Accredited testing laboratory

DAR registration number: TTI-P-G 081/94-D0

Federal Motor Transport Authority (KBA)
DAR registration number: KBA-P 00070-97

Test report no.	**: 2-3577-01-10/04-B**
Type identification	**: VAS5053**
Test specification	**: IEEE P1528/D1.2**
FCC-ID	**: LYHVAS5053**
IC	**: 267AAVAS5053**

Table of Contents

1 General Information

1.1 Notes

The test results of this test report relate exclusively to the test item specified in 1.5. The CETECOM ICT Services GmbH does not assume responsibility for any conclusions and generalisations drawn from the test results with regard to other specimens or samples of the type of the equipment represented by the test item. The test report may only be reproduced or published in full. Reproduction or publication of extracts from the report requires the prior written approval of the CETECOM ICT Services GmbH.

1.1.1 Statement of Compliance

The SAR values found for the VAS5053 **Car Diagnostic System with Bluetooth Interface** are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1 g tissue according to the FCC rule §2.1093, the ANSI/IEEE C 95.1:1992, the NCRP Report Number 86 for uncontrolled environment, according to the Health Canada's Safety Code 6 and the Industry Canada Radio Standards Specification RSS-102 for General Population/Uncontrolled exposure.
The measurement together with the test system set-up is described in chapter 2.3 of this test report. A detailed description of the equipment under test can be found in chapter 1.5.

Test laboratory manager:

2004-06-23	**Thomas Vogler**	Thomas Vogler
Date	Name	Signature

Technical responsibility for area of testing:

2004-06-23	**Bernd Rebmann**	B. Rebmann
Date	Name	Signature

1.2 Testing laboratory

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State of accreditation: The Test laboratory (area of testing) is accredited according to DIN EN ISO/IEC 17025. DAR registration number: TTI-P-G 081/94-D0

Test location, if different from CETECOM ICT Services GmbH

Name:
Street:
Town:
Country:
Phone:
Fax:

1.3 Details of applicant

Name:	Siemens AG
Street:	Östliche Rheinbrückenstr. 50
Town:	76181 Karlsruhe
Country:	Germany
Contact:	Thomas Findeisen
Telephone:	+49 (0) 721 595 45 18

1.4 Application details

Date of receipt of application:	2004-04-29
Date of receipt of test item:	2004-06-14
Start/Date of test:	2004-06-17
End of test:	
Person(s) present during the test:	Mr. Findeisen Mr. Mahlig Mr. Schevchenko

1.5 Test item

Description of the test item:	Car Diagnostic System with Bluetooth Interface
Type identification:	VAS5053
FCC-ID:	LYHVAS5053
Serial number:	A5E00262440
Manufacturer:	
Name:	Siemens Production Automatisation S.A.S.
Street:	1, Chemin de la Sandlach – B.P. 189
Town:	67506 Haguenau Cedex
Country:	France
additional information on the DUT:	
device category :	portable device (handheld device)
test device production information :	production unit
exposure category:	uncontrolled environment / general population
device operating configurations :	
operating mode(s)	Bluetooth FHSS with DH 5 packets
operating frequency range	2402 MHz (channel 1)-2480 MHz (channel 78)
measured peak output power (conducted):	
accessories / body-worn configurations :	-----
auxiliary equipment:	Laptop computer for setting up test modes

1.6 Test specification(s)

Supplement C (Edition 01-01) to OET Bulletin 65 (Edition 97-01)

IEEE P1528/D1.2 (April 21, 2003)

RSS-102: Evaluation Procedure for Mobile and Portable Radio Transmitters with respect to Health (Issue 1 (Provisional) of September 25, 1999)

Canada's Safety Code 6: Limits of Human Exposure to Radiofrequency Electromagnetic Fields in the Frequency Range from 3 kHz to 300 GHz (99-EHD-237)

IEEE Std C95.3 – 1991, IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic Fields – RF and Microwave.

1.6.1 RF exposure limits

Human Exposure	Uncontrolled Environment General Population	Controlled Environment Occupational
Spatial Peak SAR* (Brain)	**1.60 mW/g**	8.00 mW/g
Spatial Average SAR** (Whole Body)	0.08 mW/g	0.40 mW/g
Spatial Peak SAR*** (Hands/Feet/Ankle/Wrist)	4.00 mW/g	20.00 mW/g

Table 1: RF exposure limits

The limit applied in this test report is shown in **bold** letters

Notes:

* The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time

** The Spatial Average value of the SAR averaged over the whole body.

*** The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

2 Technical test

2.1 Summary of test results

No deviations from the technical specification(s) were ascertained in the course of the tests performed.	☒
The deviations as specified in 2.5 were ascertained in the course of the tests performed.	☐

2.2 Test environment

General Environment conditions in the test area are as follows :

Ambient temperature: 20°C – 24°C
Tissue simulating liquid: 20°C – 24°C
Humidity: 40% – 50%

Exact temperature values for each test are shown in the table(s) under 2.5. and/or on the measurement plots.

2.3 Measurement and test set-up

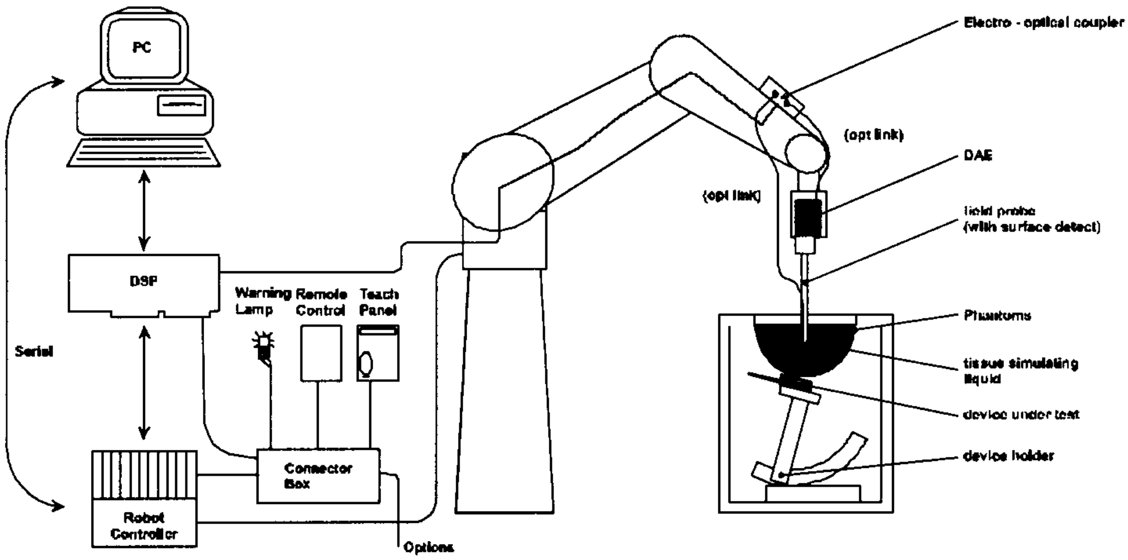
The measurement system is described in chapter 2.4.

The test setup for the system validation can be found in chapter 2.4.14.

A description of positioning and test signal control can be found in chapter 2.5 together with the test results.

2.4 Measurement system

2.4.1 System Description



The DASY4 system for performing compliance tests consists of the following items:

?? A standard high precision 6-axis robot (Stäubli RX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).

?? A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.

?? A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
?? A unit to operate the optical surface detector which is connected to the EOC.
?? The Electro-Optical Coupler (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY4 measurement server.
?? The DASY4 measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows 2000
?? DASY4 software and SEMCAD data evaluation software.
?? Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.
?? The generic twin phantom enabling the testing of left-hand and right-hand usage.
?? The device holder for handheld mobile phones.
?? Tissue simulating liquid mixed according to the given recipes.
?? System validation dipoles allowing to validate the proper functioning of the system.

2.4.2 Test environment

The DASY4 measurement system is placed at the head end of a room with dimensions :
5 x 2.5 x 3 m³, the SAM phantom is placed in a distance of 75 cm from the side walls and 1.1m from the rear wall. Above the test system a 1.5 x 1.5 m² array of pyramid absorbers is installed to reduce reflections from the ceiling.
Picture 1 of the photo documentation shows a complete view of the the test environment.
The system allows the measurement of SAR values larger than 0.005 mW/g.

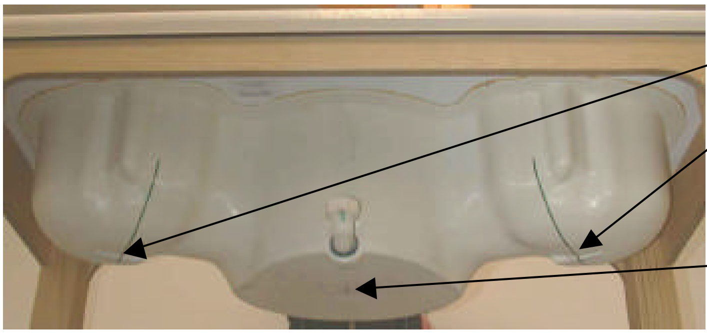
2.4.3 Probe description

Isotropic E-Field Probe ET3DV6 for Dosimetric Measurements

Technical data according to manufacturer information	
Construction	Symmetrical design with triangular core Built-in optical fiber for surface detection system Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycolether)
Calibration	In air from 10 MHz to 2.5 GHz In head tissue simulating liquid (HSL) at 900 (800-1000) MHz and 1.8 GHz (1700-1910 MHz) (accuracy ± 9.5%; k=2) Calibration for other liquids and frequencies upon request
Frequency	10 MHz to 3 GHz (dosimetry); Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity	± 0.2 dB in HSL (rotation around probe axis) ± 0.4 dB in HSL (rotation normal to probe axis)
Dynamic range	5 µW/g to > 100 mW/g; Linearity: ± 0.2 dB
Optical Surface Detection	± 0.2 mm repeatability in air and clear liquids over diffuse reflecting surfaces (ET3DV6 only)
Dimensions	Overall length: 330 mm Tip length: 16 mm Body diameter: 12 mm Tip diameter: 6.8 mm Distance from probe tip to dipole centers: 2.7 mm
Application	General dosimetry up to 3 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms (ET3DV6)

2.4.4 Phantom description

The used SAM Phantom meets the requirements specified in Edition 01-01 of Supplement C to OET Bulletin 65 for Specific Absorption Rate (SAR) measurements.
The phantom consists of a fibreglass shell integrated in a wooden table. It allows left-hand and right-hand head as well as body-worn measurements with a maximum liquid depth of 18 mm in head position and 22 mm in planar position (body measurements). The thickness of the Phantom shell is 2 mm +/- 0.1 mm.



2.4.5 Device holder description

The DASY4 device holder has two scales for device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The plane between the ear openings and the mouth tip has a rotation angle of 65°. The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. This device holder is used for standard mobile phones or PDA's only. If necessary an additional support of polystyrene material is used.

Larger DUT's (e.g. notebooks) cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values .
Therefore those devices are normally only tested at the flat part of the SAM.

2.4.6 Scanning procedure

The DASY4 installation includes predefined files with recommended procedures for measurements and validation. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.

?? The „reference“ and „drift“ measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT’s output power and should vary max. +/- 5 %.

?? The „surface check“ measurement tests the optical surface detection system of the DASY4 system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above ± 0.1mm). To prevent wrong results tests are only executed when the liquid is free of air bubbles. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within ± 30°.)

?? The „area scan“ measures the SAR above the DUT or verification dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The robot performs a stepped movement along one grid axis while the local electrical field strenth is measured by the probe. The probe is touching the surface of the SAM during acquisition of measurement values. The standard scan uses large grid spacing for faster measurement. Standard grid spacing for head measurements is 15 mm in x- and y- dimension. If a finer resolution is needed, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result. For special applications where the standard scan method does not find the peak SAR within the grid, e.g. mobile phones with flip cover, the grid can be adapted in orientation.
Results of this coarse scan are shown in annex 2.

?? A „7x7x7 zoom scan” measures the field in a volume around the 2D peak SAR value acquired in the previous „coarse“ scan. This is a fine 7x7 grid where the robot additionally moves the probe in 7 steps along the z-axis away from the bottom of the Phantom. Grid spacing for the cube measurement is 5 mm in x and y-direction and 5 mm in z-direction. DASY4 is also able to perform repeated zoom scans if more than 1 peak is found during area scan. In this document, the evaluated peak 1g and 10g averaged SAR values are shown in the 2D-graphics in annex 2. Test results relevant for the specified standard (see chapter 1.6.) are shown in table form in chapter 2.5.

?? A Z-axis scan measures the total SAR value at the x-and y-position of the maximum SAR value found during the cube 7x7x7 scan. The probe is moved away in z-direction from the bottom of the SAM phantom in 2mm steps. This measurement shows the continuity of the liquid and can - depending in the field strength – also show the liquid depth. A z-axis scan of the measurement with maximum SAR value is shown in annex 2.

2.4.7 Spatial Peak SAR Evaluation

The spatial peak SAR - value for 1 and 10 g is evaluated after the Cube measurements have been done. The basis of the evaluation are the SAR values measured at the points of the fine cube grid consisting of 7 x 7 x 7 points. The algorithm that finds the maximal averaged volume is separated into three different stages.

?? The data between the dipole center of the probe and the surface of the phantom are extrapolated. This data cannot be measured since the center of the dipole is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is about 1 mm (see probe calibration sheet). The extrapolated data from a cube measurement can be visualized by selecting 'Graph Evaluated'.

?? The maximum interpolated value is searched with a straight-forward algorithm. Around this maximum the SAR - values averaged over the spatial volumes (1g or 10 g) are computed using the 3d-spline interpolation algorithm. If the volume cannot be evaluated (i.e., if a part of the grid was cut off by the boundary of the measurement area) the evaluation will be started on the corners of the bottom plane of the cube.

?? All neighboring volumes are evaluated until no neighboring volume with a higher average value is found.

Extrapolation

The extrapolation is based on a least square algorithm [W. Gander, Computermathematik, p.168-180]. Through the points in the first 3 cm along the z-axis, polynomials of order four are calculated. These polynomials are then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from each other.

Interpolation

The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a knot"-condition [W. Gander, Computermathematik, p.141-150] (x, y and z -direction) [Numerical Recipes in C, Second Edition, p.123ff].

Volume Averaging

At First the size of the cube is calculated. Then the volume is integrated with the trapezoidal algorithm. 8000 points (20x20x20) are interpolated to calculate the average.

Advanced Extrapolation

DASY4 uses the advanced extrapolation option which is able to compansate boundary effects on E-field probes.

2.4.8 Data Storage and Evaluation

Data Storage

The DASY4 software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension ".DA4". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation by SEMCAD

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	$Norm_i$, a_{i0}, a_{i1}, a_{i2}
	- Conversion factor	$ConvF_i$
	- Diode compression point	Dcpi
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	?
	- Density	?

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY4 components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics.

If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 ? \; cf/dcp_i$$

with	V_i	= compensated signal of channel i	(i = x, y, z)
	U_i	= input signal of channel i	(i = x, y, z)
	cf	= crest factor of exciting field	(DASY parameter)
	dcp_i	= diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: $$E_i = (V_i \,/\, Norm_i \; ? \; ConvF)^{1/2}$$

H-field probes: $$H_i = (V_i)^{1/2} \; ? \; (a_{i0} + a_{i1}f + a_{i2}f^2)/f$$

?

with	V_i	= compensated signal of channel i	(i = x, y, z)
	$Norm_i$	= sensor sensitivity of channel i [mV/(V/m)^2] for E-field Probes	(i = x, y, z)
	ConvF	= sensitivity enhancement in solution	
	a_{ij}	= sensor sensitivity factors for H-field probes	
	f	= carrier frequency [GHz]	
	E_i	= electric field strength of channel i in V/m	
	H_i	= magnetic field strength of channel i in A/m	

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = (E_x^{\,2} + E_Y^{\,2} + E_z^{\,2})^{1/2}$$

The primary field data are used to calculate the derived field units.

$$SAR = (E_{tot}^{\,2} \; ? \; ?) \,/\, (? \; ? \; 1000)$$

?

with	SAR	= local specific absorption rate in mW/g
	E_{tot}	= total field strength in V/m
	?	= conductivity in [mho/m] or [Siemens/m]
	?	= equivalent tissue density in g/cm^3

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = E_{tot}^{\,2} \,/\, 3770 \qquad \text{or} \qquad P_{pwe} = H_{tot}^{\,2} \; ? \; 37.7$$

with	P_{pwe}	= equivalent power density of a plane wave in mW/cm^2
	E_{tot}	= total electric field strength in V/m
	H_{tot}	= total magnetic field strength in A/m

2.4.9 Test equipment utilized

This table gives a complete overview of the SAR measurement equipment

Devices used during the test described in chapter 2.5. are marked ☒

	Manufacturer	Device	Type	Serial number	Date of last calibration)*
☒	Schmid & Partner Engineering AG	Dosimetric E-Field Probe	ET3DV6	1558	June 3, 2004
☐	Schmid & Partner Engineering AG	Dosimetric E-Field Probe	ET3DV6	1559	April 16, 2003
☐	Schmid & Partner Engineering AG	900 MHz System Validation Dipole	D900V2	102	February 7, 2003
☐	Schmid & Partner Engineering AG	1800 MHz System Validation Dipole	D1800V2	287	February 7, 2003
☐	Schmid & Partner Engineering AG	1900 MHz System Validation Dipole	D1900V2	5d009	September 24, 2002
☒	Schmid & Partner Engineering AG	2450 MHz System Validation Dipole	D2450V2	710	September 25, 2002
☒	Schmid & Partner Engineering AG	Data acquisition electronics	DAE3V1	413	February 3, 2003
☒	Schmid & Partner Engineering AG	Software	DASY 4 V4.1b	---	N/A
☒	Schmid & Partner Engineering AG	Phantom	SAM	---	N/A
☒	Rohde & Schwarz	Universal Radio Communication Tester	CMU 200	U-972406/000	September 18, 2003
☐	Agilent	Network Analyser 300 kHz to 3 GHz	8753C	2936A00872	February 11, 2003
☐	Agilent	Dielectric Probe Kit	85070C	US99360146	N/A
☒	Agilent	Peak Power Analyzer	8990A	3128A00169	August 14, 2003
☒	Agilent	Peak Power Sensor	84813A	3125A00111	September 18, 2003
☒	Rohde & Schwarz	Signal Generator	SMPD	882.362/009	December 15, 2002
☒	Amplifier Reasearch	Amplifier	25S1G4 (25 Watt)	20452	N/A
☒	Agilent	Power Meter	438A	2804U01006	February 9, 2004
☒	Agilent	Power Meter Sensor	8482A	2703A03025	February 9, 2004

)* : Measurement devices are in a 1-year calibration cycle, validation dipoles are in a 2-year calibration cycle

2.4.10 Tissue simulating liquids : dielectric properties

The following materials are used for producing the tissue-equivalent materials

(liquids used for tests described in chapter 2.5. are marked with ☒) :

Ingredients (% of weight)	**Frequency (MHz)**					
frequency band	☐ 450	☐ 835	☐ 900	☐ 1800	☐ 1900	☐ 2450
Tissue Type	Head	Head	Head	Head	Head	Head
Water	38.56	41.45	41.05	52.64	52.64	62.7
Salt (NaCl)	3.95	1.45	1.35	0.36	0.36	0.5
Sugar	56.32	56.0	56.5	0.0	0.0	0.0
HEC	0.98	1.0	1.0	0.0	0.0	0.0
Bactericide	0.19	0.1	0.1	0.0	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	36.8
DGBE	0.0	0.0	0.0	47.0	47.0	0.0

Table 2: Head tissue dielectric properties

Ingredients (% of weight)	**Frequency (MHz)**					
frequency band	☐ 450	☐ 835	☐ 900	☐ 1800	☐ 1900	☒ 2450
Tissue Type	Body	Body	Body	Body	Body	Body
Water	51.16	52.4	56.0	69.91	69.91	73.2
Salt (NaCl)	1.49	1.40	0.76	0.13	0.13	0.04
Sugar	46.78	45.0	41.76	0.0	0.0	0.0
HEC	0.52	1.0	1.21	0.0	0.0	0.0
Bactericide	0.05	0.1	0.27	0.0	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0
DGBE	0.0	0.0	0.0	29.96	29.96	26.7

Table 3: Body tissue dielectric properties

Salt: 99+% Pure Sodium Chloride
Sugar: 98+% Pure Sucrose
Water: De-ionized, 16M? + resistivity
HEC: Hydroxyethyl Cellulose
DGBE: 99+% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]
Triton X-100(ultra pure): Polyethylene glycol mono [4-(1,1,3,3-tetramethylbutyl)phenyl]ether

2.4.11 Tissue simulating liquids : parameters

Used Target Frequency	Target Body Tissue		Measured Body Tissue		Measured Date
[MHz]	Permittivity	Conductivity [S/m]	Permittivity	Conductivity [S/m]	
2450	52.7	1.95	53.5	2.00	2004-06-17

Table 4: Parameter of the body tissue simulating liquid

Note: The dielectric properties have been measured using the contact probe method at 22.1°C.

2.4.12 Measurement uncertainty evaluation for SAR test

The overall combined measurement uncertainty of the measurement system is ± 10,3% (K=1).
The expanded uncertainty(k=2) is assessed to be ± 20.6%
This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

Error Sources	Uncertainty Value	Probability Distribution	Divi-sor	c_i 1g	c_i 10g	Standard Uncertainty 1g	Standard Uncertainty 10g	v_i^2 or v_{eff}
Measurement System								
Probe calibration	± 4.8%	Normal	1	1	1	± 4.8%	± 4.8%	8
Axial isotropy	± 4.7%	Rectangular	v3	0.7	0.7	± 1.9%	± 1.9%	8
Hemispherical isotropy	± 9.6%	Rectangular	v3	0.7	0.7	± 3.9%	± 3.9%	8
Spatial resolution	± 0.0%	Rectangular	v3	1	1	± 0.0%	± 0.0%	8
Boundary effects	± 1.0%	Rectangular	v3	1	1	± 0.6%	± 0.6%	8
Probe linearity	± 4.7%	Rectangular	v3	1	1	± 2.7%	± 2.7%	8
System detection limits	± 1.0%	Rectangular	v3	1	1	± 0.6%	± 0.6%	8
Readout electronics	± 1.0%	Normal	1	1	1	± 1.0%	± 1.0%	8
Response time	± 0.8%	Rectangular	v3	1	1	± 0.5%	± 0.5%	8
Integration time	± 2.6%	Rectangular	v3	1	1	± 1.5%	± 1.5%	8
RF ambient conditions	± 3.0%	Rectangular	v3	1	1	± 1.7%	± 1.7%	8
Probe positioner	± 0.4%	Rectangular	v3	1	1	± 0.2%	± 0.2%	8
Probe positioning	± 2.9%	Rectangular	v3	1	1	± 1.7%	± 1.7%	8
Max. SAR evaluation	± 1.0%	Rectangular	v3	1	1	± 0.6%	± 0.6%	8
Test Sample Related								
Device positioning	± 2.9%	Normal	1	1	1	± 2.9%	± 2.9%	145
Device holder uncertainty	± 3.6%	Normal	1	1	1	± 3.6%	± 3.6%	5
Power drift	± 5.0%	Rectangular	v3	1	1	± 2.9%	± 2.9%	8
Phantom and Set-up								
Phantom uncertainty	± 4.0%	Rectangular	v3	1	1	± 2.3%	± 2.3%	8
Liquid conductivity (target)	± 5.0%	Rectangular	v3	0.64	0.43	± 1.8%	± 1.2%	8
Liquid conductivity (meas.)	± 2.5%	Normal	1	0.64	0.43	± 1.6%	± 1.1%	8
Liquid permittivity (target)	± 5.0%	Rectangular	v3	0.6	0.49	± 1.7%	± 1.4%	8
Liquid permittivity (meas.)	± 2.5%	Normal	1	0.6	0.49	± 1.5%	± 1.2%	8
Combined Uncertainty						± 10.3%	± 10.0%	330
Expanded Std. Uncertainty						**± 20.6%**	**± 20.1%**	

Table 5: Measurement uncertainties

2.4.13 Measurement uncertainty evaluation for system validation

The overall combined measurement uncertainty of the measurement system is ± 8.4% (K=1).
The expanded uncertainty(k=2) is assessed to be ± 16.8%
This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

Error Sources	Uncertainty Value	Probability Distribution	Divi-sor	c_i 1g	c_i 10g	Standard Uncertainty 1g	Standard Uncertainty 10g	v_i^2 or v_{eff}
Measurement System								
Probe calibration	± 4.8%	Normal	1	1	1	± 4.8%	± 4.8%	8
Axial isotropy	± 4.7%	Rectangular	v3	0.7	0.7	± 1.9%	± 1.9%	8
Hemispherical isotropy	± 0.0%	Rectangular	v3	0.7	0.7	± 0.0%	± 3.9%	8
Boundary effects	± 1.0%	Rectangular	v3	1	1	± 0.6%	± 0.6%	8
Probe linearity	± 4.7%	Rectangular	v3	1	1	± 2.7%	± 2.7%	8
System detection limits	± 1.0%	Rectangular	v3	1	1	± 0.6%	± 0.6%	8
Readout electronics	± 1.0%	Normal	1	1	1	± 1.0%	± 1.0%	8
Response time	± 0.0%	Rectangular	v3	1	1	± 0.0%	± 0.0%	8
Integration time	± 0.0%	Rectangular	v3	1	1	± 0.0%	± 0.0%	8
RF ambient conditions	± 3.0%	Rectangular	v3	1	1	± 1.7%	± 1.7%	8
Probe positioner	± 0.4%	Rectangular	v3	1	1	± 0.2%	± 0.2%	8
Probe positioning	± 2.9%	Rectangular	v3	1	1	± 1.7%	± 1.7%	8
Max. SAR evaluation	± 1.0%	Rectangular	v3	1	1	± 0.6%	± 0.6%	8
Test Sample Related								
Dipole axis to liquid distance	± 2.0%	Normal	1	1	1	± 1.2%	± 1.2%	8
Power drift	± 4.7%	Rectangular	v3	1	1	± 2.7%	± 2.7%	8
Phantom and Set-up								
Phantom uncertainty	± 4.0%	Rectangular	v3	1	1	± 2.3%	± 2.3%	8
Liquid conductivity (target)	± 5.0%	Rectangular	v3	0.64	0.43	± 1.8%	± 1.2%	8
Liquid conductivity (meas.)	± 2.5%	Normal	1	0.64	0.43	± 1.6%	± 1.1%	8
Liquid permittivity (target)	± 5.0%	Rectangular	v3	0.6	0.49	± 1.7%	± 1.4%	8
Liquid permittivity (meas.)	± 2.5%	Normal	1	0.6	0.49	± 1.5%	± 1.2%	8
Combined Uncertainty						**± 8.4%**	**± 8.1%**	
Expanded Std. Uncertainty						**± 16.8%**	**± 16.2%**	

Table 6: Measurement uncertainties

2.4.14 System validation

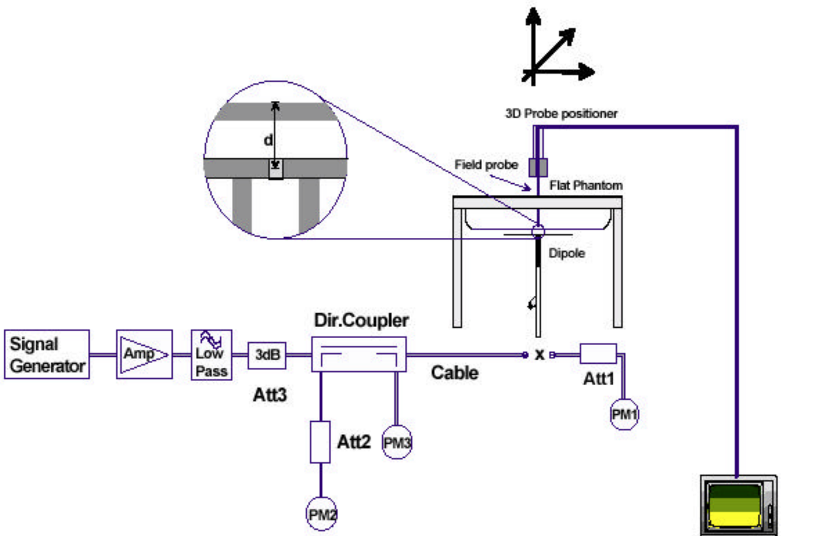
The system validation is performed for verifying the accuracy of the complete measurement system and performance of the software. The system validation is performed with tissue equivalent material according to IEEE P1528 (described above). The following table shows validation results for all frequency bands and tissue liquids used during the tests of the test item described in chapter 1.5.
(graphic plot(s) see annex 1).

Validation Kit	Frequency	Target Peak SAR (1000 mW) (+/- 10%)	Target SAR_{1g} (1000 mW) (+/- 10%)	Measured Peak SAR	Measured SAR_{1g}	Measured date
D2450V2 S/N: 710	2450 MHz body	96.8 mW/g	50.8 mW/g	105.9 mW/g	54.1 mW/g	2004-06-17

Table 7: Results system validation

2.4.15 Validation procedure

The validation is performed by using a validation dipole which is positioned parallel to the planar part of the SAM phantom at the reference point. The distance of the dipole to the SAM phantom is determined by a plexiglass spacer. The dipole is connected to the the signal source consisting of signal generator and amplifier via an directional coupler , N-connector cable and adaption to SMA. It is fed with a power of 1000 mW. To adjust this power a power meter is used . The power sensor is connected to the cable before the validation to measure the power at this point and do adjustments at the signal generator. At the outputs of the directional coupler both return loss as well as forward power are controlled during the validation to make sure that emitted power at the dipole is kept constant. This can also be checked by the power drift measurement after the test (result on plot).
Validation results have to be equal or near the values determined during dipole calibration (target SAR in table above) with the relevant liquids and test system.



2.5 Test results (Body SAR)

The table contains the measured SAR values averaged over a mass of 1 g				
Channel / frequency	Position	SAR value	Limit	Liquid temperature
39 / 2441 MHz	top touched	1.25 W/kg	1.6 W/kg	22.3 °C
39 / 2441 MHz	top 10 mm distance	0.302 W/kg	1.6 W/kg	22.2 °C
39 / 2441 MHz	rear touched	1.000 W/kg	1.6 W/kg	22.3 °C
39 / 2441 MHz	underside touched	0.00143 W/kg	1.6 W/kg	22.3 °C
00 / 2402 MHz	top touched	1.500 W/kg	1.6 W/kg	22.0 °C
78 / 2480 MHz	top touched	0.606 W/kg	1.6 W/kg	22.0 °C
00 / 2402 MHz	rear touched	1.410 W/kg	1.6 W/kg	22.0 °C
78 / 2480 MHz	rear touched	0.570 W/kg	1.6 W/kg	22.0 °C

Table 8: Test results (Body SAR)

Note : The SAR test shall be performed at the high, middle and low frequency channels of each operating mode. If the SAR measured at mid-band channel for each test configuration is at least 3.0 dB lower than the SAR limit (< 0.8 W/kg) , testing at the high and low channels is optional.

2.5.1 Description of test positions during SAR evaluation

To evaluate the maximum SAR exposure it was assumed that highest SAR values could be expected at the position of the Bluetooth antenna integrated in the device.
The Bluetooth mode was initialized by use of a notebook software allowing the setting of power level, frequency and packet size (DH 5 were used during the test).
The notebook was disconnected again after initiating continuous power mode.
For the measurements of the conducted peak power an Agilent 8990A Peak Power Analyzer was used.
The output power was measured using an integrated RF connector and attached power sensor.

top position	device top side touching SAM or 10mm distance to SAM with antenna near SAM reference point.
rear position	device rear side touching SAM or 10mm distance to SAM with antenna near SAM reference point.
underside position	device touching SAM with underside. No maximum peak generated by the bluetooth signal could be detected as measured SAR Value was near noise level.

2.6 Test results (conducted power measurement)

For the measurements an Agilent 8990A Peak Power Analyzer was used
The output power was measured using an integrated RF connector and attached power sensor.

Bluetooth 2.4 GHz	
Channel / frequency	peak power
00 / 2402 MHz	18.1 dBm
39 / 2441 MHz	18.2 dBm
78 / 2480 MHz	18.1 dBm

Table 9: Test results conducted peak power measurement

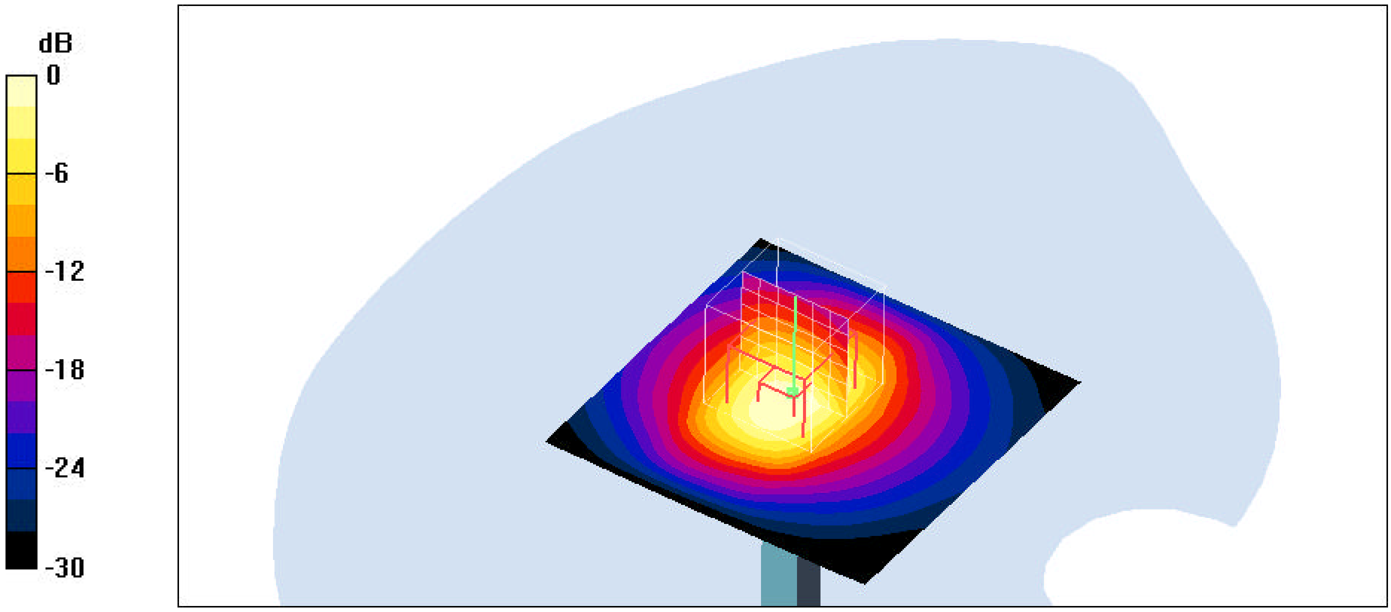
Annex 1 System performance verification

Date/Time: 06/17/04 09:23:24

SystemPerformanceCheck-D2450

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:710
Communication System: CW; Frequency: 2450 MHz;Duty Cycle: 1:1
Medium: M2450 Medium parameters used: f = 2450 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3
Phantom section: Flat Section
DASY4 Configuration:
- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

d=10mm, Pin=1000mW/Area Scan (61x61x1): Measurement grid: dx=15mm, dy=15mm
d=10mm, Pin=1000mW/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 105.9 W/kg
SAR(1 g) = 54.1 mW/g; SAR(10 g) = 25 mW/g
Reference Value = 181.8 V/m
Power Drift = -0.0 dB
Maximum value of SAR = 60.9 mW/g



0 dB = 60.9mW/g

Additional information:
position or distance of DUT to SAM (if not standard head positions) :
ambient temperature: 21.8°C; liquid temperature: 22.0°C

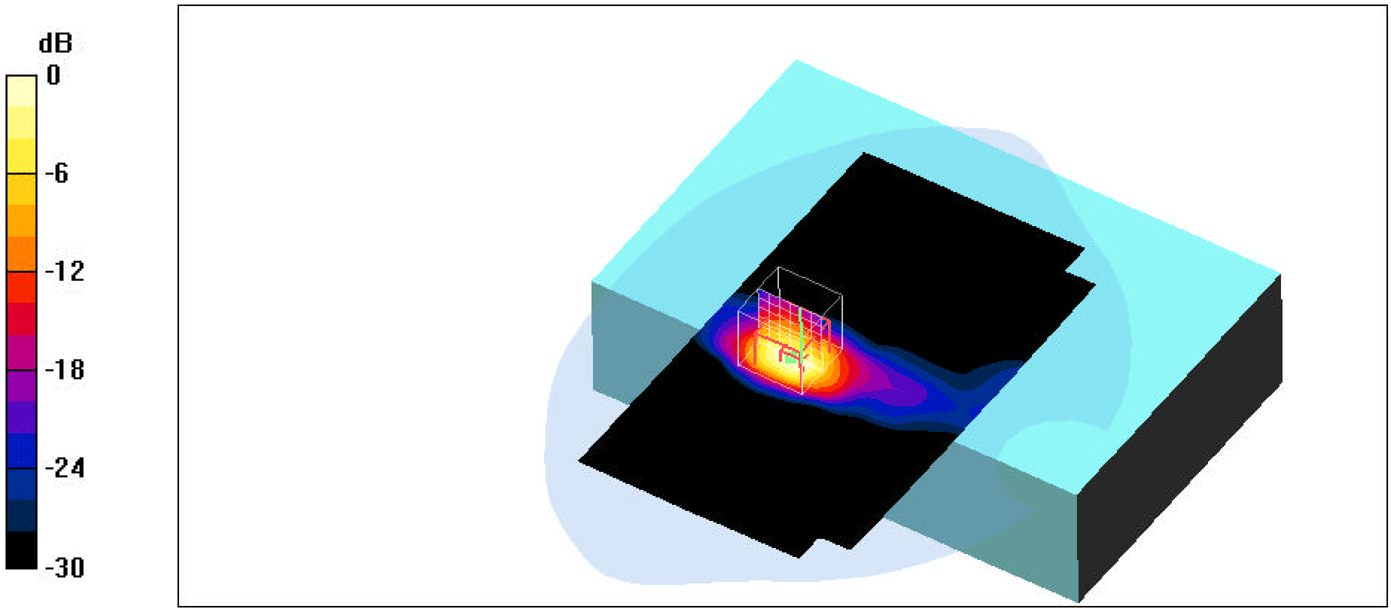
Annex 2 Measurement results (printout from DASY ™)

Date/Time: 06/17/04 09:02:11

EN50371-OET65-Body-BT2450

DUT: Siemens; Type: VAS5053; Serial: A5E00262440
Communication System: Blue Tooth; Frequency: 2441 MHz;Duty Cycle: 1:1
Medium: M2450 Medium parameters used: f = 2441 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3
Phantom section: Flat Section
DASY4 Configuration:
- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

Top position - Middle/Area Scan (81x141x1): Measurement grid: dx=15mm, dy=15mm
Top position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 3.03 W/kg
SAR(1 g) = 1.25 mW/g; SAR(10 g) = 0.479 mW/g
Reference Value = 6.03 V/m
Power Drift = -0.2 dB
Maximum value of SAR = 1.5 mW/g



0 dB = 1.5mW/g

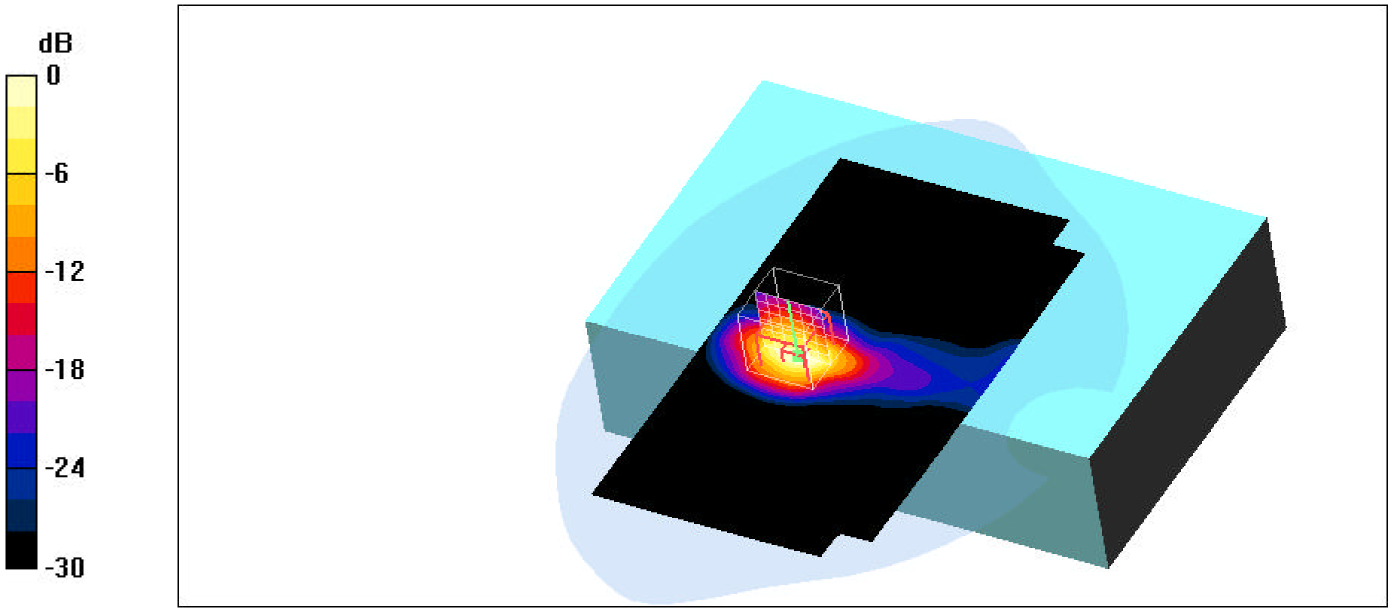
Additional information:
position or distance of DUT to SAM (if not standard head positions) :
ambient temperature: 21.5°C; liquid temperature: 22.3°C

Date/Time: 06/17/04 09:02:11

EN50371-OET65-Body-BT2450

DUT: Siemens; Type: VAS5053; Serial: A5E00262440
Communication System: Blue Tooth; Frequency: 2402 MHz;Duty Cycle: 1:1
Medium: M2450 Medium parameters used: f = 2402 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3
Phantom section: Flat Section
DASY4 Configuration:
- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

Top position - worst case low/Area Scan (81x141x1): Measurement grid: dx=15mm, dy=15mm
Top position - worst case low/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 3.45 W/kg
SAR(1 g) = 1.5 mW/g; SAR(10 g) = 0.586 mW/g
Reference Value = 9.97 V/m
Power Drift = -0.1 dB
Maximum value of SAR = 1.78 mW/g



0 dB = 1.78mW/g

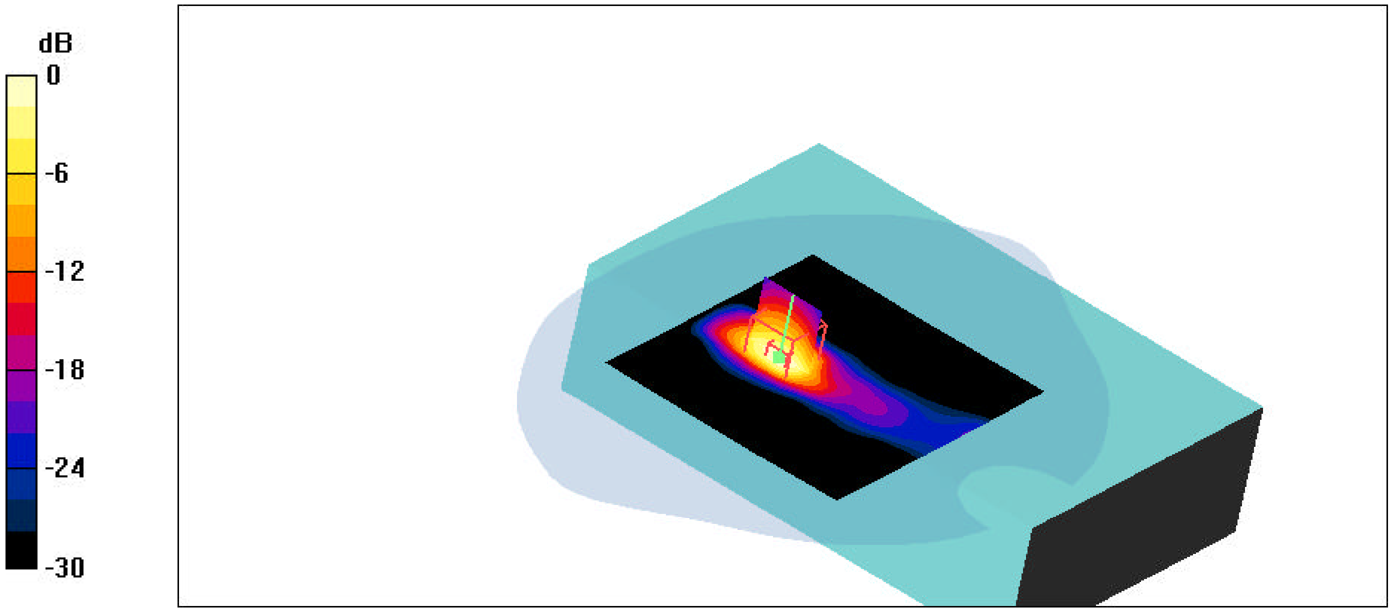
Additional information:
position or distance of DUT to SAM (if not standard head positions) : device touching SAM with antenna near reference point
ambient temperature: 21.8°C; liquid temperature: 22.0°C

Date/Time: 06/17/04 09:02:11

EN50371-OET65-Body-BT2450

DUT: Siemens; Type: VAS5053; Serial: A5E00262440
Communication System: Blue Tooth; Frequency: 2480 MHz;Duty Cycle: 1:1
Medium: M2450 Medium parameters used: f = 2480 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3
Phantom section: Flat Section
DASY4 Configuration:
- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

Top position - worst case high/Area Scan (81x91x1): Measurement grid: dx=15mm, dy=15mm
Top position - worst case high/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 1.57 W/kg
SAR(1 g) = 0.606 mW/g; SAR(10 g) = 0.228 mW/g
Reference Value = 4.72 V/m
Power Drift = -0.0 dB
Maximum value of SAR = 0.704 mW/g



0 dB = 0.704mW/g

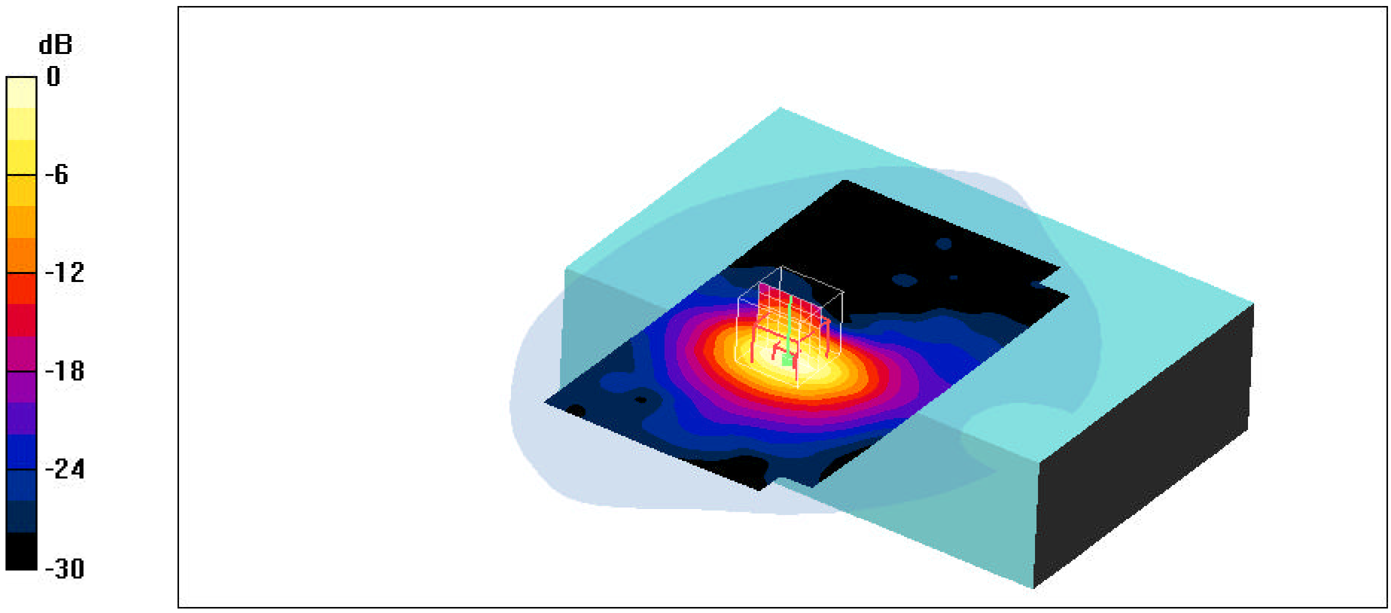
Additional information:
position or distance of DUT to SAM (if not standard head positions) : device touching SAM with antenna near reference point
ambient temperature: 21.5°C; liquid temperature: 22.0°C

Date/Time: 06/17/04 09:02:11

EN50371-OET65-Body-BT2450

DUT: Siemens; Type: VAS5053; Serial: A5E00262440
Communication System: Blue Tooth; Frequency: 2441 MHz;Duty Cycle: 1:1
Medium: M2450 Medium parameters used: f = 2441 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3
Phantom section: Flat Section
DASY4 Configuration:
- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

Top position - Middle 2/Area Scan (81x141x1): Measurement grid: dx=15mm, dy=15mm
Top position - Middle 2/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 0.618 W/kg
SAR(1 g) = 0.302 mW/g; SAR(10 g) = 0.145 mW/g
Reference Value = 5.94 V/m
Power Drift = 0.0 dB
Maximum value of SAR = 0.338 mW/g



0 dB = 0.338mW/g

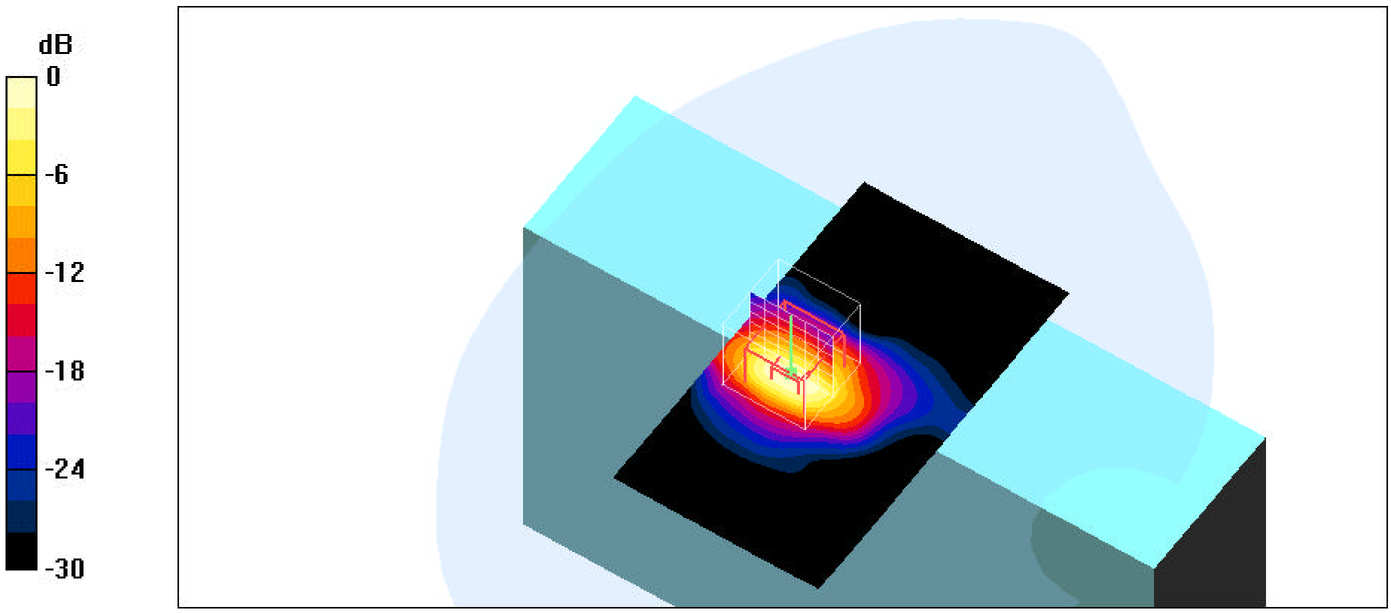
Additional information:
position or distance of DUT to SAM (if not standard head positions) : 10 mm distance to SAM with antenna near reference point
ambient temperature: 22.0°C; liquid temperature: 22.0°C

Date/Time: 06/17/04 09:02:11

EN50371-OET65-Body-BT2450

DUT: Siemens; Type: VAS5053; Serial: A5E00262440
Communication System: Blue Tooth; Frequency: 2441 MHz;Duty Cycle: 1:1
Medium: M2450 Medium parameters used: f = 2441 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3
Phantom section: Flat Section
DASY4 Configuration:
- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

Rear position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm
Rear position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 2.42 W/kg
SAR(1 g) = 1 mW/g; SAR(10 g) = 0.389 mW/g
Reference Value = 16.2 V/m
Power Drift = 0.005 dB
Maximum value of SAR = 1.21 mW/g



0 dB = 1.21mW/g

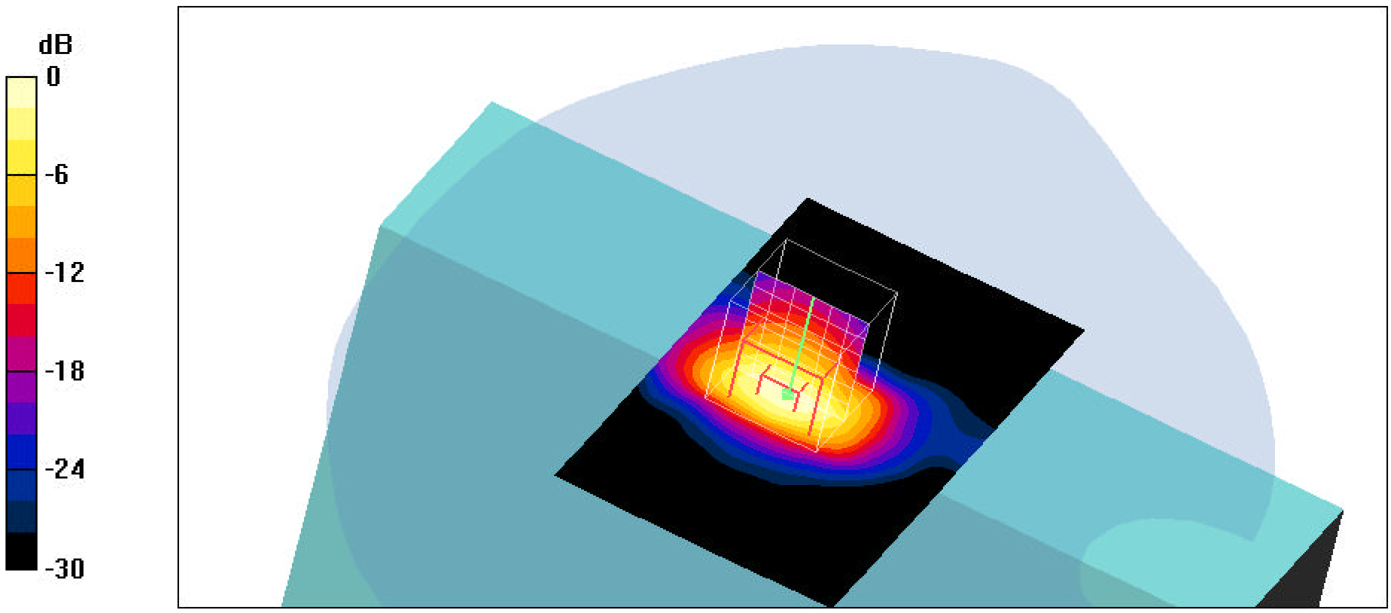
Additional information:
position or distance of DUT to SAM (if not standard head positions) : device touching SAM with antenna near reference point
ambient temperature: 21.7°C; liquid temperature: 22.1°C

Date/Time: 06/17/04 09:02:11

EN50371-OET65-Body-BT2450

DUT: Siemens; Type: VAS5053; Serial: A5E00262440
Communication System: Blue Tooth; Frequency: 2402 MHz;Duty Cycle: 1:1
Medium: M2450 Medium parameters used: f = 2402 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3
Phantom section: Flat Section
DASY4 Configuration:
- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

Rear position - worst case low/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm
Rear position - worst case low/ Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Peak SAR (extrapolated) = 3.22 W/kg
SAR(1 g) = 1.41 mW/g; SAR(10 g) = 0.552 mW/g
Reference Value = 26.8 V/m
Power Drift = 0.0 dB
Maximum value of SAR = 1.68 mW/g



0 dB = 1.68mW/g

Additional information:
position or distance of DUT to SAM (if not standard head positions) : device touching SAM with antenna near reference point
ambient temperature: 22.0°C; liquid temperature: 22.0°C

Date/Time: 06/17/04 09:02:11

EN50371-OET65-Body-BT2450

DUT: Siemens; Type: VAS5053; Serial: A5E00262440

Communication System: Blue Tooth; Frequency: 2480 MHz;Duty Cycle: 1:1

Medium: M2450 Medium parameters used: f = 2480 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

Rear position - worst case high/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Rear position - worst case high/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

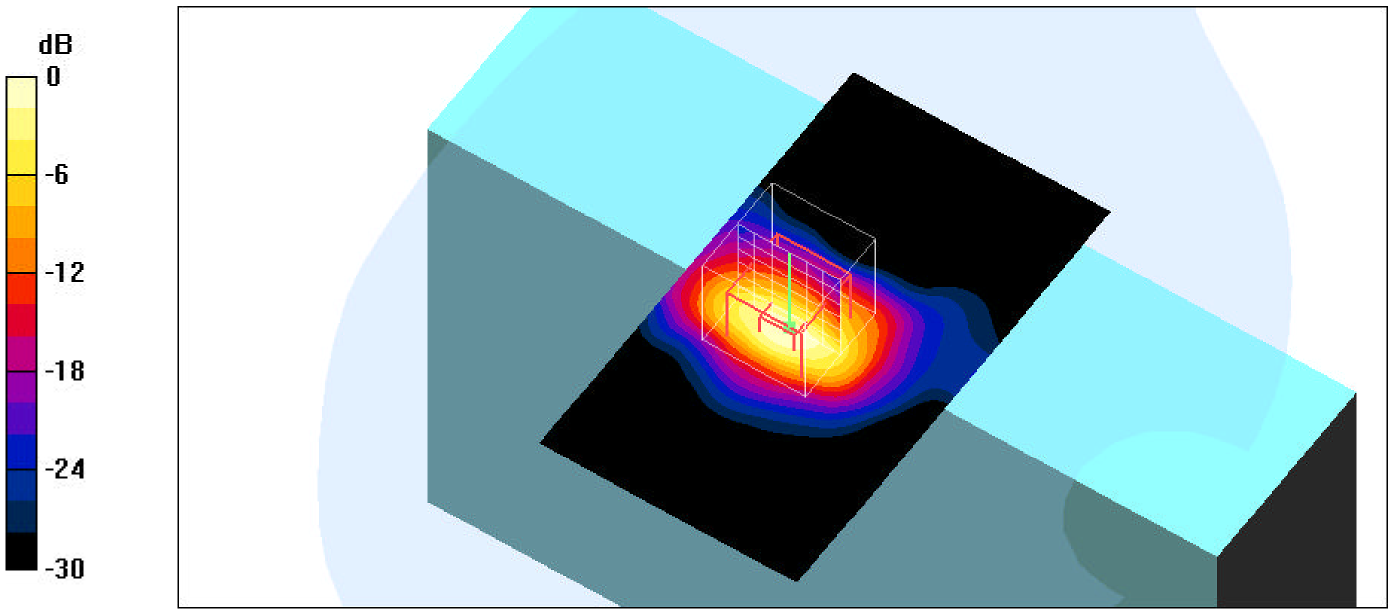
Peak SAR (extrapolated) = 1.48 W/kg

SAR(1 g) = 0.570 mW/g; SAR(10 g) = 0.217 mW/g

Reference Value = 14.1 V/m

Power Drift = -0.0 dB

Maximum value of SAR = 0.682 mW/g



0 dB = 0.682mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : device touching SAM with antenna near reference point

ambient temperature: 22.4°C; liquid temperature: 22.0°C

Date/Time: 06/17/04 09:02:11

EN50371-OET65-Body-BT2450

DUT: Siemens; Type: VAS5053; Serial: A5E00262440

Communication System: Blue Tooth; Frequency: 2441 MHz;Duty Cycle: 1:1

Medium: M2450 Medium parameters used: f = 2441 MHz; s = 2 mho/m; e_r = 53.5; ? = 1000 kg/m^3

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1558; ConvF(4.15, 4.15, 4.15); Calibrated: 03.06.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn413; Calibrated: 25.04.2003
- Phantom: SAM 12; Type: SAM; Serial: 1043
- Measurement SW: DASY4, V4.2 Build 12; Postprocessing SW: SEMCAD, V1.8 Build 93

Underside position - Middle/Area Scan (51x91x1): Measurement grid: dx=15mm, dy=15mm

Underside position - Middle/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

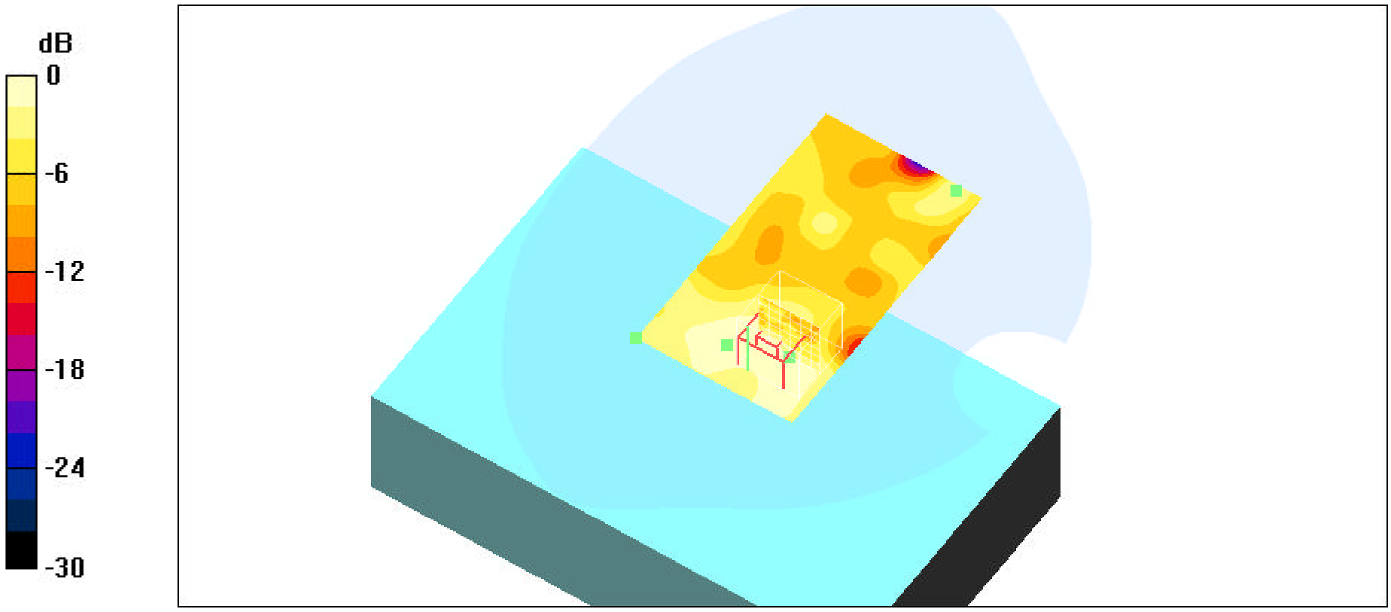
Peak SAR (extrapolated) = 0.00393 W/kg

SAR(1 g) = 0.00143 mW/g; SAR(10 g) = 0.000911 mW/g

Reference Value = 0.439 V/m

Power Drift = 0.0 dB

Maximum value of SAR = 0.00184 mW/g



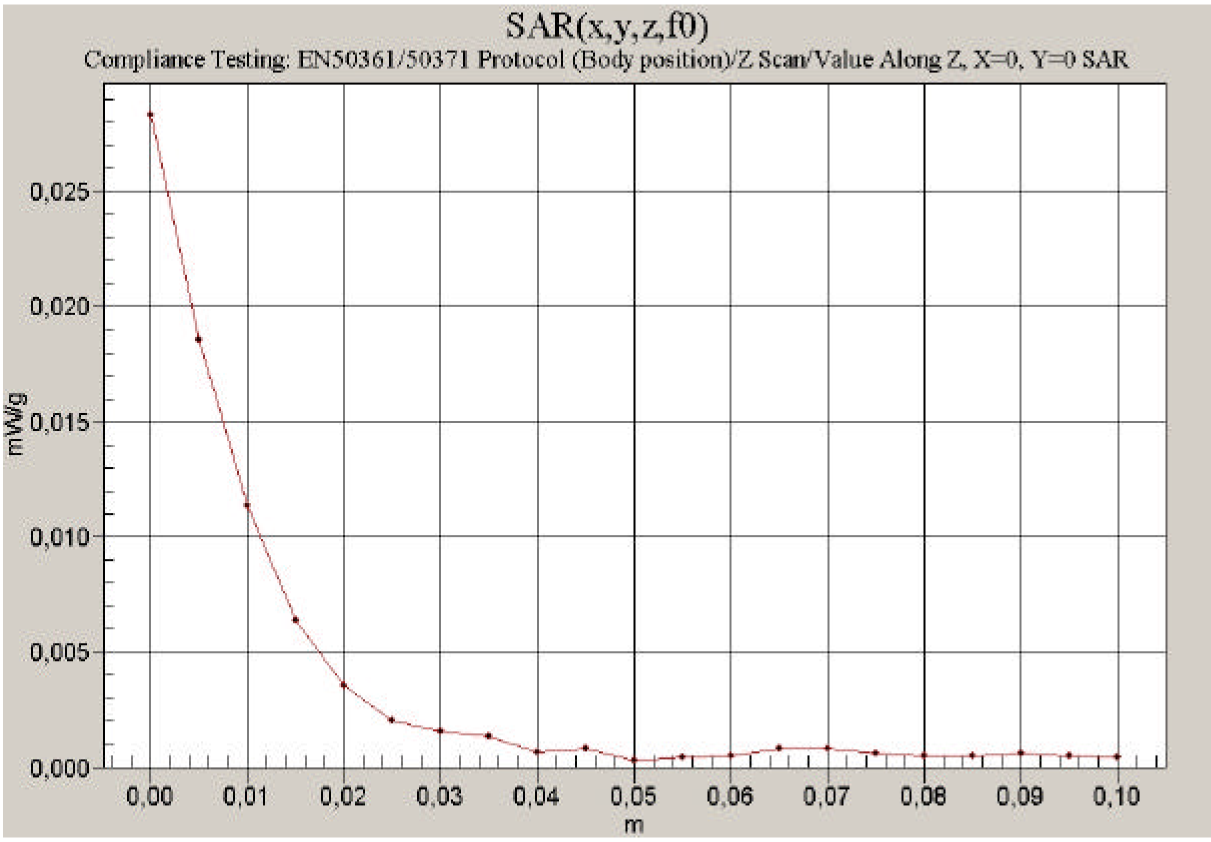
0 dB = 0.00184mW/g

Additional information:

position or distance of DUT to SAM (if not standard head positions) : device touching SAM

ambient temperature: 21.5°C; liquid temperature: 22.3°C

Z-axis scan 2450 MHz body liquid



Annex 3 Photo documentation

Picture no. 1

Measurement System DASY 4

Picture no. 2

DUT - top view

antenna position

Picture no. 3

DUT - rear view

Picture no. 4

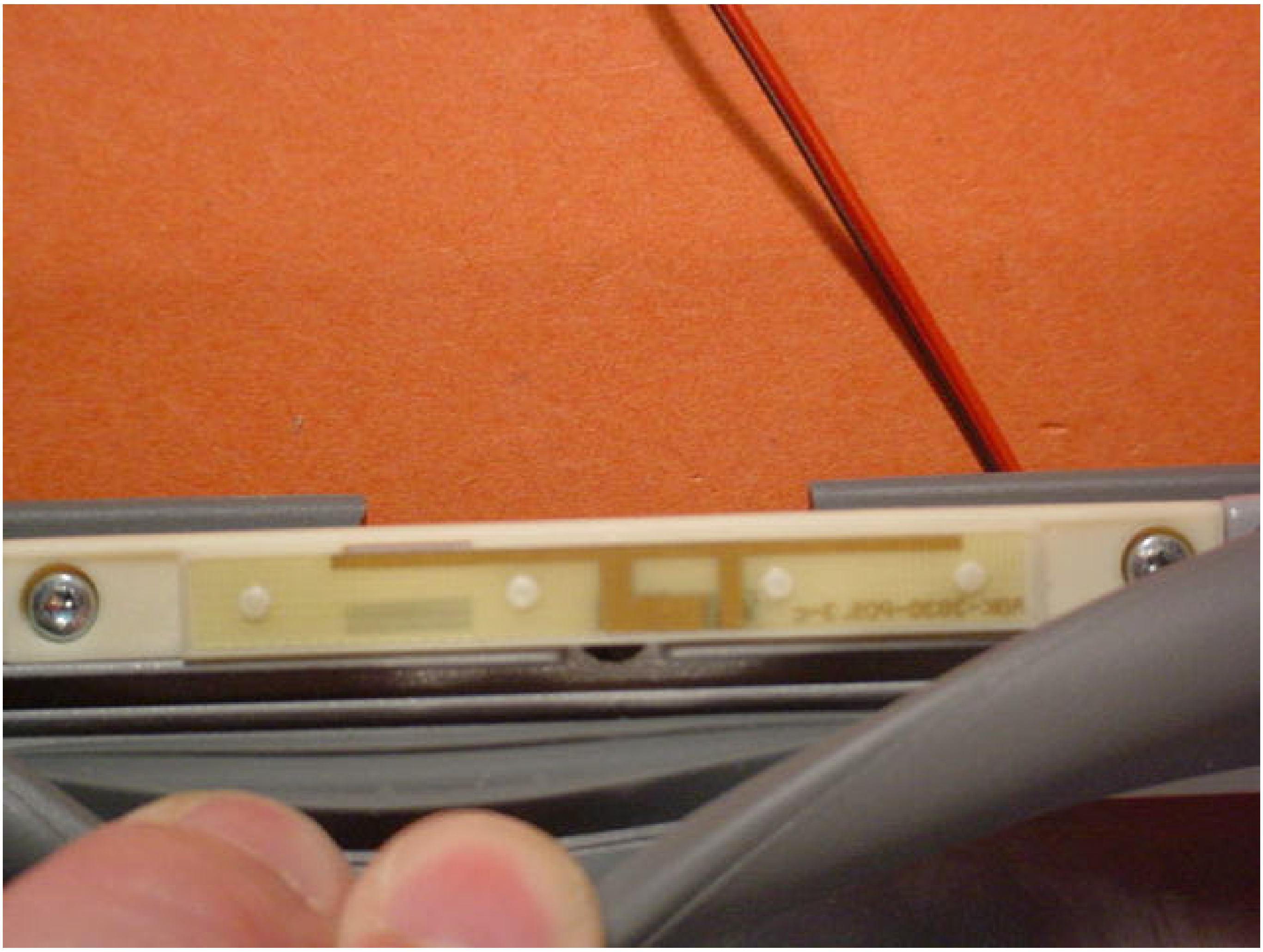
DUT - underside view

Picture no. 5

label

Picture no. 6

antenna



Picture no. 7

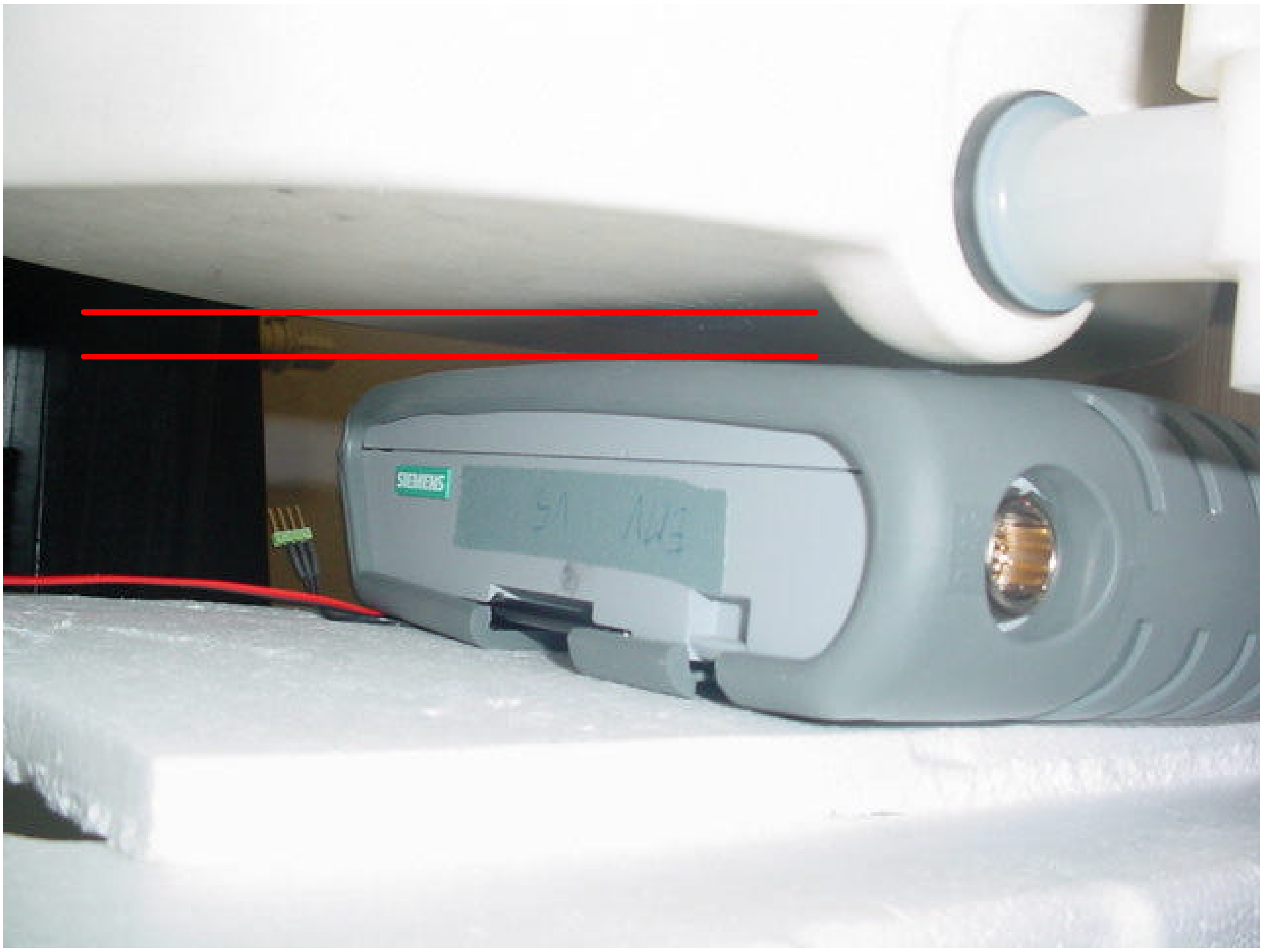
test position top (touched)

Picture no. 8

test position top (touched)

Picture no. 9

test position top (10 mm distance)



Picture no. 10

test position rear (touched)

Picture no. 11

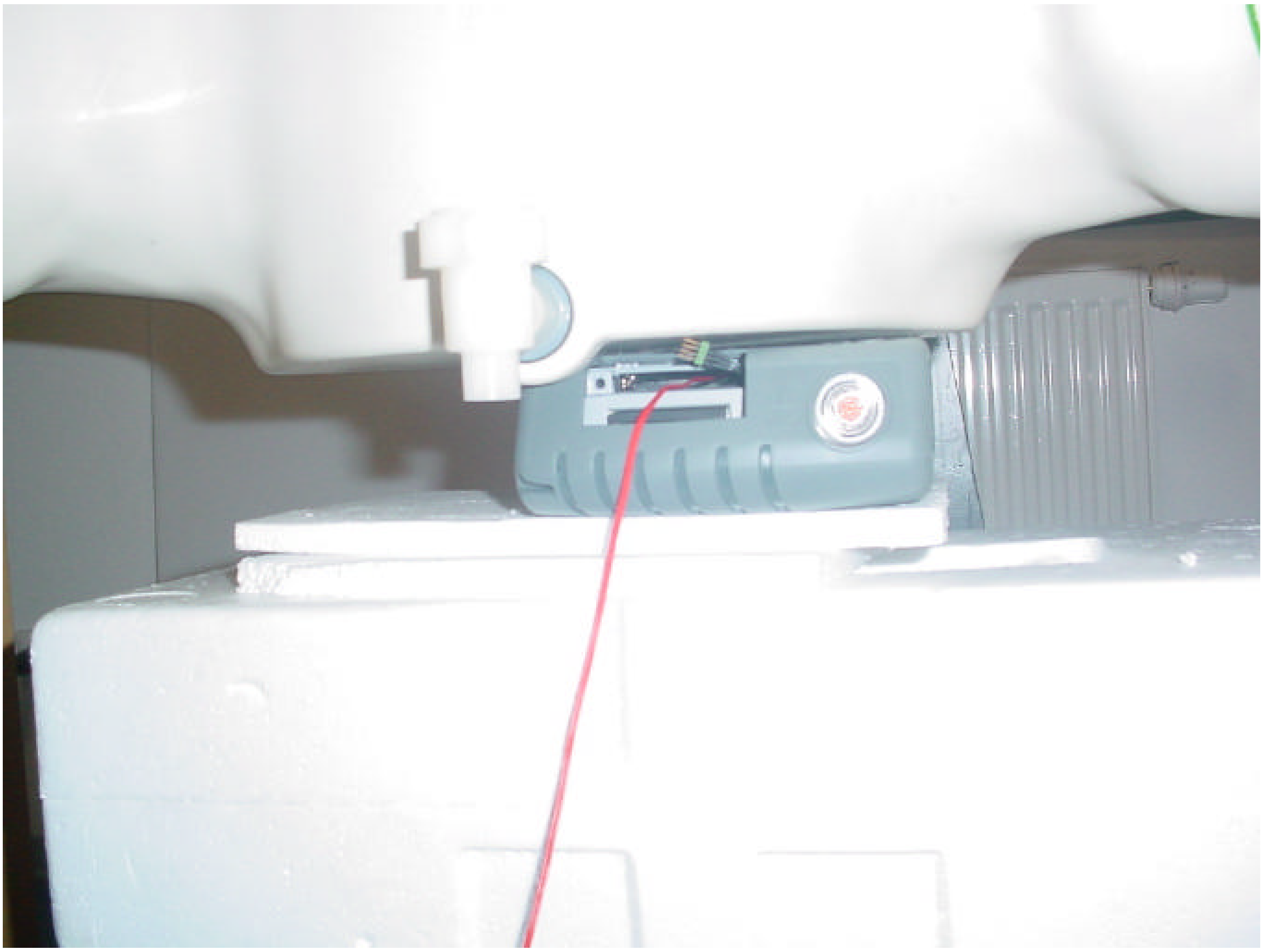
test position rear (touched)

Picture no. 12

test position rear (touched)

Picture no. 13

test position underside (touched)



Picture no. 14

test position underside (touched)

Picture no. 15

liquid depth 2450 MHz body tissue simulating liquid

Annex 4 Calibration parameters of E-field probe

Calibration parameters are described in the additional document

‘ Calibration data and Phantom information for test report no. 2-3577-01-10/04-B‘,

provided together with this document.