SlackB	erry		d Compatibility RF Emissions ⁻ erry® Smartphone model RHK2		Page 1(14)
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Annex B: Probe and dipole description and calibration certificates

B.1 Probe, measurement chain description, specification and calibration certificate

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DASY Dosimetric Assessment System by Schmid & Partner Engineering AG

DASY Schmid & Partner Engineering AG		HE
News Sales Contac	t	
Applications Support & Downloads	ER3DV6 ISOTRO MEASUREMENTS	PPIC E-FIELD PROBE FOR GENERAL NEAR-FIELD
Products DASY4 Packages	Download Produ	i <u>ct Flyar</u> (PDF, 192kB)
EASY4 Probes ET3DV6 - Isotropic Dos-Probe ES3DV3 - Isotropic Dos-Probe	Construction	One dipole parallel, two dipoles normal to probe axis Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycolether)
EX3DV4 - Isotropic Dos-Probe ET1DV3 - D-Probe	Calibration	In air from 100 MHz to 3.0 GHz (absolute accuracy $\pm 6.0\%$, k=2
EUV3 - Universal Vector E-Probe H3DV6 - Isotropic H-Probe	Frequency	100 MHz to > 6 GHz; Linearity; \pm 0.2 dB (100 MHz to 3 GHz)
HUV4 - Universal Vector H-Probe T1V3 - Temp-Probe DP1 - Dummy-Probe	Directivity	± 0.2 dB in air (rotation around probe axis) ± 0.4 dB in air (rotation normal to probe axis)
Data Acquisition System	Dynamic Range	2 V/m to > 1000 V/m; Linearity: \pm 0.2 dB
• Software • Phantoms • Robots	Dimensions	Overall length: 330 mm (Tip: 16 mm) Tip diameter: 8 mm (Body: 12 mm) Distance from probe tip to dipole centers: 2.5 mm
Validation Kits & Calibration Dipoles Hearing Aid Compatibility (HAC) Ext Tissue Simulating Liquids	Application	General near-field measurements up to 6 GHz Field component measurements Fast automatic scanning in phantoms
SPEAG Home		

http://www.dasy4.com/er3.htm

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All measurements were performed to the nearest element point as per the C63.19 standard. Offset distances were entered in the DASY5 software so that the measurement was to the nearest element.

Figures 1, provided by the manufacturer, illustrate detail of the probe tip and its dimensions.

ER3DV6 E-Field probe: The distances from the probe tip to the closest points on the dipole sensors are 1.45mm for X and Y and 1.25mm for Z. From the probe tip to the center of the sensors is 2.5mm.



E-Field Probe (ER3DV6)

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The following information is from the system manufacturer user manual describing the process chain:

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$
(20.1)

with	V_i	= compensated signal of channel i	(i = x, y, z)
	U_i	= input signal of channel i	(i = x, y, z)
	cf	= crest factor of exciting field	(DASY parameter)
	dcp_i	= diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

	$\mathrm{E-field probes}$:	$E_i = \sqrt{\frac{V_i}{Norm_i \cdot c}}$	ConvF
	$\mathbf{H}-\mathbf{fieldprobes}$:	$H_{\rm i} = \sqrt{V_i} \cdot \frac{a_{i0} + a_{\rm i1}}{2}$	$\frac{f + a_{i2}f^2}{f}$
with	= compensated signal of c = sensor sensitivity of cha $\mu V/(V/m)^2$ for E-field = sensitivity enhancement = sensor sensitivity factor = carrier frequency [GHz] = electric field strength of = magnetic field strength	nnel i l Probes t in solution rs for H-field probes f channel i in V/m	$\begin{array}{l} (i=x,y,z)\\ (i=x,y,z) \end{array}$

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$
(20.2)

The measurement / integration time per point is > 500 ms, as per the system manufacturer:

The time response of the field probes has been assessed by exposing the probe to a well-controlled field producing signals larger than HAC E- and H-fields of class M4. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/off switch of the power source with an integration time of 500 ms and a probe response time of <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization. The tolerances for the different systems had the worst-case of 2.6%.

BlackBerry			ring Aid Compatibility F IackBerry® Smartphon		
or Data oud Attayi	Dates of Test August	31- Sep. 23, 2015	Report No RTS-6066	-1509-19	FCC ID L6ARHK210LW
				TST-SARL-00	006
Sch	Ibration Labor mid & Partner ngineering AG			Schweizerischer Kalibrierdienst Service suisse d'étalonnage Servizio svizzero di taratura Świss Calibration Service	
The S	Swiss Accreditation S	preditation Service (SAS) Service is one of the signatories the recognition of calibration of	s to the EA	creditation No.: SCS 0108	
Clier	Blackberry	Waterloo	Certificate No:	ER3-2286_Jan15	
CA	LIBRATIO	N CERTIFICATE			
Obje	ect	ER3DV6 - SN:22	86	10 17 20 H	
Cali	bration procedure(s)	QA CAL-02.v8, G Calibration proce evaluations in air	dure for E-field probes optimized	for close near field	
Cali	bration date:	January 19, 2015	5		1
The All c	measurements and th calibrations have been	e uncertainties with confidence pr	onal standards, which realize the physical unit robability are given on the following pages and ny facility: environment temperature (22 ± 3)°C	I are part of the certilicate.	
Pri	mary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration	
	wer meter E4419B	GB41293874	03-Apr-14 (No. 217-01911)	Jan-15	
	wer sensor E4412A	MY41498087	03-Apr-14 (No. 217-01911)	Jan-15 Jan≓15	
	ference 3 dB Attenuate ference 20 dB Attenua		03-Apr-14 (No. 217-01915) 03-Apr-14 (No. 217-01919)	Jan-15	
	ference 30 dB Attenua	and the second se	03-Apr-14 (No. 217-01920)	Jan-15	
	ference Probe ER3DV		08-Oct-14 (No. ER3-2328_Oct14)	Aug-15	
DA	E4	SN: 789	30-Apr-14 (No. DAE4-789_Apr14)	4/30/2015	
20	condary Standards	ID	Check Date (in house)	Scheduled Chack	
	generator HP 8648C	U\$3642U0170D	4-Aug-99 (in house check Apr-13)	In house check: Apr-16	
	twork Analyzer HP 876	and an end of the second se	18-Oct-01 (in house check Oct-14)	In house check: Oct-15	
		Name	Function	Signature	
Cal	ibrated by:	Leif Klysner	Laboratory Technician	Sef Man	
App	proved by:	Kalja Pokovic	Technical Manager	Jell the	3
Th	s calibration certificate	shail not be reproduced except in	n full without written approval of the laboratory.	Issued: January 19, 2015	

Black		(STV100-1)	ry® Smartphone model RHK21	
Author Data Daoud Attayi	Dates of Test August	31- Sep. 23, 2015	Report No RTS-6066-1509-19	FCC ID L6ARHK210LW
Schr	bration Labo nid & Partne gineering AG ausstrasse 43, 800	itac up	S Schweizerischer Kalibrie Service suisse d'étalonni Servizie svizzere di tarab Swiss Calibration Service	age
The S Multile Glos	wiss Accreditation ateral Agreement (ssary: Mx,y,z	coreditation Service (SAS) Service is one of the signatories to the EA or the recognition of calibration certificates sensitivity in free space diode compression point crest factor (1/duty_cycle) of the RF modulation dependent linearization p		108
	ization () ization ()	 φ rotation around probe axis 9 rotation around an axis that is in th i.e., 9 = 0 is normal to probe axis 	e plane normal to probe axis (at measurement ce	nter).
Conn	ector Angle		align probe sensor X to the robot coordinate syste	em
a b	 IEEE Std 13 antennas, fro CTIA Test P hods Applied NORMx,y,z: 	om 9 kHz to 40 GHz", December 2005 an for Hearing Aid Compatibility, April 24 d and Interpretation of Paramet Assessed for E-field polarization 9 = 0 fe	of electromagnetic field sensors and probes, excl 210.	
		1800 MHz: R22 waveguide). z = NORMx,y,z * frequency_response (s	ee Frequency Response Chart)	
	DCPx,y.z: D		rs assessed based on the data of power sweep w	ith CW
	PAR: PAR is characteristic		alibrated but determined based on the signal	
	the data of p media. VR is	ower sweep for specific modulation sign the maximum calibration range express		sed on or
	Spherical iso waveguide s		ocally homogeneous field realized using an open	
		et: The sensor offset corresponds to the is). No tolerance required.	offset of virtual measurement center from the prol	be tip
	Connector A uncertainty r		formation gained by determining the NORMx (no	

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January 19, 2015

Probe ER3DV6

SN:2286

Manufactured: Calibrated: September 18, 2002 January 19, 2015

Calibrated for DASY/EASY Systems (Note: non-compatible with DASY2 system!)

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January 19, 2015

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2286

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm $(\mu V/(V/m)^2)$	2.23	1.47	1.51	± 10.1 %
DCP (mV) ⁸	98.9	100.3	99.7	

Modulation Calibration Parameters

UID	Communication System Name		A	B dBõV	C	D dB	VR mV	Unc ^L (k=2)
0	CW	X	0.0	0.0	1.0	0.00	182.8	±3.8 %
		Y	0.0	0.0	1.0		197.2	
		Z	0.0	0.0	1.0		175.9	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

⁶ Numerical linearization parameter: uncertainty not required.
⁶ Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

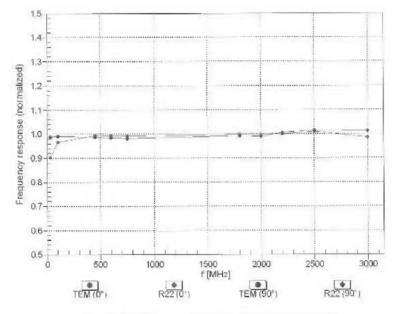
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Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

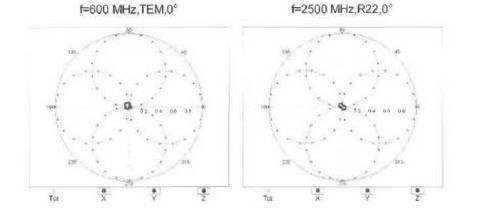
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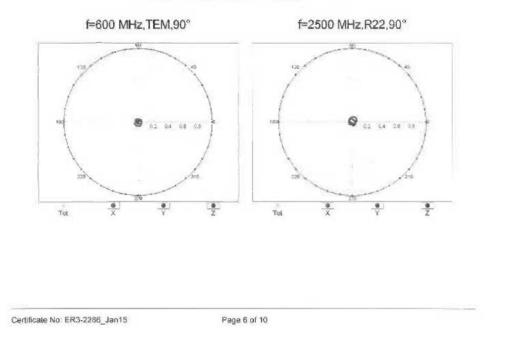
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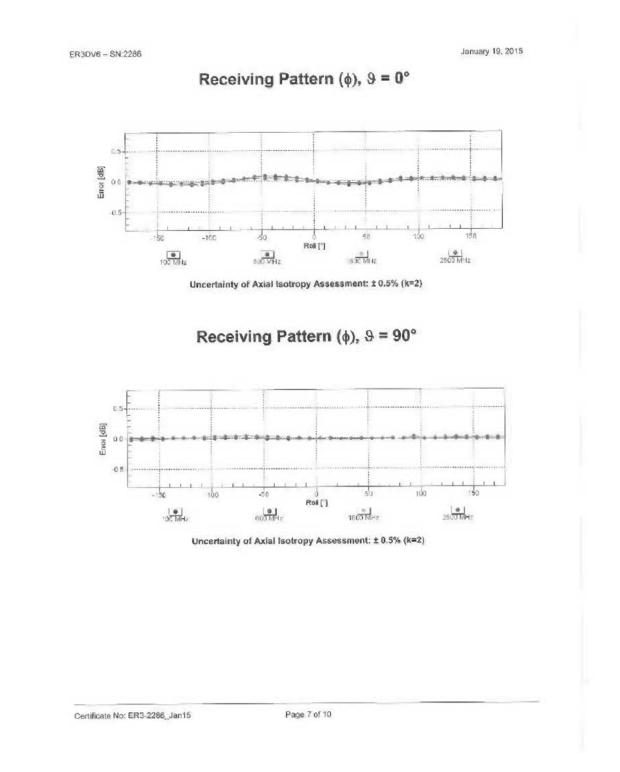
Receiving Pattern (ϕ), $\vartheta = 0^{\circ}$



Receiving Pattern (\$), & = 90°



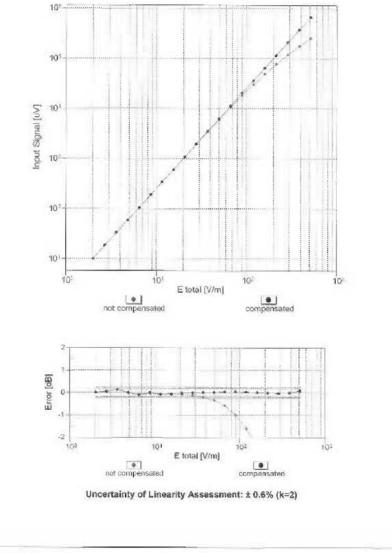
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Dynamic Range f(E-field) (TEM cell , f = 900 MHz)

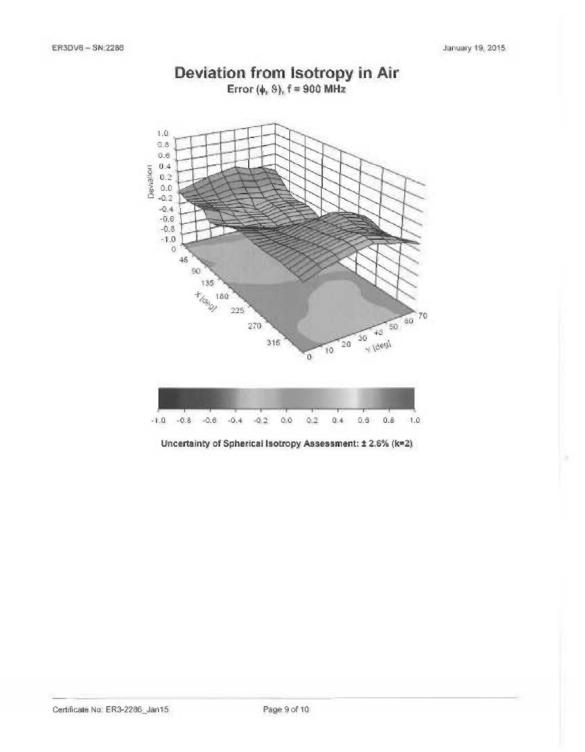


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Daoua Allayi	August	51 ⁻ 0cp. 25, 2015	110-0000-1303-13	LUA	



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DASY/EASY - Parameters of Probe: ER3DV6 - SN:2286

Other Probe Parameters

Sensor Arrangement	Rectangular		
Connector Angle (*)	-6.5		
Mechanical Surface Detection Mode	enabled		
Optical Surface Detection Mode	disabled		
Probe Overall Length	337 mm		
Probe Body Diameter	10 mm		
Tip Length	10 mm		
Tip Diameter	8 mm		
Probe Tip to Sensor X Calibration Point	2.5 mm		
Probe Tip to Sensor Y Calibration Point	2.5 mm		
Probe Tip to Sensor Z Calibration Point	2.5 mm		

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