bit 2 Co-location Wiless+BT/Zoom Scan (5x5x7)/Cube 0:

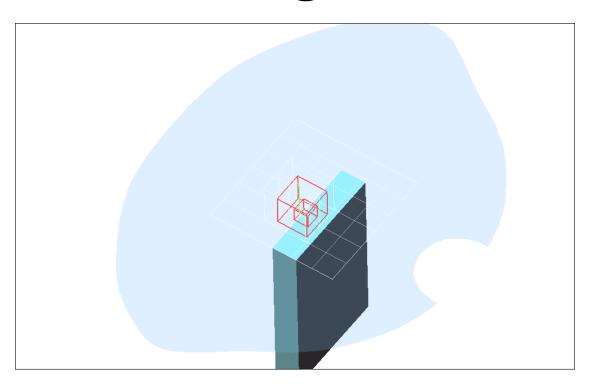
Measurement grid: dx=7.5mm, dy=7.5mm, dz=5mm Reference Value = 2.73 V/m; Power Drift = -0.9 dB Maximum value of SAR (measured) = 0.098 mW/g Peak SAR (extrapolated) = 0.179 W/kg SAR(1 g) = 0.090 mW/g; SAR(10 g) = 0.046 mW/g





Test Laboratory: Compliance Certification Services Inc.

# **Test Configuration-2**



Test Laboratory: Compliance Certification Services Inc.

# 15mm mode

# DUT: Pocket PC; Type: A730; Serial: N/A

Communication System: Poket PC; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2412 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Air Temperature:24.5 deg C;Liquid Temperature:23.5 deg C

Phantom section: Flat Section

# DASY4 Configuration:

- Probe: ES3DV2 SN3023; ConvF(4.1, 4.1, 4.1); Calibrated: 9/23/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn427; Calibrated: 3/15/2004
- Phantom: SAM 34; Type: SAM V4.0; Serial: TP-1150
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

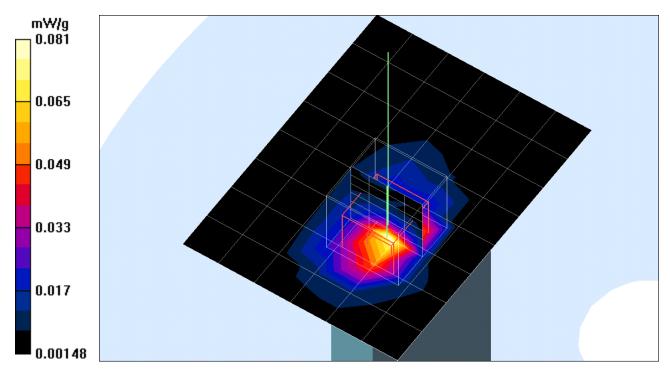
**Low Rate=11M bit /Area Scan (7x9x1):** Measurement grid: dx=15mm, dy=15mm Reference Value = 4.14 V/m; Power Drift = -0.1 dB Maximum value of SAR (measured) = 0.081 mW/g

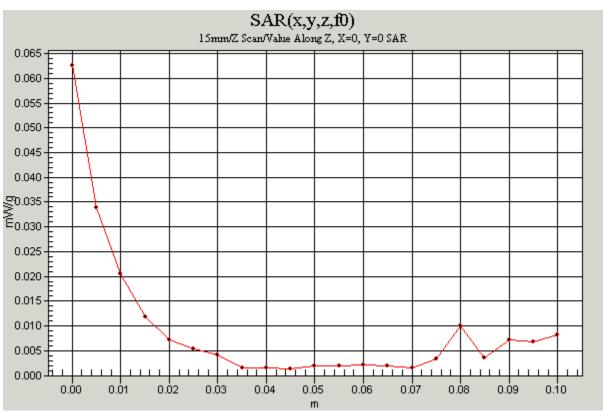
# **Low Rate=11M bit /Z Scan (1x1x21):** Measurement grid: dx=20mm, dy=20mm, dz=5mm

Reference Value = 4.14 V/m; Power Drift = -0.1 dB Maximum value of SAR (measured) = 0.063 mW/g

# Low Rate=11M bit /Zoom Scan (5x5x7)/Cube 0: Measurement grid:

dx=7.5mm, dy=7.5mm, dz=5mm Reference Value = 4.14 V/m; Power Drift = -0.1 dB Maximum value of SAR (measured) = 0.087 mW/g Peak SAR (extrapolated) = 0.159 W/kg SAR(1 g) = 0.075 mW/g; SAR(10 g) = 0.034 mW/g





Test Laboratory: Compliance Certification Services Inc.

# 15mm mode

# DUT: Pocket PC; Type: A730; Serial: N/A

Communication System: Poket PC; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2437 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Air Temperature:24.5 deg C;Liquid Temperature:23.5 deg C

Phantom section: Flat Section

# DASY4 Configuration:

- Probe: ES3DV2 SN3023; ConvF(4.1, 4.1, 4.1); Calibrated: 9/23/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn427; Calibrated: 3/15/2004
- Phantom: SAM 34; Type: SAM V4.0; Serial: TP-1150
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

mid Rate=11M bit/Area Scan (7x7x1): Measurement grid: dx=15mm, dy=15mm Reference Value = 3.59 V/m; Power Drift = -0.4 dB Maximum value of SAR (measured) = 0.062 mW/g

mid Rate=11M bit/Z Scan (1x1x21): Measurement grid: dx=20mm, dy=20mm, dz=5mm

Reference Value = 3.59 V/m; Power Drift = -0.3 dB Maximum value of SAR (measured) = 0.046 mW/g

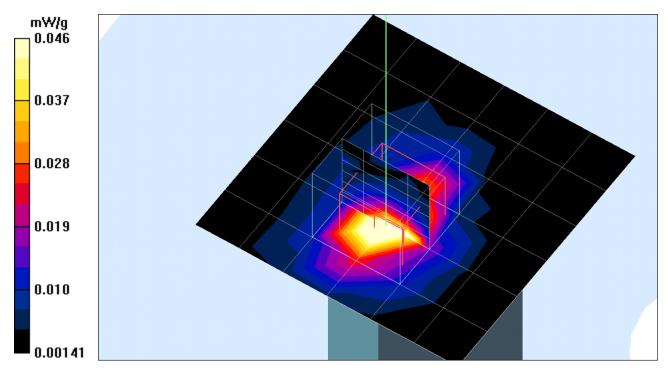
# mid Rate=11M bit/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=7.5mm, dy=7.5mm, dz=5mm

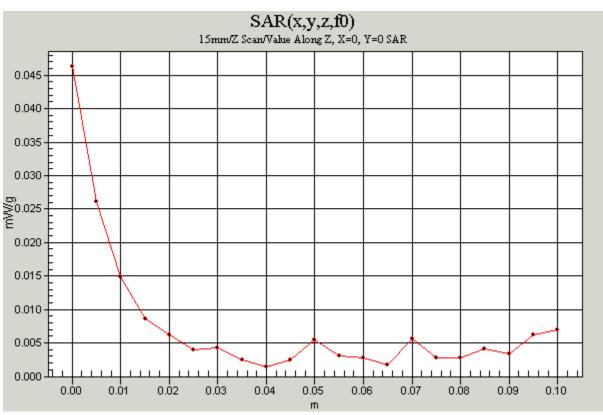
Reference Value = 3.59 V/m; Power Drift = -0.4 dB

Maximum value of SAR (measured) = 0.059 mW/g

Peak SAR (extrapolated) = 0.090 W/kg

SAR(1 g) = 0.052 mW/g; SAR(10 g) = 0.024 mW/g





Test Laboratory: Compliance Certification Services Inc.

# 15mm mode

# DUT: Pocket PC; Type: A730; Serial: N/A

Communication System: Poket PC; Frequency: 2462 MHz; Duty Cycle: 1:1

Medium parameters used: f = 2462 MHz;  $\sigma = 1.98$  mho/m;  $\varepsilon_r = 51$ ;  $\rho = 1000$  kg/m<sup>3</sup>

Air Temperature:24.5 deg C;Liquid Temperature:23.5 deg C

Phantom section: Flat Section

# DASY4 Configuration:

- Probe: ES3DV2 SN3023; ConvF(4.1, 4.1, 4.1); Calibrated: 9/23/2003
- Sensor-Surface: 4mm (Mechanical Surface Detection) Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE3 Sn427; Calibrated: 3/15/2004
- Phantom: SAM 34; Type: SAM V4.0; Serial: TP-1150
- Measurement SW: DASY4, V4.2 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 112

**High Rate=11M bit/Area Scan (7x7x1):** Measurement grid: dx=15mm, dy=15mm Reference Value = 3.1 V/m; Power Drift = -0.1 dB Maximum value of SAR (measured) = 0.047 mW/g

# **High Rate=11M bit/Z Scan (1x1x21):** Measurement grid: dx=20mm, dy=20mm, dz=5mm

Reference Value = 3.1 V/m; Power Drift = -0.2 dBMaximum value of SAR (measured) = 0.038 mW/g

# **High Rate=11M bit/Zoom Scan (5x5x7)/Cube 0:** Measurement grid:

dx=7.5mm, dy=7.5mm, dz=5mm Reference Value = 3.1 V/m; Power Drift = -0.1 dB Maximum value of SAR (measured) = 0.049 mW/g Peak SAR (extrapolated) = 0.208 W/kg SAR(1 g) = 0.044 mW/g; SAR(10 g) = 0.020 mW/g

