



XBee/XBee-PRO S2C 802.15.4

Radio Frequency (RF) Module

User Guide

Revision history—90001500

Revision	Date	Description
A	March 2016	Initial release of the document
B	April 2016	Updated the antenna tables. Added the Listen Before Talk requirement to the European certifications.

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Contents

About the XBee/XBee-PRO S2C 802.15.4 RF Module

The XBee/XBee-PRO S2C 802.15.4 RF Module	9
Applicable firmware and hardware	9

Technical specifications

Performance specifications	11
Power requirements	12
General specifications	12
Regulatory approvals	13
Serial communication specifications	13
UART	13
SPI	14
GPIO specifications	14

Hardware

Antenna options	16
Mechanical drawings	16
Mounting considerations	17
Pin signals	18
Notes	22
Design notes	22
Power supply design	22
Board layout	23
Antenna performance	23
Keepout area	23
RF pad version	25

Modes

Serial modes	28
--------------------	----

Transparent operating mode	28
API operating mode	29
Command mode	29
Transceiver modes	31
Idle mode	31
Transmit mode	31
Receive mode	31

Operation

Configure the device using XCTU	32
Over-the-air (OTA) firmware update	32
Addressing	32
Send packets to a specific device	32
Addressing modes	33
Encryption	33
Maximum Payload	35
Maximum payload rules	35
Maximum payload summary tables	36
Work with Legacy devices	37
Networking	37
MAC Mode configuration	38
XBee retries configuration	39
Transmit status based on MAC mode and XBee retries configurations	39
Peer-to-peer networks	40
Master/Slave networks	41
Clear Channel Assessment (CCA)	46
CCA operations	46
Serial interface	47
Serial port selection	47
UART data flow	48
Flow control	49
SPI operation	50
SPI signals	50
SPI parameters	51
SPI and API mode	52
Full duplex operation	52
Slave mode characteristics	52
I/O support	53
Digital I/O line support	53
Analog input	54
On demand I/O sampling	54
Periodic I/O sampling	57
Change Detect I/O sampling	58
Wakeup I/O sampling	58
Sample rate (interval)	58
I/O line passing	59

Output control	60
Sleep support	60
Sleep modes	60
Sleep parameters	62
Sleep current	62
Sleep pins	62
Direct and indirect transmission	63
Node discovery	64
Node discovery	64
Node discovery in compatibility mode	65
Directed node discovery	65
Directed node discovery in compatibility mode	65
Destination Node	65
About remote configuration commands	66
Send a remote command	66
Apply changes on remote devices	66
Remote command responses	66

AT commands

Special commands	68
WR (Write)	68
RE (Restore Defaults)	68
FR (Software Reset)	69
Networking and security commands	69
C8 (802.15.4 Compatibility)	69
CH (Operating Channel)	71
ID (Network ID)	72
DH (Destination Address High)	72
DL (Destination Address Low)	72
MY (Source Address)	73
SH (Serial Number High)	73
SL (Serial Number Low)	73
MM (MAC Mode)	73
RR (XBee Retries)	74
RN (Random Delay Slots)	75
ND (Network Discover)	75
NT (Node Discover Timeout)	76
NO (Node Discover Options)	76
DN (Discover Node)	76
CE (Coordinator Enable)	77
SC (Scan Channels)	77
SD (Scan Duration)	78
A1 (End Device Association)	79
A2 (Coordinator Association)	80
AI (Association Indication)	81
FP (Force Poll)	82

AS (Active Scan)	82
ED (Energy Detect)	84
EE (Encryption Enable)	84
KY (AES Encryption Key)	85
NI (Node Identifier)	85
RF interfacing commands	86
PL (TX Power Level)	86
PM (Power Mode)	87
CA (CCA Threshold)	88
Sleep commands	88
SM (Sleep Mode)	88
ST (Time before Sleep)	89
SP (Cyclic Sleep Period)	89
DP (Disassociated Cyclic Sleep Period)	90
SO (Sleep Options)	90
Serial interfacing commands	91
BD (Interface Data Rate)	91
NB (Parity)	93
RO (Packetization Timeout)	93
D7 (DIO7/CTS)	93
D6 (DIO6/RTS)	94
AP (API Enable)	95
I/O settings commands	95
D0 (DIO0/AD0)	95
D1 (DIO1/AD1)	96
D2 (DIO2/AD2)	97
D3 (DIO3/AD3)	97
D4 (DIO4)	98
D5 (DIO5/ASSOCIATED_INDICATOR)	98
D8 (DIO8/SLEEP_REQUEST)	99
P0 (RSSI/PWM0 Configuration)	100
P1 (PWM1 Configuration)	100
P2 (SPI_MISO)	101
M0 (PWM0 Duty Cycle)	101
M1 (PWM1 Duty Cycle)	102
P5 (SPI_MISO)	102
P6 (SPI_MOSI)	102
P7 (SPI_SSEL)	103
P8 (SPI_SCLK)	103
P9 (SPI_ATTEN)	104
PR (Pull-up/Down Resistor Enable)	104
PD (Pull Direction)	106
IU (I/O Output Enable)	106
IT (Samples before TX)	106
IS (Force Sample)	107
IO (Digital Output Level)	107
IC (DIO Change Detect)	107
IR (Sample Rate)	108

RP (RSSI PWM Timer)	108
I/O line passing	108
IA (I/O Input Address)	109
T0 (D0 Timeout)	109
T1 (D1 Timeout)	109
T2 (D2 Timeout)	109
T3 (D3 Timeout)	110
T4 (D4 Timeout)	110
T5 (D5 Timeout)	110
T6 (D6 Timeout)	110
T7 (D7 Timeout)	111
PT (PWM Output Timeout)	111
VL (Version Long)	111
Diagnostic commands	112
VR (Firmware Version)	112
HV (Hardware Version)	112
DB (Last Packet RSSI)	112
EC (CCA Failures)	113
EA (ACK Failures)	113
DD (Device Type Identifier)	113
Command mode options	113
CT (Command mode Timeout)	113
CN (Exit Command mode)	114
AC (Apply Changes)	114
GT (Guard Times)	114
CC (Command Sequence Character)	115

Operate in API mode

API mode overview	116
API frame specifications	116
Escaped characters in API frames	119
API frames	120
Modem Status frame - 0x8A	121
AT Command frame - 0x08	122
AT Command - Queue Parameter Value frame - 0x09	124
AT Command Response frame - 0x88	125
Remote AT Command Request frame - 0x17	127
Remote Command Response frame - 0x97	128
TX Request: 64-bit address frame - 0x00	129
TX Request: 16-bit address - 0x01	130
TX Status frame - 0x89	131
RX Packet: 64-bit Address frame - 0x80	133
Receive Packet: 16-bit address frame - 0x81	134
RX (Receive) Packet: 64-bit address IO - 0x82	135
RX Packet: 16-bit address IO - 0x83	137

Certifications

United States (FCC)	139
OEM labeling requirements	139
FCC notices	140
FCC-approved antennas (2.4 GHz)	141
RF exposure	158
Europe	158
OEM labeling requirements	158
Listen Before Talk requirement	159
Declarations of conformity	159
Antennas	159
Canada (IC)	159
Labeling requirements	160
For XBee S2C surface mount	160
For XBee-PRO S2C surface mount	160
For XBee S2C through hole	160
For XBee-PRO S2C through hole	160
Transmitters for detachable antennas	160
Detachable antenna	161

Load 802.15.4 firmware on ZB devices

Background	162
Load 802.15.4 firmware	163

Migrate from XBee through-hole to surface-mount devices

Pin mapping	164
Mount the devices	166

PCB design and manufacturing

Recommended solder reflow cycle	168
Recommended footprint and keepout	169
Flux and cleaning	170
Rework	171

About the XBee/XBee-PRO S2C 802.15.4 RF Module

The XBee/XBee-PRO S2C 802.15.4 RF Module

XBee/XBee-PRO S2C 802.15.4 RF Modules are embedded solutions providing wireless end-point connectivity to devices. These devices use the IEEE 802.15.4 networking protocol for fast point-to-multipoint or peer-to-peer networking. They are designed for high-throughput applications requiring low latency and predictable communication timing.

There are two footprints for the XBee/XBee-PRO S2C 802.15.4 RF Module hardware: through-hole (TH) and surface-mount (SMT). TH devices include a 20-pin header and require the placement of two 1x10 sockets on the carrier board for mounting the device. SMT devices include 37 pads. They are placed directly on the carrier board, which means they do not require holes or sockets for mounting.

The TH version may be useful for prototyping and production, but we recommend SMT for high-volume applications, as the component can be placed automatically by a pick-and-place machine and you save the cost of a socket on each board.

The XBee/XBee-PRO S2C 802.15.4 RF Module supports the needs of low-cost, low-power wireless sensor networks. The devices require minimal power and provide reliable delivery of data between devices. The devices operate within the ISM 2.4 GHz frequency band.

The XBee/XBee-PRO S2C 802.15.4 RF Module uses S2C hardware and the Silicon Labs EM357 chipset. As the name suggests, the 802.15.4 module is over-the-air compatible with our Legacy 802.15.4 module (S1 hardware), and the TH versions of the new product are also form factor compatible with designs that use the Legacy module.

Note OTA capability is only available when **MM** (Mac Mode) = 0 or 3

Applicable firmware and hardware

This manual supports the following firmware:

- 802.15.4 version 20xx

It supports the following hardware:

- XB24C TH
- XB24C SMT
- XBP24C TH
- XBP24C SMT

Technical specifications

Performance specifications

The following table provides the performance specifications for the device.

Specification	XBee value	XBee-PRO value
Indoor / urban range	Up to 200 ft (60 m)	Up to 300 ft. (90 m)
Outdoor RF line-of-sight range	Up to 4000 ft (1200 m)	Up to 2 miles (3200 m)
Transmit power output (software selectable)	6.3 mW (8 dBm), Boost mode ¹ 3.1 mW (5 dBm), Normal mode Channel 26 max power is 0.3 mW (-5 dBm)	63 mW (18 dBm) ²
RF data rate	250,000 b/s	250,000 b/s
Maximum data throughput	83,000 b/s	83,000 b/s
UART interface data rate	1200 b/s to 250,000 b/s	1200 b/s to 250,000 b/s
SPI data rate	Up to 5 Mb/s (burst)	Up to 5 Mb/s (burst)

¹Boost mode enabled by default; see [PM \(Power Mode\) on page 87](#).

²See [Certifications on page 139](#) for region-specific certification requirements.

Specification	XBee value	XBee-PRO value
Receiver sensitivity	-102 dBm, Boost mode -100 dBm, Normal mode	-101 dBm

Power requirements

The following table provides the power requirements for the device.

Specification	XBee	XBee-PRO
Supply voltage	2.1 - 3.6 V	2.7 - 3.6 V
Transmit current (typical, VCC = 3.3 V)	45 mA (8 dBm, Boost mode) 33 mA (5 dBm, Normal mode)	120 mA (18 dBm)
Idle / receive current (typical, VCC = 3.3 V)	31 mA (Boost mode) 28 mA (Normal mode)	31 mA
Power-down current	<1 uA @ 25C	<1 uA @ 25C

General specifications

The following table provides the general specifications for the device.

Specification	XBee	XBee-PRO
Operating frequency	ISM 2.4 GHz	
Supported channels	11 - 26	12 - 23
Form factor	TH: 2.438 x 2.761 cm (0.960 x 1.087 in) SMT: 2.199 x 3.4 x 0.305 cm (0.866 x 1.33 x 0.120 in)	TH: 2.438 x 3.294 cm (0.960 x 1.297 in) SMT: 2.199 x 3.4 x 0.305 cm (0.866 x 1.33 x 0.120 in)
Operating temperature	-40 to 85° C (industrial)	

Specification	XBee	XBee-PRO
Antenna options	TH: PCB antenna, U.FL connector, RPSMA connector, or integrated wire SMT: RF pad, PCB antenna, or U.FL connector	

Regulatory approvals

The following table provides the device's regulatory approvals. See [Certifications on page 139](#) for important information.

Approval	XBee (surface-mount)	XBee-PRO (surface-mount)	XBee (through-hole)	XBee-PRO (through-hole)
United States (FCC Part 15.247)	FCC ID: MCQ-XBS2C	FCC ID: MCQ-PS2CSM	FCC ID: MCQ-S2CTH	FCC ID: MCQ-PS2CTH
Industry Canada (IC)	IC: 1846A-XBS2C	IC: 1846A-PS2CSM	IC: 1846A-S2CTH	IC: 1846A-PS2CTH
FCC/IC Test Transmit Power Output range	-26 to +8 dBm	-0.7 to +19.4 dBm	-26 to +8 dBm	+1 to +19 dBm
Europe (CE)	Yes	-	Yes	-
RoHS	Compliant			

Serial communication specifications

XBee/XBee-PRO S2C 802.15.4 RF Modules support both Universal Asynchronous Receiver / Transmitter (UART) and Serial Peripheral Interface (SPI) serial connections.

UART

The SC1 (Serial Communication Port 1) of the Ember 357 is connected to the UART port. The following table provides the UART pin assignments.

Specifications	Module Pin Number	
UART Pins	XBee (Surface Mount)	XBee (Through-hole)
DOUT	3	2

Specifications	Module Pin Number	
UART Pins	XBee (Surface Mount)	XBee (Through-hole)
DIN / $\overline{\text{CONFIG}}$	4	3
$\overline{\text{CTS}}$ / DIO7	25	12
$\overline{\text{RTS}}$ / DIO6	29	16

SPI

The SC2 (Serial Communication Port 2) of the Ember 357 is connected to the SPI port.

Specifications	Module Pin Number	
SPI Pins	XBee (Surface Mount)	XBee (Through-hole)
SPI_SCLK	14	18
SPI_SSEL	15	17
SPI_MOSI	16	11
SPI_MISO	17	4

GPIO specifications

XBee/XBee-PRO S2C 802.15.4 RF Modules have 15 General Purpose Input / Output (GPIO) ports available. The exact list depends on the device configuration, as some GPIO pads are used for purposes such as serial communication.

GPIO Electrical Specification	Value
Low Schmitt switching threshold	0.42 - 0.5 x VCC
High Schmitt switching threshold	0.62 - 0.8 x VCC
Input current for logic 0	-0.5 μ A

GPIO Electrical Specification	Value
Input current for logic 1	0.5 μ A
Input pull-up resistor value	29 k Ω
Input pull-down resistor value	29 k Ω
Output voltage for logic 0	0.18 x VCC (maximum)
Output voltage for logic 1	0.82 x VCC (minimum)
Output source/sink current for pad numbers 3, 4, 5, 10, 12, 14, 15, 16, 17, 25, 26, 28, 29, 30, and 32 on the SMT modules	4 mA
Output source/sink current for pin numbers 2, 3, 4, 9, 12, 13, 15, 16, 17, and 19 on the TH modules	4 mA
Output source/sink current for pad numbers 7, 8, 24, 31, and 33 on the SMT modules	8 mA
Output source/sink current for pin numbers 6, 7, 11, 18, and 20 on the TH modules	8 mA
Total output current (for GPIO pads)	40 mA

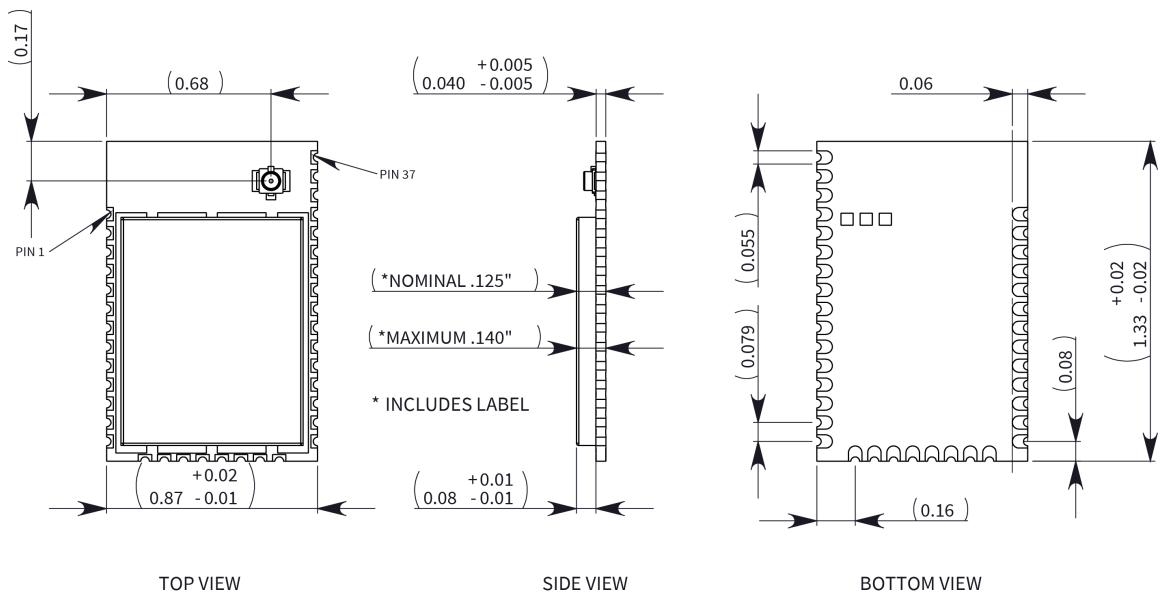
Hardware

Antenna options

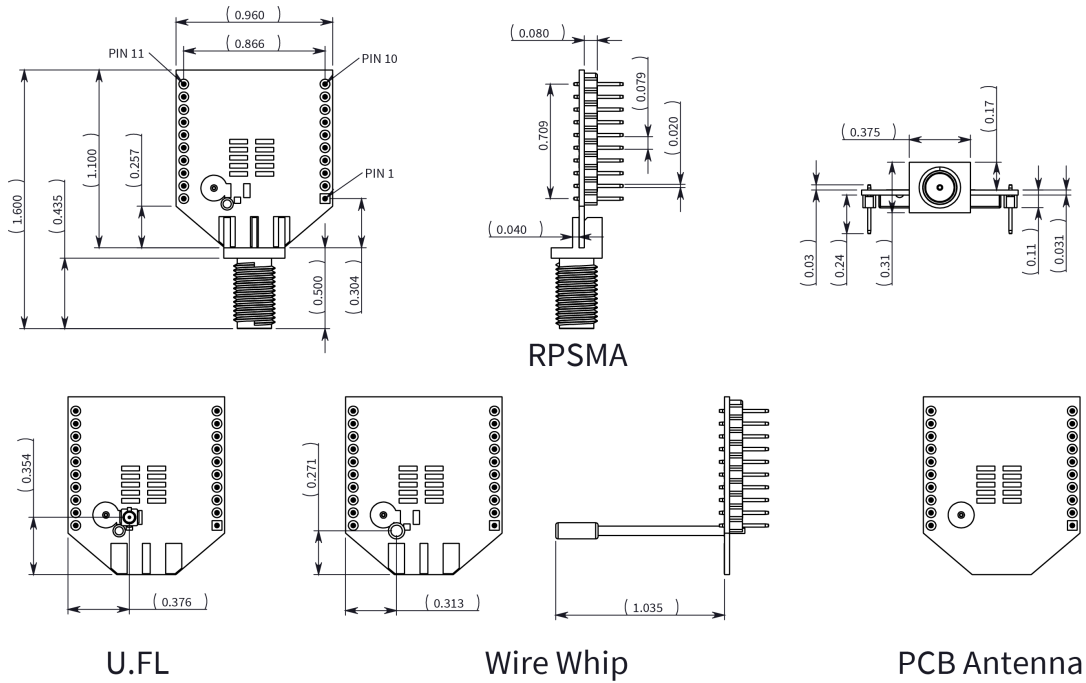
The ranges specified are typical when using the integrated whip (1.5 dBi) and dipole (2.1 dBi) antennas. The printed circuit board (PCB) antenna option provides advantages in its form factor, however, it typically yields shorter range than the whip and dipole antenna options when transmitting outdoors. For more information, refer to the [XBee and XBee-PRO OEM RF Module Antenna Considerations](http://ftp1.digi.com/support/images/XST-AN019a_XBeeAntennas.pdf) Application Note (http://ftp1.digi.com/support/images/XST-AN019a_XBeeAntennas.pdf).

Mechanical drawings

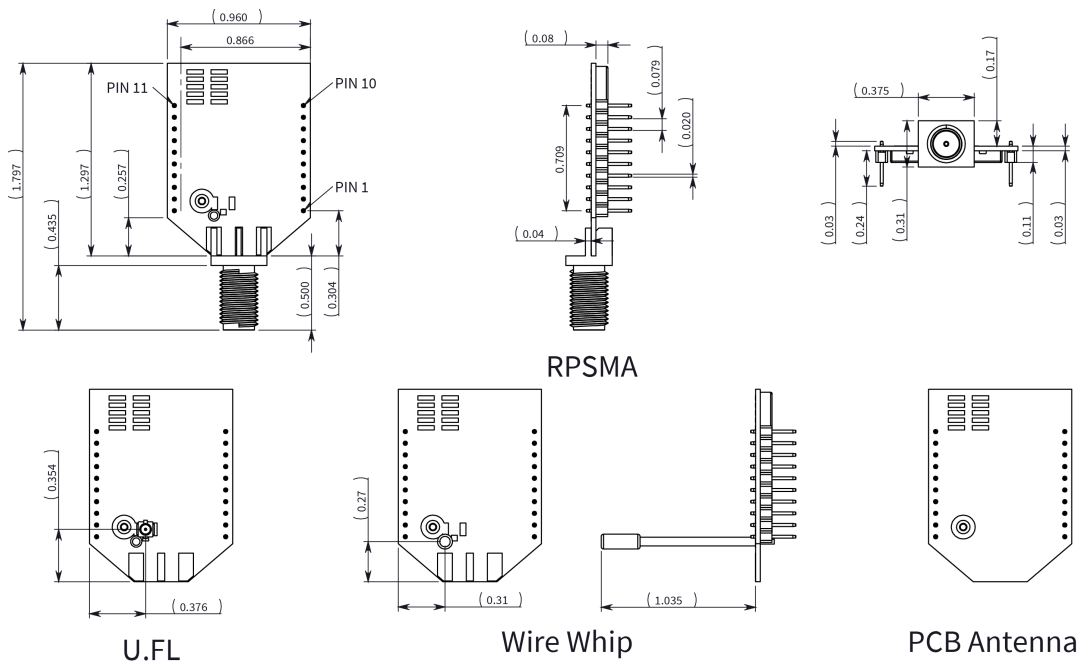
The following mechanical drawings of the XBee/XBee-PRO S2C 802.15.4 RF Module show all dimensions in inches. The first drawing shows the surface-mount device (antenna options not shown).



The following drawings show the standard (non-PRO) through-hole device.



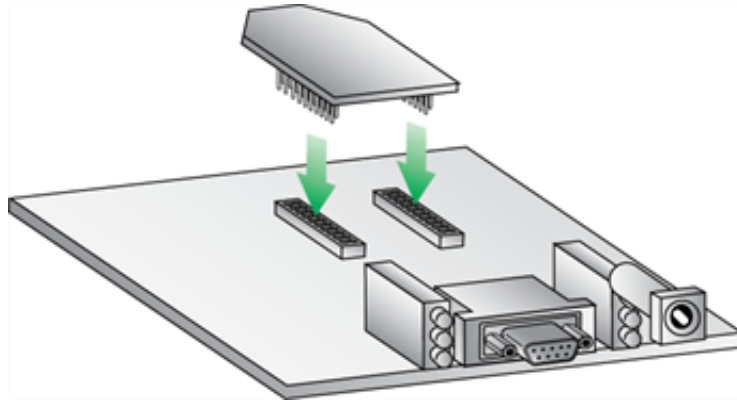
The following drawings show the Xbee-PRO through-hole device.



Mounting considerations

We design the through-hole module to mount into a receptacle so that you do not have to solder the module when you mount it to a board. The development kits may contain RS-232 and USB interface

boards that use two 20-pin receptacles to receive modules. The following illustration shows the module mounting into the receptacle on the RS-232 interface board.



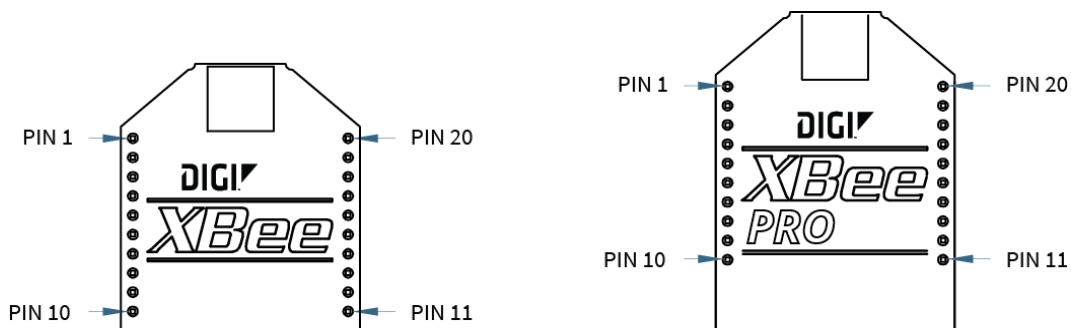
Century Interconnect and Samtec manufacture the 2 x 10 pin 2 mm spacing receptacles on Digi development boards. Several other manufacturers provide comparable mounting solutions; we currently use the following receptacles:

- Through-hole single-row receptacles: Samtec P/N: MMS-110-01-L-SV (or equivalent)
- Surface-mount double-row receptacles: Century Interconnect P/N: CPRMSL20-D-0-1 (or equivalent)
- Surface-mount single-row receptacles: Samtec P/N: SMM-110-02-SM-S

Note We recommend that you print an outline of the module on the board to indicate the correct orientation for mounting the module.

Pin signals

The following image shows the pin numbers; it shows the device's top sides, the shields are on the bottom.



The following table shows the pin assignments for the through-hole device. In the table, low-asserted signals have a horizontal line above signal name.

Pin	Name	Direction	Function
1	VCC	-	Power supply
2	DOUT	Output	UART data out
3	DIN/ $\overline{\text{CONFIG}}$	Input	UART data In
4	SPI_MISO	Output	Serial Peripheral Interface (SPI) Data Out
5	$\overline{\text{RESET}}$	Input	Module reset (reset pulse must be at least 200 ns). This must be driven as an open drain/collector. The device drives this line low when a reset occurs. Never drive this line high.
6	PWM0/RSSI PWM	Output	PWM output 0 / RX signal strength indicator
7	PWM1	Output	PWM output 1
8	[Reserved]	-	Do not connect
9	D18/ $\overline{\text{SLEEP_RQ/DTR}}$	Input	Pin sleep control line or digital input 8
10	GND	-	Ground
11	DIO4/SPI_ MOSI	Both	Digital IO 4 / SPI Data In
12	DIO7/ $\overline{\text{CTS}}$	Both	Digital IO 7 / Clear-to-send flow control
13	ON/ $\overline{\text{SLEEP}}$	Output	Device sleep status indicator
14	V _{REF}	-	Feature not supported on this device. Used on other XBee devices for analog voltage reference.
15	DIO5/ASSOC	Both	Digital IO 5 / Associated indicator
16	DIO6/ $\overline{\text{RTS}}$	Both	Digital IO 6 / Request-to-send flow control

Pin	Name	Direction	Function
17	DIO3/AD3/SPI_ SSEL	Both	Digital IO 3 / Analog input 3 / SPI select
18	DIO2/AD2/SPI_ CLK	Both	Digital IO 2 / Analog input 2 / SPI clock
19	DIO1/AD1/SPI_ ATTN	Both	Digital IO 1 / Analog input 1 / SPI Attention
20	DIO0/AD0	Both	Digital IO 0 / Analog input 0

The following table shows the pin assignments for the surface-mount device.

Pin	Name	Direction	Function
1	GND	-	Ground
2	VCC	-	Power supply
3	DOUT	Output	UART data out
4	DIN/ $\overline{\text{CONFIG}}$	Input	UART data in
5	[Reserved]	Output	Do not connect
6	$\overline{\text{RESET}}$	Input	Module reset (reset pulse must be at least 200 ns). This must be driven as an open drain/collector. The device drives this line low when a reset occurs. Never drive this line high.
7	PWM0/RSSI PWM	Output	PWM output 0 / RX signal strength indicator
8	PWM1	Output	PWM output 1
9	[Reserved]	-	Do not connect
10	DI8/ $\overline{\text{SLEEP_RQ/DTR}}$	Input	Pin sleep control line or digital input 8
11	GND	-	Ground

Pin	Name	Direction	Function
12	SPI_ $\overline{\text{ATTN/BOOTMODE}}$	Output	SPI Attention. Do not tie low on reset.
13	GND	-	Ground
14	SPI_CLK	Input	SPI clock
15	SPI_ $\overline{\text{SSEL}}$	Input	SPI select
16	SPI_MOSI	Input	SPI Data In
17	SPI_MISO	Output	SPI Data Out
18	[Reserved]	-	Do not connect
19	[Reserved]	-	Do not connect
20	[Reserved]	-	Do not connect
21	[Reserved]	-	Do not connect
22	GND	-	Ground
23	[Reserved]	-	Do not connect
24	DIO4	Both	Digital IO 4
25	DIO7/ $\overline{\text{CTS}}$	Both	Digital IO 7 / Clear-to-send flow control
26	On/ $\overline{\text{SLEEP}}$	Output	Device sleep status indicator
27	V _{REF}	-	Feature not supported on this device. Used on other XBee devices for analog voltage reference.
28	DIO5/ASSOC	Both	Digital IO 5 / Associated indicator
29	DIO6/ $\overline{\text{RTS}}$	Both	Digital IO 6 / Request-to-send flow control

Pin	Name	Direction	Function
30	DIO3/AD3	Both	Digital IO 3 / Analog input 3
31	DIO2/AD2	Both	Digital IO 2 / Analog input 2
32	DIO1/AD1	Both	Digital IO 1 / Analog input 1
33	DIO0/AD0	Both	Digital IO 0 / Analog input 0
34	[Reserved]	-	Do not connect
35	GND	-	Ground
36	RF	Both	RF connection
37	[Reserved]	-	Do not connect

Notes

Minimum connections: VCC, GND, DOUT and DIN.

Minimum connections for updating firmware: VCC, GND, DIN, DOUT, RTS and DTR.

The table specifies signal direction with respect to the device.

The device includes a 50 k Ω pull-up resistor attached to RESET.

Use the **PR** (Pull-up/Down Resistor Enable) command to configure several of the input pull-ups.

You can connect other pins to external circuitry for convenience of operation including the Associate LED pin (pin 15). The Associate LED flashes differently depending on the state of the device.

Leave any unused pins disconnected.

Design notes

The following guidelines help to ensure a robust design.

Power supply design

A poor power supply can lead to poor device performance, especially if you do not keep the supply voltage within tolerance or if it is excessively noisy. To help reduce noise, place a 1.0 μ F and 8.2 pF capacitor as near as possible to pin 1 on the PCB. If you are using a switching regulator for the power supply, switch the frequencies above 500 kHz. Limit the power supply ripple to a maximum 100 mV peak to peak.

Board layout

We design XBee devices to be self sufficient and have minimal sensitivity to nearby processors, crystals or other printed circuit board (PCB) components. Keep power and ground traces thicker than signal traces and make sure that they are able to comfortably support the maximum current specifications. There are no other special PCB design considerations to integrate XBee devices, with the exception of antennas.

Antenna performance

Antenna location is important for optimal performance. The following suggestions help you achieve optimal antenna performance. Point the antenna up vertically (up right). Antennas radiate and receive the best signal perpendicular to the direction they point, so a vertical antenna's omnidirectional radiation pattern is strongest across the horizon.

Position the antennas away from metal objects whenever possible. Metal objects between the transmitter and receiver can block the radiation path or reduce the transmission distance. Objects that are often overlooked include:

- metal poles
- metal studs
- structure beams
- concrete, which is usually reinforced with metal rods

If you place the device inside a metal enclosure, use an external antenna. Common objects that have metal enclosures include:

- vehicles
- elevators
- ventilation ducts
- refrigerators
- microwave ovens
- batteries
- tall electrolytic capacitors

Do not place XBee devices with the chip or integrated PCB antenna inside a metal enclosure.

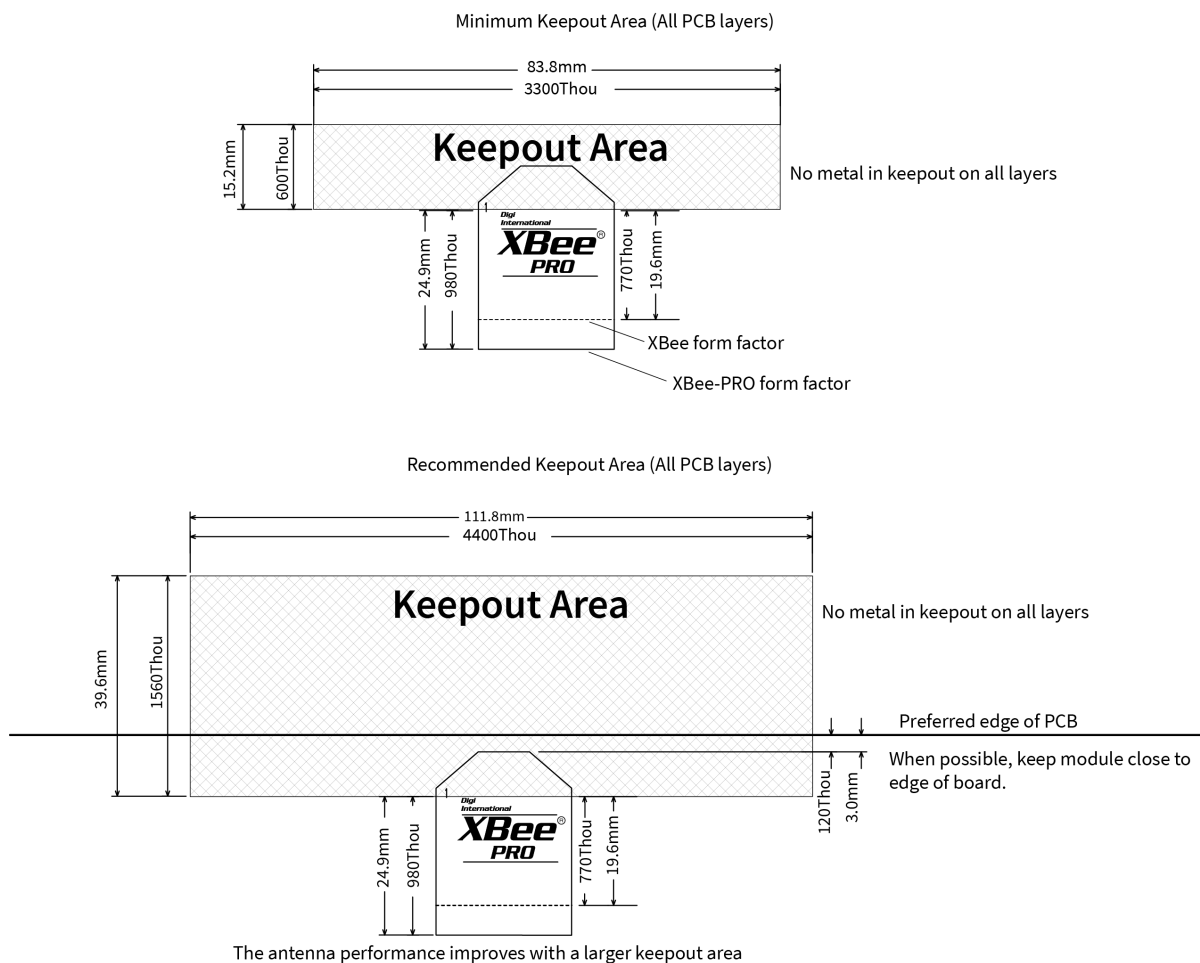
Do not place any ground planes or metal objects above or below the antenna.

For the best results, mount the device at the edge of the host PCB. Ensure that the ground, power, and signal planes are vacant immediately below the antenna section.

Keepout area

We recommend that you allow a “keepout” area, which the following drawings show.

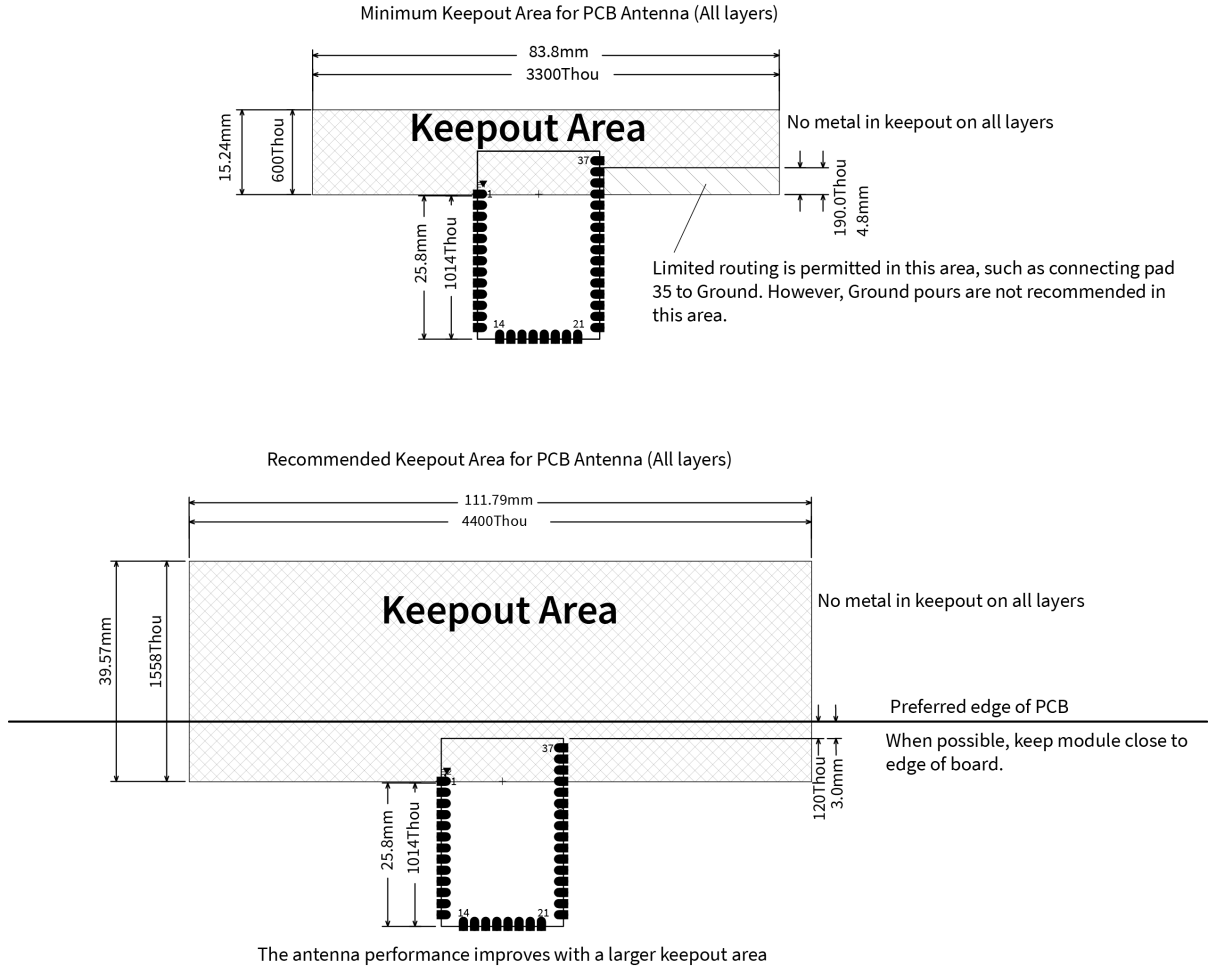
Through-hole keepout



Notes:

1. We recommend non-metal enclosures. For metal enclosures, use an external antenna.
2. Keep metal chassis or mounting structures in the keepout area at least 2.54 cm (1 in) from the antenna.
3. Maximize the distance between the antenna and metal objects that might be mounted in the keepout area.
4. These keepout area guidelines do not apply for Wire Whip antennas or external RF connectors. Wire whip antennas radiate best over the center of a ground plane.

Surface-mount keepout



Notes:

1. We recommend non-metal enclosures. For metal enclosures, use an external antenna.
2. Keep metal chassis or mounting structures in the keepout area at least 2.54 cm (1 in) from the antenna.
3. Maximize the distance between the antenna and metal objects that might be mounted in the keepout area.
4. These keepout area guidelines do not apply for Wire Whip antennas or external RF connectors. Wire whip antennas radiate best over the center of a ground plane.

RF pad version

The RF Pad is a soldered antenna connection on the surface-mount device. The RF signal travels from pin 36 on the module to the antenna through a single ended RF transmission line on the PCB. This line should have a controlled impedance of 50 Ω .

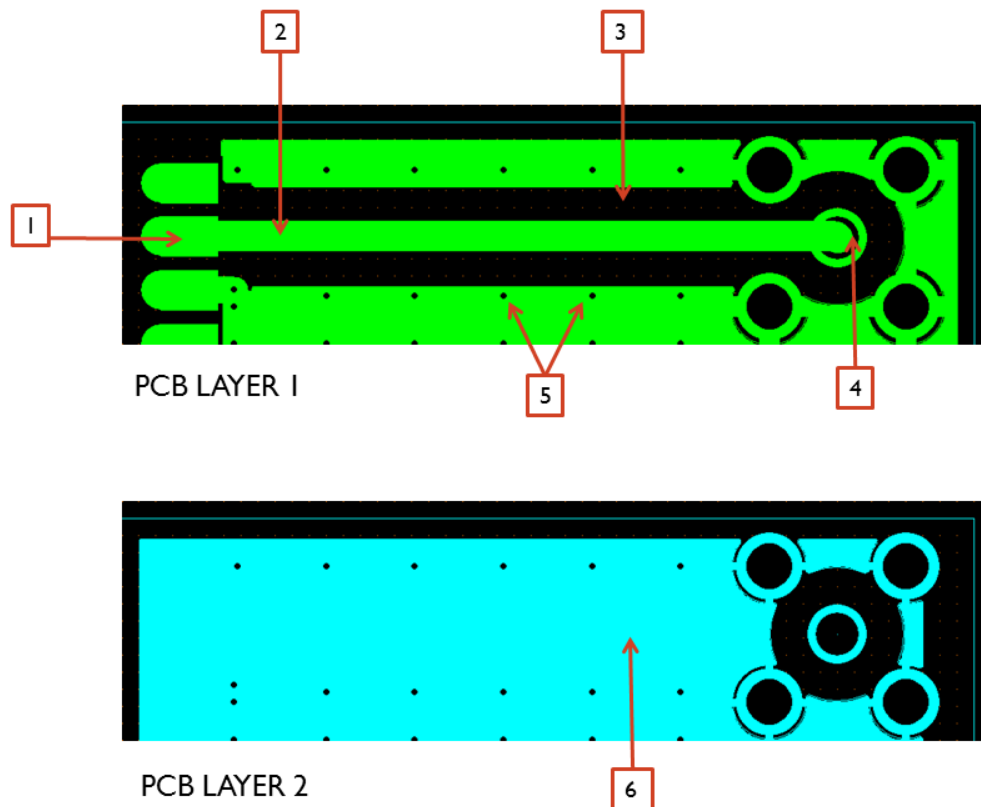
For the transmission line, we recommend either a microstrip or coplanar waveguide trace on the PCB. We provide a microstrip example below, because it is simpler to design and generally requires less area on the host PCB than coplanar waveguide.

We do not recommend using a stripline RF trace because that requires routing the RF trace to an inner PCB layer, and via transitions can introduce matching and performance problems.

The following figure shows a layout example of a microstrip connecting an RF Pad module to a through hole RPSMA RF connector.

- The top two layers of the PCB have a controlled thickness dielectric material in between. The second layer has a ground plane which runs underneath the entire RF Pad area. This ground plane is a distance d , the thickness of the dielectric, below the top layer.
- The top layer has an RF trace running from pin 36 of the module to the RF pin of the RPSMA connector. The RF trace's width determines the impedance of the transmission line with relation to the ground plane. Many online tools can estimate this value, although you should consult the PCB manufacturer for the exact width. Assuming $d = 0.025$ in, and that the dielectric has a relative permittivity of 4.4, the width in this example will be approximately 0.045 in for a 50Ω trace. This trace width is a good fit with the module footprint's 0.060 in pad width.

We do not recommend using a trace wider than the pad width, and using a very narrow trace can cause unwanted RF loss. The length of the trace is minimized by placing the RPSMA jack close to the module. All of the grounds on the jack and the module are connected to the ground planes directly or through closely placed vias. Space any ground fill on the top layer at least twice the distance d (in this case, at least 0.050 in) from the microstrip to minimize their interaction.



Number	Description
1	XBee surface-mount pin 36
2	50 Ω microstrip trace
3	Back off ground fill at least twice the distance between layers 1 and 2
4	RF connector
5	Stitch vias near the edges of the ground plane
6	Pour a solid ground plane under the RF trace on the reference layer

Implementing these design suggestions will help ensure that the RF Pad module performs to specifications.

Modes

Serial modes

The firmware operates in several different modes. Two top-level modes establish how the device communicates with other devices through its serial interface: Transparent operating mode and API operating mode.

The following modes describe how the serial port sends and receives data.

Transparent operating mode

Devices operate in this mode by default. We also call this mode “AT mode.” The device acts as a serial line replacement when it is in Transparent operating mode. The device queues all UART data it receives through the DIN pin for RF transmission. When a device receives RF data, it sends the data out through the DOUT pin. You can set the configuration parameters using the AT Command interface.

Note Transparent operating mode is not available when using the SPI interface.

The device buffers data in the the serial receive buffer until one of the following causes the data to be packetized and transmitted:

- The device receives no serial characters for the amount of time determined by the RO (Packetization Timeout) parameter. If RO = 0, packetization begins when a character is received.
- The device receives the Command Mode Sequence (GT + CC + GT). Any character buffered in the serial receive buffer before the sequence is transmitted.
- The device receives the maximum number of characters that will fit in an RF packet. See the NP parameter.

Serial-to-RF packetization

Data is buffered in the DI buffer until one of the following causes the data to be packetized and transmitted:

1. No serial characters are received for the amount of time determined by the **RO** (Packetization Timeout) parameter. If **RO** = 0, packetization begins when a character is received.
2. The maximum number of characters that will fit in an RF packet (100) is received. The maximum payload depends on whether you use Compatibility mode or not. If you use it, the maximum payload is 100 characters, but if you do not use it, depending on encryption, the App header and addressing, the payload can be larger.
3. The Command Mode Sequence (**GT + CC + GT**) is received. Any character buffered in the DI buffer before the sequence is transmitted.

If the device cannot immediately transmit (for instance, if it is already receiving RF data), the serial data is stored in the DI Buffer. The data is packetized and sent at any **RO** timeout or when 100 bytes (maximum packet size without Compatibility mode) are received.

If the DI buffer becomes full, hardware flow control must be implemented in order to prevent overflow (loss of data between the host and device).

API operating mode

API operating mode is an alternative to Transparent mode. It is helpful in managing larger networks and is more appropriate for performing tasks such as collecting data from multiple locations or controlling multiple devices remotely. API mode is a frame-based protocol that allows you to direct data on a packet basis. It can be particularly useful in large networks where you need control over the operation of the radio network or when you need to know which node a data packet is from. The device communicates UART or SPI data in packets, also known as API frames. This mode allows for structured communications with serial devices.

For more information, see [API mode overview on page 116](#).

Command mode

Command mode is a state in which the firmware interprets incoming characters as commands. Command mode allows you to modify the device's firmware using parameters you can set using AT commands. When you want to read or set any parameter of the device when operating in Transparent mode, you have to send an AT command while in Command mode. Every AT command starts with the letters "AT" followed by the two characters that identify the command the device issues and then by some optional configuration values.

Command mode is available on the UART interface in both Transparent and API modes. You cannot use the SPI interface to enter Command mode.

The availability of AT commands in API mode does not imply that Command mode is available in API mode. Also, command mode may be entered whether or not API mode is configured, providing the UART is the serial interface.

Enter Command mode

To get a device to switch into this mode, you must issue the following sequence: **GT + CC (+++) + GT**. When the device sees a full second of silence in the data stream (the guard time) followed by the string +++ (without Enter or Return) and another full second of silence, it knows to stop sending data through and start accepting commands locally.

Note Do not press Return or Enter after typing +++ because it will interrupt the guard time silence and prevent you from entering Command mode.

Once you send the Command mode sequence, the device sends **OK** out the UART pin. The device may delay sending the **OK** if it has not transmitted all of the serial data it received.

Once the device is in Command mode, it listens for user input and is able to receive AT commands on the UART. If **CT** time (default is 10 seconds) passes without any user input, the device drops out of Command mode and returns to Receive mode.

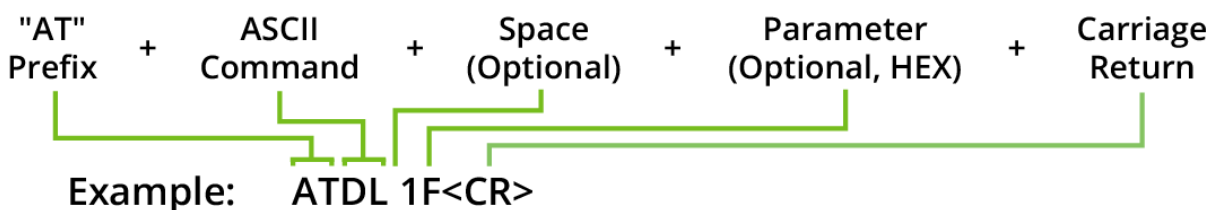
You can customize the guard times and timeout in the device's configuration settings. For information on how to do this, see [CC \(Command Sequence Character\) on page 115](#), [CT \(Command mode Timeout\) on page 113](#) and [GT \(Guard Times\) on page 114](#).

Troubleshooting

Failure to enter Command mode is commonly due to baud rate mismatch. Ensure that the baud rate of the connection matches the baud rate of the device. By default, the **BR** parameter = 3 (9600 b/s).

Send AT commands

Once the device enters Command mode, use the syntax in the following figure to send AT commands.



To read a parameter value stored in the device's register, omit the parameter field.

The preceding example would change the device's destination address (Low) to 0x1F.

To store the new value to non-volatile (long term) memory, send the **WR** (Write) command. This allows parameter values that you modify to persist in the device's registry after a reset. Otherwise, the device restores parameters to the previous values after a reset.

Respond to AT commands

When you send a command to the device, the device parses and runs the command. If the command runs successfully, the device returns an **OK** message. If the command errors, the device returns an **ERROR** message.

When reading parameters, the device returns the current parameter value instead of an **OK** message.

Apply command changes

Any changes you make to the configuration command registers using AT commands do not take effect until you apply the changes. For example, if you send the **BD** command to change the baud rate, the actual baud rate does not change until you apply the changes. To apply changes:

1. Send the **AC** (Apply Changes) command
or:
2. Exit AT Command mode

Exit Command mode

1. Send the **CN** (Exit Command Mode) command followed by a carriage return.
or:
2. If the device does not receive any valid AT commands within the time specified by **CT** (Command Mode Timeout), it returns to Transparent or API mode. The default Command Mode Timeout is 10 seconds.

Transceiver modes

The following modes describe how the transceiver sends and receives over-the-air (OTA) data.

Idle mode

When not receiving or transmitting data, the device is in Idle mode. During Idle mode, the device listens for valid data on both the RF and serial ports.

Transmit mode

When the device receives serial data and is ready to packetize it, the device attempts to transmit the serial data. The destination address determines which node(s) will receive and send the data.

Receive mode

This is the default mode for the XBee/XBee-PRO S2C 802.15.4 RF Module. The device is in receive mode when it is not transmitting data.

Operation

Configure the device using XCTU

XBee Configuration and Test Utility (XCTU) is a multi-platform program that enables developers to interact with Digi radio frequency (RF) devices through a graphical interface. The application includes built-in tools that make it easy to set up, configure, and test Digi RF devices.

For full support of the XBee/XBee-PRO S2C 802.15.4 RF Module, you must use XCTU version 6.3.0 or higher.

For instructions on downloading and using XCTU, go to:

<http://www.digi.com/products/xbee-rf-solutions/xctu-software/xctu>

Over-the-air (OTA) firmware update

The XBee/XBee-PRO S2C 802.15.4 RF Module supports OTA firmware updates using XCTU version 6.3.0 or higher. For instructions on performing an OTA firmware update, see:

<https://docs.digi.com/display/XCTU/How-to%3A+Update+the+firmware+of+your+modules>

OTA capability is only available when **MM** (Mac Mode) = 0 or 3

Addressing

Every RF data packet sent over-the-air contains a Source Address and Destination Address field in its header. The XBee/XBee-PRO S2C 802.15.4 RF Module conforms to the 802.15.4 specification and supports both short 16-bit addresses and long 64-bit addresses. A unique 64-bit IEEE source address is assigned at the factory and can be read with the **SL** (Serial Number Low) and **SH** (Serial Number High) commands. You must manually configure short addressing. A device uses its unique 64-bit address as its Source Address if its **MY** (16-bit Source Address) value is 0xFFFF or 0xFFFE.

Send packets to a specific device

To send a packet to a specific device using 64-bit addressing:

- Set the Destination Address (**DL** + **DH**) of the sender to match the Source Address (**SL** + **SH**) of the intended destination device.

To send a packet to a specific device using 16-bit addressing:

1. Set the **DL** parameter to equal the **MY** parameter of the intended destination device.
2. Set the **DH** parameter to 0.

Addressing modes

802.15.4 frames have a source address, a destination address, and a destination PAN ID in the over-the-air (OTA) frame. The source and destination addresses may be either long or short and the destination address may be either a unicast or a broadcast. The destination PAN ID is short and it may also be the broadcast PAN ID.

In Transparent mode, the destination address is set by the **DH** and **DL** parameters, but, in API mode, it is set by the TX Request: 64-bit address (0x00) or TX Request: 16-bit Address (0x01) frames. In either Transparent mode or API mode, the destination PAN ID is set with the **ID** parameter, and the source address is set with the **MY** parameter.

Broadcasts and unicasts

Broadcasts are identified by the 16-bit short address of 0xFFFF. Any other destination address is considered a unicast and is a candidate for acknowledgments, if enabled.

Broadcast PAN ID

The Broadcast PAN ID is also 0xFFFF. Its effect is to traverse all PANs in the vicinity. Typically, this only makes sense during association time when sending beacon requests to find PAN IDs.

Short and long addresses

A short address is 16 bits and a long address is 64 bits. The short address is set with the **MY** parameter. If the short address is 0xFFFE or 0xFFFF, then the address of the device is long and it is the serial number of the device as read by the **SH** and **SL** parameters.

Note When an end device associates to a coordinator, it is assigned the short address of 0xFFFE.

Encryption

The XBee/XBee-PRO S2C 802.15.4 RF Module supports AES 128-bit encryption. 128-bit encryption refers to the length of the encryption key entered with the **KY** command. (128 bits = 16 bytes.) The 802.15.4 protocol specifies eight security modes, enumerated as shown in the following table.

Level	Name	Encrypted?	Length of Message Integrity Check	Packet Length overhead
0	N/A	No	0 (no check)	0

Level	Name	Encrypted?	Length of Message Integrity Check	Packet Length overhead
1	MIC-32	No	4	9
2	MIC-64	No	8	13
3	MIC-128	No	16	21
4	ENC	Yes	0 (no check)	5
5	ENC-MIC-32	Yes	4	9
6	ENC-MIC-64	Yes	8	13
7	ENC-MIC-128	Yes	16	21

The XBee/XBee-PRO S2C 802.15.4 RF Module only supports security levels 0 and 4. It does not support message integrity checks. **EE 0** selects security level 0 and **EE 1** selects security level 4. When using encryption, all devices in the network must use the same 16-byte encryption key for valid data to get through. Mismatched keys will corrupt the data output on the receiving device. Mismatched **EE** parameters will prevent the receiving device from outputting received data.

Working from a maximum packet size of 116 bytes, encryption affects the maximum payload as shown in the following table.

Factor	Effect on Maximum Payload	Comment
Compatibility mode	Force to 95	If C8 bit 0 is set, all packets are limited to 95 bytes, regardless of other factors listed below. This is how the Legacy 802.15.4 module (S1 hardware) functions.
Packet overhead	Reduce by 5	This penalty for enabling encryption is unavoidable due to the 802.15.4 protocol.
Source address	Reduce by 6	This penalty is unavoidable because the 802.15.4 requires encrypted packets to be sent with a long source address, even if a short address would otherwise be used.

Factor	Effect on Maximum Payload	Comment
Destination address	Reduce by 6	This penalty only applies if sending to a long address rather than a short address.
App header	Reduce by 4	The app header for encryption is 4 bytes long. This penalty only applies if MM = 0 or 3.

Because of the two mandatory reductions when using encryption, no packet can exceed $116 - (5+6) = 105$ bytes. The other options may further reduce the maximum payload to 101 bytes, 99 bytes, or 95 bytes.

When operating in API mode and not using encryption, if the source address is long, the receiving device outputs an RX Indicator (0x80) frame for received data. But, if the source address is short, the receiving device outputs an Receive Packet (0x81) frame for received data. These same rules apply for encryption if **MM** is 0 or 3. This is possible because the four-byte encryption App header includes the short address of the sender and the long received address is not used for API output. If encryption is enabled with **MM** of 1 or 2, then no App header exists, the source address is always long, and the receiving device in API mode always outputs an RX Indicator (0x80) frame.

Maximum Payload

There is a maximum payload that you can send at one time, depending on the device's configuration.

These maximums only apply in API mode. If you attempt to send an API packet with a larger payload than specified, the device responds with a Transmit Status frame (0x89) with the Status field set to 74 (Data payload too large).

When using Transparent mode, the firmware splits the data as necessary to cope with maximum payloads.

Maximum payload rules

- If you enable transmit compatibility with the Legacy 802.15.4 module (S1 hardware):
 - There is a fixed maximum payload of 100 bytes if not using encryption
 - There is a fixed maximum payload of 95 bytes if using encryption
 - The rest of the rules do not apply. They apply only when you disable transmit compatibility with the Legacy 802.15.4 module.

2. The maximum achievable payload is 116 bytes. This is achieved when:
 - Not using encryption.
 - Not using the application header.
 - Using the short source address.
 - Using the short destination address.
3. If you are using the application header, the maximum achievable payload is reduced by:
 - 2 bytes if not using encryption.
 - 4 bytes if using encryption.
4. If you are using the long source address, the maximum achievable payload is reduced by 6 bytes (size of long address (8) - size of short address (2) = 6).
5. If you are using encryption, the short source addresses are promoted to long source addresses, so the maximum achievable payload is reduced by 6 bytes.
6. If you are using the long destination address, the maximum achievable payload is reduced by 6 bytes (the difference between the 8 bytes required for a long address and the 2 bytes required for a short address).
7. If you are using encryption, the maximum achievable payload is reduced by 5 bytes.

Maximum payload summary tables

The following table indicates the maximum payload when using transmit compatibility with the Legacy 802.15.4 module (S1 hardware).

Encryption	
Enabled	Disabled
95 B	100 B

The following table indicates the maximum payload when using the application header and not using encryption. Increment the maximum payload in 2 bytes if you are not using the application header.

Source Address	Destination Address	
	Short	Long
Short	114 B	108 B
Long	108 B	102 B

The following table indicates the maximum payload when using the application header and using encryption. Increment the maximum payload in 4 bytes if you are not using the application header.

	Destination Address	
	Short	Long
Source Address	Short	Long
Short	101 B	95 B
Long	101 B	95 B

Work with Legacy devices

The Legacy 802.15.4 module (S1 hardware) transmits packets one by one. It does not transmit a packet until it receives all expected acknowledgments of the previous packet or the timeout expires.

The new XBee/XBee-PRO S2C 802.15.4 RF Modules enhance transmission by implementing a transmission queue that allows the device to transmit to several devices at the same time. Broadcast transmissions are performed in parallel with the unicast transmissions.

This enhancement in the XBee/XBee-PRO S2C 802.15.4 RF Module can produce problematic behavior under certain conditions if the receiver is a Legacy 802.15.4 module (S1 hardware).

The conditions are:

- The sender is a XBee/XBee-PRO S2C 802.15.4 RF Module, and the receiver is a Legacy 802.15.4 module.
- The sender has the Digi Header enabled (**MM** = 0 or 3) and **RR** (XBee Retries) > 0.
- The sender sends broadcast and unicast messages at the same time to the Legacy 802.15.4 module without waiting for the transmission status of the previous packet.

The effect is:

- The receiver may display duplicate packets.

The solution is:

- Set bit 0 of the **C8** (802.15.4 Compatibility) parameter to 1 to enable TX compatibility mode in the XBee/XBee-PRO S2C 802.15.4 RF Module. This eliminates the transmission queue to avoid sending to multiple addresses simultaneously. It also limits the packet size to the levels of the Legacy 802.15.4 module.

Networking

The following table describes some common terms we use when discussing networks.

Term	Definition
Association	Establishing membership between End Devices and a Coordinator.
Coordinator	A full-function device (FFD) that provides network synchronization by polling nodes.
End Device	When in the same network as a Coordinator. Devices that rely on a Coordinator for synchronization and can be put into states of sleep for low-power applications.
PAN	Personal Area Network. A data communication network that includes one or more End Devices and optionally a Coordinator.

MAC Mode configuration

Medium Access Control (MAC) Mode configures two functions:

1. Enables or disables the use of a Digi header in the 802.15.4 RF packet.
When the Digi header is enabled (**MM** = 0 or 3), duplicate packet detection is enabled as well as certain AT commands.
Modes 1 and 2 do not include a Digi header, which disables many features of the device. All data is strictly pass through.
2. Enables or disables MAC acknowledgment request for unicast packets.
When MAC ACK is enabled (**MM** = 0 or 2), transmitting devices send packets with an ACK request so receiving devices send an ACK back (acknowledgment of RF packet reception) to the transmitter. If the transmitting device does not receive the ACK, it re-sends the packet up to three times or until the ACK is received.
Modes 1 and 3 disable MAC acknowledgment. Transmitting devices send packets without an ACK request so receiving devices do not send an ACK back to the transmitter.
Broadcast messages are always sent with the MAC ACK request disabled.

The following table summarizes the functionality.

Mode	Digi Header	MAC ACK
0 (default)	V	V
1		
2		V

Mode	Digi Header	MAC ACK
3	V	

The default value for the **MM** configuration parameter is 0 which enables both the Digi header and the MAC acknowledgment.

XBee retries configuration

Configures the maximum number of retries the device executes in addition to the three retries provided by the 802.15.4 MAC. The **RR** parameter controls XBee retries configuration. It is also known as Application Retries.

For each XBee retry, the 802.15.4 MAC can execute up to three retries.

This only applies if MAC Mode configuration has Digi Header enabled.

Transmit status based on MAC mode and XBee retries configurations

When working in API mode, a transmit request frame sent by the user is always answered with a transmit status frame sent by the device, if the frame ID is non-zero.

The following tables report the expected transmit status for unicast transmissions and the maximum number of MAC and application retries the device attempts.

The tables also report the transmit status reported when the device detects energy above the CCA threshold (when a CCA failure happens).

The following table applies in either of these cases:

- Digi Header is disabled.
- Digi Header is enabled and XBee Retries (**RR** parameter) is equal to 0 (default configuration).

Mac ACK Config	Destination reachable			Destination unreachable			CCA failure happened		
	TX status	Retries		TX status	Retries		TX status	Retries	
		MAC	App		MAC	App		MAC	App
Enabled	00 (Success)	up to 3	0	01 (No acknowledgment received)	3	0	02 (CCA failure)	3	0

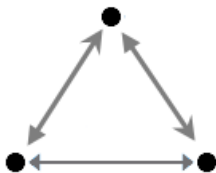
Mac ACK Config	Destination reachable			Destination unreachable			CCA failure happened		
	TX status	Retries		TX status	Retries		TX status	Retries	
		MAC	App		MAC	App		MAC	App
Disabled	00 (Success)	0	0	00 (Success)	0	0	02 (CCA failure)	3	0

The following table applies when:

- Digi Header is enabled and XBee Retries (**RR** parameter) is bigger than 0.

Mac ACK Config	Destination reachable			Destination unreachable			CCA failure happened		
	TX status	Retries		TX status	Retries		TX status	Retries	
		MAC	App		MAC	App		MAC	App
Enabled	00 (Success)	up to 3 per app retry	up to RR value	21 (Network ACK Failure)	3	RR value	02 (CCA failure)	3	RR value
Disabled	00 (Success)	0	up to RR value	21 (Network ACK Failure)	0	RR value	02 (CCA failure)	3	RR value

Peer-to-peer networks



By default, XBee/XBee-PRO S2C 802.15.4 RF Modules are configured to operate within a peer-to-peer network topology and therefore are not dependent upon Master/Slave relationships. This means that devices remain synchronized without the use of master/server configurations and each device in the network shares both roles of master and slave. Our peer-to-peer architecture features fast synchronization times and fast cold start times. This default configuration accommodates a wide range of RF data applications.

Master/Slave networks

In a Master Slave network, there is a coordinator and one or more end devices. When end devices associate to the coordinator, they become members of that Personal Area Network (PAN). As such, they share the same channel and PAN ID. PAN IDs must be unique to prevent miscommunication between PANs. Depending on the **A1** and **A2** parameters, association may assist in automatically assigning the PAN ID and the channel. These parameters are specified below based on the network role (end device or coordinator).

End device association

End device association occurs if **CE** is 0 and **A1** has bit 2 set. See the following table.

Bit	Hex value	Meaning
0	0x01	Allow PAN ID reassignment
1	0x02	Allow channel reassignment
2	0x04	Auto association
3	0x08	Poll coordinator on pin wake

By default, **A1** is 0, which disables association and effectively causes an end device to operate in peer-to-peer mode. When bit 2 is set, the end device associates to a coordinator. This is done by sending out an active scan to detect beacons from nearby networks. The active scan selects one channel and transmits a Beacon Request command to the broadcast address and the broadcast PAN ID. It then listens on that channel for beacons from any coordinator operating on that channel. The listen time on each channel is determined by the **SD** parameter. Once that time expires, the active scan selects the next channel, repeating until all channels have been scanned.

If **A1** is 0x04 (bit 0 clear, bit 1 clear, and bit 2 set), then the active scan will reject all beacons that do not match both the configured PAN ID and the configured channel. This is the best way to join a particular coordinator.

If **A1** is 0x05 (bit 0 set, bit 1 clear, and bit 2 set), then the active scan will accept a beacon from any PAN ID, providing the channel matches. This is useful if the channel is known, but not the PAN ID.

If **A1** is 0x06 (bit 0 clear, bit 1 set, and bit 2 set), then the active scan will accept a beacon from any channel, providing the PAN ID matches. This is useful if the PAN ID is known, but not the channel.

If **A1** is 0x07 (bit 0 set, bit 1 set, and bit 2 set), then the active scan will accept a beacon from any PAN ID and from any channel. This is useful when the network does not matter, but the one with the best signal is desired.

Whenever multiple beacons are received that meet the criteria of the active scan, then the beacon with the best link quality is selected. This applies whether **A1** is 0x04, 0x05, 0x06, or 0x07.

Before the End Device joins a network, the Associate LED will be on solid. After it joins a network, the Associate LED will blink twice per second.

In the event that association parameters are changed after the end device is associated, the end device will leave the network and re-join in accordance with the new configuration parameters.

Coordinator association

Coordinator association occurs if **CE** is 1 and **A2** has bit 2 set. See the following table.

Bit	Hex value	Meaning
0	0x01	Allow PAN ID reassignment
1	0x02	Allow channel reassignment
2	0x04	Allow association

By default, **A2** is 0, which prevents devices from associating to the coordinator. So, if **CE** is 1 and **A2** bit 2 is 0, the device still creates a network, but end devices are unable to associate to it.

If **A2** bit 2 is set, then joining is allowed after the coordinator forms a network.

If **A2** bit 0 is set, the coordinator issues an active scan. This means it will send out beacon requests to the broadcast address (0xFFFF) and the broadcast PAN ID (0xFFFF). Then, it will listen for beacons. The listen time is determined by the **SD** parameter. Then the same beacon request is sent out on the next channel and the device listens for beacon responses on that channel. This process repeats until each channel in the channel mask (**SC**) is scanned for **SD** time. If none of the beacons on any of the channels return a PAN ID equivalent with the **ID** parameter, then the coordinator will use the **ID** parameter for the PAN ID of the new network it forms. But, if a beacon response matches the PAN ID of the coordinator, the coordinator will form a PAN on a unique PAN ID.

If **A2** bit 0 is clear, then the coordinator will form a network on the PAN ID identified by the **ID** parameter, without regard to another network that might have the same PAN ID.

If **A2** bit 1 is set, the coordinator will issue an energy scan, similar to the active scan. It will listen on each channel specified in the **SC** parameter for the time indicated by the **SD** parameter. After the scan is complete, the channel with the least energy is selected to form the new network.

If **A2** bit 1 is clear, then no energy scan is performed and the **CH** parameter is used to select the channel of the new network.

If bits 0 and 1 of **A2** are both set, then an active scan is done followed by an energy scan. However, the channels on which the active scan finds a coordinator are eliminated as possible channels for the energy scan, unless such an action would eliminate all channels. If beacons are found on all channels in the channel mask, then the energy scan behaves the same as it would if beacons are not found on any of those channels. Therefore, the active scan will be performed on all channels in the channel mask. Then, an energy scan will be performed on the channels in the channel mask that did not find a coordinator.

Depending on the result of the active scan, the set of channels for the energy scan varies. If a PAN ID is found on all the channels in the channel mask, then the energy scan operates on all the channels in the channel mask. If at least one of the channels in the channel mask did not find a PAN ID, then the channels with PAN IDs are eliminated from consideration for the energy scan. After the energy scan completes, the channel with the least energy is selected for forming the new network.

Whenever **CE**, **ID**, **A2**, or **MY** changes, the network will leave and association will recur with the new parameters. Any end devices associated to the coordinator prior to changing one of these parameters will lose association. For this reason, it is important not to change these parameters on a coordinator unless needed.

Before the Coordinator forms a network, the Associate LED will be on solid. After it forms a network, the Associate LED will blink once per second.

Indirect addressing

The XBee/XBee-PRO S2C 802.15.4 RF Module may hold indirect messages until it runs out of buffers and the size of those messages does not matter. A brief summary follows:

A coordinator (**CE** = 1) must have **SP** set to a non-zero value to use indirect addressing. Otherwise, all frames will be sent directly, assuming the target device is awake. For best operation, **SP** and **ST** should be set to match the **SP** and **ST** values of the end nodes. The coordinator will hold onto an indirect message until it receives a poll from the device to which the message is addressed, or until a timeout, whichever occurs first. The timeout is 2.5 times the value of **SP**.

After an indirect message is sent, subsequent messages to the same address will be sent directly for a period of time equal to the **ST** parameter. The assumption is that the end device will remain awake for **ST** time after the last transmission or reception. Therefore, after a poll, every transmission and reception involving that address restart the **ST** timer. After the **ST** timer expires, the coordinator will again use indirect messaging (i.e it will hold messages awaiting a poll.)

End devices using cyclic sleep send a poll to the coordinator when they wake up unless **SO** bit 0 is set. End devices using pin sleep may be configured to send a poll on a pin wakeup by setting bit 3 of **A1**. Also the **FP** command can be used to send a poll upon exiting command mode. However, the poll is not sent while in command mode. Rather the poll is sent after changes are applied so that the module is ready to receive data after the poll is sent.

It is more difficult to use indirect addressing with pin sleep than with cyclic sleep because the end device must wake up periodically to poll for the data from the coordinator. Otherwise, the coordinator will discard the data. Therefore, cyclic sleep is the only recommended sleep mode for indirect addressing.

Association indicators

There are two types of association indicators: Asynchronous device status messages, and on demand queries. Asynchronous device status messages occur whenever a change occurs and API mode is enabled. On demand queries occur when the **AI** command is issued, which can occur in Command mode, in API mode, or as a remote command.

Device Status Messages

Not all device status messages are related with association, but for completeness all device status types reported by XBee/XBee-PRO S2C 802.15.4 RF Module are listed in the following table.

Type	Meaning
0x00	Hardware reset.
0x01	Watchdog reset.
0x02	End device successfully associated with a coordinator.
0x03	End device disassociated from coordinator or coordinator failed to form a new network.
0x06	Coordinator formed a new network.
0x0D	Input voltage on the XBee-PRO device is too high, which prevents transmissions.

Association indicator status codes

The XBee/XBee-PRO S2C 802.15.4 RF Module code can potentially give any of the status codes in the following table.

Code	Meaning
0x00	Coordinator successfully started, End device successfully associated, or operating in peer to peer mode where no association is needed.
0x03	Active Scan found a PAN coordinator, but it is not currently accepting associations.
0x04	Active Scan found a PAN coordinator in a beacon-enabled network, which is not a supported feature.
0x05	Active Scan found a PAN, but the PAN ID does not match the configured PAN ID on the requesting end device and bit 0 of AI is not set to allow reassignment of PAN ID.

Code	Meaning
0x06	Active Scan found a PAN on a channel does not match the configured channel on the requesting end device and bit 1 of A1 is not set to allow reassignment of the channel.
0x0C	Association request failed to get a response.
0x13	End device is disassociated or is in the process of disassociating.
0xFF	Initialization time; no association status has been determined yet.

Sleep

Sleep is implemented to support installations where a mains power source is not available and a battery is required. In order to increase battery life, the device sleeps, which means it stops operating. It can be woken by a timer expiration or a pin.

For more information about sleep modes, see [Sleep modes on page 60](#).

Sleep conditions

Since instructions stop executing while the device is sleeping, it is important to avoid sleeping when the device has work to do. For example, the device will not sleep if any of the following are true:

1. The device is operating in command mode, or in the process of getting into command mode with the +++ sequence.
2. The device is processing AT commands from API mode
3. The device is processing remote AT commands
4. Something is queued to the serial port and that data is not blocked by $\overline{\text{RTS}}$ flow control

If each of the above conditions are false, then sleep may still be blocked in these cases:

1. Enough time has not expired since the device has awakened.
 - a. If the device is operating in pin sleep, the amount of time needed for one character to be received on the UART is enough time.

- b. If the device is operating in cyclic sleep, enough time is defined by a timer. The duration of that timer is:
 - i. defined by **ST** if in **SM 5** mode and it is awakened by a pin
 - ii. 30 ms to allow enough time for a poll and a poll response
 - iii. 750 ms to allow enough time for association, in case that needs to happen
 - c. In addition, the wake time is extended by an additional **ST** time when new OTA data or serial data is received.
2. Sleep Request pin is not asserted when operating in pin sleep mode
 3. Data is waiting to be sent OTA.

Clear Channel Assessment (CCA)

Prior to transmitting a packet, a CCA (Clear Channel Assessment) is performed on the channel to determine if the channel is available for transmission. The detected energy on the channel is compared with the **CA** (Clear Channel Assessment) parameter value. If the detected energy exceeds the **CA** parameter value, the packet is not transmitted.

Also, a delay is inserted before a transmission takes place. You can set this delay using the **RN** (Backoff Exponent) parameter. If you set **RN** to 0, then there is no delay before the first CCA is performed. The **RN** parameter value is the equivalent of the “minBE” parameter in the 802.15.4 specification. The transmit sequence follows the 802.15.4 specification.

By default, the **MM** (MAC Mode) parameter = 0. On a CCA failure, the device attempts to re-send the packet up to two additional times.

When in Unicast packets with **RR** (Retries) = 0, the device executes two CCA retries. Broadcast packets always get two CCA retries.

Customers in Europe who have the XBee 802.15.5 module must manage their CCA settings. See [CA \(CCA Threshold\) on page 88](#) for **CA** values.

CCA operations

CCA is a method of collision avoidance that is implemented by detecting the energy level on the transmission channel before starting the transmission. The CCA threshold (defined by the **CA** parameter) defines the energy level that it takes to block a transmission attempt. For example, if CCA is set to the default value of 0x2C (which is interpreted as -44 dBm) then energy detected above the -44 dBm level (for example -40 dBm) temporarily blocks a transmission attempt. But if the energy level is less than that (for example -50 dBm), the transmission is not blocked. The intent of this feature is to prevent simultaneous transmissions on the same channel.

CCA can be set down to 0x50 (or -80 dBm), which approaches the sensitivity level. Setting such a threshold may not work in a noisy environment.

In the event that the energy level exceeds the threshold, the transmission is blocked some random number of backoff periods. The number of backoff periods is defined by $\text{random}(2^n - 1)$ where the initial value of n is defined by the **RN** parameter and it increments after each failure. When **RN** is set to its default value of 0, then $2^n - 1$ is 0, preventing any delay before the first energy detection on a new frame. However, n increments after each CCA failure, giving a greater range for the number of backoff periods between each energy detection cycle.

In the event that five energy detection cycles occur and each one detects too much energy, the application tries again 1 to 48 ms later. After the application retries are exhausted, then the transmission fails with a CCA error.

Whenever the MAC code reports a CCA failure, meaning that it performed five energy detection cycles with exponential random back-offs, and each one failed, the **EC** parameter is incremented. The EC parameter can be read at any time to find out how noisy the operating channel is. It continues to increment until it reaches its maximum value of 0xFFFF. To get new statistics, you can always set **EC** back to 0.

Serial interface

The XBee/XBee-PRO S2C 802.15.4 RF Module interfaces to a host device through a serial port. The device can communicate through its serial port with:

- Any logic and voltage compatible universal asynchronous receiver/transmitter (UART).
- Through a level translator to any serial device, for example, through an RS-232 or USB interface board.
- Through an SPI, as described in [SPI signals on page 50](#).

Serial port selection

The device has two serial ports and only one is active at a time. To be active, a port must be enabled and in use.

The UART is always enabled. The SPI is enabled if it is configured. To be configured, SPI_MISO, SPI_MOSI, SPI_SSEL, and SPI_CLK must all be configured as peripherals. On the surface-mount device, these lines are configured as peripherals by setting P5, P6, P7, and P8 to 1. This is also the default configuration for surface-mount devices.

On the through-hole device, those pins are not available and SPI is disabled by default. Therefore, the SPI pins are configured on a through-hole device by holding DOUT low during a reset. If the UART is not hooked up, then DOUT can be treated as an input to force the device into SPI mode. This special operation is best followed by a **WR** operation so that the SPI port will still be enabled on future resets without forcing DOUT low.

Once the SPI port is enabled by either means, it is still not active until the external SPI master asserts SPI_SSEL low. After the SPI port is active, the device will continue to use the SPI port until the next reset.

Serial receive buffer

When serial data enters the device through the DIN Pin (or the MOSI pin), it stores the data in the serial receive buffer until the device can process it. Under certain conditions, the device may not be able to process data in the serial receive buffer immediately. If large amounts of serial data are sent to the device such that the serial receive buffer would overflow, then it discards new data. If the UART is in use, you can avoid this by the host side honoring CTS flow control.

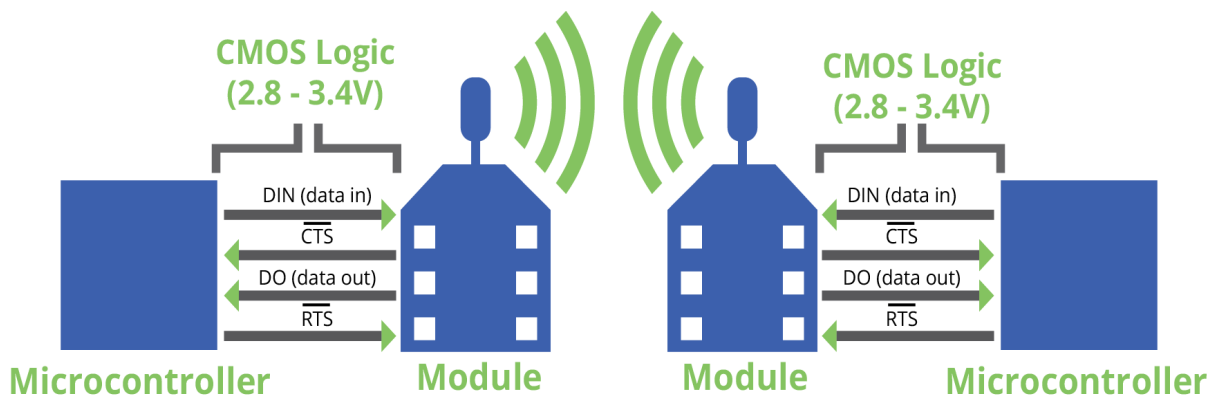
If the SPI is the serial port, no hardware flow control is available. It is your responsibility to ensure that the receive buffer does not overflow. One reliable strategy is to wait for a TX_STATUS response after each frame sent to ensure that the device has had time to process it.

Serial transmit buffer

When the device receives RF data, it moves the data into the serial transmit buffer and sends it out the UART or SPI port. If the serial transmit buffer becomes full and the system buffers are also full, then it drops the entire RF data packet. Whenever the device receives data faster than it can process and transmit the data out the serial port, there is a potential of dropping data.

UART data flow

Devices that have a UART interface can connect directly to the pins of the XBee/XBee-PRO S2C 802.15.4 RF Module as the following figure shows. The figure shows system data flow in a UART-interfaced environment. Low-asserted signals have a horizontal line over the signal name.

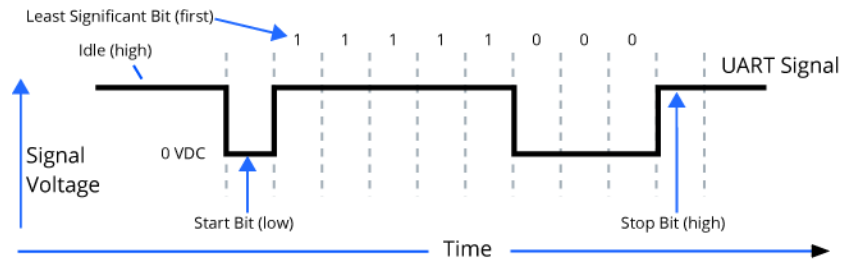


Serial data

A device sends data to the device's UART through pin 3 (DIN) as an asynchronous serial signal. When the device is not transmitting data, the signal idles high.

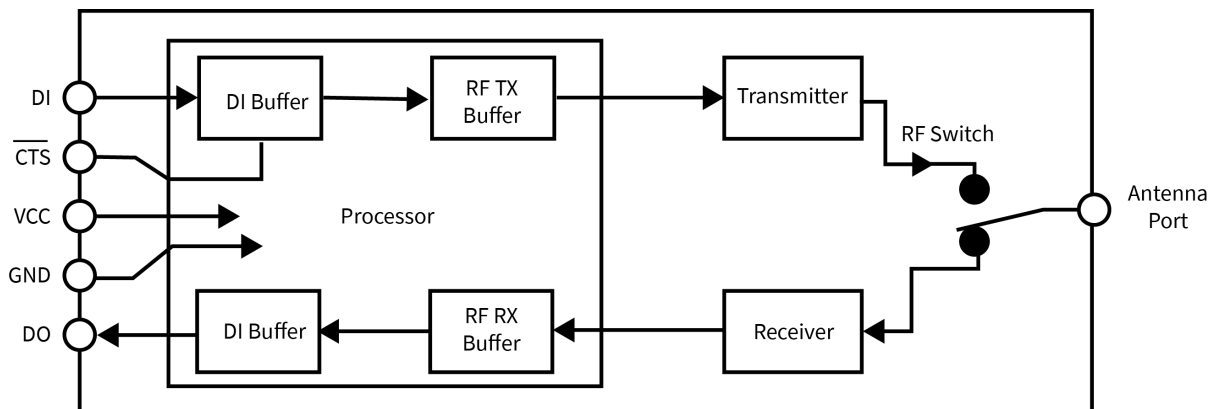
For serial communication to occur, you must configure the UART of both devices with compatible settings for the baud rate, parity, start bits, stop bits, and data bits. Each data byte consists of a start bit (low), 8 data bits (least significant bit first) and a stop bit (high). The following diagram illustrates the serial bit pattern of data passing through the device. It shows UART data packet 0x1F (decimal number 31) as transmitted through the device.

You can configure the UART baud rate, parity, and stop bits settings on the XBee module with the BD, NB, and SB commands respectively. See [Command reference](#) tables for details.



Flow control

The XBee/XBee-PRO S2C 802.15.4 RF Module maintains buffers to collect serial and RF data that it receives. The serial receive buffer collects incoming serial characters and holds them until the device can process them. The serial transmit buffer collects the data it receives via the RF link until it transmits that data out the serial port. The following figure shows the process of device buffers collecting received serial data.



CTS flow control

If you enable CTS flow control (by setting D7 to 1), when the serial receive buffer is 17 bytes away from being full, the device de-asserts CTS (sets it high) to signal to the host device to stop sending serial data. The device reasserts CTS after the serial receive buffer has 34 bytes of space. The maximum space available for receiving serial data is 174 bytes, which is enough to hold 1.5 full packets of data.

Flow Control Threshold

Use the **FT** parameter to set the flow control threshold. Since the receive serial buffer is 174 bytes, you cannot set **FT** to more than $174 - 17 = 147$ bytes. This allows up to 17 bytes of data to come in after CTS is de-asserted before data is dropped. The default value of **FT** is 109, leaving space for an external device that responds slowly to CTS being de-asserted. The minimum value of **FT** is 17, which is the minimal operational level.

RTS flow control

If you send the **D6** command to enable $\overline{\text{RTS}}$ flow control, the device does not send data in the serial transmit buffer out the DOUT pin as long as $\overline{\text{RTS}}$ is de-asserted (set high). Do not de-assert $\overline{\text{RTS}}$ for long periods of time or the serial transmit buffer will fill. If the device receives an RF data packet and the serial transmit buffer does not have enough space for all of the data bytes, it discards the entire RF data packet.

If the device sends data out the UART when $\overline{\text{RTS}}$ is de-asserted (set high) the device could send up to five characters out the UART port after $\overline{\text{RTS}}$ is de-asserted.

Cases in which the DO buffer may become full, resulting in dropped RF packets:

1. If the RF data rate is set higher than the interface data rate of the device, the device may receive data faster than it can send the data to the host. Even occasional transmissions from a large number of devices can quickly accumulate and overflow the transmit buffer.
2. If the host does not allow the device to transmit data out from the serial transmit buffer due to being held off by hardware flow control.

Asynchronous Parameters

Asynchronous communication over a UART is configured with a start bit, data bits, parity, stop bits, and baud rate. Out of these, only parity and baud rate are configurable on the device for 802.15.4. This means that the connecting micro-controller must match the the start bits (1), the data bits (8), and the stop bits (1) of the device for proper communication.

Parity

Use the **NB** command to configure parity; see [NB \(Parity\) on page 93](#).

SPI operation

This section specifies how SPI is implemented on the device, what the SPI signals are, and how full duplex operations work.

SPI signals

The XBee/XBee-PRO S2C 802.15.4 RF Module supports SPI communications in slave mode. Slave mode receives the clock signal and data from the master and returns data to the master. The SPI port uses the following signals on the device:

Signal	SMT Pin #	SMT Applicable AT command	TH Pin #	TH Applicable AT command
SPI_MOSI (Master out, Slave in)	16	P6	11	D4
SPI_MISO (Master in, Slave out)	17	P5	4	P2
SPI_SCLK (Serial clock)	14	P8	18	D2
SPI_SSEL (Slave select)	15	P7	17	D3
SPI_ATT \bar{N} (Attention)	12	P9	19	D1

By default, the inputs have pull-up resistors enabled. Use the **PR** command to disable the pull-up resistors. When the SPI pins are not connected but the pins are configured for SPI operation, then the device requires the pull-ups for proper UART operation.

Signal description

SPI_MISO: When SPI_CLK is active, the device outputs the data on SPI_MISO at the SPI_CLK rate. If there are other SPI slave devices connected to the same SPI master, then the SPI_MISO output from XBee device must be externally tri-stated when SPI_SSEL is de-asserted to prevent multiple devices from driving SPI_MISO.

SPI_MOSI: The SPI master outputs data on this line at the SPI_CLK rate after it selects the desired slave. When you configure the device for SPI operations, this pin is an input.

SPI_SCLK: The SPI master outputs a clock on this pin, and the rate must not exceed the maximum allowed, 5 Mb/s. This signal clocks data transfers on MOSI and MISO.

SPI_SSEL: The SPI master outputs a low signal on this pin to select the device as an SPI slave. When you configure the device for SPI operations, this pin is an input. This signal enables serial communication with the slave.

SPI_ATT \bar{N} : The device asserts this pin low when it has data to send to the SPI master. When you configure this pin for SPI operations, it is an output (not tri-stated). This signal alerts the master that the slave has data queued to send. The device asserts this pin as soon as data is available to send to the SPI master and it remains asserted until the SPI master has clocked out all available data.

SPI parameters

Most host processors with SPI hardware allow you to set the bit order, clock phase and polarity. For communication with all XBee devices the host processor must set these options as follows:

- Bit order: send MSB first
- Clock phase (CPHA): sample data on first (leading) edge
- Clock polarity (CPOL): first (leading) edge rises

This is SPI Mode 0 and MSB first for all XBee devices. Mode 0 means that data is sampled on the leading edge and that the leading edge rises. MSB first means that bit 7 is the first bit of a byte sent over the interface.

SPI and API mode

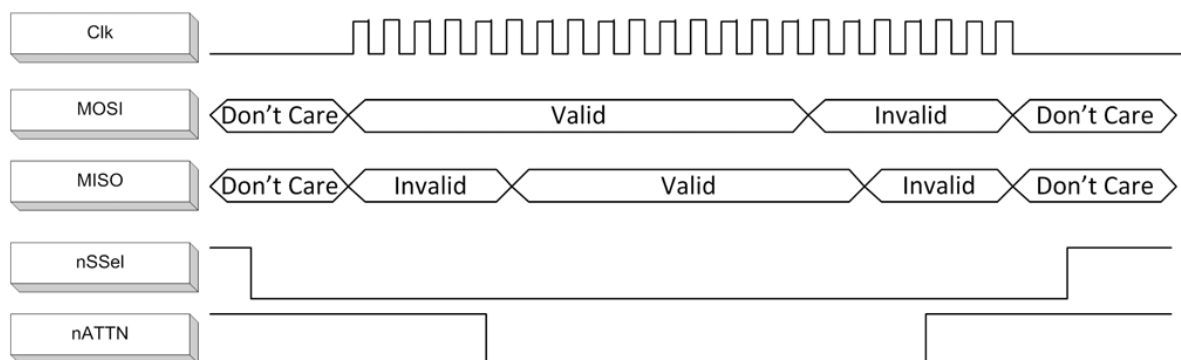
The SPI only operates in API mode 1. The SPI does not support Transparent mode or API mode 2 (with escaped characters). This means that the **AP** configuration only applies to the UART interface and is ignored while using the SPI.

Full duplex operation

When using SPI on the XBee/XBee-PRO S2C 802.15.4 RF Module the device uses API operation without escaped characters to packetize data. The device ignores the configuration of **AP** because SPI does not operate in any other mode. SPI is a full duplex protocol, even when data is only available in one direction. This means that whenever a device receives data, it also transmits, and that data is normally invalid. Likewise, whenever a device transmits data, invalid data is probably received. To determine whether or not received data is invalid, the firmware places the data in API packets.

SPI allows for valid data from the slave to begin before, at the same time, or after valid data begins from the master. When the master sends data to the slave and the slave has valid data to send in the middle of receiving data from the master, a full duplex operation occurs, where data is valid in both directions for a period of time. Not only must the master and the slave both be able to keep up with the full duplex operation, but both sides must honor the protocol.

The following figure illustrates the SPI interface while valid data is being sent in both directions.

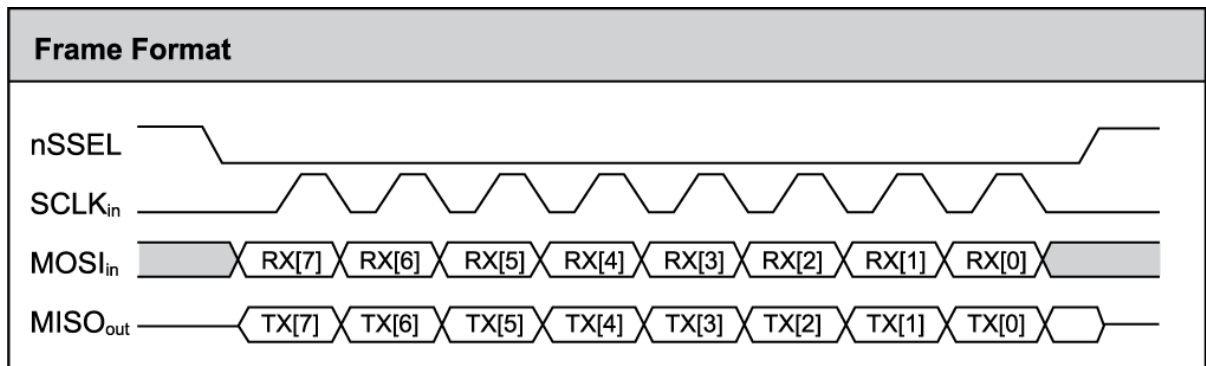


Slave mode characteristics

In slave mode, the following apply:

- SPI Clock rates up to 5 MHz (5 Mb/s) are possible.
- Data is MSB first.
- It uses Frame Format Mode 0. This means CPOL= 0 (idle clock is low) and CPHA = 0 (data is sampled on the clock's leading edge). The picture below diagrams Mode 0.
- The SPI port is setup for API mode and is equivalent to **AP** = 1.

The following picture show the frame format for SPI communications.



I/O support

The following topics describe analog and digital I/O line support, line passing and output control.

Digital I/O line support

Digital I/O is available on pins D0 through D8. Each of these pins may be configured as 3, 4, or 5 with the following meanings:

- 3 is digital input
- 4 is digital output low
- 5 is digital output high

Pins D0 through D8 are available for digital input, but only D0 through D7 are available for digital output.

Function	SMT pin	TH pin	AT command
DIO0	33	20	D0 (DIO0/AD0) on page 95
DIO1	32	19	D1 (DIO1/AD1) on page 96
DIO2	31	18	D2 (DIO2/AD2) on page 97

Function	SMT pin	TH pin	AT command
DIO3	30	17	D3 (DIO3/AD3) on page 97
DIO4	24	11	D4 (DIO4) on page 98
DIO5	28	15	D5 (DIO5/ASSOCIATED_INDICATOR) on page 98
DIO6	29	16	D6 (DIO6/RTS) on page 94
DIO7	25	12	D7 (DIO7/CTS) on page 93
DIO8	10	9	D8 (DIO8/SLEEP_REQUEST) on page 99

Analog input

Analog input is available on D0 through D3 by configuring these parameters to 2. Analog input is not available on D4 and D5.

On demand I/O sampling

You can use the **IS** (Force Sample) command to sample pins configured as Digital I/O and Analog input. If no pins are configured in this manner (with the **DO** - **D8** commands set to 2, 3, 4, or 5), then the **IS** command returns an error.

In Command mode, the output is:

Output	Description
01	Indicates one sample. That is the only possibility for Command mode.
20E	Mask to indicate which lines are sampled (A0, D3, D2, and D1).
00A	Digital sample indicates D3 high, D2 low, and D1 high.
3FF	Analog sample for A0 indicates that A0 is reading maximum voltage of 1.2 V.

In API mode, the output is:

```
7E 00 0C 83 00 00 00 00 01 03 3E 01 2A 02 10 FD
```

where:

83 Indicates RX Packet: 16-bit Address IO frame (0x83).

- 00 00 Indicates 16-bit source address.
- 00 Indicates RSSI (does not apply).
- 00 Indicates options.
- 01 Indicates the number of samples.
- 03 3E Mask to indicate which lines are sampled (A0, D8, D5, D4, D3, D2, and D1).
- 01 2A Digital sample that indicates that D8 is high, D5 is high, D4 is low, D3 is high, D2 is low, and D1 is high.
- 02 10 Indicates that A0 has input voltage nearly half of capacity, where 03 FF would indicate the full voltage of 1.2 V = 1200 mV.

For a remote **IS** command sent to the device listed above with the same configuration, the output is:

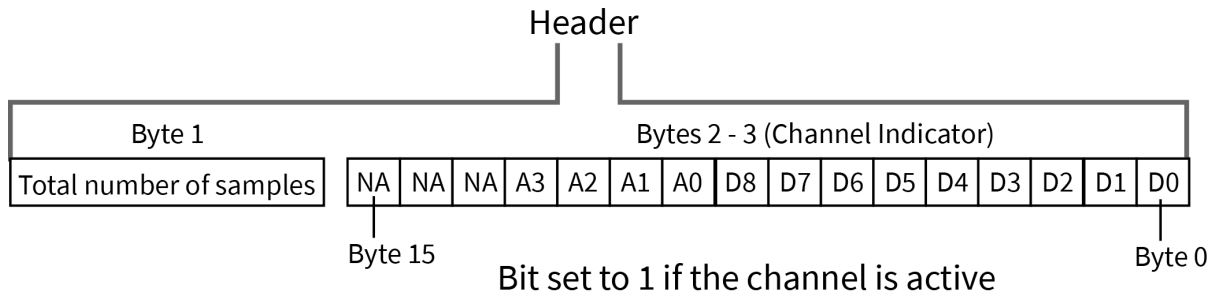
```
7E 00 16 97 01 00 13 A2 00 40 E3 C0 15 00 00 49 53 00 01 03 3E 01 2A 02 10 9F
```

where:

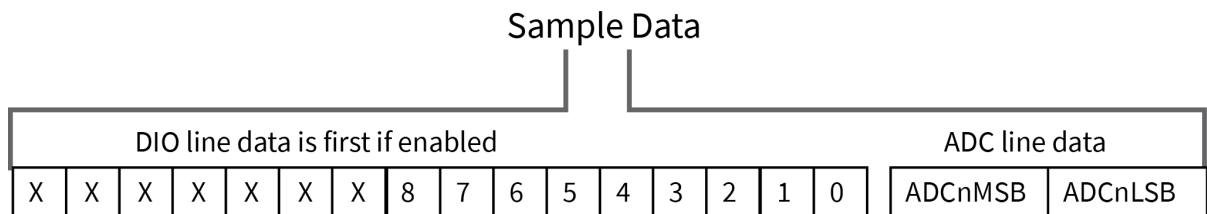
- 97 Indicates Remote AT Command Response frame (0x97).
- 01 Is the Frame ID.
- 00 13 A2 00 40 E3 C0 15 Is the 64-bit source address.
- 00 00 Indicates 16-bit source address.
- 49 53 (IS) Indicates command response to the **IS** command.
- 00 Indicates the status is OK.
- 01 Indicates the number of samples.
- 03 3E Mask to indicate which lines are sampled (A0, D8, D5, D4, D3, D2, and D1).
- 01 2A Digital sample that indicates that D8 is high, D5 is high, D4 is low, D3 is high, D2 is low, and D1 is high.
- 02 10 Indicates that A0 has input voltage about half of capacity, where 03 FF would indicate full voltage of 1.2 V = 1200 mV.

I/O data format

I/O data begins with a header. The first byte of the header defines the number of samples forthcoming. The last two bytes of the header (Channel Indicator) define which inputs are active. Each bit represents either a DIO line or ADC channel. The following figure illustrates the bits in the header.



Sample data follows the header and the channel indicator frame determines how to read the sample data. If any of the DIO lines are enabled, the first two bytes are the DIO sample. The ADC data follows. ADC channel data is represented as an unsigned 10-bit value right-justified on a 16-bit boundary. The following figure illustrates the sample data bits.



Multiple samples per packet

The **IT** parameter specifies how many I/O samples can be transmitted in a single OTA packet. Any single-byte value (0 - 0xFF) is accepted for input. However, the value is adjusted downward based on how many I/O samples can fit into a maximum size packet; see [Maximum Payload on page 35](#). A query of the **IT** parameter after changes are applied tells how many I/O samples actually occur.

Since **MM** must be 0 or 3 to send I/O samples, the maximum payload in the best of conditions (short source address, short destination address, and no encryption) is 114 bytes. Seven of those bytes are used by the command header and the I/O header, leaving 107 bytes for I/O samples. The minimum I/O sample is 2 bytes. Therefore the maximum possible usable value for **IT** is 53 (or 0x35).

API support

I/O data is sent out the UART using an API frame. All other data can be sent and received using Transparent Operation or API frames if API mode is enabled (**AP** > 0).

API Operations support two RX (Receive) frame identifiers for I/O data (set 16-bit address to 0xFFFFE and the device does 64-bit addressing):

- 0x82 for RX Packet: 64-bit Address IO
- 0x83 for RX Packet: 16-bit Address IO

The API command header is the same as shown in [RX Packet: 64-bit Address frame - 0x80 on page 133](#) and [RX Packet: 16-bit address IO - 0x83 on page 137](#). RX data follows the format described in [I/O data format on page 55](#).

Periodic I/O sampling

Periodic I/O sampling is done by periodically gathering samples on the source node and sending the samples to the destination node to output on its serial port.

Source node

On the source node, the **IR** parameter specifies how many milliseconds between samples. The **IT** parameter specifies how many samples will be sent OTA in a single packet, and the **DH/DL** parameters designate the node that will receive the samples. In addition **MM** must be 0 or 3 for I/O samples to be sent.

The maximum value of **IR** is 0xFFFF. If **IR** is 0, periodic I/O sampling is disabled. Otherwise, **IR** specifies the number of milliseconds between samples.

If **IT** is 0, then an I/O sample is sent every **IR** milliseconds. If **IR** is greater than 0, then an I/O sample is sent every **IR*IT** milliseconds. Any single-byte value (0 - 0xFF) is accepted for input. However, the value is adjusted downward based on how many I/O samples can fit into a maximum size packet. A query of the **IT** parameter after changes are applied tells how many I/O samples will actually occur. Since **MM** must be 0 or 3 to send I/O samples, the maximum payload in the best of conditions (short source address, short destination address, and no encryption) is 114 bytes. Seven of those bytes are used by the command header and the I/O header, leaving 107 bytes for I/O samples. The minimum I/O sample is 2 bytes. Therefore the maximum possible usable value for **IT** is 53 (or 0x35).

Although samples may be taken every millisecond, **IR*IT** should be at least 20 milliseconds. This allows time for OTA transmission and output on the serial port of the receiving module.

Destination node

On the destination node, the **IU** parameter enables the serial port to output I/O samples it receives. **IU** is set to 1 by default. If **IU** is set and the destination node is not in Command mode, it displays samples it receives on its serial port in API format. The **AP** parameter is ignored in this case.

Data format

The I/O sample is formatted as follows:

IT	Mask	Samples
1 byte	2 bytes	2 * number of samples

The **IT** field is described above.

The Mask is a bit field formatted as follows:

Reserved	A3 - A0	D8 - D0
3 bits	4 analog bits	9 digital bits

If you set any of the digital bits, then a digital sample follows the Mask.

For every analog bit that is set, there is a 10-bit sample using two bytes where **A0** is included first and **A3** is included last.

The number of samples indicated by the mask is repeated **IT** times. The mask is not repeated.

The sending node sends I/O samples to the address specified by **DH/DL**. The receiving node displays the samples as described above, providing API mode is enabled, the node is not in Command mode, and the **IU** parameter is 1 (**IU** is 1 by default). If any of these are false, the I/O sample is discarded without being displayed.

Change Detect I/O sampling

When you use the **IC** (DIO Change Detect) command to enable DIO Change Detect, DIO lines 0-7 are monitored. When a change is detected on a DIO line, the following occurs:

1. This packet does not contain DIO8 and does not contain any analog samples. However, it does contain a digital reading of the D0 - D7 pins configured for input or output, whether or not all those bits are set in **IC**.
2. Any queued samples are transmitted before the change detect data. This may result in receiving a packet with less than **IT** (Samples before TX) samples.

Change detect does not affect Pin Sleep wake-up. The D8 pin (DI8/SLEEP_RQ/DTR) is the only line that wakes a device from Pin Sleep. If not all samples are collected, the device still enters Sleep Mode after a change detect packet is sent.

Change detect is only supported when the **Dx** (DIOx Configuration) parameter equals 3, 4 or 5.

Wakeup I/O sampling

Bit 2 of the **SO** parameter specifies whether or not the device automatically samples the ADC/DIO lines on wakeup. On the receiving side the I/O sample may go to the I/O pins, the serial port, both, or neither based on the settings of the **IA** (I/O Input Address) and **IU** (I/O Output Enable) parameters.

For more information, see [SO \(Sleep Options\) on page 90](#), [IA \(I/O Input Address\) on page 109](#), and [IU \(I/O Output Enable\) on page 106](#).

Sample rate (interval)

The Sample Rate (Interval) feature allows enabled ADC and DIO pins to be read periodically on devices that are not configured to operate in Sleep Mode. When one of the Sleep Modes is enabled and the **IR** (Sample Rate) parameter is set, the device stays awake until **IT** (Samples before TX) samples have been collected.

Once a particular pin is enabled, the appropriate sample rate must be chosen. The maximum sample rate that can be achieved while using one A/D line is 1 sample/ms or 1 kHz. The device cannot keep up with transmission when **IR** and **IT** are equal to 1 and we do not recommend configuring the device to sample at rates greater than once every 20 ms.

I/O line passing

You can configure XBee/XBee-PRO S2C 802.15.4 RF Modules to perform analog and digital line passing. When a device receives an RF I/O sample data packet, you can setup the receiving device to update any enabled outputs (PWM and DIO) based on the data it receives.

Digital I/O lines are mapped in pairs, pins configured as digital input on the transmitting device affect the corresponding digital output pin on the receiving device. For example: DI5 (pin 25) can only update DO5 (pin 25).

No I/O line passing occurs if the receiving device does not have the corresponding pins set for output.

For Analog Line Passing, the XBee/XBee-PRO S2C 802.15.4 RF Module has two PWM output pins that simulate the voltage measured by the ADC lines AD0 and AD1. For example, when configured as an ADC, AD0 (pin 33) updates PWM0 (pin 7); AD1 (pin 32) updates PWM1 (pin 8).

The default setup is for outputs to not be updated. Instead, a device sends I/O sample data out the serial interface in API mode, even if the destination node is not configured for API mode. You can use the **IU** command to disable sample data output.

To enable updating the outputs, set the **IA** (I/O Input Address) parameter with the address of the device that has the appropriate inputs enabled. This effectively binds the outputs to a particular device's input. This does not affect the ability of the device to receive I/O line data from other devices - only its ability to update enabled outputs. Set the **IA** parameter to 0xFFFF (broadcast address) to setup the device to accept I/O data for output changes from any device on the network.

For line passing to function the device configured with inputs must generate sample data.

When outputs are changed from their configured state, the device can be setup to return the output level to its configured state after a timer expires. The timers are set using the **Tn (Dn Output Timer)** and **PT** (PWM Output Timeout) commands. The timers are reset every time the device receives a valid I/O sample packet with a matching **IA** address. You can adjust the **IT** (Samples before TX) and **IR** (Sample Rate) parameters on the transmitting device to keep the outputs set to their active output if the system needs more time than the timers can handle. Alternatively, the timers can be set to 0xFF, which prevents them from expiring (in other words, the outputs remain in the state specified by the input device indefinitely).

I/O line passing details

The same message is received for both I/O sampling and for I/O line passing. But I/O line passing only occurs if **IA** matches the short or long address of the sending node or if **IA** is 0xFFFF to match a sample from any node. The default value of **IA** is 0xfffffff, which prevents I/O line passing from occurring on the node because no node has that address. Additionally, the receiving device must have a matching value for output. For example, if an ADC0 sample is received, then **P0** must be configured with 2 for PWM output. Otherwise, the analog signal will not be reflected with a matching PWM signal. Likewise, if the sample indicates that D2 is high, but **D2** is not set to 4 or 5 on the receiving device, then the D2 pin will not be affected by I/O line passing.

Whenever a digital output pin is set to something different than its configured value, that pin may return to its configured value after the time specified for the corresponding timer. **TO** specifies how long D0 will hold its non-configured value and **T1** specifies how long D1 will hold its non-configured

value. A value of 0xFF indicates that a pin holds the value of the input of the corresponding device indefinitely and a value less than 0xFF specifies how many tenth second units the pin holds the non-configured value.

For PWM outputs, PT timer applies to both PWM0 and PWM1. Again, a value of 0xFF allows the PWM pin to output a duty cycle reflective of the analog input indefinitely and a smaller value indicates how many 10th second units before PWM output reverts to the duty cycle specified by **M0** or **M1**.

Output control

The **IO** (Digital Output Level) command controls the output levels of D0 through D7 that are configured as output pins (either 4 or 5). These values override the configured output levels of the pins until they are changed again (the pins do not automatically revert to their configured values after a timeout.) You can use the **IO** command to trigger a sample on change detect.

Sleep support

Automatic wake-up sampling can be suppressed by setting **SO** bit 1. When a device wakes, it always performs a sample based on any active ADC or DIO lines. This allows sampling based on the sleep cycle whether it be Cyclic Sleep (**SM** parameter = 4 or 5) or Pin Sleep (**SM** = 1). To gather more samples when awake, set the **IR** (Sample Rate) parameter.

For Cyclic Sleep modes: If the **IR** parameter is set, the device stays awake until the **IT** (Samples before TX) parameter is met. The device stays awake for **ST** (Time before Sleep) time.

Sleep modes

Sleep Modes enable the device to enter states of low-power consumption when not in use. In order to enter Sleep Mode, one of the following conditions must be met (in addition to the device having a non-zero **SM** parameter value):

- Sleep_RQ (pin 9 on through-hole devices, pin 10 on surface-mount devices) is asserted and the device is in a pin sleep mode (**SM** = 1, or 5)
- The device is idle (no data transmission or reception) for the amount of time defined by the **ST** (Time before Sleep) parameter.

Note **ST** is only active when **SM** = 4 or 5.

The following table shows the sleep modes.

Sleep mode	Description
SM 0	No sleep
SM 1	Pin Sleep
SM 4	Cyclic Sleep

Sleep mode	Description
SM 5	Cyclic Sleep with Pin Wake-up

Pin Sleep mode (SM = 1)

Pin Sleep mode minimizes quiescent power (power consumed when in a state of rest or inactivity). This mode is voltage level-activated; when Sleep_RQ (pin 9 for through-hole, pin 10 for surface-mount) is asserted, the device finishes any transmit, receive or association activities, enters Idle mode, and then enters a state of sleep. The device does not respond to either serial or RF activity while in pin sleep.

To wake a sleeping device operating in Pin Sleep mode, de-assert Sleep_RQ. The devices when Sleep_RQ is de-asserted and is ready to transmit or receive when the CTS line is low. When waking the device, the pin must be de-asserted at least two 'byte times' after $\overline{\text{CTS}}$ goes low. This assures that there is time for the data to enter the DI buffer.

Cyclic Sleep mode (SM = 4)

The Cyclic Sleep modes allow devices to periodically check for RF data. When the **SM** parameter is set to 4, the XBee/XBee-PRO S2C 802.15.4 RF Module is configured to sleep, then wakes once a cycle to check for data from a coordinator. The Cyclic Sleep Remote sends a poll request to the coordinator at a specific interval set by the **SP** (Cyclic Sleep Period) parameter. The coordinator transmits any queued data addressed to that specific remote upon receiving the poll request.

If no data is queued for the remote, the coordinator does not transmit and the remote returns to sleep for another cycle. If queued data is transmitted back to the remote, it stays awake to allow for back and forth communication until the **ST** (Time before Sleep) timer expires.

ON_SLEEP goes high and $\overline{\text{CTS}}$ goes low each time the remote wakes, allowing for communication initiated by the remote host if desired.

Cyclic Sleep with Pin Wake-up mode (SM = 5)

Use this mode to wake a sleeping remote device through either the RF interface or by de-asserting SLEEP_RQ for event-driven communications. The cyclic sleep mode works as described above with the addition of a pin-controlled wake-up at the remote device. The SLEEP_RQ pin is level-triggered. The device wakes when a low is detected then set CTS low as soon as it is ready to transmit or receive.

Any activity resets the **ST** (Time before Sleep) timer, so the device goes back to sleep only after there is no activity for the duration of the timer. Once the device wakes (pin-controlled), it ignores further pin activity. The device transitions back into sleep according to the **ST** time regardless of the state of the pin.

Sleep parameters

The following AT commands are associated with the sleep modes. See the linked commands for the parameter's description, range and default values.

- [SM \(Sleep Mode\) on page 88](#)
- [SO \(Sleep Options\) on page 90](#)
- [A1 \(End Device Association\) on page 79](#)
- [ST \(Time before Sleep\) on page 89](#)
- [SP \(Cyclic Sleep Period\) on page 89](#)
- [DP \(Disassociated Cyclic Sleep Period\) on page 90](#)

Sleep current

The following table shows the sleep current during the XBee/XBee-PRO S2C 802.15.4 RF Module sleep modes.

Sleep mode	SM command setting	Sleep current
Pin sleep	1	<1 μ A @ 25°C
Cyclic sleep	4	<1 μ A @ 25°C
Cyclic sleep with pin wake-up	5	<1 μ A @ 25°C

Low sleep current is achieved by driving PWM outputs high during sleep and by using internal pull-ups/pull-downs on disabled/unused pins. The sleep pins are set up for sleeping as specified in [Sleep pins on page 62](#). Additionally, pins that are outputs (other than PWM outputs) continue to output the same levels during sleep. Normally, this means that pins configured for output high or low will output high or low accordingly. However, if the output is overridden by I/O line passing, then the overridden output level is maintained during the sleep time.

Sleep pins

The following table describes the Three external device pins associated with sleep. For more details about the pins, see [Pin signals on page 18](#).

Pin name	Through-hole pin #	Surface-mount pin #	Description
SLEEP_RQ	9	10	For SM = 1, high puts the device to sleep and low wakes it up. For SM = 5, a high to low transition wakes the device up for ST time. The device ignores a low to high transition in SM = 5.
$\overline{\text{CTS}}$	12	25	If D7 = 1, high indicates that the device is asleep and low indicates that it is awake and ready to receive serial data.
$\overline{\text{ON_SLEEP}}$	13	26	Low indicates that the device is asleep and high indicates that it is awake and ready to receive serial data. For the 802.15.4 RF Module, this pin cannot be configured to anything different.

Direct and indirect transmission

There are two methods to transmit data:

- Direct transmission: data is transmitted immediately to the Destination Address
- Indirect transmission: a packet is retained for a period of time and is only transmitted after the destination device (source address = destination address) requests the data.

Indirect transmissions can only occur on a Coordinator. Thus, if all nodes in a network are End Devices, only direct transmissions will occur. Indirect transmissions are useful to ensure packet delivery to a sleeping node. The Coordinator currently is able to retain up to five indirect messages.

Direct transmission

A Coordinator can be configured to use only direct transmission by setting the **SP** (Cyclic Sleep Period) parameter to 0. Also, a Coordinator using indirect transmissions reverts to direct transmission if it knows the destination device is awake.

To enable this behavior, the **ST** (Time before Sleep) value of the Coordinator must be set to match the **ST** value of the End Device. Once the End Device either transmits data to the Coordinator or polls the Coordinator for data, the Coordinator uses direct transmission for all subsequent data transmissions to that device address until **ST** time occurs with no activity (at which point it reverts to using indirect transmissions for that device address). "No activity" means no transmission or reception of messages with a specific address. Broadcast messages do not reset the **ST** timer.

Indirect transmission

To configure Indirect Transmissions in a Personal Area Network (PAN), the **SP** (Cyclic Sleep Period) parameter value on the Coordinator must be set to match the longest sleep value of any End Device.

The sleep period value on the Coordinator determines how long (time or number of beacons) the Coordinator retains an indirect message before discarding it.

An End Device must poll the Coordinator once it wakes from Sleep to determine if the Coordinator has an indirect message for it. For Cyclic Sleep Modes, this is done automatically every time the device wakes (after **SP** time). For Pin Sleep Modes, the **A1** (End Device Association) parameter value must be set to enable Coordinator polling on pin wake-up (set in bit 3). Alternatively, an End Device can use the **FP** (Force Poll) command to poll the Coordinator as needed.

Acknowledgment

If the transmission is not a broadcast message, the device expects to receive an acknowledgment from the destination node. If an acknowledgment is not received, the packet is resent up to three more times. If the acknowledgment is not received after all transmissions, an ACK failure is recorded.

Node discovery

Node discovery has three variations as shown in the following table:

Commands	Syntax	Description
Node Discovery	ND	Seeks to discover all nodes in the network (on the current PAN ID).
Directed Node Discovery	ND <NI String>	Seeks to discover if a particular node named <NI String> is found in the network.
Destination Node	DN <NI String>	Sets DH/DL to point to the MAC address of the node whose <NI String> matches.

Node discovery

The node discovery command (without an NI string designated) sends out a broadcast to every node in the PAN ID. Each node in the PAN sends a response back to the requesting node.

When the node discovery command is issued in AT command mode, all other AT commands are inhibited until the node discovery command times out, as specified by the **NT** parameter. After the timeout, an extra CRLF is output to the terminal window, indicating that new AT commands can be entered. This is the behavior whether or not there were any nodes that responded to the broadcast.

When the node discovery command is issued in API mode, the behavior is the same except that the response is output in API mode. If no nodes respond, there will be no responses at all to the node discover command. The requesting node is not able to process a new AT command until **NT** times out.

Node discovery in compatibility mode

Node discovery (without an **NI** string parameter) in compatibility mode operates the same in compatibility mode as it does outside of compatibility mode with one minor exception:

If **C8** bit 1 is set and if requesting node is operating in API mode and if no responses are received by the time **NT** times out, then an API AT command response of OK (API frame type 0x88) is sent out the serial port rather than giving no response at all, which would happen if **C8** bit 1 is not set.

Directed node discovery

The directed node discovery command (**ND** with an **NI** string parameter) sends out a broadcast to find a node in the network with a matching **NI** string. If such a node exists, it sends a response with its information back to the requesting node.

In transparent mode, the requesting node will output an extra CRLF following the response from the designated node and the command will terminate, being ready to accept a new AT command. In the event that the requested node does not exist or is too slow to respond, the requesting node outputs an ERROR response after **NT** expires.

In API mode, the response from the requesting node will be output in API mode and the command will terminate immediately. If no response comes from the requested node, the requesting node outputs an error response in API mode after **NT** expires.

Directed node discovery in compatibility mode

The behavior of the Legacy 802.15.4 module (S1 hardware) varies with the default behavior described above for the directed node discovery command. The Legacy module does not complete the command until **NT** expires, even if the requested node responds immediately. After **NT** expires, it gives a successful response, even if the requested node did not respond. To enable this behavior to be equivalent to the Legacy 802.15.4 module, set bit 1 of the **C8** parameter.

Destination Node

The Destination Node command (**DN** with an **NI** string parameter) sends out a broadcast containing the **NI** string being requested. The responding node with a matching **NI** string sends its information back to the requesting node. The local node then sets **DH/DL** to match the address of the responding node. As soon as this response occurs, the command terminates successfully. If operating in AT command mode, an OK string is output and command mode exits. In API mode another AT command may be entered.

If an **NI** string parameter is not provided, the **DN** command terminates immediately with an error. If a node with the given **NI** string doesn't respond, the **DN** command terminates with an error after **NT** times out.

Unlike **ND** (with or without an **NI** string), **DN** does not cause the information from the responding node to be output; rather it simply sets **DH/DL** to the address of the responding node. If the responding node has a short address, then **DH/DL** is set to that short address (with **DH** at 0 and the

ms 16 bits of **DL** at 0). If the responding node has a long address (**MY** is FFFE), then **DH/DL** are set to the **SH/SL** of the responding node.

About remote configuration commands

The API firmware has provisions to send configuration commands to remote devices using the Remote AT Command Request frame (0x17); see [Remote AT Command Request frame - 0x17 on page 127](#). You can use this frame to send commands to a remote device to read or set command parameters.



Caution It is important to set the short address to 0xFFFE when sending to a long address. Any other value causes the long address to be ignored. This is particularly problematic in the case where nodes are set up with default addresses of 0 and the 16-bit address is erroneously left at 0. In that case, even with a correct long address the remote command goes out to all devices with the default short address of 0, potentially resulting in harmful consequences, depending on the command.

Send a remote command

To send a remote command populate the Remote AT Command Request frame (0x17) with:

1. The 64-bit address of the remote device
2. The correct command options value
3. The command and parameter data (optional). If and only if all nodes in the PAN have unique short addresses, then remote configuration commands can be sent to 16-bit short addresses by setting the short address in the API frame for Remote AT commands. In that case, the 64-bit address is unused and does not matter.

If you want to receive a command response, set the Frame ID to a non-zero value.

Apply changes on remote devices

Any changes you make to the configuration command registers using AT commands do not take effect until you apply the changes. For example, if you send the **BD** command to change the baud rate, the actual baud rate does not change until you apply the changes. To apply changes:

1. Set the apply changes option bit in the Remote AT Command Request frame (0x17).
2. Issue an **AC** (Apply Changes) command to the remote device.
3. Issue a **WR + FR** command to the remote device to save changes and reset the device.

Remote command responses

If the remote device receives a remote command request transmission, and the API frame ID is non-zero, the remote will send a remote command response transmission back to the device that sent the remote command. When a remote command response transmission is received, a device sends a

remote command response API frame out its UART. The remote command response indicates the status of the command (success, or reason for failure), and in the case of a command query, it includes the register value. The device that sends a remote command will not receive a remote command response frame if:

- The destination device could not be reached
- The frame ID in the remote command request is set to 0.

AT commands

Special commands

The following AT commands are special commands.

WR (Write)

Writes parameter values to non-volatile memory so that parameter modifications persist through subsequent resets.

Writing parameters to non-volatile memory does not apply the changes immediately. However, since non-volatile memory is used to determine initial configuration following reset, the written parameters are applied following a reset.

Note Once you issue **WR**, do not send any additional characters to the device until after you receive the **OK** response.

Parameter range

N/A

Default

N/A

RE (Restore Defaults)

Restore device parameters to factory defaults. Does not exit out of Command mode.

Parameter range

N/A

Default

N/A

FR (Software Reset)

Reset the device. The device responds immediately with an **OK** and performs a reset 100 ms later.

Parameter range

N/A

Default

N/A

Networking and security commands

The following AT commands are networking and security commands.

C8 (802.15.4 Compatibility)

Sets or reads the operational compatibility with the Legacy 802.15.4 module (S1 hardware).

Parameter range

0 - 3

Bit field:

Bit	Meaning	Setting	Description
0 ¹	TX compatibility	0	<p>Transmissions are optimized as follows:</p> <ol style="list-style-type: none"> 1. Maximum transmission size is affected by multiple factors (MM, MY, DH, DL, and EE). See Maximum payload rules on page 35. In the best case, with no app header, short source and destination addresses, and no encryption, the maximum transmission size is 116 bytes. 2. Multiple messages can be present simultaneously on the active queue, providing they are all destined for different addresses. This improves performance.
		1	<p>Transmissions operate like the Legacy 802.15.4 module, which means the following:</p> <ol style="list-style-type: none"> 1. Maximum transmission size is 95 bytes for encrypted packets and 100 bytes for un-encrypted packets. These maximum transmission sizes are not adjusted upward for short addresses or for lack of an APP header. 2. Only one transmission message can be active at a time, even if other messages in the queue would go to a different destination address.

¹This bit does not normally need to be set. However, when the XBee/XBee-PRO S2C 802.15.4 RF Module is streaming broadcasts in transparent mode to a Legacy 802.15.4 module (S1 hardware), and **RR** > 0, then this bit does need to be set to avoid a watchdog reset on the Legacy 802.15.4 module.

Bit	Meaning	Setting	Description
1	Node Discovery compatibility	0	Node discovery operates like other XBee devices and not like the Legacy 802.15.4 module. This means the following: <ol style="list-style-type: none"> 1. A directed ND request terminates after the single response arrives. This allows the device to process other commands without waiting for the NT to time out. 2. The device outputs an error response to the directed ND request if no response occurs within the time out.
		1	The module operates like the Legacy 802.15.4 module, which has the following effect: <ol style="list-style-type: none"> 1. When the expected response arrives, the command remains active until NT times out. (NT defaults to 2.5 seconds.) This prevents the device from processing any other AT command, even if the desired response occurs immediately. 2. When the timeout occurs, the command silently terminates and indicates success, whether or not a response occurred within the NT timeout.

Default

0

CH (Operating Channel)

Set or read the operating channel devices use to transmit and receive data. The channel is one of three addressing configurations available to the device. The other configurations are the PAN ID (**ID** command) and destination addresses (**DL** and **DH** commands).

In order for devices to communicate with each other, they must share the same channel number. A network can use different channels to prevent devices in one network from listening to the transmissions of another. Adjacent channel rejection is 23 dB.

The command uses 802.15.4 channel numbers. Center frequency = 2405 MHz + (**CH** - 11 decimal) * 5 MHz.

Parameter range

0xB - 0x1A (XBee)

0x0C - 0x17 (XBee-PRO)

Default

0xC (12 decimal)

ID (Network ID)

Set or read the user network identifier.

Devices must have the same network identifier to communicate with each other.

Setting the ID parameter to 0xFFFF indicates a global transmission for all PANs. It does not indicate a global receive.

Parameter range

0 - 0xFFFF

Default

0x3332 (13106 decimal)

DH (Destination Address High)

Set or read the upper 32 bits of the 64-bit destination address. When you combine **DH** with **DL**, it defines the destination address that the device uses for transmissions in Transparent mode. The destination address is also used for I/O sampling in both Transparent and API modes.

To transmit using a 16-bit address, set **DH** to 0 and **DL** less than 0xFFFF.

0x0000000000000000FFFF is the broadcast address. It is also used as the polling address when the device functions as end device.

Parameter range

0 - 0xFFFFFFFF

Default

0

DL (Destination Address Low)

Set or read the upper 32 bits of the 64-bit destination address. When you combine **DH** with **DL**, it defines the destination address that the device uses for transmissions in Transparent mode. The destination address is also used for I/O sampling in both Transparent and API modes.

0x0000000000000000FFFF is the broadcast address.

Parameter range

0 - 0xFFFFFFFF

Default

0

MY (Source Address)

Sets or reads the device's 16-bit source address. Set **MY** = 0xFFFF to disable reception of packets with 16-bit addresses. Regardless of **MY**, messages addressed to the 64-bit long address of the device are always delivered.

Parameter range

0 - 0xFFFF

Default

0

SH (Serial Number High)

Reads the upper 32 bits of the device's unique IEEE 64-bit extended address. The 64-bit source address is always enabled. The device serial number is set at the factory and is read-only.

Parameter range

0 - 0xFFFFFFFF

Default

Set in the factory.

SL (Serial Number Low)

Reads the lower 32 bits of the device's unique IEEE 64-bit extended address. The device's serial number is set at the factory and is read-only.

Parameter range

0 - 0xFFFFFFFF

Default

Set in the factory

MM (MAC Mode)

The **MM** command is used to set and read the MAC Mode value. The **MM** command disables/enables the use of a Digi header contained in the 802.15.4 RF packet. By default (**MM** = 0), Digi Mode is enabled and the module adds an extra header to the data portion of the 802.15.4 packet. This enables the following features:

- **ND** and **DN** command support
- Duplicate packet detection when using ACKs
- Remote command support
- **RR** command
- DIO/AIO sampling support
- OTA firmware updates

The **MM** command allows users to turn off the use of the extra header. Modes 1 and 2 are strict 802.15.4 modes. If the Digi header is disabled, the features above are also disabled.

When **MM** = 1 or 3, MAC retries are not supported.

When the Digi header is disabled, encrypted data that is not valid will be sent out of the UART and not filtered out.

Parameter range

0 - 3

Parameter	Configuration
0	Digi Mode (802.15.4 + Digi header)
1	802.15.4 (no ACKs)
2	802.15.4 (with ACKs)
3	Digi Mode (no ACKs)

Default

0

RR (XBee Retries)

Set or reads the maximum number of retries the device executes in addition to the three retries provided by the 802.15.4 MAC. For each device retry, the 802.15.4 MAC can execute up to three retries.

The following applies for broadcast messages: If **RR** = 0, only one packet is broadcast. If **RR** is > 0, **RR** + 2 packets are sent on each broadcast. No acknowledgments are returned on a broadcast.

This value does not need to be set on all devices for retries to work. If retries are enabled, the transmitting device sets a bit in the Digi RF Packet header that requests the receiving device to send an ACK. If the transmitting device does not receive an ACK within 200 ms, it re-sends the packet within a random period up to 48 ms. Each device retry can potentially result in the MAC sending the

packet four times (one try plus three retries). Retries are not attempted for indirect messages that are purged.

Parameter range

0 - 6

Default

0

0x10

RN (Random Delay Slots)

Sets or reads the minimum value of the back-off exponent in the CSMA-CA algorithm. The Carrier Sense Multiple Access - Collision Avoidance (CSMA-CA) algorithm was engineered for collision avoidance (random delays are inserted to prevent data loss caused by data collisions).

If **RN** = 0, there is no delay between a request to transmit and the first iteration of CSMA-CA.

Unlike CSMA-CD, which reacts to network transmissions after collisions have been detected, CSMA-CA acts to prevent data collisions before they occur. As soon as a device receives a packet that is to be transmitted, it checks if the channel is clear (no other device is transmitting). If the channel is clear, the packet is sent over-the-air. If the channel is not clear, the device waits for a randomly selected period of time, then checks again to see if the channel is clear. After a time, the process ends and the data is lost.

Parameter range

0 - 3 (exponent)

Default

0

ND (Network Discover)

Discovers and reports all of the devices it finds on a network. The command reports the following information for each device it discovers.

MY<CR>

SH<CR>

SL<CR>

DB<CR> (Contains the detected signal strength of the response in negative dBm units)

NI<CR> (Variable length)

For details of how this command works, see [Node discovery on page 64](#).

Parameter range

N/A

Default

N/A

NT (Node Discover Timeout)

Sets the amount of time a base node waits for responses from other nodes when using the **ND** (Node Discover) command. The **NT** value is transmitted with the **ND** command.

Remote nodes set up a random hold-off time based on this time. Once the **ND** command has ended, the base discards any response it receives.

Parameter range

0x1 - 0xFC (x 100 ms)

Default

0x19 (2.5 decimal seconds)

NO (Node Discover Options)

Use **NO** to suppress or include a self-response to **ND** (Node Discover) commands. When **NO** = 1, a device performing a Node Discover includes a response entry for itself.

Parameter range

0 - 1

Default

0x0

DN (Discover Node)

Resolves an **NI** (Nostring to a physical address (case sensitive).

The following events occur after **DN** discovers the destination node:

When **DN** is sent in Command mode:

1. The device sets **DL** and **DH** to the address of the device with the matching **NI** string. The address selected (either 16-bit short address or 64-bit extended address) is chosen based on the destination device's **MY** command configuration.
2. The receiving device returns OK (or ERROR).

3. The device exits Command mode to allow for immediate communication. If an ERROR is received, then Command mode does not exit.

When **DN** is sent as a local AT Command API frame (0x08):

1. The receiving device returns a success response in a AT Command Response (0x88) frame.
2. If there is no response from a module within (**NT** * 100) milliseconds or you do not specify a parameter (by leaving it blank), the receiving device returns an ERROR message.

Parameter range

20-byte ASCII string

Default

N/A

CE (Coordinator Enable)

Parameter range

0 - 1

Parameter	Description
0	End Device
1	Coordinator

Default

0

SC (Scan Channels)

Sets or reads the list of channels to scan for all Active and Energy Scans as a bit field. This affects scans initiated in by the **AS** (Active Scan) and **ED** (Energy Scan) commands in Command mode and during End Device Association and Coordinator startup.

Parameter range

0 - 0xFFFF (bit field)

Bit field:

Bit	Parameter
0	0x0B (not available on XBee-PRO)
1	0x0C
2	0x0D
3	0x0E
4	0x0F
5	0x10
6	0x11
7	0x12
8	0x13
9	0x14
10	0x15
11	0x16
12	0x17
13	0x18 (not available on XBee-PRO)
14	0x19 (not available on XBee-PRO)
15	0x1A (not available on XBee-PRO)

Default

0x1FFE

SD (Scan Duration)

Sets or reads the scan duration exponent.

End Device: Duration of Active Scan during Association.

Coordinator : If you set the **ReassignPANID** option on the Coordinator (refer to [A2 \(Coordinator Association\) on page 80](#)), **SD** determines the length of time the Coordinator scans channels to locate existing PANs. If you set the **ReassignChannel** option, **SD** determines how long the Coordinator performs an Energy Scan to determine which channel it will operate on.

Scan Time is measured as:

$$(\text{\# of channels to scan}] * (2 \wedge \text{SD}) * 15.36\text{ms})$$

Use the **SC** (Scan Channels) command to set the number of channels to scan. The XBee can scan up to 16 channels (**SC** = 0xFFFF). The XBee-PRO can scan up to 13 channels (**SC** = 0x3FFE).

Example

The following table shows the results for a thirteen channel scan.

SD setting	Time
0	0.18 s
2	0.74 s
4	2.95 s
6	11.80 s
8	47.19 s
10	3.15 min
12	12.58 min
14	50.33 min

Parameter range

0 - 0x0F (exponent)

Default

4

A1 (End Device Association)

Sets or reads the End Device association options.

Parameter range

0 - 0x0F (bit field)

Bit field:

Bit	Meaning	Setting	Description
0	Allow PanId reassignment	0	Only associates with Coordinator operating on PAN ID that matches device ID.
		1	May associate with Coordinator operating on any PAN ID.
1	Allow Channel reassignment	0	Only associates with Coordinator operating on matching CH channel setting.
		1	May associate with Coordinator operating on any channel.
2	Auto Associate	0	Device will not attempt association.
		1	Device attempts association until success.
3	Poll coordinator on pin wake	0	Pin Wake does not poll the Coordinator for indirect (pending) data.
		1	Pin Wake sends Poll Request to Coordinator to extract any pending data.
4 - 7	Reserved		

Default

0

A2 (Coordinator Association)

Sets or reads the Coordinator association options.

Parameter range

0 - 7 (bit field)

Bit field:

Bit	Meaning	Setting	Description
0	Allow PanId reassignment	0	Coordinator will not perform Active Scan to locate available PAN ID. It will operate on ID (PAN ID).
		1	Coordinator will perform Active Scan to determine an available ID (PAN ID). If a PAN ID conflict is found, the ID parameter will change.
1	Allow Channel reassignment	0	Coordinator will not perform Energy Scan to determine free channel. It will operate on the channel determined by the CH parameter.
		1	Coordinator will perform Energy Scan to find the quietest channel, then operate on that channel.
2	Allow Association	0	Coordinator will not allow any devices to associate to it.
		1	Coordinator will allow devices to associate to it.
3 - 7	Reserved		

Default

0

AI (Association Indication)

Reads the Association status code to monitor association progress. The following table provides the status codes and their meanings.

Status code	Meaning
0x00	Coordinator successfully started, End device successfully associated, or operating in peer to peer mode where no association is needed.
0x03	Active Scan found a PAN coordinator, but it isn't currently accepting associations.
0x04	Active Scan found a PAN coordinator in a beacon-enabled network, which is not a supported feature.

Status code	Meaning
0x05	Active Scan found a PAN, but the PAN ID doesn't match the configured PAN ID on the requesting end device and bit 0 of A1 is not set to allow reassignment of PAN ID.
0x06	Active Scan found a PAN on a channel that does not match the configured channel on the requesting end device and bit 1 of A1 is not set to allow reassignment of the channel.
0x0C	Association request failed to get a response.
0x13	End device is disassociated or is in the process of disassociating.
0xFF	Initialization time; no association status has been determined yet.

Parameter range

0 - 0x13 (read-only)

Default

-

FP (Force Poll)

Requests indirect messages being held by a Coordinator. The **FP** command is deferred until changes are applied. This prevents indirect messages from arriving at the end device while it is operating in Command mode.

Parameter range

N/A

Default

N/A

AS (Active Scan)

Sends a Beacon Request to a Broadcast address (0xFFFF) and Broadcast PAN (0xFFFF) on every channel in **SC**. **SD** determines the amount of time the device listens for Beacons on each channel. A PanDescriptor is created and returned for every Beacon received from the scan. Each PanDescriptor contains the following information:

CoordAddress (**SH** + **SL** parameters)<CR> (If **MY** on the coordinator is set less than 0xFFFF, the **MY** value is displayed)

CoordPanID (**ID** parameter)<CR>

CoordAddrMode <CR>

0x02 = 16-bit Short Address

0x03 = 64-bit Long Address

Channel (**CH** parameter) <CR>

SecurityUse<CR>

ACLEntry<CR>

SecurityFailure<CR>

SuperFrameSpec<CR> (2 bytes):

bit 15 - Association Permitted (MSB)

bit 14 - PAN Coordinator

bit 13 - Reserved

bit 12 - Battery Life Extension

bits 8-11 - Final CAP Slot

bits 4-7 - Superframe Order

bits 0-3 - Beacon Order

GtsPermit<CR>

RSSI<CR> (- RSSI is returned as -dBm)

TimeStamp<CR> (3 bytes)

<CR> (A carriage return <CR> is sent at the end of the **AS** command)

The Active Scan is capable of returning up to five PanDescriptors in a scan. The actual scan time on each channel is measured as:

$$\text{Time} = [(2 \wedge (\mathbf{SD} \text{ Parameter})) * 15.36] \text{ ms.}$$

Total scan time is this time multiplied by the number of channels to be scanned (as determined by the **SC** parameter).

Refer to the scan table in [SD \(Scan Duration\) on page 78](#) to determine scan times. If using API Mode, no <CR>'s are returned in the response. For more information, see [Operate in API mode on page 116](#).

Parameter range

0 - 6

Default

-

ED (Energy Detect)

Starts an energy detect scan. This parameter is the time in milliseconds to scan all channels. The device loops through all the channels until the time elapses. It returns the maximal energy on each channel, a comma follows each value, and the list ends with a carriage return. The values returned reflect the energy level that **ED** detects in -dBm units.

Parameter range

0 - 6

Default

N/A

EE (Encryption Enable)

Enable or disable 128-bit Advanced Encryption Standard (AES) encryption.

Set this command parameter the same on all devices in a network.

The firmware uses the 802.15.4 Default Security protocol and uses AES encryption with a 128-bit key. AES encryption dictates that all devices in the network use the same key, and that the maximum RF packet size is 95 bytes if Tx compatibility is enabled (you set bit 0 of **C8**). If **C8**, bit 0 is not set, see [Maximum Payload on page 35](#).

When encryption is enabled, the device always uses its 64-bit long address as the source address for RF packets. This does not affect how the **MY** (Source Address), **DH** (Destination Address High) and **DL** (Destination Address Low) parameters work.

If **MM** (MAC Mode) is set to 1 or 2 and **AP** (API Enable) parameter > 0:

With encryption enabled and a 16-bit short address set, receiving devices can only issue RX (Receive) 64-bit indicators. This is not an issue when **MM** = 0 or 3.

If a device with a non-matching key detects RF data, but has an incorrect key:

When encryption is enabled, non-encrypted RF packets received are rejected and are not sent out the UART.

Parameter range

0 - 1

Parameter	Description
0	Disabled
1	Enabled

Default

0

KY (AES Encryption Key)

Sets the 128-bit network security key value that the device uses for encryption and decryption.

This command is write-only. If you attempt to read **KY**, the device returns an OK status.

Set this command parameter the same on all devices in a network.

The entire payload of the packet is encrypted using the key and the CRC is computed across the ciphertext.

Parameter range

128-bit value (up to 16 bytes)

Default

N/A

NI (Node Identifier)

Stores the node identifier string for a device, which is a user-defined name or description of the device. This can be up to 20 ASCII characters.

The string only accepts printable ASCII data in Command mode.

The string cannot start with a space.

Use a carriage return or comma to end the command.

The command automatically ends when you enter the maximum bytes for the string.

Use the **ND** (Network Discovery) command with this string as an argument to easily identify devices on the network.

The **DN** command also uses this identifier.

Parameter range

Up to 20-byte ASCII string

Default

0x20 (an ASCII space character)

RF interfacing commands

The following AT commands are RF interfacing commands.

PL (TX Power Level)

Sets or reads the power level at which the device transmits conducted power.

For XBee-PRO, **PL**= 4 is calibrated and the remaining power levels are approximate. The device recalibrates its power setting every 15 seconds based on factory calibration settings and the current temperature.

For XBee, **PL** = 4, **PM** = 1 is tested at the time of manufacturing. Other power levels are approximate. On channel 26, transmitter power will not exceed -5 dBm.

Parameter range

0 - 4

The following table shows the TX power versus the **PL** setting.

XBee modules

PL setting	PM setting	Channel(s)	TX power* (dBm)
4	1	11 to 25	8
4	0	11 to 25	5
4	X	26	-5
3	1	11 to 25	6
3	0	11 to 25	3
3	X	26	-5
2	1	11 to 25	4
2	0	11 to 25	1
2	X	26	-5

PL setting	PM setting	Channel(s)	TX power* (dBm)
1	1	11 to 25	2
1	0	11 to 25	-1
1	X	26	-5
0	1	11 to 25	-2
0	0	11 to 25	-5
0	1	26	-5
0	0	26	-6

* Highest power level is tested during manufacturing. Other power levels are approximate.

XBee-PRO modules

PL setting	PM setting	Channel(s)	TX power* (dBm)
4	N/A	12 to 23	18
3	N/A	12 to 23	16
2	N/A	12 to 23	15
1	N/A	12 to 23	12
0	N/A	12 to 23	0

* Highest power level is tested during manufacturing. Other power levels are approximate.

Default

4

PM (Power Mode)

Selects or reads the device's Boost mode setting on a non-PRO device (this parameter has no effect on PRO devices). If enabled, boost mode improves sensitivity by 2 dB and increases output power by

2-3 dB, improving the link margin and range.

Parameter range

0 - 1

Setting	Meaning
0	Boost mode disabled
1	Boost mode enabled

Default

1

CA (CCA Threshold)

Set or read the Clear Channel Assessment (CCA) threshold. Prior to transmitting a packet, the device performs a CCA to detect energy on the channel. If the device detects energy above the CCA threshold, it will not transmit.

The **CA** parameter is measured in units of -dBm.

Note If device is operating in Europe, this value must be set to 0x34 to comply with EN 300 328 Listen Before Talk requirements. Alternatively the device can be set to **PL3** as explained in [Europe on page 158](#).

Parameter range

0x28 - 0x50

Default

0x2C (-44 decimal dBm)

Sleep commands

The following AT commands are sleep commands.

SM (Sleep Mode)

Sets or reads the sleep mode of the device.

By default, Sleep Modes are disabled (**SM** = 0) and the device remains in Idle/Receive mode. When in this state, the device is constantly ready to respond to either serial or RF activity.

Parameter range

0 - 1, 4 - 5

Parameter	Description
0	No sleep (disabled)
1	Pin sleep
2	Reserved
4	Cyclic Sleep Remote
5	Cyclic Sleep Remote with pin wakeup

Default

0

ST (Time before Sleep)

Sets or reads the wake time of the device.

The **ST** parameter is only valid for end devices configured with Cyclic Sleep settings (**SM** = 4 - 5) and for coordinators.

Coordinator and End Device **ST** values must be equal.

Parameter range

1 - 0xFFFF (x 1 ms)

Default

0x1388 (5 seconds)

SP (Cyclic Sleep Period)

Sets and reads the duration of time that a remote device sleeps. After the cyclic sleep period is over, the device wakes and checks for data. If data is not present, the device goes back to sleep. The maximum sleep period is 268 seconds (**SP** = 0x68B0).

The **SP** parameter is only valid if you configure the end device to operate in Cyclic Sleep (**SM** = 4-5). Coordinator and End Device **SP** values should always be equal.

To send Direct Messages on a coordinator, set **SP** = 0.

End Device: **SP** determines the sleep period for cyclic sleeping remotes. The maximum sleep period is 268 seconds (0x68B0).

Coordinator: If non-zero, **SP** determines the time to hold an indirect message before discarding it. A Coordinator discards indirect messages after a period of (2.5 * **SP**).

Parameter range

0 - 0x68B0 (x 10 ms) (4 min 28 seconds)

Default

0

DP (Disassociated Cyclic Sleep Period)

Sets or reads the sleep period for cyclic sleeping remotes that are configured for Association but that are not associated to a Coordinator. For example, if a device is configured to associate, and is configured as a Cyclic Sleep remote, but does not find a Coordinator, it sleeps for **DP** time before reattempting association.

The Maximum sleep period is 268 seconds (0x68B0).

DP should be > 0.

Parameter range

1 - 0x68B0 (x 10 ms)

Default

0x3E8 (10 seconds)

SO (Sleep Options)

Set or read the sleep options bit field of a device. This command is a bitmask.

You can set or clear any of the available sleep option bits.

Parameter range

0 - 0x3

Bit field:

Bit	Setting	Meaning	Description
0x01	0	Normal operations	A device configured for cyclic sleep will poll for data on waking

Bit	Setting	Meaning	Description
	1	Disable wakeup poll	A device configured for cyclic sleep will not poll for data on waking
0x02	0	Normal operations	A device configured in a sleep mode with ADC/DIO sampling enabled will automatically perform a sampling on wakeup
	1	Suppress sample on wakeup	A device configured in a sleep mode with ADC/DIO sampling enabled will not automatically sample on wakeup
Set all other option bits to 0.			

Default

0

Serial interfacing commands

The following AT commands are serial interfacing commands.

BD (Interface Data Rate)

Set or read the serial interface baud rate for communication between the serial port of the device and the host.

To request non-standard baud rates with values between 1200 b/s and 250,000 b/s (0x4B0 and 0x3D090), you can use the Serial Console toolbar in XCTU to configure the serial connection (if the console is connected), or click the **Connect** button (if the console is not yet connected).

When you send non-standard baud rates to a device, it stores the closest interface data rate represented by the number in the **BD** register. Read the **BD** command by sending **ATBD** without a parameter value, and the device returns the value stored in the **BD** register.

The RF data rate is not affected by the **BD** parameter.

Non-standard interface data rates

The firmware interprets any value from 0x4B0 through 0x3D090 as an actual baud rate. When the firmware cannot configure the exact rate specified, it configures the closest approximation to that rate. For example, to set a rate of 57600 b/s send the following command line: **ATBDE100**. Then, to find out the closest approximation, send **ATBD** to the console window. It sends back a response of 0xE0D1, which is the closest approximation to 57600 b/s attainable by the hardware.

Note When using XCTU, you can only set and read non-standard interface data rates using the XCTU Serial Console tool. You cannot access non-standard rates through the configuration section of XCTU.

When you send the **BD** command with a non-standard interface data rate, the UART adjusts to accommodate the interface rate you request. In most cases, the clock resolution causes the stored **BD** parameter to vary from the sent parameter. Sending **ATBD** without an associated parameter value returns the value actually stored in the device's **BD** register.

The following table provides the parameters sent versus the parameters stored.

BD parameter sent (HEX)	Interface data rate (b/s)	BD parameter stored (HEX)
0	1200	0
4	19,200	4
7	115,200	7
E100	57,600	E0D1
1C200	115,200	1C2B8

Parameter range

0 - 8 (standard rates)

Parameter	Description
0	1200 b/s
1	2400 b/s
2	4800 b/s
3	9600 b/s
4	19200 b/s
5	38400 b/s
6	57600 b/s
7	115200 b/s
8	230400 b/s

Default

3 (9600 b/s)

NB (Parity)

Set or read the parity settings for UART communications.

The device does not actually calculate and check the parity; it only interfaces with devices at the configured parity and stop bit settings.

Parameter range

0 - 4

Parameter	Description
0	No parity
1	Even parity
2	Odd parity
3	Mark parity (forced high)

Default

0

RO (Packetization Timeout)

Set or read the number of character times of inter-character silence required before transmission begins when operating in Transparent mode. RF transmission will also commence when the maximum payload (see [Maximum Payload on page 35](#)) is received in the DI buffer.

Set **RO** to 0 to transmit characters as they arrive instead of buffering them into one RF packet.

Parameter range

0 - 0xFF (x character times)

Default

3

D7 (DIO7/CTS)

The DIO7/CTS pin configuration (pin 12 for through-hole, pin 25 for surface-mount).

Parameter range

0, 1, 3 - 5

Parameter	Description
0	Disabled
1	$\overline{\text{CTS}}$ flow control
2	N/A
3	Digital input
4	Digital output, low
5	Digital output, high

Default

1

D6 (DIO6/ $\overline{\text{RTS}}$)

The DIO6/ $\overline{\text{RTS}}$ pin configuration (pin 16 for through-hole, pin 29 for surface-mount).

Parameter range

0, 1, 3 - 5

Parameter	Description
0	Disabled
1	$\overline{\text{RTS}}$ flow control
2	N/A
3	Digital input
4	Digital output, low
5	Digital output, high

Default

0

AP (API Enable)

The API mode setting. The device can format the RF packets it receives into API frames and send them out the serial port.

When you enable API, you must format the serial data as API frames because Transparent operating mode is disabled.

Parameter range

0 - 2

Parameter	Description
0	Transparent Mode. All UART input and output is raw data and the device uses the RO parameter to delineate packets.
1	API Mode Without Escapes. The device packetizes all UART input and output data in API format, without escape sequences.
2	API Mode With Escapes. The device is in API mode and inserts escaped sequences to allow for control characters. When XON (0x11), XOFF (0x13), Escape (0x7D), and start delimiter 0x7E are data, these bytes are escaped so that they never appear in the data and so that they can always be interpreted with their special meanings.

Default

0

I/O settings commands

The following AT commands are I/O settings commands.

D0 (DIO0/AD0)

The DIO0/AD0 pin configuration (pin 20 for through-hole, pin 33 for surface-mount).

Parameter range

0, 2 - 5

Parameter	Description
0	Disabled
1	N/A
2	ADC
3	Digital Input
4	Digital output, low
5	Digital output, high

Default

0

D1 (DIO1/AD1)

The DIO1/AD1 pin configuration (pin 19 for through-hole, pin 32 for surface-mount).

Parameter range

0 - 5

Parameter	Description
0	Disabled
1	$\overline{\text{SPI_ATTN}}$ for the through-hole device
2	ADC
3	Digital input
4	Digital output, low
5	Digital output, high

Default

0

D2 (DIO2/AD2)

The DIO2/AD2 pin configuration (pin 18 for through-hole, pin 31 for surface-mount).

Parameter range

0 - 5

Parameter	Description
0	Disabled
1	SPI_CLK for through-hole device
2	ADC
3	Digital input
4	Digital output, low
5	Digital output, high

Default

0

D3 (DIO3/AD3)

The DIO3/AD3 pin configuration (pin 17 for through-hole, pin 30 for surface-mount).

Parameter range

0 - 5

Parameter	Description
0	Disabled
1	SPI_SSEL for the through-hole device
1	SPI Slave Select
2	ADC

Parameter	Description
3	Digital input
4	Digital output, low
5	Digital output, high

Default

0

D4 (DIO4)

The DIO4 pin configuration (pin 11 for through-hole, pin 24 for surface-mount).

Parameter range

0, 1, 3 - 5

Parameter	Description
0	Disabled
1	SPI_MOSI for the through-hole device
2	N/A
3	Digital input
4	Digital output, low
5	Digital output, high

Default

0

D5 (DIO5/ASSOCIATED_INDICATOR)

The DIO5/ASSOCIATED_INDICATOR pin configuration (pin 15 for through-hole, pin 28 for surface-mount).

Parameter range

0, 1, 3-5

Parameter	Description
0	Disabled
1	Associate LED indicator - blinks when associated
2	N/A
3	Digital input
4	Digital output, low
5	Digital output, high

Default

1

D8 (DIO8/SLEEP_REQUEST)

The DIO8/SLEEP_REQUEST pin configuration (pin 9 for through-hole, pin 10 for surface-mount).

This command enables you to configure the pin to function as a digital input. This line is also used with Pin Sleep, but pin sleep ignores the D8 configuration. It is always used to control pin sleep, regardless of configuration of D8.

Parameter range

0, 3

Parameter	Description
0	Disabled
1	N/A
2	N/A
3	Digital input

Parameter	Description
4	N/A
5	N/A

Default

0

P0 (RSSI/PWM0 Configuration)

The RSSI/PWM0 pin configuration (pin 6 for through-hole, pin 7 for surface-mount).

This command enables the option of translating incoming data to a PWM so that the output can be translated back into analog form.

If the **IA** (I/O Input Address) parameter is correctly set and **P0** is configured as PWM0 output, incoming AD0 samples automatically modify the PWM0 value.

Parameter range

0 - 2

Parameter	Description
0	Disabled
1	RSSI PWM0 output
2	PWM0 output

Default

1

P1 (PWM1 Configuration)

The PWM1 pin configuration (pin 7 for through-hole, pin 8 for surface-mount).

If the **IA** (I/O Input Address) parameter is correctly set and **P1** is configured as PWM1 output, incoming AD0 samples automatically modify the PWM1 value.

Parameter range

0, 2

Parameter	Description
0	Disabled
2	PWM1 output

Default

0

P2 (SPI_MISO)

The SPI_MISO pin configuration (pin 4). This only applies to through-hole devices.

Parameter range

0 - 1

Parameter	Description
0	Disabled
1	SPI_MISO

Default

0

M0 (PWM0 Duty Cycle)

The duty cycle of the PWM0 line (pin 6 for through-hole, pin 7 for surface-mount). Use the **P0** command to configure the line as a PWM output.

If the **IA** (I/O Input Address) parameter is correctly set and **P0** is configured as PWM0 output, incoming AD0 samples automatically modify the PWM0 value.

Before setting the line as an output:

1. Enable PWM0 output (**P0** = 2).
2. Apply settings (use **CN** or **AC**).

The PWM period is 64 μ sec and there are 0x03FF (1023 decimal) steps within this period. When **M0** = 0 (0% PWM), 0x01FF (50% PWM), 0x03FF (100% PWM), and so forth.

Parameter range

0 - 0x3FF

Default

0

M1 (PWM1 Duty Cycle)

The duty cycle of the PWM1 line (pin 7 for through-hole, pin 8 for surface-mount). Use the **P1** command to configure the line as a PWM output.

Before setting the line as an output:

1. Enable PWM1 output (**P1** = 2).
2. Apply settings (use **CN** or **AC**)

Parameter range

0 - 0x3FF

Default

0

P5 (SPI_MISO)

The SPI_MISO pin configuration (pin 17). This only applies to surface-mount devices.

Parameter range

0, 1

Parameter	Description
0	Disabled
1	SPI_MISO

Default

1

P6 (SPI_MOSI)

The SPI_MOSI pin configuration (pin 16). This only applies to surface-mount devices.

Parameter range

0, 1

Parameter	Description
0	Disabled
1	SPI_MOSI

Default

1

P7 (SPI_SSEL)

The SPI_SSEL pin configuration (pin 15). This only applies to surface-mount devices.

Parameter range

1, 2

Parameter	Description
0	Disabled
1	SPI_SSEL

Default

1

P8 (SPI_SCLK)

The SPI_SCLK pin configuration (pin 14). This only applies to surface-mount devices.

Parameter range

1, 2

Parameter	Description
0	Disabled
1	SPI_SCLK

Default

1

P9 (SPI_ $\overline{\text{ATTN}}$)

The SPI_ $\overline{\text{ATTN}}$ pin configuration (pin 12). This only applies to surface-mount devices.

Parameter range

1, 2

Parameter	Description
0	Disabled
1	SPI_ $\overline{\text{ATTN}}$

Default

1

PR (Pull-up/Down Resistor Enable)

The bit field that configures the internal pull-up/down resistor status for the I/O lines. If you set a **PR** bit to 1, it enables the pull-up/down resistor; 0 specifies no internal pull-up/down resistor. The following table defines the bit-field map for both the **PR** and **PD** commands.

The **PD** (Pull Direction) parameter determines the direction of the internal pull-up/down resistor.

Bit	I/O line
0	DIO4 (pin 11)
1	AD3/DIO3 (pin 17)
2	AD2/DIO2 (pin 18)
3	AD1/DIO1 (pin 19)
4	AD0/DIO0 (pin 20)
5	$\overline{\text{RTS}}$ /DIO6 (pin 16)
6	DI8 (pin 9)
7	DIN/CONFIG (pin 3)

Bit	I/O line
Bit	I/O line
0	DIO4 (pin 11)
1	AD3/DIO3 (pin 17)
2	AD2/DIO2 (pin 18)
3	AD1/DIO1 (pin 19)
4	AD0/DIO0 (pin 20)
5	$\overline{\text{RTS}}$ /DIO6 (pin 16)
6	DI8 (pin 9)
7	DIN/CONFIG (pin 3)
Bit	I/O line
0	DIO4 (pin 11)
1	AD3/DIO3 (pin 17)
2	AD2/DIO2 (pin 18)
3	AD1/DIO1 (pin 19)
4	AD0/DIO0 (pin 20)
5	$\overline{\text{RTS}}$ /DIO6 (pin 16)
6	DI8 (pin 9)
7	DIN/CONFIG (pin 3)

Parameter range

0 - 0xFF (bit field)

Default

0xFF

Example

Sending the command **ATPR 6F** will turn bits 0, 1, 2, 3, 5 and 6 ON, and bits 4 and 7 OFF. The binary equivalent of **0x6F** is **01101111**. Bit 0 is the last digit in the bit field.

PD (Pull Direction)

See [PR \(Pull-up/Down Resistor Enable\) on page 104](#) for bit mappings, which are the same.

Parameter range

0x0-0xFF

Default

0xFF

IU (I/O Output Enable)

The **IU** command disables or enables I/O UART output. When enabled (**IU** = 1), received I/O line data packets are sent out the UART. The data is sent using an API frame regardless of the current **AP** parameter value.

Parameter range

Parameter	Description
0	Disabled
1	Enabled

Default

1

IT (Samples before TX)

Sets or reads the number of samples to collect before transmission. The maximum number of samples is dependent on the number of enabled I/O lines and the maximum payload available.

If **IT** is set to a number too big to fit in the maximum payload, it is reduced such that it will fit. A query of **IT** after setting it reports the actual number of samples in a packet.

Parameter range

0x1 - 0xFF

Default

1

IS (Force Sample)

Forces a read of all enabled digital and analog input lines. The data is returned through the UART or SPI.

When operating in Transparent Mode (**AP** = 0), the data is returned in the following format:

All bytes are converted to ASCII:

number of samples<CR>

channel mask<CR>

DIO data<CR> (If DIO lines are enabled)

ADC channel Data<CR> (This will repeat for every enabled ADC channel)

<CR> (end of data noted by extra <CR>)

When operating in API mode (**AP** = 1), the command immediately returns an **OK** response. The data follows in the normal API format for DIO data.

Parameter range

N/A

Default

N/A

IO (Digital Output Level)

Sets digital output levels. This allows DIO lines setup as outputs to be changed through Command Mode.

Parameter range

8-bit bit map; each bit represents the level of an I/O line setup as an output

Default

-

IC (DIO Change Detect)

Set or read the digital I/O pins to monitor for changes in the I/O state.

Each bit enables monitoring of DIO0 - DIO7 for changes. If detected, data is transmitted with DIO data only. Any samples queued waiting for transmission is sent first.

Set unused bits to 0.

Parameter range

0 - 0xFFFF

Default

0

IR (Sample Rate)

Set or read the I/O sample rate to enable periodic sampling. When set, this parameter causes the device to sample all enabled DIO and ADC at a specified interval.

To enable periodic sampling, set **IR** to a non-zero value, and enable the analog or digital I/O functionality of at least one device pin (see D0-D9, P0-P2 commands).

Parameter range

0 - 0xFFFF (x 1 ms)

Default

0

RP (RSSI PWM Timer)

The PWM timer expiration in 0.1 seconds. **RP** sets the duration of pulse width modulation (PWM) signal output on the RSSI pin. The signal duty cycle updates with each received packet and shuts off when the timer expires.

When **RP** = 0xFF, the output is always on.

Parameter range

0 - 0xFF (x 100 ms)

Default

0x28 (four seconds)

I/O line passing

The following AT commands are I/O line passing commands.

IA (I/O Input Address)

The source address of the device to which outputs are bound. Setting all bytes to 0xFF disables I/O line passing. Setting **IA** to 0xFFFF allows any I/O packet addressed to this device (including broadcasts) to change the outputs.

Parameter range

0 - 0xFFFF FFFF FFFF FFFF

Default

0xFFFFFFFFFFFFFFFF (Line passing disabled)

T0 (D0 Timeout)

Specifies how long pin D0 holds a given value before it reverts to configured value. If set to 0, there is no timeout.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

T1 (D1 Timeout)

Specifies how long pin D1 holds a given value before it reverts to configured value. If set to 0, there is no timeout.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

T2 (D2 Timeout)

Specifies how long pin D2 holds a given value before it reverts to configured value. If set to 0, there is no timeout.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

T3 (D3 Timeout)

Specifies how long pin D3 holds a given value before it reverts to configured value. If set to 0, there is no timeout.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

T4 (D4 Timeout)

Specifies how long pin D4 holds a given value before it reverts to configured value. If set to 0, there is no timeout.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

T5 (D5 Timeout)

Specifies how long pin D5 holds a given value before it reverts to configured value. If set to 0, there is no timeout.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

T6 (D6 Timeout)

Specifies how long pin D6 holds a given value before it reverts to configured value. If set to 0, there is no timeout.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

T7 (D7 Timeout)

Specifies how long pin D7 holds a given value before it reverts to configured value. If set to 0, there is no timeout.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

PT (PWM Output Timeout)

Specifies how long both PWM outputs (**P0**, **P1**) output a given PWM signal before it reverts to the configured value (**M0/M1**). If set to 0, there is no timeout. This timeout only affects these pins when they are configured as PWM output.

Parameter range

0 - 0xFF (x 100 ms)

Default

0xFF

VL (Version Long)

Shows detailed version information including the application build date and time.

Parameter range

N/A

Default

N/A

Diagnostic commands

The following AT commands are diagnostic commands. Diagnostic commands are typically volatile and will not persist across a power cycle.

VR (Firmware Version)

Reads the firmware version on a device.

Firmware version numbers have four significant digits. The reported number shows three or four numbers in hexadecimal notation. A version is reported as **ABCD**. Digits ABC are the main release number and D is the revision number from the main release.

Parameter range

0x2000 - 0x20FF

Default

Set in the factory

HV (Hardware Version)

Read the device's hardware version number.

Parameter range

0 - 0xFFFF (read-only)

Default

Set in the factory

DB (Last Packet RSSI)

This command reports the received signal strength of the last RF data packet that a device receives.

If the device has been reset and has not yet received a packet, this variable reports 0.

The command measures RSSI in -dBm. For example if **DB** returns 0x60, then the RSSI of the last packet received was -96 dBm.

Parameter range

[Read-only] 0x17 - 0x5C (XBee) 0x24 - 0x64 (XBee-PRO)

[Read-only] 0-0xFF

Default

-

EC (CCA Failures)

Resets or reads the count of Clear Channel Assessment (CCA) failures. This register increments when the device does not transmit a packet because it detected energy above the CCA threshold level set with **CA** command. This count saturates at its maximum value. Set the count to zero to reset the count.

Parameter range

0 - 0xFFFF

Default

-

EA (ACK Failures)

Resets or reads the count of acknowledgment failures. This register increments when the device expires the retries without receiving an ACK on a packet transmission. This count saturates at its maximum value. Set the count to zero to reset the count.

Parameter range

0 - 0xFFFF

Default

-

DD (Device Type Identifier)

The Digi device type identifier value. Use this value to differentiate between multiple devices.

Parameter range

0 - 0xFFFFFFFF (read-only)

Default

0x10000

Command mode options

The following AT commands are Command mode option commands.

CT (Command mode Timeout)

Set or read the Command mode timeout parameter. If a device does not receive any valid commands within this time period, it returns to Idle mode from Command mode.

Parameter range

2 - 0x1770 (x 100 ms)

Default

0x64 (10 seconds)

CN (Exit Command mode)

Makes the device exit Command mode, applying changes.

Parameter range

N/A

Default

N/A

AC (Apply Changes)

Immediately applies new settings without exiting Command mode.

Applying changes means that the device is re-initialized based on changes made to its parameter values. Once changes are applied, the device immediately operates according to the new parameter values.

This behavior is in contrast to issuing the **WR** (Write) command. The **WR** command saves parameter values to non-volatile memory, but the device still operates according to previously saved values until the device is rebooted or the **CN** (Exit AT Command Mode) or **AC** commands are issued. For more information, see [AT Command - Queue Parameter Value frame - 0x09 on page 124](#).

Parameter range

N/A

Default

N/A

GT (Guard Times)

Set the required period of silence before and after the command sequence characters of the Command mode sequence (**GT** + **CC** + **GT**). The period of silence prevents inadvertently entering Command mode.

Parameter range

2 - 0xCE4 (x 1 ms)

Default**CC (Command Sequence Character)**

The character value you use to enter Command mode.

The default value (0x2B) is the ASCII code for the plus (+) character. You must enter it three times within the guard time to enter Command mode from Idle mode. To enter Command mode, there is also a required period of silence before and after the command sequence characters of the Command mode sequence (**GT** + **CC** + **GT**). The period of silence prevents inadvertently entering Command mode.

Parameter range

0 - 0xFF

Default

0x2B (+)

Operate in API mode

API mode overview

As an alternative to Transparent operating mode, you can use API operating mode. API mode provides a structured interface where data is communicated through the serial interface in organized packets and in a determined order. This enables you to establish complex communication between devices without having to define your own protocol. The API specifies how commands, command responses and device status messages are sent and received from the device using the serial interface.

We may add new frame types to future versions of firmware, so build the ability to filter out additional API frames with unknown frame types into your software interface.

API frame specifications

The firmware supports two API operating modes: without escaped characters and with escaped characters. Use the AP command to enable either mode. To configure a device to one of these modes, set the following AP parameter values:

1. AP = 0: Transparent operating mode, UART serial line replacement with API modes disabled. This is the default option.
2. AP = 1: API operation.
3. AP = 2: API operation with escaped characters.

The API data frame structure differs depending on what mode you choose.

API operation (AP parameter = 1)

This mode eliminates escaping character sequences. We do not recommend this mode for noisy radio environments and where payload data may include special characters (specifically 0x7E, 0x7D, 0x11, and 0x13). The following table shows the data frame structure when you enable this mode:

Frame fields	Byte	Description
Start Delimiter	1	0x7E
Length	2 - 3	Most Significant Byte, Least Significant Byte
Frame Data	4 - n	API-specific structure
Checksum	n + 1	1 byte

The firmware silently discards any data it receives prior to the start delimiter. If the device does not receive the frame correctly or if the checksum fails, the device discards the frame.

API operation-with escaped characters (AP parameter = 2)

API escaped operating mode works similarly to API mode. The only difference is that when working in API escaped mode, the software must escape any payload bytes that match API frame specific data, such as the start-of-frame byte (0x7E). The following table shows the structure of an API frame with escaped characters:

Frame fields	Byte	Description
Start Delimiter	1	0x7E
Length	2 - 3	Most Significant Byte, Least Significant Byte
Frame Data	4 - n	API-specific structure
Checksum	n + 1	1 byte

Characters escaped if needed

Start delimiter

This field indicates the beginning of a frame. It is always 0x7E. This allows the device to easily detect a new incoming frame.

Length

The length field specifies the total number of bytes included in the frame's data field. Its two-byte value excludes the start delimiter, the length, and the checksum.

Frame data

This field contains the information that a device receives or will transmit. The structure of frame data depends on the purpose of the API frame:

Start delimiter	Length		Frame data								Checksum
			Frame type	Data							
1	2	3	4	5	6	7	8	9	...	n	n+1
0x7E	MSB	LSB	API frame type	Data							Single byte

- **Frame type** is the API frame type identifier. It determines the type of API frame and indicates how the Data field organizes the information.
- **Data** contains the data itself. This information and its order depend on the what type of frame that the Frame type field defines.

Checksum

Checksum is the last byte of the frame and helps test data integrity. It is calculated by taking the hash sum of all the API frame bytes that came before it, excluding the first three bytes (start delimiter and length).

The device does not process frames sent through the serial interface with incorrect checksums, and ignores their data.

Calculate and verify checksums

To calculate the checksum of an API frame:

1. Add all bytes of the packet, excluding the start delimiter 0x7E and the length (the second and third bytes).
2. Keep only the lowest 8 bits from the result.
3. Subtract this quantity from 0xFF.

To verify the checksum of an API frame:

1. Add all bytes including the checksum; do not include the delimiter and length.
2. If the checksum is correct, the last two digits on the far right of the sum will equal 0xFF.

Escaped characters in API frames

If operating in API mode with escaped characters (**AP** parameter = 2), when you send or receive an API frame, you must escape (flag) specific data values so they do not interfere with data frame sequencing. In API operating mode with escaped characters, you must escape the following data bytes:

- 0x7E: start delimiter
- 0x7D: escape character
- 0x11: XON
- 0x13: XOFF

API operating mode with escaped characters guarantees that all the 0x7E bytes a device receives are start delimiters: this character cannot be part of any of the other frame fields (length, data, or checksum) since you must escape it.

To escape a character:

1. Insert 0x7D, the escape character.
2. Append it with the byte you want to escape, XORed with 0x20.

In API operating mode with escaped characters, the length field does not include any escape characters in the frame and the firmware calculates the checksum with non-escaped data.

API frames

The device sends multi-byte values in big-endian format. The XBee/XBee-PRO S2C 802.15.4 RF Module supports API frames in the following table. Request frames are less than 0x80 and responses are always 0x80 or higher.

API frame name	API ID
Modem Status	0x8A
AT Command	0x08
AT Command - Queue Parameter Value	0x09
AT Command Response	0x88
Remote AT Command Request	0x17
Remote AT Command Response	0x97
Transmit (TX) Request: 64-bit address	0x00
Transmit (TX) Request: 16-bit Address	0x01
Transmit (TX) Status	0x89
Receive (RX) Packet: 64-bit address	0x80
Receive (RX) Packet: 16-bit address	0x81
RX Packet: 64-bit Address IO	0x82
RX Packet: 16-bit Address IO	0x83

Modem Status frame - 0x8A

Description

Devices send the status messages in this frame in response to specific conditions.

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	0x8A
Status	4	0x00 Hardware reset 0x01 Watchdog reset 0x02 End device successfully associated with a coordinator 0x03 End device disassociated from coordinator or coordinator failed to form a new network 0x06 Coordinator formed a new network 0x0D Input voltage on the XBee-PRO device is too high, which prevents transmissions

Example

When a device powers up, it returns the following API frame.

Frame data fields	Offset	Example
Start Delimiter	0	0x7E
Length	MSB 1	0x00
	LSB 2	0x02
Frame Type	3	0x8A
Status	4	0x00
Checksum	5	0x75

AT Command frame - 0x08

Description

Use this frame to query or set device parameters on the local device. This API command applies changes after running the command. You can query parameter values by sending the 0x08 AT Command frame with no parameter value field (the two-byte AT command is immediately followed by the frame checksum).

A 0x88 response frame is populated with the parameter value that is currently set on the device. The Frame ID of the 0x88 response is the same one set by the command in the 0x08 frame.

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	
Frame ID	4	Identifies the data frame for the host to correlate with a subsequent ACK (0x88). If set to 0 , the device does not send a response.
AT command	5-6	Command name: two ASCII characters that identify the AT command.
Parameter value	7-n	If present, indicates the requested parameter value to set the given register. If no characters are present, it queries the register.

Example

The following example illustrates an AT Command frame when you modify the device's **DL** parameter value.

Frame data fields	Offset	Example
Start delimiter	0	0x7E

Frame data fields	Offset	Example
Length	MSB 1	0x00
	LSB 2	0x08
Frame type	3	0x08
Frame ID	4	0x4D (M) ¹
AT command	5	0x44 (D)
	6	0x4C (L)
Parameter value	7-10	0x00000FFF
Checksum	11	0x0C

¹M was arbitrarily selected.

AT Command - Queue Parameter Value frame - 0x09

Description

This frame allows you to query or set device parameters. In contrast to the AT Command (0x08) frame, this frame queues new parameter values and does not apply them until you issue either:

- The AT Command (0x08) frame (for API type)
- The **AC** command

When querying parameter values, the 0x09 frame behaves identically to the 0x08 frame. The device returns register queries immediately and does not queue them. The response for this command is also an AT Command Response frame (0x88).

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Note In this example, the parameter could have been sent as a zero-padded 2-byte or 4-byte value.

Frame data fields	Offset	Description
Frame type	3	0x09
Frame ID	4	Identifies the data frame for the host to correlate with a subsequent ACK. If set to 0 , the device does not send a response.
AT command	5-6	Command name: two ASCII characters that identify the AT command.
Parameter value (optional)	7-n	If present, indicates the requested parameter HEX (non-ASCII) value to set the given register. If no characters are present, queries the register.

AT Command Response frame - 0x88

Description

A device sends this frame in response to an AT Command (0x08) frame and a queued AT command 0x09. Some commands send back multiple frames; for example, the **ND** command. This command ends by sending a frame with a status of **0** (OK) and no value. In the particular case of **ND**, a frame is received via a remote node in the network and when the process is finished, the AT command response is received. For details on the behavior of **ND**, see [ND \(Network Discover\) on page 75](#).

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	
Frame ID	4	Identifies the data frame for the host to correlate with a subsequent ACK (0x08 or 0x09). If set to 0 , the device does not send a response.
AT Command	5-6	Command name: two ASCII characters that identify the command.
Command Status	7	0 = OK 1 = ERROR 2 = Invalid command 3 = Invalid parameter
Command data	8-n	The register data in hexadecimal format. If the host sets the register, the device does not return this field.

Example

If you change the **BD** parameter on a local device with a frame ID of 0x01, and the parameter is valid, the user receives the following response.

Frame data fields	Offset	Example
Start delimiter	0	0x7E
Length	MSB 1	0x00
	LSB 2	0x05
Frame type	3	0x88
Frame ID	4	0x01
AT command	5	0x42 (B)
	6	0x44 (D)
Command status	7	0x00
Command data		In this example, if BD was queried instead of being set, its current value would be returned here
Checksum	8	0xF0

Remote AT Command Request frame - 0x17

Description

Used to query or set device parameters on a remote device. For parameter changes on the remote device to take effect, you must apply changes, either by setting the apply changes options bit, or by sending an **AC** command to the remote.

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	
Frame ID	4	Identifies the data frame for the host to correlate with a subsequent ACK (0x97). If set to 0 , the device does not send a response.
64-bit Destination Address	5-12	MSB first, LSB last. Set to the 64-bit address of the destination device. Broadcast = 0x000000000000FFFF. If the 16-bit parameter has a different value from 0xFFFE the 64-bit address is used, otherwise, the 16-bit address is used.
16-bit Destination Address	13-14	Set to match the 16-bit network address of the destination, MSB first, LSB last. Set to 0xFFFE if 64-bit addressing is being used.
Remote Command Options	15	0x02 = Apply changes on remote. If you do not set this, you must send the AC command for changes to take effect. Set all other bits to 0.
AT Command	16-17	Command name: two ASCII characters that identify the command.
Command Parameter	18-n	If present, indicates the parameter value you request for a given register. If no characters are present, it queries the register.

Remote Command Response frame - 0x97

Description

If a device receives this frame in response to a Remote Command Request (0x17) frame, the device sends an AT Command Response (0x97) frame out the serial interface.

Some commands, such as the **ND** command, may send back multiple frames. For details on the behavior of **ND**, see [ND \(Network Discover\) on page 75](#).

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	
Frame ID	4	This is the same value that is passed in to the request. The request is a 0x17 frame.
64-bit source (remote) address	5-12	The address of the remote device returning this response.
16-bit source (remote) address	13-14	Set to the 16-bit network address of the remote device of the remote device returning this response.
AT commands	15-16	The name of the command.
Command status	17	0 = OK 1 = ERROR 2 = Invalid Command 3 = Invalid Parameter 4 = No response
Command data	18-n	The value of the required register in hexadecimal notation (non-ASCII).

TX Request: 64-bit address frame - 0x00

Description

This frame causes the device to send payload data as an RF packet.

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	0x00
Frame ID	4	Identifies the data frame for the host to correlate with a subsequent ACK, which is a 0x89 (Tx status) frame that indicates the packet was transmitted successfully. If set to 0 , the device does not send a response.
64-bit destination address	5-12	MSB first, LSB last. Set to the 64-bit address of the destination device. If set to 0x000000000000FFFF, the broadcast address is used.
Options	13	0x01 = Disable ACK 0x04 = Send packet with Broadcast PAN ID. Set all other bits to 0.
RF data	14-n	The RF data length can be up to 110 bytes, but may be less depending on other factors discussed in Maximum Payload on page 35 .

TX Request: 16-bit address - 0x01

Description

A TX Request message causes the device to transmit data as an RF Packet.

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	0x01
Frame ID	4	Identifies the data frame for the host to correlate with a subsequent ACK (0x89). If set to 0 , the device does not send a response.
16-bit destination address	5-6	MSB first, LSB last. Set to the 16-bit address of the destination device. Broadcast = 0xFFFF.
Options	7	0x01 = Disable ACK. 0x04 = Send packet with Broadcast PAN ID. Set all other bits to 0.
RF data	8-n	The RF data length can be up to 116 bytes, but may be less depending on other factors discussed in Maximum Payload on page 35 .

TX Status frame - 0x89

Description

When a TX request: 64-bit address (0x00) or 16-bit address (0x01) is complete, the device sends a TX Status frame. This message indicates if the packet transmitted successfully or if there was a failure.

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	0x89
Frame ID	4	Identifies the TX Request frame being reported. If the Frame ID = 0 in the TX Request, no AT Command Response is given.
Status	5	0x00 = standard 0x01 = no ACK received 0x02 = CCA failure 0x03 = Transmission was purged because a coordinator tried to send to an end device, but it timed out waiting for a poll from the end device that never occurred 0x21 = Network ACK failure 0x22 = Transmission failed because an end device was not joined to the network 0x31 = Internal error 0x32 = Transmission failed due to resource depletion (for example, out of buffers, especially for indirect messages from coordinator) 0x74 = The payload in the frame was larger than allowed

Notes:

STATUS = 1 occurs when all retries are expired and no ACK is received.

If transmitter broadcasts (destination address = 0x000000000000FFFF), status 0x01 and 0x21 will never be returned.

STATUS = 3 occurs when Coordinator times out of an indirect transmission. Timeout is defined as (2.5 x **SP** (Cyclic Sleep Period) parameter value).

Example

The following example shows a successful status received.

Frame data fields	Offset	Example
Start delimiter	0	0x7E
Length	MSB 1	0x00
	LSB 2	0x03
Frame type	3	0x89
Frame ID	4	0x01
Status	5	0x00
Checksum	6	0x75

RX Packet: 64-bit Address frame - 0x80

Description

When a device receives an RF data packet from a device configured to use 64-bit addressing (**MY** = FFFF or FFFE), it sends this frame out the serial interface.

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	0x80
64-bit source address	4-11	The sender's 64-bit address. Set to 0xFFFFFFFFFFFFFFFF (unknown 64-bit address) if the sender's 64-bit address is unknown. MSB first, LSB last.
RSSI	12	Received Signal Strength Indicator. The Hexadecimal equivalent of (-dBm) value. For example if RX signal strength is -40 dBm, then 0x28 (40 decimal) is returned.
Options	13	Bit field: 0 = [reserved] 1 = Address broadcast 2 = PAN broadcast 3-7 = [reserved]
Received data	14-n	The RF data length can be up to 110 bytes, but may be less depending on other factors discussed in Maximum Payload on page 35 .

Receive Packet: 16-bit address frame - 0x81

Description

When the device receives an RF packet from a device configured to use 16 bit addressing (**MY** < FFFE), it sends this frame out the serial interface.

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Description
Frame type	3	0x81
Source address	4-5	MSB first LSB last
RSSI	6	RSSI = hexadecimal equivalent of -dBm value. For example, if RX signal strength = -40 dBm, it returns 0x28 (40 decimal).
Options	7	Bit 0 = [reserved] Bit 1 = Address broadcast Bit 2 = PAN broadcast Bits 3 - 7 = [reserved]
RF data	8-n	The RF data length can be up to 116 bytes, but may be less depending on other factors discussed in Maximum Payload on page 35 .

RX (Receive) Packet: 64-bit address IO - 0x82

Description

When the device receives an I/O sample from a remote device configured to use 64-bit addressing, the I/O data is sent out the UART using this frame type

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Total number of samples	Description
Frame type	3	N/A	0x82
64-bit source address	4-11	N/A	MSB first, LSB last.
RSSI	12	N/A	RSSI: Hexadecimal equivalent of (-dBm) value. For example, if RX signal strength = -40 dBm, the device returns 0x28 (40 decimal).
Status	13	N/A	bit 0 = reserved bit 1 = Address broadcast bit 2 = PAN broadcast bits 3-7 = [reserved]
Number of samples	14	N/A	Total number of samples.
Channel Indicator (see bit field table below)	15	MSB	Indicates which inputs have sampling enabled (if any). Each bit represents either a DIO line or ADC channel. Bit set to 1 if channel is active
	16	LSB	
Digital Samples (if enabled) (see bit field table below)	17	MSB	If any of the DIO lines are enabled in the Channel indicator, these two bytes contain samples for all enabled DIO lines. DIO lines that do not have sampling enabled return 0. If no DIO line is enabled, no bytes are included in the frame.
	18	LSB	

Frame data fields	Offset	Total number of samples	Description
	19	ADC0 MSB	If the sample set includes any ADC data, each enabled analog input returns a two-byte value indicating the A/D measurement of that input. ADC channel data is represented as an unsigned 10-bit value right-justified on a 16-bit boundary. Analog samples are ordered sequentially from AD0 to AD5.
	20	ADC0 LSB	
	...	N/A	
	n - 1	ADCn mSB	
	n	ADCn LSB	

The following table shows the Channel Indicator and Digital Samples bit fields.

Bit field	Description
Reserved	3 bits
A3 - A0	4 analog bits
D8 - D0	9 digital bits

RX Packet: 16-bit address IO - 0x83

Description

When the device receives an I/O sample from a remote device configured to use 16-bit addressing, the I/O data is sent out the UART using this frame type

Format

The following table provides the contents of the frame. For details on frame structure, see [API frame specifications on page 116](#).

Frame data fields	Offset	Total number of samples	Description
Frame type	3	N/A	0x83
Source Address	4-5	N/A	MSB first, LSB last.
RSSI	6	N/A	RSSI: Hexadecimal equivalent of (-dBm) value. For example, if RX signal strength = -40 dBm, the device returns 0x28 (40 decimal).
Options	7	N/A	bit 0 = reserved bit 1 = Address broadcast bit 2 = PAN broadcast bits 3-7 = [reserved]
Number of samples	8	N/A	Total number of samples.
Channel Indicator (see bit field table below)	9	MSB	Indicates which inputs have sampling enabled (if any). Each bit represents either a DIO line or ADC channel. Bit set to 1 if channel is active.
	10	LSB	

Frame data fields	Offset	Total number of samples	Description
Digital Samples (if enabled) (see bit field table below)	11	MSB	If any of the DIO lines are enabled in the Channel indicator, these two bytes contain samples for all enabled DIO lines. DIO lines that do not have sampling enabled return 0. If no DIO line is enabled, no bytes are included in the frame.
	12	LSB	
Analog samples	13	ADC0 MSB	If the sample set includes any ADC data, each enabled analog input returns a two-byte value indicating the A/D measurement of that input. ADC channel data is represented as an unsigned 10-bit value right-justified on a 16-bit boundary. Analog samples are ordered sequentially from AD0 to AD5.
	14	ADC0 LSB	
	...		
	n - 1	ADCn MSB	
	n	ADCn LSB	

The following table shows the Channel Indicator bit field.

Bit field	Description
Reserved	3 bits
A3 - A0	4 analog bits
D8 - D0	9 digital bits

Certifications

United States (FCC)

The XBee/XBee-PRO S2C 802.15.4 RF Modules comply with Part 15 of the FCC rules and regulations. Compliance with the labeling requirements, FCC notices and antenna usage guidelines is required.

To fulfill FCC Certification, the OEM must comply with the following regulations:

1. The system integrator must ensure that the text on the external label provided with this device is placed on the outside of the final product.
2. RF Modules may only be used with antennas that have been tested and approved for use with the modules; see [FCC-approved antennas \(2.4 GHz\) on page 141](#).

OEM labeling requirements



Warning As an Original Equipment Manufacturer (OEM) you must ensure that FCC labeling requirements are met. You must include a clearly visible label on the outside of the final product enclosure that displays the following content:

Required FCC Label for OEM products containing the XBee S2C SMT RF Module

Contains FCC ID: MCQ-XBS2C

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1.) this device may not cause harmful interference and (2.) this device must accept any interference received, including interference that may cause undesired operation.

Required FCC Label for OEM products containing the XBee-PRO S2C SMT RF Module

Contains FCC ID: MCQ-PS2CSM

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1.) this device may not cause harmful interference and (2.) this device must accept any interference received, including interference that may cause undesired operation.

Required FCC Label for OEM products containing the XBee S2C TH RF Module

Contains FCC ID: MCQ-S2CTH

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1.) this device may not cause harmful interference and (2.) this device must accept any interference received, including interference that may cause undesired operation.

Required FCC Label for OEM products containing the XBee-PRO S2C TH RF Module

Contains FCC ID: MCQ-PS2CTH

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1.) this device may not cause harmful interference and (2.) this device must accept any interference received, including interference that may cause undesired operation.

FCC notices

IMPORTANT: The XBee and XBee-PRO RF Modules have been certified by the FCC for use with other products without any further certification (as per FCC section 2.1091). Modifications not expressly approved by Digi could void the user's authority to operate the equipment.

IMPORTANT: OEMs must test final product to comply with unintentional radiators (FCC section 15.107 & 15.109) before declaring compliance of their final product to Part 15 of the FCC Rules.

IMPORTANT: The RF module has been certified for remote and base radio applications. If the module will be used for portable applications, the device must undergo SAR testing.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation.

If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures: Re-orient or relocate the receiving antenna, Increase the separation between the equipment and receiver, Connect equipment and receiver to outlets on different circuits, or Consult the dealer or an experienced radio/TV technician for help.

FCC-approved antennas (2.4 GHz)

The XBee and XBee-PRO ZB RF Modules can be installed utilizing antennas and cables constructed with non-standard connectors (RPSMA, RPTNC, etc.) An adapter cable may be necessary to attach the XBee connector to the antenna connector.

The modules are FCC approved for fixed base station and mobile applications for the channels indicated in the tables below. If the antenna is mounted at least 25 cm (10 in) from nearby persons, the application is considered a mobile application. Antennas not listed in the table must be tested to comply with FCC Section 15.203 (Unique Antenna Connectors) and Section 15.247 (Emissions).

The antennas in the tables below have been approved for use with this module. Cable loss is required when using gain antennas as shown in the tables. Digi does not carry all of these antenna variants. Contact Digi Sales for available antennas.

XBee S2C SMT RF module

The following table shows the antennas approved for use with the XBee S2C SMT RF module.

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
Integral antennas							
29000313	Integral PCB antenna	0.0	Fixed/Mobile	25 cm	N/A	N/A	N/A
A24-QI	Monopole (Integrated whip)	1.5	Fixed/Mobile	25 cm	N/A	N/A	N/A
Dipole antennas							

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
A24-HASM-450	Dipole (Half-wave articulated RPSMA - 4.5")	2.1	Fixed	25 cm	N/A	N/A	N/A
A24-HABSM	Dipole (Articulated RPSMA)	2.1	Fixed	25 cm	N/A	N/A	N/A
29000095	Dipole (Half-wave articulated RPSMA - 4.5")	2.1	Fixed/Mobile	25 cm	N/A	N/A	N/A
A24-HABUF-P5I	Dipole (Half-wave articulated bulkhead mount U.FL. w/ 5" pigtail)	2.1	Fixed/Mobile	25 cm	N/A	N/A	N/A
A24-HASM-525	Dipole (Half-wave articulated RPSMA - 5.25")	2.1	Fixed	25 cm	N/A	N/A	N/A
Omni-directional antennas							
A24-F2NF	Omni-directional (Fiberglass base station)	2.1	Fixed/Mobile	25 cm	N/A	N/A	N/A
A24-F3NF	Omni-directional (Fiberglass base station)	3.0	Fixed/Mobile	25 cm	N/A	N/A	N/A

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
A24-F5NF	Omni-directional (Fiberglass base station)	5.0	Fixed	25 cm	N/A	N/A	N/A
A24-F8NF	Omni-directional (Fiberglass base station)	8.0	Fixed	2 m	N/A	N/A	0.1
A24-F9NF	Omni-directional (Fiberglass base station)	9.5	Fixed	2 m	N/A	N/A	1.6
A24-F10NF	Omni-directional (Fiberglass base station)	10.0	Fixed	2 m	N/A	N/A	2.1
A24-F12NF	Omni-directional (Fiberglass base station)	12.0	Fixed	2 m	N/A	N/A	4.1
A24-W7NF	Omni-directional (Fiberglass base station)	7.2	Fixed	2 m	N/A	N/A	N/A
A24-M7NF	Omni-directional (Mag-mount base station)	7.2	Fixed	2 m	N/A	N/A	N/A

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
A24-F15NF	Omni-directional (Fiberglass base station)	15.0	Fixed	2 m	1.1	1.1	7.1
Panel antennas							
A24-P8SF	Flat Panel	8.5	Fixed	2 m	N/A	N/A	6.1
A24-P8NF	Flat Panel	8.5	Fixed	2 m	N/A	N/A	6.1
A24-P13NF	Flat Panel	13.0	Fixed	2 m	N/A	3.1	10.6
A24-P14NF	Flat Panel	14.0	Fixed	2 m	N/A	4.1	11.6
A24-P15NF	Flat Panel	15.0	Fixed	2 m	N/A	5.1	12.6
A24-P16NF	Flat Panel	16.0	Fixed	2 m	N/A	6.1	13.6
A24-P19NF	Flat Panel	19.0	Fixed	2 m	1.1	9.1	16.6
Yagi antennas							

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
A24-Y6NF	Yagi (6-element)	8.8	Fixed	2 m	N/A	N/A	3.9
A24-Y7NF	Yagi (7-element)	9.0	Fixed	2 m	N/A	N/A	4.1
A24-Y9NF	Yagi (9-element)	10.0	Fixed	2 m	N/A	N/A	5.1
A24-Y10NF	Yagi (10-element)	11.0	Fixed	2 m	N/A	0.6	6.1
A24-Y12NF	Yagi (12-element)	12.0	Fixed	2 m	N/A	1.6	7.1
A24-Y13NF	Yagi (13-element)	12.0	Fixed	2 m	N/A	1.6	7.1
A24-Y15NF	Yagi (15-element)	12.5	Fixed	2 m	N/A	2.1	7.6
A24-Y16NF	Yagi (16-element)	13.5	Fixed	2 m	N/A	3.1	8.6
A24-Y16RM	Yagi (16-element, RPSMA connector)	13.5 dBi	Fixed	2 m	N/A	3.1	8.6
A24-Y18NF	Yagi (18-element)	15.0	Fixed	2 m	1.1	4.6	10.1

XBee S2C TH RF Module

The following table shows the antennas approved for use with the XBee S2C TH RF Module.

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
Integral antennas							
29000294	Integral PCB antenna	-0.5	Fixed/Mobile	25 cm	N/A	N/A	N/A
A24-QI	Monopole (Integrated whip)	1.5	Fixed/Mobile	25 cm	N/A	N/A	N/A
Dipole antennas							
A24-HASM-450	Dipole (Half-wave articulated RPSMA - 4.5")	2.1	Fixed	25 cm	N/A	N/A	N/A
A24-HABSM	Dipole (Articulated RPSMA)	2.1	Fixed	25 cm	N/A	N/A	N/A
29000095	Dipole (Half-wave articulated RPSMA - 4.5")	2.1	Fixed/Mobile	25 cm	N/A	N/A	N/A
A24-HABUF-P5I	Dipole (Half-wave articulated bulkhead mount U.FL. w/ 5" pigtail)	2.1	Fixed/Mobile	25 cm	N/A	N/A	N/A

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
A24-HASM-525	Dipole (Half-wave articulated RPSMA - 5.25")	2.1	Fixed	25 cm	N/A	N/A	N/A
Omni-directional antennas							
A24-F2NF	Omni-directional (Fiberglass base station)	2.1	Fixed/Mobile	25 cm	N/A	N/A	N/A
A24-F3NF	Omni-directional (Fiberglass base station)	3.0	Fixed/Mobile	25 cm	N/A	N/A	N/A
A24-F5NF	Omni-directional (Fiberglass base station)	5.0	Fixed	25 cm	N/A	N/A	N/A
A24-F8NF	Omni-directional (Fiberglass base station)	8.0	Fixed	2 m	N/A	N/A	N/A
A24-F9NF	Omni-directional (Fiberglass base station)	9.5	Fixed	2 m	N/A	N/A	0.9
A24-F10NF	Omni-directional (Fiberglass base station)	10.0	Fixed	2 m	N/A	N/A	1.4
A24-F12NF	Omni-directional (Fiberglass base station)	12.0	Fixed	2 m	N/A	N/A	3.4
A24-W7NF	Omni-directional (Fiberglass base station)	7.2	Fixed	2 m	N/A	N/A	N/A
A24-M7NF	Omni-directional (Mag-mount base station)	7.2	Fixed	2 m	N/A	N/A	N/A

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
A24-F15NF	Omni-directional (Fiberglass base station)	15.0	Fixed	2 m	0.4	0.4	6.4
Panel antennas							
A24-P8SF	Flat Panel	8.5	Fixed	2 m	N/A	N/A	4.9
A24-P8NF	Flat Panel	8.5	Fixed	2 m	N/A	N/A	4.9
A24-P13NF	Flat Panel	13.0	Fixed	2 m	N/A	3.4	9.4
A24-P14NF	Flat Panel	14.0	Fixed	2 m	N/A	4.4	10.4
A24-P15NF	Flat Panel	15.0	Fixed	2 m	N/A	5.4	11.4
A24-P16NF	Flat Panel	16.0	Fixed	2 m	N/A	6.4	12.4
A24-P19NF	Flat Panel	19.0	Fixed	2 m	0.4	9.4	15.4
Yagi antennas							
A24-Y6NF	Yagi (6-element)	8.8	Fixed	2 m	N/A	N/A	4.7

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB)		
					Channels 11-24	Channel 25	Channel 26
A24-Y7NF	Yagi (7-element)	9.0	Fixed	2 m	N/A	N/A	4.9
A24-Y9NF	Yagi (9-element)	10.0	Fixed	2 m	N/A	0.4	5.9
A24-Y10NF	Yagi (10-element)	11.0	Fixed	2 m	N/A	1.4	6.9
A24-Y12NF	Yagi (12-element)	12.0	Fixed	2 m	N/A	2.4	7.9
A24-Y13NF	Yagi (13-element)	12.0	Fixed	2 m	N/A	2.4	7.9
A24-Y15NF	Yagi (15-element)	12.5	Fixed	2 m	N/A	2.9	8.4
A24-Y16NF	Yagi (16-element)	13.5	Fixed	2 m	N/A	3.9	9.4
A24-Y16RM	Yagi (16-element, RPSMA connector)	13.5	Fixed	2 m	N/A	3.9	9.4
A24-Y18NF	Yagi (18-element)	15.0	Fixed	2 m	0.4	5.4	10.9

XBee-PRO S2C SMT RF Module

The following table shows the antennas approved for use with the XBee-PRO S2C SMT RF Module.

Part Number	Type (Description)	Gain (dBi)	Application*	Min Separation	Required antenna cable loss (dB) Channels 12-23
Internal antennas					
29000313	Integral PCB antenna	0.0	Fixed/Mobile	25 cm	N/A
A24-QI	Monopole (Integrated whip)	1.5	Fixed/Mobile	25 cm	N/A
Dipole antennas					
A24-HASM-450	Dipole (Half-wave articulated RPSMA - 4.5")	2.1	Fixed	25 cm	N/A
A24-HABSM	Dipole (Articulated RPSMA)	2.1	Fixed	25 cm	N/A
29000095	Dipole (Half-wave articulated RPSMA - 4.5")	2.1	Fixed/Mobile	25 cm	N/A
A24-HABUF-P5I	Dipole (Half-wave articulated bulkhead mount U.F.L. w/ 5" pigtail)	2.1	Fixed/Mobile	25 cm	N/A
A24-HASM-525	Dipole (Half-wave articulated RPSMA - 5.25")	2.1	Fixed	25 cm	N/A

Part Number	Type (Description)	Gain (dBi)	Application*	Min Separation	Required antenna cable loss (dB) Channels 12-23
Omni-directional antennas					
A24-F2NF	Omni-directional (Fiberglass base station)	2.1	Fixed/Mobile	25 cm	N/A
A24-F3NF	Omni-directional (Fiberglass base station)	3.0	Fixed/Mobile	25 cm	N/A
A24-F5NF	Omni-directional (Fiberglass base station)	5.0	Fixed	25 cm	N/A
A24-F8NF	Omni-directional (Fiberglass base station)	8.0	Fixed	2 m	N/A
A24-F9NF	Omni-directional (Fiberglass base station)	9.5	Fixed	2 m	N/A
A24-F10NF	Omni-directional (Fiberglass base station)	10	Fixed	2 m	N/A
A24-F12NF	Omni-directional (Fiberglass base station)	12	Fixed	2 m	N/A
A24-W7NF	Omni-directional (Fiberglass base station)	7.2	Fixed	2 m	N/A
A24-M7NF	Omni-directional (Mag-mount base station)	7.2	Fixed	2 m	N/A
A24-F15NF	Omni-directional (Fiberglass base station)	15.0	Fixed	2 m	1.1

Part Number	Type (Description)	Gain (dBi)	Application*	Min Separation	Required antenna cable loss (dB) Channels 12-23
Panel antennas					
A24-P8SF	Flat Panel	8.5	Fixed	2 m	N/A
A24-P8NF	Flat Panel	8.5	Fixed	2 m	N/A
A24-P13NF	Flat Panel	13.0	Fixed	2 m	2.7
A24-P14NF	Flat Panel	14.0	Fixed	2 m	3.7
A24-P15NF	Flat Panel	15.0	Fixed	2 m	4.7
A24-P16NF	Flat Panel	16.0	Fixed	2 m	5.7
A24-P19NF	Flat Panel	19.0	Fixed	2 m	8.7
Yagi antennas					
A24-Y6NF	Yagi (6-element)	8.8	Fixed	2 m	N/A
A24-Y7NF	Yagi (7-element)	9.0	Fixed	2 m	N/A

Part Number	Type (Description)	Gain (dBi)	Application*	Min Separation	Required antenna cable loss (dB) Channels 12-23
A24-Y9NF	Yagi (9-element)	10.0	Fixed	2 m	N/A
A24-Y10NF	Yagi (10-element)	11.0	Fixed	2 m	0.6
A24-Y12NF	Yagi (12-element)	12.0	Fixed	2 m	1.6
A24-Y13NF	Yagi (13-element)	12.0	Fixed	2 m	1.6
A24-Y15NF	Yagi (15-element)	12.5	Fixed	2 m	2.1
A24-Y16NF	Yagi (16-element)	13.5	Fixed	2 m	3.1
A24-Y16RM	Yagi (16-element, RPSMA connector)	13.5	Fixed	2 m	3.1
A24-Y18NF	Yagi (18-element)	15.0	Fixed	2 m	4.6

XBee-PRO S2C TH RF Module

The following table shows the antennas approved for use with the XBee-PRO S2C TH RF Module.

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB) Channels 12-23
Integral antennas					
29000294	Integral PCB antenna	-0.5	Fixed/Mobile	25 cm	N/A
A24-QI	Monopole (Integrated whip)	1.5	Fixed/Mobile	25 cm	N/A
Dipole antennas					
A24-HASM-450	Dipole (Half-wave articulated RPSMA - 4.5")	2.1	Fixed/Mobile	25 cm	N/A
A24-HABSM	Dipole (Articulated RPSMA)	2.1	Fixed	25 cm	N/A
29000095	Dipole (Half-wave articulated RPSMA - 4.5")	2.1	Fixed/Mobile	25 cm	N/A
A24-HABUF-P5I	Dipole (Half-wave articulated bulkhead mount U.F.L. w/ 5" pigtail)	2.1	Fixed	25 cm	N/A
A24-HASM-525	Dipole (Half-wave articulated RPSMA - 5.25")	2.1	Fixed/ Mobile	25 cm	N/A

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB) Channels 12-23
Omni-directional antennas					
A24-F2NF	Omni-directional (Fiberglass base station)	2.1	Fixed/Mobile	25 cm	N/A
A24-F3NF	Omni-directional (Fiberglass base station)	3.0	Fixed/Mobile	25 cm	N/A
A24-F5NF	Omni-directional (Fiberglass base station)	5.0	Fixed	25 cm	N/A
A24-F8NF	Omni-directional (Fiberglass base station)	8.0	Fixed	2 m	N/A
A24-F9NF	Omni-directional (Fiberglass base station)	9.5	Fixed	2 m	N/A
A24-F10NF	Omni-directional (Fiberglass base station)	10.0	Fixed	2 m	N/A
A24-F12NF	Omni-directional (Fiberglass base station)	12.0	Fixed	2 m	N/A
A24-W7NF	Omni-directional (base station)	7.2	Fixed	2 m	N/A
A24-M7NF	Omni-directional (Mag-mount base station)	7.2	Fixed	2 m	N/A
A24-F15NF	Omni-directional (Fiberglass base station)	15.0	Fixed	2 m	0.4

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB) Channels 12-23
Panel antennas					
A24-P8SF	Flat Panel	8.5	Fixed	2 m	N/A
A24-P8NF	Flat Panel	8.5	Fixed	2 m	N/A
A24-P13NF	Flat Panel	13	Fixed	2 m	2.4
A24-P14NF	Flat Panel	14	Fixed	2 m	3.4
A24-P15NF	Flat Panel	15.0	Fixed	2 m	4.4
A24-P16NF	Flat Panel	16.0	Fixed	2 m	5.4
A24-19NF	Flat Panel	19.0	Fixed	2 m	8.4
Yagi antennas					
A24-Y6NF	Yagi (6-element)	8.8	Fixed	2 m	N/A
A24-Y7NF	Yagi (7-element)	9.0	Fixed	2 m	N/A

Part number	Type (description)	Gain (dBi)	Application*	Min. separation	Required antenna cable loss (dB) Channels 12-23
A24-Y9NF	Yagi (9-element)	10.0	Fixed	2 m	N/A
A24-Y10NF	Yagi (10-element)	11.0 dBi	Fixed	2 m	0.4
A24-Y12NF	Yagi (12-element)	12.0	Fixed	2 m	1.4
A24-Y13NF	Yagi (13-element)	12.0	Fixed	2 m	1.4
A24-Y15NF	Yagi (15-element)	12.5	Fixed	2 m	1.9
A24-Y16NF	Yagi (16-element)	13.5	Fixed	2 m	2.9
A24-Y16RM	Yagi (16-element, RPSMA connector)	13.5	Fixed	2 m	2.9
A24-Y18NF	Yagi (18-element)	15.0	Fixed	2 m	4.4

* If using the RF module in a portable application (for example - if the module is used in a handheld device and the antenna is less than 25 cm from the human body when the device is in operation): The integrator is responsible for passing additional SAR (Specific Absorption Rate) testing based on FCC rules 2.1091 and FCC Guidelines for Human Exposure to Radio Frequency Electromagnetic Fields, OET Bulletin and Supplement C. The testing results will be submitted to the FCC for approval prior to selling the integrated unit. The required SAR testing measures emissions from the module and how they affect the person.

RF exposure

If you are an integrating the XBee into another product, you must include the following Caution statement in OEM product manuals to alert users of FCC RF exposure compliance:



Caution To satisfy FCC RF exposure requirements for mobile transmitting devices, a separation distance of 25 cm or more should be maintained between the antenna of this device and persons during device operation. To ensure compliance, operations at closer than this distance are not recommended. The antenna used for this transmitter must not be co-located in conjunction with any other antenna or transmitter.

Europe

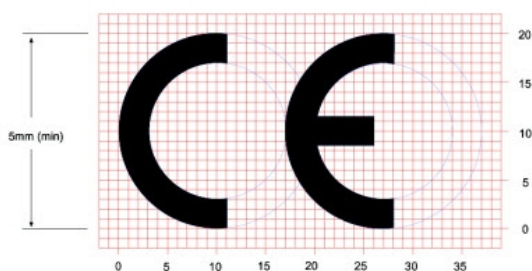
The XBee S2C modules (non-PRO versions only) have been tested for use in several European countries. For a complete list, refer to www.digi.com.

If the modules are incorporated into a product, the manufacturer must ensure compliance of the final product to the European harmonized standards. A Declaration of Conformity must be issued for each of these standards and kept on file as described in Annex II of the R&TTE Directive and other applicable European Directives.

Furthermore, the manufacturer must maintain a copy of the XBee user manual documentation and ensure the final product does not exceed the specified power ratings, antenna specifications, and/or installation requirements as specified in the user manual. If any of these specifications are exceeded in the final product, a submission must be made to a notified body for compliance testing to all required standards.

OEM labeling requirements

The “CE” marking must be affixed to a visible location on the OEM product. The following figure shows CE labeling requirements.



The CE mark shall consist of the initials “CE” taking the following form:

- If the CE marking is reduced or enlarged, the proportions given in the above graduated drawing must be respected.
- The CE marking must have a height of at least 5 mm except where this is not

possible on account of the nature of the apparatus.

- The CE marking must be affixed visibly, legibly, and indelibly.

Listen Before Talk requirement

The XBee/XBee-PRO S2C 802.15.4 RF Module must be configured to comply with the Listen Before Talk (LBT) requirements in the EN 300 328 standard. This can be accomplished by one of the following options:

1. Set the **PL** command to 3 (6 dBm) or lower, which ensures that the maximum transmitter power is under the limit at which LBT is required.
or
2. Set the **CA** command as described in [CA \(CCA Threshold\) on page 88](#) to enable LBT at the required noise threshold level.

Declarations of conformity

Digi has issued Declarations of Conformity for the XBee RF Modules concerning emissions, EMC and safety. Files can be obtained by contacting Digi Support.

Important note

Digi does not list the entire set of standards that must be met for each country. Digi customers assume full responsibility for learning and meeting the required guidelines for each country in their distribution market. Refer to the radio regulatory agency in the desired countries of operation for more information.

Antennas

The following antennas have been tested and approved for use with the XBee S2C RF Module:

- Dipole (2.1 dBi, Omni-directional, Articulated RPSMA, Digi part number A24-HABSM)
- PCB Antenna (0.0 dBi)
- Monopole Whip (1.5 dBi)

Canada (IC)

This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes : (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Labeling requirements

Labeling requirements for Industry Canada are similar to those of the FCC. A clearly visible label on the outside of the final product enclosure must display the following text.

For XBee S2C surface mount

Contains Model XBee S2C Radio, IC: 1846A-XBS2C

The integrator is responsible for its product to comply with IC ICES-003 & FCC Part 15, Sub. B - Unintentional Radiators. ICES-003 is the same as FCC Part 15 Sub. B and Industry Canada accepts FCC test report or CISPR 22 test report for compliance with ICES-003.

For XBee-PRO S2C surface mount

Contains Model PS2CSM Radio, IC: 1846A-PS2CSM

The integrator is responsible for its product to comply with IC ICES-003 & FCC Part 15, Sub. B - Unintentional Radiators. ICES-003 is the same as FCC Part 15 Sub. B and Industry Canada accepts FCC test report or CISPR 22 test report for compliance with ICES-003.

For XBee S2C through hole

Contains Model S2CTH Radio, IC: 1846A-S2CTH

The integrator is responsible for its product to comply with IC ICES-003 & FCC Part 15, Sub. B - Unintentional Radiators. ICES-003 is the same as FCC Part 15 Sub. B and Industry Canada accepts FCC test report or CISPR 22 test report for compliance with ICES-003.

For XBee-PRO S2C through hole

Contains Model PS2CTH Radio, IC: 1846A-PS2CTH

The integrator is responsible for its product to comply with IC ICES-003 & FCC Part 15, Sub. B - Unintentional Radiators. ICES-003 is the same as FCC Part 15 Sub. B and Industry Canada accepts FCC test report or CISPR 22 test report for compliance with ICES-003.

Transmitters for detachable antennas

This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the tables in [FCC-approved antennas \(2.4 GHz\) on page 141](#) with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device. The required antenna impedance is 50 ohms.

Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

Detachable antenna

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication.

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante.

Load 802.15.4 firmware on ZB devices

Background

Our XBee/XBee-PRO ZB RF modules are built on the same hardware as the XBee/XBee-PRO S2C 802.15.4 RF Module. It is possible to load 802.15.4 firmware on existing ZB modules. The table below shows which part numbers are compatible with 802.15.4 firmware.

Note Currently the 802.15.4 firmware is approved for use only in the United States, Canada, and Europe.



Caution The antenna cable loss requirements for the 802.15.4 firmware are different than the ZB firmware for gain antennas exceeding 2.1 dBi. If you migrate a ZB device to 802.15.4 firmware, and are using gain antennas, you must adhere to the cable loss requirements found in [Certifications on page 139](#).

XBee/XBee-PRO ZB S2C part numbers	Revision	Form factor	Hardware version (HV)
XB24CZ7PIS-004 XB24CZ7RIS-004 XB24CZ7UIS-004	All	XBee SMT	0x22
XB24CZ7PIT-004 XB24CZ7SIT-004 XB24CZ7UIT-004 XB24CZ7WIT-004	All	XBee TH	0x2E
XBP24CZ7PIS-004 XBP24CZ7RIS-004 XBP24CZ7UIS-004	Rev L (and later)	XBee SMT	0x30

XBee/XBee-PRO ZB S2C part numbers	Revision	Form factor	Hardware version (HV)
XBP24CZ7PIT-004 XBP24CZ7SIT-004 XBP24CZ7UIT-004 XBP24CZ7WIT-004	All	XBee TH	0x2D

In addition to the differences between the 802.15.4 and ZigBee protocols, some of the operational features are different between the two firmware versions. For example, the XBee-PRO 802.15.4 supports fewer channels than the ZigBee firmware. It is important that you read and understand this user guide before developing with the 802.15.4 firmware.

Load 802.15.4 firmware

To load 802.15.4 firmware on an existing ZB module, use the following instructions. You must use the serial interface to perform this update. The device does not support OTA updates for changing 802.15.4 to ZB firmware or vice versa.

1. Verify that your device's part number (listed on the label) is included in the list shown in [Background on page 162](#).
2. Install the device in a Digi development board and connect it to your PC.
3. The next steps involve loading firmware using XCTU. To download XCTU and read detailed instructions about it, go to:
<http://www.digi.com/products/xbee-rf-solutions/xctu-software/xctu>
4. When you get to the **Update firmware** dialog box, in the **Function set** area, click the **802.15.4** option, and the newest firmware version.
5. Click **Update** and follow the instructions.
6. When the updating process successfully completes, your device runs 802.15.4 firmware. You can change back to ZigBee firmware at any time by following the same process and selecting the ZigBee firmware option instead.

Migrate from XBee through-hole to surface-mount devices

We design the XBee surface mount and through-hole devices to be compatible with each other and offer the same basic feature set. The surface mount form factor has more I/O pins. Because the XBee device was originally offered in only the through-hole form factor, we offer this section to help you migrate from the through-hole to the surface-mount form factor.

Pin mapping

The following table shows the pin mapping for the surface-mount (SMT) pins to the through-hole (TH) pins. The pin names are from the XBee S2C SMT device.

SMT Pin #	Name	TH Pin #
1	GND	
2	VCC	1
3	DOUT	2
4	DIN/ $\overline{\text{CONFIG}}$	3
5	[Reserved]	4
6	$\overline{\text{RESET}}$	5
7	PWM0/RSSI PWM	6
8	PWM1	7
9	[Reserved]	8

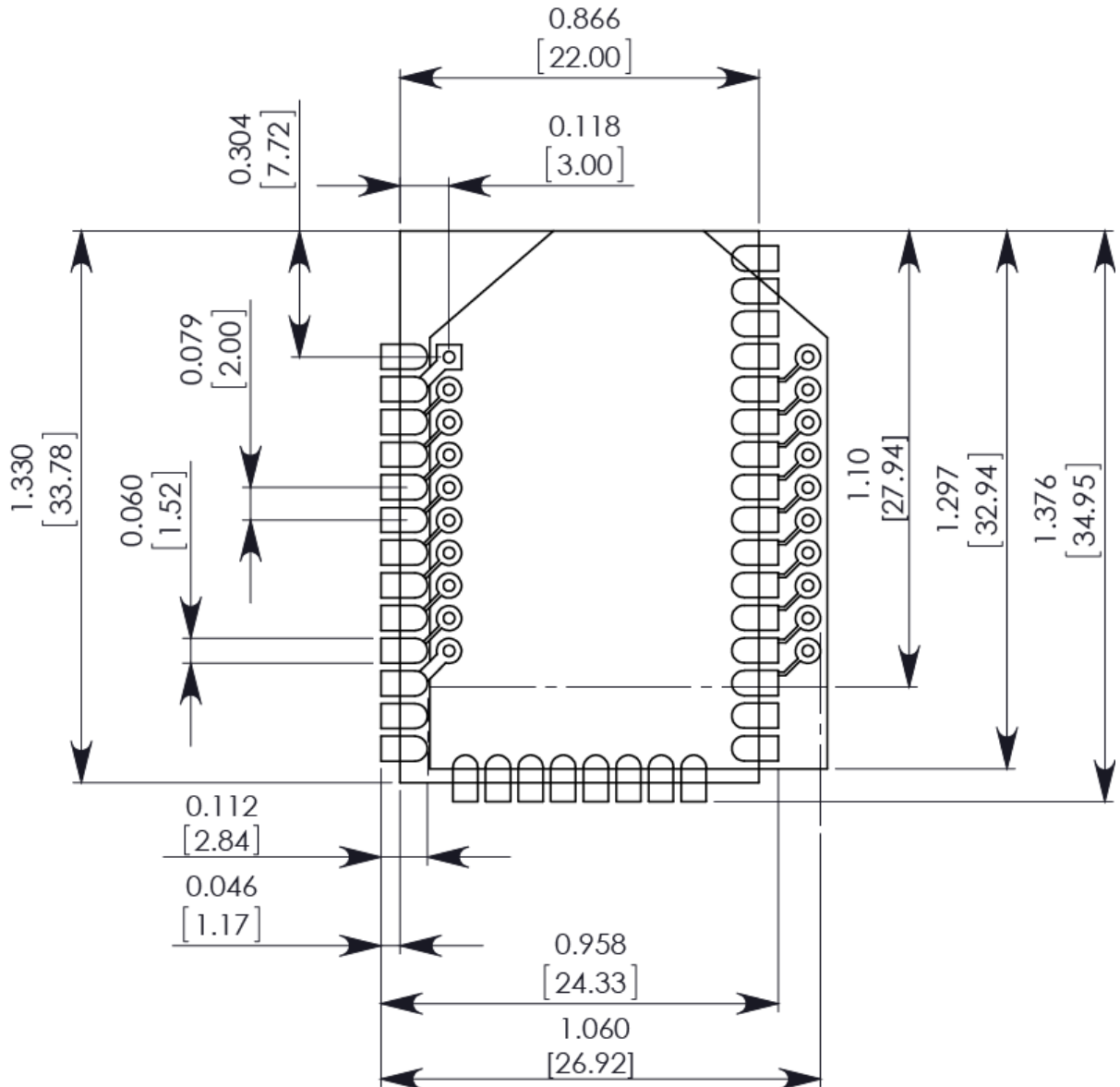
SMT Pin #	Name	TH Pin #
10	DI8/SLEEP_RQ/ $\overline{\text{DTR}}$	9
11	GND	10
12	SPI_ $\overline{\text{ATTN}}$ / $\overline{\text{BOOTMODE}}$	
13	GND	
14	SPI_CLK	
15	SPI_ $\overline{\text{SSEL}}$	
16	SPI_MOSI	
17	SPI_MISO	
18	[Reserved]	
19	[Reserved]	
20	[Reserved]	
21	[Reserved]	
22	GND	
23	[Reserved]	
24	DIO4	11
25	DIO7/ $\overline{\text{CTS}}$	12
26	On/ $\overline{\text{SLEEP}}$	13
27	V _{REF}	14
28	DIO5/ASSOC	15

SMT Pin #	Name	TH Pin #
29	DIO6/ $\overline{\text{RTS}}$	16
30	DIO3/AD3	17
31	DIO2/AD2	18
32	DIO1/AD1	19
33	DIO0/AD0	20
34	[Reserved]	
35	GND	
36	RF	
37	[Reserved]	

Mount the devices

One important difference between the SMT and TH devices is the way they mount to a printed circuit board (PCB). Each footprint requires different mounting techniques.

We designed a footprint that allows you to attach either device to a PCB. The following drawing shows the layout.



The round holes in the diagram are for the TH design, and the semi-oval pads are for the SMT design. Pin 1 of the TH design is lined up with pad 1 of the SMT design, but the pins are actually offset by one pad; see [Pin mapping on page 164](#). By using diagonal traces to connect the appropriate pins, the layout will work for both devices.

[PCB design and manufacturing on page 168](#) contains information on attaching the SMT device.

PCB design and manufacturing

The XBee/XBee-PRO S2C 802.15.4 RF Module is designed for surface mount on the OEM PCB. It has castellated pads to allow for easy solder attach inspection. The pads are all located on the edge of the module, so there are no hidden solder joints on these modules.

Recommended solder reflow cycle

The following table provides the recommended solder reflow cycle. The table shows the temperature setting and the time to reach the temperature; It does not show the cooling cycle.

Time (seconds)	Temperature (degrees C)
30	65
60	100
90	135
120	160
150	195
180	240
210	260

The maximum temperature should not exceed 260°C.

The device will reflow during this cycle, and therefore must not be reflowed upside down. Take care not to jar the device while the solder is molten, as this can remove components under the shield from their required locations.

Hand soldering is possible and should be performed in accordance with approved standards.

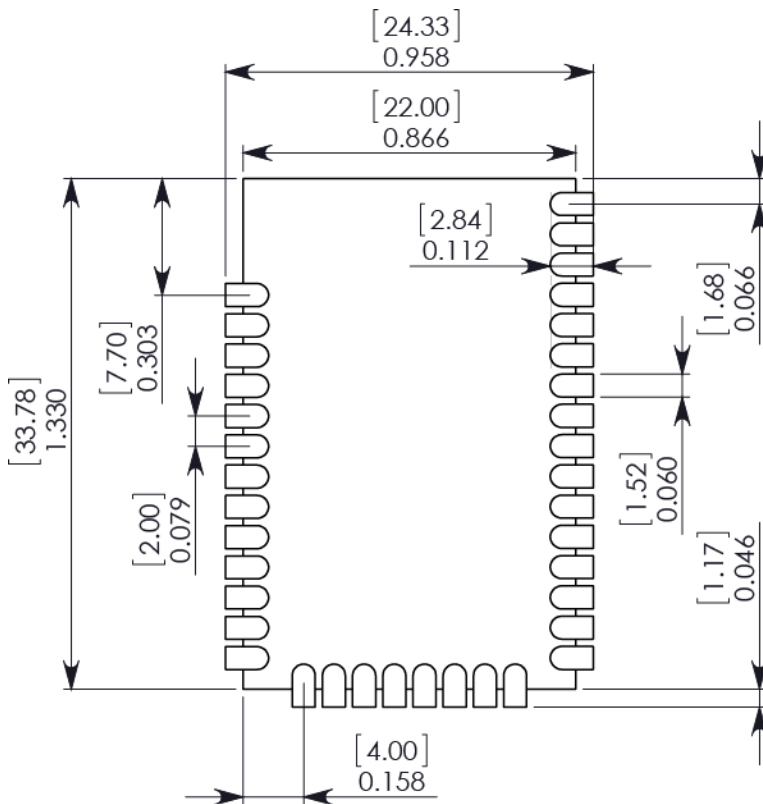
The device has a Moisture Sensitivity Level (MSL) of 3. When using this product, consider the relative requirements in accordance with standard IPC/JEDEC J-STD-020.

In addition, note the following conditions:

- a. Calculated shelf life in sealed bag: 12 months at < 40°C and < 90% relative humidity (RH).
- b. Environmental condition during the production: 30°C /60% RH according to IPC/JEDEC J-STD-033C, paragraphs 5 through 7.
- c. The time between the opening of the sealed bag and the start of the reflow process cannot exceed 168 hours if condition b) is met.
- d. Baking is required if conditions b) or c) are not met.
- e. Baking is required if the humidity indicator inside the bag indicates a RH of 10% more.
- f. If baking is required, bake modules in trays stacked no more than 10 high for 4-6 hours at 125°C.

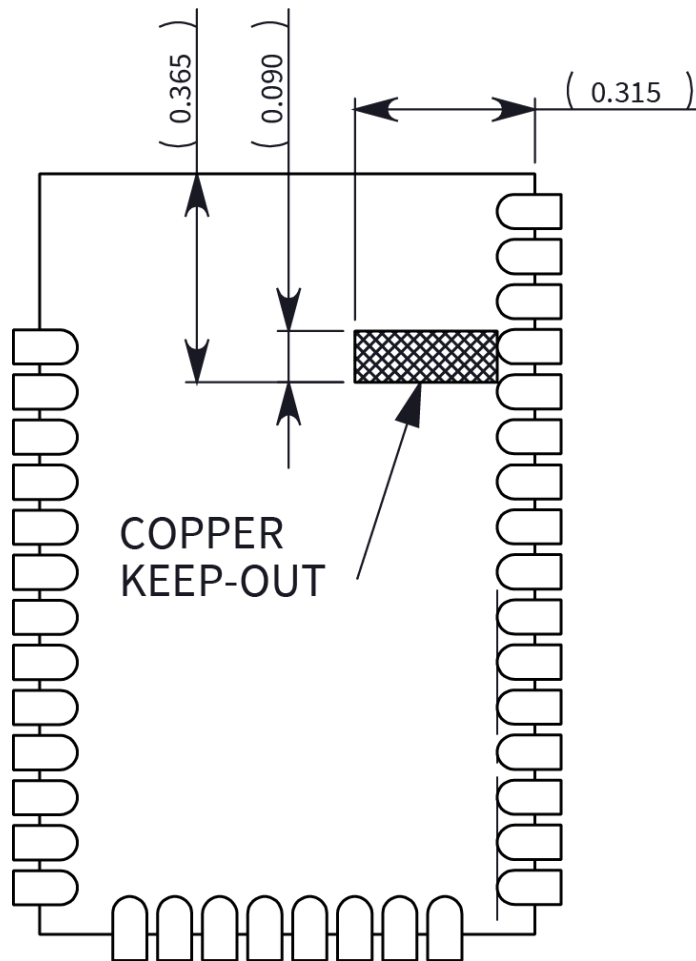
Recommended footprint and keepout

We recommend that you use the following PCB footprint for surface mounting.



Match the solder footprint to the copper pads, but you may need to adjust it depending on the specific needs of assembly and product standards. We recommend a stencil thickness of 0.15 mm (0.005 in). Place the component last and set the placement speed to the slowest setting.

While the underside of the module is mostly coated with solder resist, we recommend that the copper layer directly below the module be left open to avoid unintended contacts. Copper or vias must not interfere with the three exposed RF test points on the bottom of the module (see below). Furthermore, these modules have a ground plane in the middle on the back side for shielding purposes, which can be affected by copper traces directly below the module.



Flux and cleaning

We recommend that you use a “no clean” solder paste in assembling these devices. This eliminates the clean step and ensures that you do not leave unwanted residual flux under the device where it is difficult to remove. In addition:

- Cleaning with liquids can result in liquid remaining under the device or in the gap between the device and the host PCB. This can lead to unintended connections between pads.

- The residual moisture and flux residue under the device are not easily seen during an inspection process.

Rework

Caution Any modification to the device voids the warranty coverage and certifications.



Rework should never be performed on the module itself. The module has been optimized to give the best possible performance, and reworking the module itself will void warranty coverage and certifications. We recognize that some customers will choose to rework and void the warranty; the following information is given as a guideline in such cases to increase the chances of success during rework, though the warranty is still voided.

The module may be removed from the OEM PCB by the use of a hot air rework station, or hot plate. Care should be taken not to overheat the module. During rework, the module temperature may rise above its internal solder melting point and care should be taken not to dislodge internal components from their intended positions.