CELLTECH RESEARCH INC.
1955 Moss Court, Kelowna
B.C. Canada V1Y 9L3

Test Report S/N: 031402-221MIV
Test Date(s): March 15, 2002
FCC SAR Evaluation

16.0 MEASUREMENT UNCERTAINTIES

Error Description	Uncertainty Value ±%	Probability Distribution	Divisor	c_i 1g	Standard Uncertainty ±% (1g)	v_i or v_{eff}
Measurement System						
Probe calibration	± 4.8	Normal	1	1	± 4.8	∞
Axial isotropy of the probe	± 4.7	Rectangular	√3	$(1-c_p)$	± 1.9	∞
Spherical isotropy of the probe	± 9.6	Rectangular	√3	(c_p)	± 3.9	∞
Spatial resolution	± 0.0	Rectangular	√3	1	± 0.0	∞
Boundary effects	± 5.5	Rectangular	√3	1	± 3.2	∞
Probe linearity	± 4.7	Rectangular	√3	1	± 2.7	∞
Detection limit	± 1.0	Rectangular	√3	1	± 0.6	∞
Readout electronics	± 1.0	Normal	1	1	± 1.0	∞
Response time	± 0.8	Rectangular	√3	1	± 0.5	∞
Integration time	± 1.4	Rectangular	√3	1	± 0.8	∞
RF ambient conditions	± 3.0	Rectangular	√3	1	± 1.7	∞
Mech. constraints of robot	± 0.4	Rectangular	√3	1	± 0.2	∞
Probe positioning	± 2.9	Rectangular	√3	1	± 1.7	∞
Extrapolation & integration	± 3.9	Rectangular	√3	1	± 2.3	∞
Test Sample Related						
Device positioning	± 6.0	Normal	0.89	1	± 6.7	12
Device holder uncertainty	± 5.0	Normal	0.84	1	± 5.9	8
Power drift	± 5.0	Rectangular	√3		± 2.9	∞
Phantom and Setup						
Phantom uncertainty	± 4.0	Rectangular	√3	1	± 2.3	∞
Liquid conductivity (target)	± 5.0	Rectangular	√3	0.6	± 1.7	∞
Liquid conductivity (measured)	± 10.0	Rectangular	√3	0.6	± 3.5	∞
Liquid permittivity (target)	± 5.0	Rectangular	√3	0.6	± 1.7	∞
Liquid permittivity (measured)	± 5.0	Rectangular	√3	0.6	± 1.7	∞
Combined Standard Uncertainty					± 13.7	
Expanded Uncertainty (k=2)					± 27.5	

The divisor for device positioning uncertainty and holder uncertainty are based on the procedure defined in IEEE Std 1528 (draft) (see reference [5]), or based on the degrees of freedom for each error source.

For estimation of Device Positioning Uncertainty (divisor=0.89) 12 different devices were used (see last column - i.e. degrees of freedom). The corresponding k_p factor for v_{eff}=12 is 2.23, therefore the divisor is 2/2.23=0.89.

For estimation of Device Holder Uncertainty (divisor=0.84) 8 different devices were used (see last column - i.e. degrees of freedom). The corresponding k_p factor for v_{eff}=8 is 2.37, therefore the divisor is 2/2.37=0.84.