

Technical Description

The Equipment Under Test (EUT) is a 2.4GHz Controller operating from 2407-2477MHz with 1MHz channel spacing for RC Car. The EUT is powered by 3.0V AAA batteries. After switch on the EUT and paired with RC Car, the EUT can be controlled to move forward, backward, turn left/right.

The brief circuit description is listed as below:

- 1) U1 acts as 2.4GHz RF Module Circuit (RX2B-2.4G).**
- 2) Y1 is 16MHz crystal oscillator providing clock for U1.**

Antenna Type: Internal antenna

Antenna Gain: 0dBi

Nominal rated field strength: 82.8dB μ V/m at 3m

Maximum allowed field strength of production tolerance: +/- 3dB

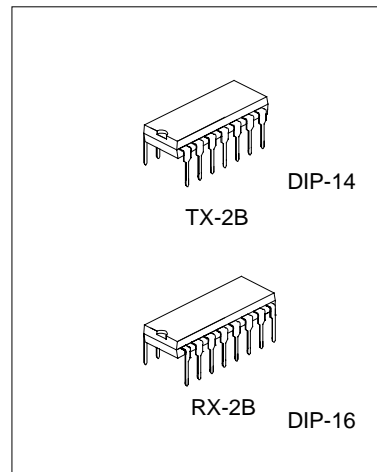
REMOTE CONTROLLER WITH FIVE FUNCTIONS

DESCRIPTION

The TX-2B/RX-2B is a pair of CMOS LSIs designed for remote controlled car applications. The TX-2B/RX-2B has five control keys for controlling the motions (i.e. forward, backward, rightward, leftward and the turbo function) of the remote controlled car.

FEATURES

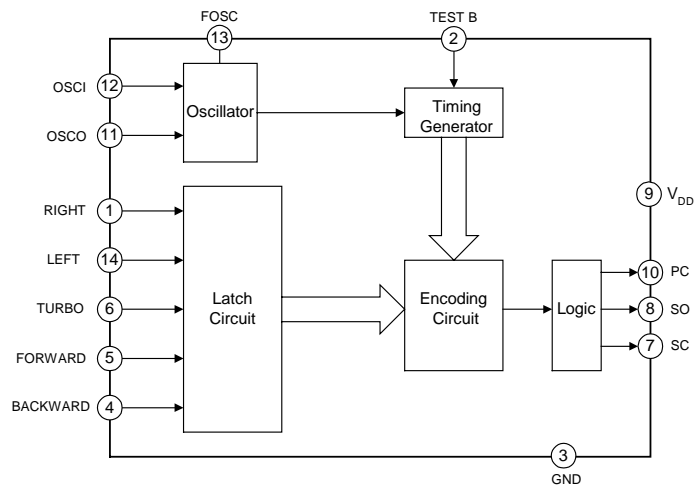
- * Wide operating voltage range ($V_{CC}=1.5\sim 5.0V$)
- * Low stand-by current
- * Auto-power-off function for TX-2B
- * Few external components are needed



ORDERING INFORMATION

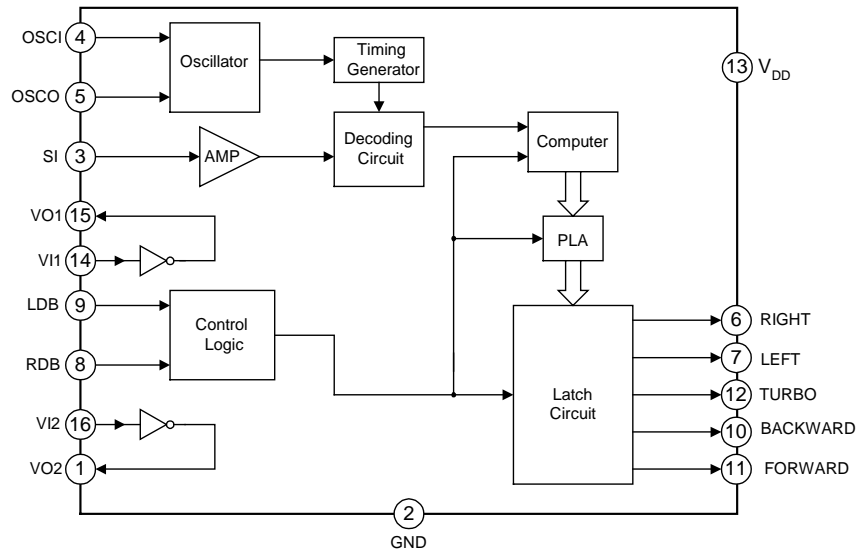
| Part No. | Package |
|----------|-----------------|
| TX-2B | DIP-14-300-2.54 |
| RX-2B | DIP-16-300-2.54 |

BLOCK DIAGRAM



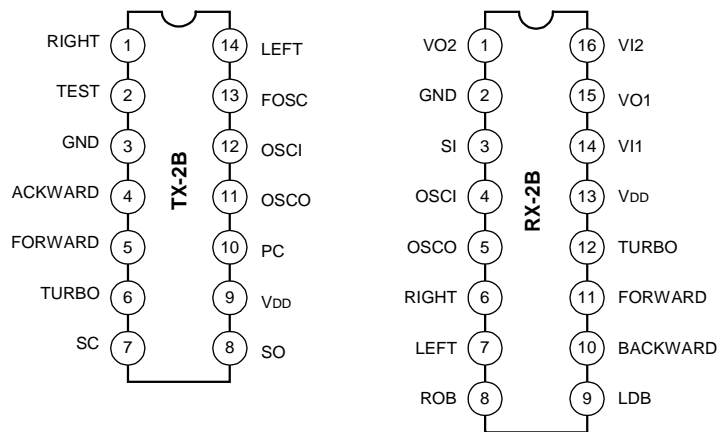
TRANSMITTER TX-2B Block Diagram

BLOCK DIAGRAM



RECEIVER RX-2B Block Diagram

PIN CONFIGURATION



ABSOLUTE MAXIMUM RATINGS

| Characteristic | Symbol | Value | Unit |
|------------------------|-----------|-----------------|------|
| Supply Voltage | VDD | 0.3~5.0 | V |
| Input / Output Voltage | VIN, VOUT | GND-0.3~VDD+0.3 | V |
| Operating Temperature | TOPR | -10~65 | °C |
| Storage Temperature | Tstg | -25~125 | °C |

ELECTRICAL CHARACTERISTICS

1. **TX-2B** (VDD=4.0V, Fosc=128KHz, Tamb =25°C, unless otherwise specified.)

| Characteristic | Symbol | Min | Typ | Max | Unit |
|------------------------|--------|-----|-----|-----|------|
| Operating Voltage | VDD | 1.5 | 4.0 | 5.0 | V |
| Operating Current | IDD | -- | -- | 2.0 | mA |
| Stand-By Current | ISTB | -- | -- | 10 | μA |
| DC O/P Driving Current | Idrive | 5 | -- | -- | mA |
| AC O/P Driving Current | Idrive | 5 | -- | -- | mA |
| AC O/P Frequency | Faudio | 0.5 | -- | 1.0 | kHz |

2. **RX-2B** (VDD=4.0V, Fosc=128KHz, Tamb=25°C, unless otherwise specified.)

| characteristic | Symbol | Min | Typ | Max | Unit |
|-------------------------------------|------------|-----|-----|-----|------|
| Operating Voltage | VDD | 1.5 | 4.0 | 5.0 | V |
| Operating Current | IDD | -- | -- | 3.0 | mA |
| O/P Driving Current | Idrive | 1 | -- | -- | mA |
| O/P Sinking Current | Isink | 1 | -- | -- | mA |
| Effect Decoding Frequency Variation | Ftolerance | -20 | -- | 20 | % |

PIN DESCRIPTION

1. TX-2B

| Pin No. | Symbol | Description |
|---------|----------|--|
| 1 | RIGHT | The rightward function will be selected, if this pin is connected to GND |
| 2 | TEST | This pin is used for testing mode |
| 3 | GND | Negative power supply |
| 4 | BACKWARD | The backward function will be selected, if this pin is connected to GND |
| 5 | FORWARD | The forward function will be selected, if this pin is connected to GND |

(To be continued)

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(Continued)

| Pin No. | Symbol | Description |
|---------|--------|---|
| 6 | TURBO | The turbo function will be selected if this pin is connected to GND |
| 7 | SC | Output pin of the encoding signal with carrier frequency |
| 8 | SO | Output pin of the encoding signal without carrier frequency |
| 9 | VDD | Positive power supply |
| 10 | PC | Power control output pin |
| 11 | OSCO | Oscillator output pin |
| 12 | OSCI | Oscillator input pin |
| 13 | FOSC | This pin is used for testing mode |
| 14 | LEFT | The leftward function will be selected, if this pin is connected to GND |

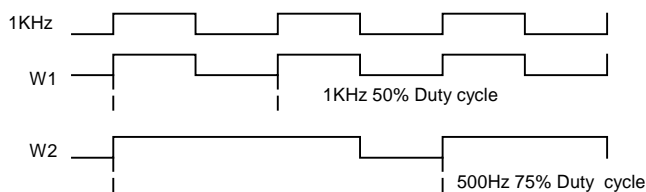
2. RX-2B

| Pin No. | Symbol | Description |
|---------|----------|---|
| 1 | VO2 | Inverter 2 output pin for power amplify |
| 2 | GND | Negative power supply |
| 3 | SI | Input pin of the encoding signal |
| 4 | OSCI | Oscillator input pin |
| 5 | OSCO | Oscillator output pin |
| 6 | RIGHT | Rightward output pin |
| 7 | LEFT | Leftward output pin |
| 8 | ROB | Rightward function disable, if this pin is connected to GND |
| 9 | LDB | Leftward function disable, if this pin is connected to GND |
| 10 | BACKWARD | Backward output pin |
| 11 | FORWARD | Forward output pin |
| 12 | TURBO | TURBO output pin |
| 13 | VDD | Positive power supply |
| 14 | VI1 | Inverter 1 input pin for power amplify |
| 15 | VO1 | Inverter 1 output pin for power amplify |
| 16 | VI2 | Inverter 2 input pin for power amplify |

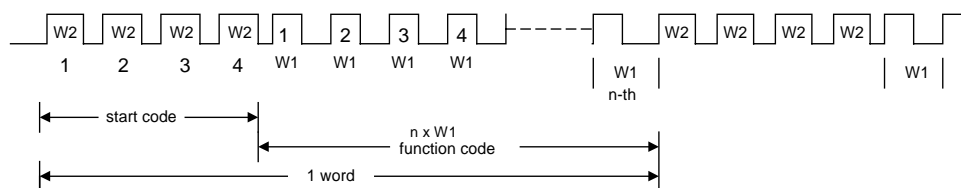
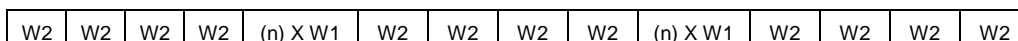
CODE FORMAT

1. ENCODE RULE

(A).Bit Format (W1 is used for function codes,W2 for start codes)

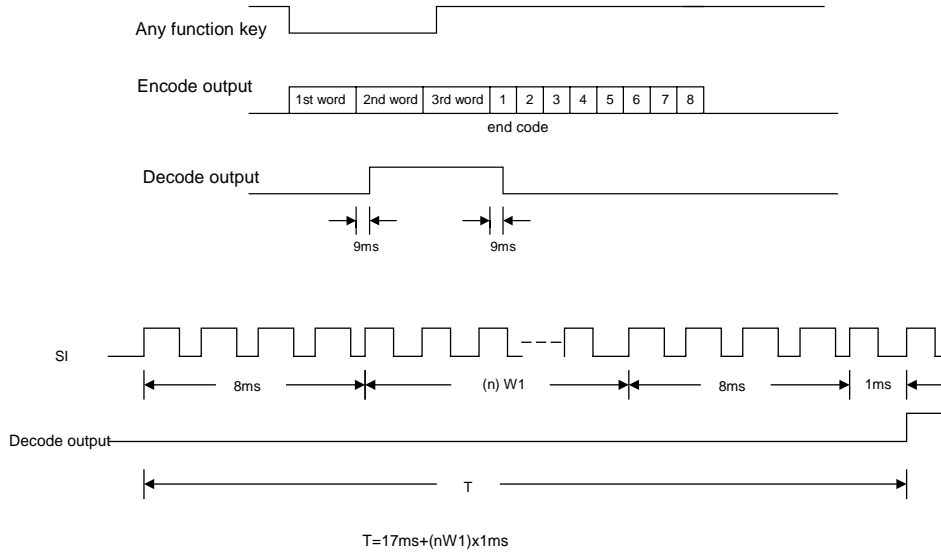


(B).Date Format



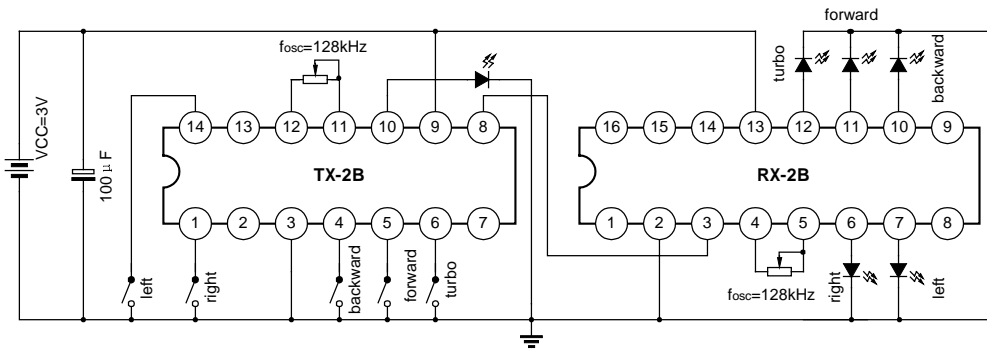
| Number Of Function Code (N) W1 | Function Key | Decode Result |
|--------------------------------|-------------------------|------------------|
| 4 | | End Code |
| 10 | Forward | Forward |
| 16 | Forward & Turbo | Forward |
| 22 | Turbo | Turbo |
| 28 | Turbo & Forward & Left | Forward & Left |
| 34 | Turbo & Forward & Right | Forward & Right |
| 40 | Backward | Backward |
| 46 | Backward & Right | Backward & Right |
| 52 | Backward & Left | Backward & Left |
| 58 | Left | Left |
| 64 | Right | Right |

2. ENCODE/DECODE TIMING



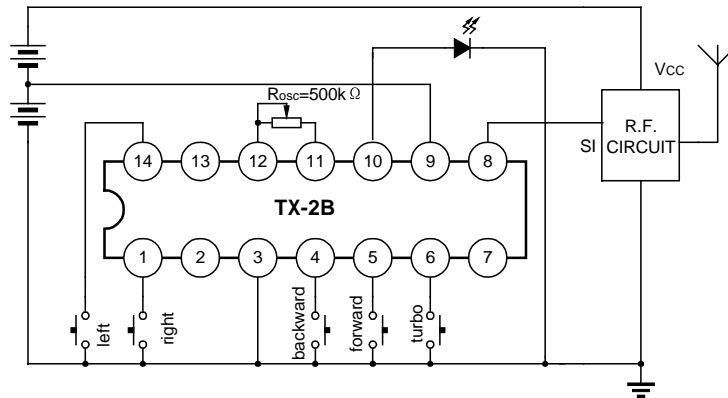
TESTING CIRCUIT

(The oscillator frequency of TX-2B, RX-2B is 128KHz, the oscillator resistor is 160KΩ and 250KΩ respectively)

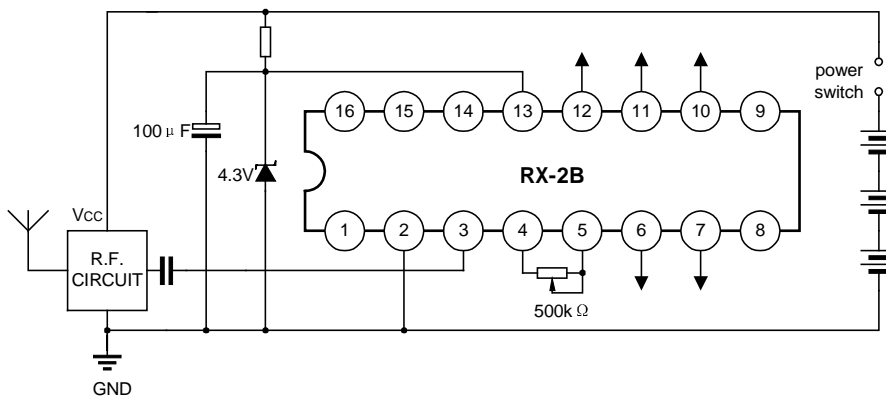


TYPICAL APPLICATION CIRCUIT

TRANSMITTER

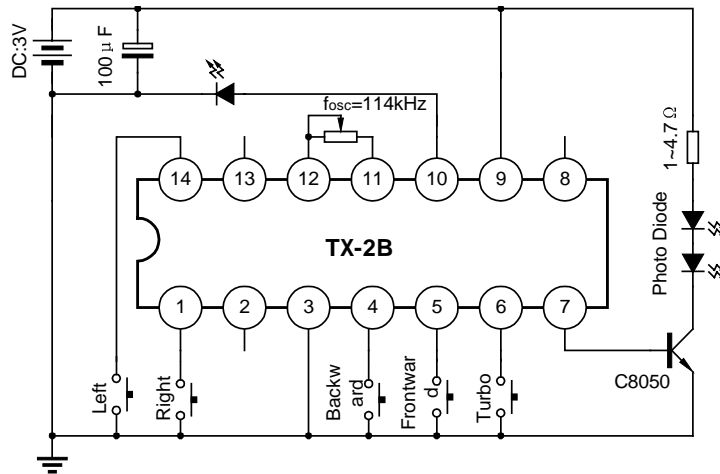


RECEIVER

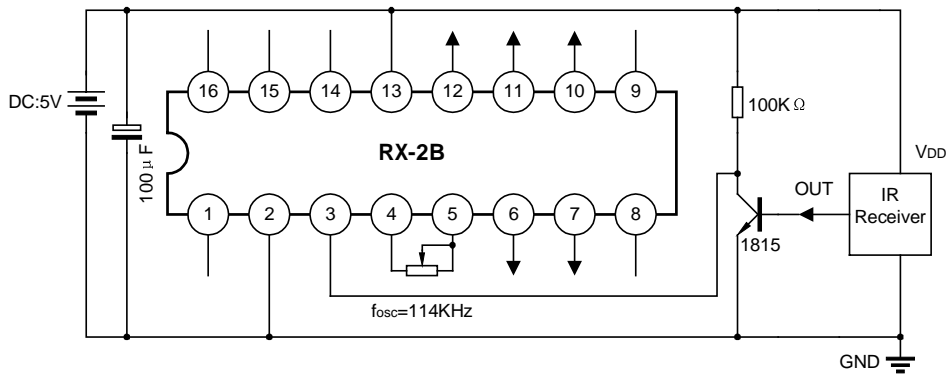


INFRARED APPLICATION CIRCUIT

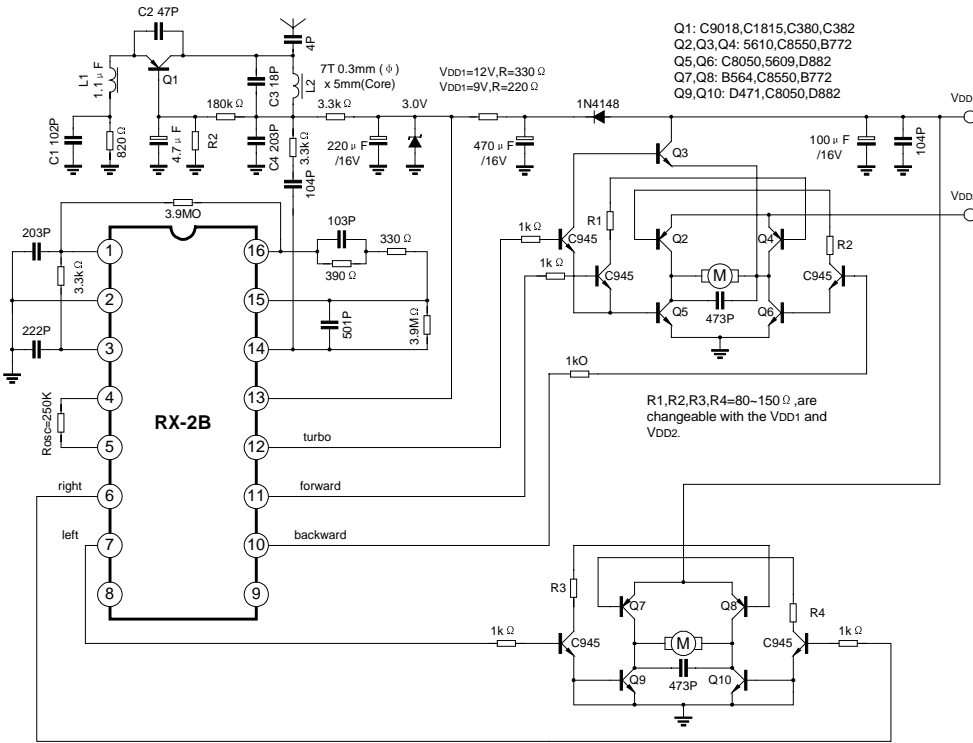
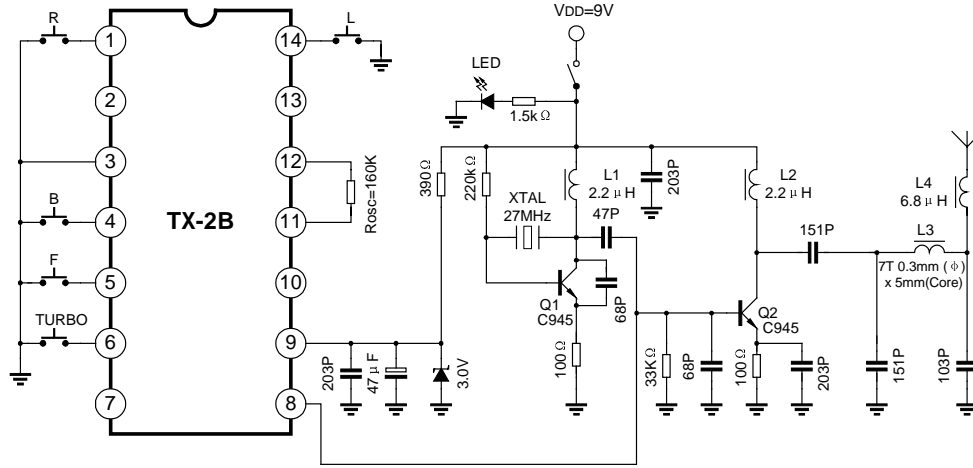
TRANSMITTER



RECEIVER



RECOMMENDED APPLICATION CIRCUIT



- Q1: C9018, C1815, C380, C382
- Q2, Q3, Q4: 5610, C8550, B772
- Q5, Q6: C8050, 5609, D882
- Q7, Q8: B564, C8550, B772
- Q9, Q10: D471, C8050, D882

PACKAGE OUTLINE

