

Annex B: Probe and dipole description and calibration certificates

B.1 Probe, measurement chain description, specification and calibration certificate



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Report No

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Author Data

Daoud Attayi

Dates of Test

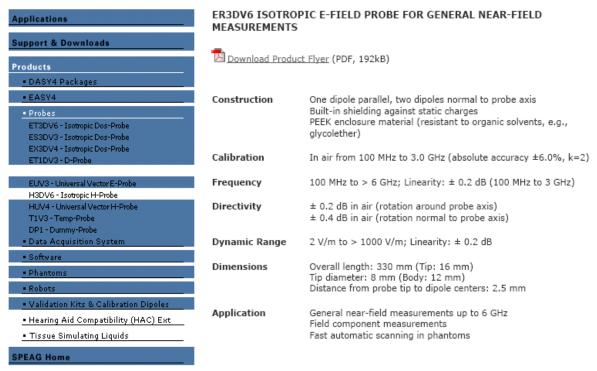
August 31- October 27, 2015

RTS-6066-1511-05

FCC ID L6ARHT180LW

DASY Dosimetric Assessment System by Schmid & Partner Engineering AG





http://www.dasy4.com/er3.htm



All measurements were performed to the nearest element point as per the C63.19 standard. Offset distances were entered in the DASY5 software so that the measurement was to the nearest element.

Figures 1, provided by the manufacturer, illustrate detail of the probe tip and its dimensions.

ER3DV6 E-Field probe: The distances from the probe tip to the closest points on the dipole sensors are 1.45mm for X and Y and 1.25mm for Z. From the probe tip to the center of the sensors is 2.5mm.



E-Field Probe (ER3DV6)



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The following information is from the system manufacturer user manual describing the process chain:

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$
(20.1)

From the compensated input signals the primary field data for each channel can be evaluated:

E – field
probes :
$$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

$${
m H-field probes}$$
 : $H_i = \sqrt{V_i} \cdot rac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$

with
$$V_i$$
 = compensated signal of channel i (i = x, y, z
 $Norm_i$ = sensor sensitivity of channel i (i = x, y, z

sensor sensitivity of channel i

$$\mu V/(V/m)^2$$
 for E-field Probes

$$a_{ij}$$
 = sensor sensitivity factors for H-field probes

$$f$$
 = carrier frequency [GHz]

$$E_i$$
 = electric field strength of channel i in V/m
 H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$
(20.2)

The measurement / integration time per point is > 500 ms, as per the system manufacturer:

The time response of the field probes has been assessed by exposing the probe to a well-controlled field producing signals larger than HAC E- and H-fields of class M4. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/off switch of the power source with an integration time of 500 ms and a probe response time of <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization. The tolerances for the different systems had the worst-case of 2.6%.



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TST-SARL-00006

Calibration Laboratory of Schmid & Partner Engineering AG Zeughausstrasse 43, 8004 Zurich, Switzerland





Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura Swiss Calibration Service

Accreditation No.: SCS 0108

Accredited by the Swiss Accreditation Service (SAS) The Swins Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Blackberry Waterloo

Certificate No: ER3-2286_Jan15

CALIBRATION CERTIFICATE

ER3DV6 - SN:2286 Object

Calibration procedure(8) QA CAL-02.v8, QA CAL-25.v6

Calibration procedure for E-field probes optimized for close near field

evaluations in air

Calibration date: January 19, 2015

This calibration cartificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Calibration
s Check
sheck: Apr-16
theck: Oct-15

	Namo	Function	Signature
Calibrated by:	Leif Klysner	Laboratory Technician	Sef Man
Approved by:	Katja Pokovic	Technical Manager	Lelly-
			Issued: January 19, 2015

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S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
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Glossary:

NORMX,y,z DCP

CF

sensitivity in free space

diode compression point

crest factor (1/duty_cycle) of the RF signal modulation dependent linearization parameters

A, B, C, D Polarization o

o rotation around probe axis

Polarization 3

3 rotation around an axis that is in the plane normal to probe axis (at measurement center),

i.e., 3 = 0 is normal to probe axis

Connector Angle

information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- iEEE Std 1309-2005, * IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz*, December 2005.
- b) CTIA Test Plan for Hearing Aid Compatibility, April 2010.

Methods Applied and Interpretation of Parameters:

- NORMs, y, z: Assessed for E-field polarization 9 = 0 for XY sensors and 9 = 90 for Z sensor (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide).
- NORM(f)x,y,z = NORMx,y,z * frequency_response (see Frequency Response Chart).
- DCPx,y,z: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- Ax.y,z: Bx.y,z; Cx,y,z; Dx,y,z, VRx,y,z; A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORMx (no uncertainty required).

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RTS-6066-1511-05

L6ARHT180LW

ER3DV6 - SN:2286

January 19, 2015.

Probe ER3DV6

SN:2286

Manufactured: Calibrated:

September 18, 2002 January 19, 2015

Calibrated for DASY/EASY Systems (Note: non-compatible with DASY2 system!)

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ER3DV6 - SN:2286

January 19, 2015

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2286

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (µV/(V/m) ²)	2.23	1.47	1.51	± 10.1 %
DCP (mV) ⁸	98.9	100.3	99.7	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB√μV	C	D dB	VR mV	Unc (k=2)
0	CW	X	0.0	0.0	1.0	0.00	182.8	±3.8 %
		Y	0.0	0.0	1.0		197.2	
		Z	0.0	0.0	1.0		175.9	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Numerical linearization parameter: uncertainty not required.
Uncertainty is determined using the max, deviation from linear response applying rectangular distribution and is expressed for the square of the field value.



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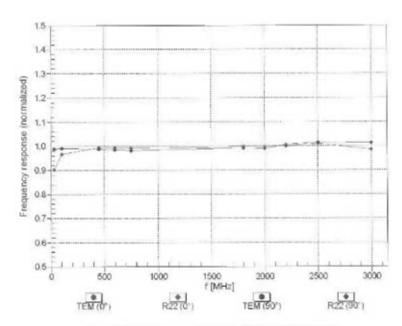
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Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

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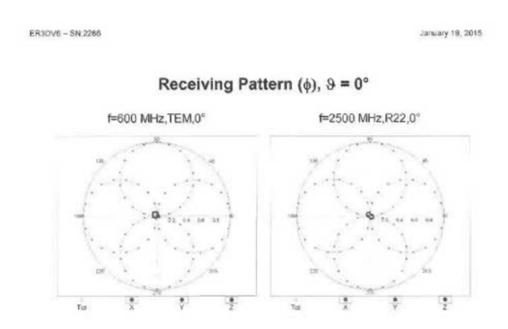
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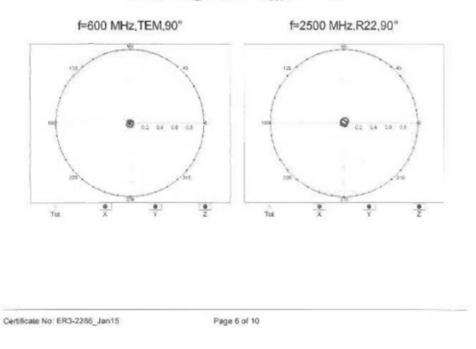
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Receiving Pattern (\$\phi\$), \$\partial = 90°





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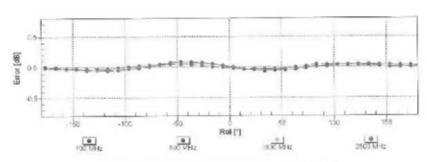
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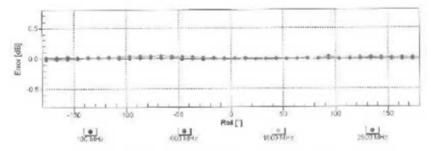
January 19, 2015

Receiving Pattern (\$), 9 = 0°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

Receiving Pattern (\$\phi\$), \$\theta = 90°



Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

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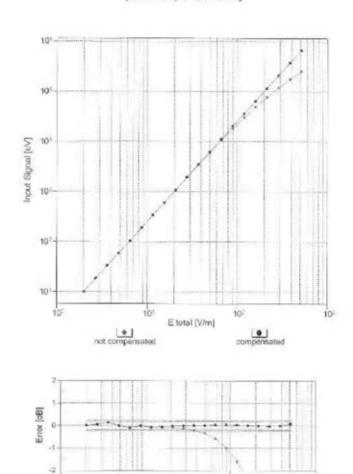
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Dynamic Range f(E-field) (TEM cell, f = 900 MHz)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)

E total [V/m]

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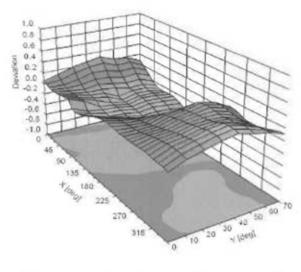
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ER3DV6 - SN:2286

Deviation from Isotropy in Air Error (\$\phi\$, \$\theta\$), f = 900 MHz

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Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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DASY/EASY - Parameters of Probe: ER3DV6 - SN:2286

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (*)	-6.5
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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